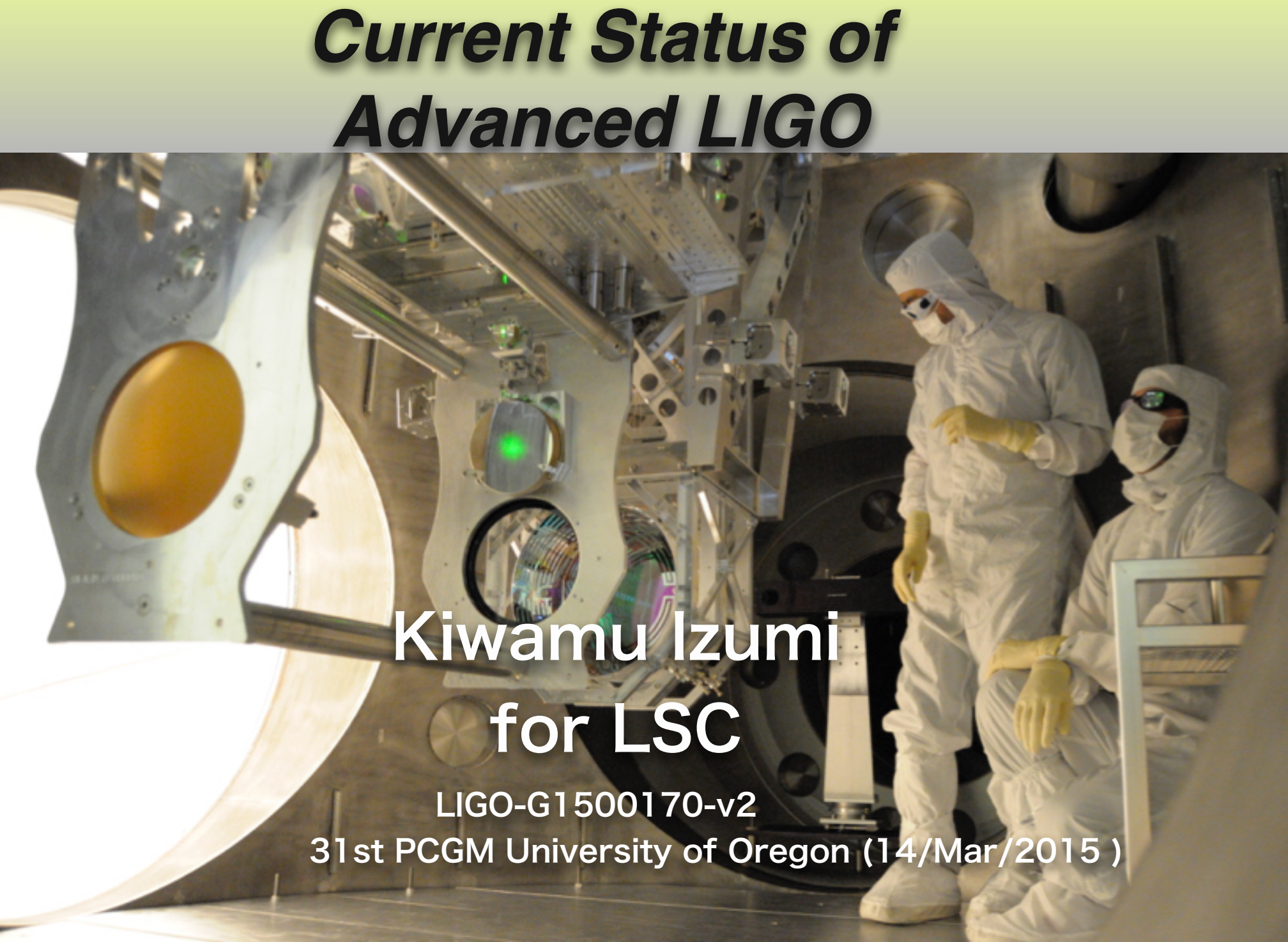


Current Status of Advanced LIGO

The image shows two technicians in white cleanroom suits and yellow gloves working on the Advanced LIGO interferometer. The technician on the left is standing and pointing towards the equipment, while the one on the right is sitting on a metal stool. The background is filled with complex metallic structures, including a large yellow circular component on the left and various optical paths with green and purple laser beams. The overall environment is a clean, industrial laboratory setting.

**Kiwamu Izumi
for LSC**

LIGO-G1500170-v2

31st PCGM University of Oregon (14/Mar/2015)

