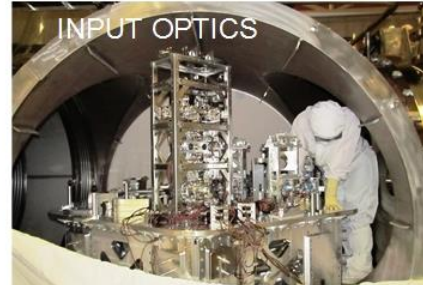
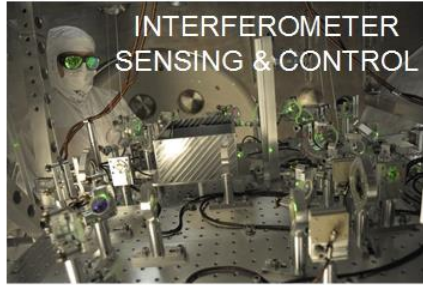




LIGO



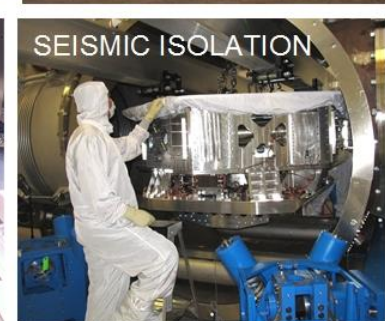
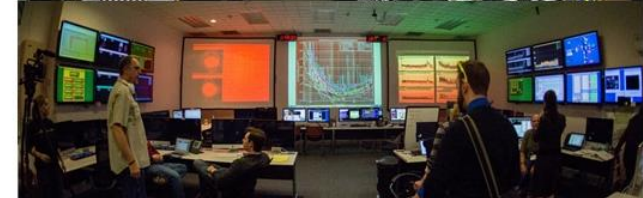
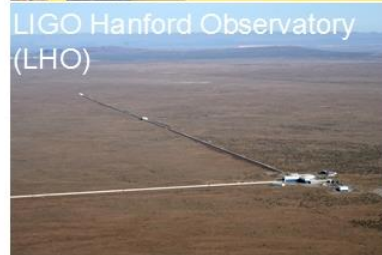
Brief LIGO Controls Overview

Dennis Coyne

LIGO Laboratory, Caltech

26 Aug 2017

LIGO-G1701594-v1



- ❖ **Hardware architecture**
- ❖ **Software architecture**
- ❖ **“Plants” to be controlled**
- ❖ **Control group focus areas/priorities**

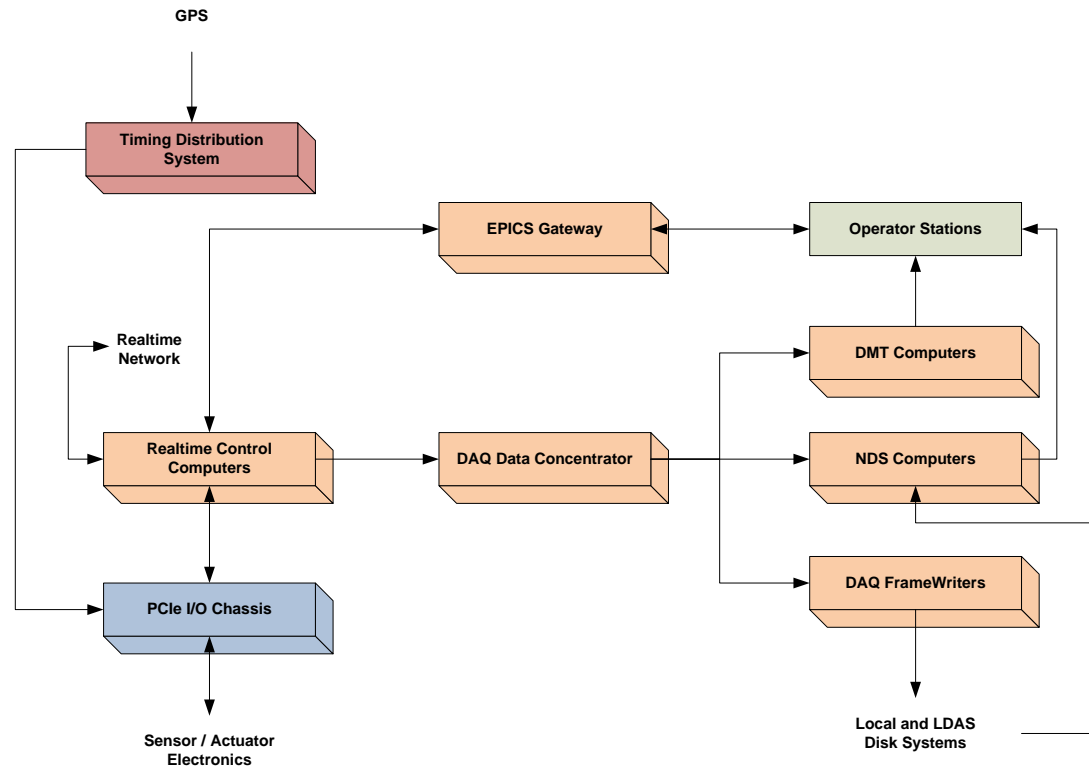
Overall references on the Advanced LIGO detector:

