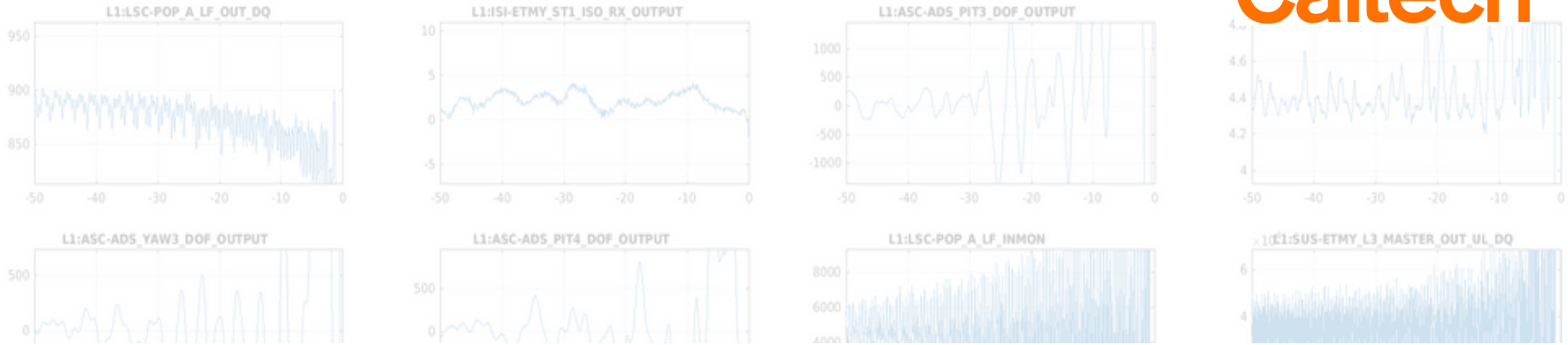
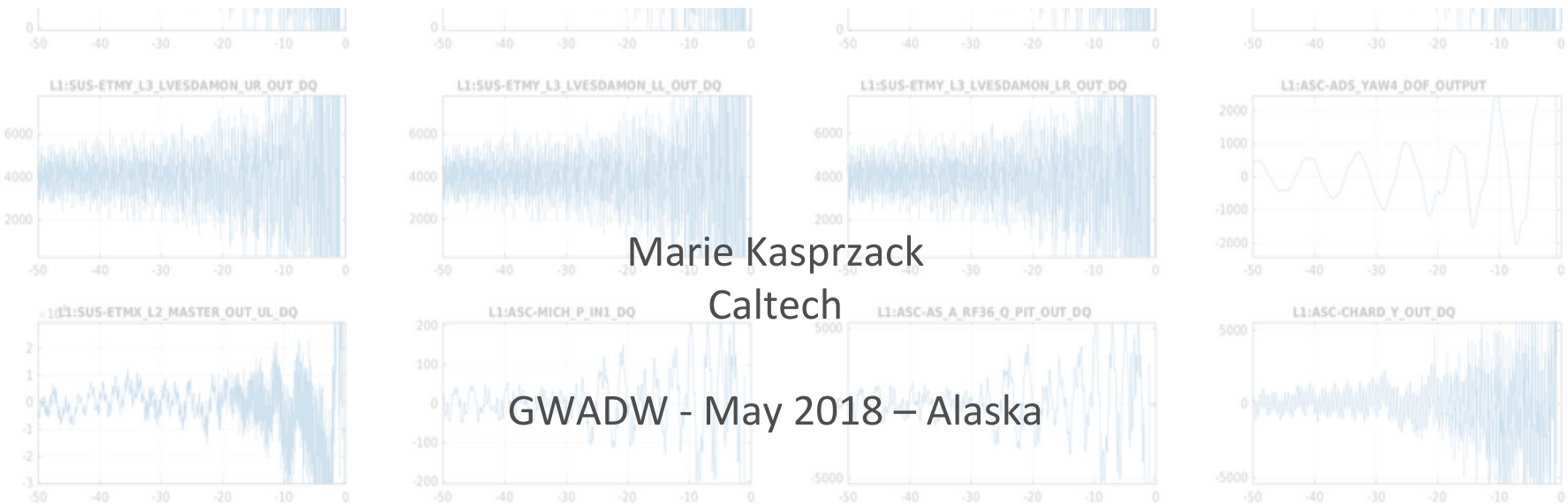


LOCKLOSS MONITOR RESULTS
LOW_NOISE to LOCKLOSS at GPS 1186528327

Caltech



Angular Control Issues in Advanced LIGO

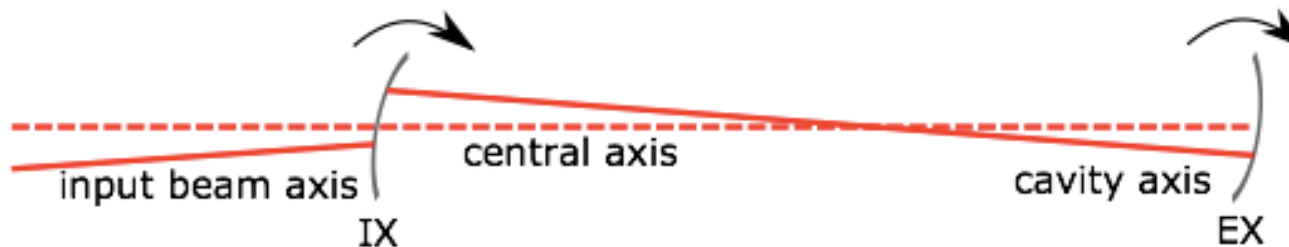
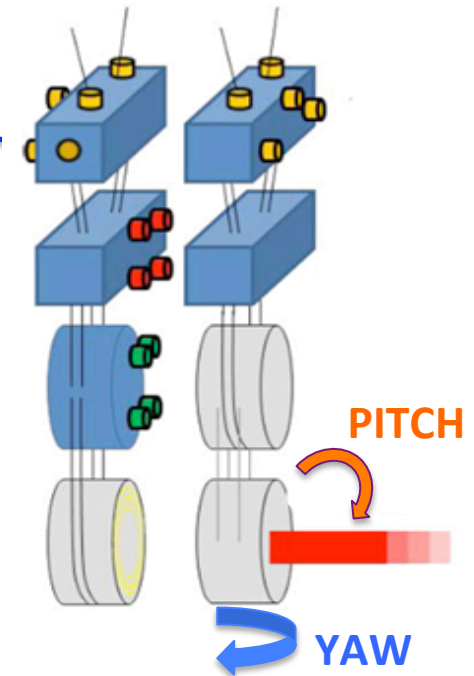