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■ Advanced LIGO

■ Experimental highlights and challenges

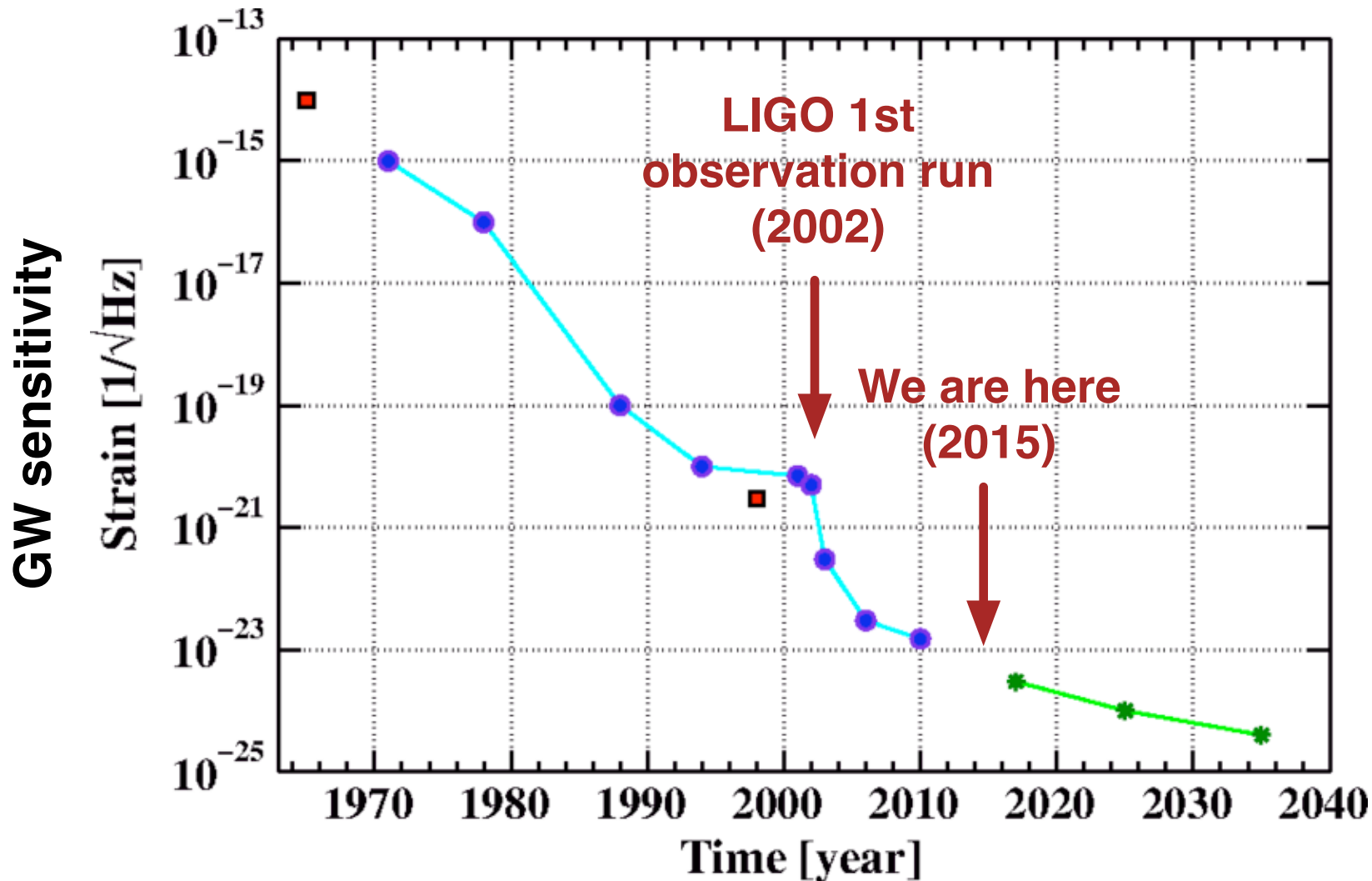
■ Prospects

■ Conclusions

Evolution in 40 yrs

and beyond

Almost 9 orders of magnitude improvement

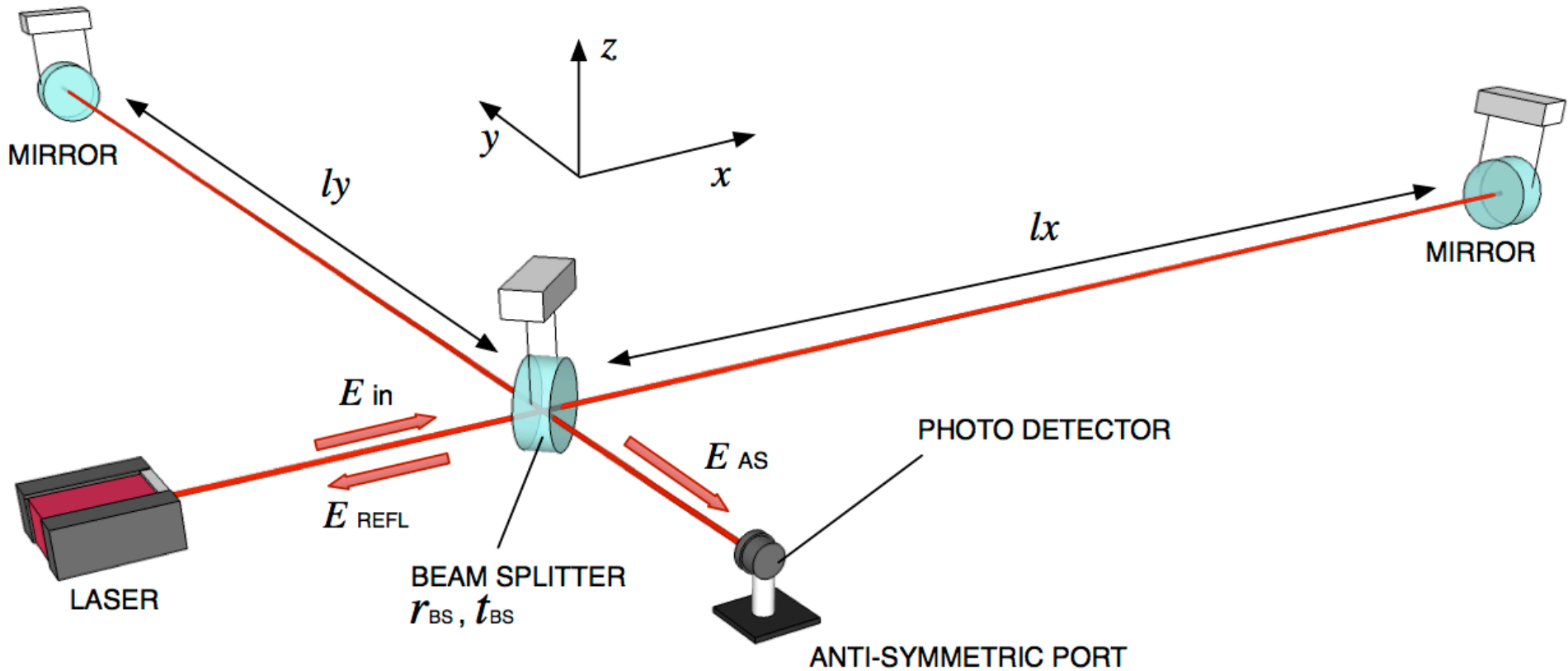


LIGO

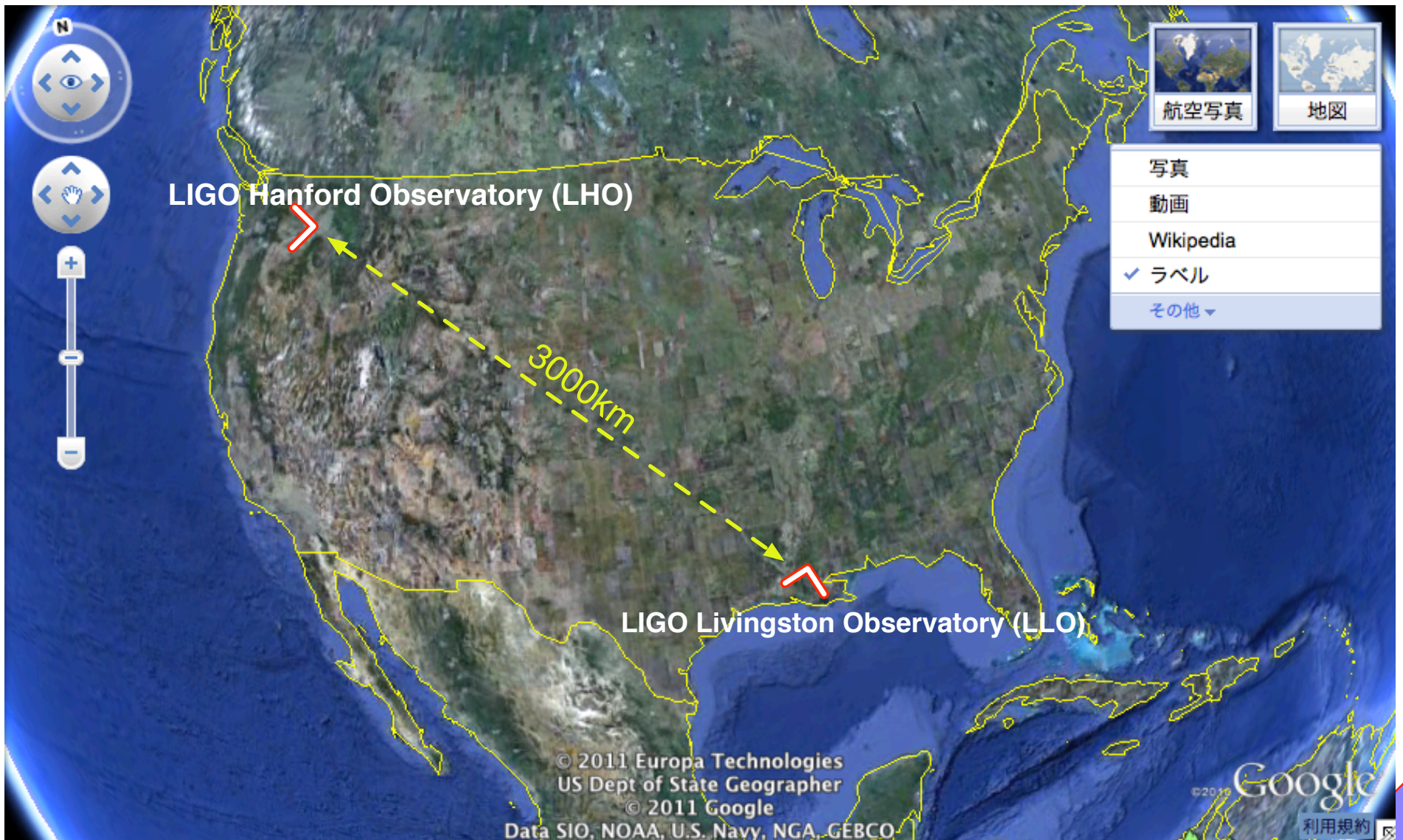
- LIGO = **L**aser **I**nterferometer
Gravitational wave **O**bservatory
- Joint project between Caltech
and MIT funded by NSF
- Collaboration with ~ 90 institutes
all over the world
- The detectors have been upgraded to
Advanced LIGO (aLIGO)

