



How to Detect a Gravitational Wave: A discussion about the Advanced LIGO Interferometers

Dr. Brian Lantz
for the LIGO Scientific Collaboration &
the Virgo Collaboration
May 18, 2016

LIGO

LSC

LIGO Scientific Collaboration



International Network

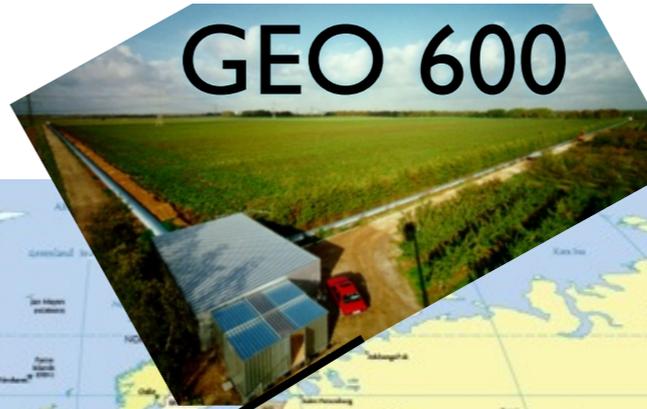


Sept. 14, 2015

LIGO Hanford



GEO 600



KAGRA



VIRGO



LIGO India

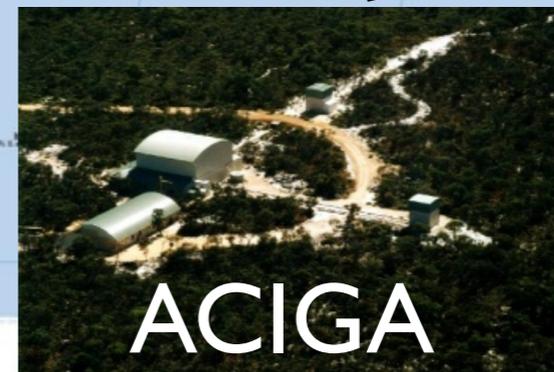


project approved

LIGO Livingston



ACIGA



Se

LIGO Hanford



LIGO Livingston



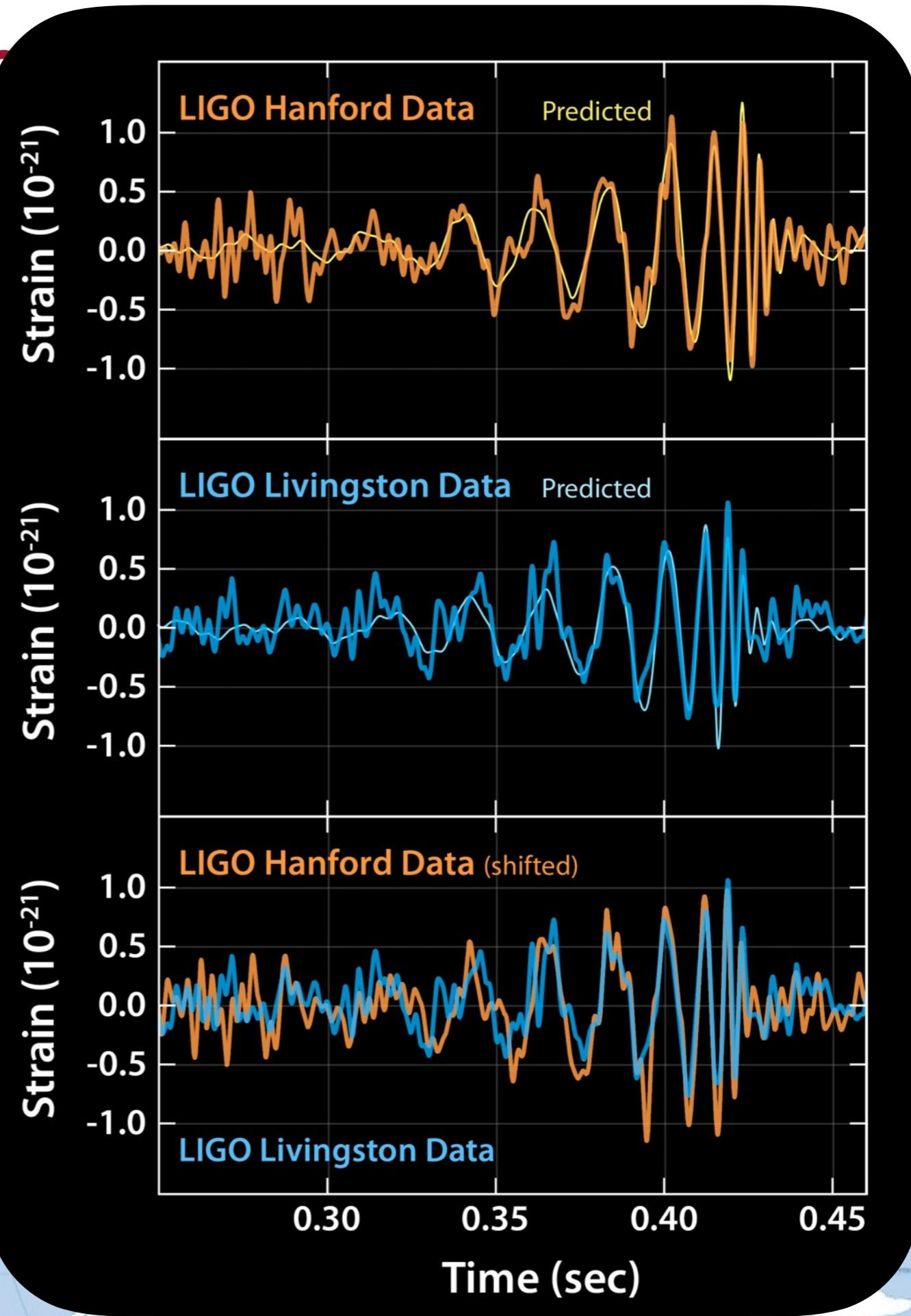
VIRGO VIRGO



KAGRA

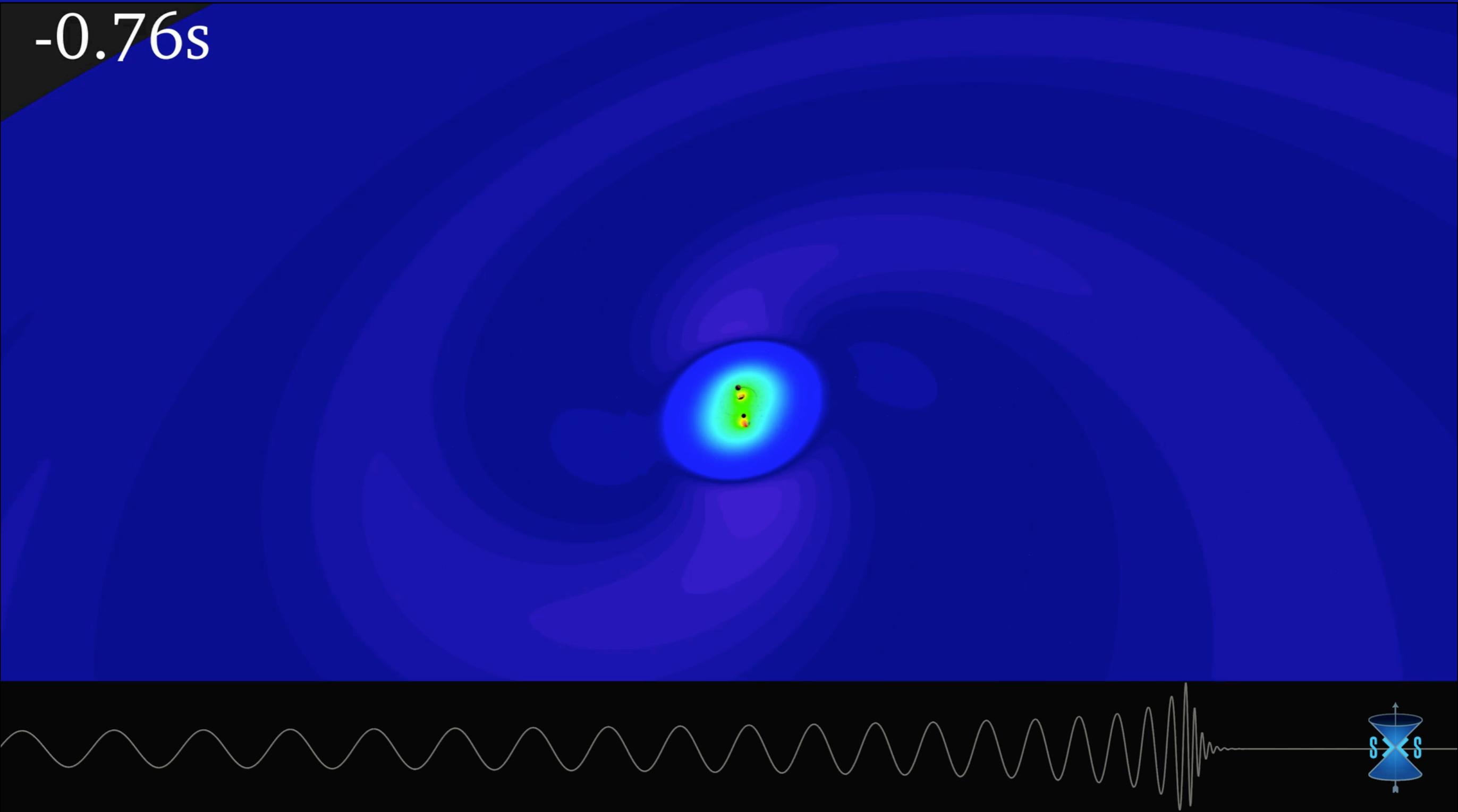


India approved



Simulation of the event

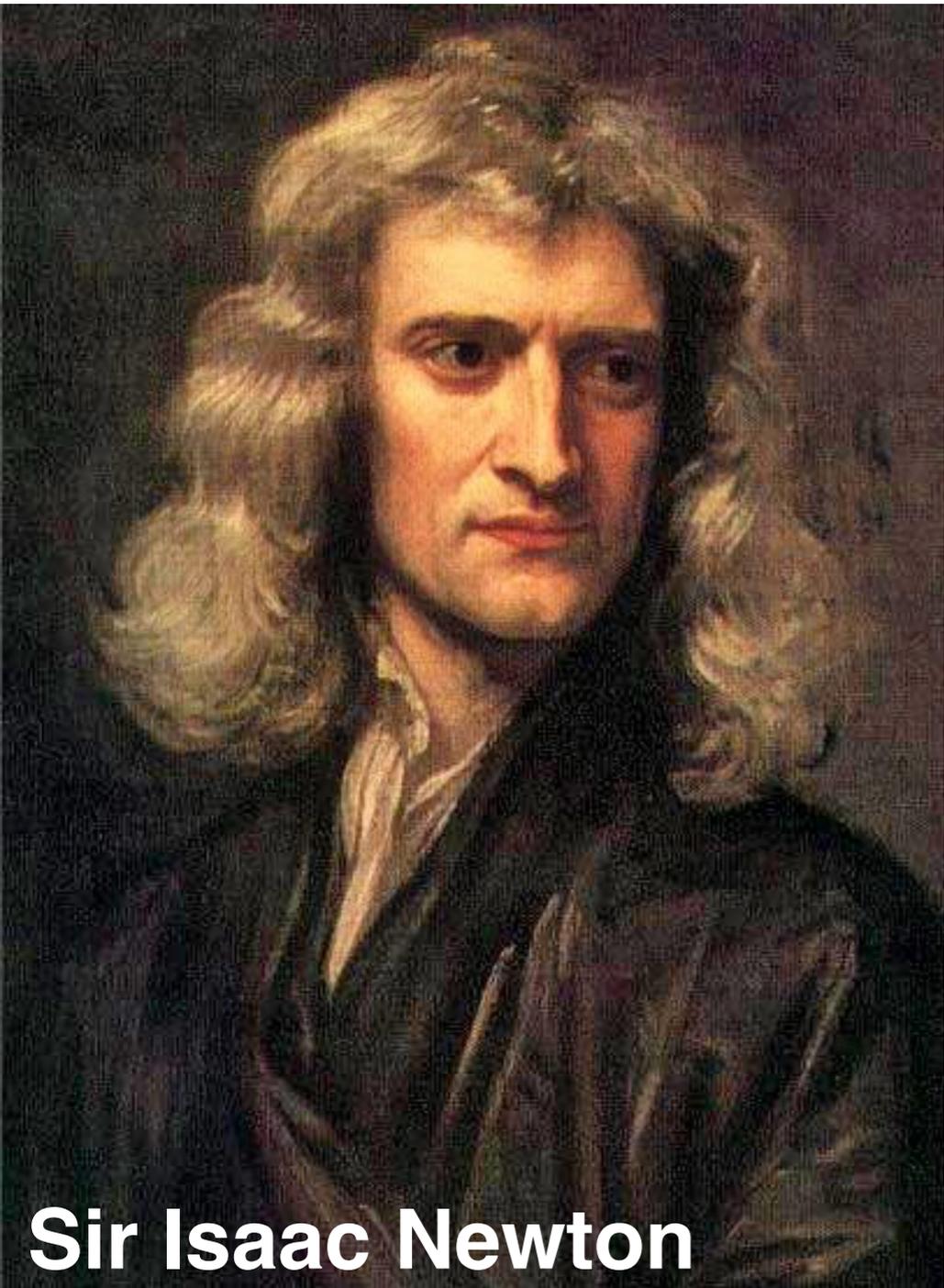
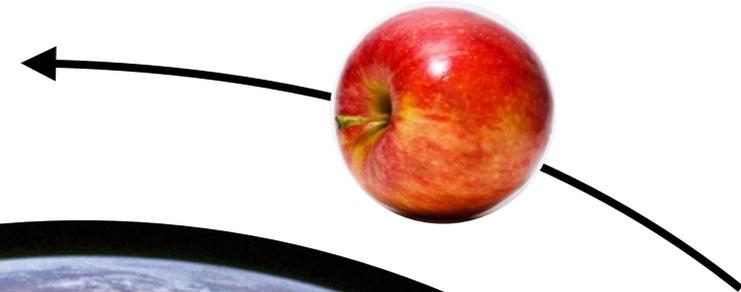
-0.76s



What is a Gravitational Wave?

$$F = \frac{Gm_1m_2}{r^2}$$

Implies immediate
action at a distance



Sir Isaac Newton

By Sir Godfrey Kneller

- <http://www.newton.cam.ac.uk/art/portrait.html>

Earth - By NASA/Apollo 17 crew; taken by either Harrison Schmitt or Ron Evans
- http://www.nasa.gov/images/content/115334main_image_feature_329_ys_full.jpg
- apple by Abhijit Tembhekar from Mumbai, India

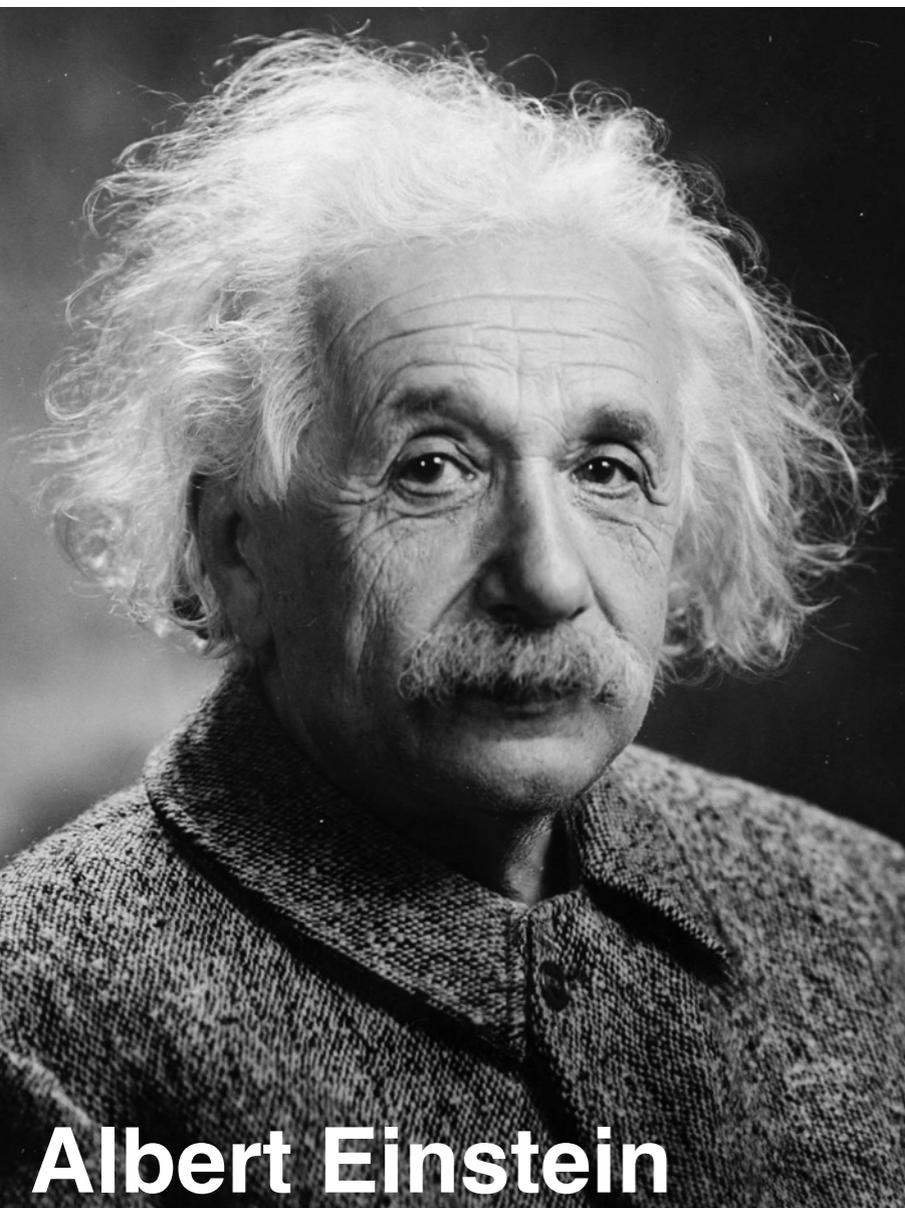
What is a Gravitational Wave?

Predicted by Einstein in 1916 as part of GR.

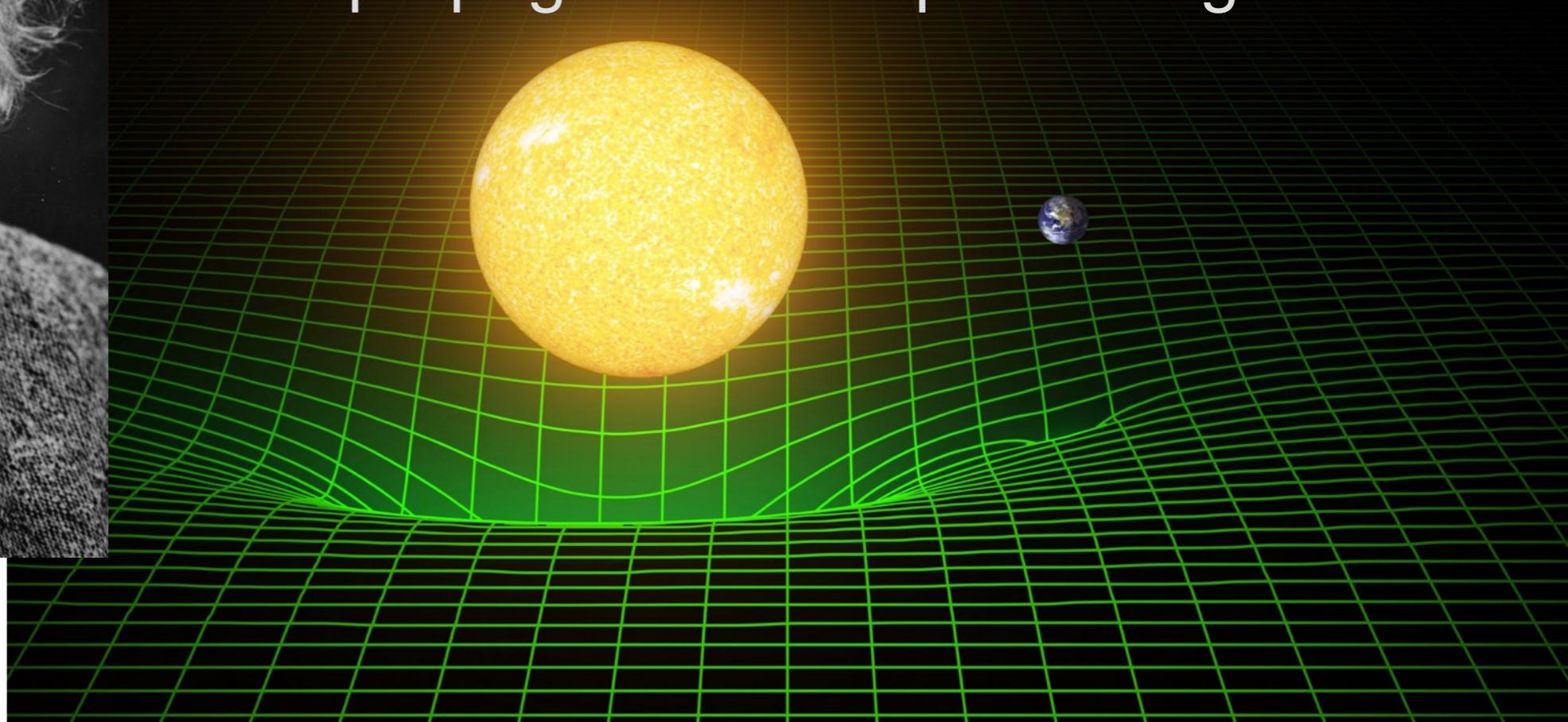
“Spacetime tells matter how to move,
matter tells spacetime how to curve”

- J. A. Wheeler

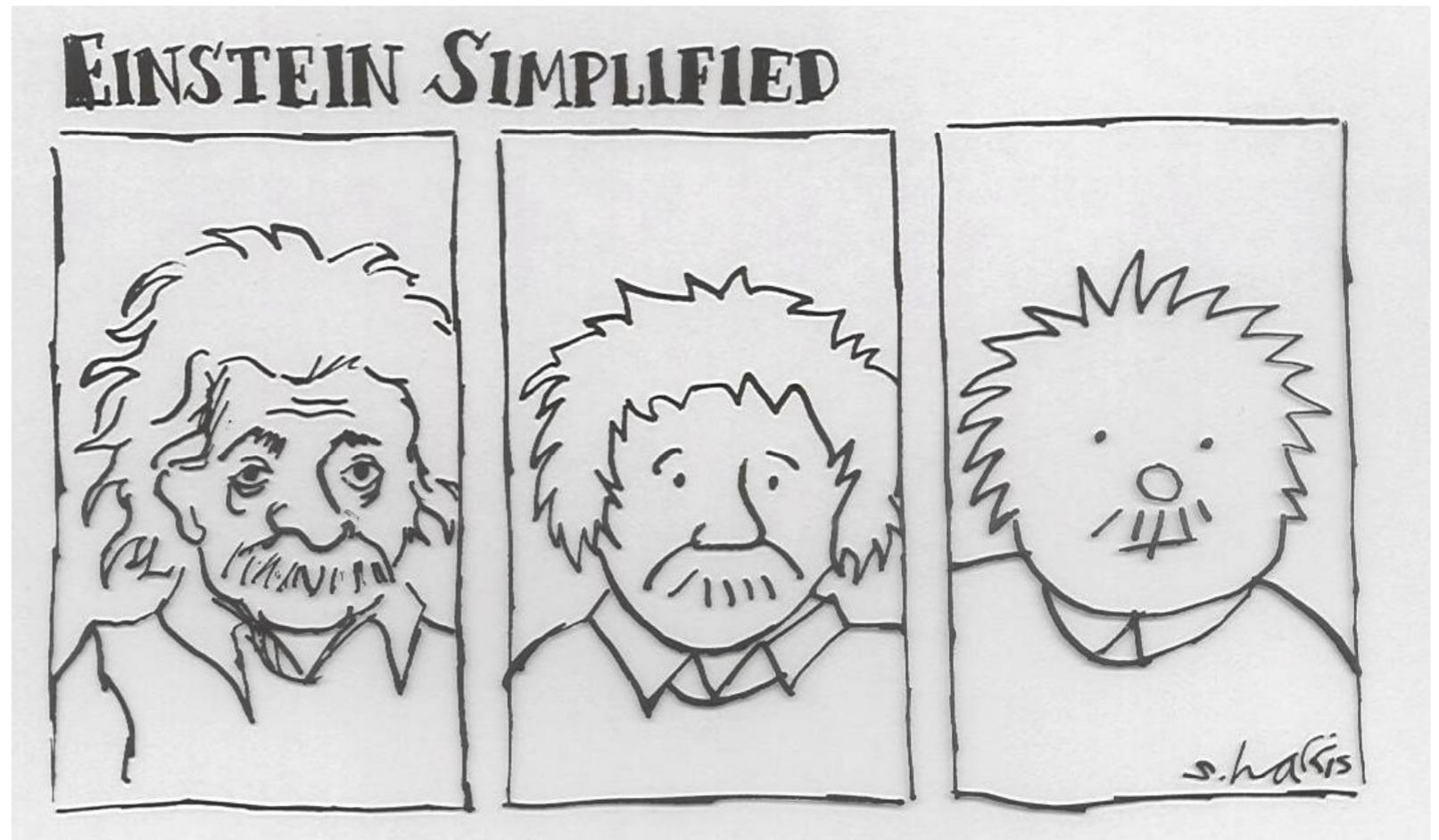
There are traveling wave solutions, the
waves propagate at the speed of light



Albert Einstein



What is a Gravitational Wave?



Assert an analogy:

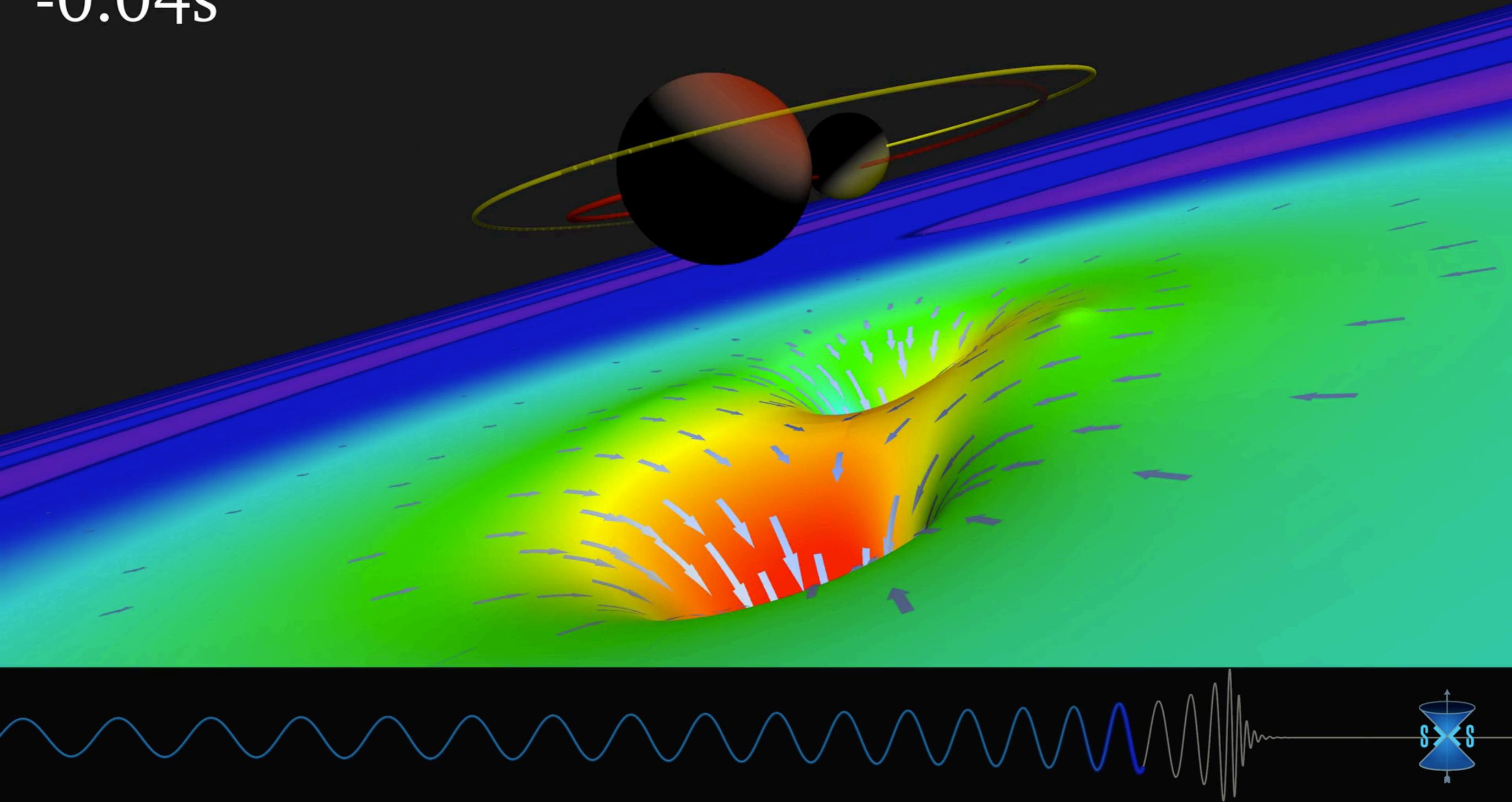
A stationary electron has an electric field, and accelerating the electron creates waves.

A stationary mass has a gravitational field, and accelerating the mass creates waves.

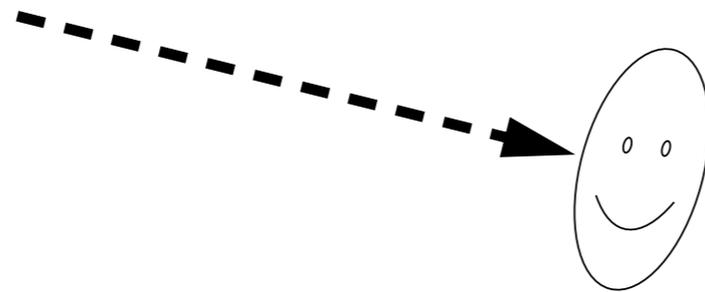
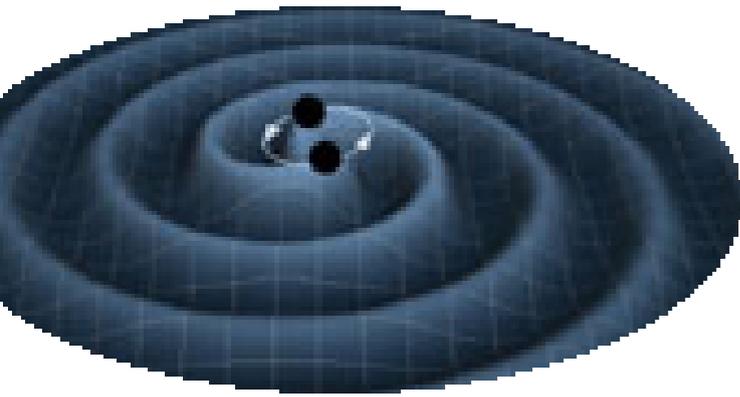
But, gravitational forces are relatively weak, or space is very stiff.

