

The Road to Multimessenger Astronomy with Advanced LIGO

Leo Singer • LIGO Laboratory, Caltech

lsinger@caltech.edu • Document LIGO-G1300492-V5

The story so far

- Global network of 3 multi-km interferometric observatories: LIGO–Hanford, LIGO–Livingston, Virgo
- During joint LIGO–Virgo science run in Summer—Fall 2010, sent alerts to astronomers to point telescopes see Abadie et al. 2012, A&A 541, A155
- Detectors off-line while they are reconfigured as advanced detectors → eventually 10x greater range for binary neutron stars
- More detectors planned: KAGRA, LIGO–India



Possible electromagnetic counterparts

- 2 neutron stars merge, form compact object and accretion disk
- Accretion feeds pair of jets
- Internal shocks in jet produce prompt γ -ray burst
- Shock between jet and ISM produces optical and radio afterglow

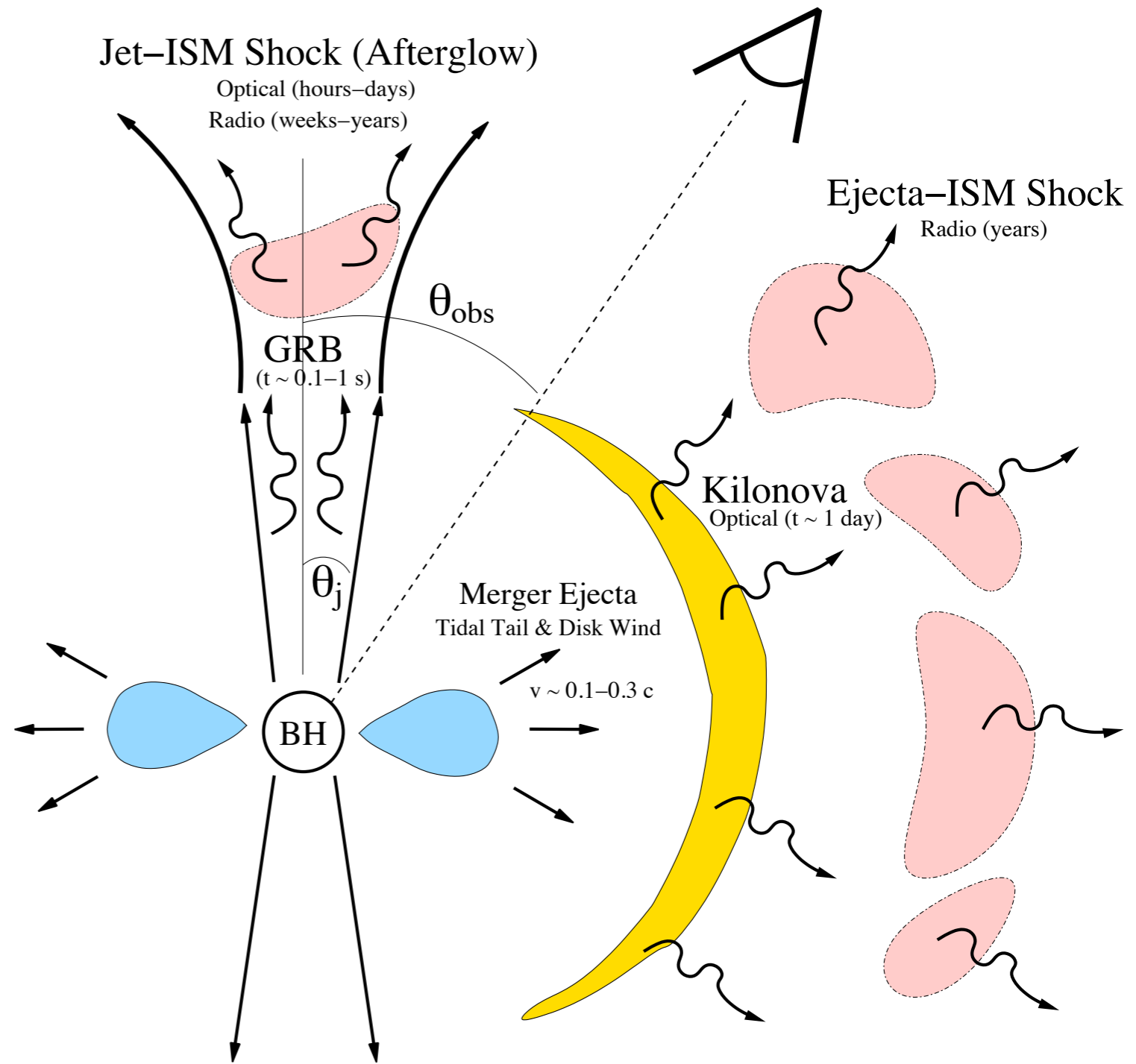
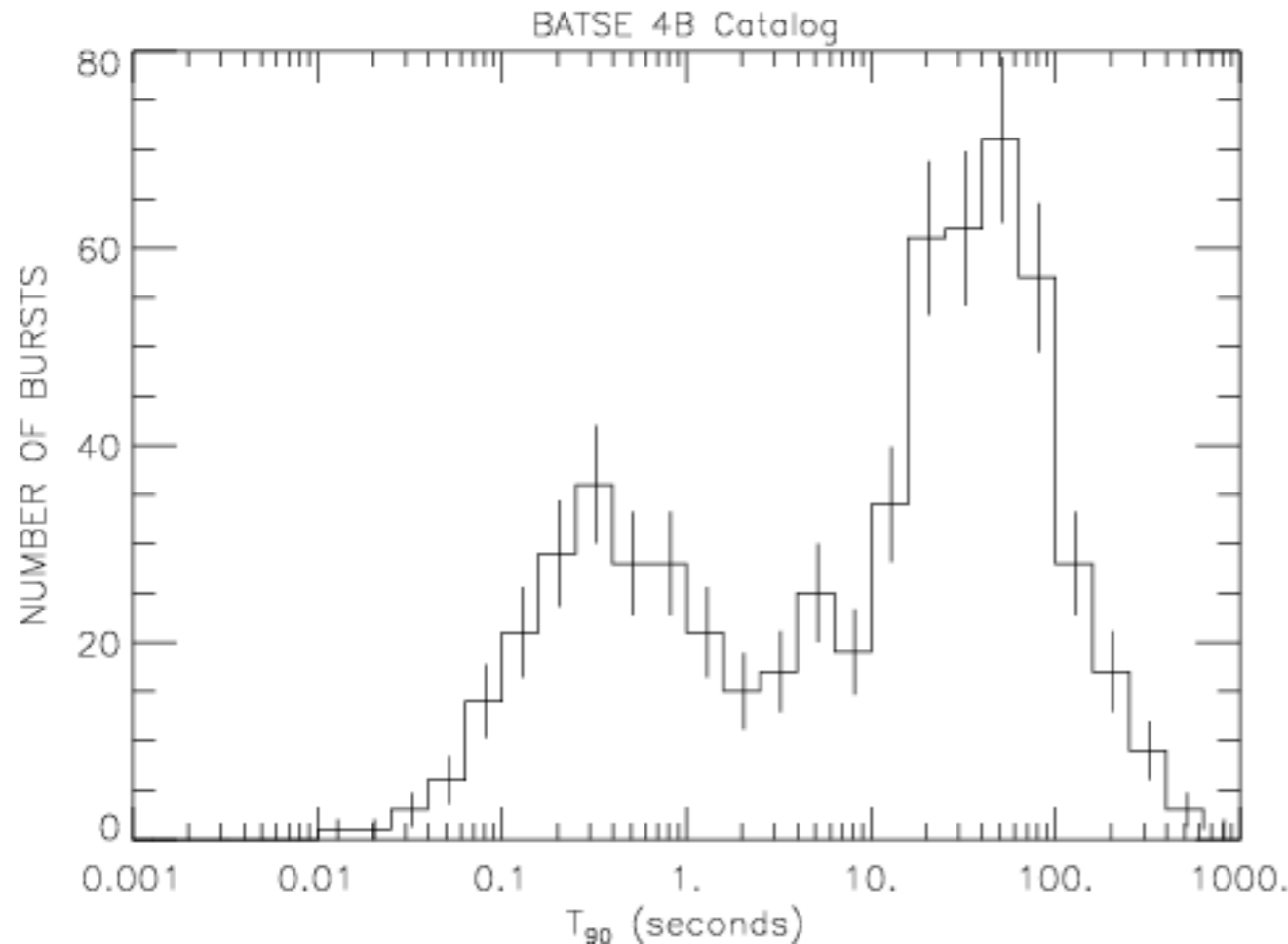


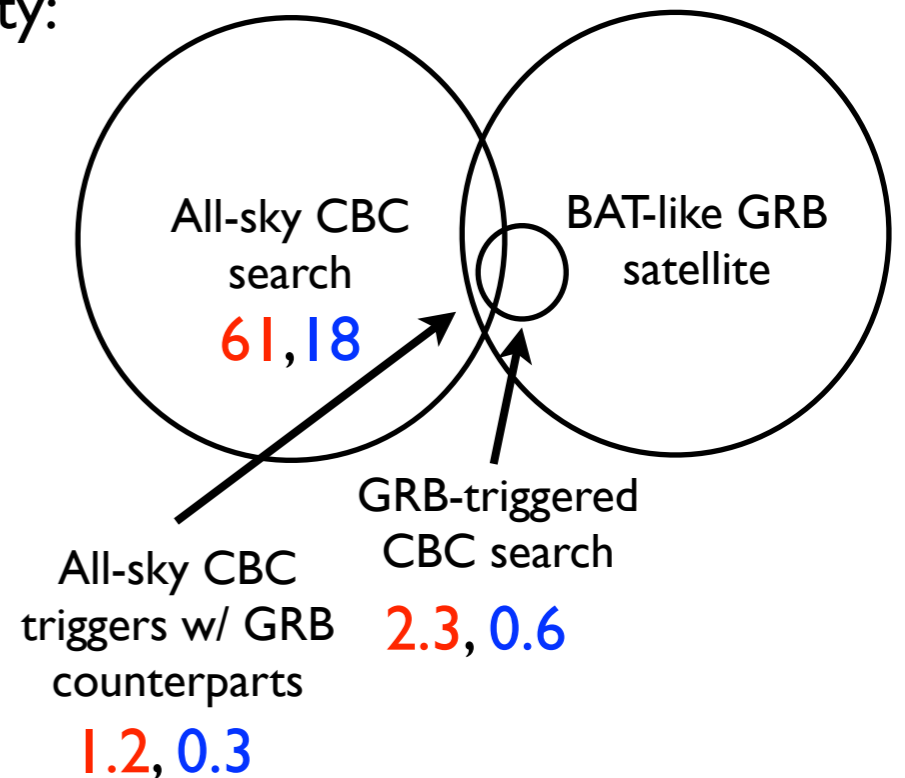
Figure 1 of Meztger & Berger 2012, ApJ, 746, 48

GRBs



- High-energy sky is relatively clean; temporal coincidence with GW trigger is enough
- But what GRB satellites will be up in 2018?...
IPN, *Swift*, *Fermi*, *Lobster*, *SVOM*, anything at all?

Number of **BNS**, **NSBH** sources per year at aLIGO/Virgo design sensitivity:



Outlook for detection of GW inspirals by GRB-triggered searches in the advanced detector era

Deitz, Fotopolous, Singer, and Cutler (2013, PRD 87:064033)
<http://dx.doi.org/10.1103/PhysRevD.87.064033>

Optical afterglows

- Often faint (16-22 mag)
- Fade rapidly (~several mag/night)
- Optical sky is crowded (rocks, quasars, variable stars, supernovae)
- Orphan afterglows! (PTFI I agg, <http://arxiv.org/abs/1304.4236>)

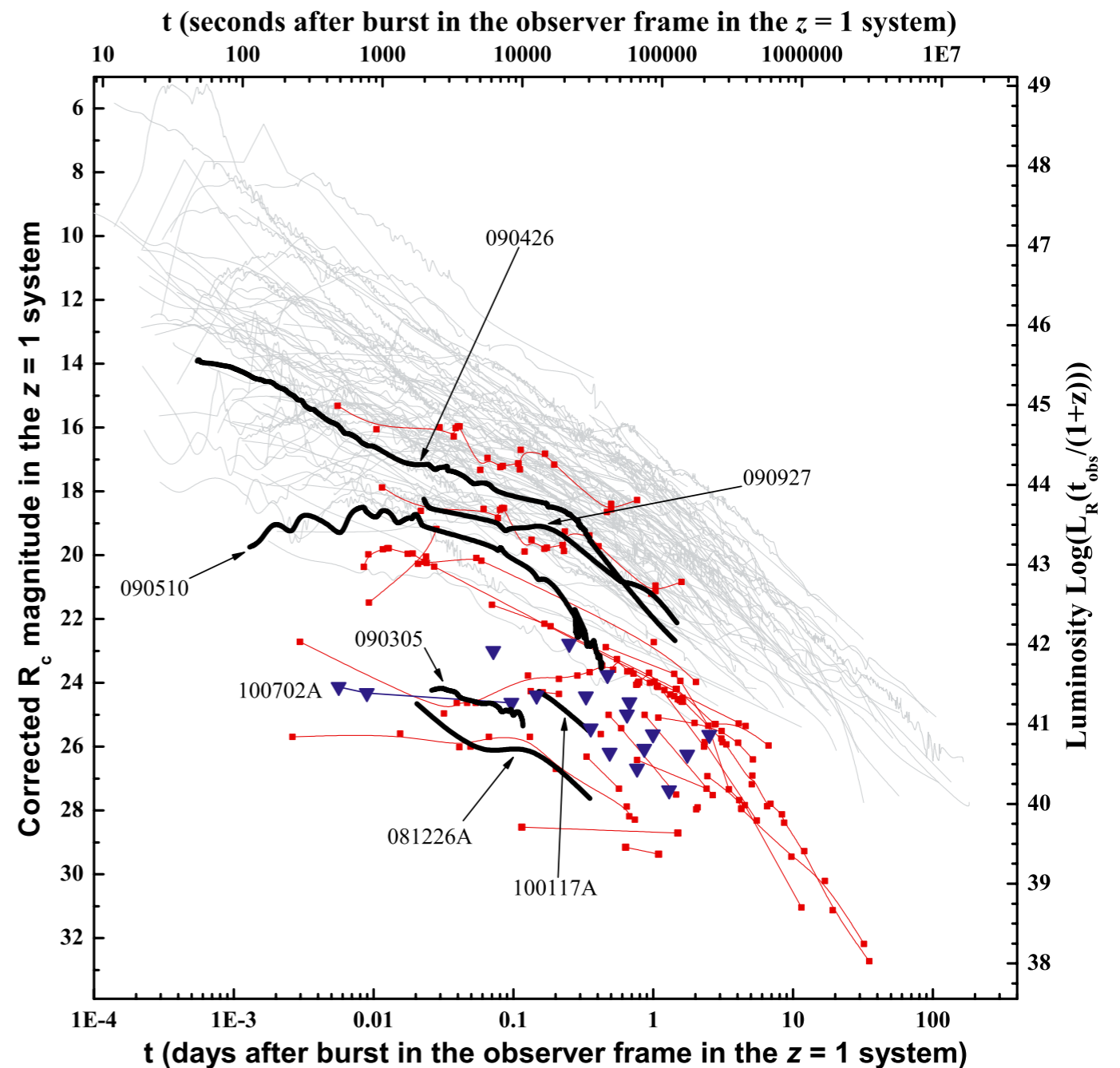


Fig. 15 of Guelbenzu et al. (2012)
A&A 548,A101 (2012)

How do we get there?

low-latency event detection

K. Cannon, C. Hanna, D. Keppel + many others + me

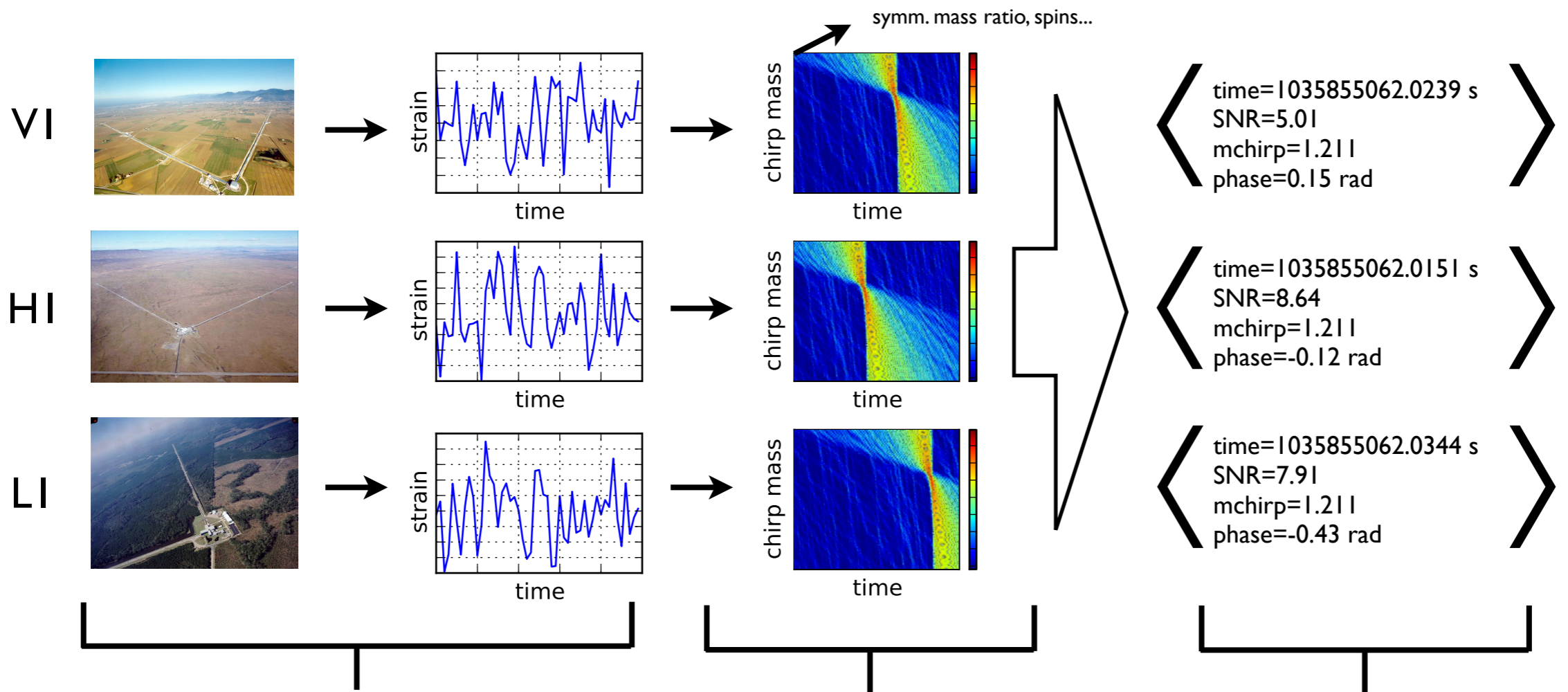
rapid sky localization

L. Price + me + many others

timely optical transient detection

Palomar Transient Factory + S. B. Cenko + D. Brown + M. Kasliwal+ myself

Detection



Strain transduced by detectors

also: data quality, vetoes, aggregate data to analysis clusters

Matched filter

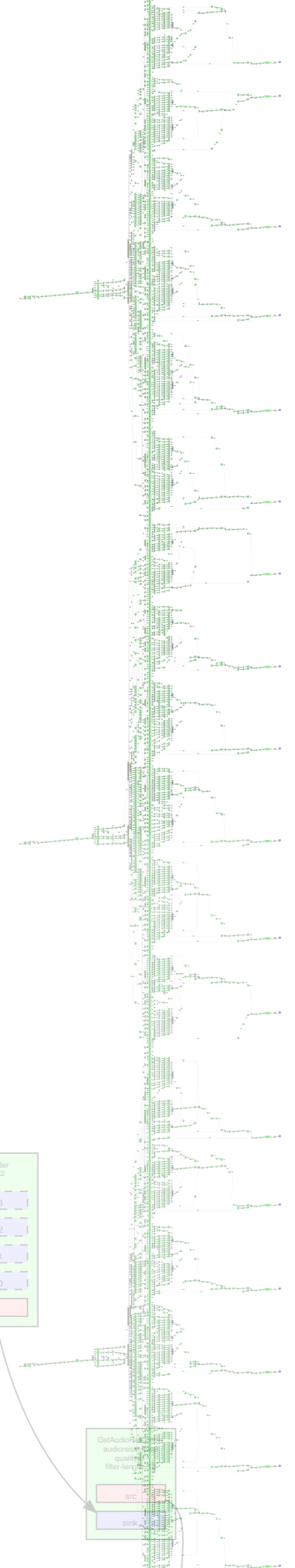
sliding dot product of strain data w/ sampling of all possible inspiral signals

Triggering, coincidence

excursion in matched filter *signal-to-noise ratio (SNR)* at similar times in all detectors

GstLAL:

online inspiral detection engine powered by

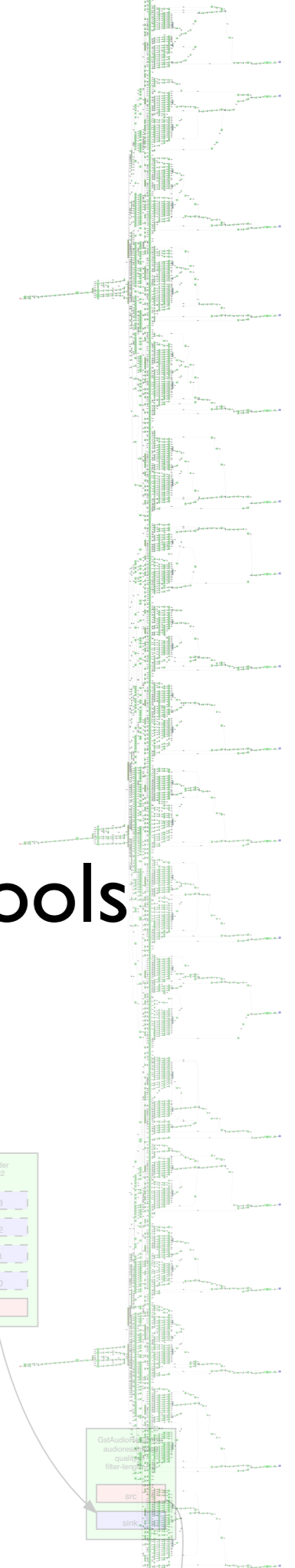


GstLAL:

online inspiral detection engine powered by



Built from “off the shelf” open-source DSP tools



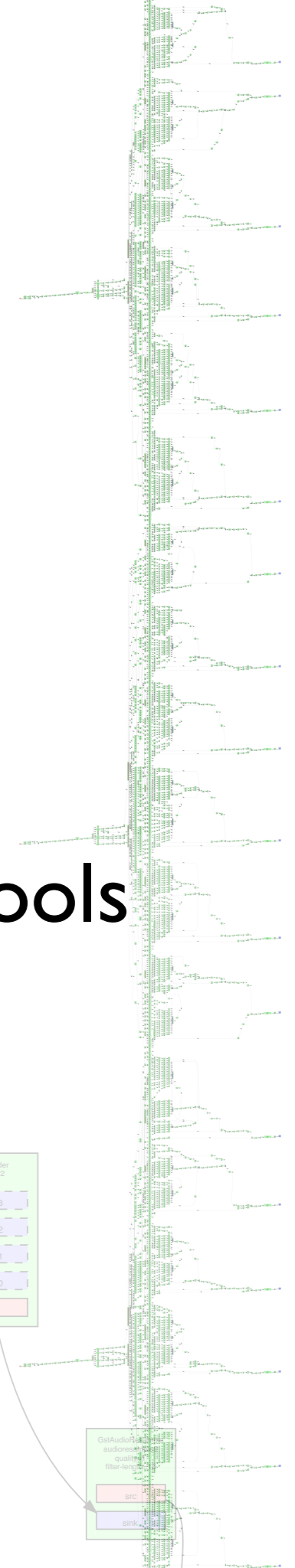
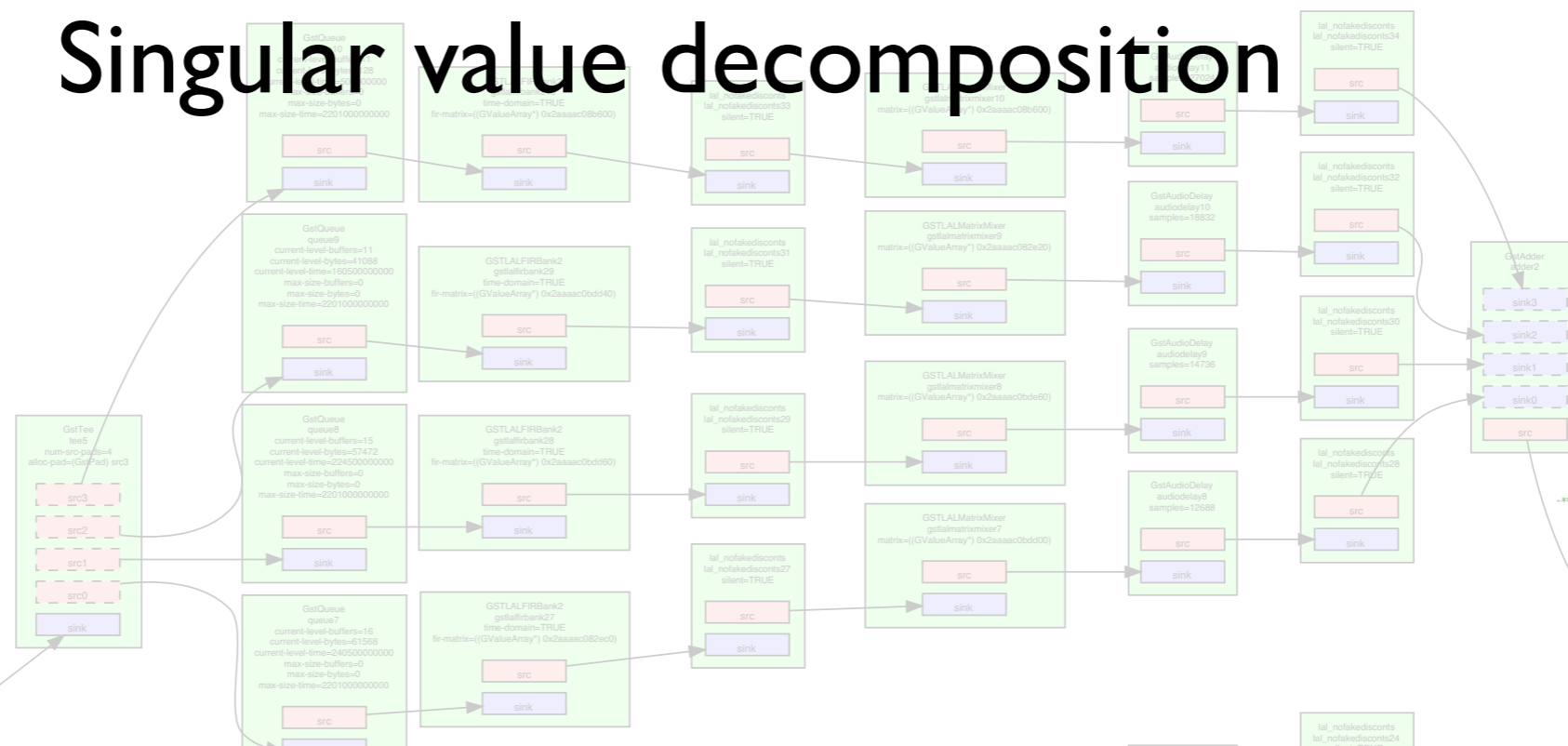
GstLAL:

online inspiral detection engine powered by



Built from “off the shelf” open-source DSP tools

Singular value decomposition



GstLAL:

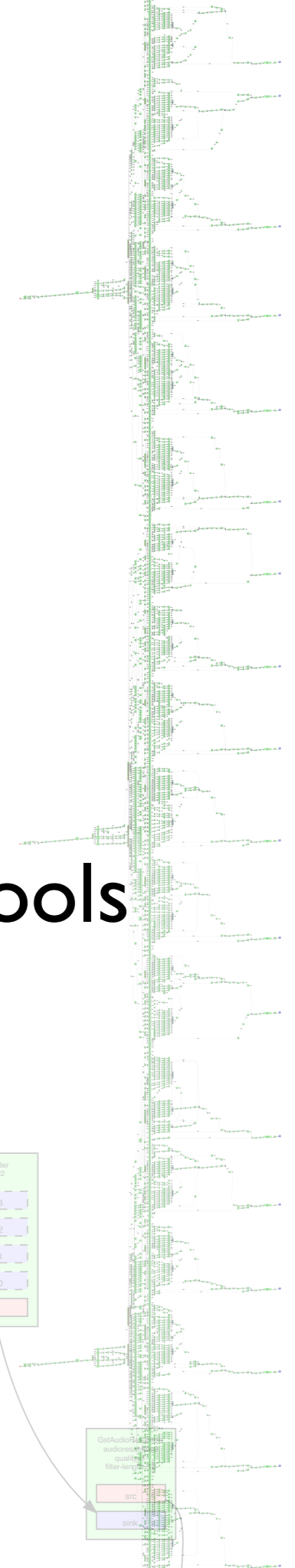
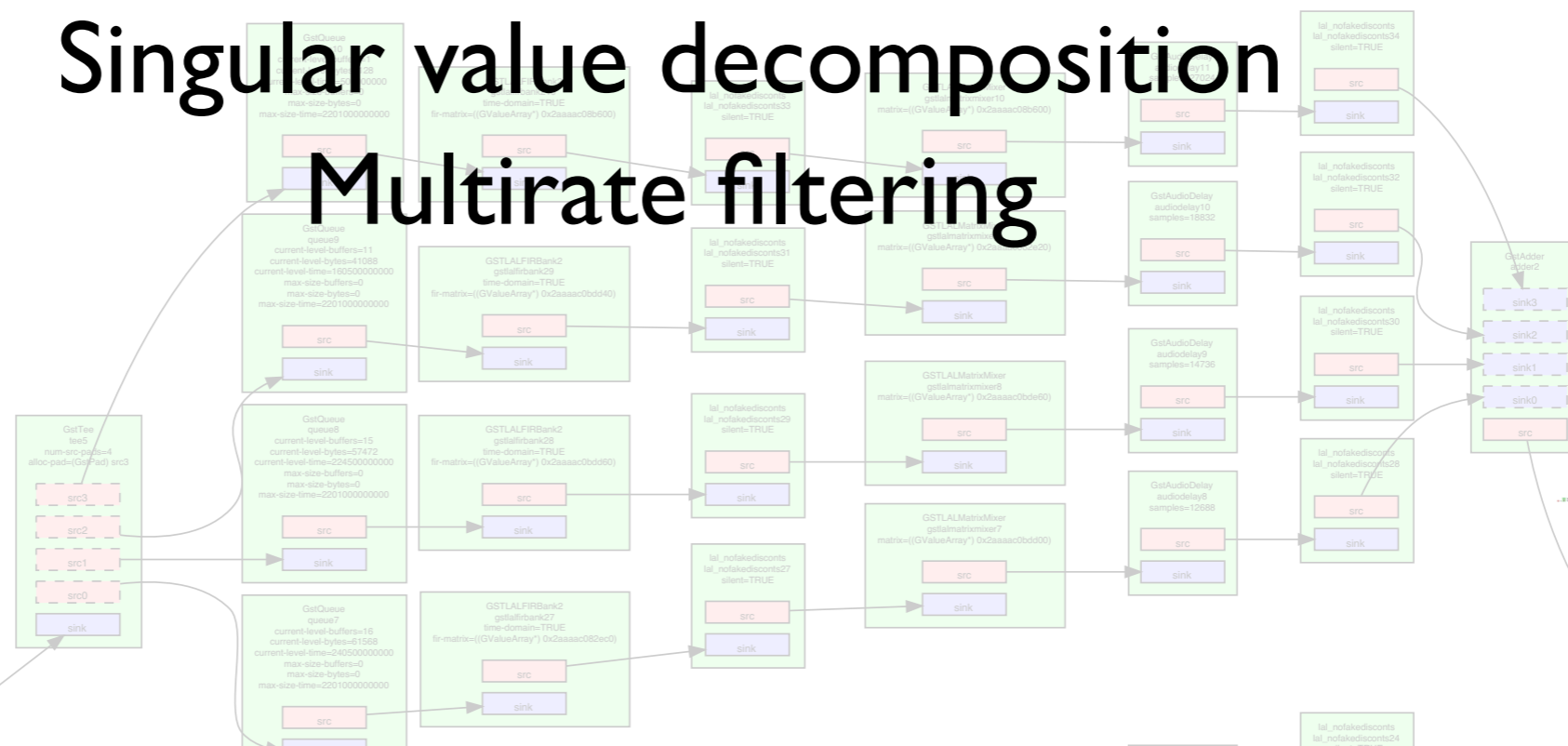
online inspiral detection engine powered by



Built from “off the shelf” open-source DSP tools

Singular value decomposition

Multirate filtering



GstLAL:

online inspiral detection engine powered by

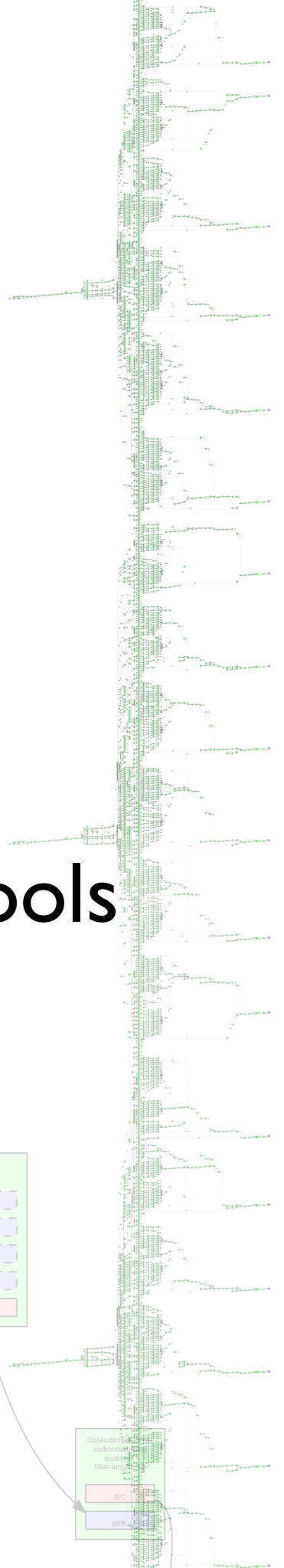
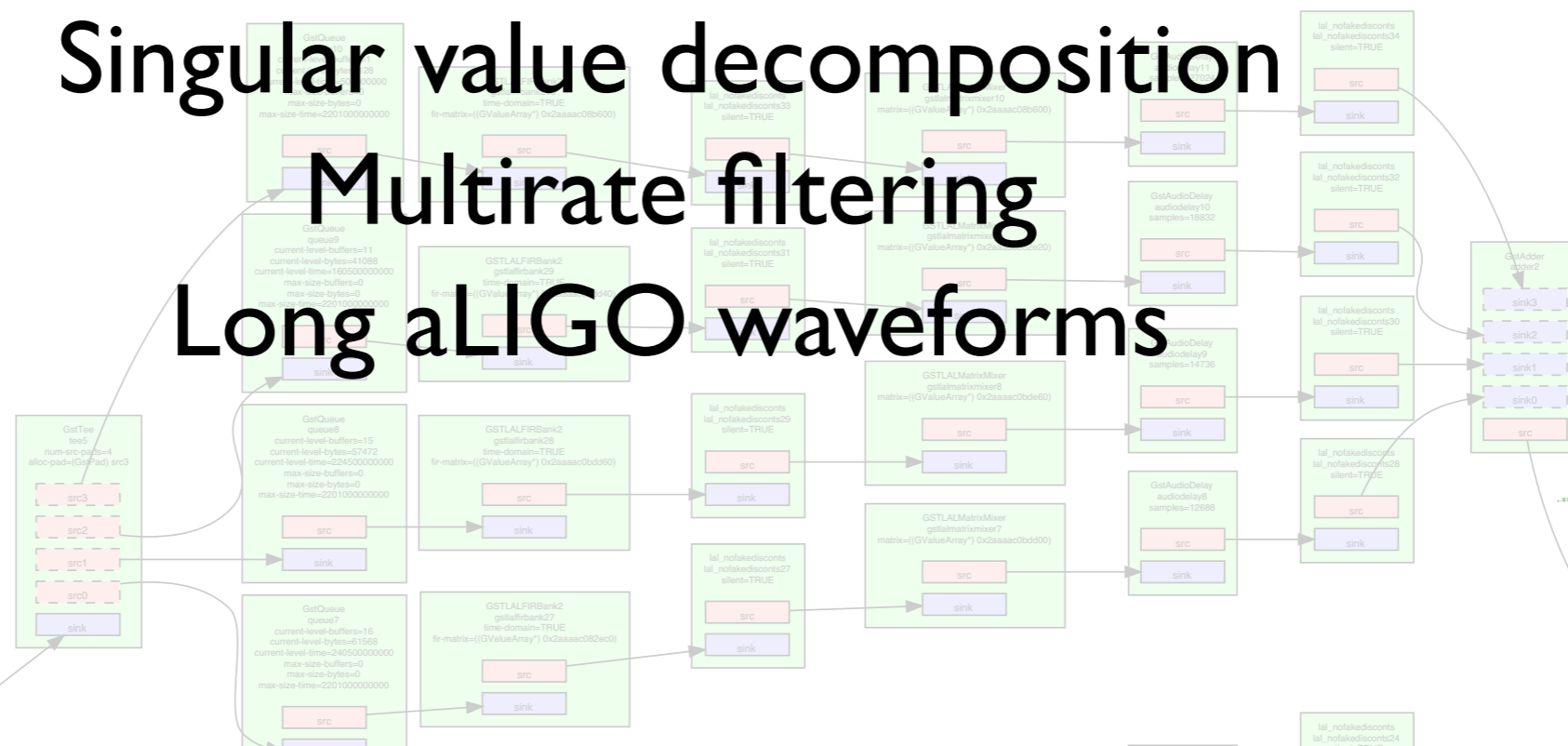