Working principle

Sensitive in 10 to several kHz band

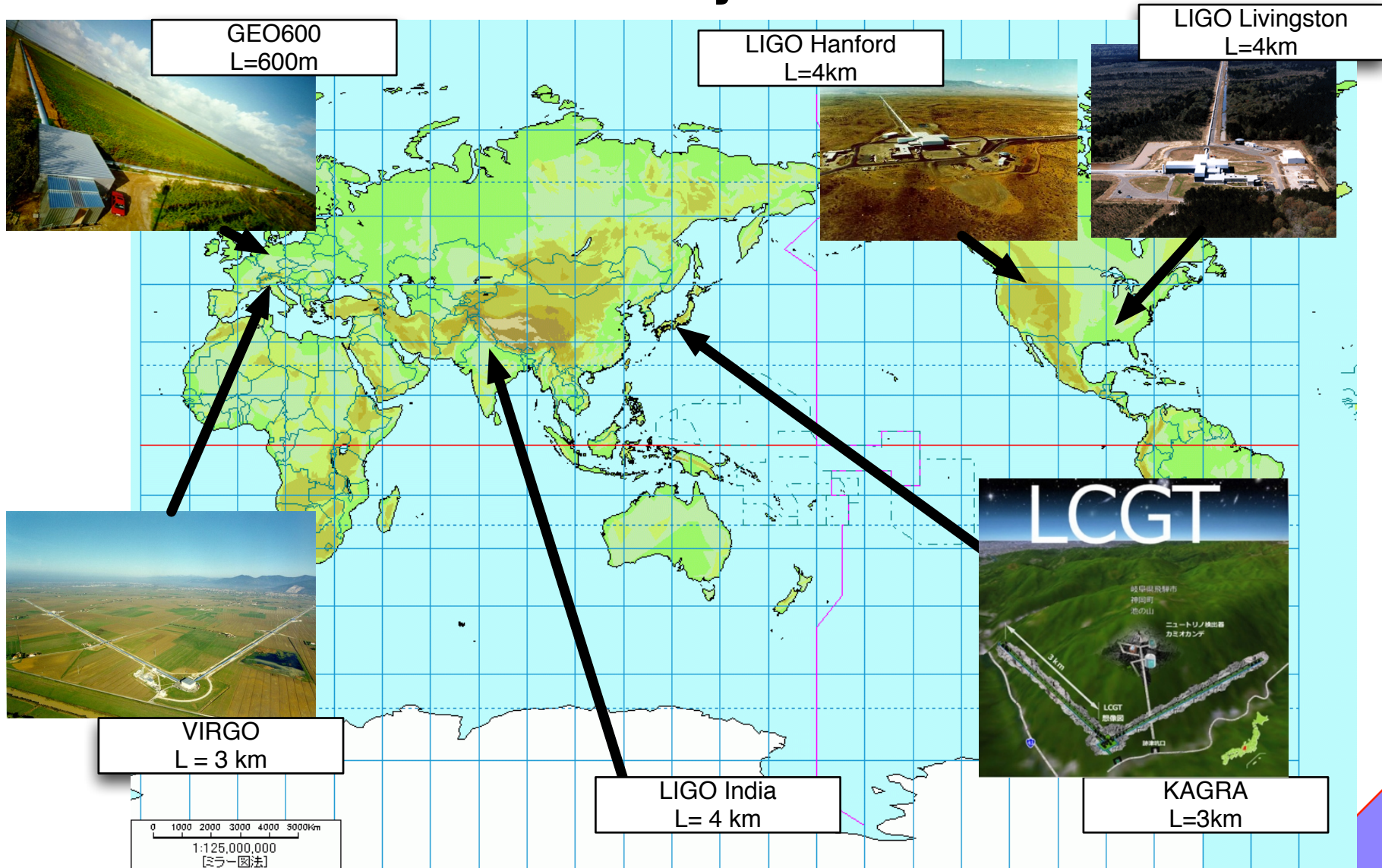


Two LIGO observatories



World Wide Network

Allows for sky localization



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■ **Advanced LIGO**

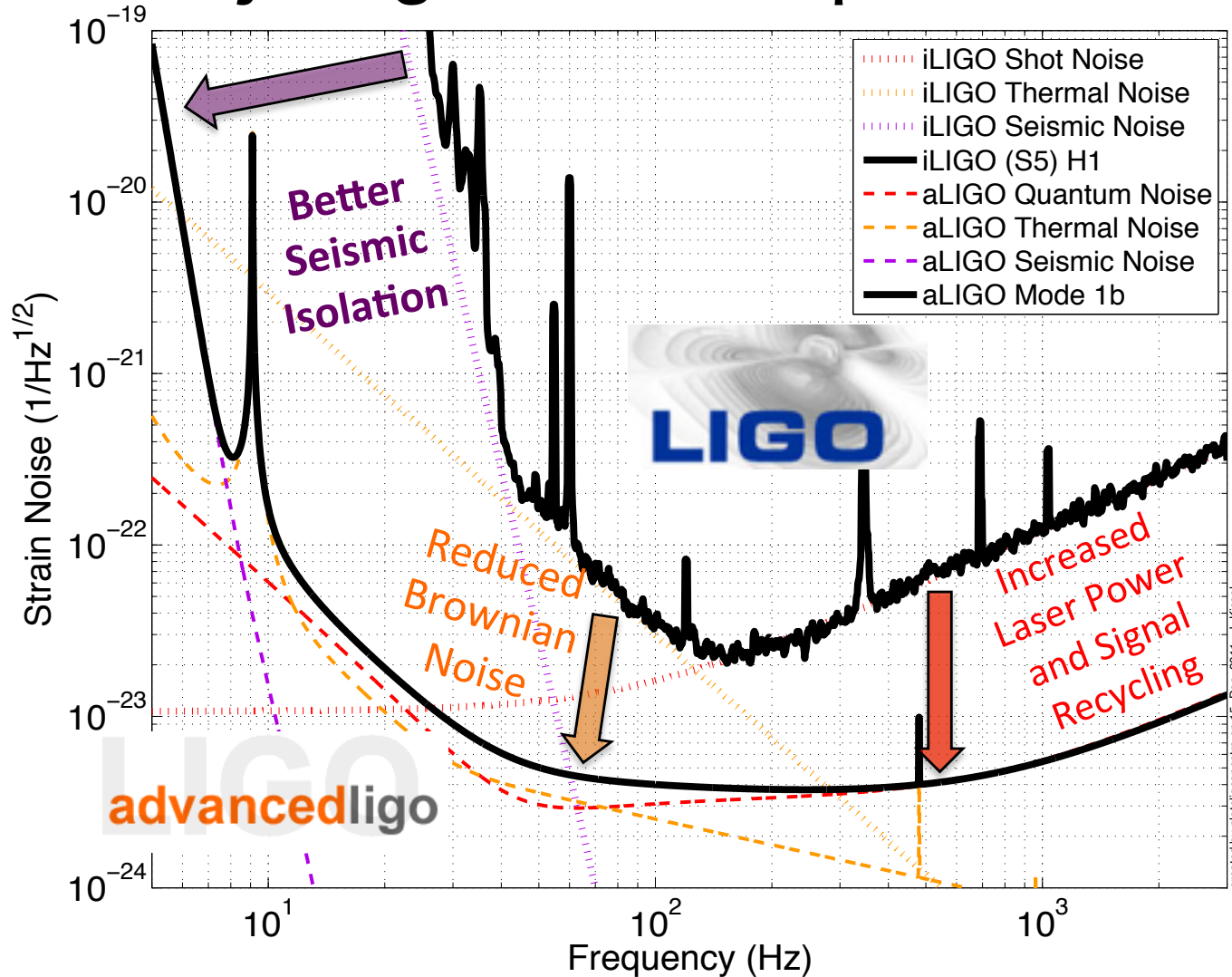
■ Experimental highlights and challenges

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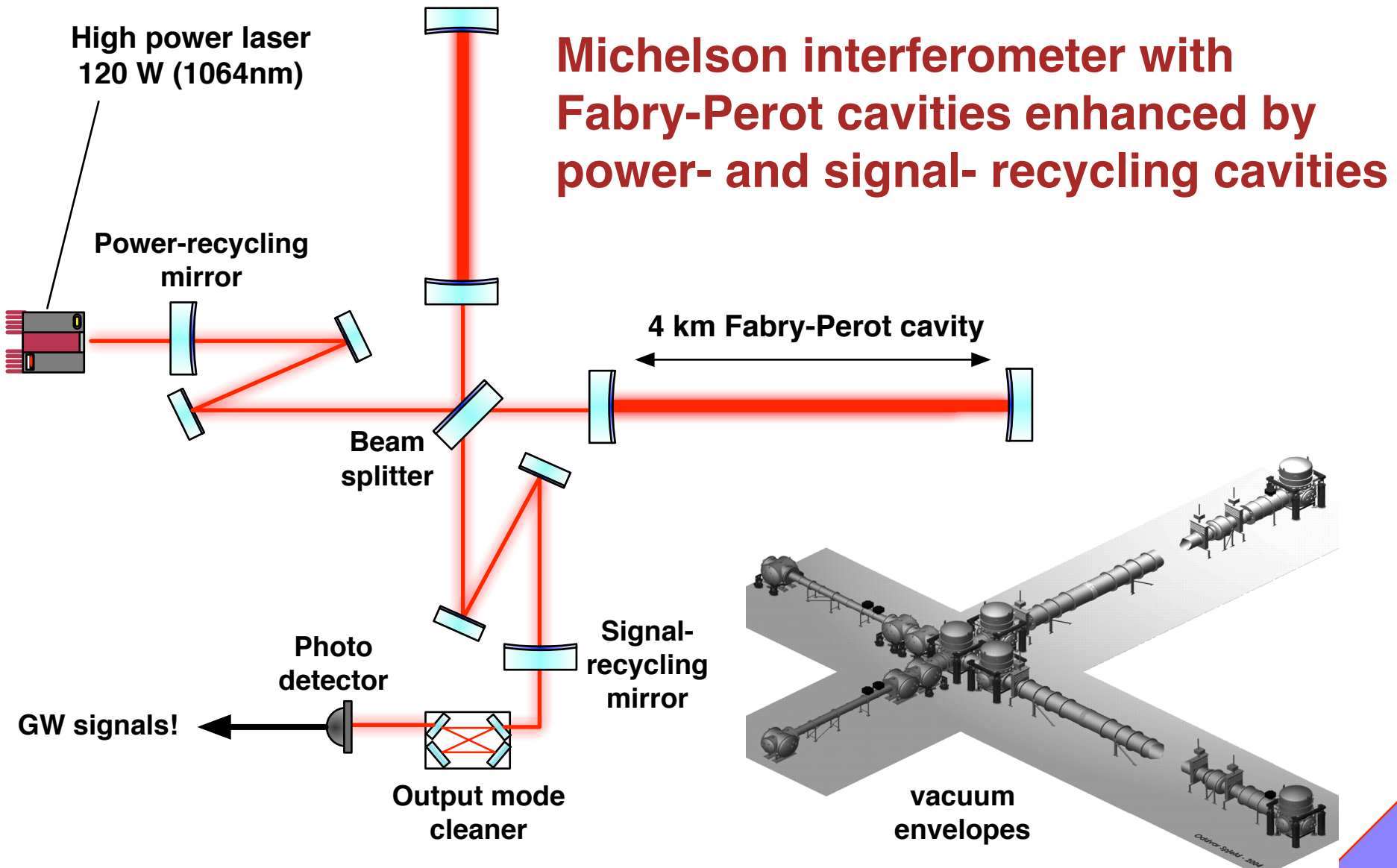
■ Conclusions