Simulation of the event

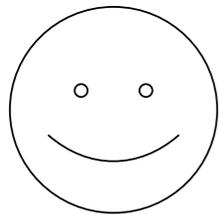
-0.04s



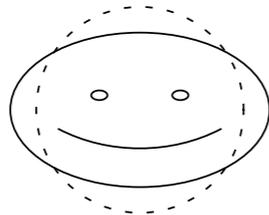
The LIGO concept



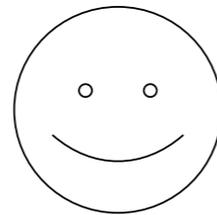
h_+



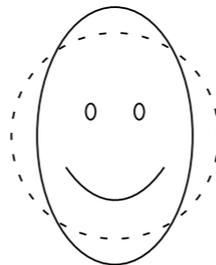
Time = 0



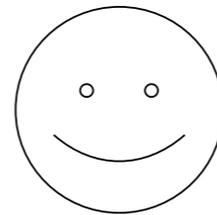
$T = \frac{P}{4}$



$T = \frac{P}{2}$

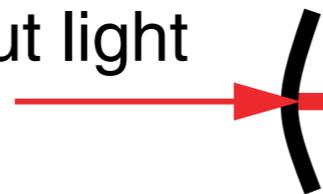


$T = \frac{3P}{4}$



$T = 1 \text{ Period}$

input light



4km arm cavity



4km arm cavity



output light, containing gravitational wave signal



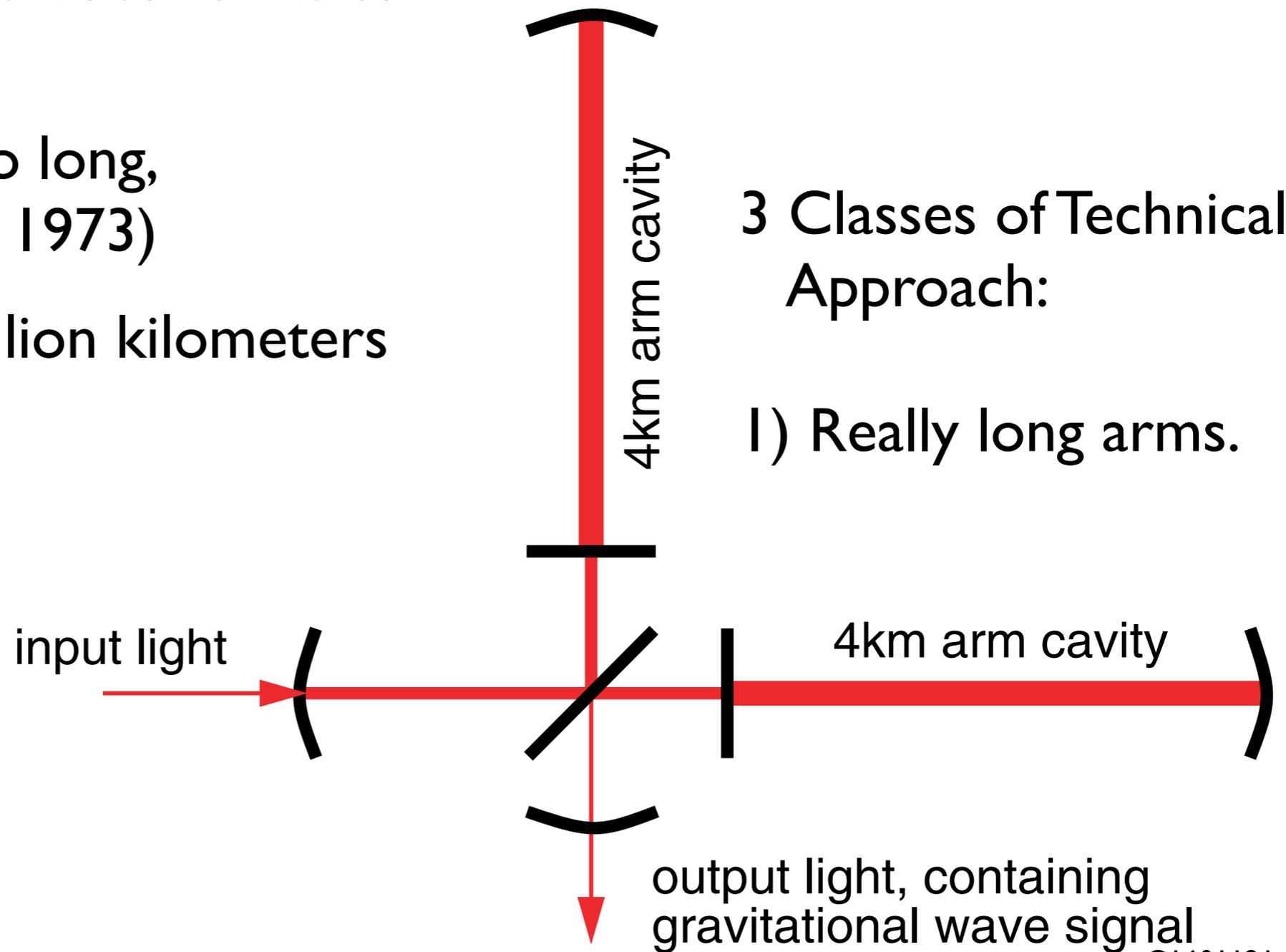
The LIGO concept

why it is nearly impossible

Gravitational waves are hard to measure because space doesn't like to stretch.

(that's why it's taken so long,
Einstein 1916, Weiss 1973)

Earth-to-Sun ~ 150 million kilometers
 $1.5 \times 10^8 \text{ m} * 10^{-21} \text{ strain}$
 $= 1.5 \times 10^{-10} \text{ meters}$

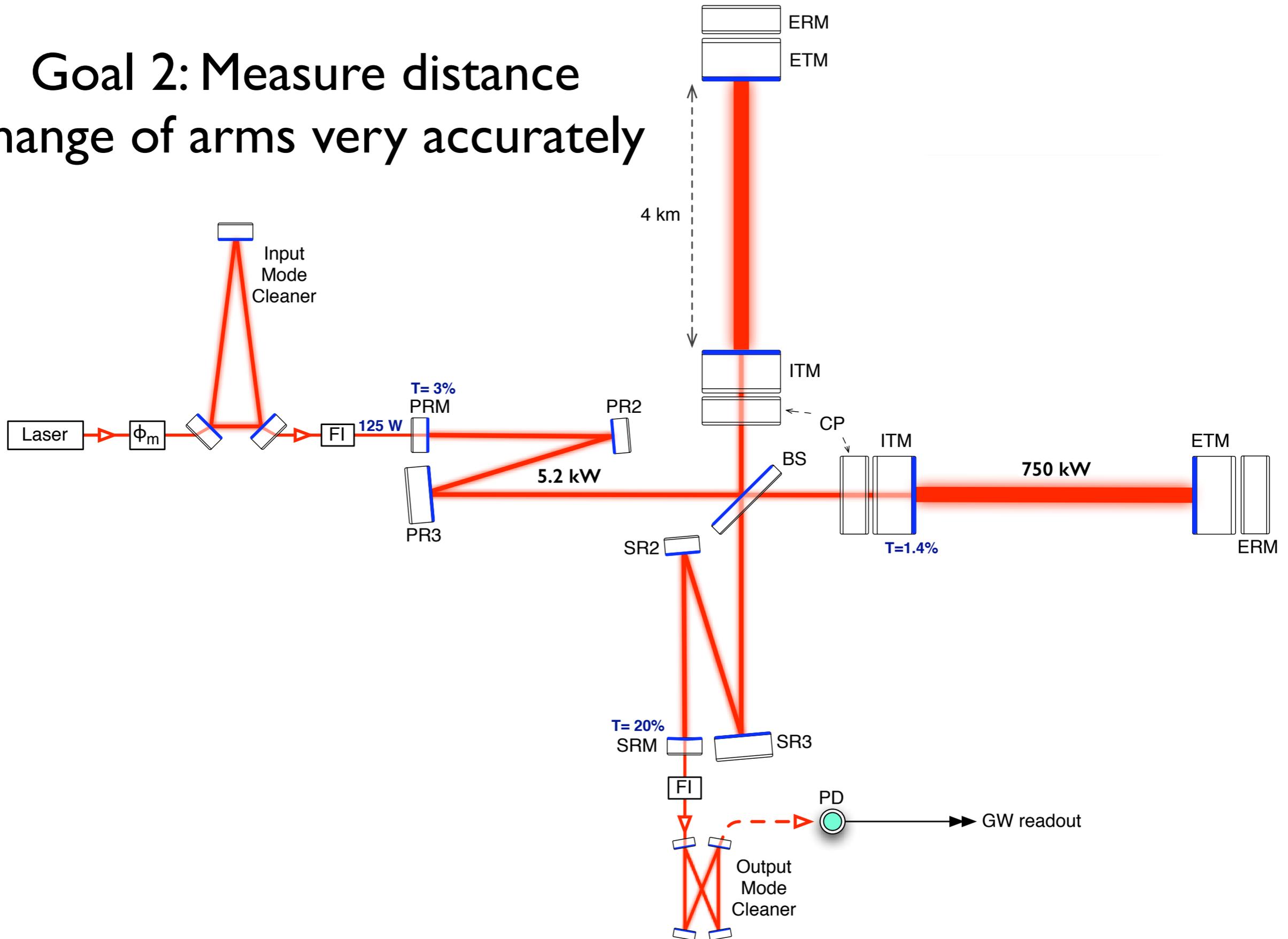


3 Classes of Technical Approach:

1) Really long arms.

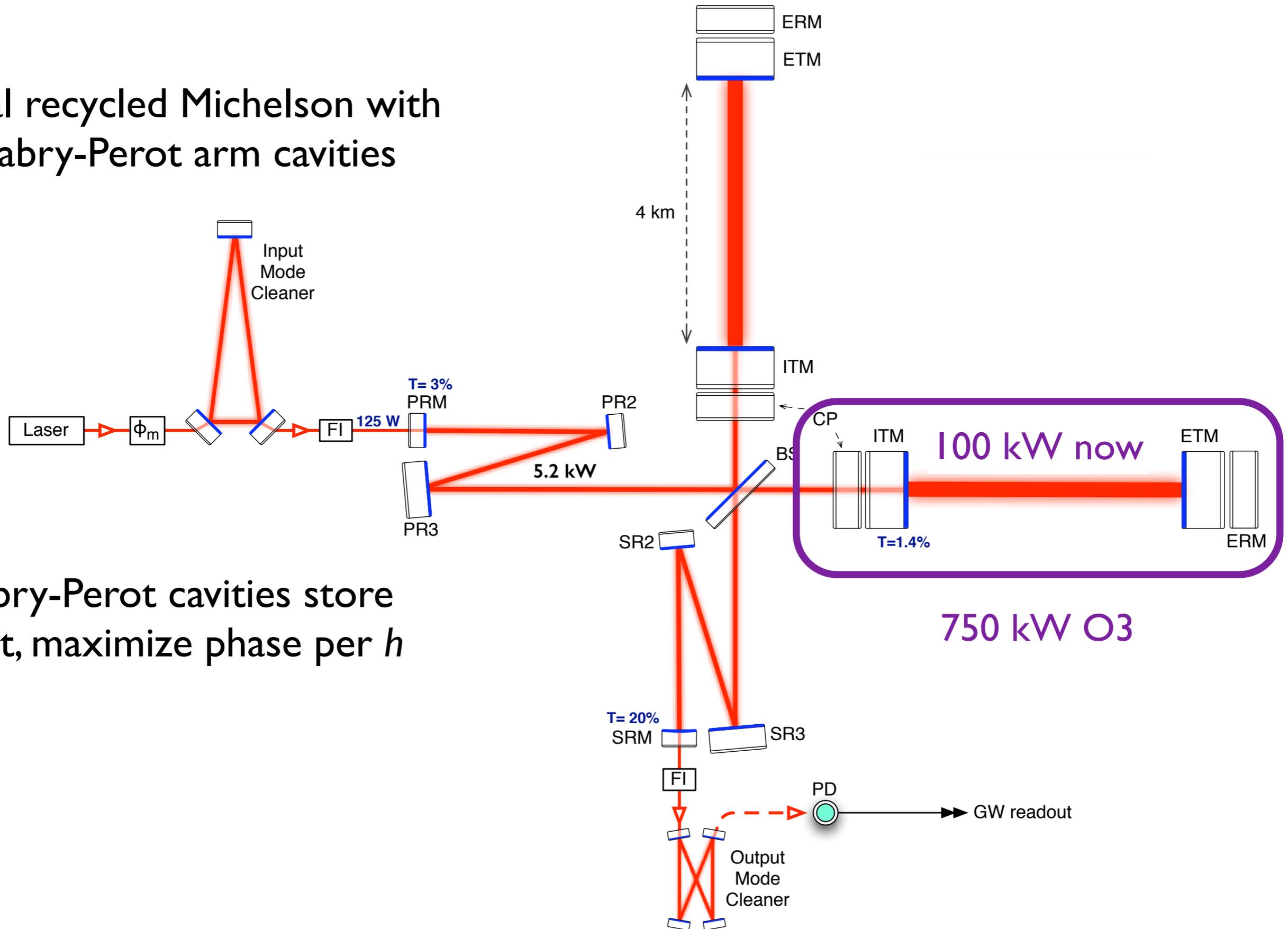
Layout of the interferometer

Goal 2: Measure distance change of arms very accurately



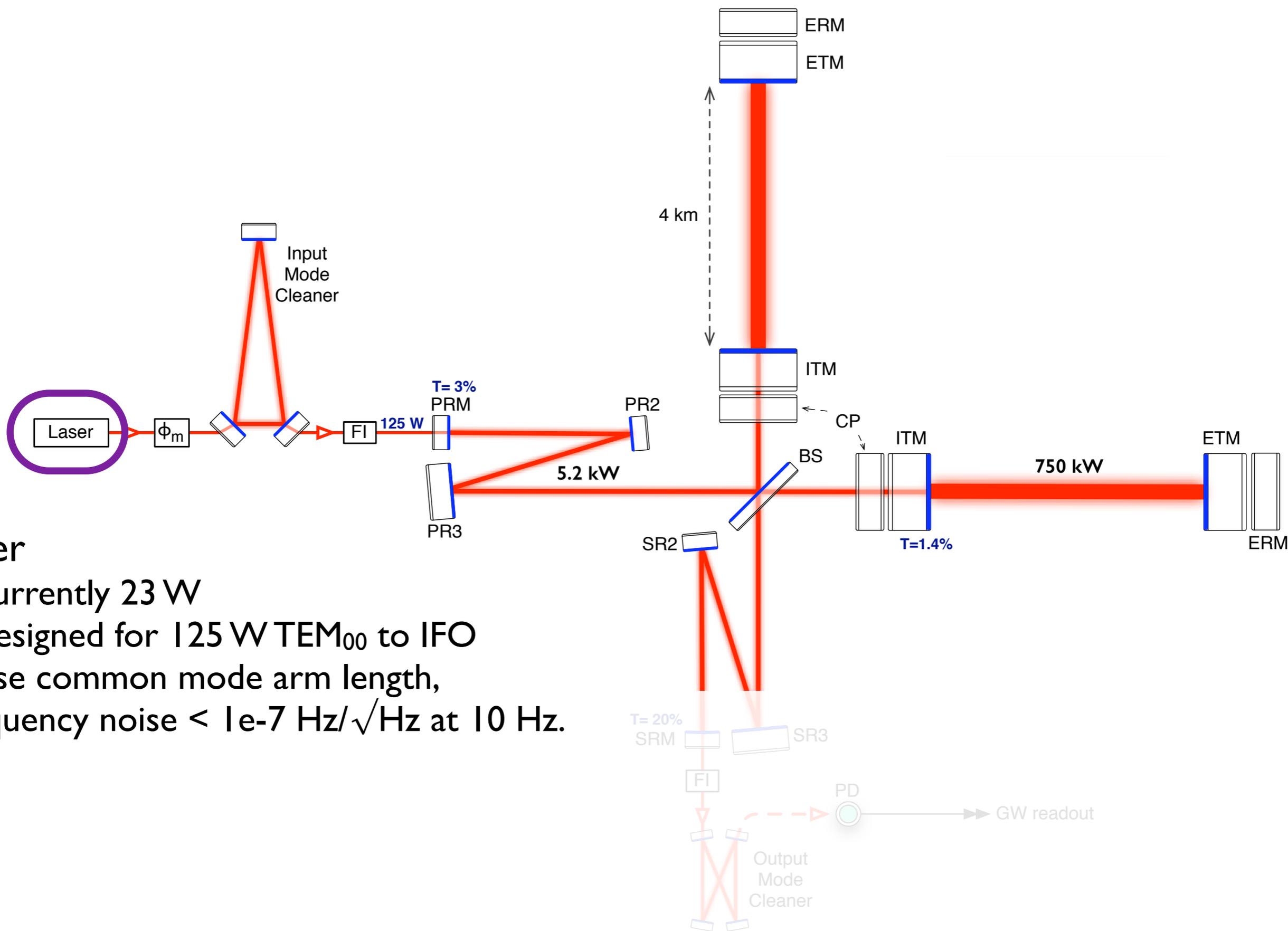
Fabry-Perot arms

Dual recycled Michelson with Fabry-Perot arm cavities



Fabry-Perot cavities store light, maximize phase per h

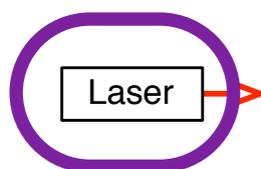
Power



Laser

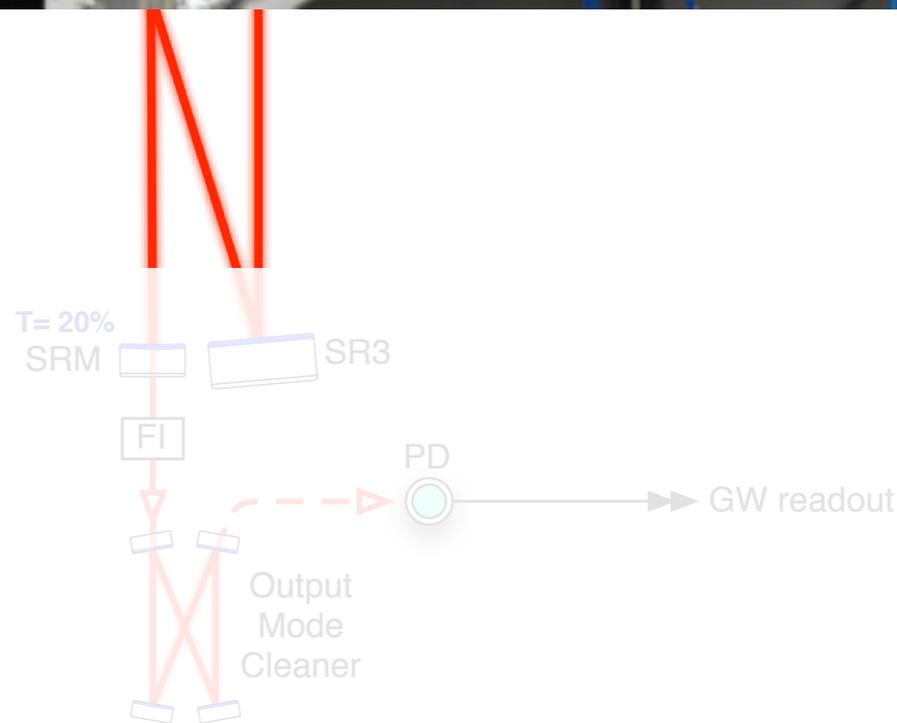
- currently 23 W
- designed for 125 W TEM₀₀ to IFO
- use common mode arm length, frequency noise $< 1e-7$ Hz/ $\sqrt{\text{Hz}}$ at 10 Hz.

Power



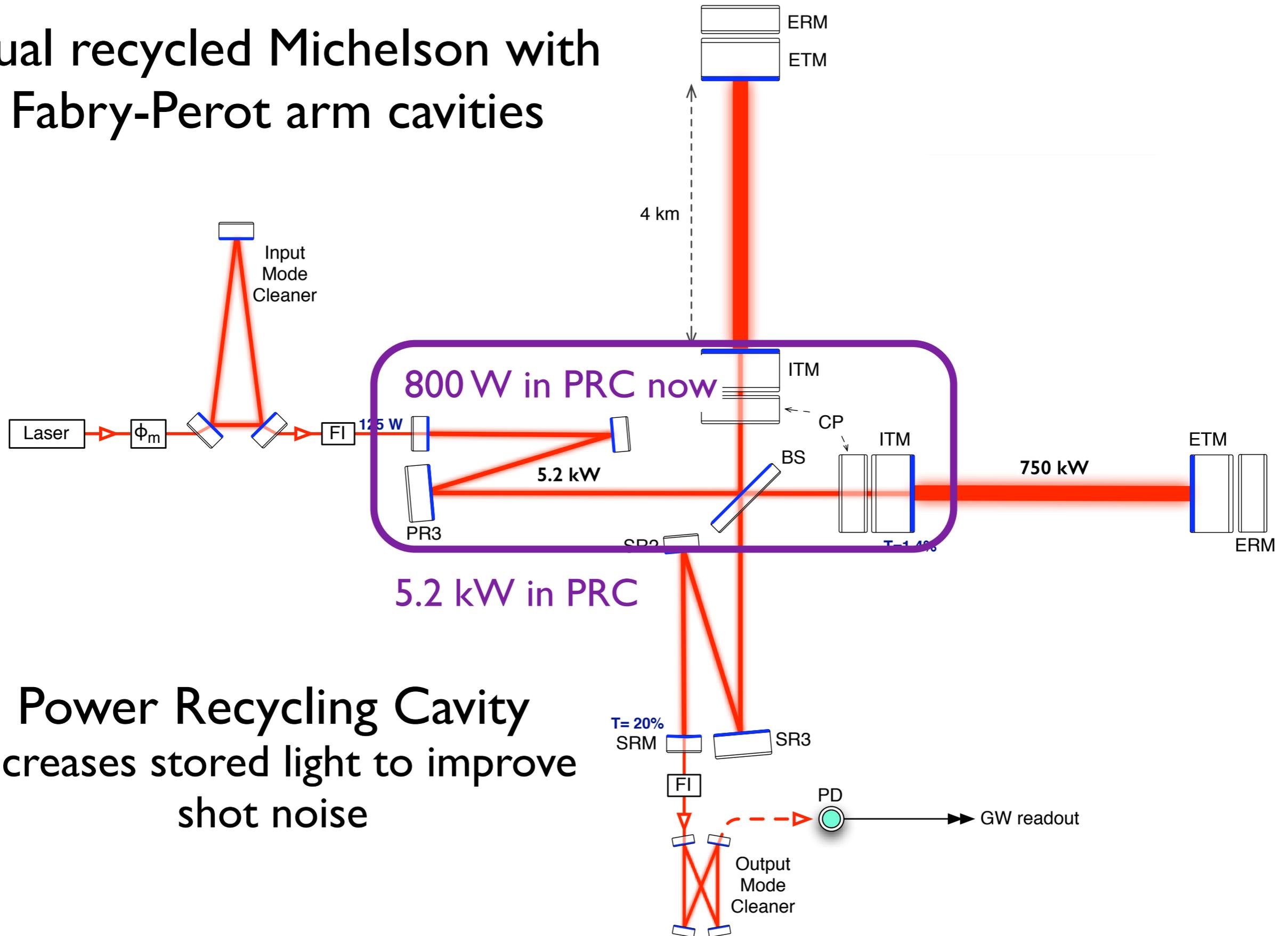
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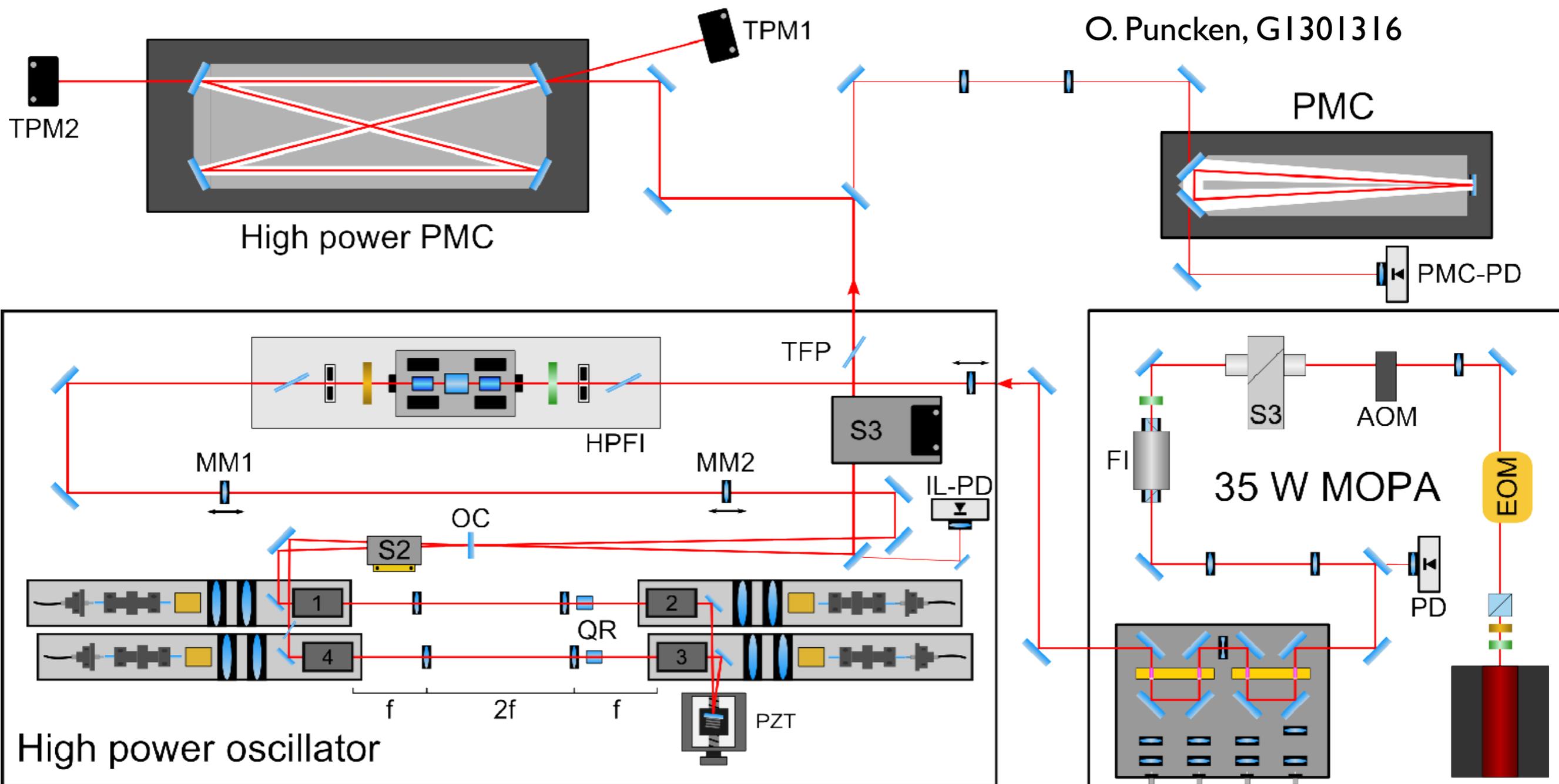


Power recycling

Dual recycled Michelson with Fabry-Perot arm cavities



Power Recycling Cavity increases stored light to improve shot noise

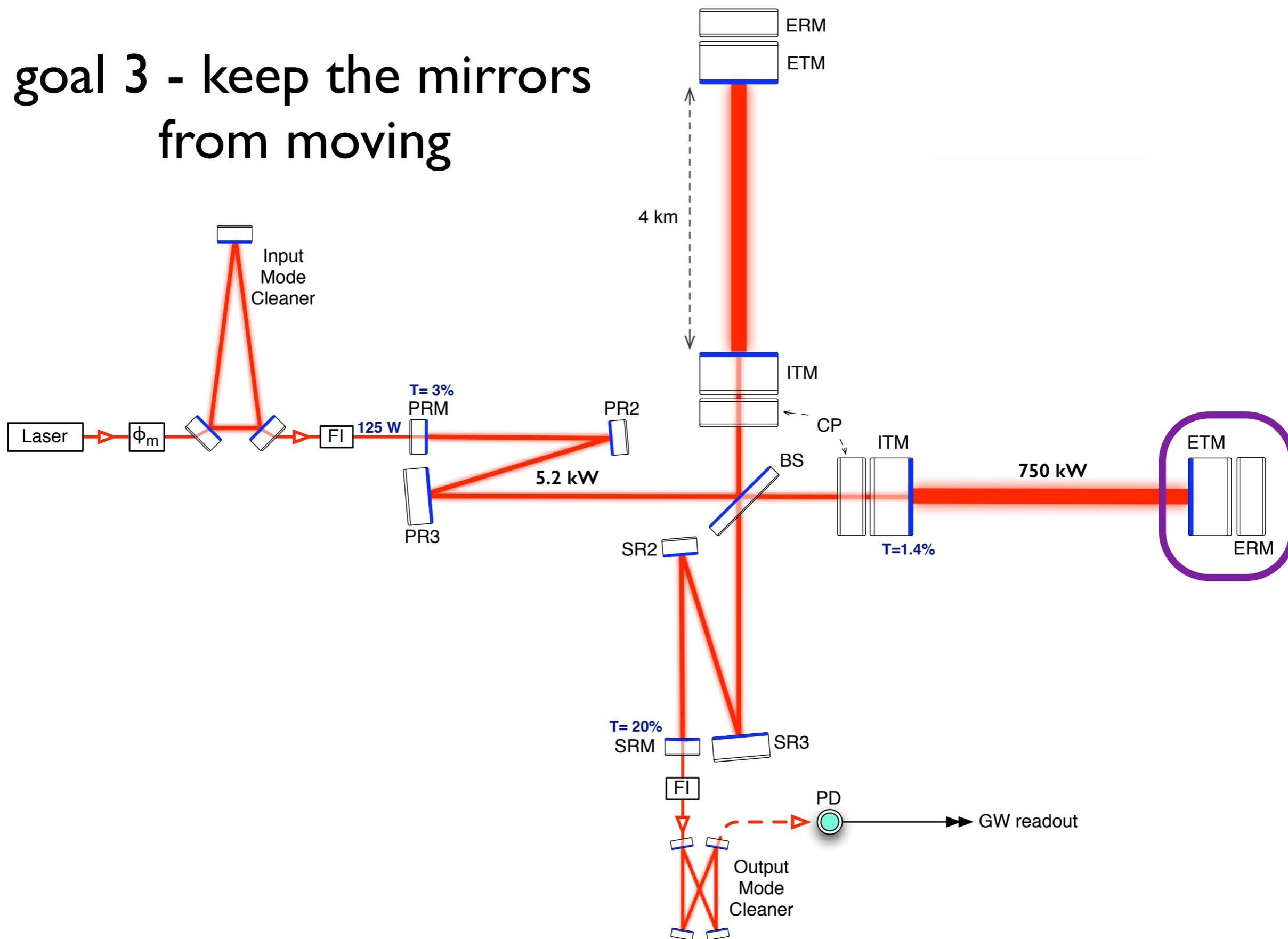


O. Puncken, GI301316

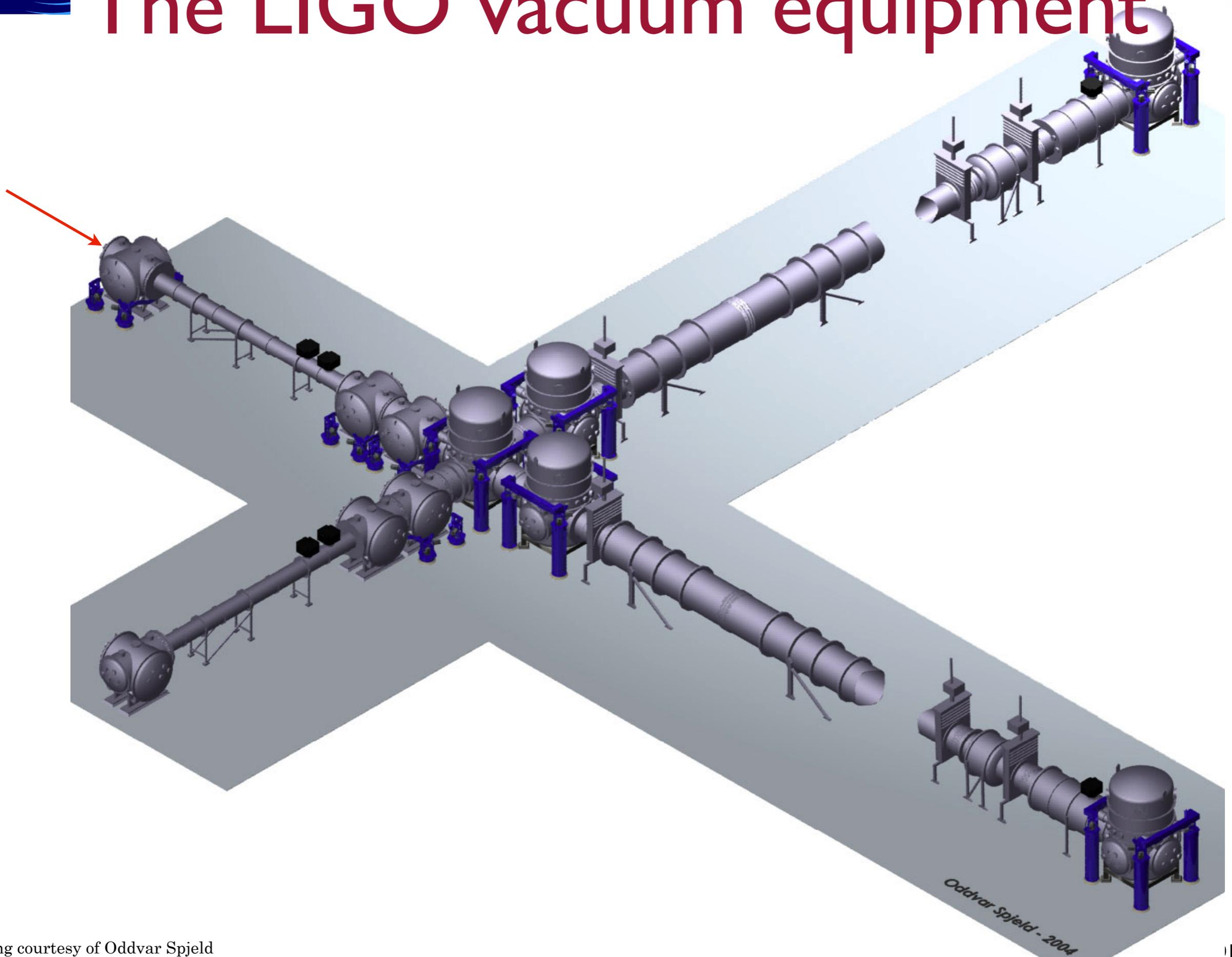
- Commercial NPRO, 2 W, Nd:YAG crystal pumped by laser diodes at 808 nm
- Medium power amp, 35 W, 4 Nd:YVO₄ crystals pumped fiber-coupled LD at 808 nm
- Ring oscillator, 220 W, 4 Nd:YAG crystals each pumped by 7 LD at 808 nm

