

Newtonian noise simulations and subtraction for ET and Advanced Virgo

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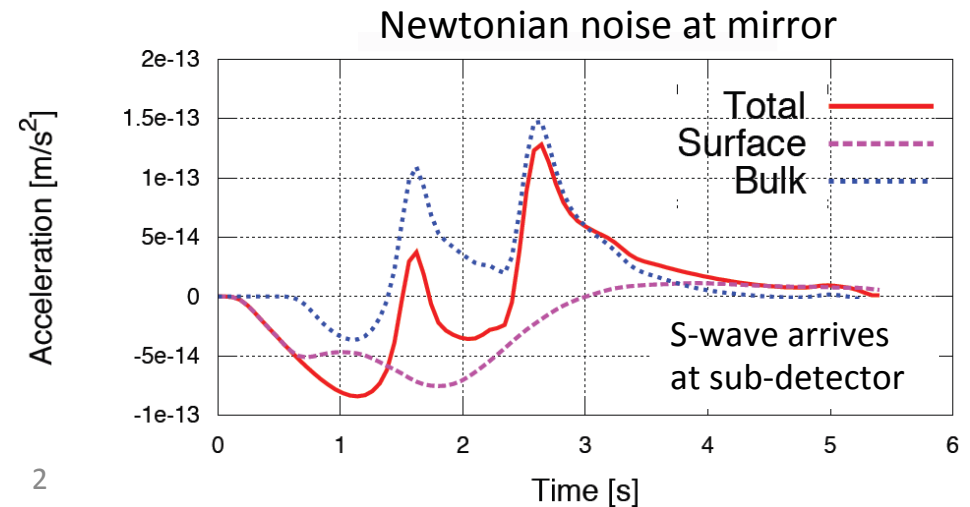
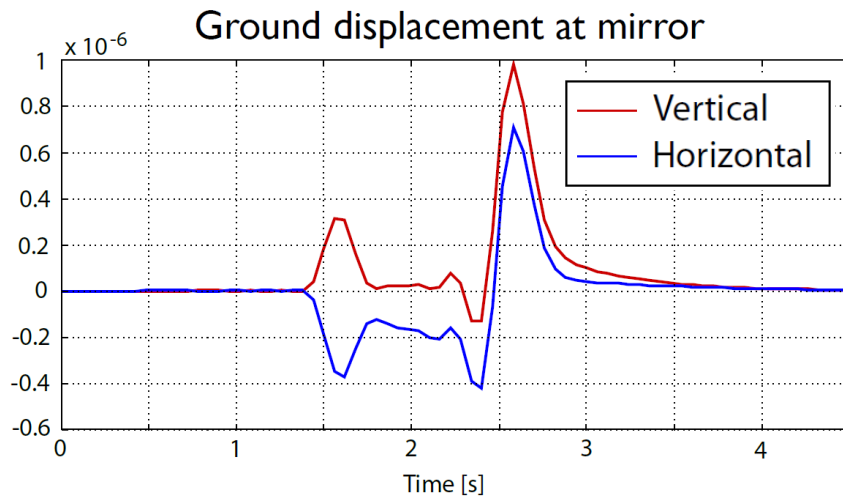
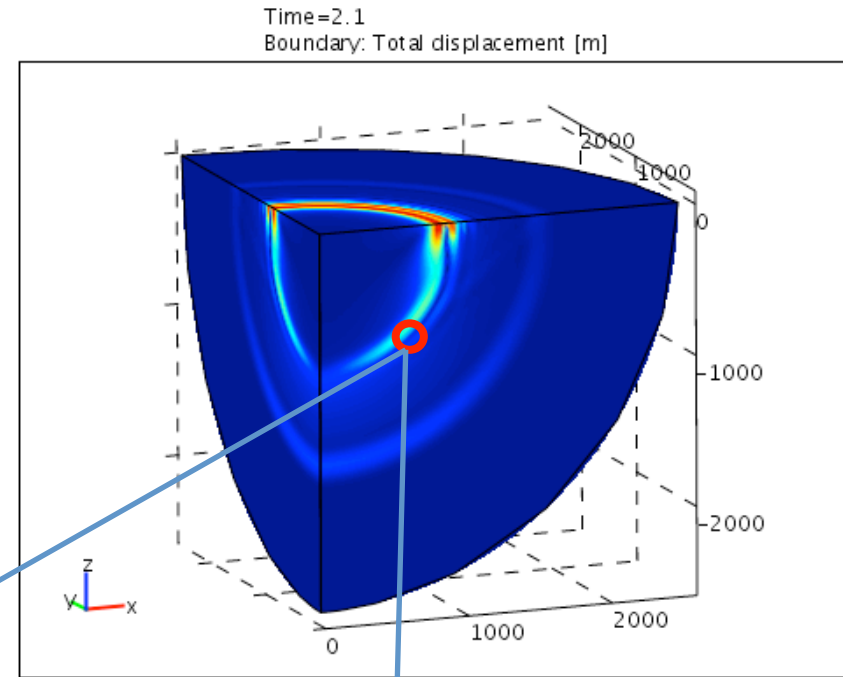
GWADW 2012, Waikoloa Beach, Hawaii
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15 May 2012
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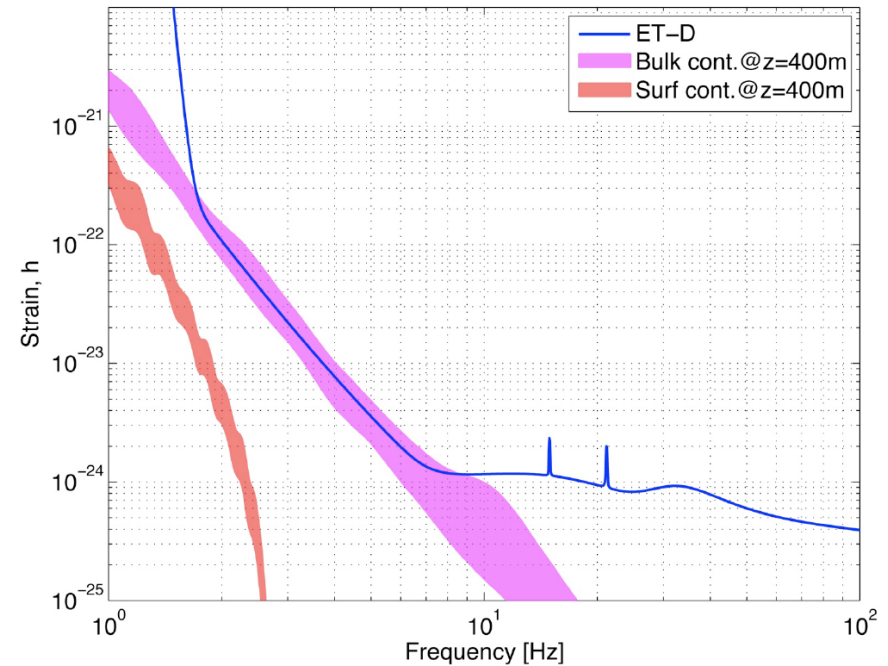
Simulations made in the context of ET