Advanced LIGO

- ▣ Aims to increase the sensitivity by a factor of ~ 10
- ▣ NS-NS binary range of ~ 200 Mpc

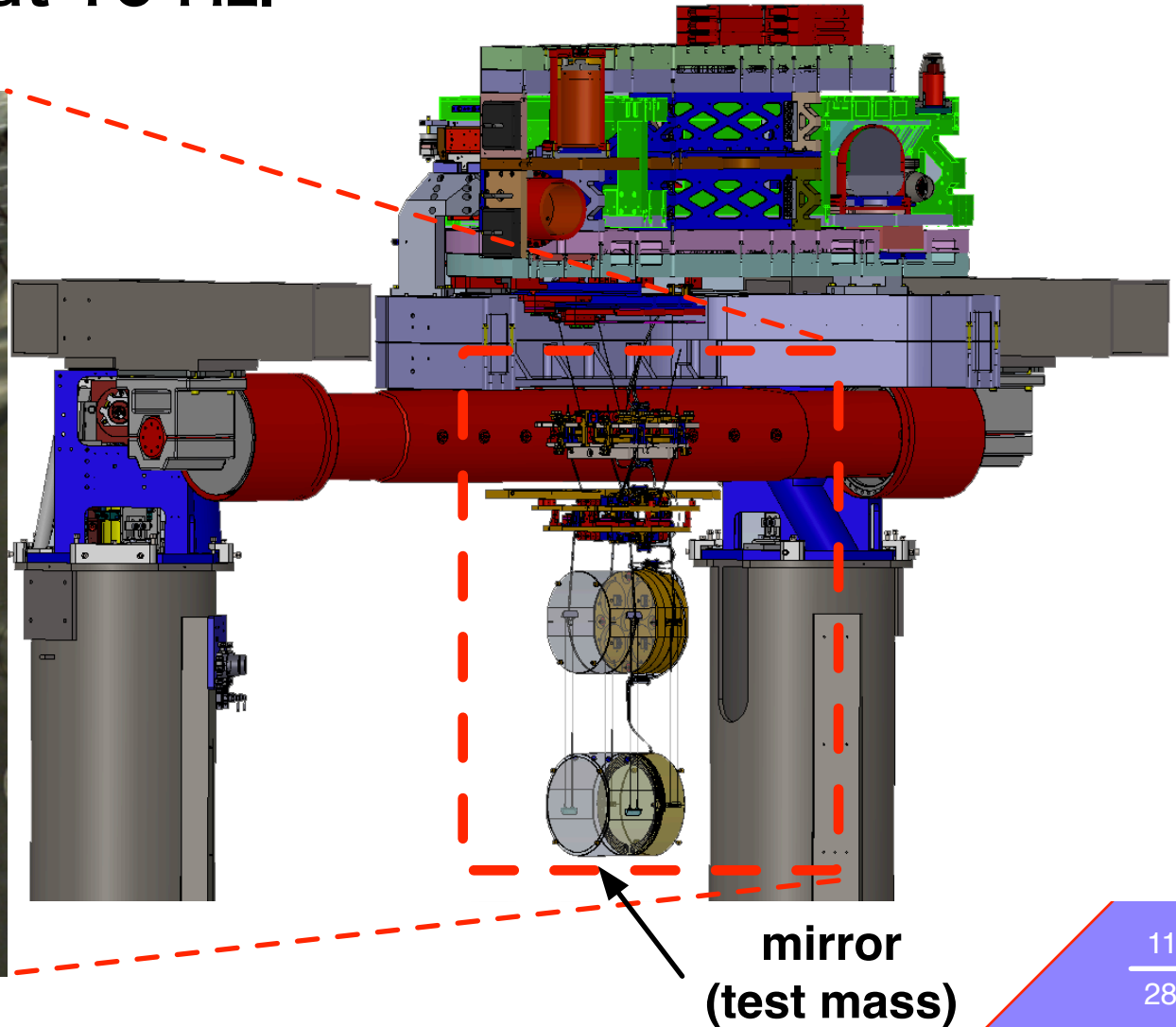
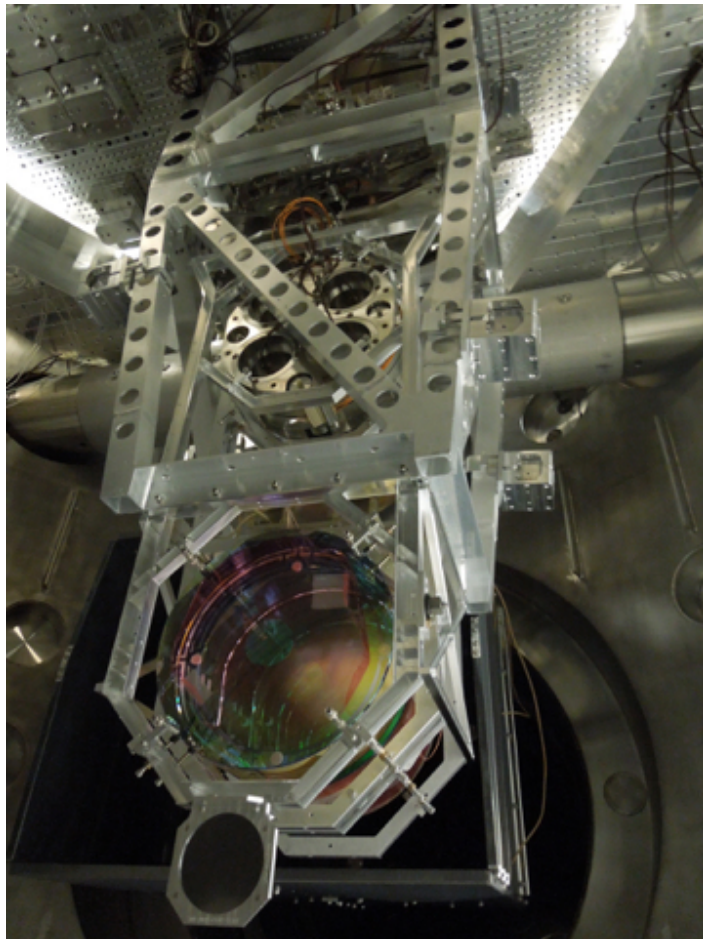


