

LIGO LIVINGSTON OBSERVATORY

# FILTER CAVITY ANGULAR CONTROL SYSTEM FOR GREEN AUXILIARY BEAM

Tomris İlkim Doğan

CALTECH LIGO SURF SUMMER 2025

Mentors: Adam Mullavey Begüm Kabagöz

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05 ZM's Squeezing 06 FC's 02 Filter Cavity 03 ALOGs Results 04 Alignment Control Loop 08 Conclusion and Outlook

# QUANTUM NOISE

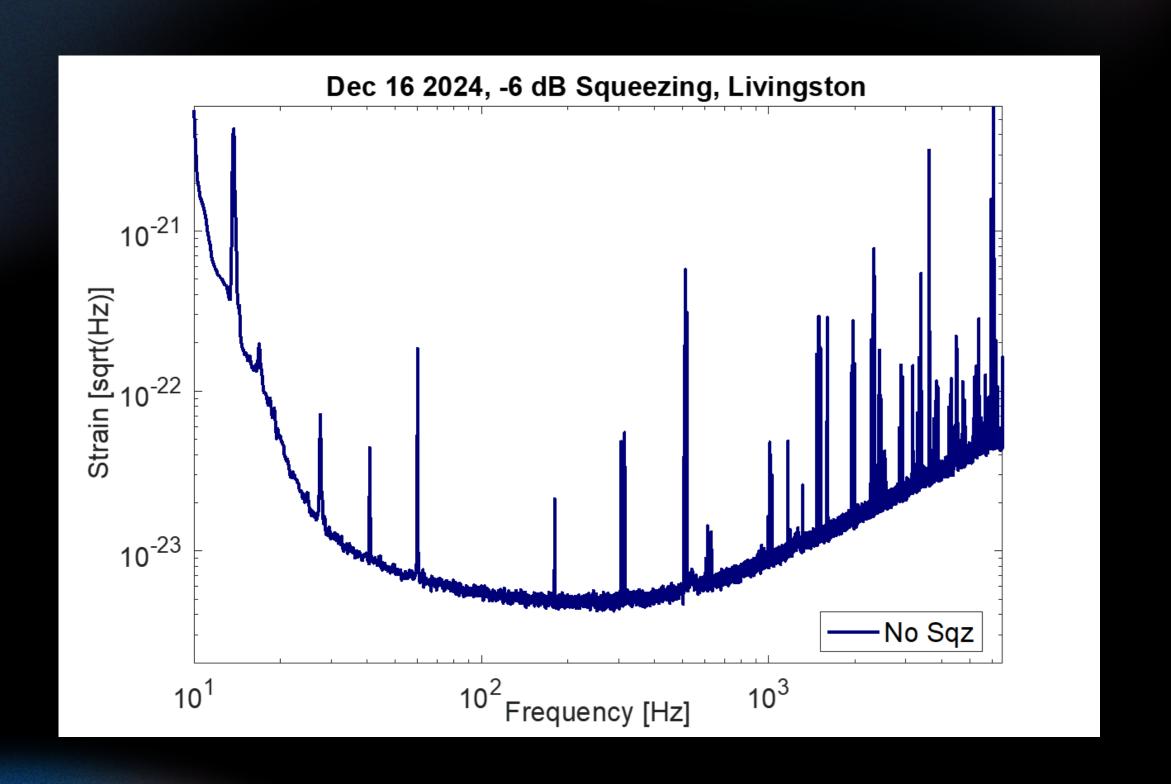
Quantum noise = fundamental measurement limit in LIGO

AMPLITUDE QUADRATURE

radiation pressure noise (dominant at low freq)

PHASE QUADRATURE

shot noise (dominant at high freq)

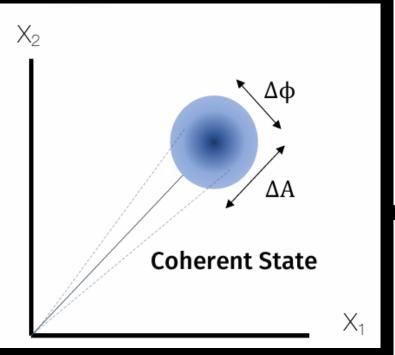


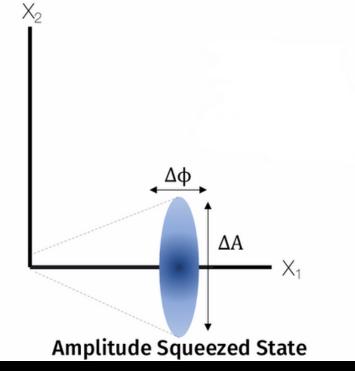
# SQUEEZING

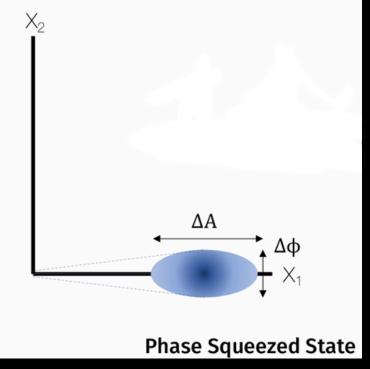
- Coherent state: equal uncertainty in both quadratures
- Squeezed state: reduce uncertainty in one quadrature at the cost of the other

$$E = \sin(\omega t + \phi) = \sin\phi\cos(\omega t) + \cos\phi\sin(\omega t) \ = X_1\cos\phi + X_2\sin\phi$$

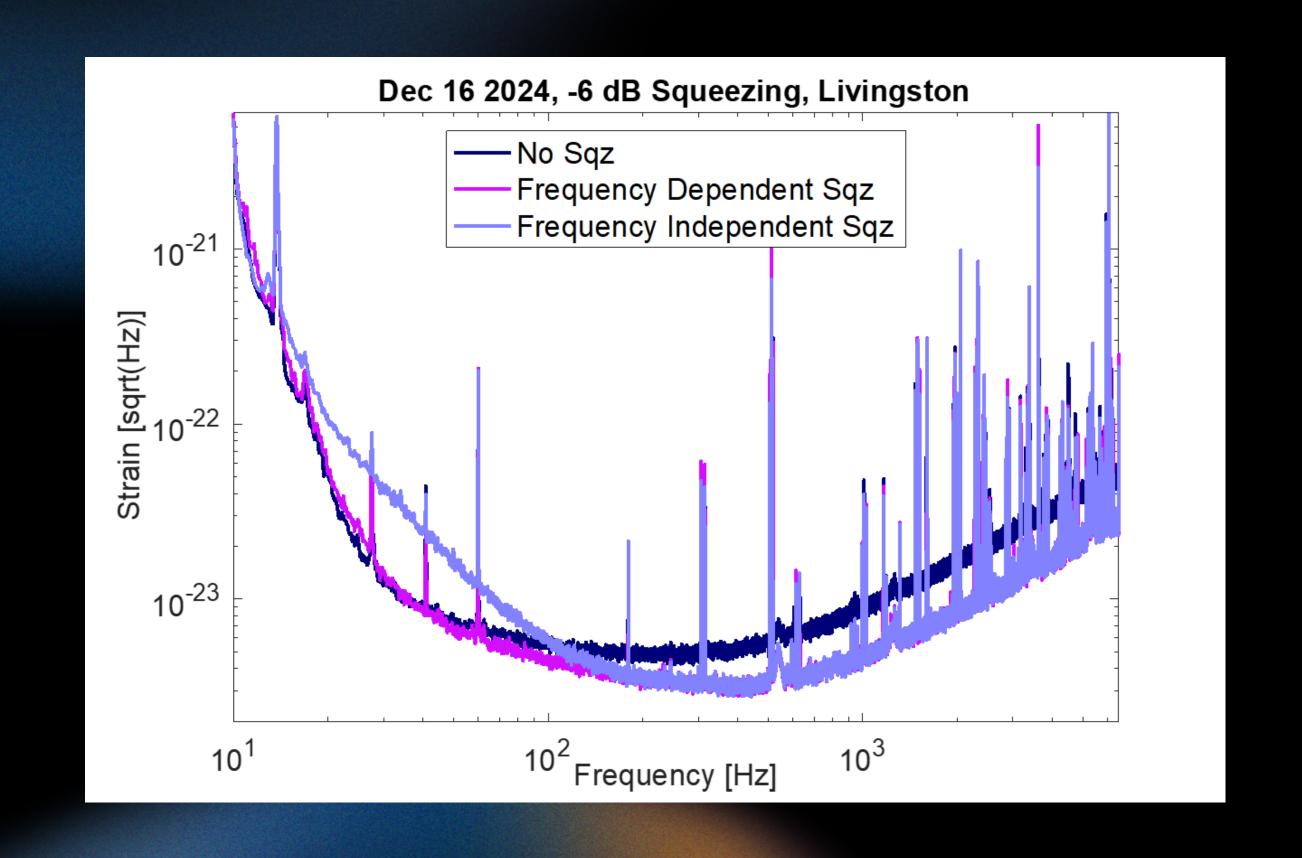
$$\Delta X_1 \, \Delta X_2 \, \geq \, rac{1}{4}$$

