

PROGRESS IN NOISE CHARACTERIZATION

BERNARD WHITING

(GROUPS AT ANU & UFL)

PREPARATION

COMPUTATION NOISE

DIGITIZING NOISE

SPECTRAL UNIFORMITY

NOISE IDENTIFICATION

DIGITAL FILTERS ...

EXAMINING DATA

FREQUENCY MISMATCH

NOISE UNIFORMITY

A-D UNIFORMITY

LINE INTERFERENCE

DISTRIBUTIONAL DIVERSITY...

Examining 40 M data

Computational Noise

Frequency Mismatch

Digital Noise / Uniformity

Random Noise Uniformity

Examining frequency mismatch
Aliasing

{ Noise scaling with sample length
Averaging techniques
(Establishing confidence techniques)

A-D uniformity .

Spectral Uniformity

Line Interference

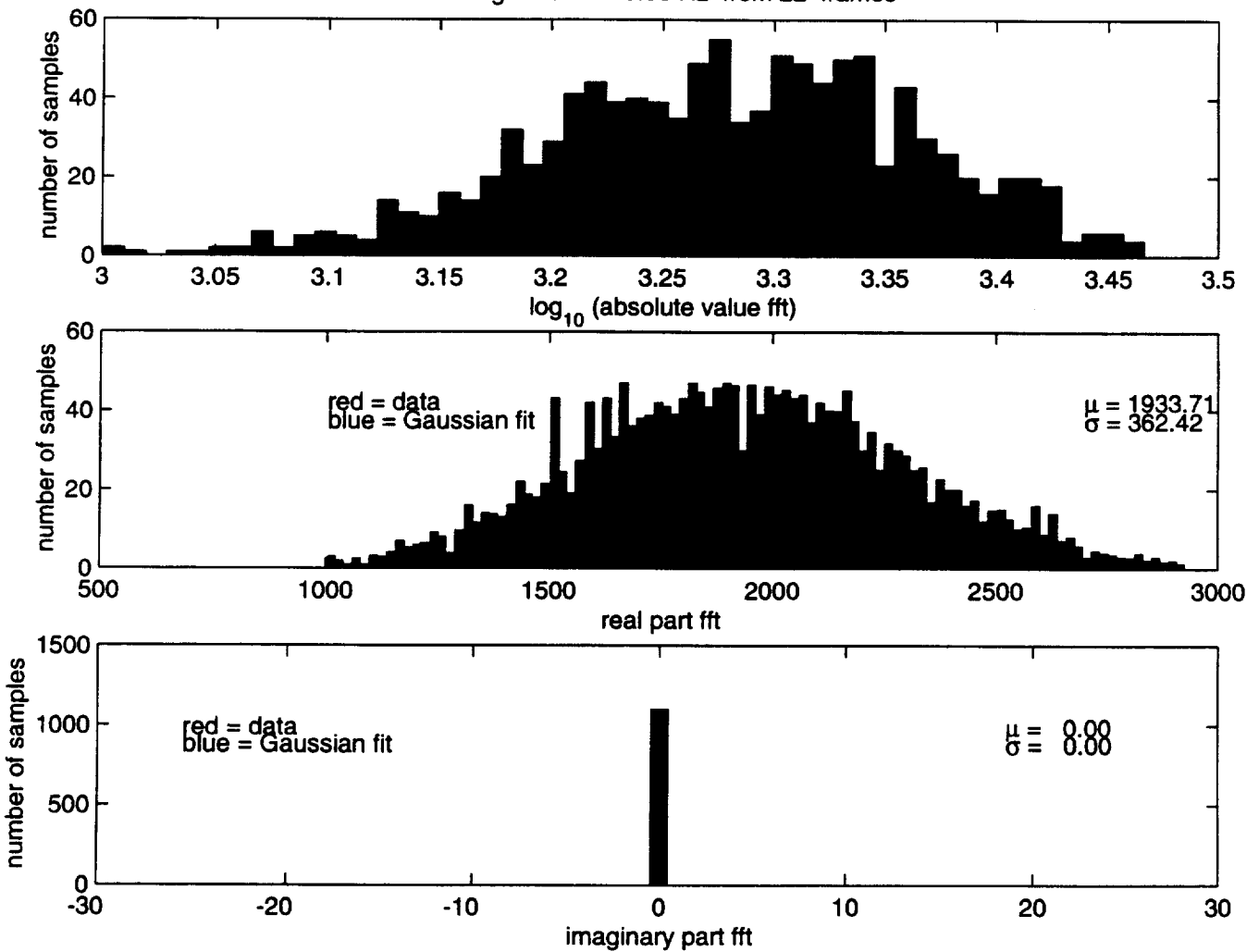
FFT time vs length

Digital filtering / smoothing

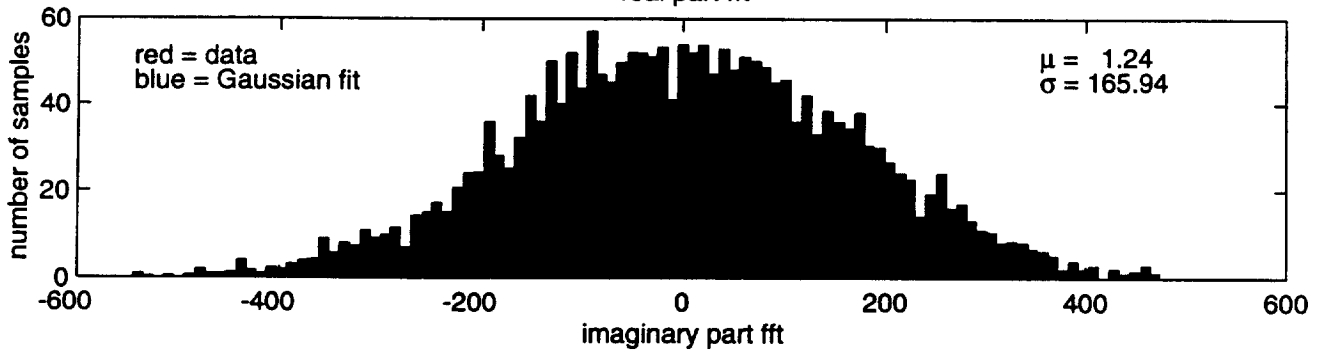
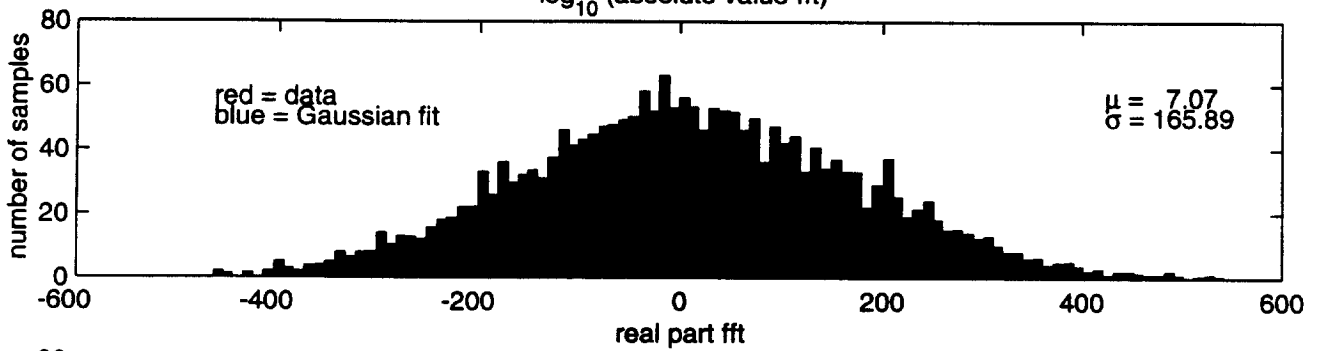
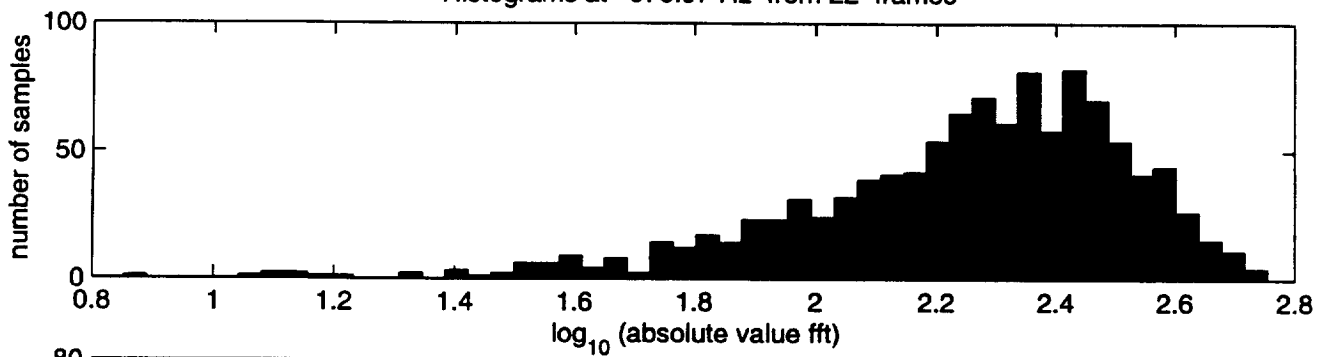
Distribution density .

SPECTRAL UNIFORMITY

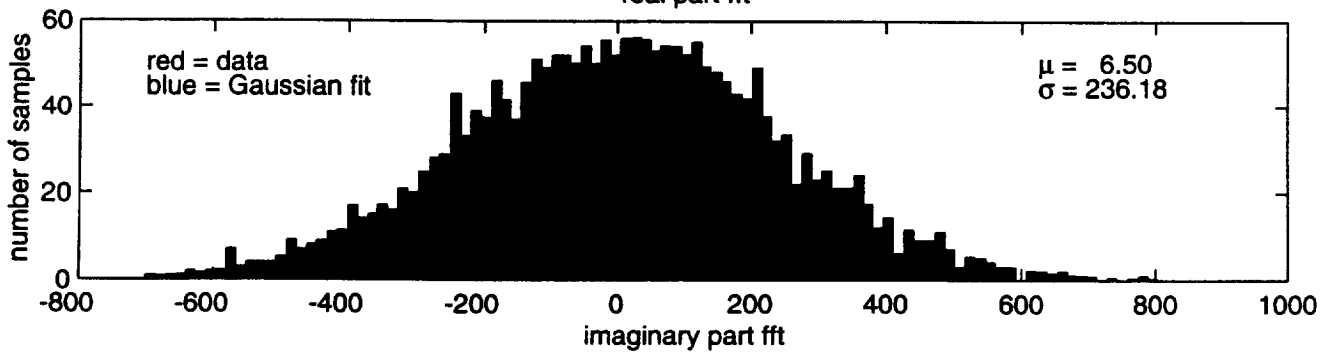
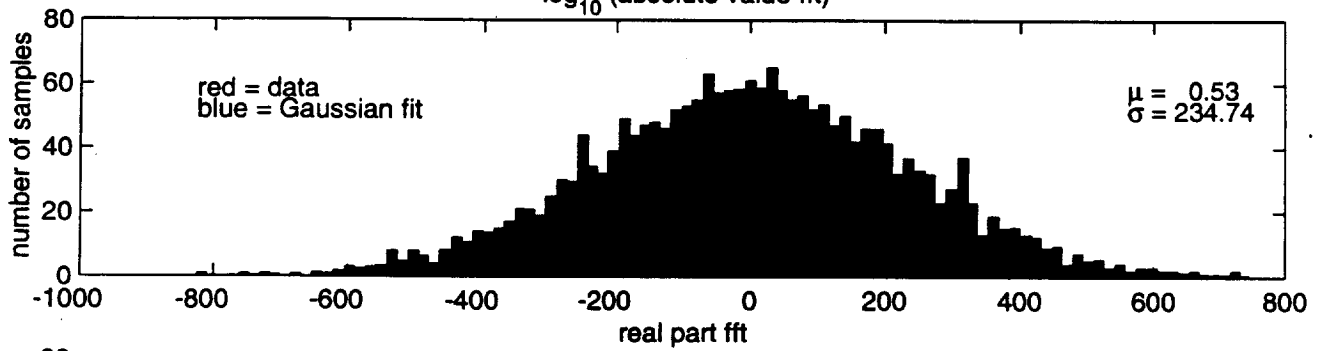
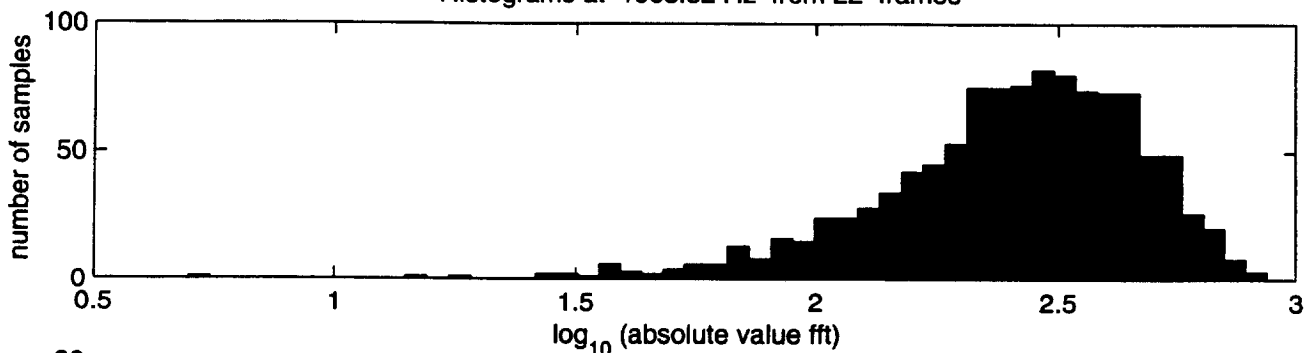
Histograms at 0.00 Hz from 22 frames



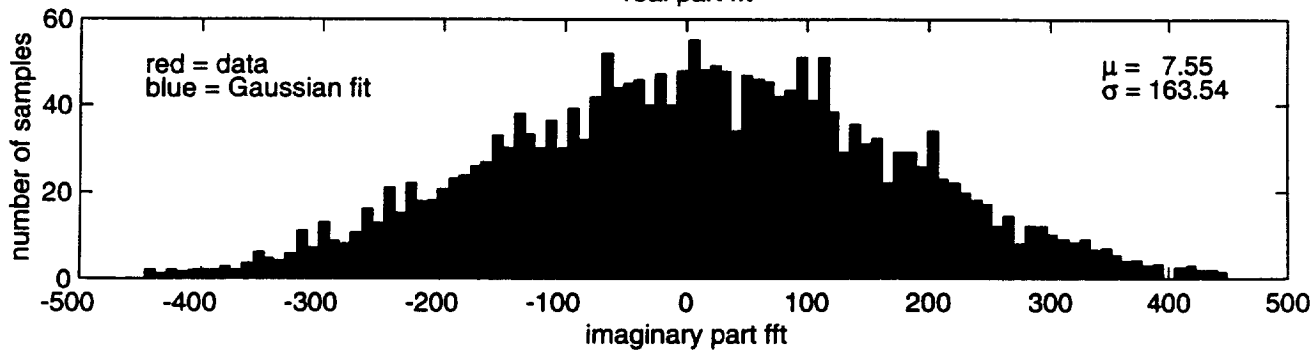
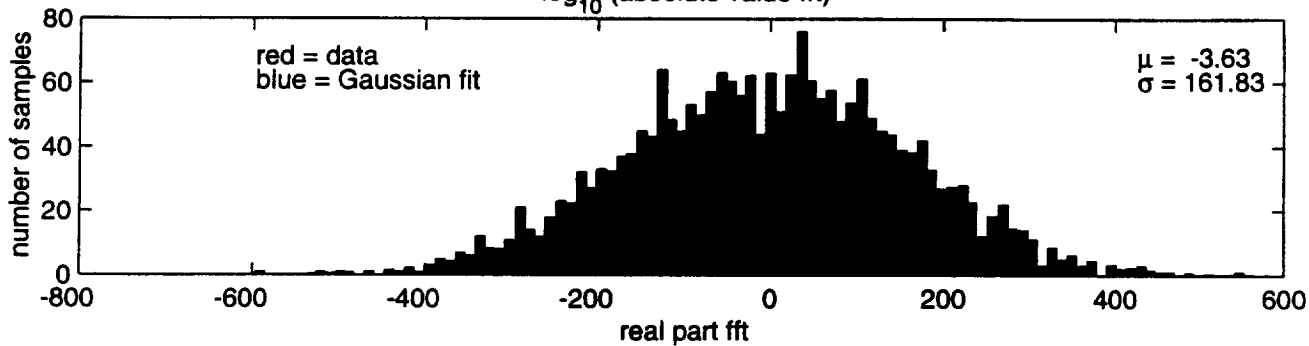
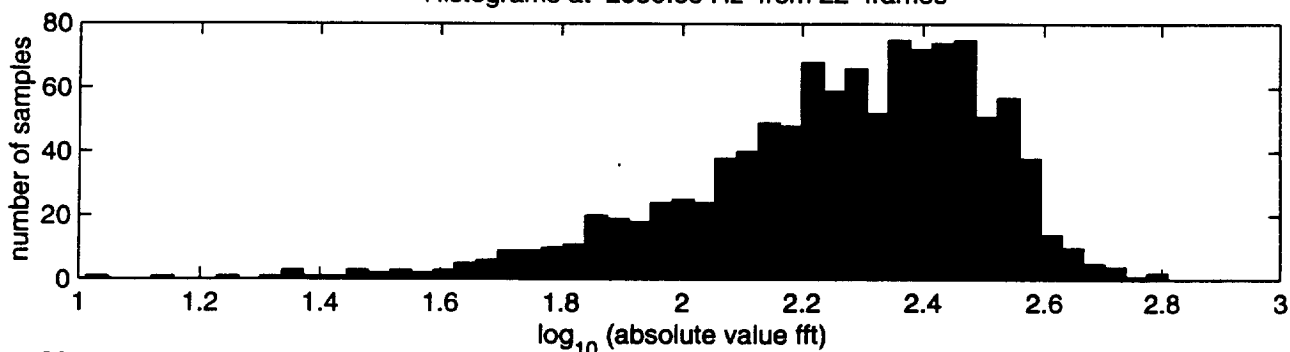
Histograms at 976.97 Hz from 22 frames