- *Advanced LIGO, [LIGO-P1400177](#), <https://arxiv.org/abs/1411.4547>*
- *The Sensitivity of the Advanced LIGO Detectors at the Beginning of Gravitational Wave Astronomy, LIGO-P1500260, <https://arxiv.org/abs/1604.00439>, Phys. Rev. D 93, 112004, June 2016.*

Control & Data System

Hardware Architecture Overview

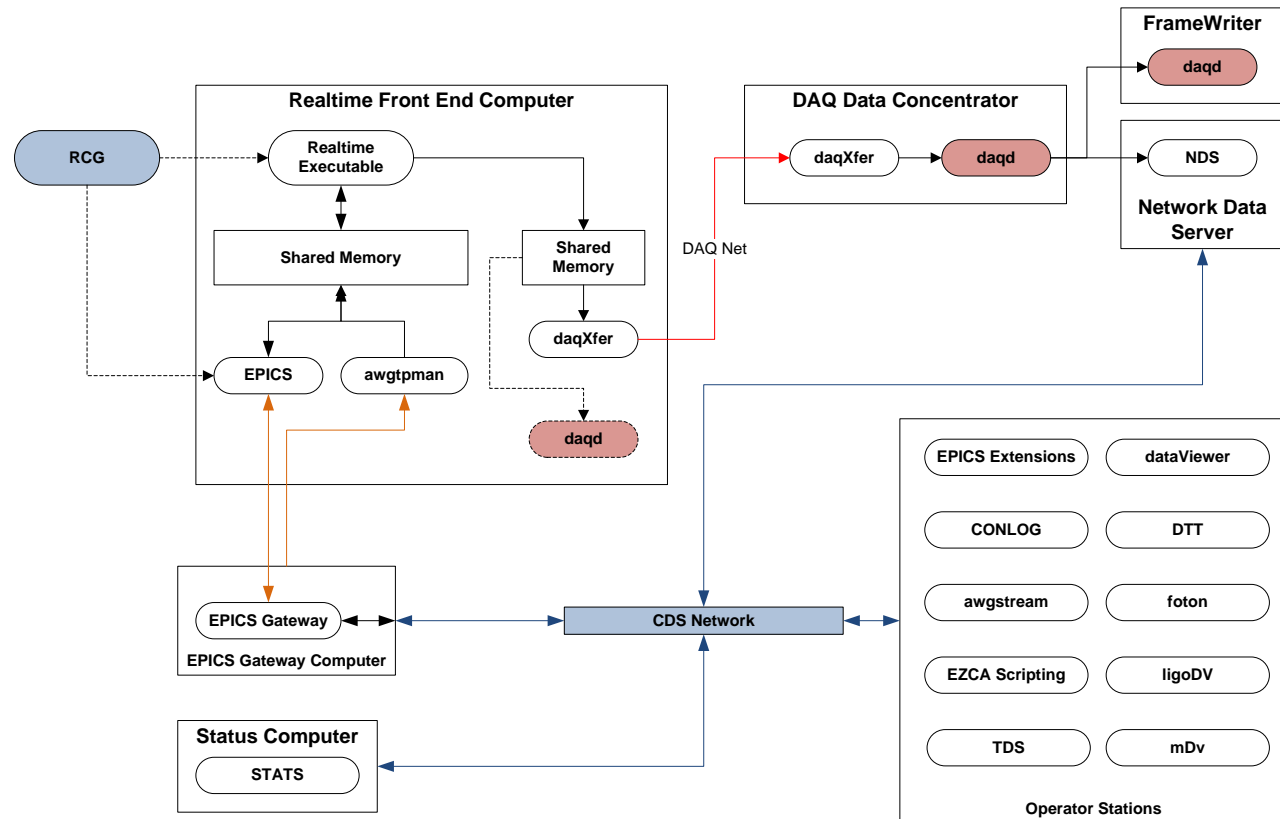
- ❖ Timing derived from GPS
- ❖ Front-End Computers
 - ❖ hard, real-time
 - ❖ Linux real-time OS
 - ❖ multi-core, server class
- ❖ Fiber-linked PCIe I/O bus with 18-bit ADC/DAC
- ❖ Servo loop rates up to 65 kHz
- ❖ Synchronous, deterministic operation to within a few microseconds



- *AdvLIGO CDS Design Overview, [LIGO-T0900612](#)*
- *New Control and Data Acquisition System in the AdvLIGO Project, [LIGO-P1100052](#)*