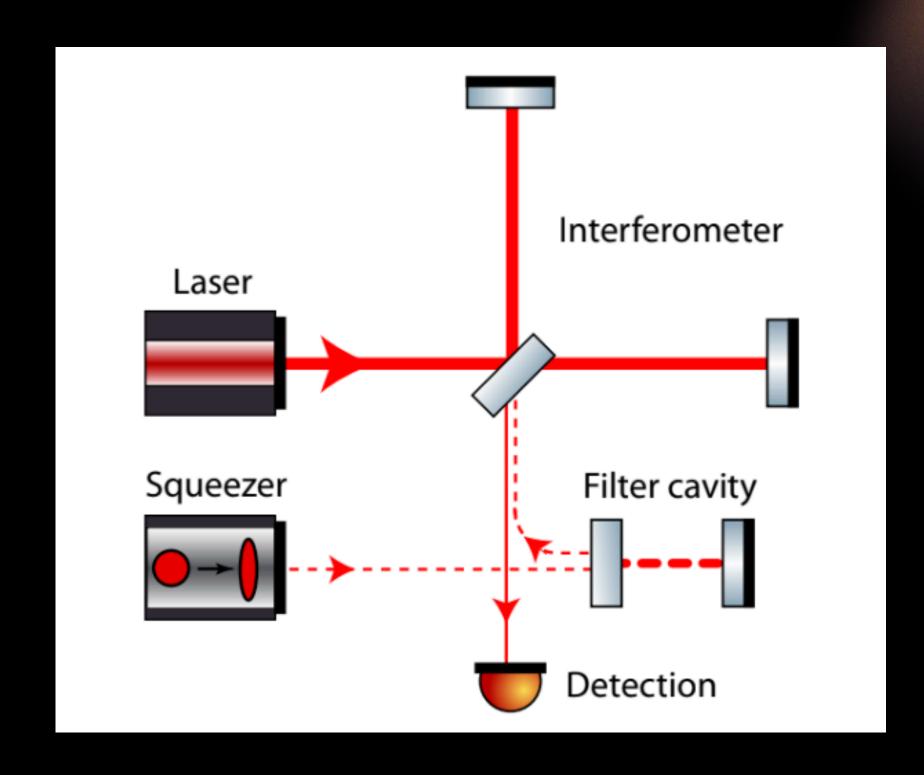






# FREQUENCY DEPENDENT SQUEEZING





# FILTER CAVITY

A long, high-finesse optical cavity that rotates the phase of squeezed vacuum light in a frequency-dependent way.

- Enables frequency-dependent squeezing.
- Green beam (532 nm) pre-locks cavity length near IR (1064 nm) resonance.
- Squeezed light enters; cavity detuning controls quadrature rotation.
- Length ~300 m

Reports until 15:48, Sunday 13 July 2025

begum.kabagoz@LIGO.ORG - posted 15:48, Sunday 13 July 2025 (77575)

FC green alignment + polarization into the fiber

TJ and Radar called. FC was unable to proceed through the Green Locked polarization correction fixed the issue. We locked smoothly after that.

Trending back the FC TRANS (green) signal, the power has been drifting do polarization drifting through the fiber, since adjustment with the half wave plat from about 600 counts. It is probably a good idea to check the FC\_trans sign: Adam M. as far as I know.

Some notes about the FC guardian

- . DO NOT LOAD or PAUSE the FC GRD. For some reason, this crashe
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Reports until 01:54, Thursday 23 January 2025

begum.kabagoz@LIGO.ORG - posted 01:54, Thursday 23 January 2025 - last comment -SQZ FC realignment due to cold

Begum, Adam

Due to unusually cold weather (and the FC end station temperature issues), the alignment f So much so that the FC refl and trans beams were out of the FOV of the cameras. ZM1&3 v on the cavity axis and FC1/2 to optimize the coupling to the cavity. FC trans&refl cameras, FC\_TRANS\_A\_SUM\_OUT, IR flashing measured with SQZ-FC\_WFS\_A\_I\_SUM\_NORM, CI OMC\_TRANS\_RF3\_ABS\_OUT were used to optimize the signals. Care was taken to keep t before, so that the alignment adjustments can happen adiabatically via FC ASC, while the a the FC IR lock was achieved, FC ASC aligned the optics well (~1400 counts on SQZ-FC\_TF to fiber ~26 mW), a photo of the screenshots for the beam positions are given here. Note the (marked with green) while beam on FC2 was still out of FOV of camera. During the day, the down, see current

To help track the alignment changes easier, we recomissioned the FC ASC offload (this was Since FC GR and IR were co-aligned recently, see alog 74867, this should be fine now.

## Images attached to this report



## Comments related to this report

begum.kabagoz@LIGO.ORG - 03:36, Thursday 23 January 2025 (74937)SQZ

After the lockloss, FC had trouble finalizing lock again, see 74936. FC green lock was very g the FC2 got kicked. It turned out the LO signal was too small. Some ZM3 alignment tweaking issue. This is potentially a reason to avoid offloading FC ASC, so I commented the FC ASC

begum.kabagoz@LIGO.ORG - 17:38, Thursday 23 January 2025 (74951)SQZ

Here is a plot of the FCES end station temperature drop (~12 F°) that caused the big drift o

#### Images attached to this comment



Displaying report 1-1 of 1.

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karla.ramirez@LIGO.ORG - 23:15, Sunday 24 Novel

As of 05:10 UTC, the IFO is in OBSERVE mode. Begu add a comment along with more details.

begum.kabagoz@LIGO.ORG - 23:22, Sunday 24 No

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Some quick references: Channel to check while alignin Can also use the FCGS REFL and FCGS TRANS cam green circle on REFL cam, and pink circle on TRANS of

Displaying report 1-1 of 1.

Reports until 18:20, Saturday 05 July 2025

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begum.kabagoz@LIGO.ORG - posted 18:20, Saturday 05 July 2025 (77470)

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While I was aligning the FC, I saw the FC guardian being restarted, see 77469 from Vlad. After

## Images attached to this report





Displaying report 1-1 of 1.

02 74935 77575

03 74190

04 77470

LIGO-T2500287

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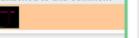
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Here is a plot of the FCES end station

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77575

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- 5. Looking at green trans signal, adjust the polarization into the FC green fiber (attached s the FC guardian being restarted, see 77469 from Vlad. After
- 6. Ideally at this point, the green trans signal > locking threshold+100. If not, decrease the FC LSC Mini screen (threshold marked with red in attached screenshot), by clicking c button on the top left of the SQZ Overview, see red marked).
- 7. If the issue persists, call an expert.

Images attached to this report









Displaying report 1-1 of 1.

04 77470

Reports until 15:48, Sunday 13 July 2025

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## Images attached to this comment



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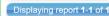
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Lockloss at 01:59 UTC - Unknown

At approximately 01:59 UTC (1416535213), a lock loss occurred. The cause is unclear, but the lock loss page in the ETMX suspension L3 outputs. Five seconds after the lock loss, the MC2 suspension watchdog tripped and r until I received a one-hour lost lock call, which required human intervention.

Microseism noise is slightly higher than the last time the interferometer (IFO) lost lock and subsequently relocke contributes to the IFO's difficulty in locking as quickly as before. Please refer to the attached document for more

Over the last hour, the IFO has struggled to reach a low noise state. It lost lock twice during the TURN\_ON\_DHA during the SWITCH ESD TO LOW NOISE state.

Currently, the IFO is attempting to lock again, and I hope it will succeed this time.

## Images attached to this report



**Comments related to this report** 

karla.ramirez@LIGO.ORG - 23:02, Sunday 24 November 2024 (74188)

IFO reached LOW NOISE at 04:52 UTC, but SQZ is having difficulty locking FC. I contacted Begum, and she is currently investigating this issue.

karla.ramirez@LIGO.ORG - 23:15, Sunday 24 November 2024 (74189)

As of 05:10 UTC, the IFO is in OBSERVE mode. Begum mentioned tweaking the alignment a little bit, and then add a comment along with more details.

begum.kabagoz@LIGO.ORG - 23:22, Sunday 24 November 2024 (74190)SQZ

FC1 and FC2 alignment needed some minor tweaking, using the procedure outlined in the SQZ Wiki. After that the smoothly.

Some quick references: Channel to check while aligning is SQZ-FC TRANS A SUM OUT. Can also use the FCGS REFL and FCGS TRANS cameras while aligning, a good beam position for green locking green circle on REFL cam, and pink circle on TRANS cam.

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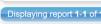
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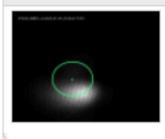






