

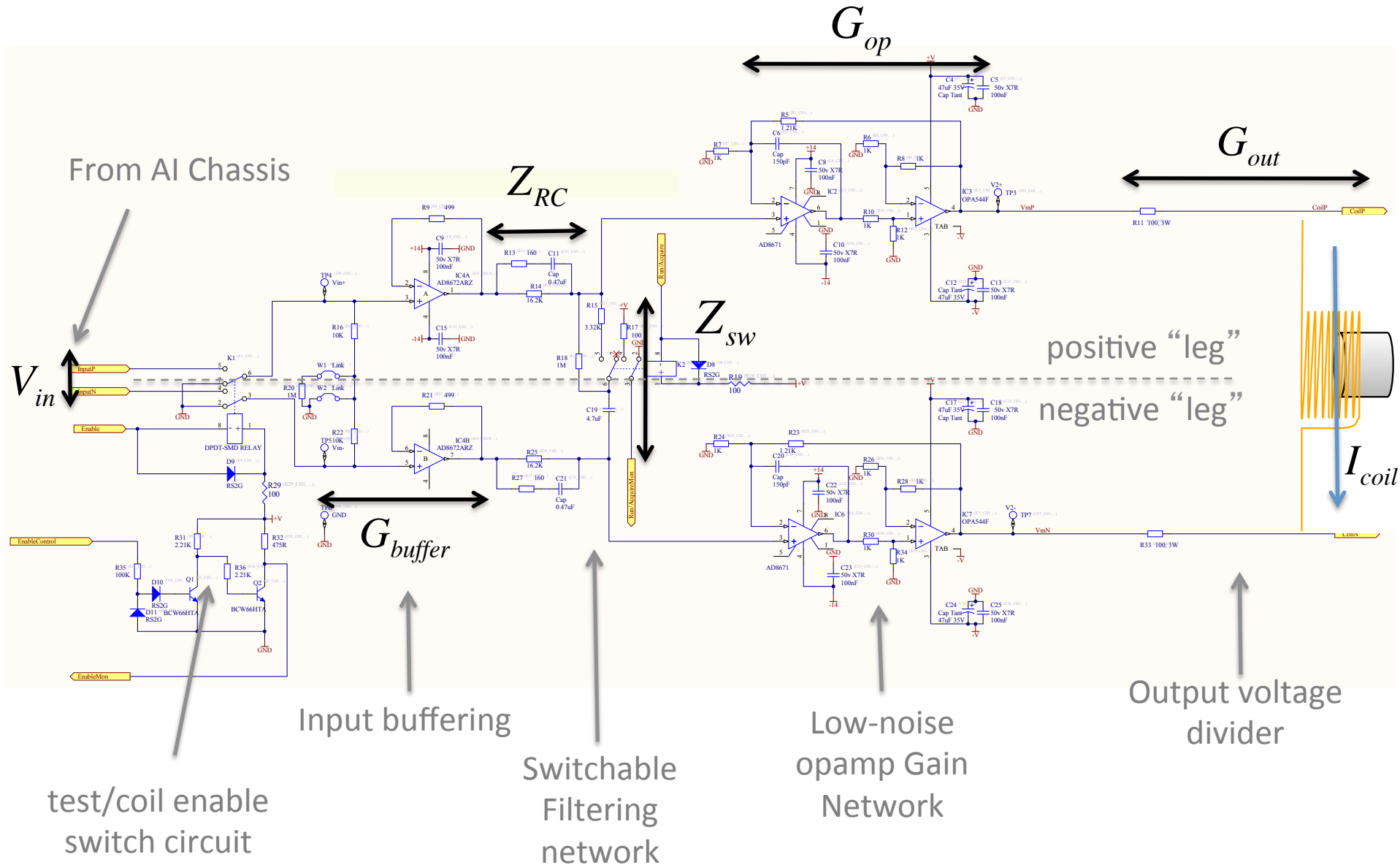
# HAM-A Coil Driver Design Study

R. Abbott, J. Kissel

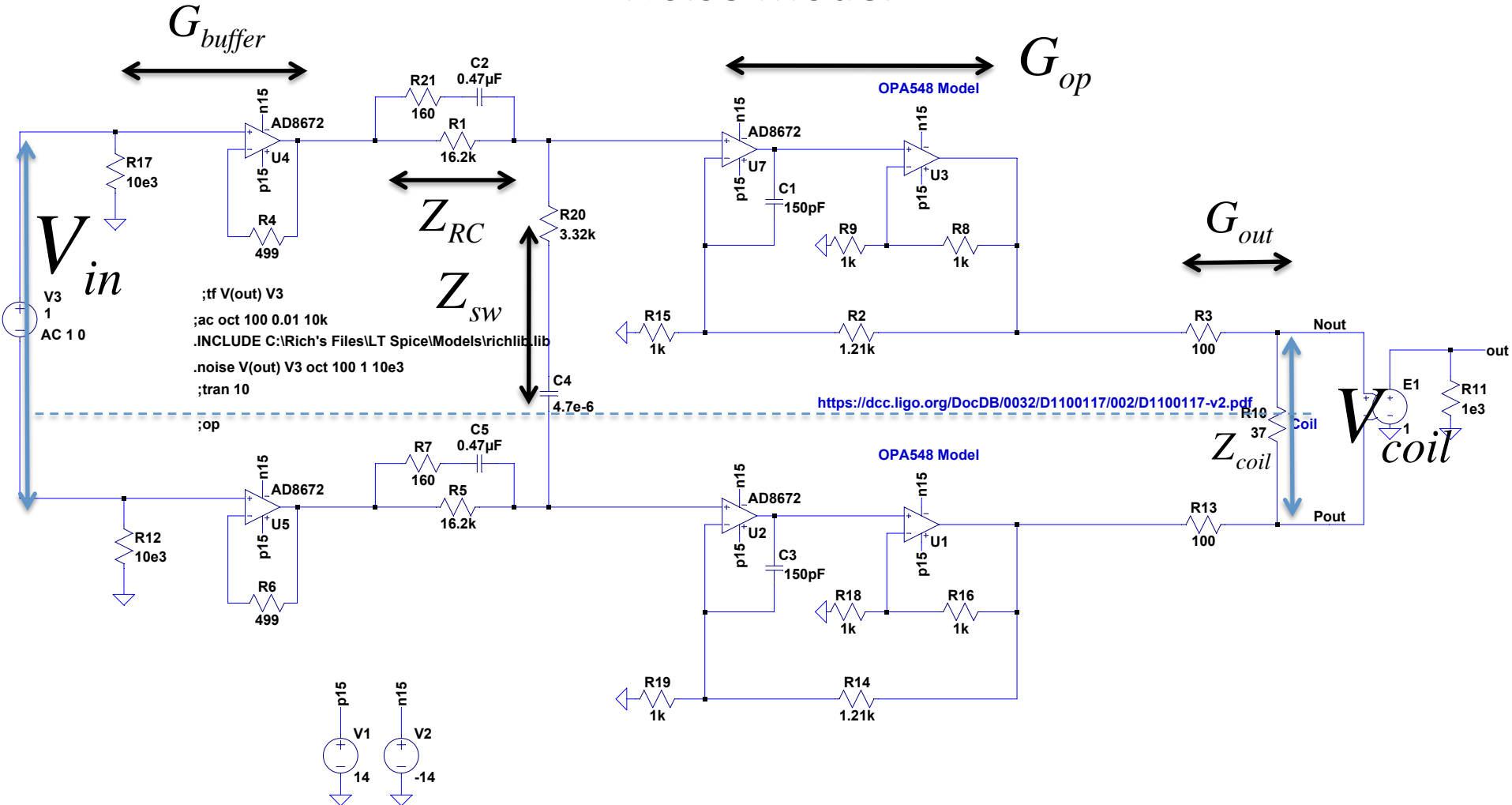
T1200264-v4

# The Full Schematic

## D1100117-v2



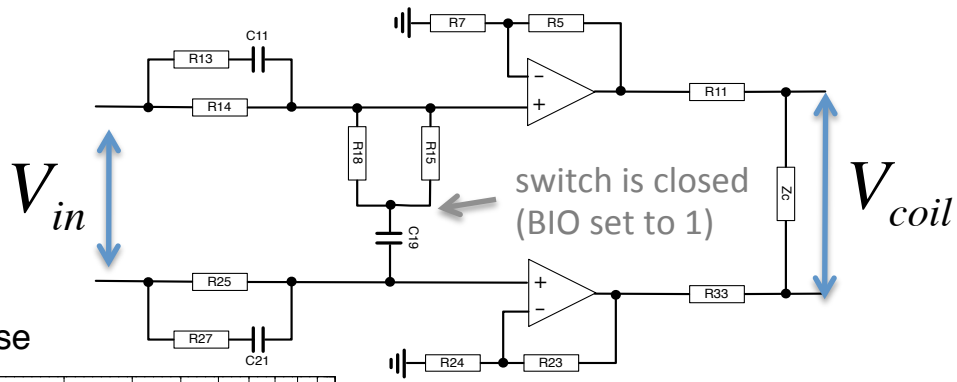
# A More Simple Schematic Noise Model



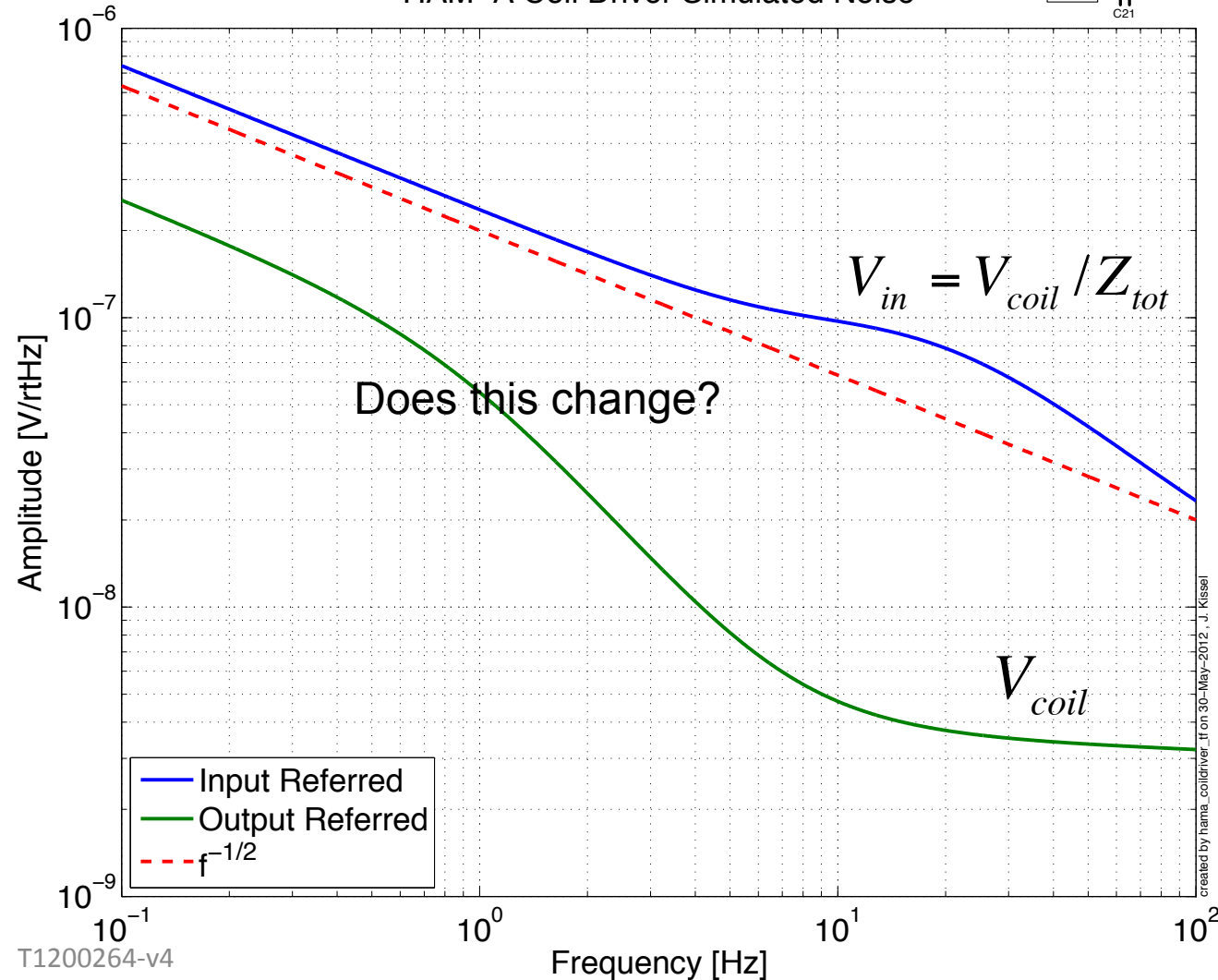
- Rich used Spice to model the input and output referred voltage noise of the driver
- Assumed the “low-noise” mode, where “acq/lp” switch is closed/enabled
- Assumed R18 portion of  $Z_{sw}$  is negligible
- Assumed  $L_{coil}$  and  $C_{cable}$  was negligible below 100 Hz

# Noise Model

## Low-Noise ("Run") Mode



HAM-A Coil Driver Simulated Noise



Note: The noise performance is \*different/worse\* in acquire mode (proportional to the change in impedance of the transfer function [see later pages]), but we're typically not worried about noise performance in high-dynamic range mode, so it's not shown

