

## Design inputs and concept

### Specifications:

- Geometry:
  - Aperture of 1000 mm
  - About 100 km long
- Vacuum: 10<sup>-9</sup> mbar
  - → Low outgassing materials
  - → In-situ bake out at 150 °C
- Mechanics:
  - Vacuum/atmospheric pressure
  - Gravity
- Environment
  - Corrosion resistant
- As cheap as possible

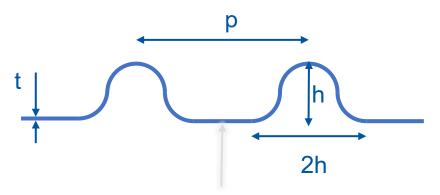
### Design inputs and concept

### Mechanical aspects of thin-walled corrugated tubes

- Withstand external pressure
- Stainless steel material
- No need of bellows
- Easier bake out
- Less raw material
- lighter forming equipment (thinner wall)

The design is driven by the buckling pressure of a corrugated tube.

Simplified geometry with two parameters.



Unfolded length of one pitch: Lr



Equivalent thickness for the material quantity:  $t_{eq} = t^*L_r/p$ 

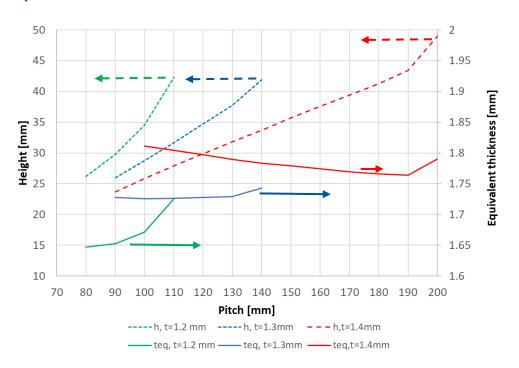
A flat section between each corrugation accommodates baffle interfaces and simplifies tooling insertion if required

For long thin tube, typical buckling mode 2 is observed.

Safety coefficient of 3 is included.



Wall thickness in the range 1.2-1.5 mm can be considered for a buckling differential pressure of 3 bars.



1.5 mm thick wall chamber could be a good starting point considering welding, convolution height.

### Specific stiffness:

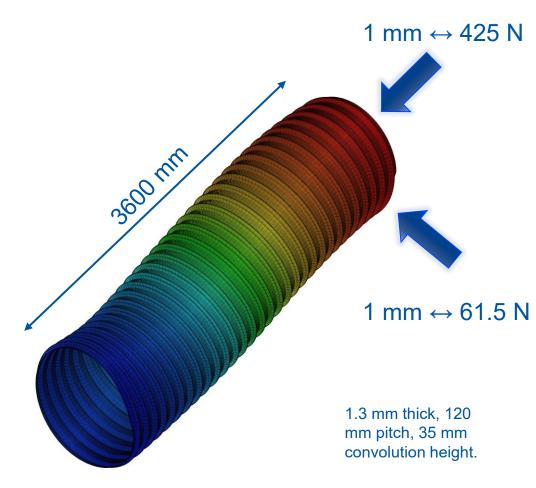
- Axial (E.S): 1.53E6 N
- Transversal (E.I): 2.4E11 N.mm<sup>2</sup>

Specific weight: 48 kg/m

Bakeout induced axial force: -3.3 kN (< 95 kN thrust force)

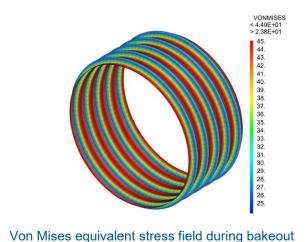
Euler buckling force (in case of accidental venting during bakeout), assuming simple supports distanced by 7.5 m: -42 kN

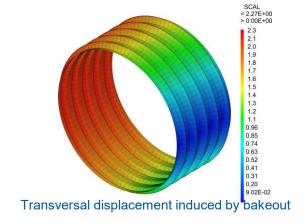
→ Global column instability not expected.