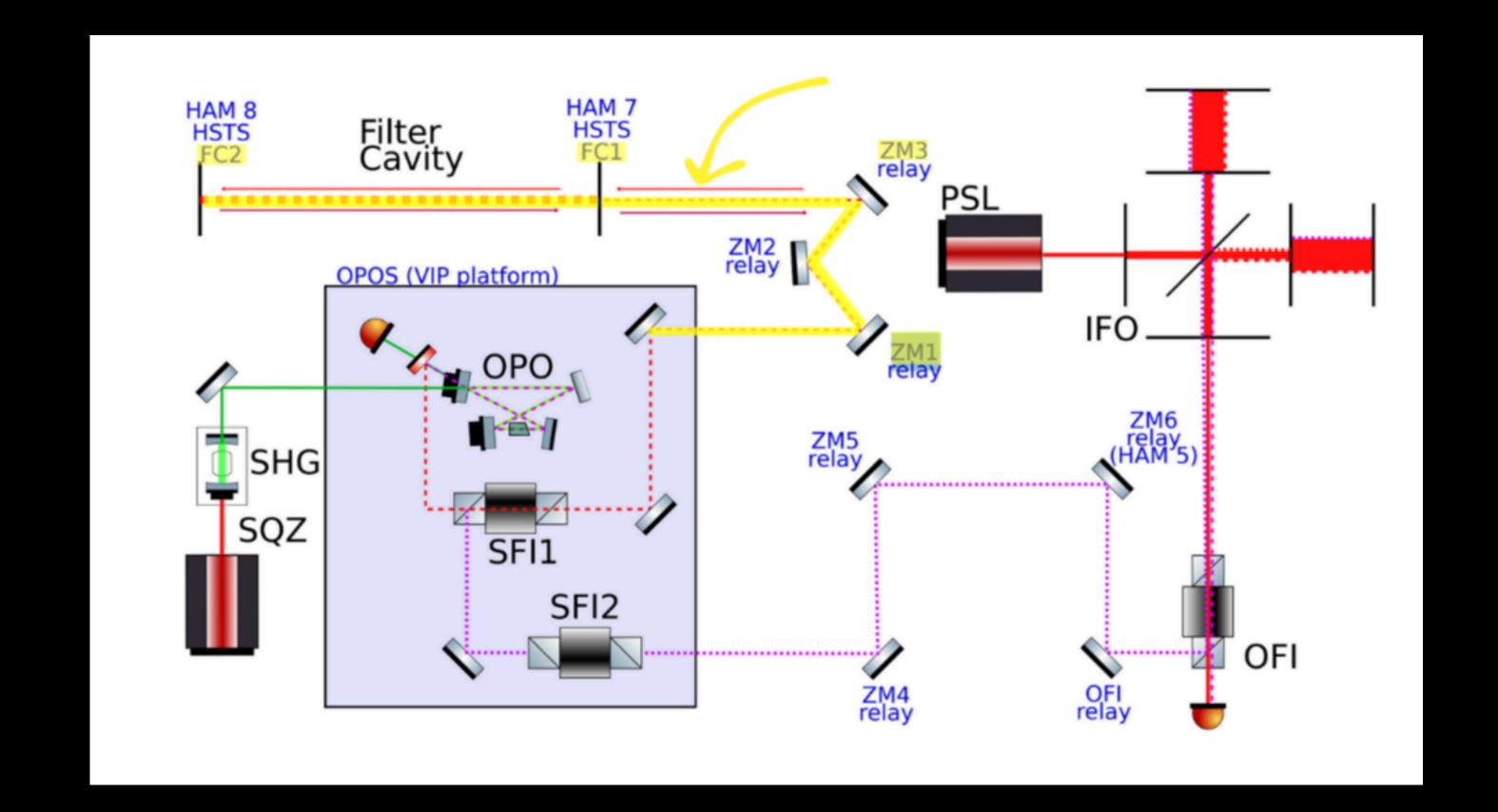
## 01 <u>77575</u>

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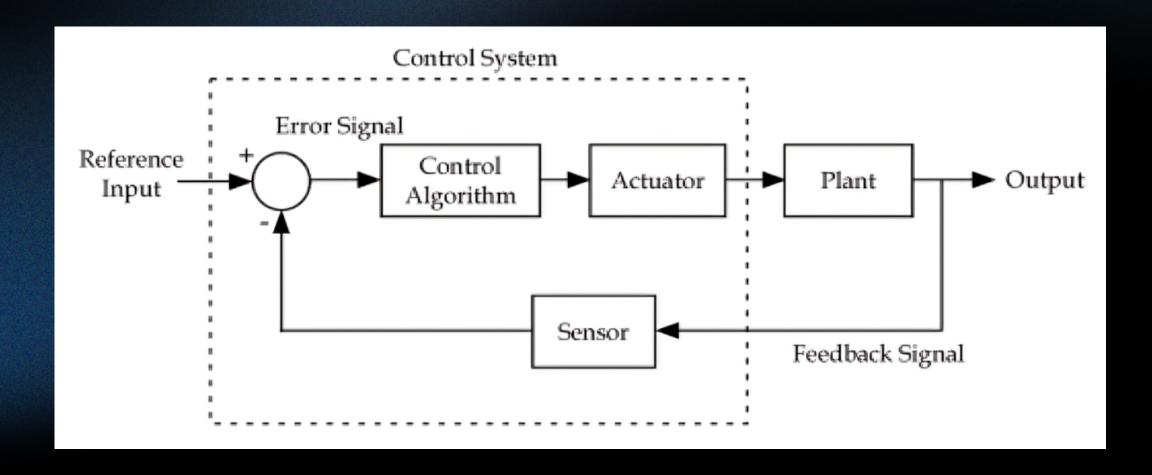




Displaying report 1-1 of 1.



# ALIGNMENT CONTROL LOOP



Sensor

Filter Cavity Transmitted Green Signal

> Filter Cavity Length Control Signal

Controller

Filter Bank

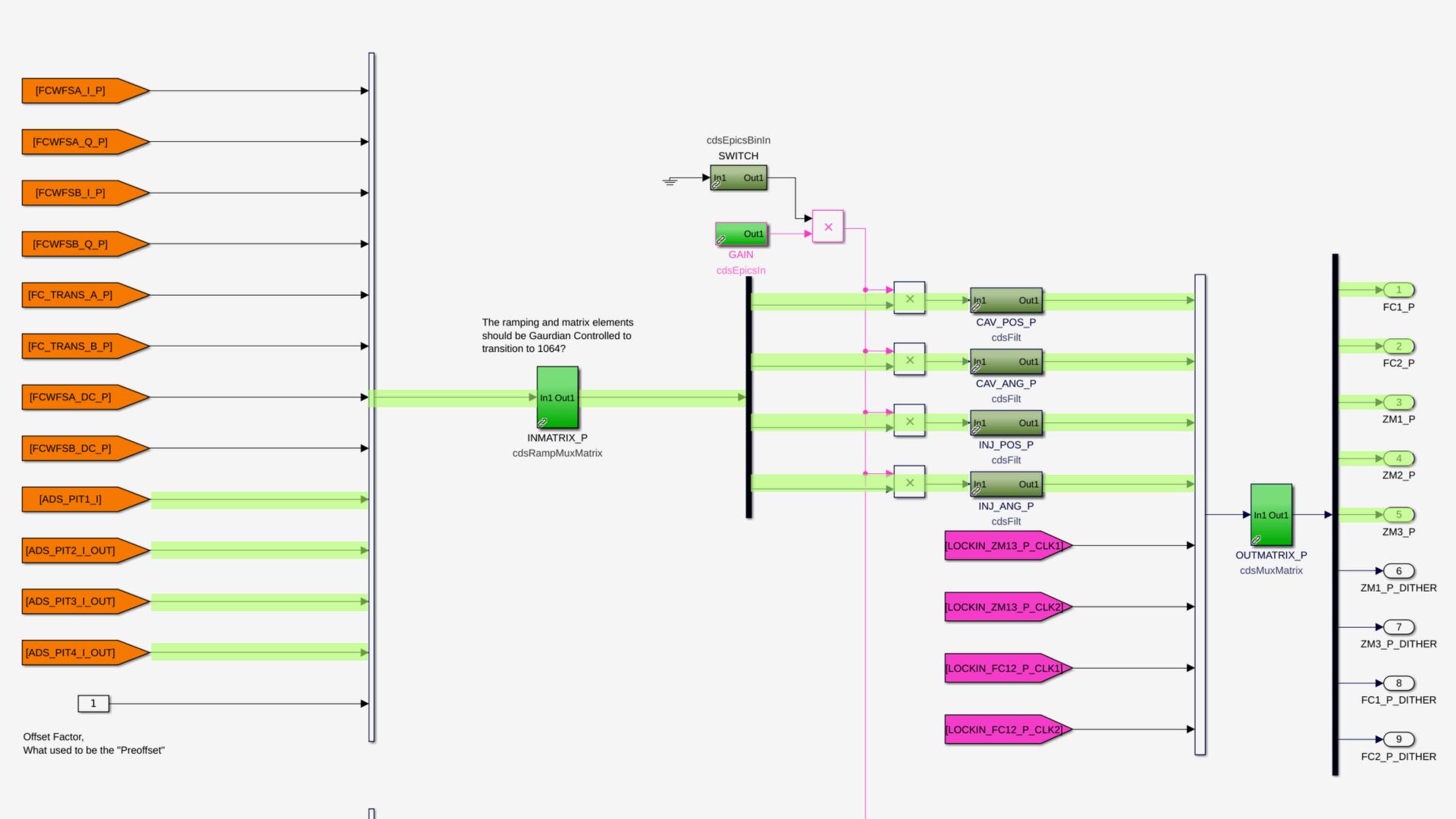
Filter Bank

Actuator

Electro-Magnetic actuator on ZM mirrors

Electro-Magnetic

actuator on FC mirrors



# DITHER & DEMODULATION

## Dithering

- Apply small sinusoidal excitation (mirror pitch/yaw) at a known frequency.
- This creates a controlled oscillation in a chosen readout signal.

## Demodulation

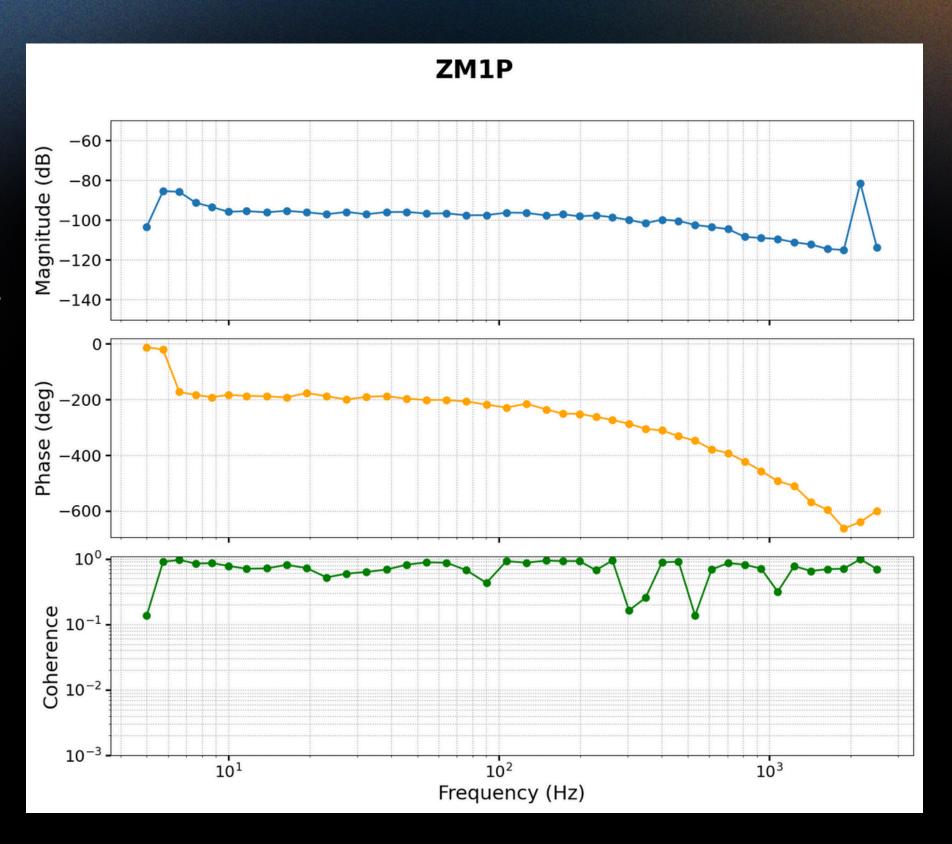
- Take the readout signal (contains oscillation at dither frequency).
- Multiply by reference sine at same frequency and low-pass filter.
- Output is an error signal
- ZM mirrors → green transmission signal.
- FC mirrors → cavity length control signal

