

TMTS (RIGHT-HANDED) M1 Loop Sign Table

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|--|--------------|------------|--------------|---------------|-------------|---------------|---------------|------------|--------------|-----------------|------------|-------------|--|
| OSEM Basis | | | | | EULER Basis | | | | OSEM Basis | | | | |
| Real Motion | OSEM Sensing | Elec. Gain | OSEMINF Gain | OSEM2EUL Gain | DAMP Gain | EUL2OSEM Gain | COILOUTF Gain | Elec. Gain | Current Sign | Magnet Polarity | OSEM Force | Real Motion | |
| | | | | | | | | | | | | | |
| + L | + SD | + | + | + | - | + | - | + | + | S | Pull | - L | |
| | | | | | | | | | | | | | |
| | - F2 | + | + | - | - | - | - | + | - | S | Push | | |
| + T | | | | | | | | | | | | - T | |
| | - F3 | + | + | - | - | - | + | + | + | N | Push | | |
| | | | | | | | | | | | | | |
| | - LF | + | + | - | - | - | - | + | - | S | Push | | |
| + V | | | | | | | | | | | | - V | |
| | - RT | + | + | - | - | - | + | + | + | N | Push | | |
| | | | | | | | | | | | | | |
| | + F1 | + | + | + | - | + | + | + | - | N | Pull | | |
| + R | - F2 | + | + | - | - | - | - | + | - | S | Push | - R | |
| | - F3 | + | + | - | - | - | + | + | + | N | Push | | |
| | | | | | | | | | | | | | |
| | - LF | + | + | - | - | - | - | + | - | S | Push | | |
| + P | | | | | | | | | | | | - P | |
| | + RT | + | + | + | - | + | + | + | - | N | Pull | | |
| | | | | | | | | | | | | | |
| | + F2 | + | + | + | - | + | - | + | + | S | Pull | | |
| + Y | | | | | | | | | | | | - Y | |
| | - F3 | + | + | - | - | - | + | + | + | N | Push | | |
| | | | | | | | | | | | | | |

Sensing Chain

Actuation Chain