- Cultural noise / Impulse excitations
 - NN “felt” at test mass before seismic wave field arrives

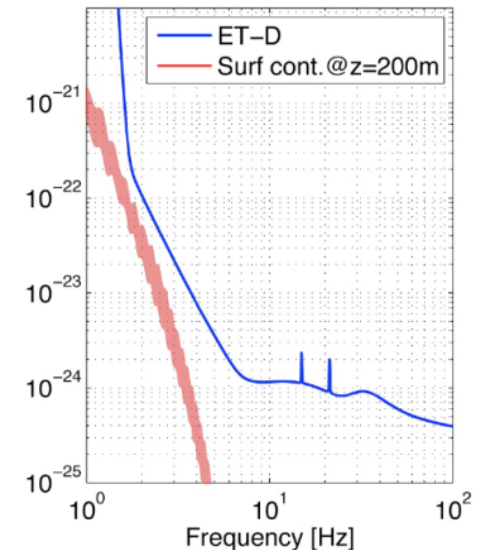
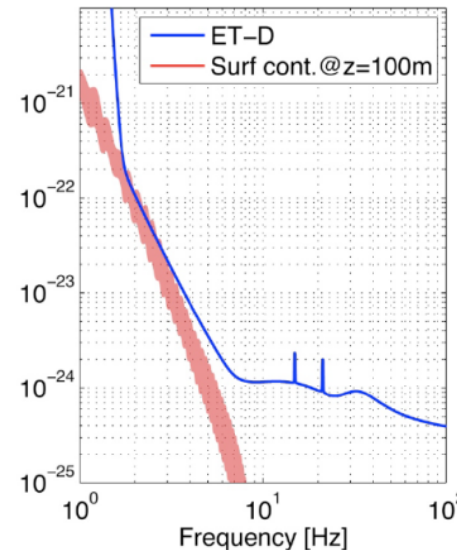
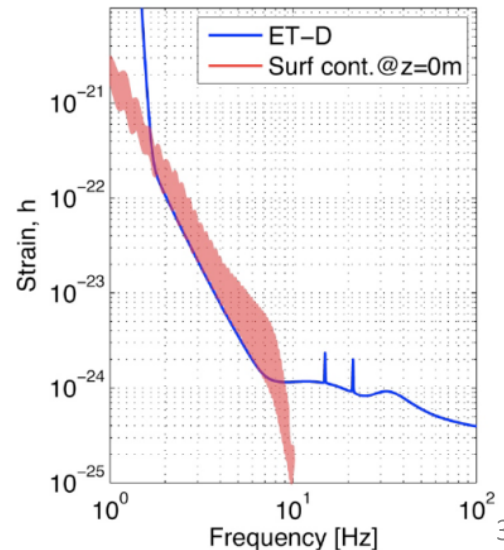


