

Advanced LIGO

and the bright future of
Gravitational Wave Observation

Sunrise on Kerala's backwaters

Lisa Barsotti (LIGO-MIT)
on behalf of the
LIGO Scientific Collaboration

LIGO - G1301287

Upcoming Network in the Advanced Detector Era



LIGO Hanford Observatory (WA)

H1 – in the desert



LIGO Livingston Observatory (LA)

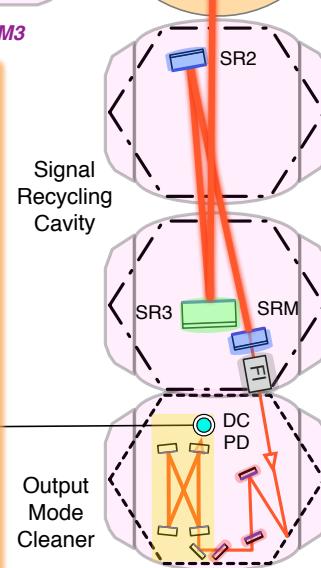
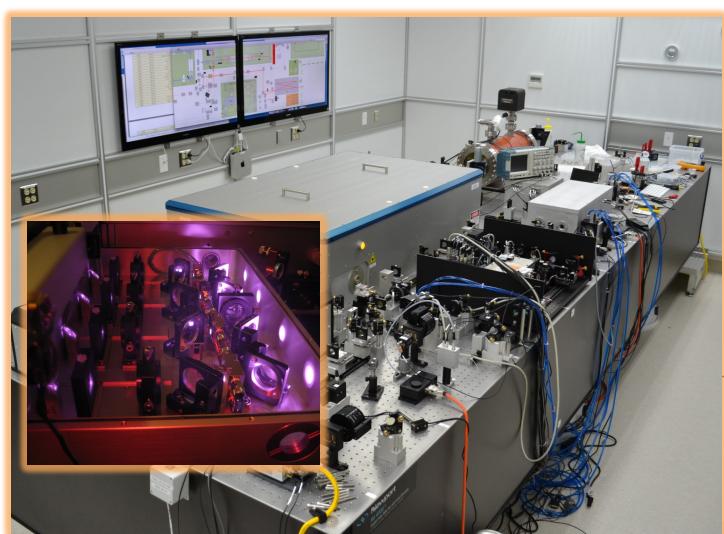
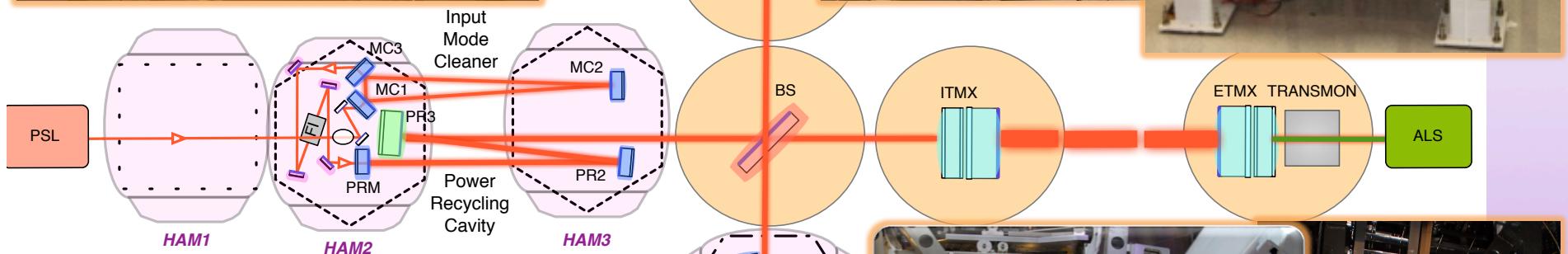
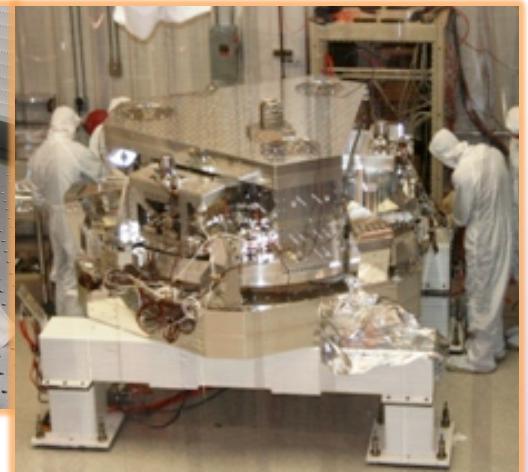
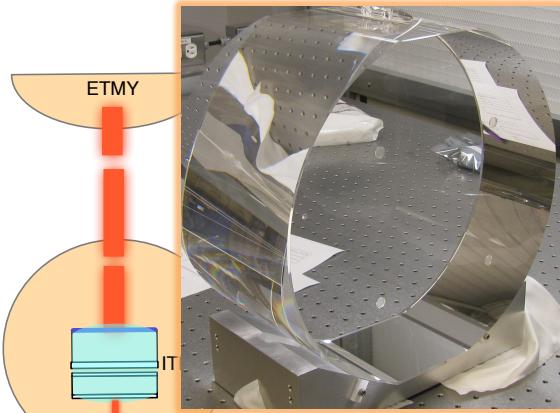
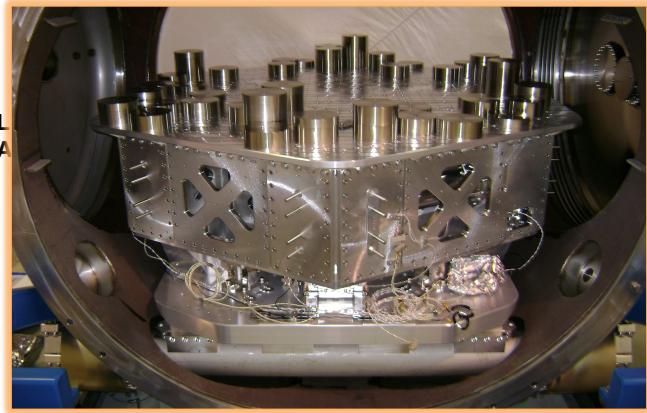
L1 – in the jungle



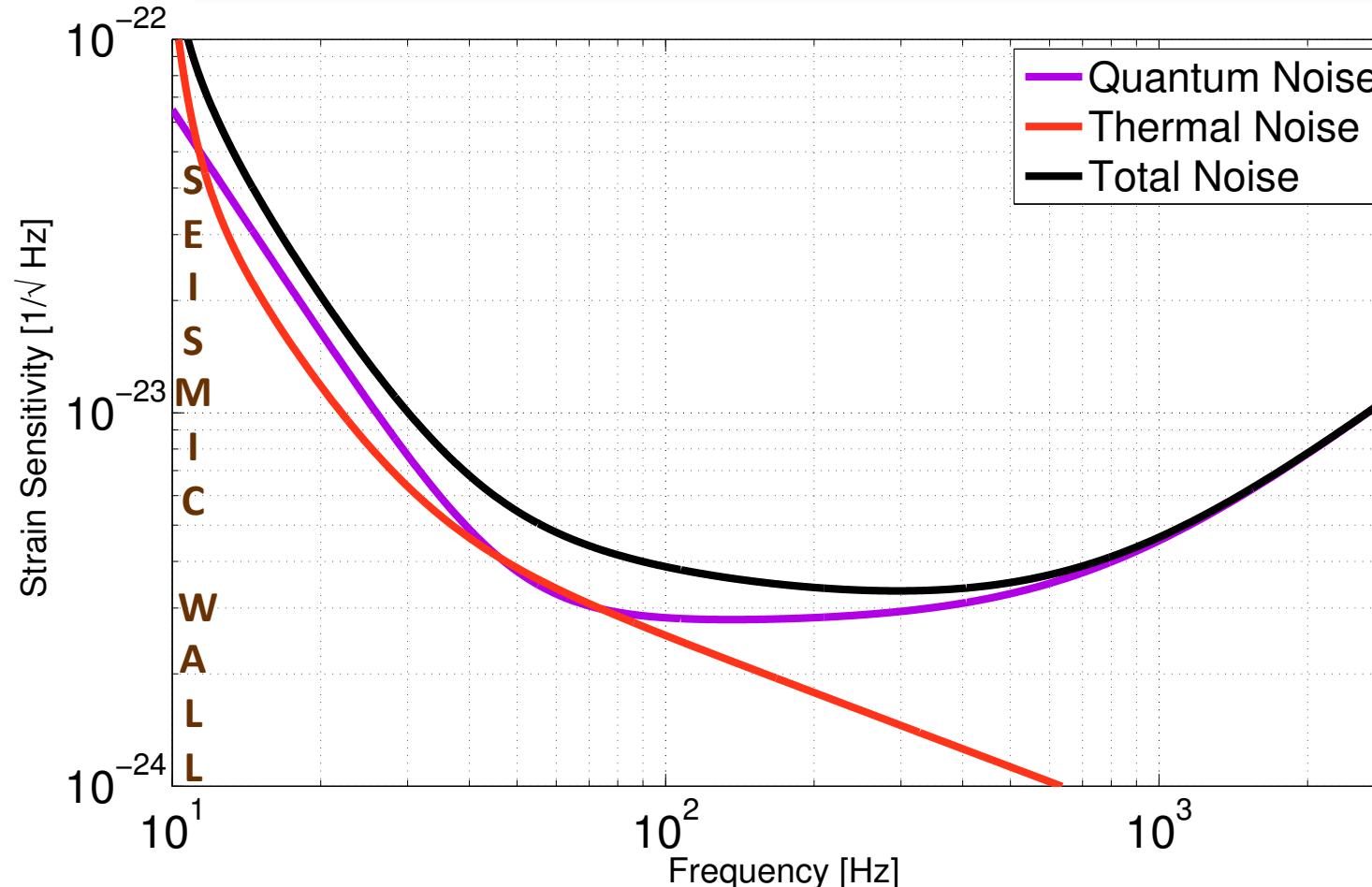
- ✓ 36 hours drive
- ✓ 10 ms if traveling at the speed of light



Advanced LIGO: L1 & H1



Advanced LIGO Design Sensitivity..