Layout of the interferometer

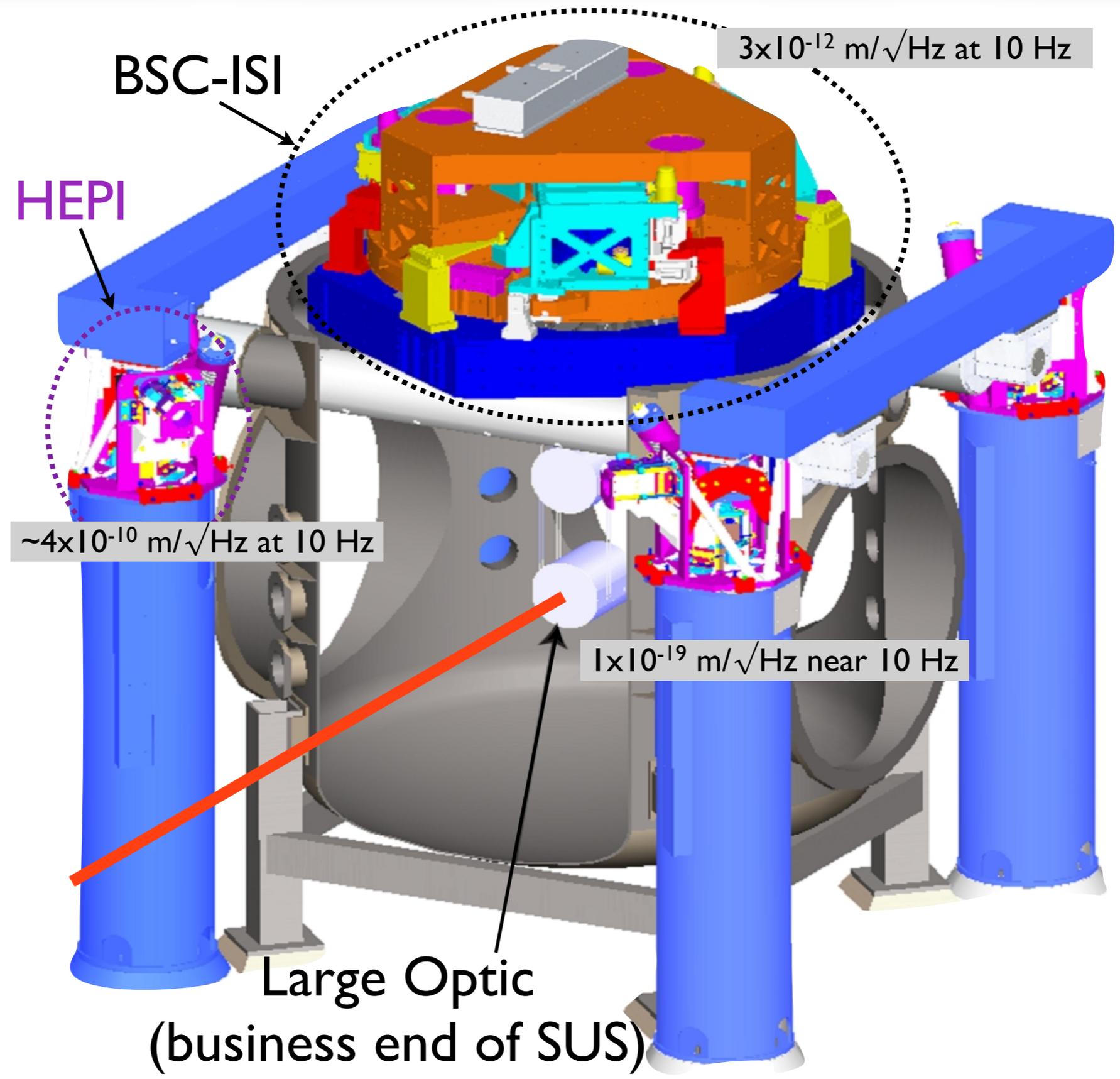
goal 3 - keep the mirrors from moving



The LIGO vacuum equipment



Overall Isolation of Test Masses

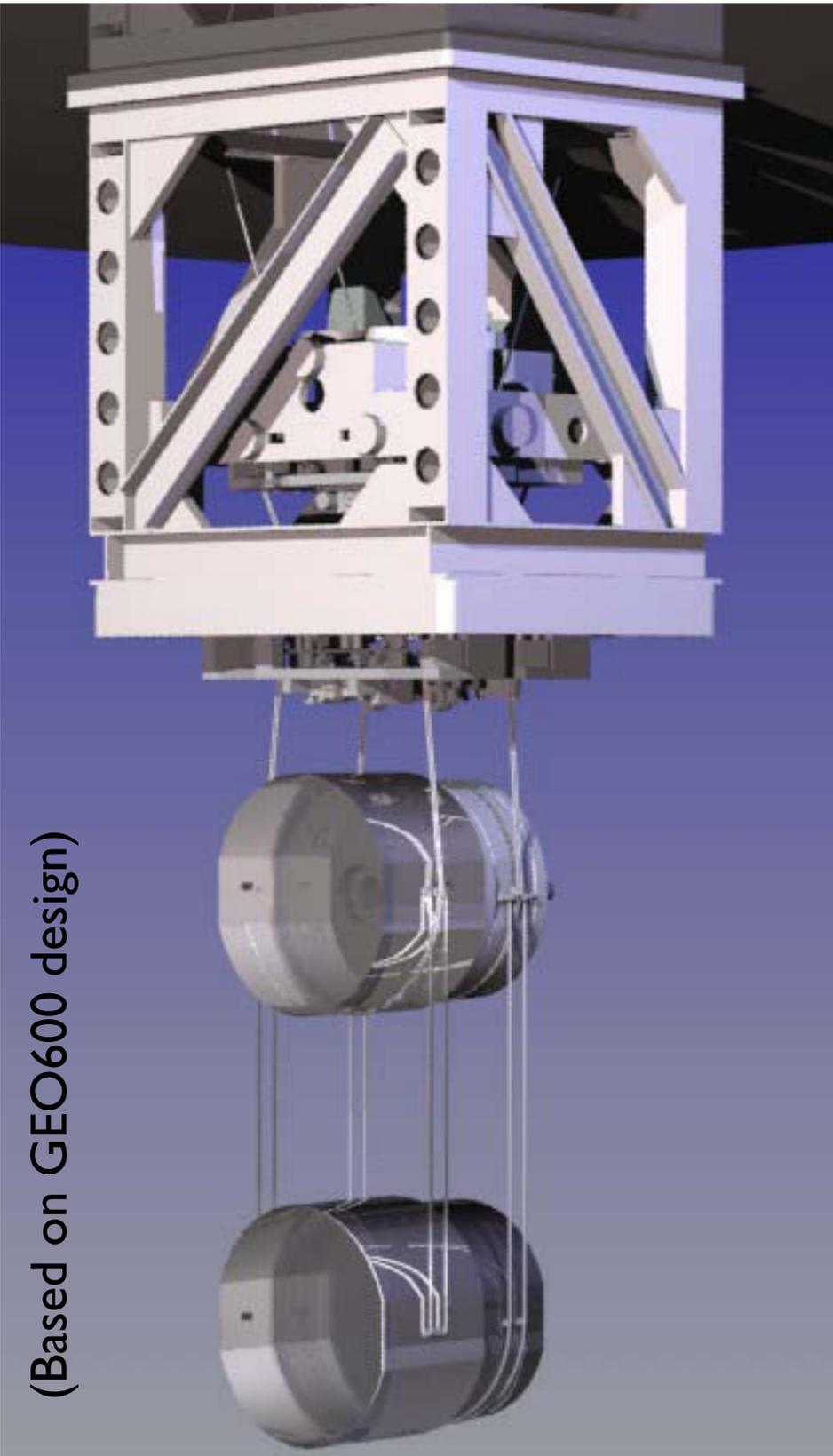
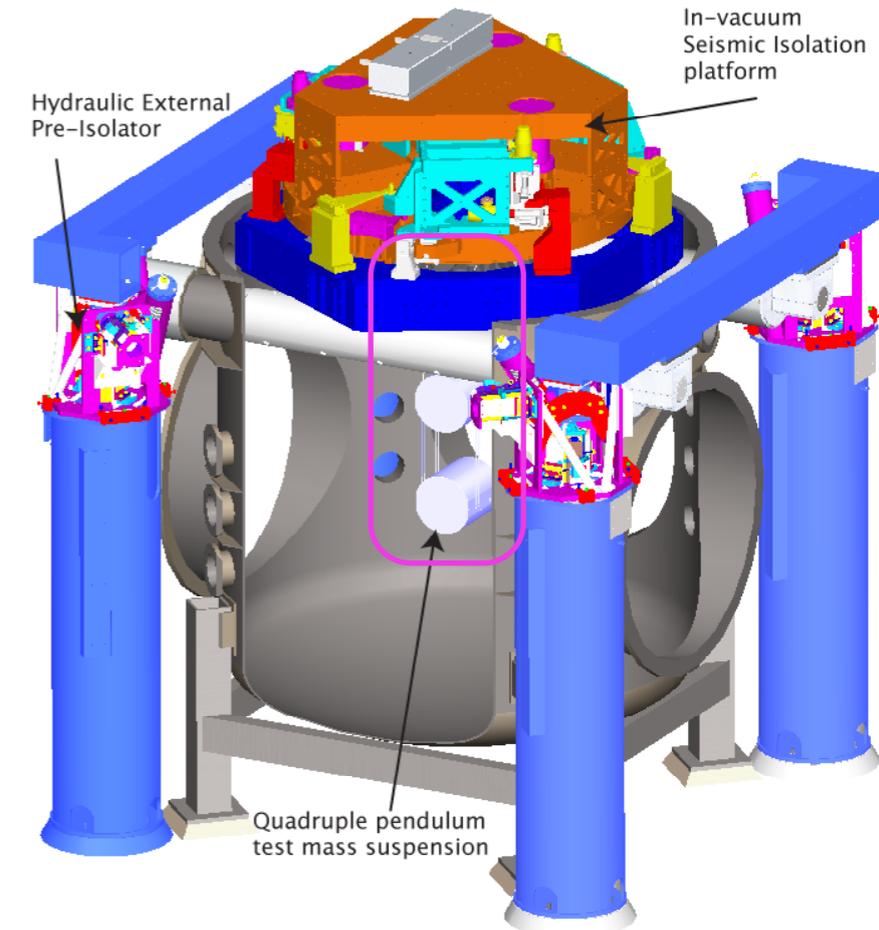


Pendulum Suspension

Suspensions material from N. Robertson, GEO600, and the SUS team

Multiple-pendulums for control flexibility & seismic attenuation

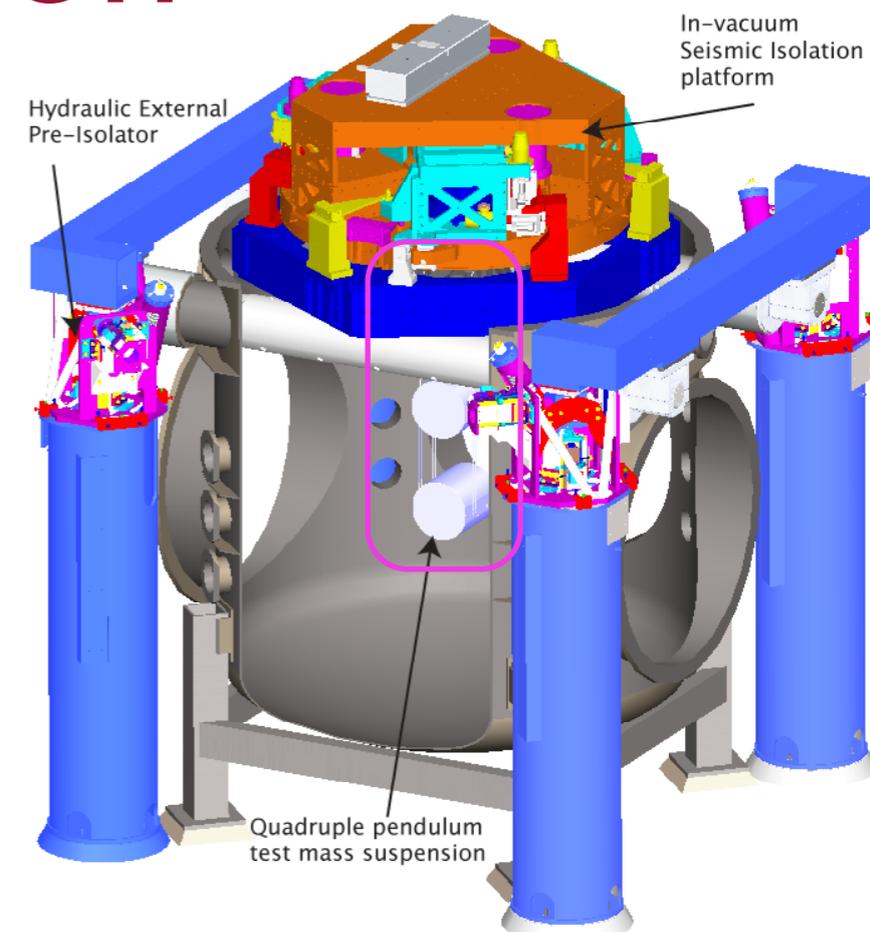
Each stage gives $\sim 1/f^2$ isolation above the natural frequency.
More than $1e6$ at 10 Hz.



(Based on GEO600 design)

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Test masses:

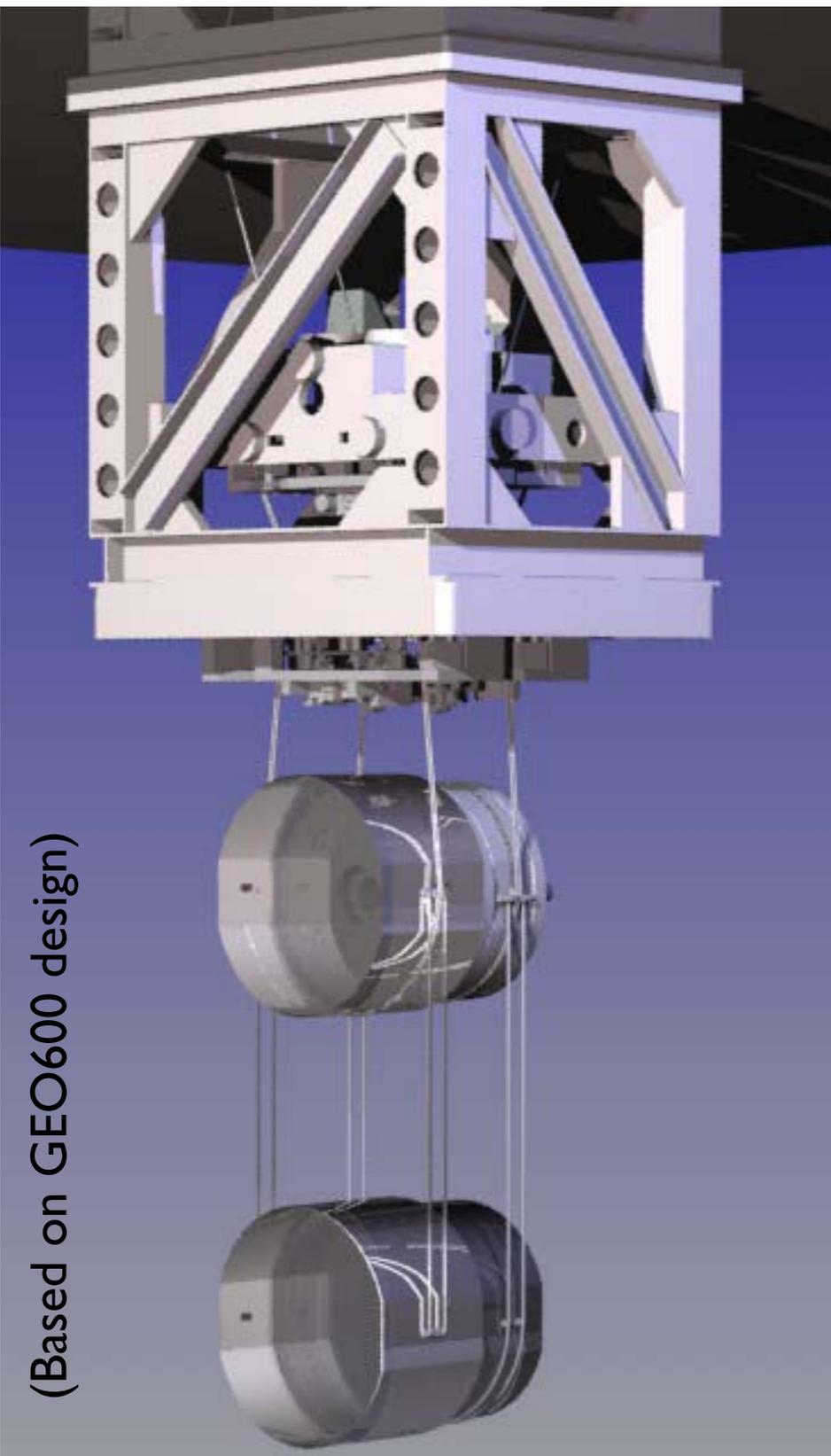
Synthetic fused silica,
40 kg, 34 cm dia.

» $Q \geq 1e7$

» low optical absorption

Final suspensions are fused silica, joined to form monolithic final stages.

Thermal vibrations at the optical surface set the performance limit of the suspension.

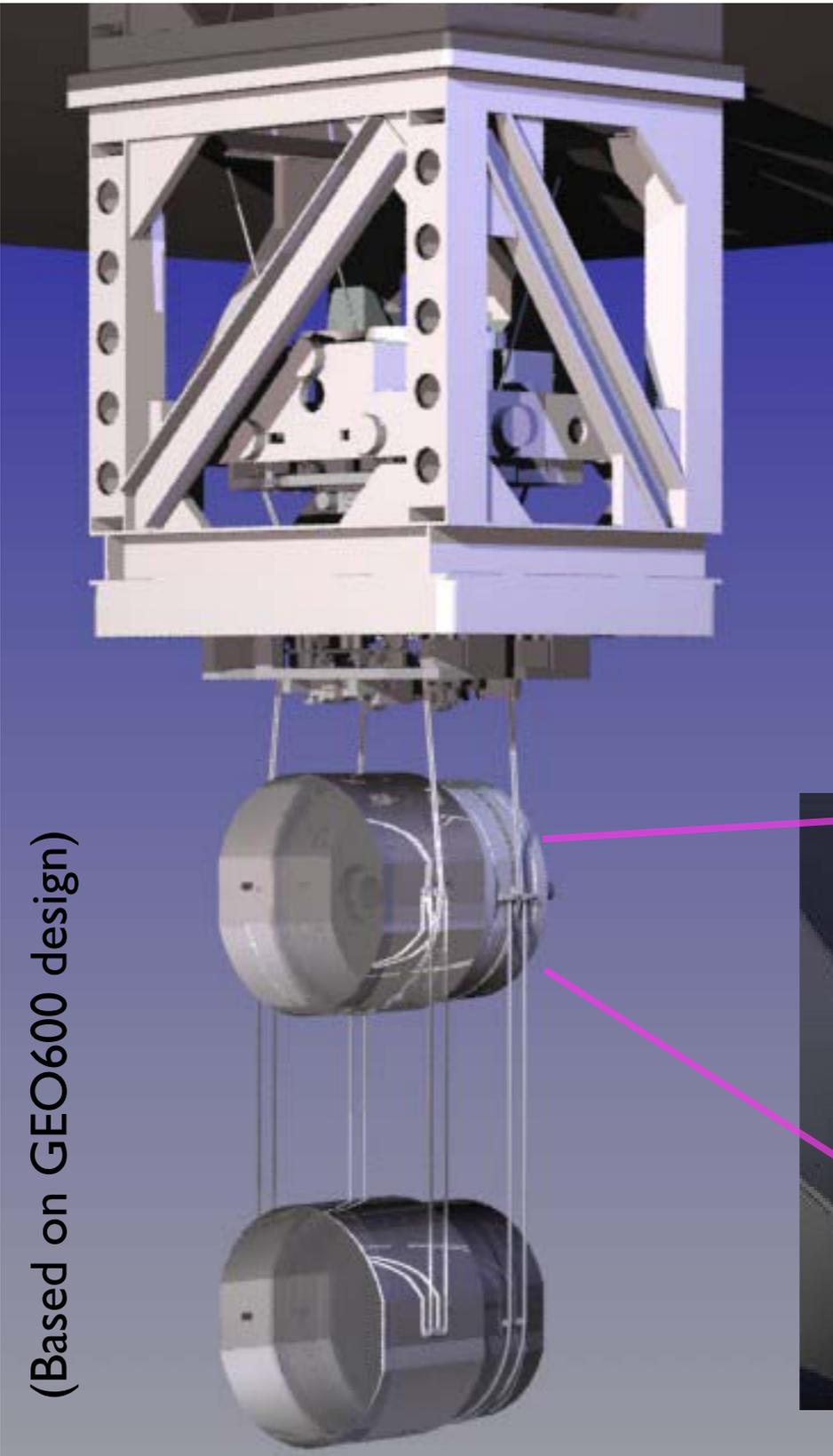
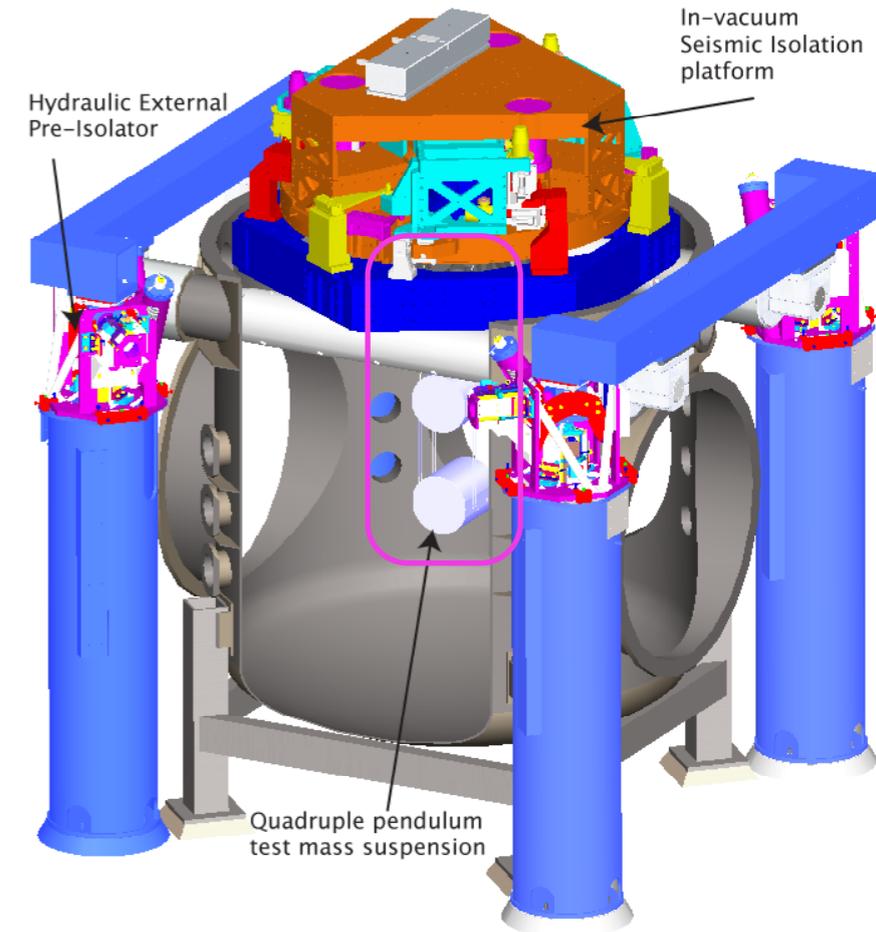


(Based on GEO600 design)

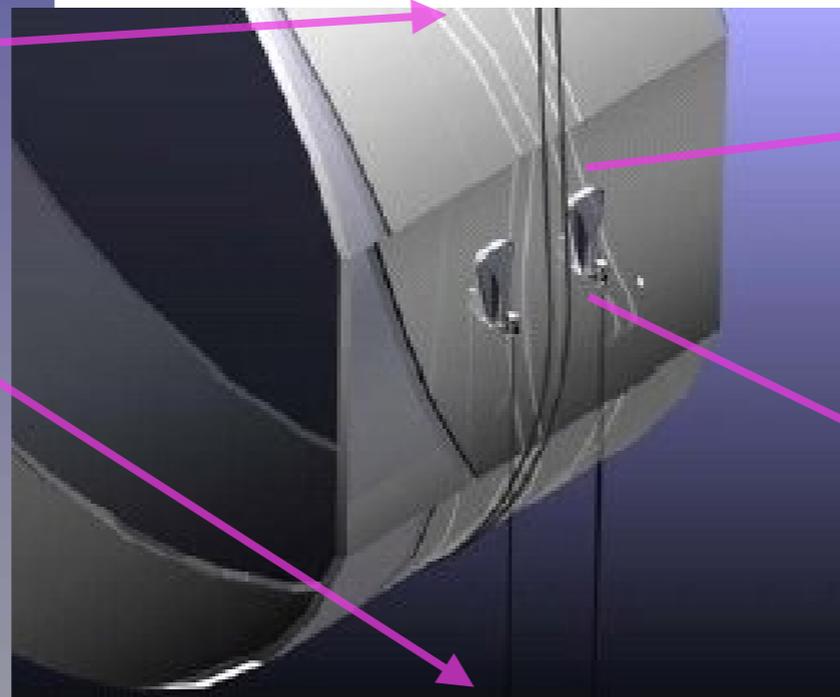
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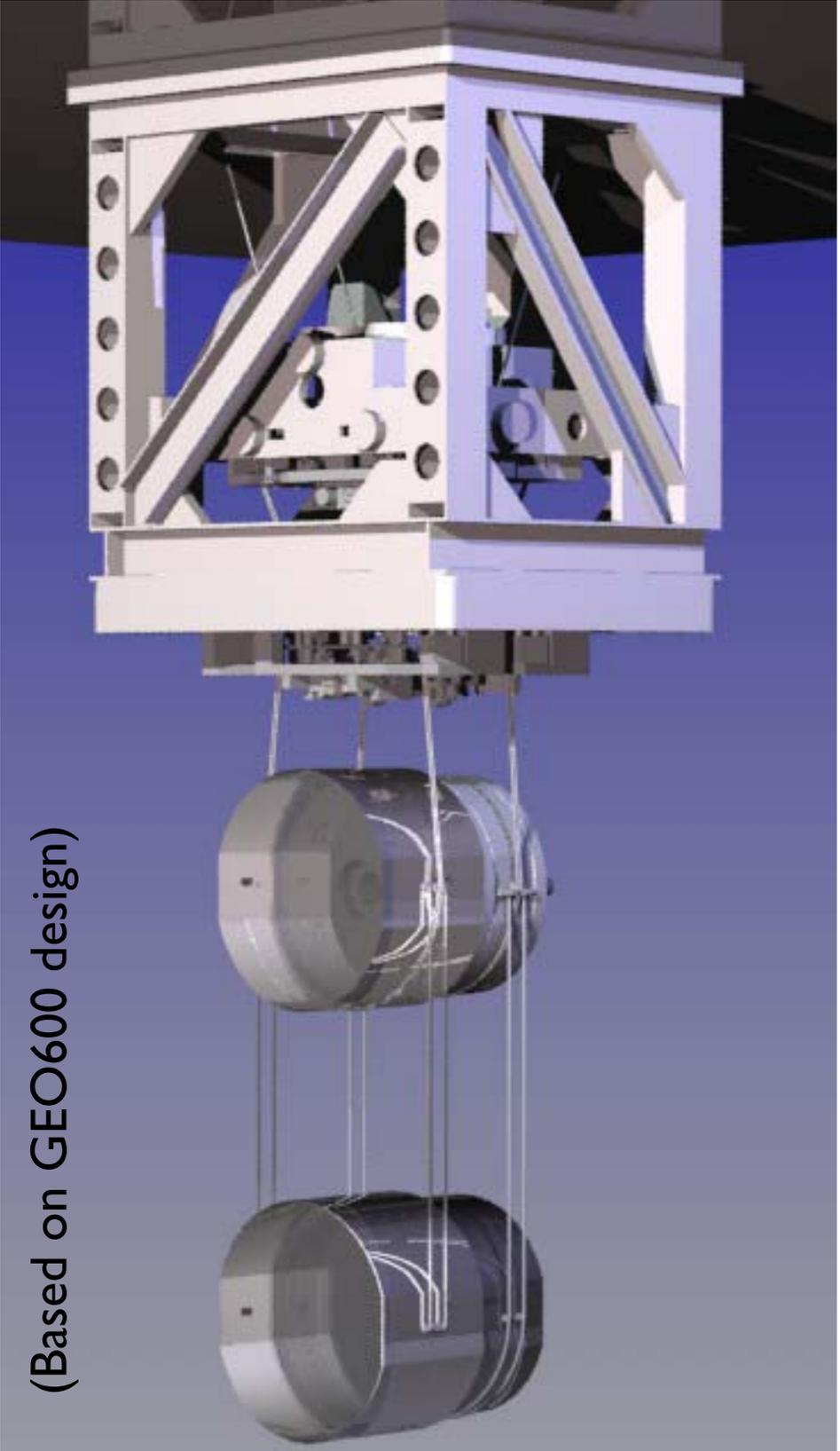


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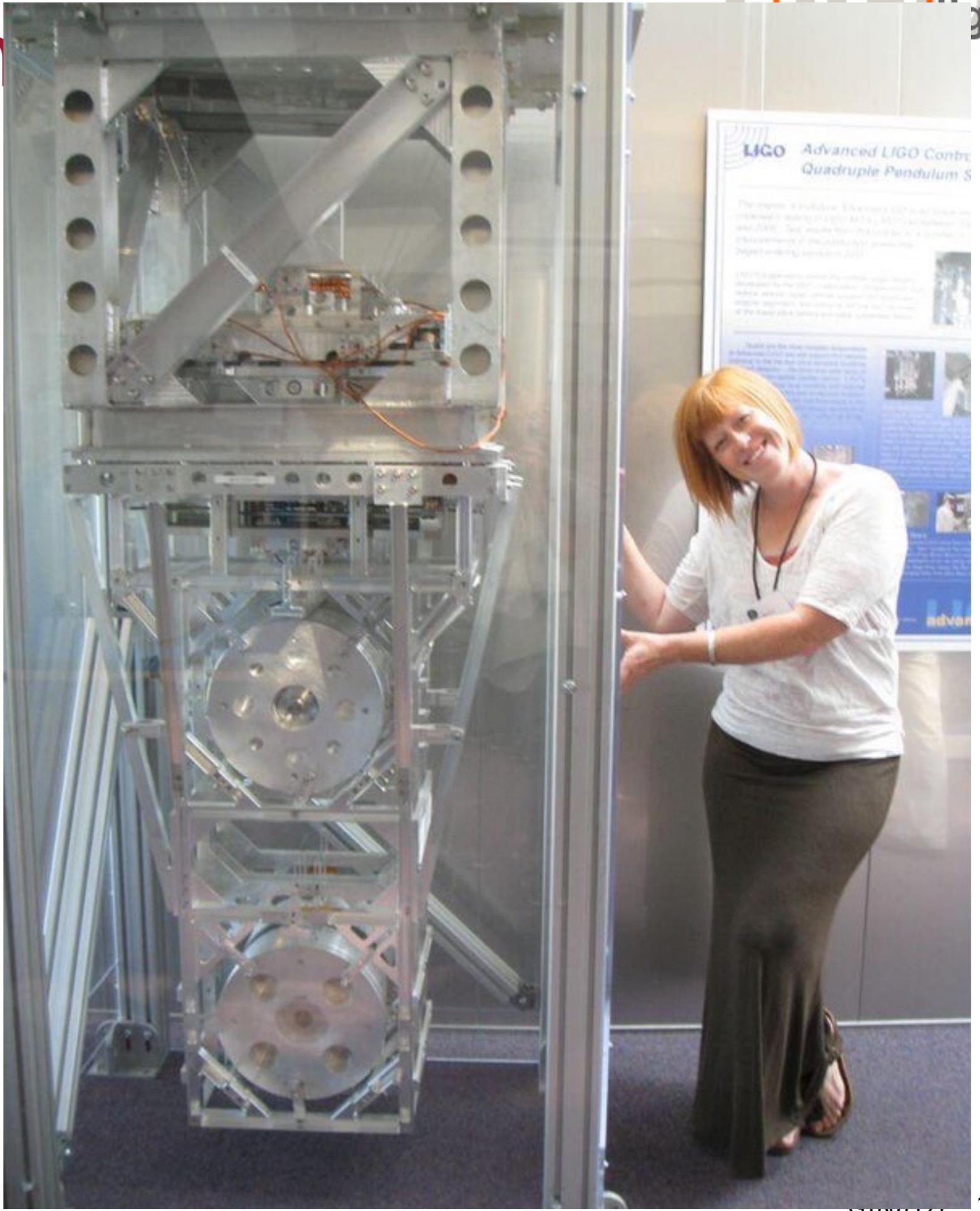
silicate bonding creates a monolithic final stage

