



# Seismic Control during Earthquakes: a Review of the proposed scheme

G1800399, March 20, 2018

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New control scheme for use during teleseismic earthquakes

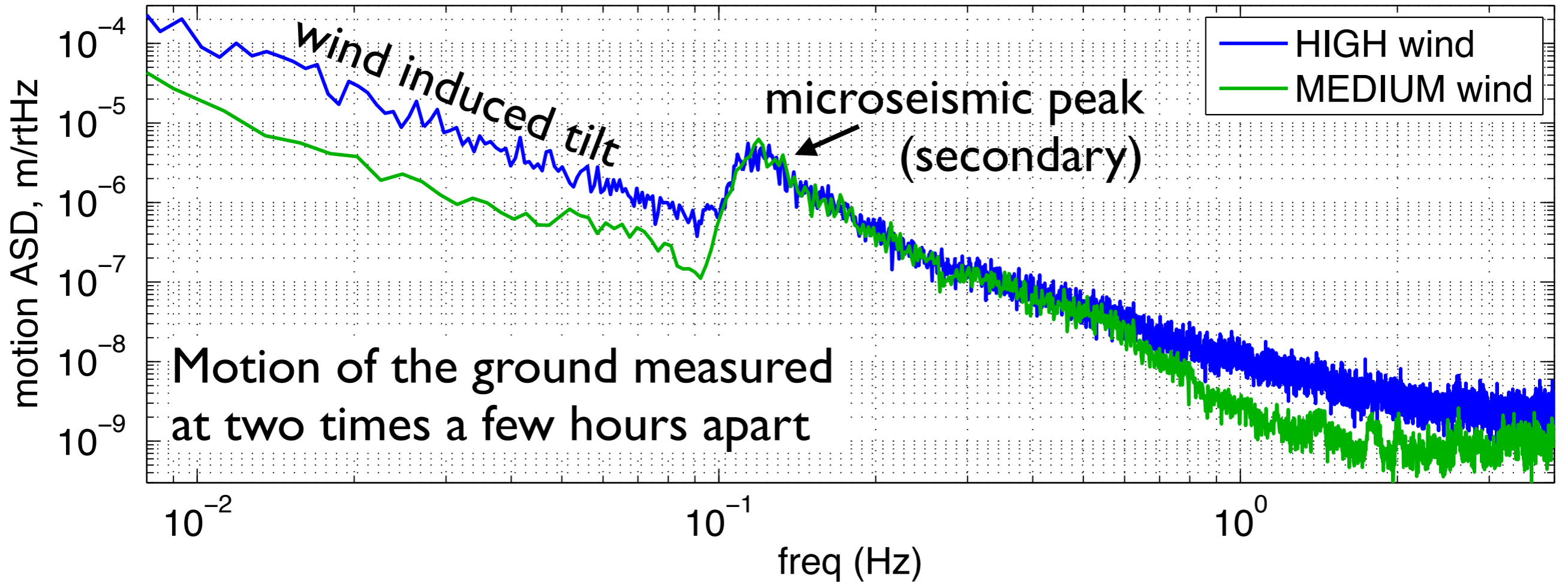
Installation is very soon. (We've been talking about this for a while)

Discuss at CSWG because it uses several control choices not used before.

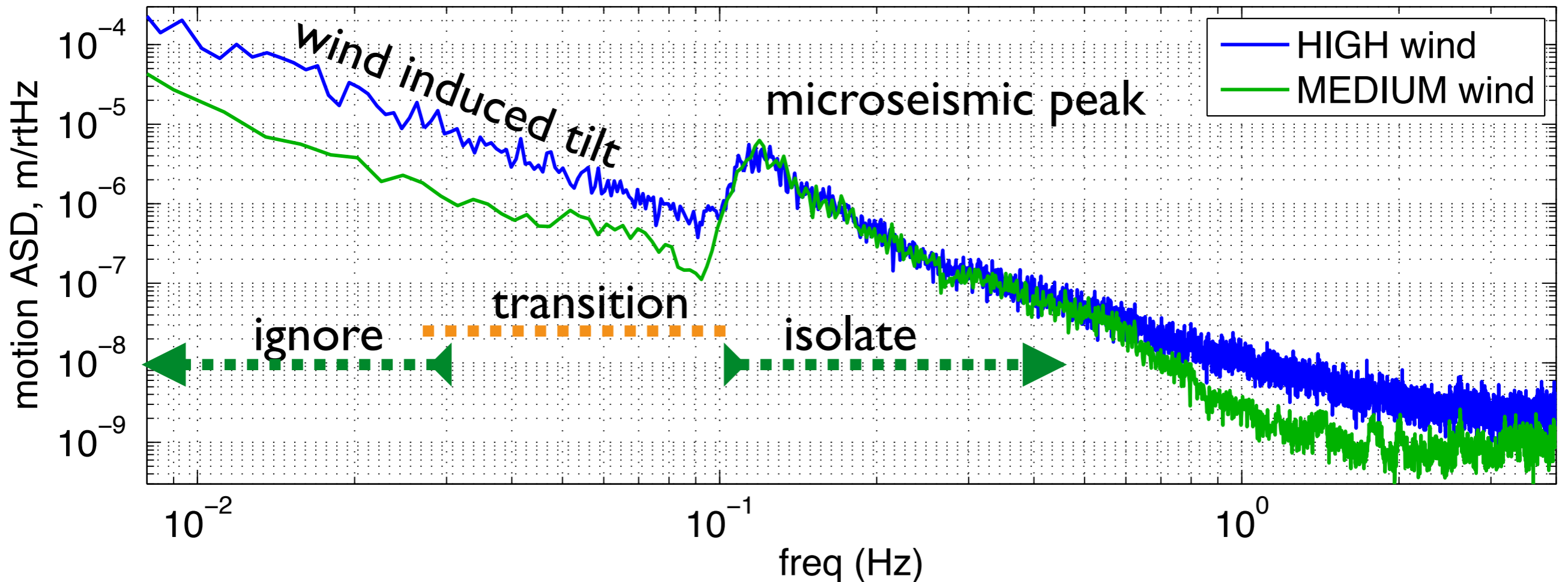
1. Routinely Change control based on predictions of the future.  
(done a few times in past)
2. Design for isolation below 100 mHz.
3. Do not isolate to minimize the inertial motion.  
Allow system to ride on the common-mode, and  
only isolate on the local differential.

# Recall - typical control condition

T240X as disp, loud v. quiet



T240X as disp, loud v. quiet



Use the ground motion signal for low freq. control (Sensor Correction)

- Use the signals above  $\sim 100$  mHz to isolate against the microseism
- Filter out signals below  $\sim 30$  mHz to not couple measured ground tilt.
- Transition band has amplification (waterbed effect). OK if band is quiet.

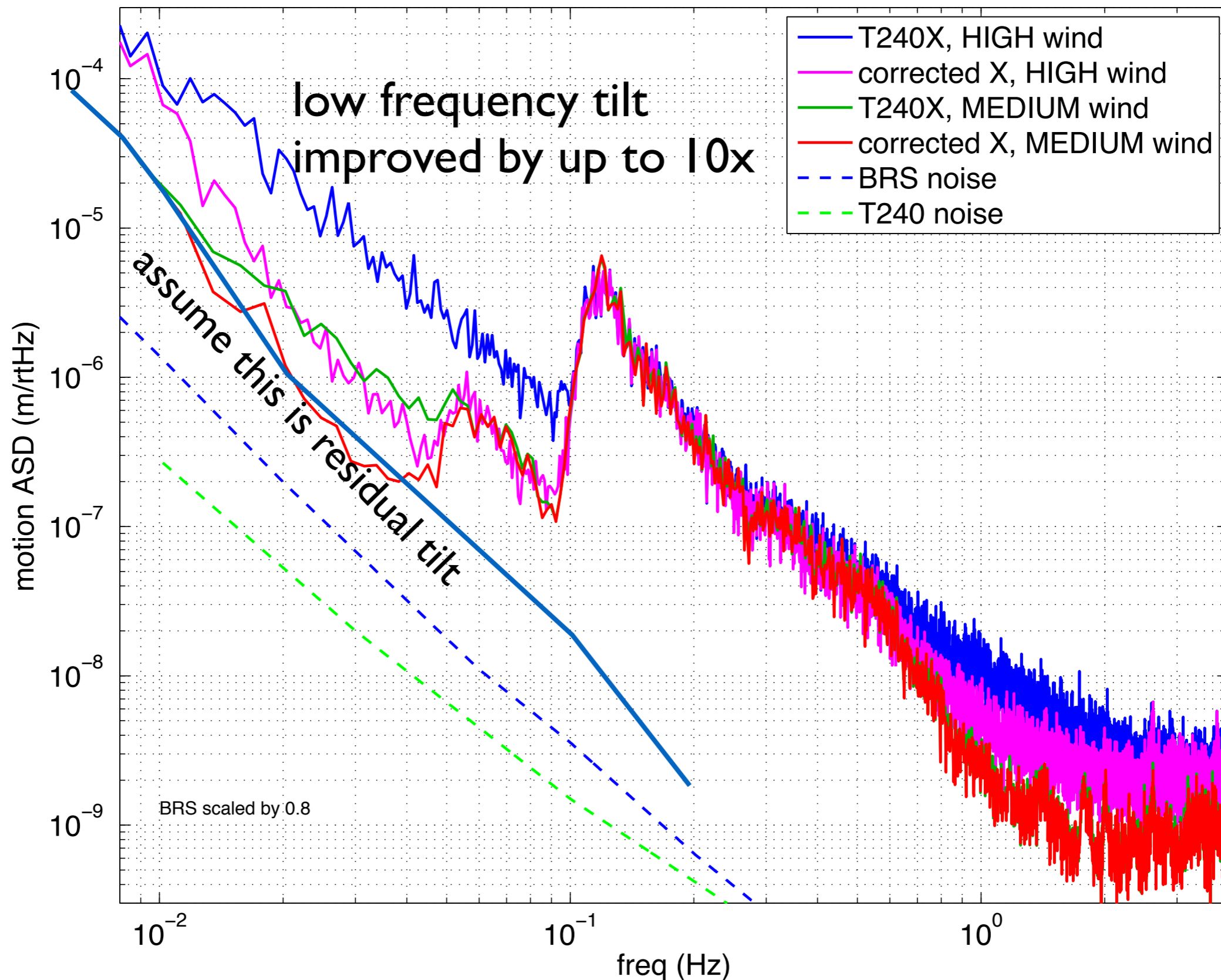


Difference #1

# BRS Improves measured motion

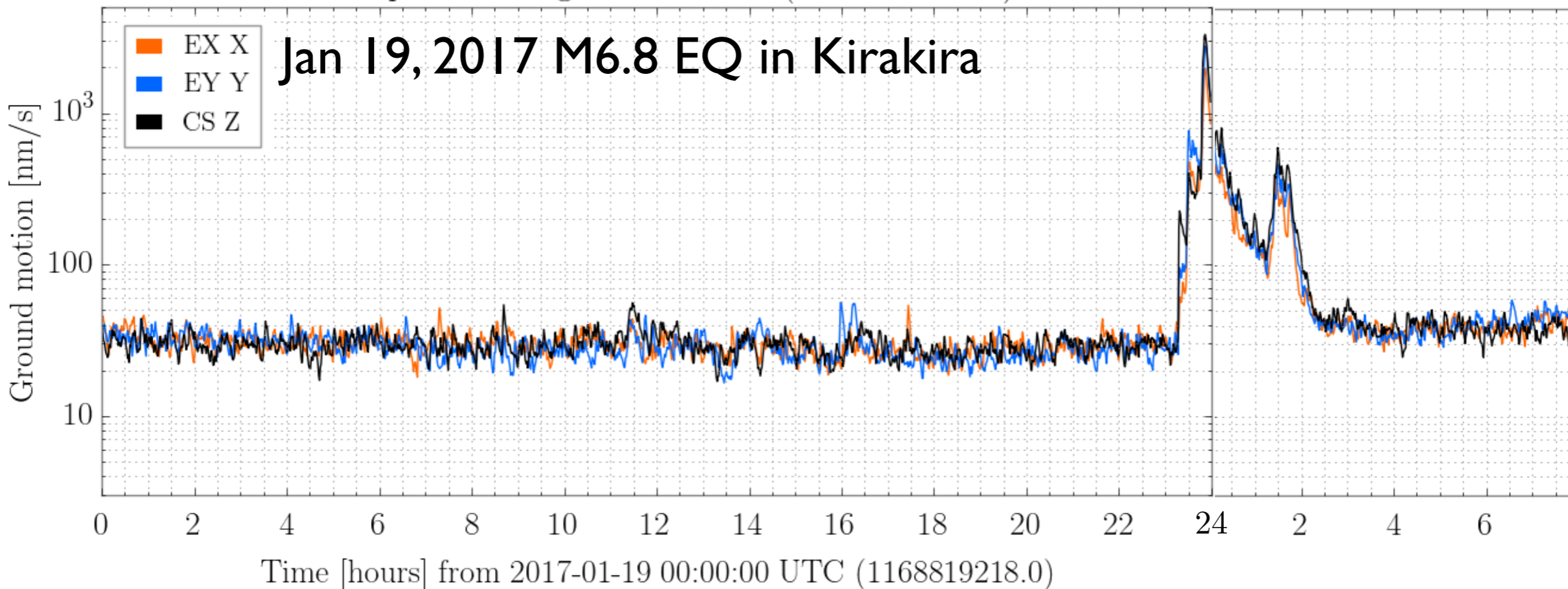


Corrected horizontal motion



# Earthquakes = motion at $\sim 50$ mHz

Earthquake band ground motion (0.03 Hz–0.1 Hz)



In this case, the BLRMS hits  $\sim 3$  microns/sec

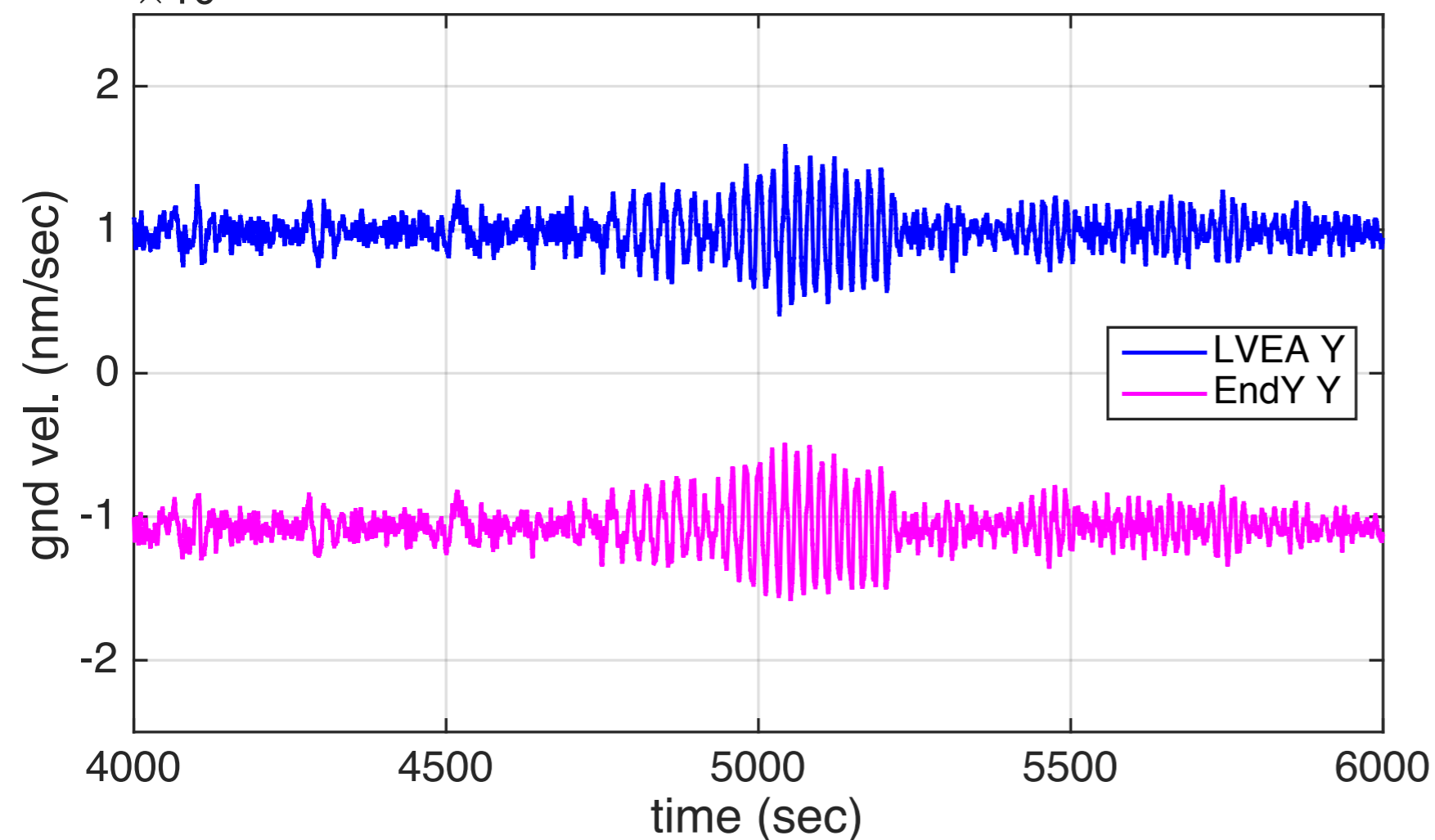
IFO loses  $\sim 4$  hours of Observation time.