Simulations made in the context of ET

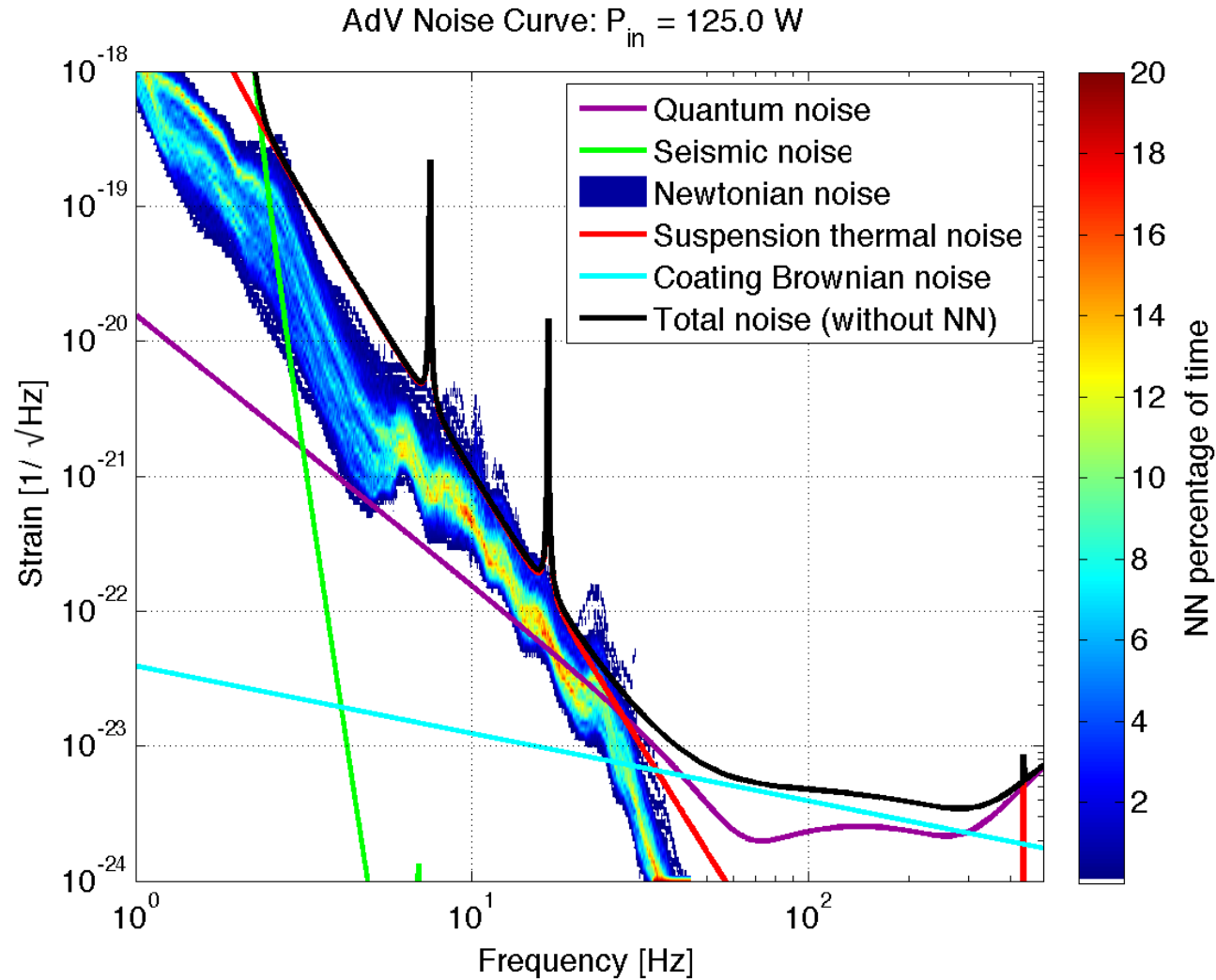
- Cultural noise / Impulse excitations
 - NN “felt” at test mass before seismic wave field arrives
- Ambient seismic motion
 - Surface wave models developed by Cella
 - Thorne and Hughes model for bulk contribution
 - Estimates made using real seismic data



A few hundreds meters enough to suppress surface contribution
Bulk contribution remains



Newtonian noise could limit Advanced Virgo sensitivity during high seismic activity



[VIR-0073B-12]

Seismic sensor networks could be used for Newtonian noise subtraction

- Seismic sensor (signal + noise)
- ITF output (GW signal + N. noise)
- Find $\alpha_I(\omega)$ to minimize “subtracted” signal

$$X_I = s_I + \sigma_I$$

$$Y = H + N$$

$$Y_s(\omega) = Y(\omega) + \int d\omega' \sum_I \alpha_I(\omega, \omega') X_I(\omega')$$

$$\frac{\delta \langle Y_s(\omega)^* Y_s(\omega) \rangle}{\delta \alpha_I(\omega, \omega')} = 0$$

Sensor noise appears in diagonal elements of cross-correlation matrix

- Optimal filters

$$\alpha_I(\omega, \omega') = - \sum_K \int d\omega' \underbrace{\langle X_I(\omega)^* X_K(\omega') \rangle}^{-1} \underbrace{\langle X_K(\omega')^* Y(\omega) \rangle}$$

- Subtraction efficiency

- 1 = No subtraction
- 0 = 100% subtraction

$$(1 - \epsilon(\omega))^2 = 1 - \frac{C_{SN}^\dagger(\omega) C_{SS}(\omega)^{-1} C_{SN}(\omega)}{C_{NN}(\omega)}$$