Marie Kasprzack
Caltech

GWADW - May 2018 – Alaska

Angular Sensing and Control

- The main optics of the aLIGO detectors are suspended
 - 2 stages of seismic isolation + 4 stages pendulum
 - **PITCH** \approx 3-5 **YAW** motion
- The cavities have to be **actively aligned**:
 - To maximize the power build-up in the cavities
 - To minimize the geometric losses



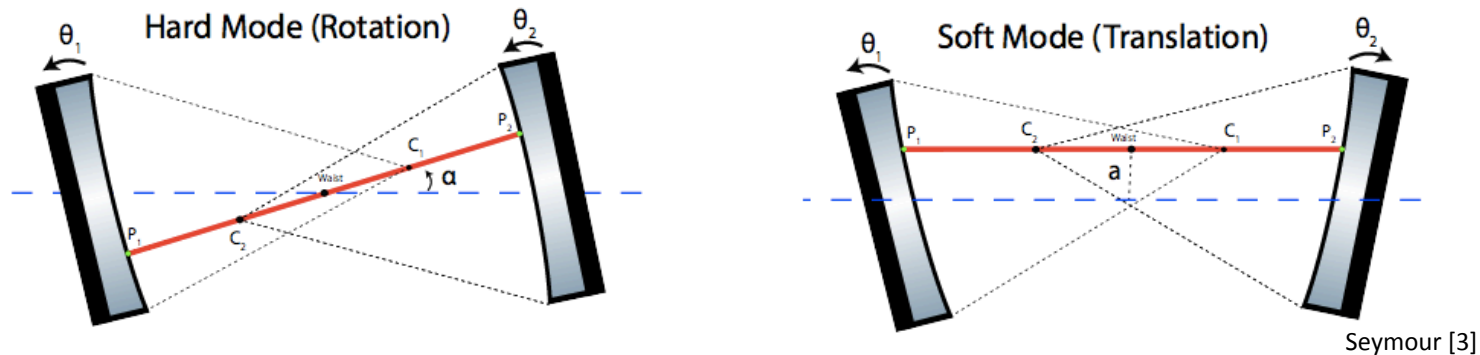
D. Martynov [1]

aLIGO arm geometry:

angular axis motion is x10 the angular motion of the test masses

Angular Sensing and Control

- Radiation pressure creates additional torque : $\tau = \hat{K}_{opt}(g_1, g_2, L, P) \begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix}$
- Each arm cavity can therefore be treated as a unit with two orthogonal modes:

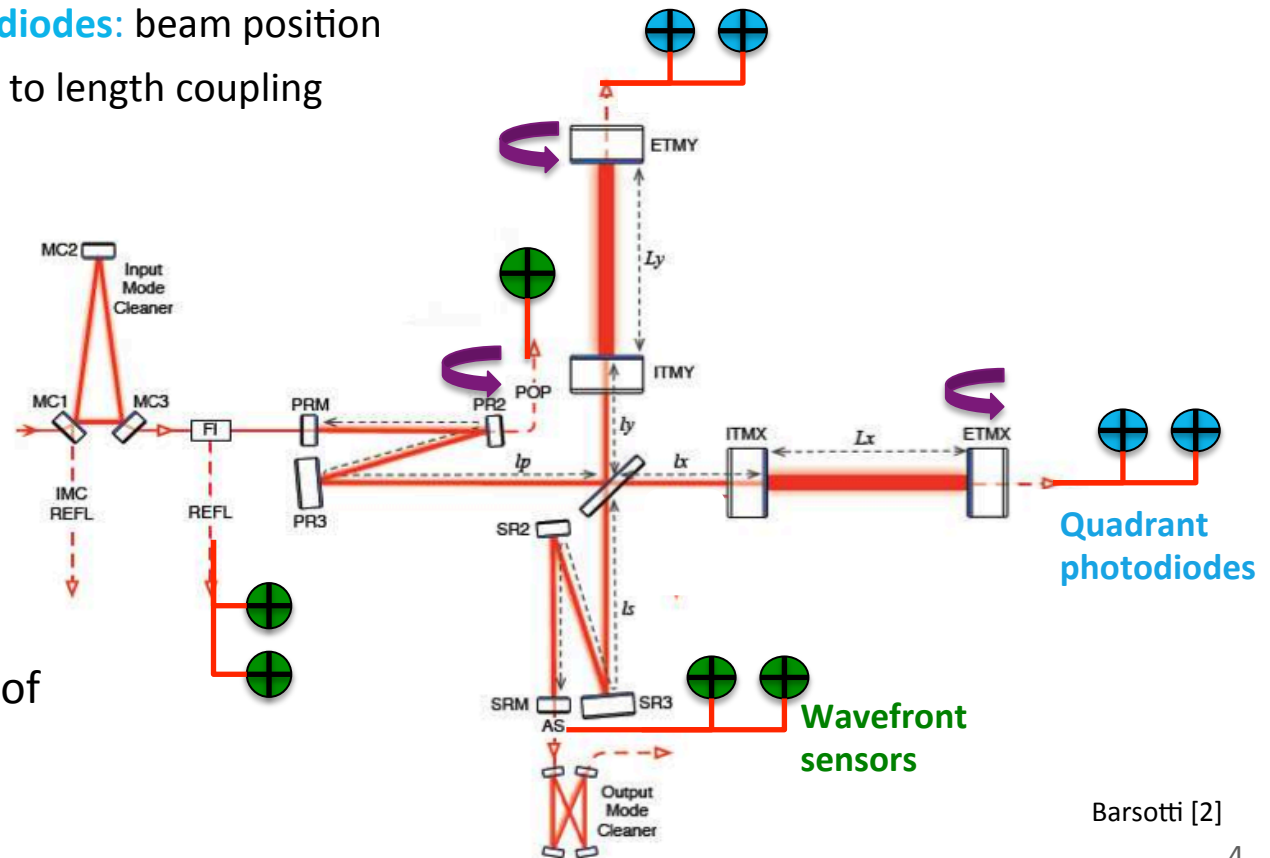


4 modes of angular motion: **CHARD, DHARD, CSOFT, DSOFT**

- During O2, the intra-cavity power was about 105-110 kW

Angular Sensing and Control

- Alignment signals, acquired with dedicated sensors, are filtered and fed-back to the mirror coil-magnet actuators to keep the mirrors aligned
- Three types of sensing:
 - **Wavefront sensors:** demodulated signals from RF sidebands (9, 36 and 45 MHz)
 - **Quadrant photodiodes:** beam position
 - **Dithering:** angle to length coupling
- 2x9 angular loops