Control & Data System Software Architecture Overview

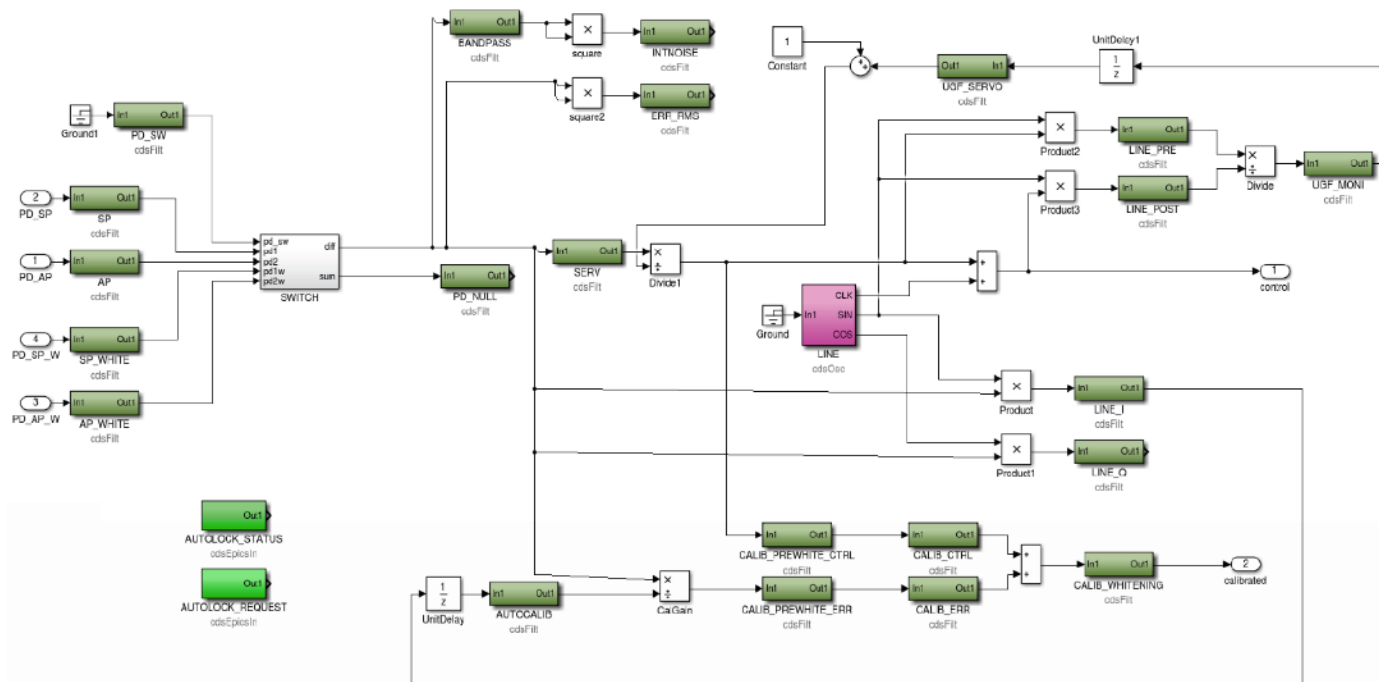
- ❖ **Real-Time Code Generator (RCG)**
 - ❖ Matlab Simulink graphical interface used to sketch control
- ❖ **EPICS**
 - ❖ Interface for setting parameters
- ❖ **Guardian**
 - ❖ State machine for sequencing



▪ *aLIGO, DAQ, Software Design Documentation, [LIGO-T1000625](https://www.ligo.caltech.edu/publications/LIGO-T1000625)*

Real-time digital control

- ❖ Matlab/Simulink used as a graphical interface to sketch control system using standard blocks
- ❖ Generates real-time code to run on linux front-end machine