# PART 1

TRANSFER FUNCTIONS OF ZM'S

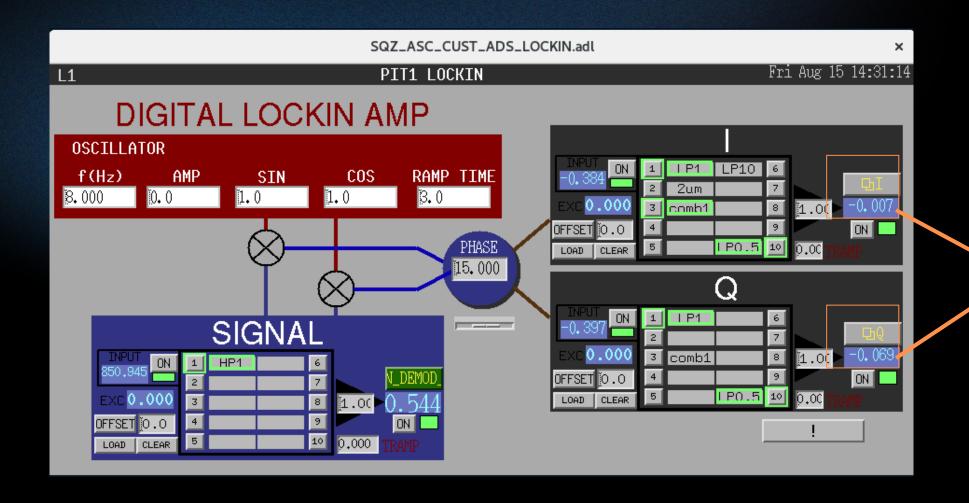
# ZM1 PITCH TF

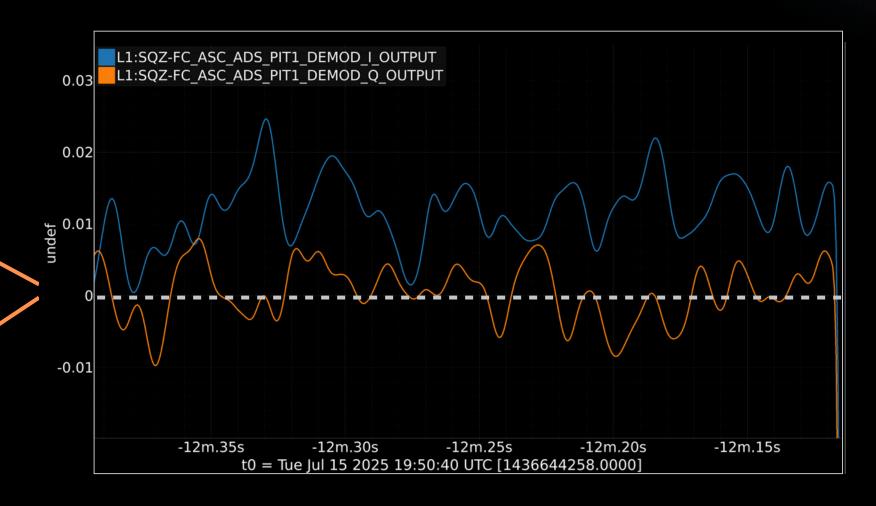
- Dither frequency selection requires actuator TFs
- Measured ZM1 & ZM3 bottom-stage (M2) transfer functions
- Applied swept sine: 5–2500 Hz
- Signal: excitation → 'L1:SUS-{ZM1,ZM3}\_M2\_DITHER\_{P,Y}\_OUT'
- Readout: transmitted green → 'L1:SQZ-FC\_TRANS\_A\_SUM\_OUT'
- Cavity DoFs deliberately misaligned to enhance sensitivity



# PART 2 ZM DITHER / DEMODULATION

# DITHER PHASE





# Excitation (dither):

o Small sinusoidal modulation applied to ZM1/ZM3 DoFs..

# Error signal (sensing):

- Demodulated TRANS\_A\_SUM photodiode signal at each dither frequency.
- Output is proportional to misalignment in pitch/yaw.

# Servo filter (controller):

- Error signal is processed (gain, phase compensation, filtering).
- o Converts raw error into a stable control signal.

# Control signal (output):

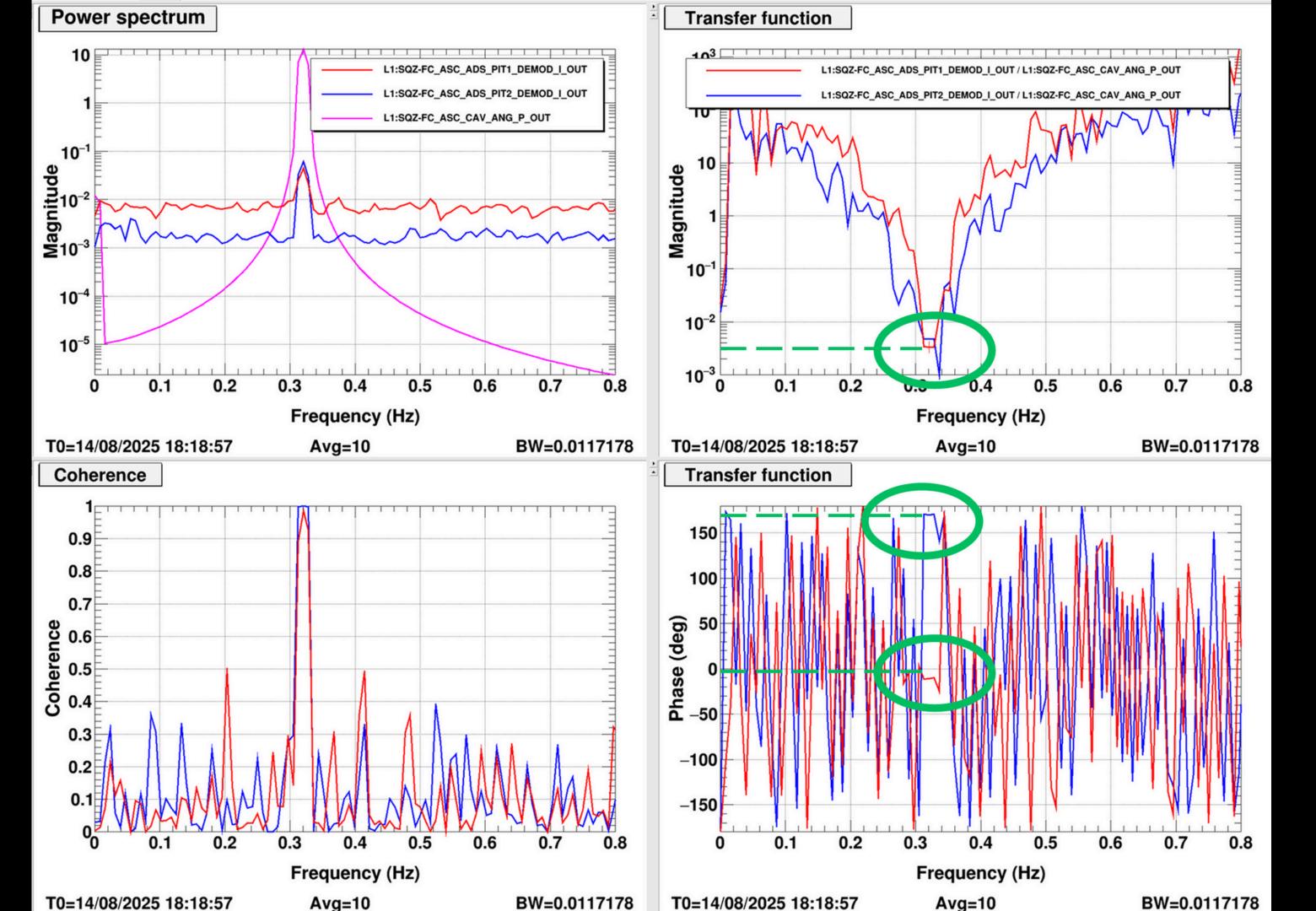
- Sent to angular actuation channels:
- INJ\_POS\_P / INJ\_POS\_Y → ZM1 pitch & yaw
- INJ\_ANG\_P / INJ\_ANG\_Y → ZM3 pitch & yaw

# **Actuators (plant):**

- Electromagnetic coil actuators at mirror suspensions
- Adjust mirror angles → correct cavity alignment