Simplified overview of Advanced LIGO

Barsotti [2]

ASC performance

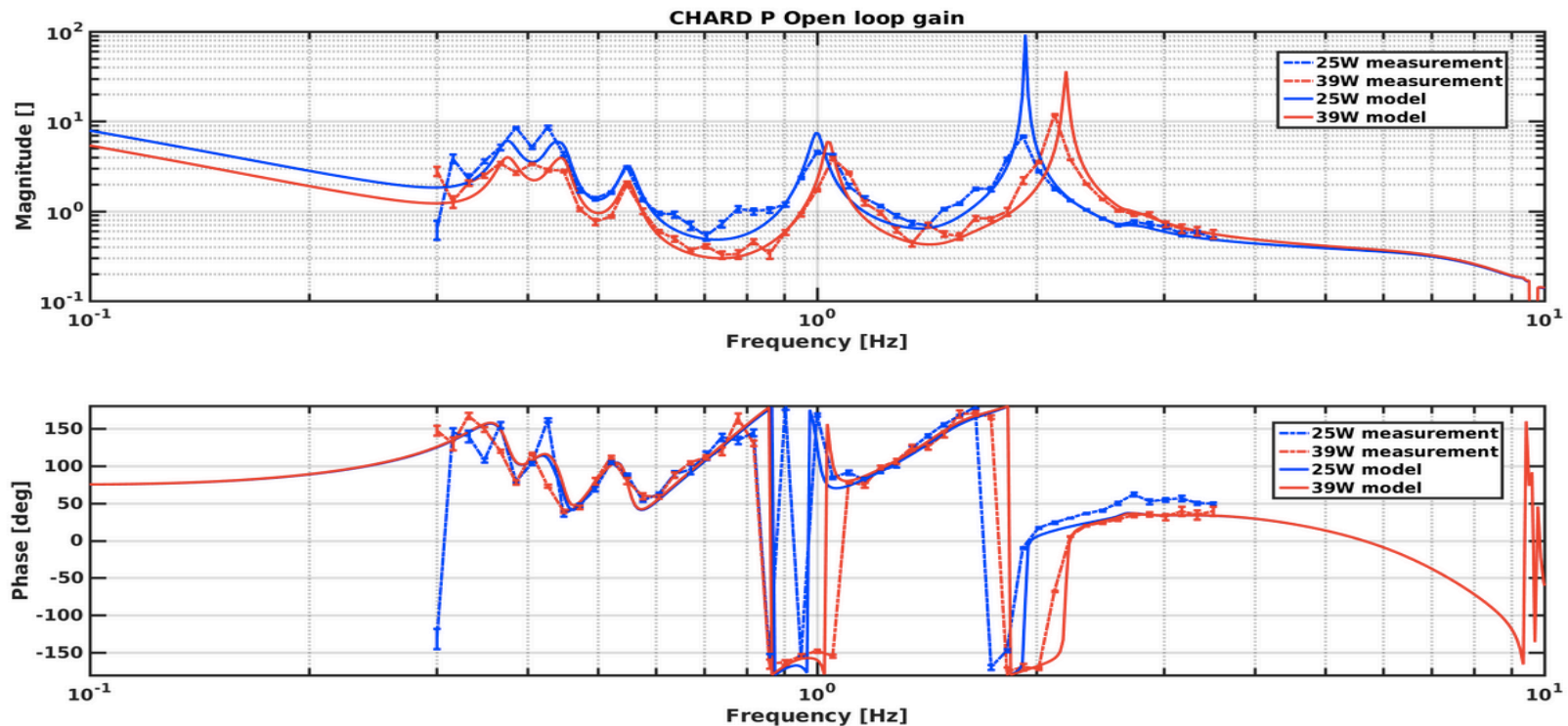
- ASC should maintain a residual angular motion of the arm cavity mirrors at ~ 1 nrad RMS in order to meet the aLIGO sensitivity target^[2]
- **Control up to few Hz is challenging and directly impacts the interferometer:**
 - **Stability:** Duty cycle reduced by the lock losses
 - Impact from environmental conditions
 - Radiation Pressure instability
 - **Noise:** Sensitivity compromised by the coupling to DARM
 - ASC can couple linearly or bi-linearly to length
 - Limiting the low frequency of the observing band
 - Searches impacted by the glitches

Power increase in the arms

For the next runs of ALIGO, increase of the power in the arms:

But the plant changes with power:

- shift in the resonance frequency
- The overall gain is decreasing

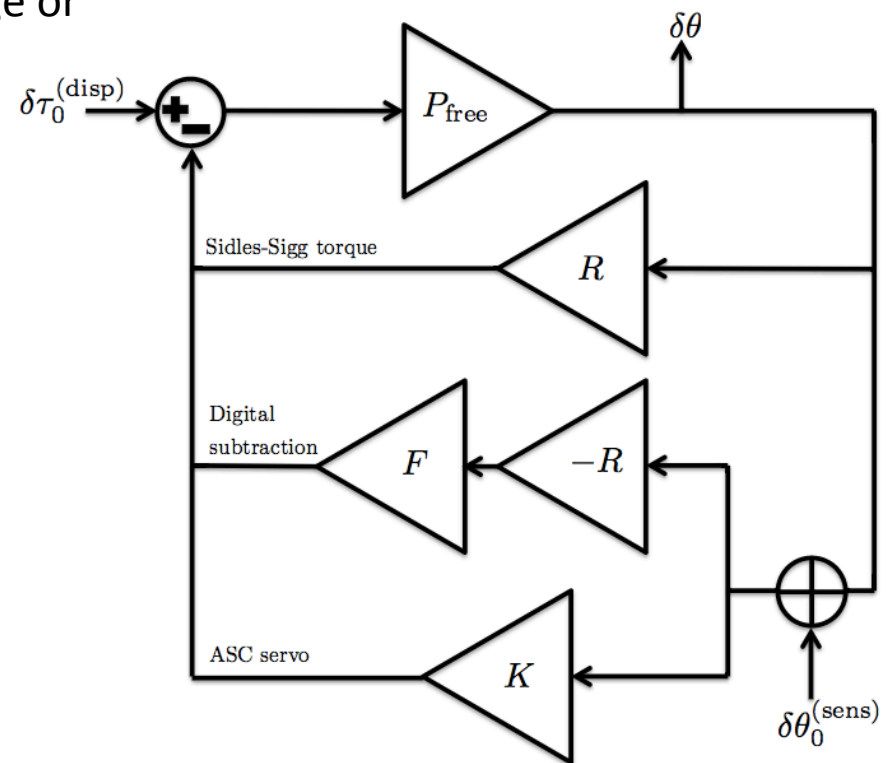


Good agreement between measurements and model → we know the plant

Power increase in the arms

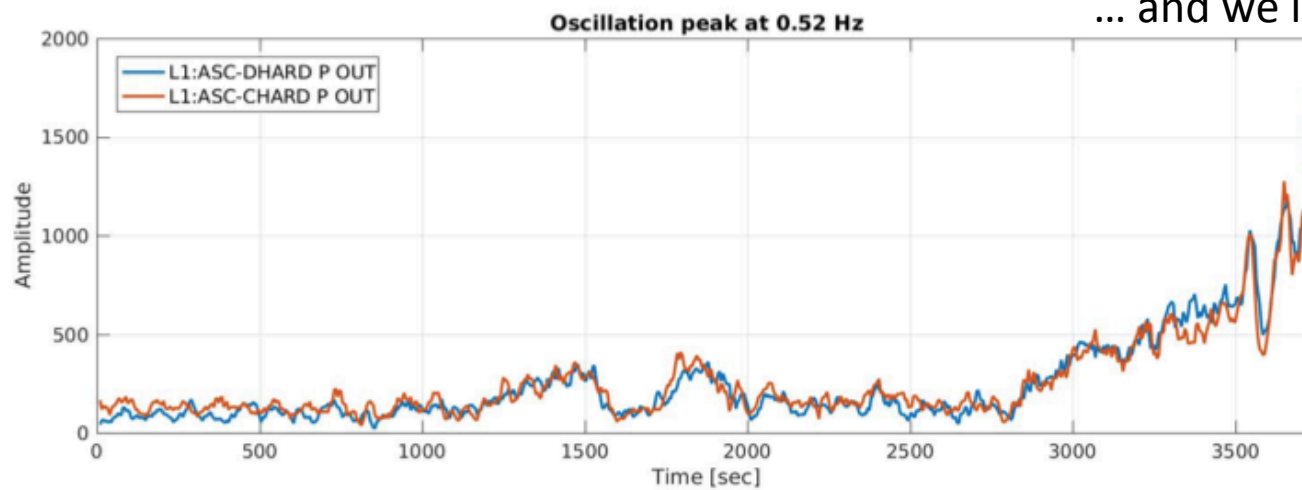
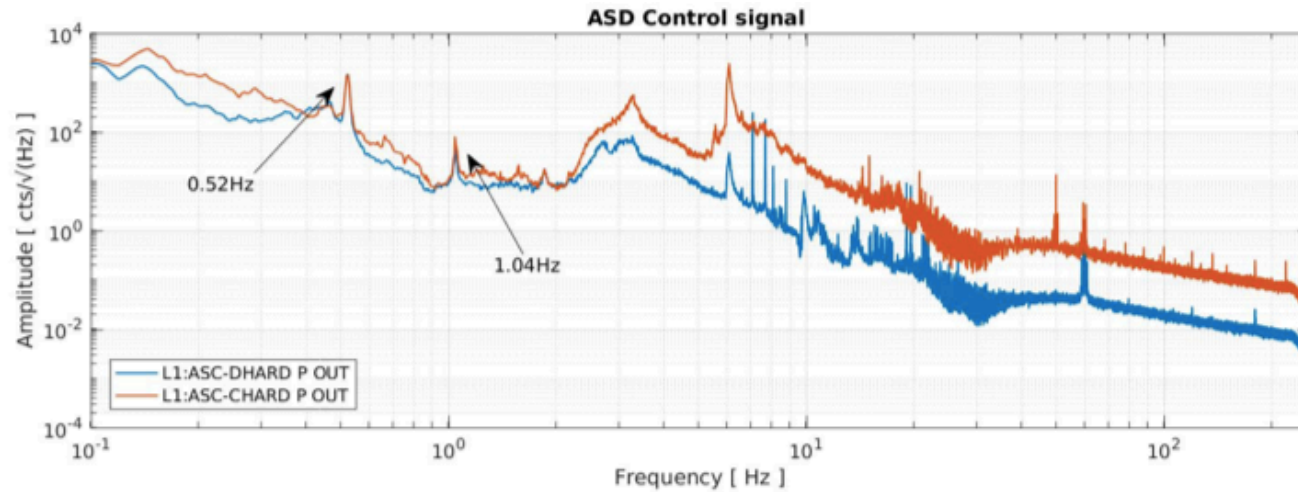
Stable at all frequencies but we have to:

- tune the filters for each power or
- Design filters stable for the power range or
- make the plant power independent :
 - digitally compensate for the power dependent plant
 - → See Hang talk



Power increase in the arms

However we see an unforeseen 0.5 Hz soft radiation pressure oscillation:



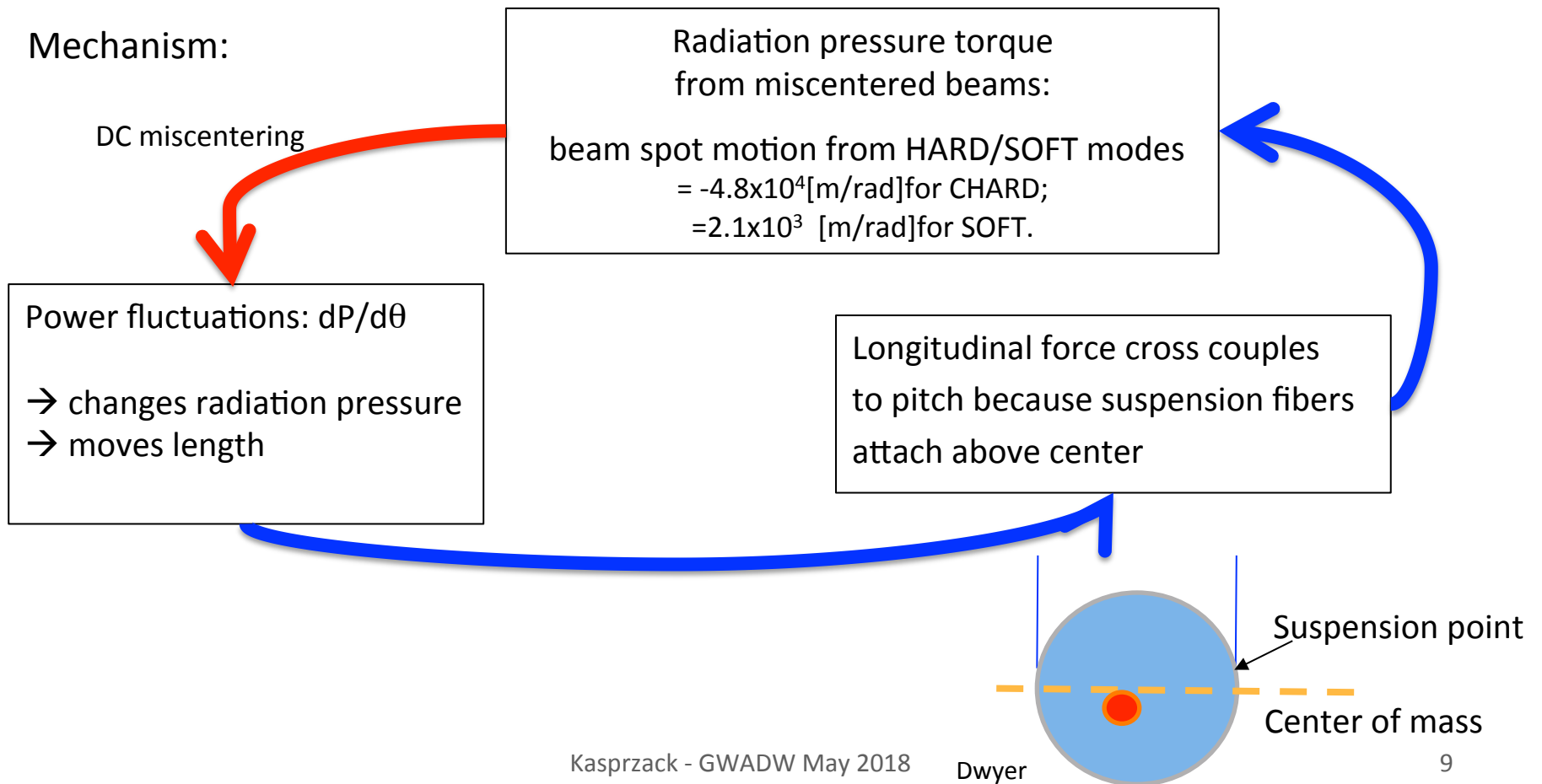
... and we loose lock!

Power increase in the arms

0.5 Hz soft radiation pressure oscillation:

- First seen at LIGO Hanford in 2015, then at LLO
- From a spurious dependence of circulating power on the beam spot position

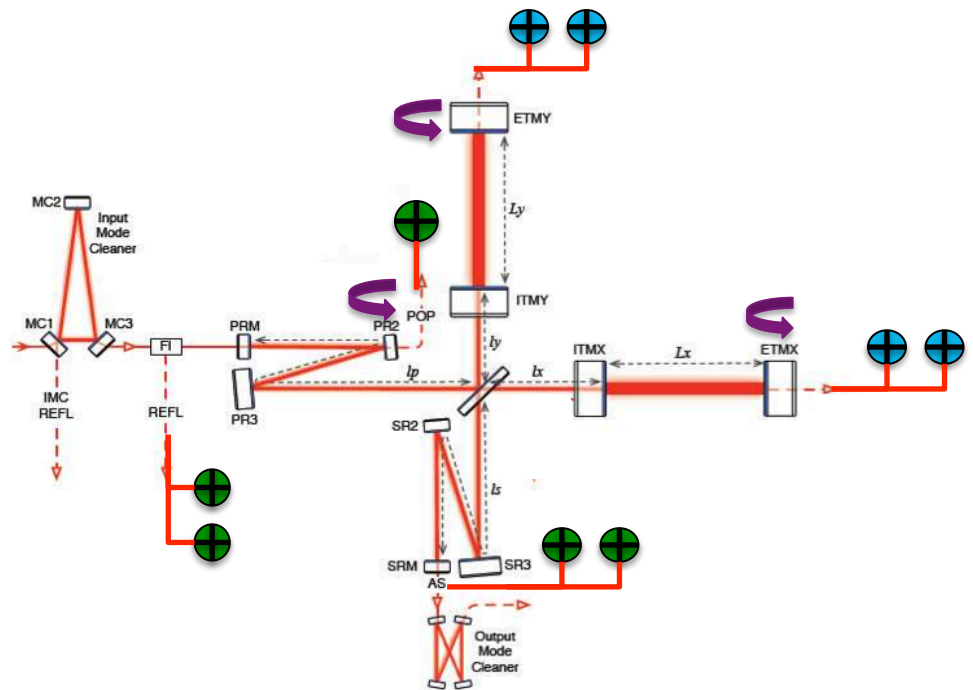
Mechanism:



Power increase in the arms

0.5 Hz soft radiation pressure oscillation can be suppressed or reduced:

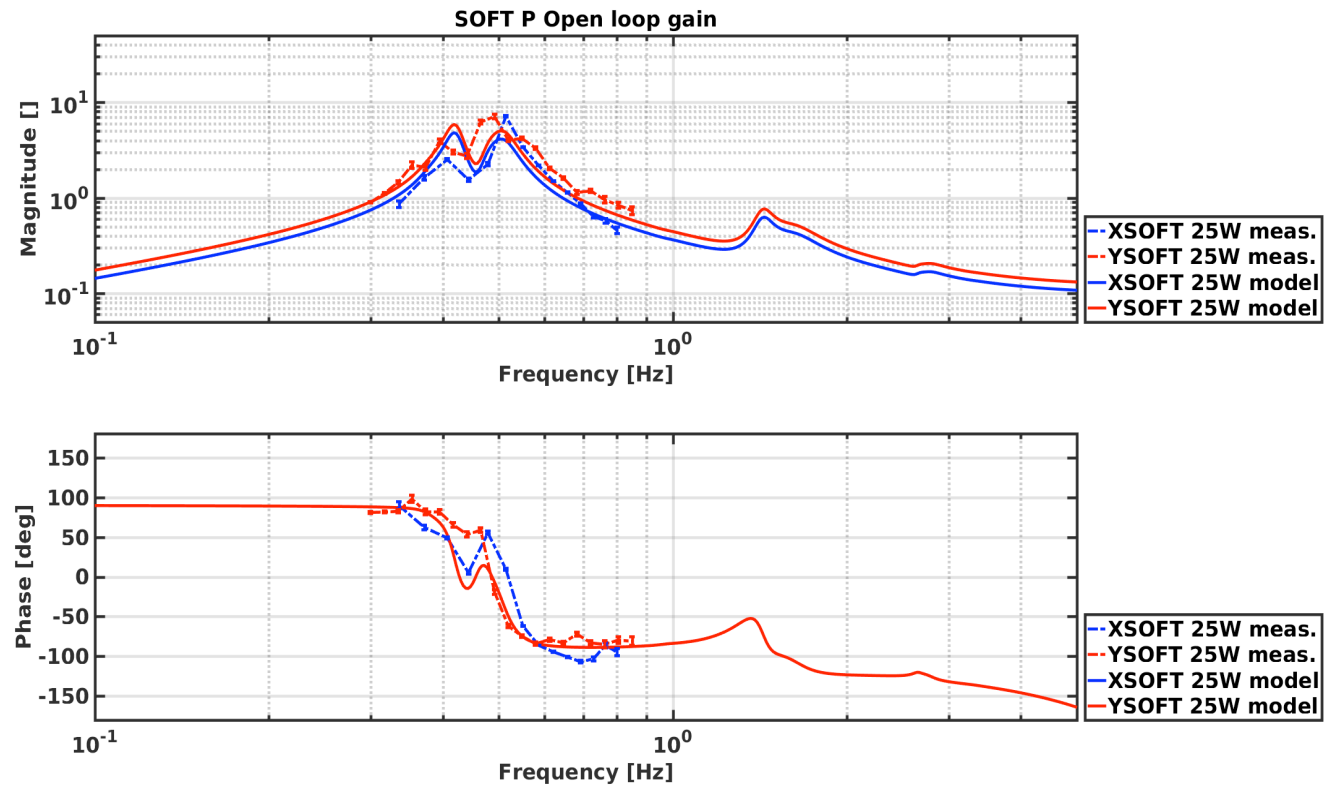
- Controlling CSOFT pit using the transmission of the arms
- Optical lever damping
- Changing coupling from spot position to circulating power
- Feedback to laser intensity to stabilize arm powers



Power increase in the arms

- Tested solution at LLO:

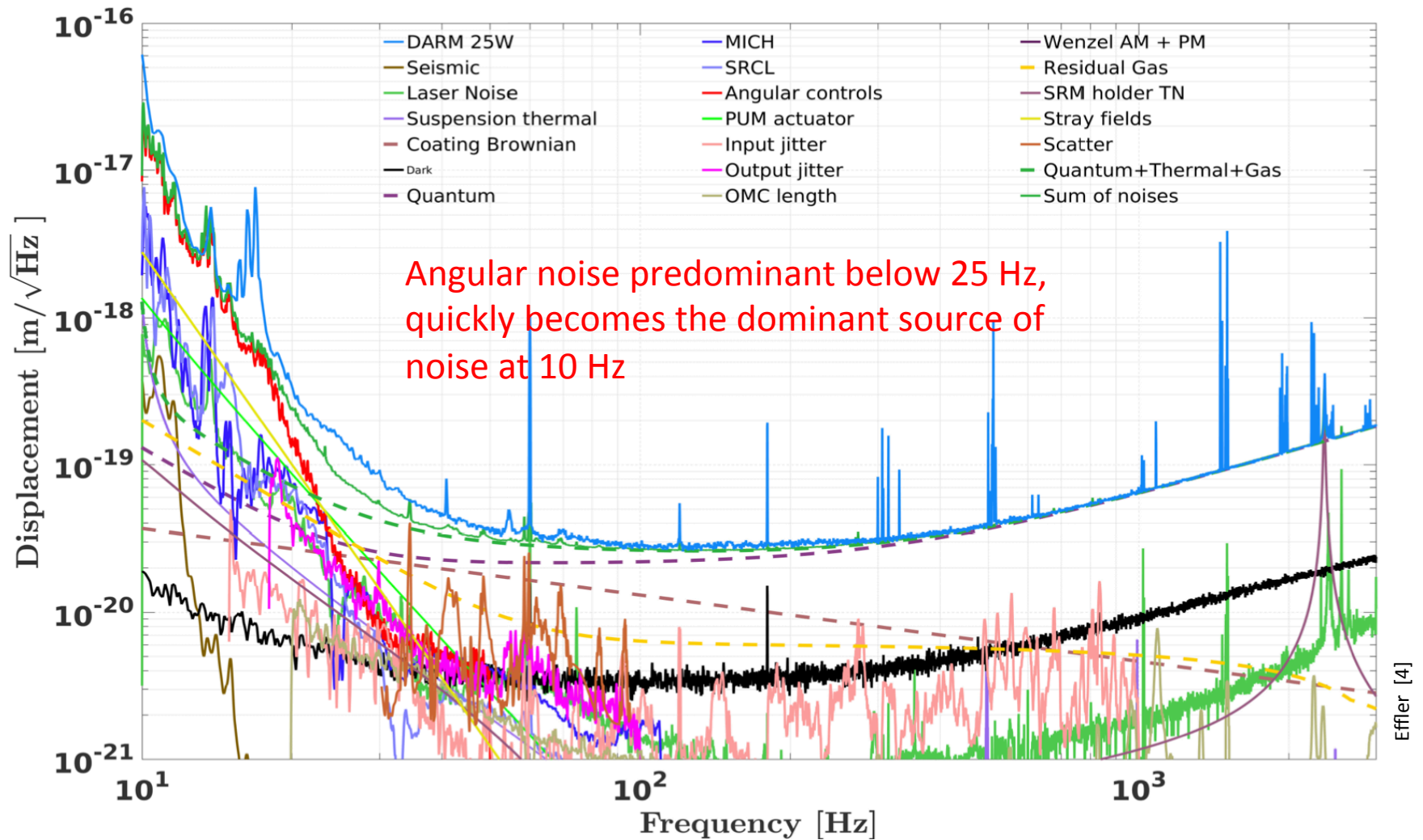
Extra damping with the arm transmission QPDs



