Building a Detector

Build-a-Detector Workshop
University of Glasgow – LIGO India Partnership
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Thanks to...

- The many colleagues from whom I have borrowed slides
- The LIGO Lab MIT, Caltech, Hanford and Livingston Observatories
- The LIGO Scientific Collaboration; Virgo and KAGRA; Cosmic Explorer
- The US National Science Foundation for extraordinary support and perseverance for LIGO



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References

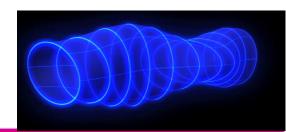
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Scope

- Already heard of the 'fundamental' noise sources
- This talk:
 - » Detector design overview
 - » A couple of additional limits to sensitivity
 - » System engineering to move from theory to practice
- Coming soon:
 - » Jamie Rollins: pygwinc, a software tool to show graphically the sensitivity of a GW detector design
- Kevin Kuns:
 - » examples of how to actually implement design choices in pygwinc
 - » how you can use them to actually make the design choices and what some of the constraints on those choices are

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What is our measurement technique?



- Enhanced Michelson interferometers
- GWs modulate the distance between the end test mass optic and the beam splitter
- The interferometer acts as a transducer, turning GWs into photocurrent proportional to the strain amplitude

Time Laser Output photodiode $P_{\text{input}} \\$ **Jutput** power

 ΔL

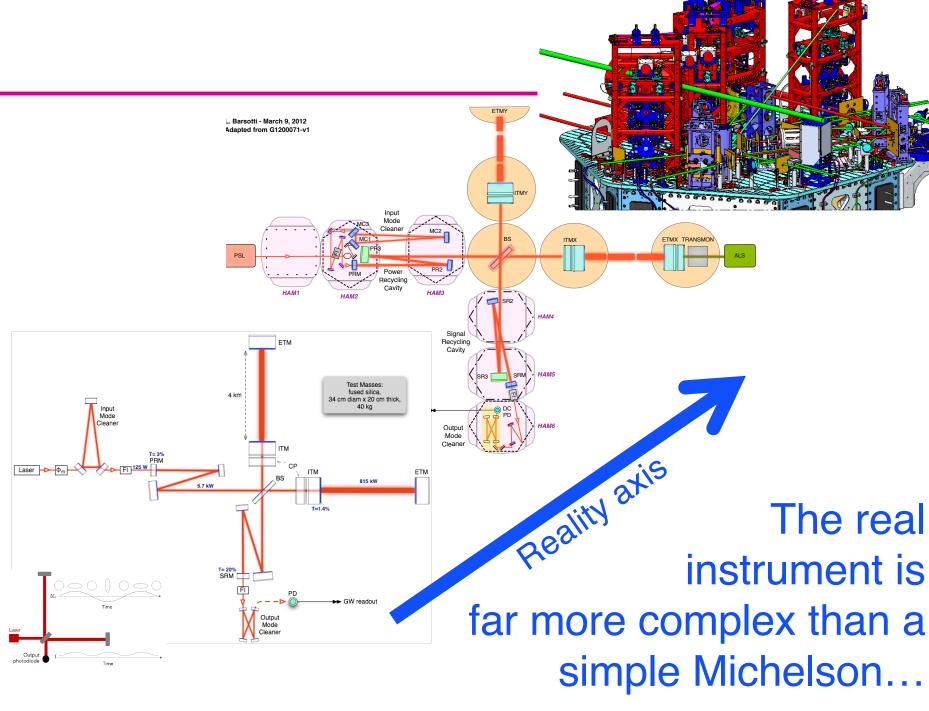
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For a given strain $h = \Delta L/L$,

$$\Delta P_{\rm GW} \sim h L P_{\rm laser} / \lambda_{\rm laser}$$

 ΔL_{GW}

 $\lambda/2$



Useful paradigm in considering limits to detector sensitivity

- Ability to measure the position of our test mass
 - » Quantum noise
 - » Scattered light
 - » Laser light defects intensity, position, mode shape, frequency noise
 - » Laser path noise fluctuations, apparent or real
 - » Electronics noise
- True noise motions of the reference surface on our 'free test mass' which can mask GWs
 - » Thermal noise
 - » Radiation pressure
 - » Environmental mechanical forces seismic, anthropogenic, weather
 - » Stray electric, magnetic fields
 - » Accidental noise forces from our control systems and sensors

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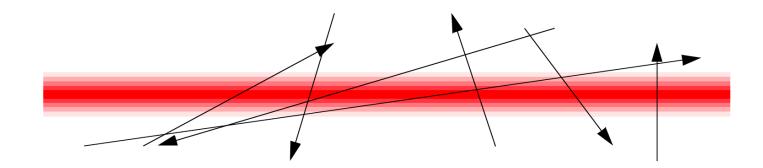
In the school so far...