DoF	Frequ ency (Hz)	Gain	Phase (°)
ZM1 Pitch	101.1	2000	-40
ZM1 Yaw	126.1	2000	+140
ZM3 Pitch	151.1	200	+120
ZM3 Yaw	176.1	200	+105

# PART 3 ZM INPUT MATRIX DETECTION



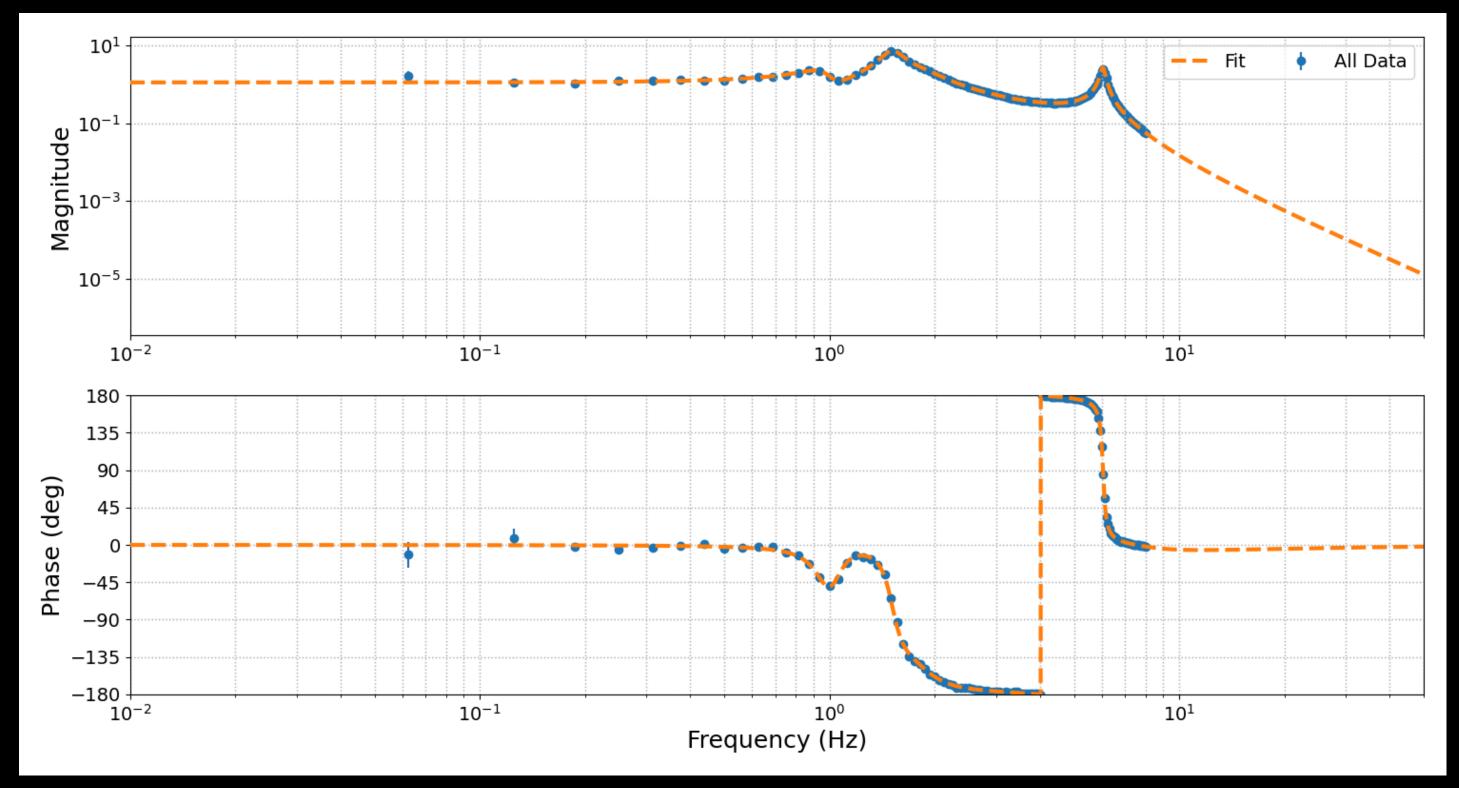
$$egin{bmatrix} {
m ZM1_{Pitch}} \ {
m ZM3_{Pitch}} \end{bmatrix} = egin{bmatrix} -0.004 & 0.003 \ 0.003 & -0.004 \end{bmatrix} egin{bmatrix} X_{
m FC1} \ X_{
m FC2} \end{bmatrix} \qquad egin{bmatrix} -571.4 & -428.6 \ -428.6 & -571.4 \end{bmatrix}$$

$$\begin{bmatrix} \mathrm{ZM1_{Yaw}} \\ \mathrm{ZM3_{Yaw}} \end{bmatrix} = \begin{bmatrix} 0.005 & -0.004 \\ 0.003 & -0.004 \end{bmatrix} \begin{bmatrix} X_{\mathrm{FC1}} \\ X_{\mathrm{FC2}} \end{bmatrix} \qquad \begin{bmatrix} 500.0 & -500.0 \\ 375.0 & -625.0 \end{bmatrix}$$

# ZM'S - PART 4

PLANT FILTERS FOR ZM'S

## ZM1 PITCH Fitting Plot



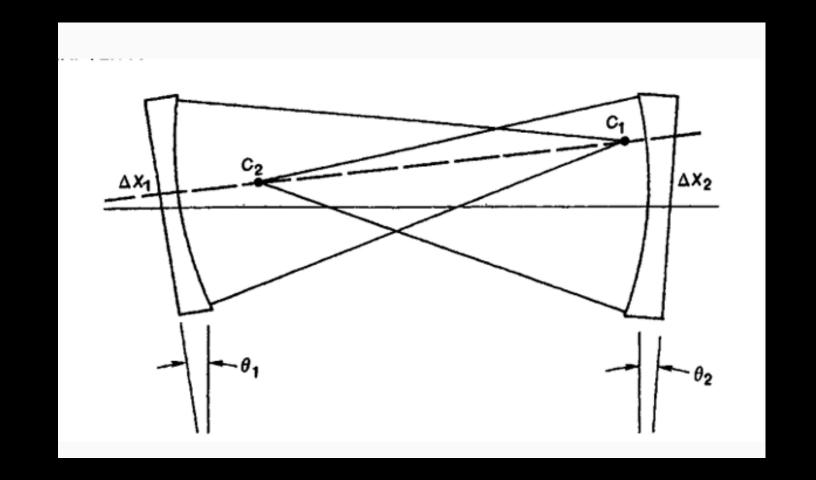
https://git.ligo.org/vladimir.bossilkov/chebychef

PART 5
FC LOOPS

# BEAM SPOT POSITION

$$egin{bmatrix} x_1 \ x_2 \end{bmatrix} = rac{L}{1-g_1g_2} egin{bmatrix} g_2 & 1 \ 1 & g_1 \end{bmatrix} egin{bmatrix} heta_1 \ heta_2 \end{bmatrix}$$