Built from “off the shelf” open-source DSP tools

Singular value decomposition

Multirate filtering

Long aLIGO waveforms



GstLAL:

online inspiral detection engine powered by



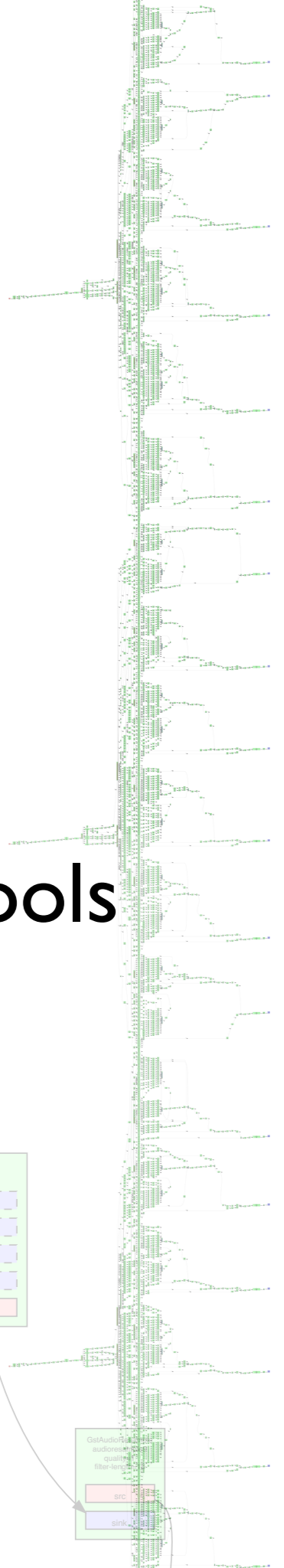
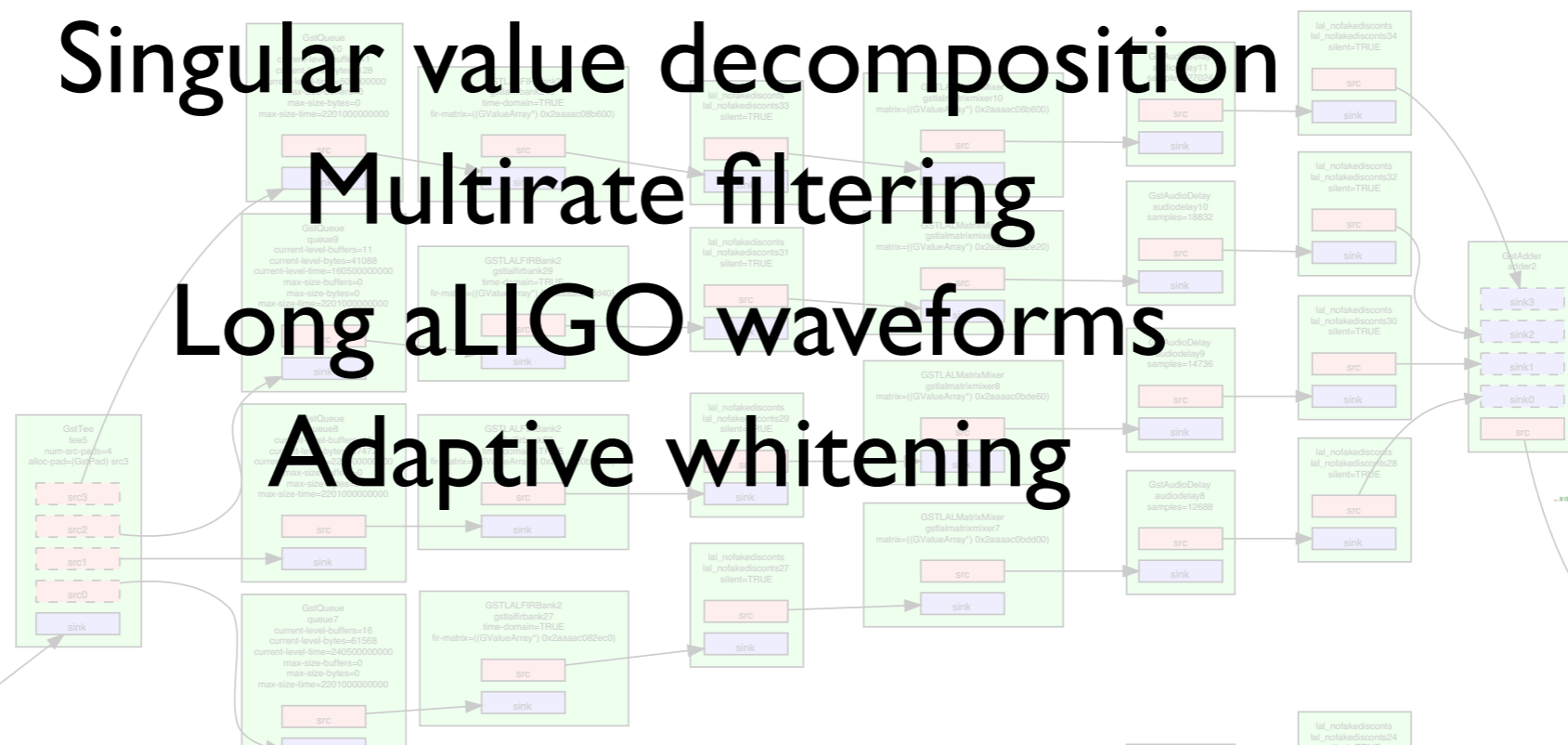
Built from “off the shelf” open-source DSP tools

Singular value decomposition

Multirate filtering

Long aLIGO waveforms

Adaptive whitening



GstLAL:

online inspiral detection engine powered by



Built from “off the shelf” open-source DSP tools

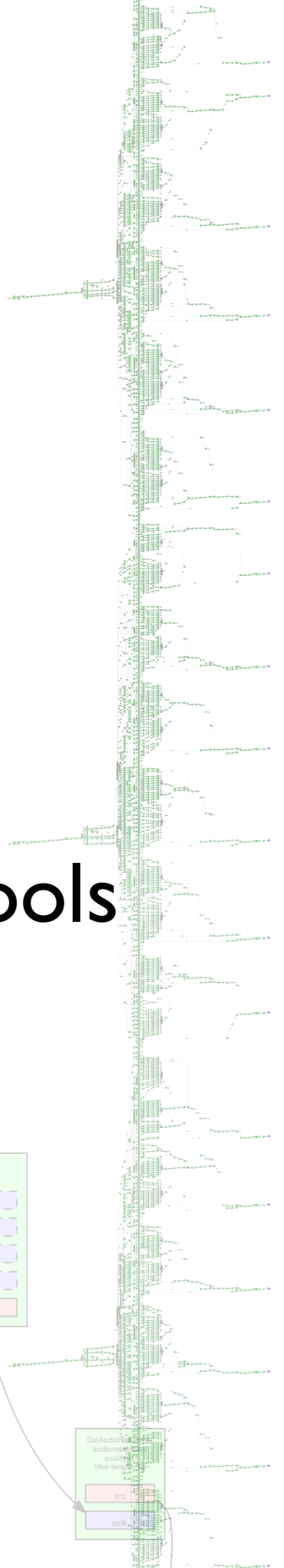
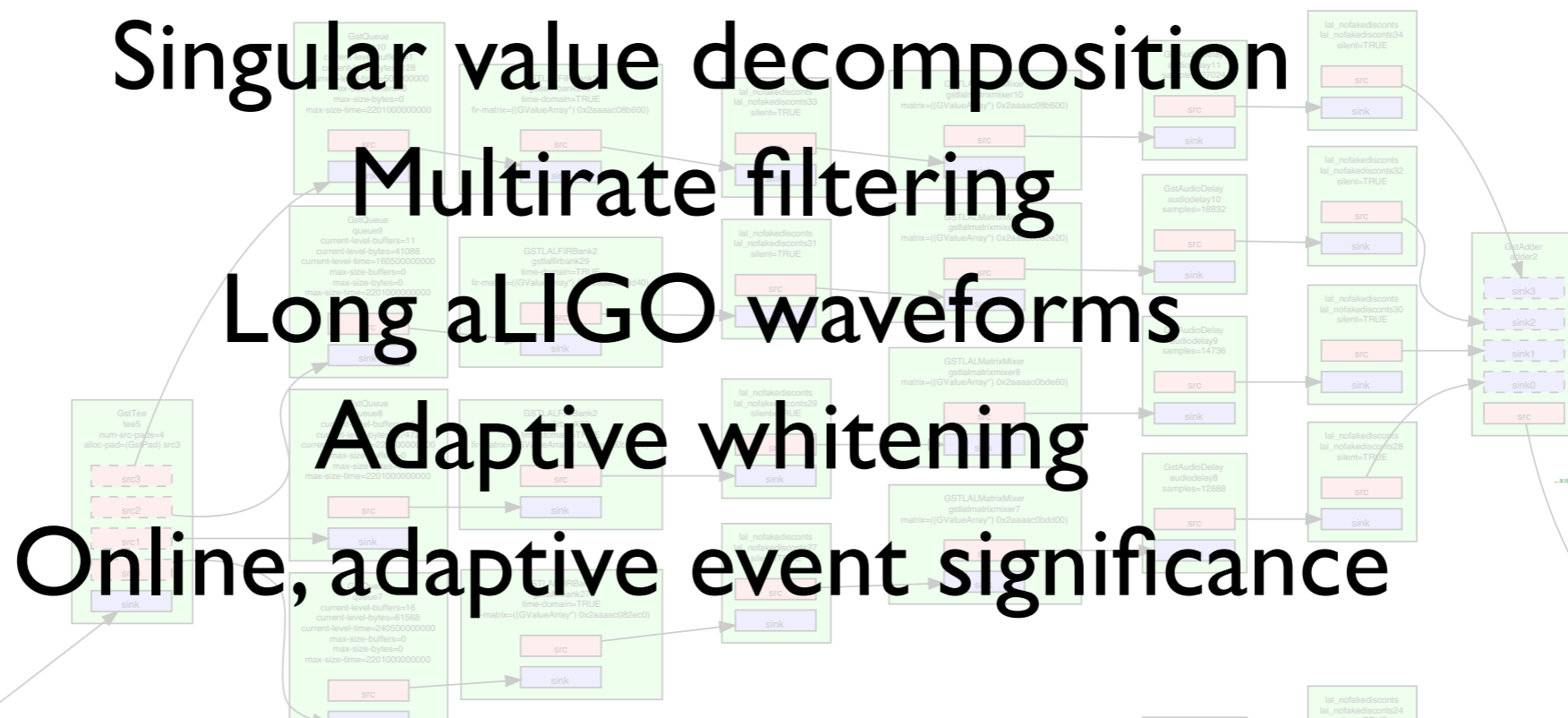
Singular value decomposition

Multirate filtering

Long aLIGO waveforms

Adaptive whitening

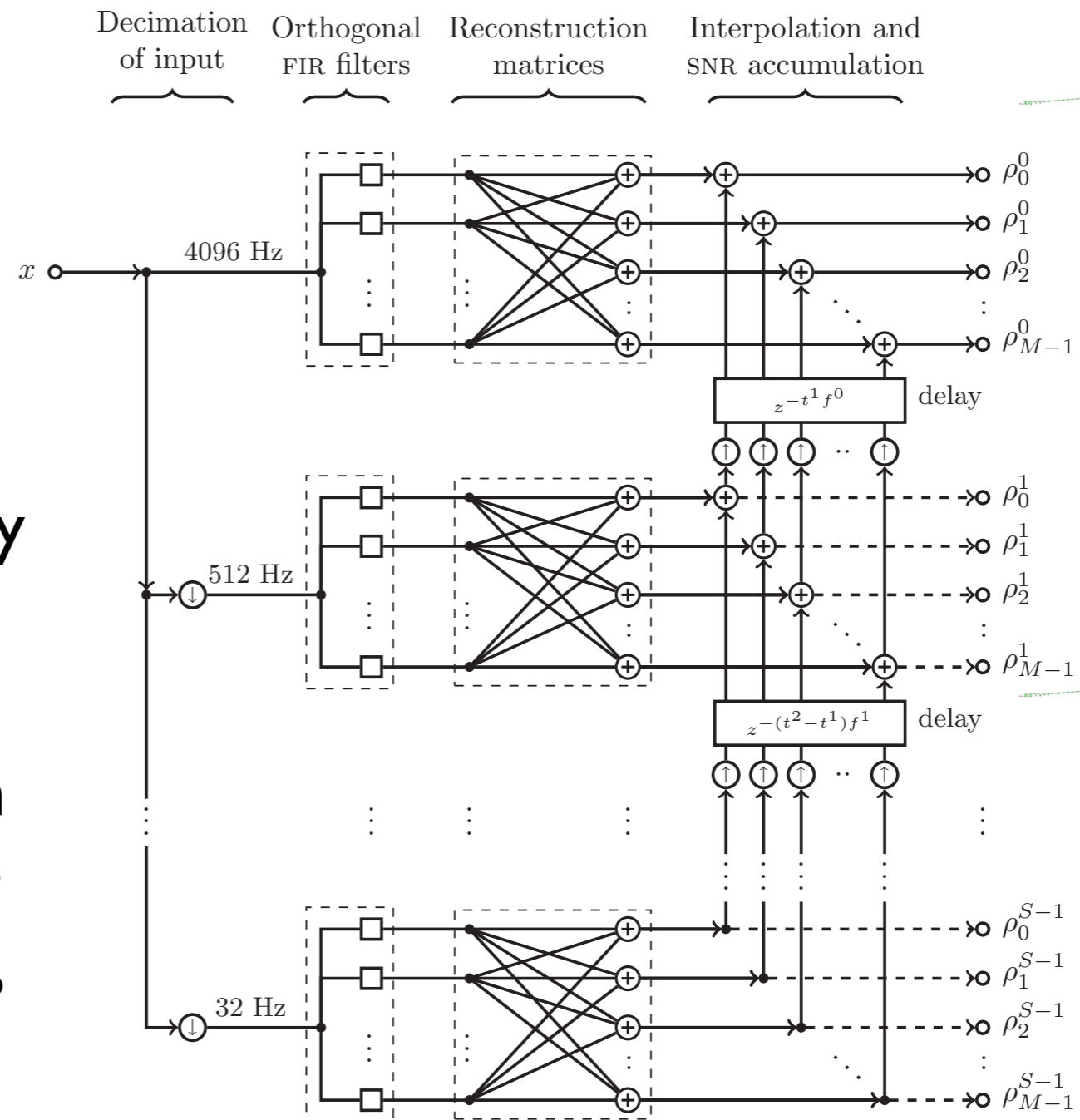
Online, adaptive event significance



GstLAL:

my contributions

- handle data gaps efficiently (particularly resampling)
- computational budget
- first complete description of algorithm for literature
- improve accuracy of time, SNR of triggers

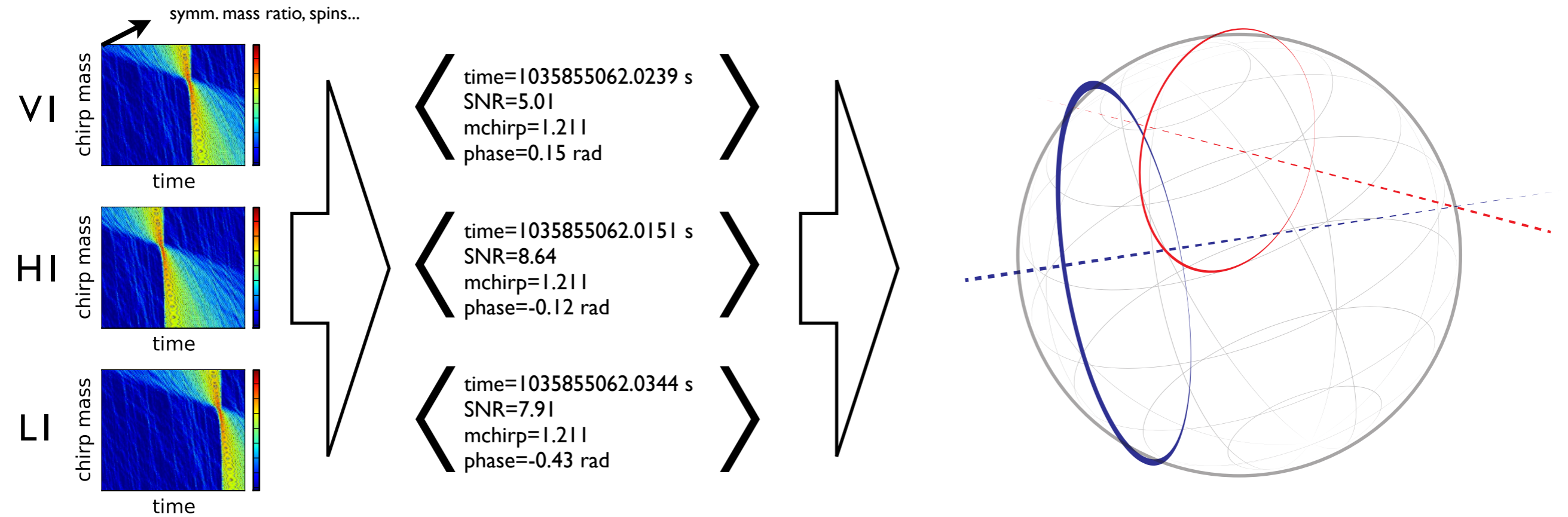


Toward early-warning detection of gravitational waves from compact binary coalescence

Cannon et al. (2012, ApJ 748:136)

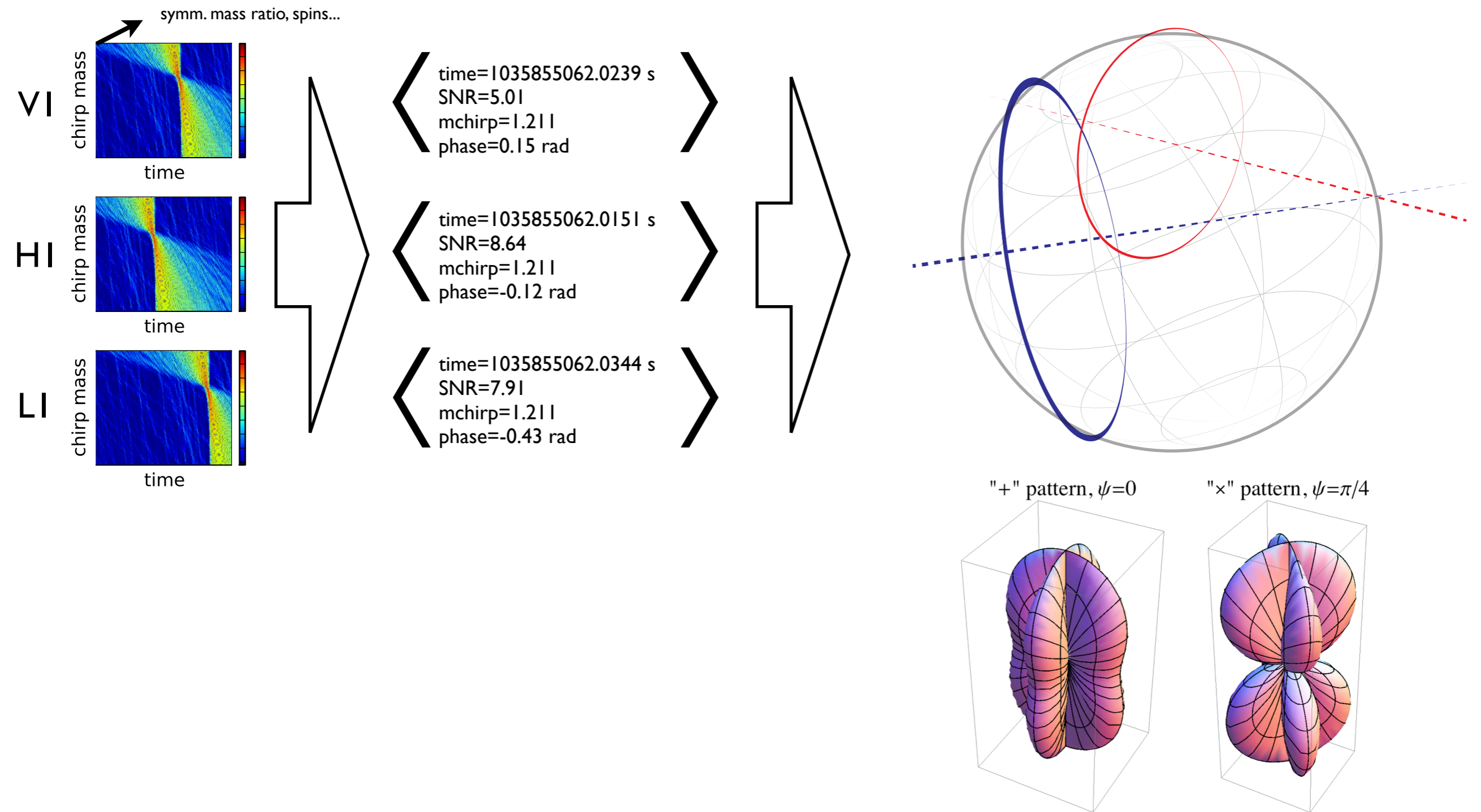
<http://dx.doi.org/10.1088/0004-637X/748/2/136>

Triangulation



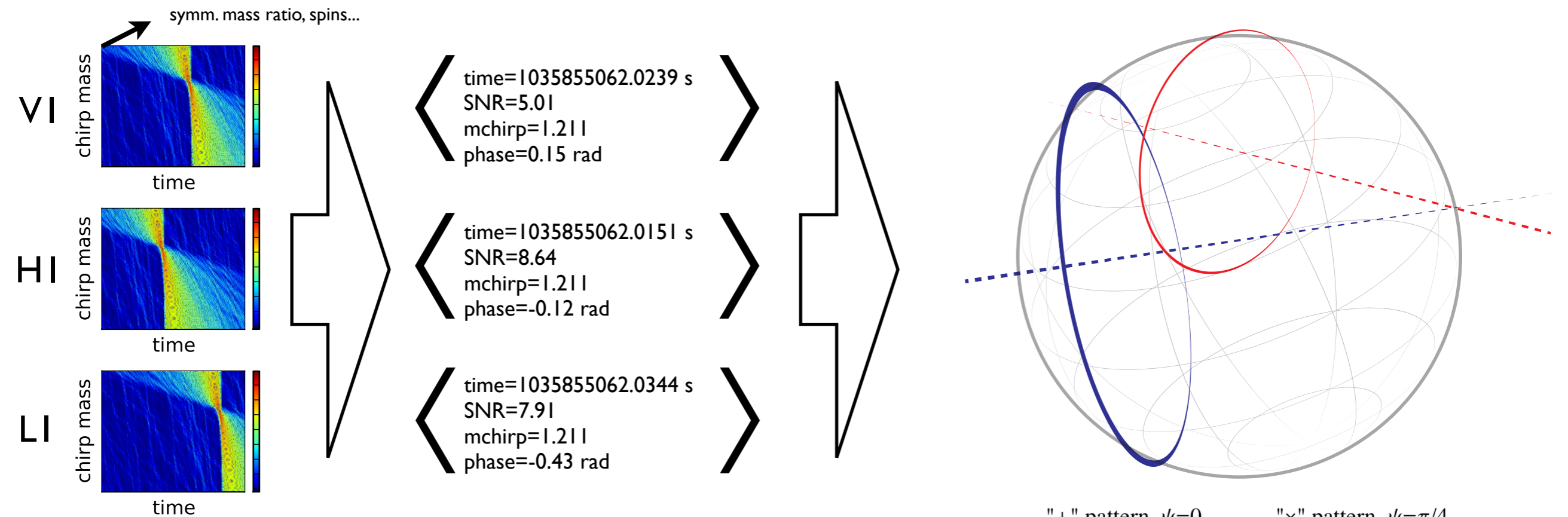
See also: Fairhurst, 2009, New J. Phys., 11, 123006),
Fairhurst, 2011, Class. Quantum Grav., 28, 105021

Triangulation



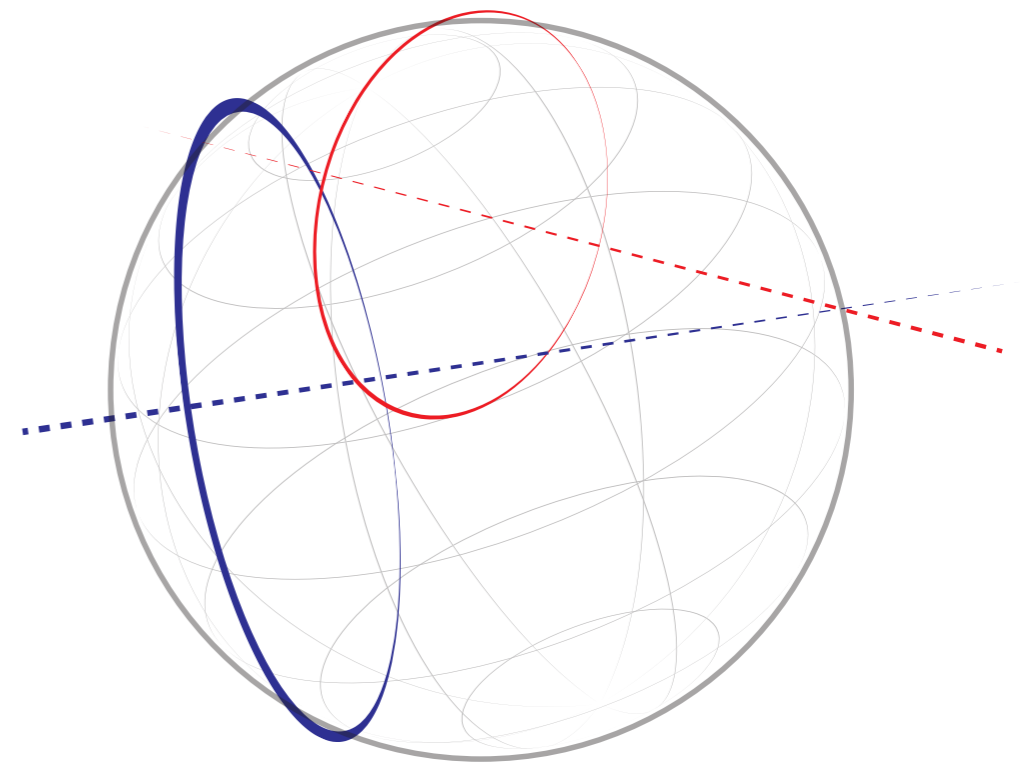
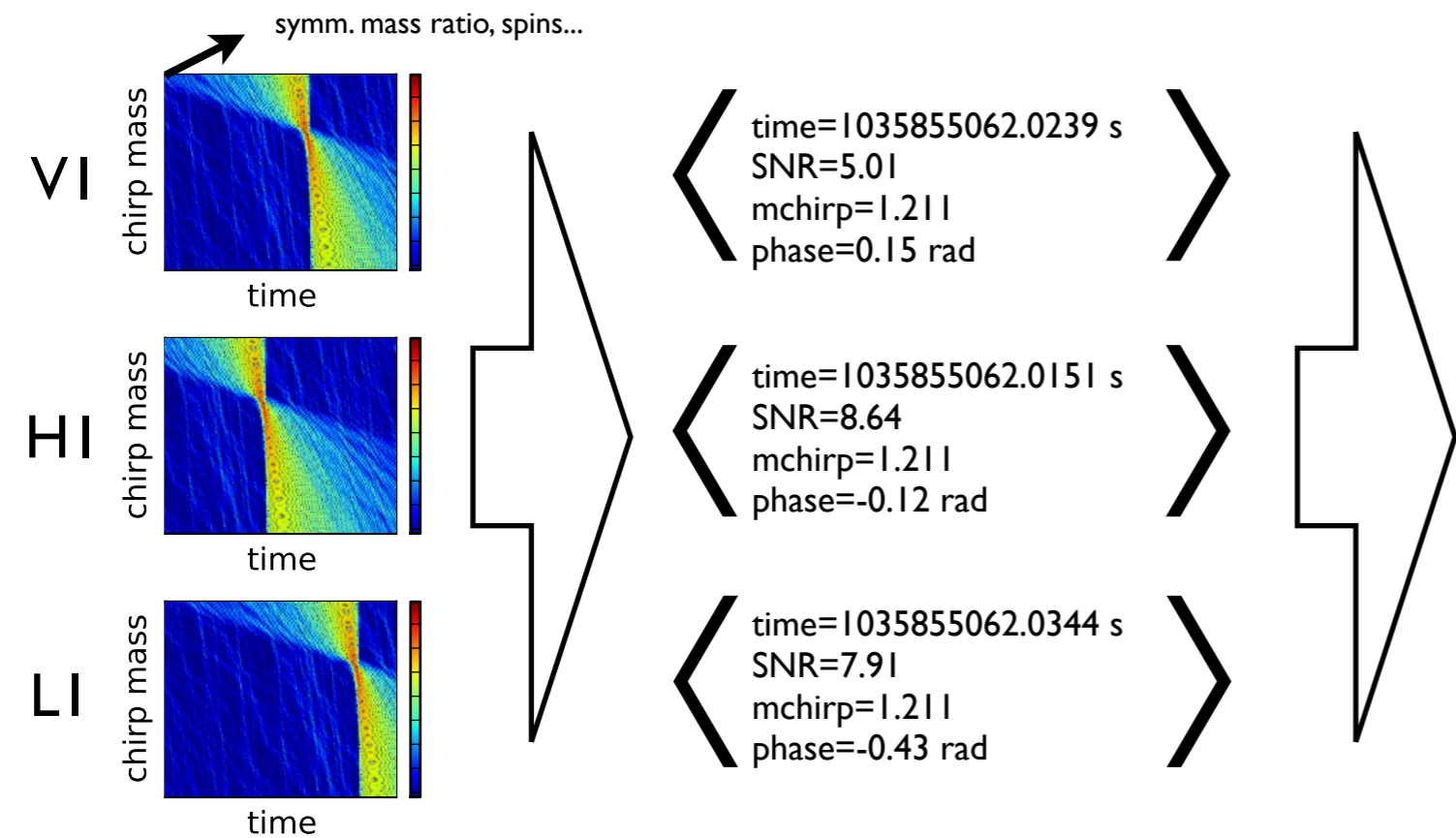
See also: Fairhurst, 2009, New J. Phys., 11, 123006),
Fairhurst, 2011, Class. Quantum Grav., 28, 105021

Triangulation



- Time delays & relative amplitudes \Rightarrow inform sky location
- Triggers = point estimates
- Statistics of estimation error
- Very fast!

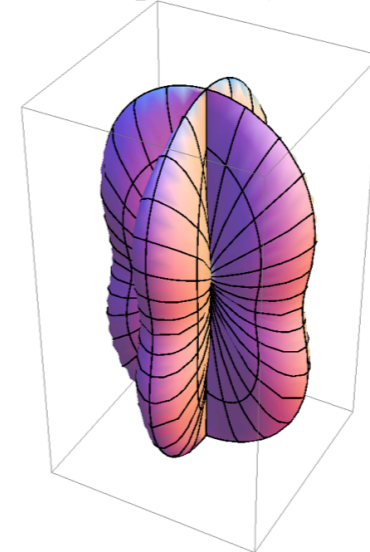
Triangulation



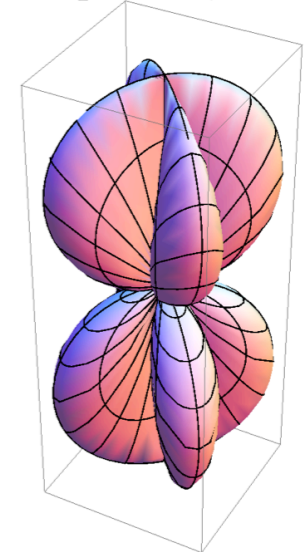
- Time delays & relative amplitudes
⇒ inform sky location

- Triggers = point estimates
- Statistics of estimation error
- Very fast!

"+" pattern, $\psi=0$

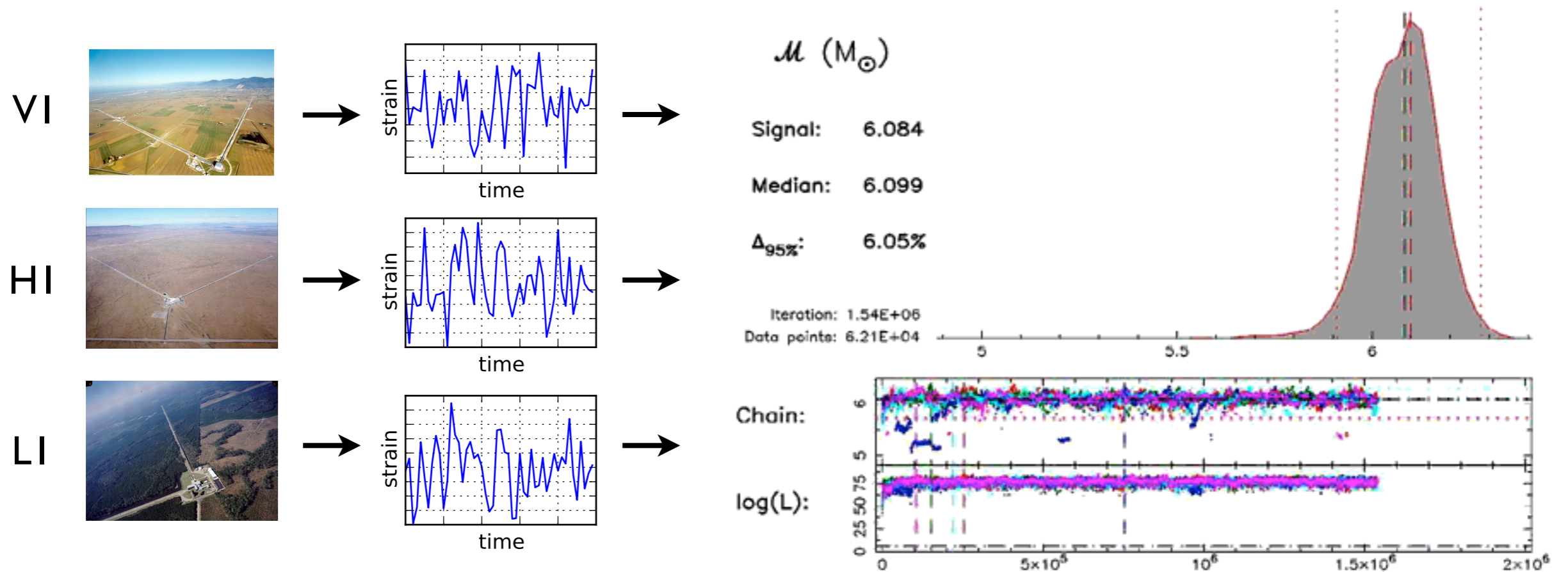


"x" pattern, $\psi=\pi/4$



See also: Fairhurst, 2009, New J. Phys., 11, 123006),
Fairhurst, 2011, Class. Quantum Grav., 28, 105021

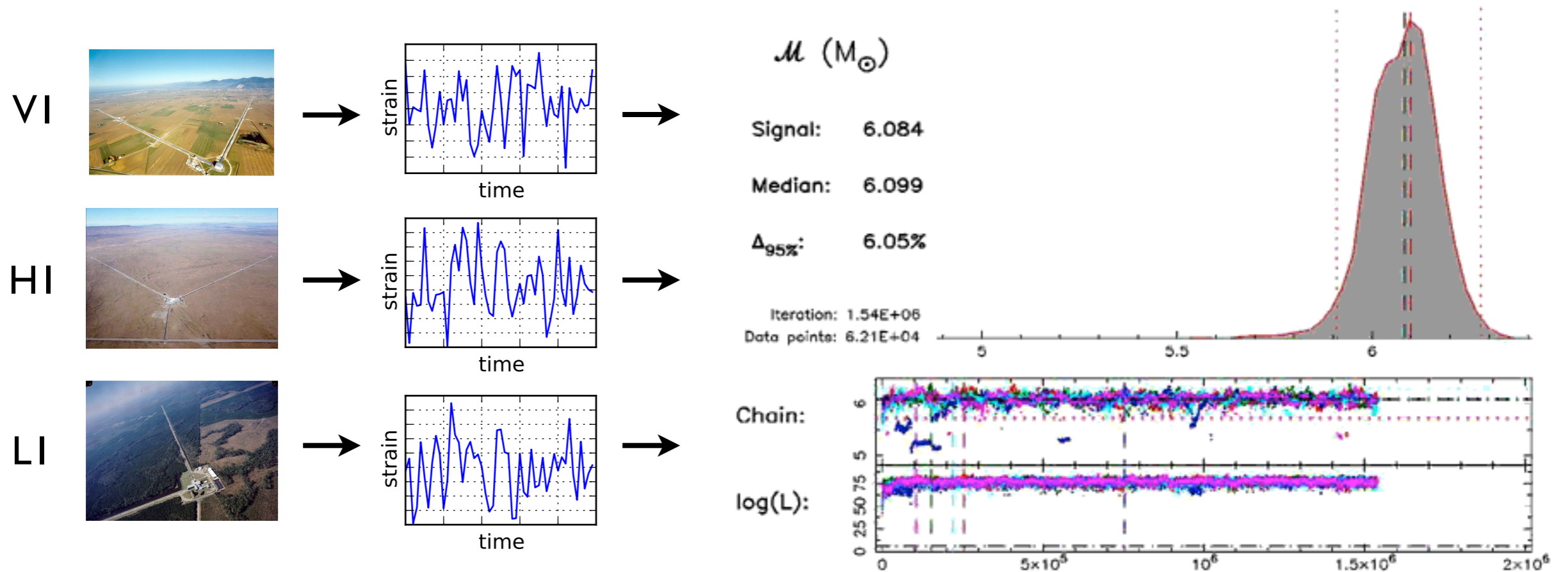
Bayesian Markov-chain Monte Carlo



Vivien Raymond, <<http://www.ligo.caltech.edu/~vraymond/>>

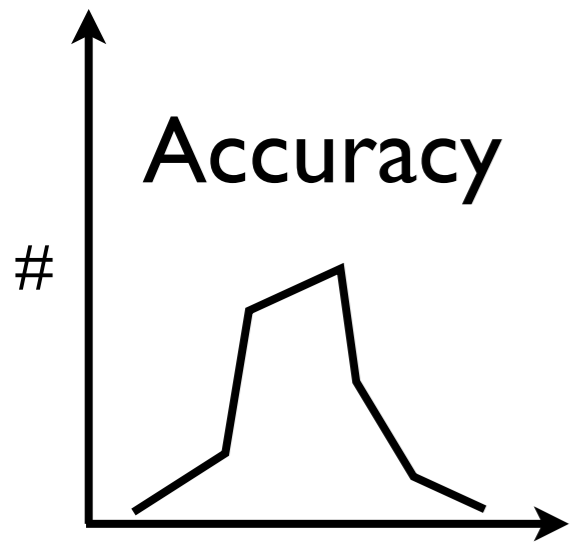
- Input: strain time series from all detectors
- Stochastically sample from parameter space, compute overlap of signal with data in each detector
- Sample distribution converges to posterior
- Can be computationally expensive
- Takes hours to days, currently

Bayesian Markov-chain Monte Carlo

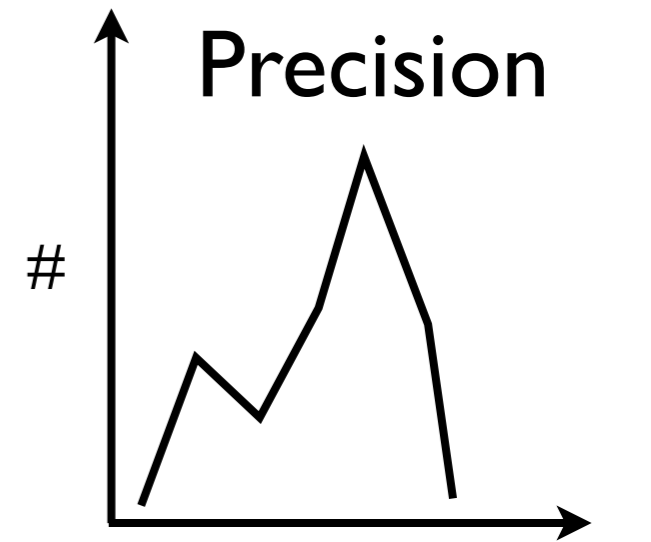


Vivien Raymond, <<http://www.ligo.caltech.edu/~vraymond/>>

- Input: strain time series from all detectors
- Stochastically sample from parameter space, compute overlap of signal with data in each detector
- Sample distribution converges to posterior
- Can be computationally expensive
- Takes hours to days, currently

