LIGO-G1400785-v1

#### Notes on DRMI locking at LLO

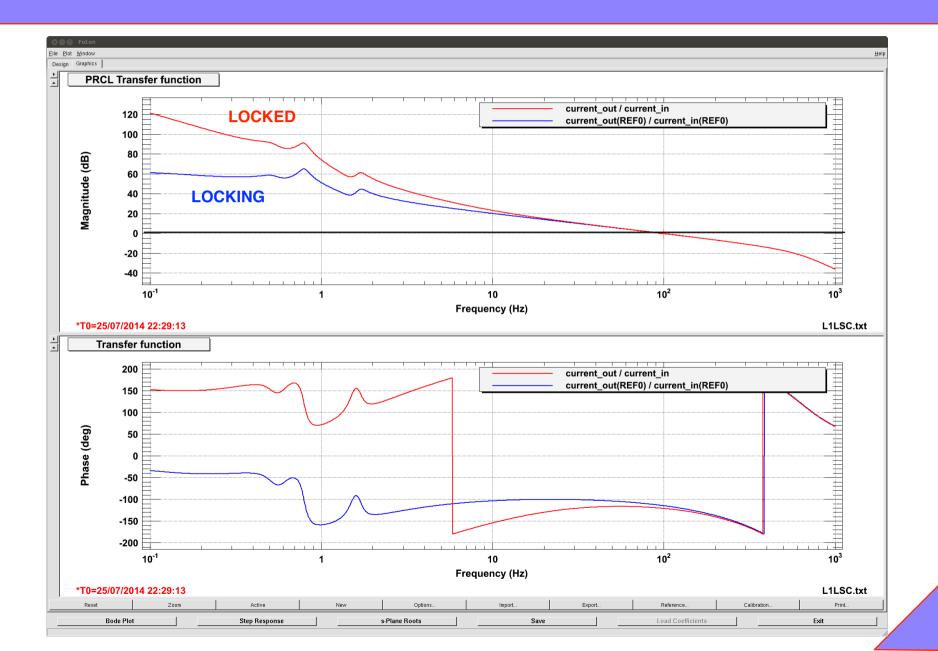
K.Izumi 2014.July.20

# LSC settings Overview

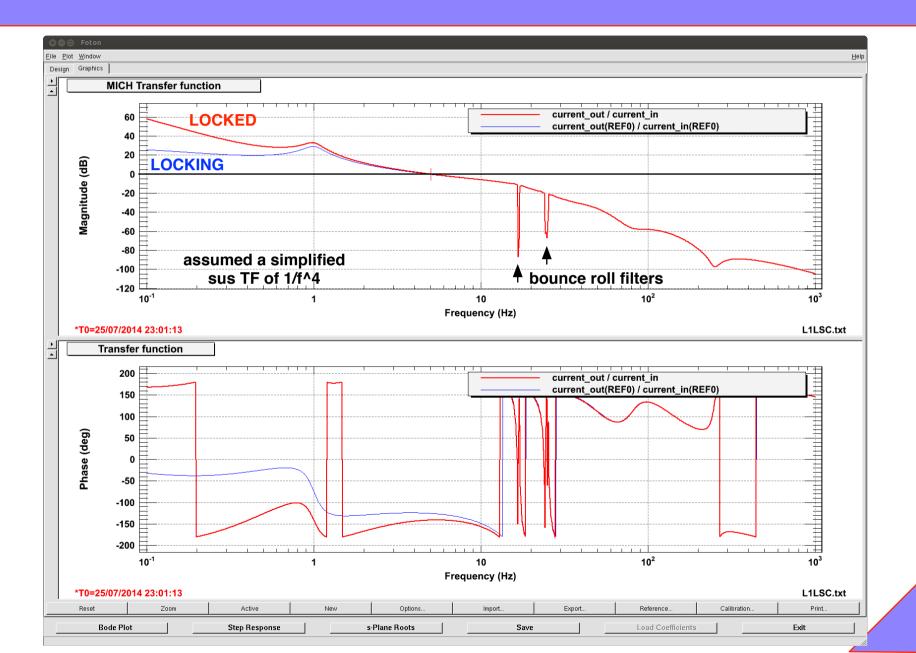
- Guardian-based (a part of the full lock sequence)
- No separate DRMI guardian (AM is working on)
- Several realtime triggers
- Non-diagonalized output matrix (AE is working on)

```
    REFL9I -> PRCL (UGF = 100Hz)
    REFL45Q -> MICH (UGF = 5Hz)
    REFL45I + REFL9I -> SRCL (UGF = 50Hz)
```