- An in-depth review of the 'fundamental' noise sources:
 - » Quantum noise, and interferometer topologies; squeezing
 - » Thermal noise, and low-mechanical-loss construction methods
 - » Coating Brownian noise, choice of materials, coating processes
 - » Newtonian noise environment around test masses; sensing
 - » Seismic noise active and passive attenuation
- I'll now add to that a couple of others:
 - » Path-length fluctuations due to residual gas in arms
 - » Scattered light
 - » Taxpayer noise

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Vacuum System

 The 3 or 4km (or 15 or 40km...) path of the laser from beam splitter to end mirror must be in an excellent vacuum

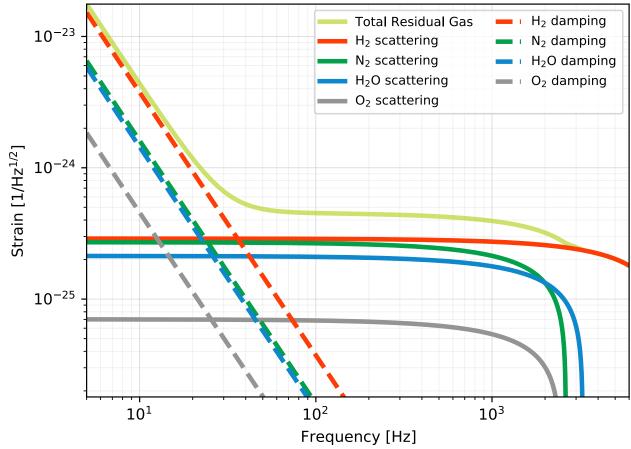


• Polarizability α of the remaining gas molecules induces path-length fluctuations; Poisson Statistics, and an effect proportional to square root of density $\rho^{1/2}$ along the path 1

$$h(f) \approx 4\pi\alpha \left(\frac{2\rho}{v_0 w_0 L}\right)^{\frac{2}{2}}$$

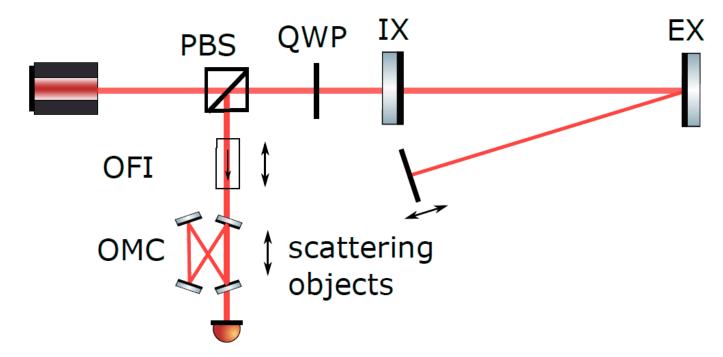
Residual gas: path-length fluctuations, pendulum damping

- Pygwinc model for residual gas, for
 - » The path length fluctuations for gas along the n*km path
 - » Pendulum suspension thermal noise due to transfer of momentum to/from gas molecules from/to test mass



Scattered light

- Light scattered out of the main beam by a defect on e.g., a mirror
- ...to a moving object like baffles or chamber walls
- ...and back into the main beam (via the same or a different defect)

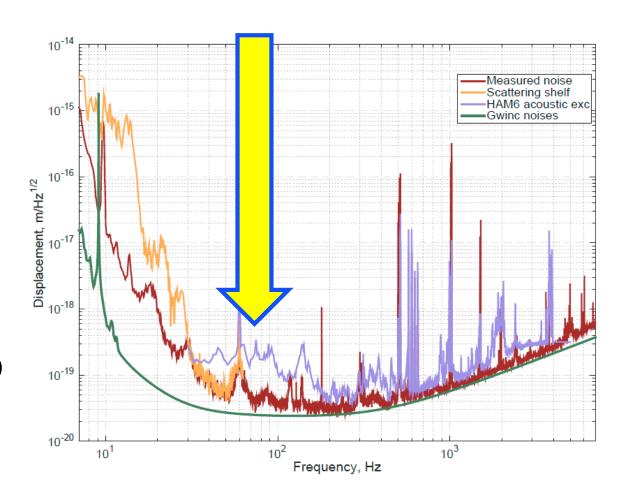


- Scattered light noise is seen in the frequency range 10-200 Hz.
- Significant noise source, difficult to track down and mitigate
 - » ...reduction in motion (isolation) of chambers, or better baffling

Finding coupling to scattered light

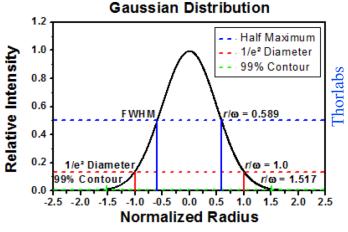
How do we determine that at least some of the excess noise is related to scattering?