### Behaviour during bakeout (150°C):

- Stress of about 50 MPa
- Diameter dilatation of about 2.3 mm



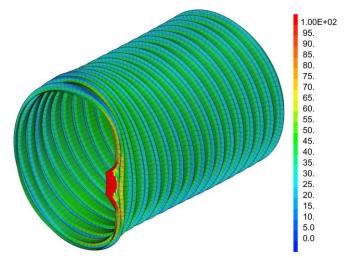


### Behaviour during bakeout with gravity:

- Assumption of a 14 m long tube
  - Supported at 3.25 m from the extremities
    - Sag ~ 18.3 mm
    - Stress in the 60 MPa (support area excluded)
  - Supported at 3.25 m from the extremities with central crutch
    - Sag ~ 2.5 mm
    - Stress in the 50 MPa (support area excluded)



Von Mises equivalent stress field during bakeout under gravity with supports distanced by 7.5 m (deformed shape factor: 100)



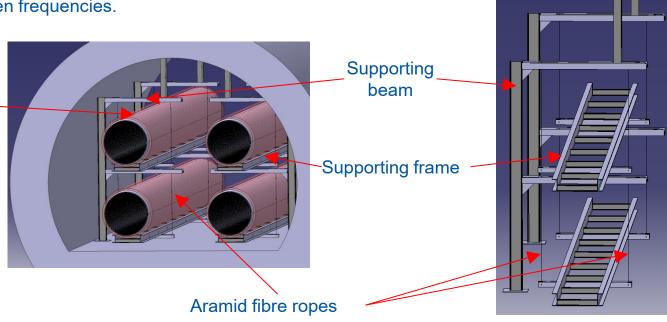
Von Mises equivalent stress field during bakeout under gravity with additional central support (deformed shape factor: 100)

# A support proposal

The proposed design, based on a suspended vacuum chamber, aims at reducing vibrations on the baffles.

Basic concept is based on harmonic oscillator and aims at lowering the first eigen frequencies.

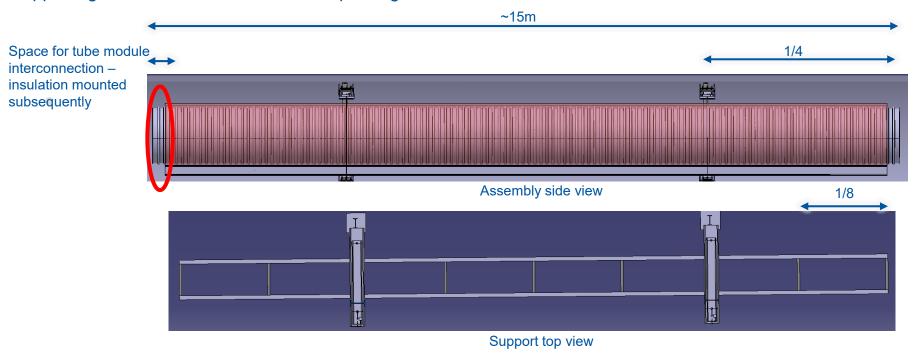
Insulated vacuum chamber



### A support proposal

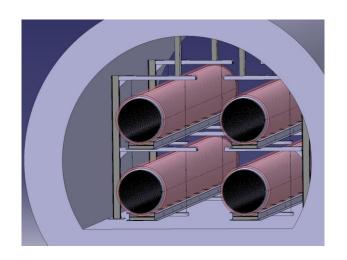
Elementary module would be composed of a ~15m long chamber, insulated and installed on a the supporting frame.

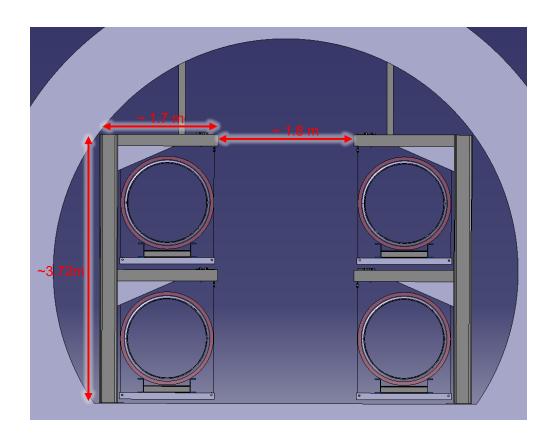
Supporting beam would be mounted and pre-aligned before module installation.



### Preliminary implementation in a tunnel cross-section

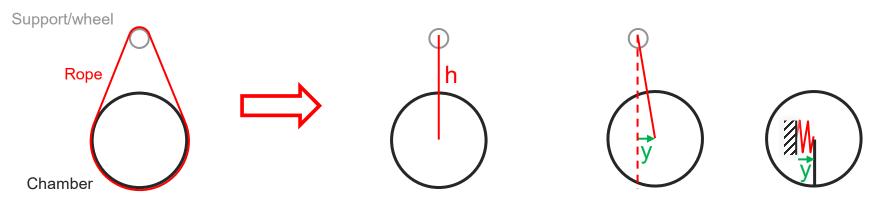
- Passage width: 1,8 m
- Depending on the tunnel floor heigh





### Column Stability for hanging structure

During the thermal treatment, the chamber is in compression without vacuum  $\rightarrow$  subjected to column buckling.



