### Status of the Advanced LIGO Project

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ICALEPCS 2015

Melbourne, Victoria, Australia October 19, 2015

LIGO-G1501274



### **Gravitational Waves**

Predicted by Einstein in 1916 as a consequence of the General Theory of Relativity

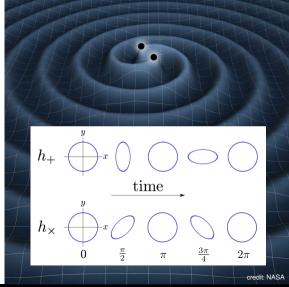
Generated from changing quadrupolar mass moments

Produce transverse strain: 
$$h = \frac{\Delta L}{L}$$

Two polarizations:  $h_+$  and  $h_\times$ 

Travel at the speed of light

Weakly interacting with matter

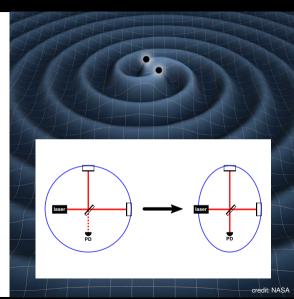


### Gravitational Waves

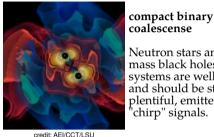
Prevailing concept for direct measurment of gravitational waves:

look for deviations in light travel time due to passing gravitational waves

Interferometric detectors (e.g. LIGO) use light interference to measure differential length changes  $\rightarrow$ 







coalescense

Neutron stars and stellarmass black holes in binary systems are well-modeled and should be strong, plentiful, emitters of "chirp" signals.



credit: NASA/JPL-Caltech/Univ. of Minn

#### core-collapse supernovae

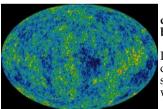
Weak and not well modeled, core-collapse supernovae could provide short bursts that could be detectable from nearby galaxies.



credit: Casey Reed, Penn State

#### spinning neutron stars

Neutron stars with "bumps" and/or strong magnetic fields could produce long-lasting, single-frequency waves.



credit: NASA/WMAP

#### cosmic gravitational-wave background

Inflation after the Big Bang could have produced a stochastic gravitationalwave background.

### The LIGO Laboratory

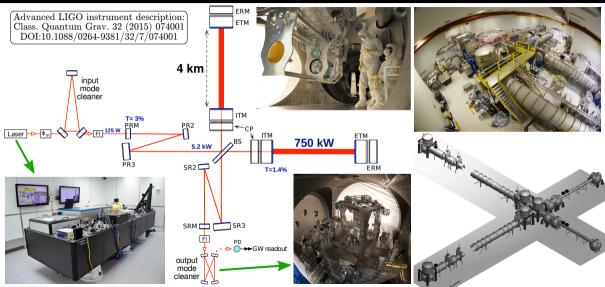


### World Wide Network of LIGO-like Detectors

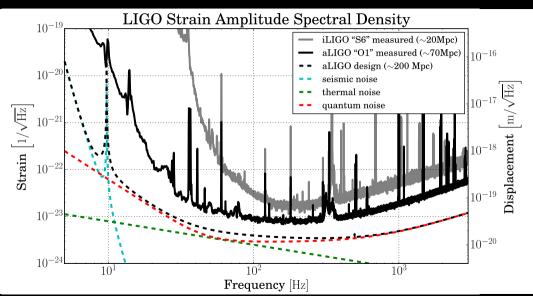




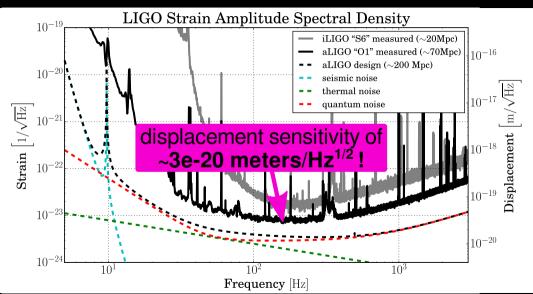
### The Advanced LIGO Detectors



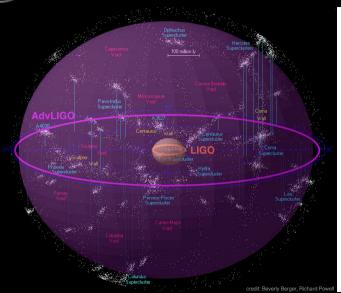
### Detector Strain Sensitivity



### Detector Strain Sensitivity



#### Potential Detection Rates



At full/design sensitivity, Advanced LIGO expects to see a neutron star binary merger rate of...