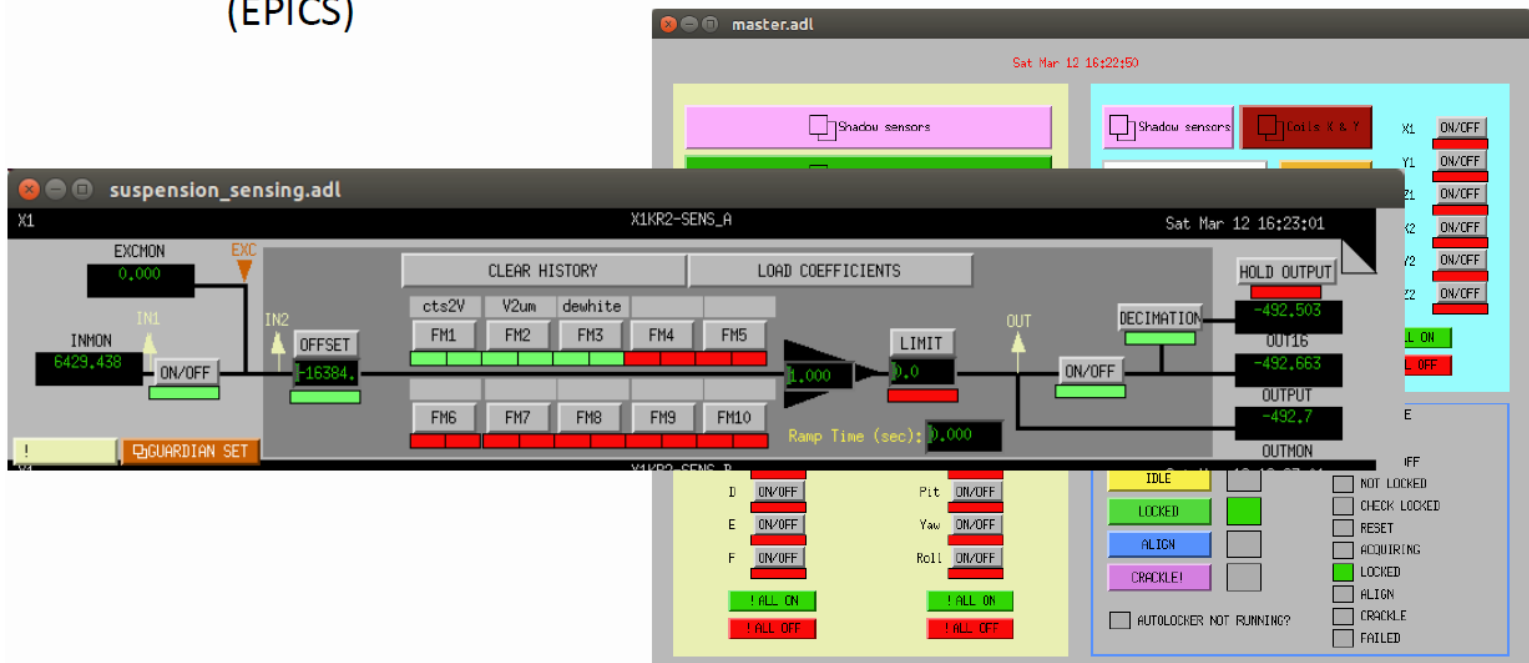


- Real-time Code Generator (RCG) Software Component Overview, [LIGO-T1200291](#)

Real-time digital control

- ❖ Interface to the front-end, real-time “models” is via EPICS
- ❖ Change filters, gains, parameters
- ❖ Set Point Definition/Monitor software automates configuration control for the ~100k servo system parameters

(EPICS)

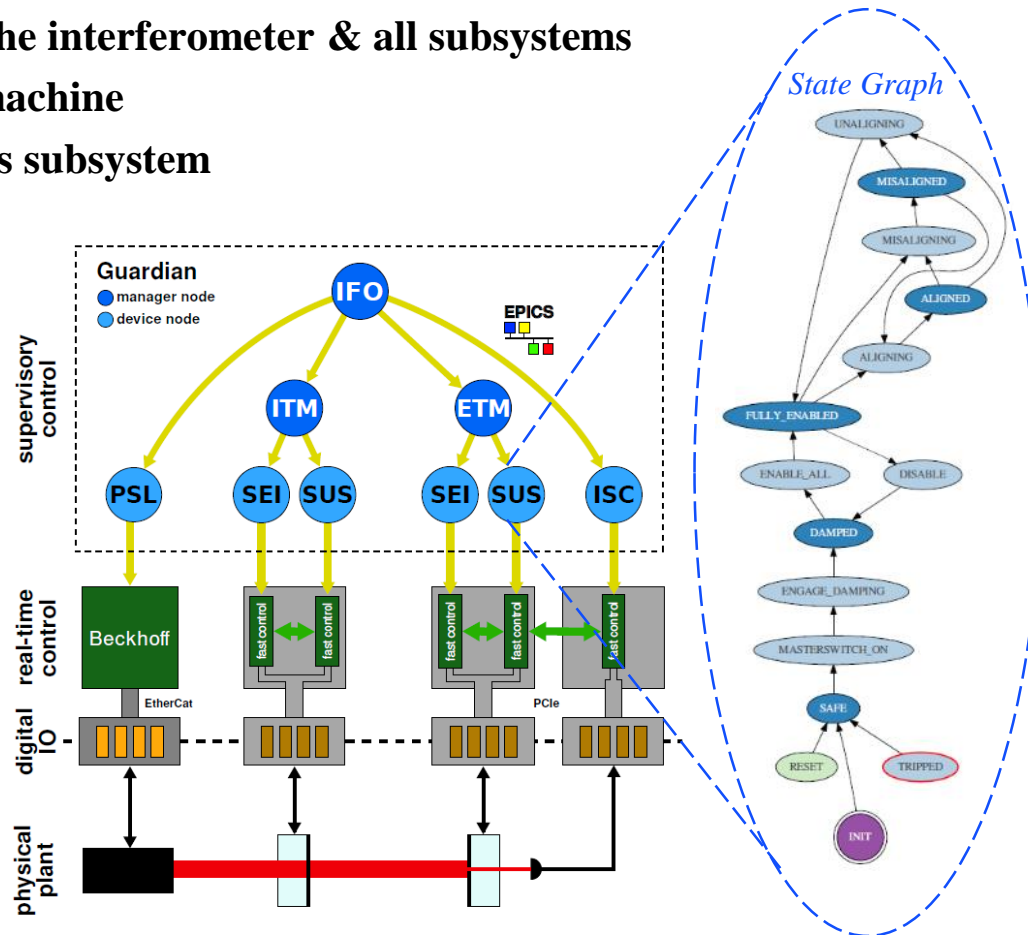
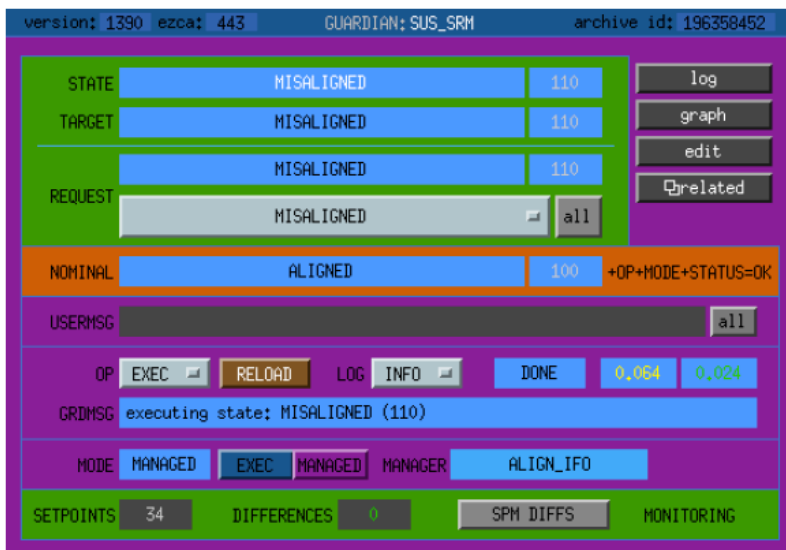