Advanced LIGO



Vibration Isolation

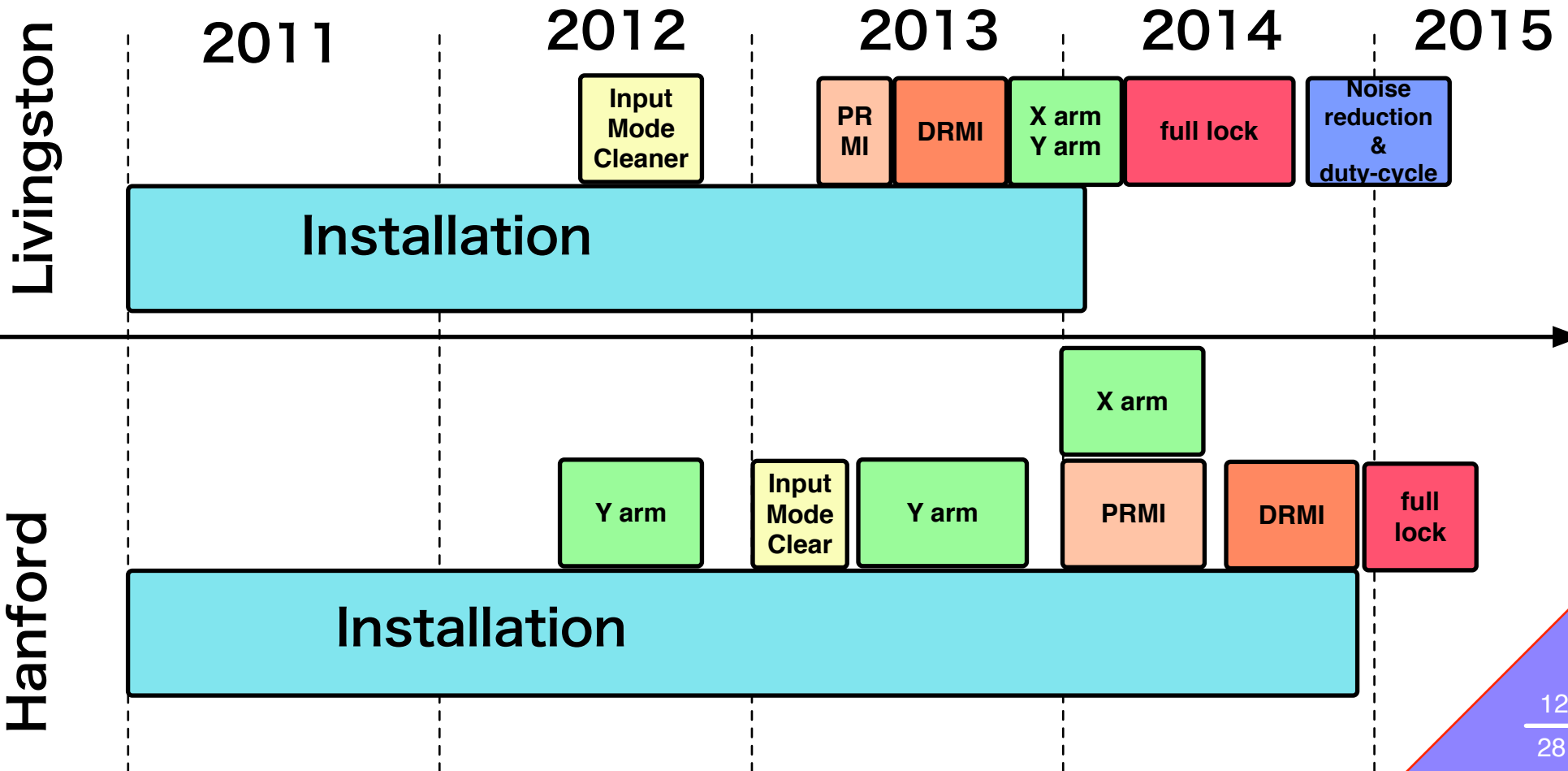
- Multiple isolation stages to provide seismic level of $10e-19$ m/sqrtHz at 10 Hz.



mirror
(test mass)

Installation and integration tests

We performed several integration tests as the hardware was installed and became ready for testing



Current Status

Goals for the installation are achieved

Goals: we provide

- ▣ Fully locked interferometer.
- ▣ Stable operation for 2 hours.

We are preparing for observation runs

- ▣ Noise hunting
- ▣ Duty-Cycle improvement

with a low laser power (10-25 W)

Livingston achieved 60 Mpc binary range

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What are difficulties ?

▣ More complicated interferometer control

- Large number of active control loops to handle
- Signal-recycling optical cavity is newly implemented
- Weaker test mass position actuators

▣ Use of high power laser

- Opto-mechanical couplings
- Thermal deformations of mirror substrates

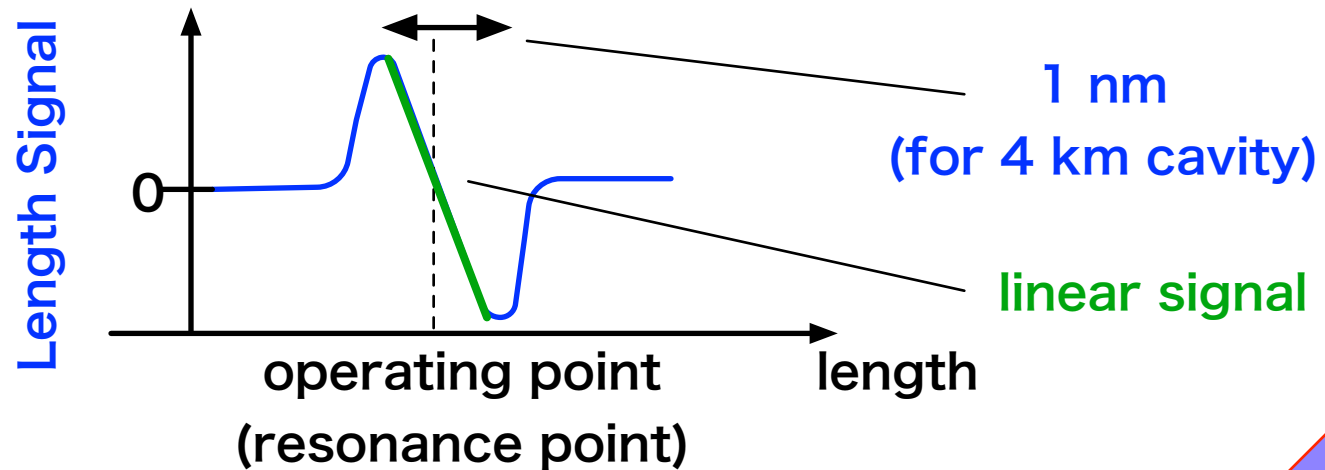
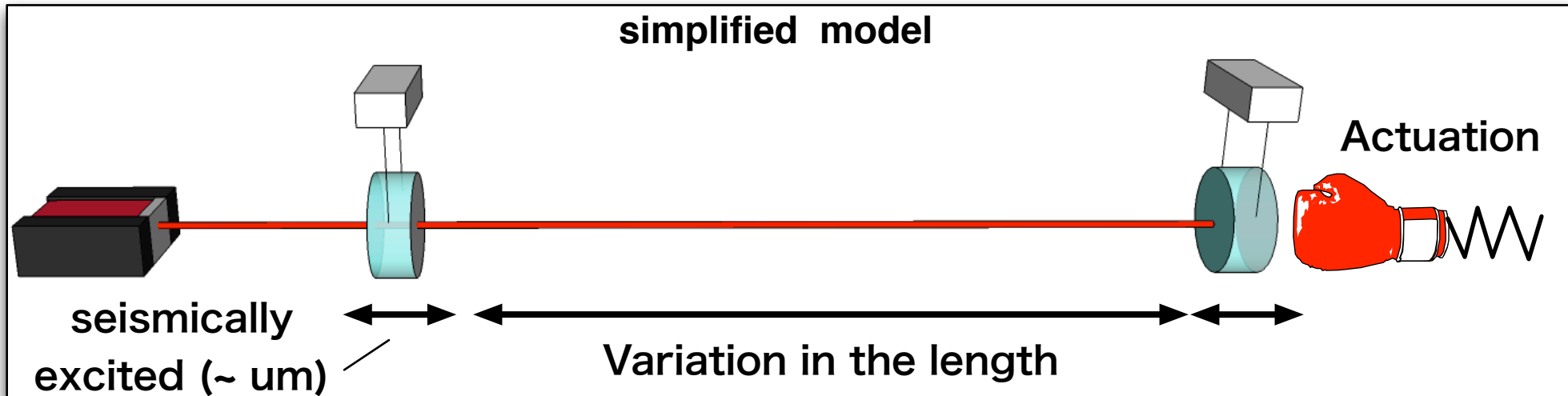
▣ Noise Hunting