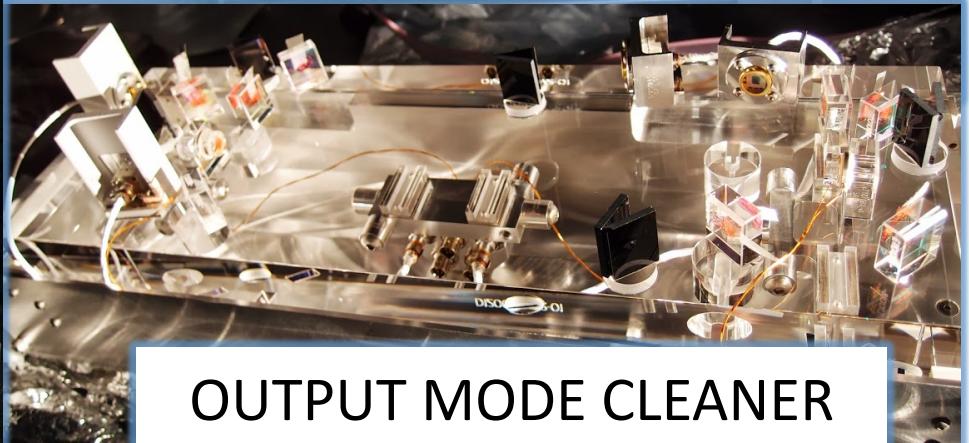
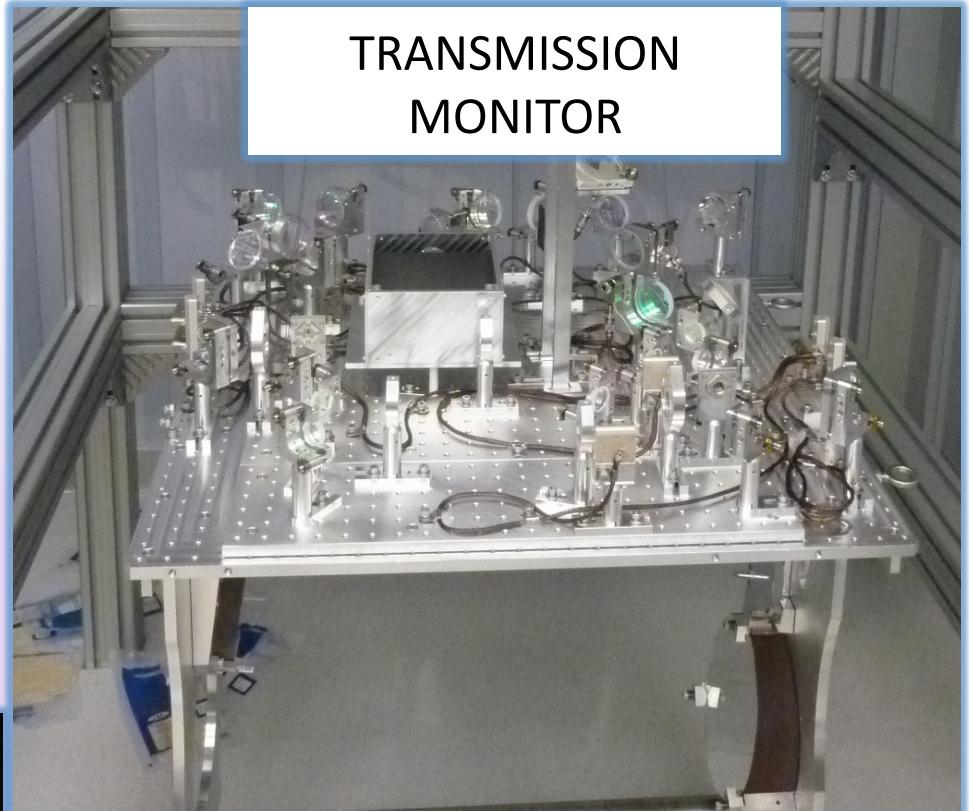
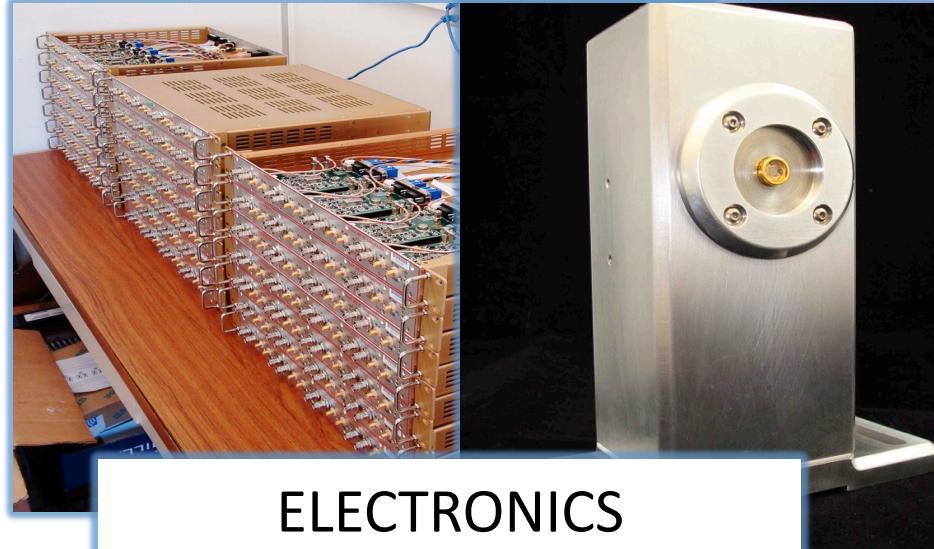


..but what about technical noises? How about data quality?
And, by the way...how do we get to the design sensitivity?

“EVERYTHING is better in Advanced LIGO!”

Incorporated lessons learned
from initial detectors to:

- ✓ reduce impact of technical noises
- ✓ reduce causes of glitches
- ✓ reduce commissioning time





Advanced LIGO Status



Installation and integration inspiring “principles”:

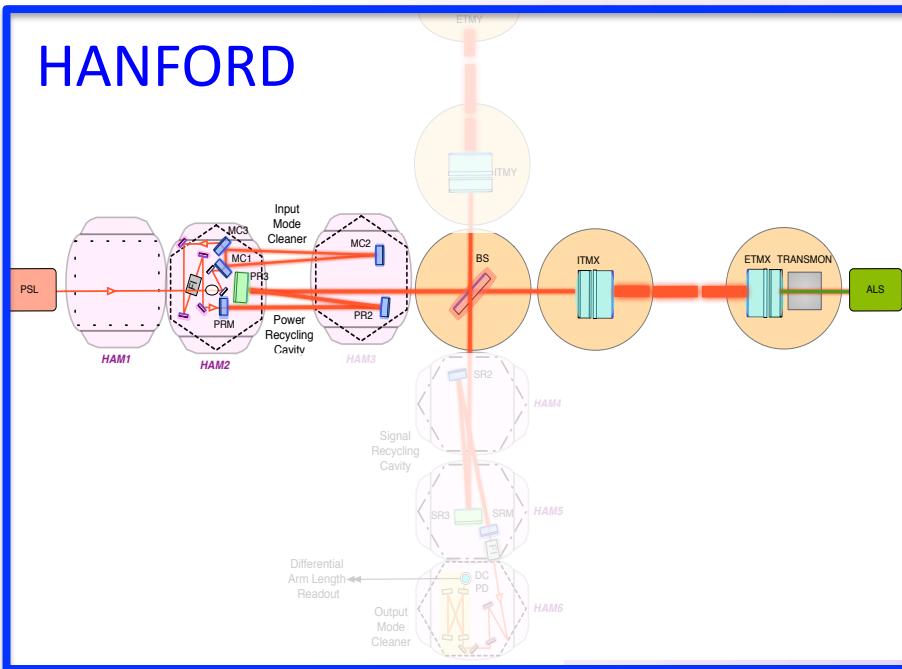
- ✧ Parallel effort between Hanford and Livingston
- ✧ Installation of “new” things as soon as possible
- ✧ Test configurations of increased complexity