$$g_i=1-rac{L}{R_i}, \quad i=1,2$$

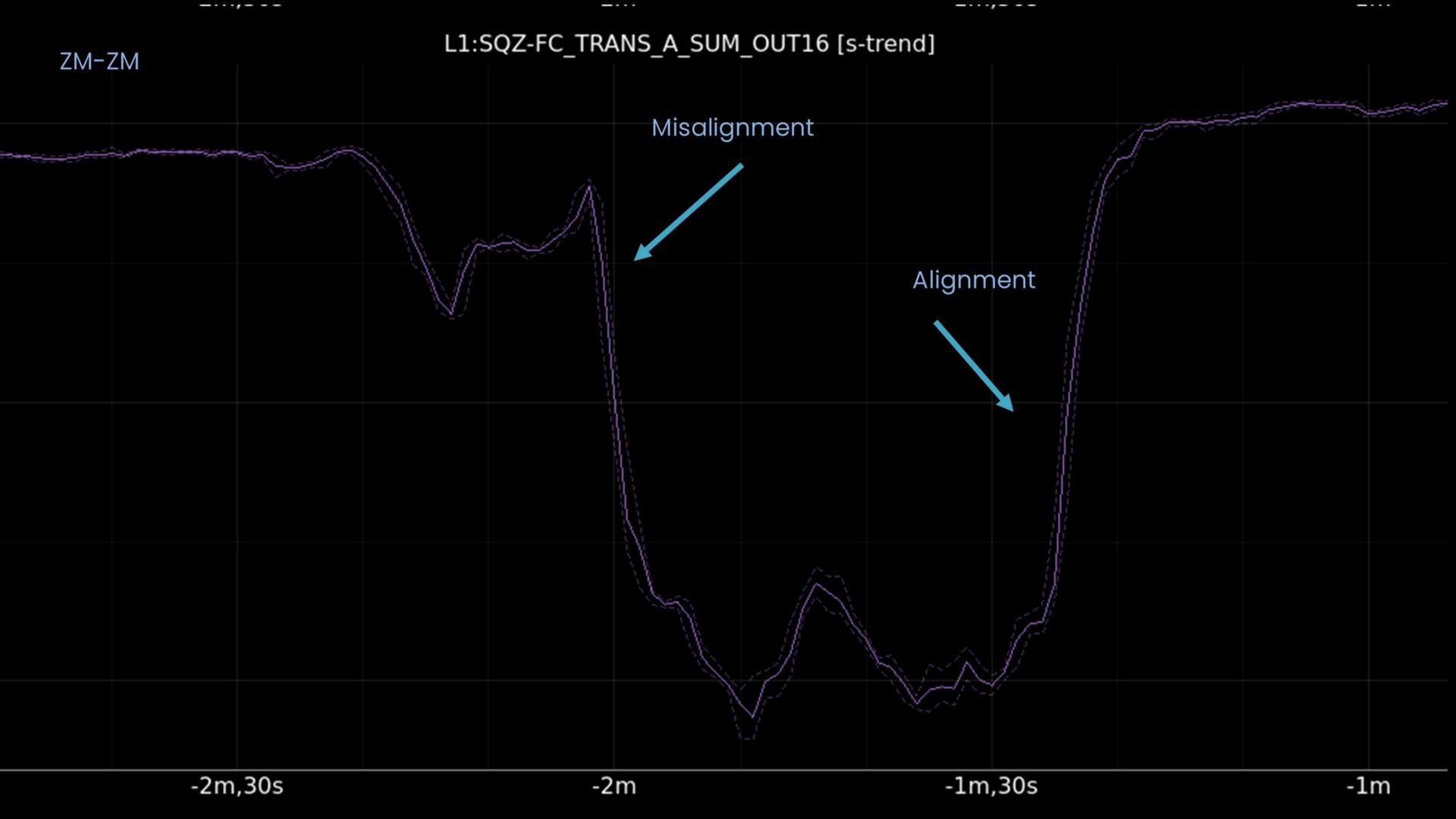


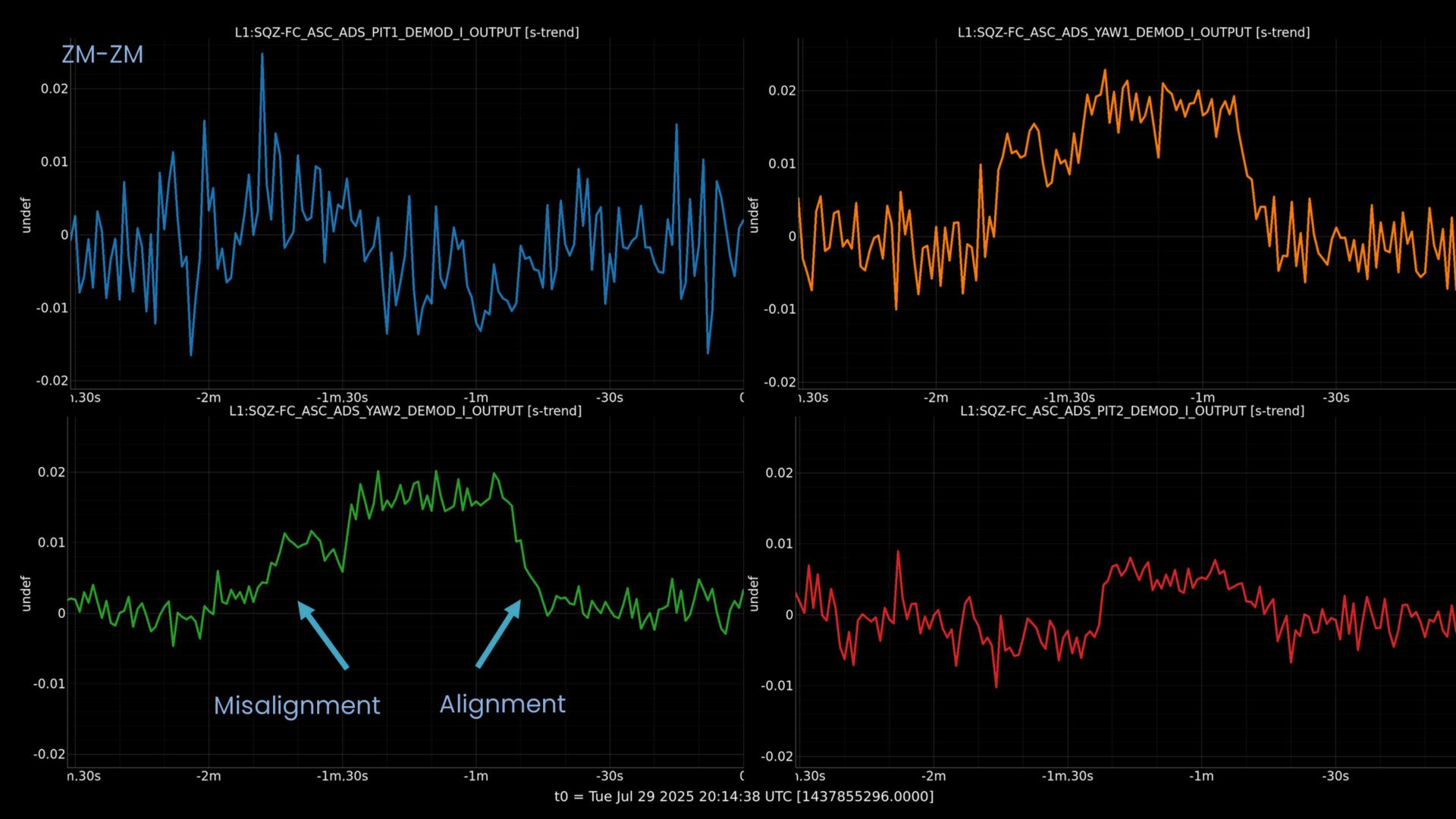
Substitute L, gl and g2 
$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \frac{L}{1-g_1g_2} \begin{bmatrix} g_2 & 1 \\ 1 & g_1 \end{bmatrix} \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix}$$
 Invert the Matrix 
$$\begin{bmatrix} X_{\mathrm{FC1}} \\ X_{\mathrm{FC2}} \end{bmatrix} = \begin{bmatrix} 231 & 531 \\ 531 & 531 \end{bmatrix} \begin{bmatrix} \theta_{\mathrm{FC1}} \\ \theta_{\mathrm{FC2}} \end{bmatrix}$$
 Pitch 
$$\begin{bmatrix} \theta_{\mathrm{FC1}} \\ \theta_{\mathrm{FC2}} \end{bmatrix} = \begin{bmatrix} -3 & 3 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} X_{\mathrm{FC1}} \\ X_{\mathrm{FC2}} \end{bmatrix}$$
 Pitch 
$$\begin{bmatrix} \theta_{\mathrm{FC1}} \\ \theta_{\mathrm{FC2}} \end{bmatrix} = \begin{bmatrix} -3 & 3 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} X_{\mathrm{FC1}} \\ X_{\mathrm{FC2}} \end{bmatrix}$$
 Yaw

