*LIGO Laboratory / LIGO Scientific Collaboration*

LIGO- E1300829 *LIGO* Nov 04, 2013

**aLIGO HEPI H1 HAM3**

**Assembly Validation Report**

**E1300829-v2**

Hugo Paris, Fabrice Matichard for the SEI Team

Distribution of this document:

Advanced LIGO Project

This is an internal working note

of the LIGO Laboratory

|  |  |
| --- | --- |
| **California Institute of Technology**  **LIGO Project – MS 18-34**  **1200 E. California Blvd.**  **Pasadena, CA 91125**  Phone (626) 395-2129  Fax (626) 304-9834  E-mail: info@ligo.caltech.edu | **Massachusetts Institute of Technology**  **LIGO Project – NW22-295**  **185 Albany St**  **Cambridge, MA 02139**  Phone (617) 253-4824  Fax (617) 253-7014  E-mail: info@ligo.mit.edu |
| **LIGO Hanford Observatory**  **P.O. Box 1970**  **Mail Stop S9-02**  **Richland WA 99352**  Phone 509-372-8106  Fax 509-372-8137 | **LIGO Livingston Observatory**  **P.O. Box 940**  **Livingston, LA 70754**  Phone 225-686-3100  Fax 225-686-7189 |

Contents

[1.Introduction 4](#__RefHeading__2417_754021944)

[2.Sub-Components Testing 4](#__RefHeading__2419_754021944)

[3.Load Cells assembly 4](#__RefHeading__178_1185372569)

[4.Boot Location 6](#__RefHeading__162_870708744)

[5.Check Stops Gaps 7](#__RefHeading__836_1185372569)

[6.Gaps check 7](#__RefHeading__170_870708744)

[7.IPS Centering 8](#__RefHeading__840_1185372569)

[8.Sensor ASD 9](#__RefHeading__98_503471281)

[9.SUS-watchdogs interaction test 11](#__RefHeading__196_1185372569)

[10.Static Test local drive 11](#__RefHeading__23664_1262773321)

[11.Linearity Test/Range of motion in the local basis 12](#__RefHeading__444_1185372569)

[12.Actuator Plate to Shields gap 13](#__RefHeading__854_1185372569)

[13.Valve Check 14](#__RefHeading__208_1185372569)

[14.Local-to-local measurements 15](#__RefHeading__126_1080062798)

[15. Alignment offsets: 18](#__RefHeading__2421_754021944)

# Introduction

This document summarizes the steps to be done to validate HEPI assemblies. Corresponding reports must be posted in :

LIGO-E1300454: aLIGO HEPI Testing Reports

# Sub-Components Testing

* Kaman Inductive Position Sensors: calibration, linearity, factory data, noise measurements (E0900426 – HEPI Kaman Sensor Receiving Analysis - Results posted in the SVN )
* HEPI actuator linearity test (E1100338 – aLIGO HEPI Actuators Test Results)
* L4C test (Q0900007)

# Load Cells assembly

BSC HEPI load cell capacity → 3000 lbs

HAM HEPI load cell capacity → 2000 lbs

|  |  |  |
| --- | --- | --- |
|  | **Left Spring (lbs)** | **Right Spring (lbs)** |
| **Pier 1** |  |  |
| **Pier 2** |  |  |
| **Pier 3** |  |  |
| **Pier 4** |  |  |

**Acceptance criteria:**

* The values must not exceed 80% of the load cell capacity (2400lbs for BSC and 1600lbs for HAM).