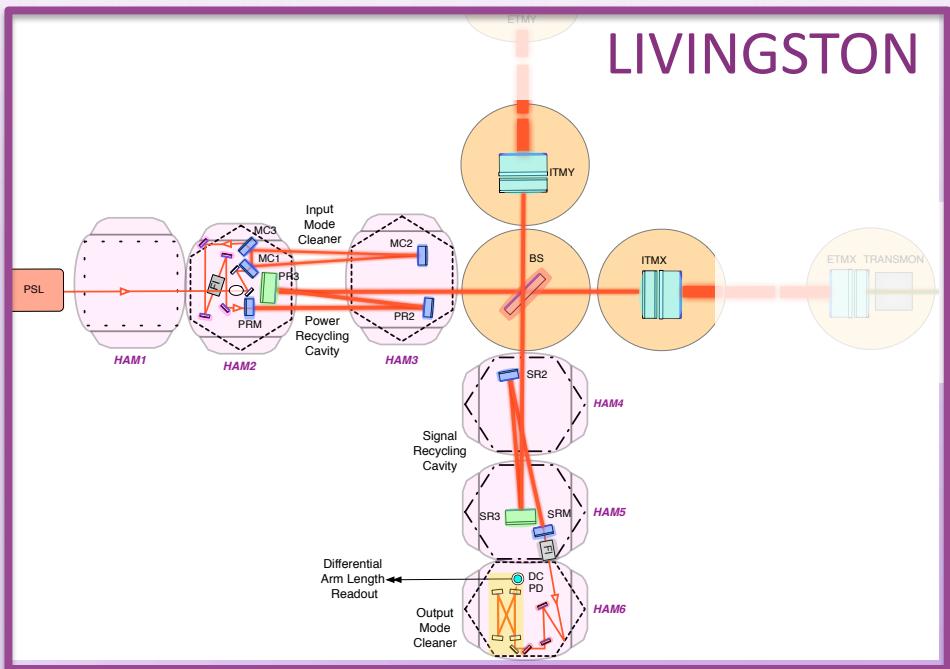
Advanced LIGO Status



HANFORD



LIVINGSTON

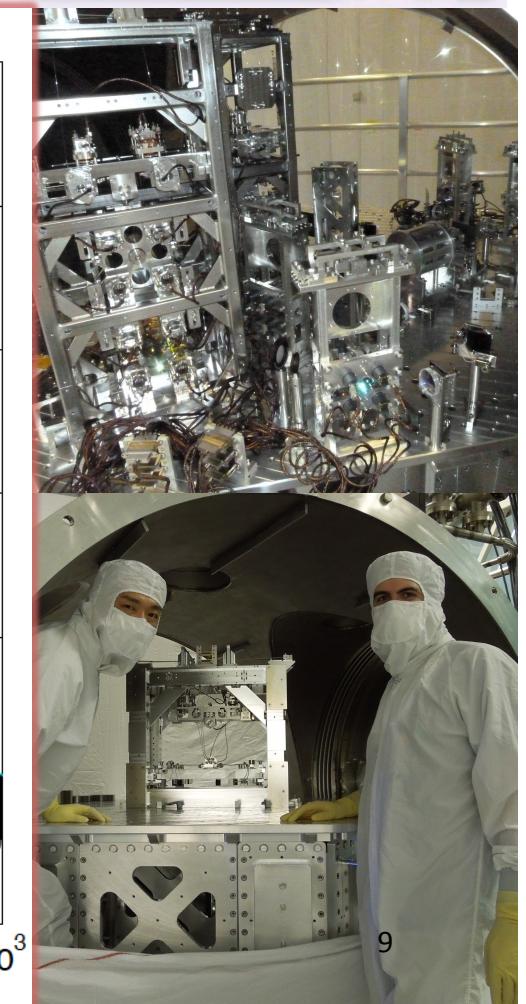
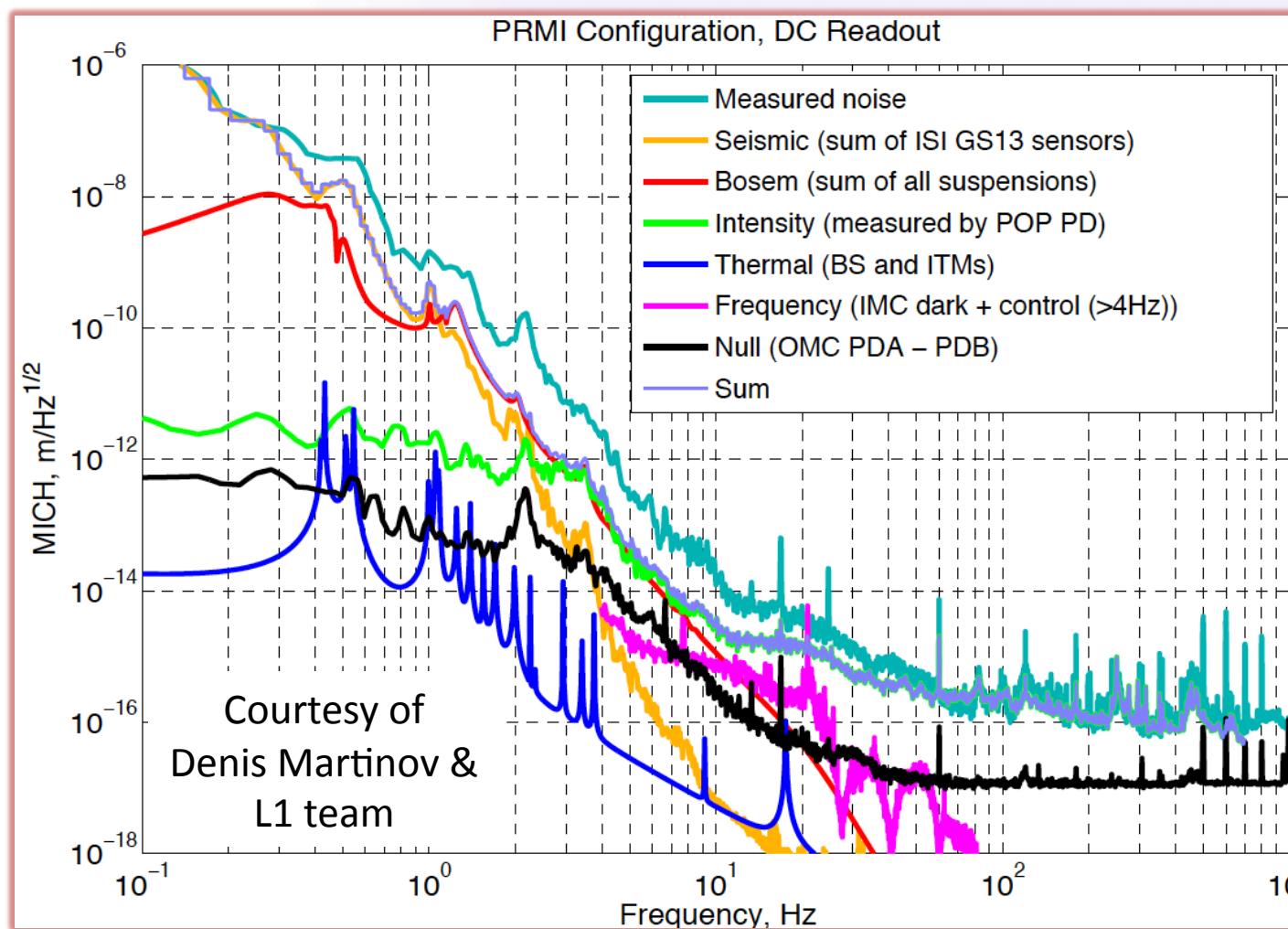


- ✓ Completed first tests on one arm
- ✓ Other arm + central interferometer under installation

- ✓ Completed first tests on central interferometer
- ✓ Both arms under installation

Advanced LIGO Status: LIVINGSTON

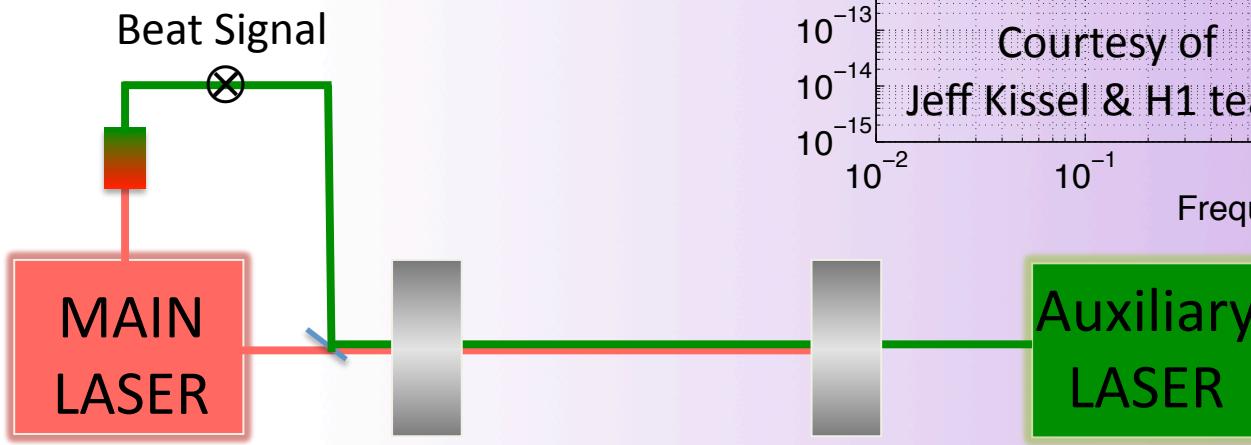
Noise Budget for the central part of the interferometer (no arms)