#### 40 events per year!

Not to mention other similar sources at similarly appreciable rates:

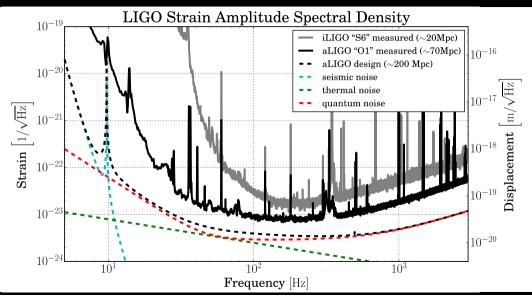
Table 5. Detection rates for compact binary coalescence sources

IFO	Source <sup>a</sup>	$\dot{N}_{\rm low}~{ m yr}^{-1}$	$\dot{N}_{\rm re} \ { m yr}^{-1}$	$\dot{N}_{\rm high}~{ m yr}^{-1}$
	NS-NS	$2 \times 10^{-4}$	0.02	0.2
	NS-BH	$7 \times 10^{-5}$	0.004	0.1
Initial	BH-BH	$2 \times 10^{-4}$	0.007	0.5
	IMRI into IMBH			<0.001 <sup>b</sup>
	IMBH-IMBH			$10^{-4  d}$
Advanced	NS-NS	0.4	40	400
	NS-BH	0.2	10	300
	BH-BH	0.4	20	1000
	IMRI into IMBH			10 <sup>b</sup>
	IMBH-IMBH			0.1 <sup>d</sup>

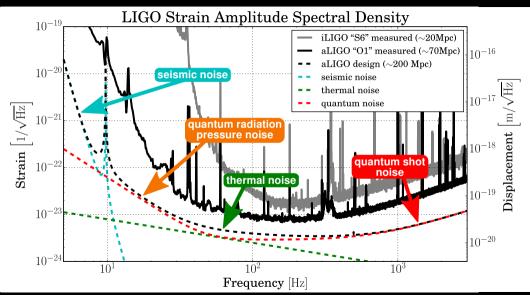
Class. Quant. Grav, 27 (2010) 173001

Status of the Advanced LIGO Project

### **Fundamental Noise Limits**



### Fundamental Noise Limits



#### Seismic Isolation

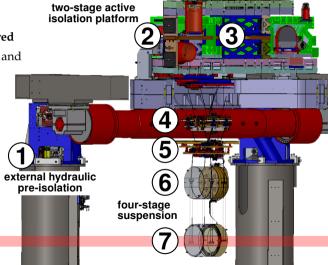
#### seismic noise

Ground motion at 10 Hz:  $1x10^{-9}$  m/Hz<sup>1/2</sup>

#### >10 orders of magnitude supression required

Test masses suspended from 7 stages of active and passive seismic isolation.



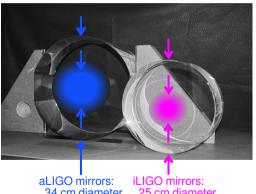




### Optics and Suspension Systems

#### quantum radiation pressure noise

Increase optic mass to reduce effects of quantum radiation pressure.

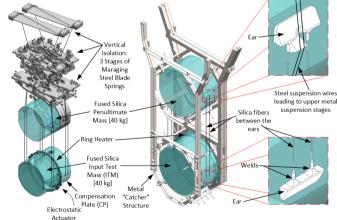


34 cm diameter 40 kg mass

25 cm diameter 10 kg mass 12 cm beam 8 cm beam

#### thermal noise

Increase optic/beam spot diameter to increase area over which thermal noise is integrated.

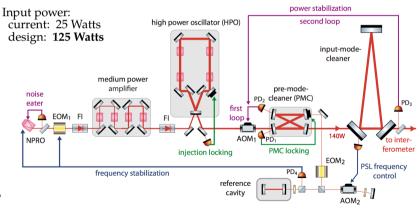


### Pre-stabilized Laser

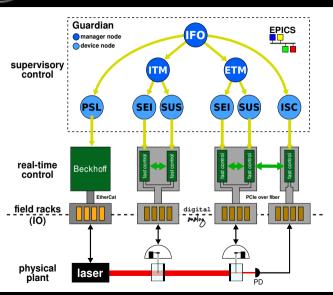


#### quantum shot noise

Increase laser power to reduce quantum shot noise from photon counting statistics.