Nothing special about this event,  
chosen because I had to time to follow up

# Most of the motion is Common-mode

Time Series, LHO, Local motion for Y

$\times 10^4$  M6.8 Kirakira, Solomon Islands, 19 Jan 2017



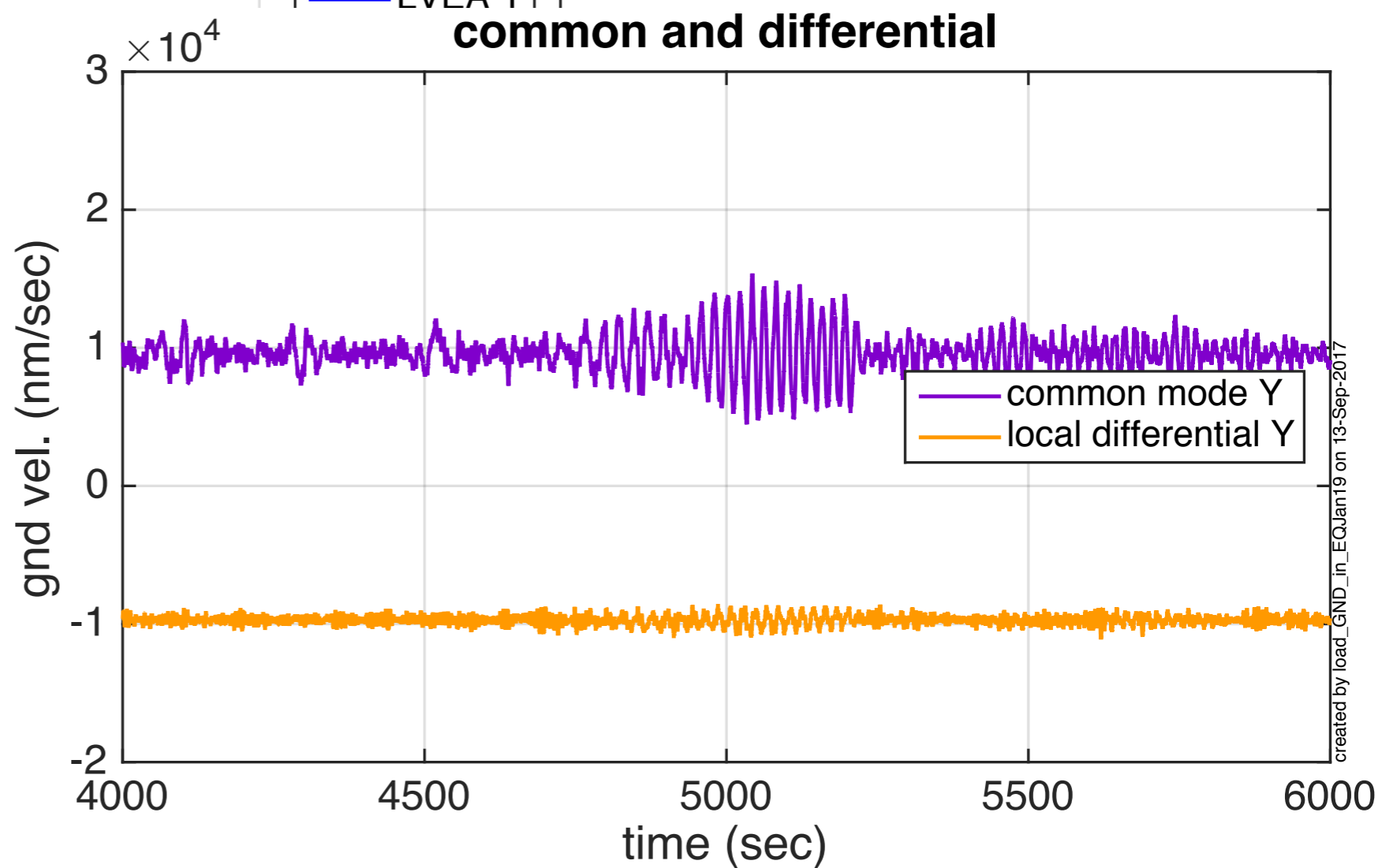
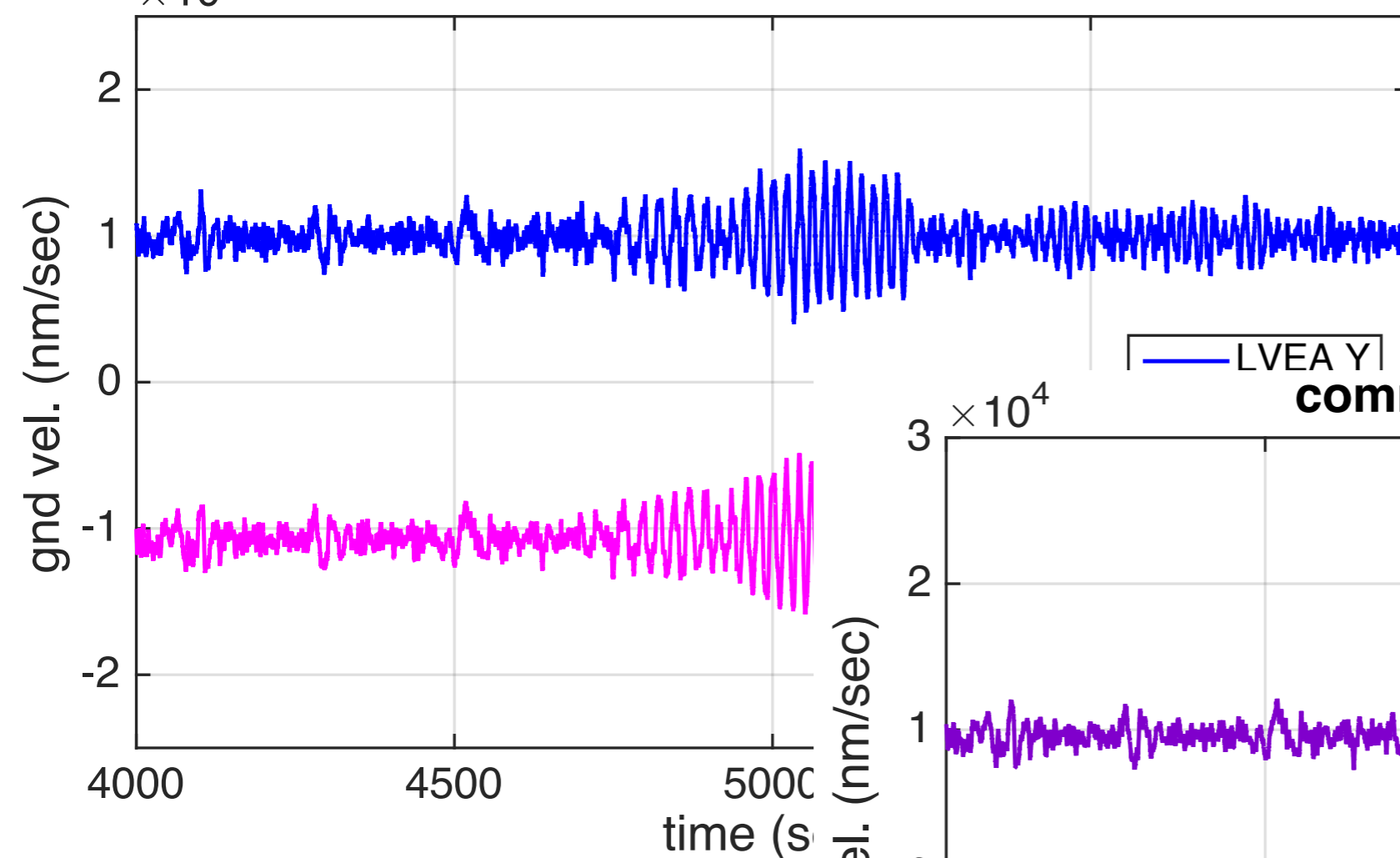


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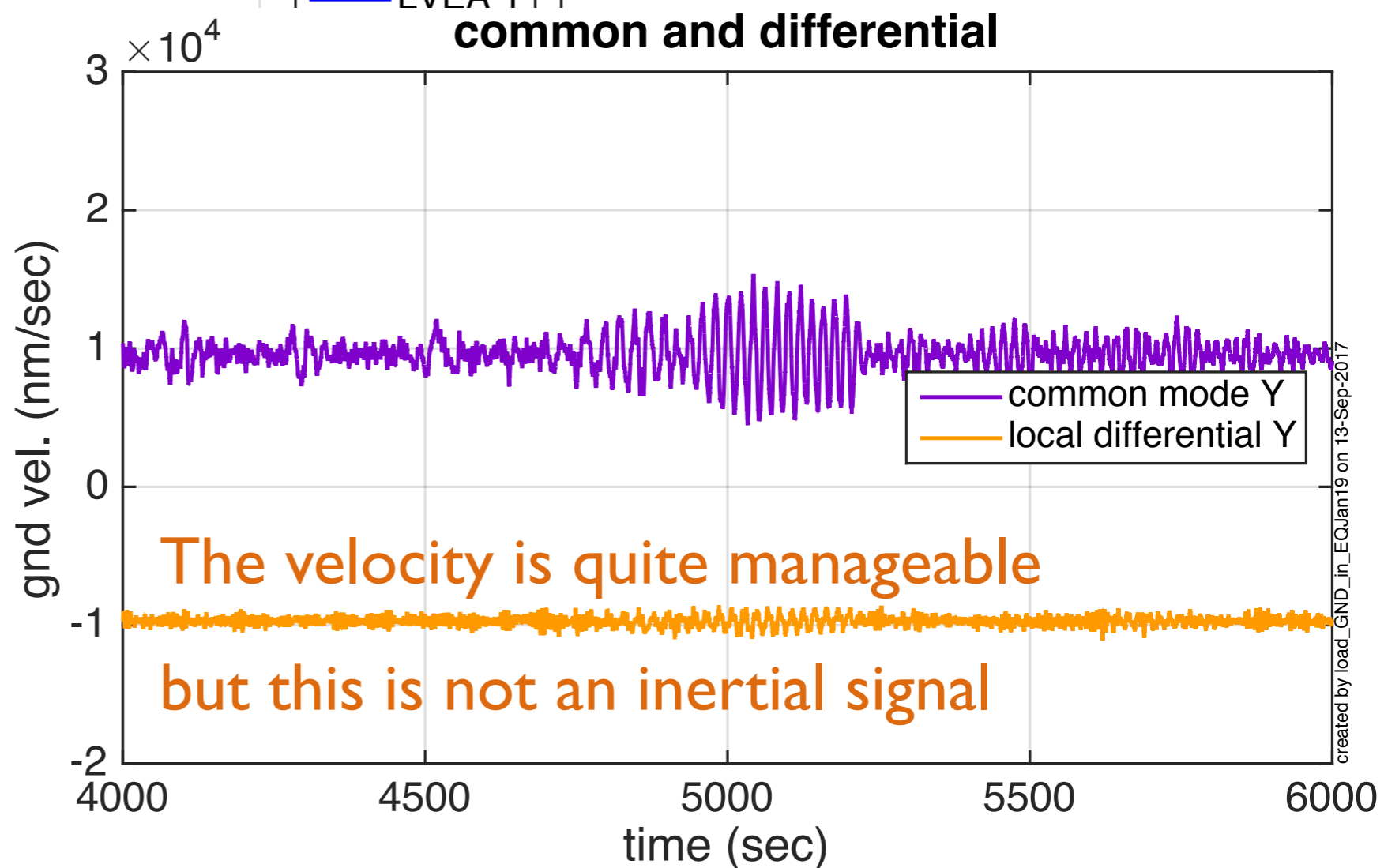
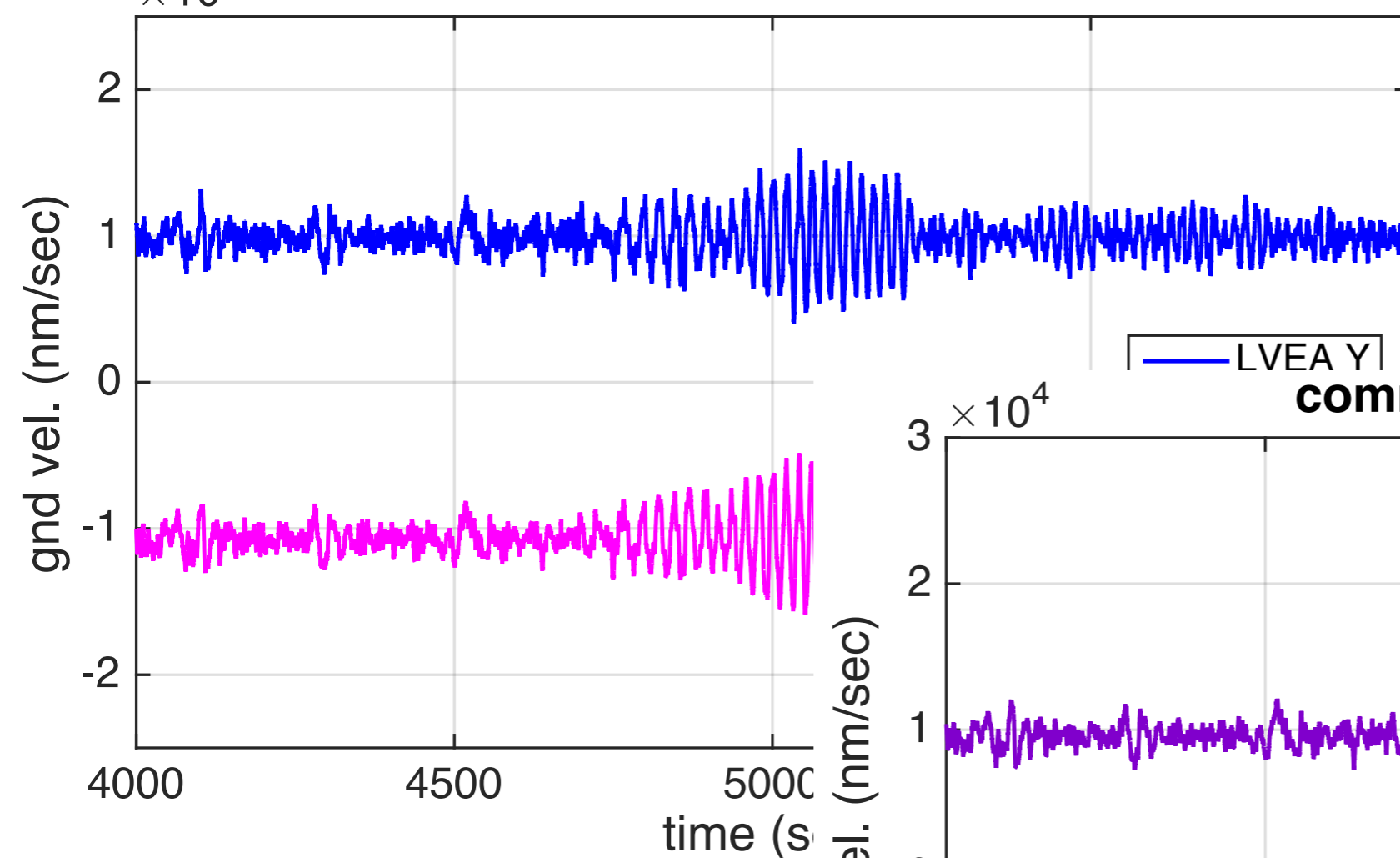




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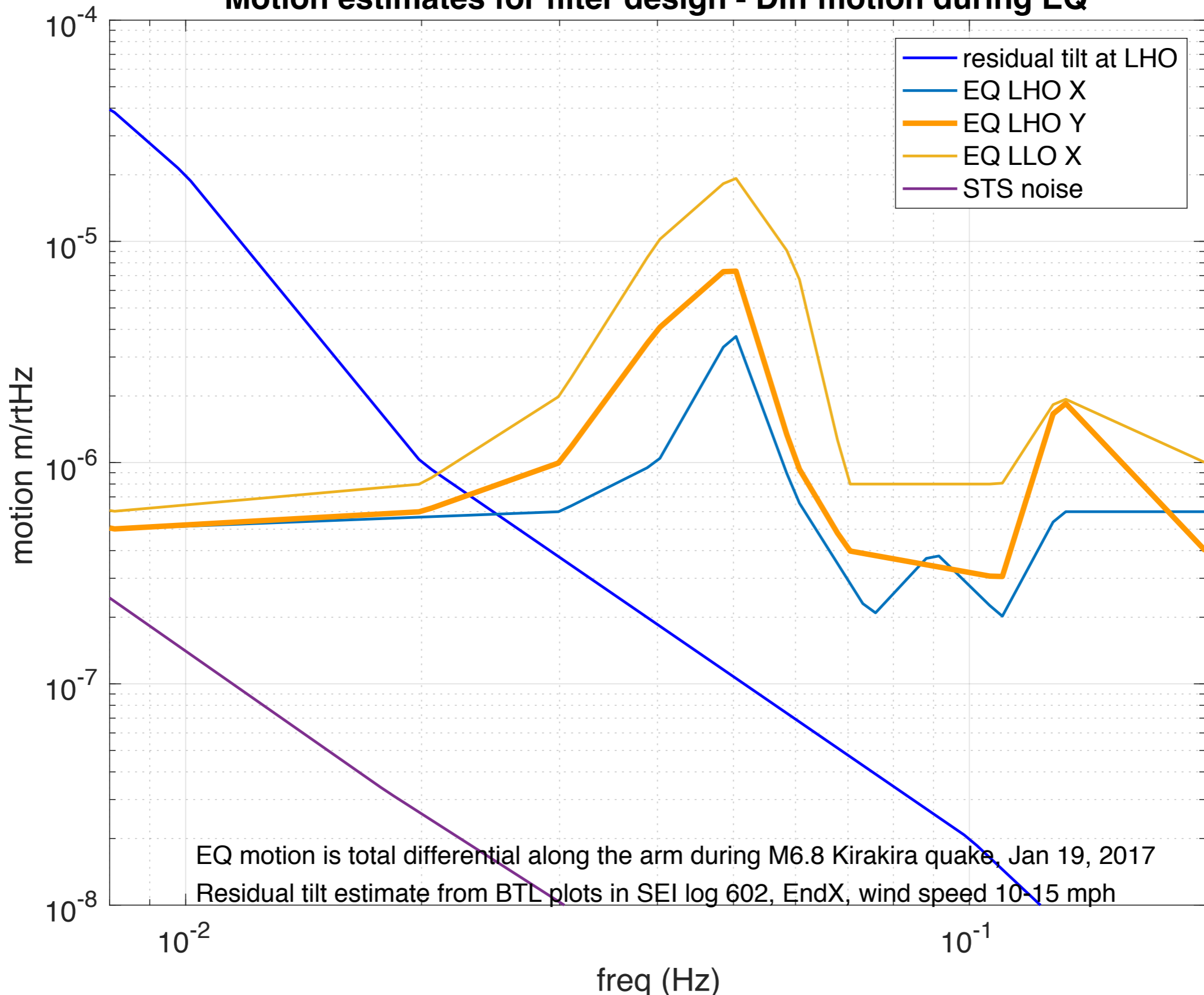


The velocity is quite manageable  
but this is not an inertial signal

# Motion estimates

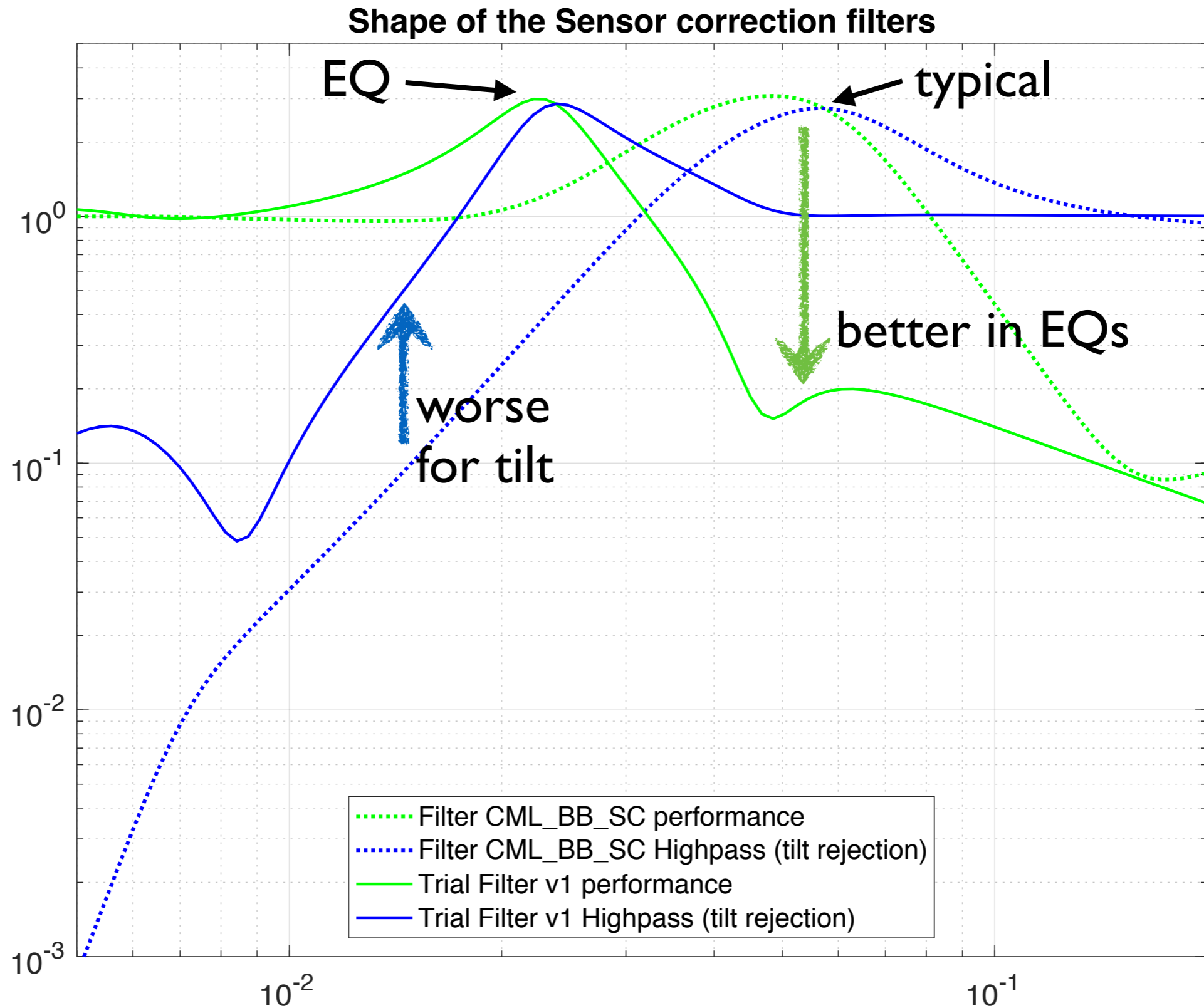


Motion estimates for filter design - Diff motion during EQ



# New Sensor Correction

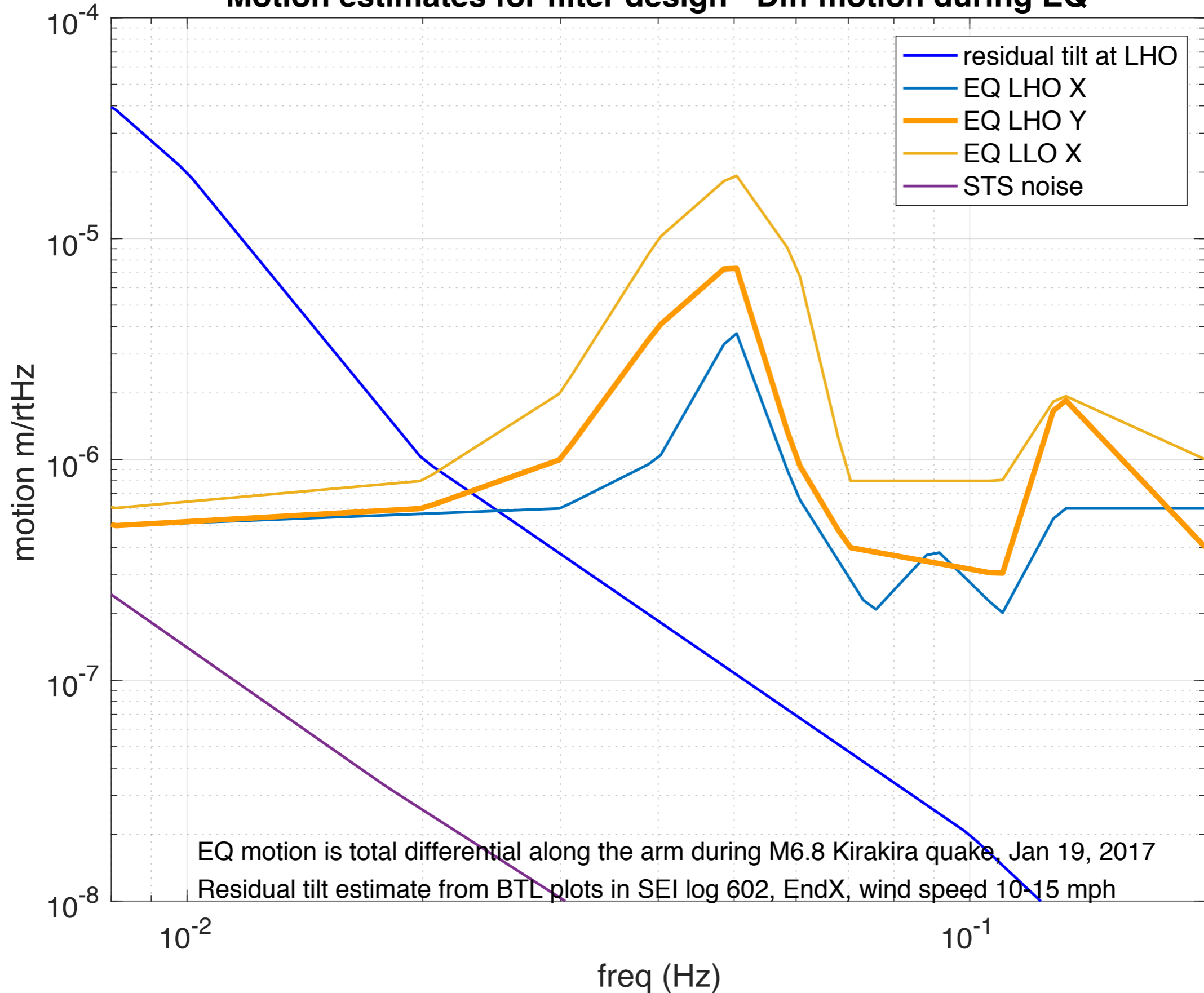
Pick a shape that works better for the EQ motion