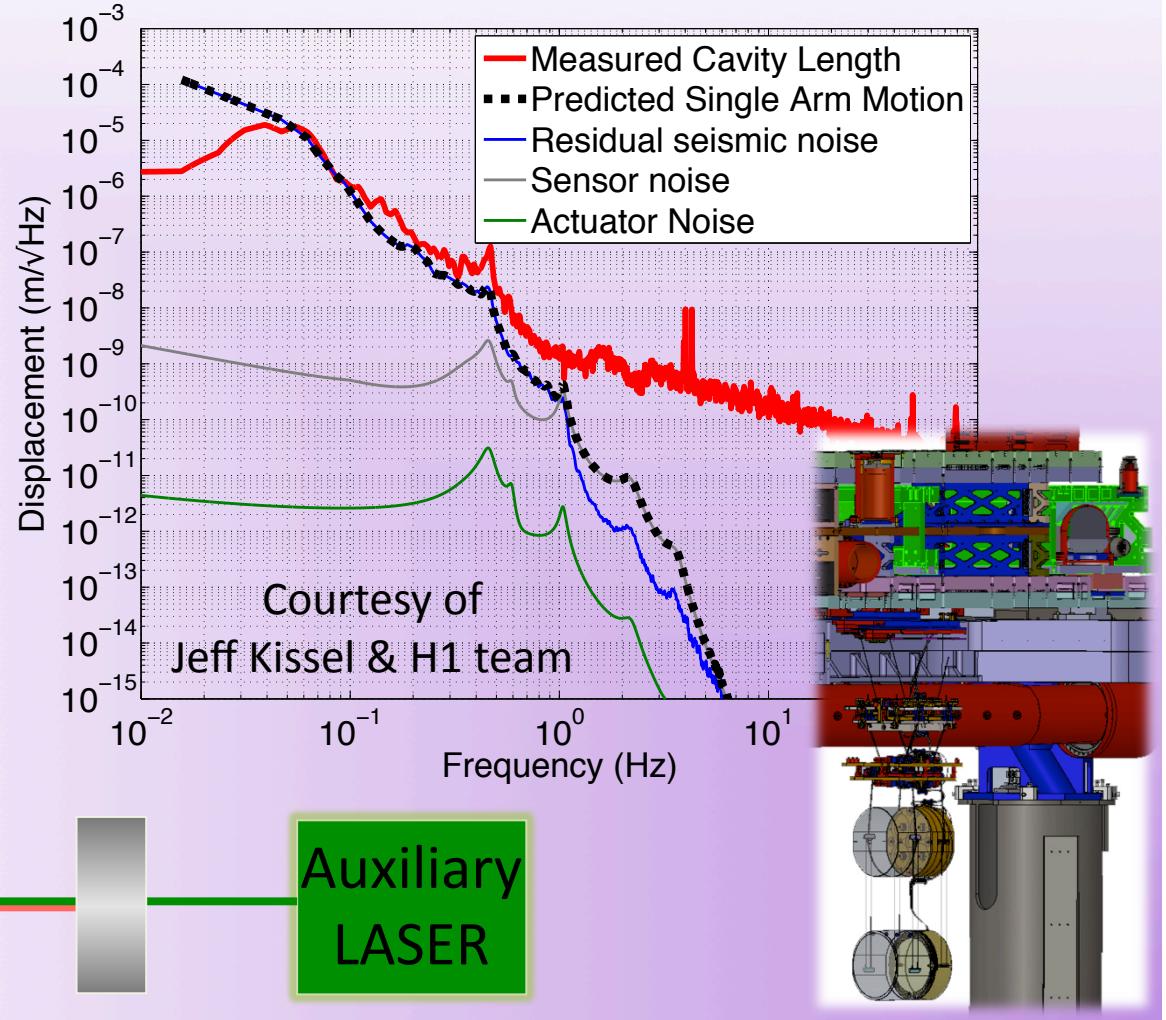


Advanced LIGO Status: HANFORD

- ✧ New “Arm Length Stabilization System” for lock acquisition tested for one arm, performing as expected



- ✧ First measurement of 4 km arm cavity motion with new seismic isolation



Advanced LIGO Timeline

2014

2015

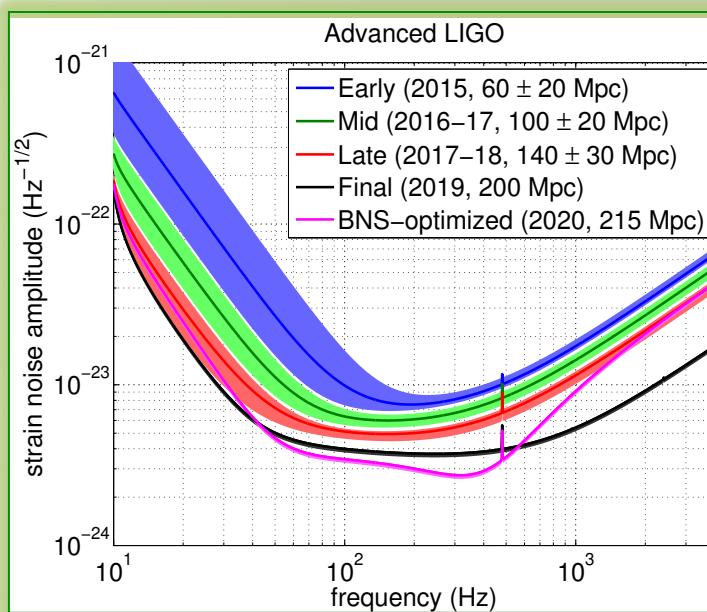
2016

2017

2018

2019

- both detectors “locked” on operating point
- “commissioning phase”: noise reduction



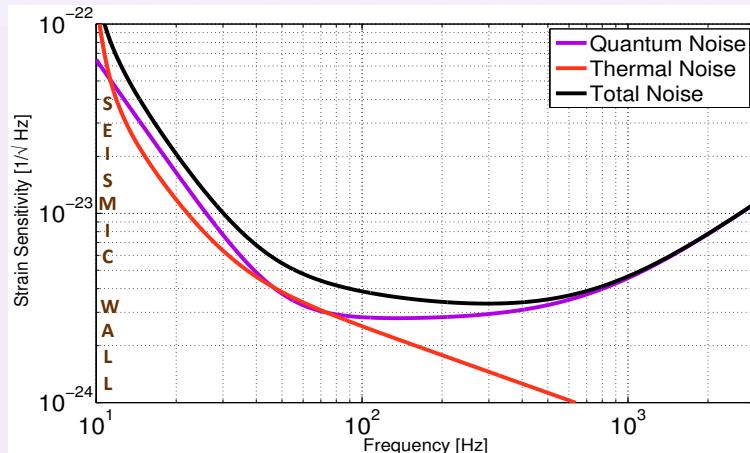
GW detection events

$$\propto (\text{obs time}) \times (\text{sensitivity})^3$$

→ Strategize between
“observing” and
sensitivity improvements

Potential complications

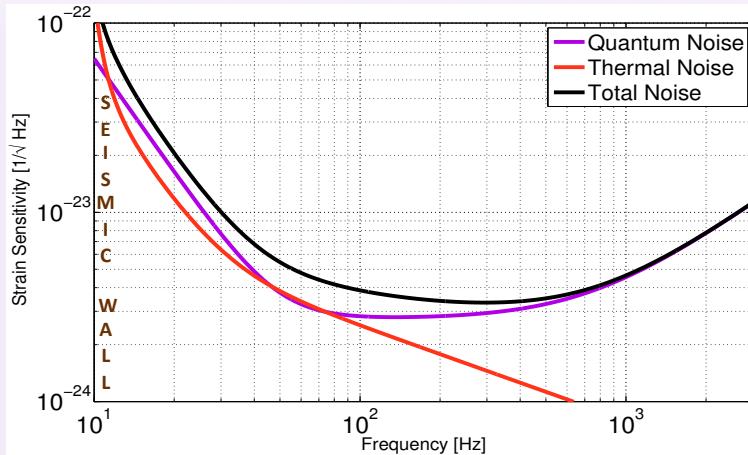
- ❖ **Required displacement noise levels not verified directly**
(for a good reason... essentially impossible to test in subscale setups!)



- ❖ **High power operations**
 - ✓ Up to 1 MW stored inside the arm cavity (absorption, thermal compensation, etc)
- ❖ **Increased complexity**
 - ✓ Number of control loops x10 larger than in initial LIGO
 - ✓ Mechanical systems have many more degrees-of-freedom
(Test Mass suspension has 48 DOF vs. 6 in initial LIGO)

Potential complications (according to me, today)

- ❖ **Required displacement noise levels not verified directly**
(for a good reason... essentially impossible to test in subscale setups!)