**Test result: Passed: Failed: .**

# Boot Location

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
|  | Pier 1 | Pier 2 | Pier 3 | Pier 4 |
| Point 1a (Tangential) |  |  |  |  |
| Point 1b (Tangential) |  |  |  |  |
| Point 2a (Tangential) |  |  |  |  |
| Point 2b (Tangential) |  |  |  |  |
| Point 3 (Radial Back) |  |  |  |  |
| Point 4 (Radial Front) |  |  |  |  |
| Point 5 (Vertical) |  |  |  |  |

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
|  | Pier 1 | Pier 2 | Pier 3 | Pier 4 |
| Point 1a (Tangential) |  |  |  |  |
| Point 1b (Tangential) |  |  |  |  |
| Point 2a (Tangential) |  |  |  |  |
| Point 2b (Tangential) |  |  |  |  |
| Point 3 (Radial Back) |  |  |  |  |
| Point 4 (Radial Front) |  |  |  |  |
| Point 5 (Vertical) |  |  |  |  |

**Acceptance criteria:**



**Test result: Passed: Failed: .**

# Check Stops Gaps

The stops must not touch the boot. There is 15 stops per boot, 5 per F bracket.

|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | **Bracket 1** | | | | | | **Bracket 2** | | | | | | **Bracket 3** | | | | | |
|  | **Gap1** | **Gap2** | **Gap3** | **Gap4 above** | **Gap4 under** | **Gap5** | **Gap1** | **Gap2** | **Gap3** | **Gap4 above** | **Gap4 under** | **Gap5** | **Gap1** | **Gap2** | **Gap3** | **Gap4 above** | **Gap4 under** | **Gap5** |
| **Pier 1** |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| **Pier 2** |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| **Pier 3** |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| **Pier 4** |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

**Test result: Passed: Failed:**

# Gaps check

Four particular gaps need to be check.

**Acceptance criteria:**

* a 0.08” shim must fit in these two gaps

Issues/difficulties/comments regarding this test: Gap#1 is tricky to reach. At LASTI, the solution found was to tape the shim to an extension (rod, rigid ruler, etc.).

Gap#2 should be reachable by hand.

Gap#3 and 4 are tricky, but should also be doable (no picture)

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
|  | **Gap#1** | **Gap#2** | **Gap#3** | **Gap#4** |
| **Pier 1** |  |  |  |  |
| **Pier 2** |  |  |  |  |
| **Pier 3** |  |  |  |  |
| **Pier 4** |  |  |  |  |

**Test result: Passed: Failed: .**

# IPS Centering

**Scripts files for processing and plotting in SVN at:**

/SeiSVN/seismic/HEPI/Common/Testing\_Functions\_HEPI/Offset\_STD\_IPS\_HEPI.m

**Data in SVN at:**

/ligo/svncommon/SeiSVN/seismic/HEPI/H1/HAM3/Data/Static\_Tests/

\_IPS\_Read\_Back\_\_20131031\_15:23.mat

All the loops must be turned off during this test.

Issues/difficulties/comments regarding this test:

The test was performed on October 31st 2013, with HEPI Locked.

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | H1 | H2 | H3 | H4 | V1 | V2 | V3 | V4 |
| Mean (counts) | 5801.06 | 771.10 | -1873.13 | -1737.85 | -3931.03 | -3650.12 | -1845.86 | -4244.17 |
| Acceptance | +/- 15000 | +/- 15000 | +/- 15000 | +/- 15000 | +/- 15000 | +/- 15000 | +/- 15000 | +/- 15000 |

**Test result: Passed: X Failed:**

# Sensor ASD

**Scripts files for processing and plotting in SVN at:**

/SeiSVN/seismic/HEPI/Common/Testing\_Functions\_HEPI/ASD\_Measurements\_Local\_HEPI.m