# Motion estimates



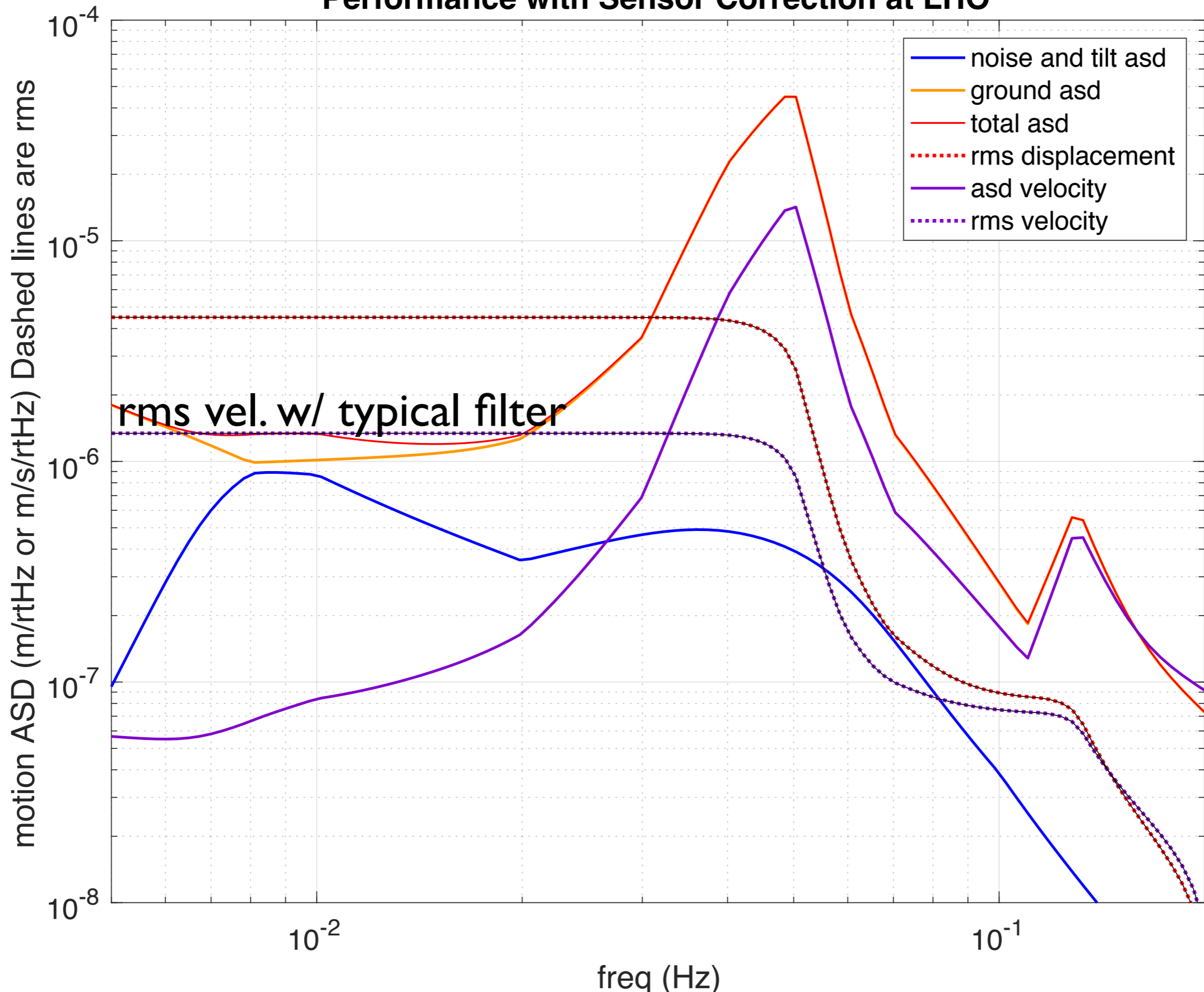
Motion estimates for filter design - Diff motion during EQ



# Sensor Correction



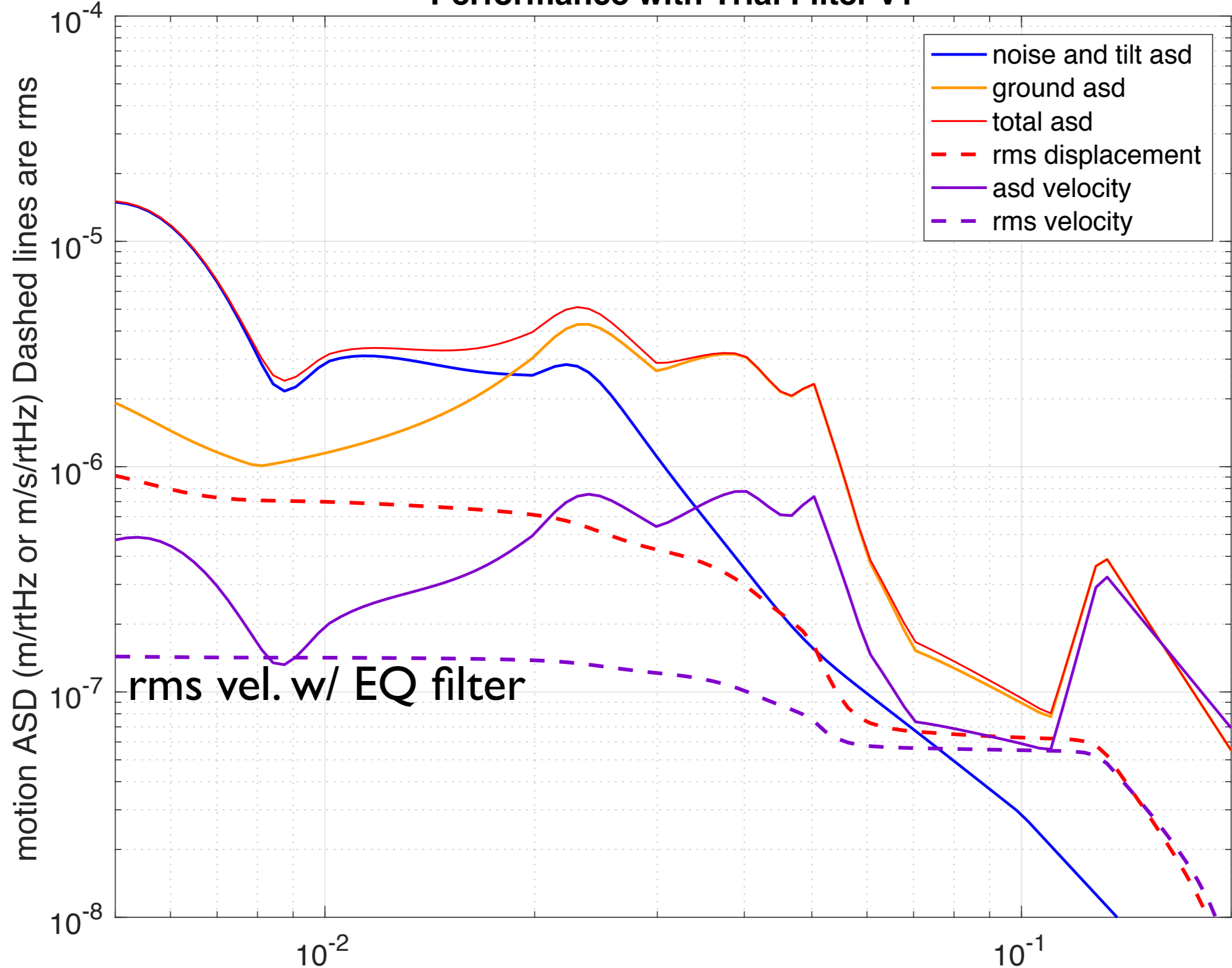
Performance with Sensor Correction at LHO



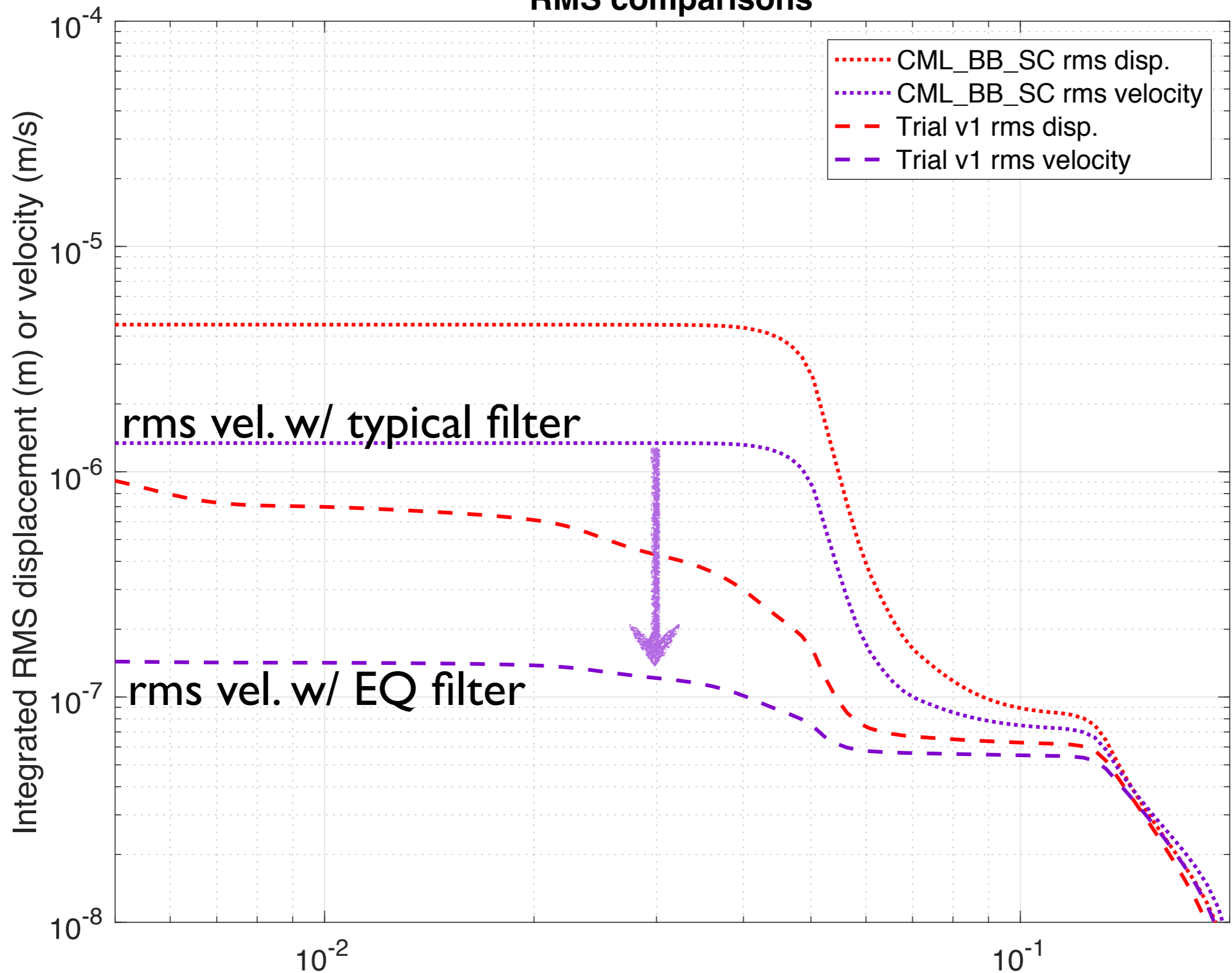
# Sensor Correction



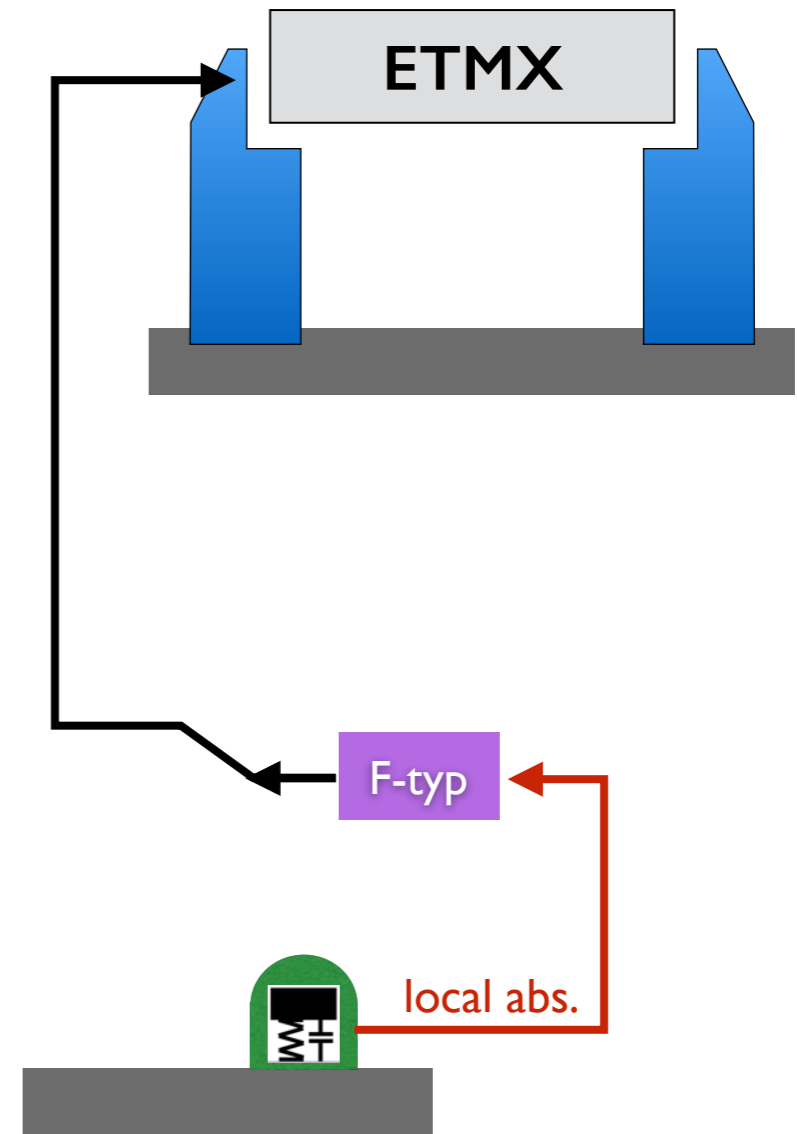
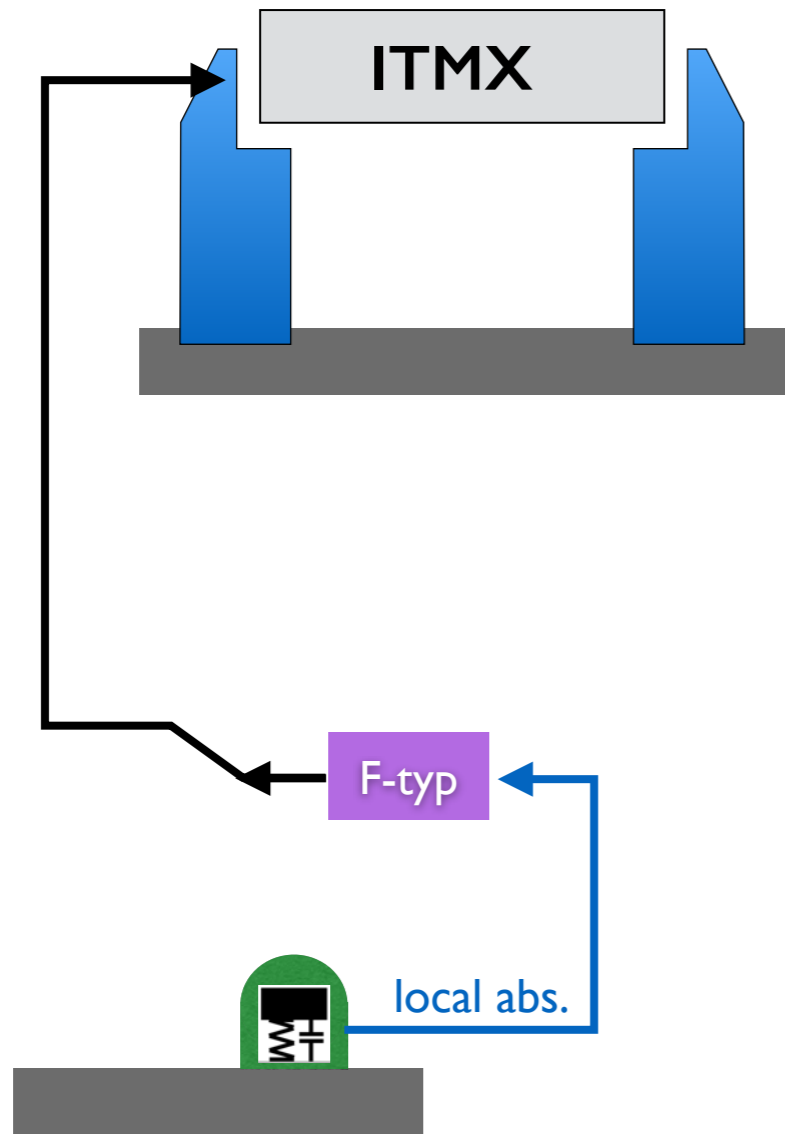
Performance with Trial Filter v1