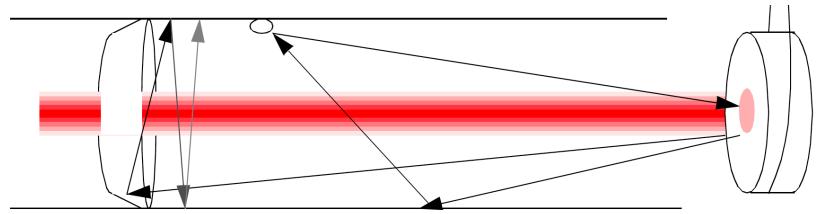
- Scattering from chamber walls is measured via acoustic excitation, then measuring response in GW strain output.
- If clean room fans (in ceiling above chambers) are turned on, motion of chamber walls increases by factor of 30-100 above 40Hz.
- Plot shown shows acoustic coupling to detector output via scattered light
- → add baffles, acousticisolation



Beam Tube Scattered Light

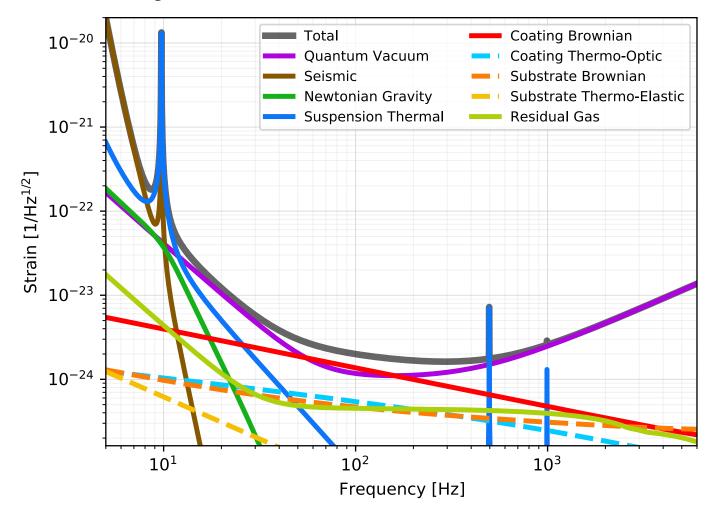
- Laser wavelength determines the minimum beam size after 4km propagation for 1064nm Nd:YAG, this leads to 10-12cm diameter for $1/e^2$ but in fact mirrors must be much further in the tails of Gaussian, ~10⁻⁶ loss per bounce
- In addition, the mirrors are not perfect
 - "'dust' and point defects
 - » Large-scale 'waviness' (~10 nm over 1 cm)
- very low scatter mirrors
- → 1.2m diameter beam tube
- → baffles to catch scattered light





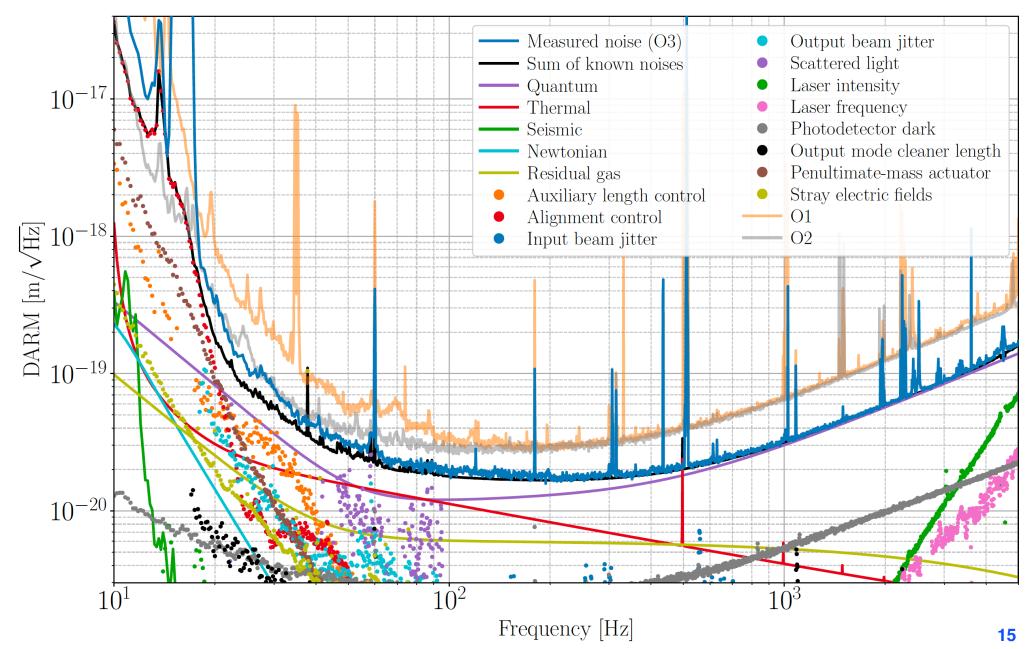
A+ noise model

- The pygwinc model for a set of analytically calculable noise sources
 - » Kevin and Jamie will show you how to make these models
 - » Scattered light not here...can't calculate ab initio





Scattered light as measured, along with a few other additional terms....