The chamber behaves as a pendulum that corresponds in lateral direction to an elastic foundation.

Specific mass

Specific foundation stiffness:  $K_S = \frac{m_l \cdot g}{h}$ Pendulum height

Expected buckling force for infinitely long column on elastic foundation:

$$F_{cr} = \sqrt{4 \cdot K_S \cdot E \cdot I}$$

For h = 1 m, EI =  $2.4E11 \text{ N.mm}^2$  and m=  $48 \text{ kg.m}^{-1}$ :  $F_{cr} \sim 21.25 \text{ kN}$ 

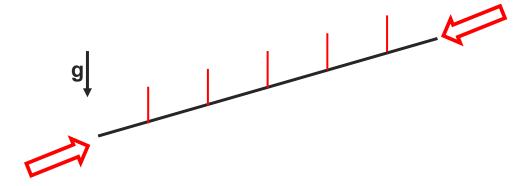
### Column Stability for hanging structure

#### Two models:

• Beams in 2D with equivalent springs to model the pendulum effect; eigen mode study



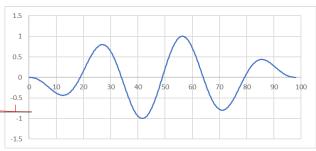
Beams in 3D with gravity and initial imperfection; non linear large displacement study



### Column Stability for hanging structure

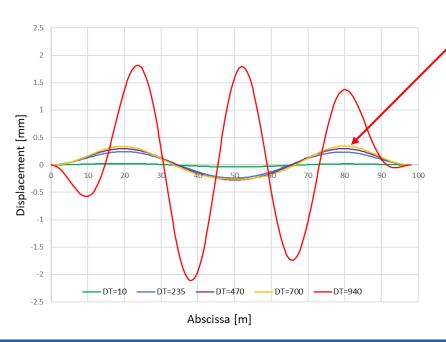
#### 100 m model:

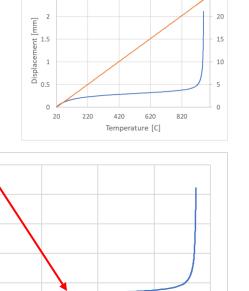
• 2D eigen value model: buckling force: 22.15 kN



- 3D non linear model:
  - Instability at ~ 23 kN (930 C)

• Plateau with stable deformation related to initial imperfection





10

Force [kN]

15

20

25

2.5

2

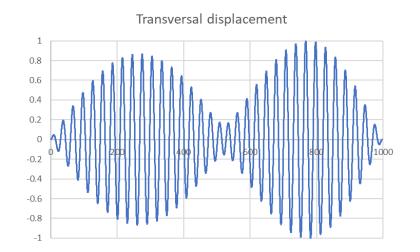
1

Displacement [mm]

### Column Stability for hanging structure

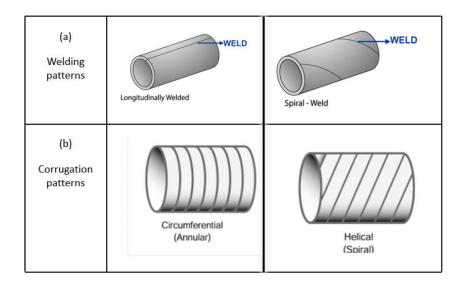
#### 1000 m model:

2D eigen value model: buckling force: 21.3 kN



No significant difference between the 100 and 1000 m models. Very good agreement between the two models and the theoretical values. The chamber remains stable during the heat treatment in the 200-300 C range (Safety coefficient: 3-4).

# Annular vs spiral corrugations









Spiral corrugations

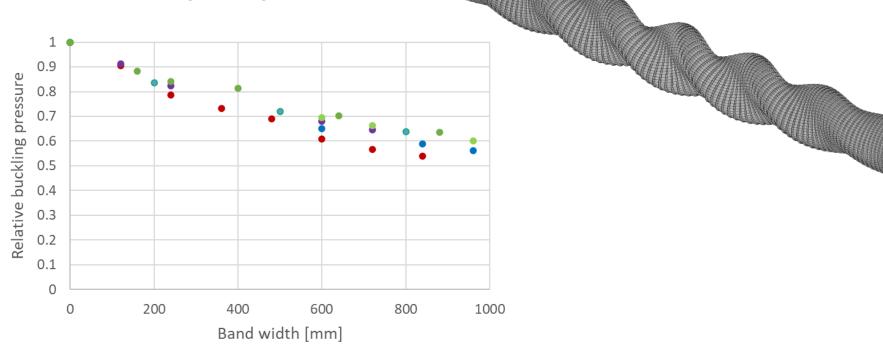


#### **Drawbacks**

Decrease of mechanical performance:

Higher longitudinal stiffness

Lower buckling strength



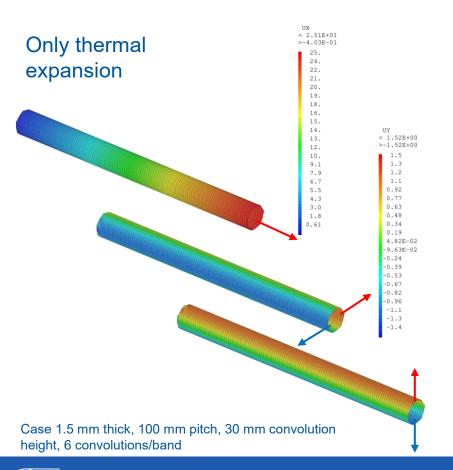
Influence of band width (helice angle) on the relative buckling pressure for different convolution parameters

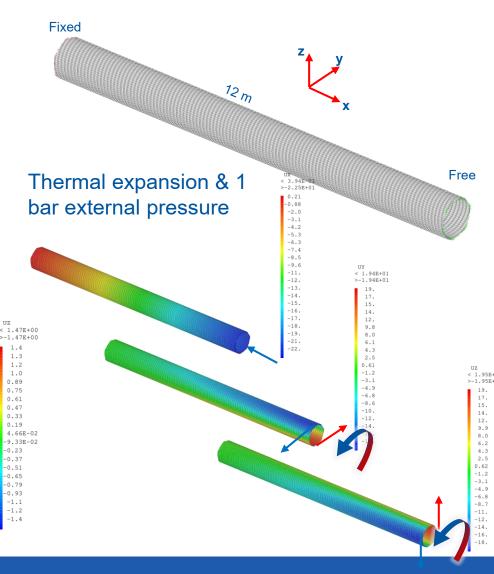


### **Drawbacks**

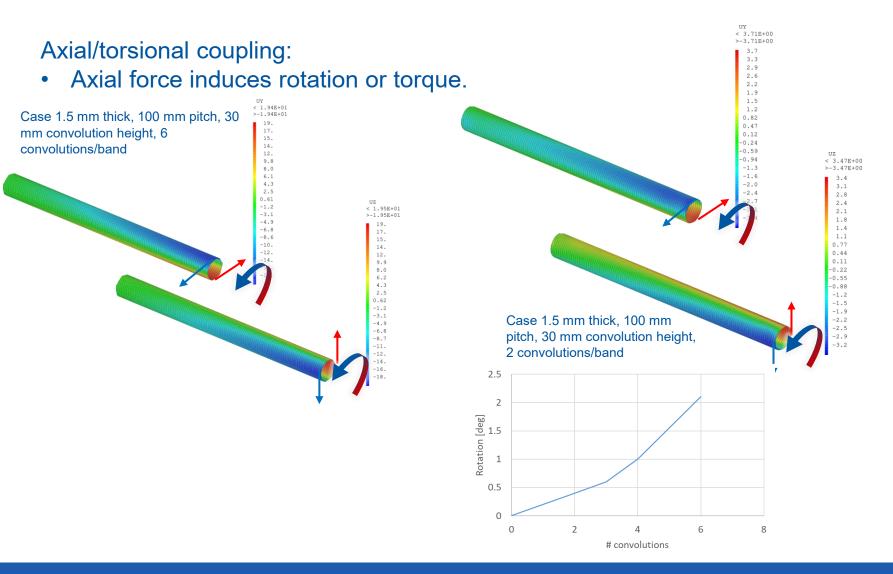
### Axial/torsional coupling:

Axial force induces rotation or torque.