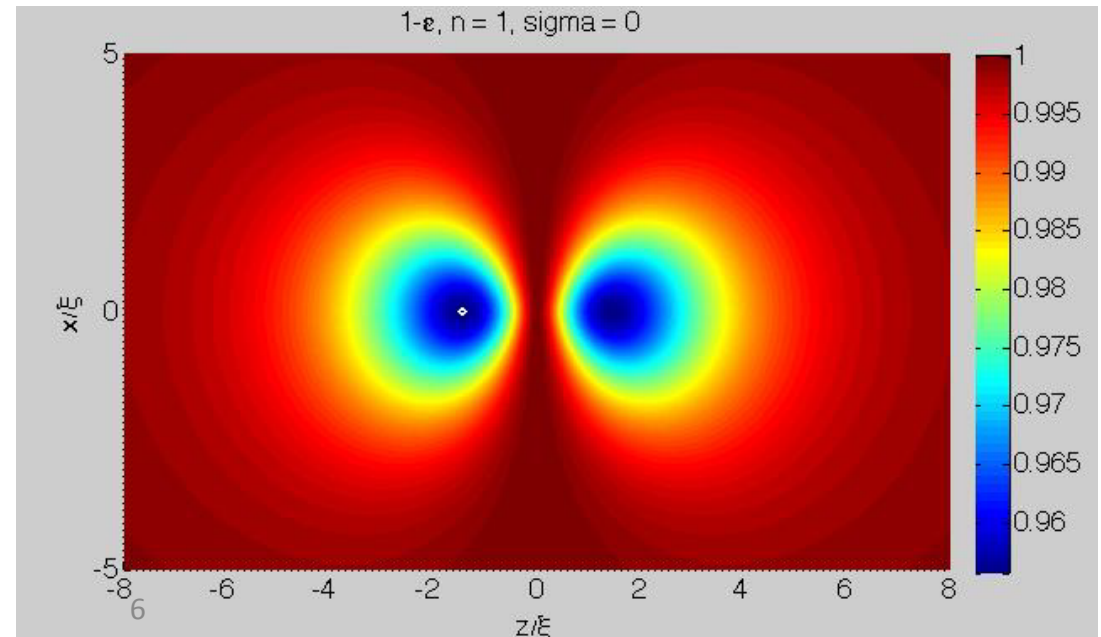
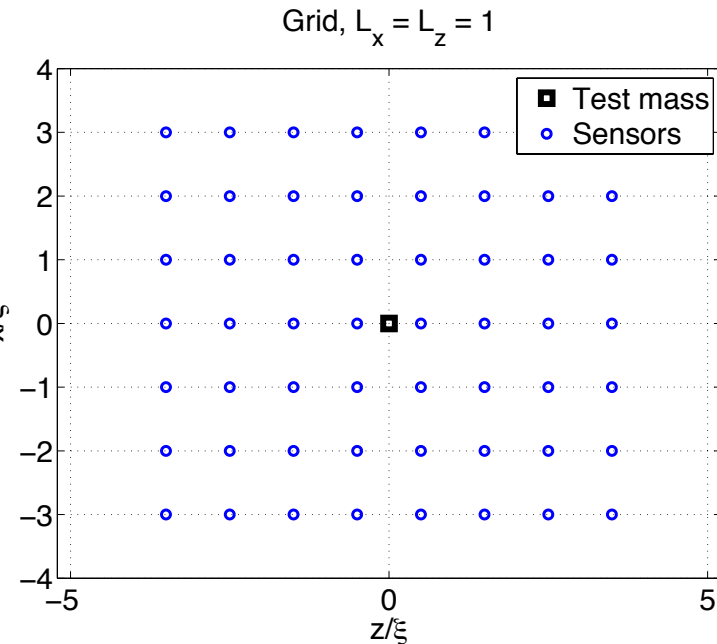
[G. Cella, *et. al.*, Gen. Rel. Grav. (2010)]

Newtonian noise subtraction simulations

- Simplified model
 - Exponential cross correlation function between sensors
- Regular grid
 - Centered around test mass
 - For NN in z direction only
- “Optimal” positioning of sensors
 - Keeping previous sensors fixed, calculate subtraction efficiency as function of position of next sensor
 - Optimized for particular correlation length (frequency)

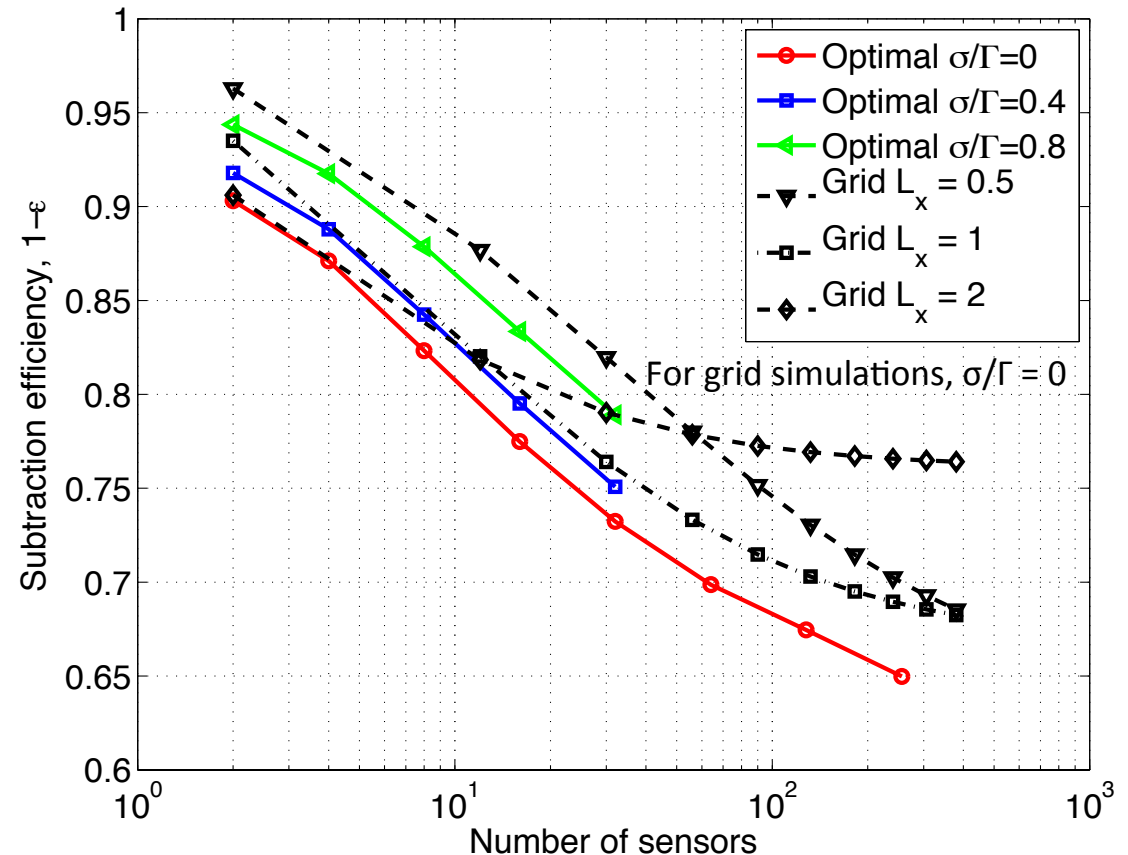
$$\langle \rho(\omega, \mathbf{x})^* \rho(\omega', \mathbf{x}') \rangle = 2\pi\Gamma(\omega)^2 \delta(\omega - \omega') e^{-\frac{|\mathbf{x} - \mathbf{x}'|}{\xi(\omega)}}$$