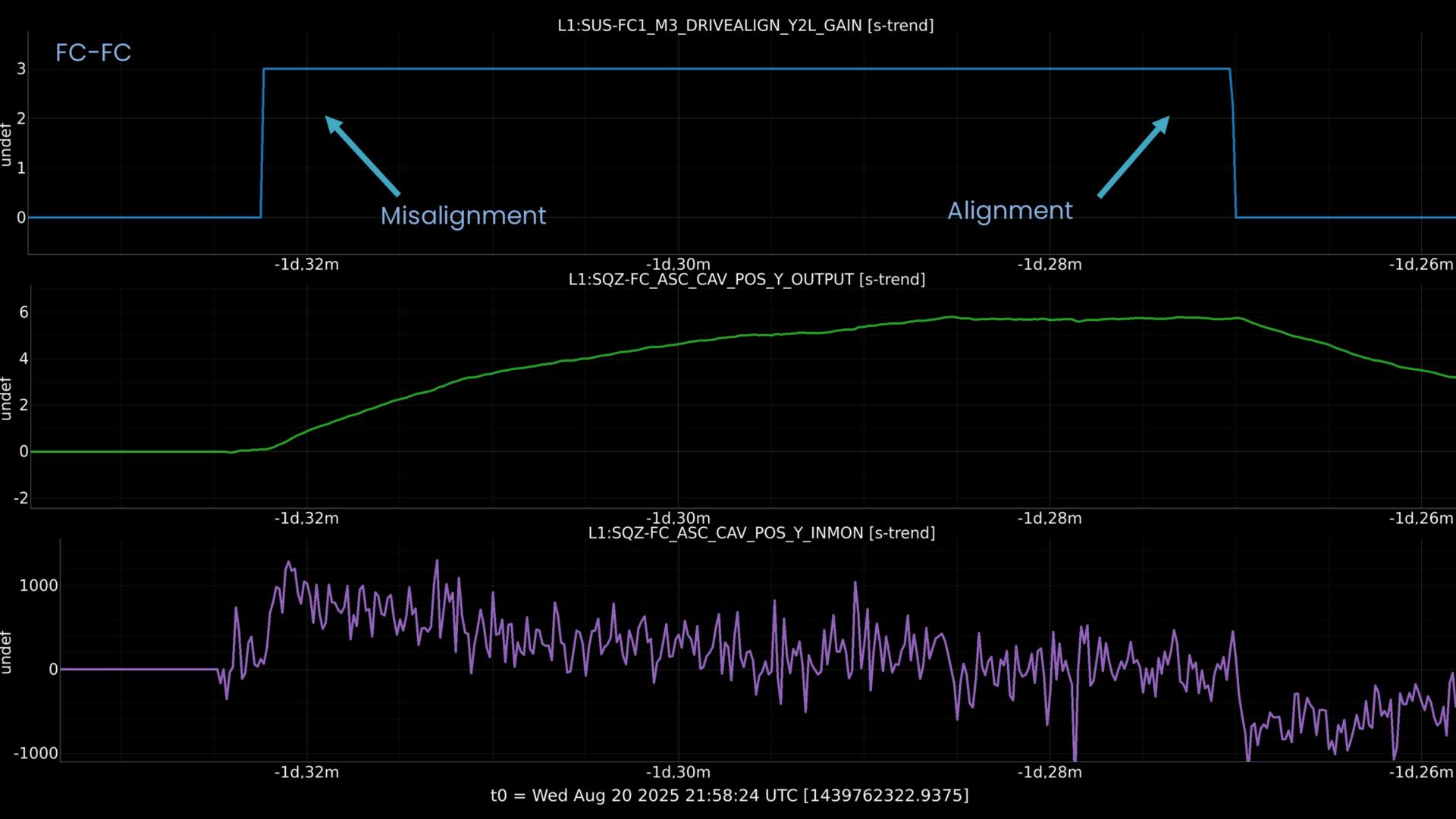
L = 300,

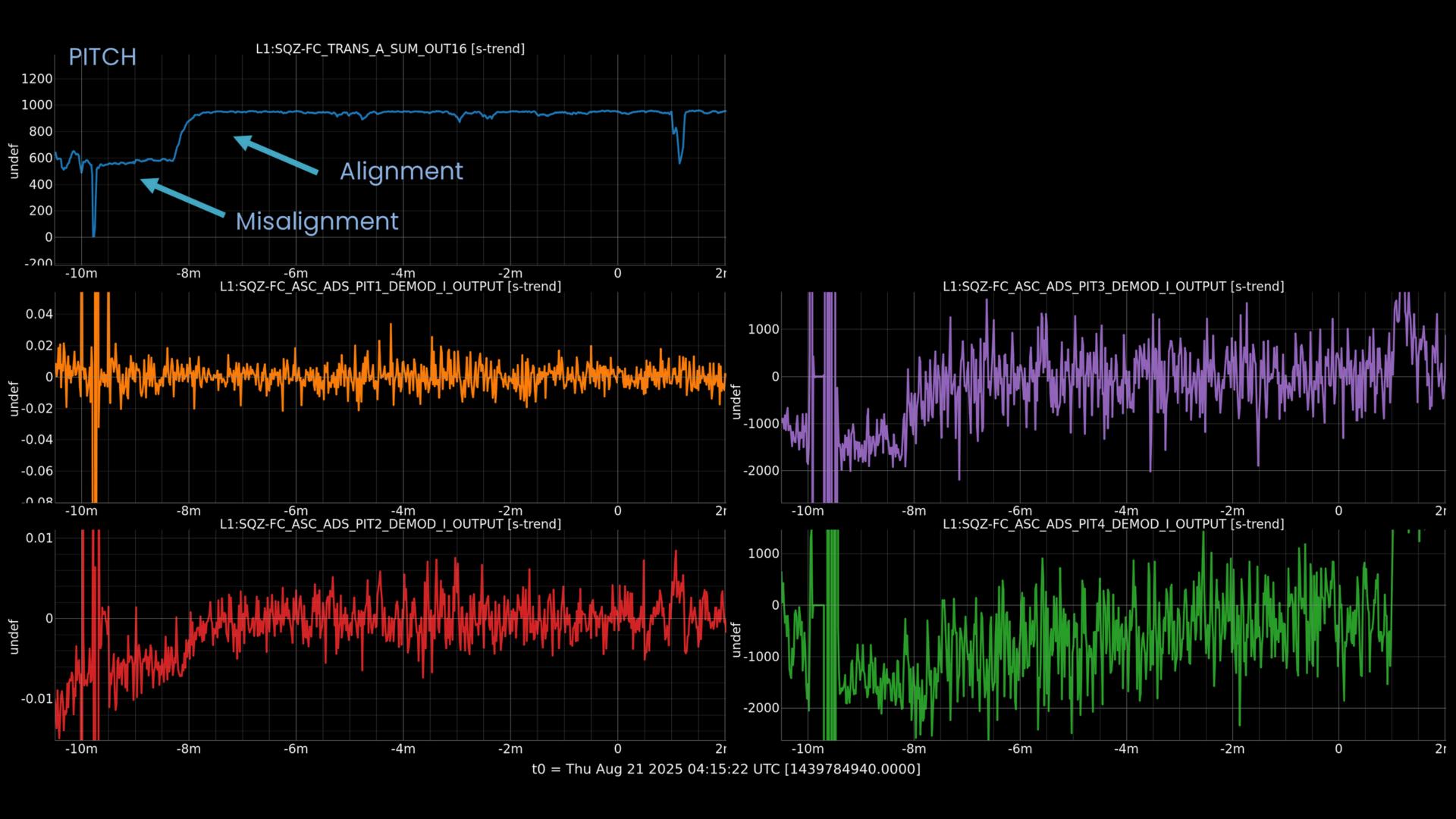
$$egin{bmatrix} heta_{ ext{FC2}} \ heta_{ ext{FC2}} \end{bmatrix} = egin{bmatrix} heta & heta \ -3 & 1 \end{bmatrix} egin{bmatrix} X_{ ext{FC2}} \ X_{ ext{FC2}} \end{bmatrix}$$