One more noise term...

Taxpayer noise

- I promised a page on this noise source!
 - » Finding equilibrium with funding is a crucial 'system engineering' trade
- The length of the detector is the most significant scale factor
 - » Length of vacuum pipe, support and protection structures
 - » Diameter grows as sqrt(length) due to diffraction of the beam
- Vacuum system
 - » Order of 45% of the cost for 40-km-long Cosmic Explorer (CE)
- Earthmoving and civil construction more generally
 - » If on the surface, need to deal with spherical earth and linear laser
 - Finding a 'bowl' == truly flat site can help significantly
 - » If underground, tunneling
 - » Order of 30% of the cost for CE
- Detector
 - » Order of (only) 20% of the cost for CE
- Legally spending billions of Dollars/Euros in an efficient way -- management
 - » Order of 5% of the cost of CE; order of one hundred million dollars.

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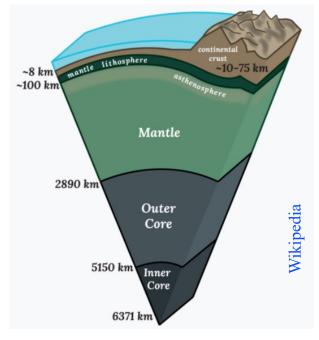
Observatory Infrastructure; LIGO as an example

Civil Construction

- Light travels in straight lines (when far from black holes)
 - » The Earth is not flat (whatever some political partisans may say)
 - » Sagitta for 4km is some 0.3m some earthmoving needed
 - » For 40km more like 30m need to find a truly flat (not spherical) site
- Also need stable foundation to support 1.2m beam tube (aligned to ~1mm)
- And some weather protection for the beam tube
 - » Turns out that there are stainless-steel eating microbes
 - » Also wasps and black-widow spiders
 - And rodents
 - » ...and, worst of all, humans



<u>fantasticpestcontrol.co.uk</u>, terro.com



Civil Construction: Beam Tube cover, foundation, earthmoving



...and worst of all, humans



Length

- Length is great for sensitivity! Technically much easier than lowering noises
 - » Signals get larger, noises tend not until one is comparable to $\lambda/2$
 - » Optimum for coalescence of BNS around 20km
- Increases the GW signal size, but reduces thermal noise, quantum limits,
 Newtonian background, seismic noise, electronics/control noise...

 Length scaling dominates the cost for a detector

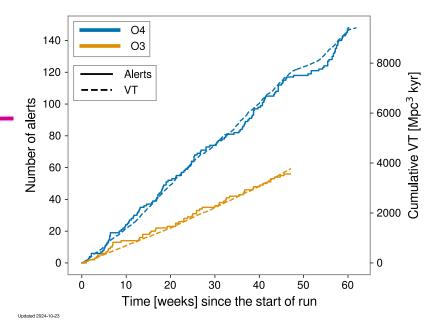
Strain sensitivity as function of length *L*

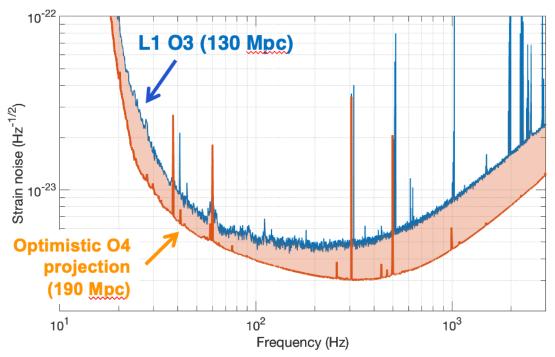
Noise	Scaling
Coating Brownian	$1/L^{3/2}$
Substrate Thermo-Refractive	$1/L^2$
Suspension Thermal	1/L, 1
Seismic	1/L, 1
Newtonian	1/L
Residual Gas Scattering	$1/L^{3/4}$
Residual Gas Damping	1/L
*Quantum Shot Noise	$1/L^{1/2}$
*Quantum Radiation pressure	$1/L^{3/2}$

Sensitivity improvements are very well rewarded

- LIGO 'A+' Incremental changes to the Advanced LIGO design; 2 x improvement
 - » Similar changes planned for Virgo
- Rough doubling of reach
 - $2^3 = 8$ greater volume
 - » 8x higher rate
 - » 17-300 BBH/month
 - » 1-13 BNS/month
 - » 2-11 BNS x SGRB coincidences/year
- Population studies
- Hubble Constant
- ...higher SNR for e.g., tests of GR

O4 used some A+ technology





Surface or Underground?