**Data in SVN at:**

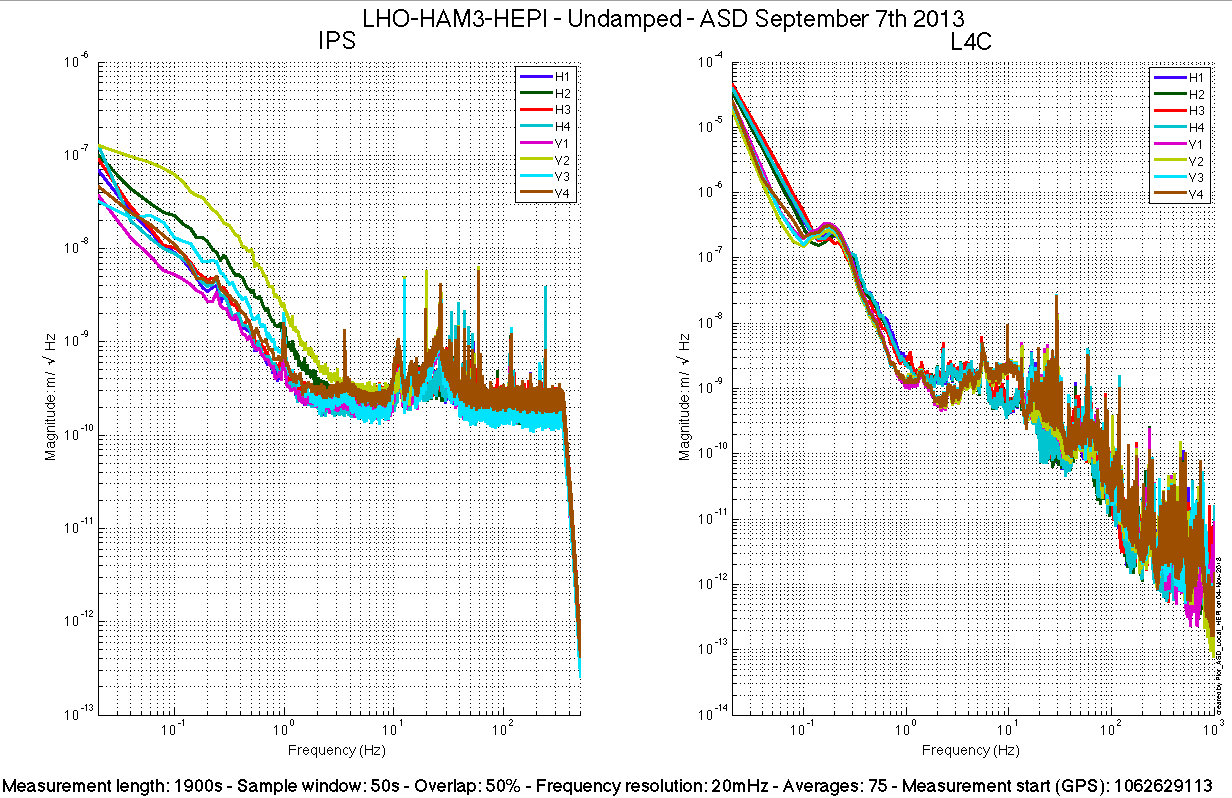
SeiSVN/seismic/HEPI/H1/HAM3/Data/Spectra/Undamped/

LHO\_HPI\_HAM3\_ASD\_m\_IPS\_L4C\_2013\_09\_07.mat

**Figures in SVN at:**

/SeiSVN/seismic/HEPI/H1/HAM3/Data/Figures/Spectra/Undamped/

LHO\_HPI\_HAM3\_ASD\_m\_IPS\_L4C\_2020\_09\_07\_3 5:4:.fig



Issues/difficulties/comments regarding this test:

Measurements were performed with all PreFilters ON.

**Acceptance criteria:**



**Test result: Passed: X Failed: .**

# SUS-watchdogs interaction test

**This test will be obsolete very soon, as the payload-HEPI WD connection is planned for removal.**

. Set up a zero value on the payload watchogs.

. Check that the payload watchdog screen of HEPI tripped.

. In the payload watchdog screen, click on the OVERRIDE button and reset the watchdog.

. Do the same process for all the payloads

**Acceptance criteria:**

* The HEPI must trip when the payload watchdogs are tripped
* The HEPI watchdogs could be reset when the OVERRIDE button is ON

**Test result: Passed: Failed: .**

When this test is done, reset everything (OVERRIDE button OFF, put back the value on the payload watchdog).