## RMS comparisons

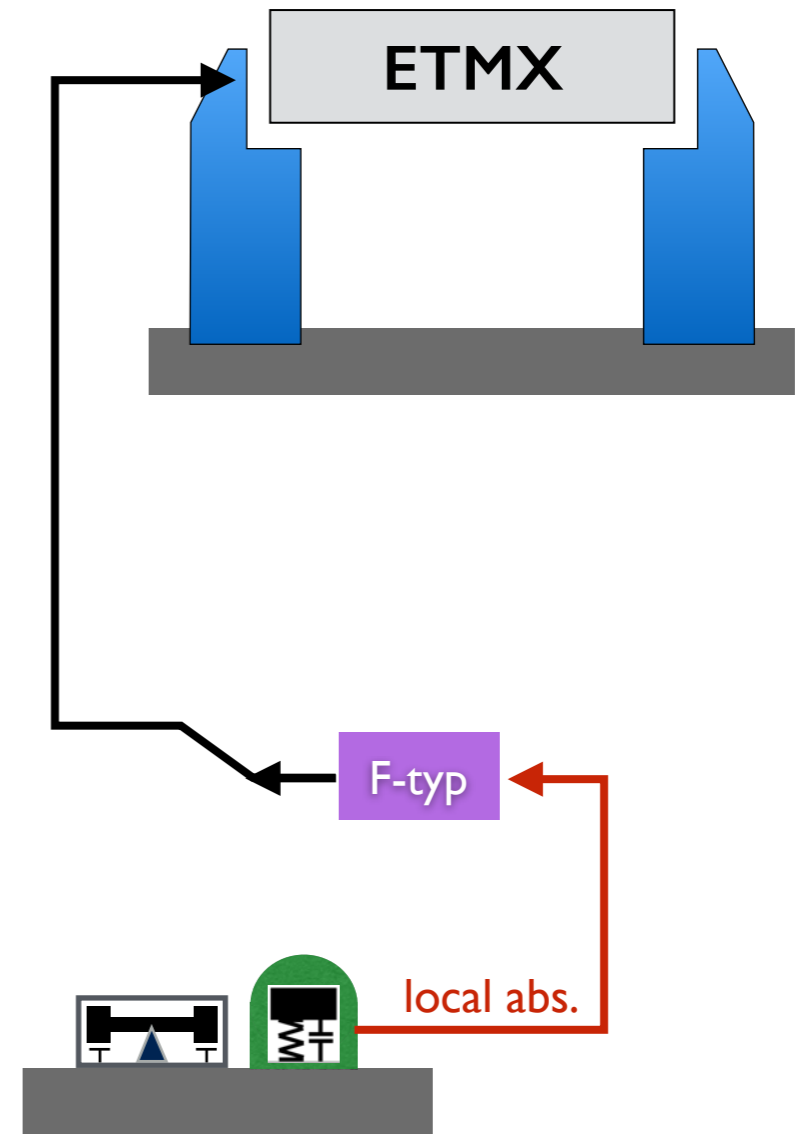
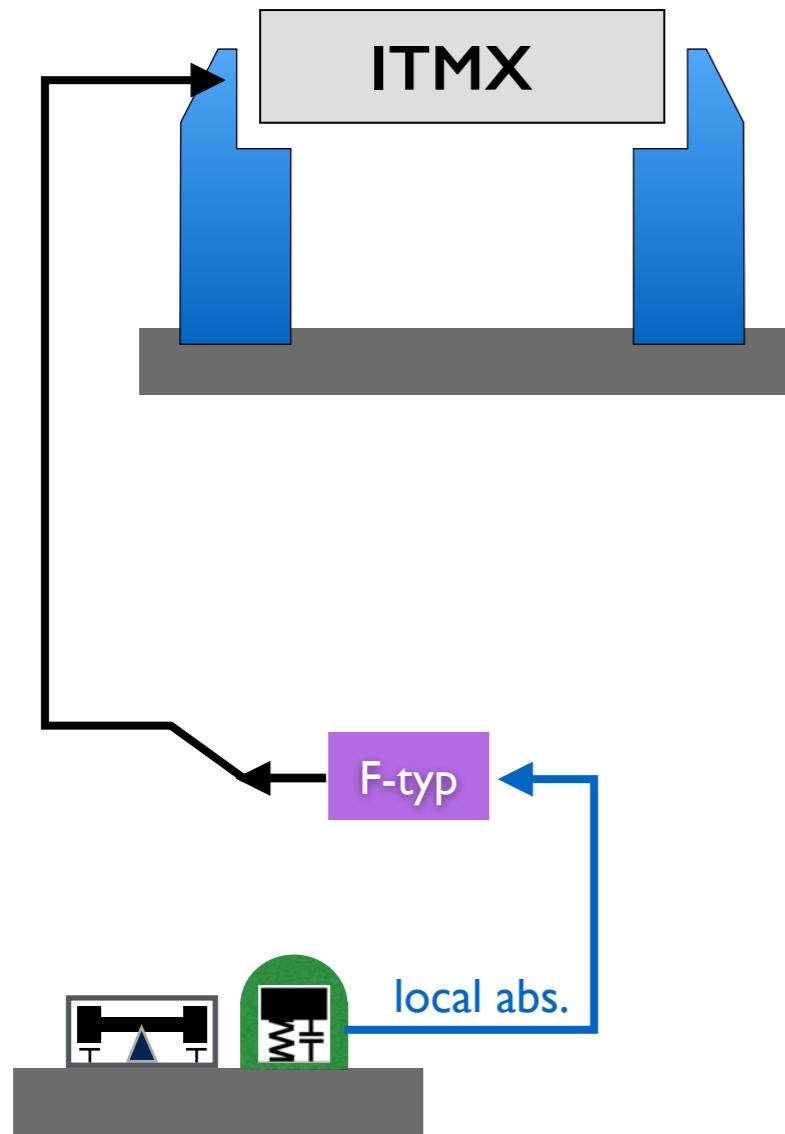