- Source identification

▣ And more

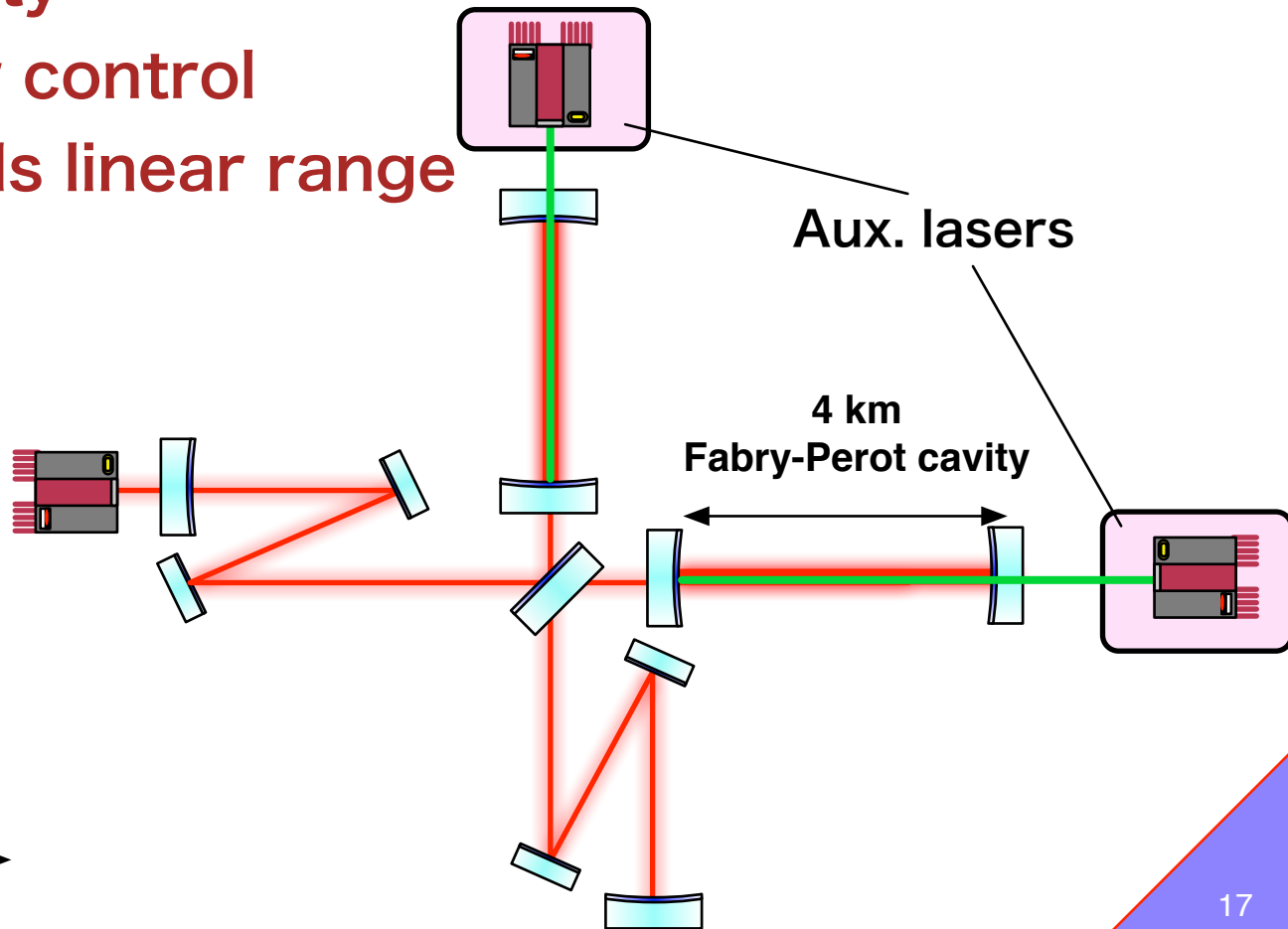
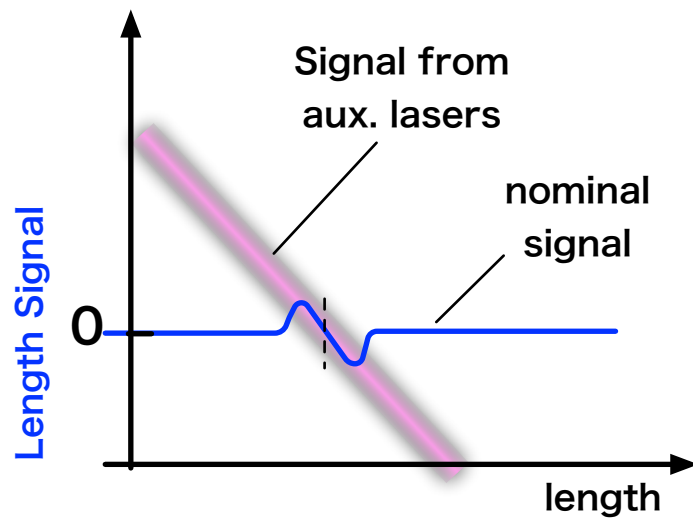
Interferometer Control

Signal can be obtained
only when the cavity is in the vicinity of operating point



Arm Length Stabilisation (ALS)

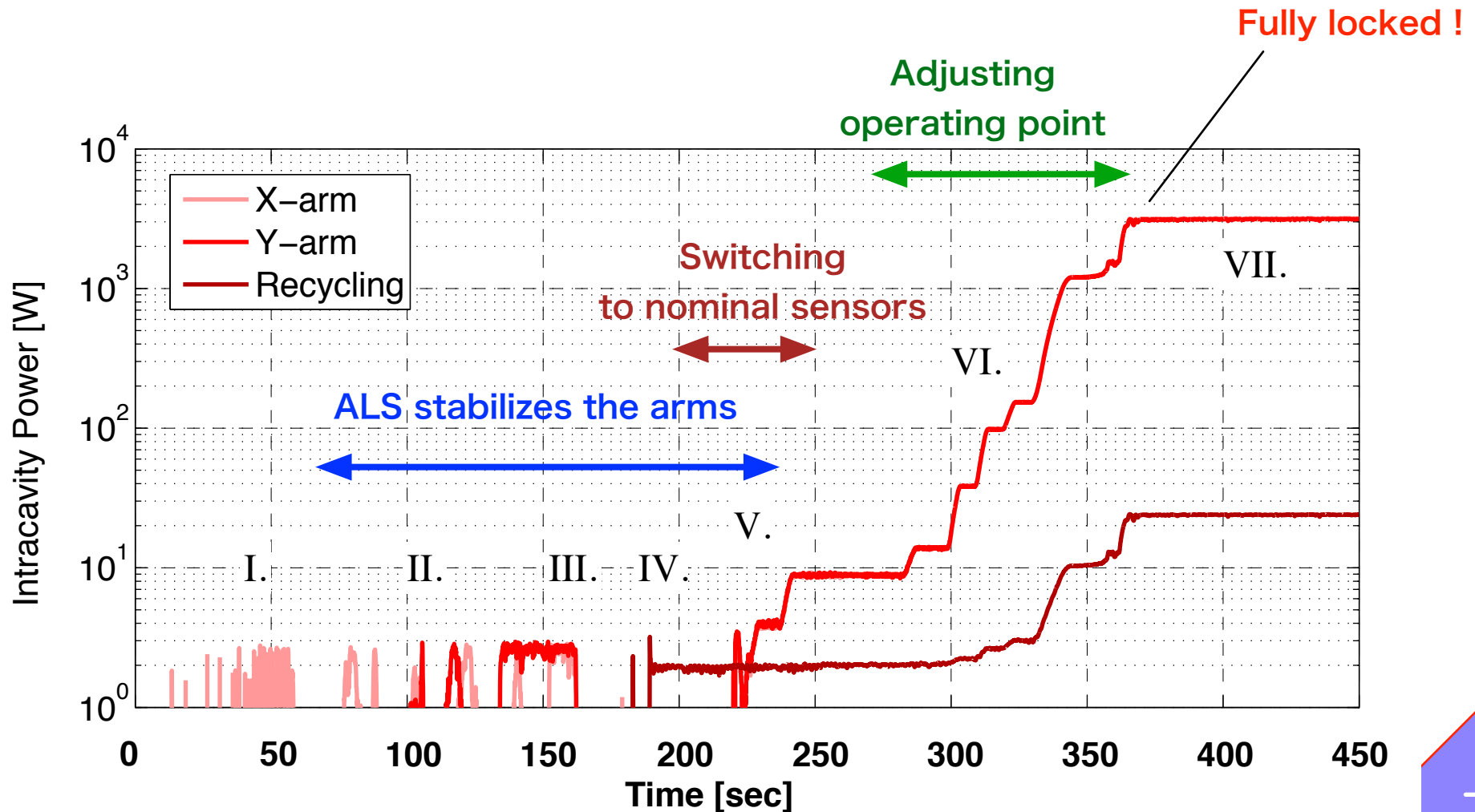
- Uses auxiliary lasers (532 nm, visible)
- Senses the arm lengths independently
- Reduces complexity of interferometer control
- Effectively expands linear range but noisier



Details:[1] A.Mullavey et al., Opt. Express, 20, 1, 81 (2012)
[2] KI et al., J.Opt.Soc.Am.A, 29,10,2092 (2012)