# Static Test local drive

**Scripts files for processing in SVN at:**

/SeiSVN/seismic/HEPI/Common/Testing\_Functions\_HEPI/Static\_Test\_Local\_Basis\_HEPI.m

. ***Drive of 5000 counts***

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | H1 | H2 | H3 | H4 | V1 | V2 | V3 | V4 |
| H1 | 8698.1 | -5129.7 | -501.2 | -1956.1 | -81.1 | 317.6 | 242.9 | -315.0 |
| H2 | -4450.0 | 8740.6 | -2061.1 | -544.7 | 24.7 | -176.3 | -328.0 | 201.9 |
| H3 | -523.3 | -1723.0 | 8385.3 | -4620.9 | 177.2 | -259.8 | -381.9 | 65.1 |
| H4 | -1863.2 | -525.2 | -4418.2 | 8496.6 | -442.7 | 320.4 | 110.8 | -559.7 |
| V1 | -123.3 | 170.4 | 307.9 | -377.9 | 7339.5 | 876.5 | -1628.8 | 776.8 |
| V2 | 134.7 | -178.5 | -266.9 | 294.2 | 1302.4 | 7453.2 | 636.0 | -1626.4 |
| V3 | 202.8 | -248.6 | -319.2 | 259.8 | -1011.9 | 1544.1 | 7961.9 | 743.7 |
| V4 | -284.1 | 396.0 | 257.5 | -459.4 | 1367.6 | -986.9 | 1110.3 | 8496.3 |

*Table - Main couplings and cross couplings*

. ***Drive of 1000 counts***

*Table - Main couplings and cross couplings*

. ***Drive of 2500 counts***

*Table - Main couplings and cross couplings*

Issues/difficulties encountered during this test:

**Drive of 1000 and 2500 counts were skipped. Static\_Test\_Local\_Basis\_HEPI.m drives at 5000 counts only.**

**Acceptance criteria:**

* The results in these three tables must be the same (within xxx%)

**Test result: Passed: X Failed: .**

# Linearity Test/Range of motion in the local basis

**Scripts files for processing and plotting in SVN at:**

/SeiSVN/seismic/HEPI/Common/Testing\_Functions\_HEPI/Linearity\_Test\_Awgstream\_HEPI.m

**Data in SVN at:**

SeiSVN/seismic/HEPI/H1/HAM3/Data/Linearity\_Test/ LHO\_HPI\_HAM3\_Linearity\_test\_20130903T135532.mat