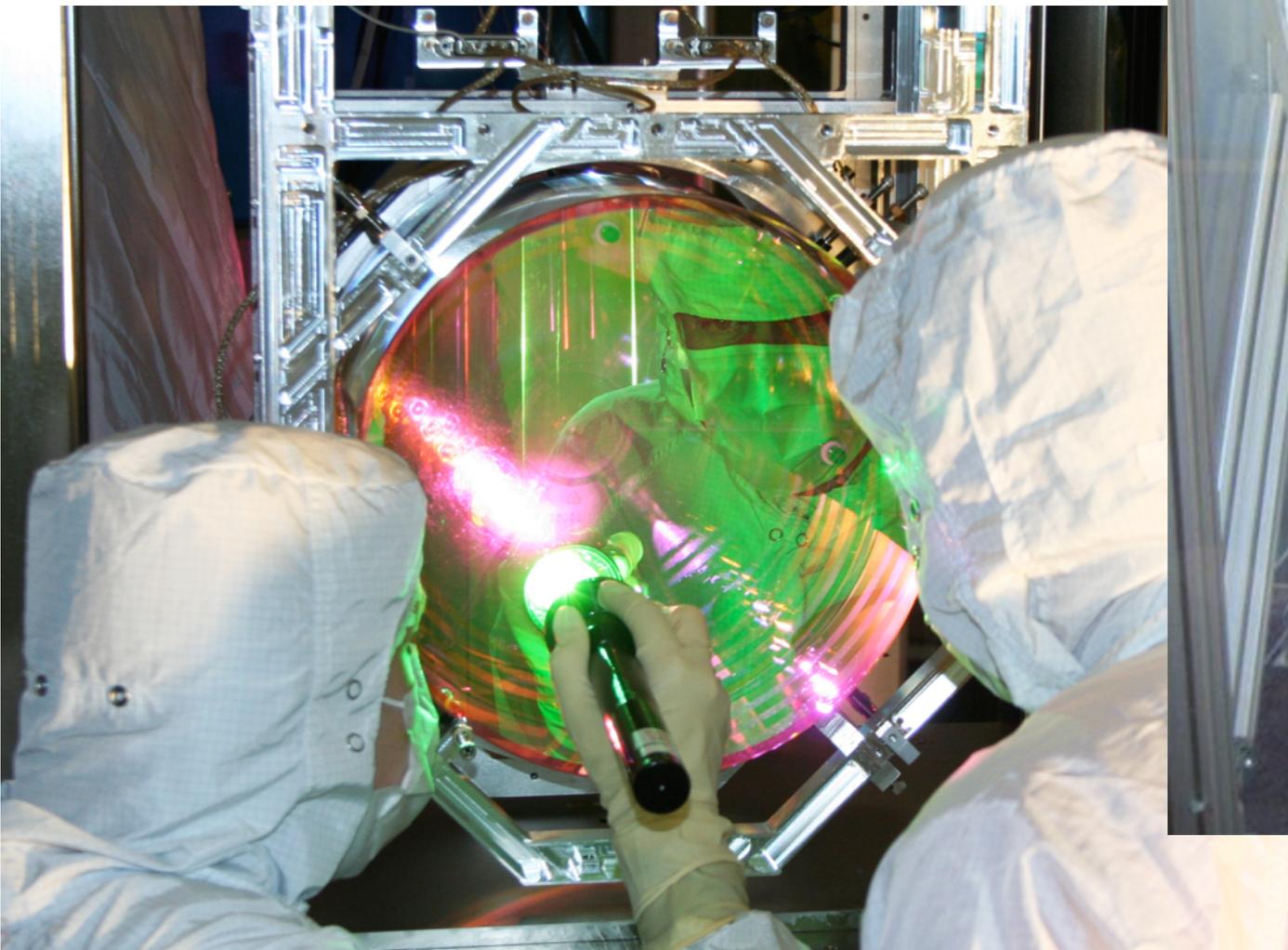
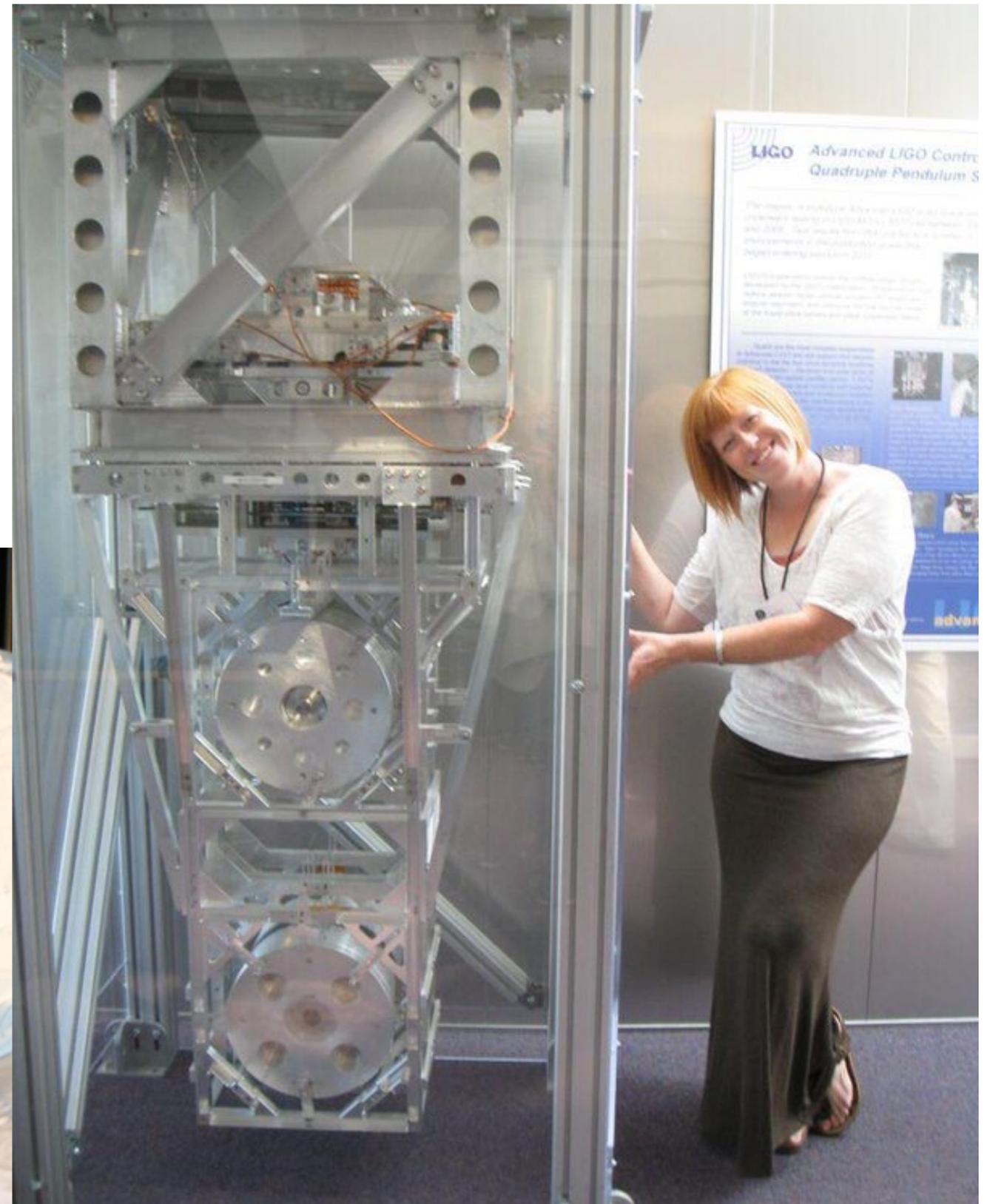
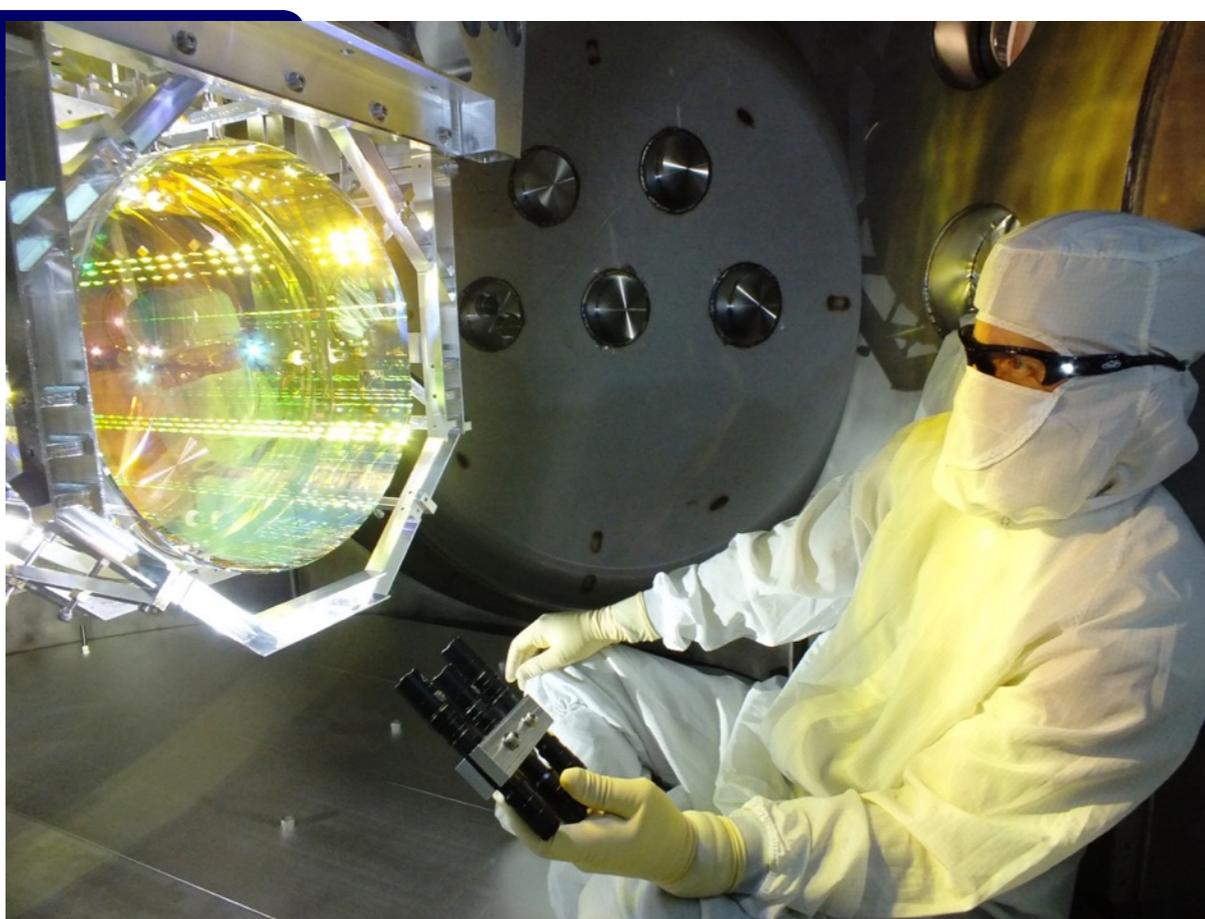
Pendulum



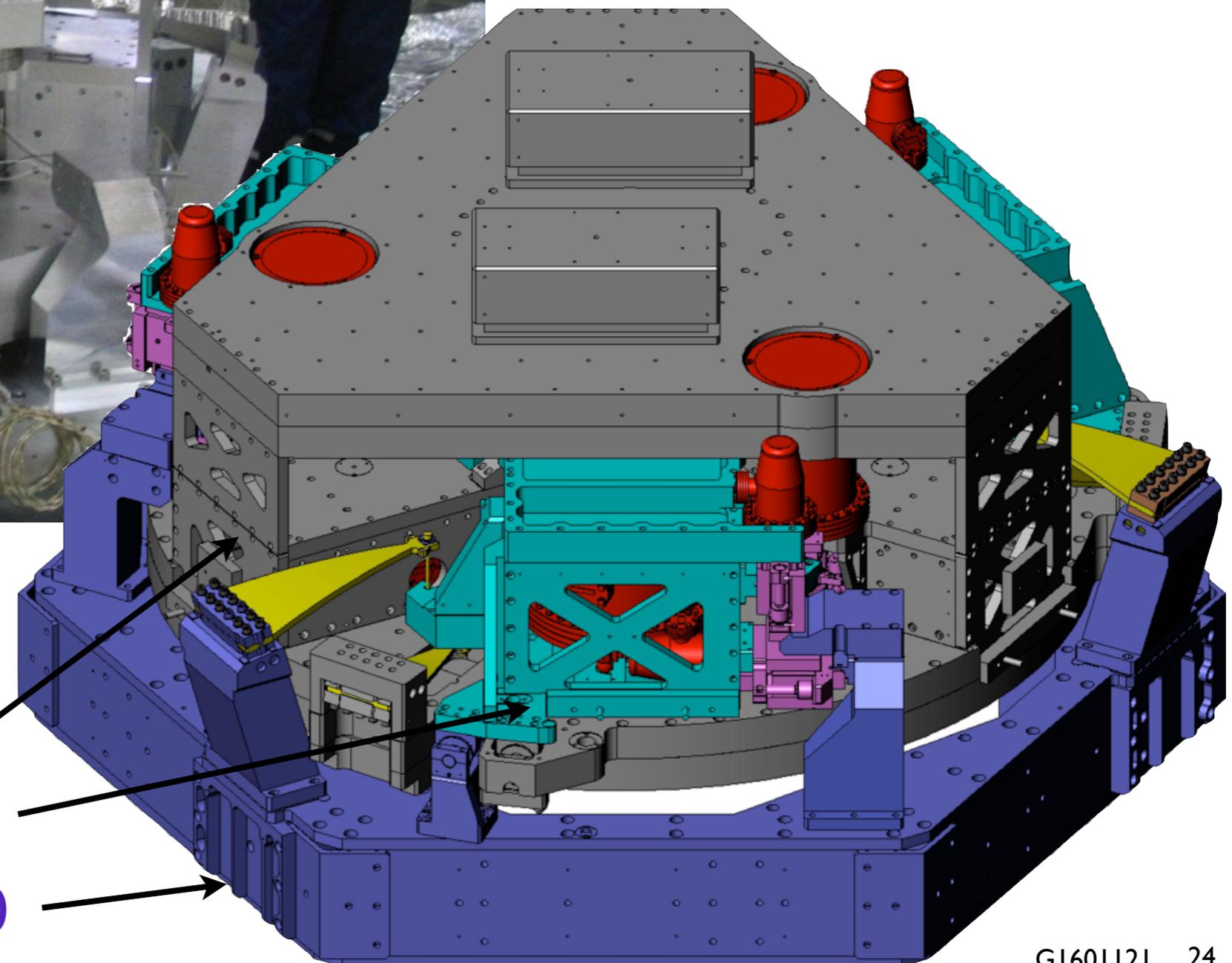
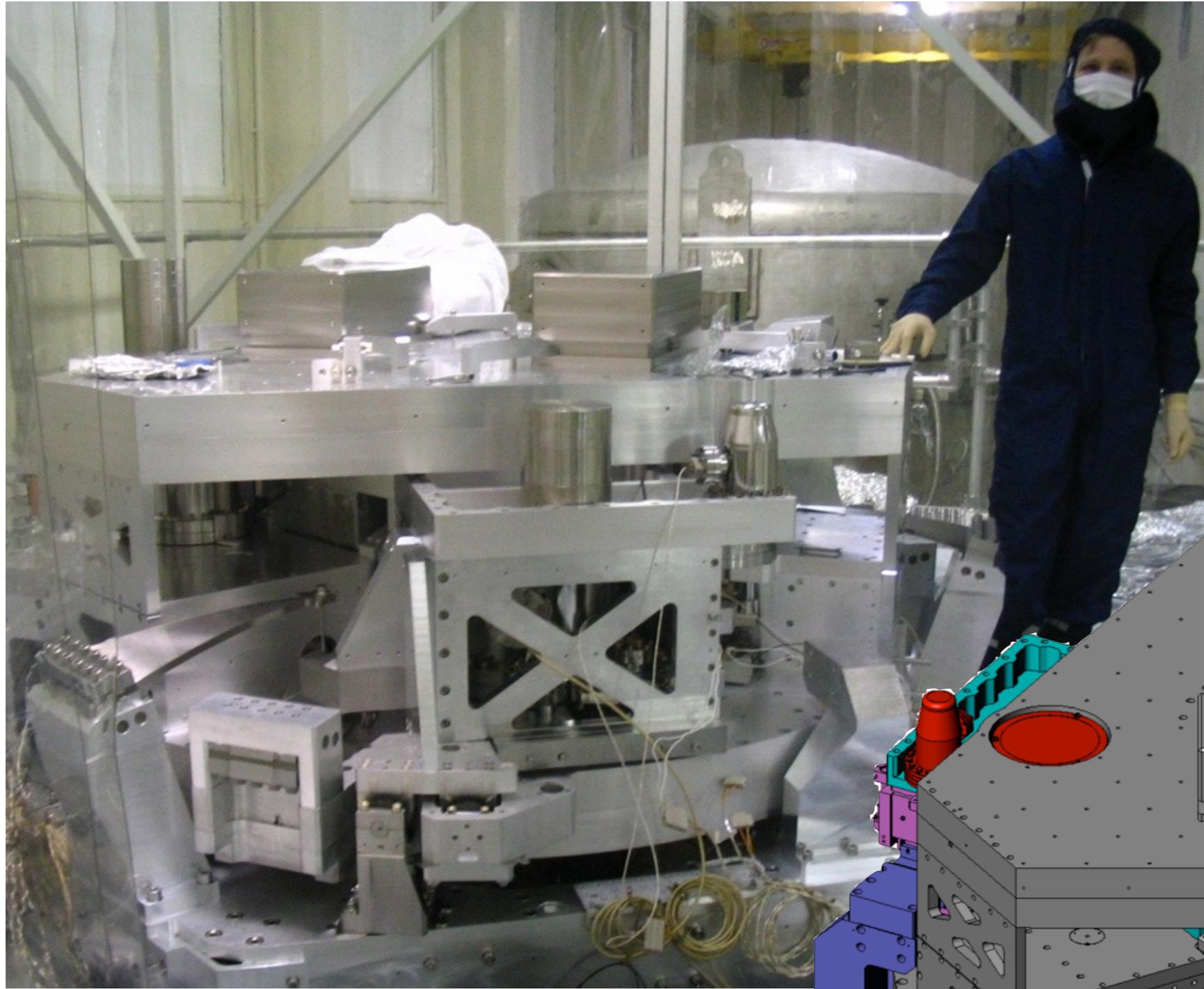
(Based on GEO600 design)

Drawings courtesy of Calum Torrie and GEO600





BSC-ISI

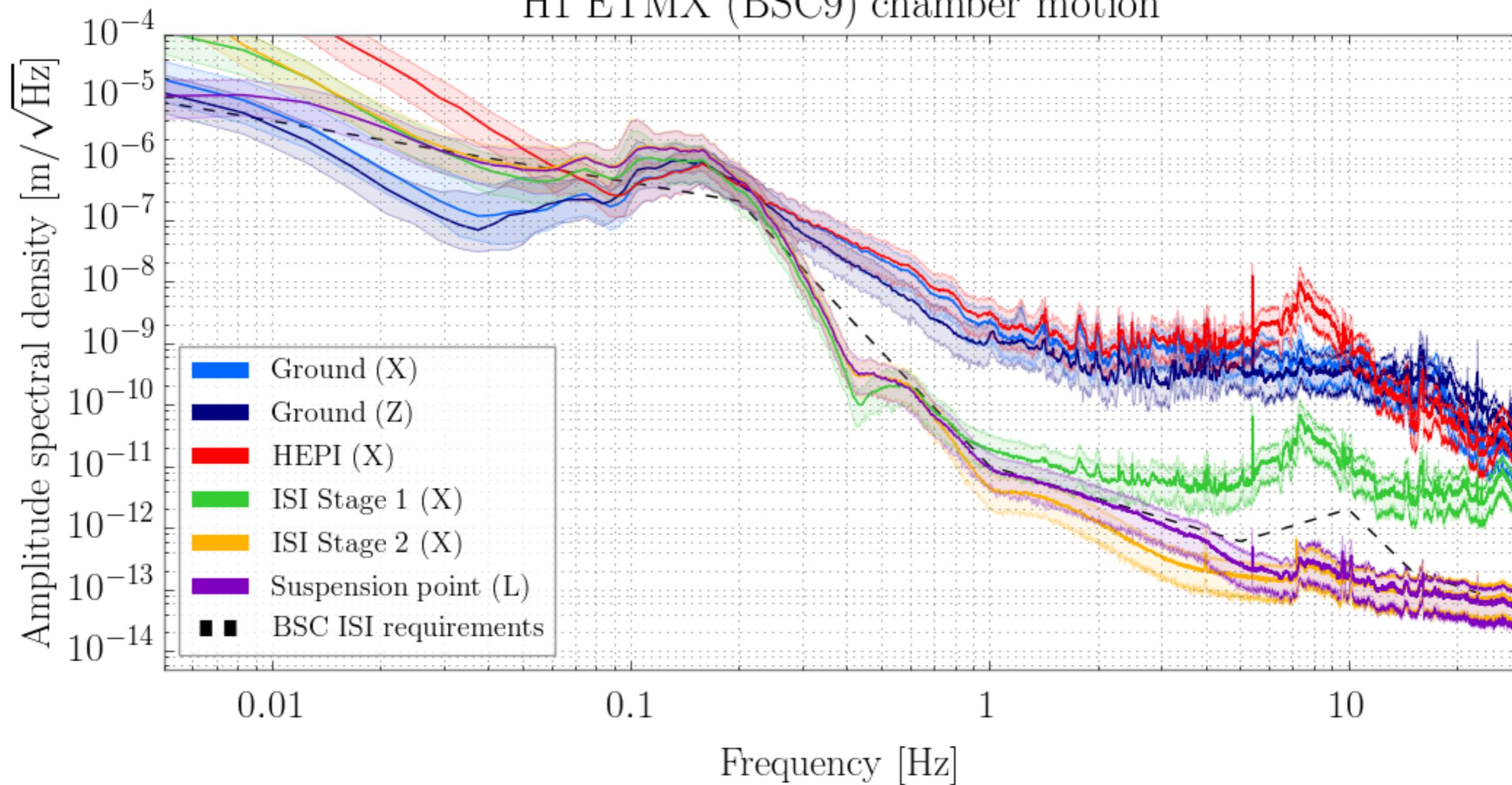


optics table - stage 2
stage 1
support - stage 0

'Typical' performance

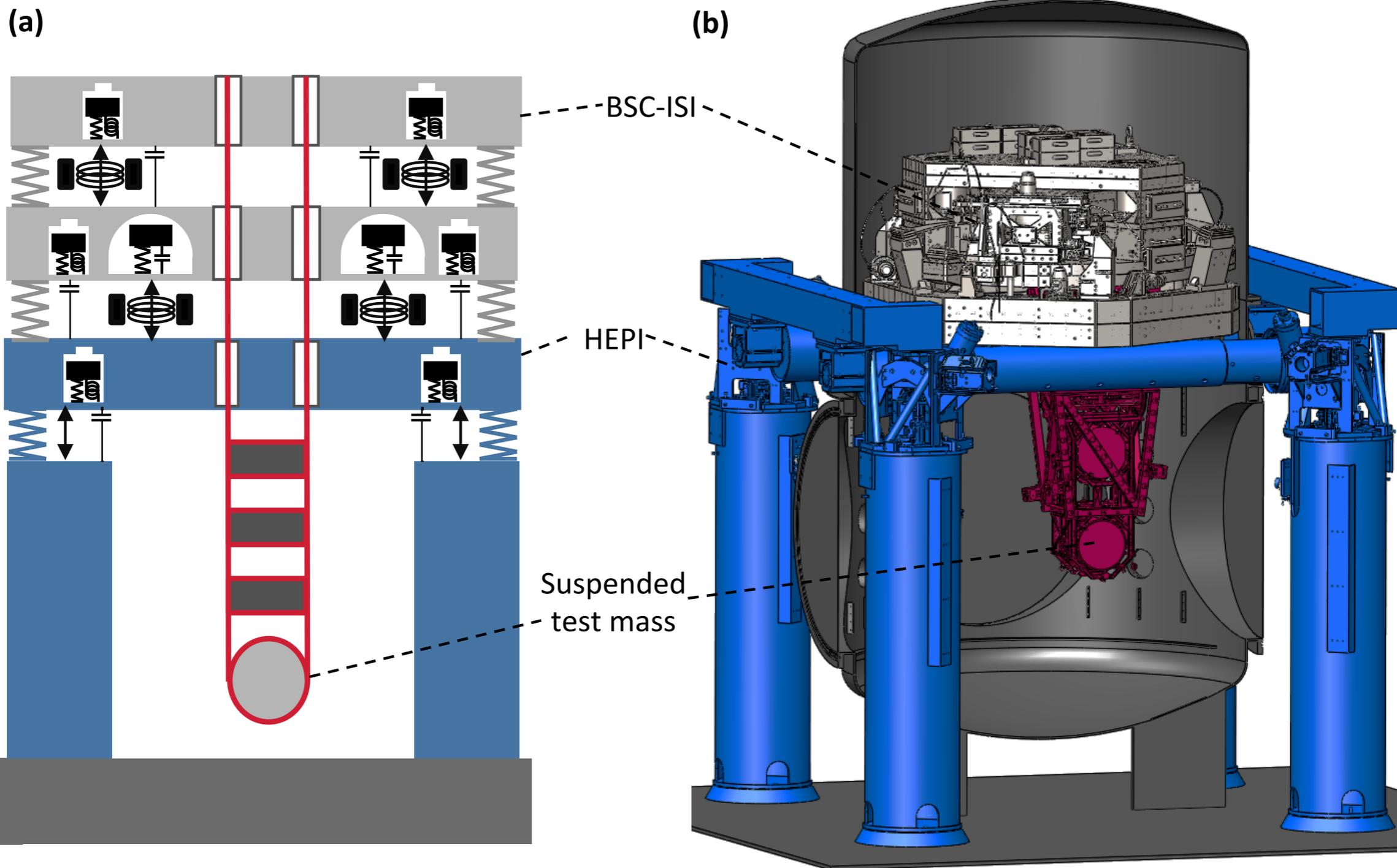
[1132704017-1132790417, state: ISI ODC]

H1 ETMX (BSC9) chamber motion



Signals for processing

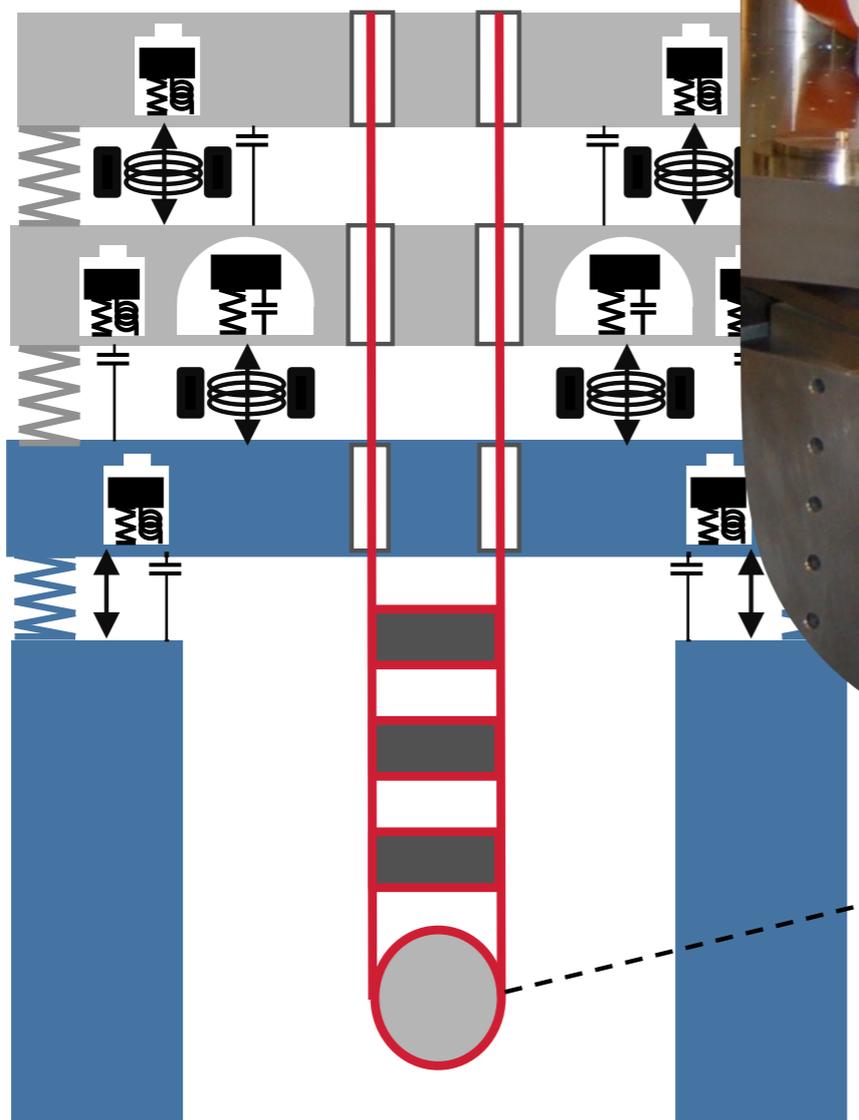
Use active and passive techniques to get good performance



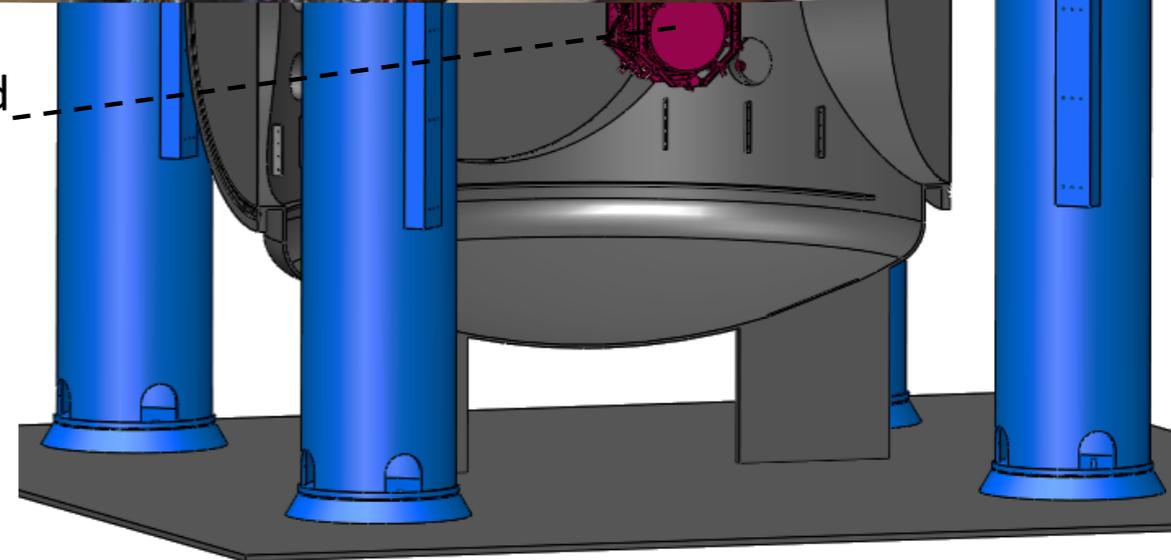
Signals for processing

Use active and passive techniques to get good performance

(a)