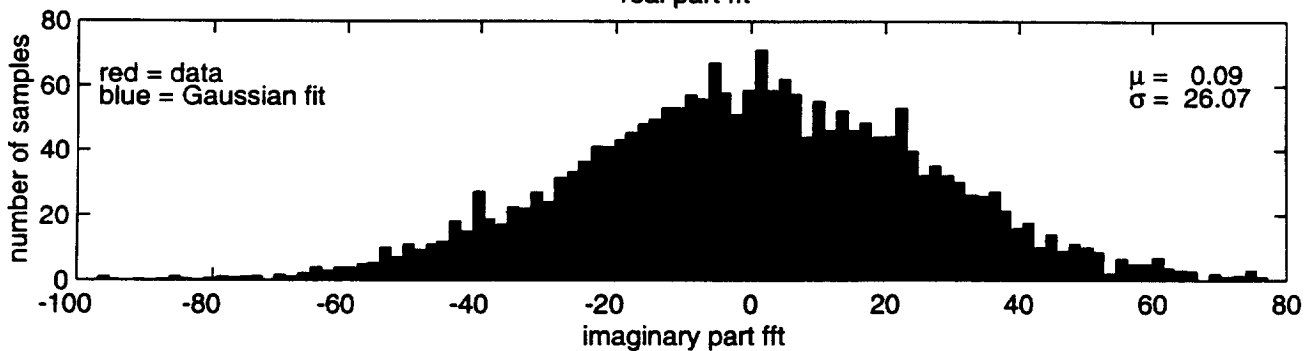
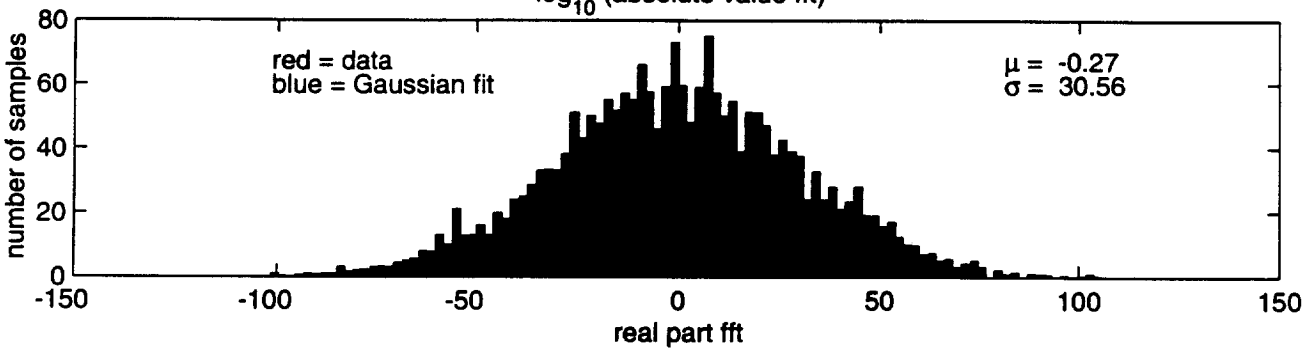
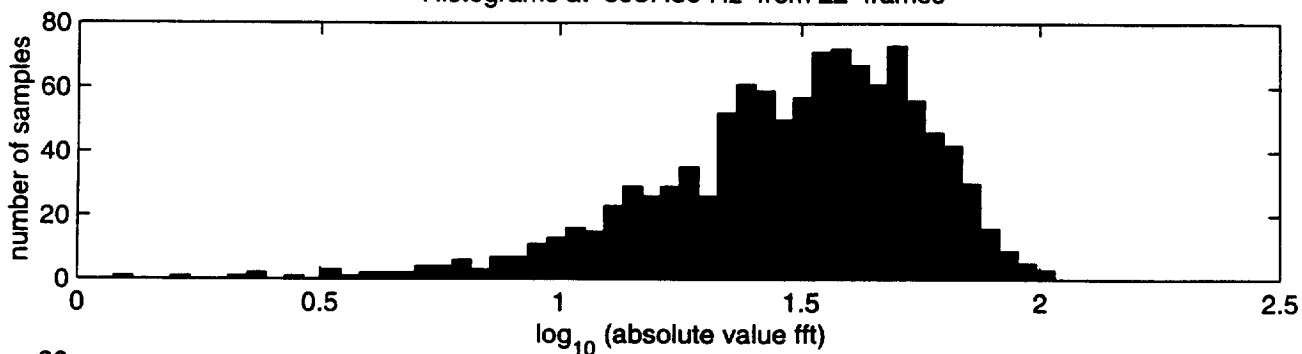
Histograms at 1963.82 Hz from 22 frames



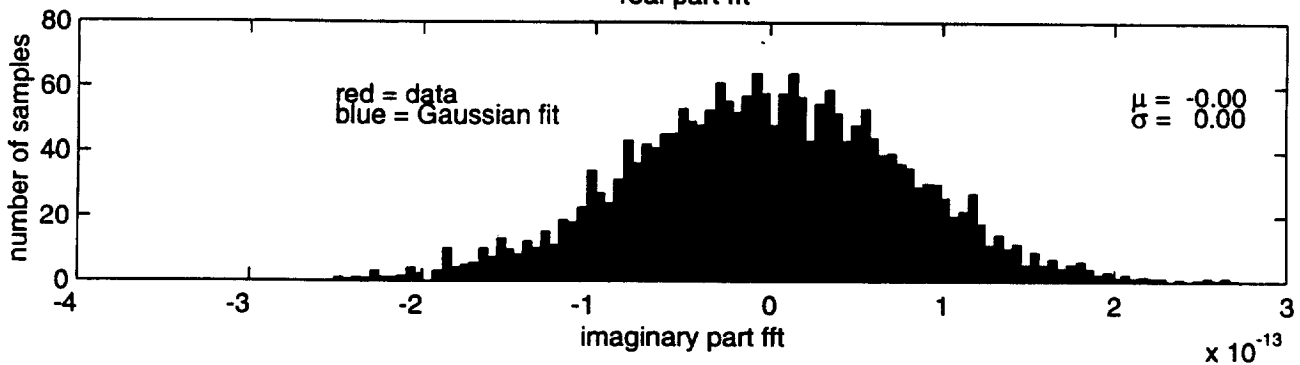
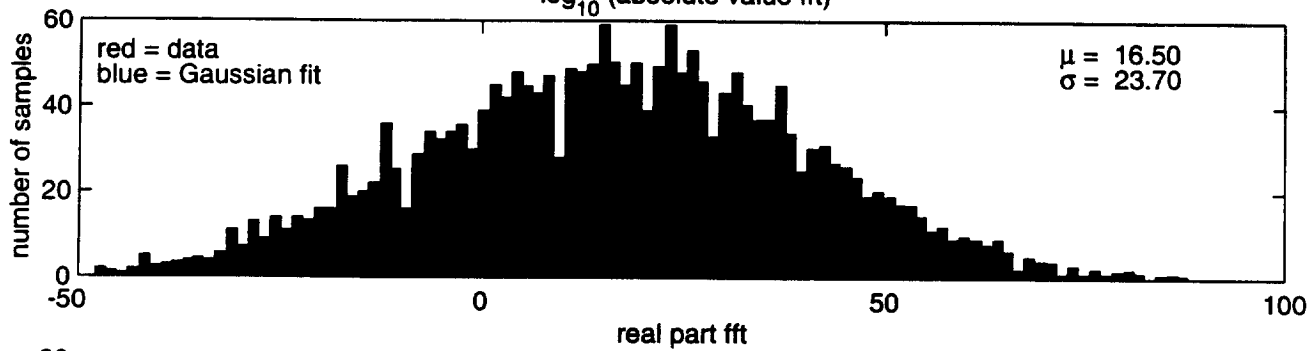
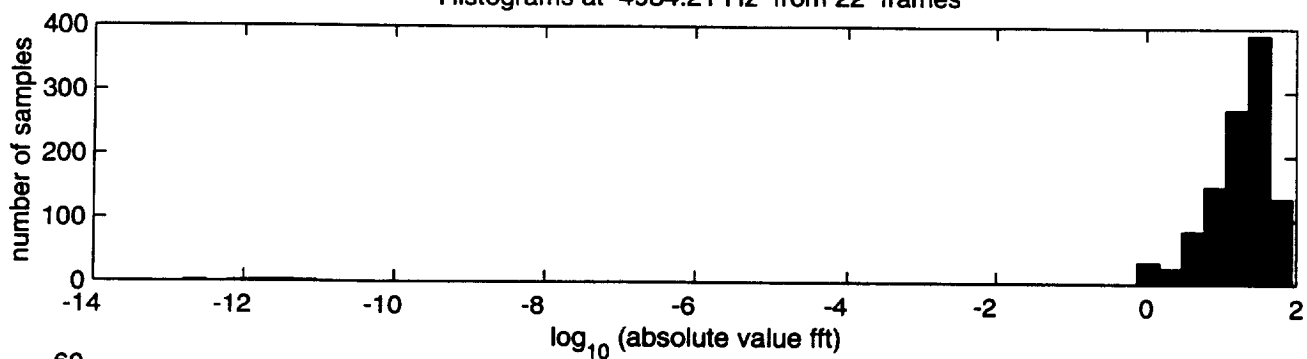
Histograms at 2950.66 Hz from 22 frames



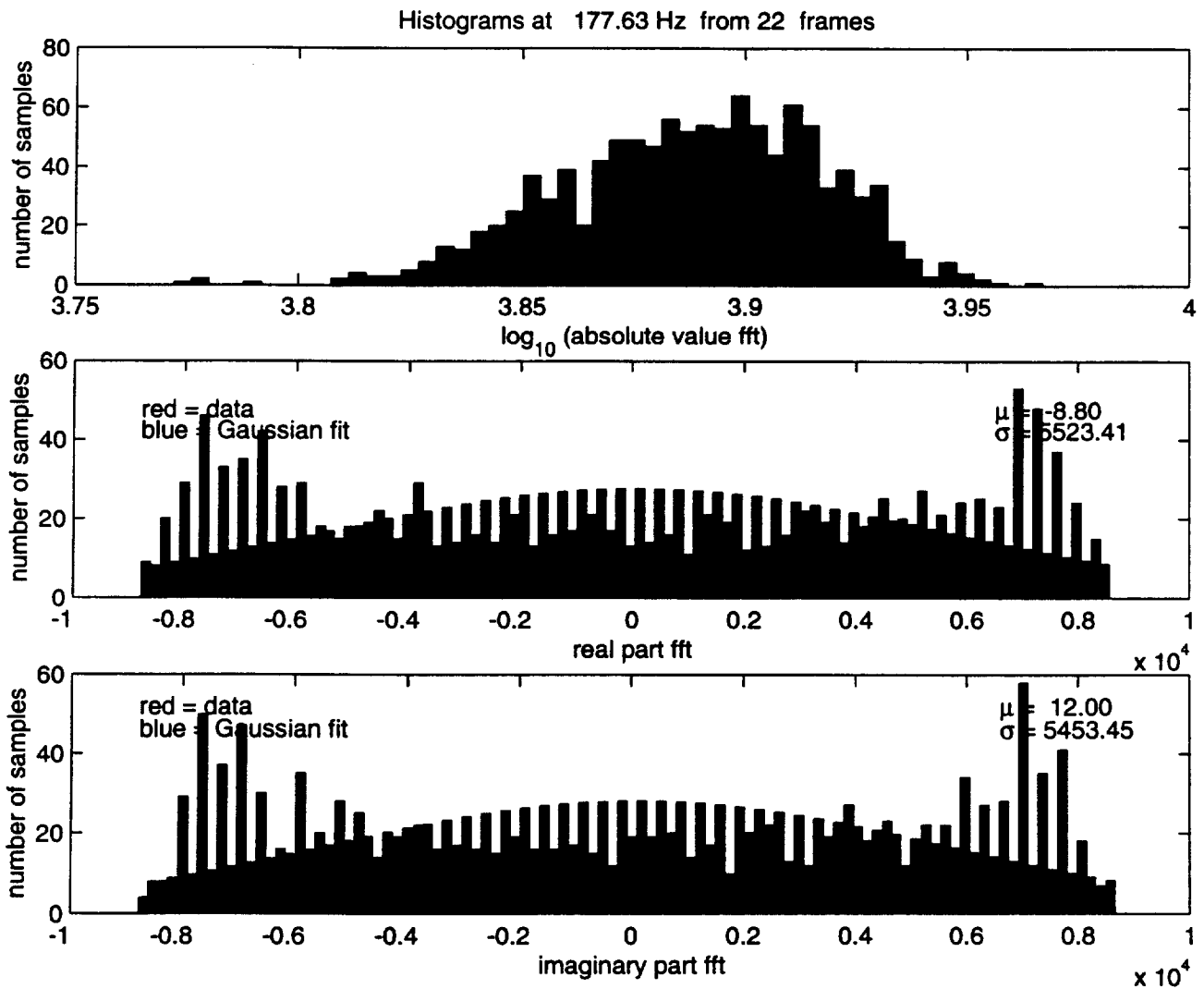
Histograms at 3937.50 Hz from 22 frames



Histograms at 4934.21 Hz from 22 frames



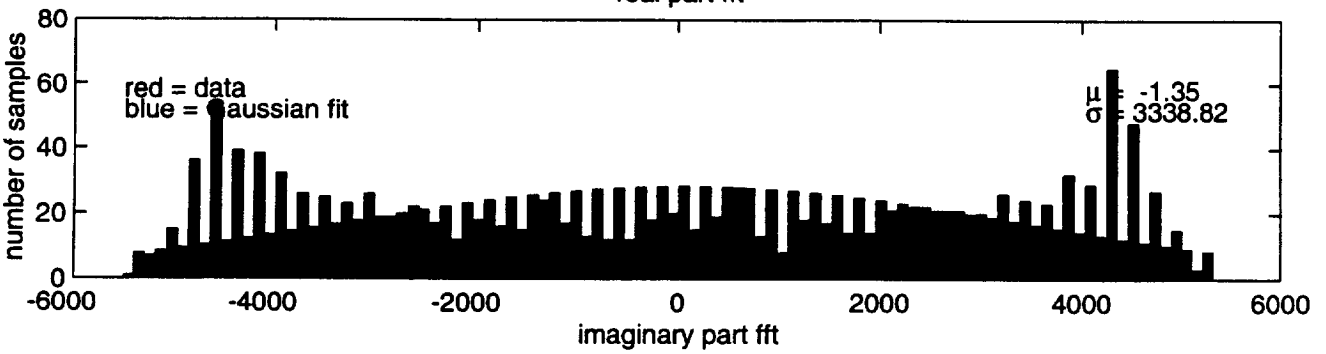
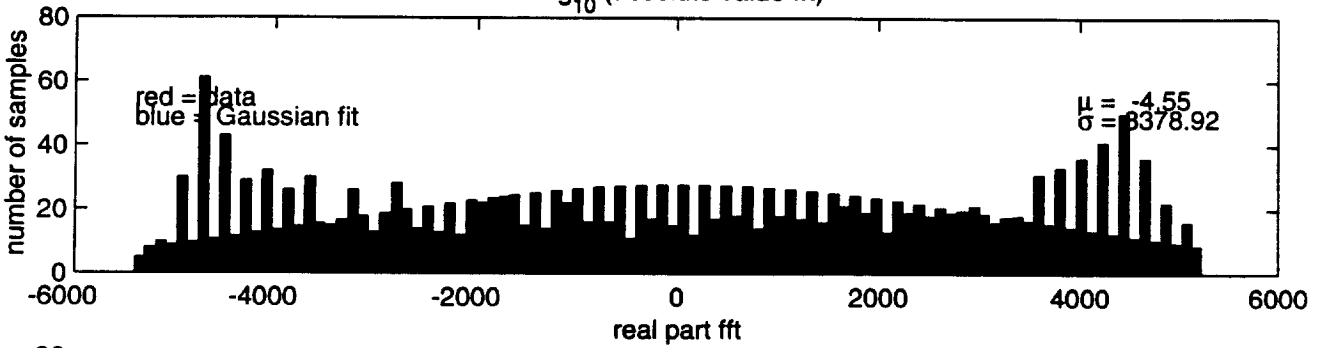
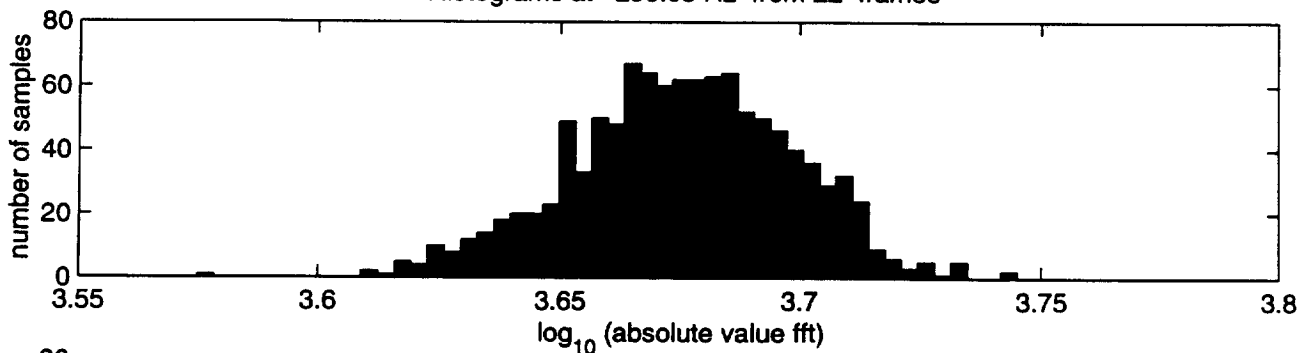
LINE INTERFERENCE NOISE (180 Hz)



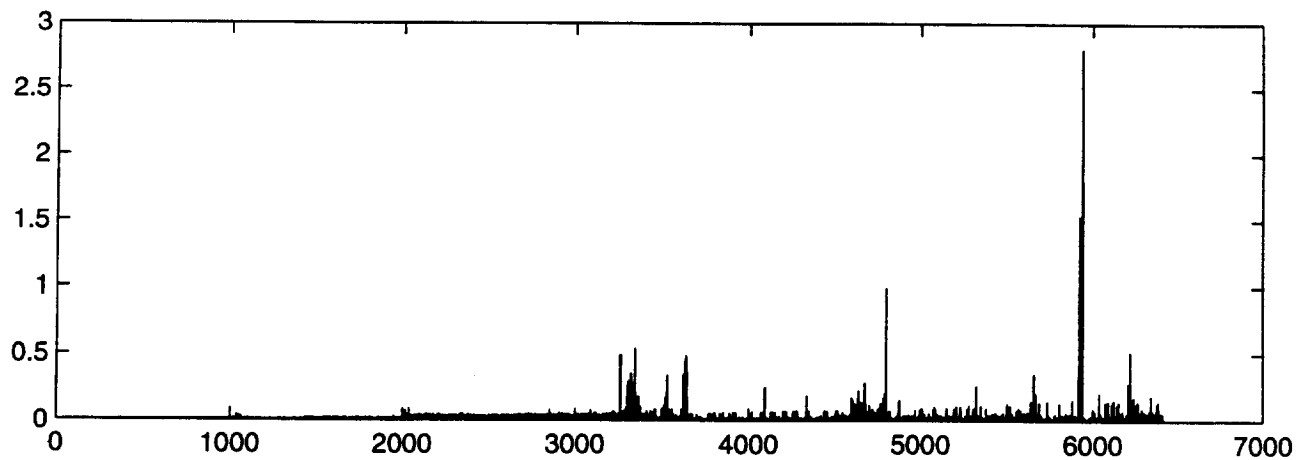
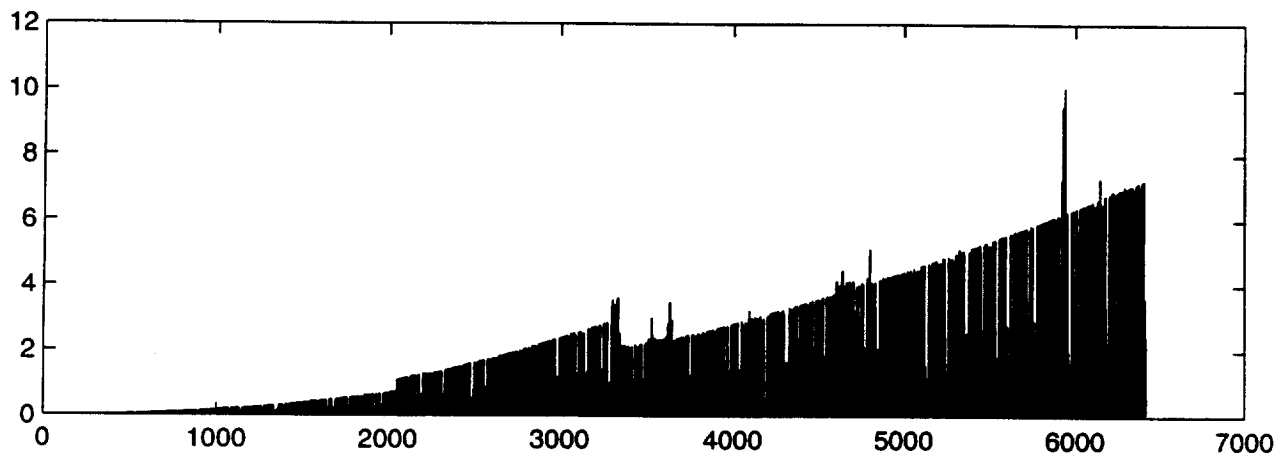
WISH TO RE-EXAMINE AFTER LINE REMOVAL!