- ❖ **High power operations → Still true, but less scary than before**
 - ✓ Up to 1 MW stored inside the arm cavity (absorption, thermal compensation, etc)
- ❖ **Increased complexity → Acted on, a lot of work happening**
 - ✓ Number of control loops x10 larger than in initial LIGO
 - ✓ Mechanical systems have many more degrees-of-freedom
(Test Mass suspension has 48 DOF vs. 6 in initial LIGO)

Summary & Outlook

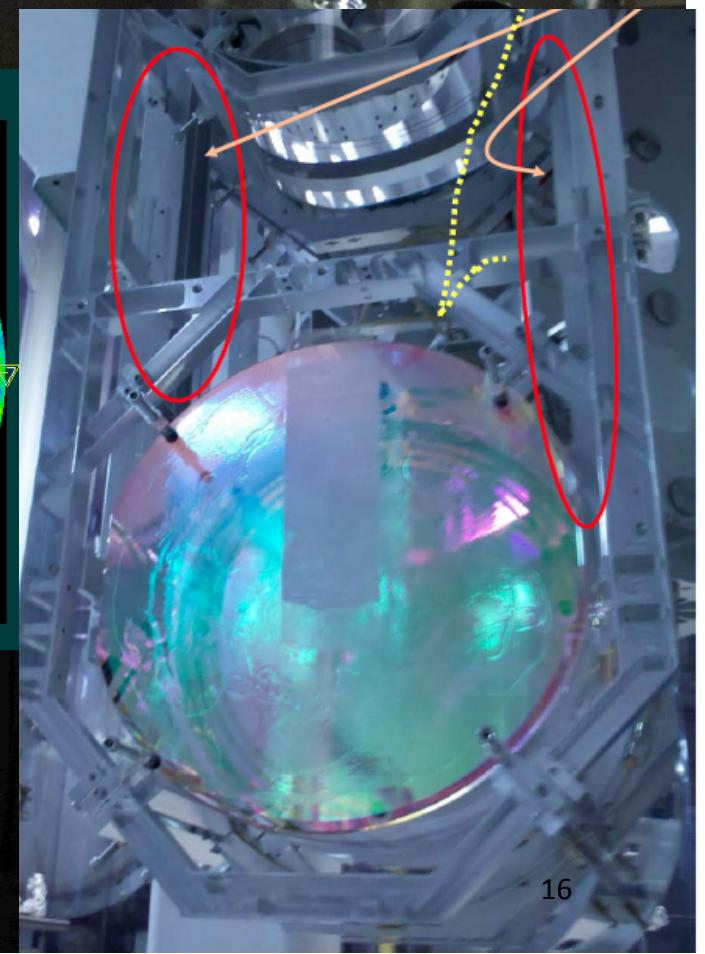
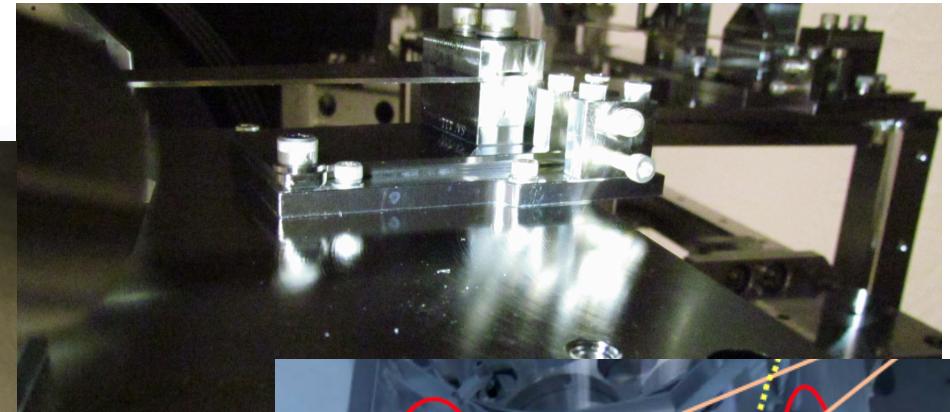
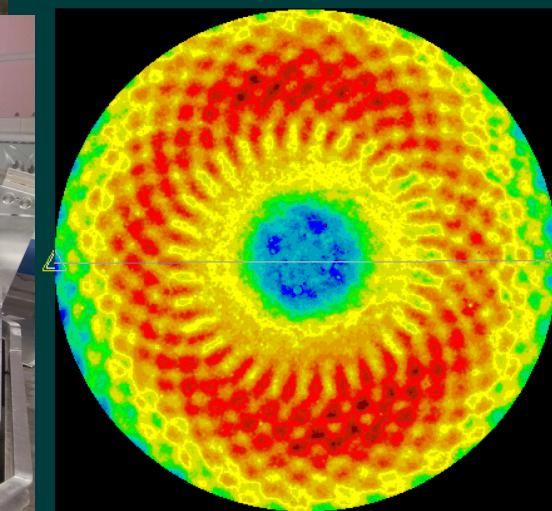
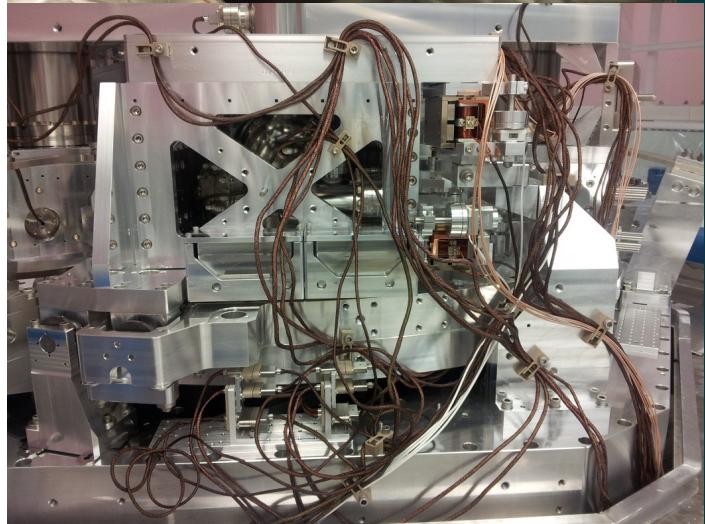
- ✧ H1 & L1 are being installed and tested, problems are found and fixed, so far no showstoppers
- ✧ Goal is to go as quickly as possible to two interferometers locked: on target for end of 2014 at both sites
- ✧ All the 2015+ projected curves that you see are “plausible”, they won’t be exactly like that
- ✧ Good data are coming, be ready! ☺

A photograph of a sunset over a beach. In the foreground, the dark silhouette of palm fronds is visible against the bright sky. The ocean is calm with gentle waves. The sky is filled with warm, golden-yellow clouds, and the sun is a small, bright red dot on the horizon.

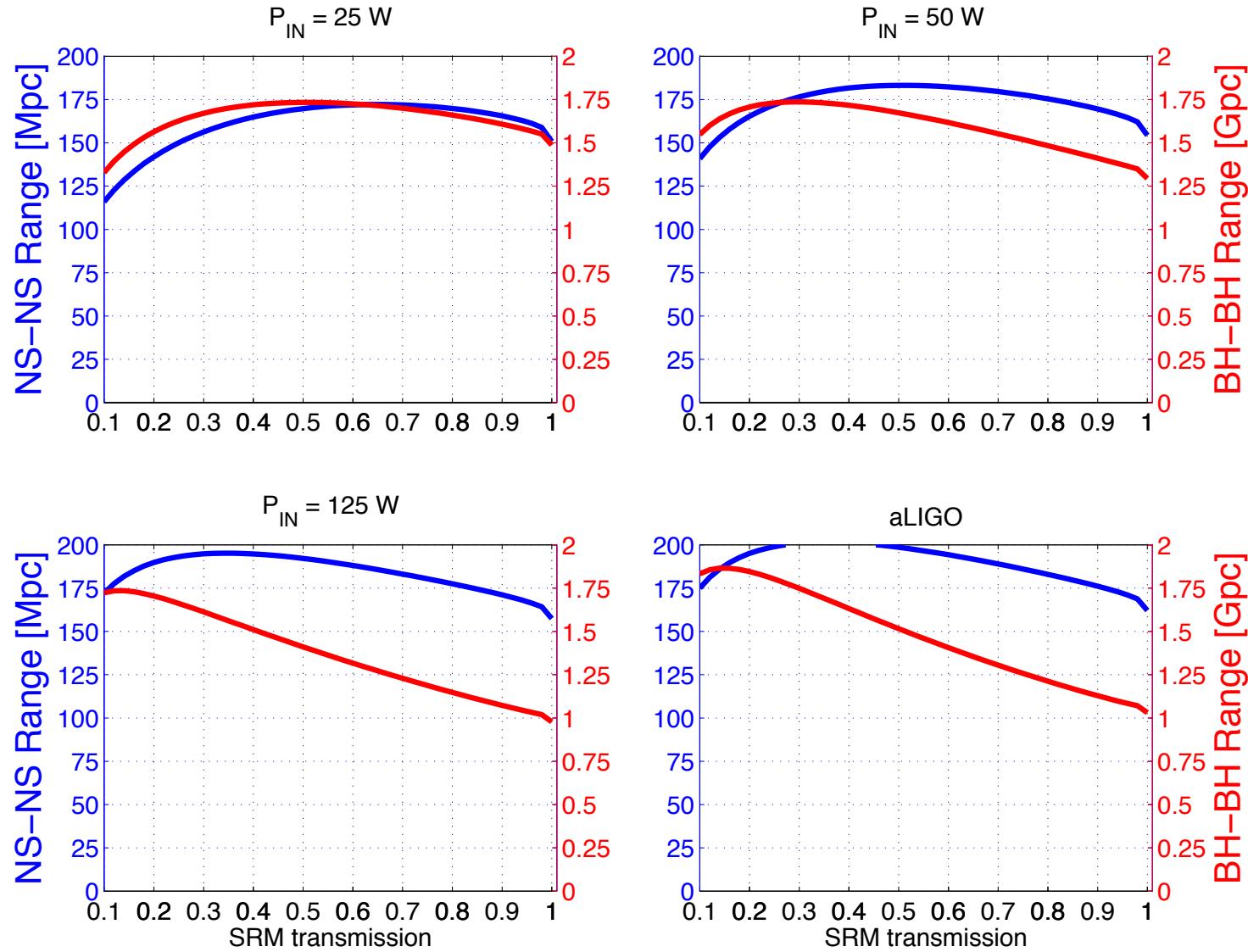
Thanks!