The screenshot displays two EPICS control windows. The foreground window is titled 'suspension_sensing.adl' and shows a control panel for 'X1KR2-SENS_A'. It includes various input fields like 'EXCHON' (0.000), 'INMON' (6429.438), and 'OFFSET' (-16384). A central section contains ten filter gain buttons (FM1-FM10) and a 'LIMIT' field (0.0). The output section shows 'DECIMATION' (-492.503), 'OUTPUT' (-492.663), and 'OUTMON' (-492.7). A 'Ramp Time (sec): 0.000' field is also present. The background window is 'master.adl', showing a 'Shadow sensors' panel and a vertical list of status indicators for X1, Y1, Z1, X2, Y2, Z2, and E, each with an 'ON/OFF' button.

▪ Real-Time Code Generator (RCG) SDF Software, [LIGO-T1500115](https://github.com/LIGO-T1500115)

the Guardian

- ❖ Robust framework for automation of the interferometer & all subsystems
- ❖ Hierarchical, distributed, finite state machine
- ❖ Each node executes a state graph for its subsystem
- ❖ Supports commissioning & operation
- ❖ EPICS interface
- ❖ Python code
- ❖ Adopted & adapted by Virgo



- *Advanced LIGO Guardian Documentation, [LIGO-T1500292](#)*
- *Distributed State Machine Supervision for Long-baseline Gravitational-wave Detectors with the Guardian Automation Platform, [LIGO-P1600066](#), <https://arxiv.org/abs/1604.01456>, Rev. Sci. Instrum. 87 (2016) 094502*

The principal “Plants”

❖ Pre-Stabilized Laser (PSL)

- ❖ Frequency, pointing & intensity stabilization

❖ Seismic Isolation System (SEI)

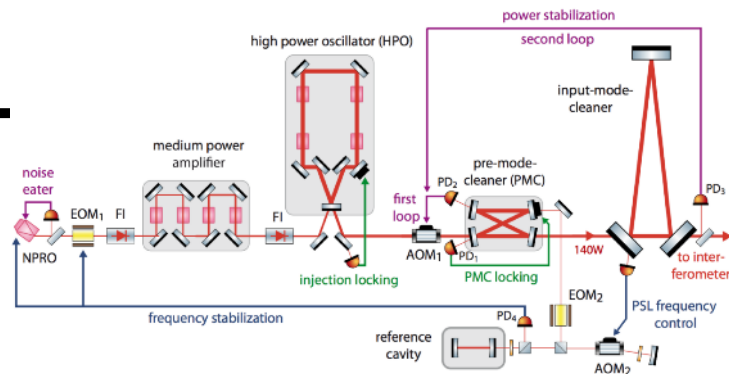
- ❖ Isolated platforms for optics
- ❖ 3 stages x 6 dof each = 18 dof
- ❖ EM actuators inner stages
- ❖ Hydraulic, actuator outer
- ❖ Blended position & velocity sensing
- ❖ MIMO, feed-forward and feedback control

❖ Suspensions (SUS)