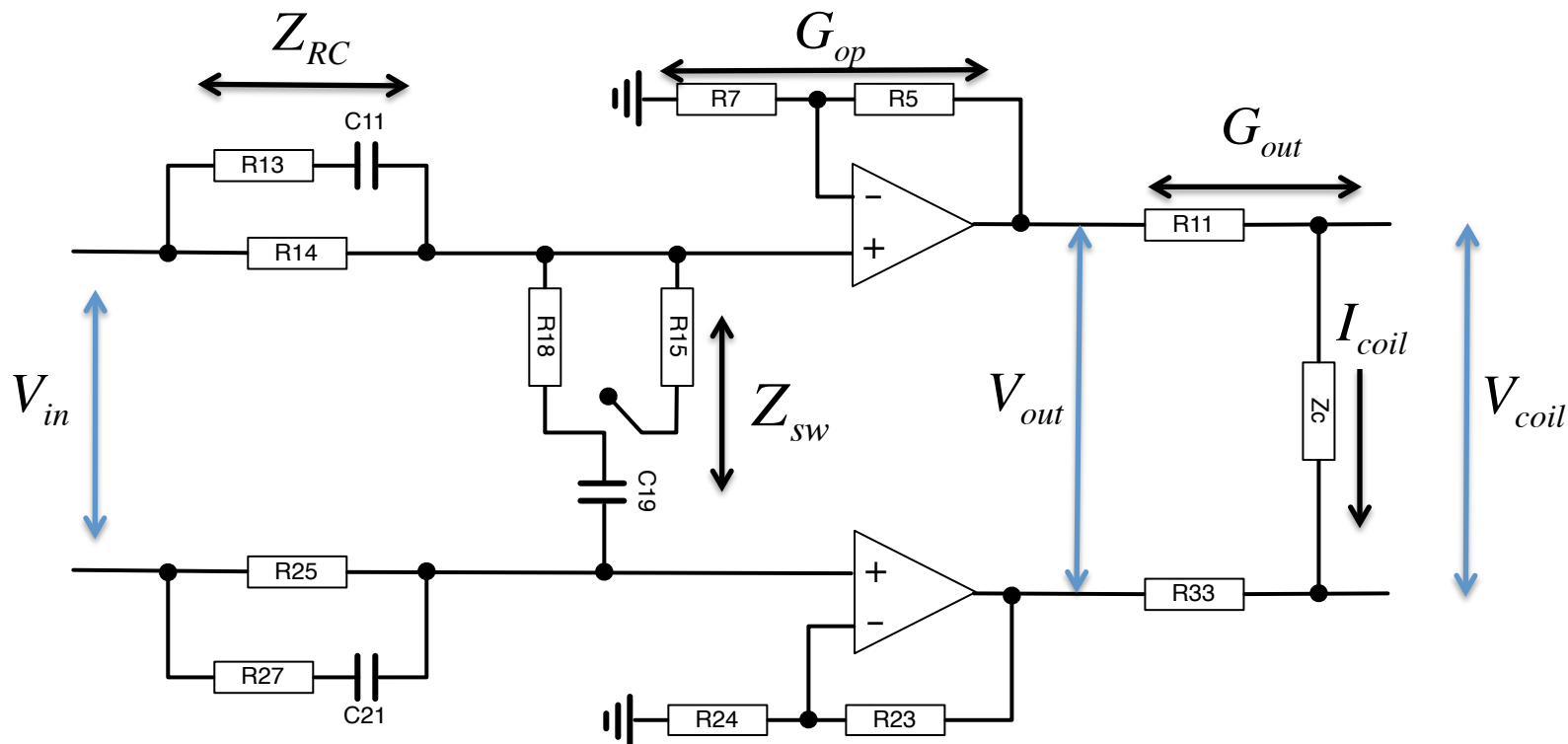
Falls as  $\frac{1}{\sqrt{f}}$

Asymptotes to 2.88 nV/rtHz

created by hama\_coildriver.tf on 30-May-2012. J. Kissel

# An Even More Simple Schematic

## Transfer Function Model



- The input buffering is designed to have a gain of 1 and no frequency response, so we ignore it.
- The complicated low-noise opamp gain network is simplified to just a non-inverting opamp, because C6 creates a high-frequency response out of the band of interest (at 10s of kHz), and the gains from R10+R12 with R6+R8 are balanced and cancel.
- Since the output resistors (R11 and R33) are usually considered tunable, and we will hook up several types of coils to the driver, we calculate the transfer function of  $V_{in}$  to  $V_{out}$  instead of to  $V_{coil}$  like Rich did for the noise calculation.
- The inductance for the OSEMs we use is non-negligible between 100 Hz and 1 kHz, so I include it in the impedance:  $Z_{coil} = R_{coil} + i\omega L_{coil}$

• However, the cable capacitance [30 pF/ft \* ~100 ft ~ 3nF] is negligible at frequencies < 10 kHz, so it's ignored

# Transfer Function Model

## The Analysis Tools


Now it's easy; we just need a few simple equations:

Converting to Impedance:

$$Z_R = R$$


$$Z_C = 1/i\omega C$$

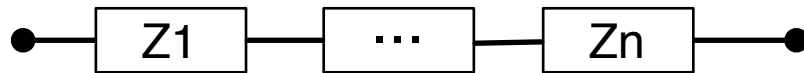
$(\omega = 2\pi f)$



$$Z_L = i\omega L$$


Series Impedance:

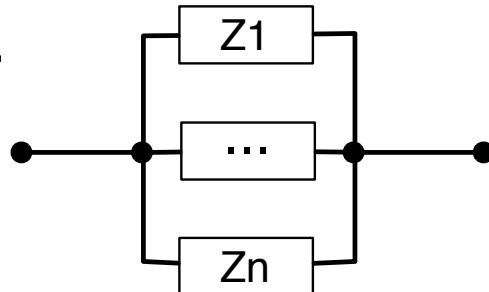
$$Z_{tot}^S = Z_1 + Z_2 + \dots$$



Parallel Impedance:

$$\frac{1}{Z_{tot}^P} = \frac{1}{Z_1} + \frac{1}{Z_2} + \dots$$

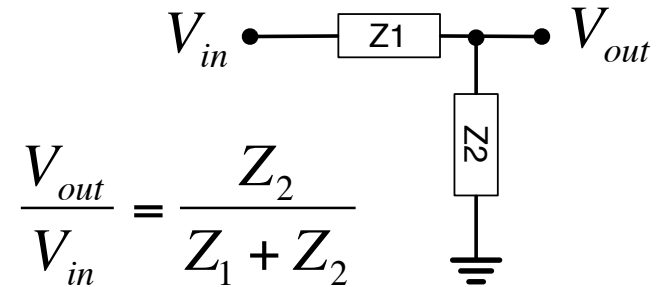
$$Z_{tot}^{P(2)} = \frac{Z_1 Z_2}{Z_1 + Z_2}$$



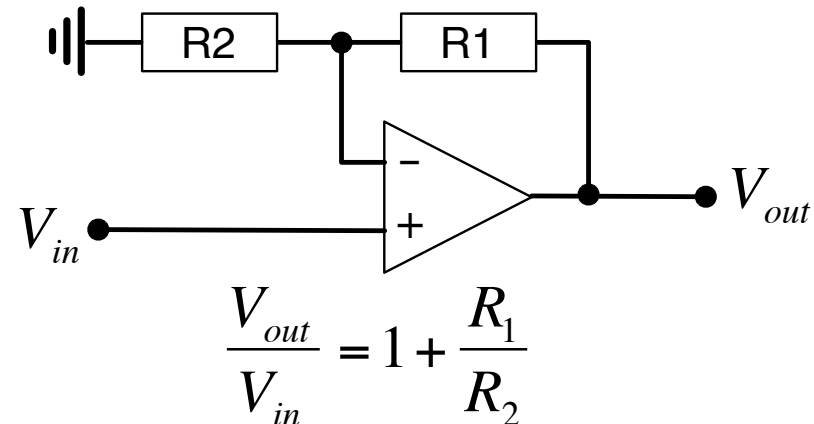
Ohm's Law:

$$V = IZ$$

Voltage Divider:

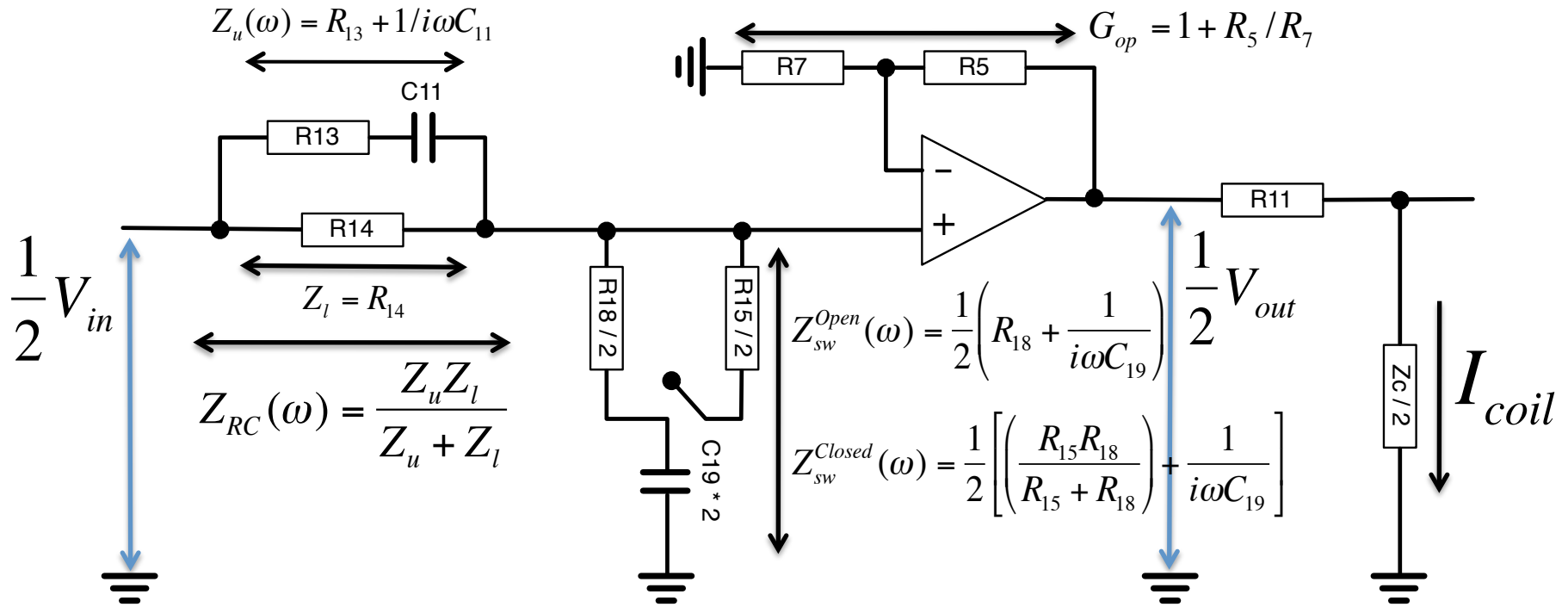


Non-inverting Op-Amp



# An Even More Simple Schematic

## Transfer Function Model



- To simplify the analysis, we can split the circuit into the positive and negative leg, by removing one leg and grounding anything that's connected/measured across the legs.
- To keep the same impedance as the differential circuit, the impedance for each component connected to "ground" is halved (" $Z$ " =  $Z/2 \rightarrow$  " $R$ " =  $R/2$ , " $C$ " =  $2C$ , " $L$ " =  $L/2$ ). This goes for  $V_{in}$  and  $V_{out}$  too, since we're also measuring with respect to "ground."

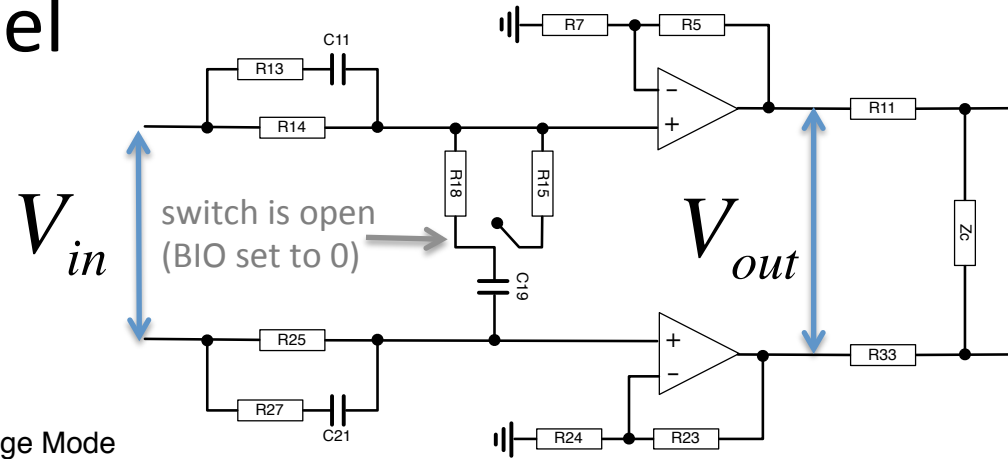
calculated as = differential single-ended

$$H = \frac{V_{out} / 2}{V_{in} / 2} = \frac{V_{out}}{V_{in}} = G_{op} \frac{Z_{sw}}{Z_{RC} + Z_{sw}}$$

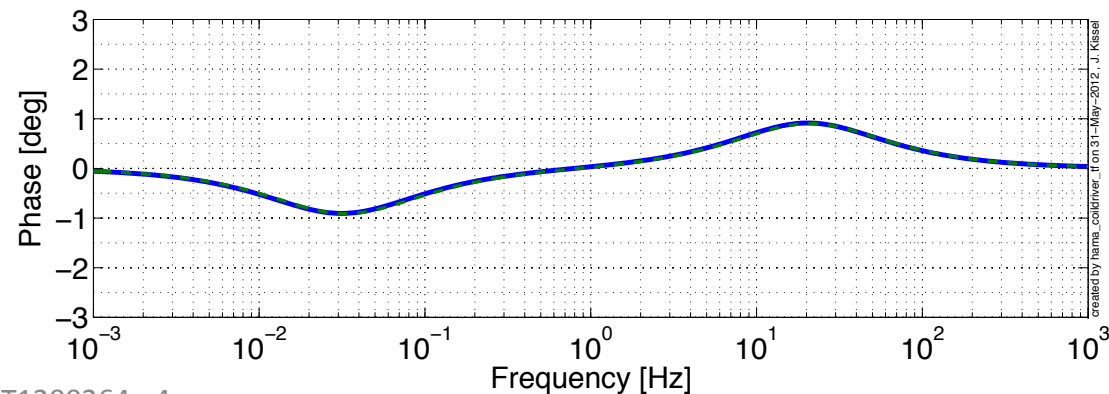
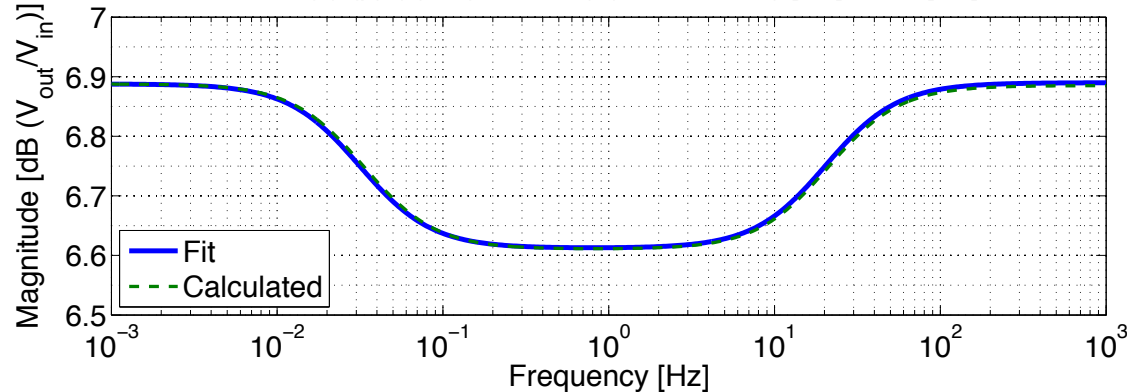
# Transfer Function Model