LINE INTERFERENCE NOISE (300 Hz)

Histograms at 296.05 Hz from 22 frames

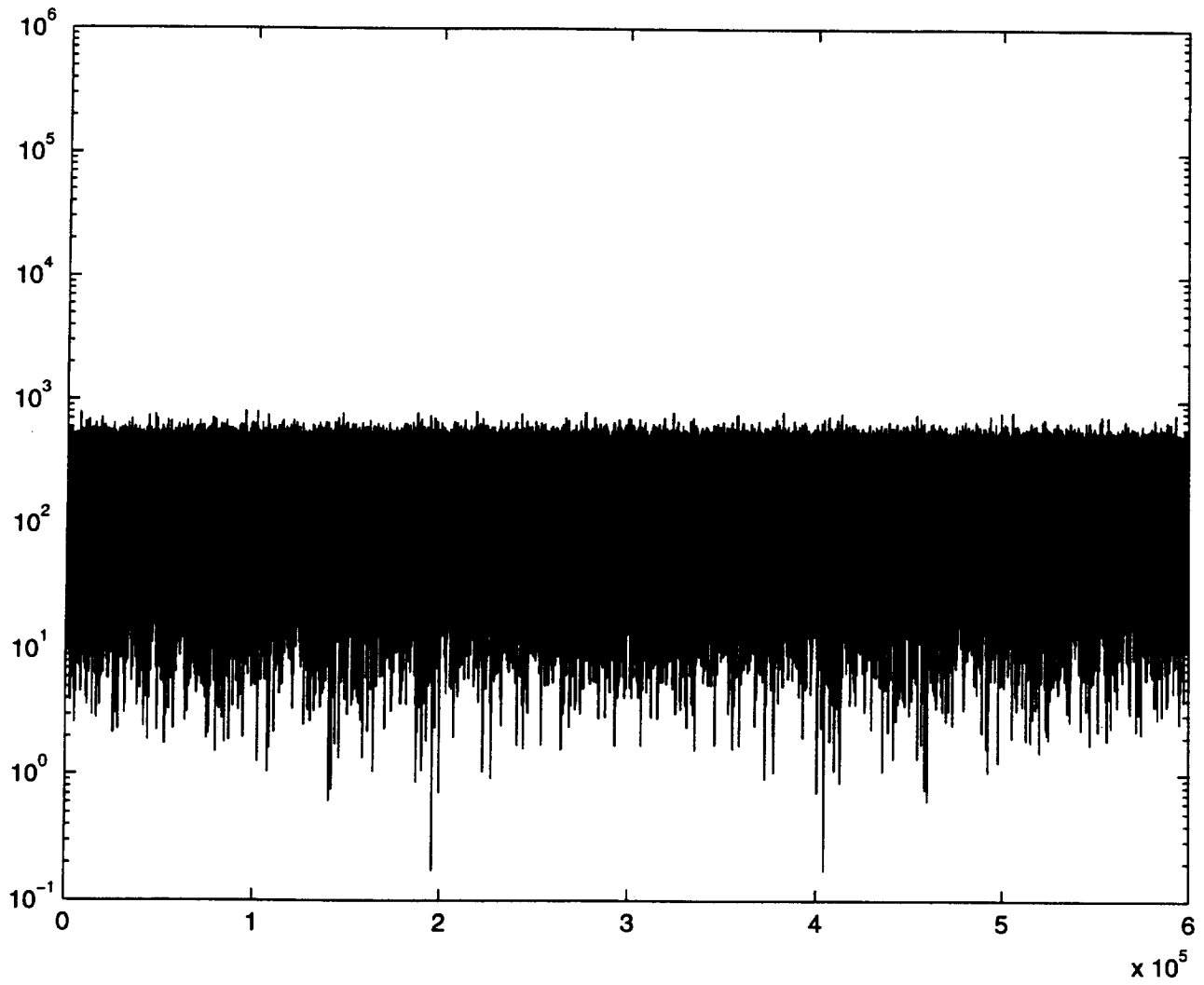


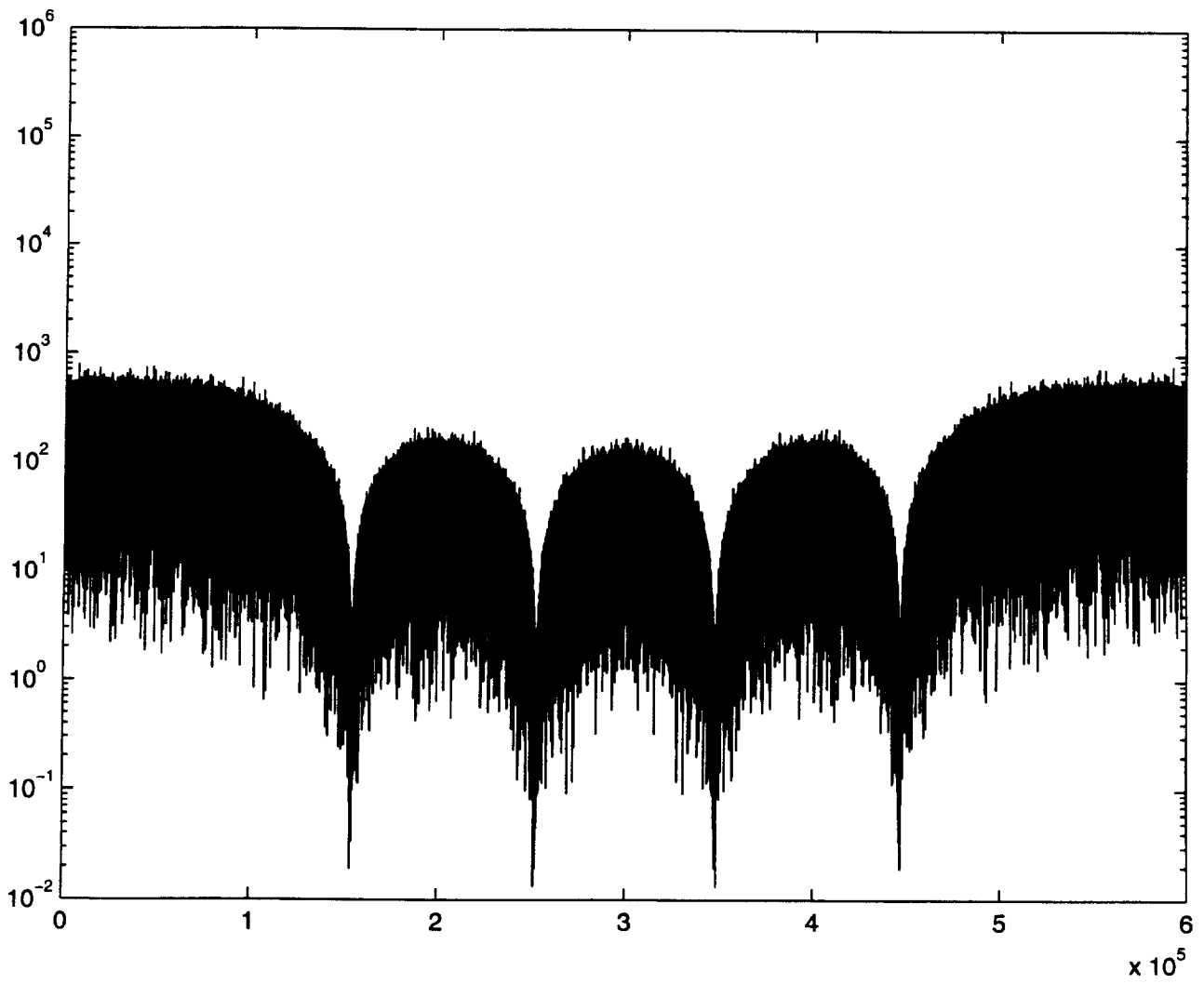
TRANSFORM LENGTH vs FFT TIME

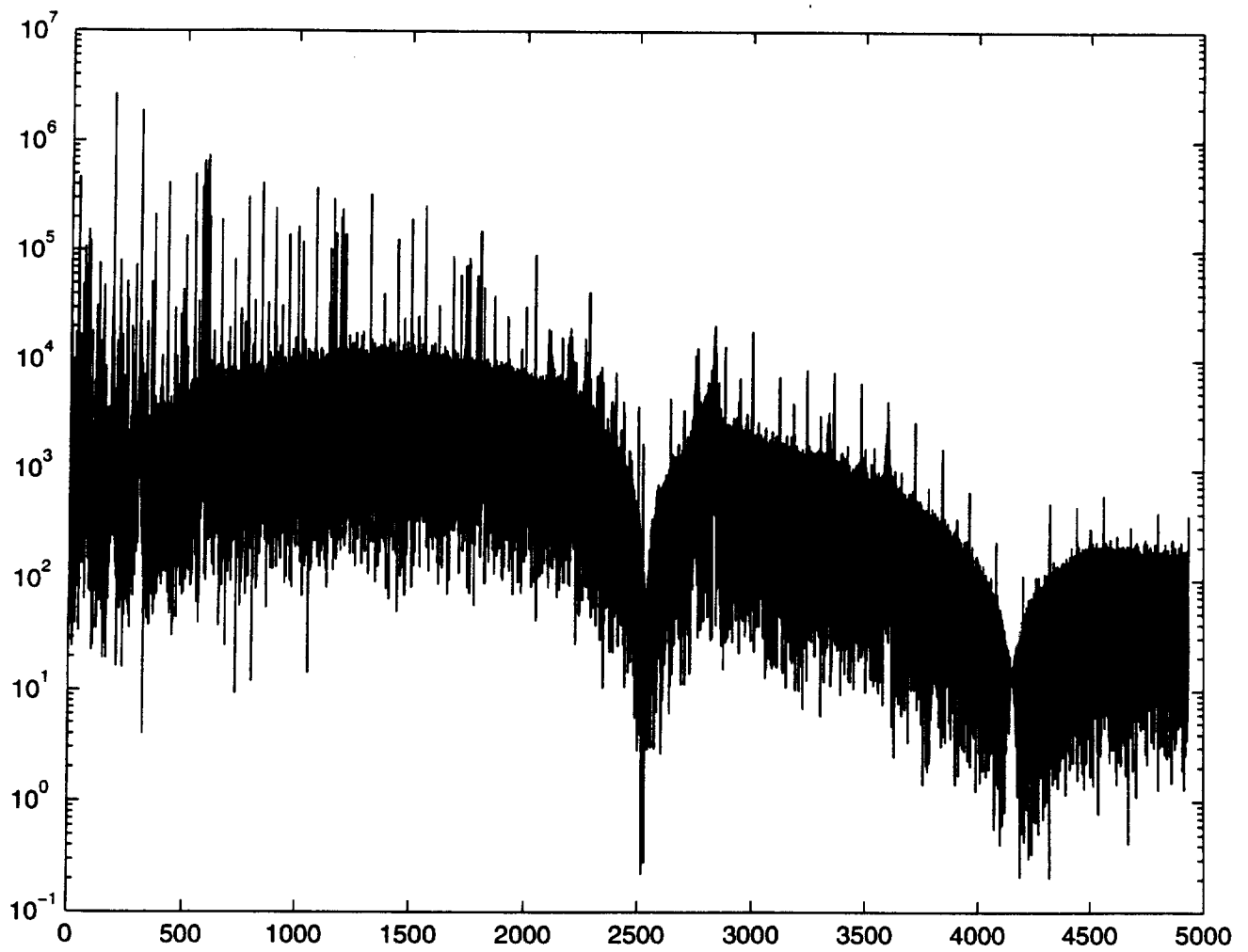


EFFICIENT METHODS FOR MANY FACTORS !

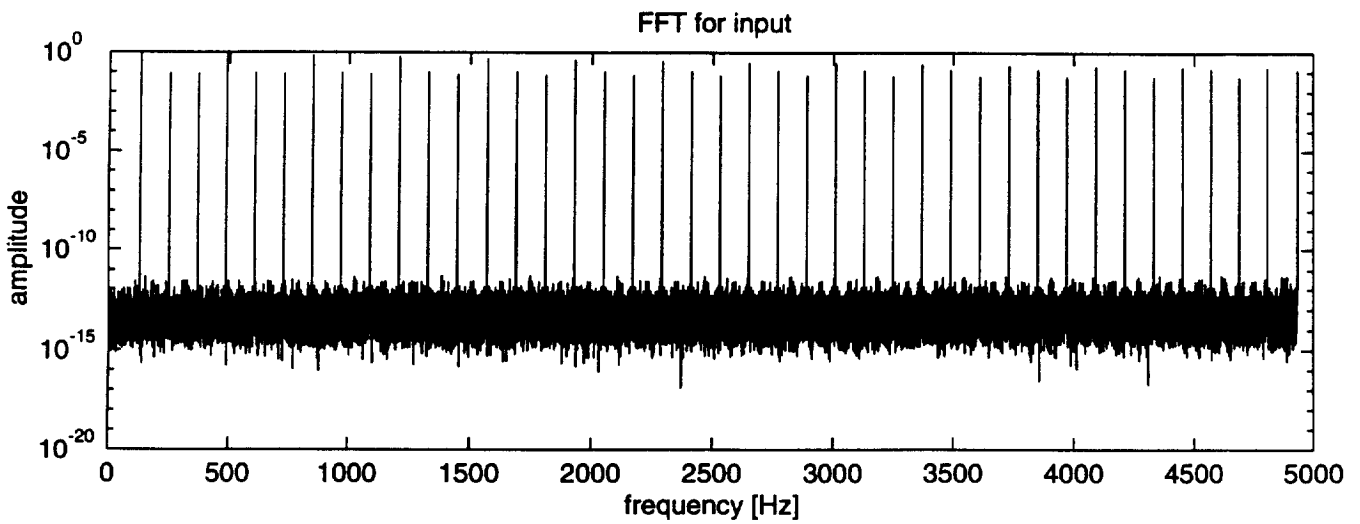
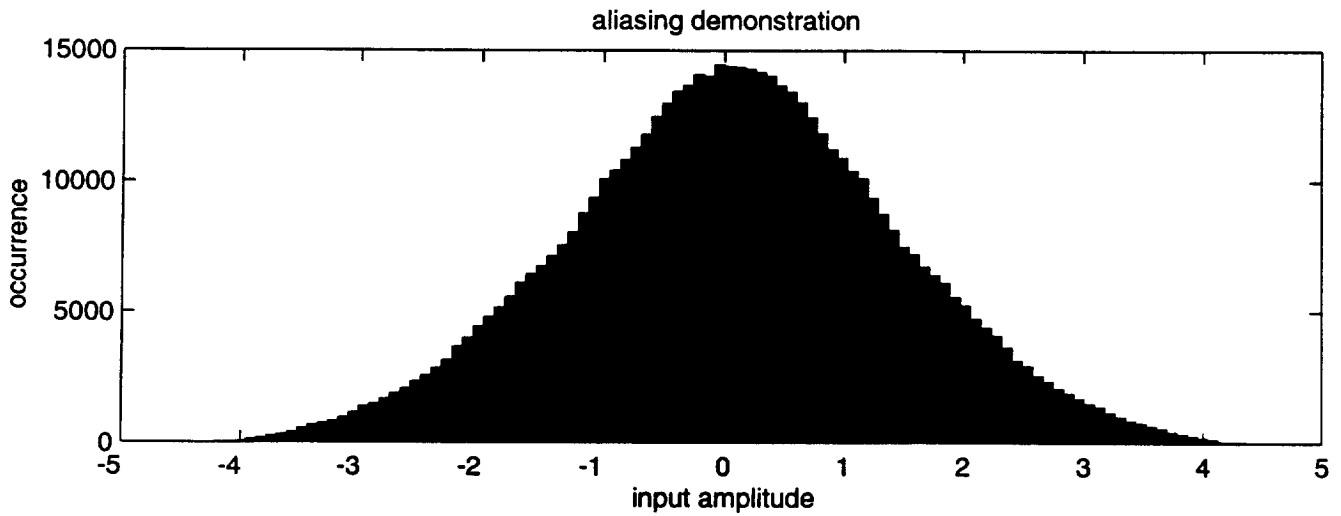
DIGITAL FILTERING / SMOOTHING