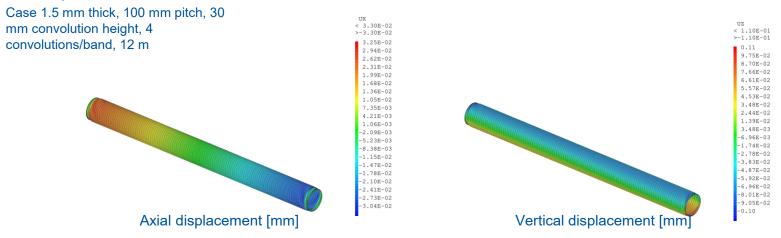


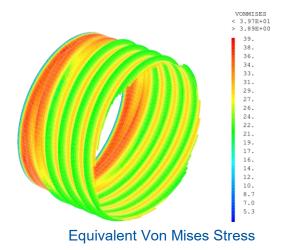
### **Drawbacks**



Reaction forces – effect of boundary conditions

### Clamped both extremities, under vacuum





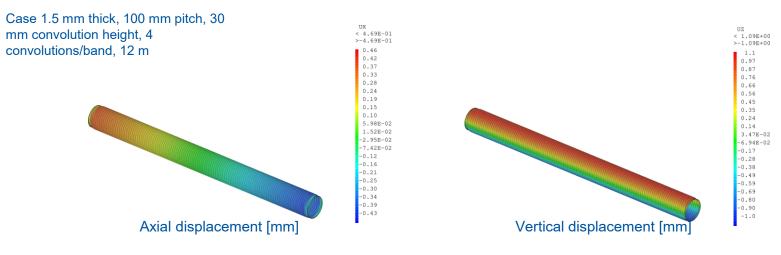
Axial moment: -6343 N.m

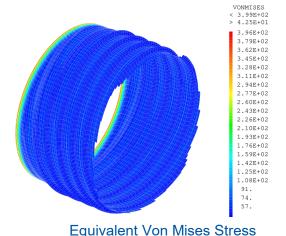
Axial force: 4820N

Stress in the 30 MPa range.

Reaction forces – effect of boundary conditions

### Clamped both extremities, under vacuum during bakeout at 150 C





Stress in the 60 MPa range.

Axial moment: -62626 N.m.

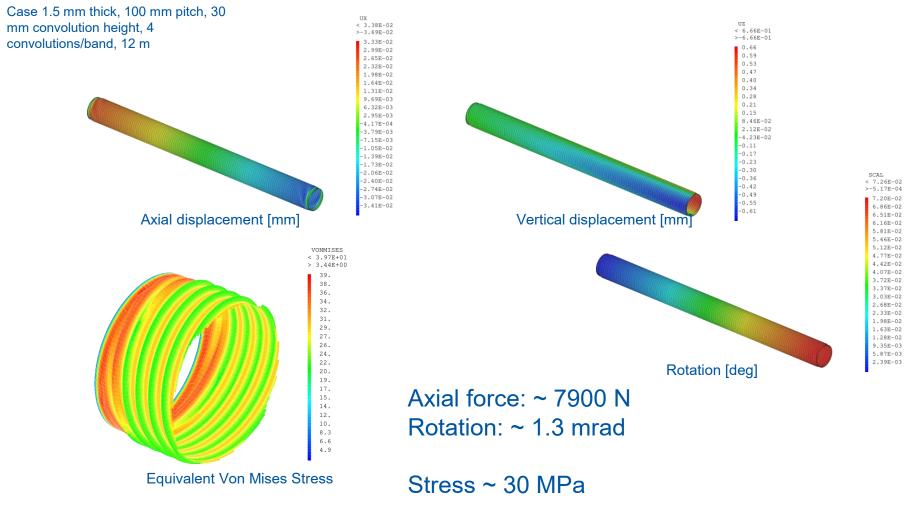
Axial force: -35340 N

### For comparison:

- Torque generated by friction under weight
   50 kg/m \* 6 m \* 9.8 \* 0.1 \* 0.5 ~ 150 N.m
- Buckling in torsion (2πEI/L): ~1.5E5 N.m

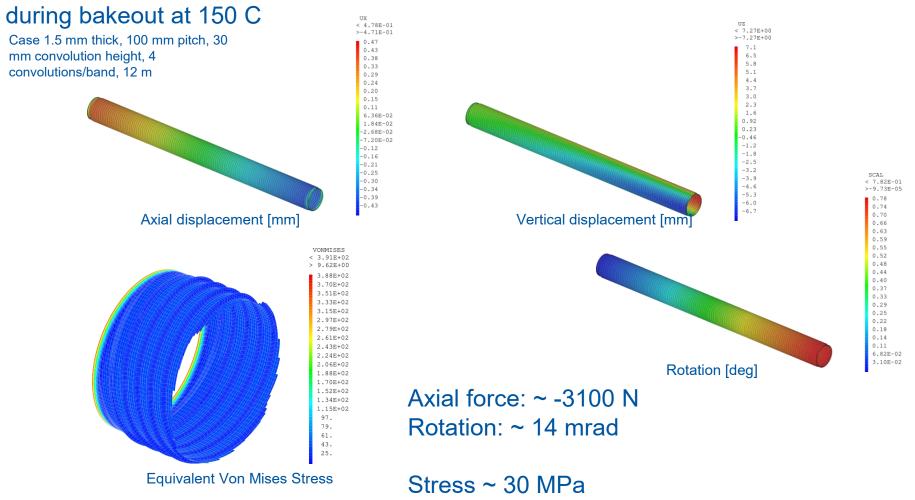
Reaction forces – effect of boundary conditions