$\xi(\omega)$: Correlation length



Newtonian noise subtraction simulation results

- Based on this model several hundred sensors needed to achieve a 50 % reduction
- Sensitivity of seismic sensors SNR > 5
- Sensor network optimized for frequency and geology
- Optimization easier for homogeneous media
 - Longer correlation lengths
- What is a realistic model of seismic activity?



Develop a seismic model based on measurable quantities

- Most relevant quantities for Newtonian noise subtraction:
 - (Power) spectral densities
 - NN scales linearly with amplitude
 - Correlation
 - As a function of distance between sensors / frequency
 - Between vertical and horizontal motion
 - Subtraction techniques rely on (cross)correlation amongst sensors and between sensors and NN

$$\alpha_I(\omega, \omega') = - \sum_K \int d\omega' \langle X_I(\omega)^* X_K(\omega') \rangle^{-1} \langle X_K(\omega')^* Y(\omega) \rangle$$

- Complex correlation: $K_k = \frac{\langle u_k z_k^* \rangle}{\sqrt{\langle u_k u_k^* \rangle \langle z_k z_k^* \rangle}}$
- Coherence: $|K_k|$
- Correlation: $\Re[K_k]$

Examples of seismic correlation measurements

- CERN
- DESY
- High coherence from micro-seismics
- Above a few Hz coherence is lost within ~ 100 m
- Literature provides models for typically behavior
 - Exponential
 - Bessel function

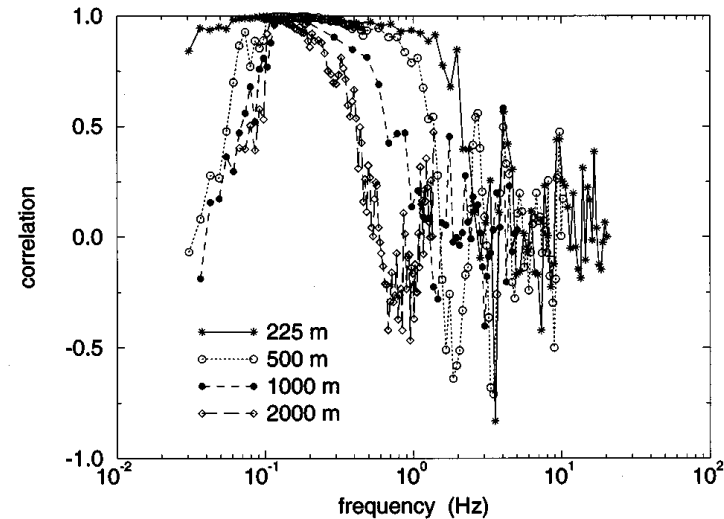
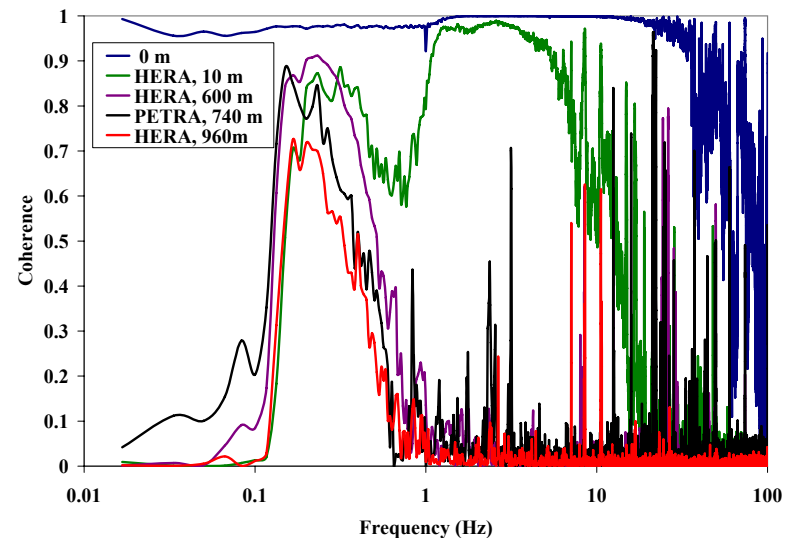


FIG. 3. Correlation spectra of ground motion measured at CERN in the LEP tunnel [7]. The distances between sensors were 225, 500, 1000, and 2000 m. A. Sery and O. Napoly, Phys. Rev E 54 (1996)