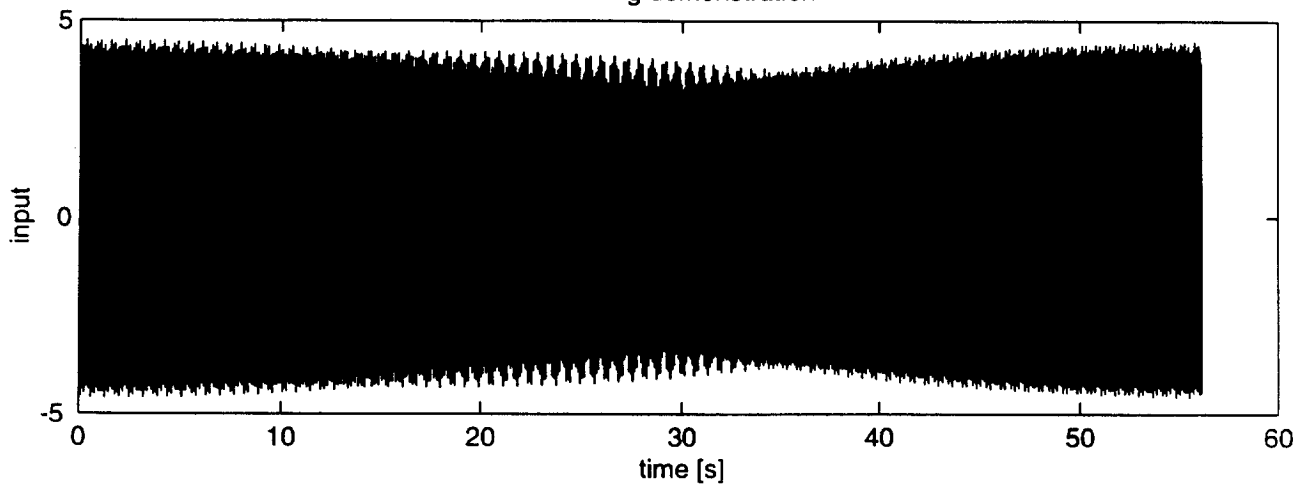




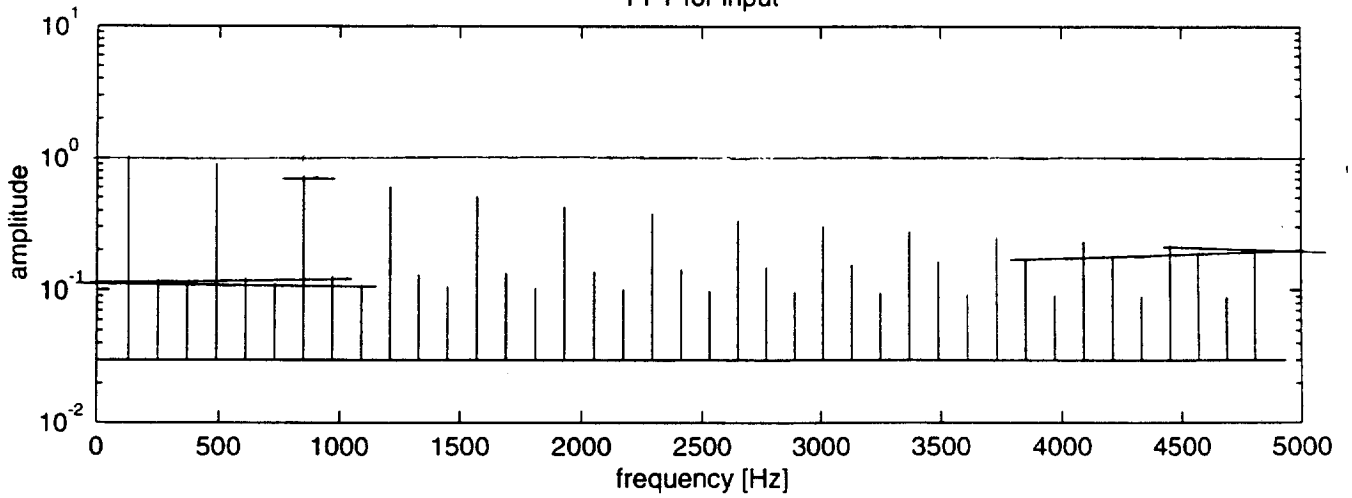
DISTRIBUTION DIVERSITY



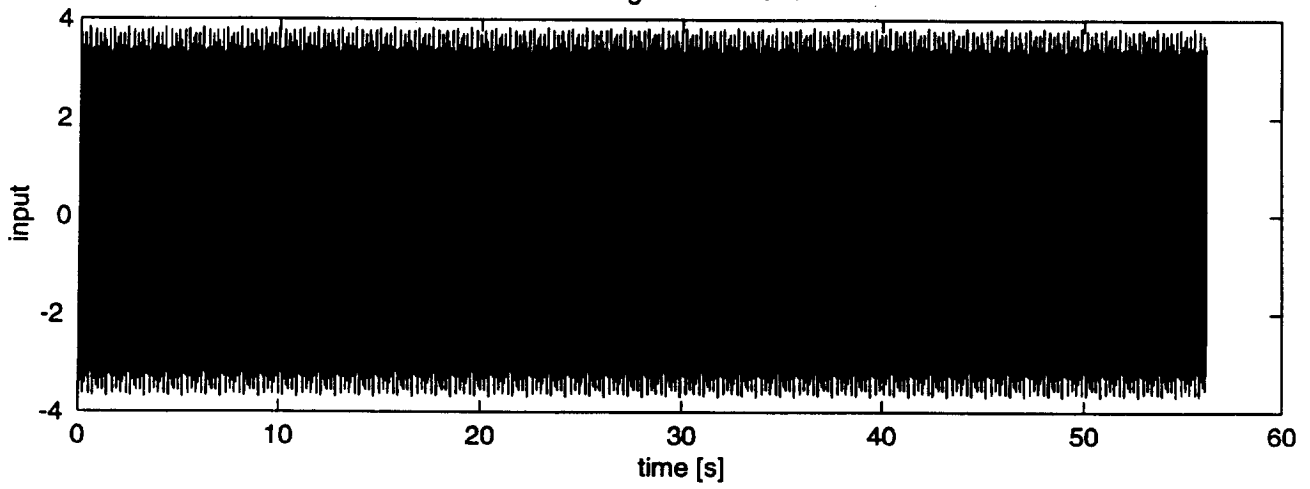
aliasing demonstration



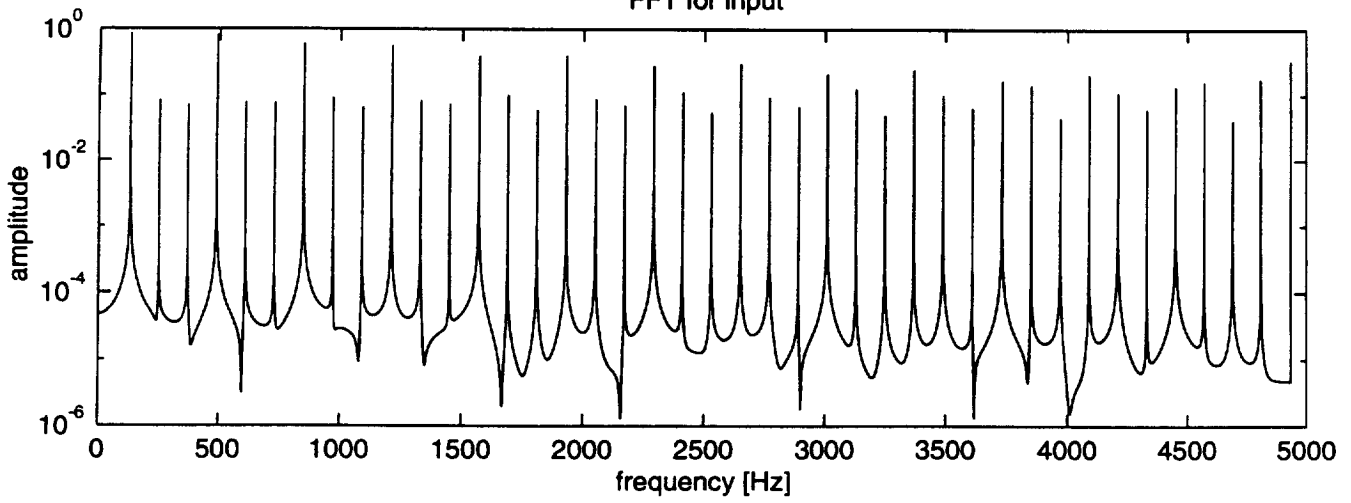
FFT for input

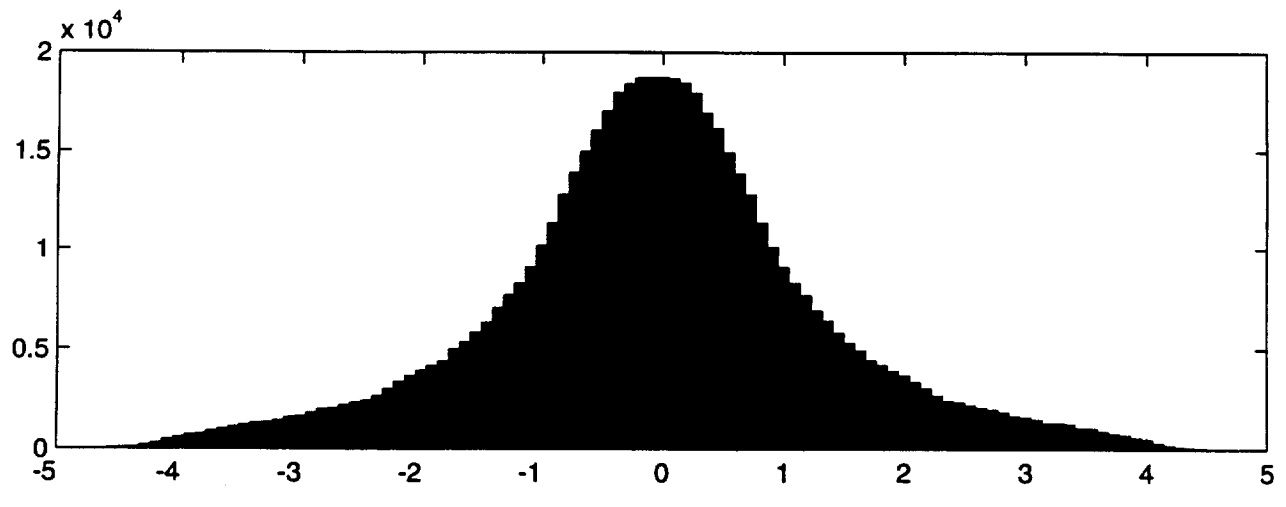
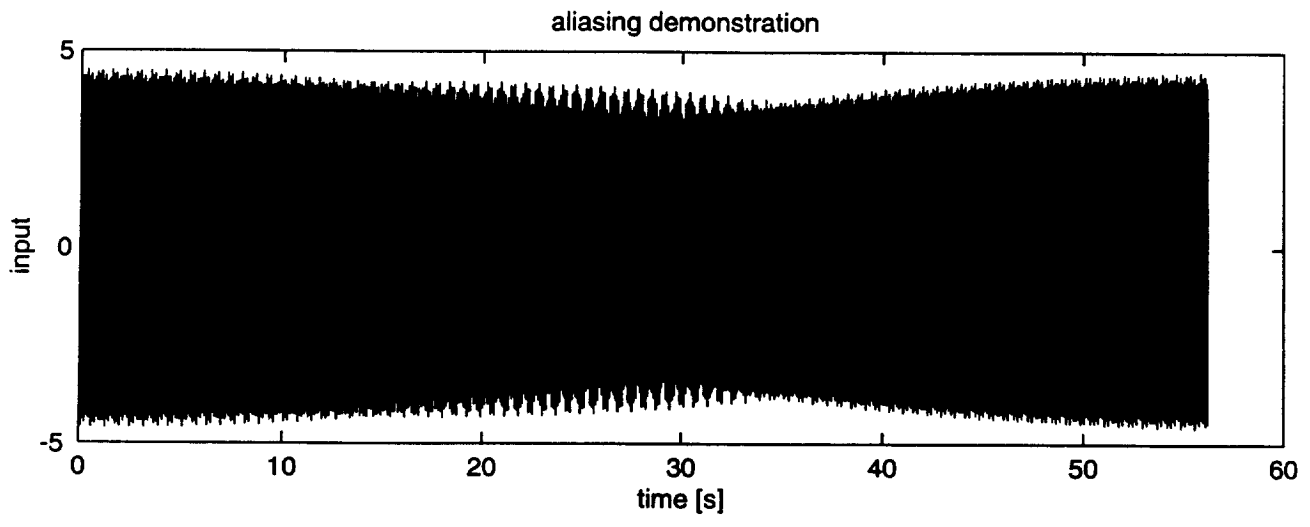


aliasing demonstration

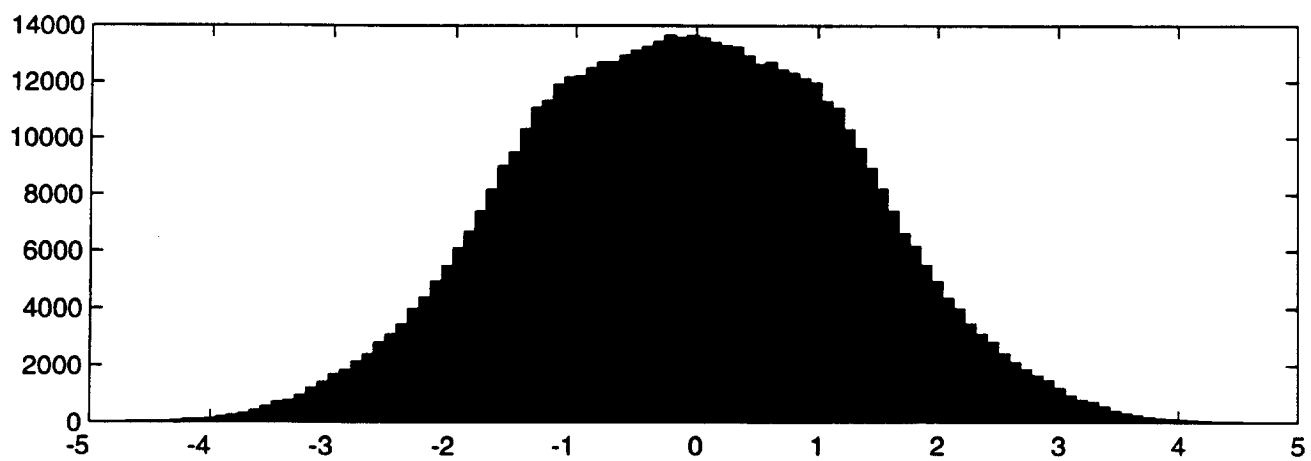
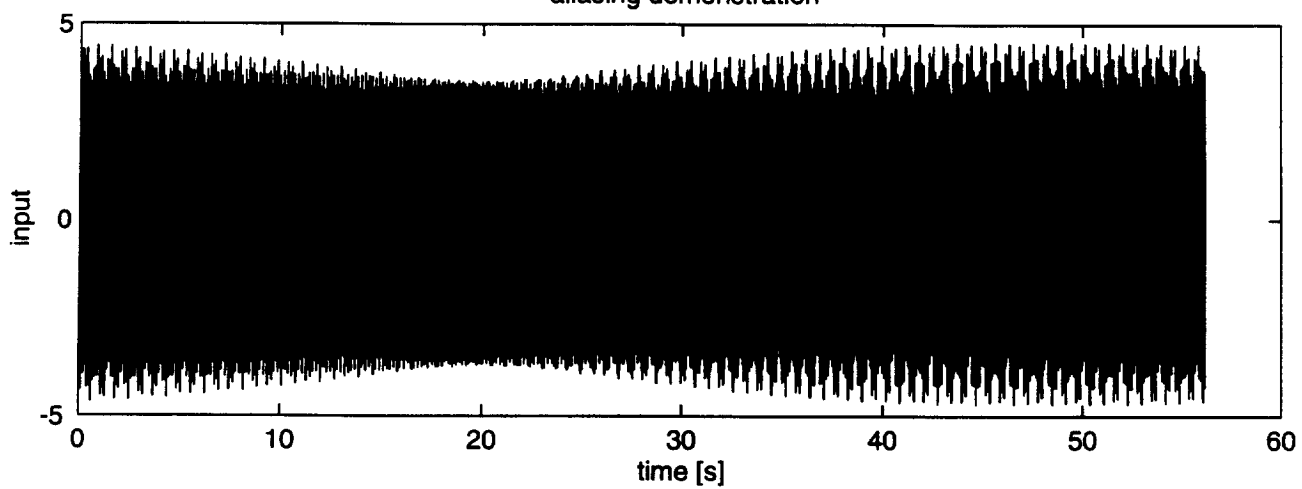


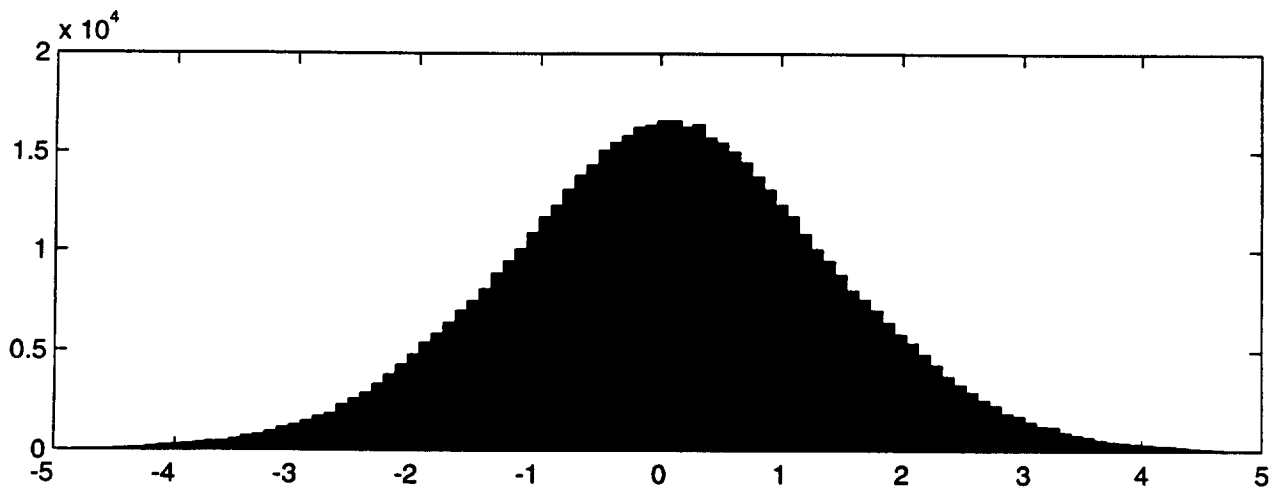
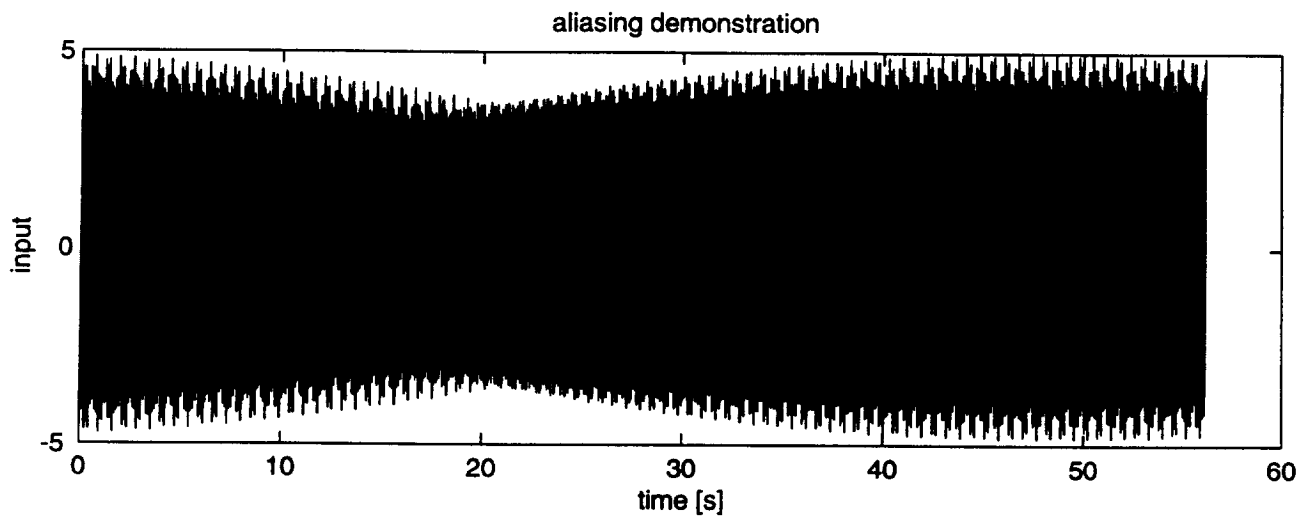
FFT for input