## High Dynamic Range Mode

a.k.a “Acquire” or just “Acq”



HAM-A Coil Driver Transfer Function, High Dyn. Range Mode  
 Fit = (z):(p):(k) = (0.032,20):(0.031,20.65) [Hz]; 6.89 [dB]



$$H = \frac{V_{out}}{V_{in}} = G_{op} \frac{Z_{sw}}{Z_{RC} + Z_{sw}}$$

Effectively Flat

(~3% drop between DC gain and  
 ~0.1-10Hz gain)

Zeros: (0.032, 20) Hz

Poles: (0.031, 20.65) Hz

DC Gain = 6.89 dB

= 2.215 [Vout/Vin]

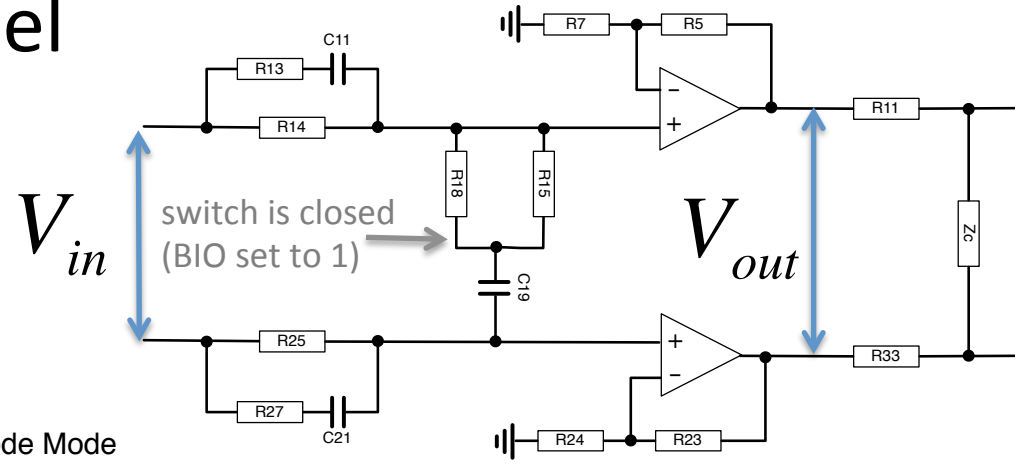
(Confirmed by Rich's Spice Model)<sub>8</sub>



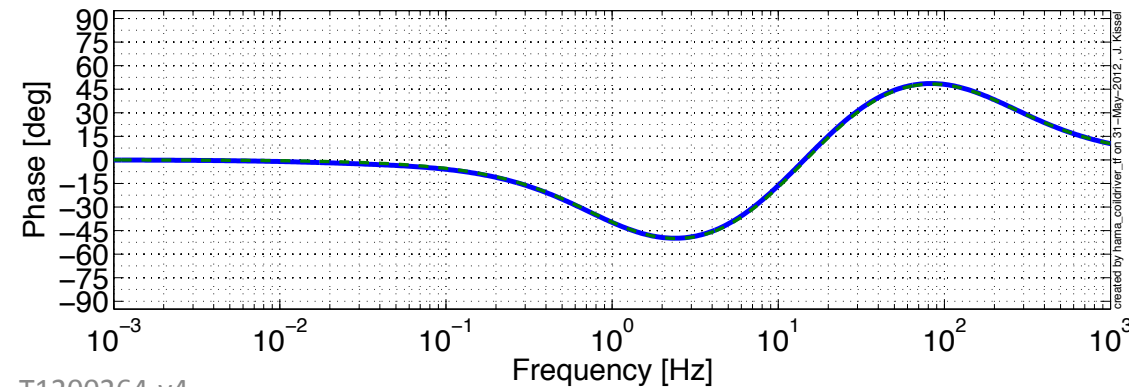
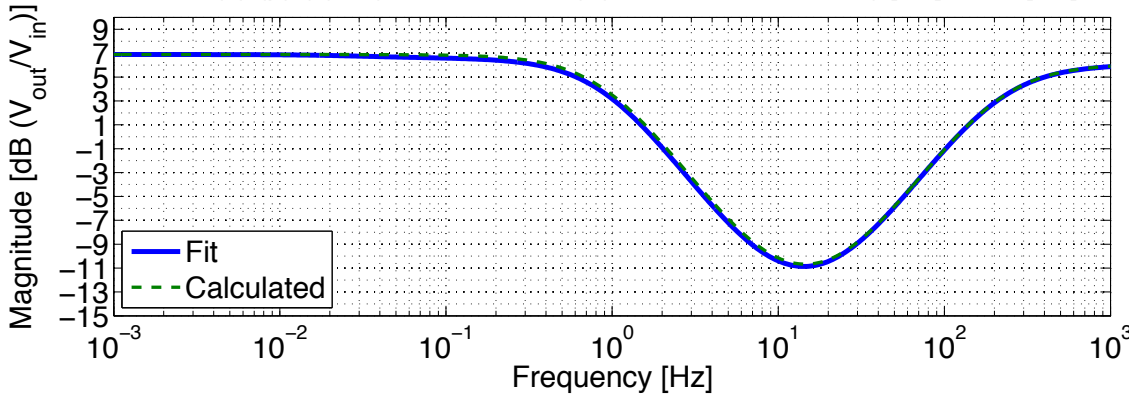
# Transfer Function Model

## Low Noise Mode

a.k.a “Run”



HAM-A Coil Driver Transfer Function, Low Noise Mode Mode  
 Fit = (z):(p);(k) = (0.032,10,20,21):(0.031,0.9,20.65,212) [Hz]; 6.89 [dB]



$$H = \frac{V_{out}}{V_{in}} = G_{op} \frac{Z_{sw}}{Z_{RC} + Z_{sw}}$$

Like “switching in” a  
 [ 10,21 : 0.9,212 ] low pass filter

Zeros: (0.032, 10, 20, 21) Hz

Poles: (0.031, 0.9, 20.65, 212) Hz

DC Gain = 6.89 dB

= 2.215 [Vout/Vin]