- Burying the detector has clear advantages (see talk on Newtonian background) to improve the low-frequency sensitivity
- The Science Case should drive the design decision here
- Asking for both an optimal length and a buried detector is probably unrealistic from a cost standpoint
- Next-generation detectors are a wonderful illustration of this 'trade'
 - » Cosmic Explorer: 40km, surface detector, best reach
 - » Einstein Telescope: 10km, underground, best low-frequency
- Also considerations beyond simple sensitivity/cost questions:
 - » Working underground, safely, is hard! Can expect slower progress in activities leading up to observation (see: KAGRA)
 - On the surface, Blocking migratory paths, occupying land belonging to indigenous peoples present challenges

Risk

- Different projects can adopt different risk levels
- GEO-600 is a great example on where risks can be taken
- Also different cultures, funding agencies, collaborations have different levels of tolerable risk
- More ambitious designs require more R&D to be successful to be realized, and may
 - » Make more significant steps forward in measurement science
 - » Lead to a more sensitive detector
 - » BUT: Take more time to get working
 - » May not work as well as hoped
 - » May even simply fail.

Safety

- » A different kind of risk, but human safety is very important
- One person seriously injured or worse is not only a human tragedy it can also kill a project.

it can also kill a project

System Engineering

- To find solutions which meet the observational science goals, manage risk, and meet cost and schedule constraints
- Can require compromises both in the initial design, and dynamically as the project advances
- Constant modeling of the sensitivity is crucial, along with modeling of schedule and cost
- A mixture of engineering, instrument science, observational science, and project management is needed to succeed
- All decisions will be made with partial information, but waiting for better data has a significant cost and risk
- The next two talks will put the sensitivity modeling tools in your hands to allow that part of the challenge to be explored
- Just keep in mind that a full design process has a great deal of richness!



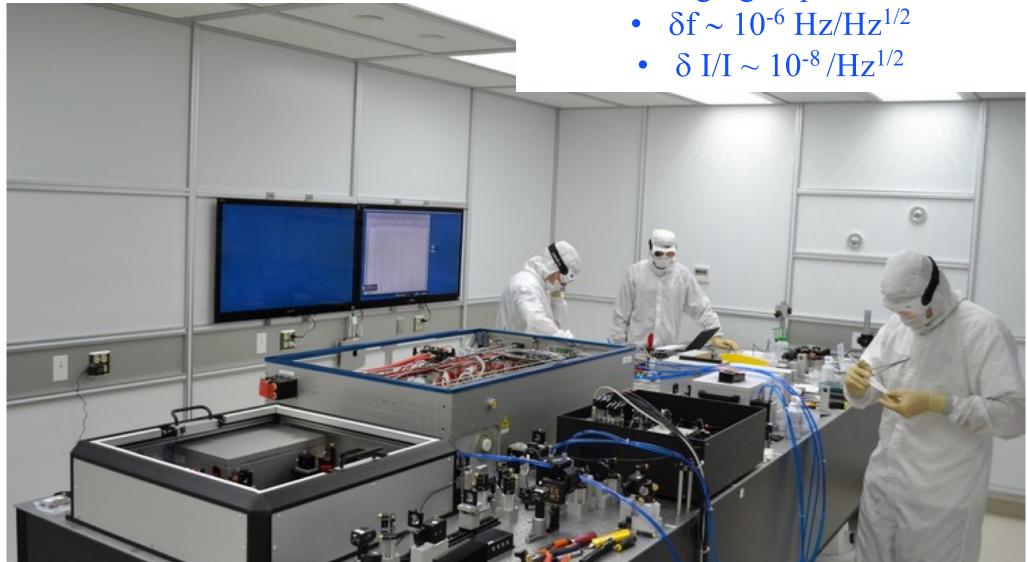
An Example: Let's look at the actual LIGO layout and hardware



Laser Clean Room; extraterrestrials for scale

200 W, single frequency, single mode, Nd:YAG laser

Challenging requirements:



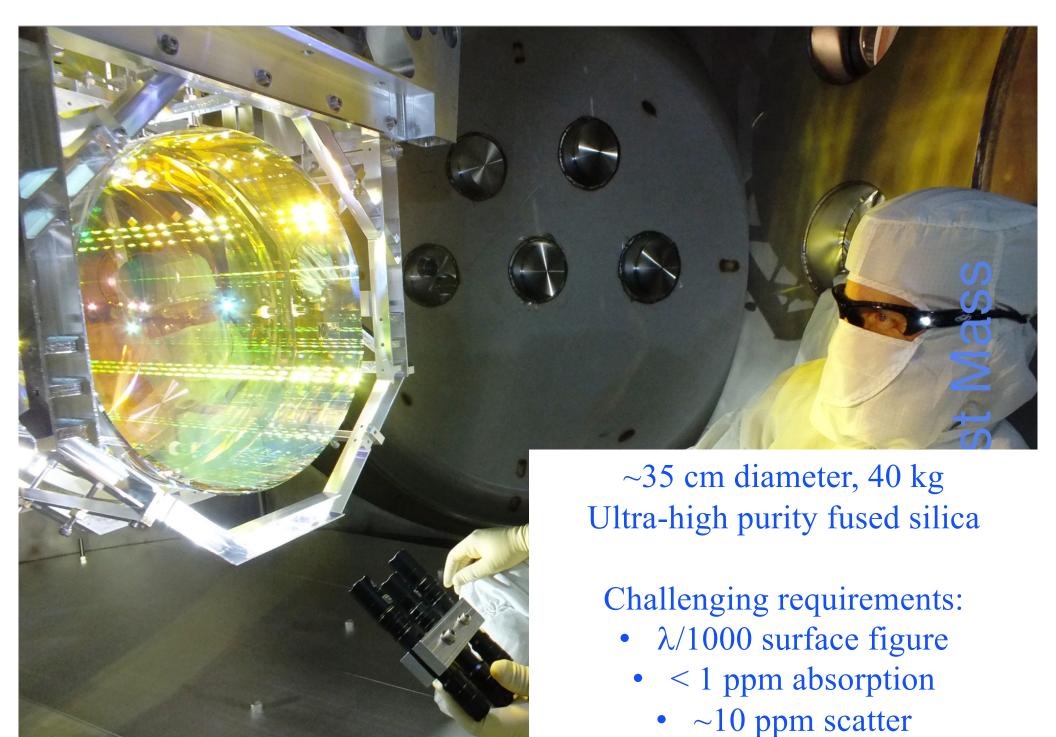
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Vacuum chambers to protect and isolate optics