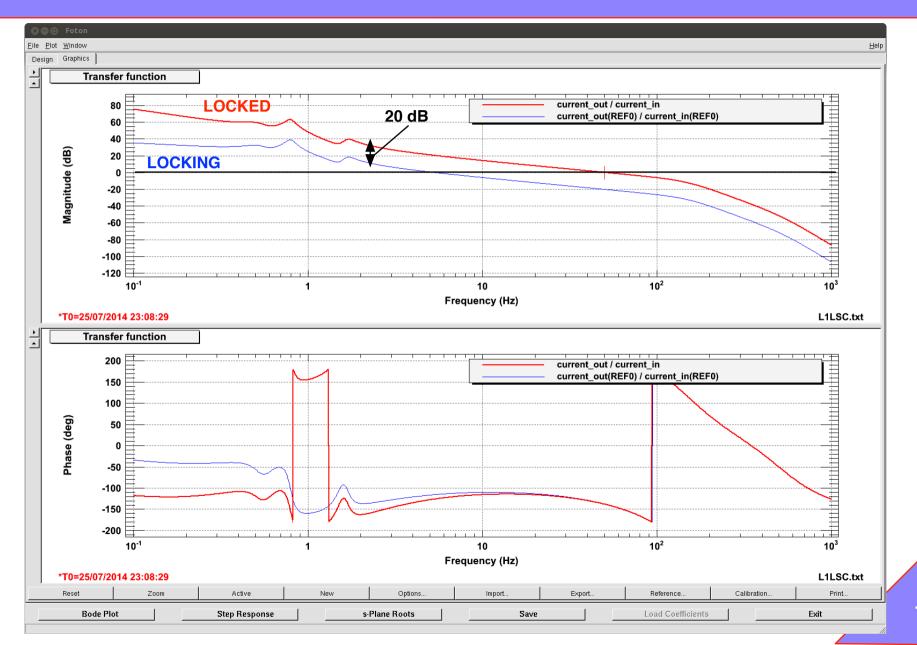
## **PRCL open loop**



## MICH open loop

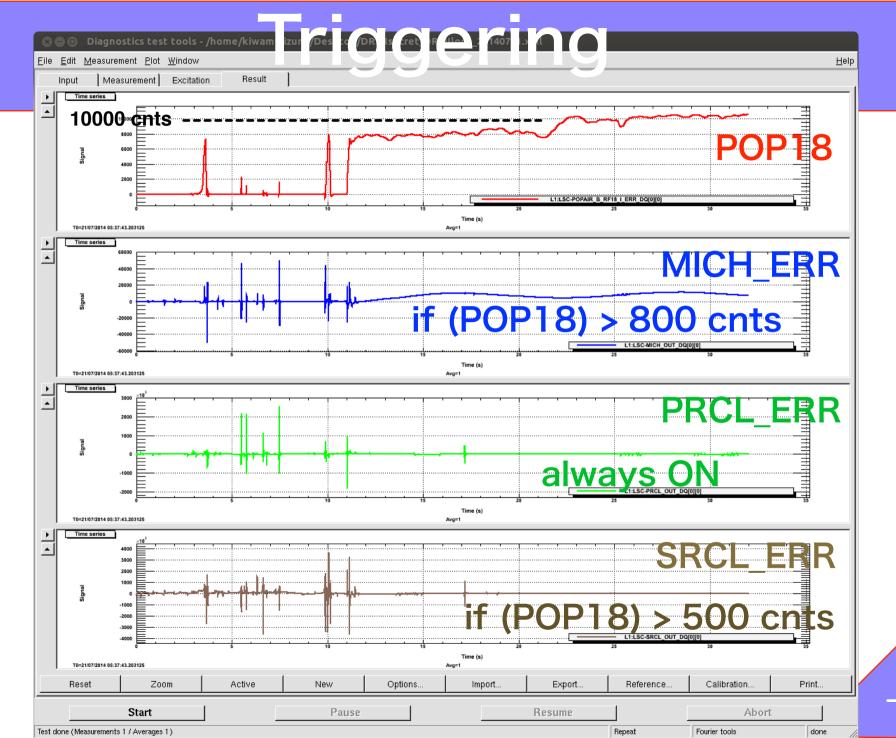


## SRCL open loop



#### **OUTPUT** matrix

SO LSC_CUST_OUT_MTRX.adl											
L1	LSC OUTPUT MATRIX							Mon (	Jul 21 (	)1:03:54 20	
DARM	MICH	PRCL	SRCL	CARM	XARM	YARM	OSC1	OSC2	OSC3		
1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	🕨 ЕТМХ	
<mark>⊢1.</mark> 00	0,000	0.000	0. 0001	0.000	0. 000	0.000	0. 000	0.000	0. 000	🕨 ЕТМУ	
0.000	0, 000	0. 000	0.000	0.000	0, 0001	0, 000	0, 493)	0.000	0.000	TU IL IL	
0.000	0.000	0.000	0.000	0.000	0.000	0. 0001	<mark>⊢0,</mark> 50(	0.000	0.000	TTMA	
0.000	0.000	1.000	0.000	0,000	0.000	0.000	0,000	0, 0001	0.000	PRM (hierar	chical)
0.000	0.000	0.000	1.000	0.000	0. 0001	0. 000	0. 000	0.000	0.000	SRM (hierar	chical)
0.000	1.000	0.000	0.000	0. 000	0. 0001	0.000	0.000	0.000	0. 000	🕨 BS (middle	stage)
0.000	0, 000	1.000	0.000	0.000	0, 0001	0, 0001	0, 0001	0,500	0, 000	PR2(bottom	stage)
0.000	0.000	0.000	1.000	0.000	0. 0001	0.000	0.000	0.000	0.500	SR2 (bottom	stage)
0.000	0.000	0, 0001	0.000	1.000	0.000	1.000	0.000	0.000	0,000	MC2	<u>6</u> 16