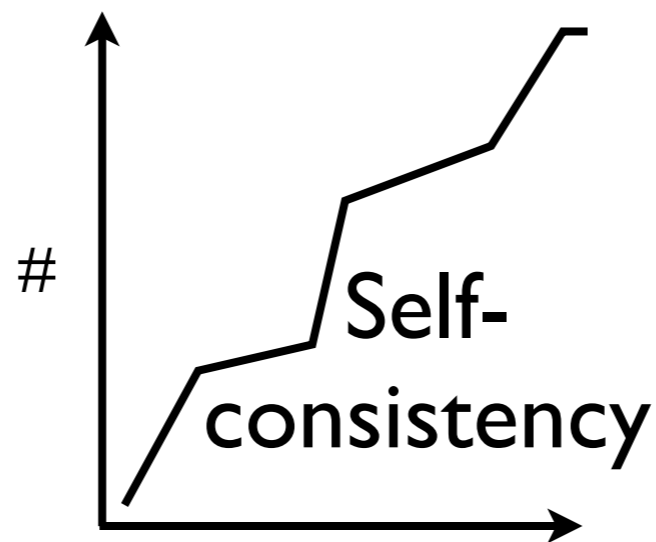
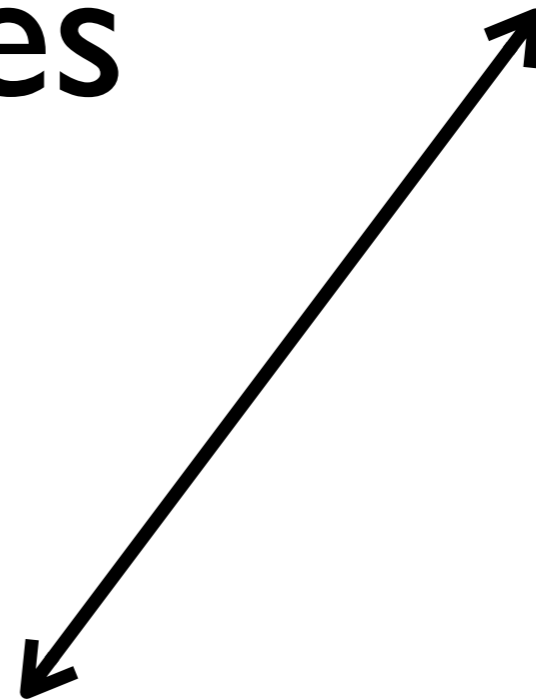
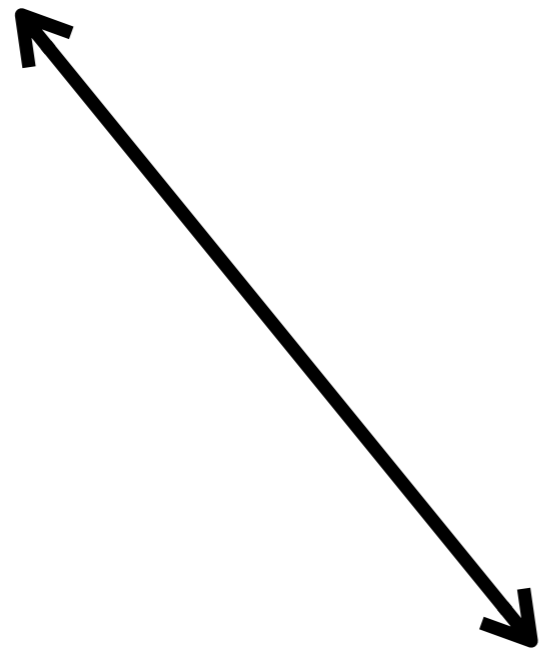


angle between true location and best estimate



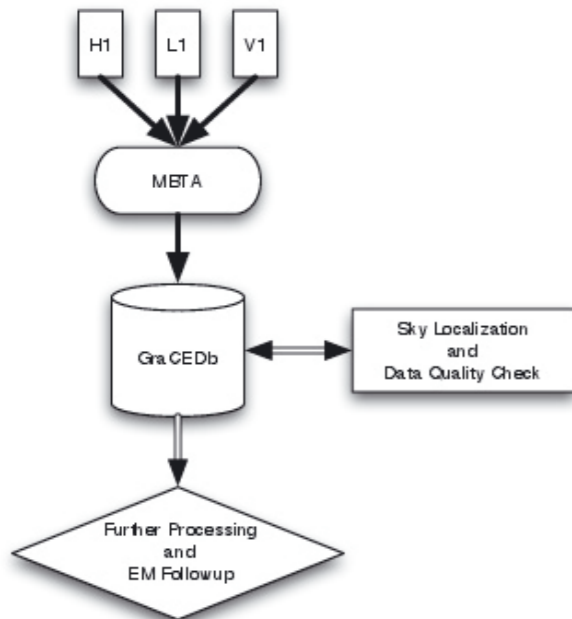
area of 90% contour

Parameter estimation:
The 3 figures of merit

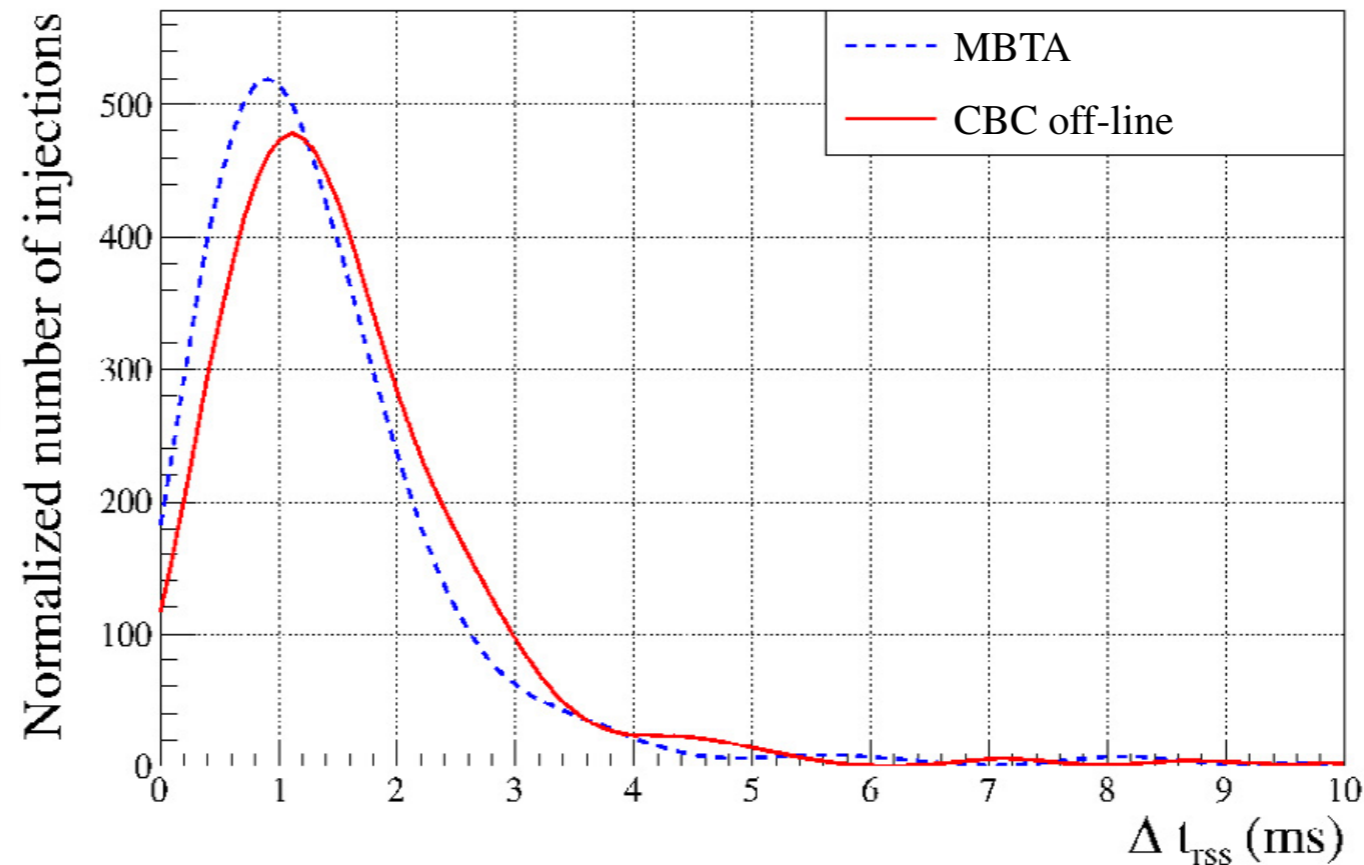


posterior probability contour containing true location

Rapid sky localization in last science run: S6/VSR3

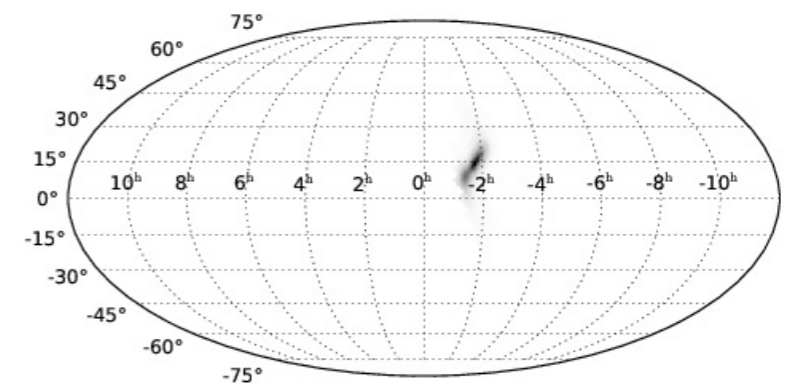


Low latency
detection
candidates
from MBTA

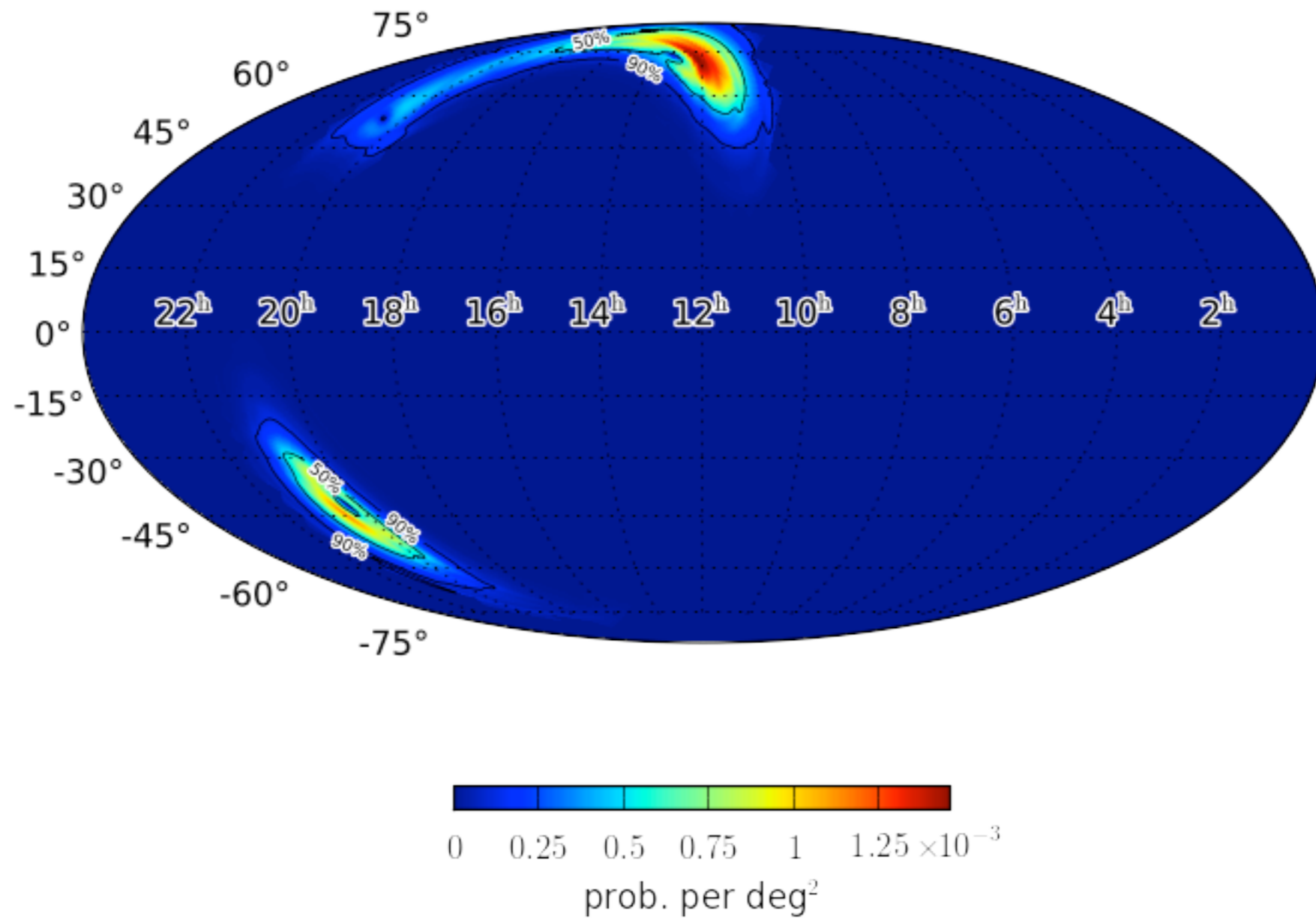


Empirical distribution
of timing accuracy from
pipeline

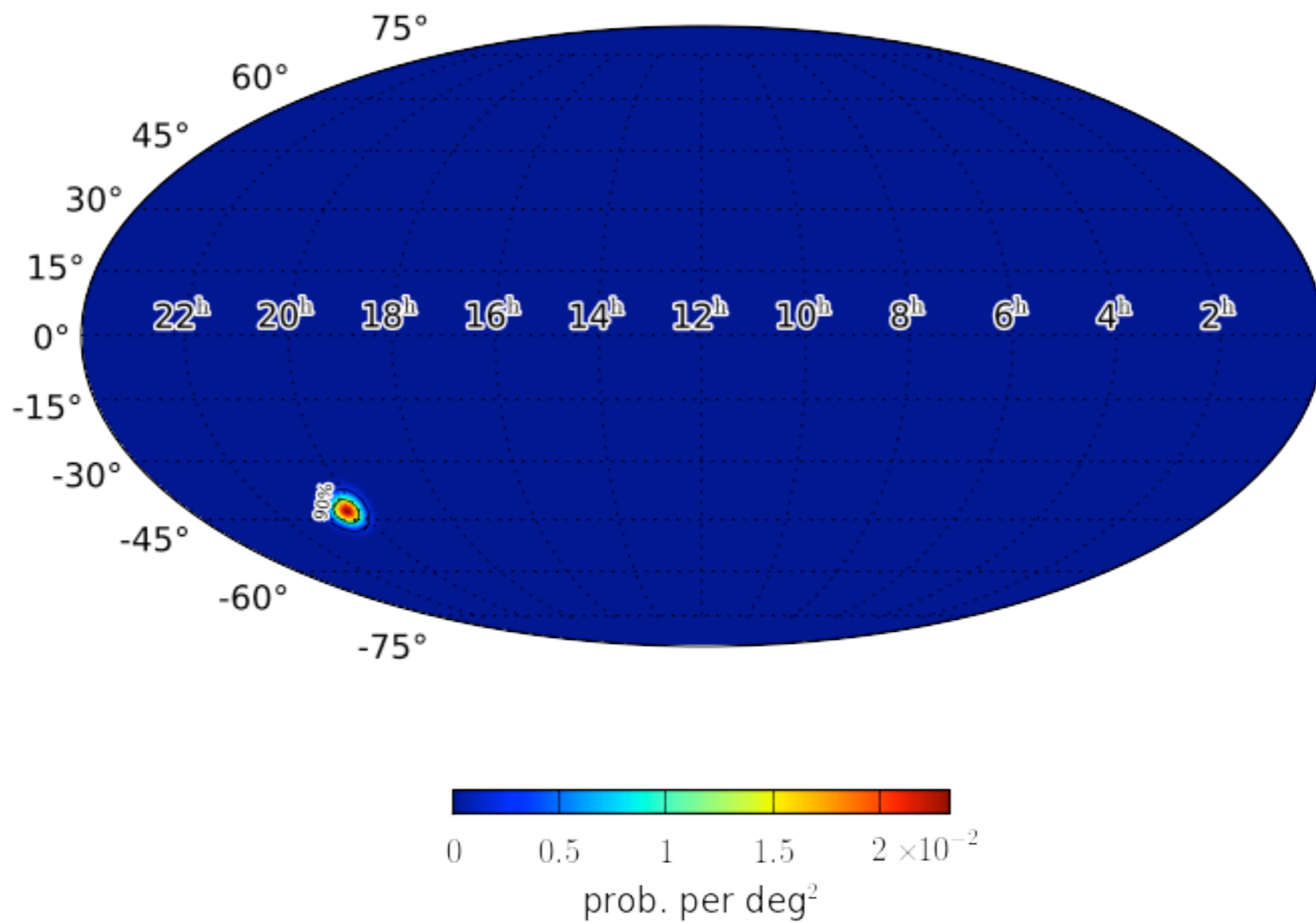
Alerts sent to
astronomers!



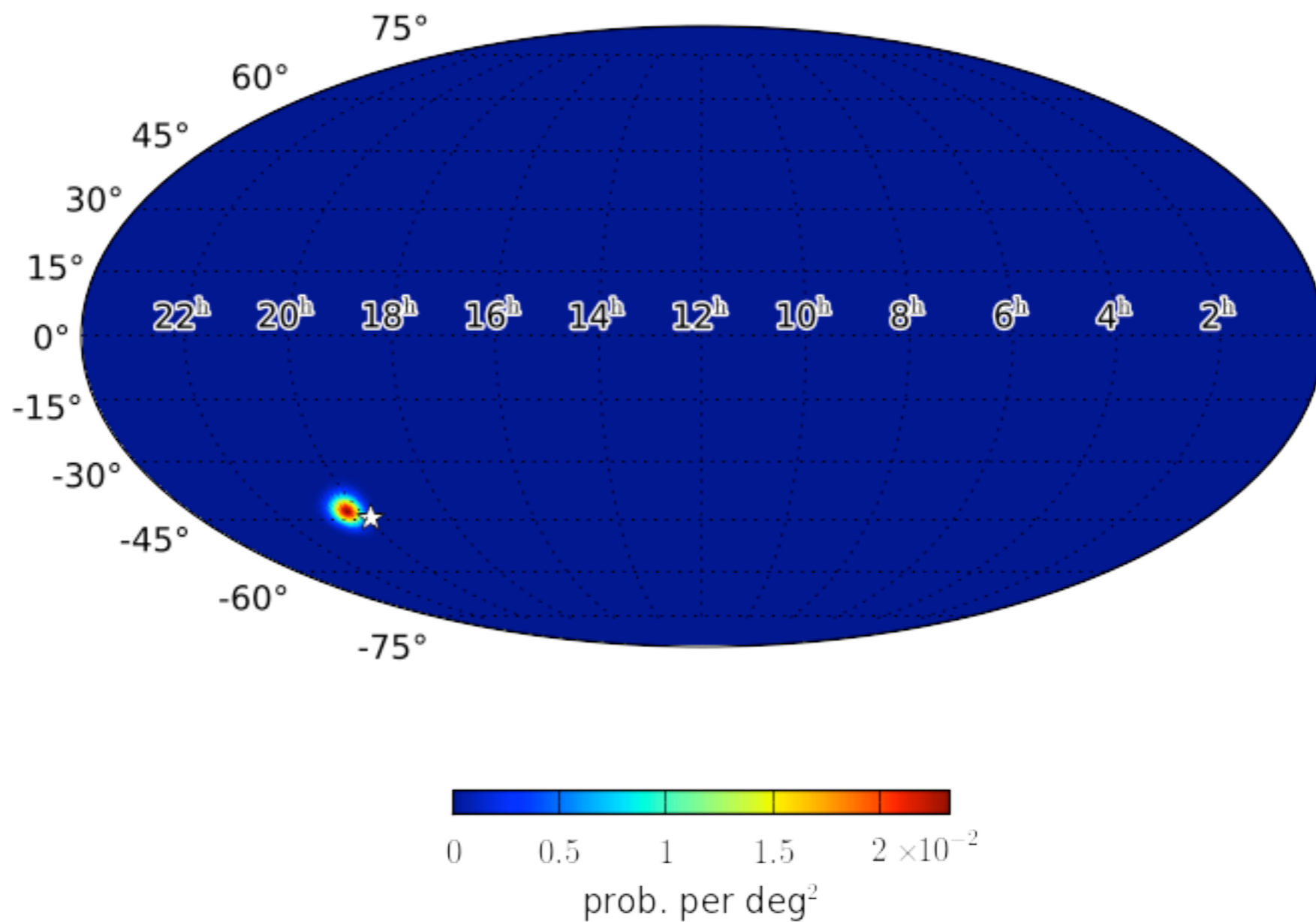
G7103 I: ER3 gstlal event, **before**



G7103 I: ER3 gstlal event, *after*



G7103 I: ER3 gstlal event, *after*



Idea: Use point estimates triggers, but *start from Bayes' theorem*
Then hold to same *self-consistency*
standards as full MCMC

Idea: Use point estimates triggers, but *start from Bayes' theorem*
**Then hold to same *self-consistency*
*standards as full MCMC***



image credit:

[http://www.scenicreflections.com/files/GRB
%20Wallpaper__yvt2.jpg](http://www.scenicreflections.com/files/GRB%20Wallpaper__yvt2.jpg)

Idea: Use point estimates triggers, but *start from Bayes' theorem*
**Then hold to same *self-consistency*
*standards as full MCMC***

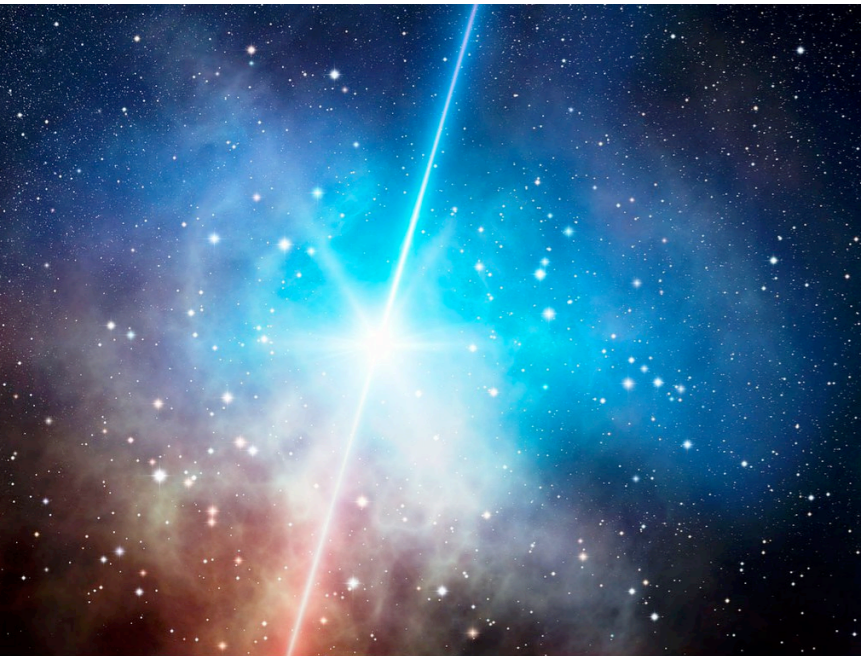


image credit:

[http://www.scenicreflections.com/files/GRB
%20Wallpaper__yvt2.jpg](http://www.scenicreflections.com/files/GRB%20Wallpaper__yvt2.jpg)

Idea: Use point estimates triggers, but *start from Bayes' theorem*
**Then hold to same *self-consistency*
*standards as full MCMC***



image credit:
[http://www.scenicreflections.com/files/GRB
%20Wallpaper__yvt2.jpg](http://www.scenicreflections.com/files/GRB%20Wallpaper__yvt2.jpg)



image credit: [http://www.fanpop.com/clubs/battlestar-galactica/images/
10655496/title/battlestar-galactica-cylon-centurion-photo](http://www.fanpop.com/clubs/battlestar-galactica/images/10655496/title/battlestar-galactica-cylon-centurion-photo)

Idea: Use point estimates triggers, but *start from Bayes' theorem*
**Then hold to same *self-consistency*
*standards as full MCMC***



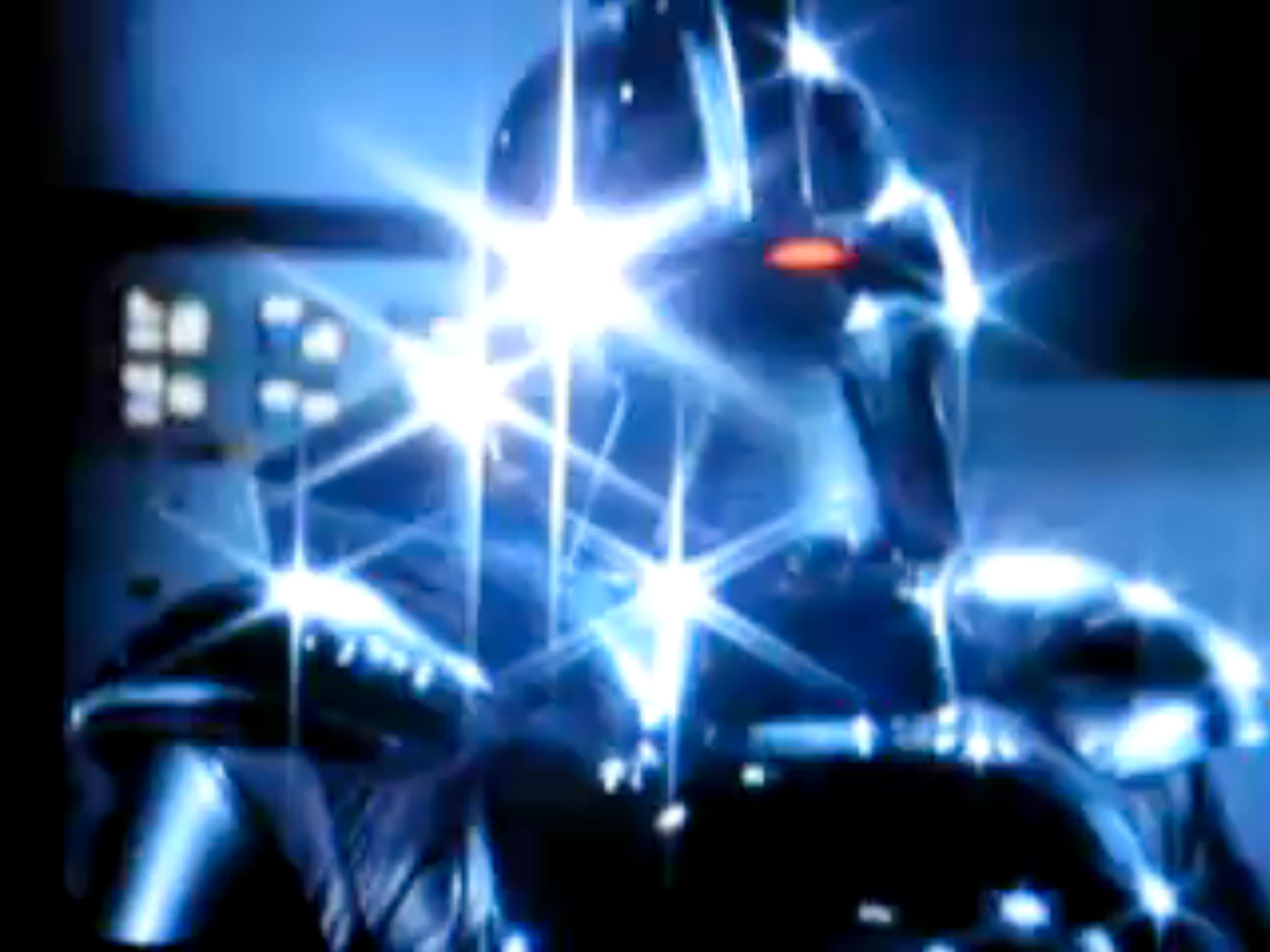
image credit:
[http://www.scenicreflections.com/files/GRB
%20Wallpaper__yvt2.jpg](http://www.scenicreflections.com/files/GRB%20Wallpaper__yvt2.jpg)



image credit: [http://www.fanpop.com/clubs/battlestar-galactica/images/
10655496/title/battlestar-galactica-cylon-centurion-photo](http://www.fanpop.com/clubs/battlestar-galactica/images/10655496/title/battlestar-galactica-cylon-centurion-photo)

thus was born...

BAYESTAR



Bayes' Rule

- Take some data, X , and form a hypothesis, Θ . How probable is your hypothesis, given the data?

$$P(\Theta|X) = \frac{\overset{\text{“likelihood”}}{P(X|\Theta)} \times \overset{\text{“prior”}}{P(\Theta)}}{\underset{\text{“evidence”}}{P(X)}}$$

- Marginalize to get rid of nuisance parameters

$$P(\Theta, \lambda|X) = \frac{\sum_{\lambda} P(X|\Theta, \lambda)P(\Theta, \lambda)}{P(X)}$$

-

Or, if hypothesis is continuously parameterized,

$$p(\theta|x) = \frac{\int p(x|\theta, \lambda)p(\theta, \lambda)d\lambda}{p(x)}$$



REV. T. BAYES

Problem setup: data, parameters

Data/observation

strain time series $x_i(t_j)$ } N detectors
 M samples

amplitude, SNR ρ_i , τ_i , ~~phase γ_i~~ } N detectors
 TOA note: not using phase right now

Nuisance variables

component masses m_1, m_2 , spins $\mathbf{S}_1, \mathbf{S}_2$

intrinsic variables (fixed at maximum-likelihood estimates for triangulation)

luminosity distance D_L , polarization angle ψ , ϕ_c
 TOA at geocenter τ_{\oplus} , inclination ι , coalescence phase

extrinsic variables

Parameters of interest

direction of source \mathbf{n}

e.g.,

right ascension, declination α, δ

Outline of calculation

Likelihood: factor into a time of arrival (TOA)-only contribution and an SNR-only contribution, both Gaussian

$$\mathcal{L} \propto \mathcal{L}_{\text{SNR}} \times \mathcal{L}_{\text{TOA}}$$

Prior: uniform in

$$\tau_{\oplus}, \phi_c, \psi, \cos \iota, D_L^3$$

Posterior: factor into an TOA-only contribution and an SNR-only contribution

$$\begin{aligned} & p(\mathbf{n} | \hat{\tau}_1, \dots, \hat{\tau}_N, \hat{\rho}_1, \dots, \hat{\rho}_N) \\ = & f_{\text{TOA}}(\mathbf{n} | \hat{\tau}_1, \dots, \hat{\tau}_N) \times f_{\text{SNR}}(\mathbf{n} | \hat{\rho}_1, \dots, \hat{\rho}_N) \end{aligned}$$

Adaptive resolution

Evaluate **TOA** posterior **first**, then evaluate **SNR** posterior for those points that comprise the **99.99th percentile** of the TOA posterior.

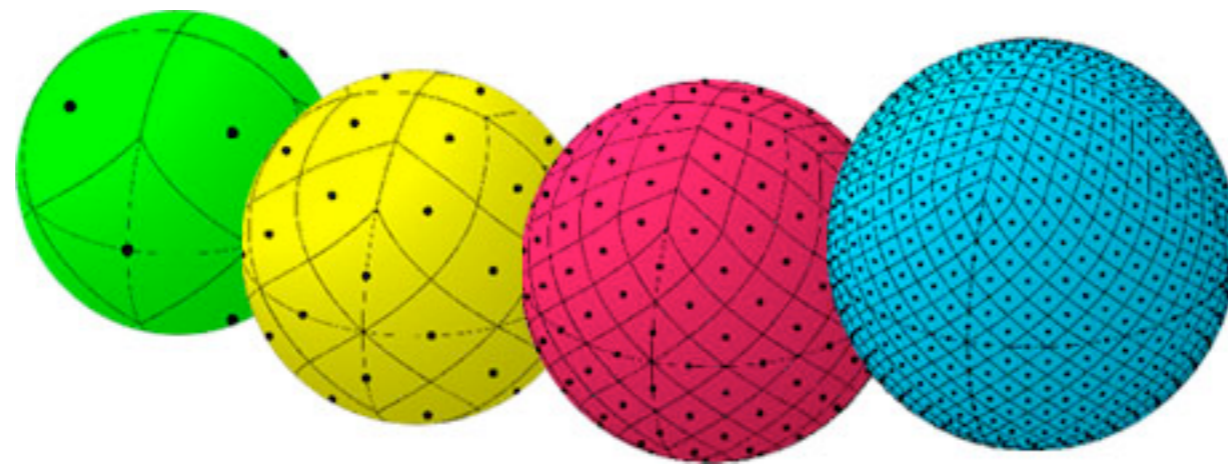
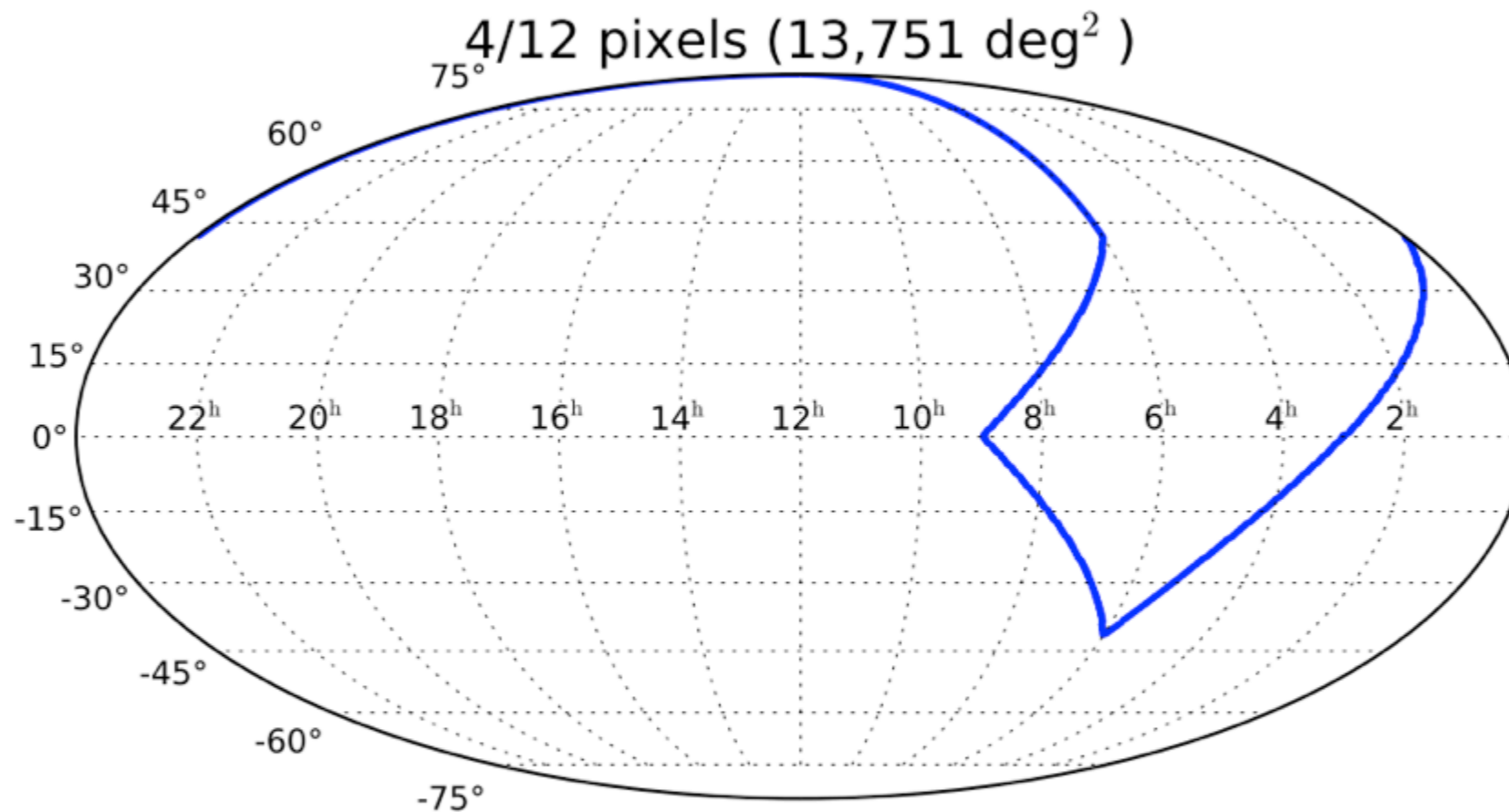


image: <http://healpix.jpl.nasa.gov>

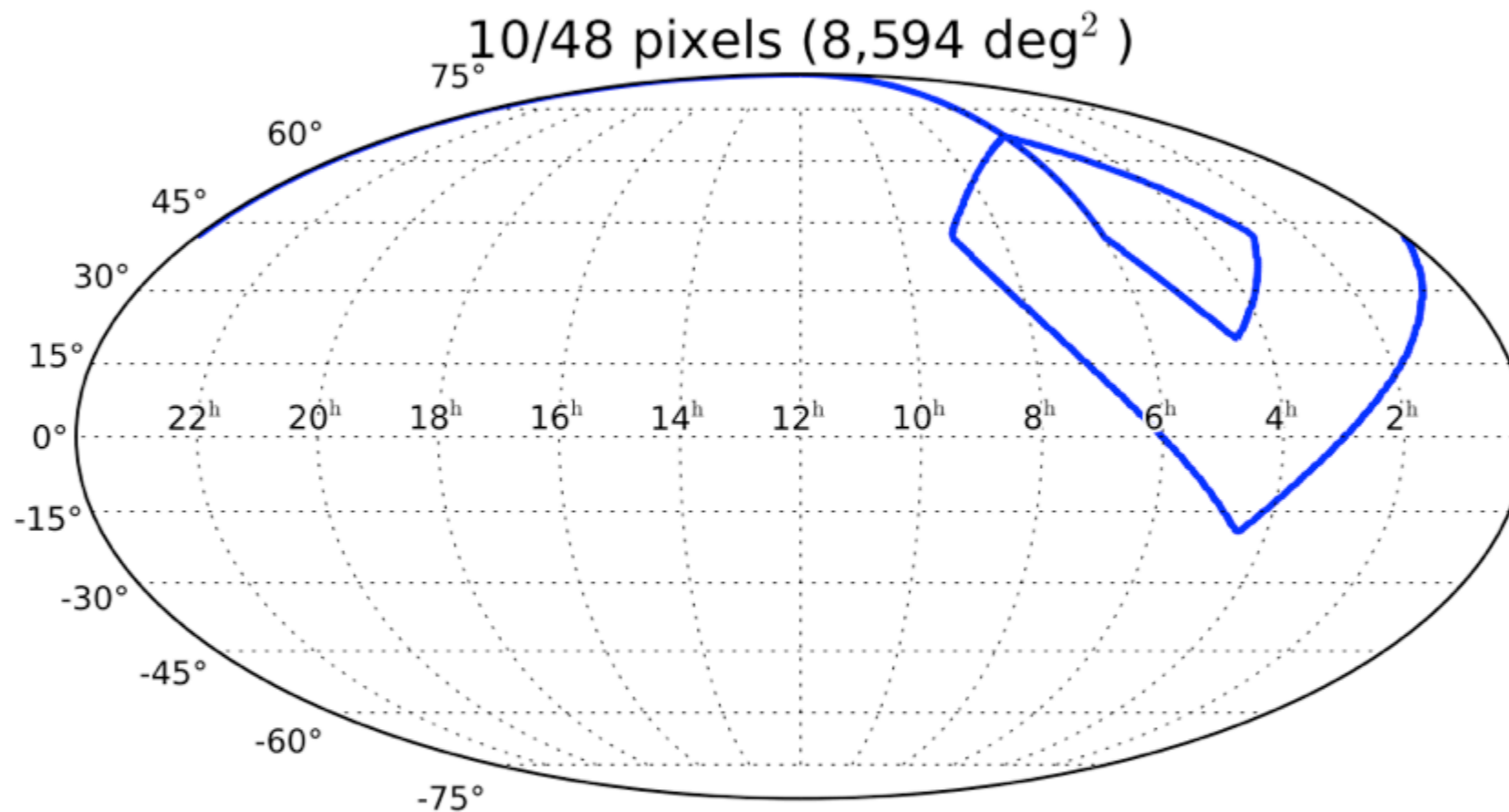
Adaptive resolution

Evaluate **TOA** posterior **first**, then evaluate **SNR** posterior for those points that comprise the **99.99th percentile** of the TOA posterior.