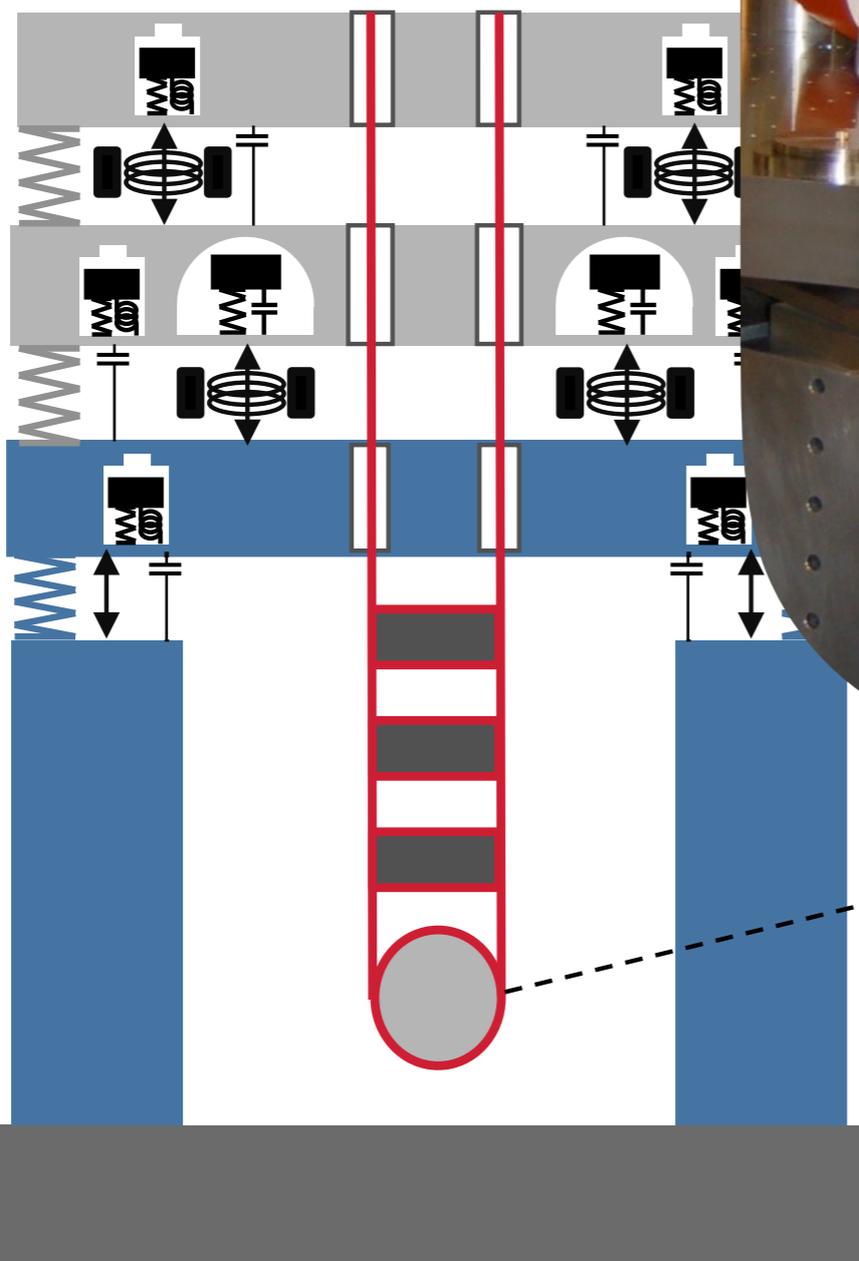
Suspended test mass



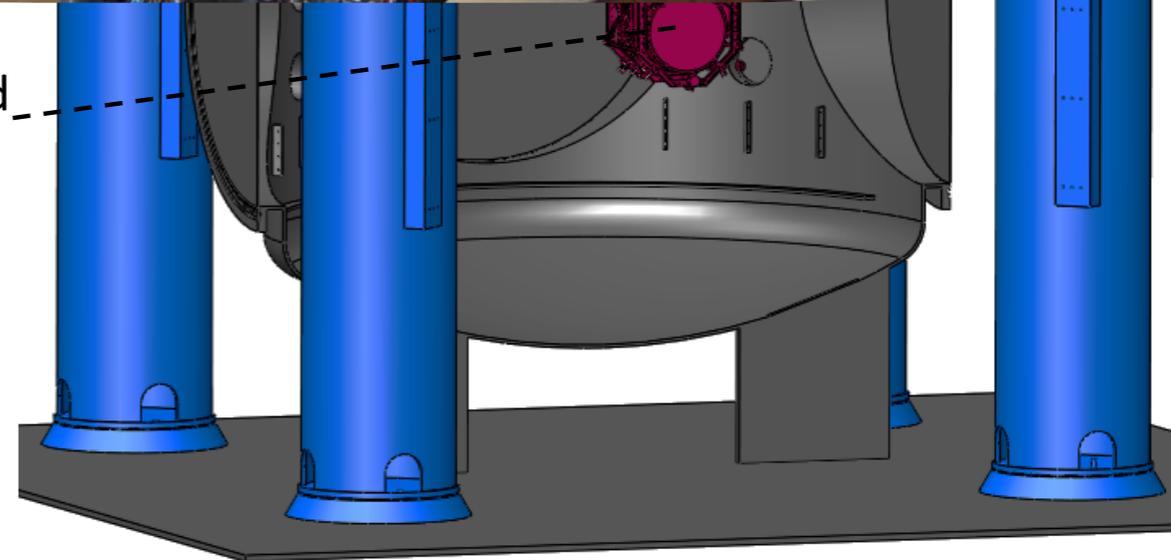
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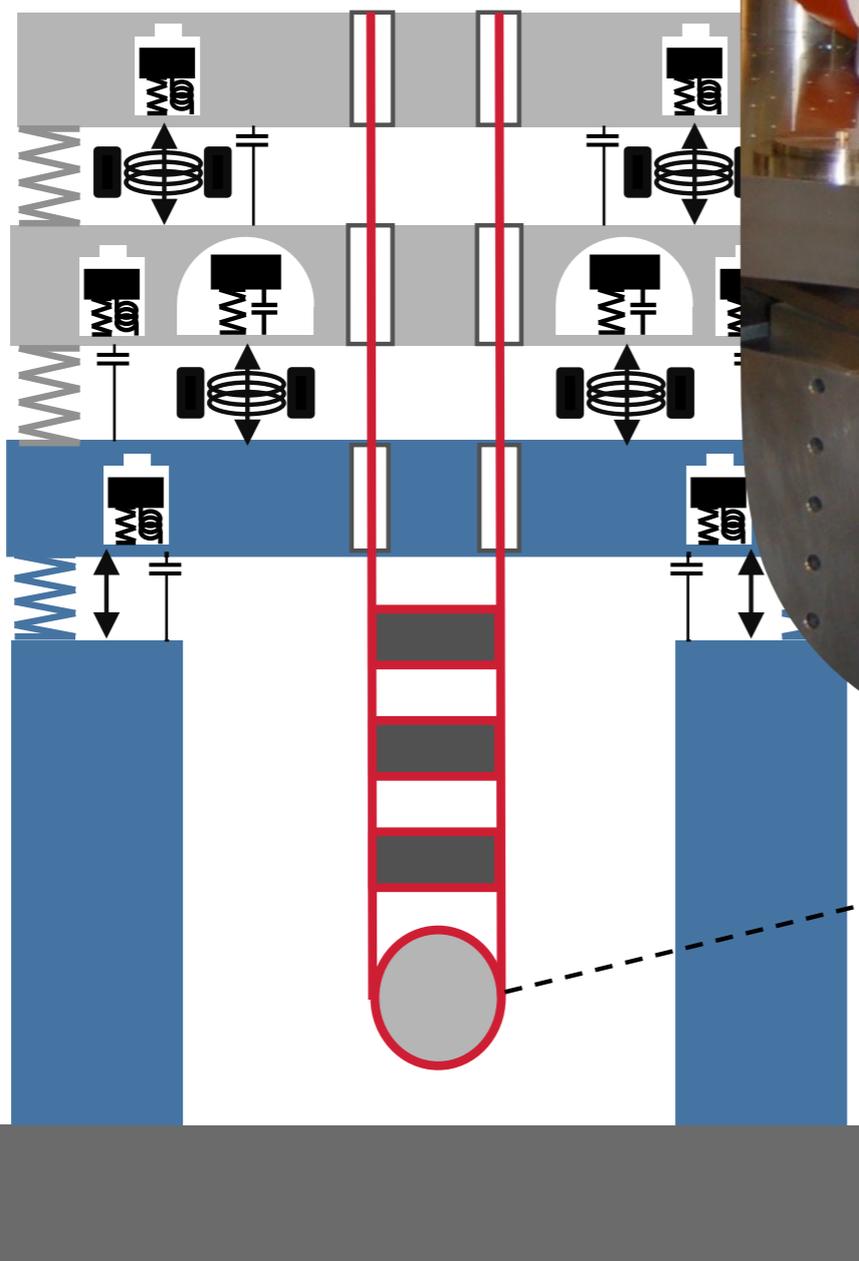
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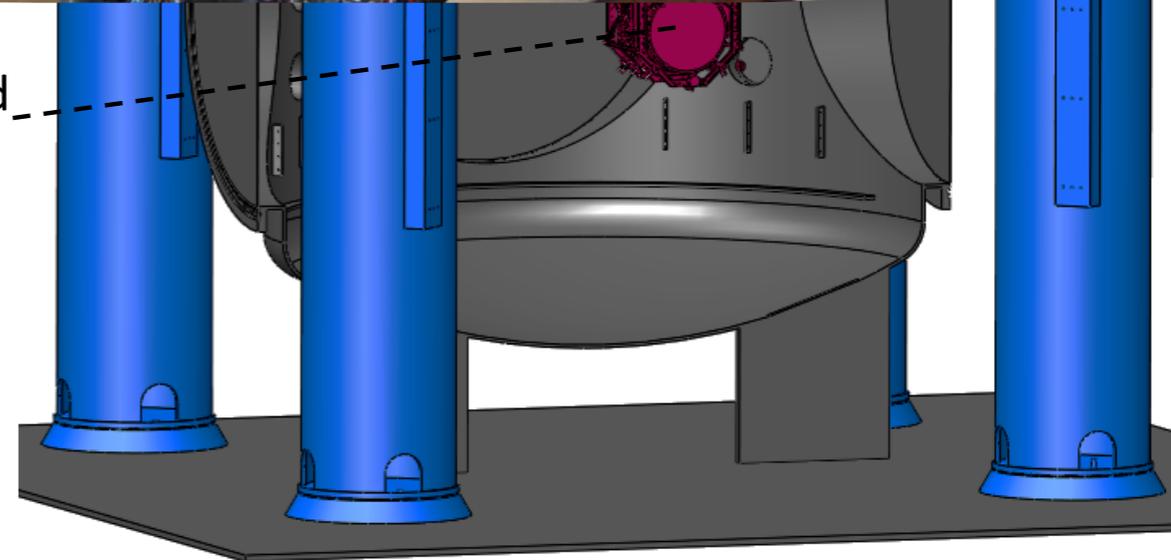
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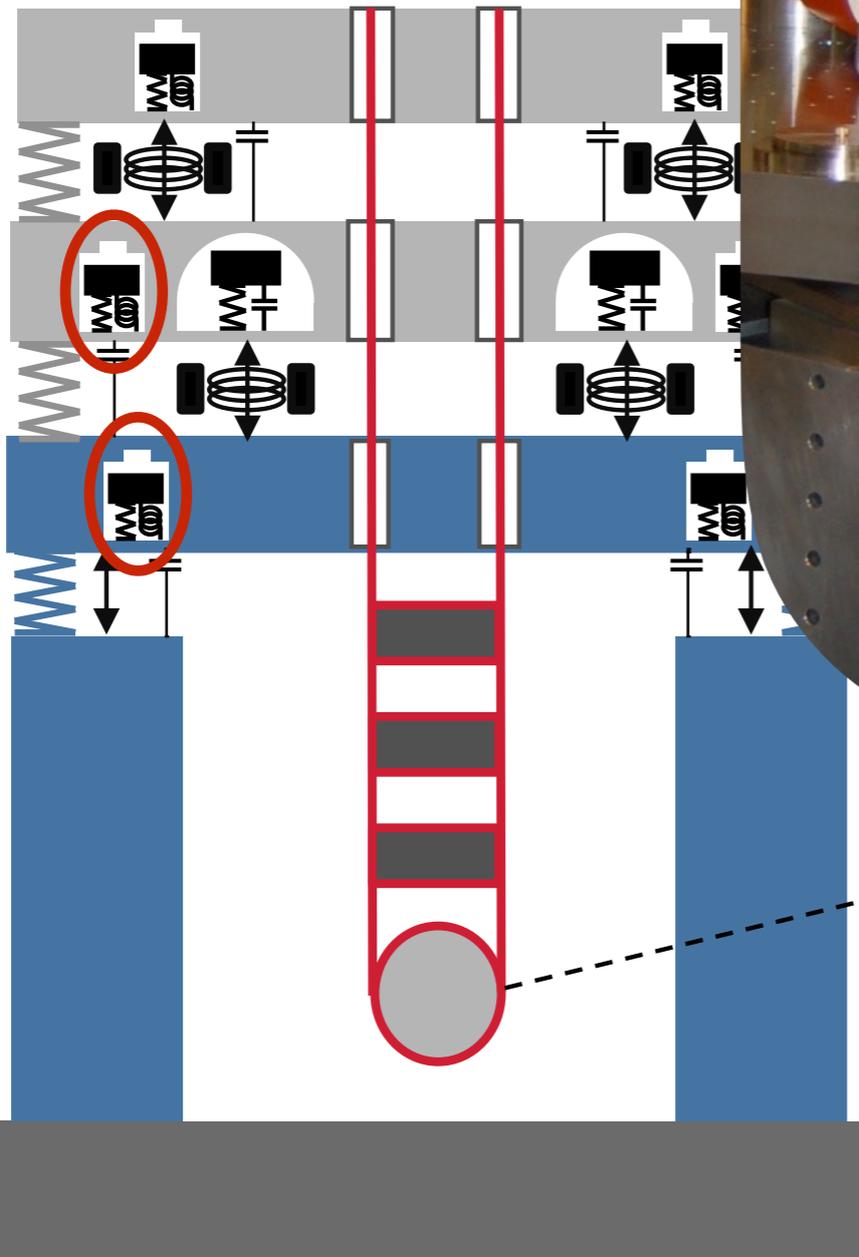
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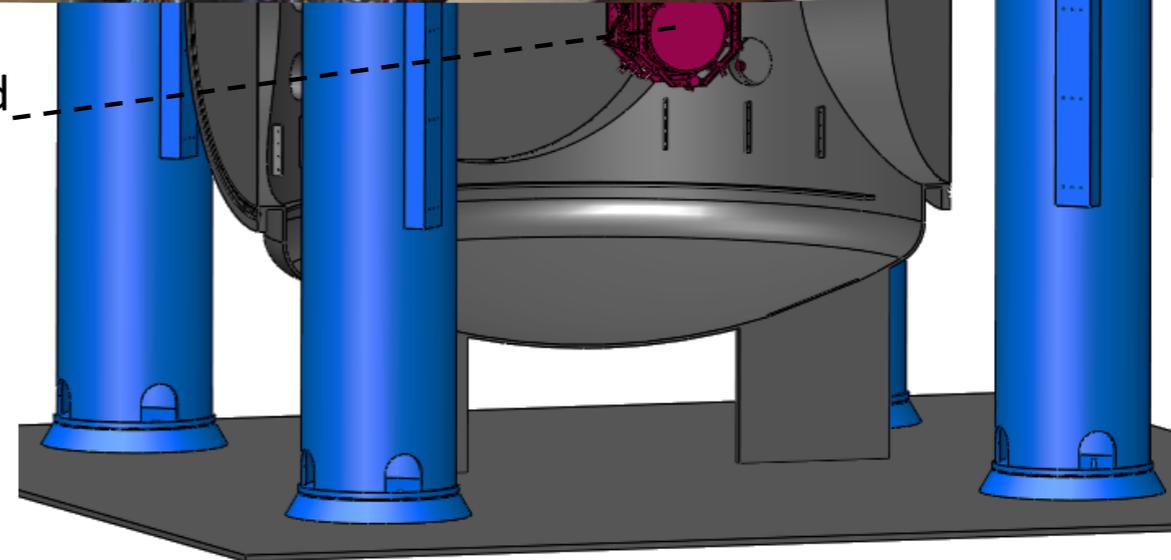
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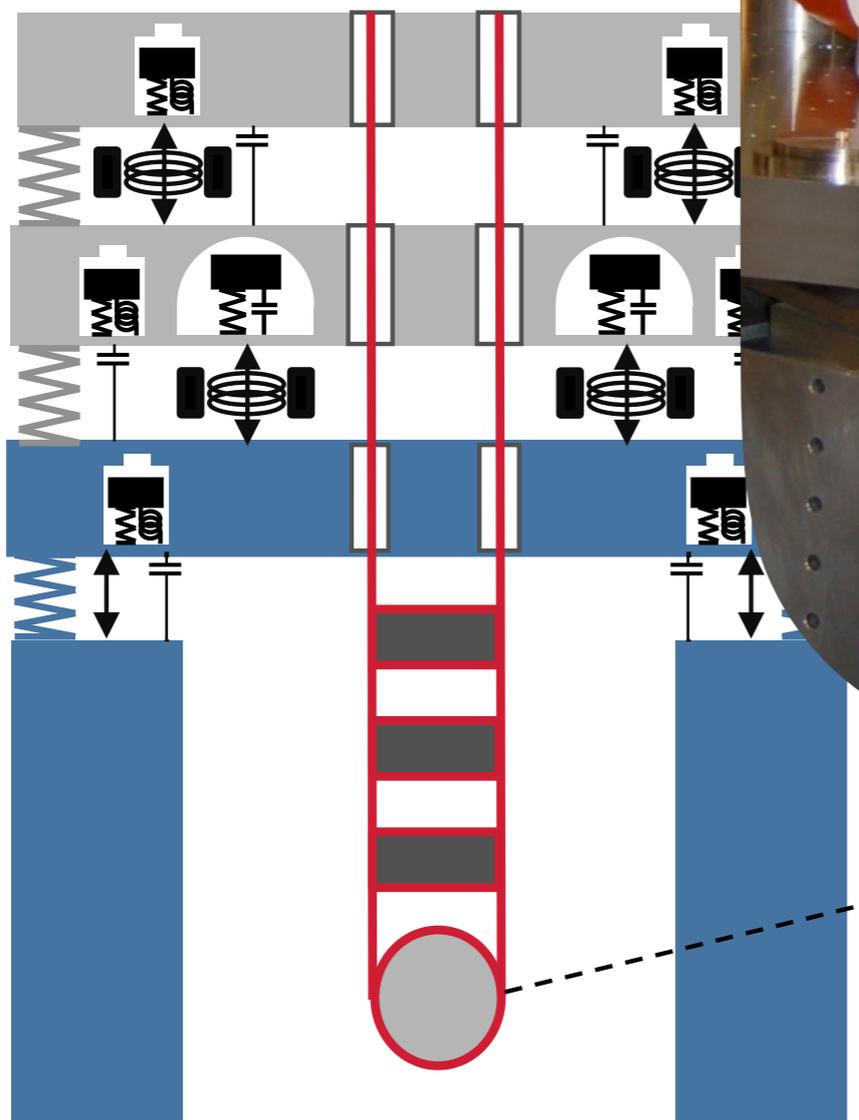
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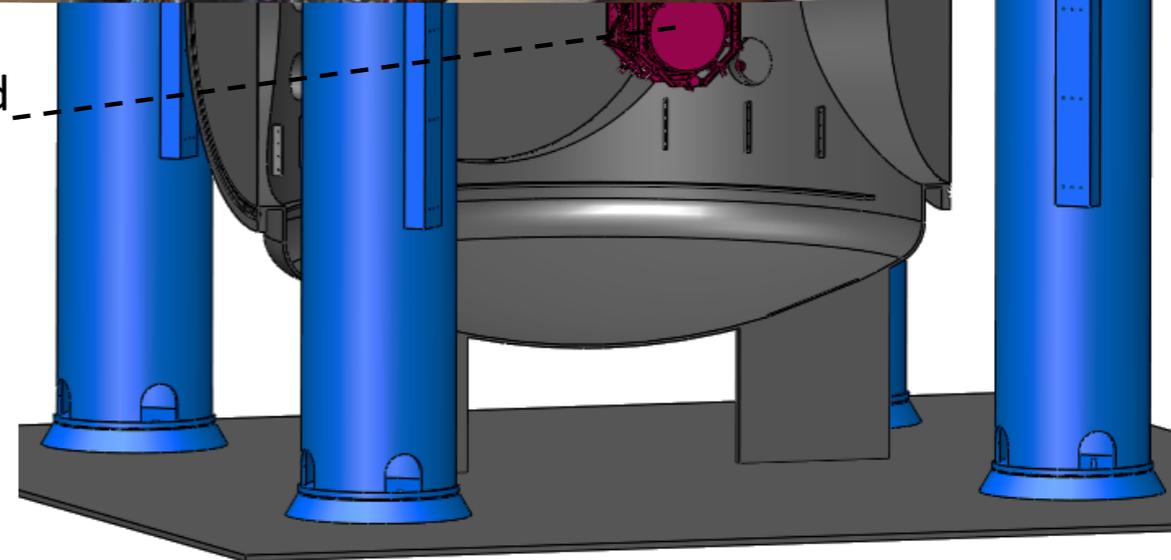
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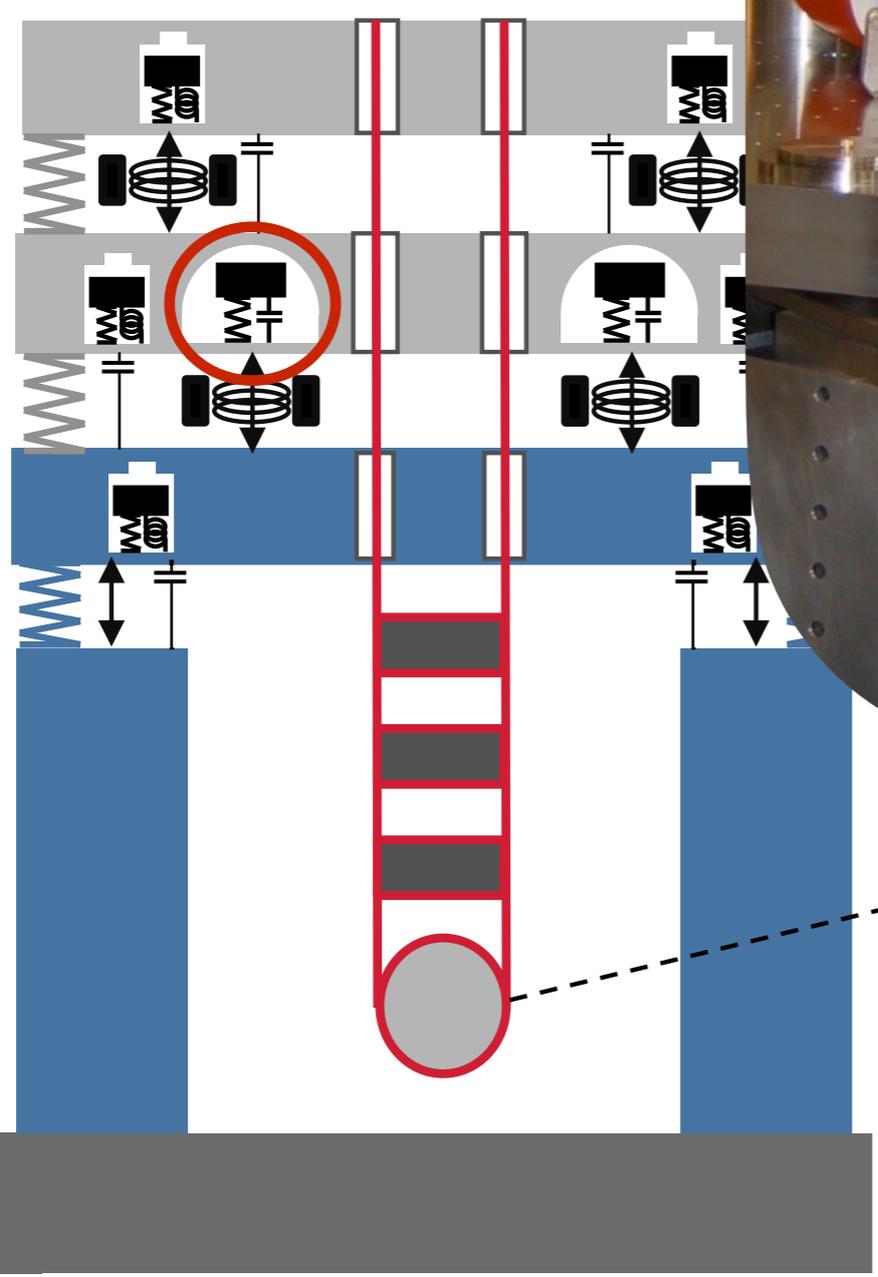


Suspended test mass

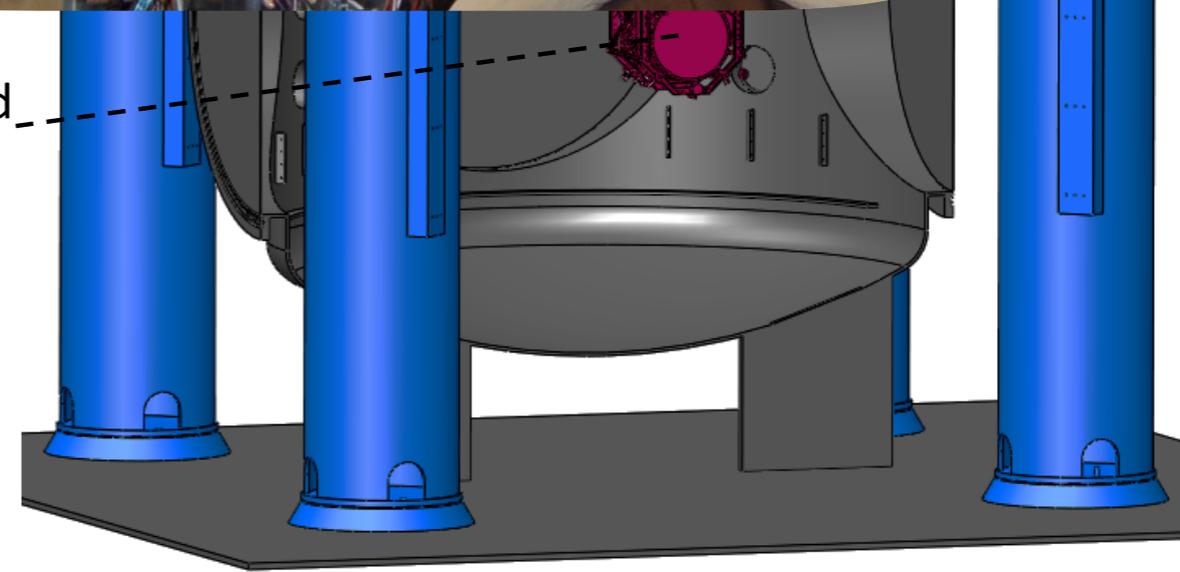


Signals for processing

(a)

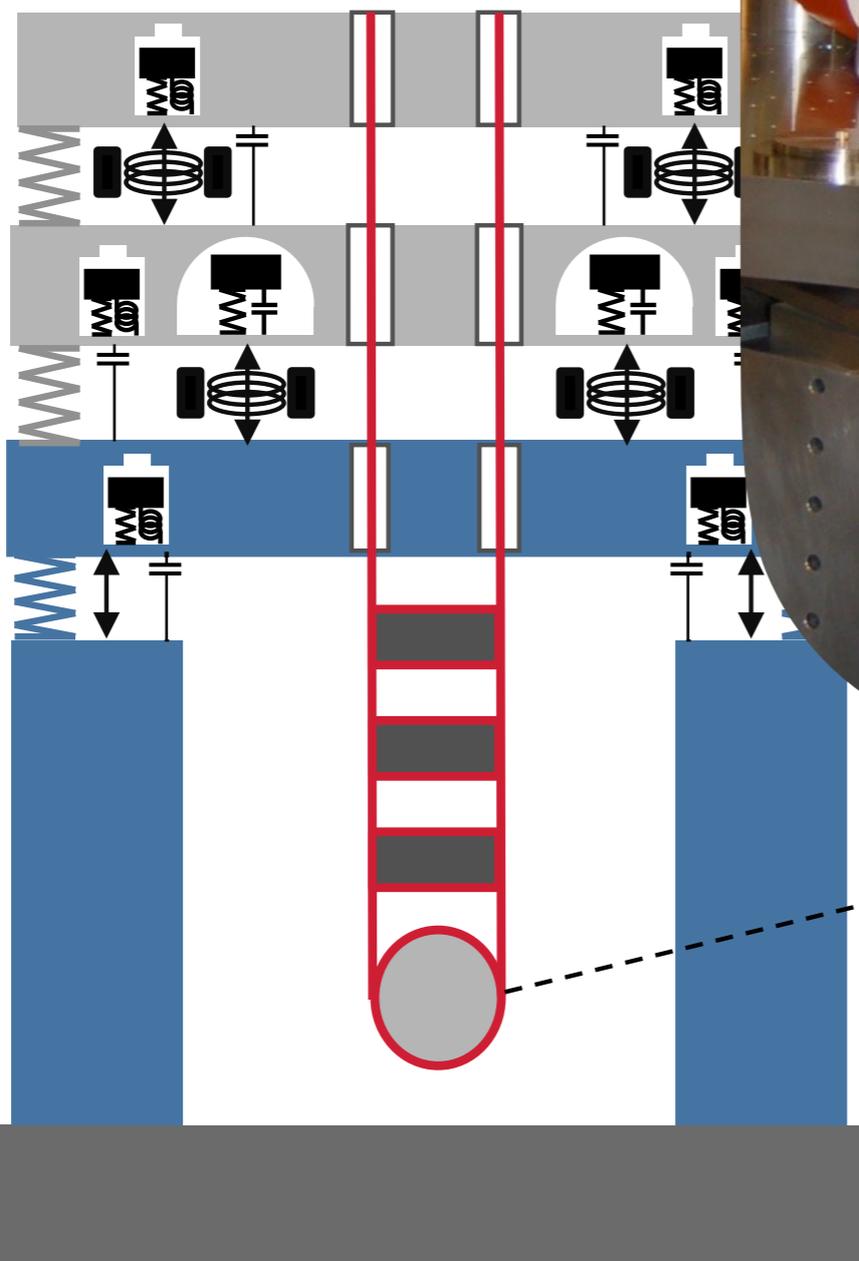


Suspended test mass

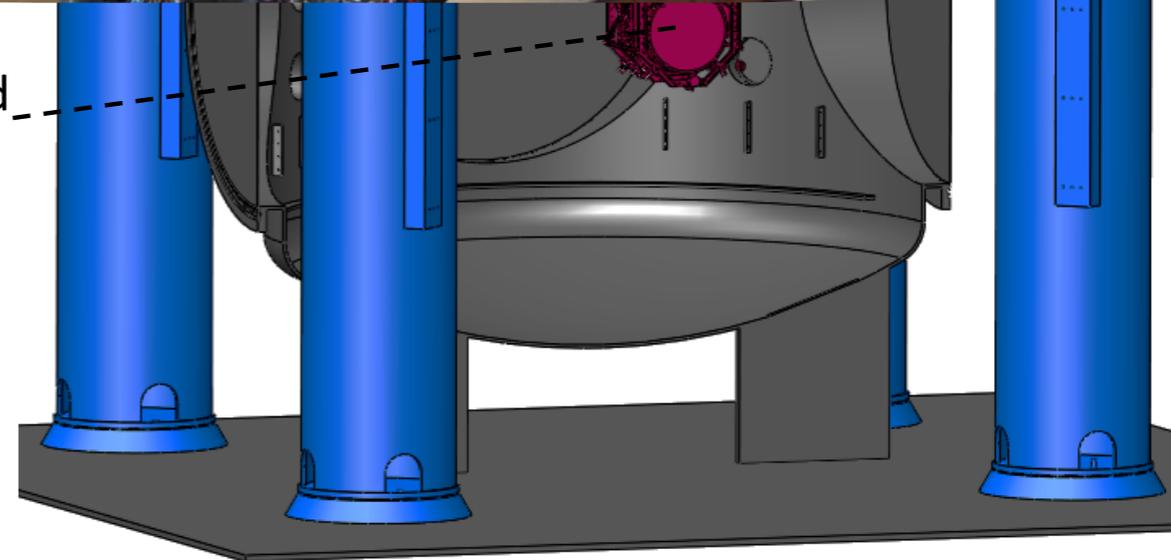


Signals for processing

(a)