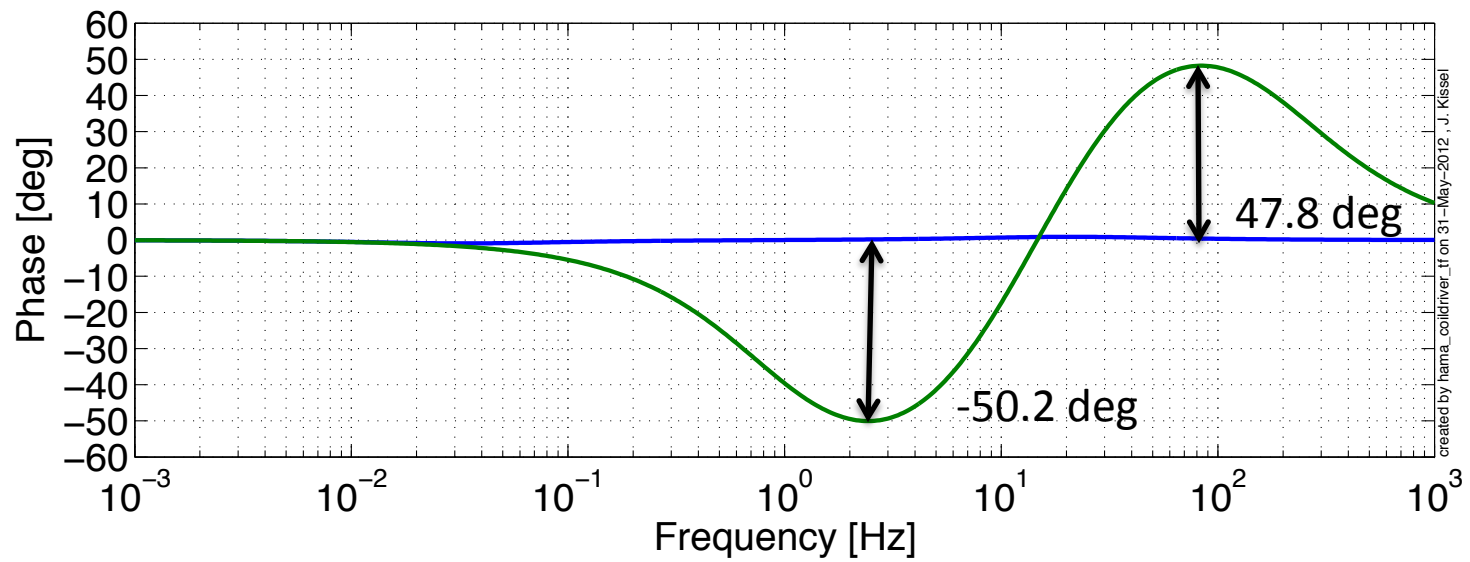
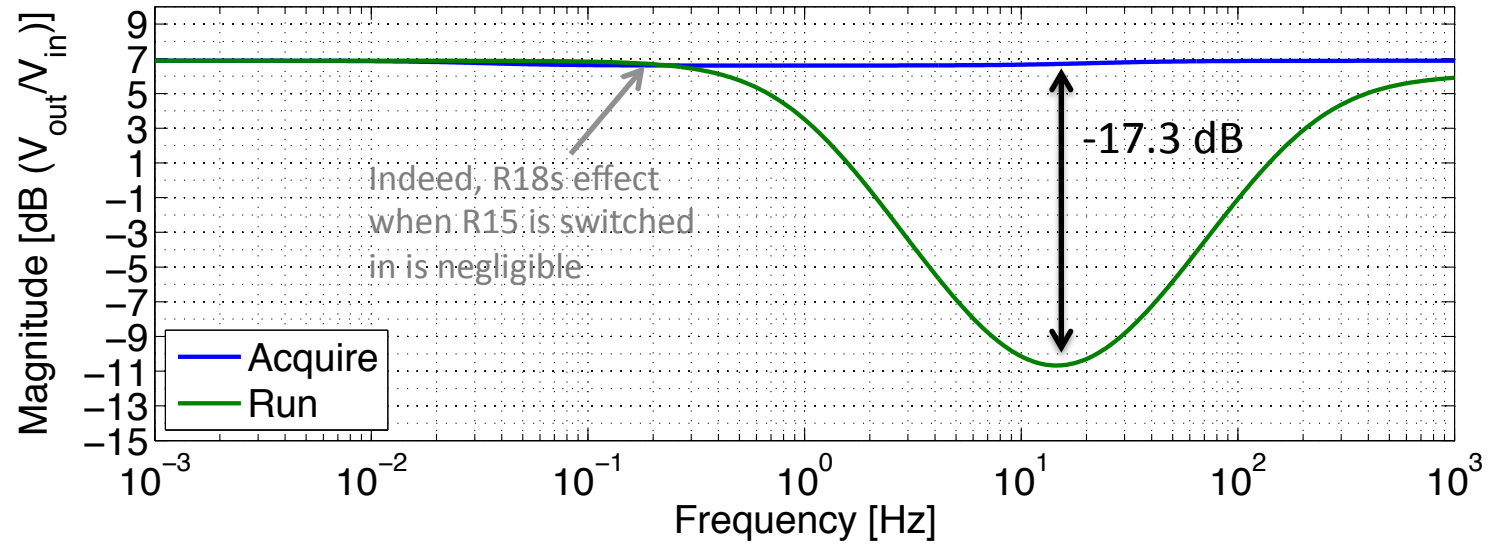
= the same as Acq.