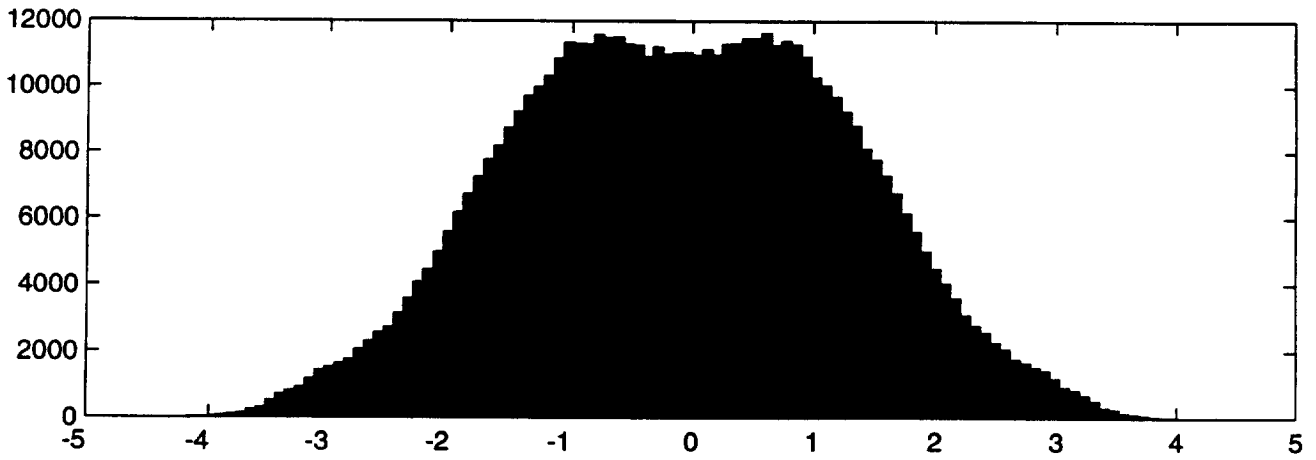
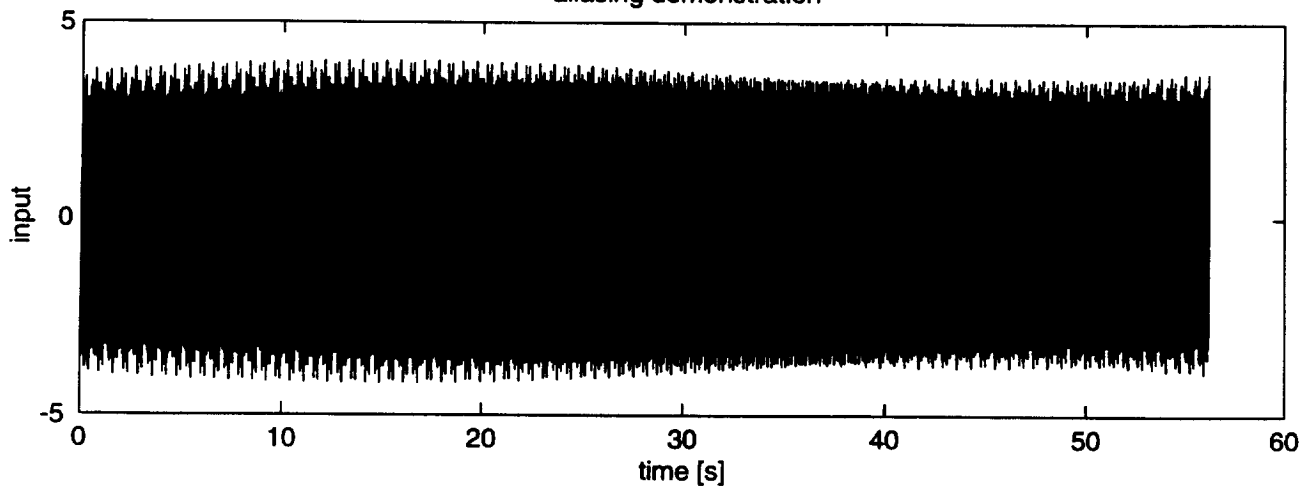


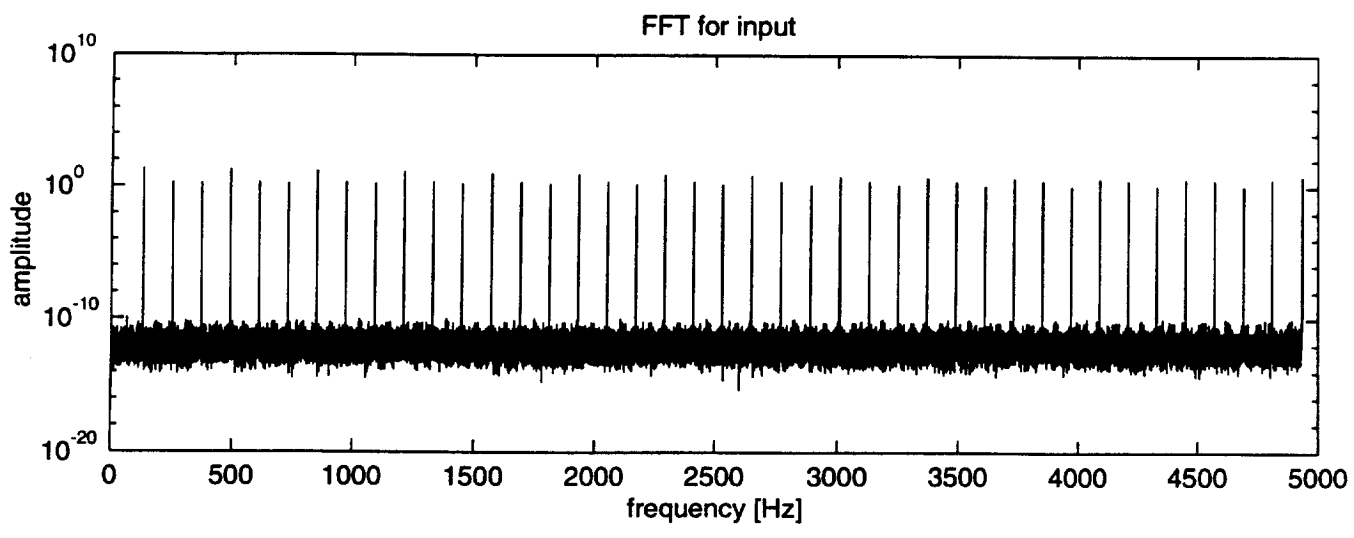
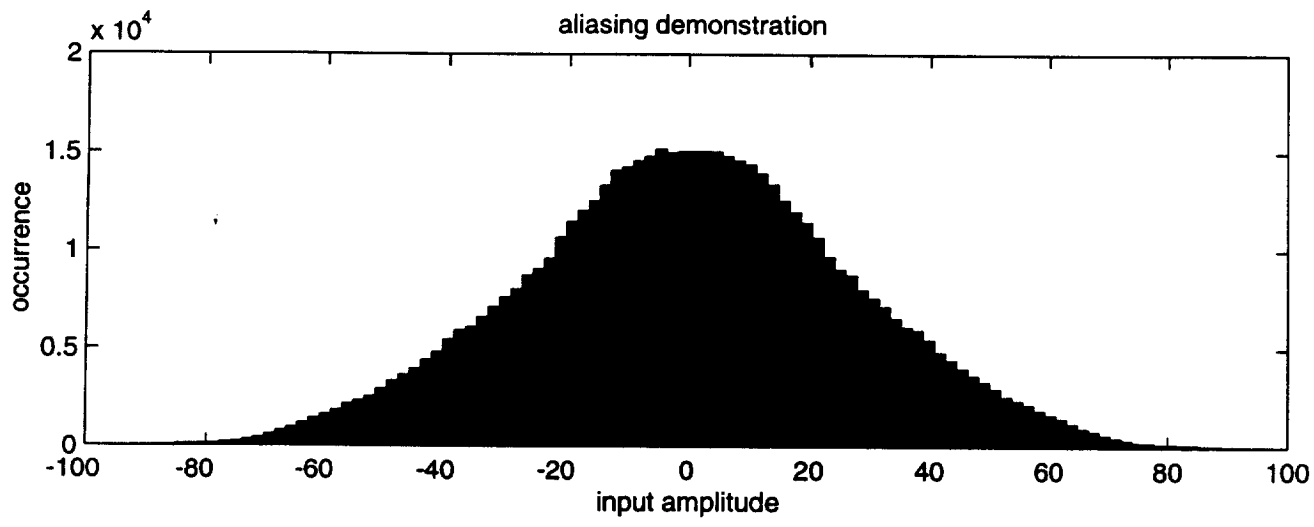
aliasing demonstration

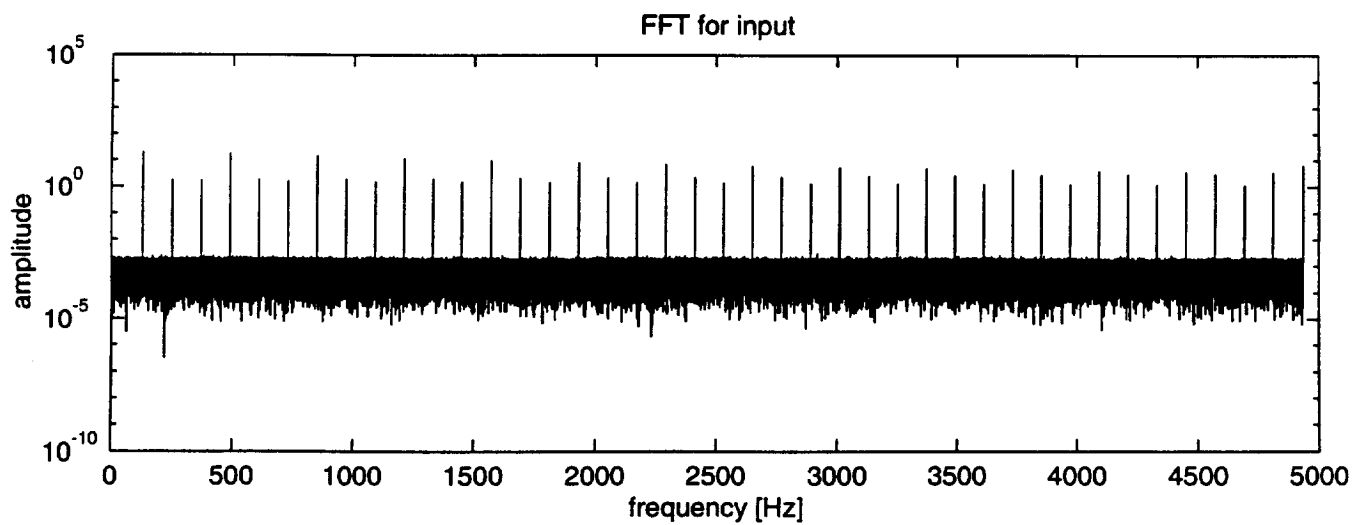
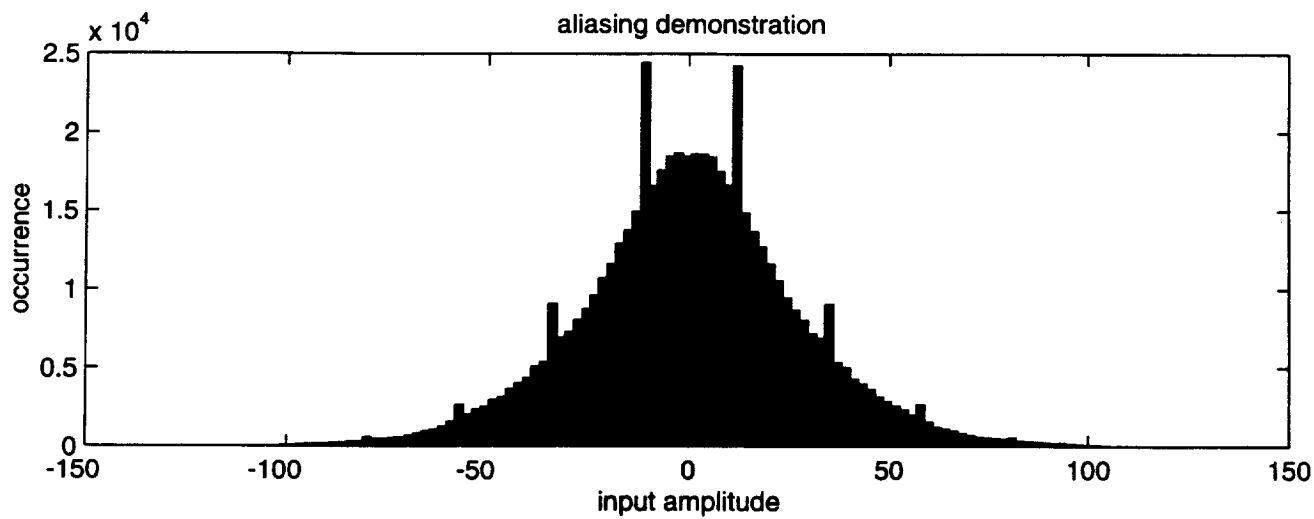




aliasing demonstration







BERNARD WHITING.
(ANU & UF)

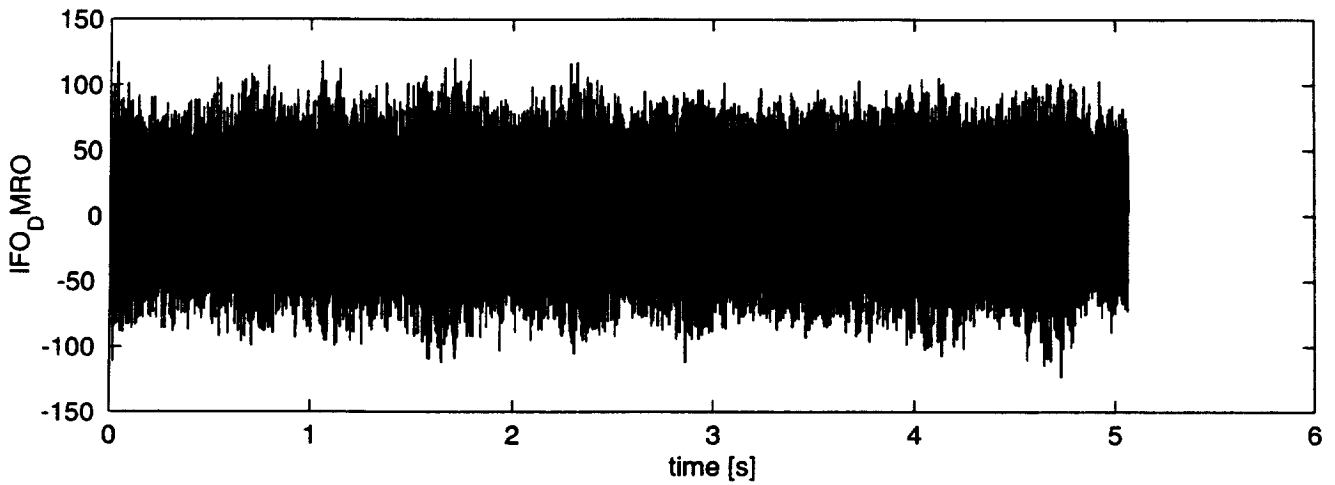
DATA ANALYSIS

bernard@phys.ufl.edu.