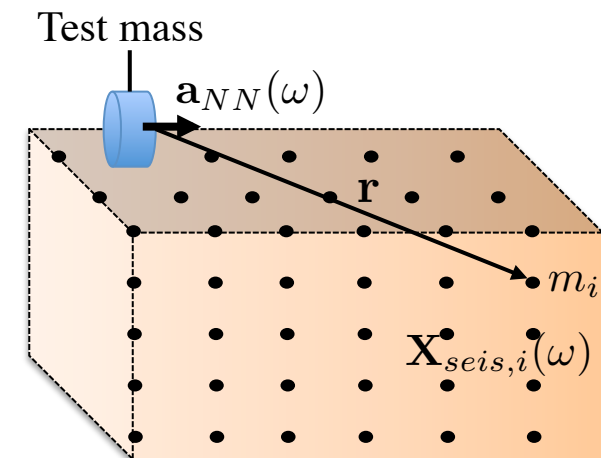


9 FIG. 6: (Color) Coherence spectra measured at different distances at DESY: 0 m, 10 m, 600 m, 740 m (diameter of PETRA ring) and 960 m in the HERA tunnel. W. Bialowons et. al, EURO-TeV Report (2007)

Frequency domain numerical correlation propagation algorithm

- Simulated seismic noise
 - Noise distributed with depth dependent $\beta_{P,S,R}$:
 - Given ratio between pressure, shear and Rayleigh waves
- A random phase and isotropic direction of propagation is selected for each frequency bin
- Correlation and relative phase of the noise between all grid points is calculated:
 - Coherence follows given function
 - Direction and wave-dependent correlation factor
 - Relative phase and relative direction of the correlated noise is calculated from the wave direction and the grid point positions.
- Correlation relationships between transverse / longitudinal directions and horizontal / vertical components

$$|X_{seis}(\omega)| \propto \frac{A_{P,S,R}}{f} e^{-z\beta_{P,S,R}/\lambda}$$

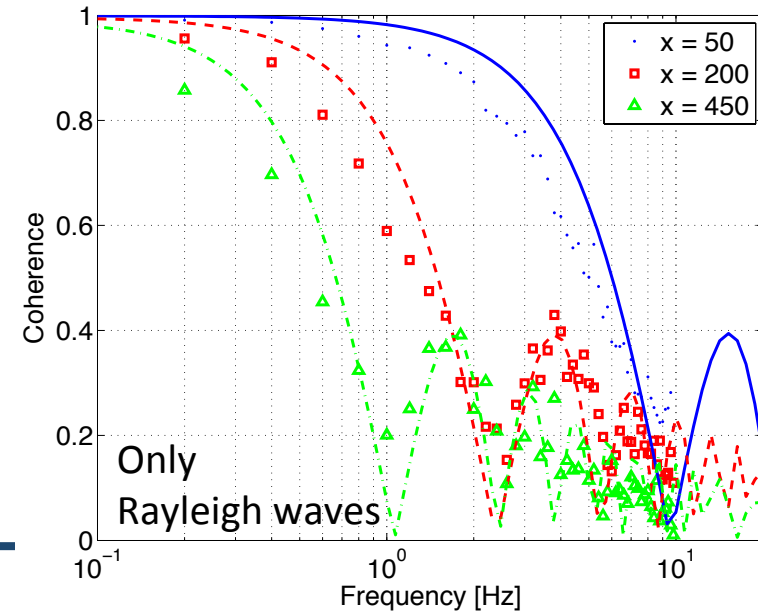
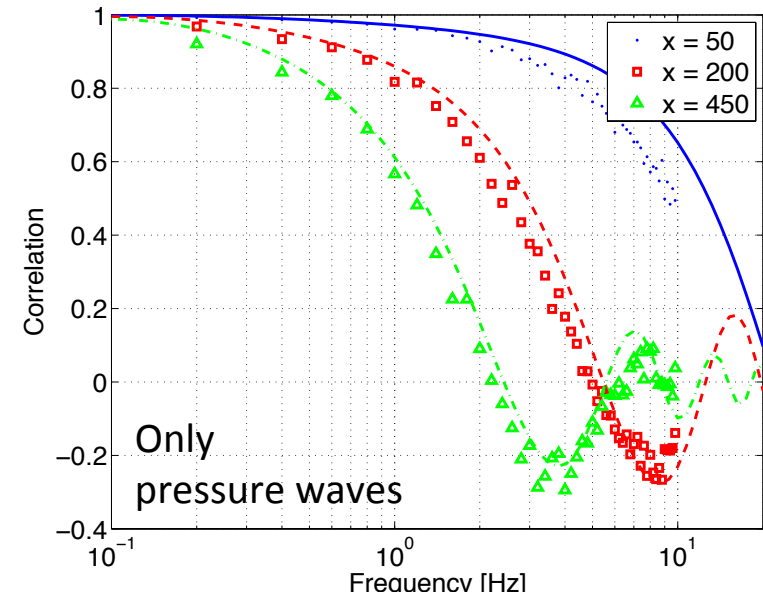


Preliminary results show coincidence with expectation

- 10 x 10 x 10 grid
- Averaged over 400 simulated FFTs
- Correlation can be modeled by exponentially decaying Bessel function