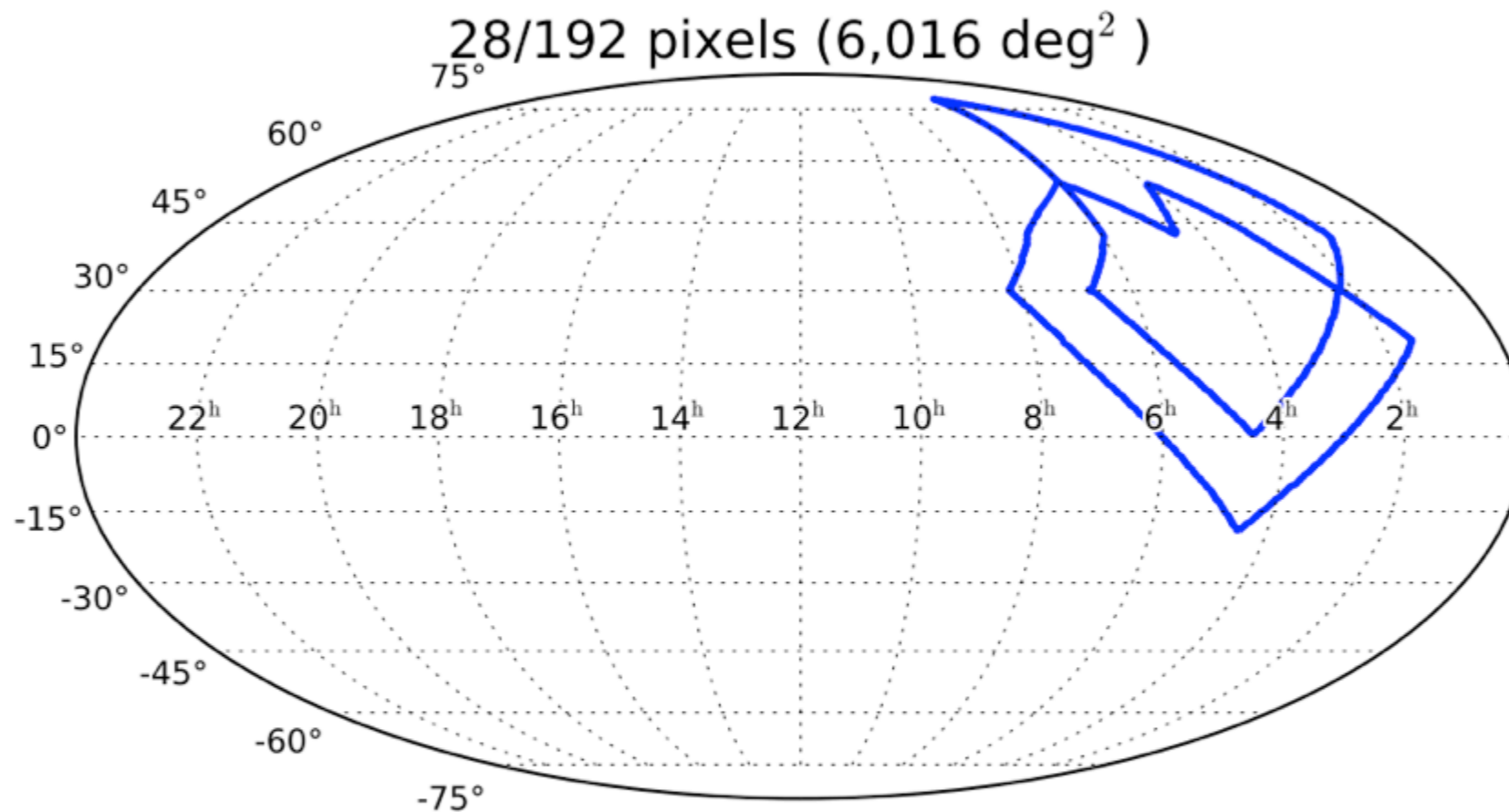
Adaptive resolution

Evaluate **TOA** posterior **first**, then evaluate **SNR** posterior for those points that comprise the **99.99th percentile** of the TOA posterior.



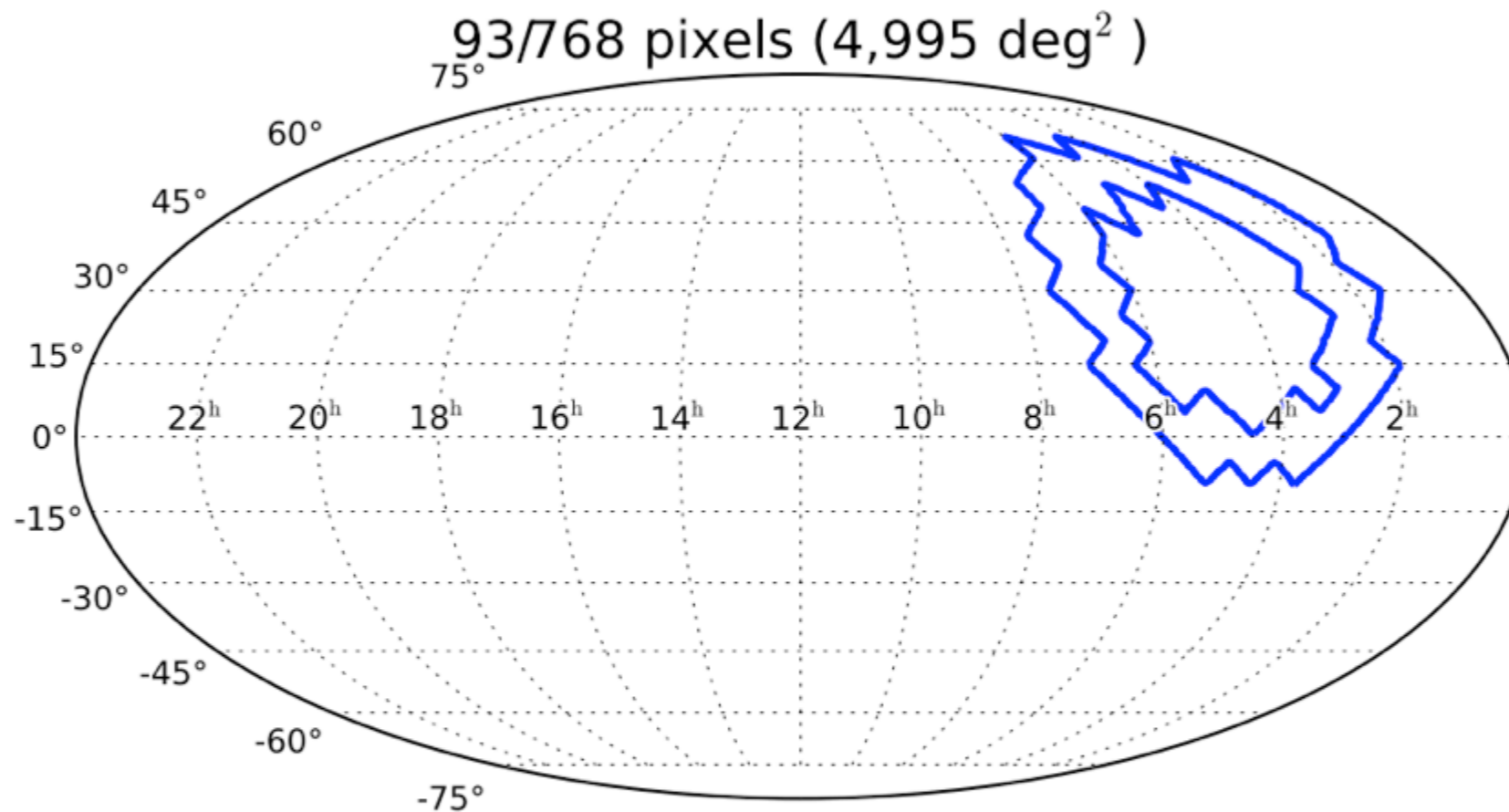
Adaptive resolution

Evaluate **TOA** posterior **first**, then evaluate **SNR** posterior for those points that comprise the **99.99th percentile** of the TOA posterior.



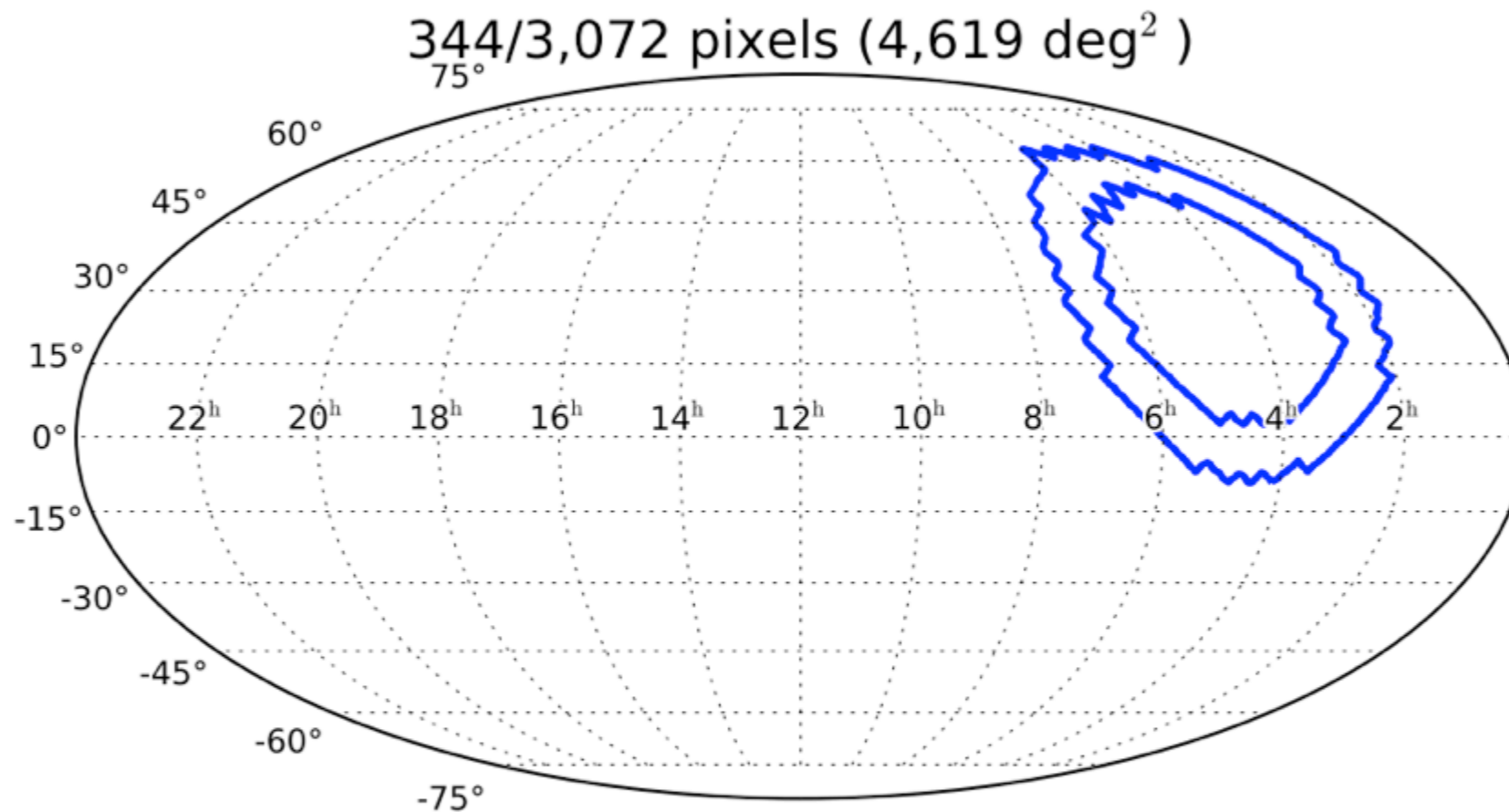
Adaptive resolution

Evaluate **TOA** posterior **first**, then evaluate **SNR** posterior for those points that comprise the **99.99th percentile** of the TOA posterior.



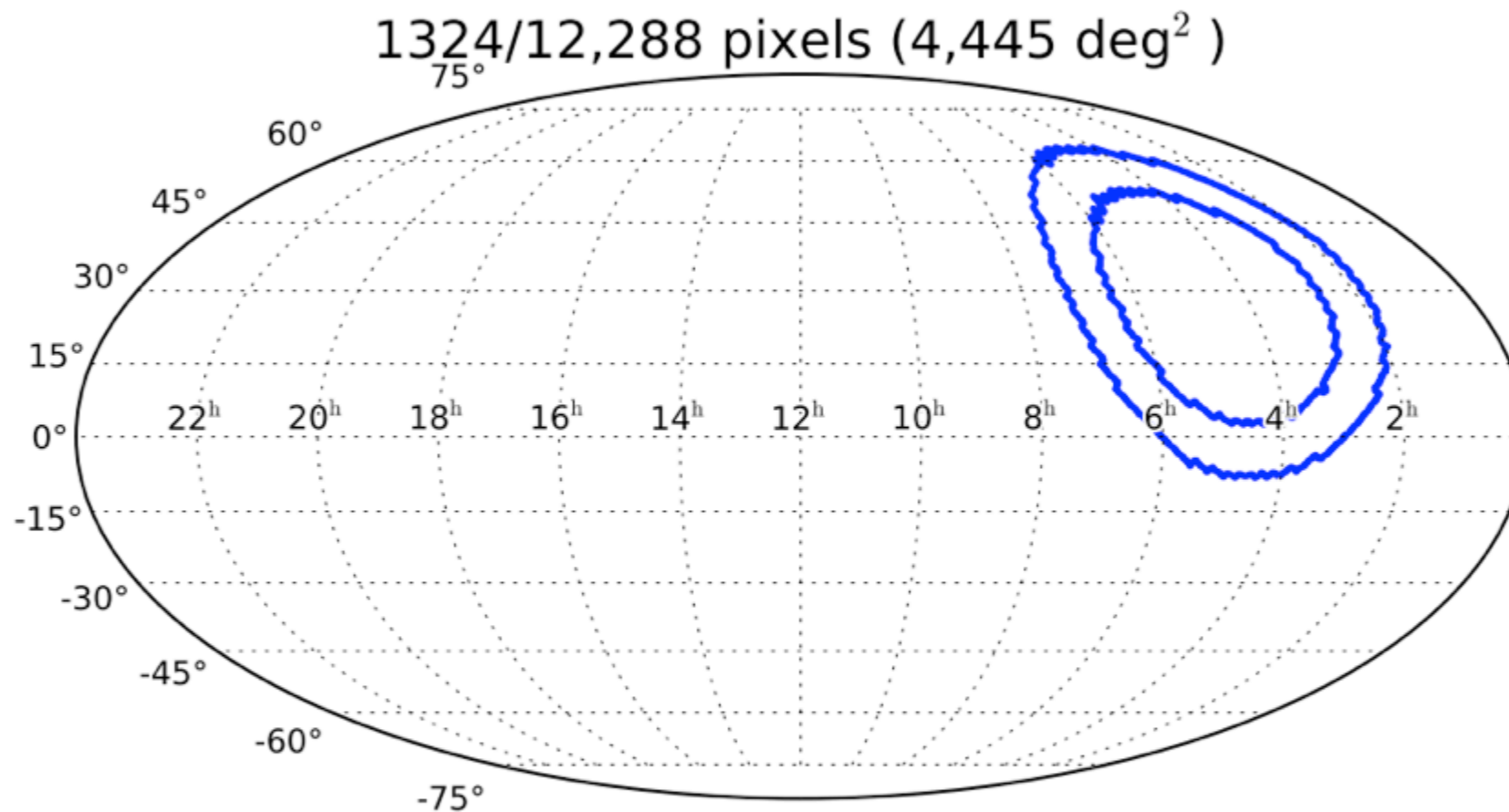
Adaptive resolution

Evaluate **TOA** posterior **first**, then evaluate **SNR** posterior for those points that comprise the **99.99th percentile** of the TOA posterior.



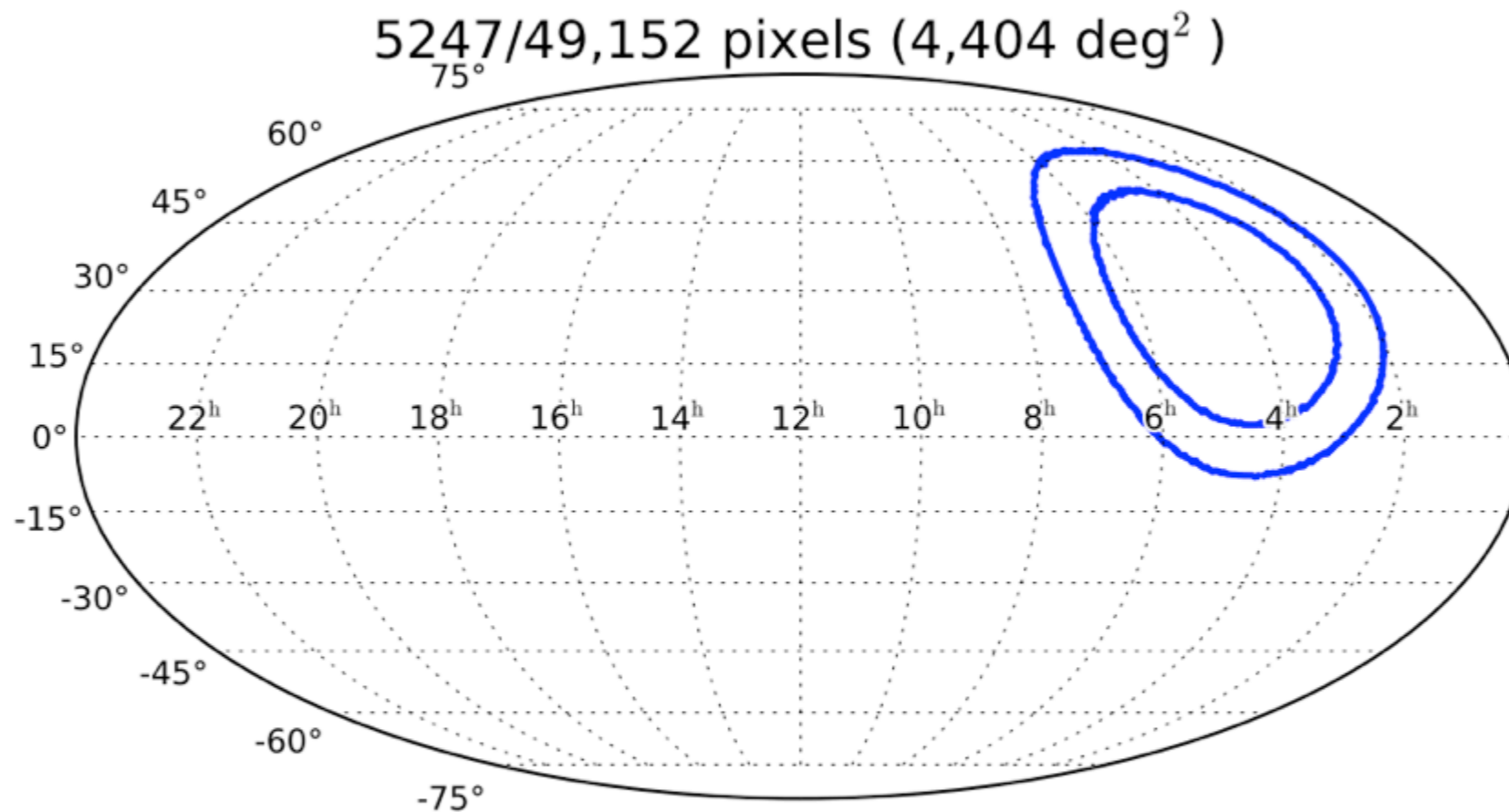
Adaptive resolution

Evaluate **TOA** posterior **first**, then evaluate **SNR** posterior for those points that comprise the **99.99th percentile** of the TOA posterior.



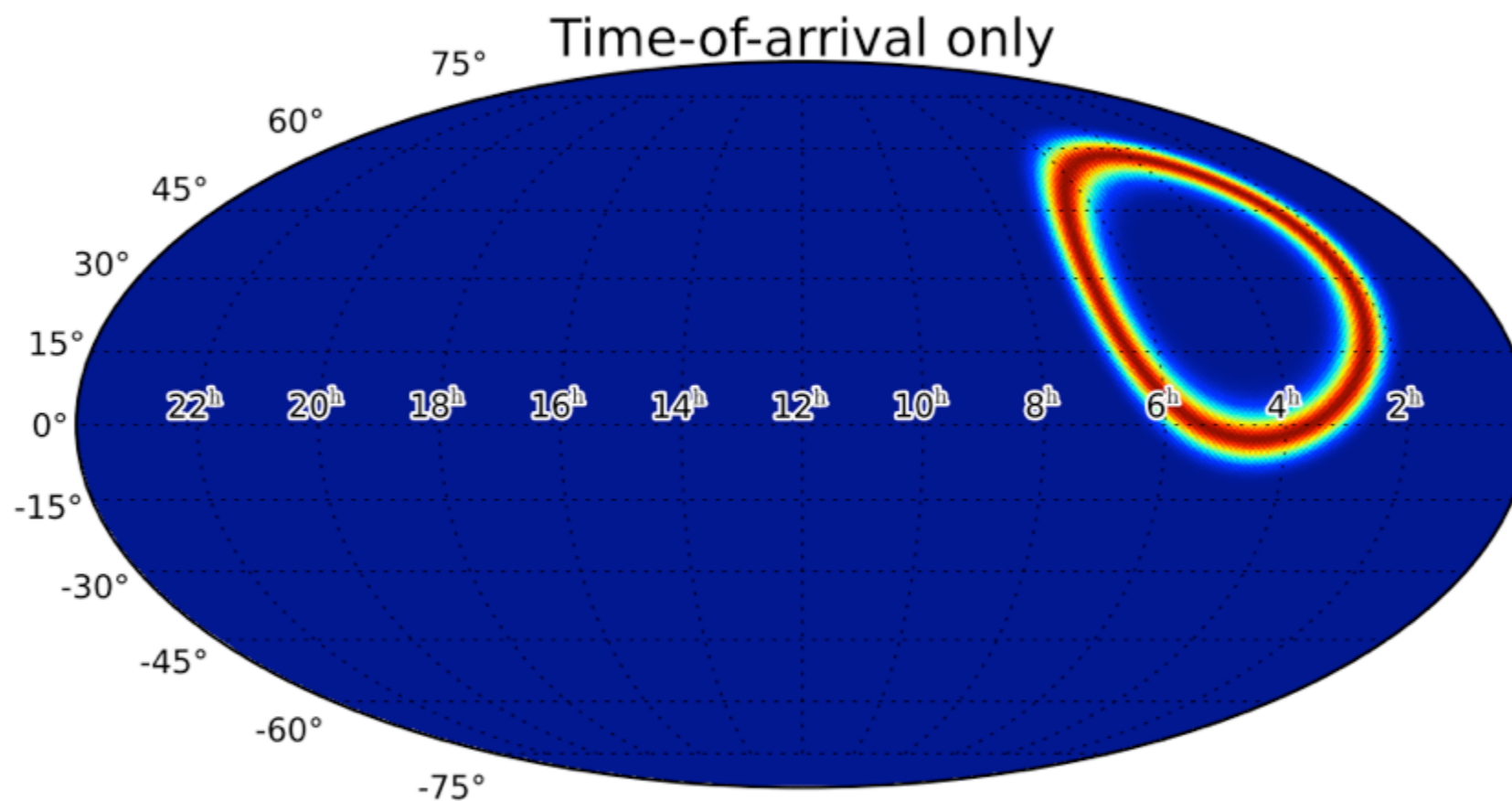
Adaptive resolution

Evaluate **TOA** posterior **first**, then evaluate **SNR** posterior for those points that comprise the **99.99th percentile** of the TOA posterior.



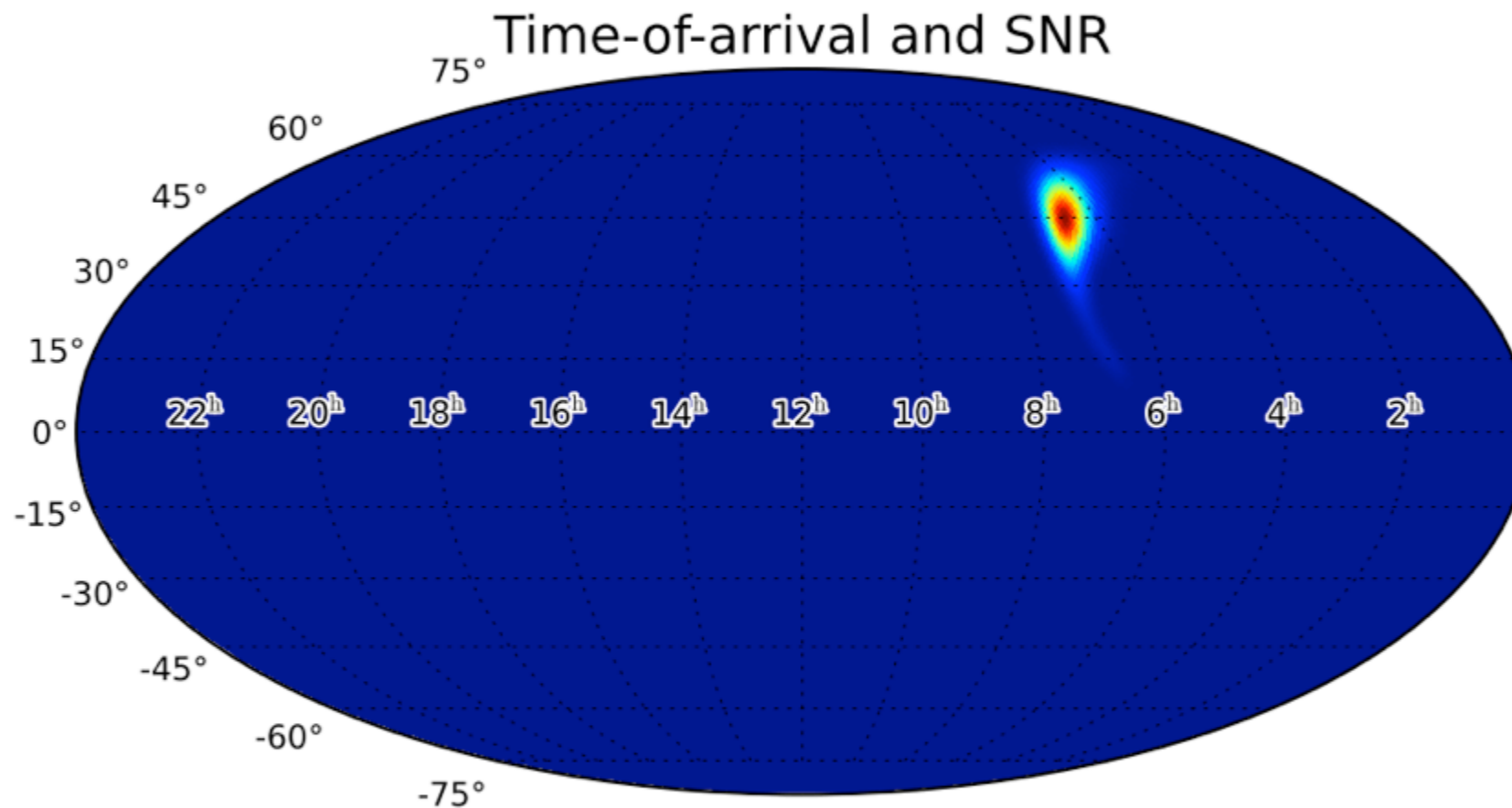
Adaptive resolution

Evaluate **TOA** posterior **first**, then evaluate **SNR** posterior for those points that comprise the **99.99th percentile** of the TOA posterior.



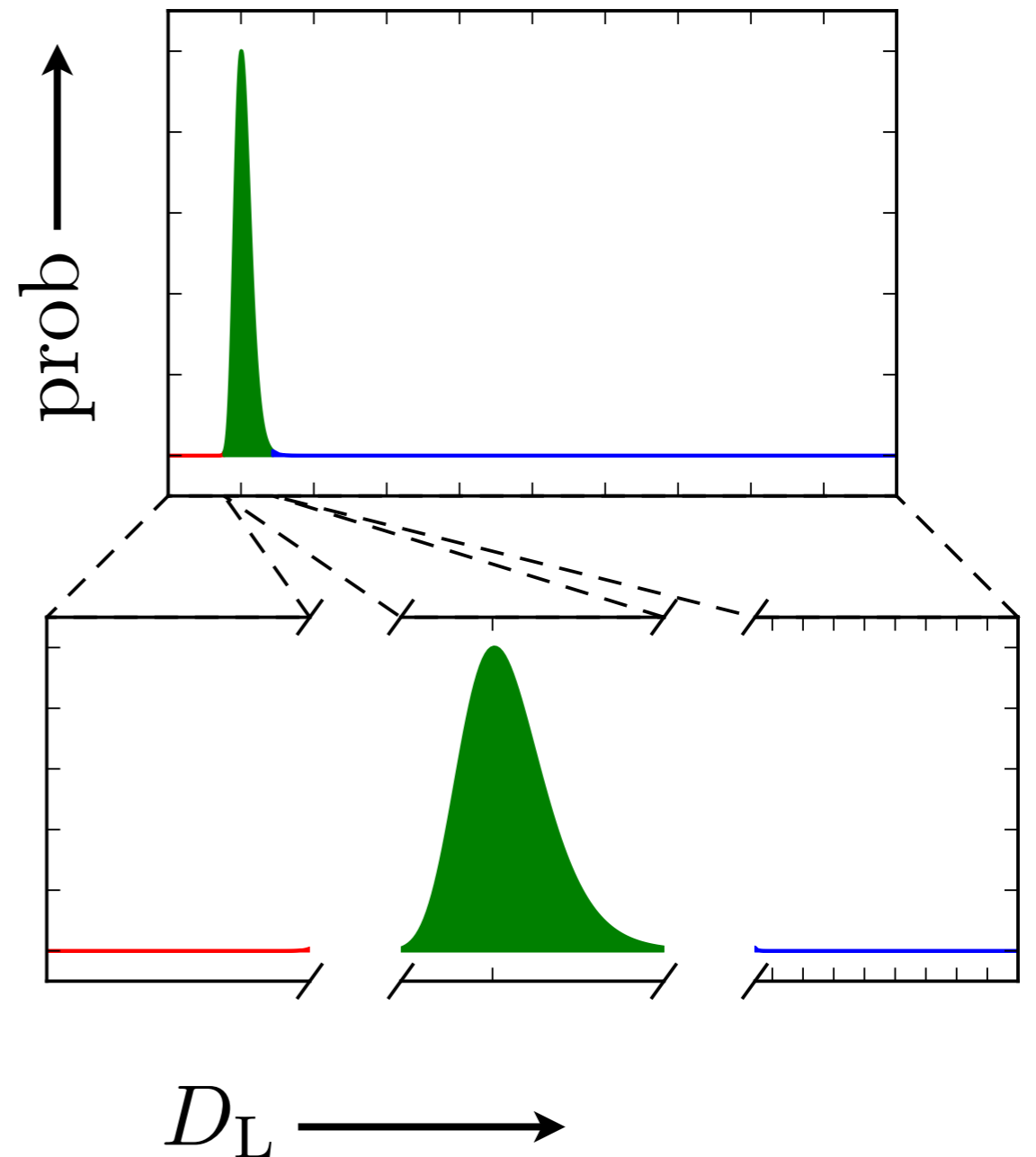
Adaptive resolution

Evaluate **TOA** posterior **first**, then evaluate **SNR** posterior for those points that comprise the **99.99th percentile** of the TOA posterior.



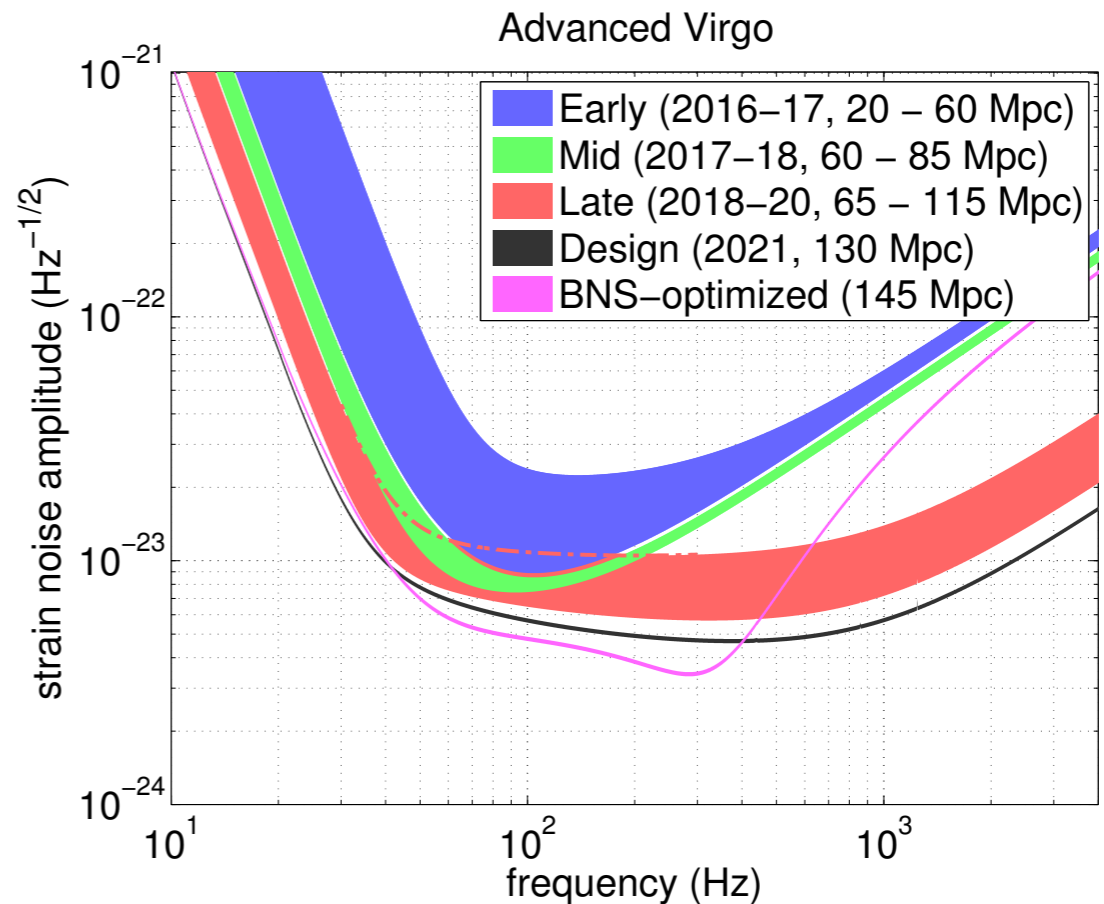
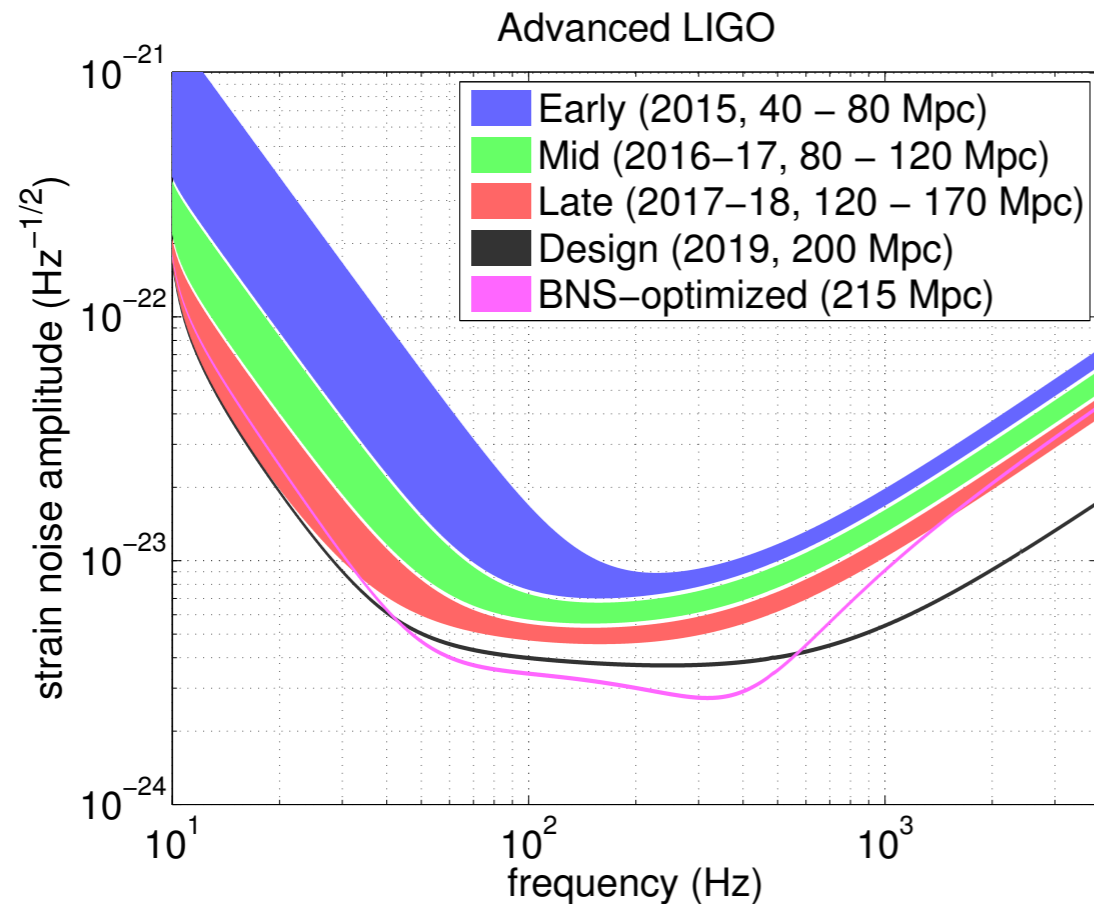
Distance marginalization