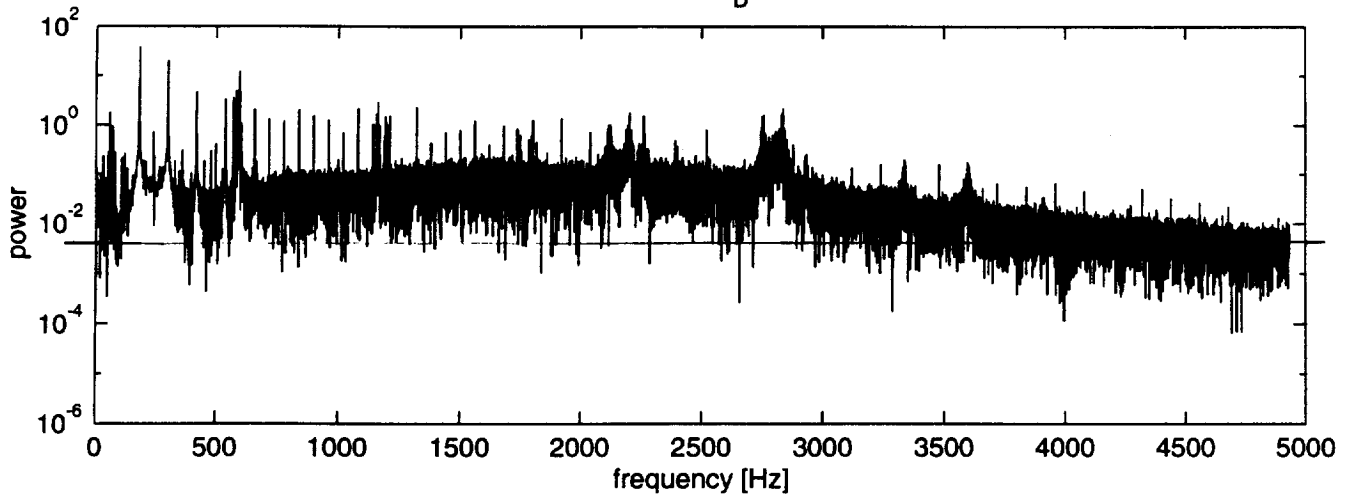
Detector Characterization

EXAMINING 40 METER DATA

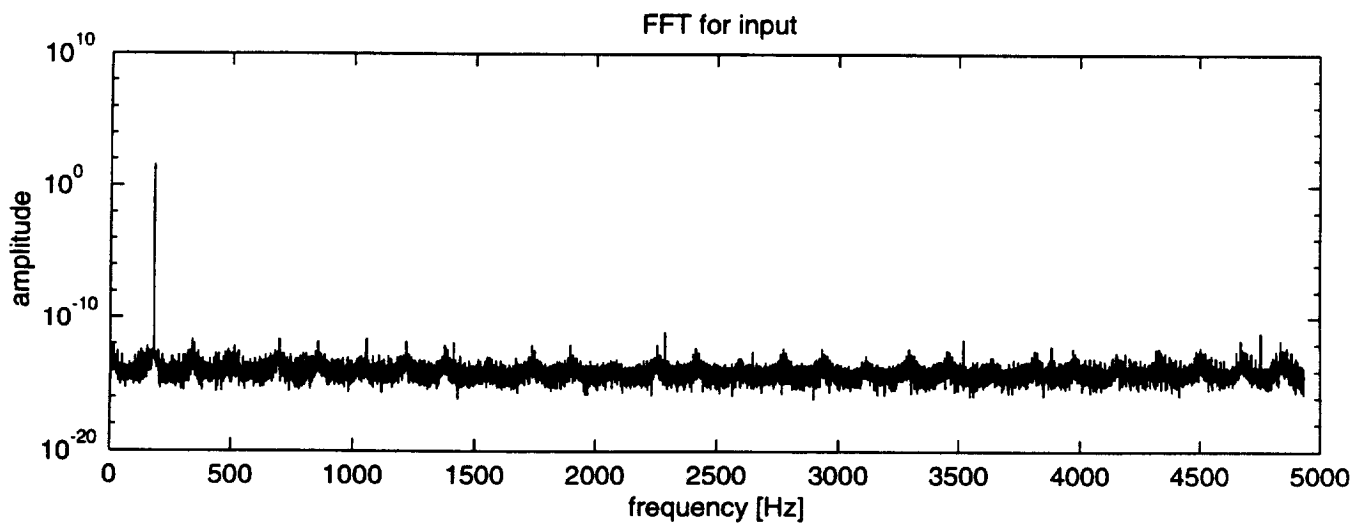
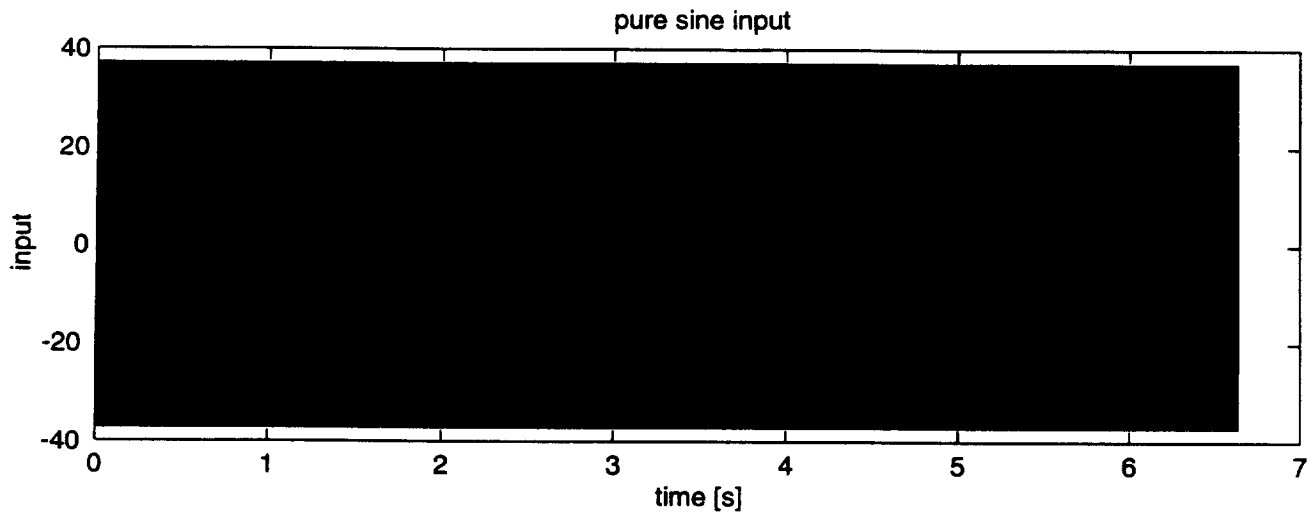
Starting GPS time: Tue Nov 20 05:22:25 1934 (and 881333 usec)



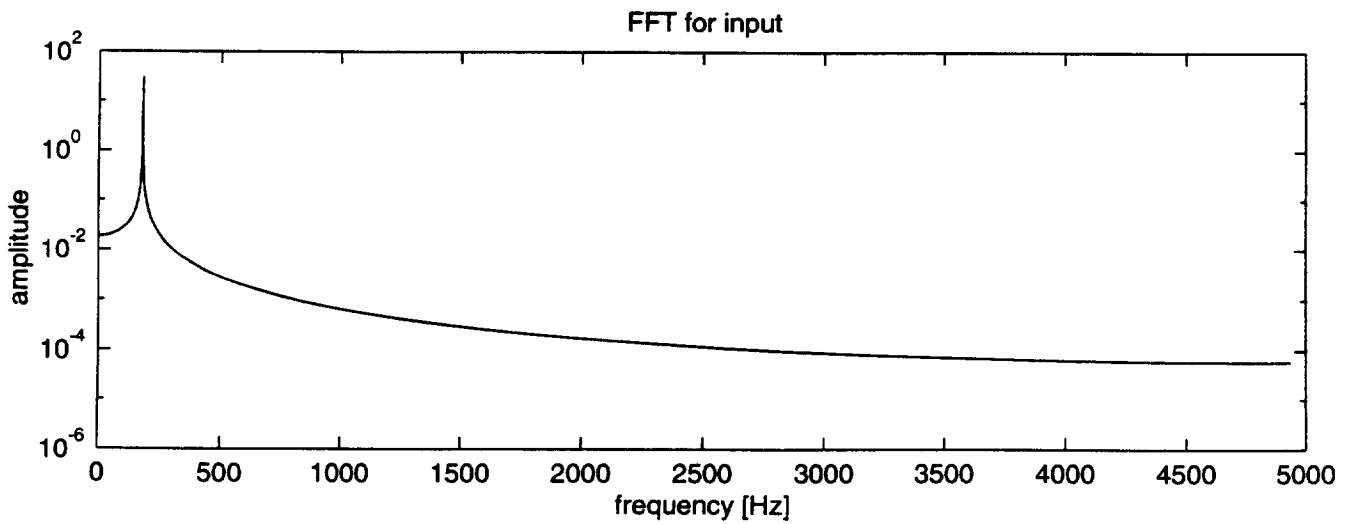
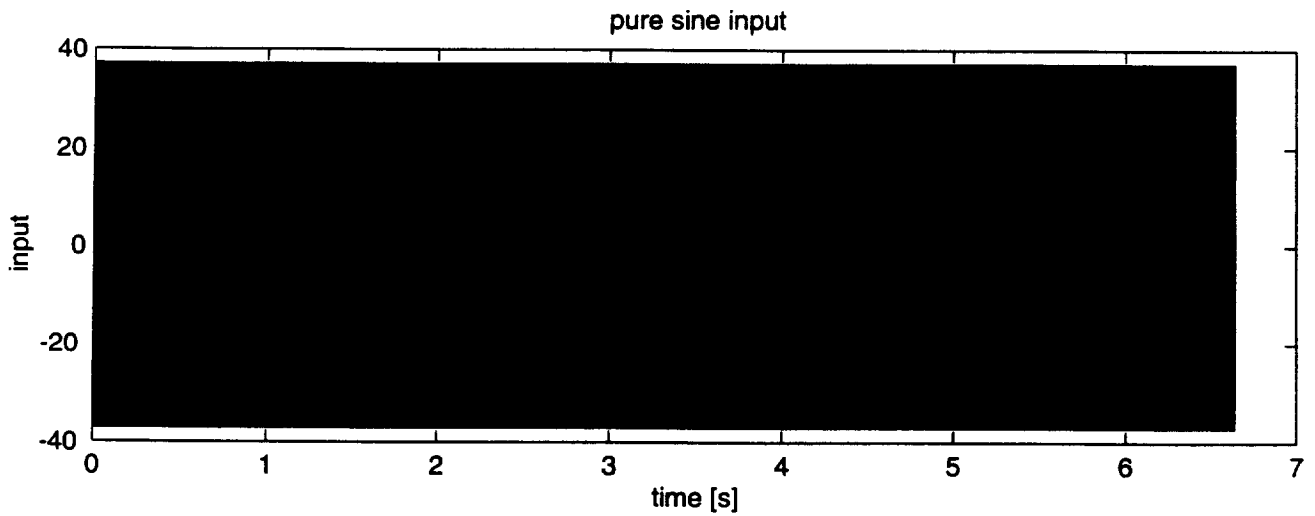
FFT for IFO_MRO



COMPUTATIONAL NOISE



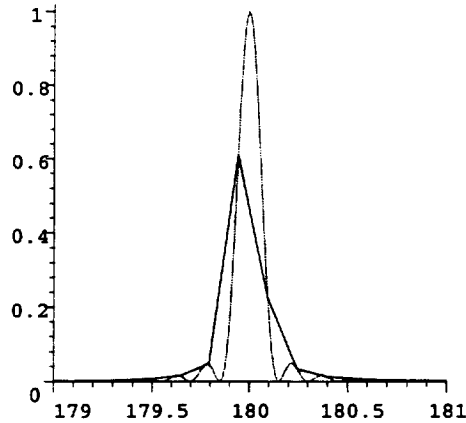
FREQUENCY MISMATCH



```

[ > n1:=round(n0);
                                     n1 := 1195
[ > f1:=n1*df;
                                     f1 :=  $\frac{56015625}{311296}$ 
[ > y1:=plot((sin(Pi*(f0-f)/df)/sin(Pi*(f0-f)/sr)/n1)^2, f=179..181):
[ > with(plots):
[ > y2:=pointplot([seq([n*df, (sin(Pi*(n0-n))/sin(Pi*(n0-n)/n1)/n1)^2
[   ], n=round(179/df)..round(181/df)]), style=line):
[ > y0:={y1,y2}:
[ > display(y0, insequence=false);

```



```

[ > y3:=plot((sin(Pi*(f1-f)/df)/sin(Pi*(f1-f)/sr)/n1)^2, f=179..181):
[ > y2:=pointplot([seq([n*df, (sin(Pi*(n1-n))/sin(Pi*(n1-n)/n1)/n1)^2
[   ], n=round(179/df)..n1-1), [n1*df, 1], seq([n*df, (sin(Pi*(n1-n))/sin
[   (Pi*(n1-n)/n1)/n1)^2], n=n1+1..round(181/df)]), style=line):
[

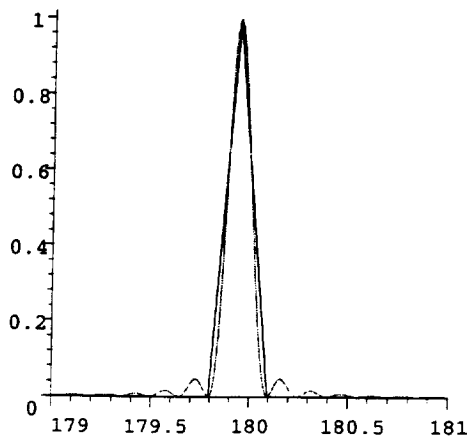
```

Page 1

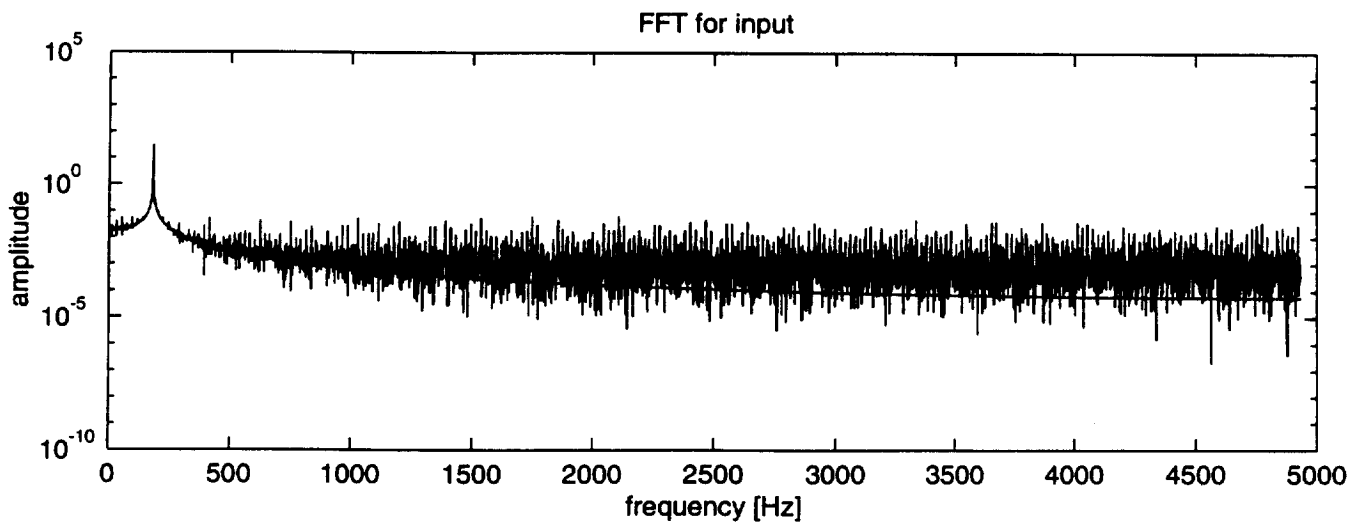
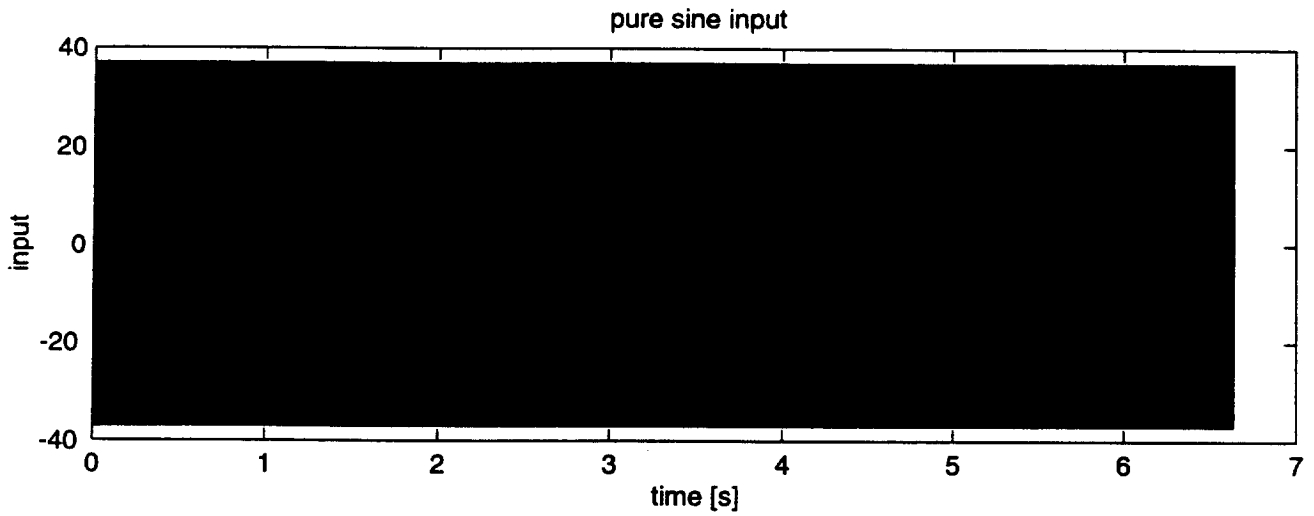
```

[ > y4:={y2,y3}:
[ > display(y4, insequence=false);

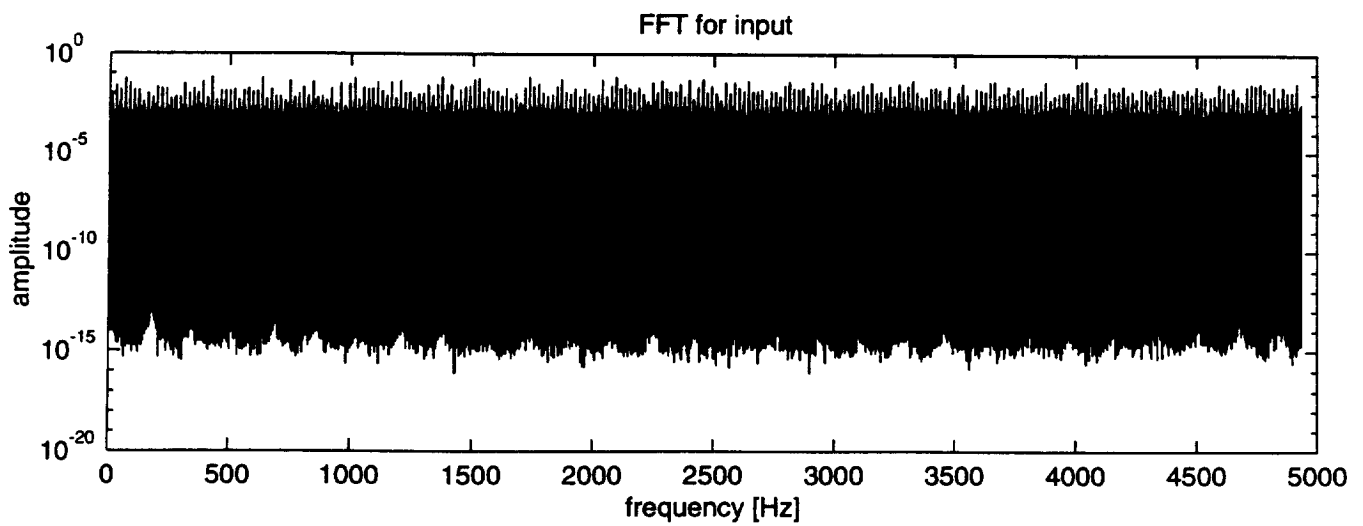
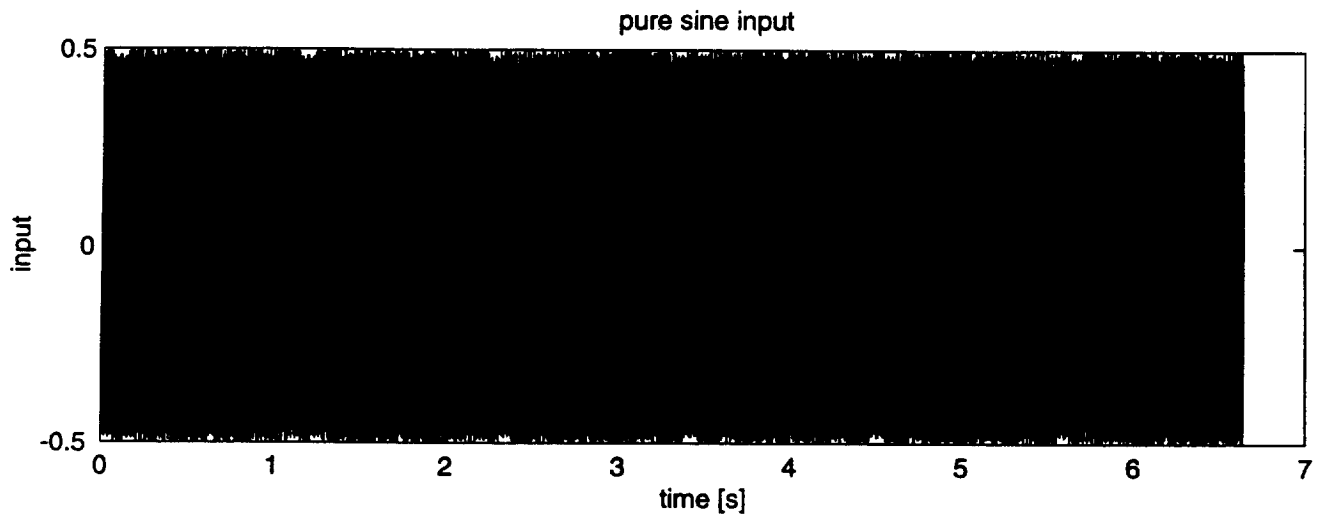
```