Full lock achieved

- Achieved at Livingston in May 2014
- Achieved at Hanford in Feb. 2015

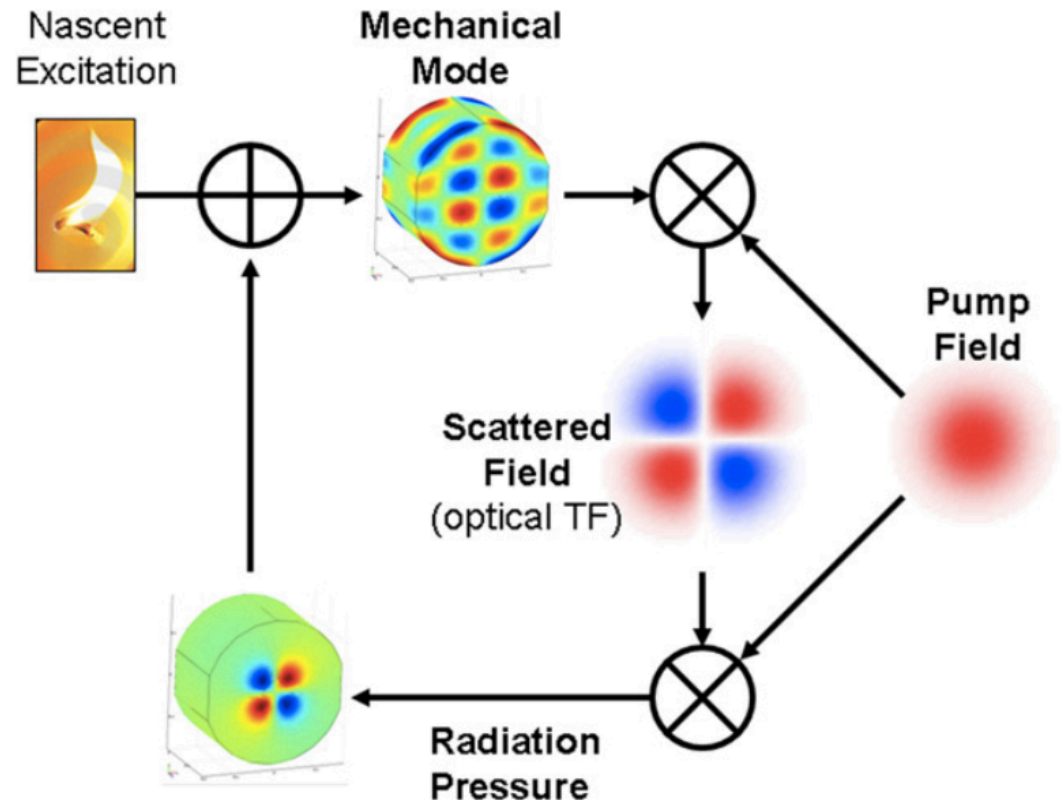


Challenges with high power

- ▣ To achieve better quantum noise, laser power will be increased
- ▣ However high power laser is known to cause a number of issues
- ▣ Thermal deformation of the mirror substrates
- ▣ Radiation pressure will be large enough to cause opto-mechanical couplings
 - => Parametric instabilities
 - => Radiation pressure angular instability
 - => we started experiencing these issues

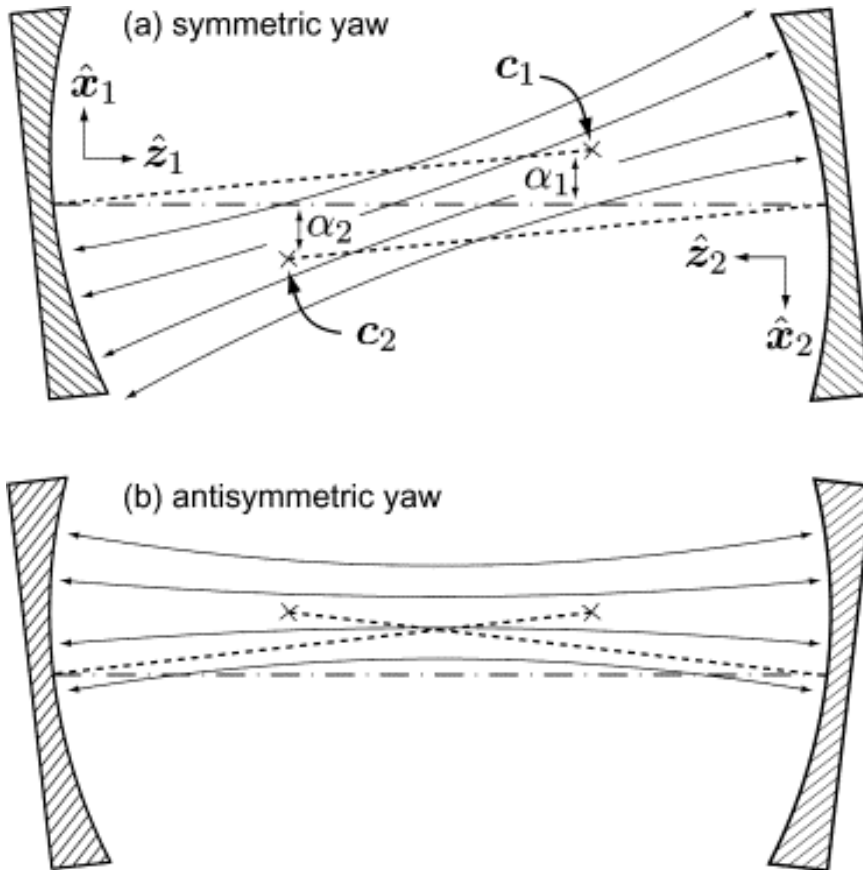
Parametric Instabilities

- ▣ Mechanical modes of the test masses couple to particular spatial mode of the laser field [1]
- ▣ Some modes can be unstable (it grows forever)
- ▣ Livingston started seeing an unstable mode at 25 W [2]
- ▣ An active damping technique will be applied [3].



[1] M.Evans et al., Phys.Letters A, 374 665 (2010)
[2] M.Evans et al., arXiv:1502.06058 (2015)
[3] J.Miller et al., Phys.Letters A, 375 3 788 (2010)

Radiation Pressure Torque



- Radiation pressure links two test masses [1]
- This leads to a unstable mechanical mode
- Experienced in initial LIGO and mitigated by active alignment control [2][3]
- We will enter the unstable regime

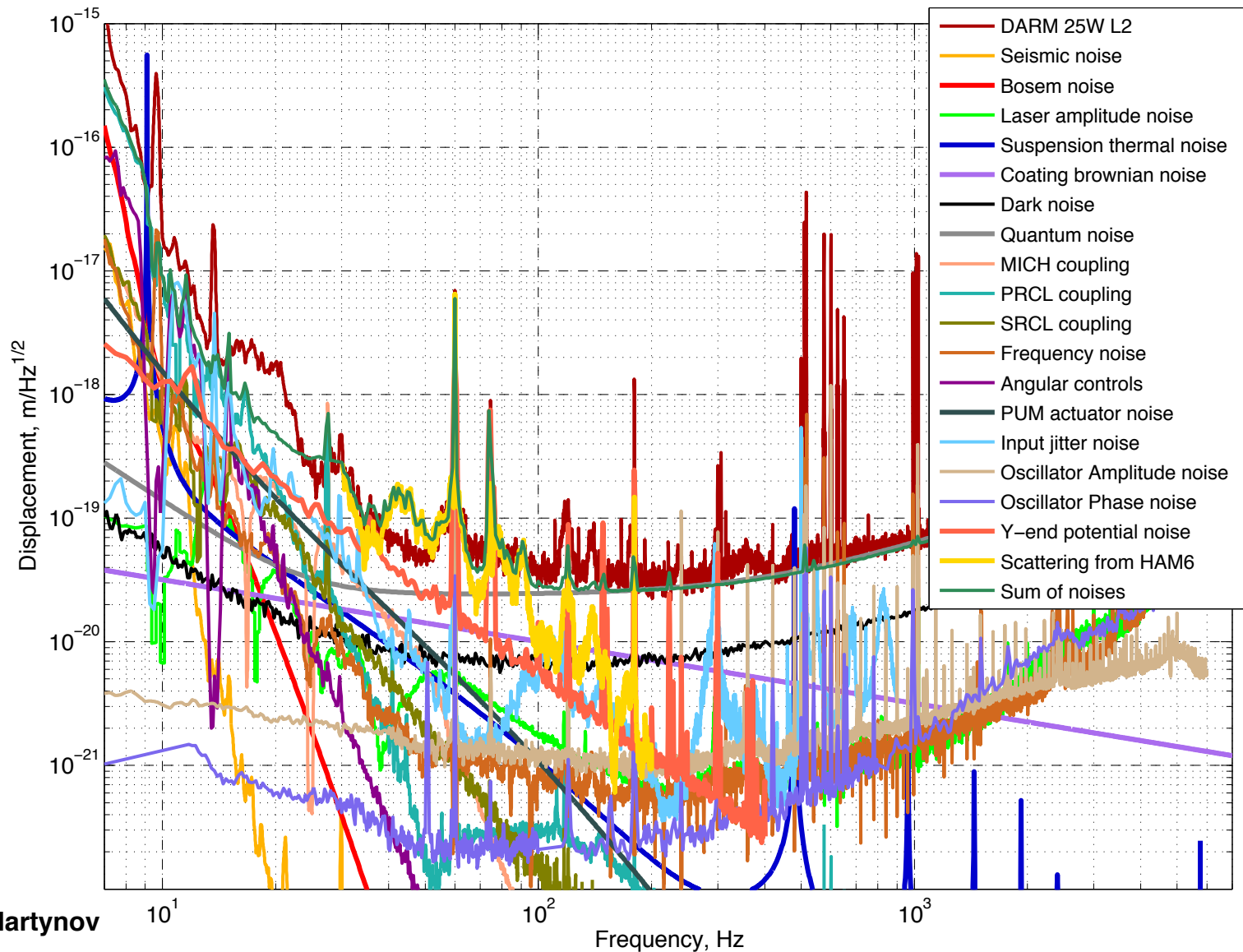
[1] J.A.Sidles and D.Sigg, Phys. Letters A, 354,3,167 (2006)