Sunset on Marari Beach

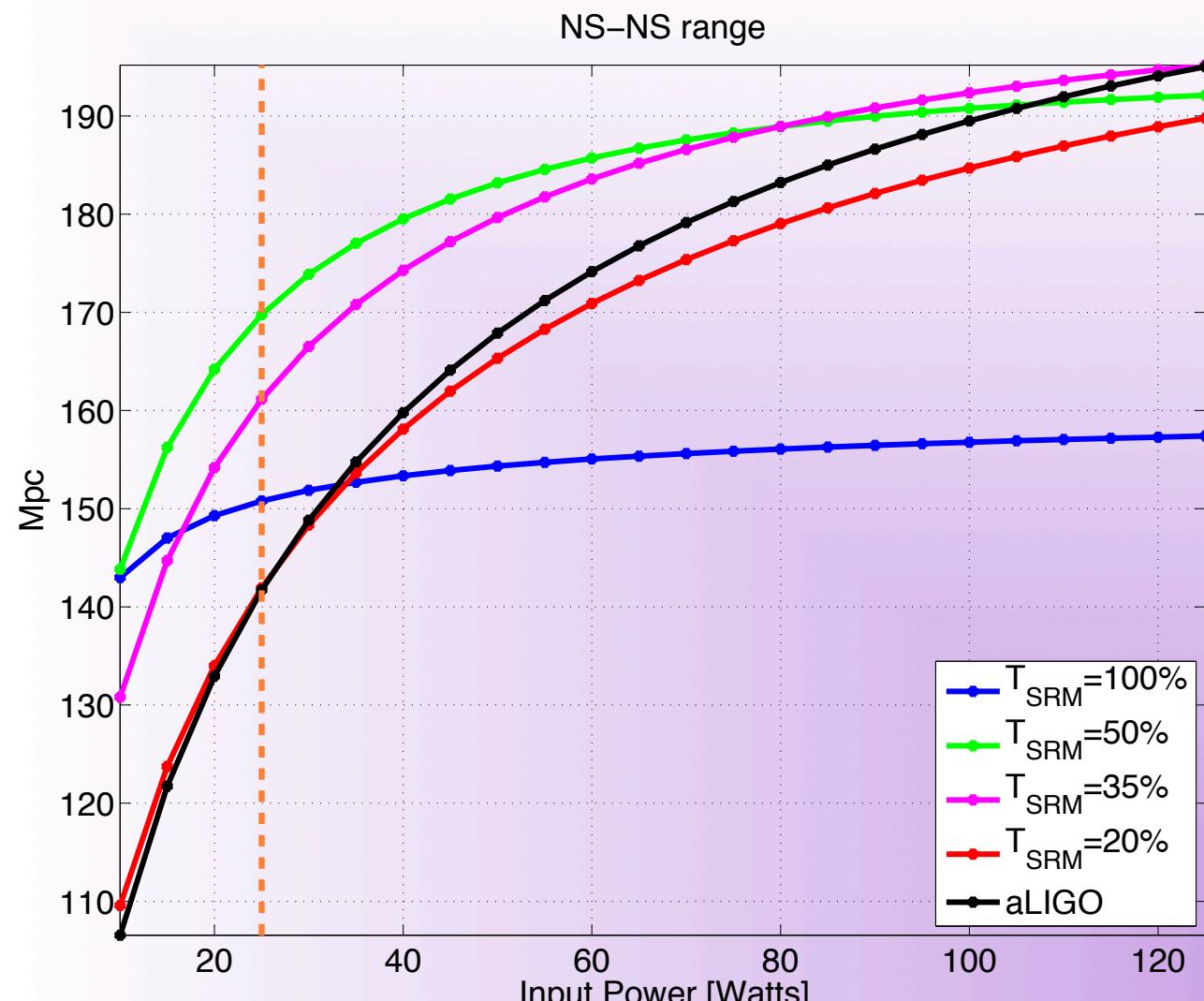
Several bumps in the road, no showstoppers so far
Pick your favorite “bump”!