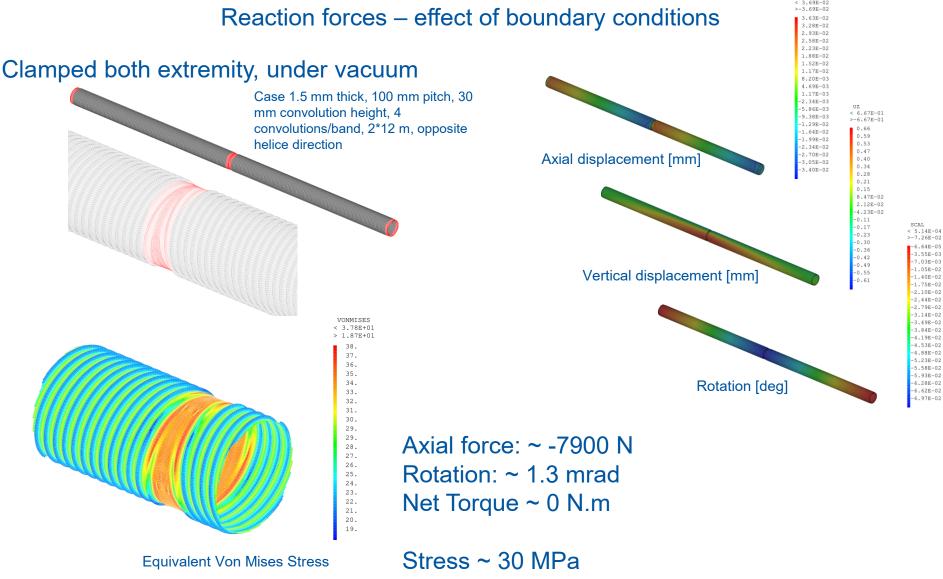
Clamped at one extremity, fixed axially and free to rotate at the other, under vacuum



Reaction forces – effect of boundary conditions

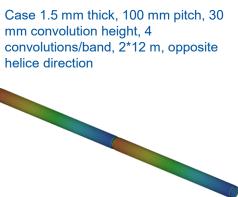
Clamped at one extremity, fixed axially and free to rotate at the other, under vacuum





Reaction forces – effect of boundary conditions

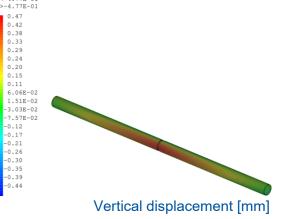
Clamped both extremity, under vacuum during bakeout



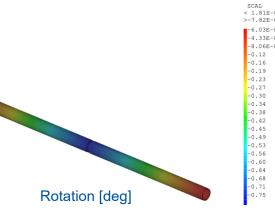
Axial displacement [mm]

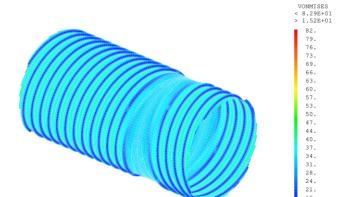


**Equivalent Von Mises Stress** 



1.6 0.92 0.23 -4.6 -5.3 -6.0 -6.7





Axial force: ~ -3100 N

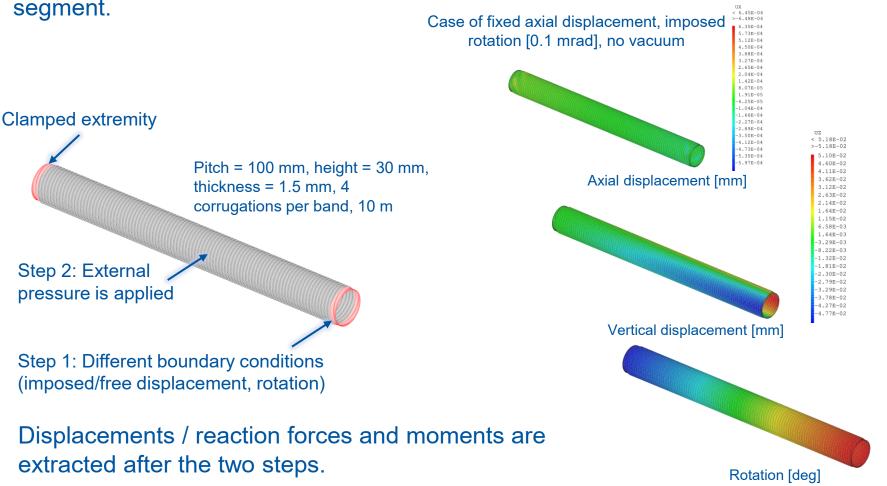
Rotation: ~ 14 mrad

Net Torque ~ 0 N.m

Stress ~ 30 MPa

Specific stiffnesses of the chamber

Stiffnesses of 10 & 15 m long vacuum chambers and 4 helicoidal pitch (1.613m)