# Control schematic

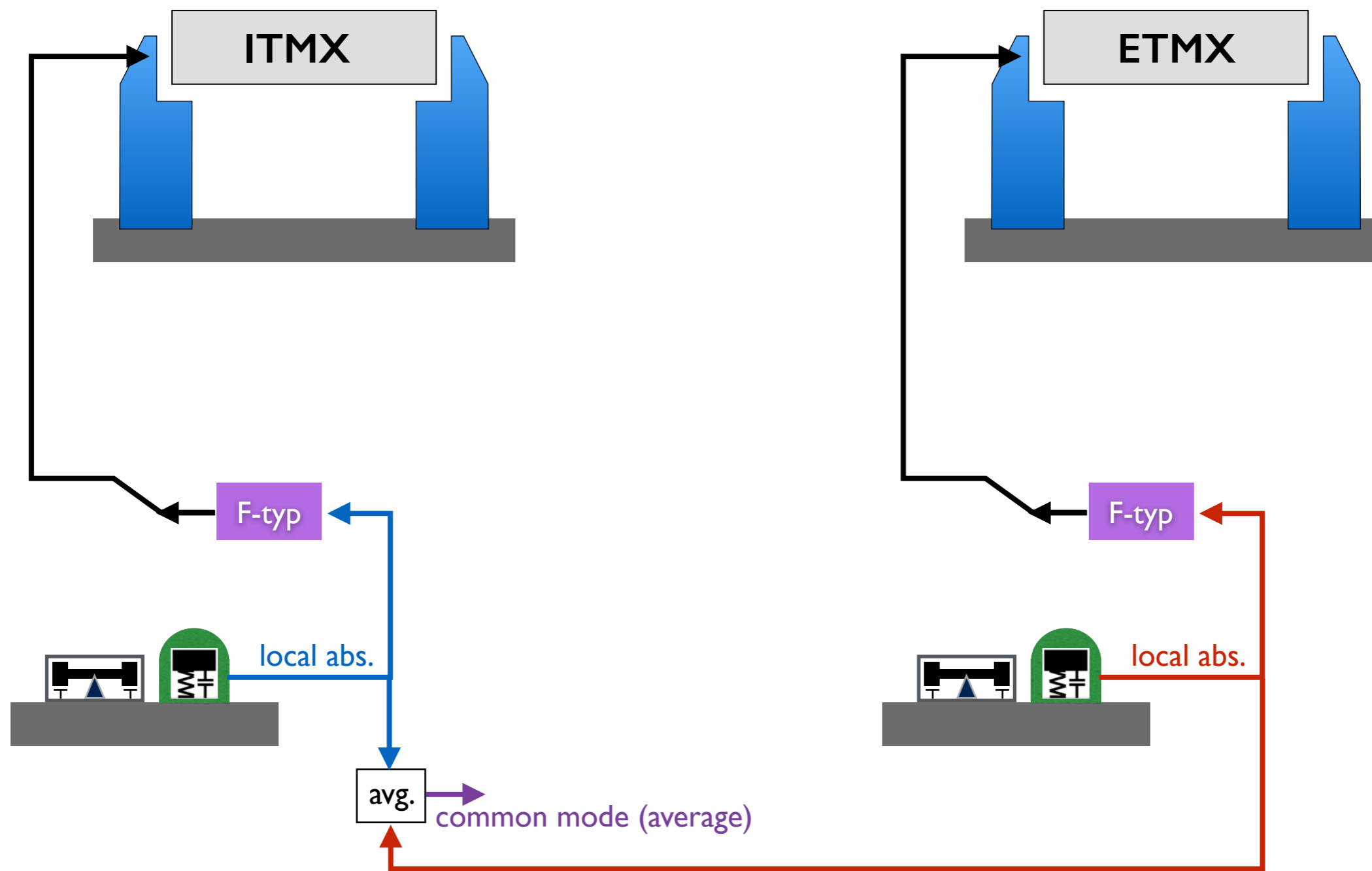




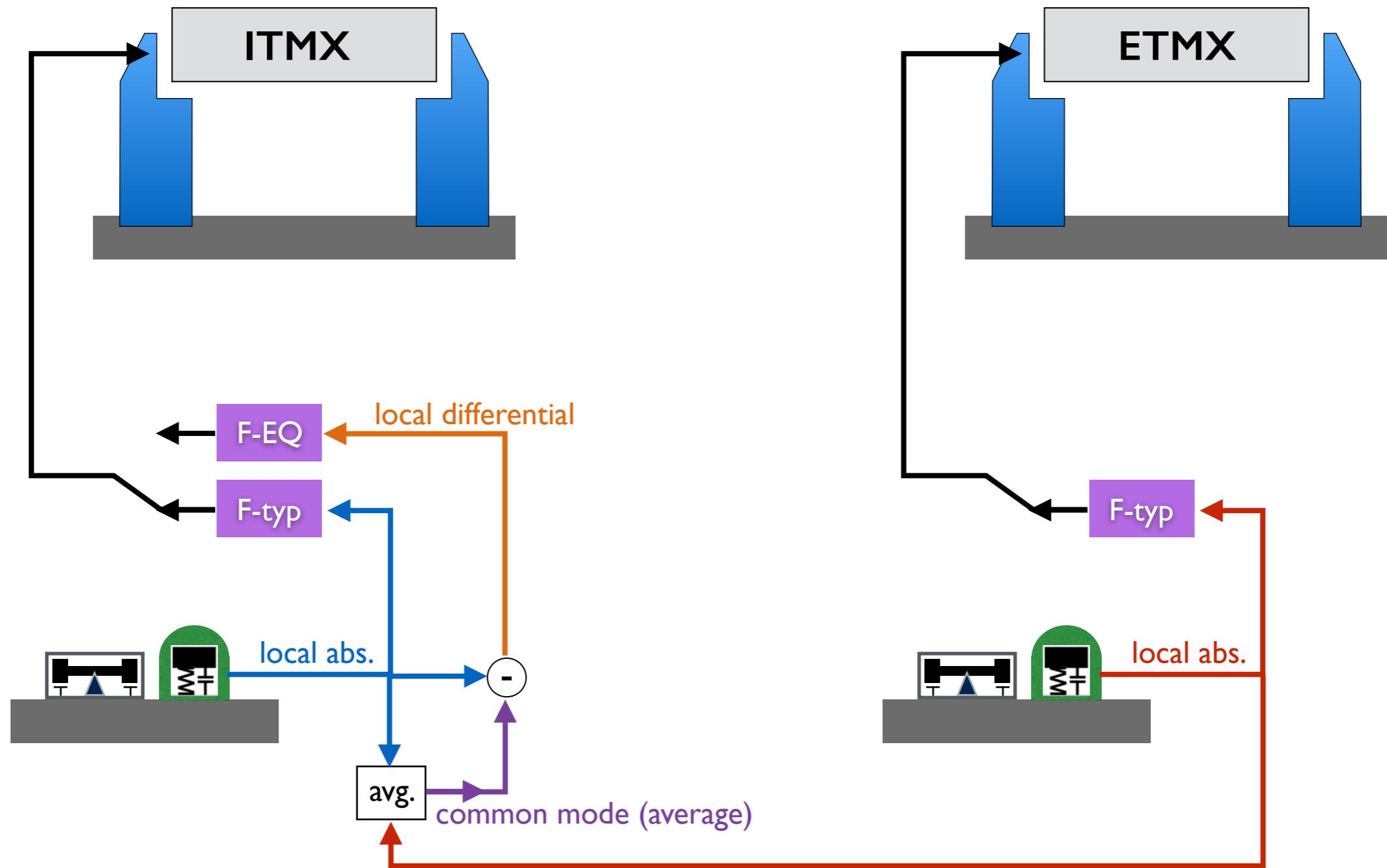
# Control schematic



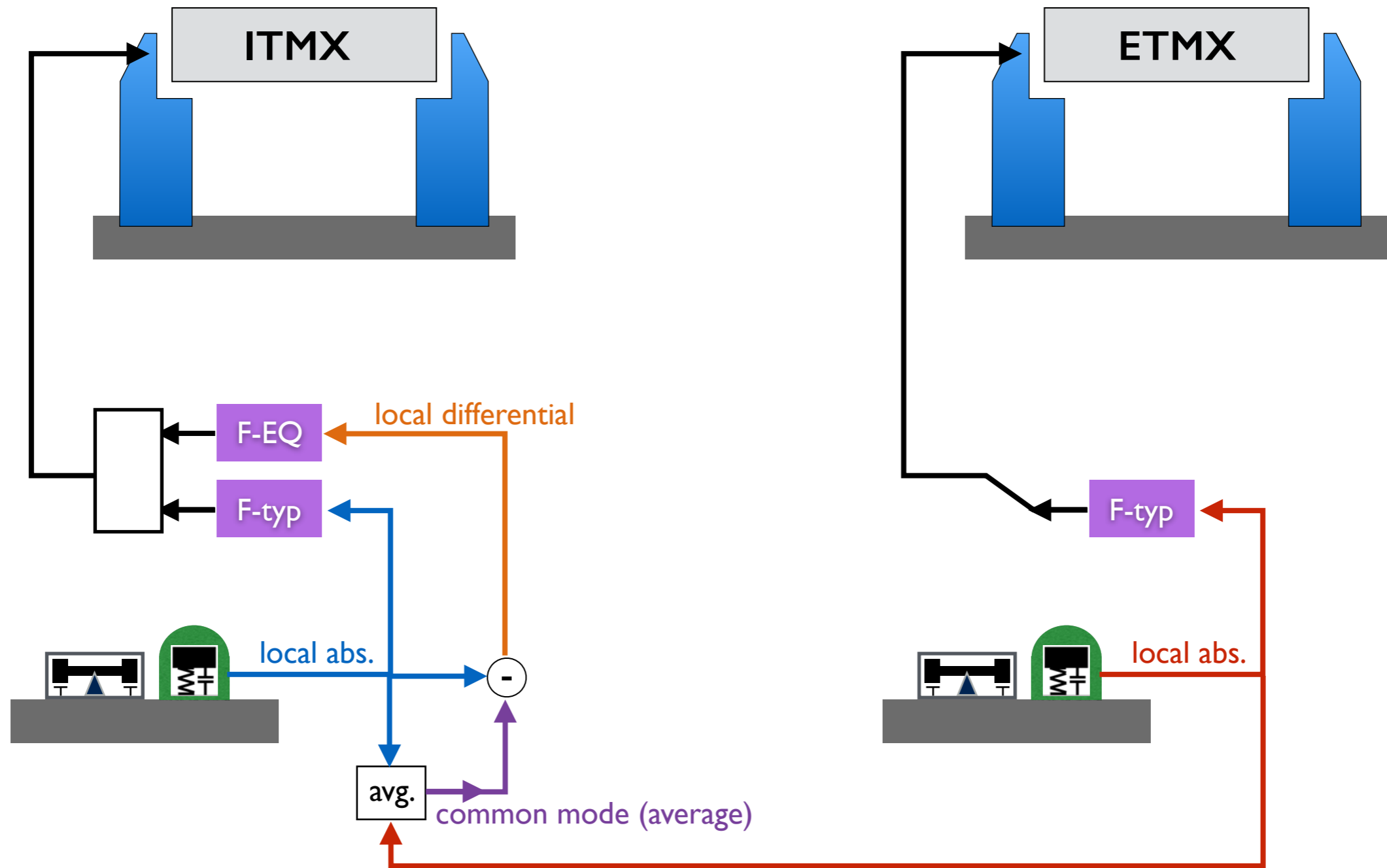
# Control schematic



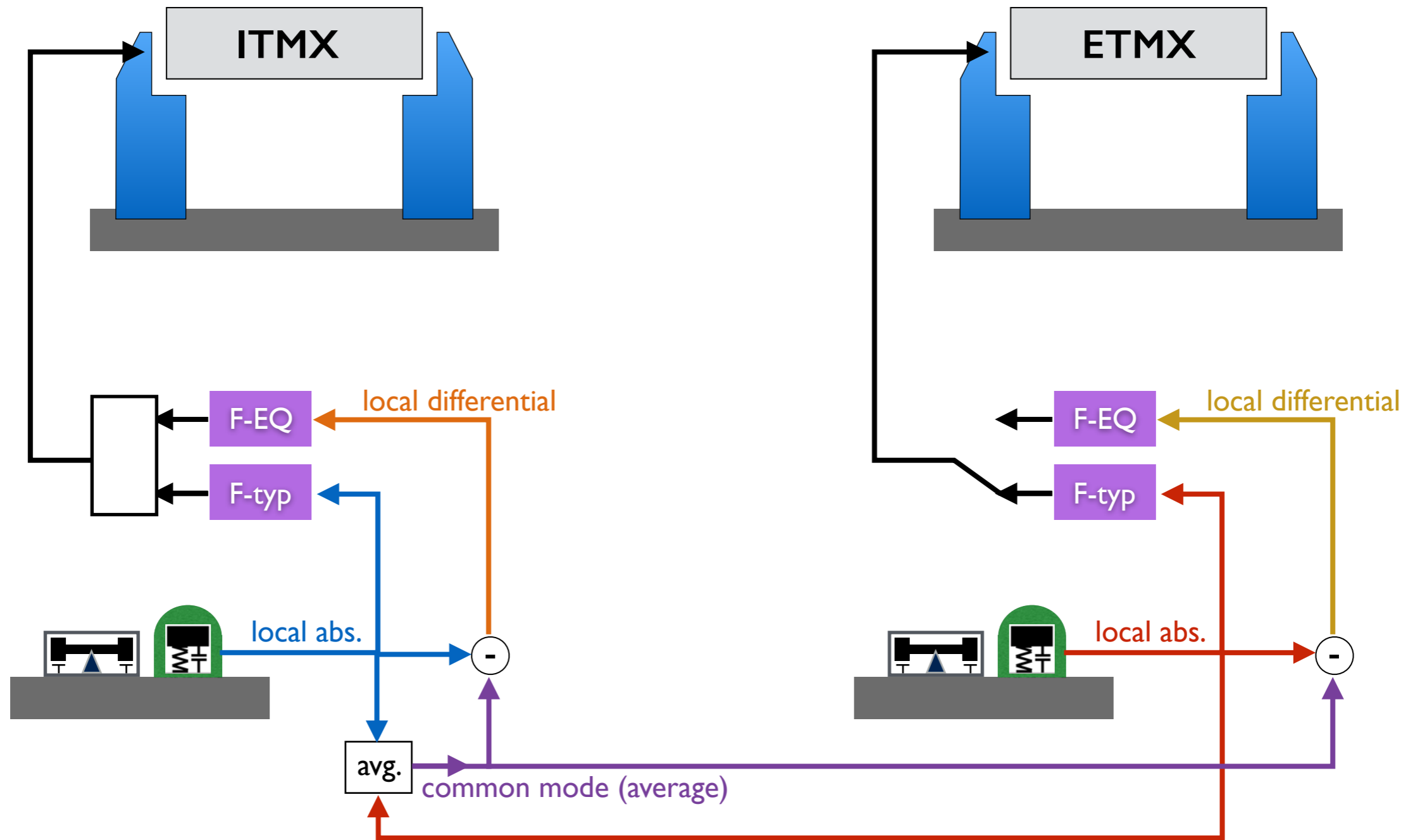
# Control schematic



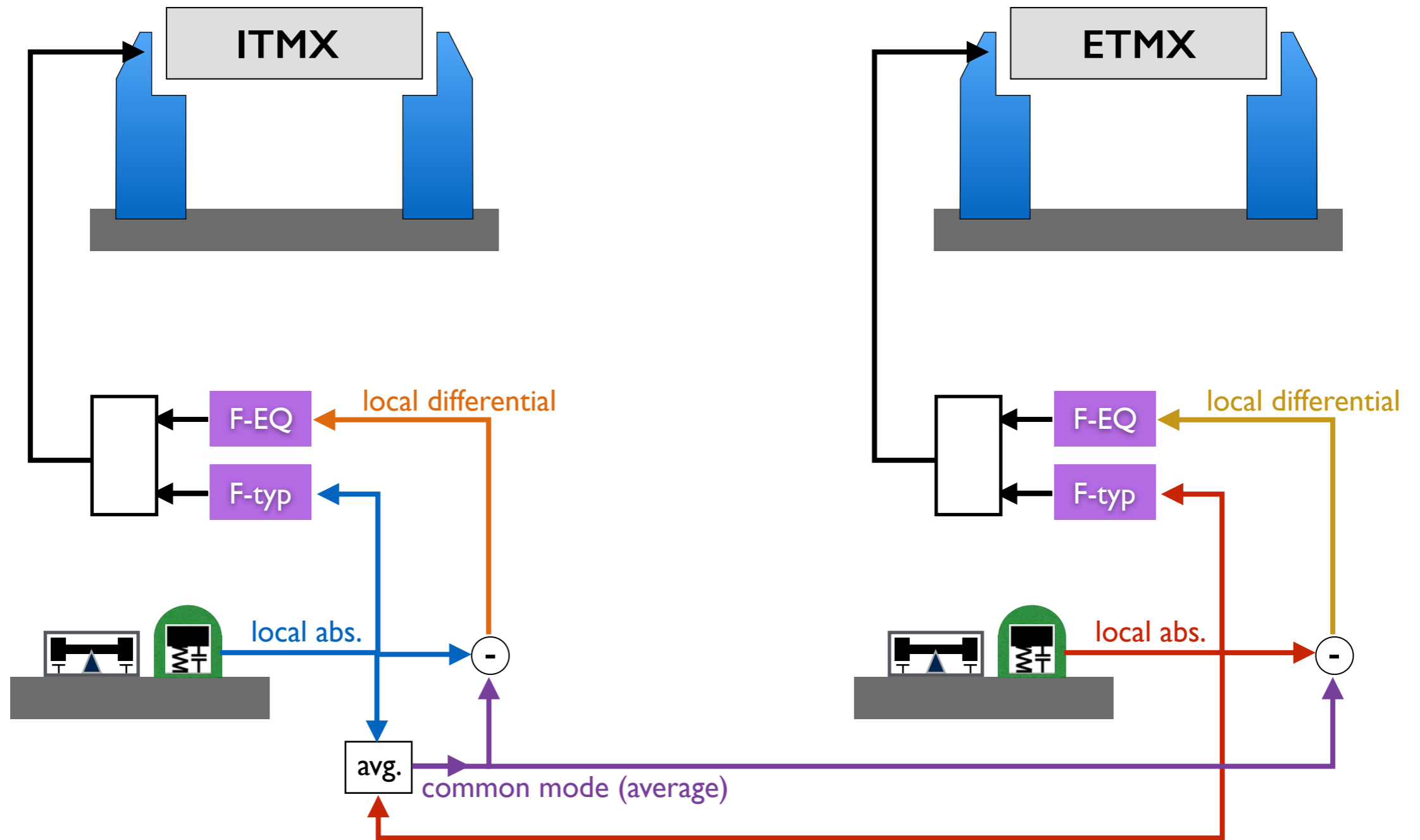
# Control schematic



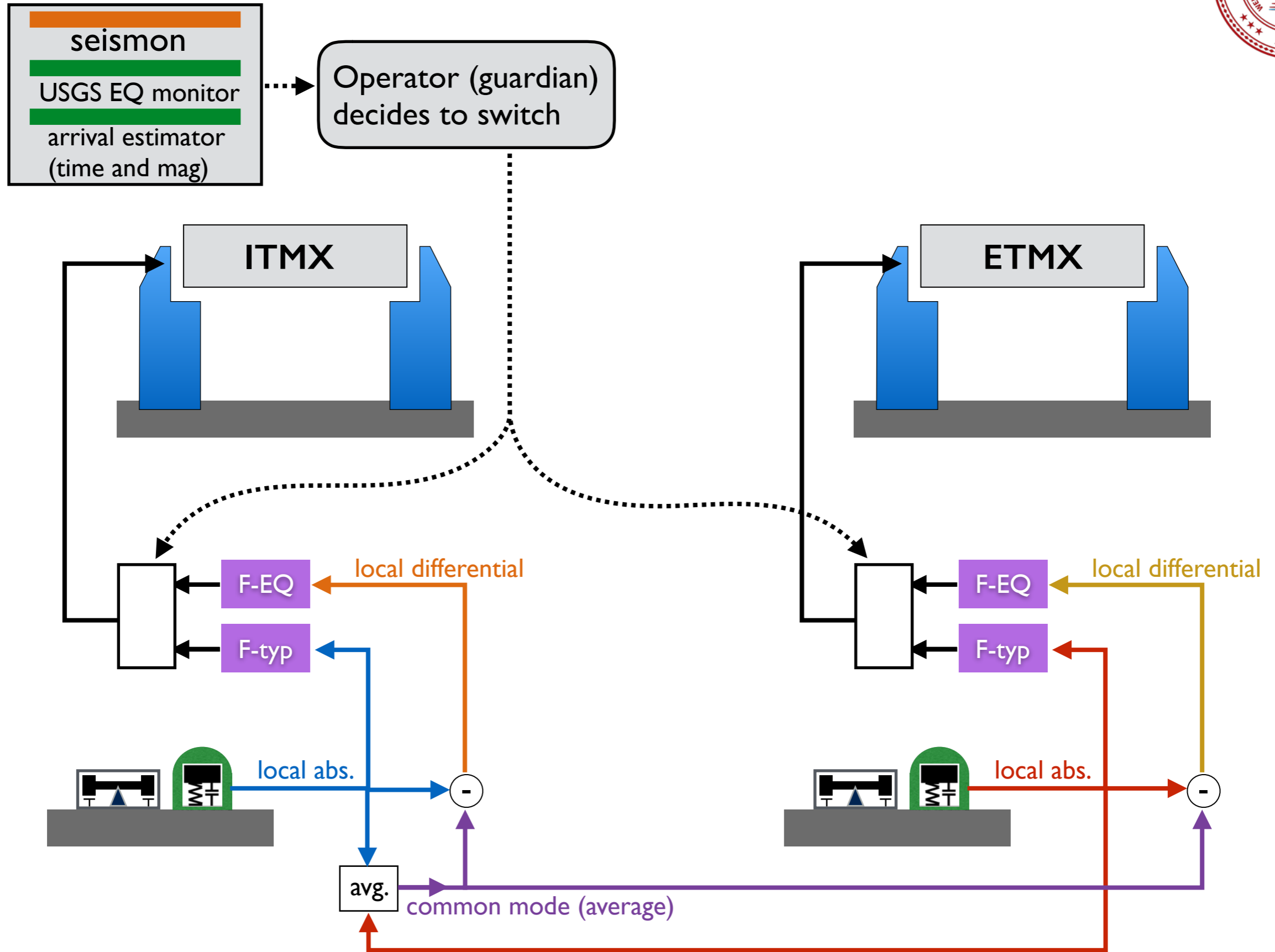
# Control schematic



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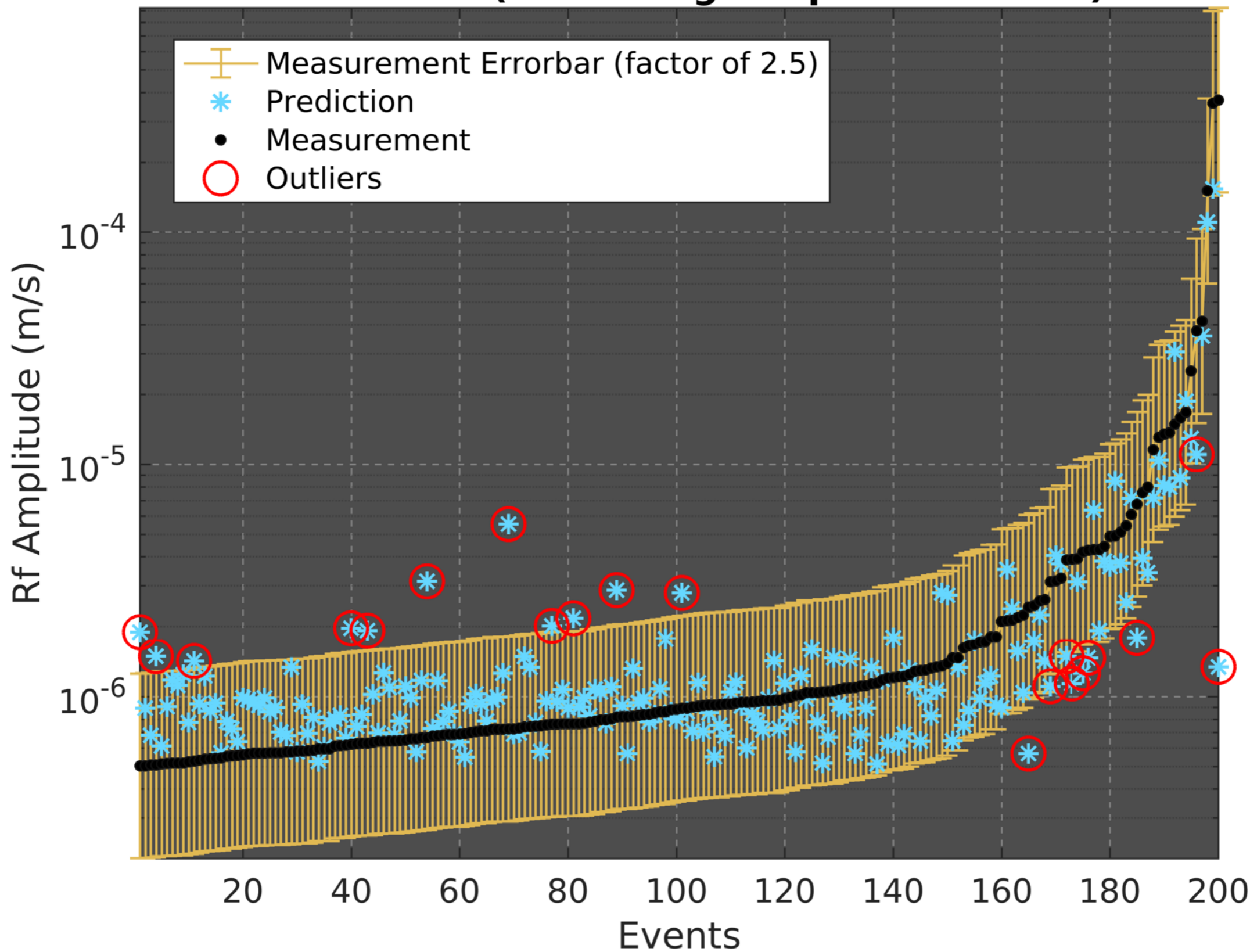


# Control schematic



# Nikhil amplitude updates

**LHO 01-02 (Percentage Captured: 90.00)**

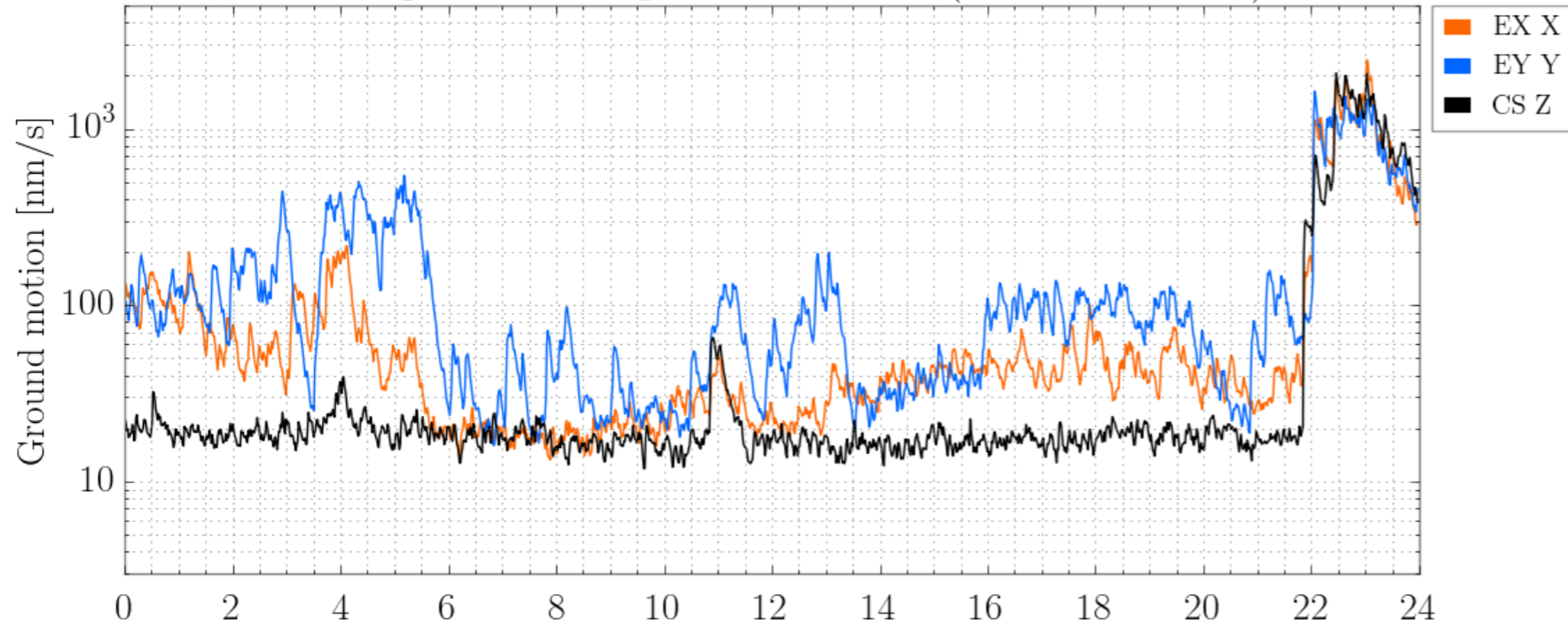




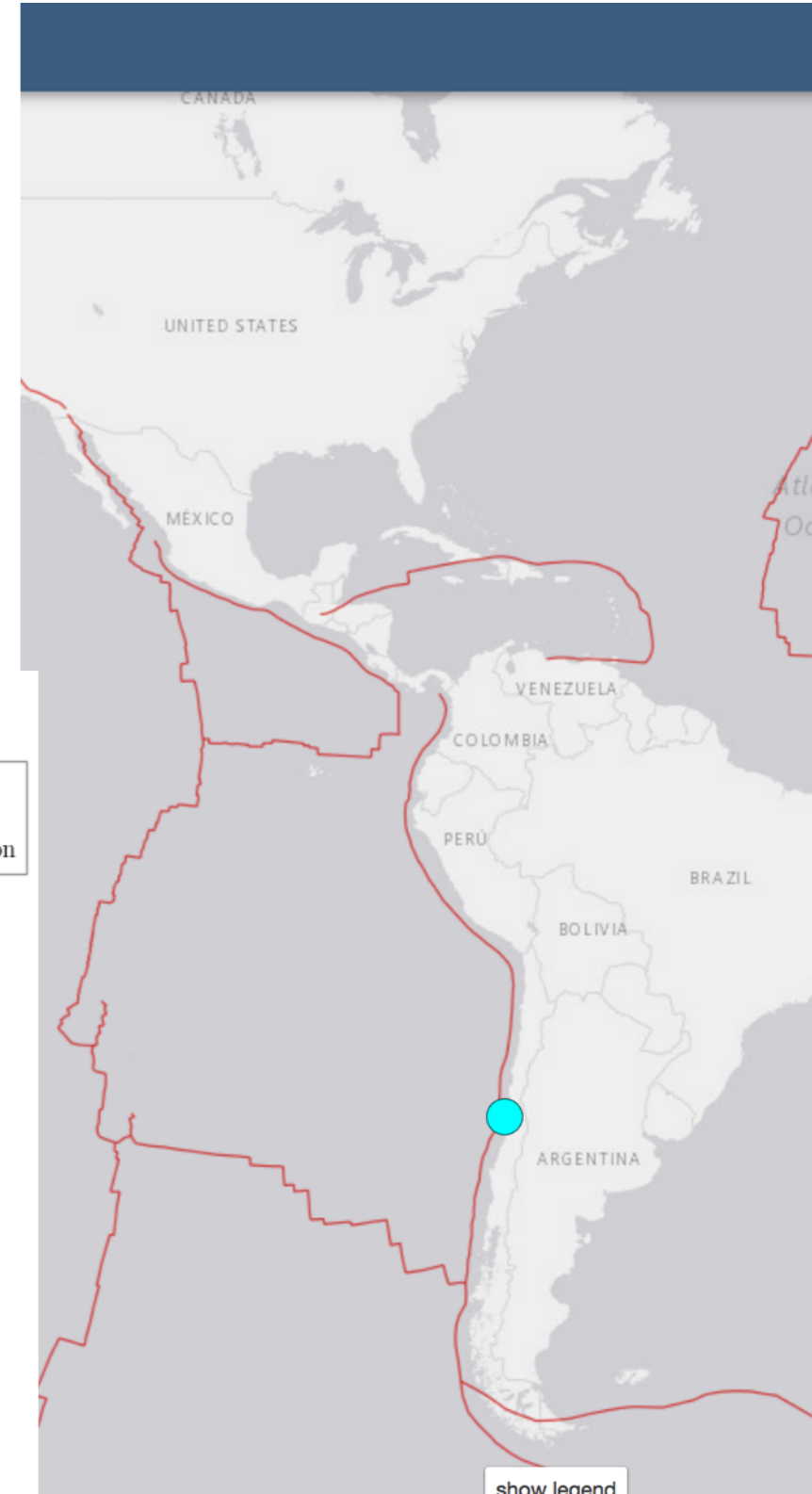
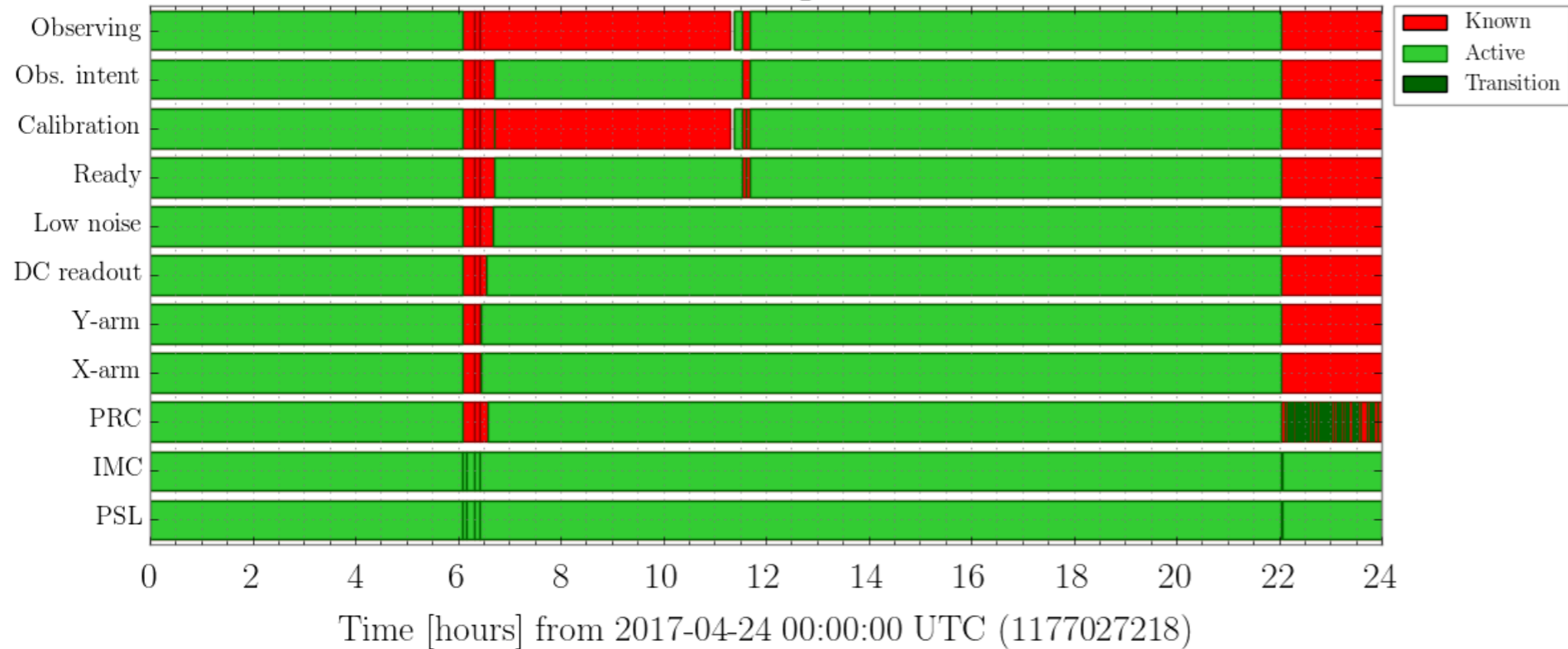
# Est. perf with a different event

## M6.9 Valparaiso

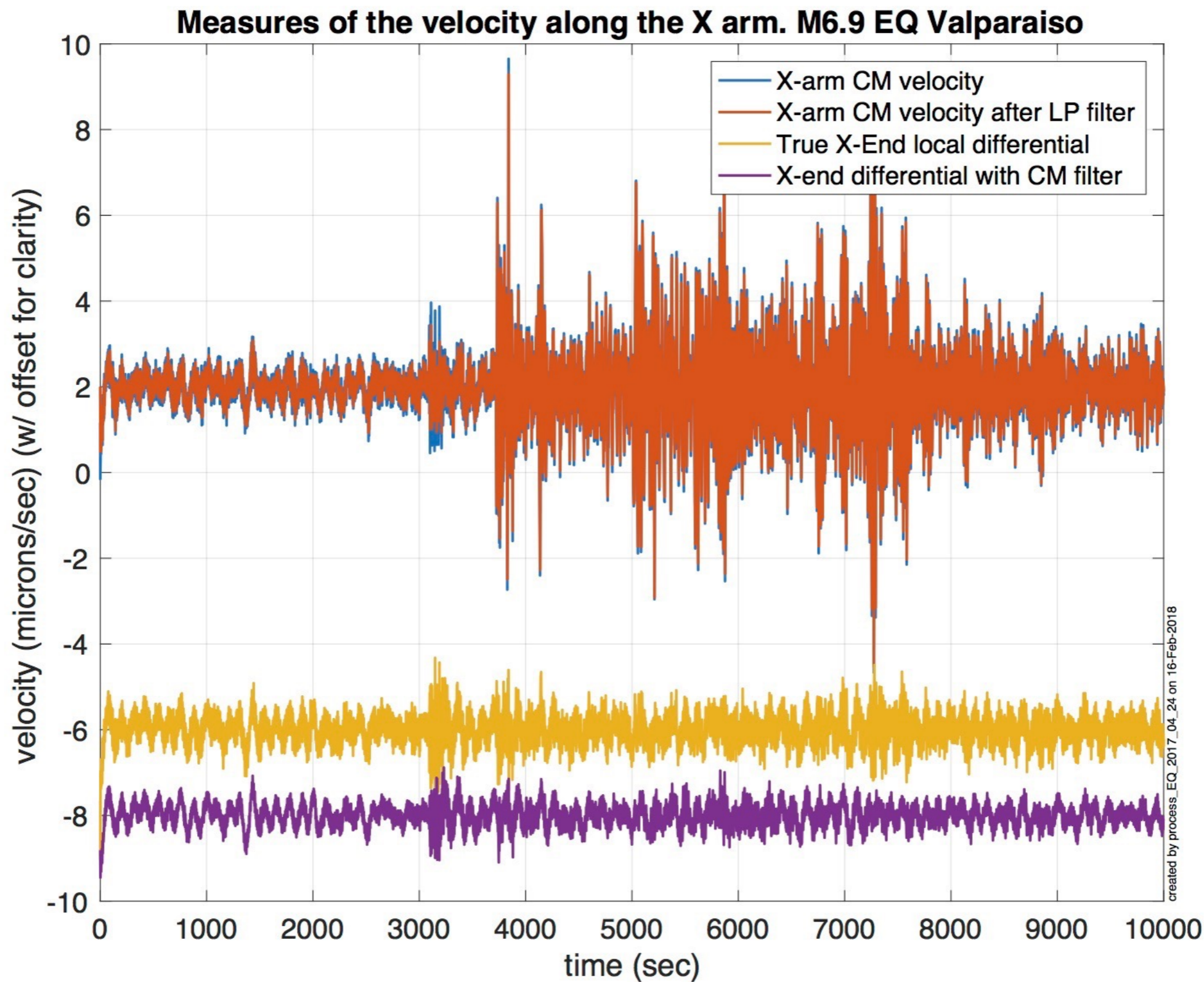
Earthquake band ground motion (0.03 Hz–0.1 Hz)