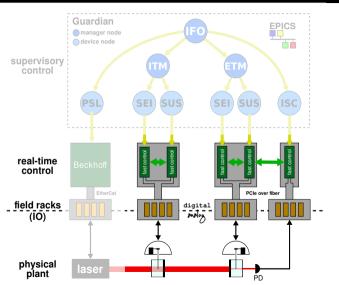
#### Interferometer Controls Overview



Advanced LIGO employs a hierarchical control structure for the full interferometer



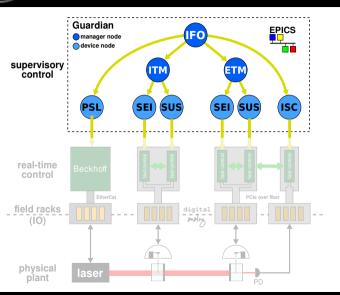
#### Interferometer Controls Overview



Fast feedback loops control all degrees of freedom (DOF) of the interferometer at the *microscopic* level via a custom built, modular, distributed, real-time digital control system (**RTS**).

Readbacks and settings of the RTS are exposed through EPICS for supervisory control and operator interfaces.

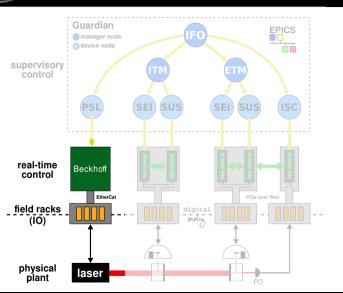




Supervisory control, i.e. automation, handled by a new hierarchical, modular, distributed, state machine platform called **Guardian**.



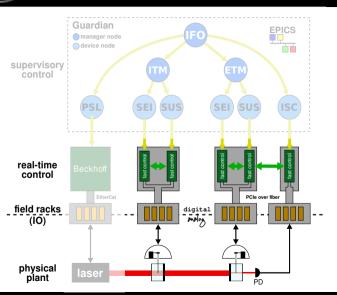
#### Interferometer Controls Overview



Additionally, a couple of auxiliary slow control systems are used:

- Beckhoff TwinCAT (EtherCAT) with custom TwinCAT EPICS IOC bridge
- Acromag (Modbus)

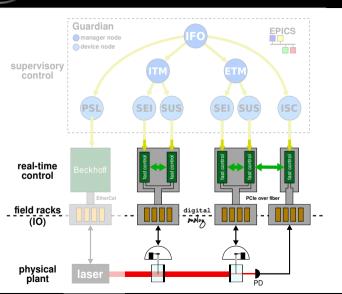
### Fast Feedback Control



Fast feedback control is the heart of aLIGO controls

# Fast

#### Fast Feedback Control



Hundreds of feedback loops in the interferometer:

#### suspensions

active damping of 3-24 DOF per suspension ( $\times 18$ )

#### seismic isolation

active damping and isolation of 18 DOF per seismic platform  $(\times 9)$ 

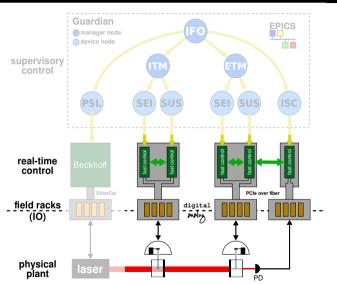
#### length control

5 global length DOF, 10 global angular DOF

many other auxiliary DOF...



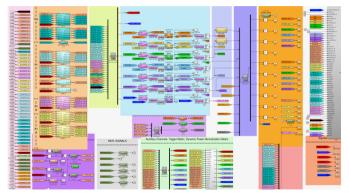
#### Fast Feedback Control



Overall sampling rate of 64 kHz.

Control loops run from  $2k \rightarrow 32k~Hz$ 





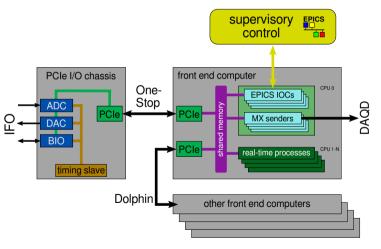
Simulink code for interferometer length DOF control

Controler signal flow and logic is drawn in MATLAB Simulink.

Real-time code generator (RCG) parses Simulink files to produce real-time code.

NOTE: This is a *custom* Simulink parser/code generator, not MATLAB.

### Real-time Computer Architecture

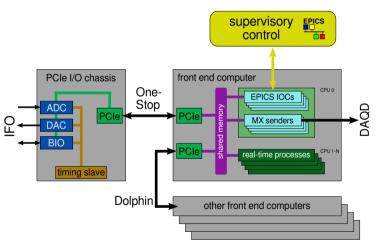


Real-time code is compiled into Linux kernel modules.

Linux kernel with custom patch loads modules and gives them each full control of a single CPU core.

CPU-0 is reserved for Linux user-space processes.