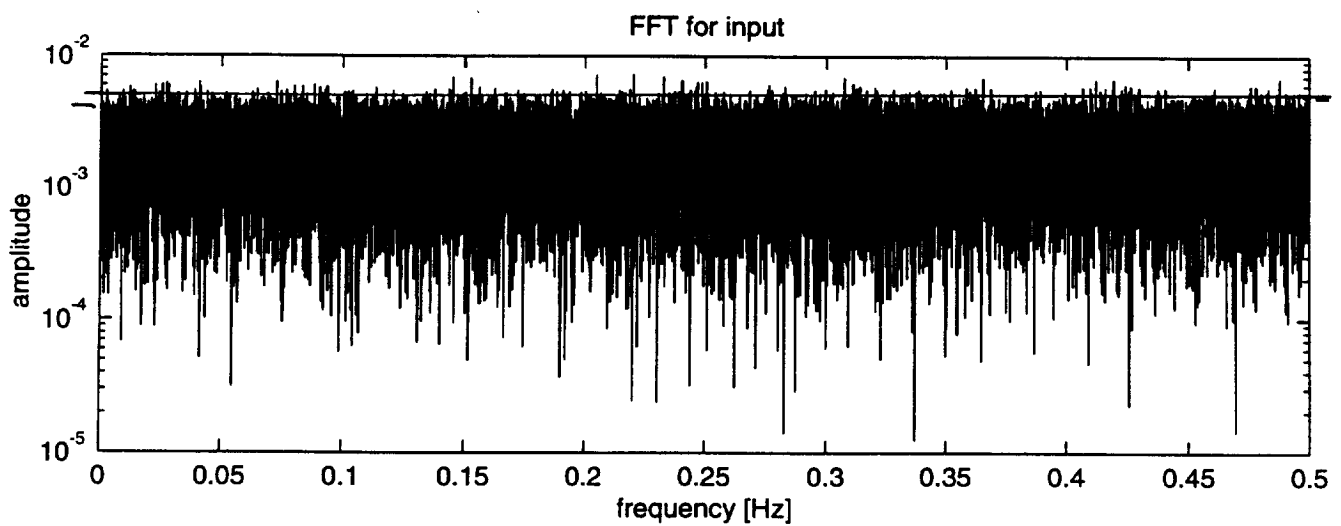
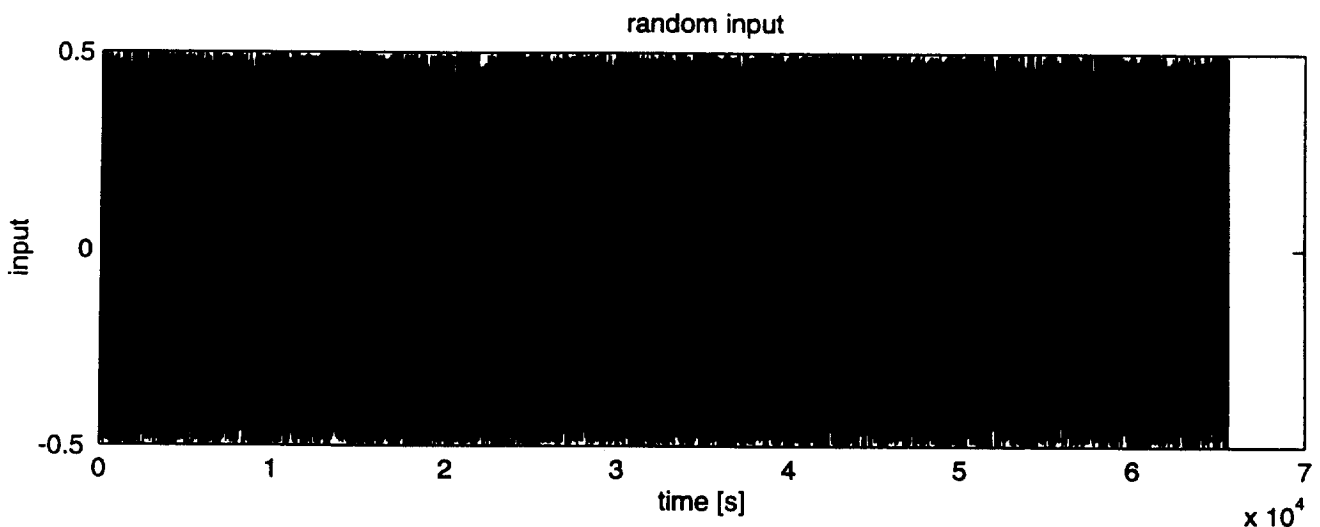
DIGITIZATION NOISE

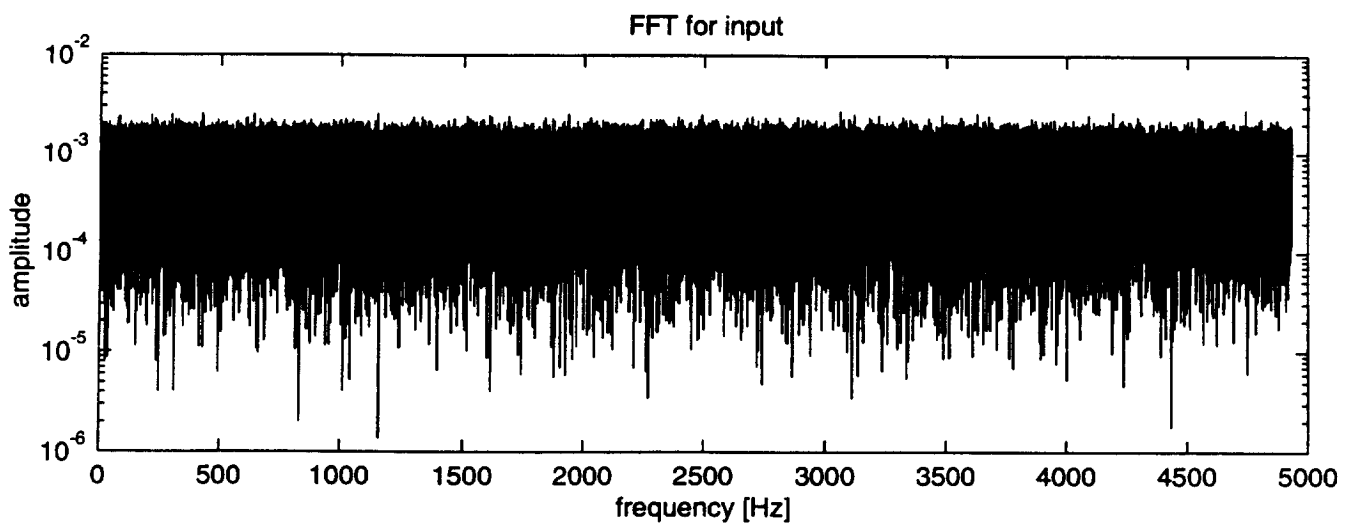
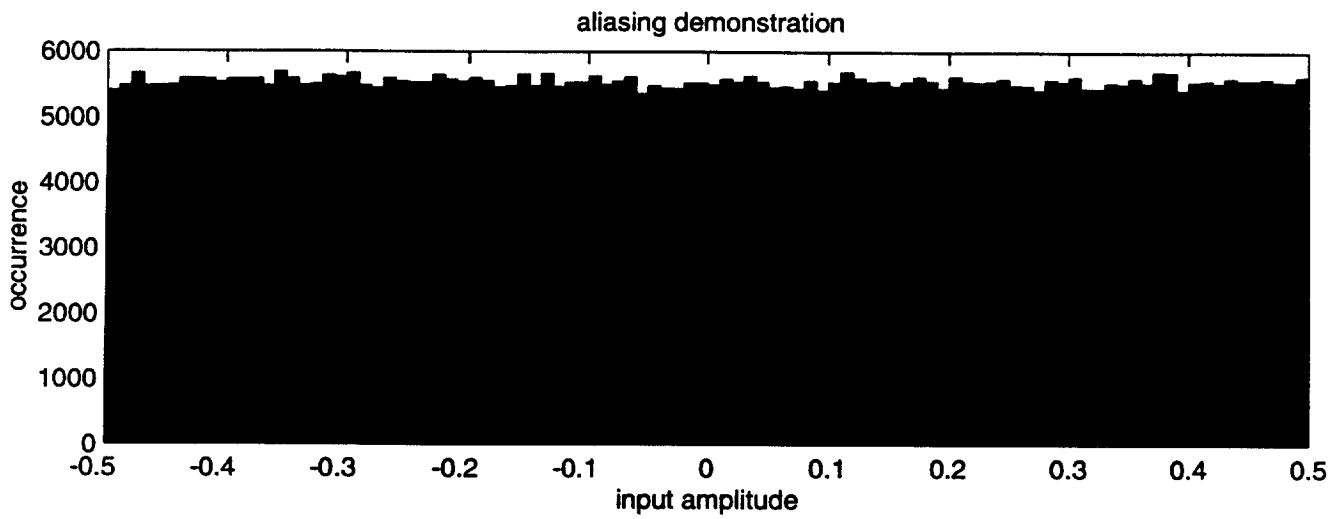


DIGITIZATION NOISE UNIFORMITY



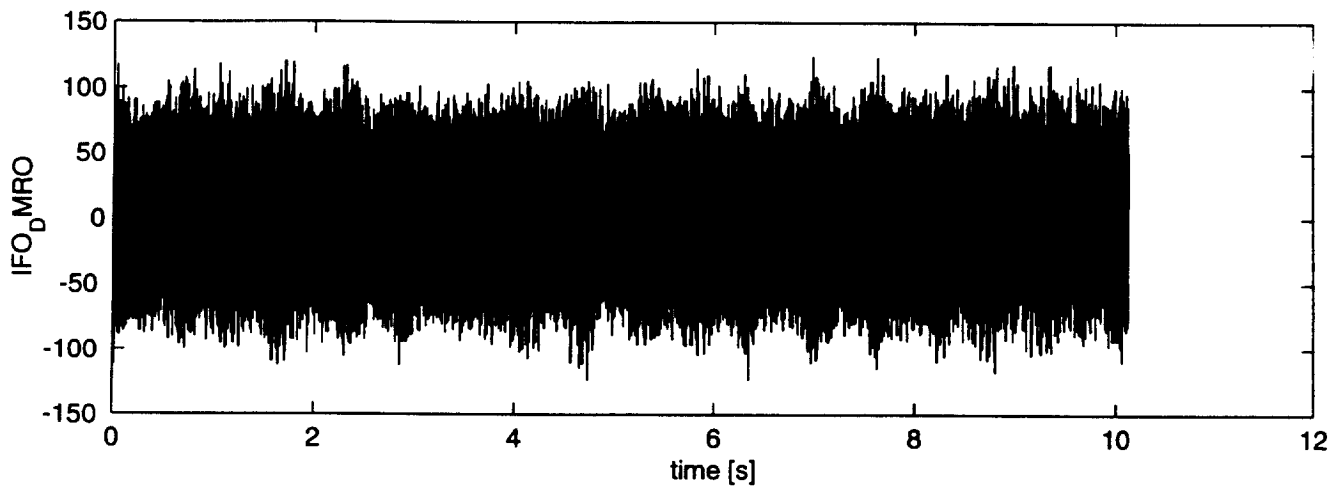
RANDOM NOISE UNIFORMITY



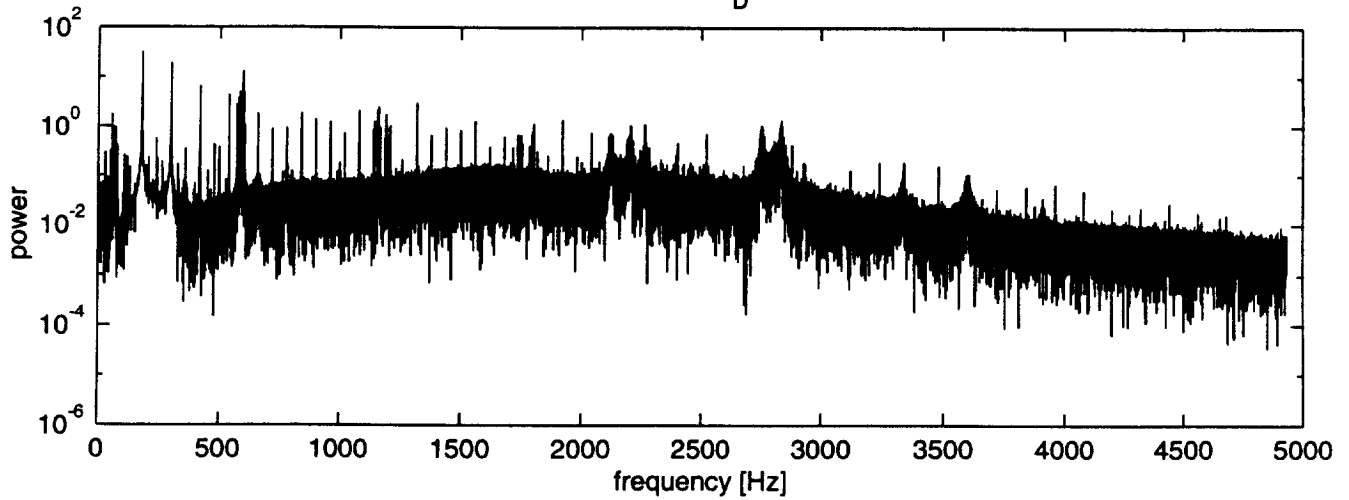


EXAMINING FREQUENCY MISMATCH

Starting GPS time: Tue Nov 20 05:22:25 1934 (and 881333 usec)

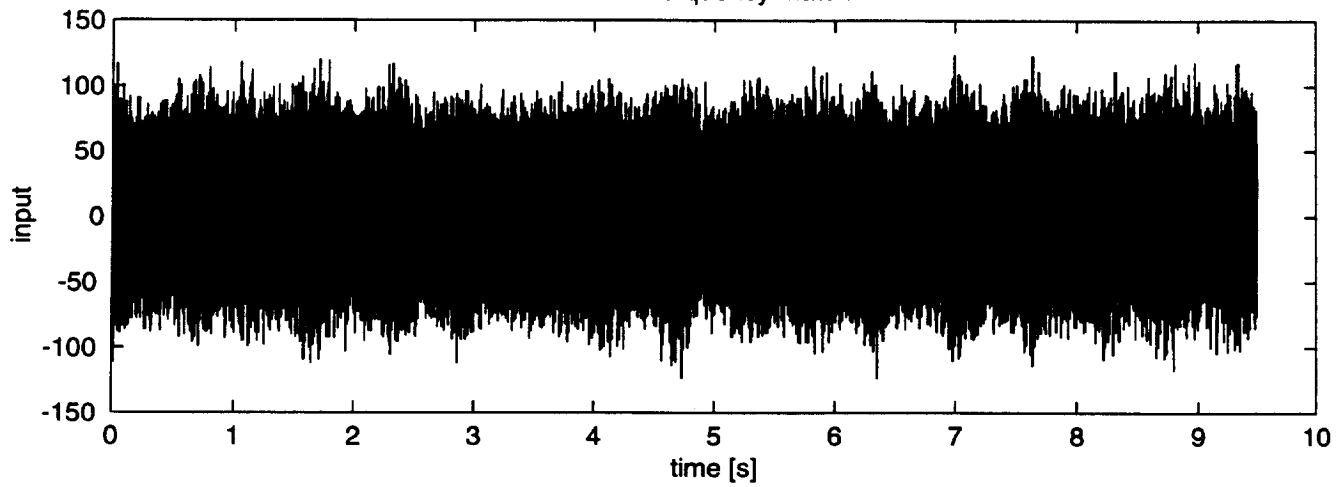


FFT for $IFO_D MRO$

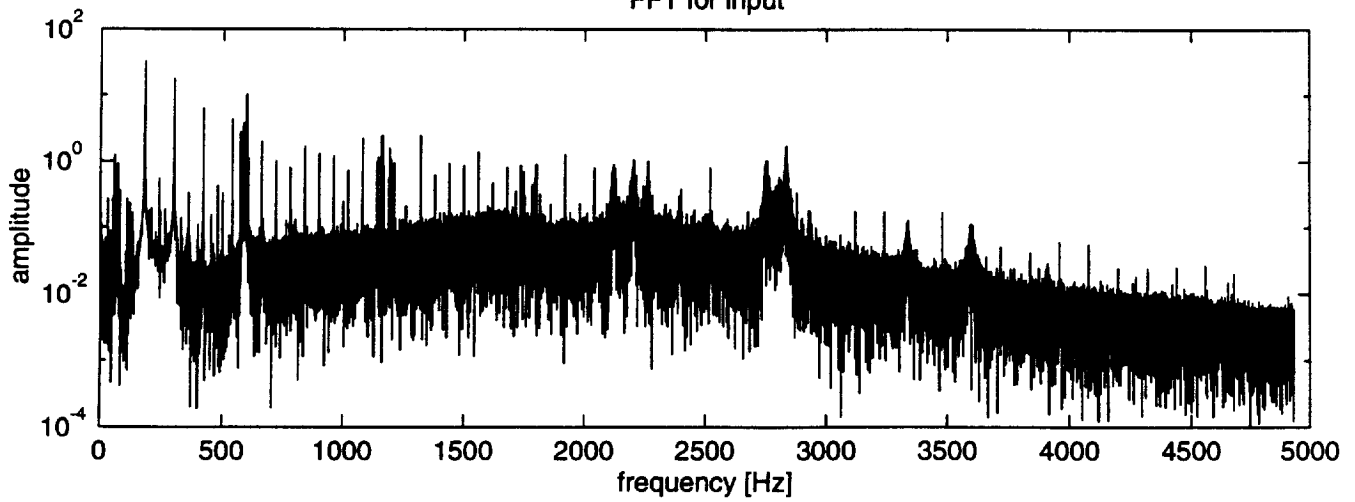


AVOIDING FREQUENCY MISMATCH

exact frequency match

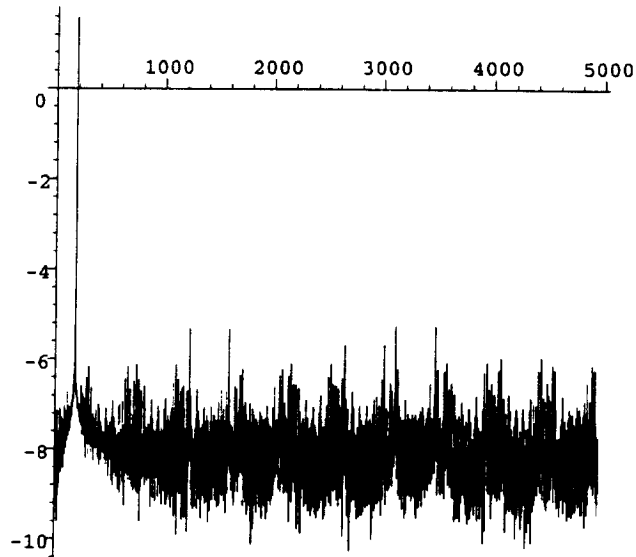


FFT for input

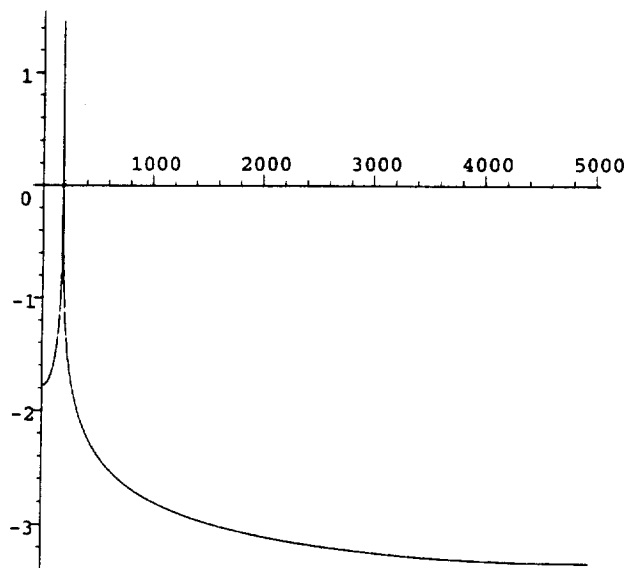


$$sqi := i \rightarrow r2_i^2$$

```
[ > b2:=vector(n1, sqi):  
[ > rr:=evalm((b1+b2)):  
[ > with(plots):  
[ > pointplot([seq([f0[i], .5*log10(rr[i])], i=1..n1/2)], style=line);
```