- Radial integrand peaks sharply at distance that is best supported by data
- Divide integration domain into 3 sub-domains that enclose **maximum likelihood peak**, **small-distance tail**, and **large-distance tail**
- Use adaptive Gaussian quadrature to discover which region dominates (`gsl_integration_qagp`)



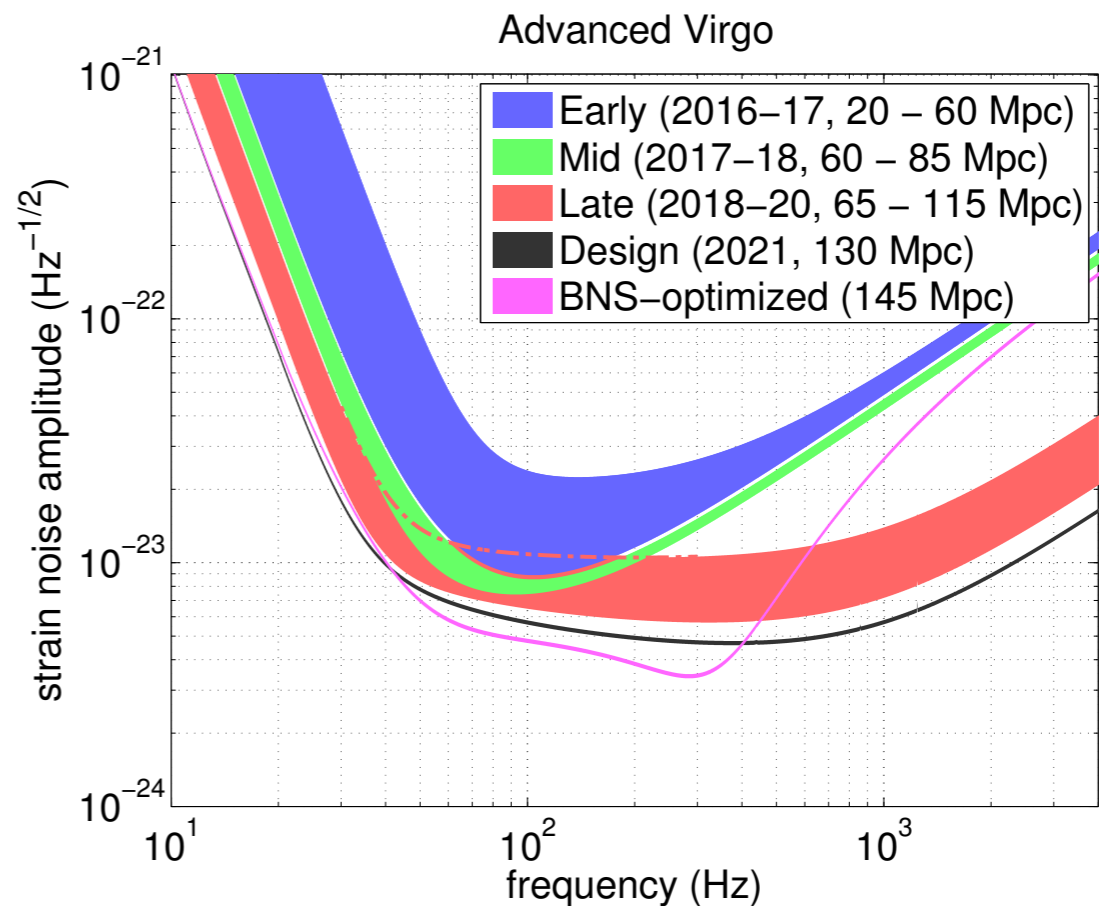
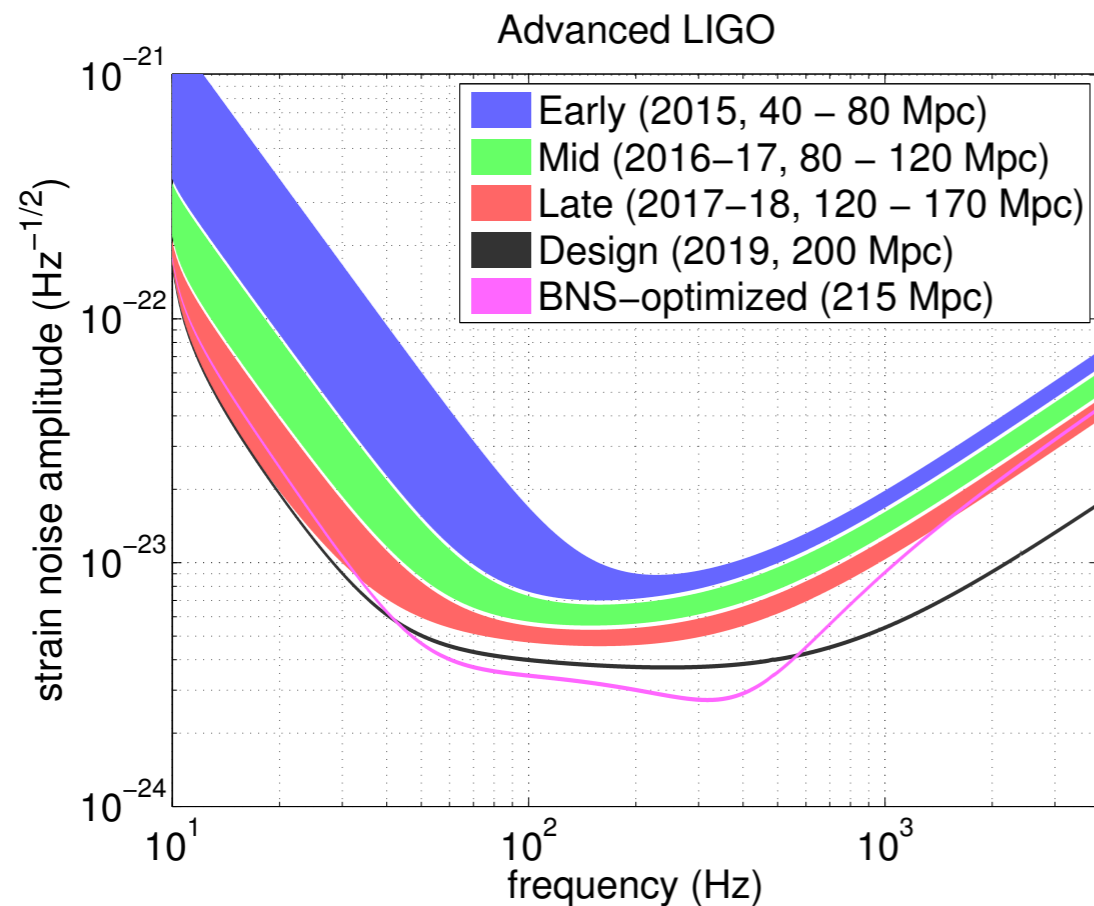
CBC Mock Data Challenge

Observing scenarios



| Epoch | Estimated Run Duration | $E_{\text{GW}} = 10^{-2} M_{\odot} c^2$ Burst Range (Mpc) | | BNS Range (Mpc) | | Number of BNS Detections | % BNS Localized within | |
|---------------|------------------------|---|---------|-----------------|----------|--------------------------|------------------------|---------------------|
| | | LIGO | Virgo | LIGO | Virgo | | 5 deg ² | 20 deg ² |
| 2015 | 3 months | 40 – 60 | – | 40 – 80 | – | 0.0004 – 3 | – | – |
| 2016–17 | 6 months | 60 – 75 | 20 – 40 | 80 – 120 | 20 – 60 | 0.006 – 20 | 2 | 5 – 12 |
| 2017–18 | 9 months | 75 – 90 | 40 – 50 | 120 – 170 | 60 – 85 | 0.04 – 100 | 1 – 2 | 10 – 12 |
| 2019+ | (per year) | 105 | 40 – 80 | 200 | 65 – 130 | 0.2 – 200 | 3 – 8 | 8 – 28 |
| 2022+ (India) | (per year) | 105 | 80 | 200 | 130 | 0.4 – 400 | 17 | 48 |

Observing scenarios



| Epoch | Estimated Run Duration | $E_{\text{GW}} = 10^{-2} M_{\odot} c^2$ Burst Range (Mpc) | | BNS Range (Mpc) | | Number of BNS Detections | % BNS Localized within | |
|---------------|------------------------|---|---------|-----------------|----------|--------------------------|------------------------|---------------------|
| | | LIGO | Virgo | LIGO | Virgo | | 5 deg ² | 20 deg ² |
| 2015 | 3 months | 40 – 60 | – | 40 – 80 | – | 0.0004 – 3 | – | – |
| 2016–17 | 6 months | 60 – 75 | 20 – 40 | 80 – 120 | 20 – 60 | 0.006 – 20 | 2 | 5 – 12 |
| 2017–18 | 9 months | 75 – 90 | 40 – 50 | 120 – 170 | 60 – 85 | 0.04 – 100 | 1 – 2 | 10 – 12 |
| 2019+ | (per year) | 105 | 40 – 80 | 200 | 65 – 130 | 0.2 – 200 | 3 – 8 | 8 – 28 |
| 2022+ (India) | (per year) | 105 | 80 | 200 | 130 | 0.4 – 400 | 17 | 48 |

BNS Mock Data Challenge

5k injections

H1-L1 network

early aLIGO configuration

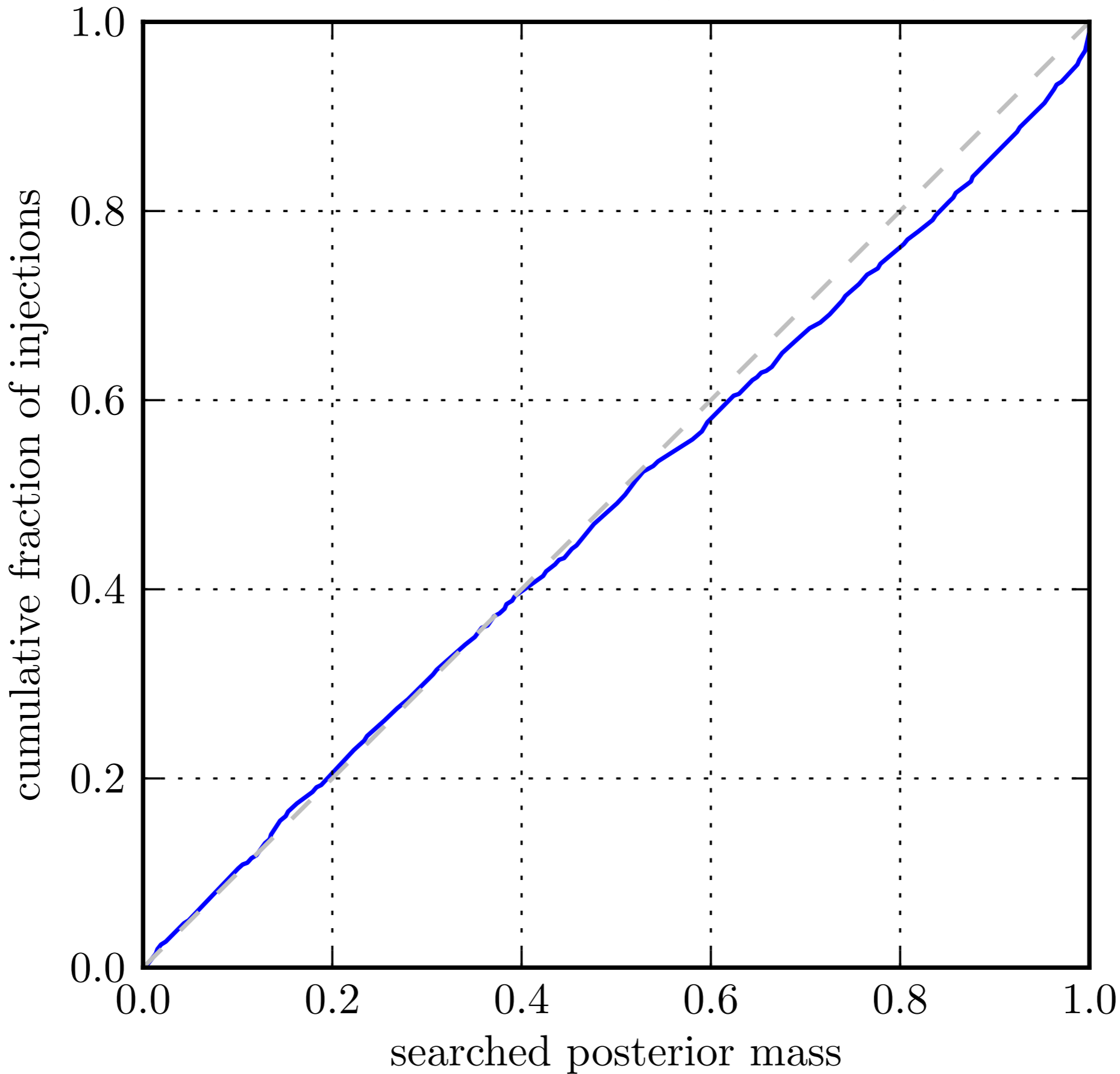
Uniformly distributed component masses

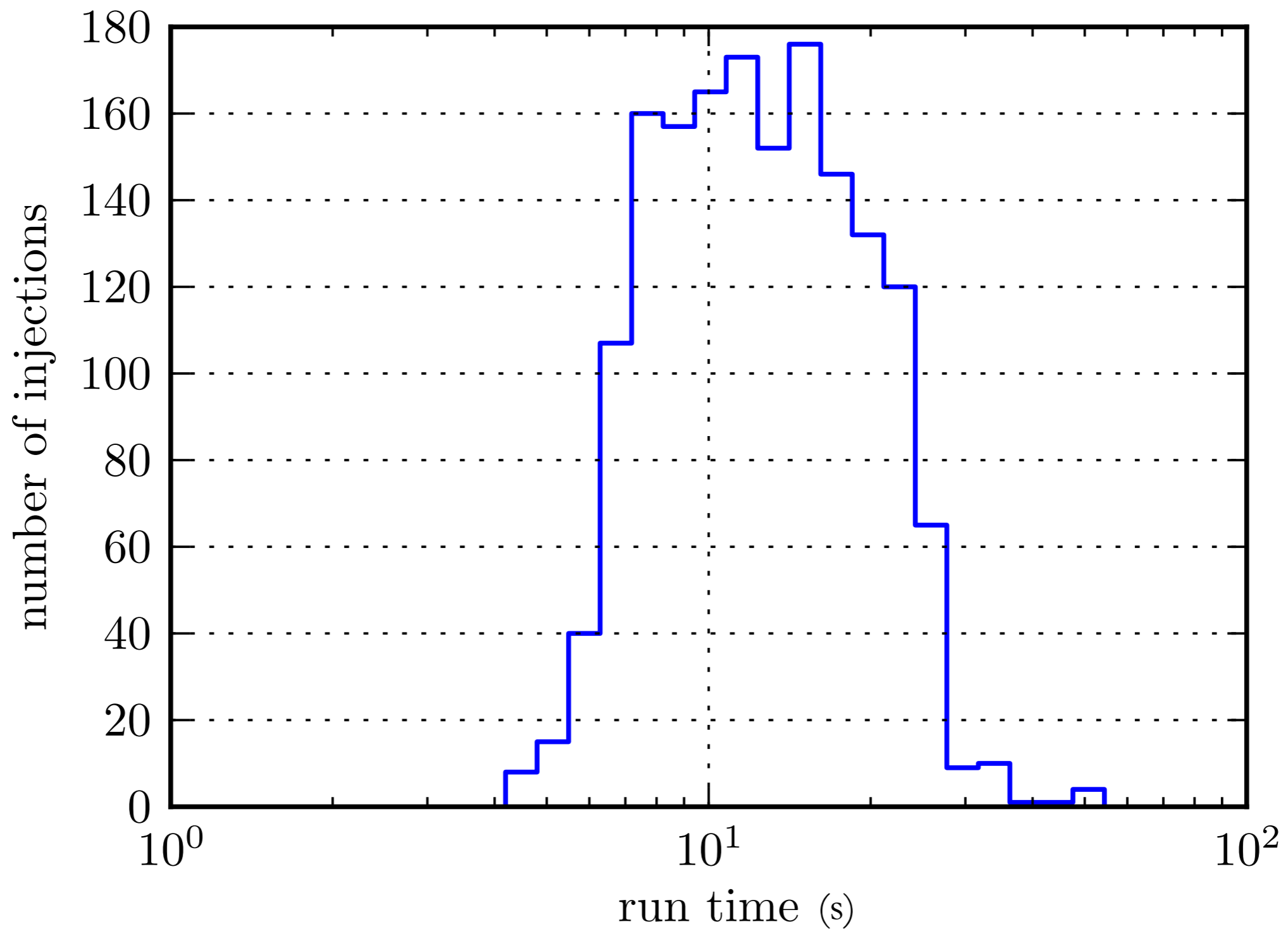
$1.2 M_{\odot} \leq m_{1,2} \leq 1.6 M_{\odot}$

TaylorT4threePointFivePN waveforms

Gaussian noise (recolored noise simulations exist too)

FAR $\leq 10^{-4}$ Hz (1643 events)



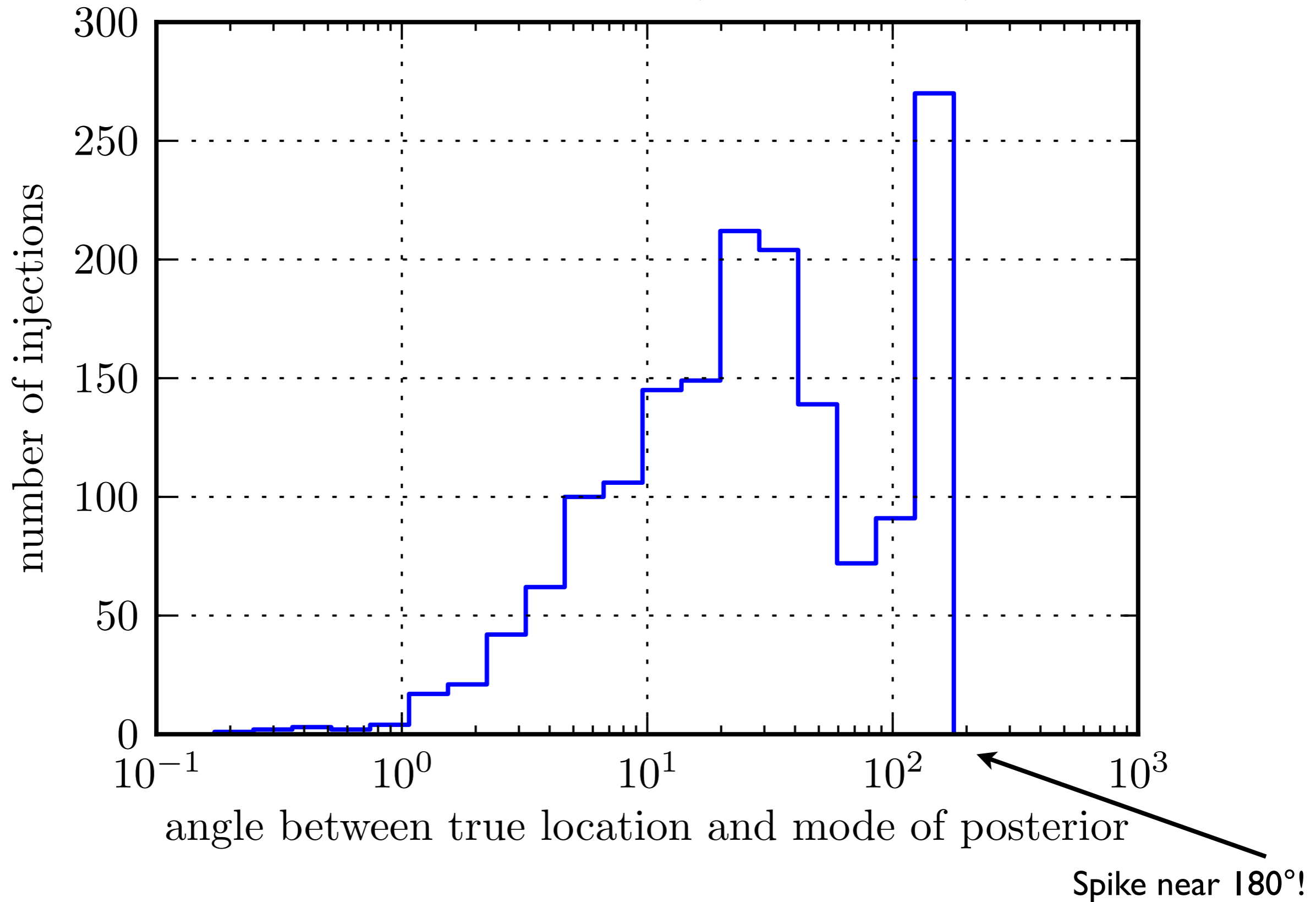


(single threaded; parallelized with

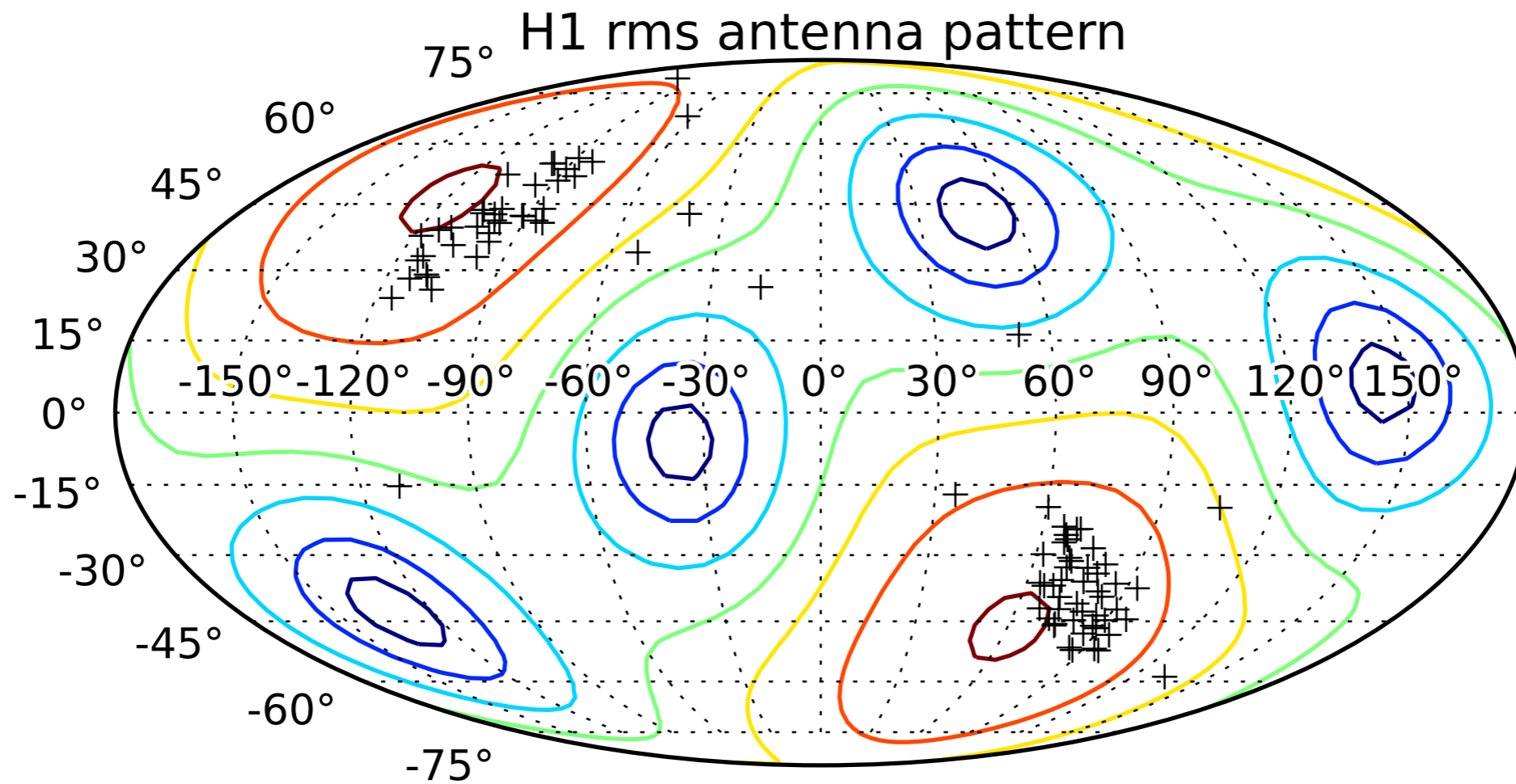


)

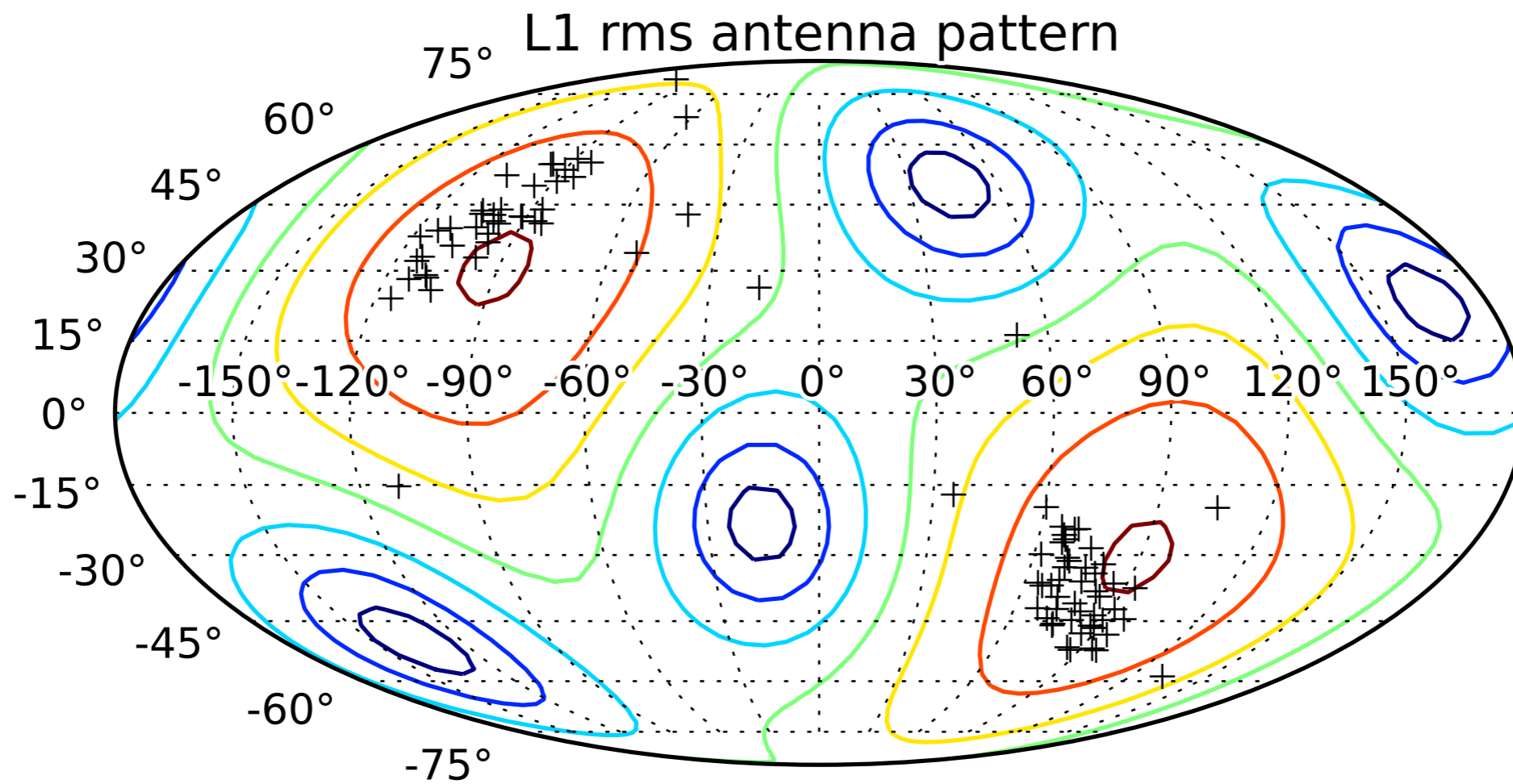
FAR $\leq 10^{-4}$ Hz (1643 events)



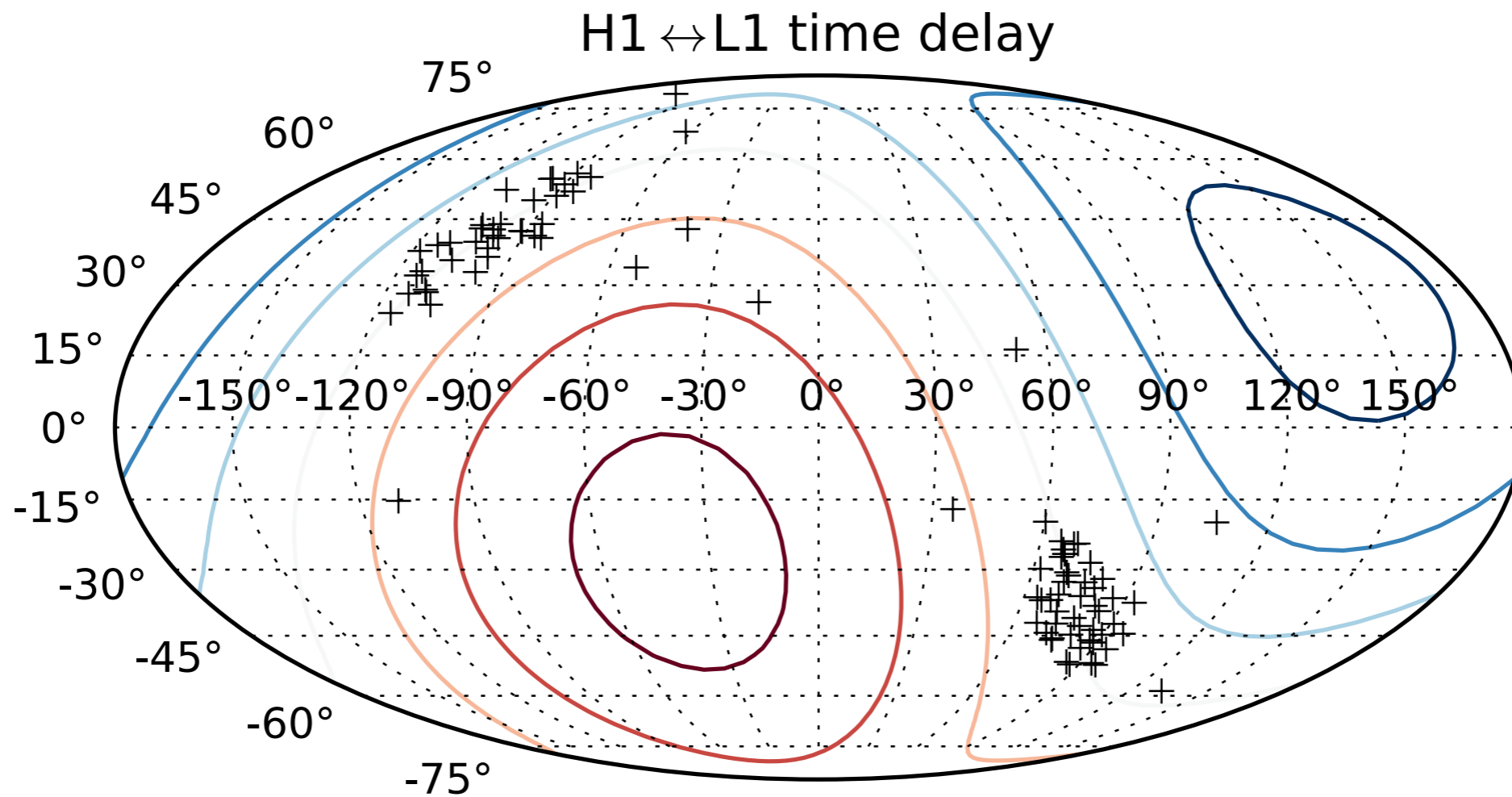
Why the bump at 180°?

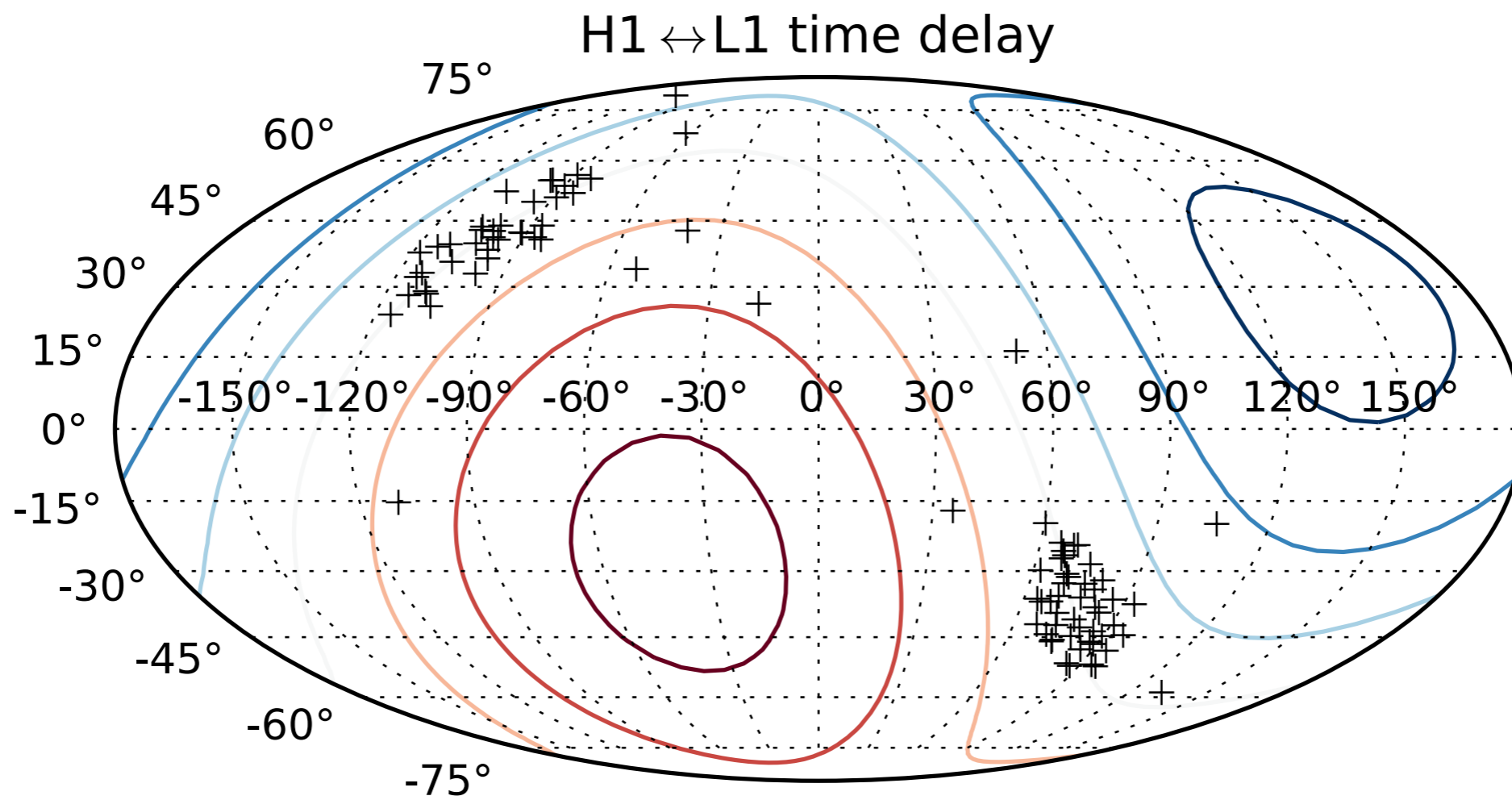


Why the bump at 180°?

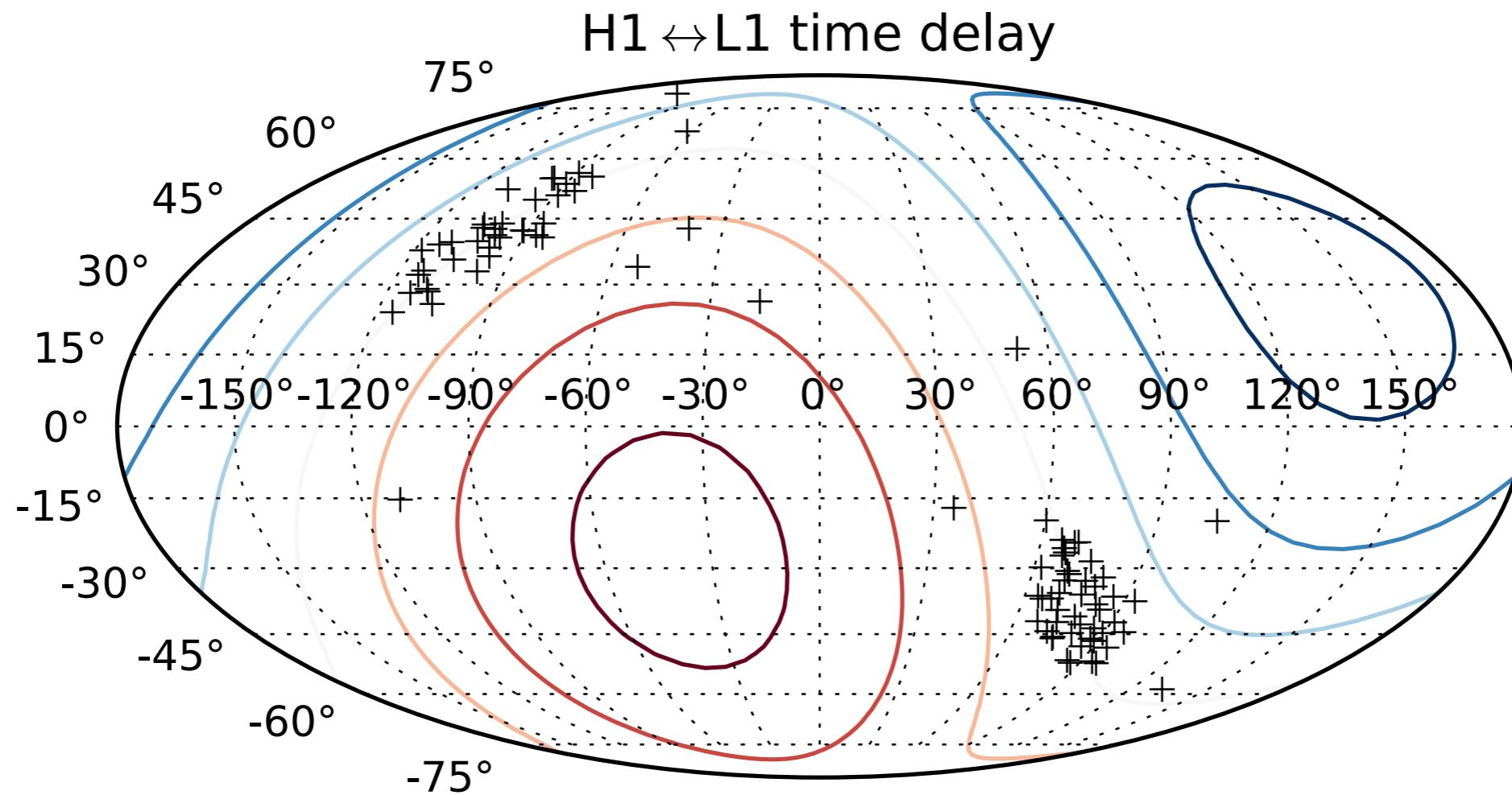


Why the bump at 180°?