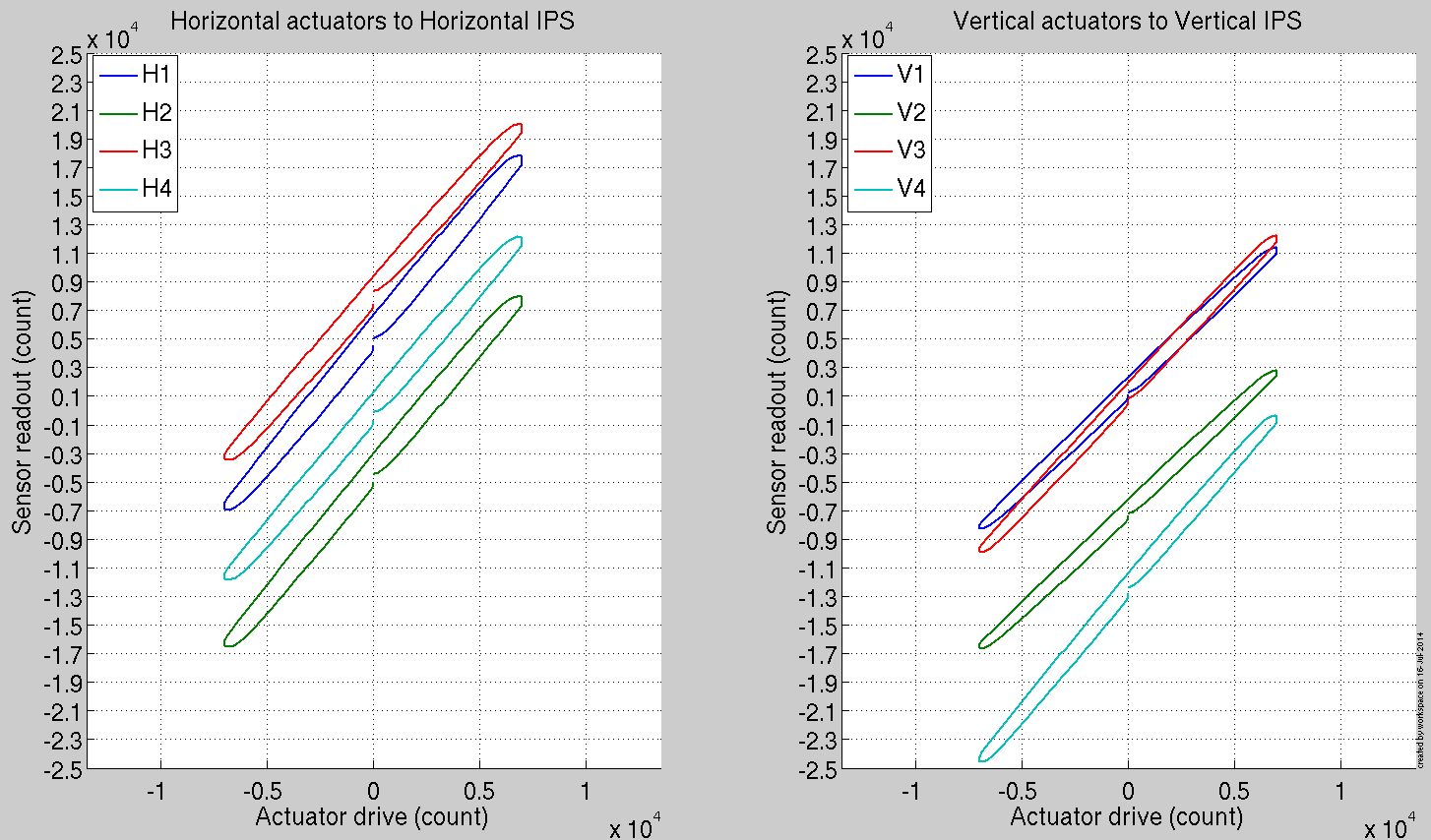
**Figures in SVN at:**

/SeiSVN/seismic/HEPI/H1/HAM3/Data/Figures/Linearity\_Test/

|  |  |  |
| --- | --- | --- |
|  | Slopes | Offsets |
| H1 | 1.79 | 5447.56 |
| H2 | 1.77 | -4190.71 |
| H3 | 1.70 | 8330.82 |
| H4 | 1.73 | 167.97 |
| V1 | 1.41 | 1587.05 |
| V2 | 1.40 | -6913.42 |
| V3 | 1.59 | 1171.49 |
| V4 | 1.75 | -12297.00 |

Issues/difficulties encountered during this test:

**The autosave failed and the plots saved under the SVN are empty.**



Data was in svn, uploaded and plotted, plot figure saved in svn--HR

**Acceptance criteria:**

**Test result: Passed: ? Failed: .**

# Actuator Plate to Shields gap

**Perform this test ONLY if the range of motion test failed.**

Three gaps per actuator need to be checked.

**Acceptance criteria:**

* A 0.1” shim must fit into the gap #1
* A 0.05 shim must fit into gap #2 and #3

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
|  | **Horizontal** | | | **Vertical** | | |
|  | **Gap #1** | **Gap #2** | **Gap #3** | **Gap #1** | **Gap #2** | **Gap #3** |
| **Pier 1** |  |  |  |  |  |  |
| **Pier 2** |  |  |  |  |  |  |
| **Pier 3** |  |  |  |  |  |  |
| **Pier 4** |  |  |  |  |  |  |