H1 lock segments

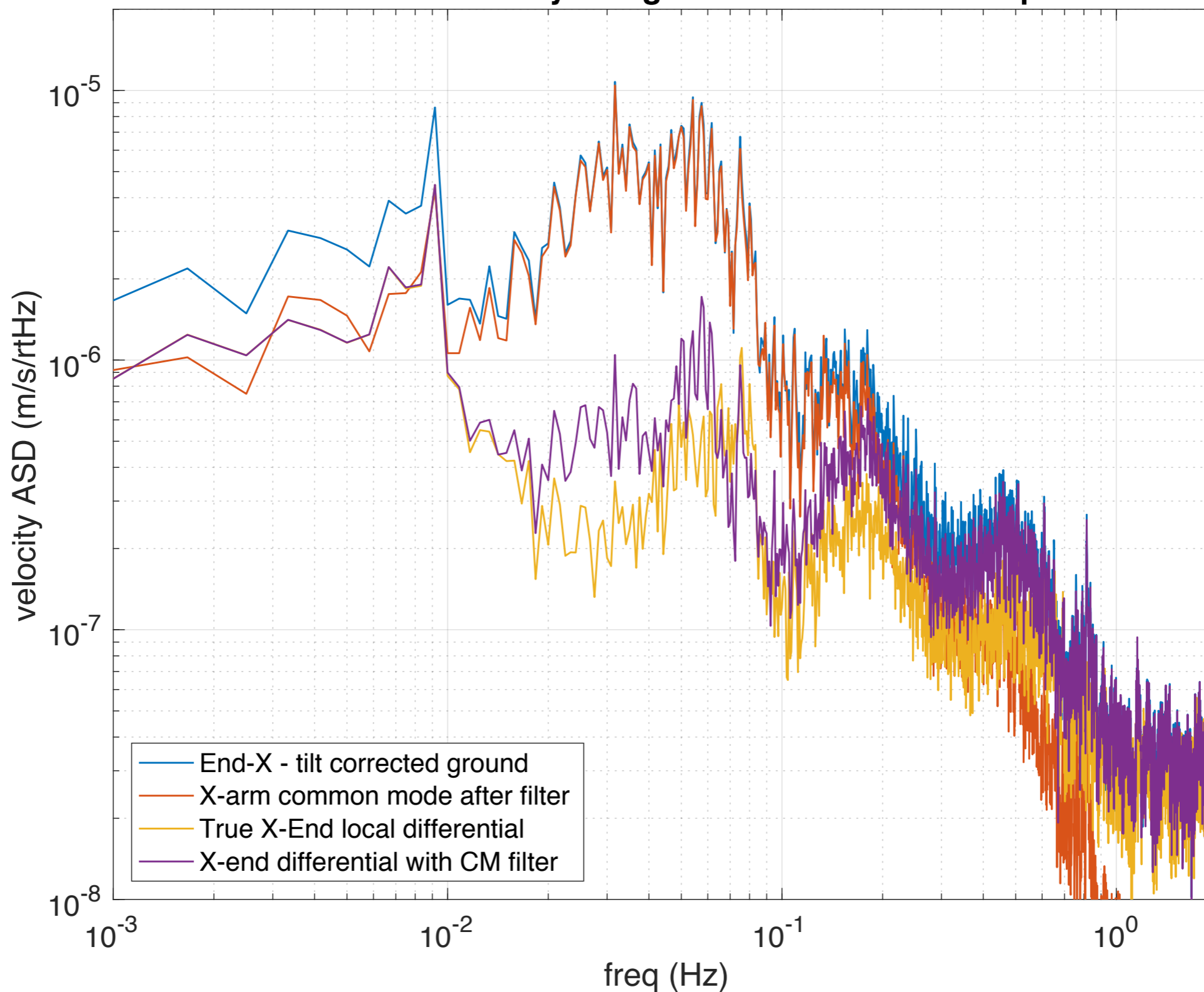


# EQ traces, M6.9 Valparaiso



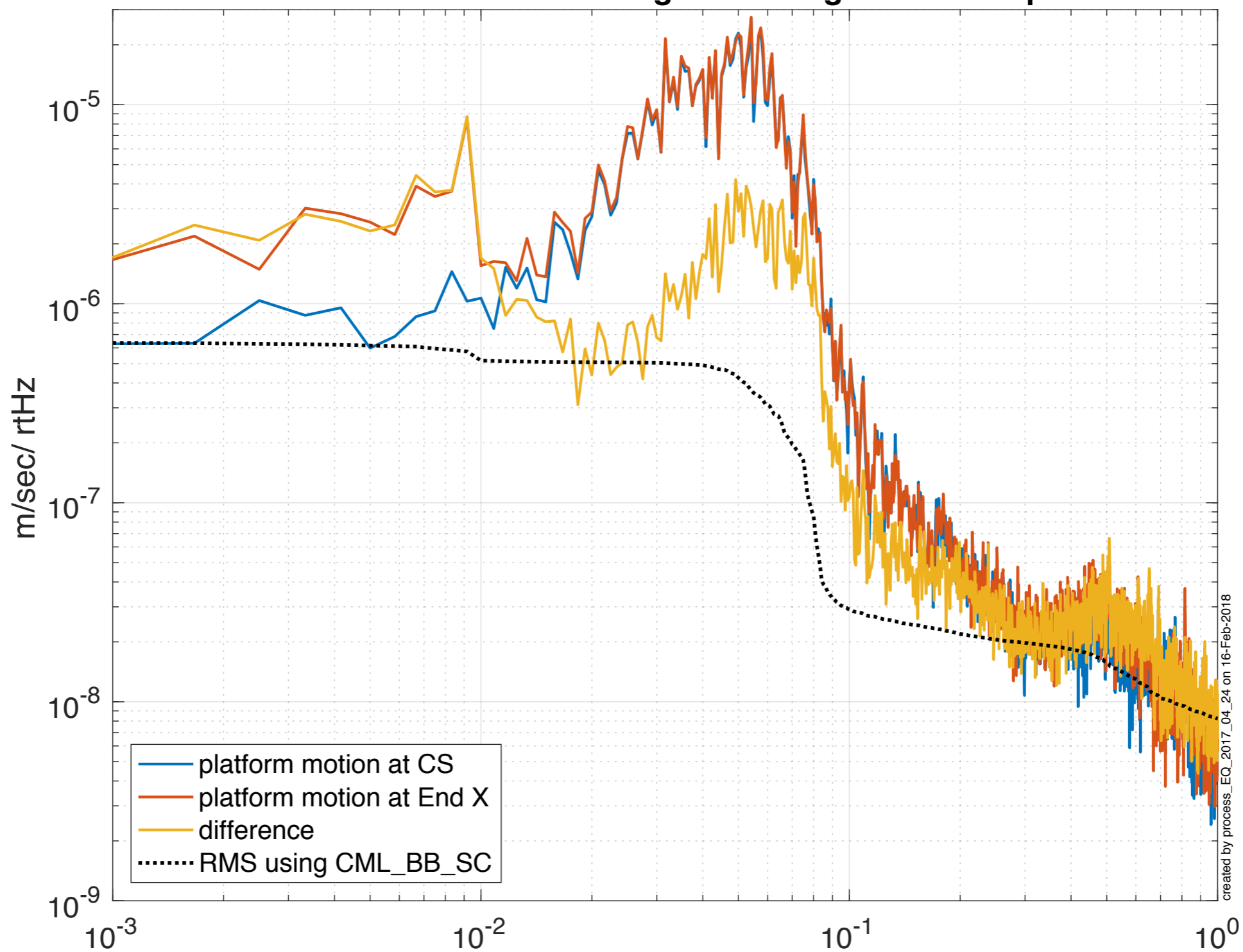
# EQ traces, M6.9 Valparaiso

Measures of the velocity along the X arm. M6.9 EQ Valparaiso



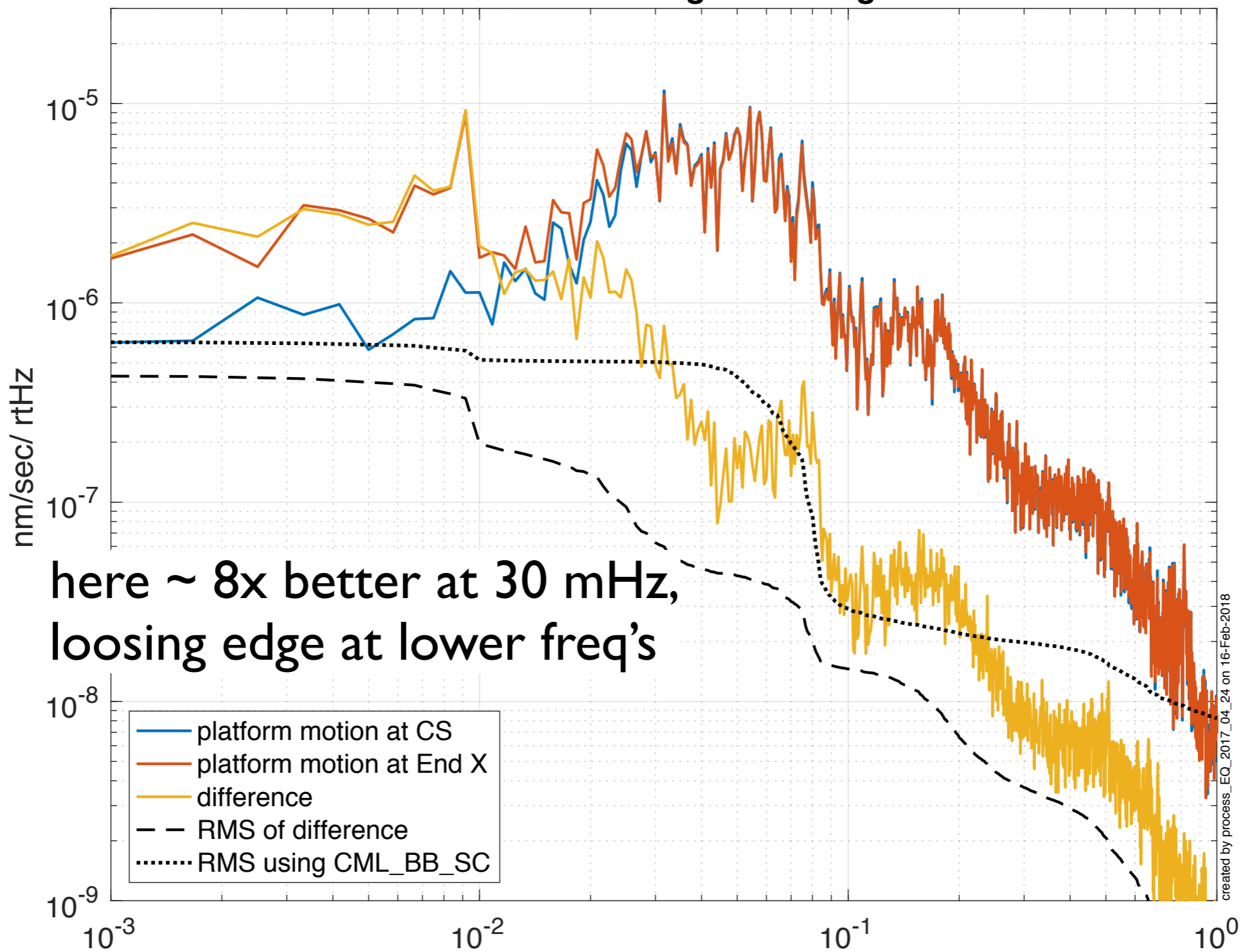
# Modeled perf. now

### Platform motion in X during EQ - using current SC plat



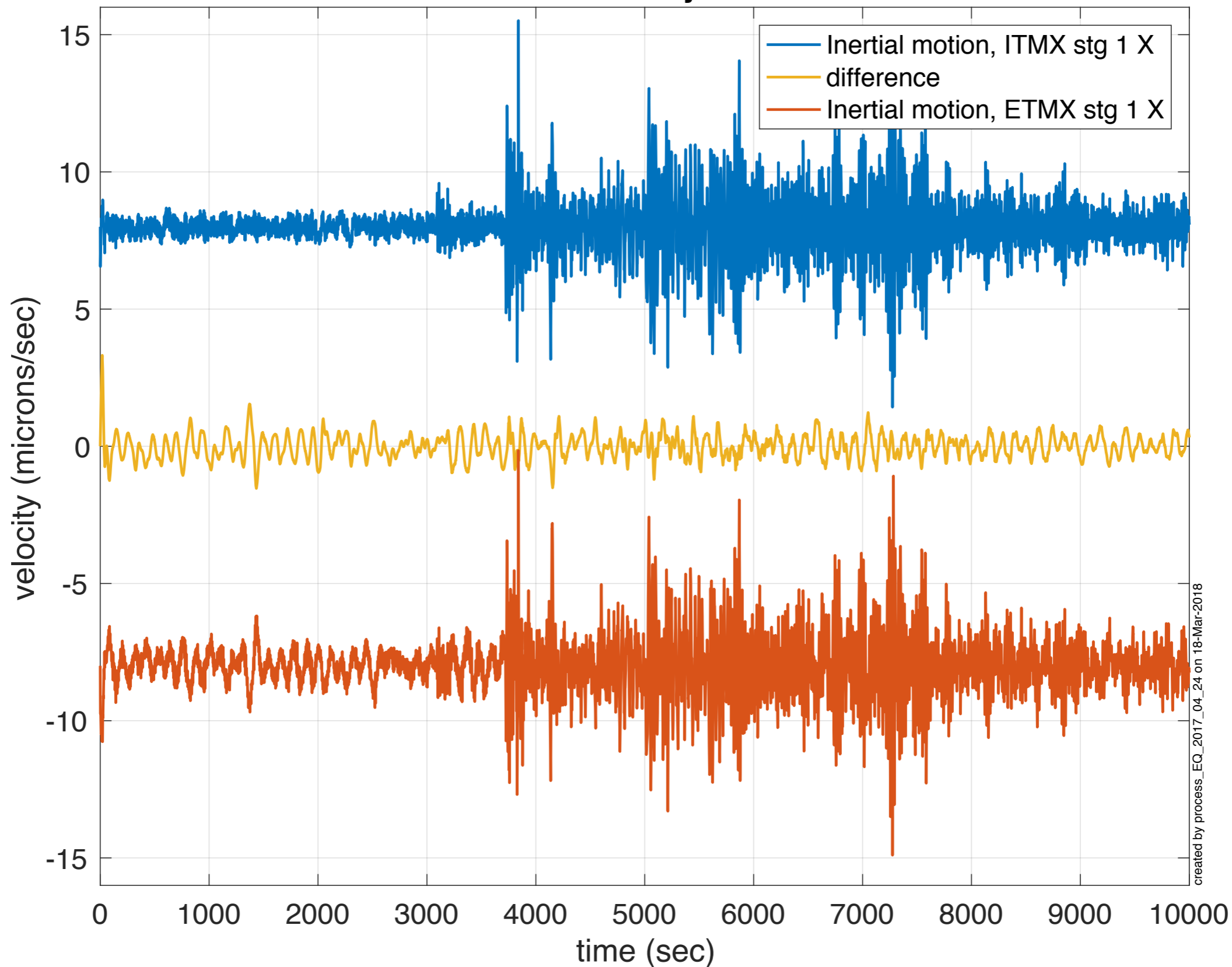
created by process\_EQ\_2017\_04\_24 on 16-Feb-2018

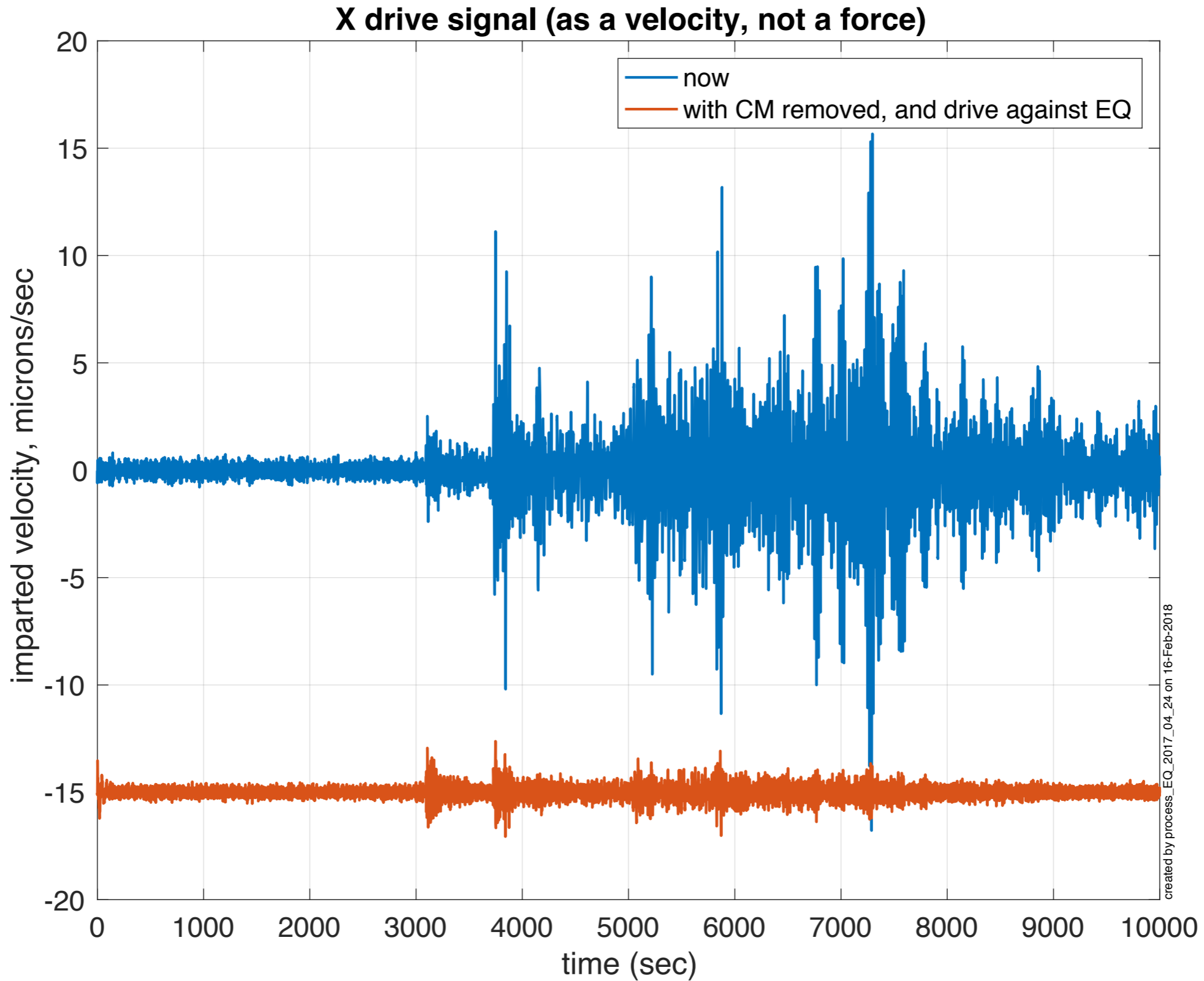
Platform motion in X during EQ - using EQ control