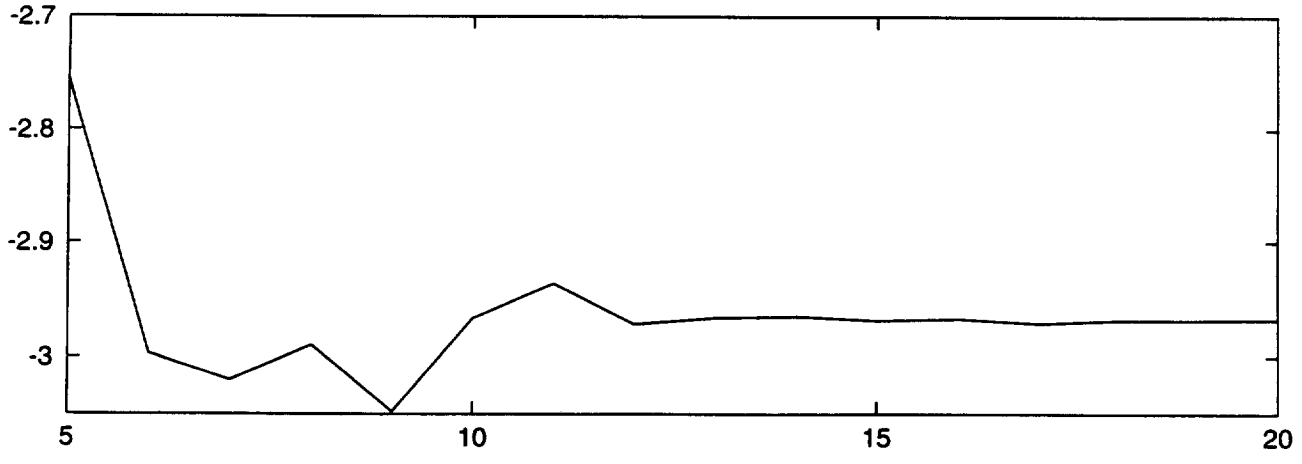
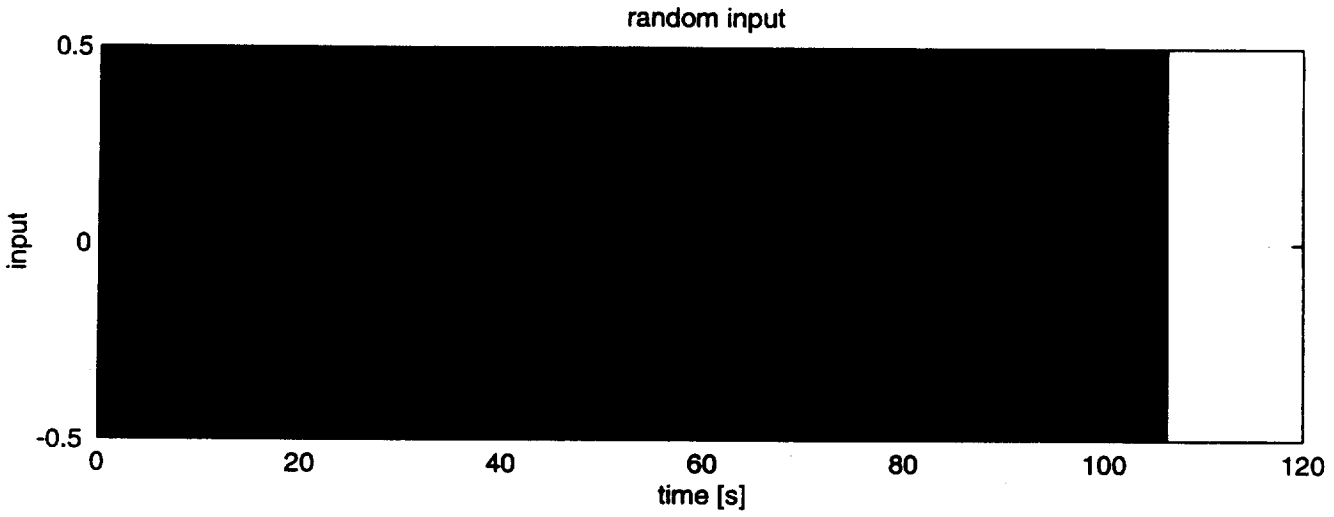


```
[ > sqrt(max(seq(rr[i], i=1..n1))); f1;  
37.17500000  
179.9432855  
[ > pointplot([seq([f0[i], .5*log10(rr[i])], i=1..n1/2)], style=line);
```



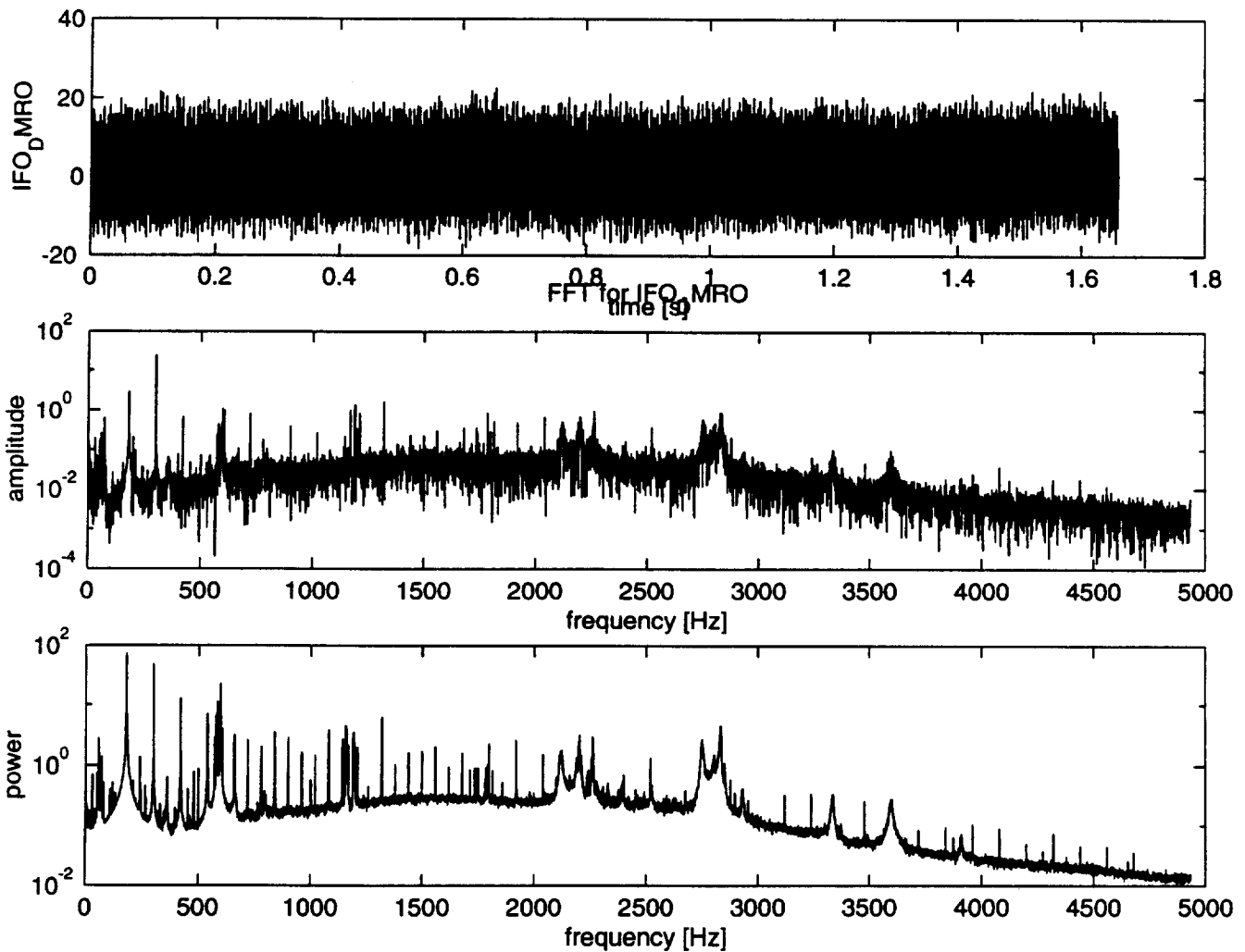
```
[ > sqrt(max(seq(rr[i], i=1..n1))); f1;
```

NOISE SCALING (WITH SAMPLE)

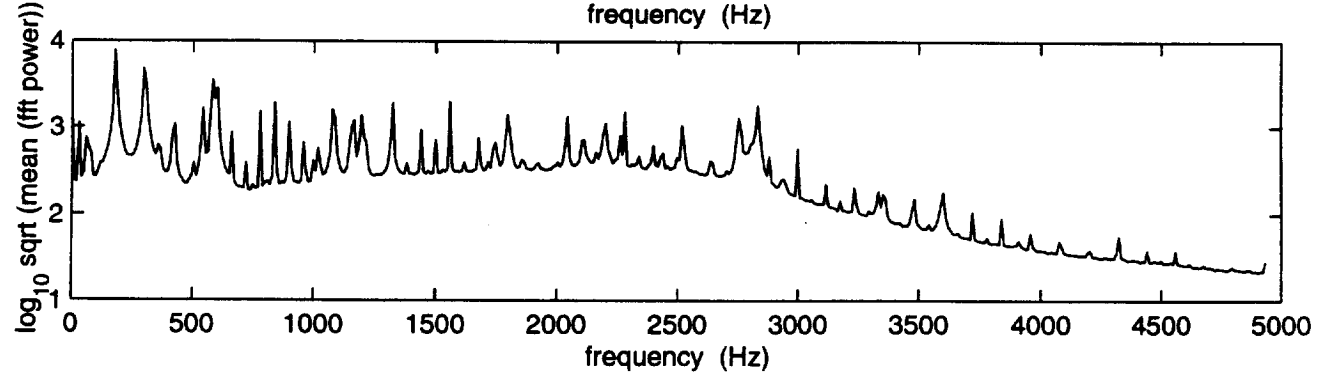
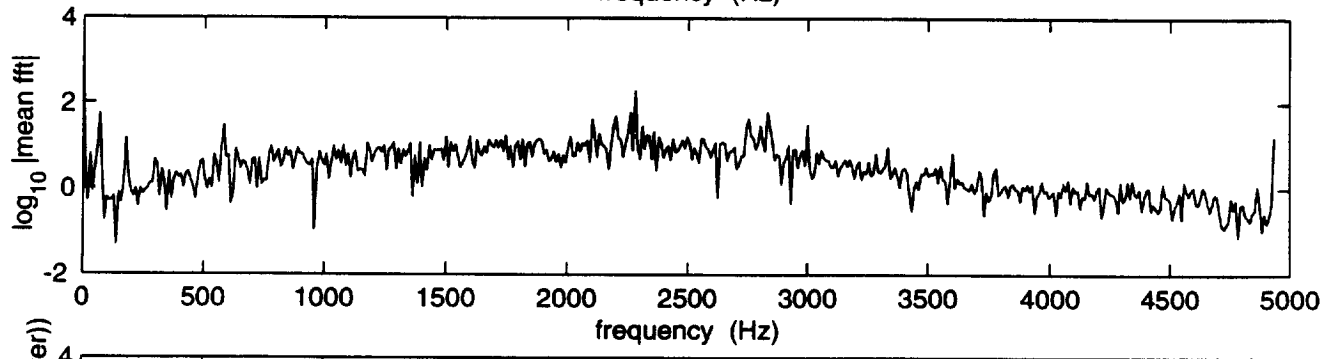
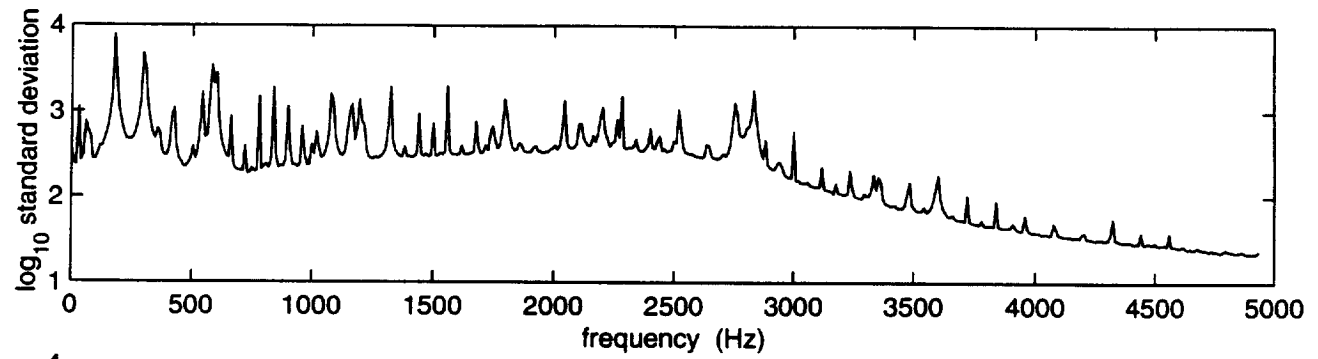


AVERAGING TECHNIQUES

Starting GPS time: Tue Nov 20 05:22:25 1934 (and 881333 usec)



AVERAGING TECHNIQUES



ESTABLISHING CONFIDENCE LIMITS

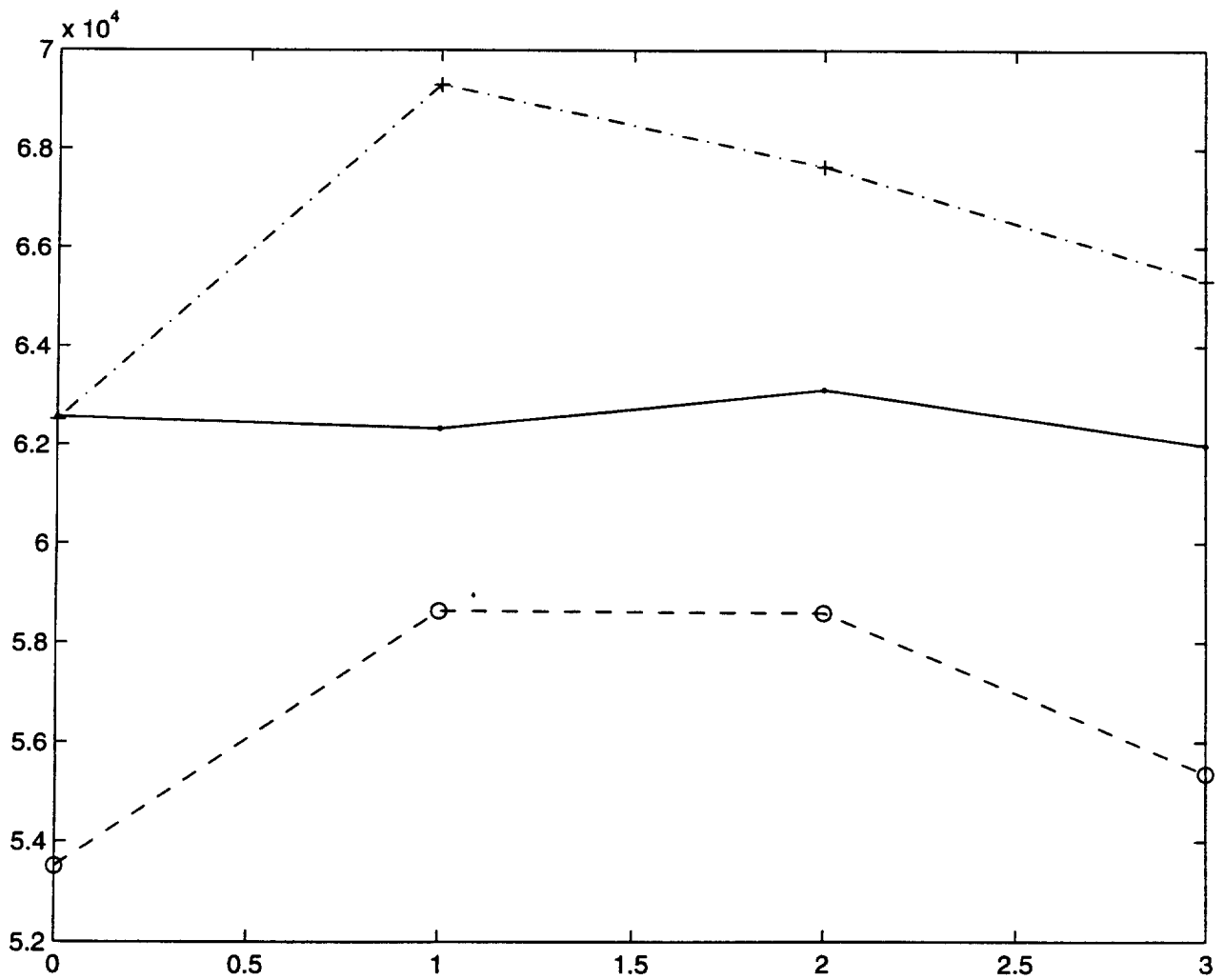
25 Hems good data.

$$25 \times 3600 \times 9868.42 = 888157894.7 \sim \underline{9 \times 10^8 \text{ pts}}$$

14209 samples at 16384 points.

or 8 sets of 105418 samples at 1024 points.

A/D UNIFORMITY (4 BITS)



A to D UNIFORMITY (64 BITS)