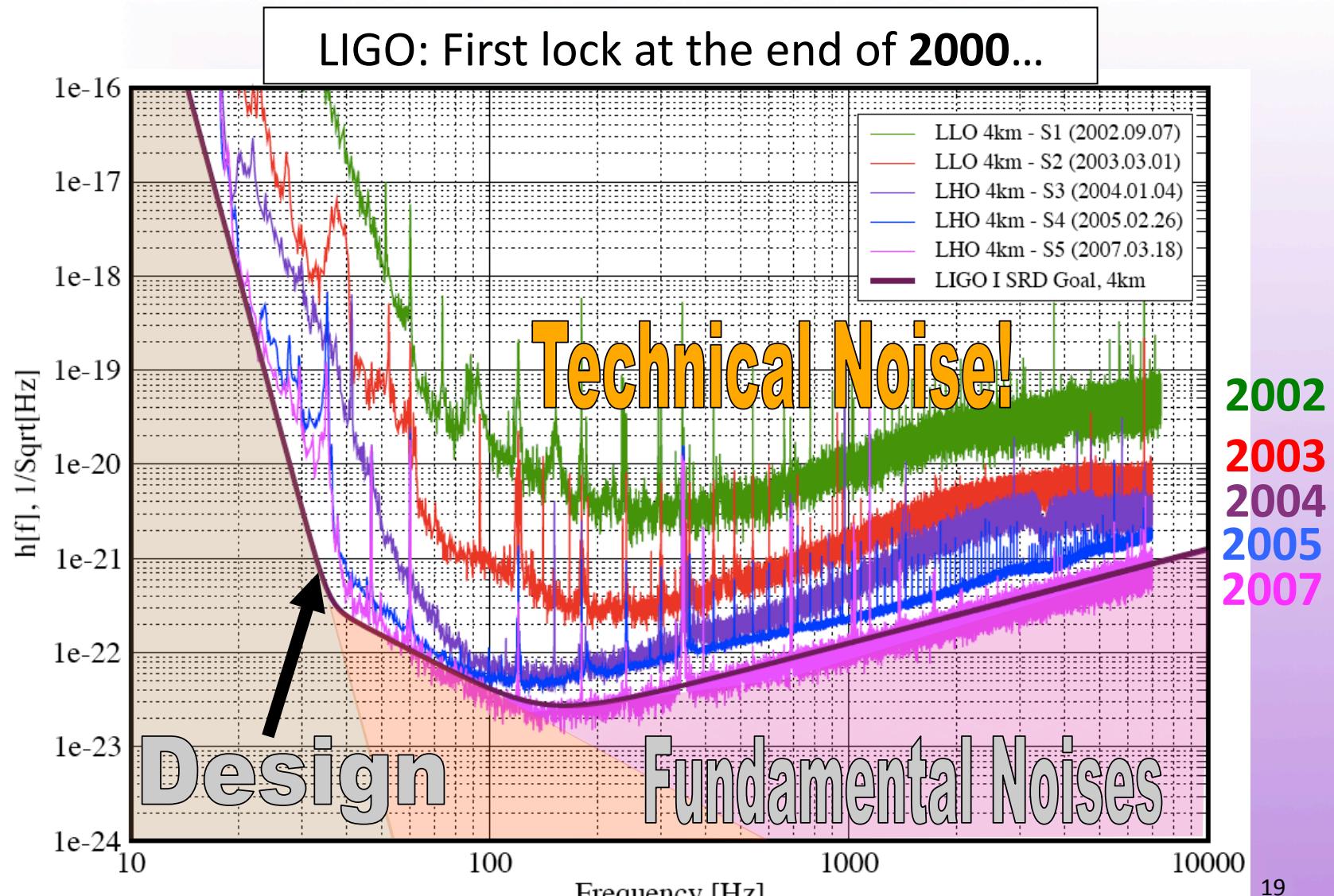
Optimization of SRM transmission



Optimization of SRM transmission

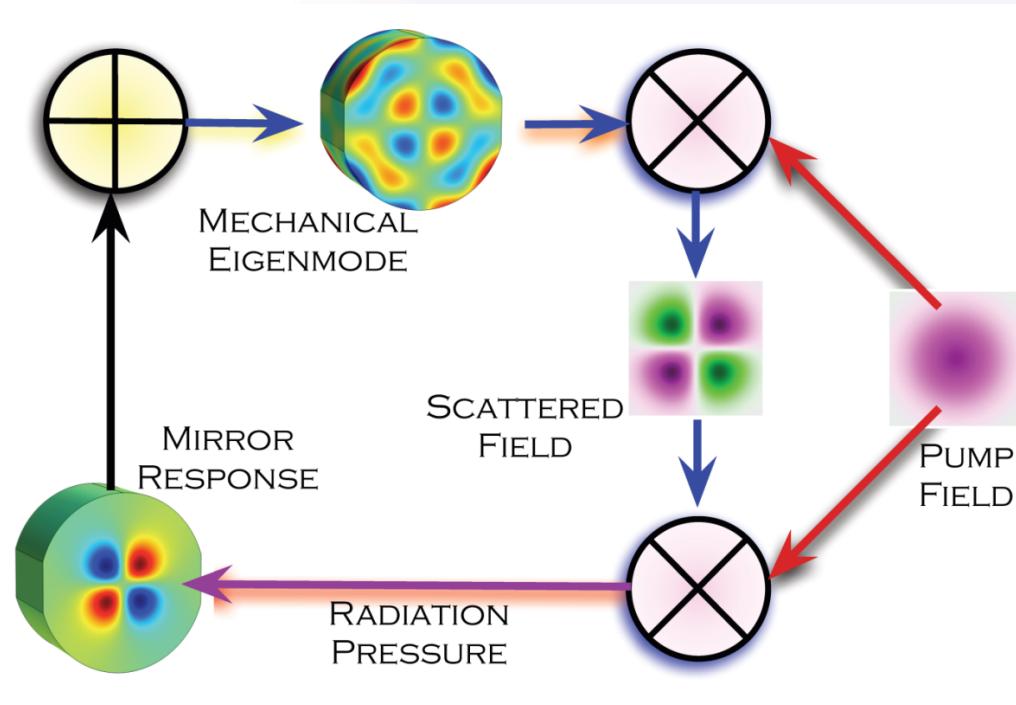


Initial LIGO Sensitivity improvement

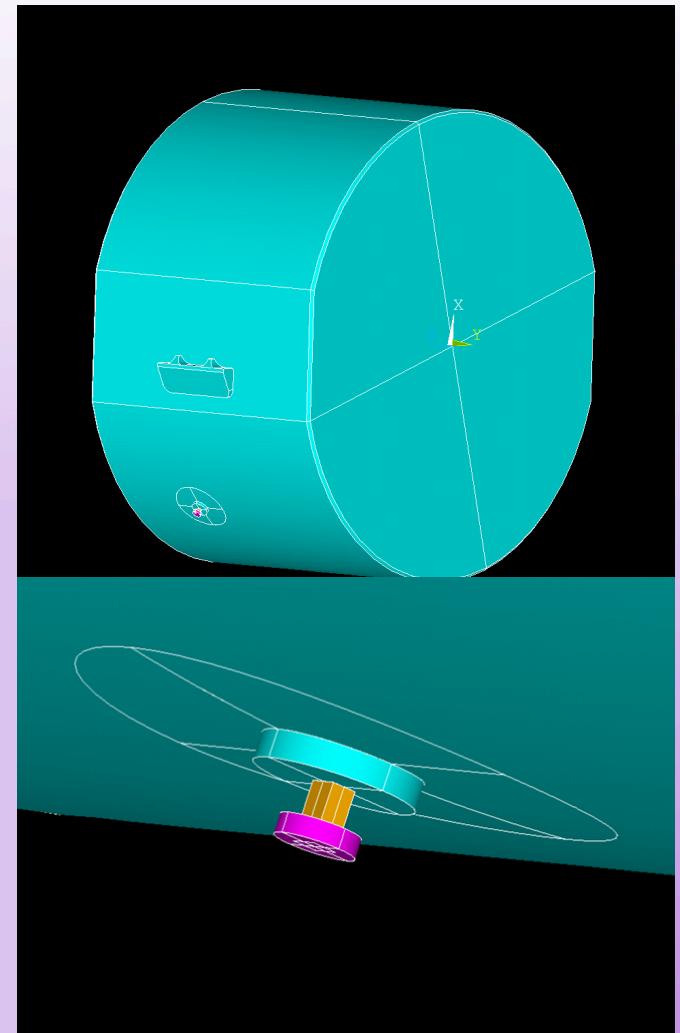


Parametric Instabilities

Slawek Gras (LIGO-MIT)

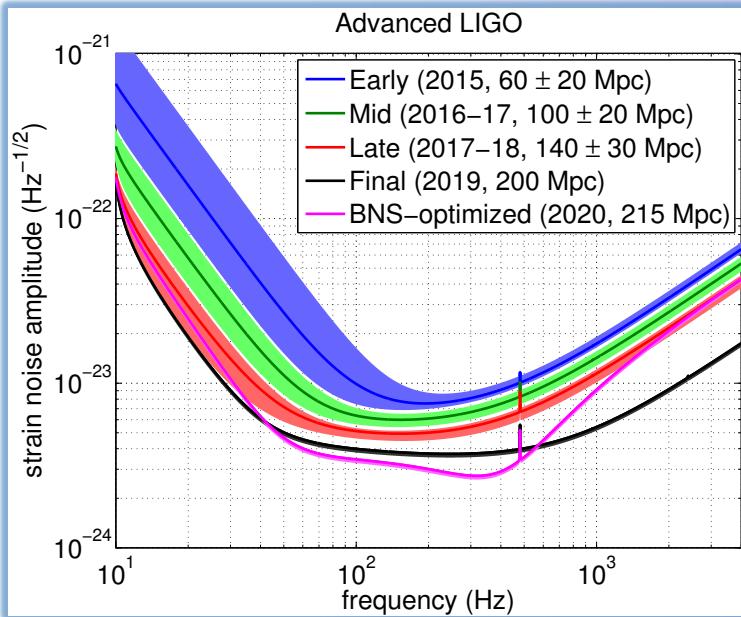


1. Test mass mechanical mode scatters fundamental mode (pump) into the higher order mode
2. After round trip scattered mode returns to the test mass and couples via radiation pressure into the mechanical mode



Detection Rates

Epoch	Estimated Run Duration	$E_{\text{GW}} = 10^{-2} M_{\odot} c^2$		BNS Range (Mpc)		Number of BNS Detections	% BNS Localized within	
		LIGO	Virgo	LIGO	Virgo		5 deg ²	20 deg ²
2015	3 months	40 – 60	–	40 – 80	–	0.0004 – 3	–	–
2016–17	6 months	60 – 75	20 – 40	80 – 120	20 – 60	0.006 – 20	2	5 – 12
2017–18	9 months	75 – 90	40 – 50	120 – 170	60 – 85	0.04 – 100	1 – 2	10 – 12
2019+	(per year)	105	40 – 80	200	65 – 130	0.2 – 200	3 – 8	8 – 28
2022+ (India)	(per year)	105	80	200	130	0.4 – 400	17	48



Neutron Star Binaries:

Advanced LIGO: ~ 200 Mpc
“Realistic rate” ~ 40/year

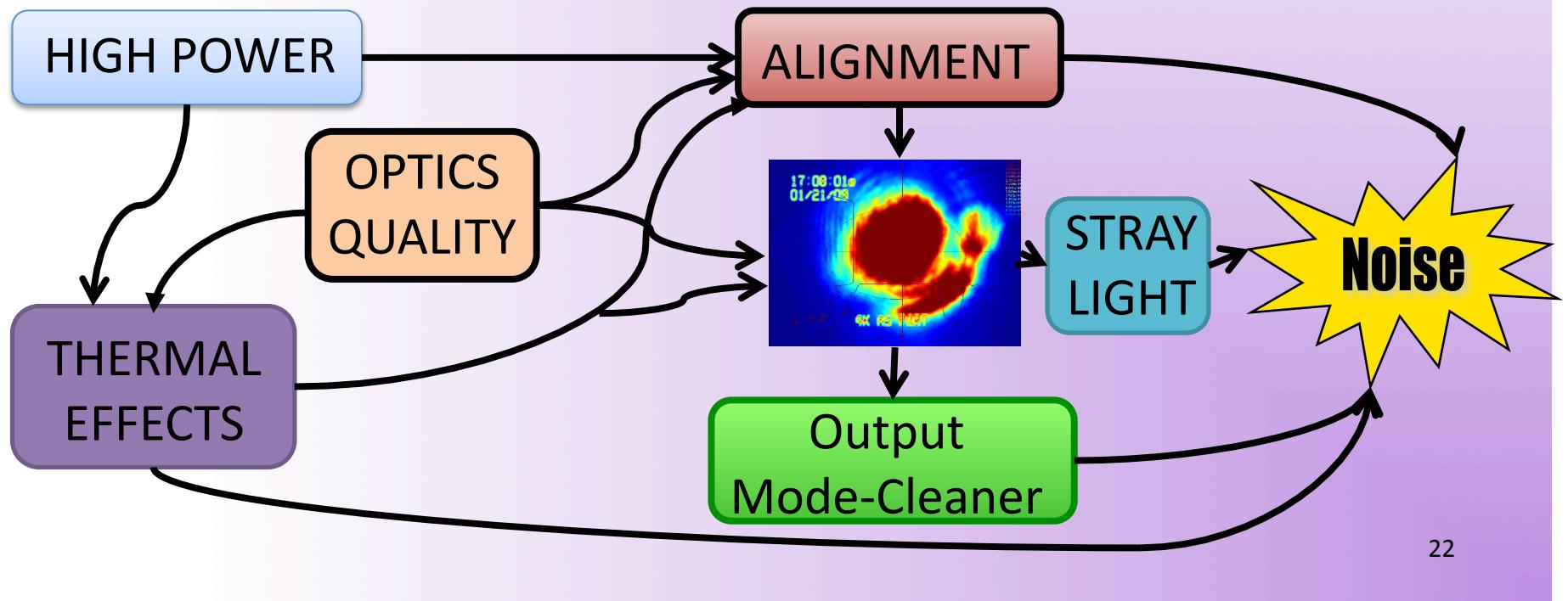
Class. Quant. Grav. **27**, 173001 (2010)