# Length actuation on SUS

- Guardian-based triggering for the hierarchical longitudinal control
- PRM M2 stage turns on when DRMI is locked
- SRM M2 stage turns on when DRMI is locked
- L2P(Y) and P(Y)2L filters are not used although once they have tried.
   crossover frequencies ?

#### **ASC** overview

Crucial for locking and long term lock

Initial alignment is critical for locking

Misalignment easily elongates the locking down time from 10 sec to several minutes.

- WFS are used for in-lock control
- Multiple-steps for initial alignment

## **ASC Loops**

 3 main loops
 4 auxiliary DC WFS centering, actuating on RM1/RM2/OM1/OM2
 BS oplev is tuend off when ASC is engaged

\* in locking sequence
\* in full lock
REFL9 -> PRM + PR2
AS36 -> BS
REFL45 -> SRM
\* in full lock
REFL45 -> SRM

control bandwidth ~ below 1 Hz

## **Initial Alignment**

Initial alignment is broken into three steps
 REFL and AS WFSs are used

(0) Assume that PR2/IM4 input pointing to X arm and ITMs' angle are already good (1) Lock PRX to determine PRM angle (REFL WFS) (2) Lock MICH to determine BS angle (AS\_WFS, currently not functional) (3) Lock SRY to determine SRM angle (REFL WFS)