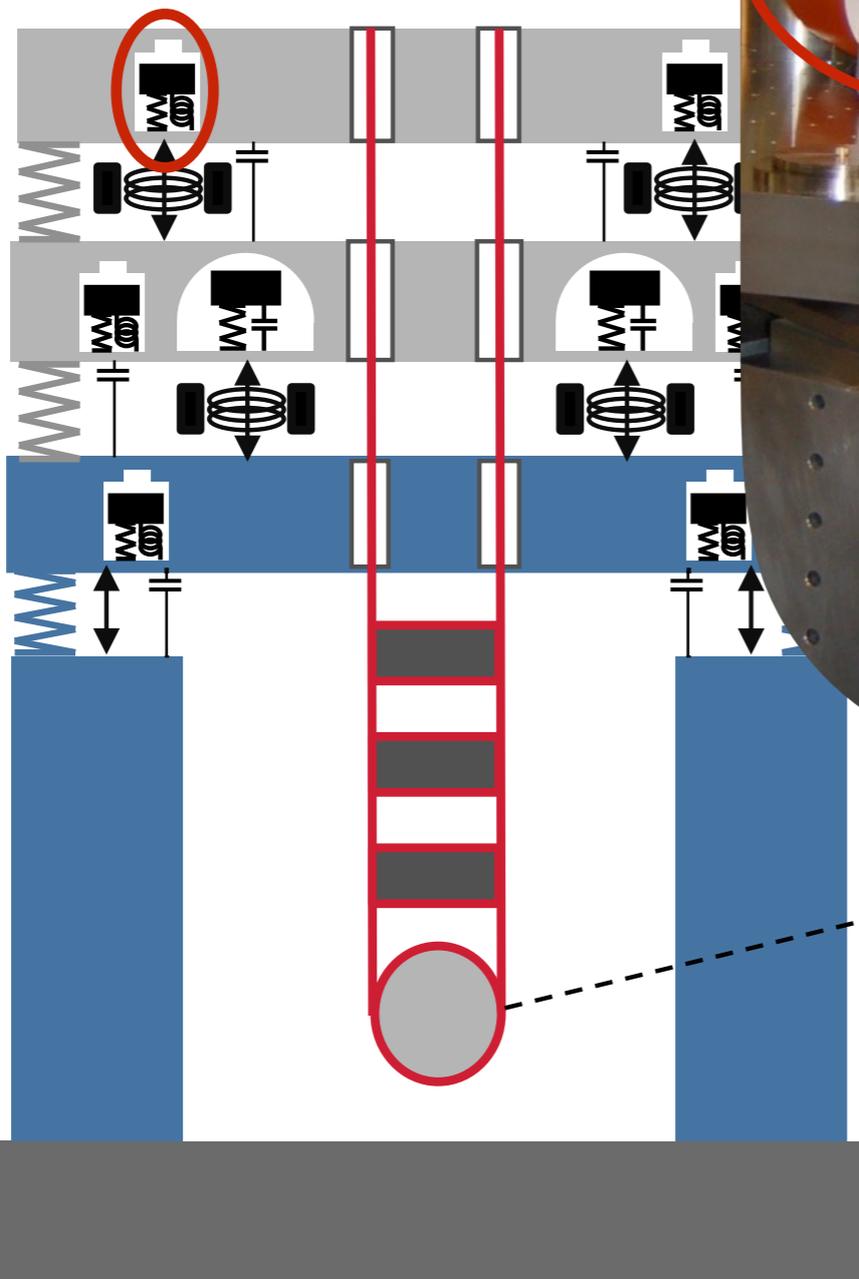


Suspended
test mass

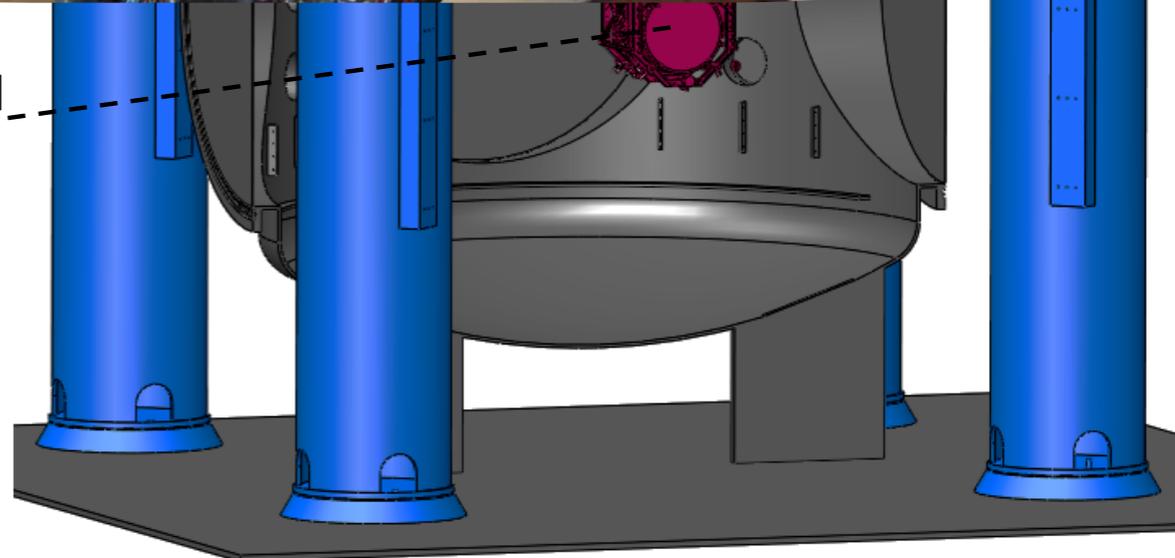


Signals for processing

(a)

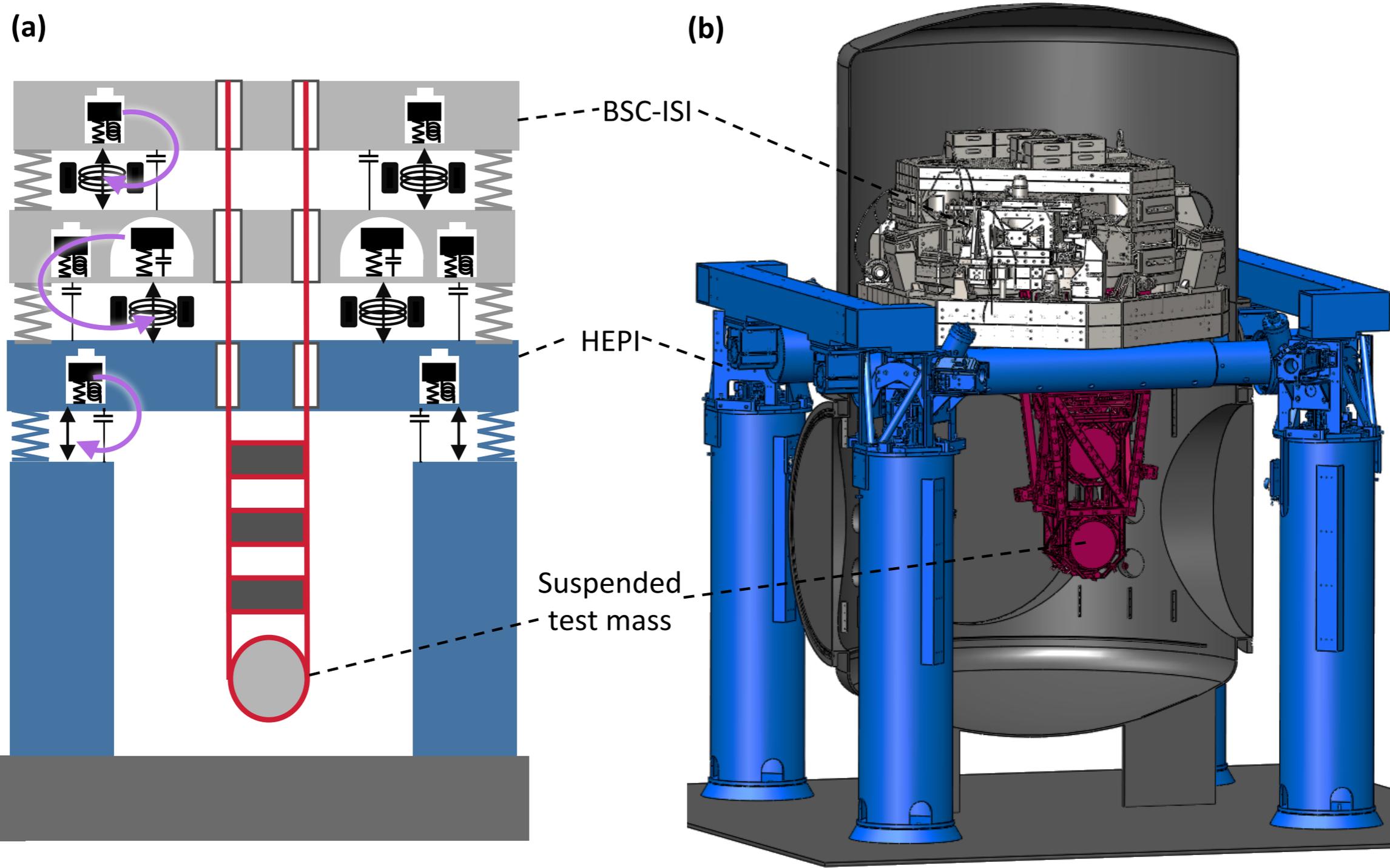


Suspended test mass



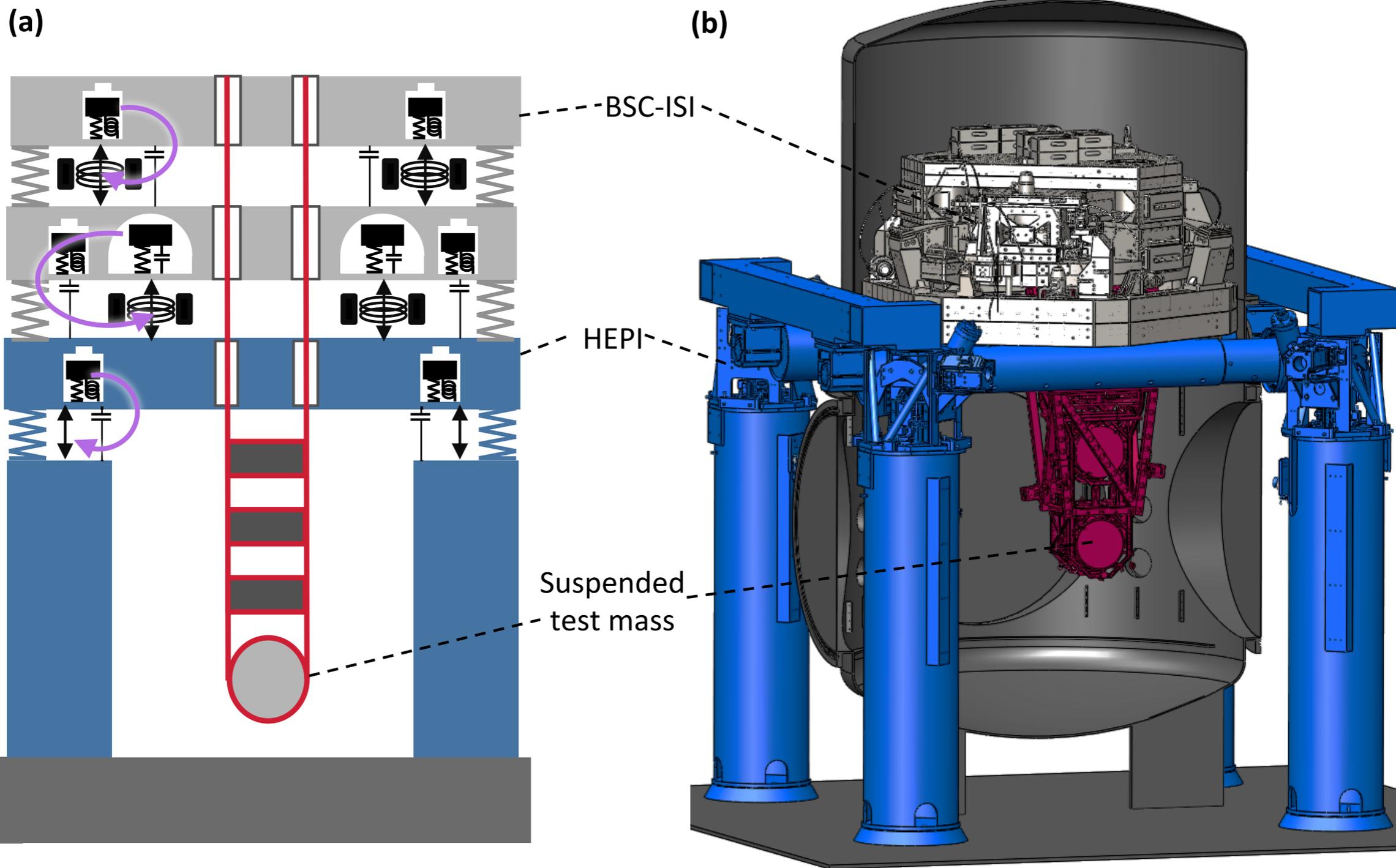
Signals for processing

Blended Feedback



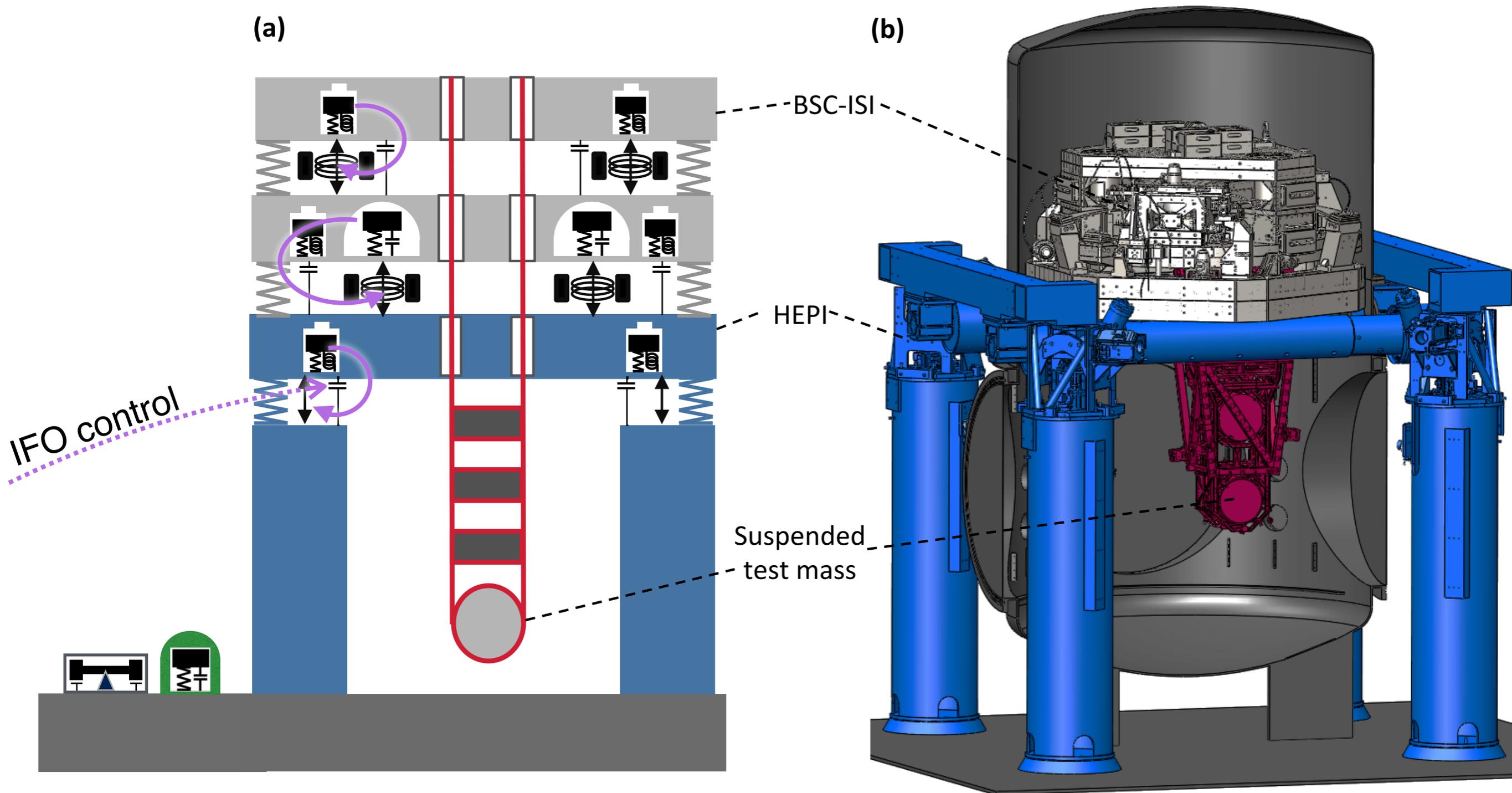
Signals for processing

Blended Feedback



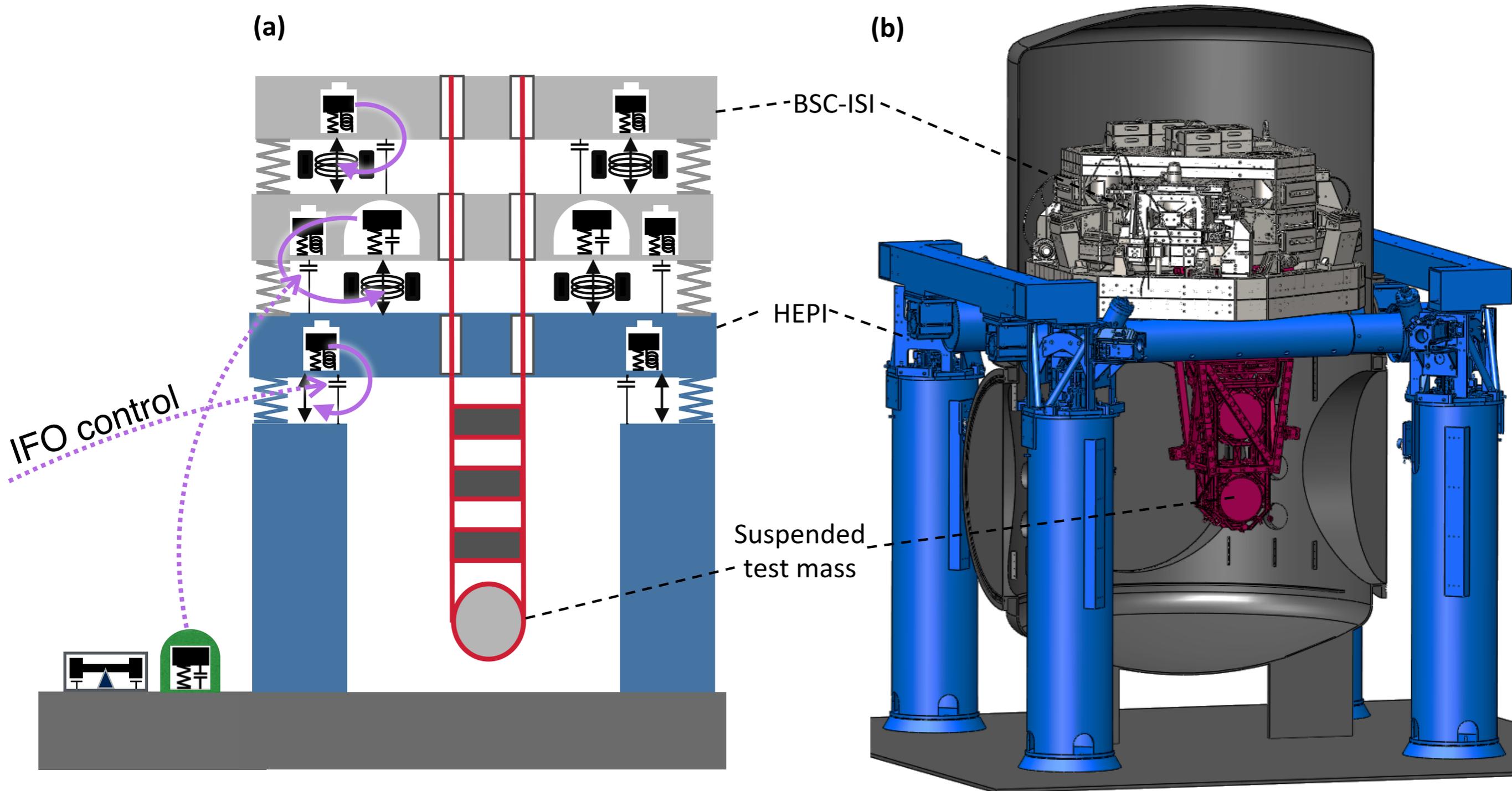
Signals for processing

Blended Feedback
Global commands



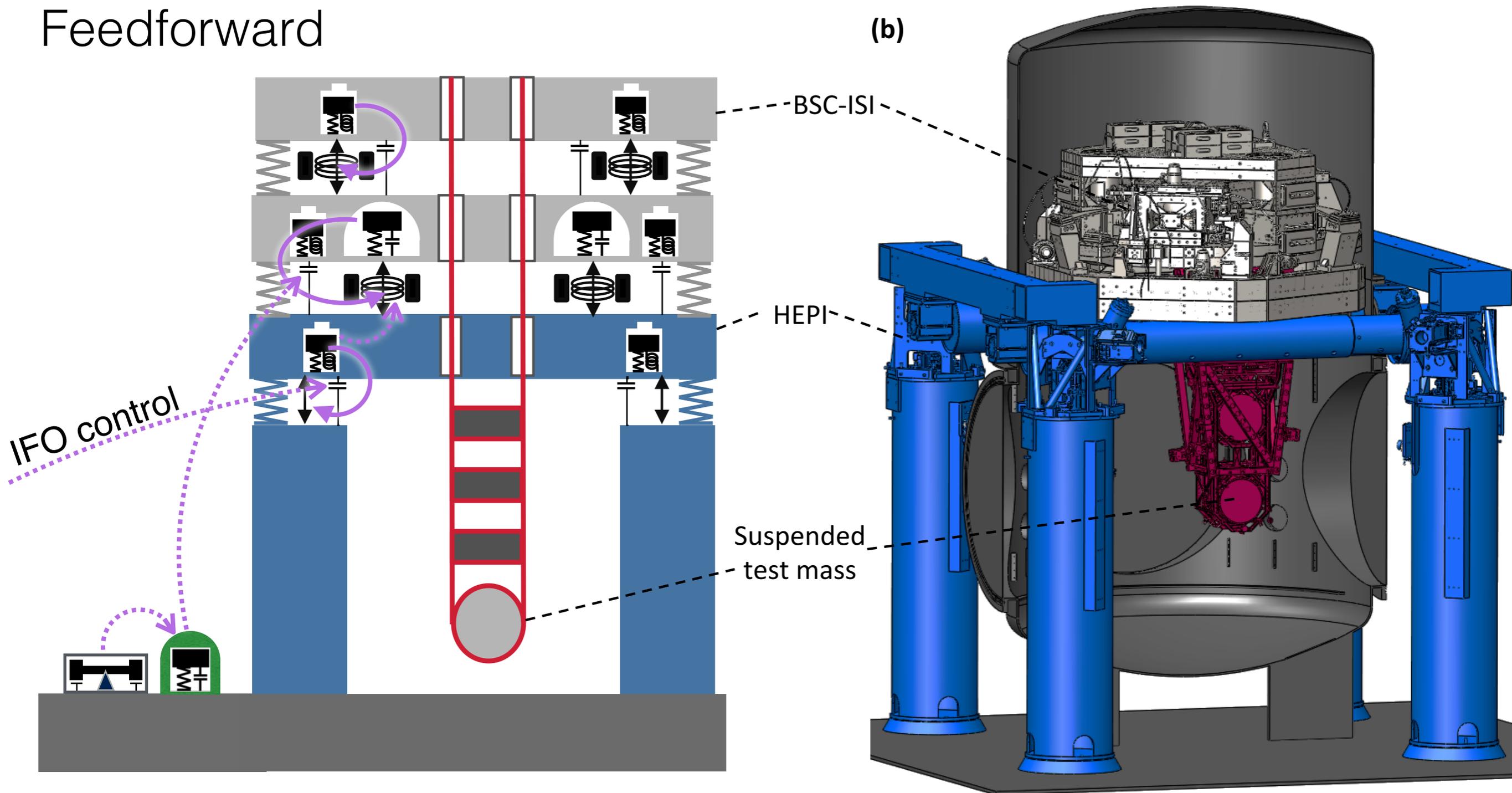
Signals for processing

Blended Feedback
Global commands
Sensor correction



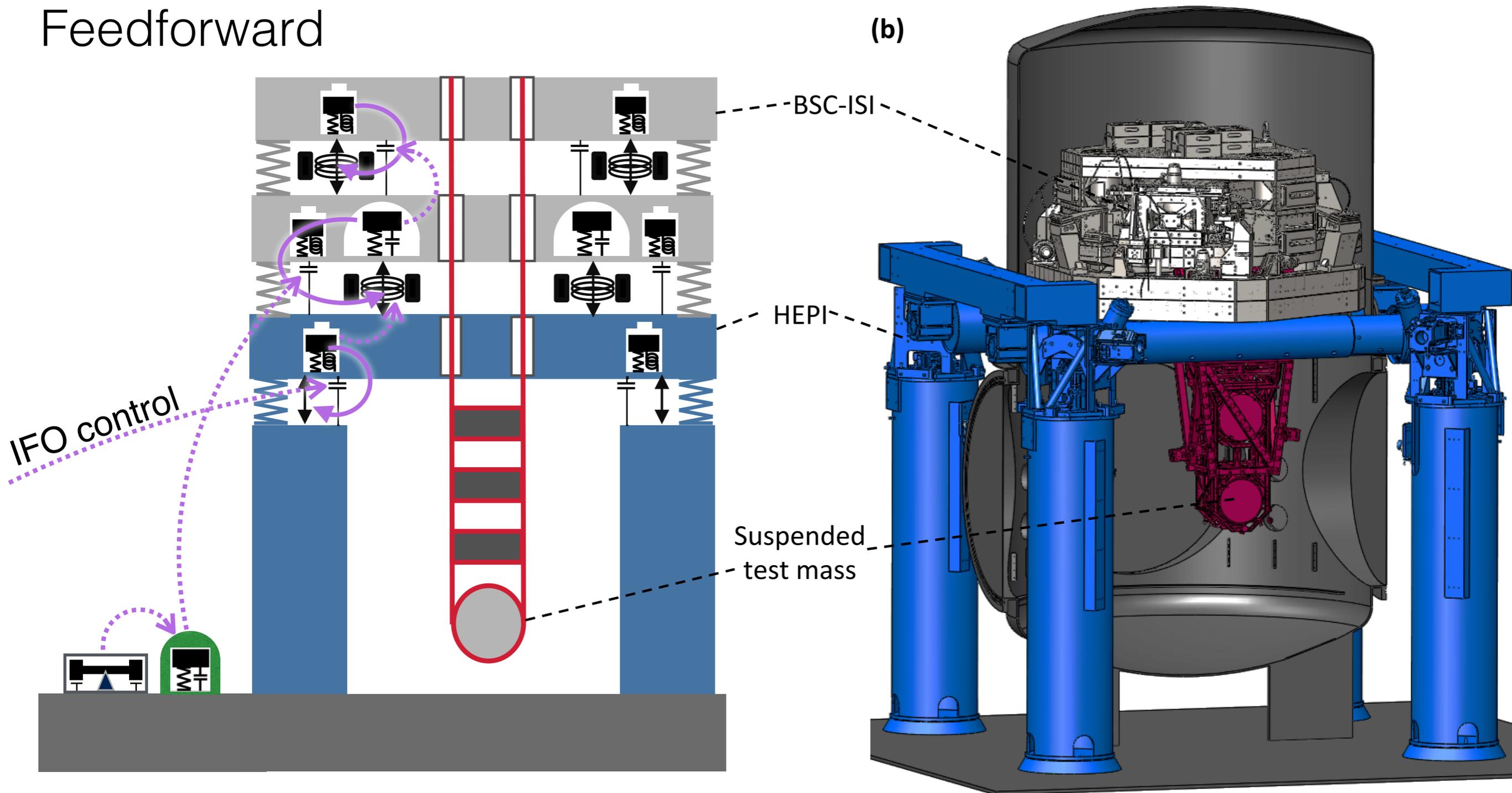
Signals for processing

- Blended Feedback
- Global commands
- Sensor correction
- Feedforward



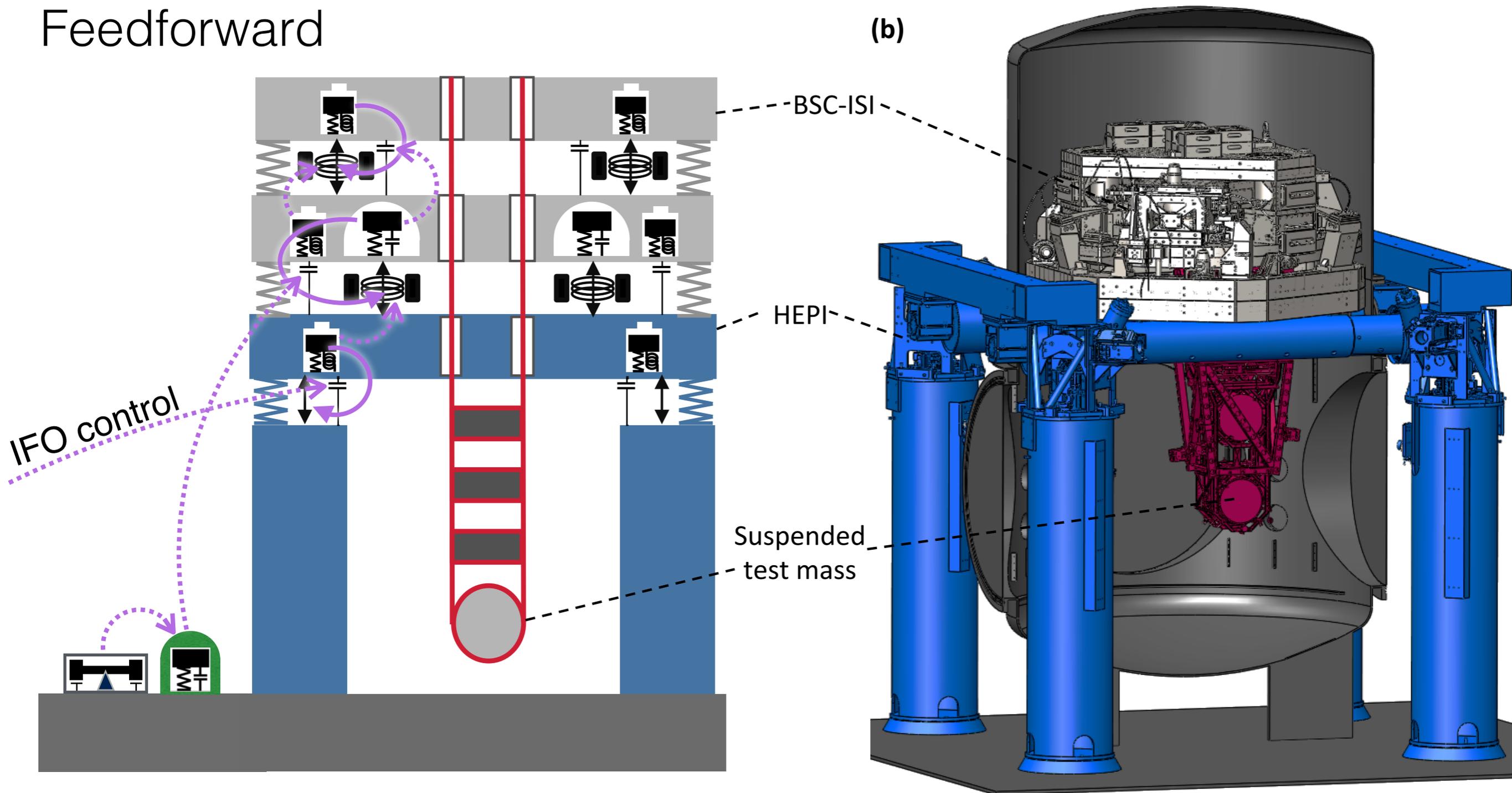
Signals for processing

Blended Feedback
Global commands
Sensor correction
Feedforward



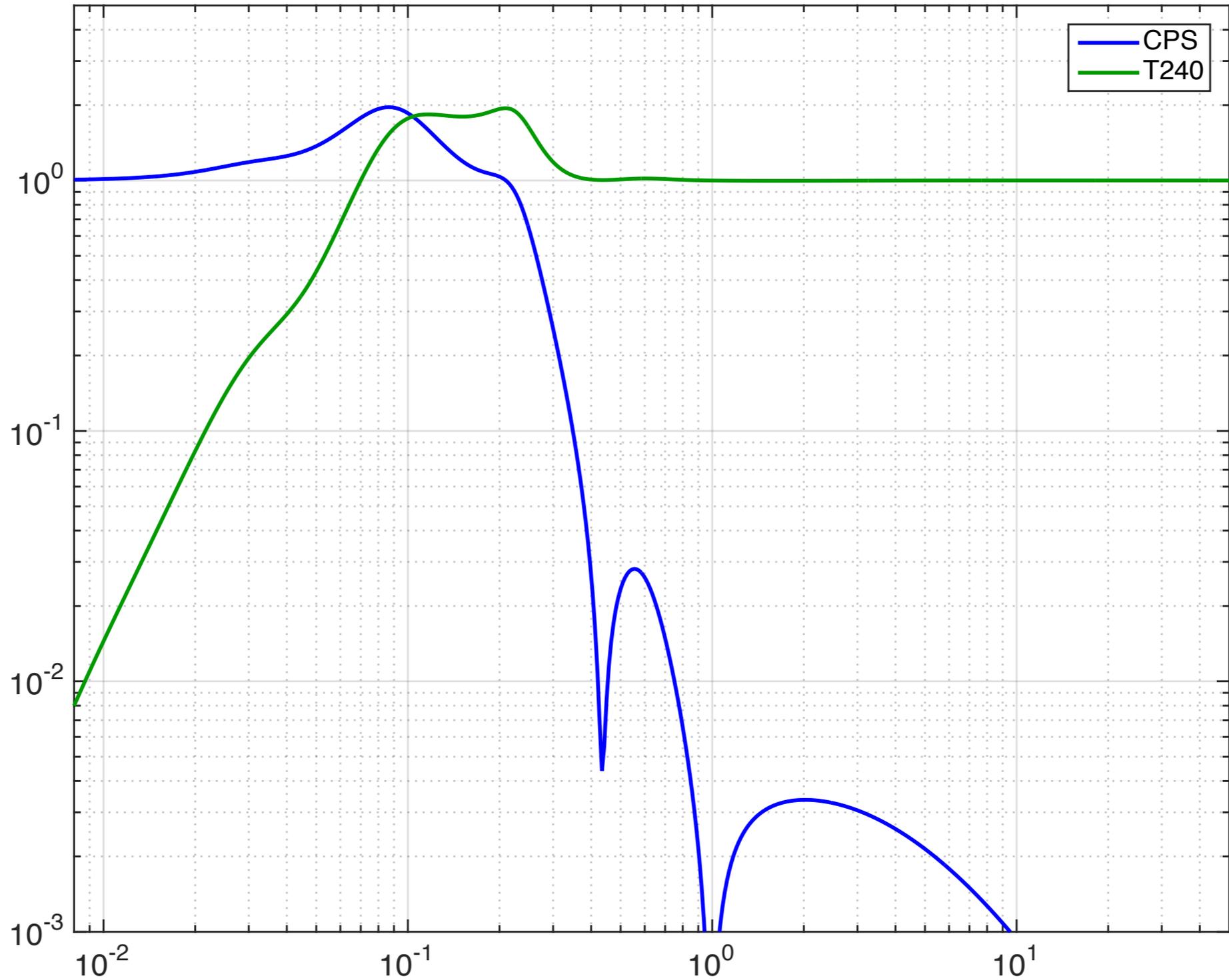
Signals for processing

- Blended Feedback
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- Feedforward