[G.A. Prieto *et. al.* Journ. Geophys. Res. 114 (2009)]

$$\Re[K_k(\omega, r)] = J_0(kr) \cdot e^{-\alpha(\omega)r}$$

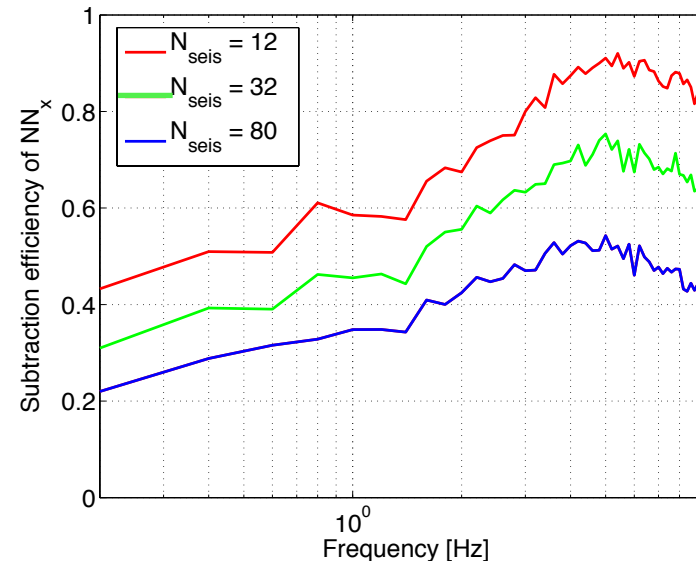
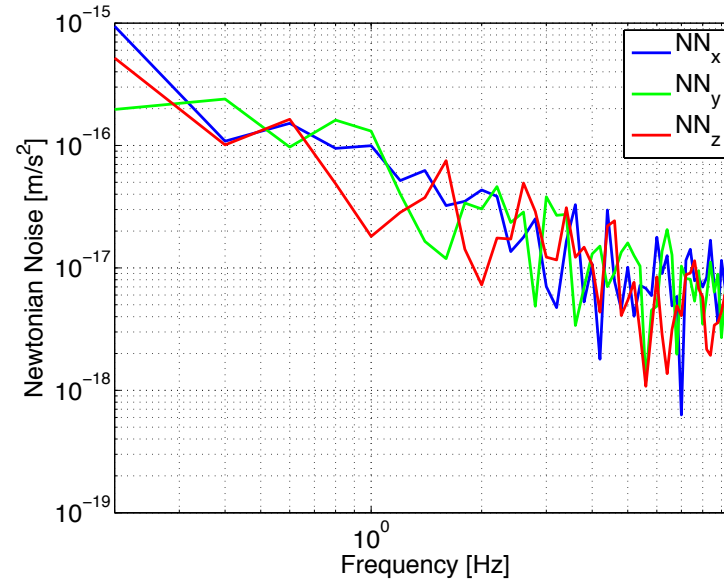


Newtonian noise computation and subtraction using correlation model

- Calculate Newtonian Noise

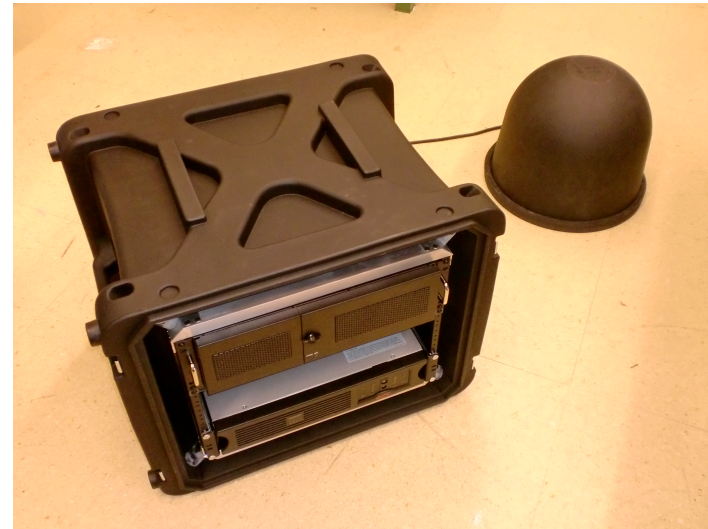
$$\mathbf{a}_{NN}(\omega) = G \sum_i m_i (\nabla \otimes \frac{\mathbf{r}_i}{|\mathbf{r}_i|^3}) \mathbf{X}_{seis,i}(\omega)$$

- Place a number of seismometers and evaluate subtraction efficiency
- Preliminary results
 - Basic regular grid of surface seismometers
 - No optimization of network
 - Simple seismic amplitude model
 - Sparse grid