# Perf. looks odd in local basis

### Absolute vs. relative velocity with the Trial V1 filter

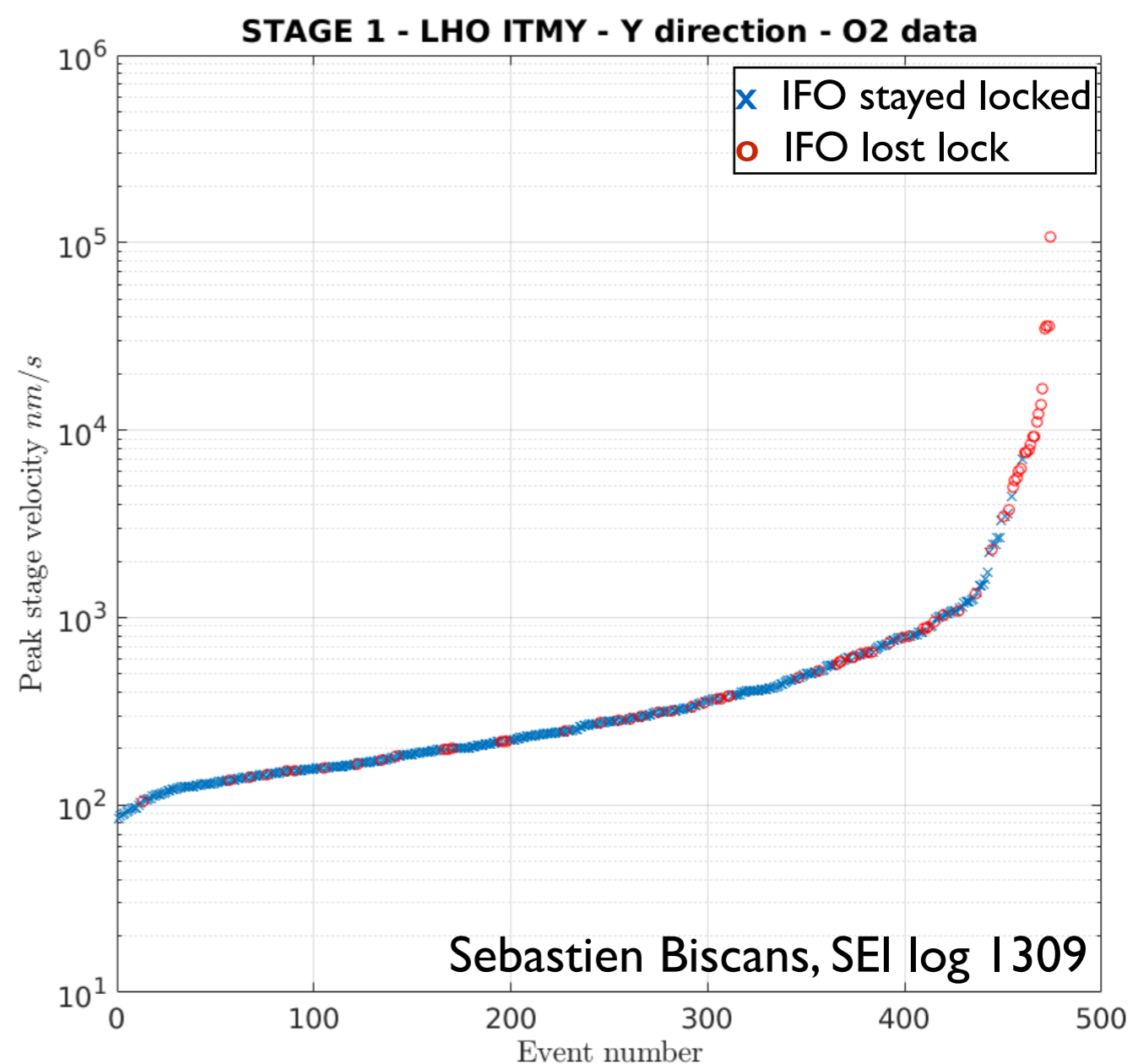
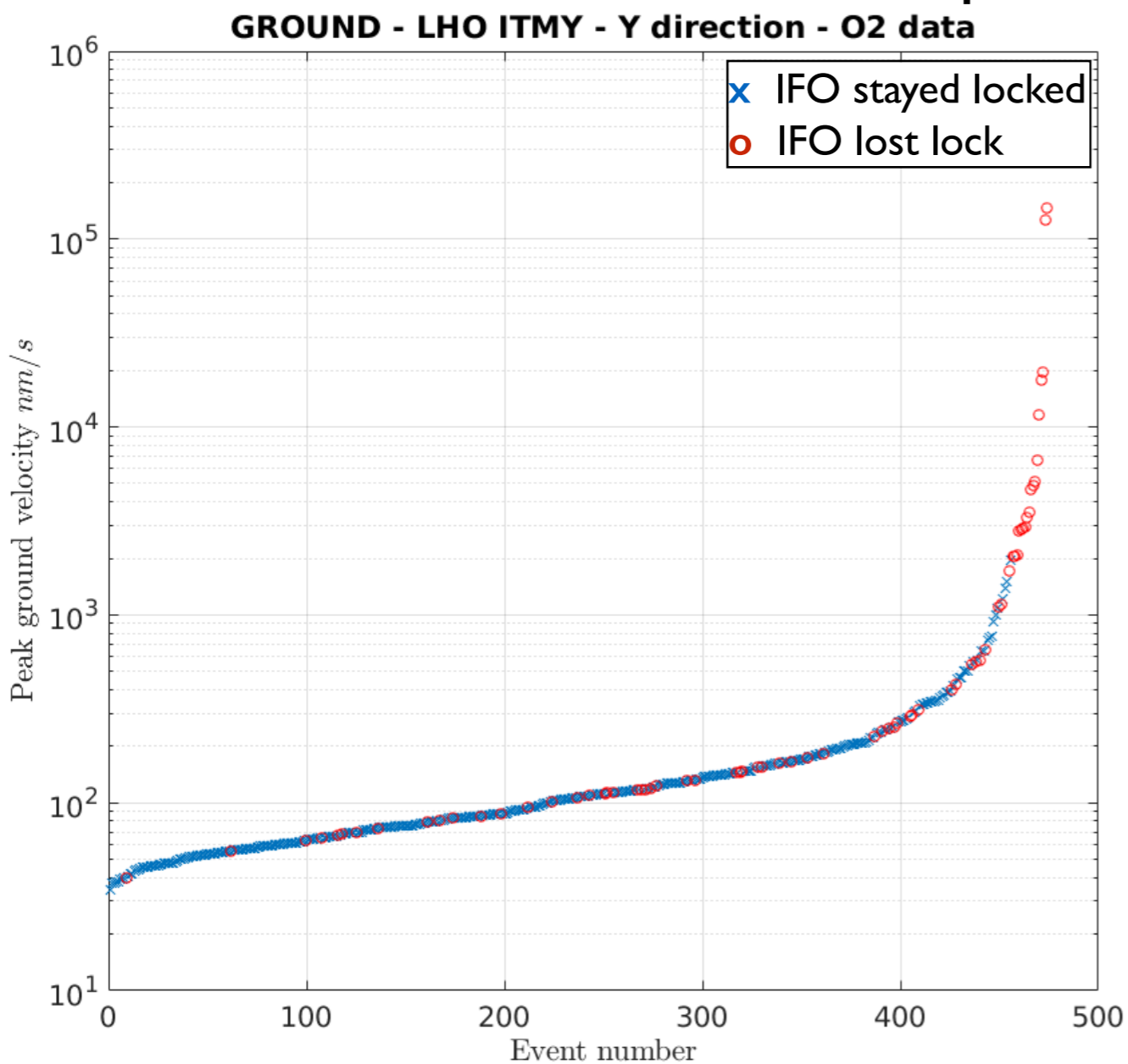




# Earthquake impact for O2

	IFO not lock at the time	IFO stayed lock	IFO lost lock	Total
Number of events	51	403	71	525

## O2 Earthquake statistics for LHO

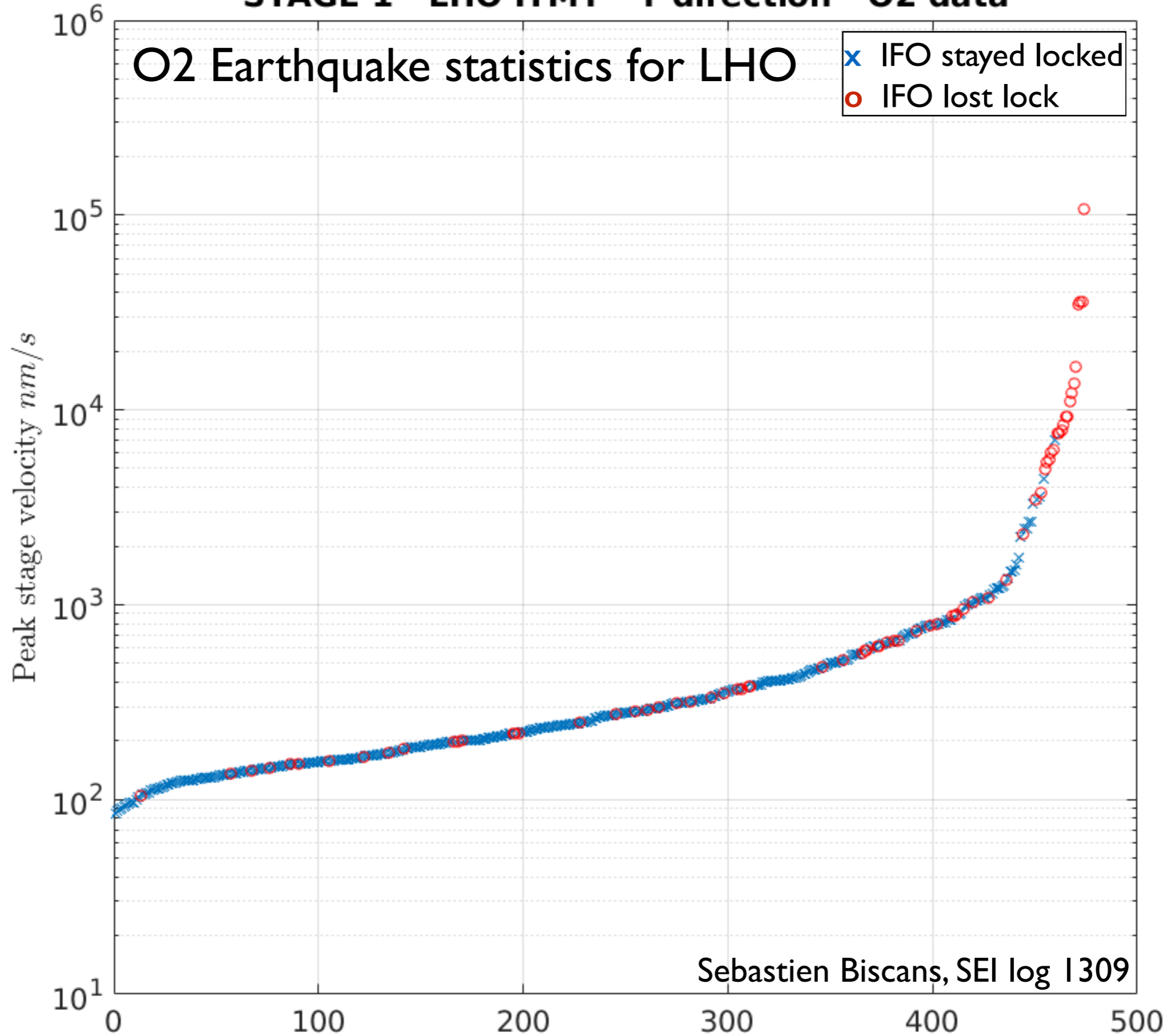


Sebastien Biscans, SEI log I309



# Potential for improvement

STAGE 1 - LHO ITMY - Y direction - O2 data



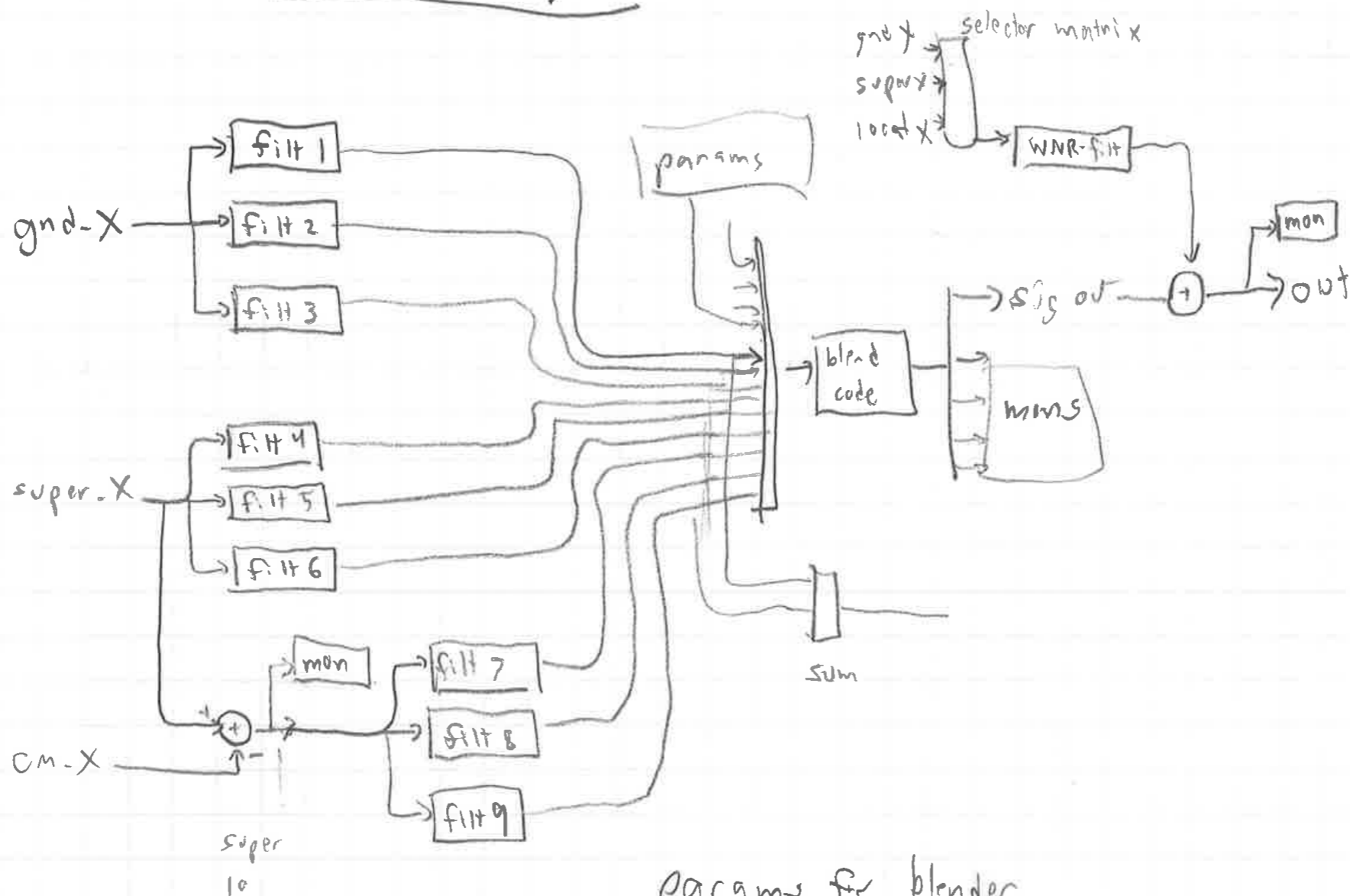
Sebastien Biscans, SEI log 1309

# Final thoughts



- We should be able to significantly improve robustness against Earthquakes.
- Part the benefit comes from having new tools (BRS, Seismon)
- Part of the benefit comes from changing the control flow/ isolation performance during observing time based on changing environmental conditions.
- Part of the benefit comes from controlling the seismic system in a non-local way, controlling relative motion instead of controlling the absolute motion.
- Implementation should be complete at LHO by ~~April~~ May.

# Sensor - X



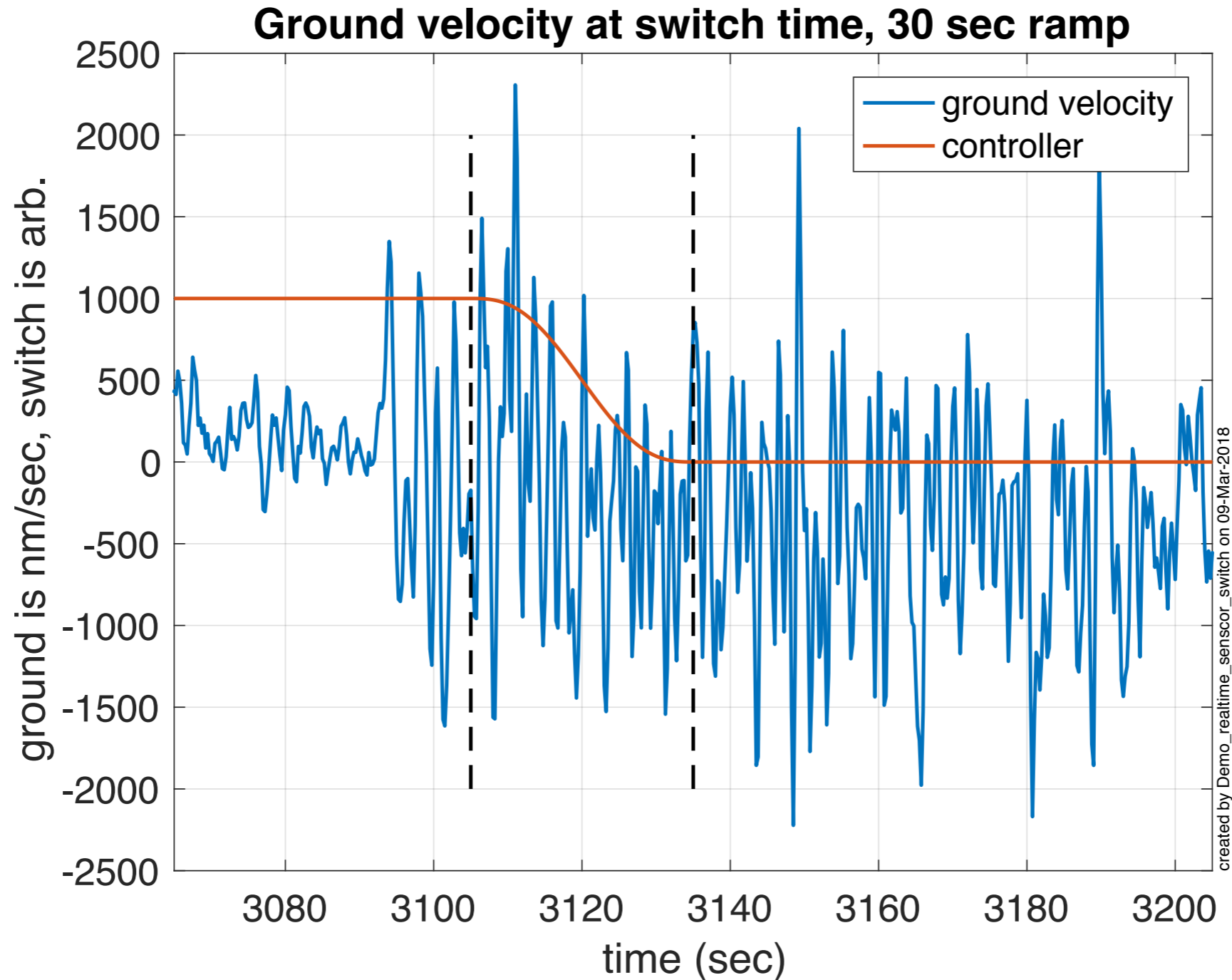
## params for blender

- startup\_channel → epics #
- next\_channel → epics #
- blend\_time → epics #
- start now → epics momentary
- jump to end → epics momentary