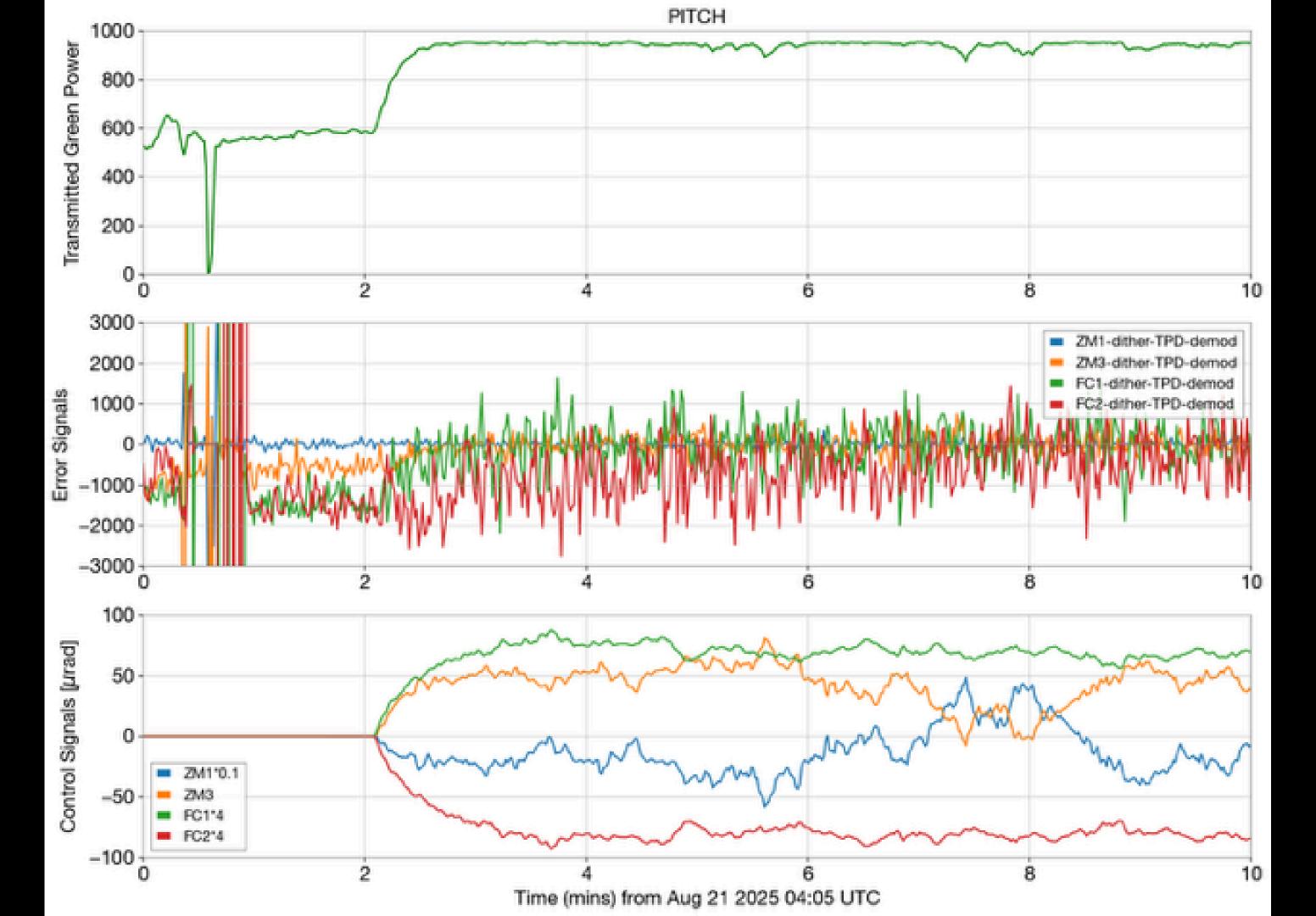
# RESULTS

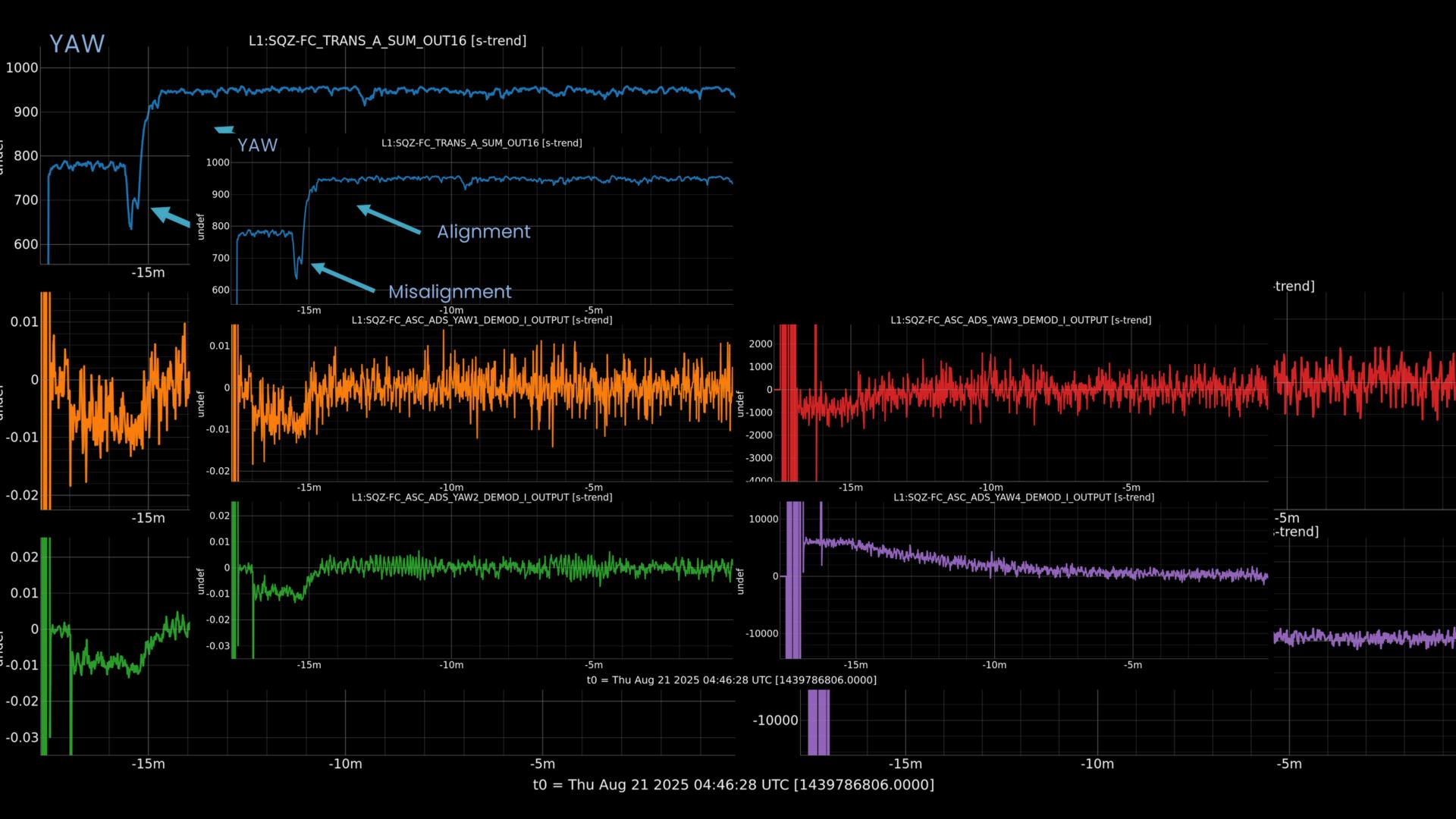


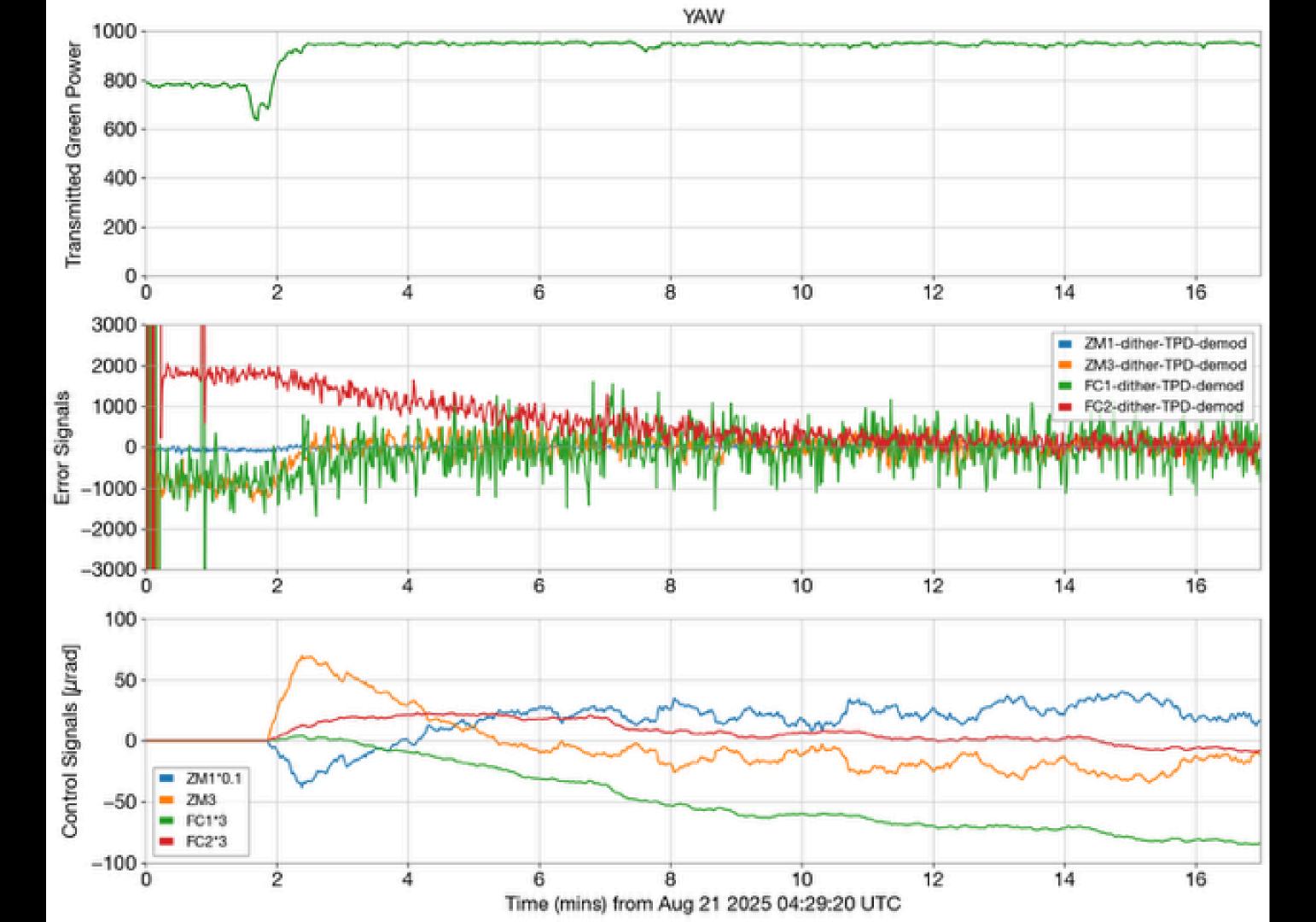












# CONCLUSION

FC GREEEN ANGULAR CONTROL LOOP COMISSIONED

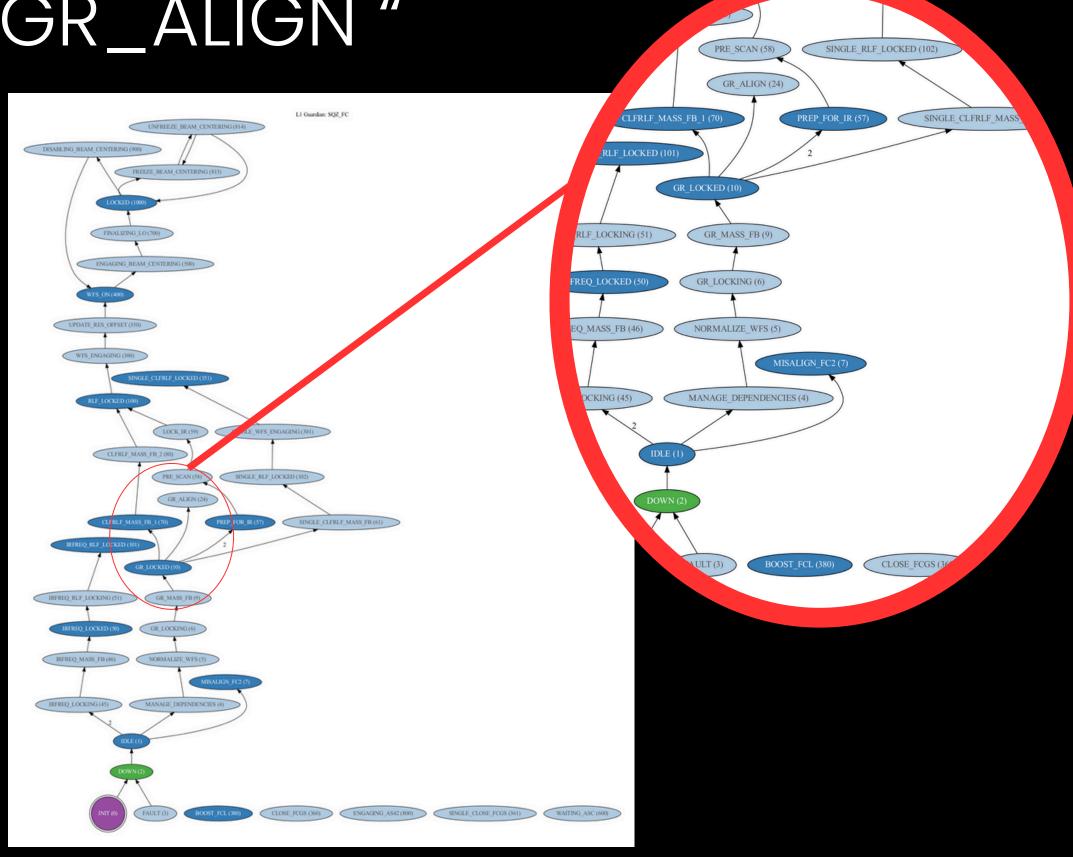
ZM TO ZM

ZM TO FC

FC TO FC

ZM Loops compensating the ZM errors ZM Loops compensating the FC errors FC Loops compensating the FC errors

# GUARD STATE "GR\_ALIGN "





## **IMPLEMENTATION**

Implementing the guardian state into filter cavity locking sequence





FINE-TUNING

Input, output matrix values



GRAD SCHOOL APPLICATION

Personal future outlook :)

# ACKNOWLEDGES







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# QUESTIONS

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