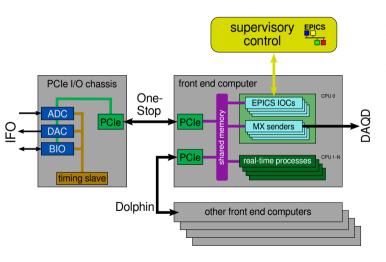
#### System is highly modular

Multiple real-time modules can be run on a single host.

Real-time modules on a single host can communicate via shared memory.

Modules on different hosts communicate via Dolphin PCIe shared memory network.

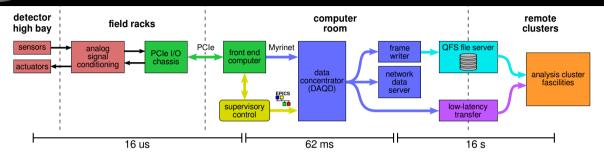
### Real-time Computer Architecture



Linux user-space process interfaces to the real-time modules:

- EPICS IOC processes provide supervisory control interfaces
- mx-stream processes send fast and slow data over a dedicated network to the data acquisition host

## Data Acquisition Pipeline



Front end ADCs and DACs operate at 64 kHz.

16-bit ADCs 18-bit DACs DAQD recieves data from all front end controllers and assembles into  $^{1}/_{16}$ -second frames.

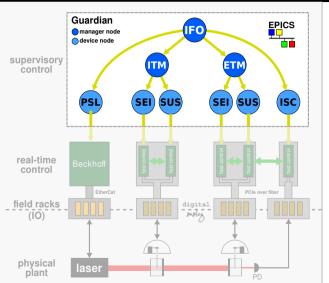
 $\sim 200$ k slow channels (16 Hz)  $\sim 7$ k fast channels (>512 Hz)

Overall 10 MB/s data rate (compressed)

Low latency (reduced channel count) frames arrive at analysis clusters in  $\sim 16$  seconds.

Full frames replicated analysis cluster:

- $\blacksquare$  on-site:  $\sim 5$  minutes
- remote:  $\sim 30$  minutes

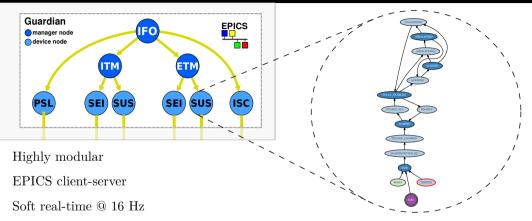


Guardian is aLIGO's new automation platform:

# Guardian is a distributed hierarchy of automaton state machines

Individual nodes oversee specific sub-domains of the instrument.

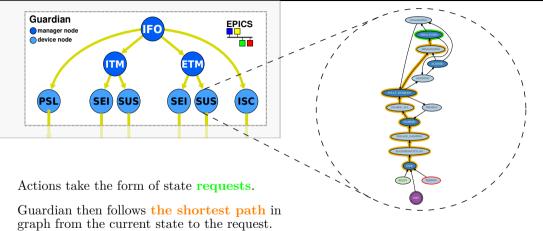
A hierarchy of nodes control the full interferometer.



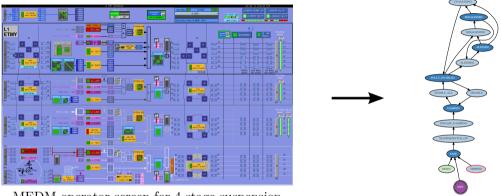
Python based

Designed for ease of commissioning: usercode can be reloaded on the fly

Each system is represented by a **state graph**.







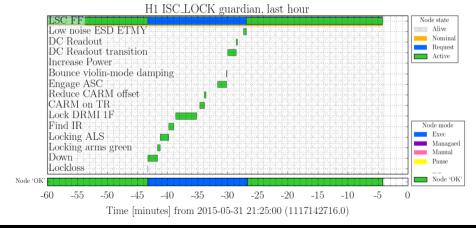
MEDM operator screen for 4-stage suspension

Guardian abstracts away the details and complexity of the control and reduces it to a finite set of desired system states.



### Guardian Lock Acquisition

Guardian manages the complex **lock acquisition** procedure that closes and tunes all feedback loops and brings the instrument to its highest sensitivity level.

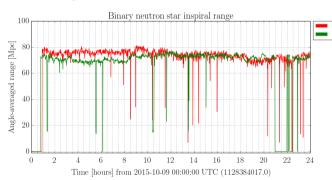




### Observatory Status

#### aLIGO started first Observing run on September 18, 2015.

The LIGO detectors are now the most sensitive gravitational-wave detectors ever made, by more than a factor of three.



A week of aLIGO is worth more than a *year* of iLIGO (in terms of time-volume product).

At full design sensitivity, aLIGO will probe  $1000 \times$  more volume than iLIGO.

Many more detector improvements and observing runs to come...