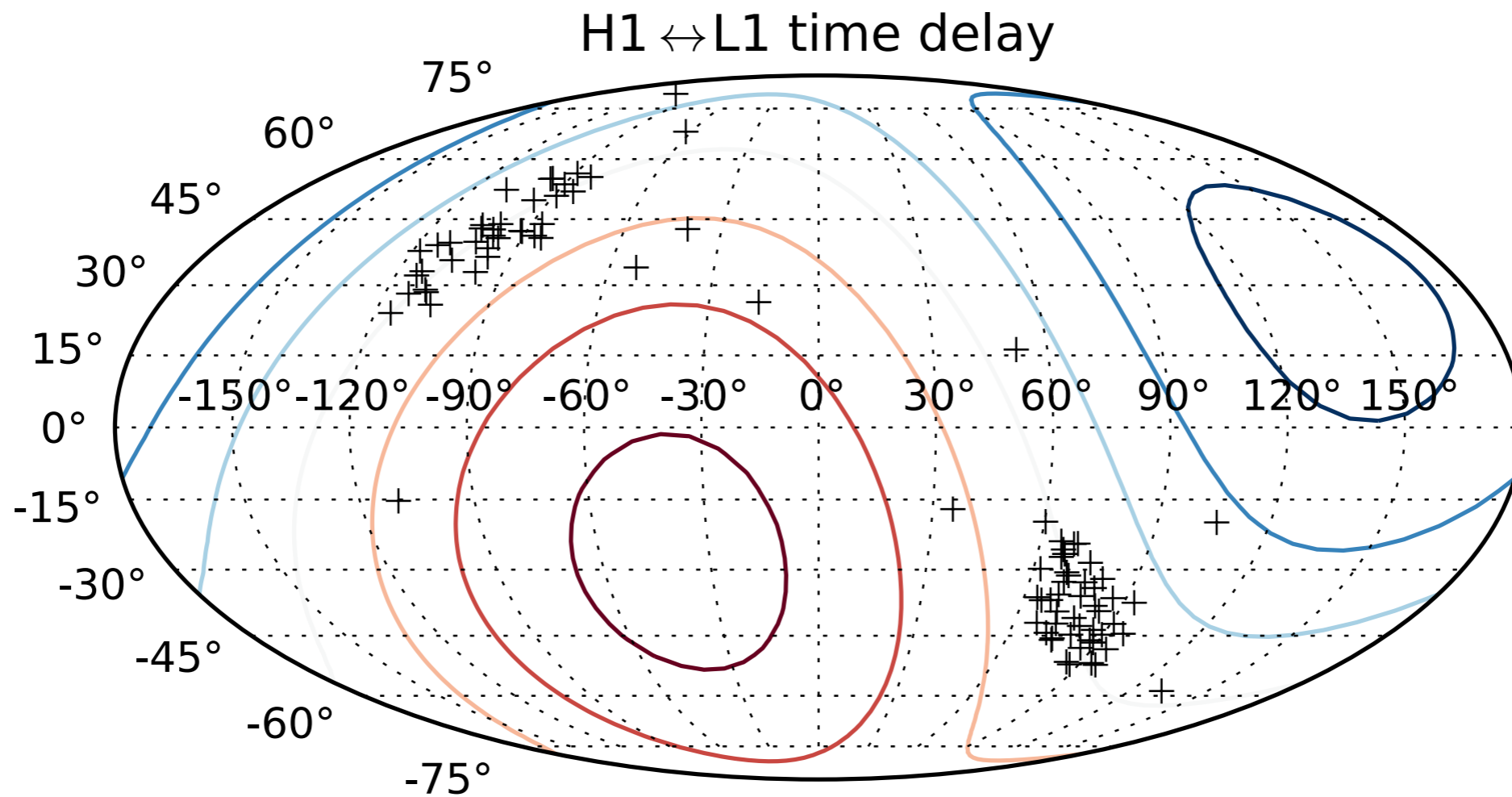
Crosshairs cluster at time delay=0 and maxima in H1, L1 antenna pattern



Crosshairs cluster at time
delay=0 and maxima in H1,
L1 antenna pattern



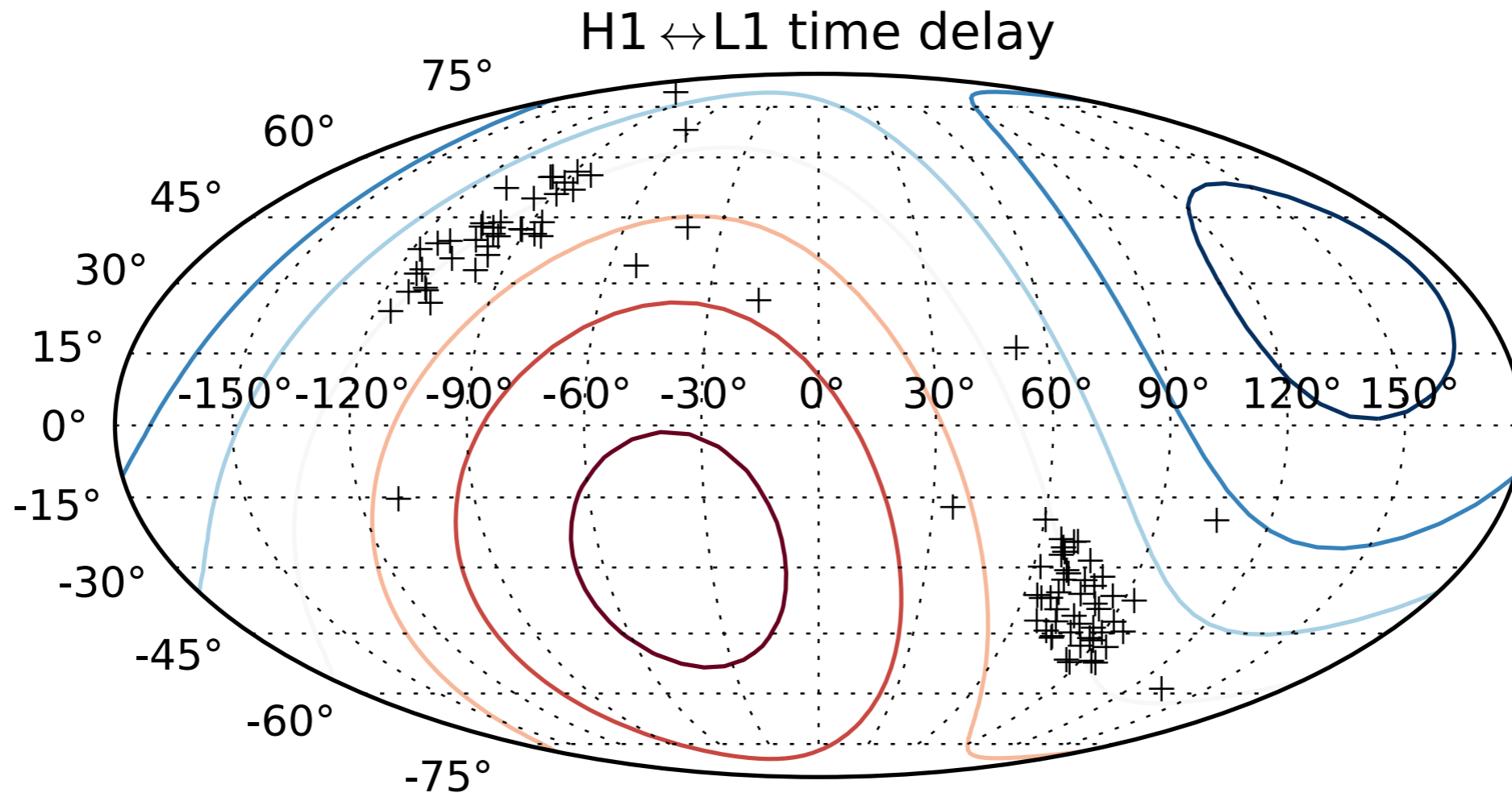
2 locations, 180° apart,
nearly indistinguishable
by TOAs or SNR



Crosshairs cluster at time
delay=0 and maxima in H1,
L1 antenna pattern



2 locations, 180° apart,
nearly indistinguishable
by TOAs or SNR

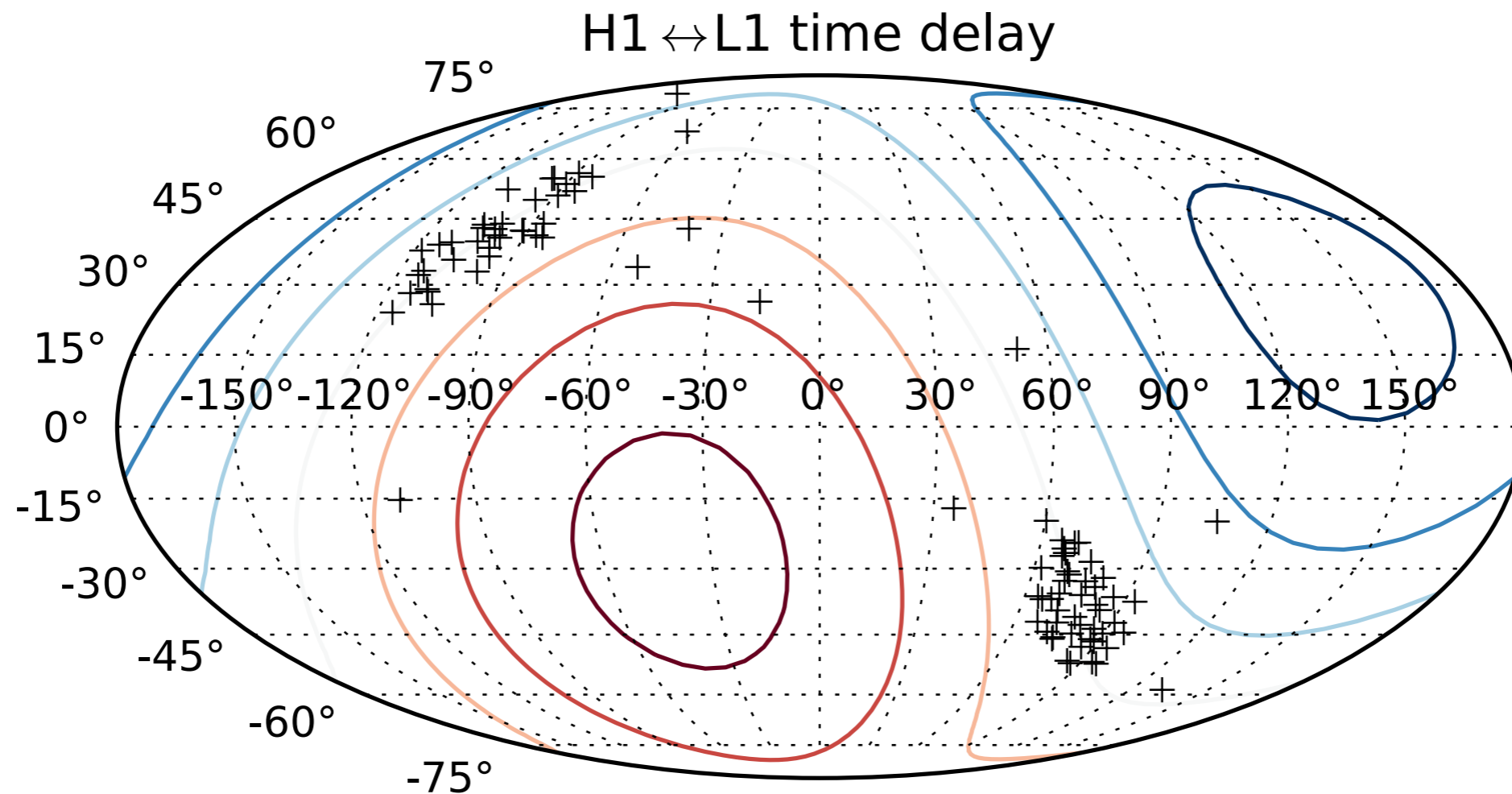


Bump near 180° is inevitable, given H1,L1 configuration.

Crosshairs cluster at time delay=0 and maxima in H1, L1 antenna pattern

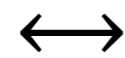


2 locations, 180° apart, nearly indistinguishable by TOAs or SNR

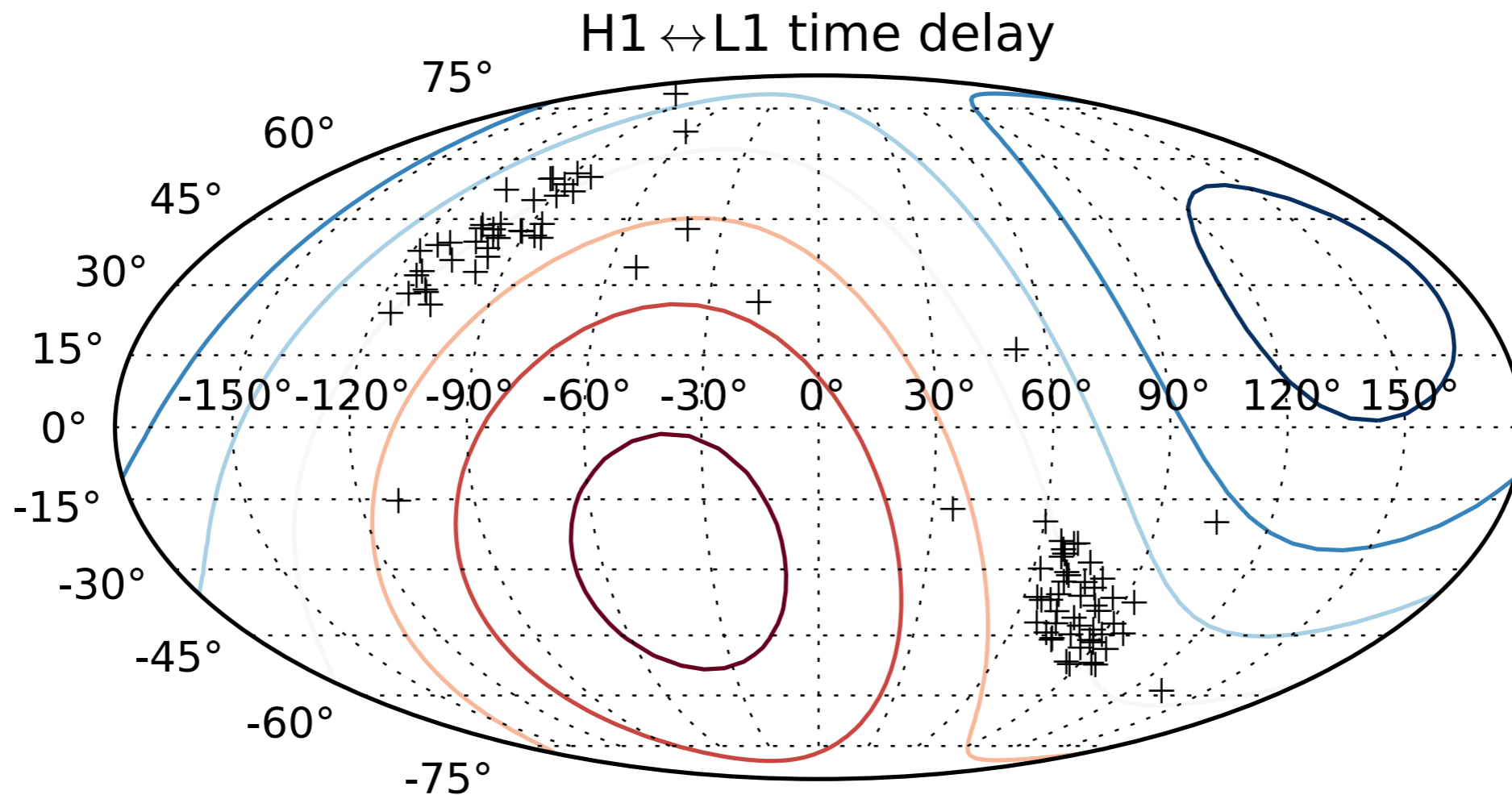


Bump near 180° is inevitable, given H1,L1 configuration.
Worse: these degenerate points are almost 12h apart in RA.

Crosshairs cluster at time
delay=0 and maxima in H1,
L1 antenna pattern



2 locations, 180° apart,
nearly indistinguishable
by TOAs or SNR



Bump near 180° is inevitable, given H1,L1 configuration.

Worse: these degenerate points are almost 12h apart in RA.

Multiple ***nights*** and multiple ***optical facilities***
required to follow up many GW events!

Observing scenarios

Observing scenarios

| Epoch |
|---------------|
| 2015 |
| 2016–17 |
| 2017–18 |
| 2019+ |
| 2022+ (India) |



Observing scenarios

| Epoch | Number of BNS Detections | % BNS Localized within | |
|---------------|--------------------------|------------------------|---------------------|
| | | 5 deg ² | 20 deg ² |
| 2015 | 0.0004 – 3 | – | – |
| 2016–17 | 0.006 – 20 | 2 | 5 – 12 |
| 2017–18 | 0.04 – 100 | 1 – 2 | 10 – 12 |
| 2019+ | 0.2 – 200 | 3 – 8 | 8 – 28 |
| 2022+ (India) | 0.4 – 400 | 17 | 48 |

Observing scenarios document doesn't even bother to put a number for % localized in 2015 run...

Observing scenarios

| Epoch | Number of BNS Detections | % BNS Localized within | |
|---------------|--------------------------|------------------------|---------------------|
| | | 5 deg ² | 20 deg ² |
| 2015 | 0.0004 – 3 | – | – |
| 2016–17 | 0.006 – 20 | 2 | 5 – 12 |
| 2017–18 | 0.04 – 100 | 1 – 2 | 10 – 12 |
| 2019+ | 0.2 – 200 | 3 – 8 | 8 – 28 |
| 2022+ (India) | 0.4 – 400 | 17 | 48 |

Observing scenarios document doesn't even bother to put a number for % localized in 2015 run...

Statistically, in “2015 epoch” MDC:

| | % BNS localized within | |
|-----------------------|---------------------------|----------------------------|
| | within 5 deg ² | within 20 deg ² |
| with $\rho_c \geq 12$ | 2.2 ± 0.6% | 9.8 ± 1.2% |

...for good reason, considering the sky maps for the HILI events in the MDC.

Observing scenarios

| Epoch | Number of BNS Detections | % BNS Localized within | |
|---------------|--------------------------|------------------------|---------------------|
| | | 5 deg ² | 20 deg ² |
| 2015 | 0.0004 – 3 | – | – |
| 2016–17 | 0.006 – 20 | 2 | 5 – 12 |
| 2017–18 | 0.04 – 100 | 1 – 2 | 10 – 12 |
| 2019+ | 0.2 – 200 | 3 – 8 | 8 – 28 |
| 2022+ (India) | 0.4 – 400 | 17 | 48 |

These numbers will be more interesting to fill in as MDCs progress through detector configurations...

Observing scenarios

| Epoch | Number of BNS Detections | % BNS Localized within | |
|---------------|--------------------------|------------------------|---------------------|
| | | 5 deg ² | 20 deg ² |
| 2015 | 0.0004 – 3 | – | – |
| 2016–17 | 0.006 – 20 | 2 | 5 – 12 |
| 2017–18 | 0.04 – 100 | 1 – 2 | 10 – 12 |
| 2019+ | 0.2 – 200 | 3 – 8 | 8 – 28 |
| 2022+ (India) | 0.4 – 400 | 17 | 48 |

Team assembled to produce MDCs for all of the observing scenarios: Chad Hanna, Chris Pankow, Branson Stephens, Alex Urban, Sarah Caudill, Ruslan Vaulin, Salvatore Vitale, Larry Price, Leo Singer

Observing scenarios

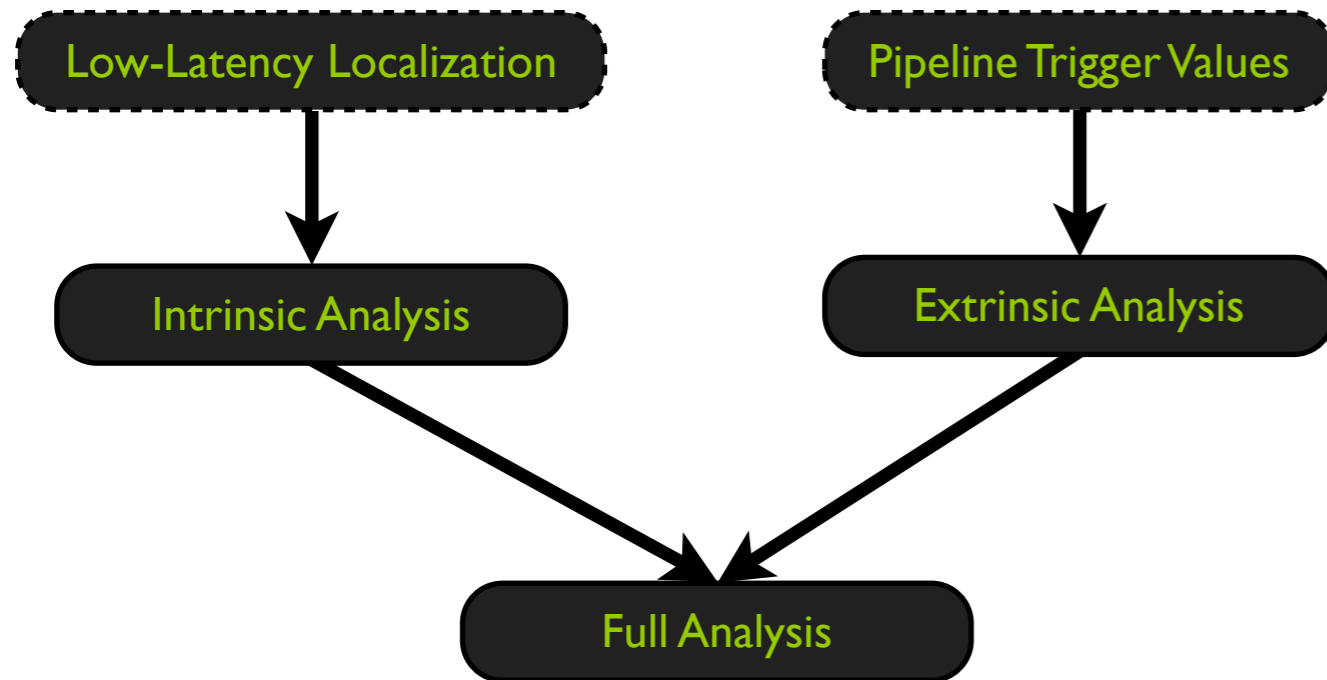
| Epoch | Number of BNS Detections | % BNS Localized within | |
|---------------|--------------------------|------------------------|---------------------|
| | | 5 deg ² | 20 deg ² |
| 2015 | 0.0004 – 3 | – | – |
| 2016–17 | 0.006 – 20 | 2 | 5 – 12 |
| 2017–18 | 0.04 – 100 | 1 – 2 | 10 – 12 |
| 2019+ | 0.2 – 200 | 3 – 8 | 8 – 28 |
| 2022+ (India) | 0.4 – 400 | 17 | 48 |

Which detector network is *likely* to produce the first well-localized CBCs?

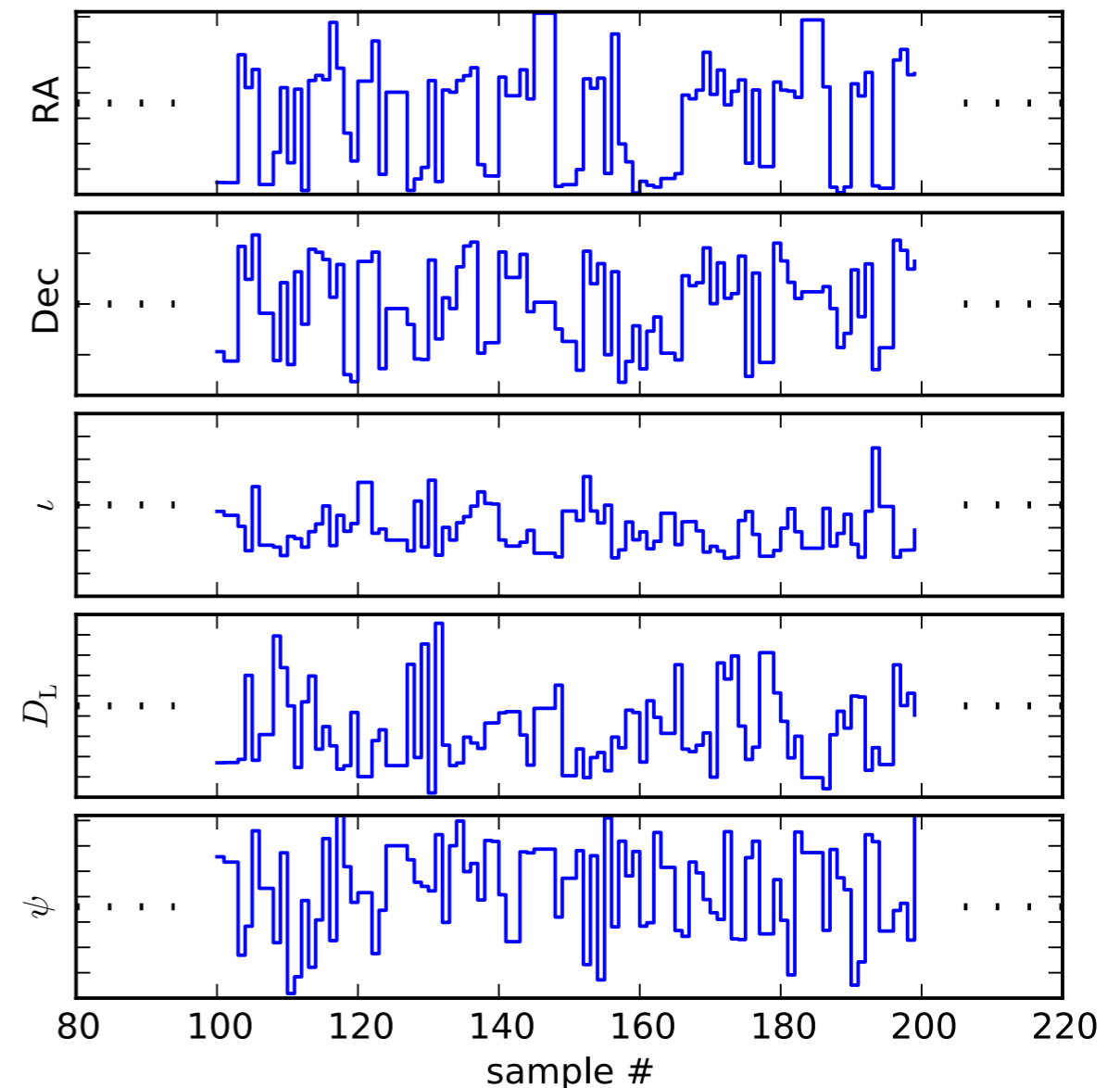
Team assembled to produce MDCs for all of the observing scenarios: Chad Hanna, Chris Pankow, Branson Stephens, Alex Urban, Sarah Caudill, Ruslan Vaulin, Salvatore Vitale, Larry Price, Leo Singer

Future work

- Feed rapid localization into full parameter estimation
- MCMC implementation of BAYESTAR developed w/ Ben Farr



see <https://dcc.ligo.org/LIGO-G1300015-v3>
Ben Farr, Northwestern U.



**Searching for optical
counterparts of GBM
events with PTF**

TITLE: GCN CIRCULAR
NUMBER: 13489
SUBJECT: GRB 120716A: Candidate Optical Afterglow from PTF
DATE: 12/07/19 00:01:37 GMT
FROM: S. Bradley Cenko at Caltech <cenko@srl.caltech.edu>

S. B. Cenko (UC Berkeley), E. O. Ofek (Weizmann Institute of Science), and P. E. Nugent (Lawrence Berkeley National Laboratory / UC Berkeley) report on behalf of a larger collaboration:

We have imaged the location of the IPN GRB 120716A (Hurley et al., GCN 13487) with the Palomar 48 inch Oschin Schmidt telescope as part of the Palomar Transient Factory (PTF). Images were obtained in the r' filter beginning at 4:25 UT on 18 July 2012 (~ 1.5 d after the IPN trigger).

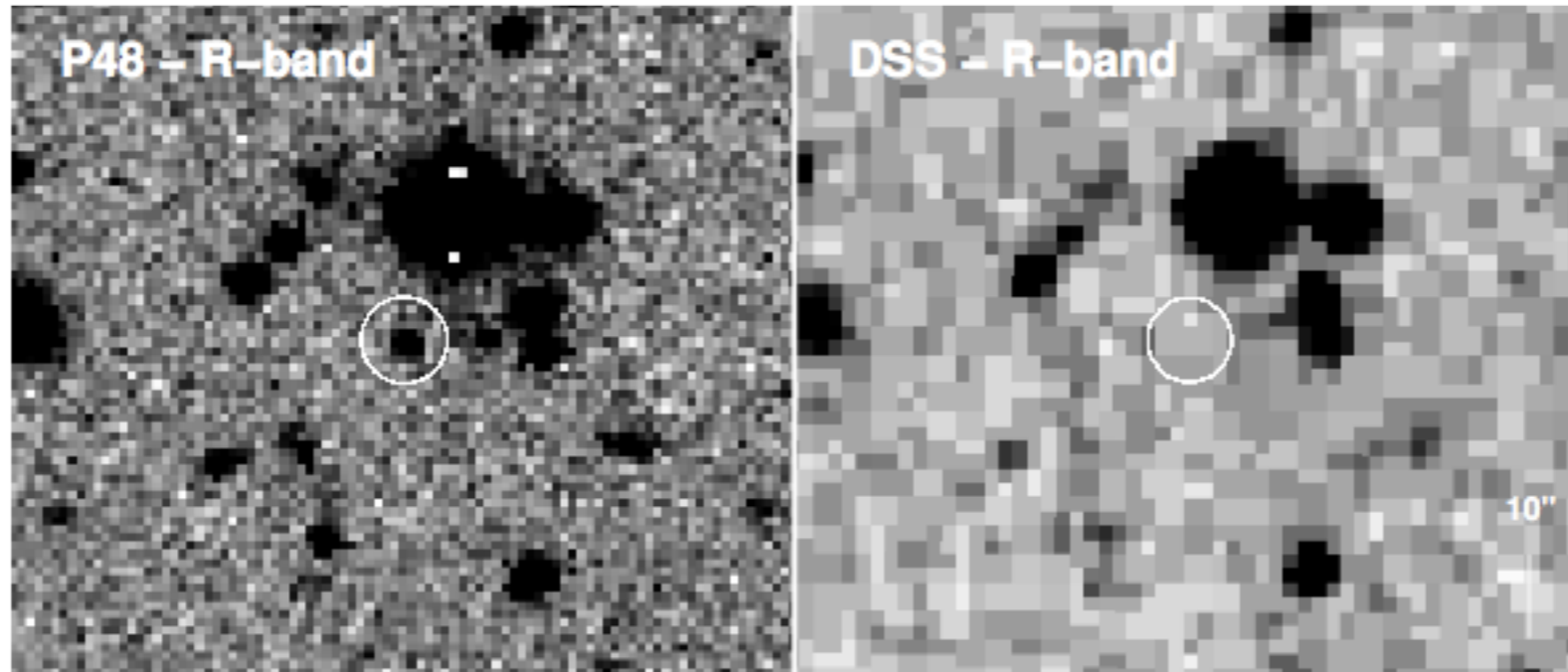
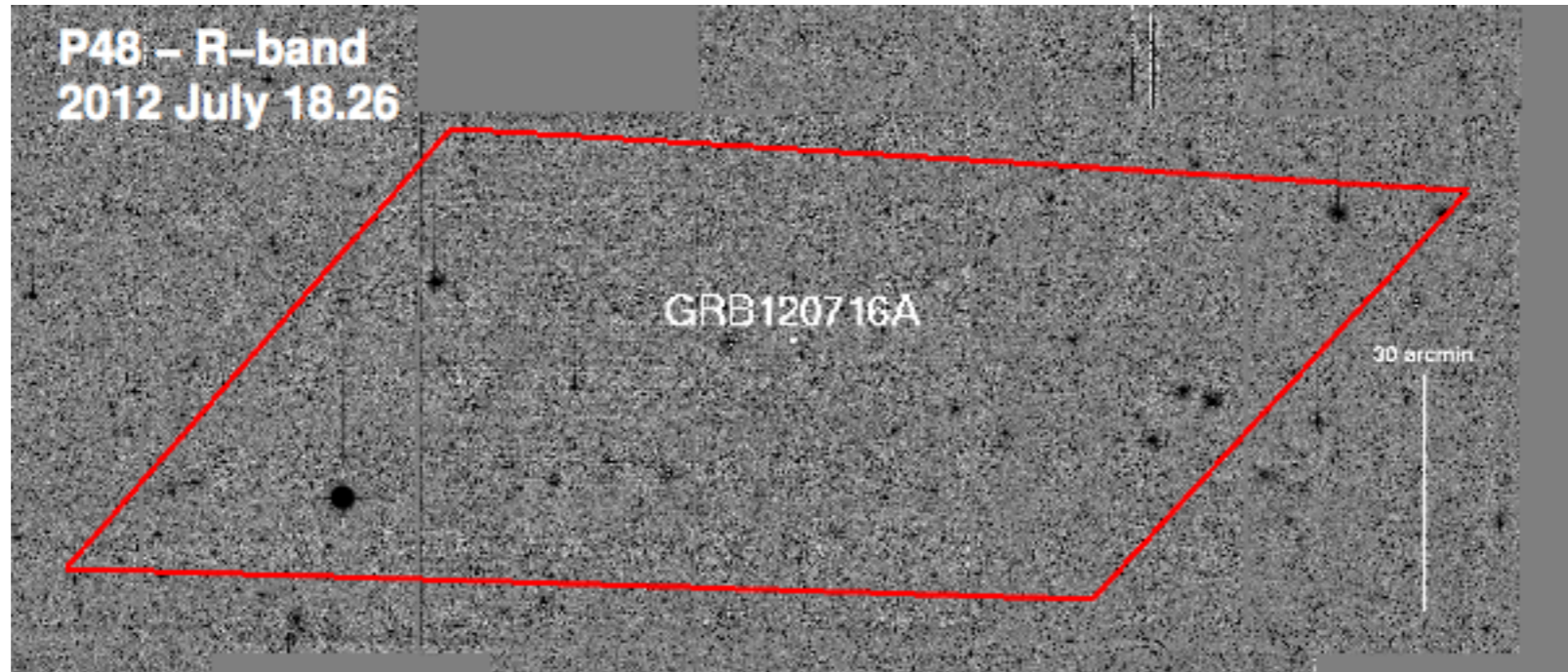
Within the IPN localization, **we identify a new point source** with coordinates:

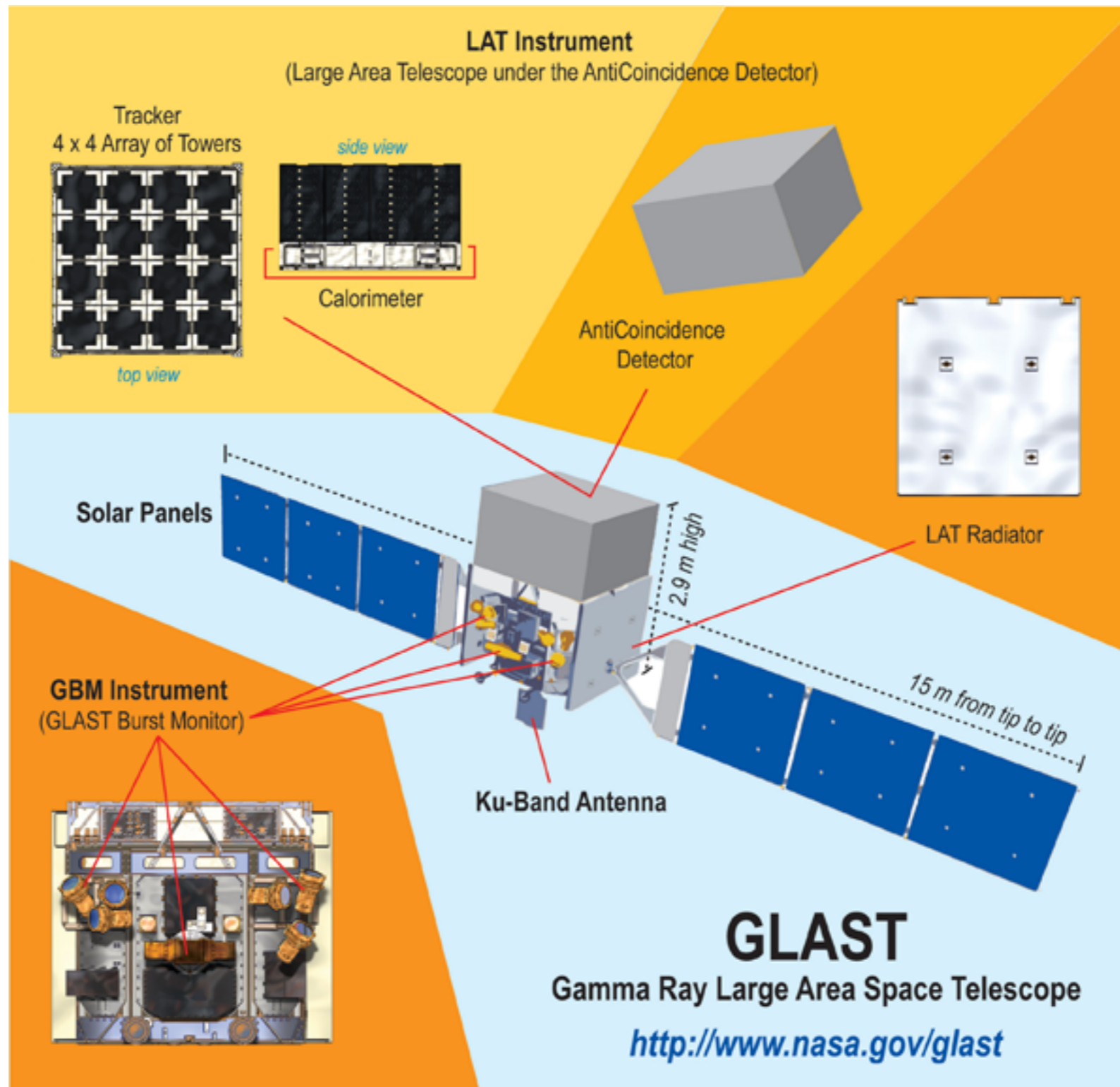
RA: 20:52:12.10 Dec: +09:35:53.7 (J2000.0)

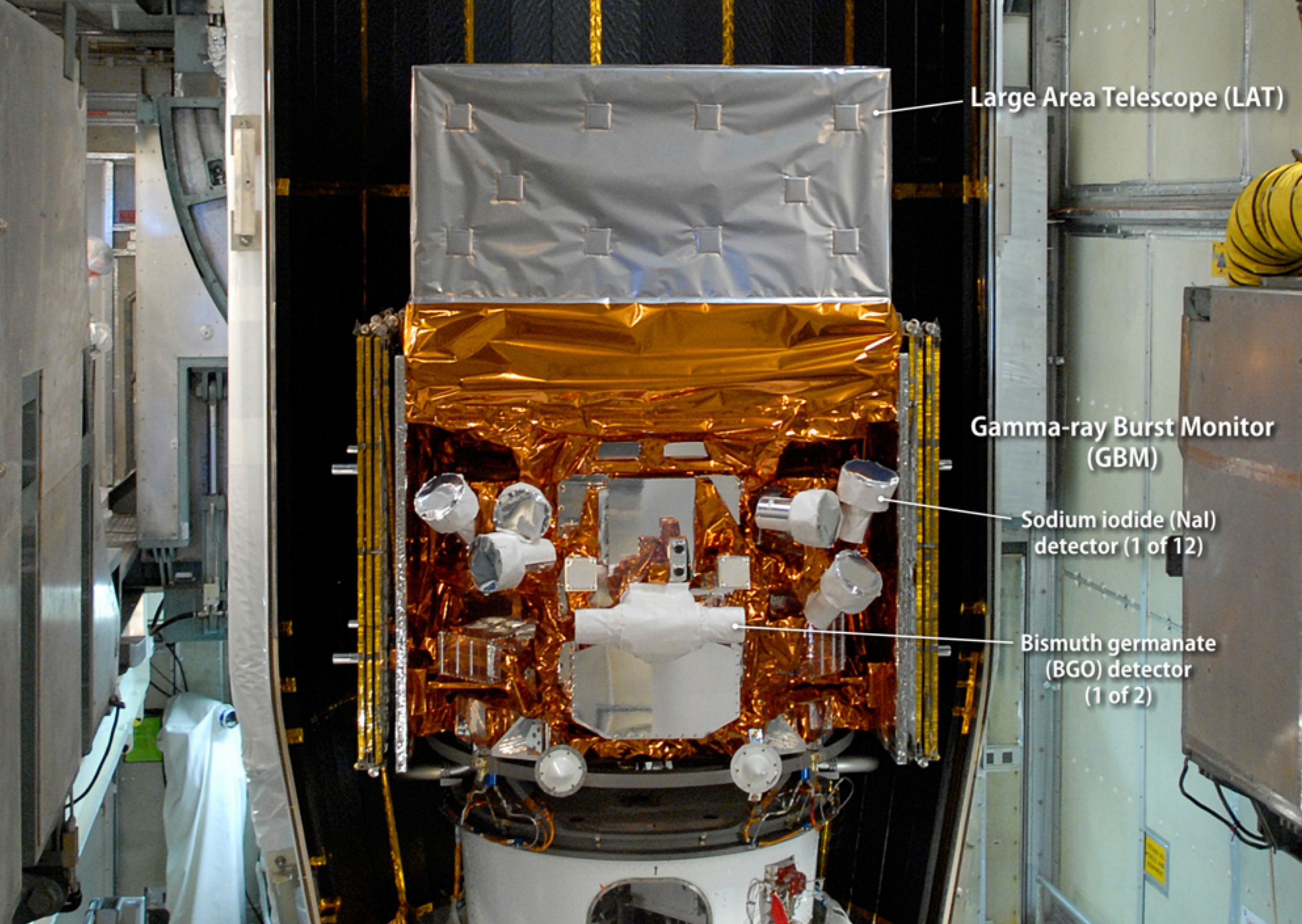
Using several nearby stars from the Sloan Digital Sky Survey for reference, we measure a **magnitude of $r' \sim 20.4$** at this time.