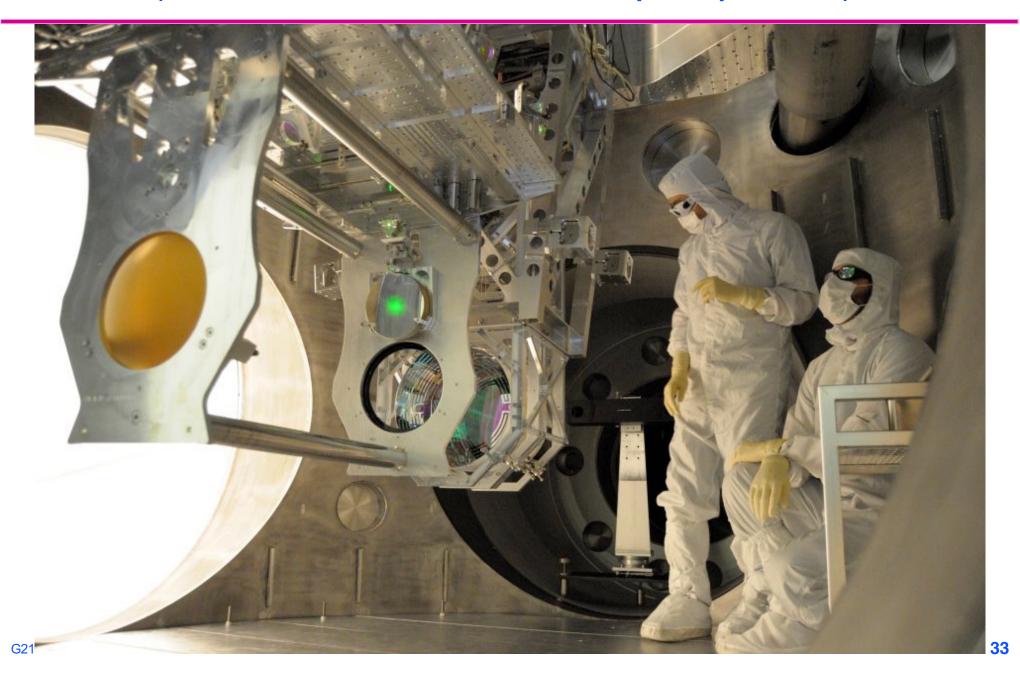
Inspecting mirror during fabrication

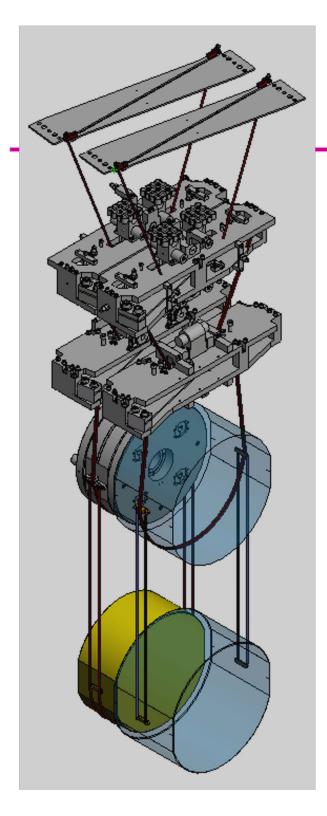




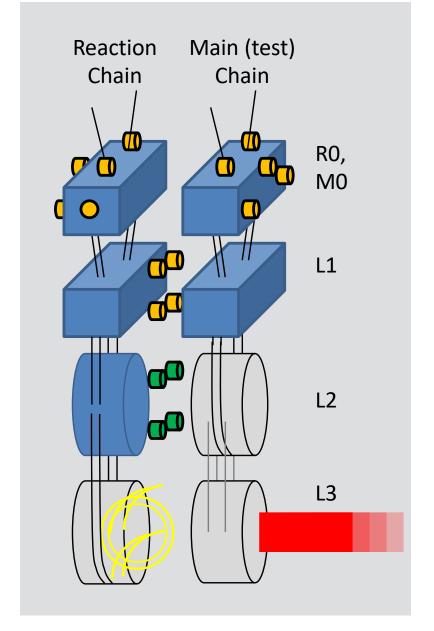
0.1 % coating uniformity

End-mirror assembly (humans removed before pumpdown)





Optic Suspensions

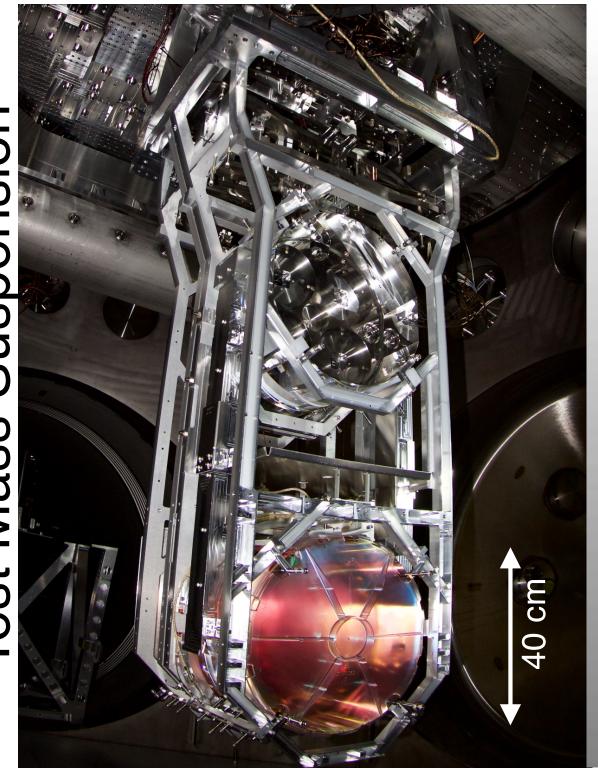


Electromagnetic sensors/actuators measure position relative to a reaction chain that is also passively isolated

Lower stage actuators used to control/maintain optic cavity length and alignment

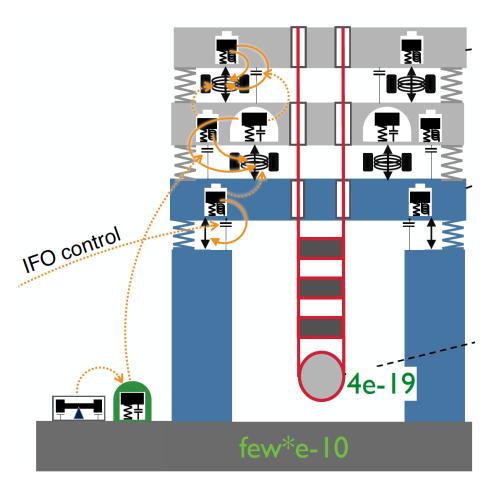
'Monolithic' – optic, penultimate mass, and suspension fibers welded together