**Test result: Passed: Failed:**

# Valve Check

**Scripts files for processing and plotting in SVN at:**

/SeiSVN/seismic/HEPI/H1/HAM3/Scripts/Valve\_Check/plot\_valve\_check.m

**Data in SVN at:**

SeiSVN/seismic/HEPI/H1/HAM3/Data/Spectra/Undamped/

/SeiSVN/seismic/HEPI/H1/HAM3/Scripts/Valve\_Check

**Figures in SVN at:**

/SeiSVN/seismic/HEPI/H1/HAM3/Scripts/Valve\_Check

**Acceptance criteria:**

**Test result: Passed: Failed: .**

# Local-to-local measurements

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| **Band (Hz)** | **Resolution** | **Amplitude** | **Nreps** | **Time (s)** | **Time (min)** | **Time (h)** |
| **500-1000** |  | 4000 – 4000\* | 250 | 4176\* | 4176 | 1\* |
| **100 - 500** | 0.5 | 4000 – 4000\* | 250 | 4176\* | 69.6 | 1.2\* |
| **10 - 100** | 0.25 | 4000 – 4000\* | 200 | 6592\* | 109.9 | 1.8\* |
| **0.7 - 10** | 0.05 | 4000 – 4000\* | 75 | 12320\* | 205.3 | 3.4\* |
| **0.1 - 0.7** | 0.025 | 4000 – 4000\* | 30 | 10080\* | 168.0 | 2.8\* |
| **0.01 - 0.1** | 0.01 | 4000 – 4000\* | 10 | 8960\* | 149.3 | 2.5\* |
| **0.002 - 0.01** | 0.002 | 4000 – 4000\* | 2 | 12160\* | 202.7 | 3.4\* |
|  |  |  |  |  |  | **16.1\*** |

\*: Values Need to be updated

**Data files in SVN at:**

/SeiSVN/seismic/HEPI/H1/HAM3/Data/Transfer\_Functions/Measurements/Undamped/

* LHO\_HPI\_HAM3\_Data\_L2L\_500Hz\_1000Hz\_20130903-172713.mat
* LHO\_HPI\_HAM3\_Data\_L2L\_100Hz\_500Hz\_20130903-194343.mat
* LHO\_HPI\_HAM3\_Data\_L2L\_10Hz\_100Hz\_20130903-205304.mat
* LHO\_HPI\_HAM3\_Data\_L2L\_700mHz\_10Hz\_20130904-163817.mat
* LHO\_HPI\_HAM3\_Data\_L2L\_100mHz\_700mHz\_20130904-200540.mat
* LHO\_HPI\_HAM3\_Data\_L2L\_10mHz\_100mHz\_20130904-225820.mat
* LHO\_HPI\_HAM3\_Data\_L2L\_2mHz\_10mHz\_20130905-014021.mat

**Data is called by** **Case #2 of:**/ligo/svncommon/SeiSVN/seismic/HEPI/H1/HAM3/Data/Figures/Transfer\_Functions/Measurements/

Measurements\_List\_H1\_HPI\_HAM3.m

**Data collection script files:**

/SeiSVN/seismic/HEPI/Common//Transfer\_Function\_Scripts/

* Run\_TF\_L2L\_10mHz\_100mHz.m
* Run\_TF\_L2L\_100mHz\_500mHz.m
* Run\_TF\_L2L\_500mHz\_5Hz.m
* Run\_TF\_L2L\_5Hz\_100Hz.m
* Run\_TF\_L2L\_100Hz\_1000Hz.m

**Scripts files for processing and plotting in SVN at:**

/SeiSVN/seismic/HEPI/H1/HAM3/Scripts/Control\_Scripts/release/

* Step\_1\_TF\_Loc\_to\_Loc\_H1\_HEPI\_HAM3.m

**Figures in SVN at:**

/SeiSVN/seismic/HEPI/H1/HAM3/Data/ Figures/Transfer\_Functions/Measurements/Undamped/

