PSL Presentation at UF September 4th, 2015 GM

Source Material:

- <u>GII00452</u>
- Optics Express, Vol 20(10), 10617 (2012)
- Dissertation presentation Jan Pöld (AEI, 2014)
- <u>GI100837</u> (PSL Training Session, incl. movies)











Why this design?

• MI:

- optimum geometry (∂l-meter)
- equal arms = common mode rejection of noise





Advanced LIGO: Back on the envelope

Displacement Sensitivity: Shot Noise only	$P_{in} = 25W N_{in} = 1.4 \cdot 10^{20} \frac{Ph}{s}$
Power Recycling:	$N_{PR} = \frac{1}{T_{PR}} N_{in} = \frac{N_{in}}{0.02} = 6.6 \cdot 10^{21} \frac{Ph}{s}$
MI-Phase sensitivity:	$\phi_{BS} = \frac{1}{\sqrt{N_{PR}}} = 1.2 \cdot 10^{-11} \frac{rad}{\sqrt{Hz}}$
Arm cavity gain:	$\phi_{cav} = \frac{T}{4}\phi_{BS} = 3.5 \cdot 10^{-14} \frac{rad}{\sqrt{Hz}}$
In length and strain:	$h_{min} = \frac{\delta l}{L} = \frac{\phi_{cav}}{2\pi} \frac{\lambda}{L} = \frac{6 \times 10^{-21} m}{4000m} = \frac{1.5 \cdot 10^{-24}}{\sqrt{Hz}}$
Low pass filter of cavity:	$h_{min}(150Hz) = h_{min} \cdot 2 = \frac{3 \times 10^{-24}}{\sqrt{Hz}}$



Advanced LIGO: Back on the envelope



Advanced LIGO: Back on the envelope

- **Displacement Noise:**
- Seismic motion
- Environmental vibrations
- Thermal noise
 - Coating
 - Substrate
 - Suspension
- Radiation Pressure Noise
 - Fundamental (Quantum)
 - Technical
 - Unbalanced Arms
- Newtonian or Gravity
- gradient noise





Key systems:

- PSL
- 0
- Core Optics
- Suspensions
- SEI
- Main IFO
 - Mode matching
 - ISC, ASC
- Output Optics
- TCS
- AOS
- Photon calibrator

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PSL: Prestabilized Laser System

Designed, developed, tested, installed by Albert Einstein Institute, Hannover, Germany

Development Lead:Benno WillkePSL-Lead at project-level:Peter KingPSL-Officer at LLO:Matt Heintze





- Stand alone Laser system
- Stabilized system

Requirement flow down:

- Top level:
 - 125W TE00 injected into IFO spatial mode
 - < 5W in higher order modes as defined by IFO
 - Saturates detectors
 - Creates stray light



Requirements:

- Stand alone Laser system
- Stabilized system

Requirement flow down:

- Top level:
 - 125W TE00 injected into IFO spatial mode
 - Laser frequency noise relative to CARM

$$\frac{\delta\nu}{\nu} \approx h \times (CARM \to DARM) \approx \frac{10^{-22}}{\sqrt{\text{Hz}}}$$
$$\delta\nu \approx 3 \times 10^{-8} \frac{\text{Hz}}{\sqrt{\text{Hz}}}$$



relative to CARM

Requirements:

- Stand alone Laser system
- Stabilized system

Requirement flow down:

- Top level:
 - 125W TEM00 injected into IFO spatial mode
 - Laser frequency noise relative to CARM
 - Laser Amplitude noise = Relative Intensity Noise (RIN)







measured at input of IFO at 125W input power

Requirements:

- Stand alone Laser system
- Stabilized system

Requirement flow down:

- Top level:
 - 125W TE00 injected into IFO spatial mode
 - Laser frequency noise relative to CARM
 - Laser Amplitude noise = Relative Intensity Noise (RIN)
 - Beam pointing = beam jitter
 - Maintain alignment into IFO (active or passive)

$$\tilde{a}_{10}^{\max}(f) \leq \frac{7 \cdot 10^{-10}}{\sqrt{\text{Hz}}} \sqrt{1 + \left(\frac{230 \,\text{Hz}}{f}\right)^4} \left(\frac{10^{-8} \text{rad}}{\Delta \Theta_{\text{ITM}}}\right) \qquad a_{10} = \frac{\delta x}{\omega} + i \frac{\delta \alpha}{\Theta}$$