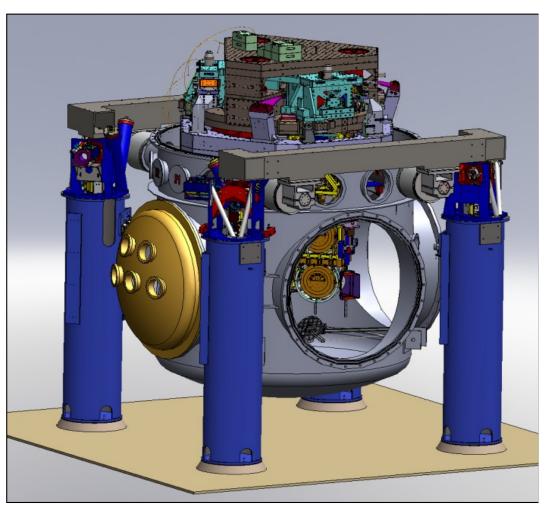
Test Mass Suspension

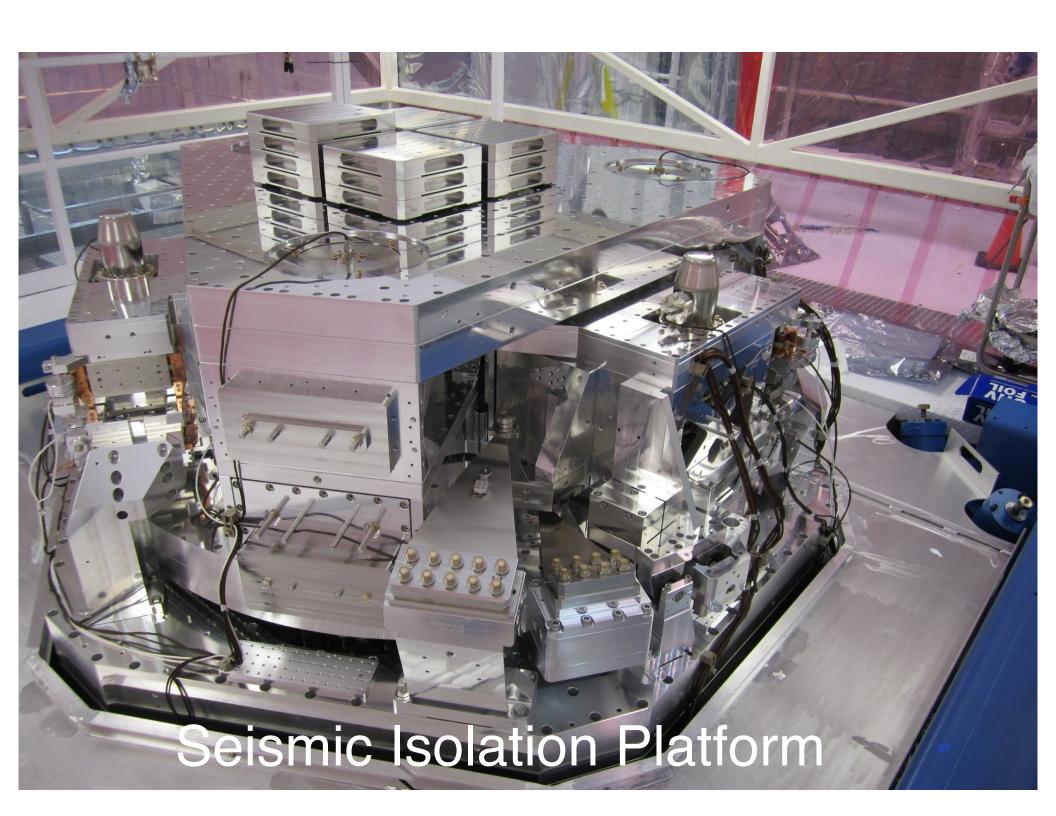




Active and passive seismic isolation









Another crucial element for success: Collaboration

- Table-top scientists precision measurement, laser, atomic started the field; tradition of small groups, small projects, and some competition
- Early general relativists, theorists, astrophysicists much the same
- Transformation when High Energy Physics types got involved
 - » Engineering, project organization, computing, analysis
- Funding agencies also saw a need for a shift
 - » There is a real skill in spending hundreds of millions of Euros!
- Goal pre-discovery was crystal-clear: Make a detection
- After the Collaborations formed and were stable, meta-collaborations: 'The LVK' – KAGRA, Virgo, and LIGO Scientific Collaborations all sharing data → IGWN
 - » The science that is possible is qualitatively greater
 - The sociology of a (mostly) non-competitive environment nurturing and supportive
- LISA and Pulsar Timing also in collaborations/consortia
- Now perhaps 3000 persons worldwide

Last Page

Hope to have given a view of the 'Meta-design' concepts and processes

Good luck, and: Have fun with your design experiment!