Blending sensors

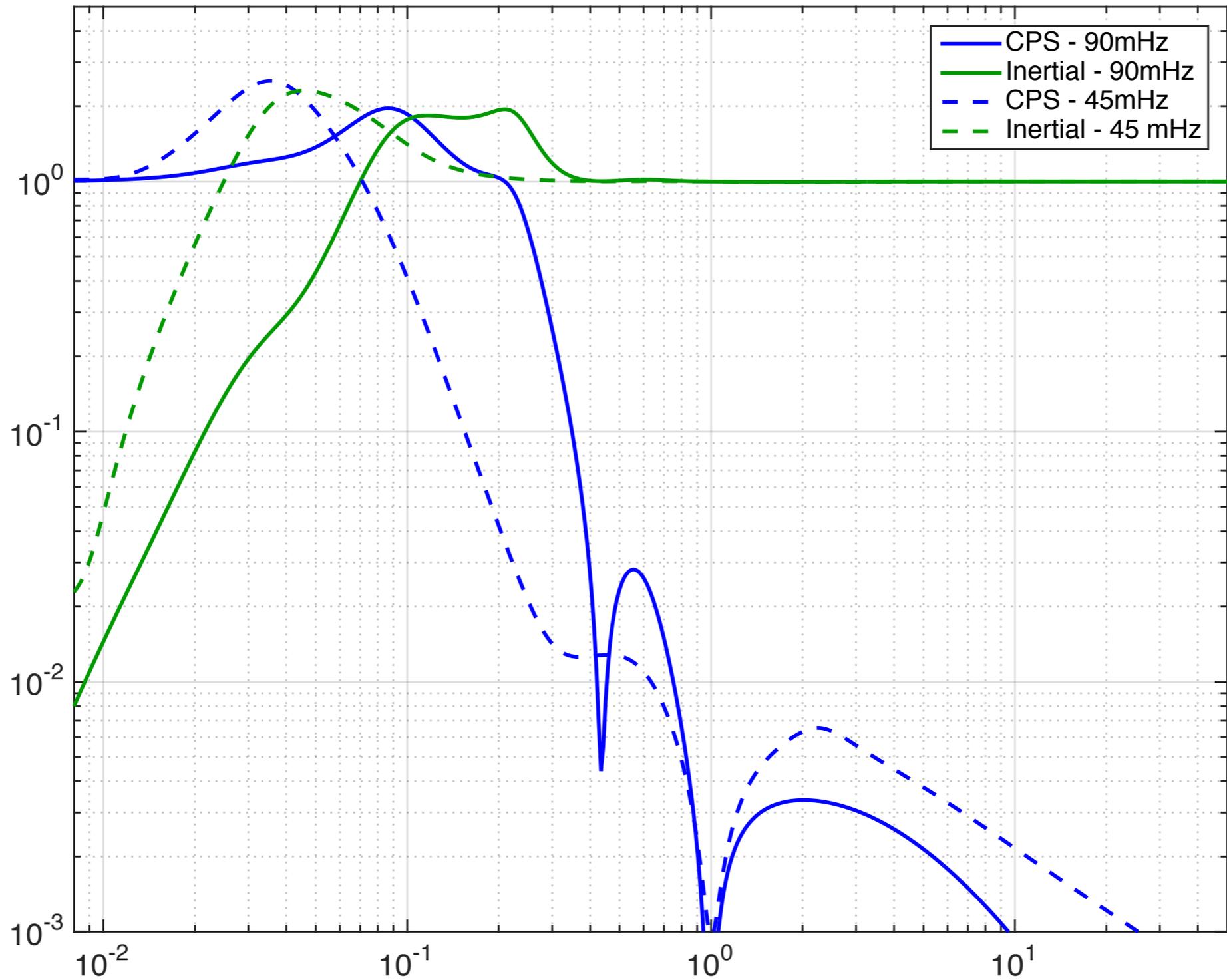
90 mHz Blend for Stage 1 Y



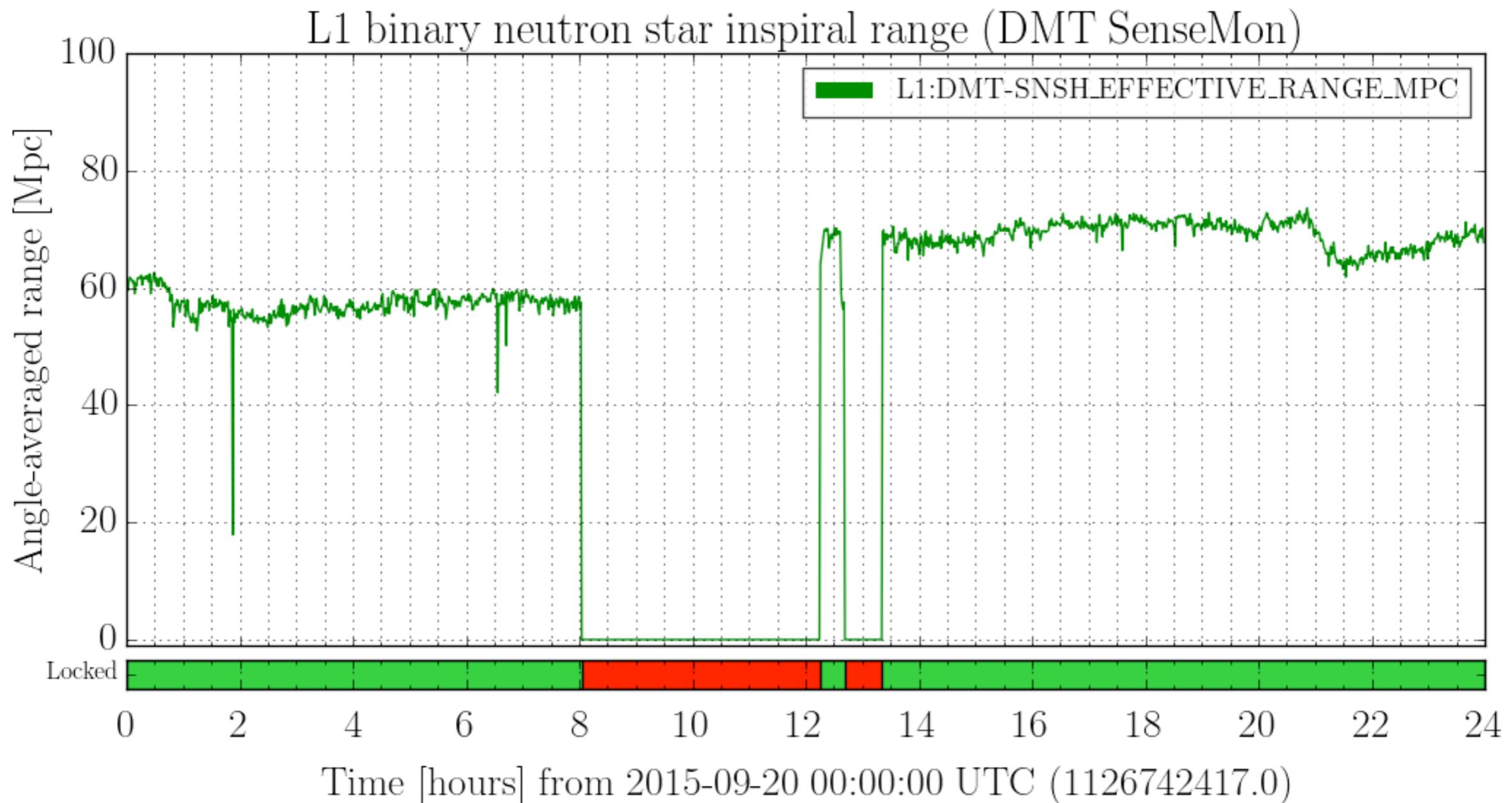
created by plot_45_vs_quite90 on 18-May-2016

Blending sensors

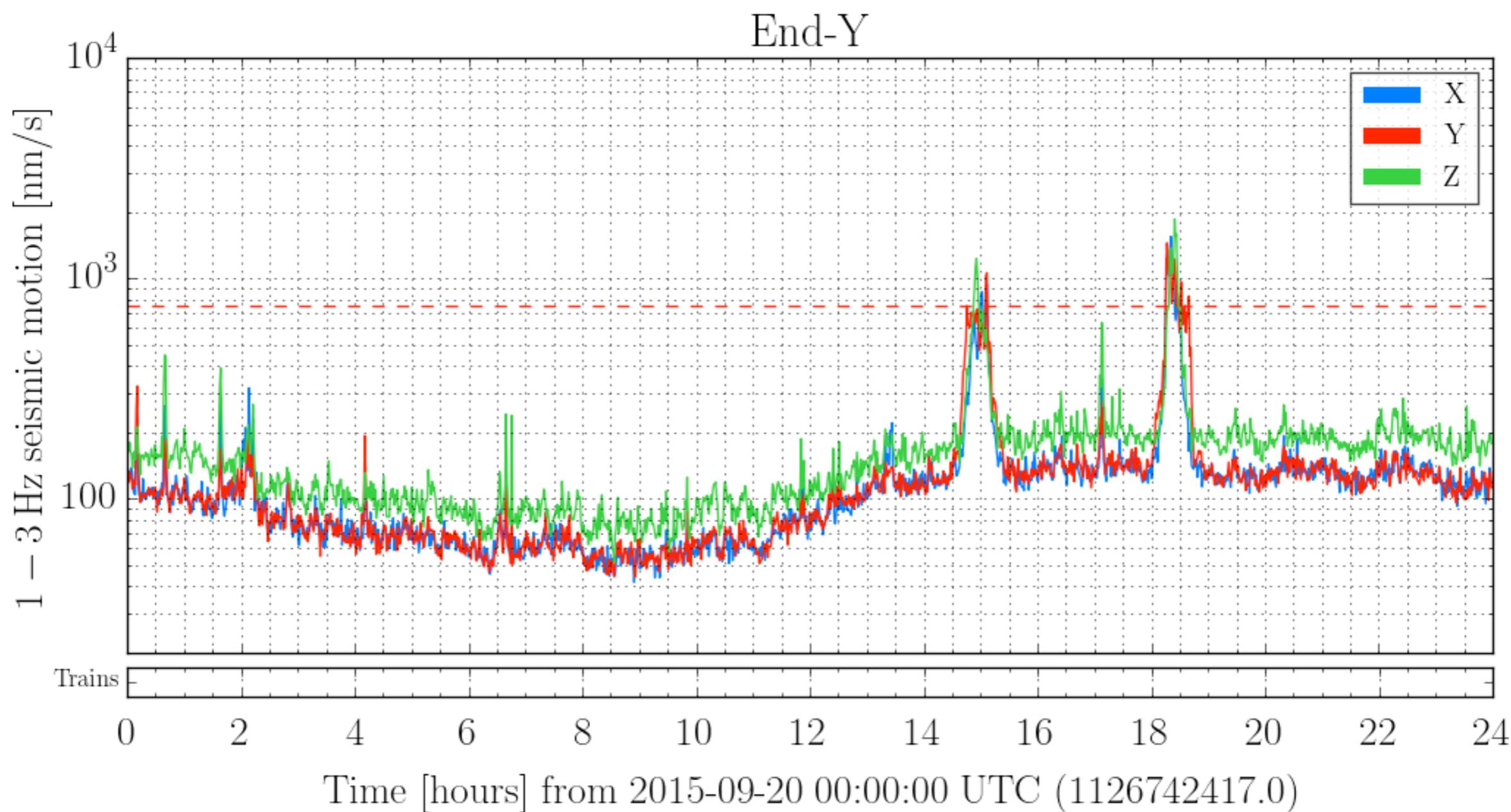
compares Blends for Stage 1 Y



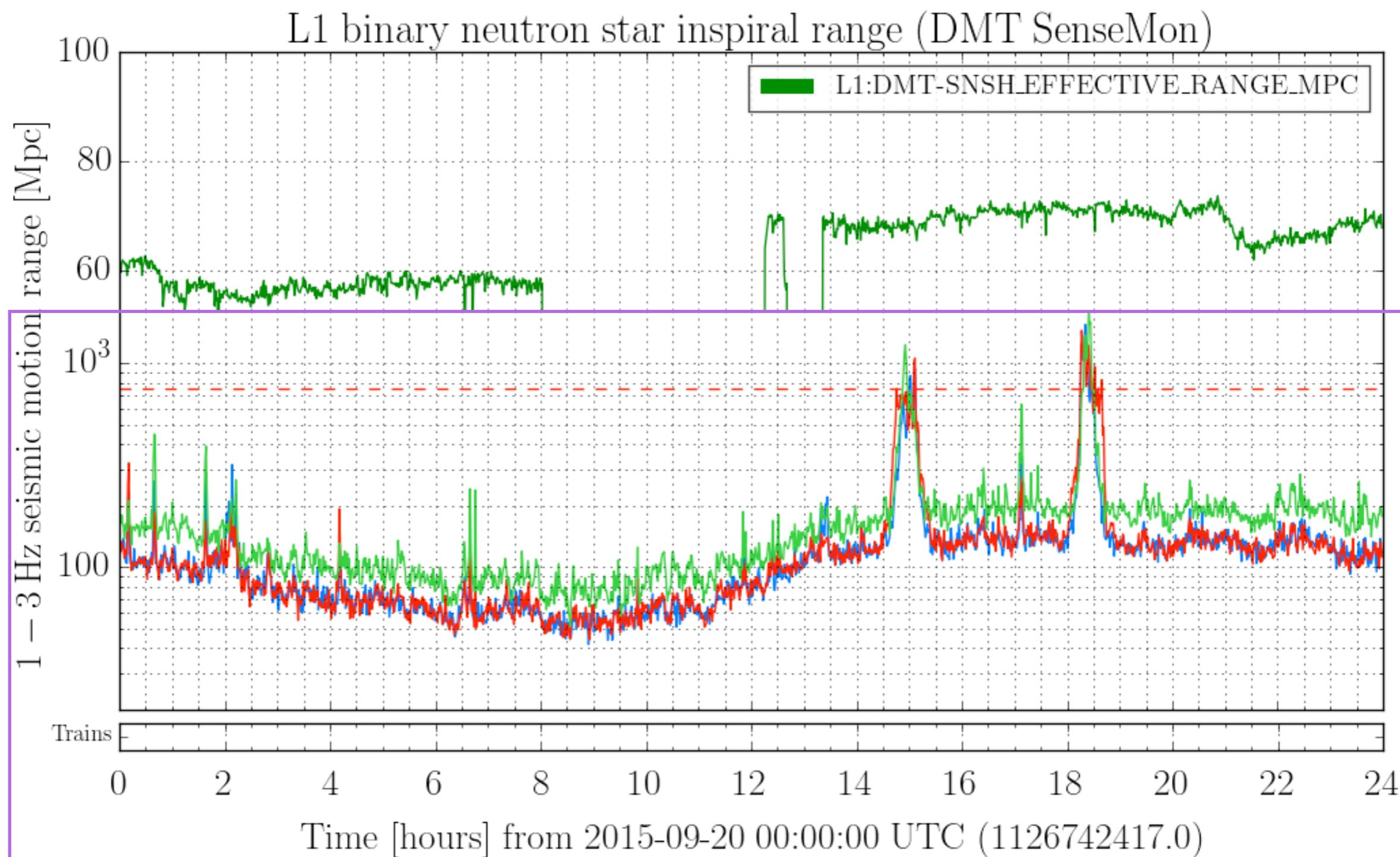
Real impact of isolation, alignment & control



but there was a train...