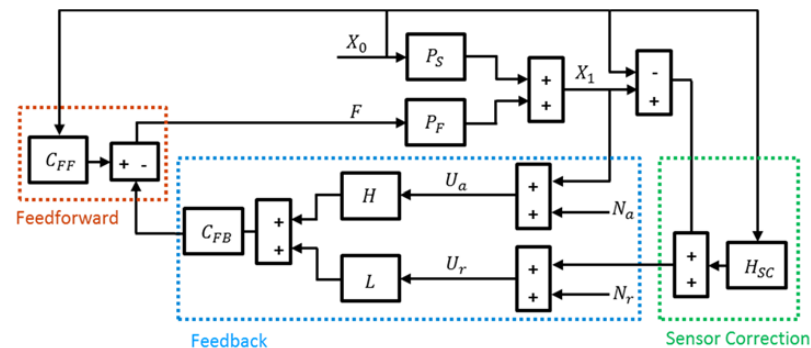
- ❖ Single, double, triple & quadruple pendulum suspensions
- ❖ Quad Test Mass (TM) suspensions with reaction chain
- ❖ 2 x 4 x 6 = 48 degrees of freedom each TM SUS
- ❖ Position sensors & EM actuators on upper stages
- ❖ Electro-static actuation at TM stage
- ❖ Damped at low frequency with rapid roll-off to prevent control loop noise injection in-band
- ❖ SUS are length and angle actuators for global interferometer control

❖ Interferometer Sensing & Control (ISC)

- ❖ Length
- ❖ Angle



Multi-stage frequency isolation. Initial frequency stabilization has 400 kHz BW (PZT, EOM, Crystal heating)

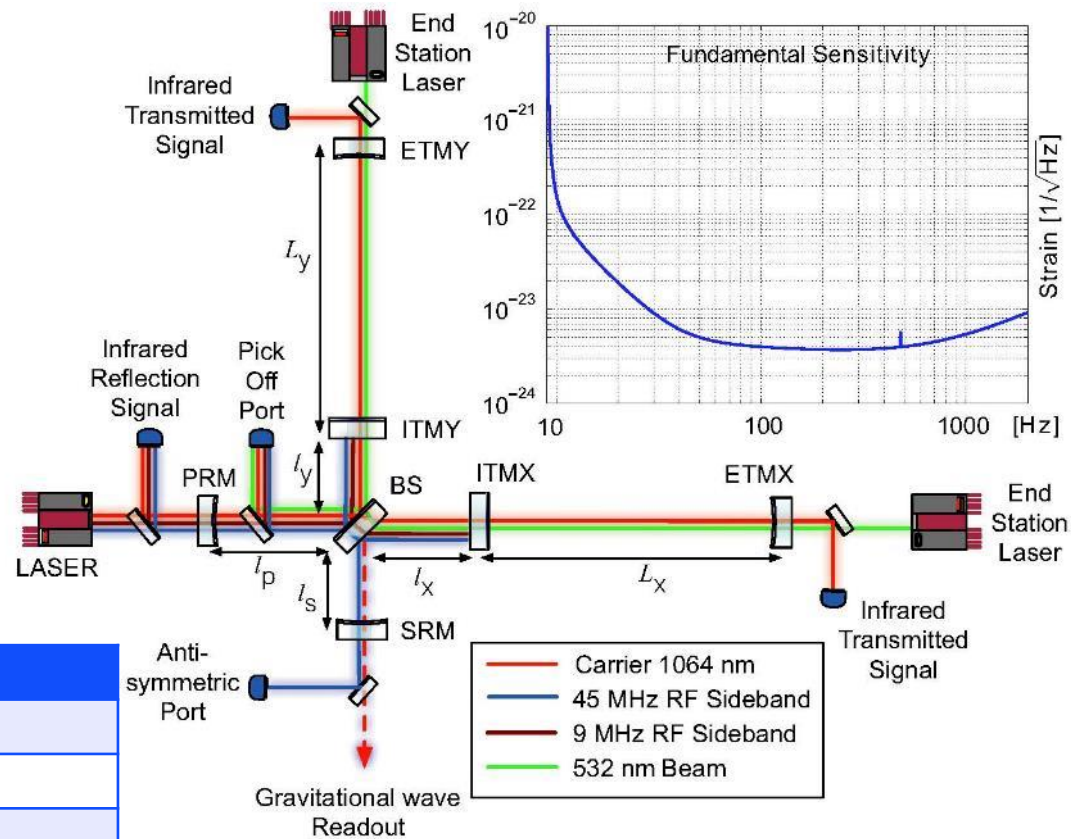


Control topology for each SEI dof.
(40 dB of isolation with bandwidths ~25 Hz, dof dependent)

- *Stabilized high-power laser system for the gravitational wave detector Advanced LIGO, LIGO-P1100192, Optics Express, Vol. 20 Issue 10, pp.10617-10634 (2012)*
- *Seismic Isolation of Advanced LIGO: Review of Strategy, Instrumentation, and Performance (CQG 2015), LIGO-P1200040, <https://arxiv.org/abs/1502.06300>*
- *Noise and Control Decoupling of Advanced LIGO Suspensions, LIGO-P1400085, 2015 Class. Quantum Grav. 32 015004 doi:10.1088/0264-9381/32/1/015004*

Interferometer Length Sensing & Control

- ❖ Nonlinear cavity lock acquisition control
- ❖ Length derived from RF demodulated signals
- ❖ Five resonant cavity lengths
- ❖ Arm Length Stabilization (ALS)
 - ❖ Acquire lock with lower finesse at doubled frequency (green wavelength) first



