# The road to Advanced LIGO's first observations

Photo: Michael Fyr



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G1400823

## Outline

- Observing transient GW signals with Advanced LIGO
  - The Advanced LIGO interferometers
  - Projected commissioning timeline
  - Likely observing scenarios
- Detector characterization efforts
  - Past strategies, challenges, and successes
  - First glimpse of Livingston data quality

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## **Advanced LIGO**



## **Advanced LIGO**



## Likely aLIGO observing scenarios



Aasi, et al. 2013 arxiv 1304.0670

## How will we get there?

## aLIGO instrumental improvements



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### LIGO Hanford observatory Each LIGO ifo has 4km arms











## Full interferometer!



ALS

ETMY

## Timeline: from eLIGO to aLIGO



## Timeline: from eLIGO to aLIGO



## Timeline: installation and testing



### Timeline: the lead up to the first observing run



## aLIGO project acceptance requires:

Subsystems meet their acceptance criteria Design and use documentation produced - Meet individual performance requirements Each interferometer locks for an extended time (2 hours) <---- Livingston has achieved this - Locking: acquire and maintain interferometer resonance under automated control

## **Commissioning at Livingston**

![](_page_20_Figure_1.jpeg)

Improving sensitivity

Increased laser power Noise hunting

- Transition to DC readout
- Improved optic alignment and angular

stability

## Prior commissioning progression

![](_page_21_Figure_1.jpeg)

![](_page_22_Figure_0.jpeg)

## The challenges of commissioning

- Many effects cannot be tested prior to large scale implementation
- Often noise sources stem from the interaction of different subsystems and cavities

![](_page_23_Figure_3.jpeg)

## Planning observing runs

## Number of detections = Rate x Volume x Time

![](_page_24_Figure_2.jpeg)

Epoch	Estimated Run Duration	$E_{\rm GW} = 10^{-2} M_{\odot} c^2$ Burst Range (Mpc)		BNS Range (Mpc)		Number of BNS	% BNS Localized within	
		LIGO	Virgo	LIGO	Virgo	Detections	$5  \mathrm{deg}^2$	$20  \mathrm{deg}^2$
2015	3 months	40 - 60	-	40 - 80	-	0.0004 - 3	-	-
2016-17	6 months	60 - 75	20 - 40	80 - 120	20 - 60	0.006 - 20	2	5 - 12
2017-18	9 months	75 - 90	40 - 50	120 - 170	60 - 85	0.04 - 100	1 - 2	10 - 12
2019 +	(per year)	105	40 - 80	200	65 - 130	0.2 - 200	3 - 8	8 - 28
2022+ (India)	(per year)	105	80	200	130	0.4 - 400	17	48

## Planning observing runs

![](_page_25_Figure_1.jpeg)

![](_page_25_Figure_2.jpeg)

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# Outline

- Detector characterization efforts
  - Past strategies, challenges, and successes
  - New approach to characterizing complex instrumentation
  - First glimpse of Livingston data quality

# GW search pipelines are adversely affected by non-Gaussian data!

Long tails (outliers) in all-sky GW burst search background triggers greatly restrict achievable false alarm rate. Non-Gaussian noise confuses parameter estimation for all transient searches.

![](_page_27_Figure_2.jpeg)

## Example: NINJA2 search results

![](_page_28_Figure_1.jpeg)

A normalized spectrogram of Hanford recolored noise only showing a transient event, or glitch, that happens to occur at the time of the injection. Solid blue – the 95% credible region for mass estimation based on EOBNRv2 analysis using recolored noise. Dashed pink – in Gaussian noise.

## How glitchy were data in past runs?

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#### A 'good' day in S6

![](_page_29_Figure_2.jpeg)

#### A 'bad' day in S6

![](_page_29_Figure_4.jpeg)

![](_page_29_Figure_5.jpeg)

![](_page_29_Figure_6.jpeg)

# What kinds of glitches affect the transient GW searches?

The **burst** search, requiring coherence and time coincidence between ifos, is more affected by very frequent glitches

### Example: 'Grid' Glitches

![](_page_30_Figure_3.jpeg)

# What kinds of glitches affect the transient GW searches?

The **CBC** search is more affected by very loud glitches, which will convolve with many waveform templates in the template bank and pollute large chunks of data

## Example: 'Spike' Glitches

![](_page_31_Figure_3.jpeg)

## First Glimpse Advanced LIGO Livingston DQ

## Livingston full interferometer glitching

Calibrated DARM (differential arm length) glitch rate comparison

### September 2010 (S6)

#### August 2014

![](_page_33_Figure_4.jpeg)

## An early DQ issue diagnosis

Calibrated DARM - 1 hour on August 9th 2014

![](_page_34_Figure_2.jpeg)

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## An early DQ issue diagnosis

![](_page_35_Figure_1.jpeg)

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### Through the lens of a single ifo burst GW pipeline

#### Calibrated DARM (differential arm length)

![](_page_36_Figure_2.jpeg)

8 hours on August 9<sup>th</sup> 2014

### The mechanism : major carry transition DAC glitching

![](_page_37_Figure_1.jpeg)

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### The mechanism : major carry transition DAC glitching

![](_page_38_Figure_1.jpeg)

First dubbed "zero crossing" glitches – identified when vertex cavity actuation signals crossed zero.

Actually a subset of a broader known issue with these DACs.

### The mechanism : major carry transition DAC glitching

![](_page_39_Figure_1.jpeg)

**Major-carry** transitions: single-code transitions that cause a most significant bit (to change because of the lower bits transitioning. **Examples:** 

![](_page_39_Figure_3.jpeg)

### Offset applied to vertex cavity actuation

![](_page_40_Figure_1.jpeg)

### Offset applied to vertex cavity actuation

![](_page_41_Figure_1.jpeg)

### End station actuator glitches identified

The Detector Characterization group also identified this behavior in one of the end stations at the 2^16 MCT accounting for ~80% of loud glitches remaining after offset applied to vertex cavity actuators

![](_page_42_Figure_2.jpeg)

Fs=16,384Hz, sec/fft = 1.00, overlap = 0.40, fft length=16,384, #-FFT = 199, bw = 1, in samples = 1,966K, low = 0.20

## Conclusions

- With less than a year to go, making good progress toward commissioning and data analysis goals
  - Commissioning following a rapid timeline, advances in sensitivity expected and well understood
  - Detector characterization investment in instrumental expertise already fruitful in preparing to improve data quality for GW searches in O1
- All indications are that we will be ready!