Nothing is detected at this location in previous PTF imaging of this field, with images beginning in June 2011. Furthermore, no source is detected in archival SDSS imaging of this location (a faint nearby object in the SDSS database, SDSS J205212.01+093551.9, appears to be of very low significance). However, our most recent epoch of PTF imaging was obtained in March 2012, so we cannot currently rule out the chance alignment of an unassociated foreground or background transient.

Further observations of this candidate optical afterglow are planned.







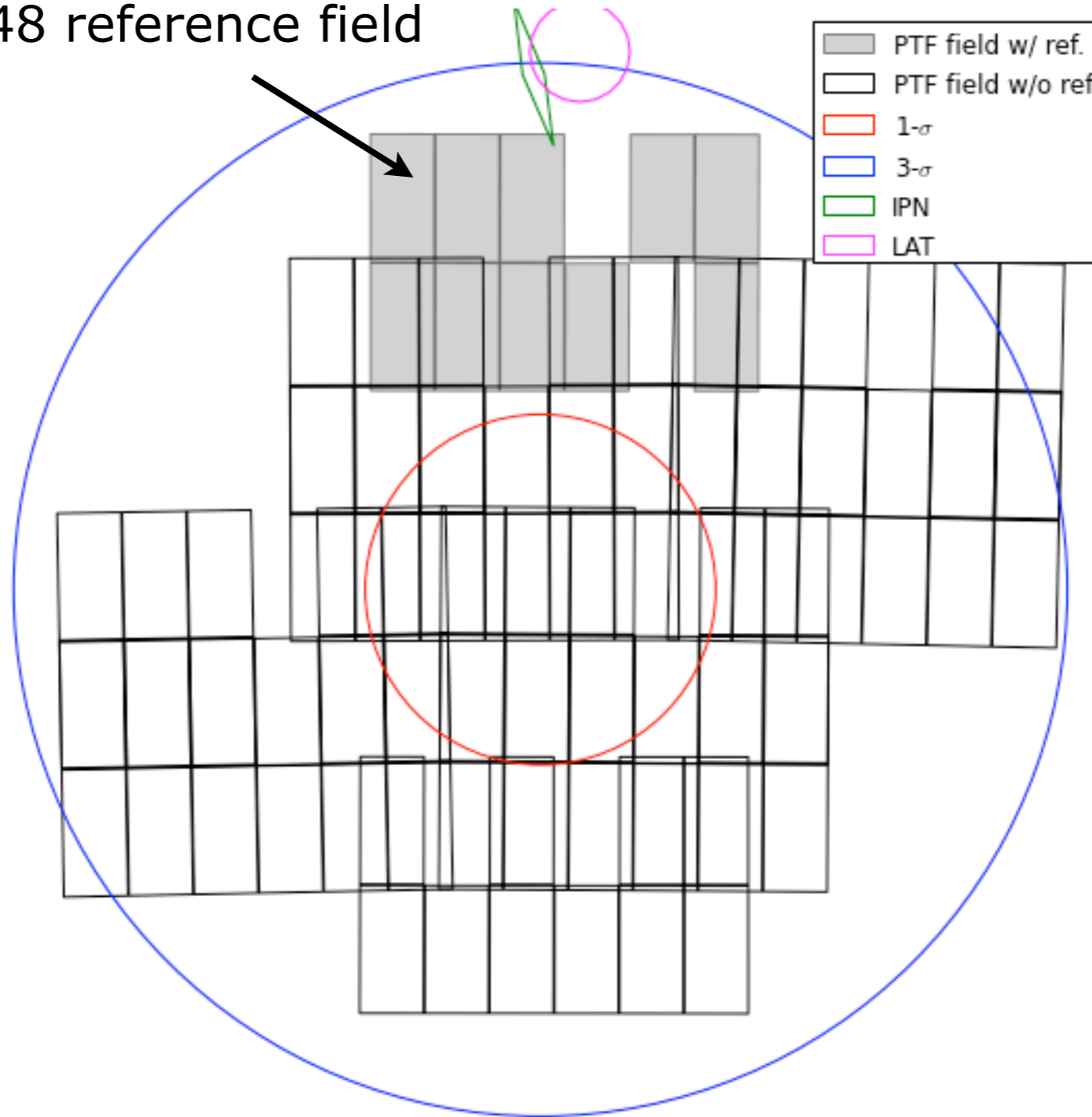
Large Area Telescope (LAT)

Gamma-ray Burst Monitor (GBM)

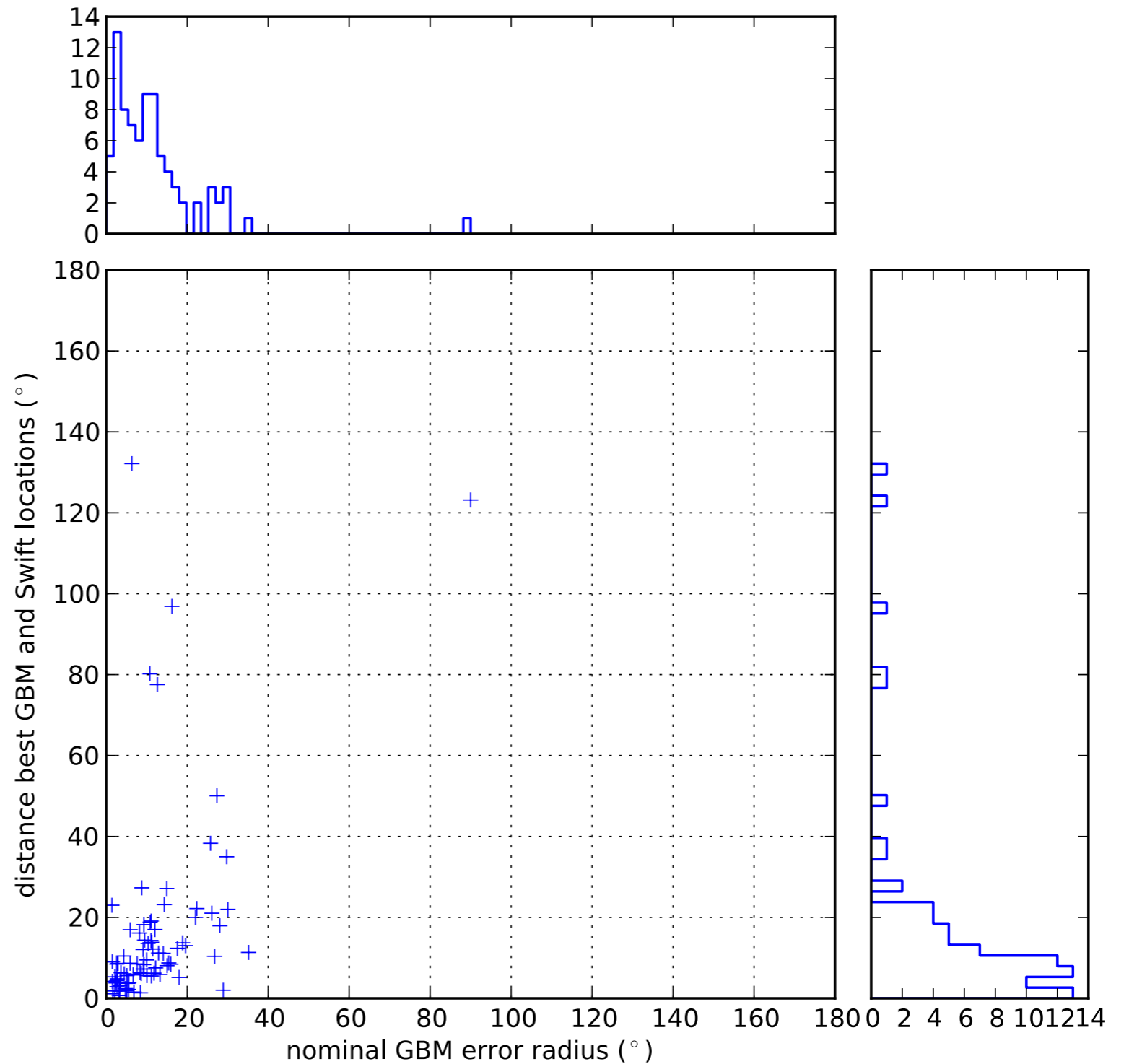
Sodium iodide (NaI) detector (1 of 12)

Bismuth germanate (BGO) detector (1 of 2)

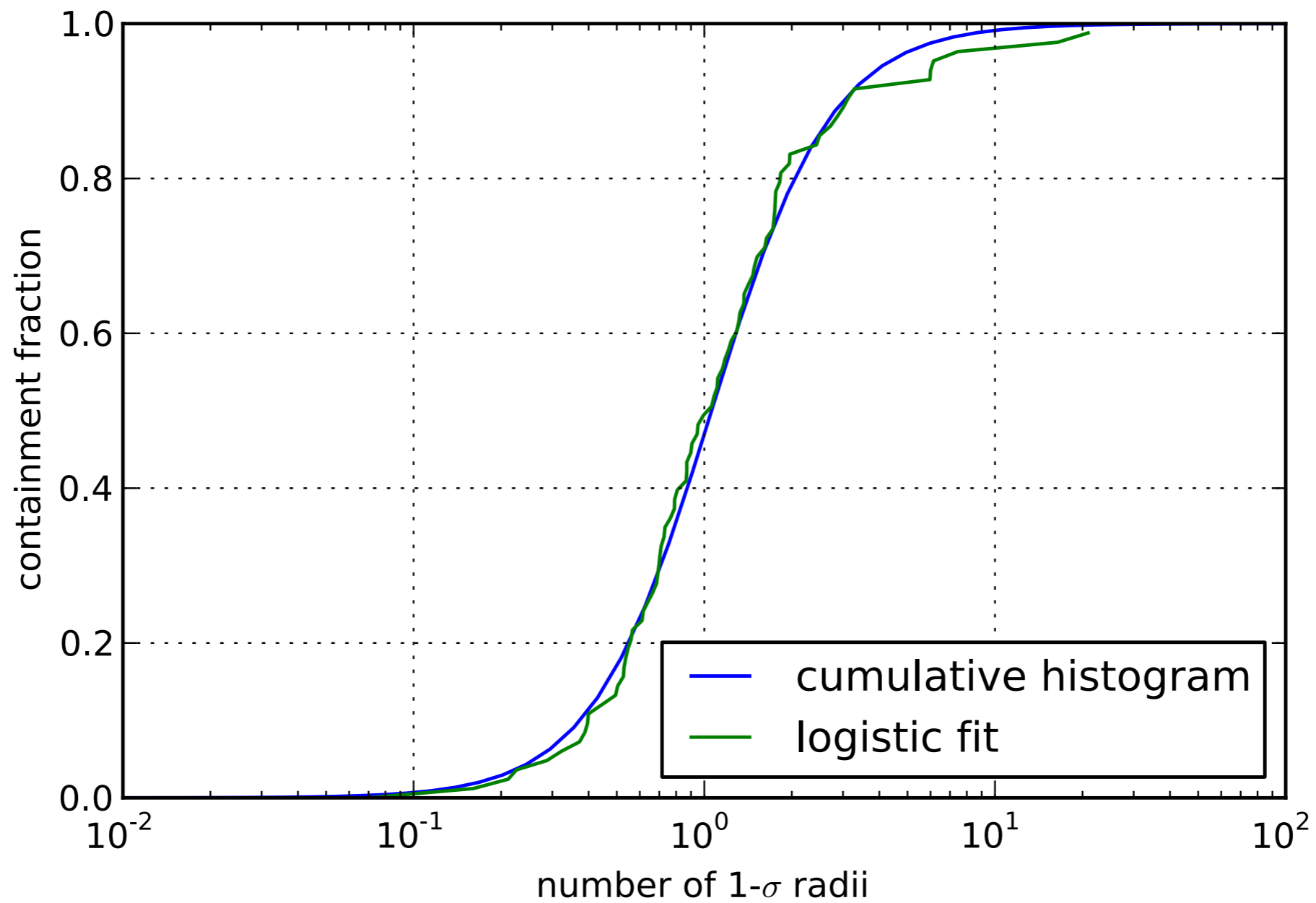
one 7.25 deg² P48 reference field

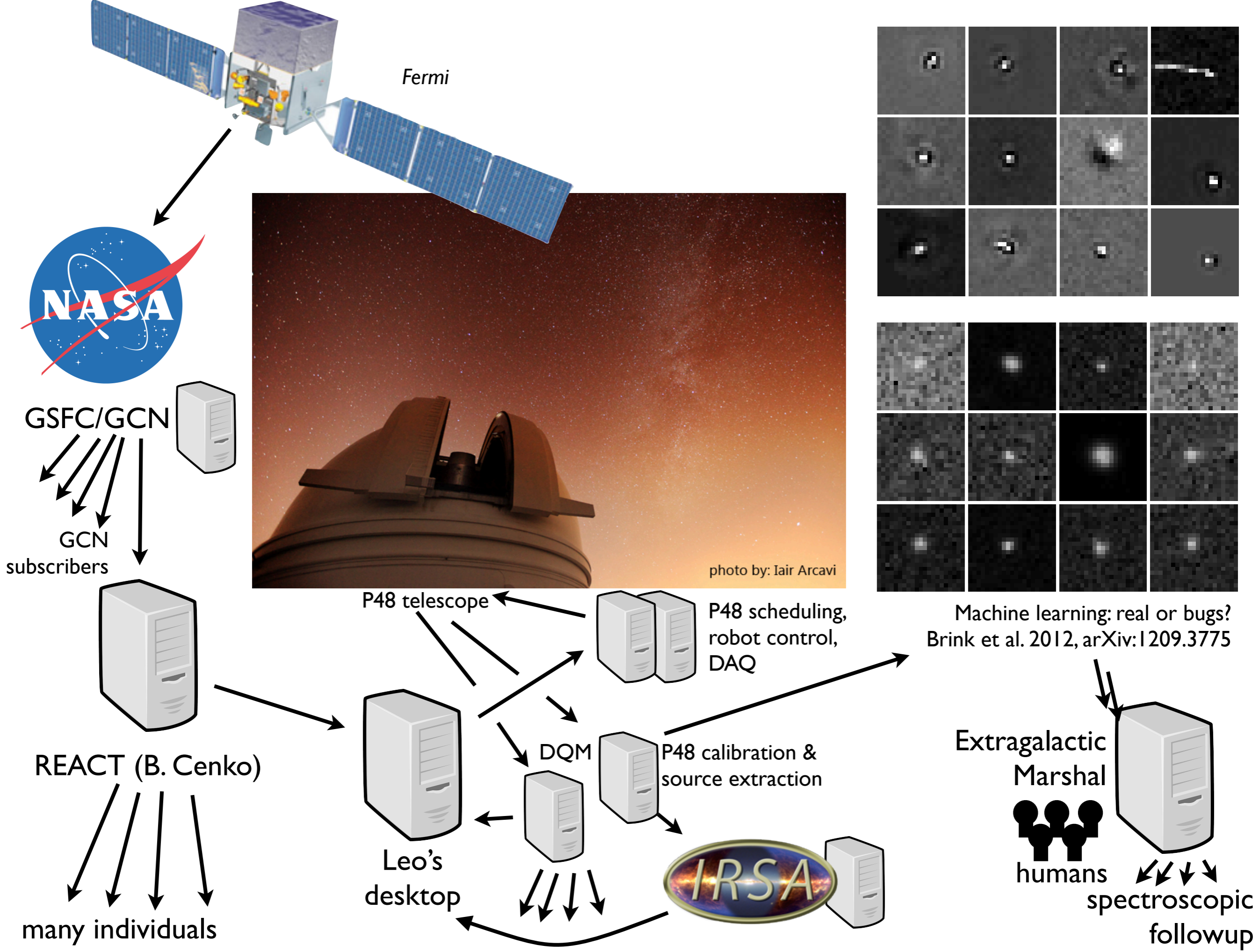


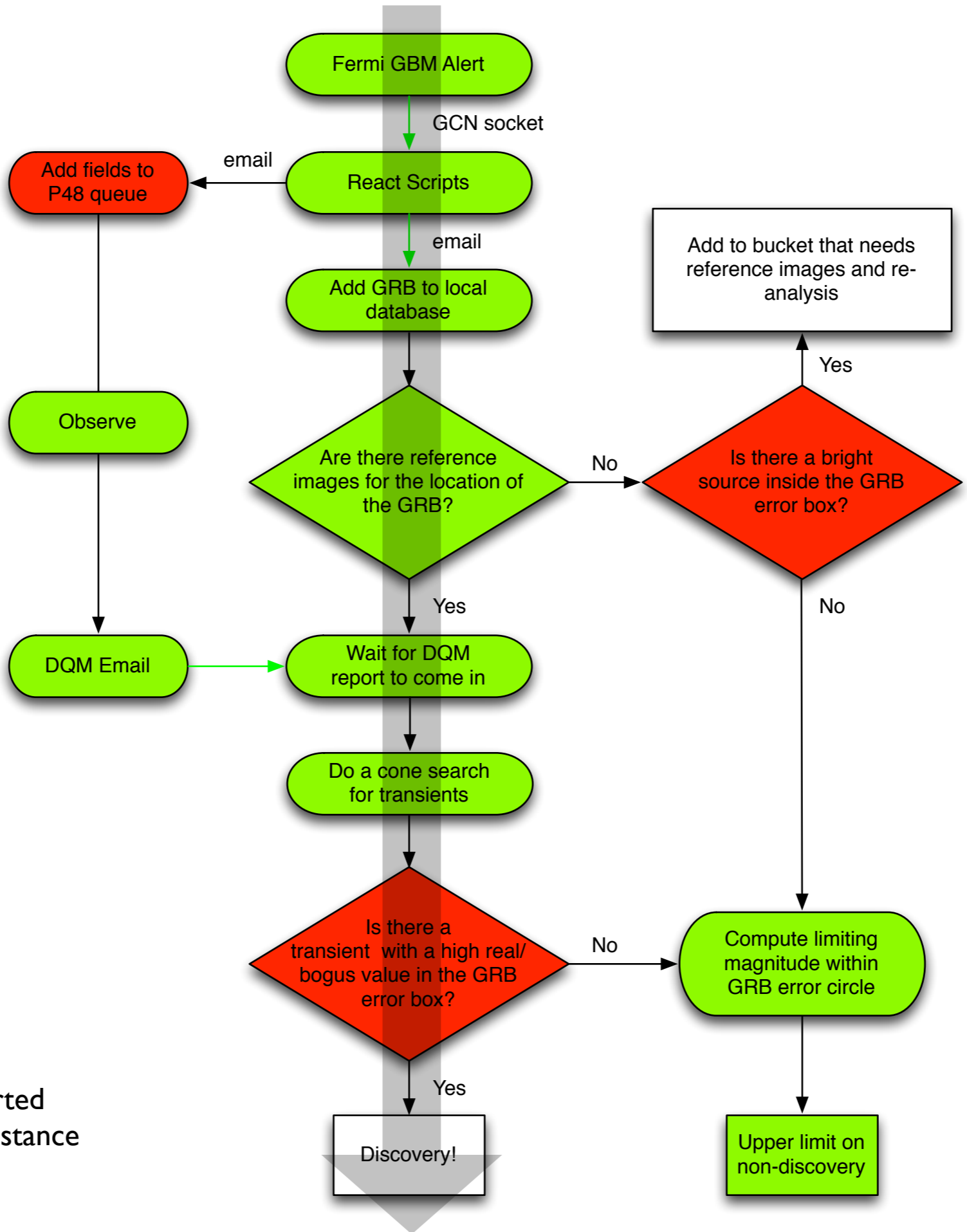
Fermi GBM triggers: localization accuracy compared with *Swift*



Estimated radial profile of *Fermi* GBM localization errors







green=done
 red=blocked
 uncolored=not started
 gray=path of least resistance

Photometric upper limits for UVOT event

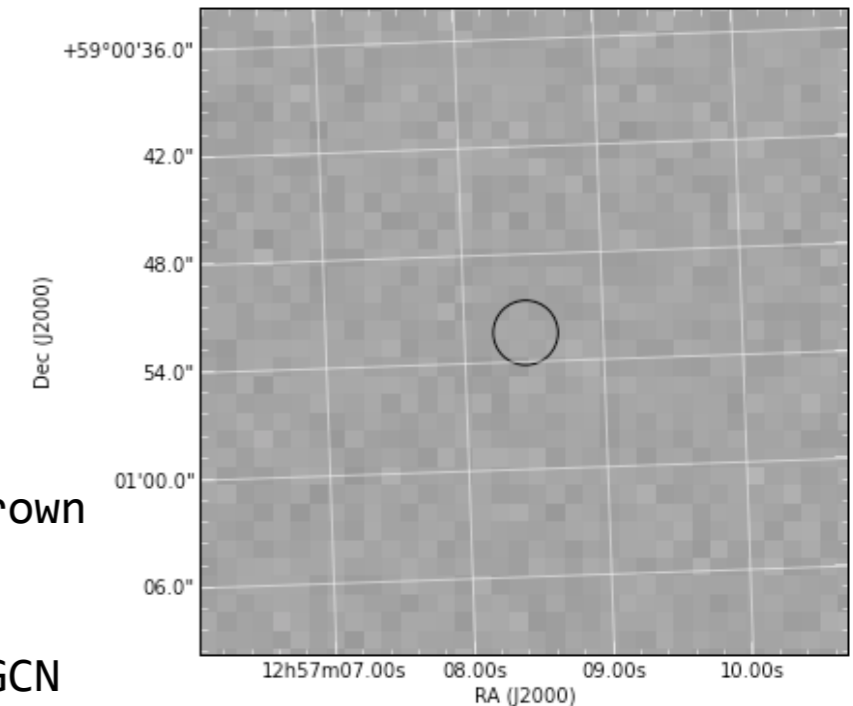
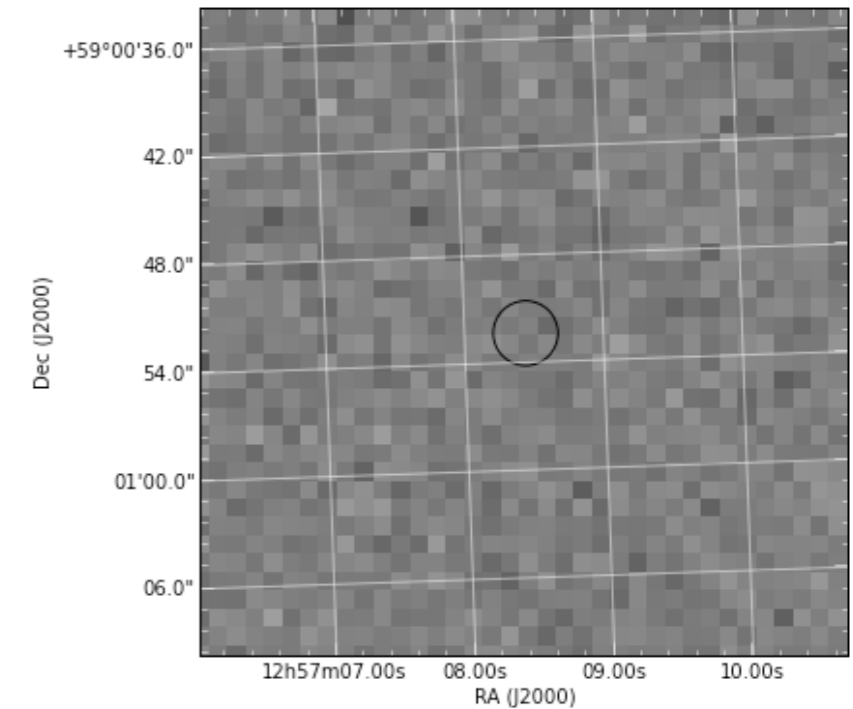
aperture photometry using P48 calibration

TITLE: GCN CIRCULAR
NUMBER: 14192
SUBJECT: GRB 130122A: PTF P48 optical upper limits
DATE: 13/02/09 15:33:37 GMT
FROM: Leo Singer at CIT/PTF <lsinger@caltech.edu>

L. P. Singer (Caltech), S. B. Cenko (UC Berkeley), and D. A. Brown (Syracuse) report on behalf of a larger collaboration:

We have imaged the **3-sigma Swift UVOT error circle** (P. Evans, GCN 14143) of GRB130122A (Swift546731, S. Barthelmy, GCN 14140) with the Palomar 48 inch Oschin telescope (P48) as part of the Palomar Transient Factory (PTF). Images were obtained in the Mould R filter at 2013-01-23 at 06:27:39 and 07:11:25 UTC, 6.7 and 7.5 hours after the trigger.

With sporadic cloud cover and a bright moon, we find no point source, fading or otherwise, to **5-sigma limiting magnitudes of 19.1 and 18.4.**



Content-Type: text/plain; charset="us-ascii"
MIME-Version: 1.0
Content-Transfer-Encoding: 7bit
Subject: GRB 130122A: PTF P48 optical upper limits

Pipeline composes GCN circulars

Dear humans,

Would you please review and submit this GCN circular?

Thanks,
react@localhost

TITLE: GCN CIRCULAR
NUMBER: 14192
SUBJECT: GRB 130122A: PTF P48 optical upper limits
DATE: 13/02/09 15:33:37 GMT
FROM: Leo Singer at CIT/PTF <lsinger@caltech.edu>

L. P. Singer (Caltech), S. B. Cenko (UC Berkeley), and D. A. Brown (Syracuse) report on behalf of a larger collaboration:

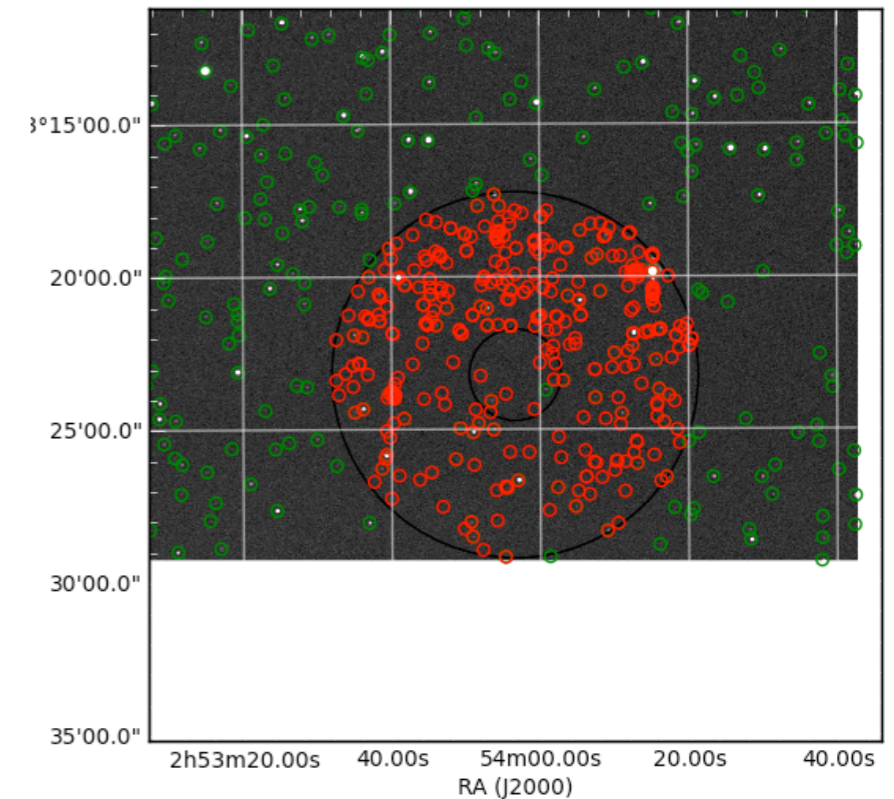
We have imaged the 3-sigma Swift UVOT error circle (P. Evans, GCN 14143) of GRB130122A (Swift546731, S. Barthelmy, GCN 14140) with the Palomar 48 inch Oschin telescope (P48) as part of the Palomar Transient Factory (PTF). Images were obtained in the Mould R filter at 2013-01-23 at 06:27:39 and 07:11:25 UTC, 6.7 and 7.5 hours after the trigger.

With sporadic cloud cover and a bright moon, we find no point source, fading or otherwise, to 5-sigma limiting magnitudes of 19.1 and 18.4.

Multiple detection of BAT event in catalog search

light curve power law index measured

TITLE: GCN CIRCULAR
NUMBER: 14244
SUBJECT: GRB 130215A: PTF P48 optical detection
DATE: 13/02/21 06:08:29 GMT
FROM: Leo Singer at CIT/PTF <lsinger@caltech.edu>



L. P. Singer (Caltech), S. B. Cenko (UC Berkeley), and D. A. Brown (Syracuse) report on behalf of a larger collaboration:

We have imaged the 3-sigma Swift BAT error circle (S. Barthelmy, GCN 14214) of GRB130215A (Swift548760, S. Barthelmy, GCN 14204) with the Palomar 48 inch Oschin telescope (P48) as part of the Palomar Transient Factory (PTF).

Images were obtained in the Mould R filter on 2013-02-15 at 02:35:05 and 04:05:52 UTC, 1.1 and 2.6 hours after the trigger. We detect a fading point source that is absent in the USNO B-1 catalog at magnitudes of 16.38 and 17.59 at

RA(J2000) = 2h 54m 00.73s

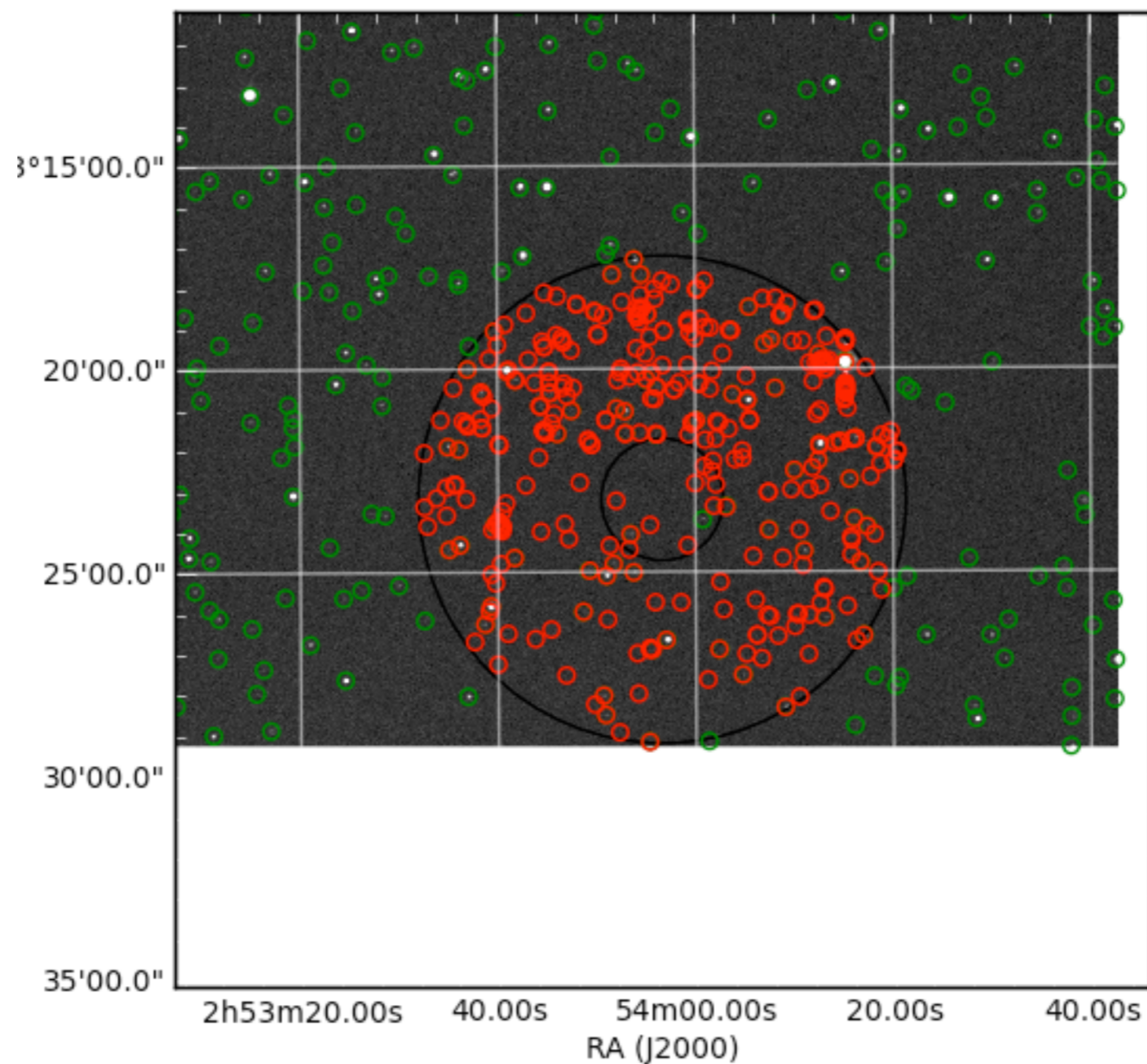
DEC(J2000) = +13d 23' 43.0"

, matching the ROTSE-IIIb position (GCN 14205, Zheng & Flewelling).

Assuming a power-law decay, these two P48 observations give us an index $\alpha = -1.25$, consistent with the index of $\alpha = -1.24$ reported by ROTSE analysis (GCN 14208, Zheng et al.).

Multiple detection of BAT event in catalog search

light curve power law index measured



Deeper photometric limit in good observing conditions

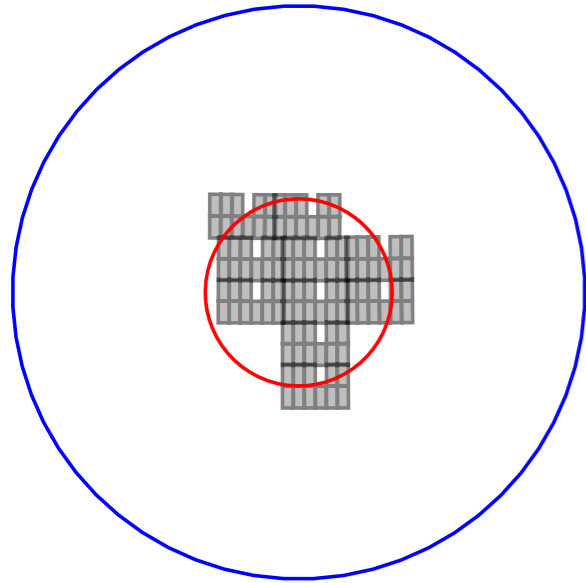
aperture photometry using P48 calibration

TITLE: GCN CIRCULAR
NUMBER: 14313
SUBJECT: GRB 130305A: PTF P48 optical upper limits
DATE: 13/03/15 19:28:32 GMT
FROM: Leo Singer at CIT/PTF <lsinger@caltech.edu>

L. P. Singer (Caltech), S. B. Cenko (UC Berkeley), and D. A. Brown (Syracuse) report on behalf of a larger collaboration:

We have imaged the 3-sigma Swift XRT error circle (D. Malesani, GCN 14263) of GRB130305A (Fermi384176354, J. R. Cummings, GCN 14257) with the Palomar 48 inch Oschin telescope (P48) as part of the Palomar Transient Factory (PTF). Images were obtained in the Mould R filter at 2013-03-06 at 05:13:35 and 05:56:17 UTC, 17.6 and 18.3 hours after the trigger.