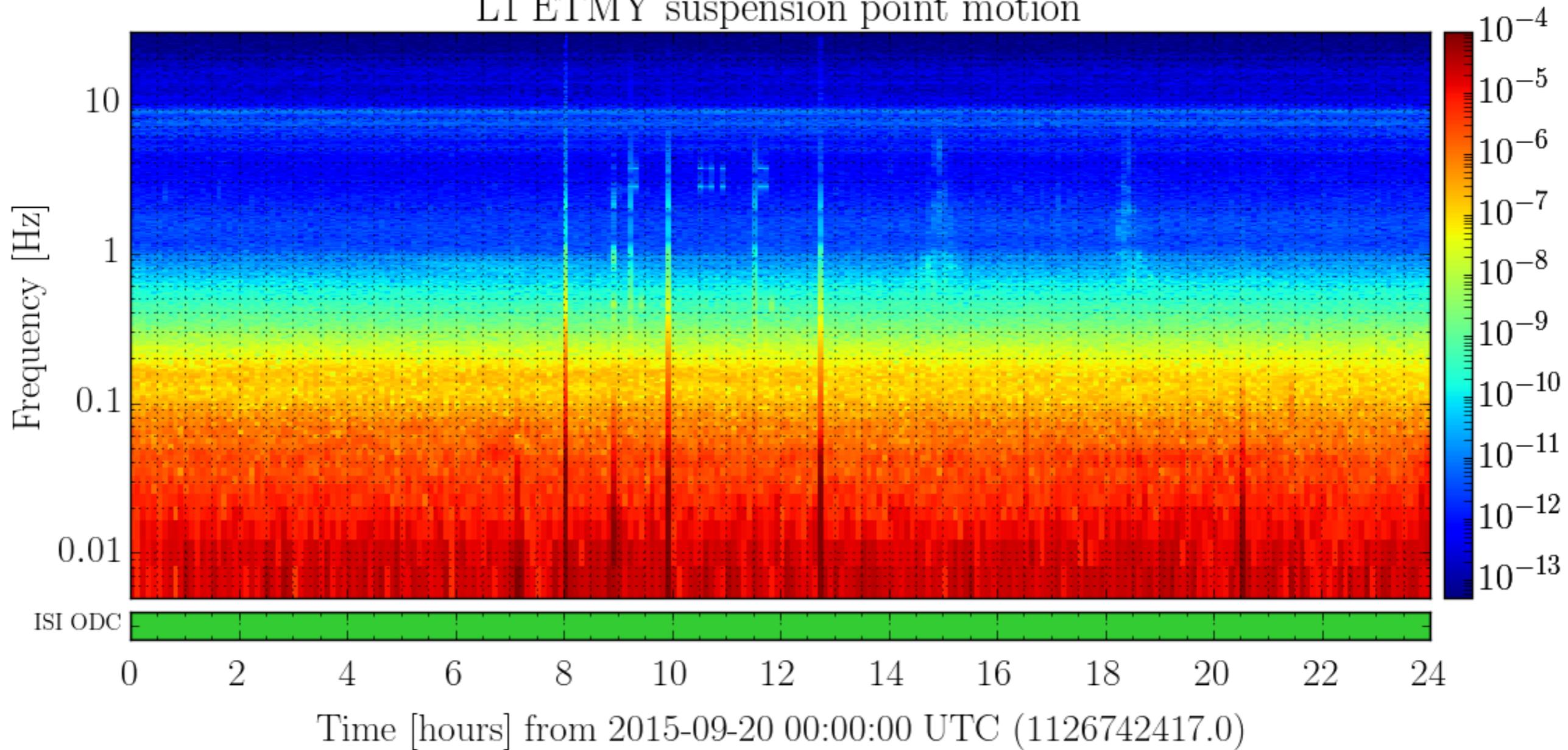


Real impact of isolation, alignment & control



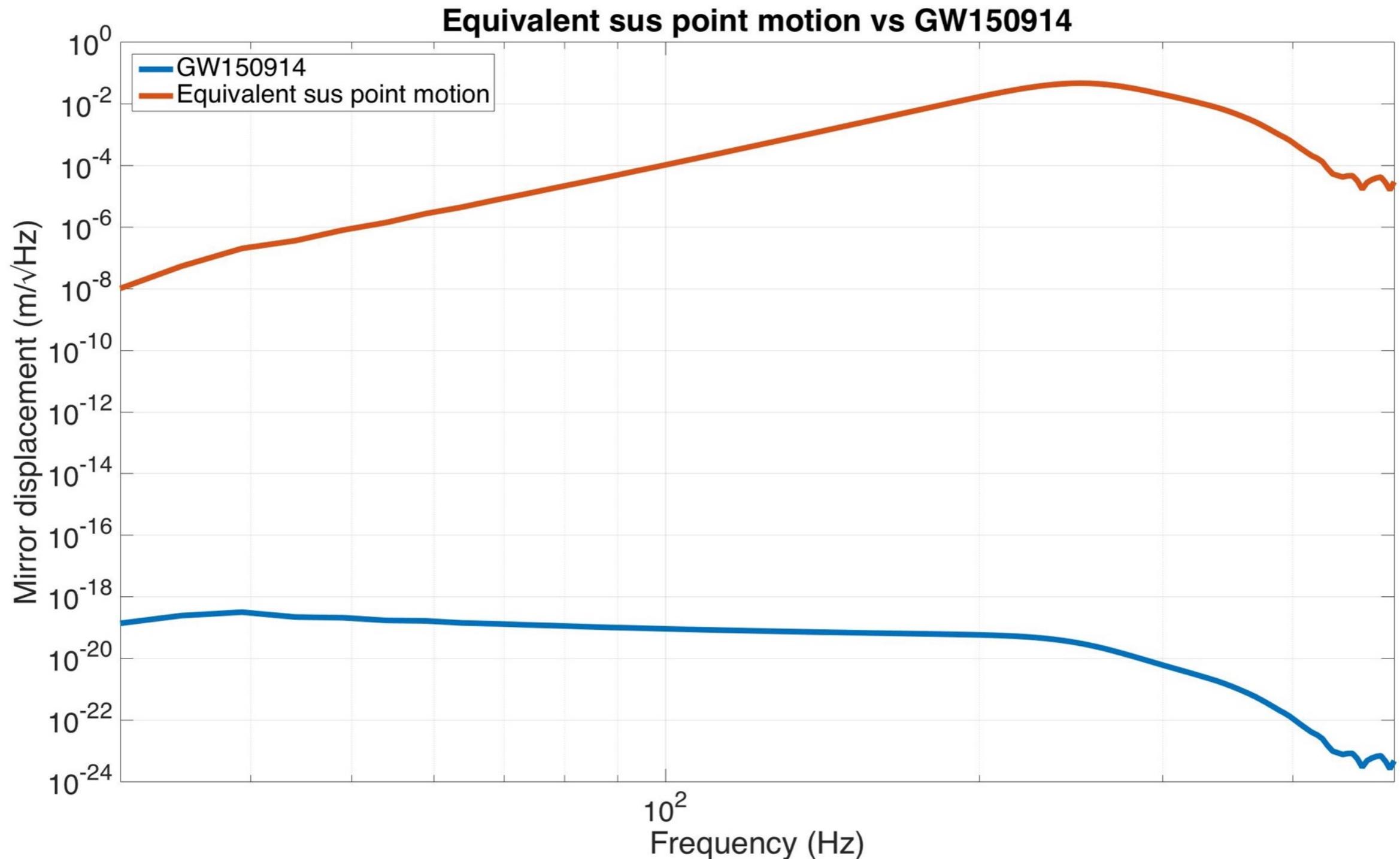
'Environmental' sensors

L1 ETMY suspension point motion

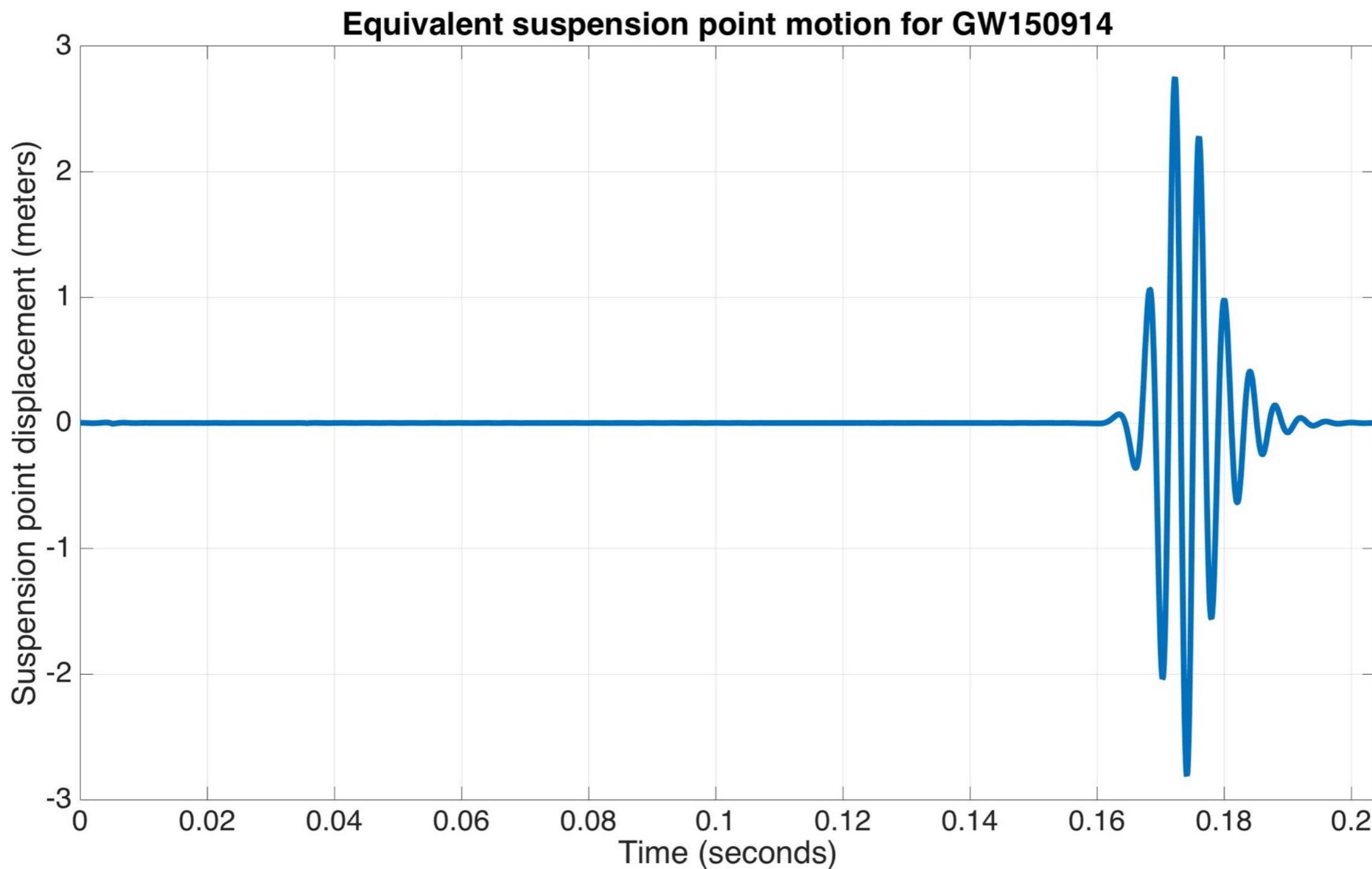


Power of the monitors

If GSI 50914 was linearly coupled seismic motion

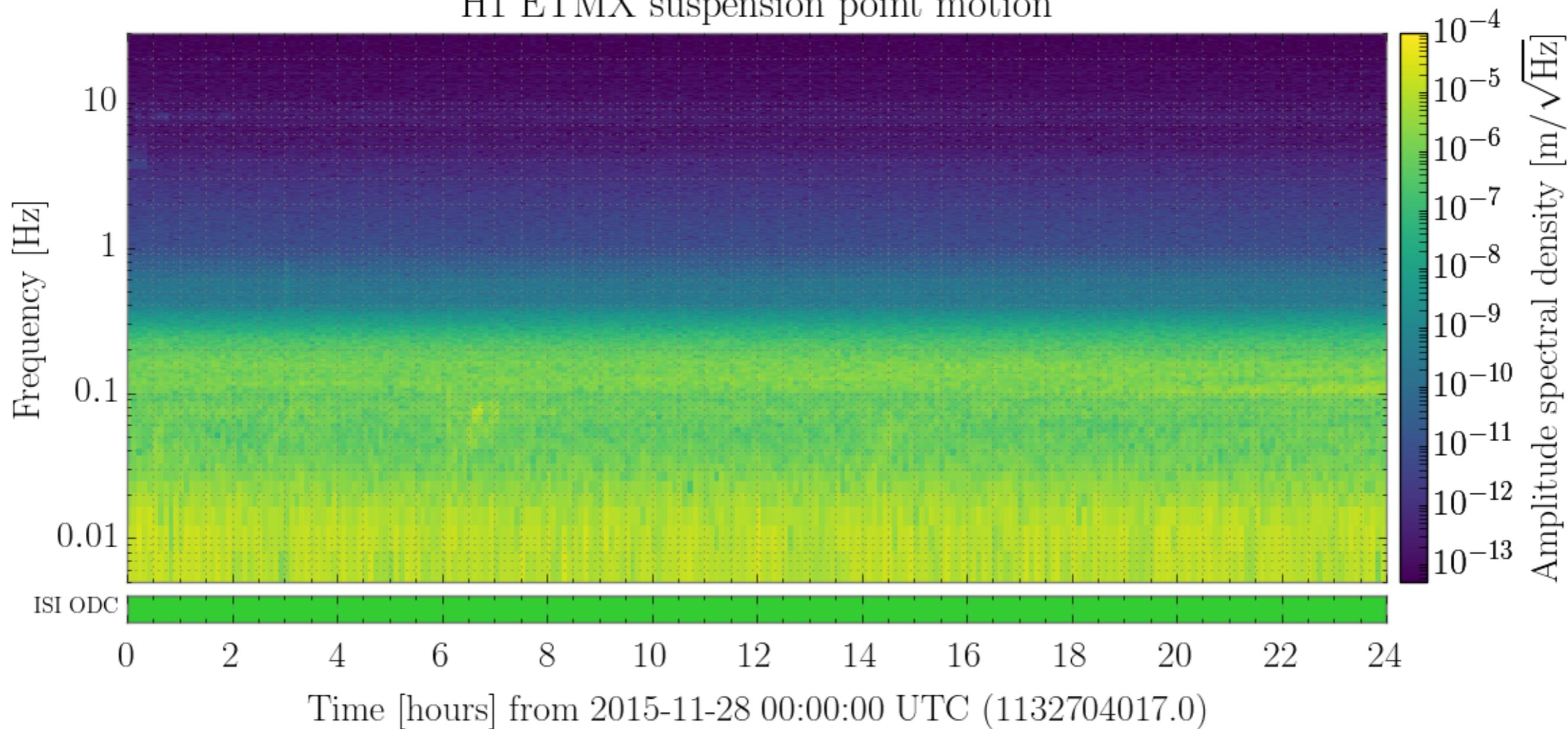


If GSI 50914 was

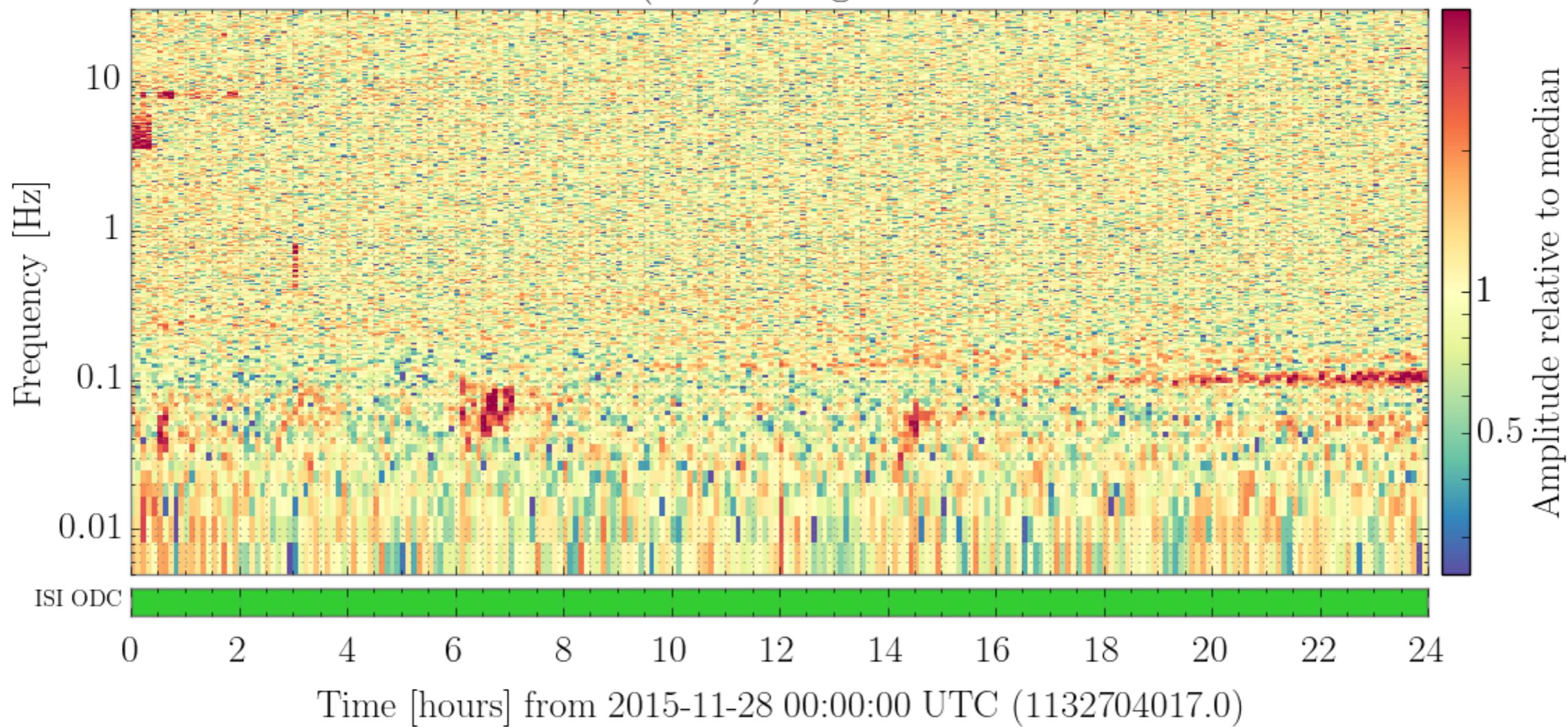


This is what we strive for

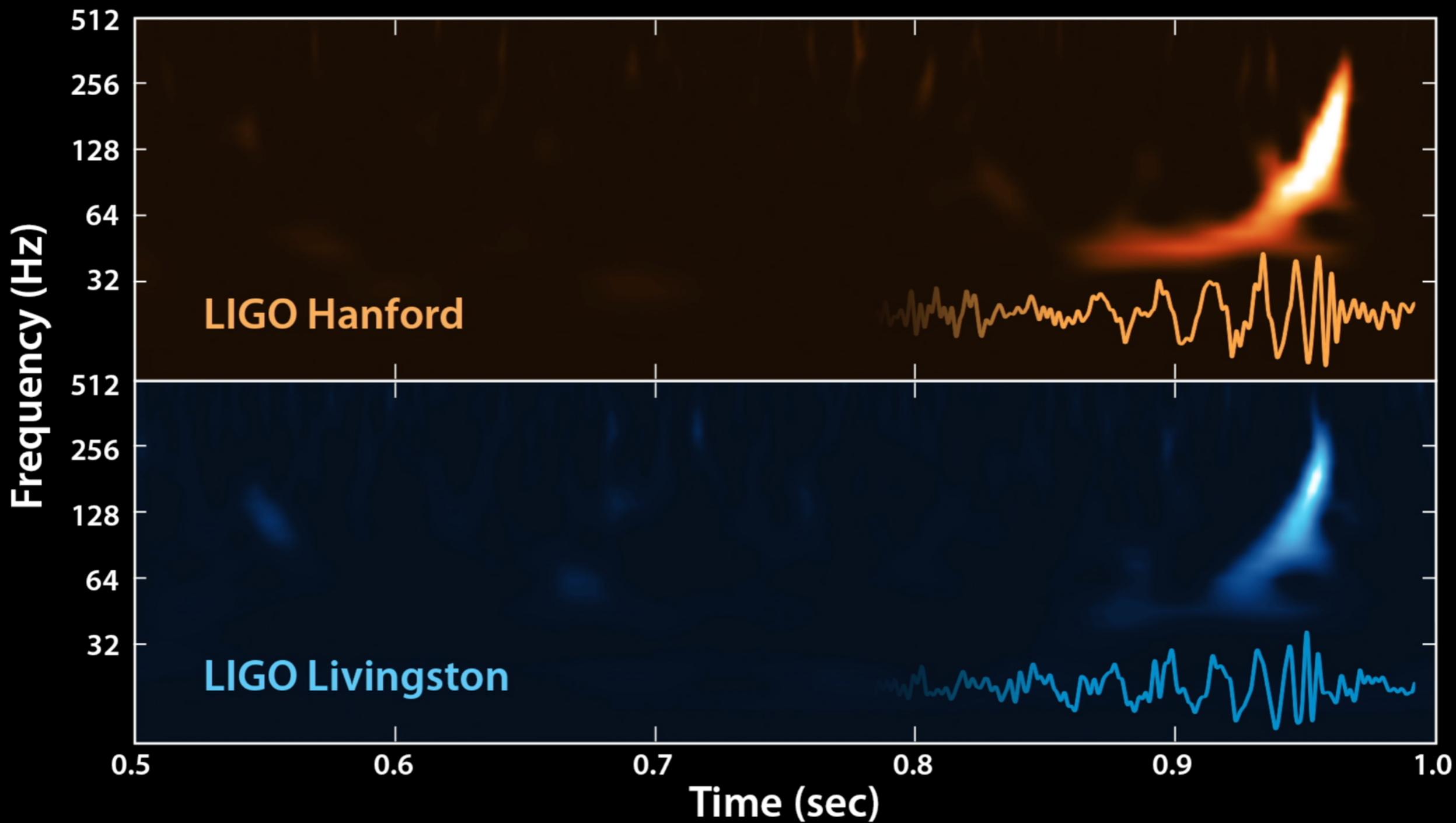
H1 ETMX suspension point motion



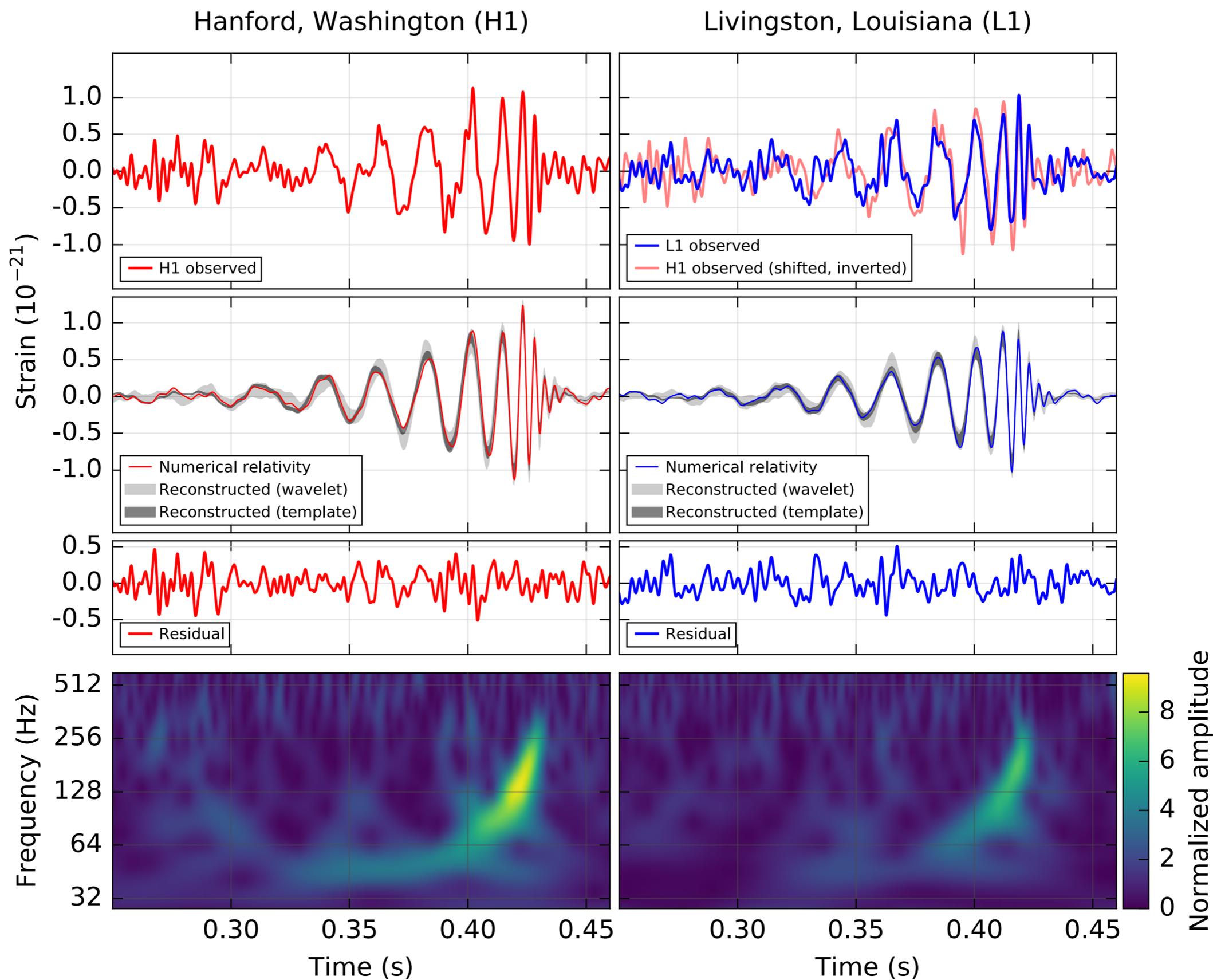
H1 ETMX (BSC9) longitudinal motion



The sound of black holes colliding



First signal - Sept 14, 2015



Best fit with numerical Relativity

Initial Masses:

29 (+4/-4) & 36 (+5/-4) M_{sun}

Final Mass:

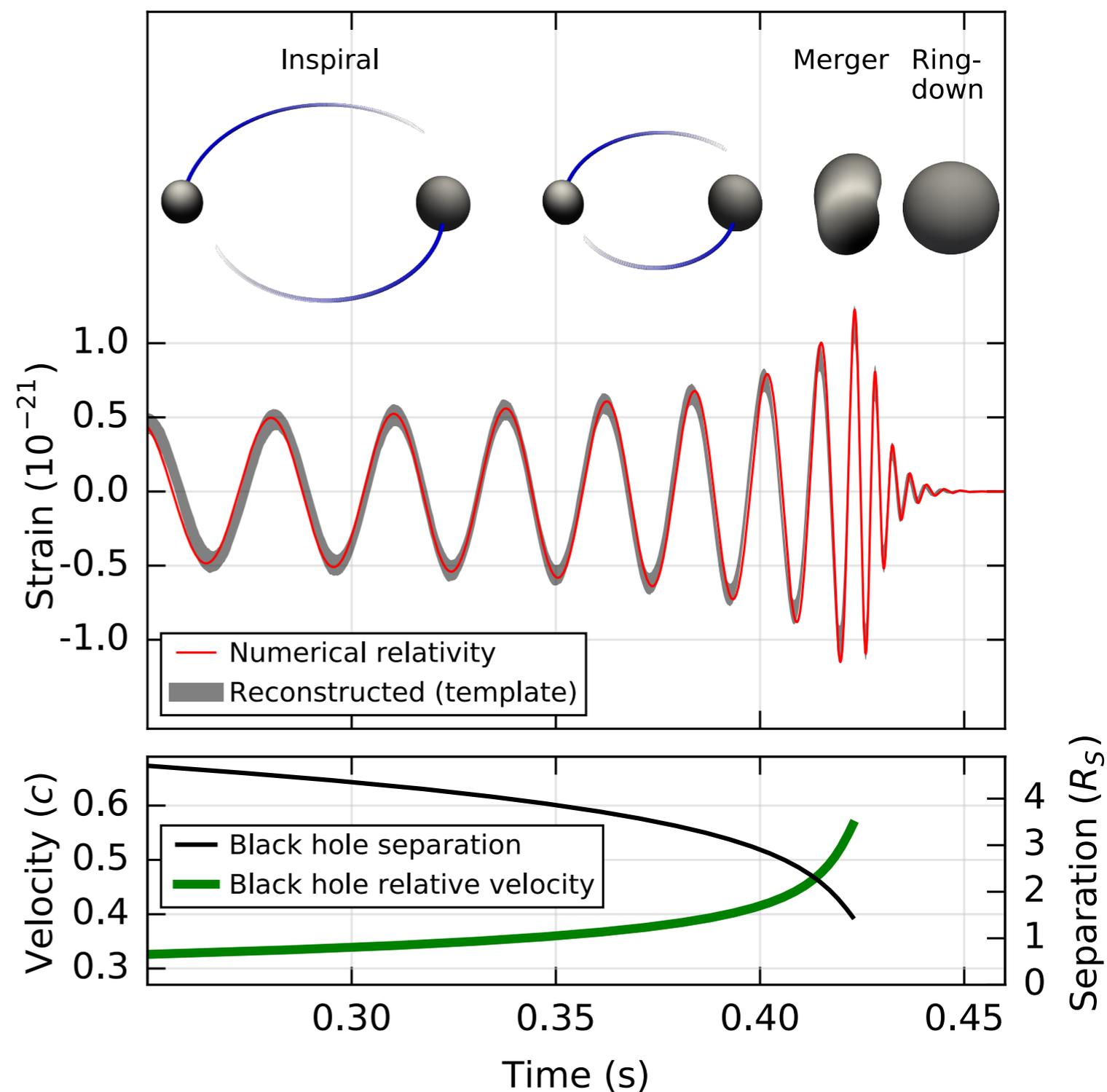
62 (+4/-4) M_{sun}

Energy radiated

3 (+0.5/-0.5) $M_{\text{sun}} c^2$

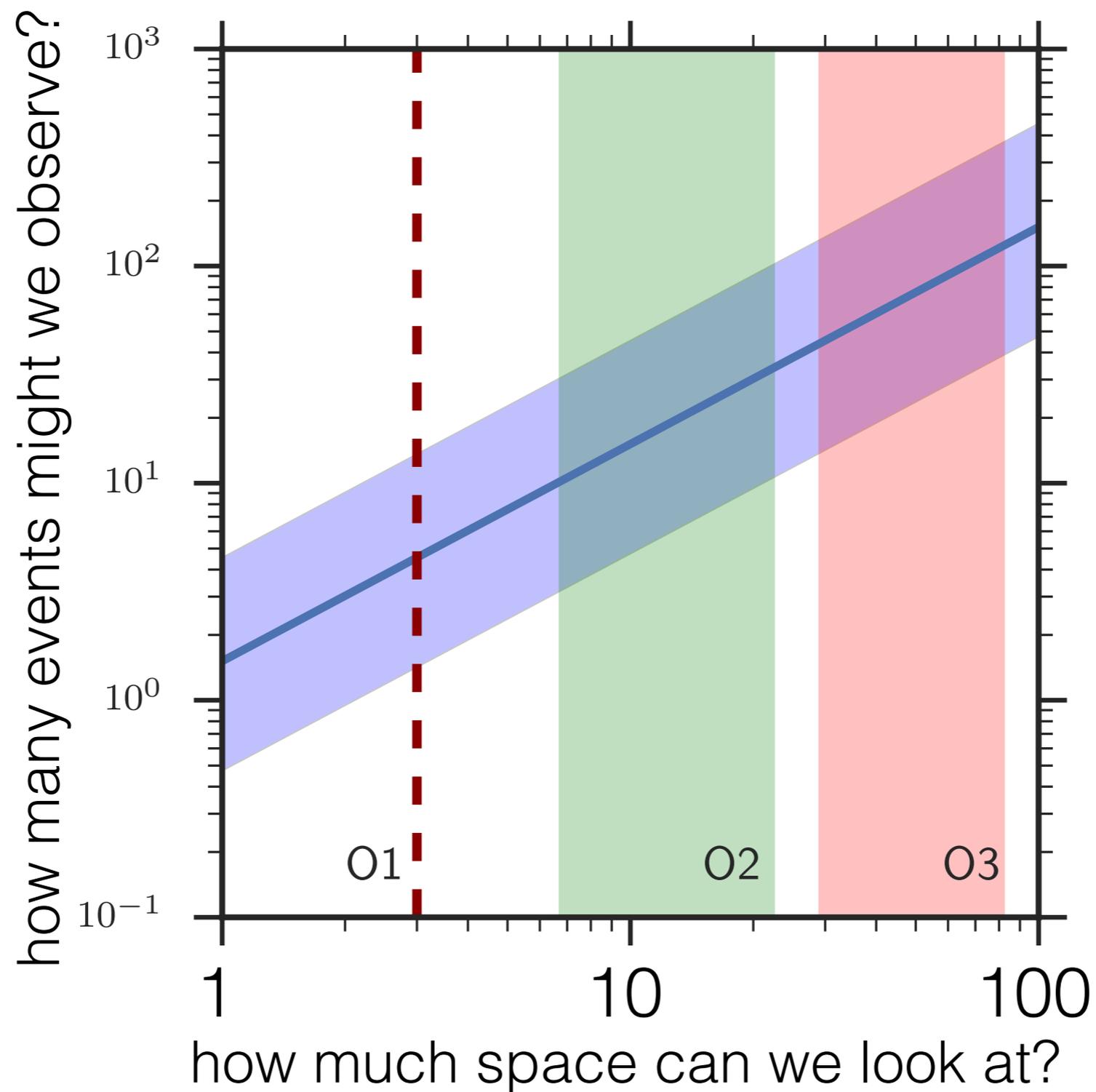
Distance

410 (+160/-180) Mpc



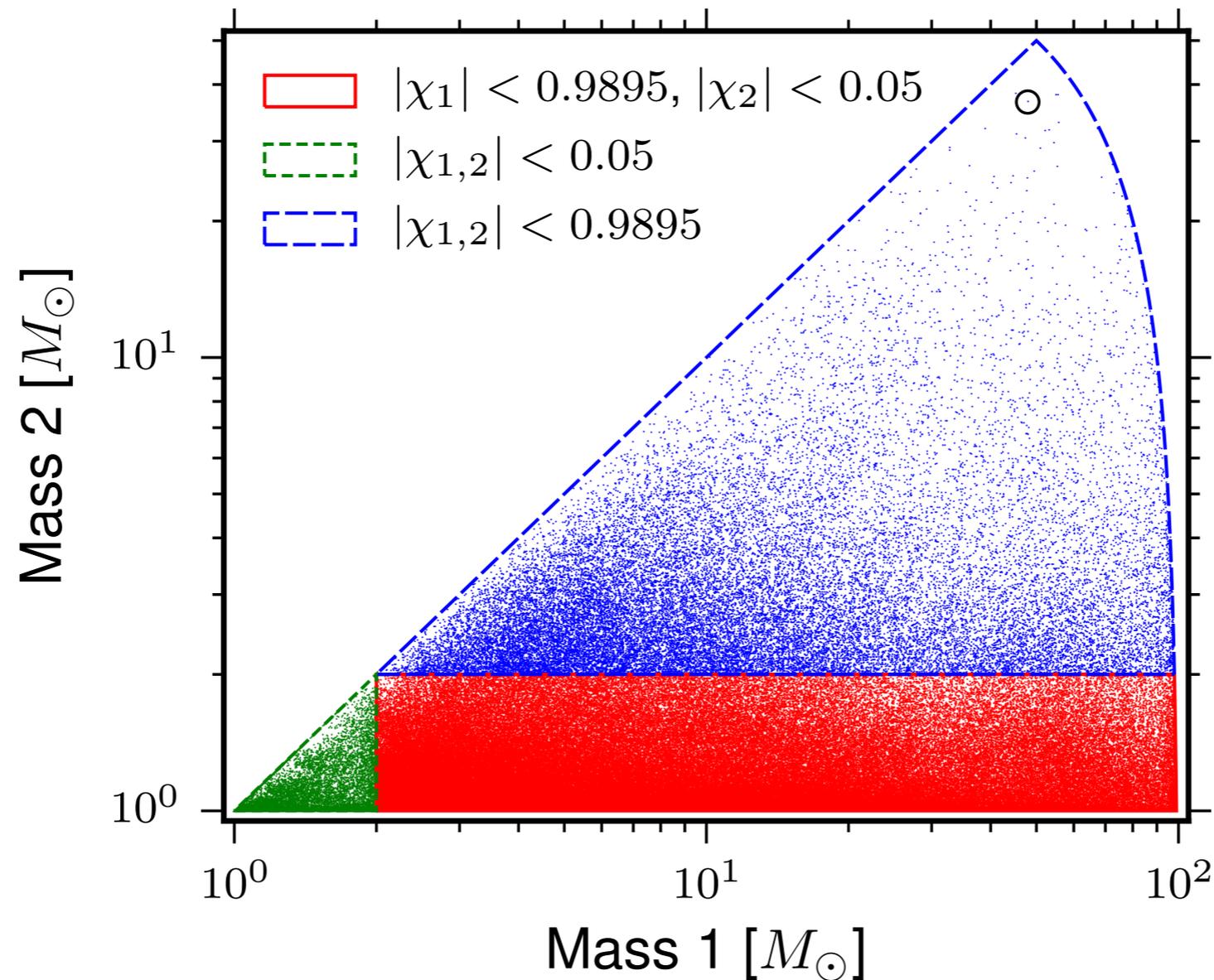
The End/ The Beginning...

How many black hole collisions can we see?





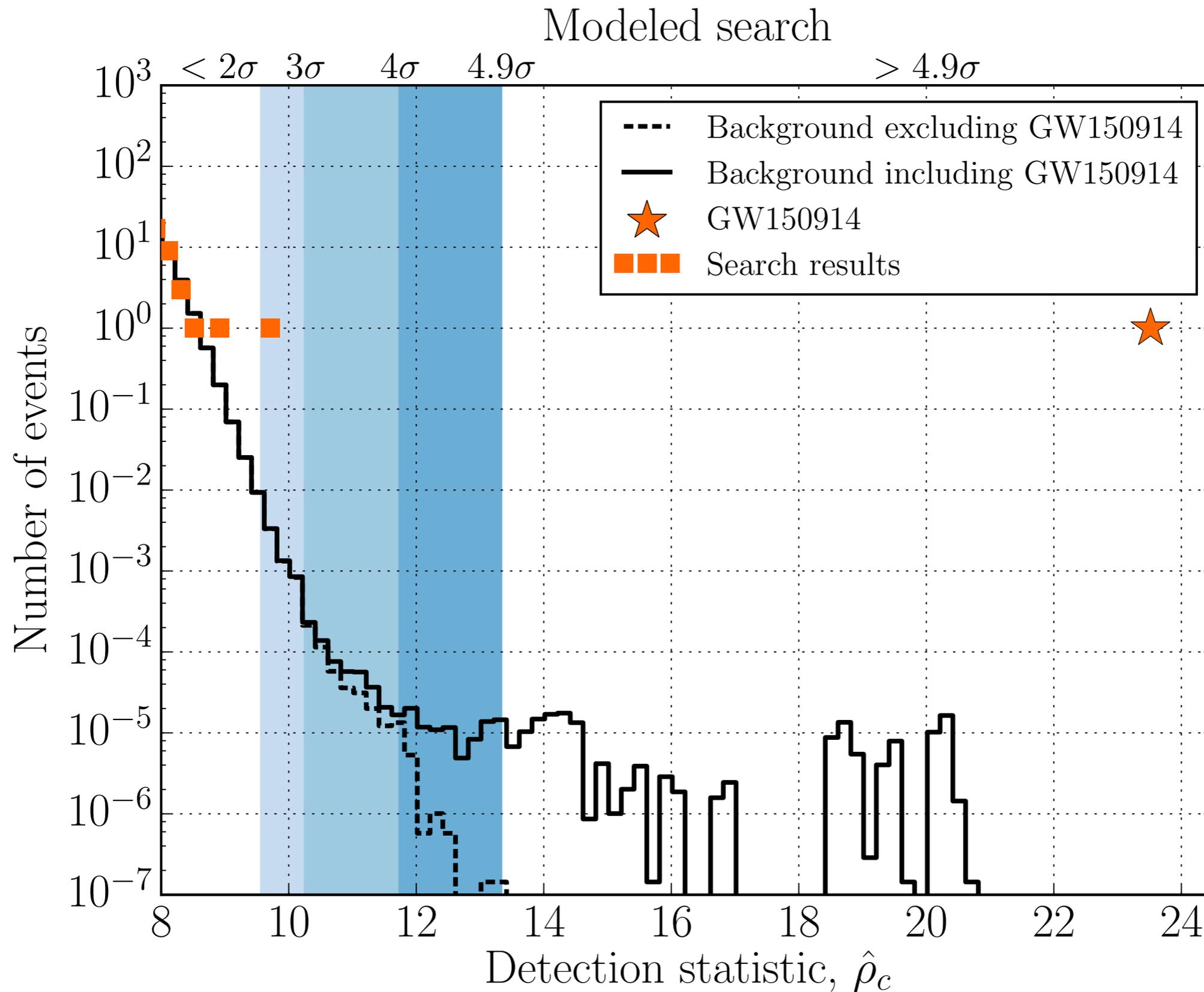
CBC template bank

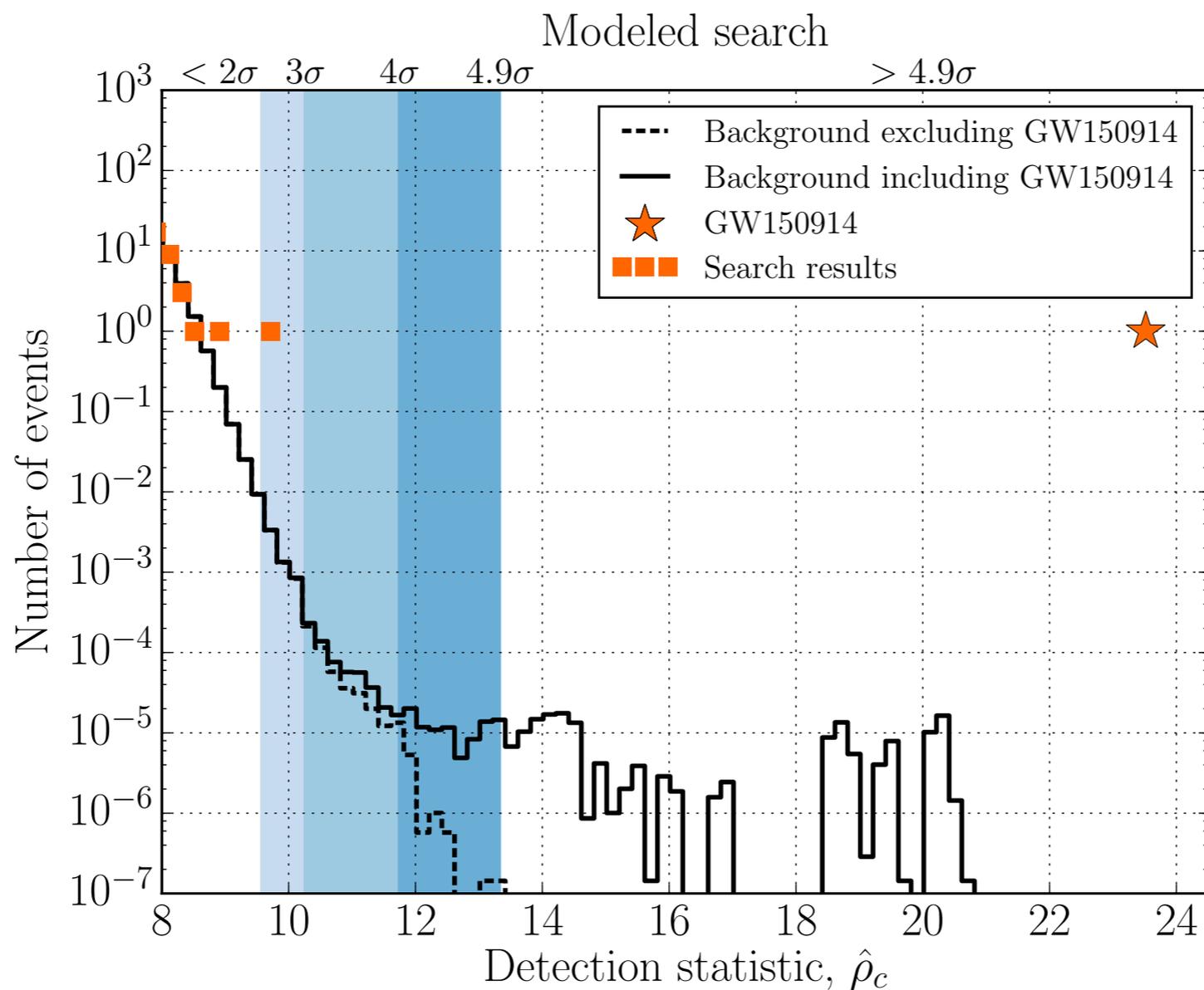


(just at the edge...)

FIG. 1. The four-dimensional search parameter space covered by the template bank shown projected into the component-mass plane, using the convention $m_1 > m_2$. The lines bound mass regions with different limits on the dimensionless aligned-spin parameters χ_1 and χ_2 . Each point indicates the position of a template in the bank. The circle highlights the template that best matches GW150914. This

Detection statistic





Event	Time (UTC)	FAR (yr^{-1})	\mathcal{F}	\mathcal{M} (M_{\odot})	m_1 (M_{\odot})	m_2 (M_{\odot})	χ_{eff}	D_L (Mpc)
GW150914	14 September 2015 09:50:45	$< 5 \times 10^{-6}$	$< 2 \times 10^{-7}$ ($> 5.1 \sigma$)	28^{+2}_{-2}	36^{+5}_{-4}	29^{+4}_{-4}	$-0.06^{+0.17}_{-0.18}$	410^{+160}_{-180}
LVT151012	12 October 2015 09:54:43	0.44	0.02 (2.1σ)	15^{+1}_{-1}	23^{+18}_{-5}	13^{+4}_{-5}	$0.0^{+0.3}_{-0.2}$	1100^{+500}_{-500}