< 5.73E-03

5.14E-03 4.87E-03 4.59E-03

4.32E-03 4.05E-03 3.77E-03

3.50E-03 3.23E-03 2.96E-03

2.41E-03 2.14E-03 1.86E-03 1.59E-03 1.32E-03

1.05E-03 7.73E-04 5.00E-04

2.27E-04

Specific stiffnesses of the chamber

Results for the 10 m long chamber

Boundary conditions		After	After
Rotation [mrad]	Axial displacement [mm]	displacement	displacement and under vacuum
0.1	Free	$M_{\alpha}$ = 82.5 N.m $\Delta_{x}$ = -0.177 mm	$M_{\alpha}$ = -14790 N.m $\Delta_{x}$ = -3.1 mm
0.1	0 (fixed)	$M_{\alpha}$ = 605 N.m $F_{x}$ = 295 N	$M_{\alpha}$ = -5730 N.m $F_{x}$ = 5120 N
0 (fixed)	1	$M_{\alpha}$ = 2950 N.m $F_{x}$ = 1670 N	$M_{\alpha}$ = -3380 N.m $F_{x}$ = 6500 N
Free	1	$\alpha$ = -0.49 mrad F <sub>x</sub> = 230 N	$\alpha$ = 0.57 mrad F <sub>x</sub> = 7900 N
Free	Free		$\alpha$ = 18.7 mrad $\Delta_x$ = -34.9 mm
Fixed	Fixed		$M_{\alpha}$ = -6330 N.m $F_{x}$ = 4830 N

Beam model

### Definition of an equivalent 1D beam:

1<sup>st</sup> step: definition and determination of the axial/torsion coupling Modification of the constitutive law:

$$F = ES*U/L + k. \alpha/L$$

Coupling term

$$C = GJ*\alpha/L + k.U/L$$

2<sup>nd</sup> step: consideration of the vacuum effect

- Contraction and twist of the chamber if free
- Tension/torque if the chamber is fixed.

Modification of the constitutive law:

F= ES\*(U/L-
$$\epsilon_0$$
) + k. ( $\alpha$ / L- $\theta_0$ )

C= GJ\* 
$$(\alpha/L-\theta_0)$$
 + k \* $(U/L-\epsilon_0)$ 

Vacuum force is introduced by the free strains in axial and rotation

The sign of k and  $\theta_0$  depends on the helice direction (left or right-hand).

#### Beam model

Definition of an equivalent 1D beam:

3<sup>rd</sup> step: Thermal strain.

F= ES\*(U/L-
$$\epsilon_0$$
- $\epsilon_{th}$ ) + k. ( $\alpha$ / L- $\theta_0$ )

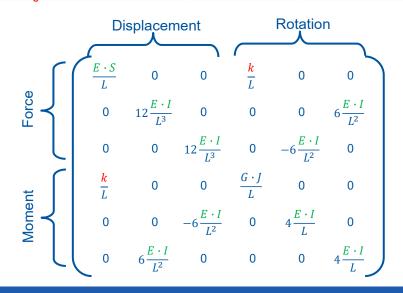
C= GJ\* (
$$\alpha$$
/ L- $\theta_0$ ) + k \*(U/L- $\epsilon_0$ - $\epsilon_{th}$ )

Thermal strain:  $\varepsilon_{th}$ = 1.6E-5· $\Delta$ T

Implementation in a FE code by modifying the stiffness matrix of the beam elements.