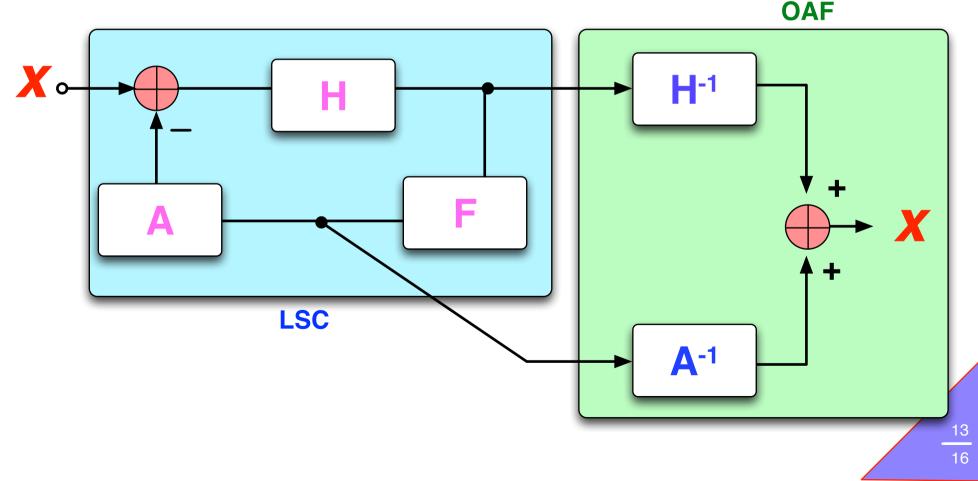
This usually gives a smooth DRMI lock (~10sec)

#### Seismic



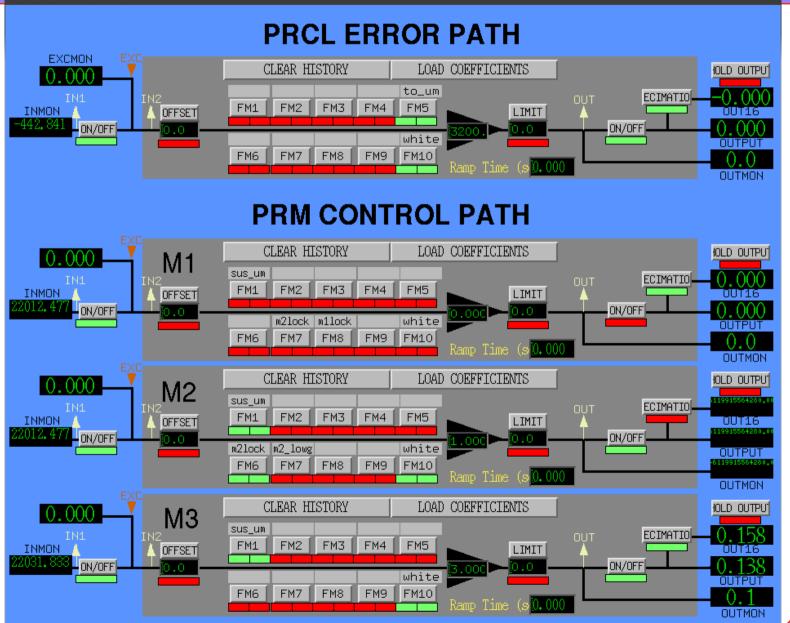
## Calibration

 Online calibration to obtain open-loop equivalent noise (i.e. unsuppressed) in displacement
 Model runs in L1OAF



#### **Calibration screen**

#### SO OAF\_CAL\_PRCL.adl



#### Misc.

- Some noise budget code in SVN...
- Modulation depths ?
- Power on 3f BBPD ?

## **Some considerations**

Decoupling of MICH actuator ? a combination of PR2, SR2 and BS seems easier than using PRM, PR2, SRM, SR2 and BS. What do we want ?

How do we measure the SRC length ?

PR3, SR2 and SR3 angles were left untouched.

Don't we want to control them in the initial

alignment ?

Is the chosen ASC loops optimum ? Is there a better solution ?