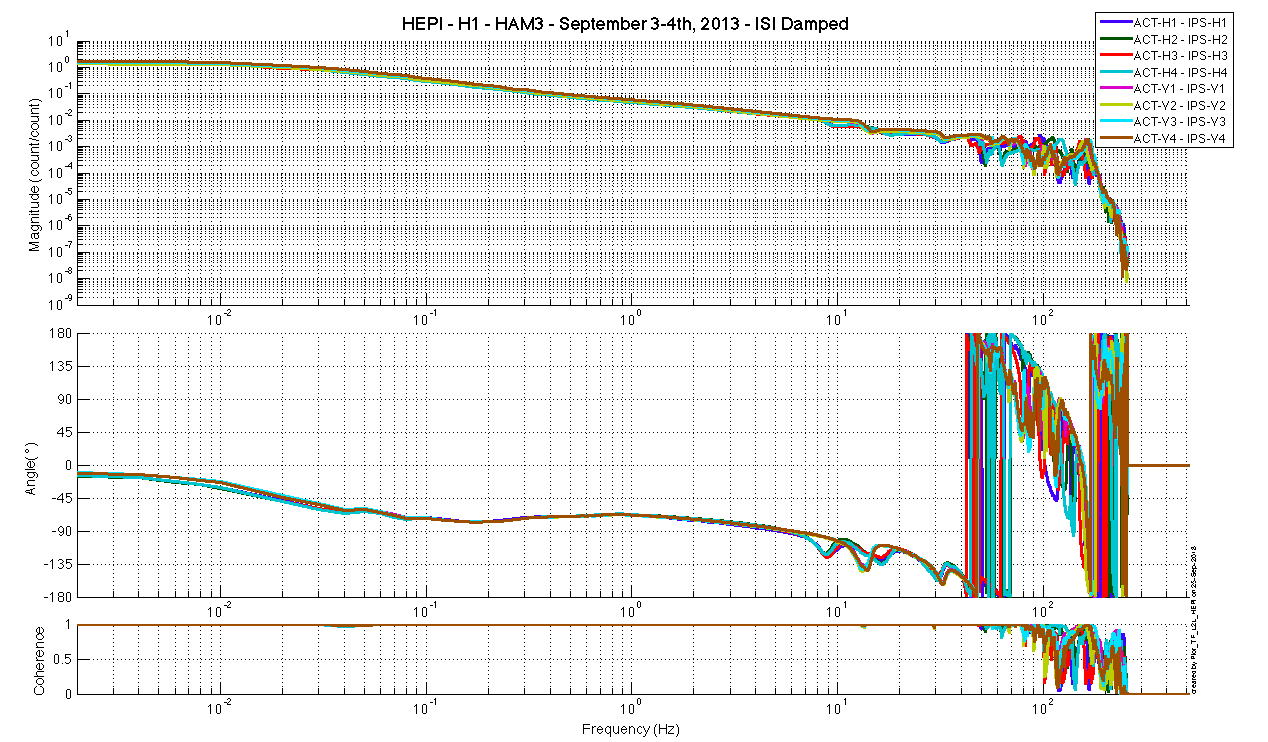
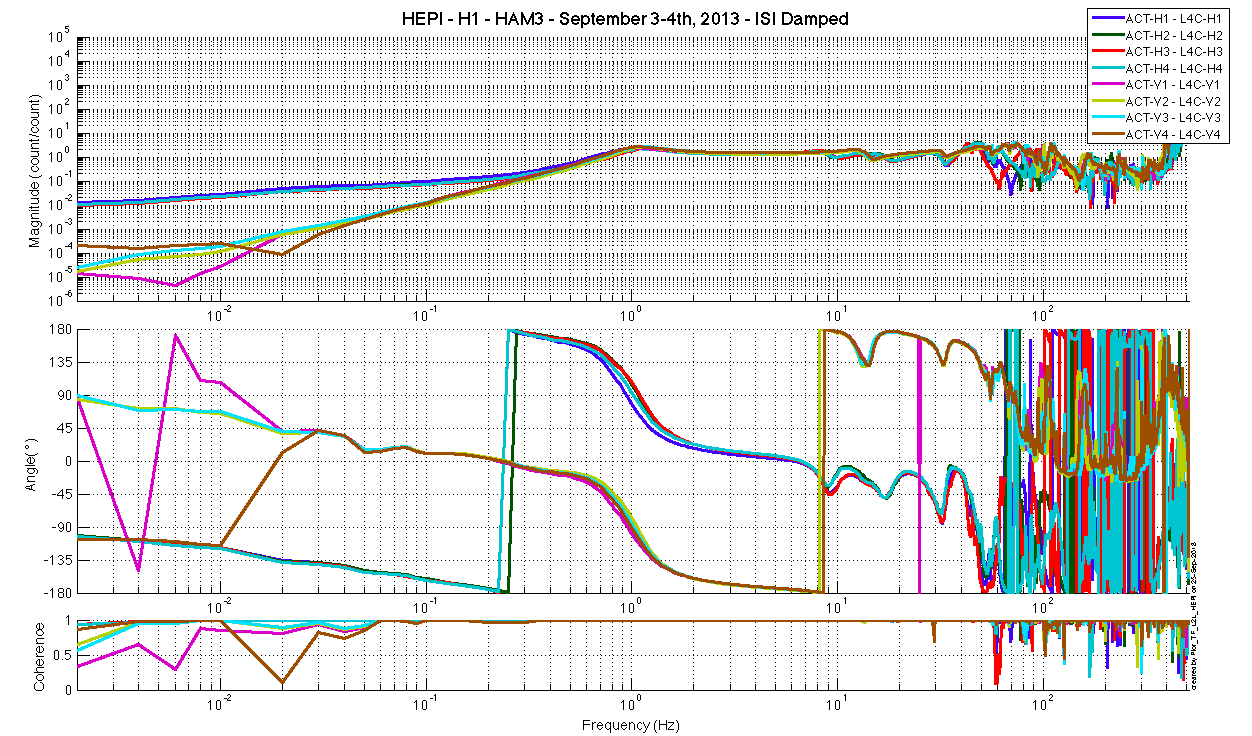
* H1\_HPI\_HAM3\_TF\_L2L\_Raw\_from\_ACT\_to\_IPS\_2013\_09\_04.fig
* H1\_HPI\_HAM3\_TF\_L2L\_Raw\_from\_ACT\_to\_IPS\_2013\_09\_04.fig