(Initial LIGO: ~15 Mpc, Rate ~1/50years)

What we call “commissioning”:

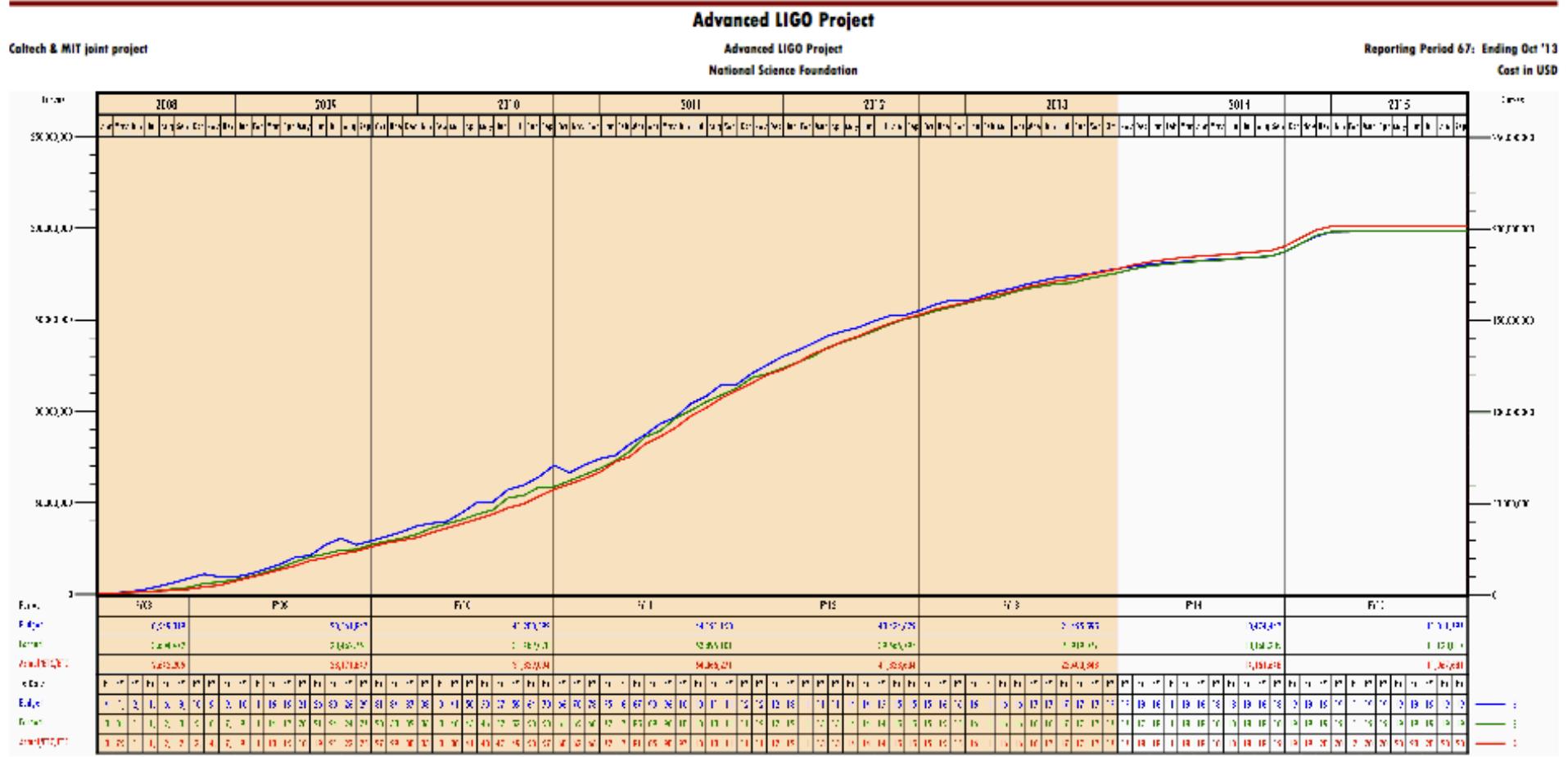
Understand and fix an entanglement of noise coupling mechanisms

Example from Enhanced LIGO



Advanced LIGO is 85.4% complete (@ July 2013)

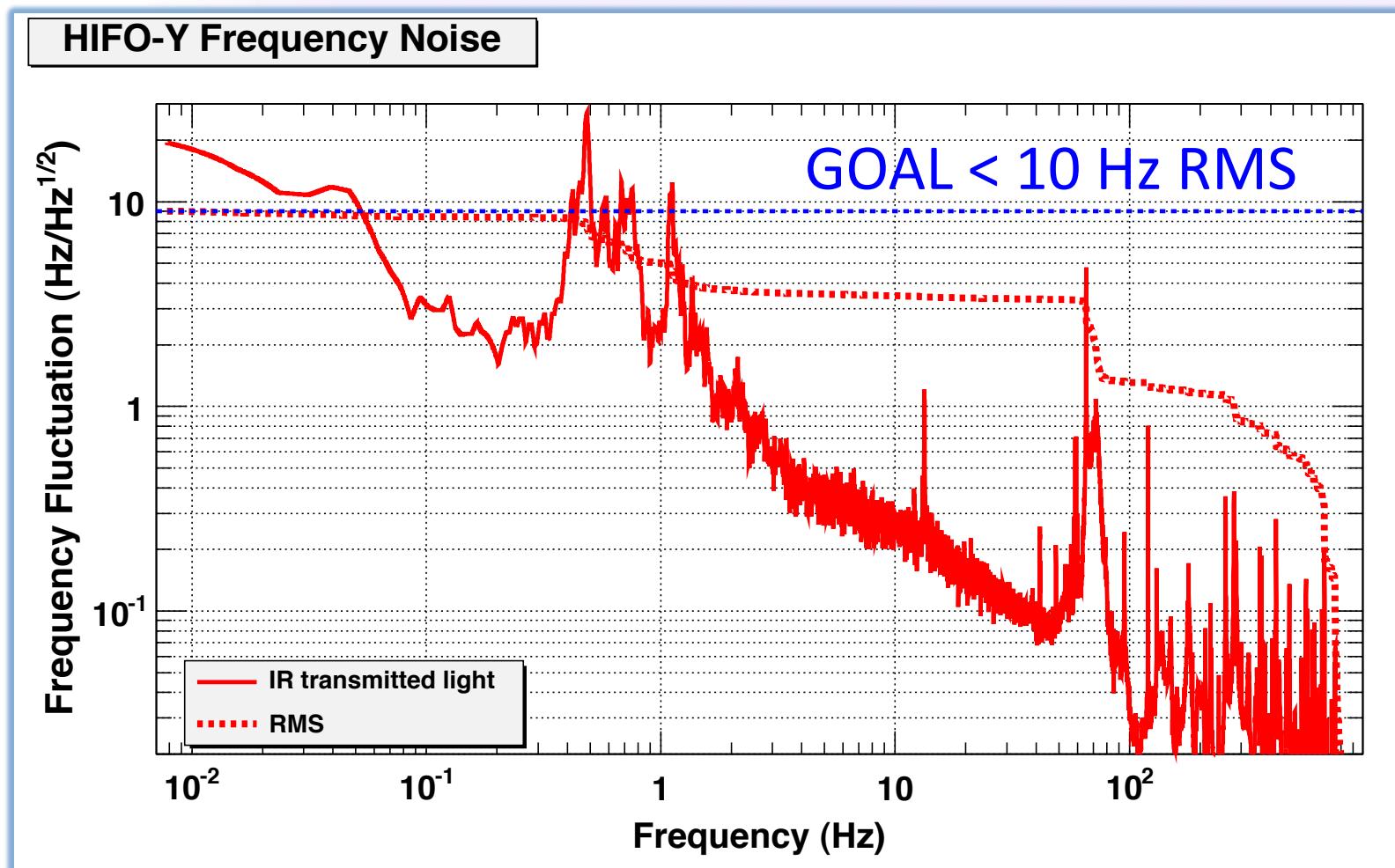
PERFORMANCE S-CURVE





“Arm Length Stabilization” System

Frequency fluctuations of main laser light is already “good enough”
(1/10 of the cavity linewidth), “noise hunting” still in progress



Seismic isolation performance