- Stand alone Laser system
- Stabilized system

Requirement flow down:

- Top level
- 'Propagate' back through IO to PSL
 - IO filters Laser noise
 - reduces requirements of stand-alone laser
- IFO and IO provide control signals to suppress laser noise
 - Requires appropriate actuators within PSL (and IO)





- Stand alone Laser system
 - Power output: Deliver 165W TEM00 to IO
 - <5% of power in higher order modes</p>





- Stand alone Laser system
 - Power output: Deliver 165W TEM00 to IO
 - <5% of power in higher order modes</p>
 - laser frequency noise







- Stand alone Laser system
 - Power out
 - <5% of po
 - laser frequ \sqrt{H}
 - RIN







- Stand alone Laser system
 - Power output: Deliver 165W TEM00 to IO
 - <5% of power in higher order modes</p>
 - laser frequency noise
 - RIN
 - Laser frequency drift: < 100kHz over 100s
 - Laser power drift: < 5% over 24h





advanced LIGO laser - layout



LIGO

LIGO



advanced LIGO laser - layout



LIGO



advanced LIGO laser - layout



eLIGO laser





LIGO

eLIGO Laser System

Amplifier



- 4 stage Nd:YVO₄
- water cooled
- fiber coupled pump diodes
- pump power 4 x 32 W
- seed power 1.7 W
- output power 35 W
- pump light pickups
 - laser pickups
- temperature monitoring







eLIGO Laser System

Diode Box



- 4 pump diodes
- water cooled heat sink
- temperature interlocks
- diode power supplies
- peltier driver boards with power supply
- Beckhoff interface

Pump diodes located in different room. Fiber coupled

















eLIGO Laser = aLIGO front end

Nd:YVO4 crystals pumped by 808nm diode lasers



Injection locked ring laser, forced to emit on the injected laser frequency

- laser frequency identical to master laser
- Pumped by four ~200W diode laser arrays, fiber coupled



Ring laser:

- 'Point' design. Requires certain pump power to create thermal lens in Nd:YAG rods to stabilize laser resonator.
- Water-cooled

Laser system can only operate at full power

• Current low power operation (25W input at PRM) works w/o high power oscillator (slave laser)!



Auxiliary parts of PSL:

- Diagnostic Breadboard (see Paul for details)
- Pre-mode cleaner: Bow tie cavity to spatially filter laser field
- Ist Stage intensity stabilization system (ISS)
 - Sensor prior to Input Optics!!





DBB: Mode Analyzer Cavity Power monitor Pointing monitor (QPD1&2)

• with respect to PMC

ISS:

- PDA: Creates error signal
- PDB: Out of loop signal
- QPD to maintain alignment
 - PD sensitivity depends on position on active element



High power laser beam:

- Fairly bad spatial mode quality (thermal distortions ...)
 - incl. beam jitter
- Pre-Mode Cleaner (PMC) filters spatial distortions
 - Locked to laser frequency via PDH signal



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Reference Cavity:

- Glass cavity in thermally isolated vacuum tank
- Ist Frequency stabilization system
- Offset lock:
 - SB generated in AOM, locked to cavity
 - Sideband frequency tunable





Sensors external to PSL:

- Frequency:
 - Input Mode Cleaner (IMC)
 - Common Arm Cavities (CARM)
- Intensity:
 - 2nd ISS uses signal in HAM2 after IO











- four photodiodes per detector
 - In-loop
 - Out of loop
- each aligned to lowest pointing coupling
- 50mA photocurrent per photodiode
- in dust-free environment with reduced pointing fluctuations
- installed in HAM 2

Sensors external to PSL:

- Frequency:
 - Input Mode Cleaner (IMC)
 - Common Arm Cavities (CARM)
- Intensity:
 - 2nd ISS uses signal in HAM2 after IO

General issues with PSL:

- Beam pointing from PSL table (out of IO) might be higher than expected due
 - Acoustic noise and water flow shakes IO periscope
- 2nd ISS loop not yet 100% functional
 - Sees also stray light from IOT2R
 - Needed for high power operation only (not yet)



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