[2] K.Dooley et al., JOSA A, 30 12 2618 (2013)

[3] E.Hirose et al., Applied Optics, 49 18 3474 (2010)

Noise hunting (identification)

Continuous effort to identify sources and reduce noise



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Observation plans

■ **O1 (nominally Sep.- Dec. 2015)**

3 months

40 - 80 Mpc range

■ **O2 (2016 - 2017 ?)**

6 months

80 - 120 Mpc range

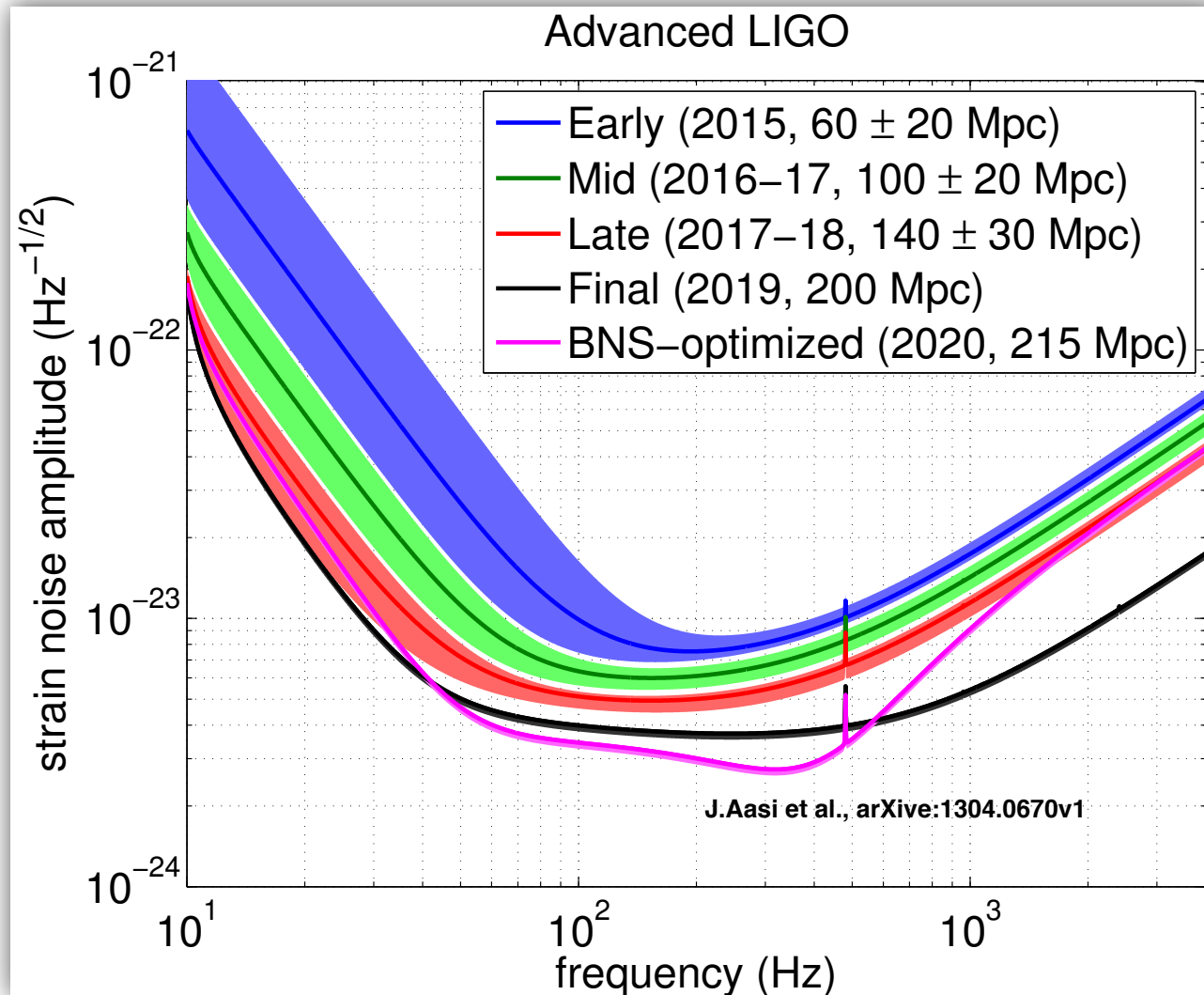
■ **O3 (2017 - 2018 ?)**

9 months

110 - 170 Mpc range

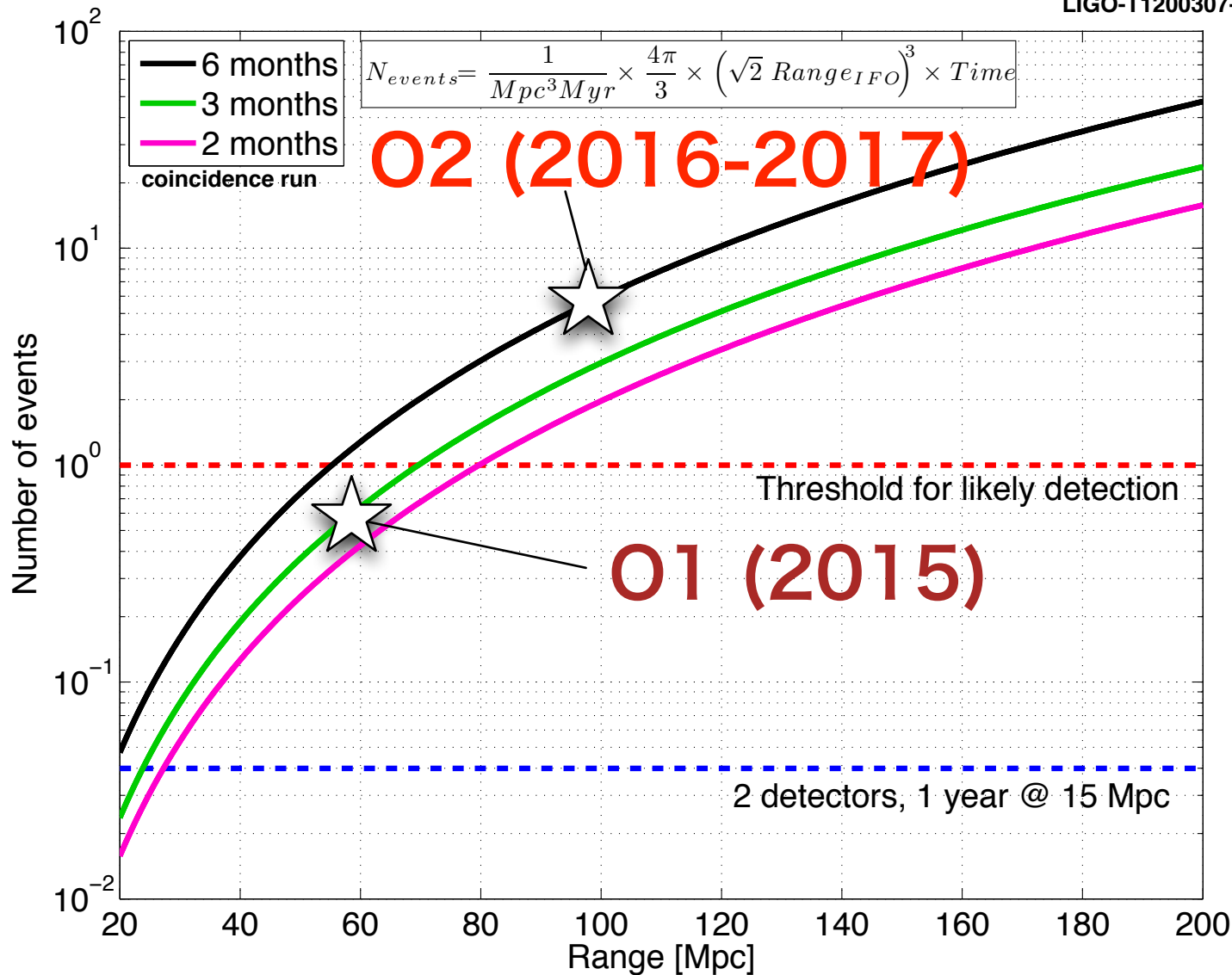
* Strongly depend on how the commissioning activities go

Example Noise Progression



Detection Rate

plot from L.Barsotti and P.Fritschel,
LIGO-T1200307-v4



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Conclusions

- Installation completed at both observatories
- Both observatories achieved full lock and demonstrated stable operation
- Currently in a low power state to improve noise and duty-cycle
- The planned 1st observation run starts Sep. 2015 with 40-80 Mpc sensitivity.