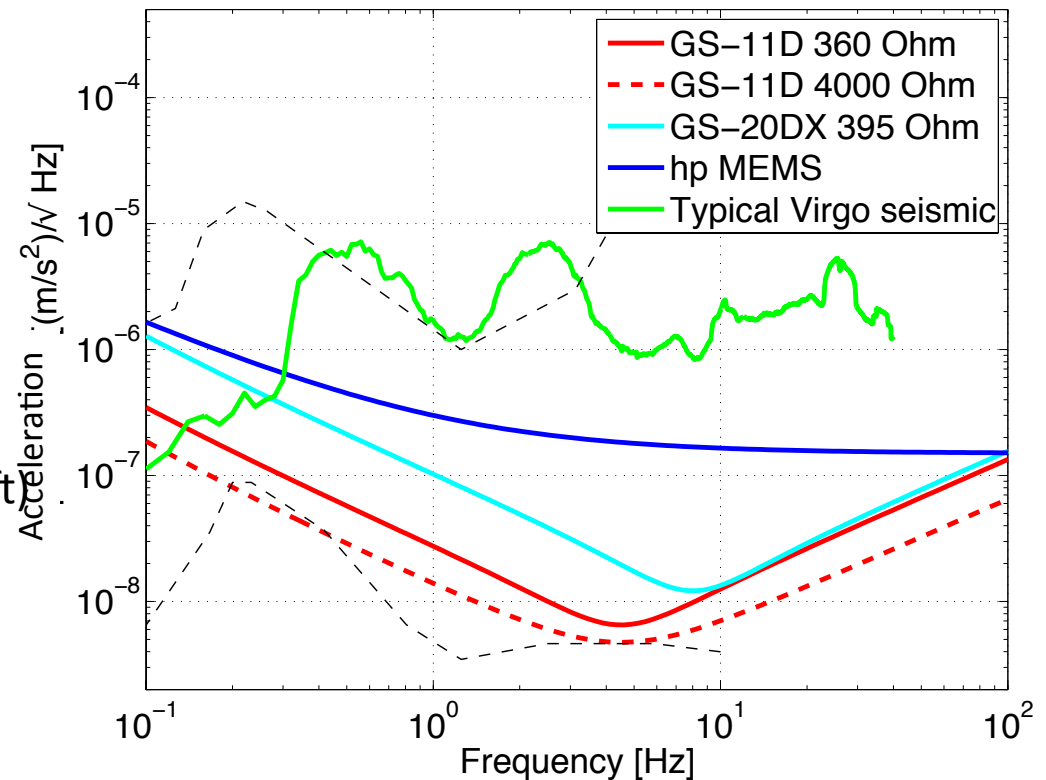
Numerical models will help to determine requirements for seismic sensor networks

- Measurements to be done at Virgo to provide input for model
 - With two portable T240 stations
- Produce an estimate of NN at the site
- Optimal density and distribution of sensors
- Requirements on the sensor sensitivity
- Expected subtraction efficiency



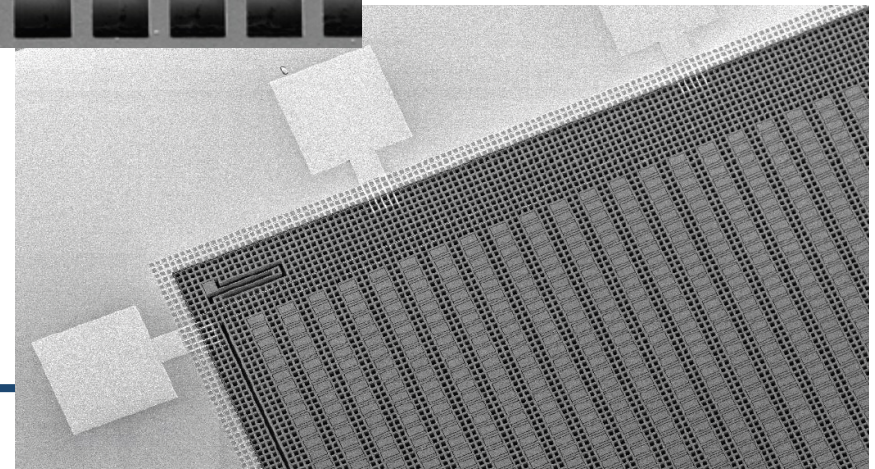
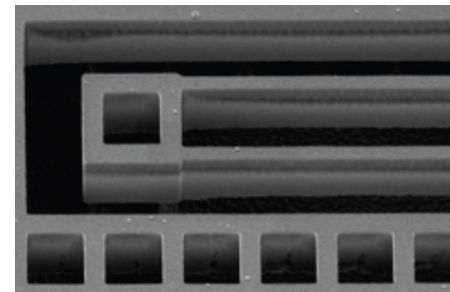
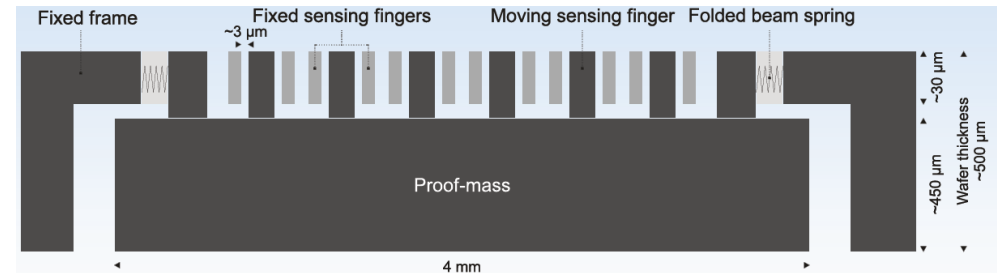
Seismic sensor network

- **Performance**
 - Geophone has superior sensitivity
- Low cost
- **Low power**
- Noise sources
 - Pre-amp voltage / current
 - Digitization noise
 - Sensor noise negligible
- In collaboration with other scientific endeavors
 - Seismic interferometry (TU Delft)
 - Lofar seismic array
 - Pierre Auger observatory



R&D into MEMS accelerometers also underway

- In cooperation with MESA+ / Universiteit Twente
- Silicon structure
- Capacitive interfaces
 - Position detection
 - Range 100 μm , nm resolution
 - 2096 pF/g; 1 fF/ μm
- Closed-loop force-feedback control of sensing electrodes
- Potentially **cheaper and more robust** than geophones



Summary

- AdvVirgo sensitivity is limited by NN during high seismic activity
- A numerical model incorporating measureable seismic quantities is being developed
- Model will be used in combination with measurements to predict NN and required subtraction parameters
- Seismic networks and sensors under development including MEMS technology