(Confirmed by Rich’s Spice Model) 9

# Transfer Function Model

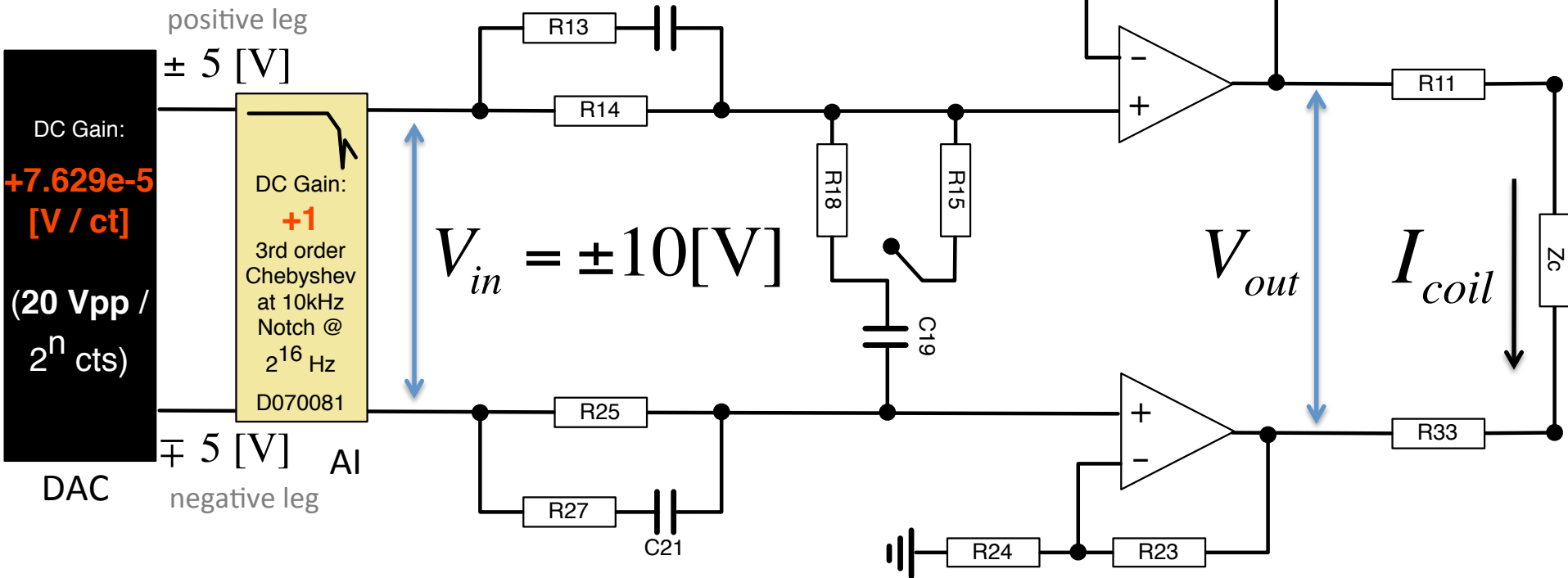
## Mode Comparison

HAM-A Coil Driver Transfer Function, Both Modes



# Maximum Output Current

See T1200311  
for DAC details



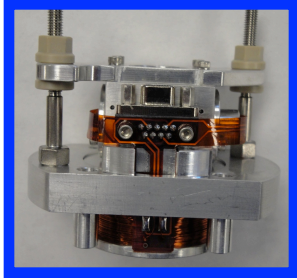
- To calculate the maximum current we assume signal chain is as shown above
- Output range = +/- (maximum current) = 2\*(max current)
- We know the aLIGO DACs, as measured differentially, produce 20 Vpp (each leg can go +/- 5 [V], or +/-10 [V] across the legs). Therefore the max voltage input into this driver,  $V_{in}$ , is **10 [V] max**. Divide this by the total impedance of the coil driver and coil circuit,  $Z_{tot}$ , and we get the maximum current:

$$V_{out} = I_{coil}(R_{11} + R_{33} + Z_c) \xrightarrow[\begin{matrix} (V_{out} = HV_{in}) \\ (R_{33} = R_{11}) \end{matrix}]{\quad} HV_{in} = I_{coil}(2R_{11} + Z_c) \longrightarrow \frac{I_{coil}}{V_{in}} = \frac{1}{Z_{tot}} = \frac{H}{(2R_{11} + Z_c)}$$

$$\longrightarrow I_{coil} = \frac{V_{out}}{Z_{tot}} = \frac{HV_{in}}{(2R_{11} + Z_c)}$$

# Maximum Output Current AOSEMs vs. BOSEMs

BOSEM



$$R_{coil} = 42.7\Omega$$

$$L_{coil} = 11.9\text{mH}$$

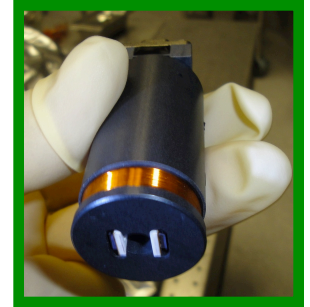
The HAM-A Driver will most likely be used for both AOSEMs (in HAUX) and BOSEMs (in HTTS)

As measured on full system by S. Aston, see  
LLO aLOG 3340

As measured on ATE by S. Aston

$$Z_{coil} = R_{coil} + i\omega L_{coil}$$

AOSEM

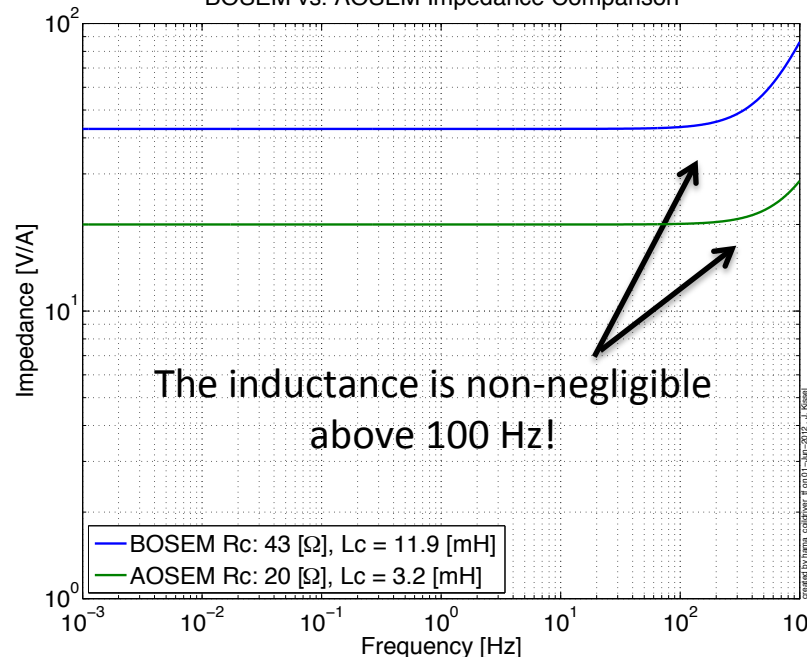


$$R_{coil} = 19.8\Omega$$

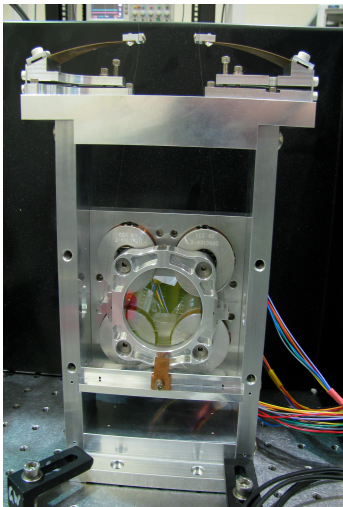
$$L_{coil} = 3.2\text{mH}$$

(remember parallel cable capacitance is negligible at these frequencies)