Up to date: 14 hours of lock at LLO with ~ 170 kW in the arms

We need to reach stability at 50 W input → seems achievable

Impact of the angular performance in O2



Design expectations: factor 10 below DARM [3]

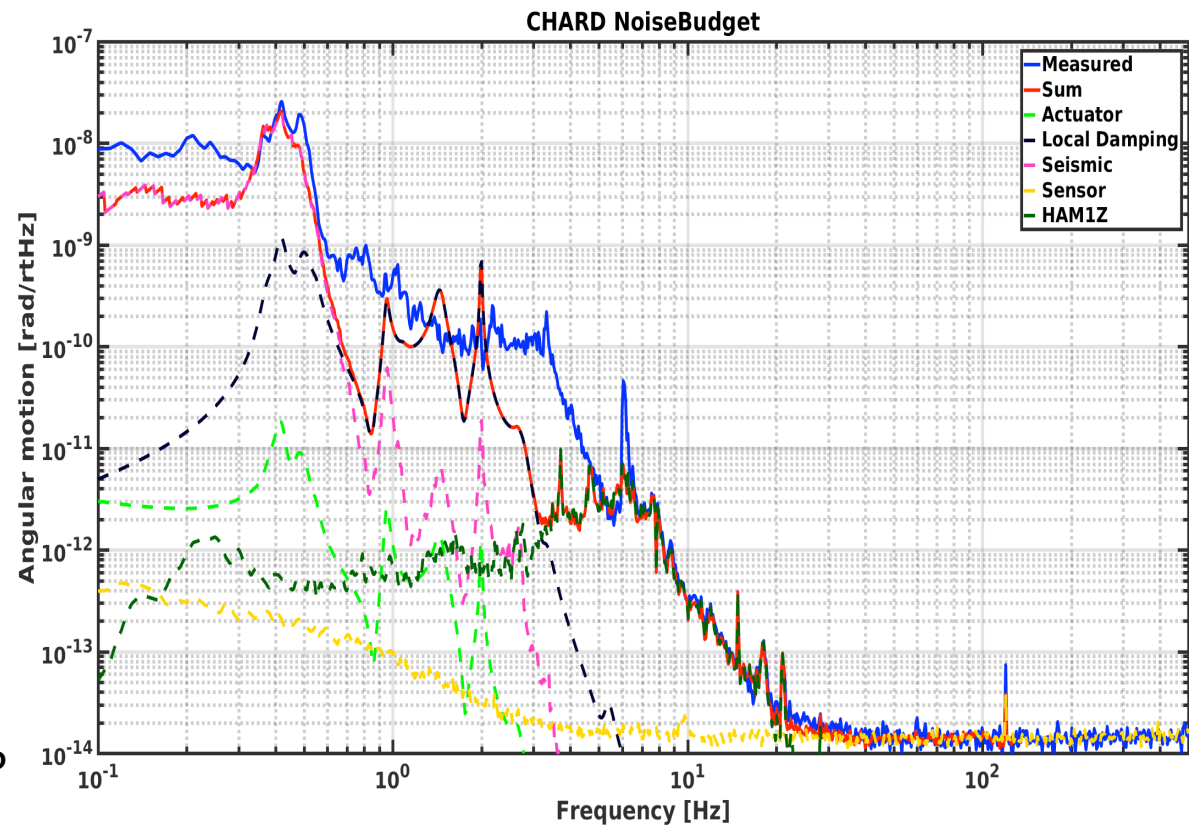
Noise

- Challenge for the control:
 - control of the arms up to few Hz
 - Then aggressive cut-off to minimize the impact on DARM

- Noise sources :

- seismic motion
- longitudinal control
- thermal drifts
- sensor noises
- radiation pressure

- Excess Noise in CHARD P

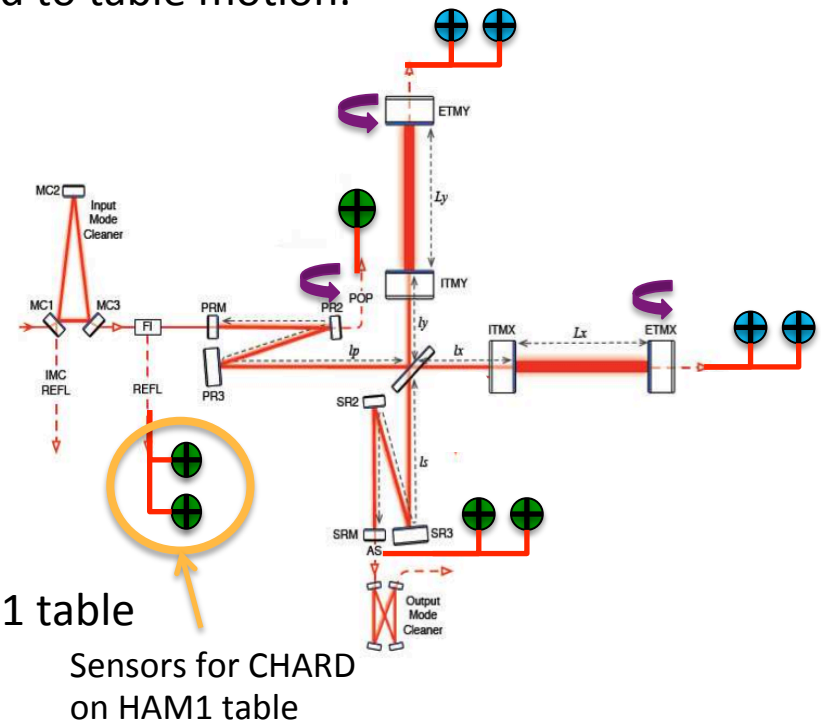


Excess noise

- Excess noise in the CHARD sensors correlated to table motion:
 - Experienced at both sites

Mitigation strategies:

- Reduce the noise
- Reduce the coupling
 - feeding forward the motion of the HAM1 table
 - Blending
- LLO worked on reducing the noise and then the coupling via FF
- LHO has the same problem but also a solution to reduce the coupling



→ to be tested soon at LLO

SRM control

- Loop does not reliably work:
 - Very slow loop
 - we can sometimes close it, sometimes not
- Sensing issue:
 - Sensing matrix measurements indicate that the coupling should be better with the new SRM but it is not the case
 - Pollution by high order modes
 - Sensor sensitive to beam spot position
- New scheme:
 - Use an additional sensor at LLO? → but needs DC centering work
 - New frequency (72 MHz) to be tested at both observatories soon.