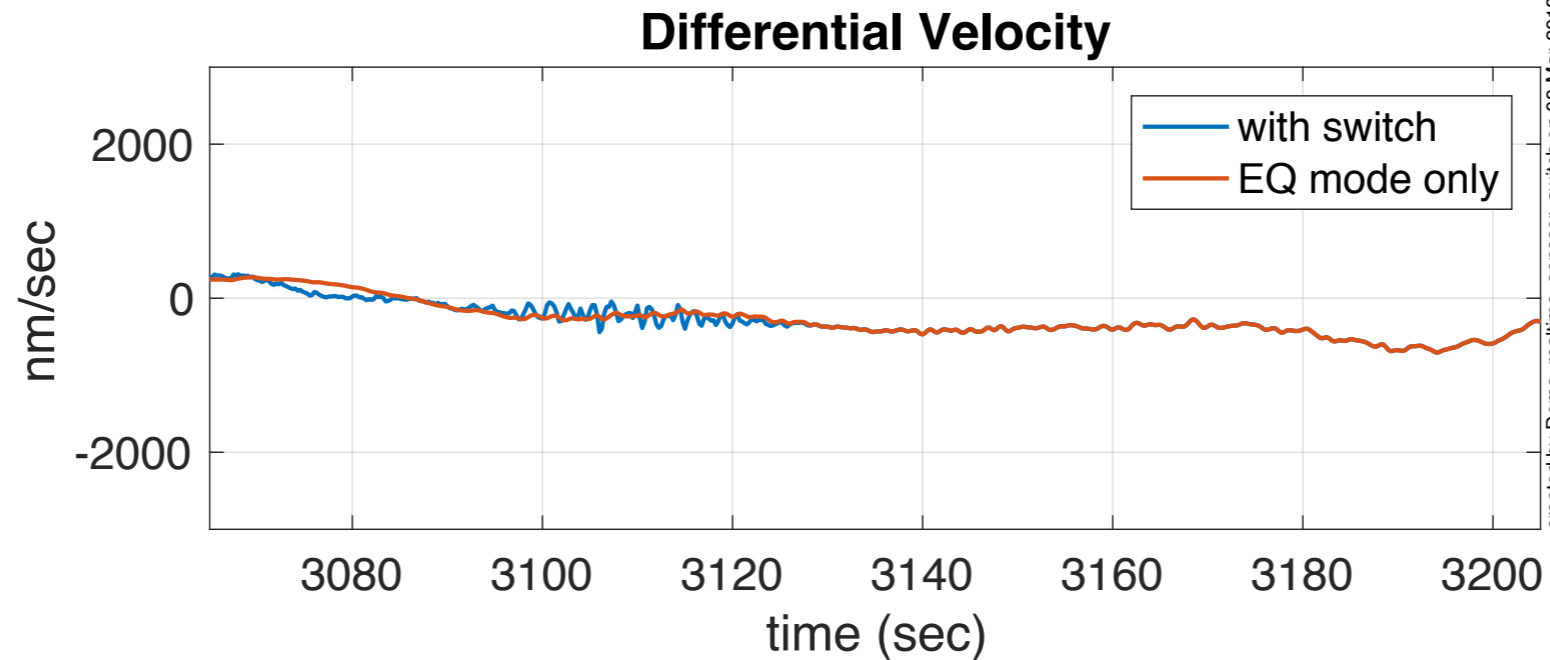
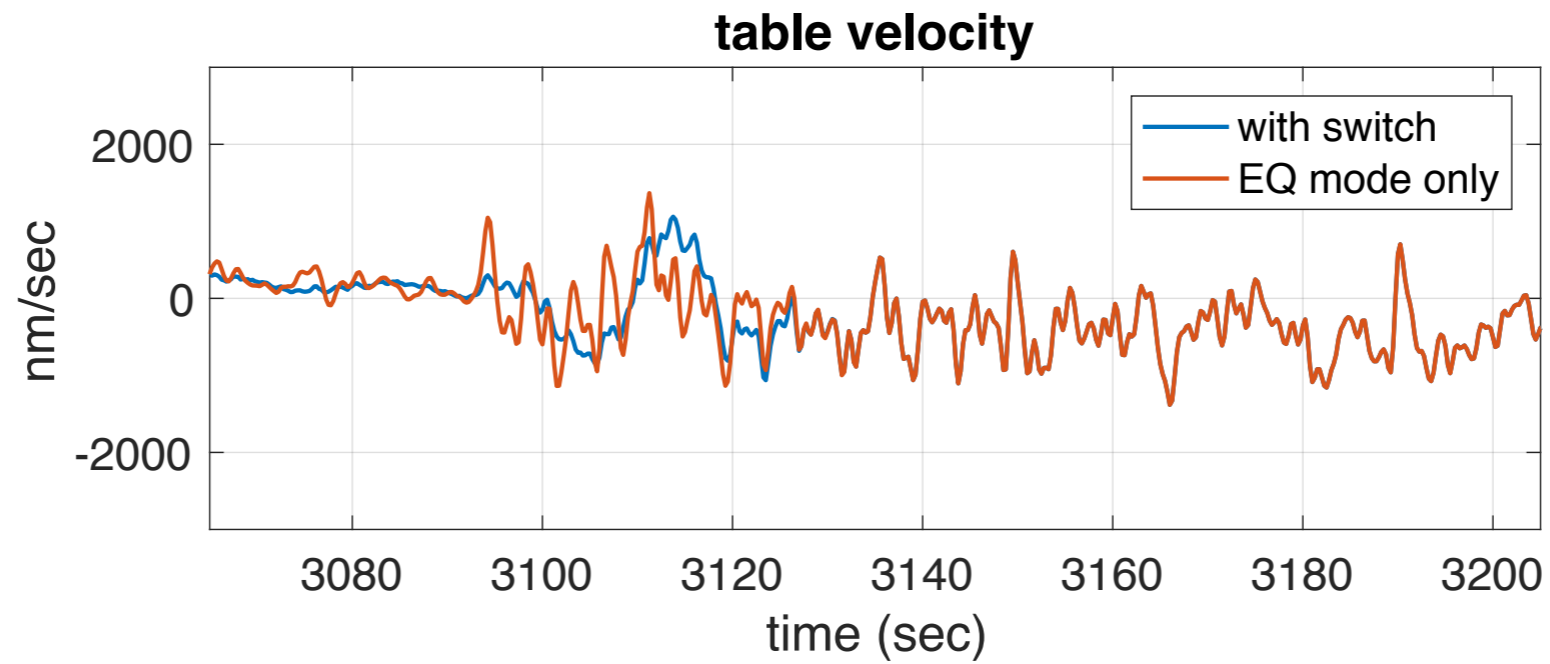
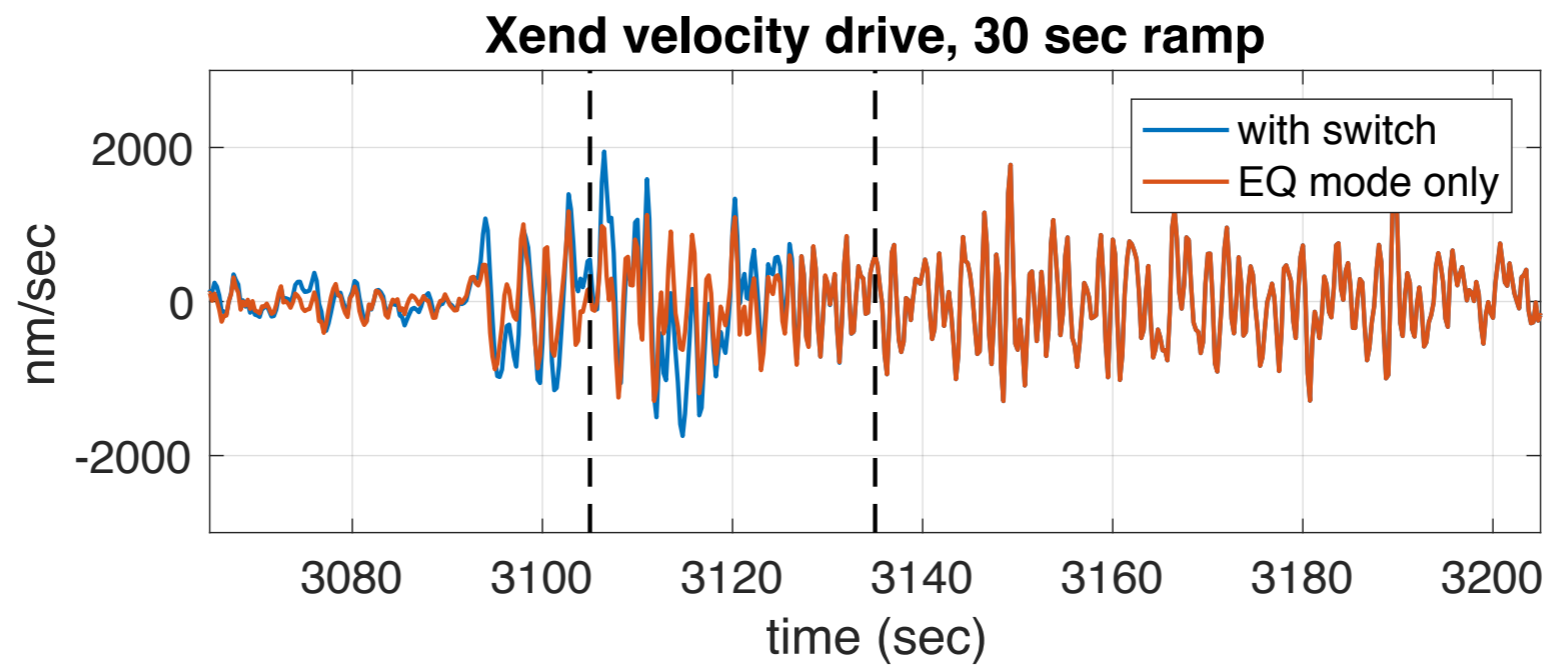
how many filter banks?

# Mode-switch transients

What happens if you switch control modes late, and the EQ has already arrived?

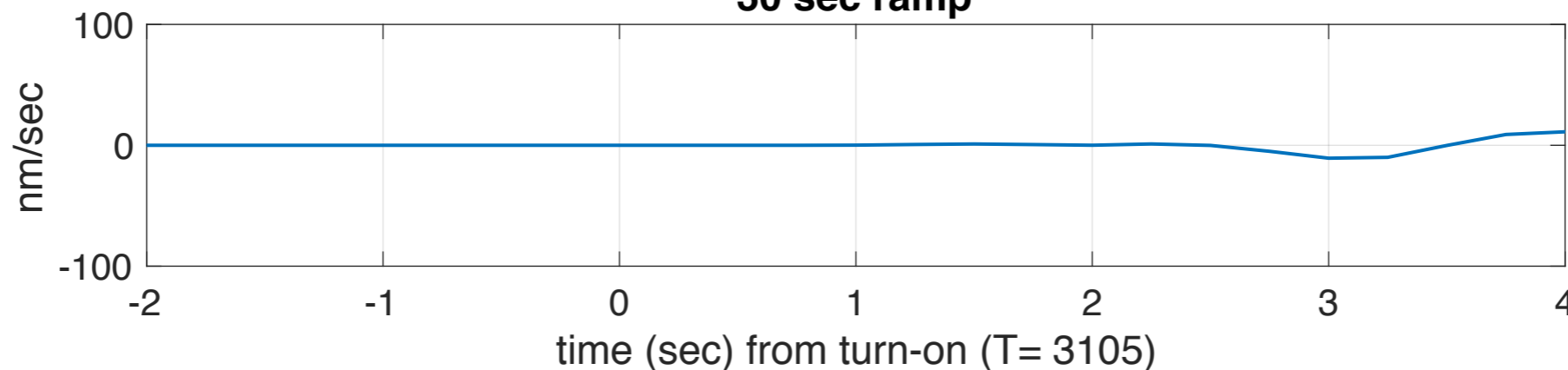


# Mode-switch transients

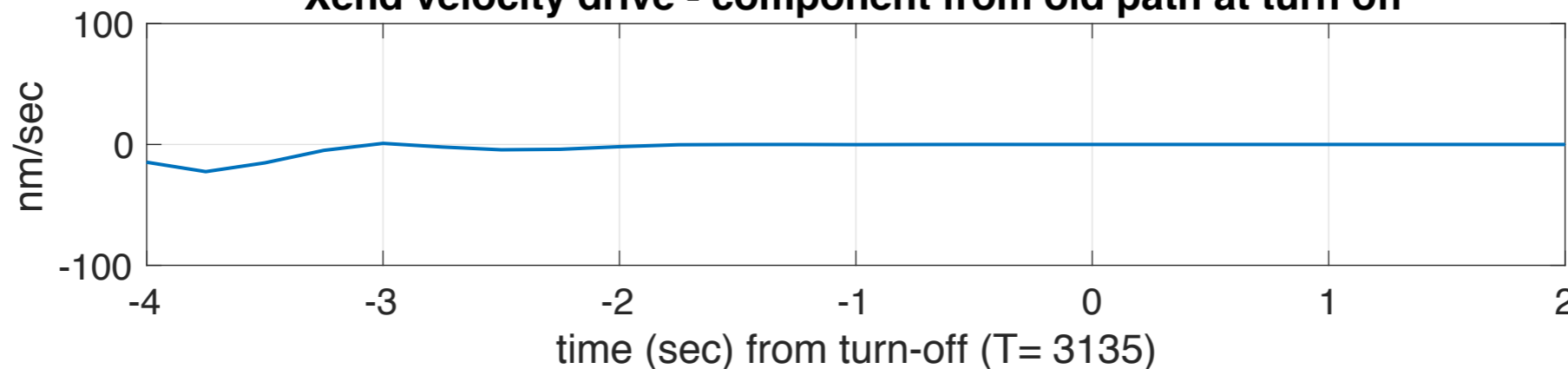


# mode switch transients

**Xend velocity drive - component from new path at turn on  
30 sec ramp**



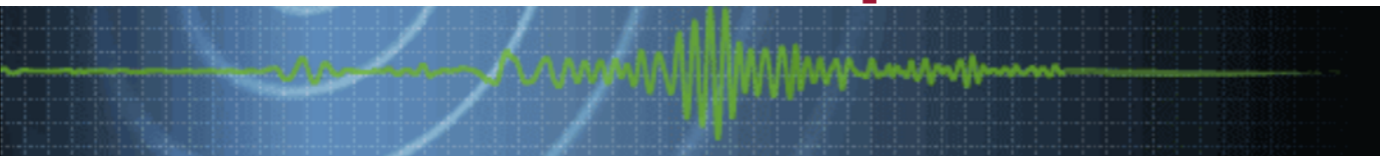
**Xend velocity drive - component from old path at turn off**



created by Demo\_realtime\_sensor\_switch on 09-Mar-2018



# Nikhil amplitude updates



## Earthquake Hazards Program

← Earthquakes

### Earthquake Statistics

- Latest Earthquakes
- Earthquake Lists, Maps & Statistics
- Search Earthquake Catalog
- Real-time Notifications, Feeds & Web Services
- Information by Region
- ANSS ComCat Documentation
- Errata for Latest Earthquakes

#### Worldwide Earthquakes 2000–2016

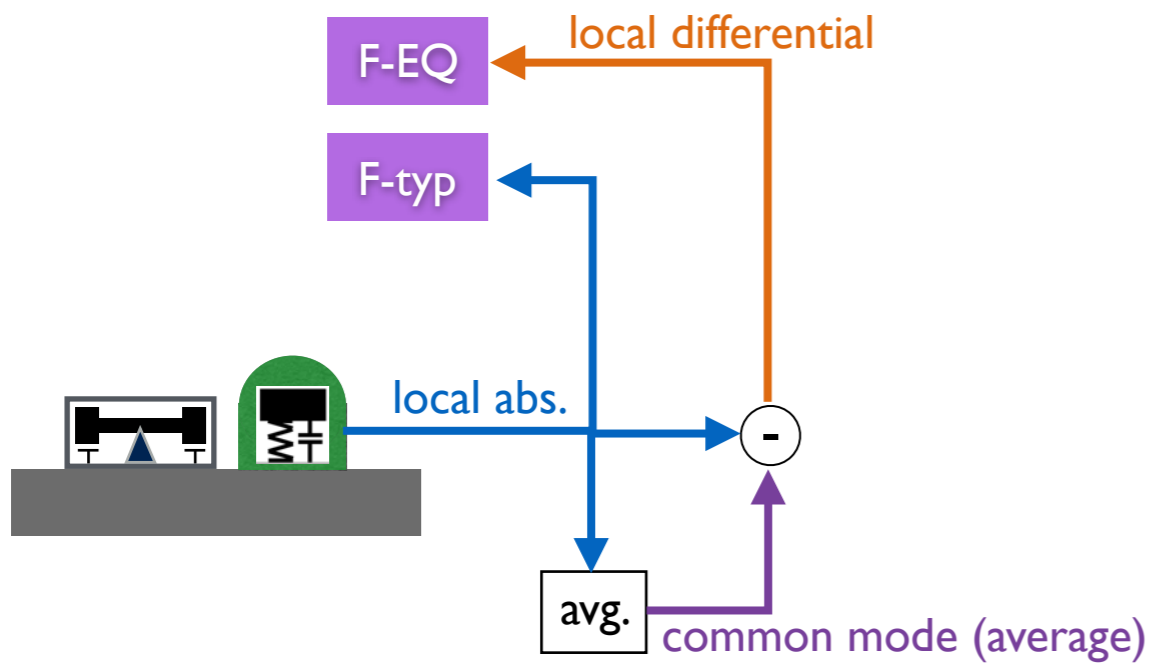
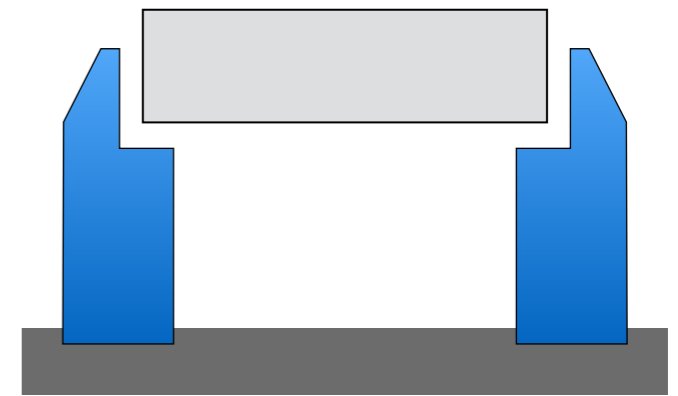
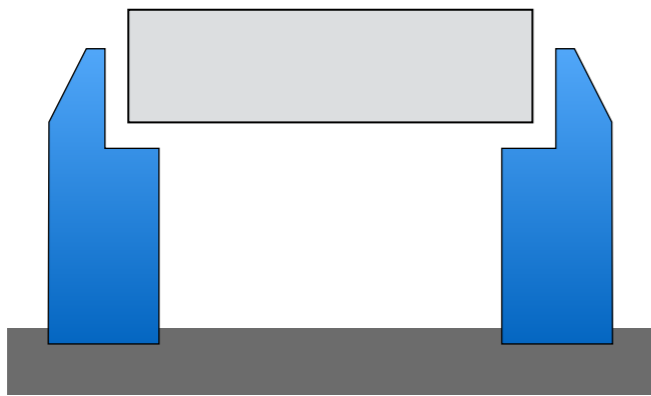
td>6

Magnitude	2000	2001	2002	2003	2004	2005	2006	2007	2008	2009	2010	2011	2012	2013	2014	2015	2016	2017
8.0+	1	1	0	1	2	1	2	4	0	1	1	1	2	2	1	1	0	1
7-7.9	14	15	13	14	14	10	9	14	12	16	23	19	12	17	11	18	16	
6-6.9	146	121	127	140	141	140	142	178	168	144	150	185	108	123	143	127	130	104
5-5.9	1344	1224	1201	1203	1515	1693	1712	2074	1768	1896	2209	2276	1401	1453	1574	1419	1550	1455
Estimated Deaths	231	21357	1685	33819	298101	87992	6605	708	88708	1790	226050	21942	689	1572	756	9624		

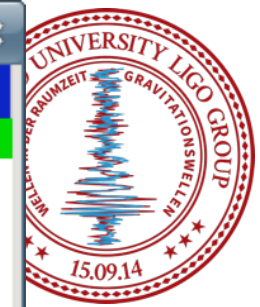
#### United States Earthquakes 2000–2012

Magnitude	2000	2001	2002	2003	2004	2005	2006	2007	2008	2009	2010	2011	2012
8+	0	0	0	0	0	0	0	0	0	0	0	0	0
7-7.9	0	1	1	2	0	1	0	1	0	0	1	1	0
6-6.9	6	5	4	7	2	4	7	9	9	4	8	3	5
5-5.9	63	41	63	54	25	47	51	72	85	58	89	51	27

- Earthquakes
- Hazards
- Data & Products
- Learn
- Monitoring
- Research







SEISMON System Time (GPS): 1186379290 System Uptime (S): 116578 Keep Alive:

**EARTHQUAKE 1**

TIME (UTC)	TIME(GPS)	MIN	SEC	Velocity
2017-08-10 03:44:06 UTC	P-Wave Arrival: 1186372036.700	-120	-54	
	S-Wave Arrival: 1186372172.900	-118	0	
	R35-Wave Arrival: 1186372246.700	-117	-24	7.7407e-07

LOCATION: Prince\_of\_Wales-Hyder,Alaska,United\_Sta

MAGNITUDE: 4.200 DEPTH (KM): 1.000  
 LAT(DEG): 54.500 LONG(DEG): -134.100 DISTANCE(KM): 1.339e+06

**EARTHQUAKE 2**

TIME (UTC)	TIME(GPS)	MIN	SEC	Velocity
2017-08-10 00:43:18 UTC	P-Wave Arrival: 1186361831.900	-290	-59	
	S-Wave Arrival: 1186362461.300	-280	0	
	R35-Wave Arrival: 1186364208.700	-251	-22	5.1483e-07

LOCATION: Lila,Bohol,Central\_Visayas,Philippines

MAGNITUDE: 5.000 DEPTH (KM): 528.100  
 LAT(DEG): 9.500 LONG(DEG): 124.100 DISTANCE(KM): 1.117e+07

**EARTHQUAKE 3**

TIME (UTC)	TIME(GPS)	MIN	SEC	Velocity
2017-08-10 00:36:29 UTC	P-Wave Arrival: 1186361279.900	-300	-11	
	S-Wave Arrival: 1186361832.900	-290	0	
	R35-Wave Arrival: 1186362868.900	-273	-42	4.3241e-07

LOCATION: Yachoyo\_Bypass,Yachiyo,Chiba,Japan

MAGNITUDE: 5.000 DEPTH (KM): 59.600  
 LAT(DEG): 35.700 LONG(DEG): 140.100 DISTANCE(KM): 7.915e+06

**EARTHQUAKE 4**

TIME (UTC)	TIME(GPS)	MIN	SEC	Velocity
2017-08-09 22:56:19 UTC	P-Wave Arrival: 1186355384.400	-310	-34	
	S-Wave Arrival: 1186356016.600	-300	0	
	R35-Wave Arrival: 1186357508.100	-275	-10	3.1190e-07

LOCATION: ÄiukurgÄMI,ÄiftlikÄly,Bodrum,MuÄila,A

MAGNITUDE: 4.100 DEPTH (KM): 10.000  
 LAT(DEG): 36.900 LONG(DEG): 27.600 DISTANCE(KM): 1.019e+07

**EARTHQUAKE 5**

TIME (UTC)	TIME(GPS)	MIN	SEC	Velocity
2017-08-09 21:05:56 UTC	P-Wave Arrival: 1186348759.600	-331	0	
	S-Wave Arrival: 1186349391.200	-320	0	
	R35-Wave Arrival: 1186350869.300	-295	-50	3.5304e-07

LOCATION: S301,Longkang,Jiuzhaigou\_County,Ngawa\_T

MAGNITUDE: 4.600 DEPTH (KM): 10.000  
 LAT(DEG): 33.300 LONG(DEG): 104.000 DISTANCE(KM): 1.013e+07