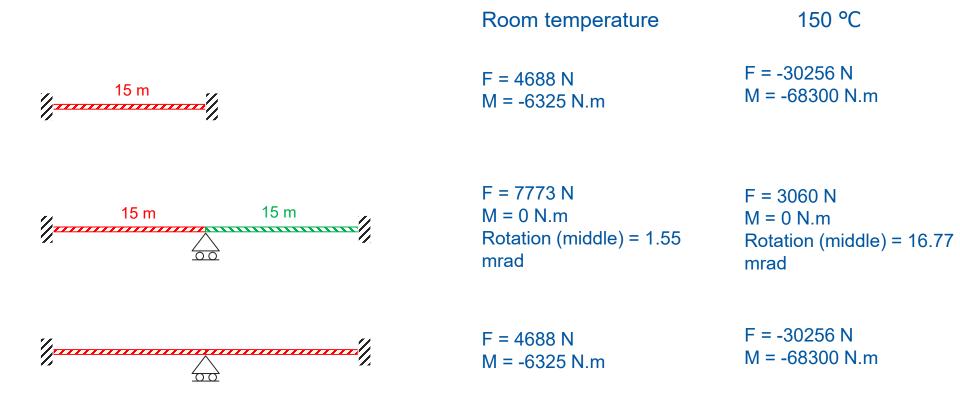
Parameter	Value	Unit
Torsion stiffness (GJ)	6.11E+07	N.m <sup>2</sup>
Coupling axial-torsion (k)	2.98E+07	N.m
Axial stiffness (ES)	1.68E+07	N
Bending stiffness (EI)	2.98E+5	N.m <sup>2</sup>

Free strain under vacuum	Value	Unit
Axial $\varepsilon_0$	-3.4306E-03 m/m	
Rotation $\theta_0$	1.7767E-03	rad/m



#### Beam model

The model has been cross-checked with 3D shell model (10 m, 15m, 1.6 m) and the applied to different configurations



#### Beam model

### Application to different configurations



#### Room temperature

F = 7722 N

M = -314 N.m

Rotation = 1.15 mrad

Axial displacement = 0.68 mm

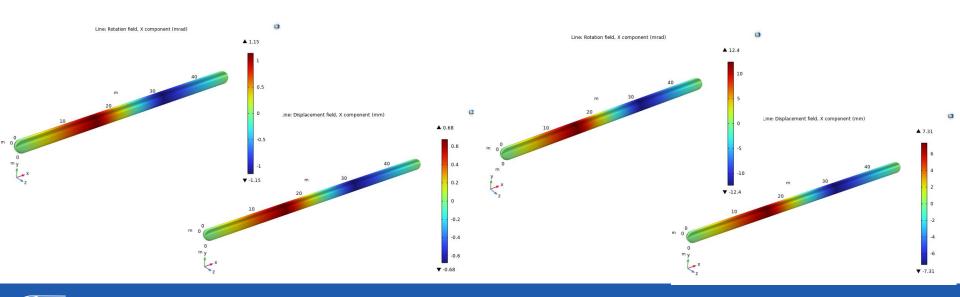
150 °C

F = 2508 N

M = -3398 N.m

Rotation = 12.4 mrad

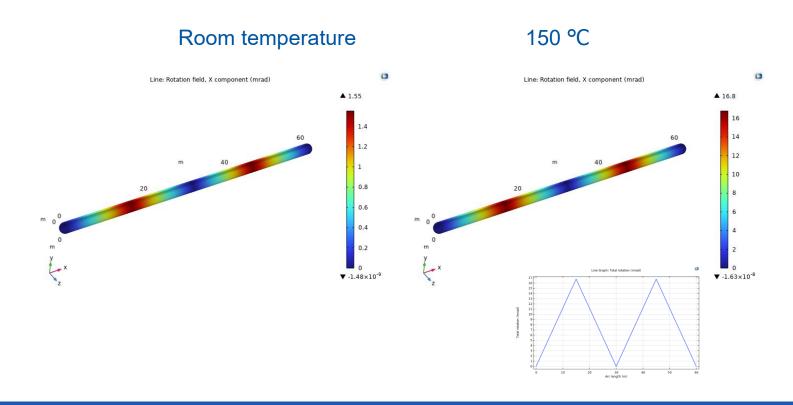
Axial displacement = 7.3 mm



Beam model

Application to different configurations

4 chambers with alternate helice direction equivalent to 2 chambers



### Conclusion

The integration of the corrugations to the sheet before the tube forming, leading to helicoidal corrugations, presents some advantages for the manufacturing.

But in addition to the corrugation effects:

- Limited bending stiffness → dedicated supports,
- Vacuum induced axial force,

the helicoidal corrugations leads to:

- Significant reduction (~50%) of the buckling strength against external pressure,
- Strong axial/torsion coupling,
- (less convenient interface to the supports).

Stresses in the chamber remain acceptable, but reaction forces in the supports can be large and strongly depend on the support configuration.

A 1D beam model has been developed to account this coupling and can be used to assess the reaction forces under vacuum and during bakeout.

Effect of the coupling can be reduced with alternated helice direction.

Despite easier manufacturing and cleaning process with spiral corrugations, vacuum chambers with annular convolutions seem required.