Issues to solve and Conclusion

- We have several issues ahead to solve:
 - Oscillation shifting down with higher circulating power
 - Sensing noise
 - Cross coupling
 - Loop control for SRM
- Angular coupling is still one of the main limits at low frequencies for the detectors
- Investigations are on-going to reduce the noise/coupling
- New challenges ahead for the future runs:
 - How do we plan for them : Better/More sensors? Optimal control ? ...
 - We need more work force in this topic

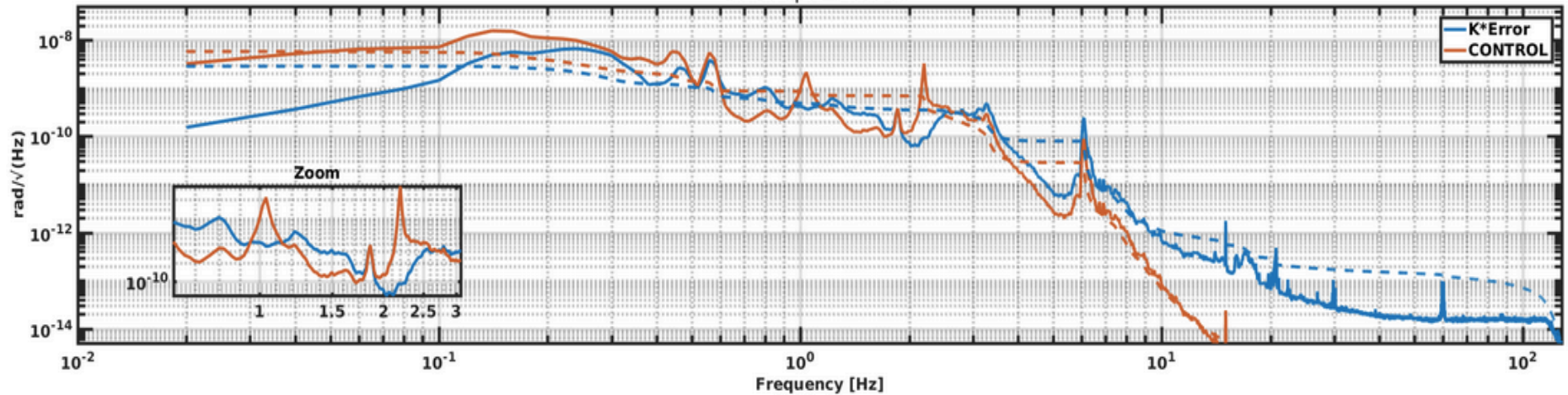
References

- 1 D. Martynov, *“Lock Acquisition and Sensitivity Analysis of Advanced LIGO Interferometers ”*
- 2 L. Barsotti, *“Modeling of Alignment Sensing and Control for Advanced LIGO”*
- 3 B. Seymour, *“Non-Linear Angular Noise Coupling into Differential Arm Length”*
- 4 <https://alog.ligo-la.caltech.edu/aLOG/index.php?callRep=33552>

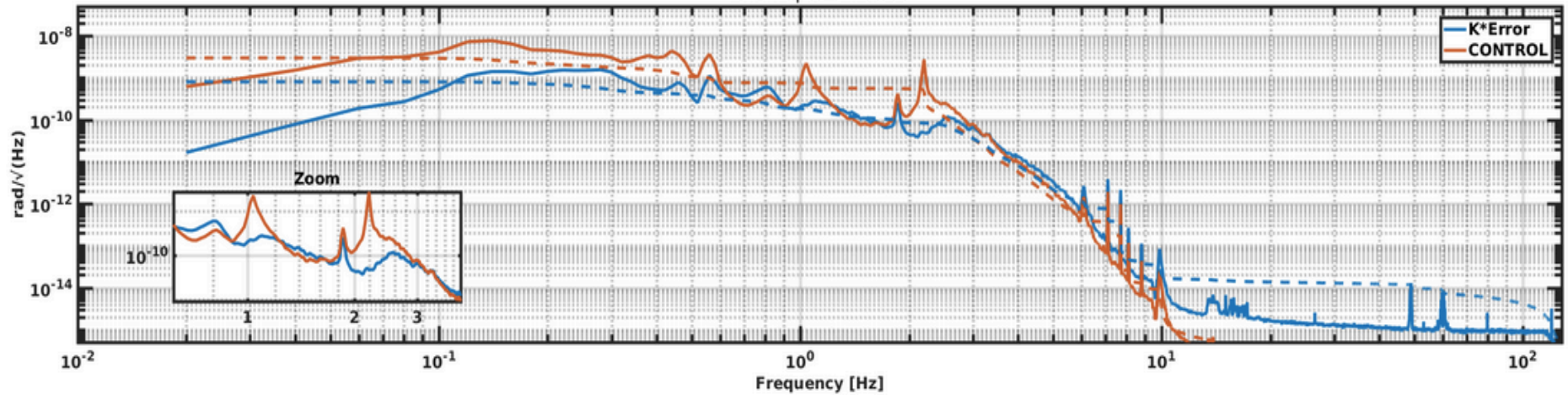
Lock at 40 W – Angular motion suppression

13-Feb-2018 10:00:01 UTC

CHARD | $K = 2.6e-10$



DHARD | $K = 2.2e-11$



REFL WFS noise

A coupling similar to L1 is observed at H1 for REFL WFS