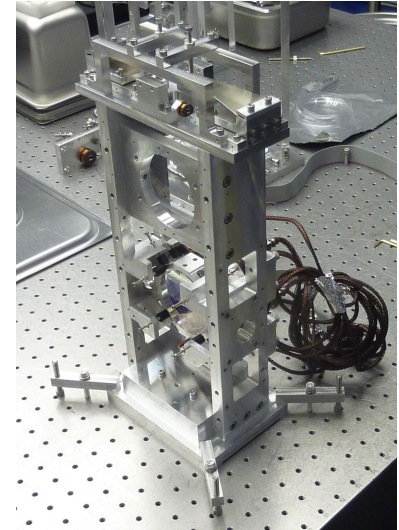
BOSEM vs. AOSEM Impedance Comparison



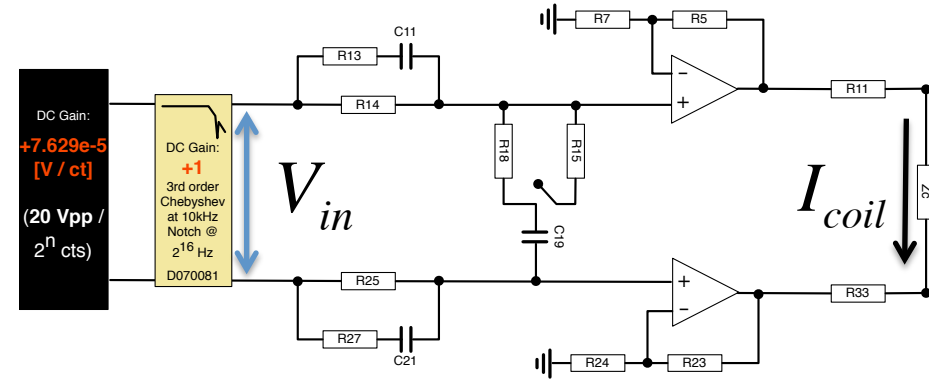
HTTS



HAUX



# Maximum Output Current



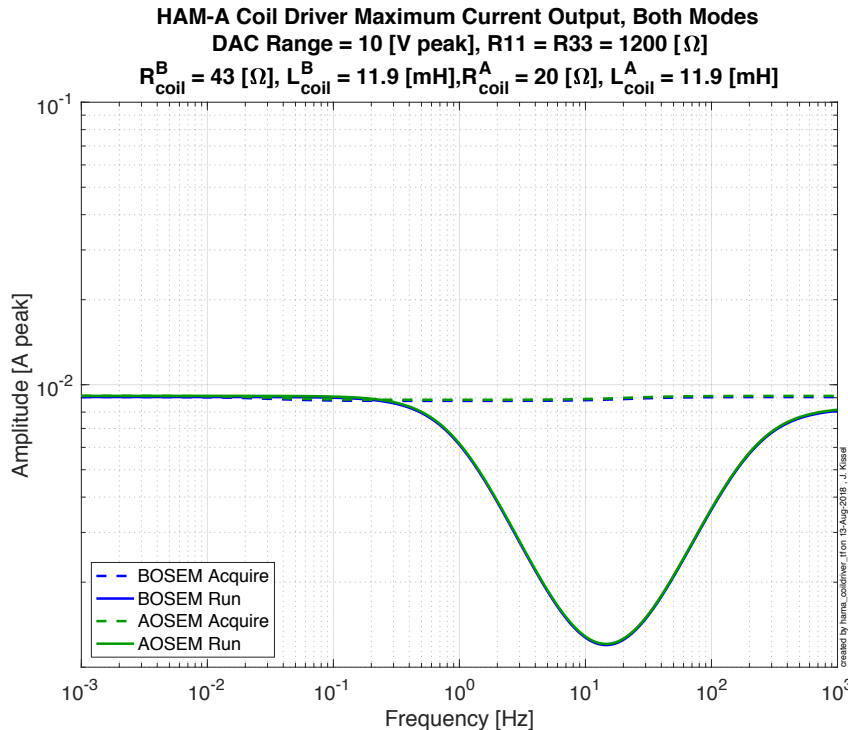
OSEM Type	Transconductance @ DC [A/V]	Maximum Output Current @ DC [A]
AOSEM	9.98e-4	9.98e-3
BOSEM	9.88e-4	9.88e-3

$$I_{coil} = \frac{V_{out}}{Z_{tot}} = \frac{HV_{in}}{(2R_{11} + Z_c)}$$

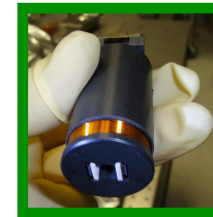
$$V_{in} = +10[V]$$

~~$$R_{11} = R_{33} = 100\Omega$$~~

as per ECR E1201027  $R_{11} = R_{33} = 1.2k\Omega$



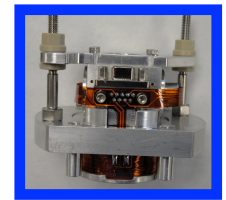
AOSEM



$$R_{coil} = 19.8\Omega$$

$$L_{coil} = 3.2mH$$

BOSEM

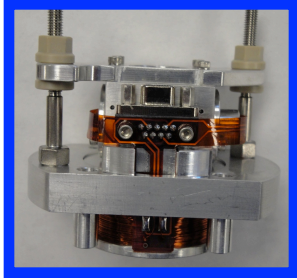


$$R_{coil} = 42.7\Omega$$

$$L_{coil} = 11.9mH$$

# Current & Force Noise HAUX vs. HTTS

BOSEM



AOSEM



HAUX use HAM-A drivers with

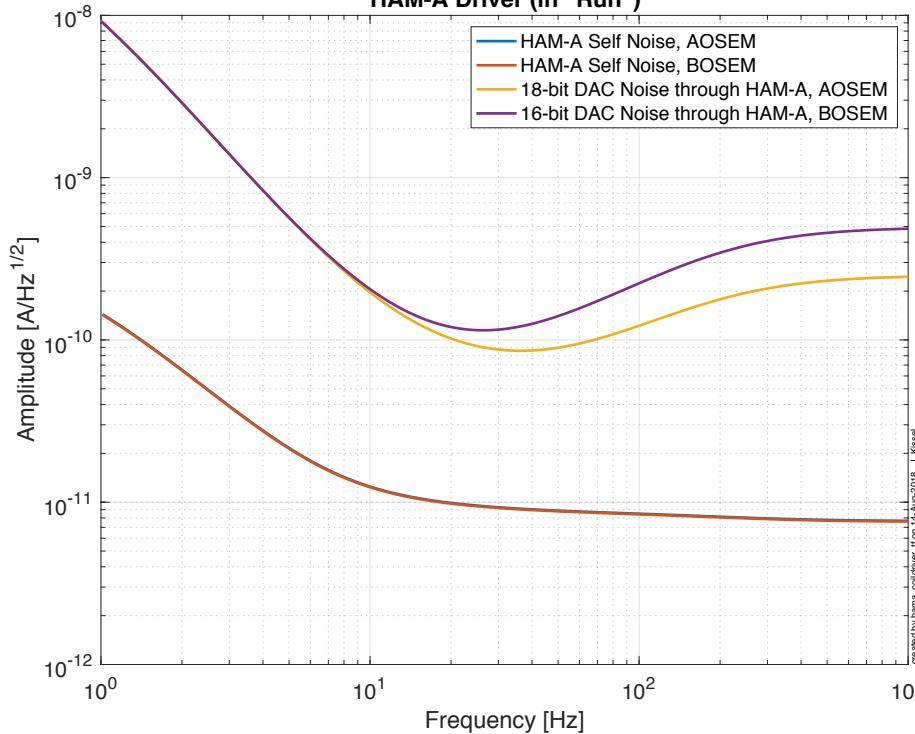
- 18-bit DACs =  $300 \text{ nV} * \text{sqrt}( (50/\text{freq})^2 + 1 )$ ;
- 1.9D x 3.2T magnets = 0.0158 N/A

HTTS use HAM-A drivers with

- 16-bit DACs =  $600 \text{ nV} * \text{sqrt}( (25/\text{freq})^2 + 1 )$ ;
- 2D x 3T magnets = 0.021 N/A

**Data shown with  $R11 = R33 = 1.2k$ , as per ECR E1201027**

DAC vs. Coil Driver Simulated Current Noise  
HAM-A Driver (in "Run")



DAC vs. Coil Driver Simulated Force Noise (Single OSEM)  
HAM-A Driver (in "Run")