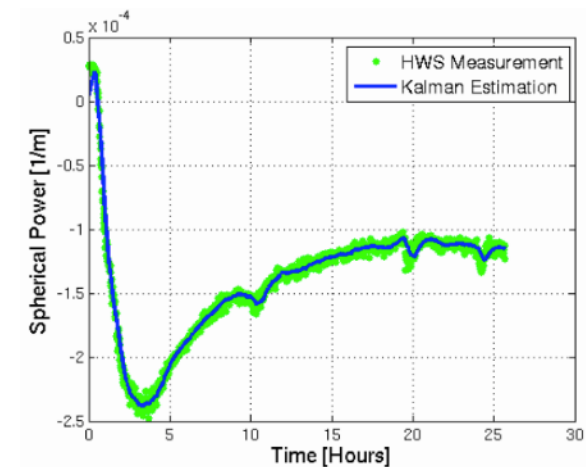
Mode	Definition
Common arm length (CARM)	$(L_x + L_y)/2$
Differential arm length (DARM)	$L_x - L_y$
Power recycling cavity length (PRC)	$l_p + (l_x + l_y)/2$
Signal recycling cavity length (SRC)	$l_s + (l_x + l_y)/2$
Michelson length (MICH)	$l_x - l_y$

- Achieving Resonance in the aLIGO Interferometer, [LIGO-P1400105](#), Class. Quantum Grav. 31 (2014) 245010
- CARM/ALS Electro-Optical Controls Diagram, [LIGO-G1500456](#)

Auxiliary Loops

Many additional, essential loops, many of which are not completely independent of the global interferometer controls:

- ❖ **Earth tidal correction**
- ❖ **Output Mode Cleaner (OMC) alignment**
- ❖ **Wavefront Sensor (WFS) centering**
- ❖ **Input Mode Cleaner (IMC) alignment**
- ❖ **Arm Length Stabilization (ALS)**
- ❖ **Thermal Compensation System (TCS)**
- ❖ **Fiber “violin” mode damping loops**
- ❖ ...

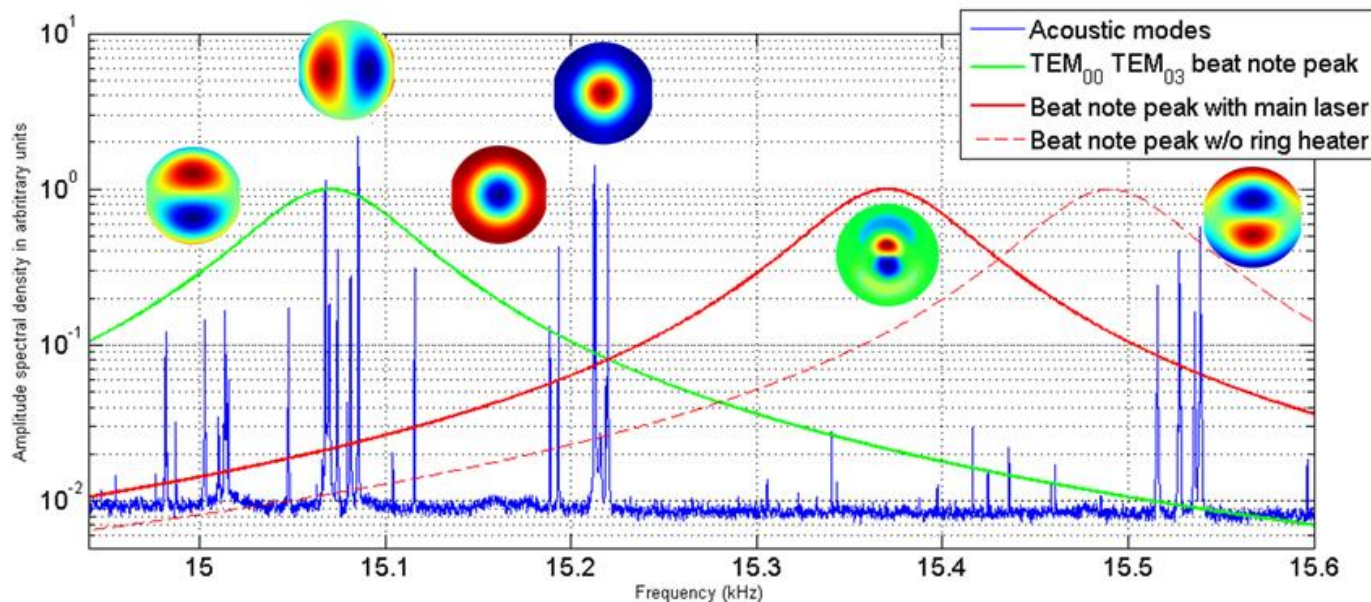
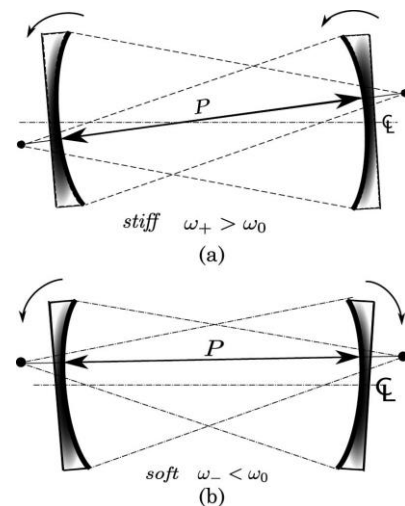