**Storage of measured transfer functions in the SVN at:**

/SeiSVN/seismic/HEPI/H1/HAM3/Data/Transfer\_functions/ Simulations/Undamped/

* H1\_HPI\_HAM3\_TF\_L2L\_Sym\_2013\_09\_04.mat

The local-to-local transfer functions are presented below.



A description...

Issues/difficulties/comments regarding this test:

**Acceptance criteria:**

* On IPS, the phase must be 0º at DC
* On geophones, the phase must be 90º at DC
* Identical shape in each corner

**Test result: Passed: X Failed: .**

# Alignment offsets:

Those are the IPS readouts that were recorded with HEPI locked, after aligment work was performed. The opposite of those values is to be installed as offset of the IPS filter banks when the Isolation loops are turned on. This way, HEPI will be operating in its *preferred alignment* state.

|  |  |  |
| --- | --- | --- |
|  | IPS Readouts HEPI Locked | Offset Value |
| H1 | 6517.4 | -6517.4 |
| H2 | -4677.9 | 4677.9 |
| H3 | 9328.4 | -9328.4 |
| H4 | -2148.2 | 2148.2 |
| V1 | 2864.2 | -2864.2 |
| V2 | -6362.4 | 6362.4 |
| V3 | 2112.5 | -2112.5 |
| V4 | -9395.8 | 9395.8 |

Issues/difficulties encountered during this test:

Offest were retrieved from LHO aLog # 7180

**Acceptance criteria:**

Offsets were recorded.

**Test result: Passed: X Failed: .**