We find no point source, fading or otherwise, to **5-sigma limiting magnitudes of 20.8 and 20.8.**

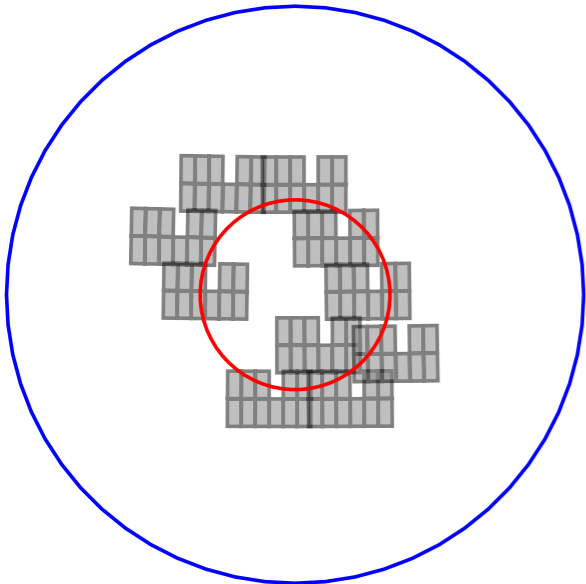


Fermi trigger from Friday, result so far:

dozens of variable stars

some image subtraction muck

two likely background supernovae, awaiting classification

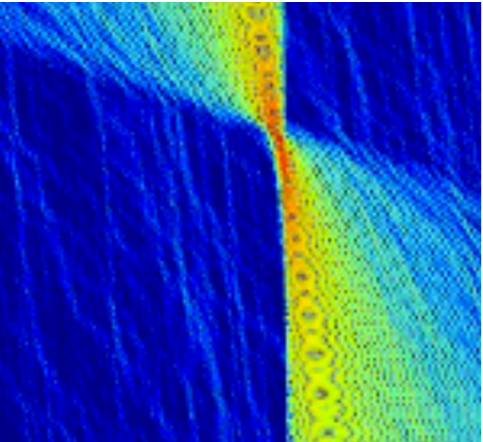


Fermi trigger from last night

more follow-up observations tonight

How do we get there?

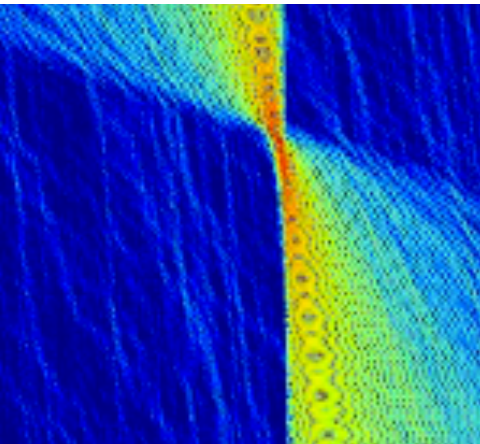
How do we get there?



low-latency event detection

seems to be in hand

How do we get there?

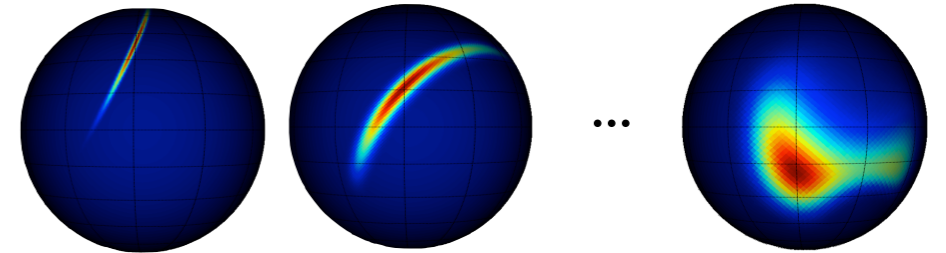


low-latency event detection

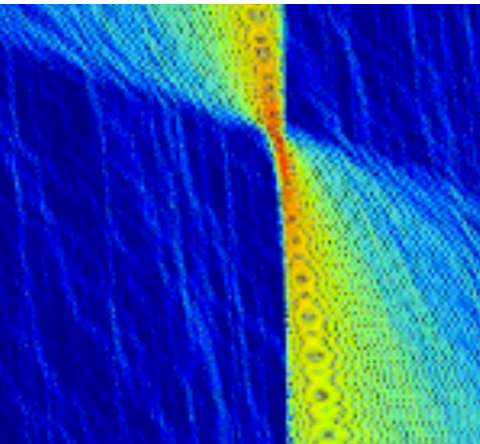
seems to be in hand

rapid sky localization

as shown by engineering runs and mock data challenges,
demonstrably ready now, but can be improved a little bit



How do we get there?

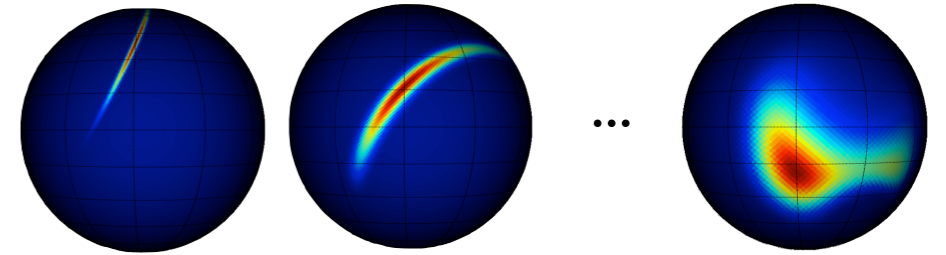


low-latency event detection

seems to be in hand

rapid sky localization

as shown by engineering runs and mock data challenges, demonstrably ready now, but can be improved a little bit



optical follow-up

the hard part: largely uncharted territory, *hic sunt dracones...*



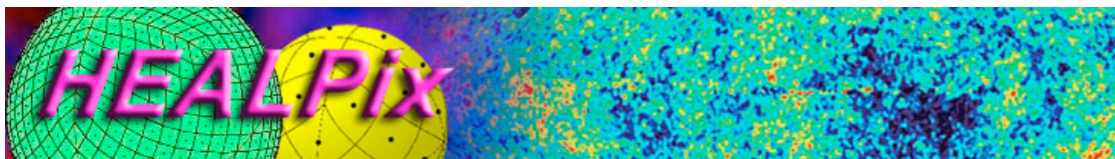
Acknowledgements

My advisor: Alan Weinstein

Larry Price, Chad Hanna, Brad Cenko, Duncan Brown, Ben Farr, and many other collaborators...

LIGO Laboratory

Palomar Transient Factory



NSF Graduate Research Fellowship



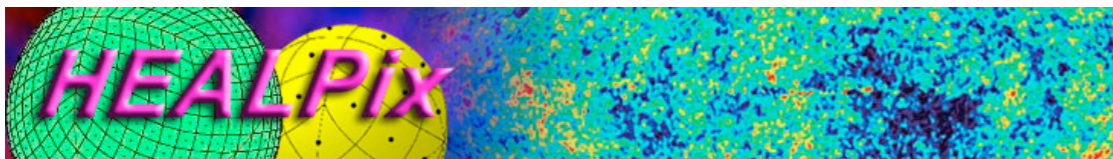
Acknowledgements

My advisor: Alan Weinstein

Larry Price, Chad Hanna, Brad Cenko, Duncan Brown, Ben Farr, and many other collaborators...

LIGO Laboratory

Palomar Transient Factory



NSF Graduate Research Fellowship

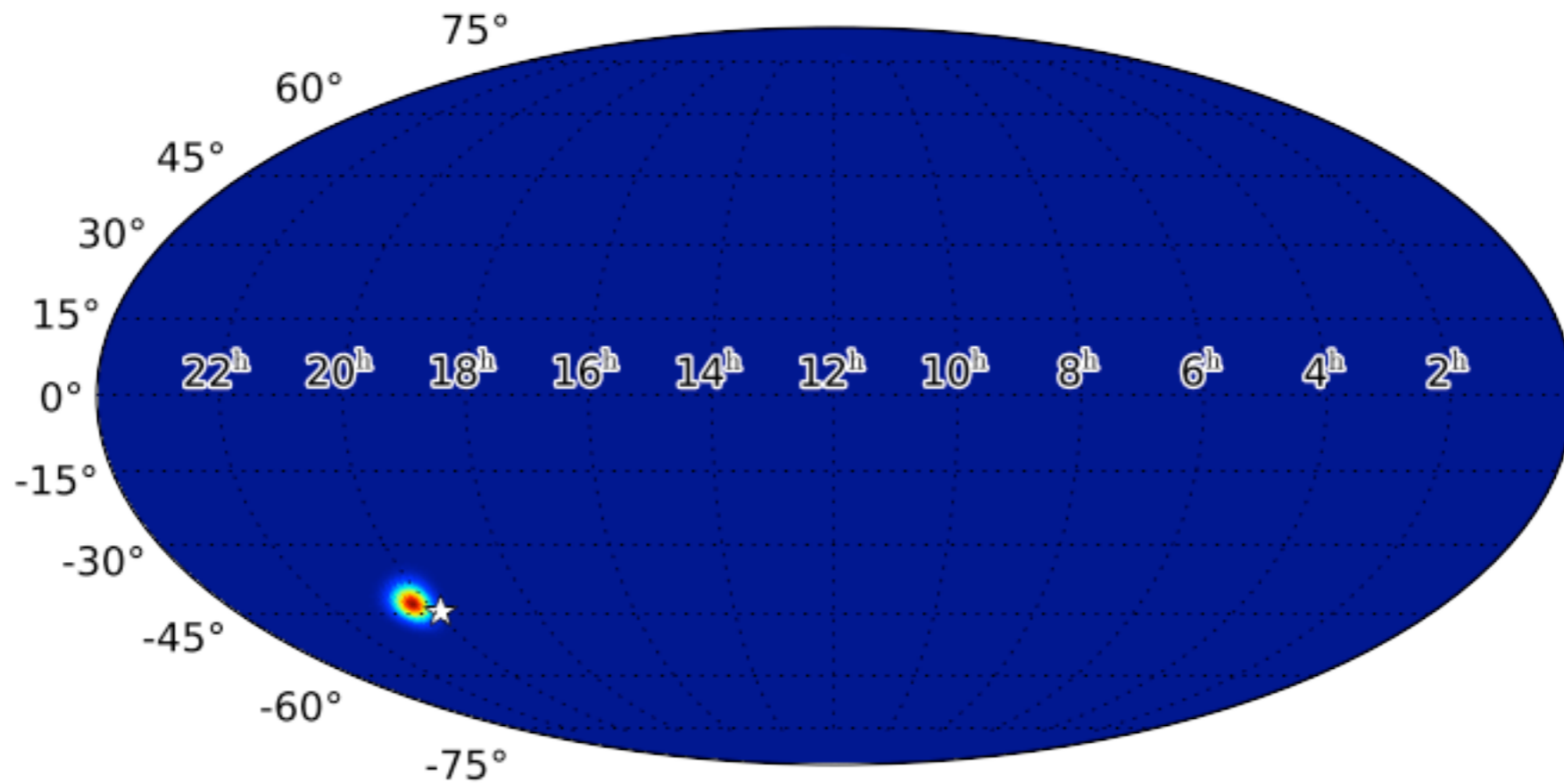


Extra slides

ER3: Injections Found

4 low-mass triggers, all reported by gstlal

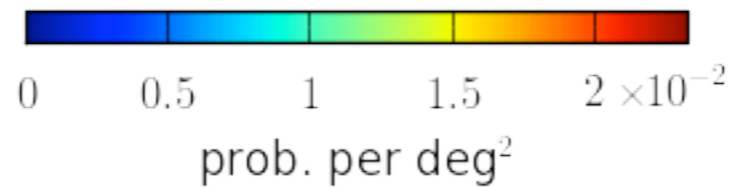
G71031



true location
19h51m58.39s
-44°36'10.2"

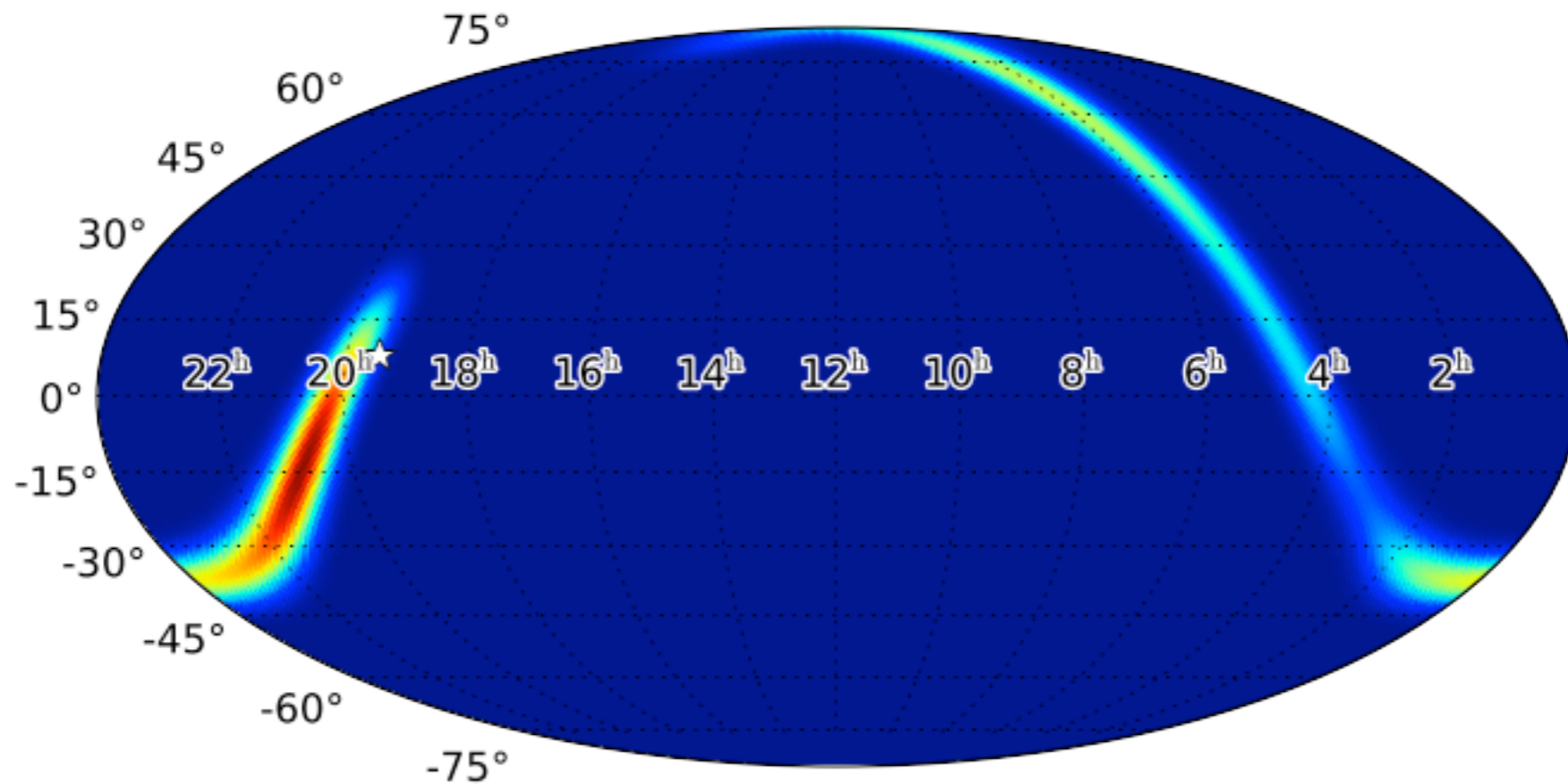
maximum *a posteriori* estimate
20h18m34.29s
-42°36'35.3"

found at confidence level: 96%
enclosing area: 140 deg²
offset: 5.2°



Event Type: LowMass
MChirp: 1.191
MTot: 2.75351202488
End Time: 1045019974.847648153
SNR: 13.656
IFOs: H1,L1,V1
FAR: 8.053e-11

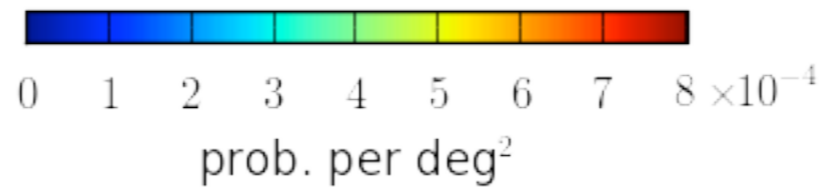
G71593



true location
19h25m10.65s
+7°53'50.3"

maximum *a posteriori* estimate
20h51m33.75s
-14°28'39.0"

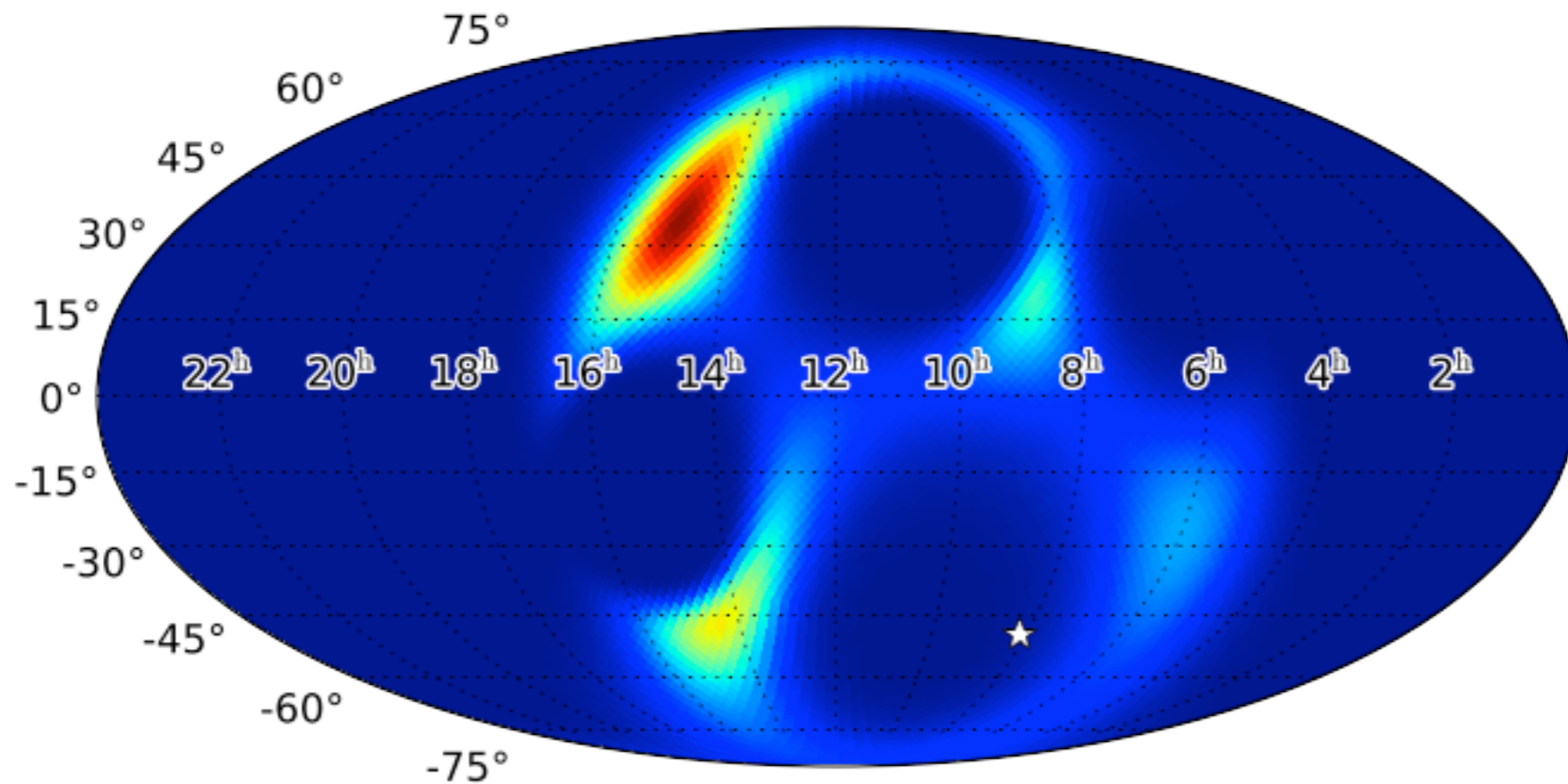
found at confidence level: 92%
enclosing area: 3240 deg²
offset: 31°



Event Type: LowMass
MChirp: 1.533
MTot: 3.53183591366
End Time: 1045456996.50528038
SNR: 10.271
IFOs: H1,L1
FAR: 1.226e-04

note: “freak” event,
with V1 in an artificially
sensitive state

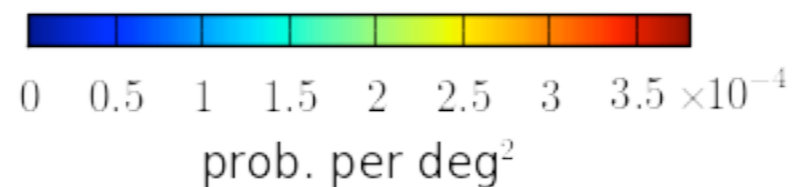
G71627



true location
8h04m29.85s
-49°37'08.1"

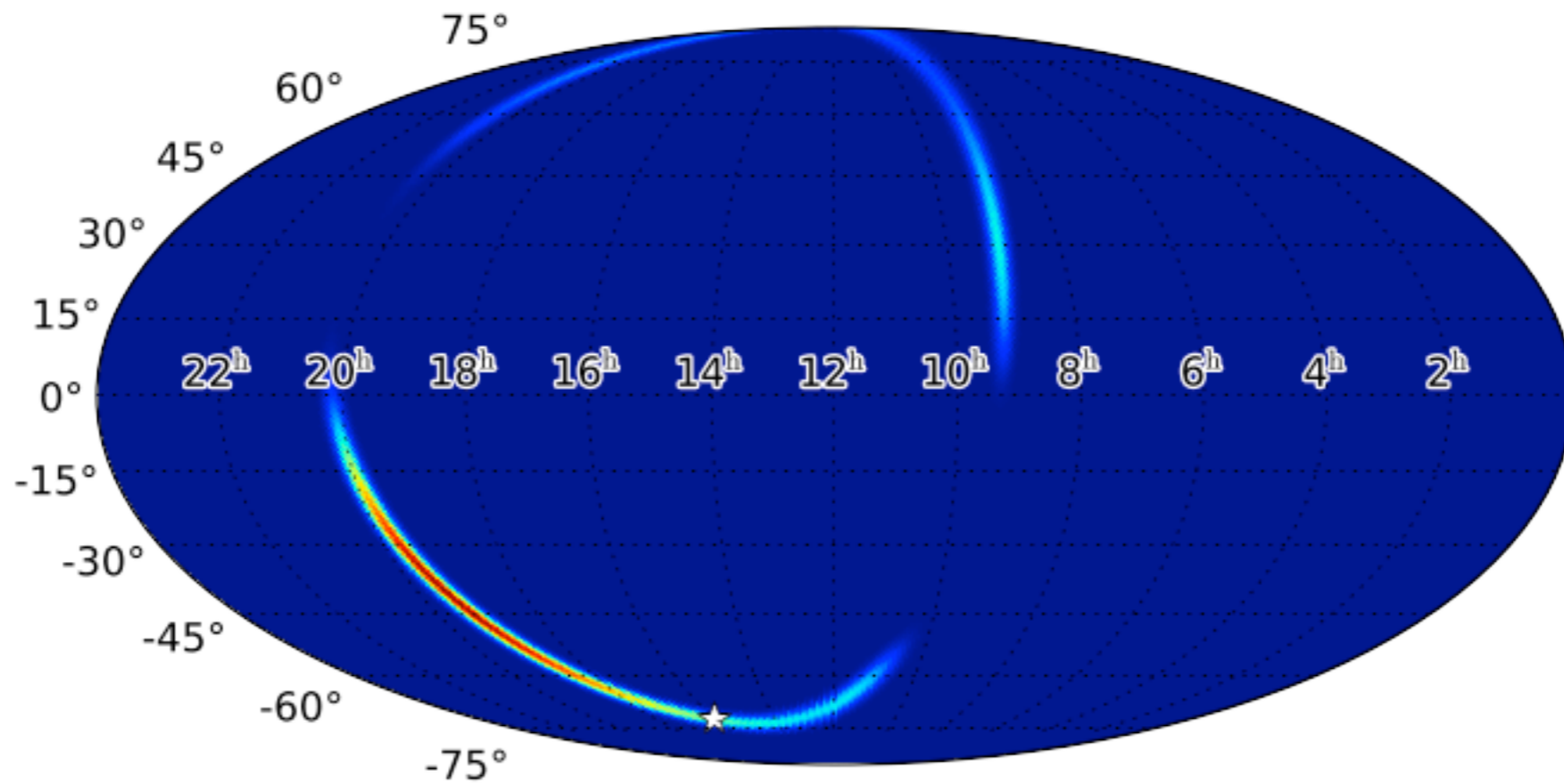
maximum *a posteriori* estimate
14h54m22.50s
+35°41'07.2"

found at confidence level: 99%
enclosing area: 15725 deg²
offset: 124°



Event Type: LowMass
MChirp: 4.536
MTot: 17.7093279362
End Time: 1045473314.707031385
SNR: 12.672
IFOs: L1,V1
FAR: 1.367e-10

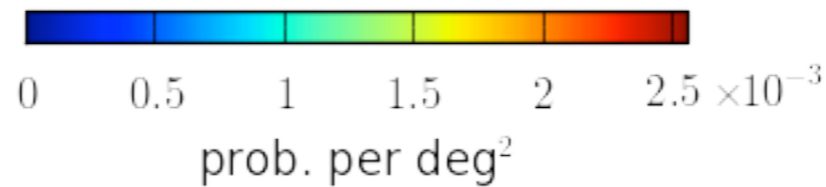
G71831



true location
16h06m35.63s
-71°58'40.0"

maximum *a posteriori* estimate
19h30m00.00s
-39°27'03.2"

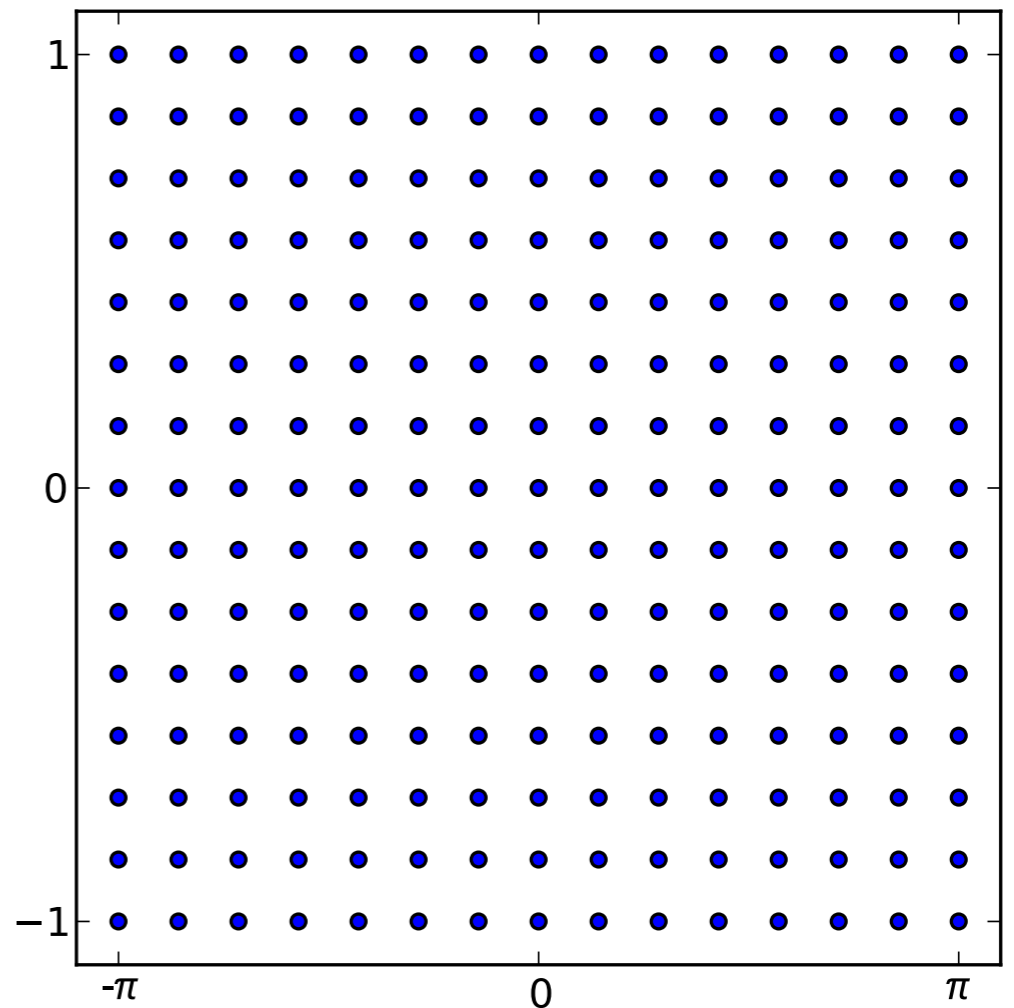
found at confidence level: 40%
enclosing area: 223 deg²
offset: 41°



Event Type: LowMass
MChirp: 1.355
MTot: 3.15994691849
End Time: 1045702467.740710217
SNR: 10.954
IFOs: L1,V1
FAR: 1.848e-06

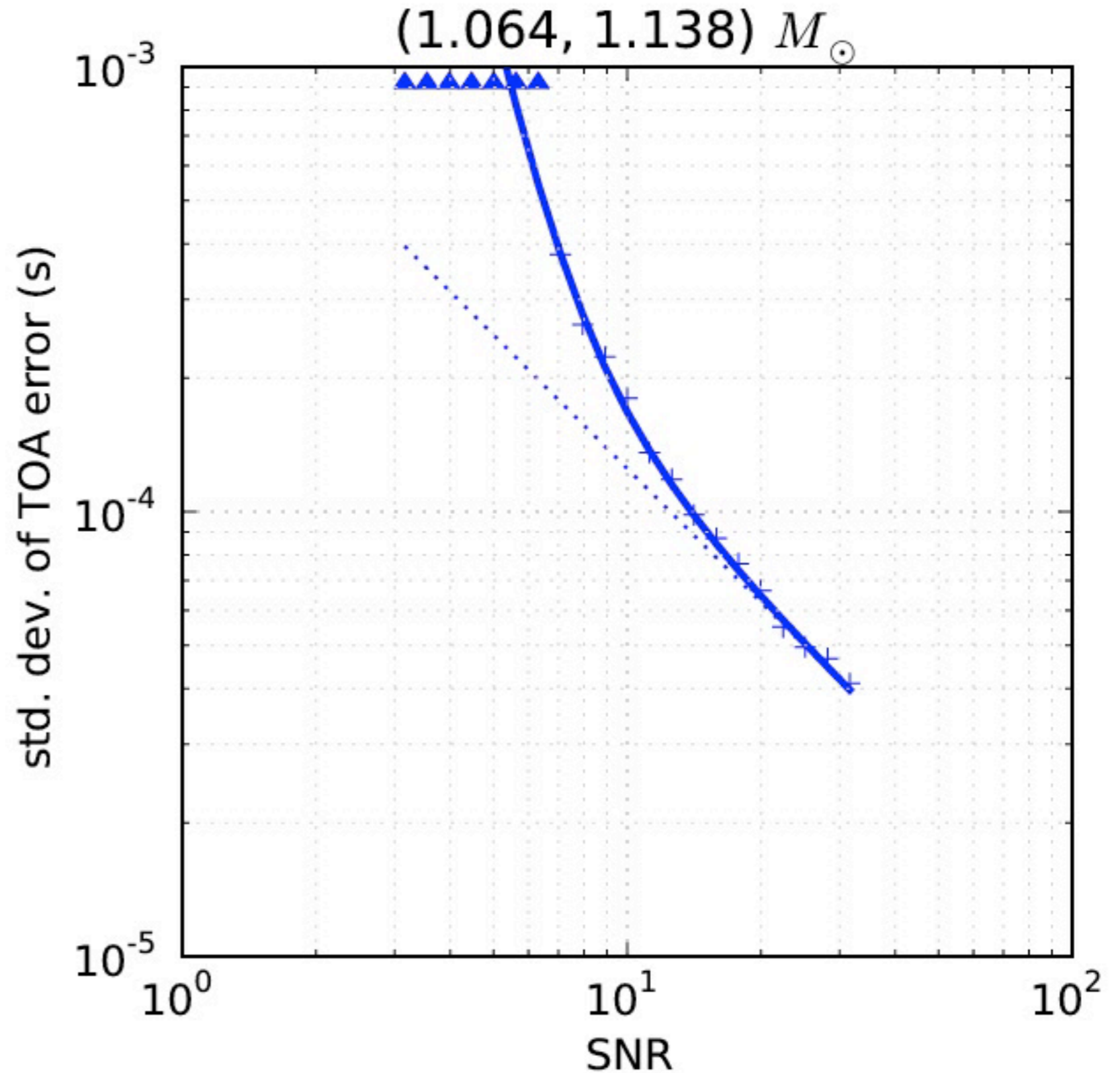
Orientation integral

- Newton-Cotes quadrature in $\psi, \cos \iota$



The devil is in the details...

- σ_t veers from $1/\rho$ dependence at $\rho \sim 10$
- Proper relation of σ_t vs. ρ critical for self-consistency
- Lots of ideas:
 - Nicholson & Vecchio 1998, PRD 57, 4588
 - ‘beyond Fisher information’ series expansions
 - Zanolin et al. 2010, PRD, 81, 124048
 - Vitale & Zanolin 2010, PRD 82, 124065
 - ‘effective Fisher information’
 - Cho et al. 2013, PRD, 87, 024004



crosses: measurement of timing uncertainty by numerical experiment
dashed line: Cramér-Rao bound
heavy line: Barankin bound
E.W. Barankin, Ann. Math. Stat., 20, 477
w/fudge factor of π (!?)

The devil is in the details...

Barankin bound on s^{th} central moment of function h :

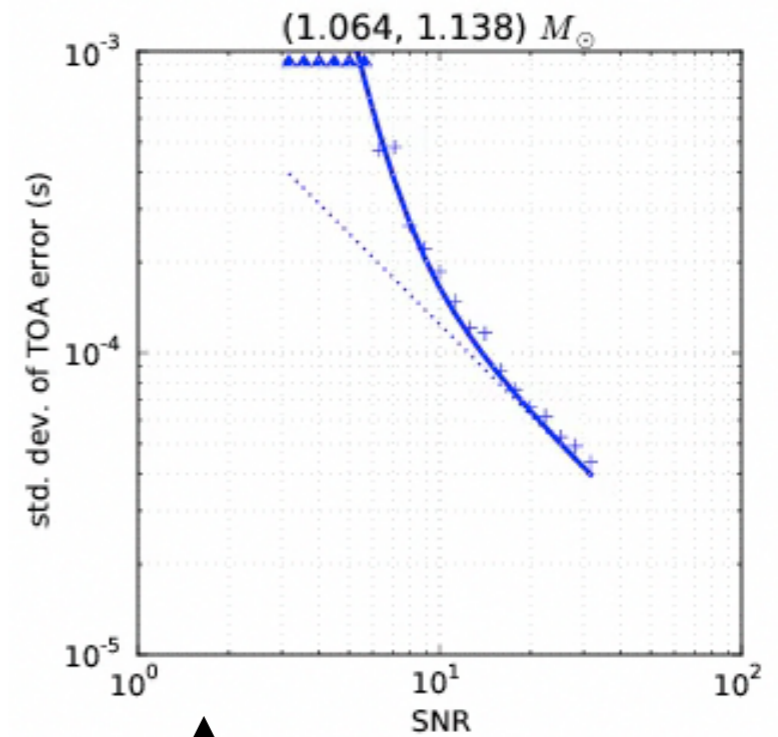
$$\sigma_s \geq \sup_{\substack{\theta_1, \dots, \theta_n \in \Theta \\ a_1, \dots, a_n \in \mathbb{R} \\ n \in \mathbb{Z}^+}} \frac{\left| \sum_{i=1}^n a_i h(\theta_i) \right|}{\left\| \sum_{i=1}^n a_i \pi_{\theta_i} \right\|_r}$$

test weights \downarrow a_i test points \downarrow θ_i

r^{th} norm, an integral \nearrow

likelihood ratio against θ_0 \uparrow π_{θ_i}

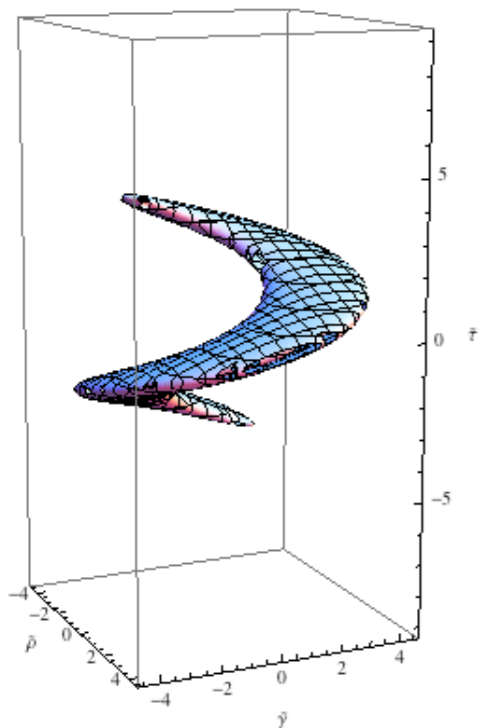
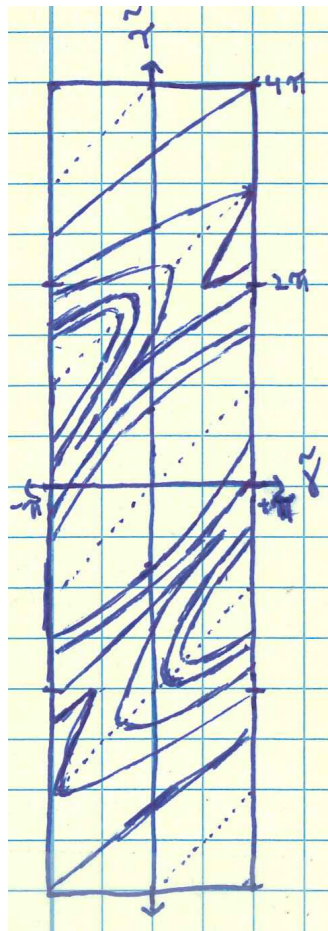
where $r = \frac{s}{s-1}$



heavy line: Barankin bound
E.W. Barankin, Ann. Math. Stat., 20, 477
w/fudge factor of π (!?)

Enhancement: fold phase measurement into likelihood

- CRB \Rightarrow time & phase errors are correlated
- Likelihood looks like Gaussian wrapped on cylinder
- At least two ways to do this:



I) Gaussian:

$$\log \mathcal{L}_{\text{net}}^{\text{I}} \sim \sum_i \left[-\frac{1}{2}(\rho_i - \hat{\rho}_i)^2 + \cos(\tilde{\gamma}_i - b_i \tilde{\gamma}_i) - \frac{1}{2}(1 - b_i^2) \tilde{\gamma}_i^2 \right]$$

II) Noncentrally χ^2 :

$$\log \mathcal{L}_{\text{net}}^{\text{II}} \sim \sum_i \left[-\frac{1}{2} \rho_i^2 - \frac{1}{2} \hat{\rho}_i^2 + \rho_i \hat{\rho}_i \cos(\tilde{\gamma}_i - b_i \tilde{\gamma}_i) - \frac{1}{2} \rho_i^2 (1 - b_i^2) \tilde{\gamma}_i^2 \right]$$