Wavefront sensor measurement and Kalman estimator

- *The Adv. LIGO Input Optics, LIGO-P1500076, <http://dx.doi.org/10.1063/1.4936974>, Rev Sci Instrum vol. 87 pg. 014502.*
- *Locking the Advanced LIGO Gravitational Wave Detector: with a focus on the Arm Length Stabilization Technique, LIGO-P1500273, <http://dx.doi.org/10.7916/D8X34WQ4>*
- *Kalman Filter for the Thermal Compensation System, LIGO-G1501532*

Interferometer Plant Changes with Optical Power

- ❖ “Stiff” and “Soft” modes
 - ❖ Radiation pressure in the Fabry-Perot arm cavities can result in instability
 - ❖ Control Hard modes with ETMs only at high bandwidth
 - ❖ Control Soft modes with ITMs only, at low bandwidth
- ❖ Parametric Instabilities
 - ❖ Overlap of high order optical modes & test mass acoustic modes
 - ❖ Shift off resonance with thermal tuning (ring heaters)
 - ❖ Damp with electro-static actuators
 - ❖ Research on passive, broadly tuned dampers



- Angular instability due to radiation pressure in LIGO, LIGO-P0900086, <https://arxiv.org/abs/0909.0010>, Applied Optics, Vol. 49, No. 18
- First Demonstration of Electrostatic Damping of Parametric Instability at Adv. LIGO, LIGO-P1600090, <https://arxiv.org/abs/1611.08997>, Phys. Rev. Lett. 118, 151102 (2017)



LSC Control Systems Working Group (CSWG¹) Priorities/Focus Areas

❖ Applications of Machine Learning (ML) to Controls

❖ Lock Maintenance

❖ Lock Acquisition²

❖ Length to Angle (L2A) decoupling

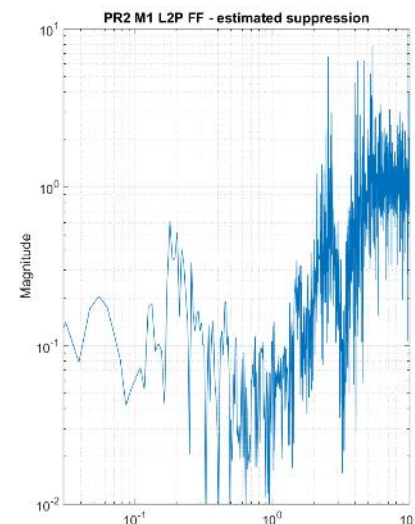
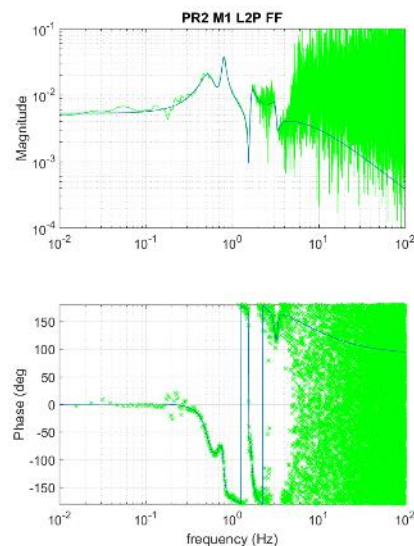
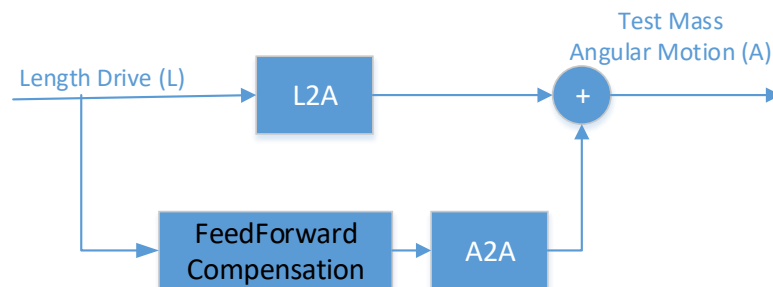
❖ Feedback optimization
(esp. applied to angular controls)

❖ System Identification

❖ Interferometer robust configuration for
earthquakes³

❖ State space control for the Real-Time
Code Generator (RCG) Software

❖ *More generally, we are working to inject
more modern control techniques to
improve performance & robustness*



1) CSWG wiki page: <https://wiki.ligo.org/viewauth/CSWG/WebHome>

2) LSC-Virgo August 2017 Meeting @CERN, Deep leaning applied to lock acquisition, LIGO-G1701589

3) LSC-Virgo August 2017 Meeting @CERN, Earthquake early warning & response, LIGO-G1701593