

# **Data Characterization**



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# Focus



- Artifact identification
  - Resolve data set as sum of instrumental artifacts & residual
- Characterization of Artifacts, Residual
  - (non-) Gaussianity
  - (non-) Stationarity
- Goal
  - Automated tools

# Artifact

# Identification



## ■ Kalman Filtering

- Estimate state of dynamical system from noisy observation
- Operates in the time domain

## ■ Components

- State:  $\vec{x}$
- State Dynamics:

$$x[k + 1] = A \cdot x[k] + N[k]$$

- Observation:

$$y[k] = C \cdot x[k] + M[k]$$

# Example: Violin

## Modes



### ■ Observation

- (Bandwidth limited) noisy detector output

### ■ System

- Damped oscillator driven by white noise

### ■ State

- State:  $x$ ,  $dx/dt$

# Analysis Procedure



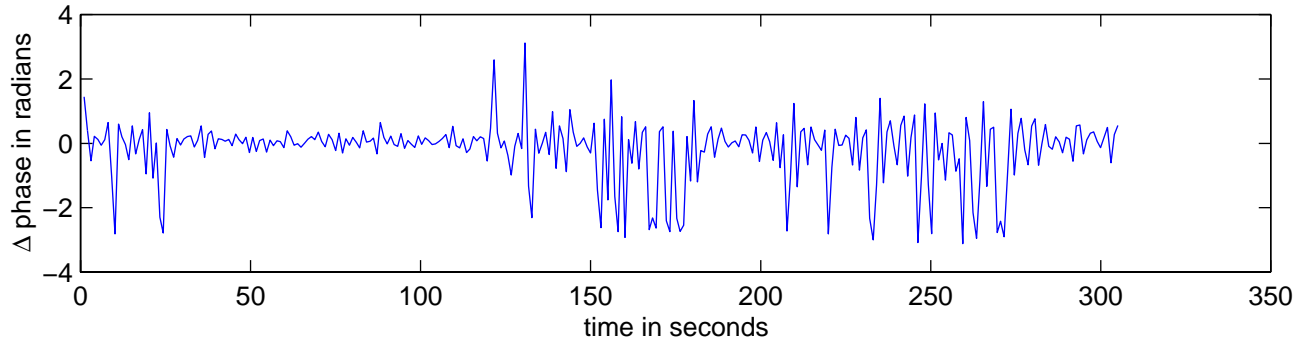
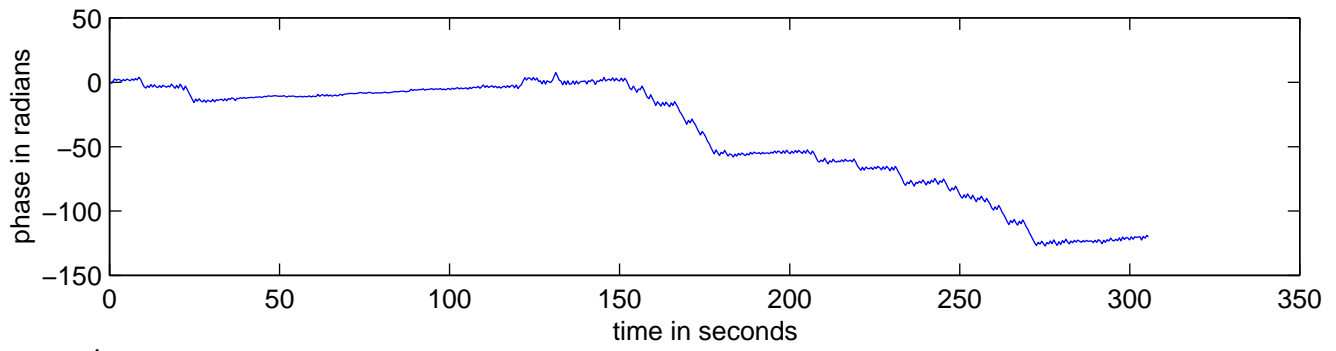
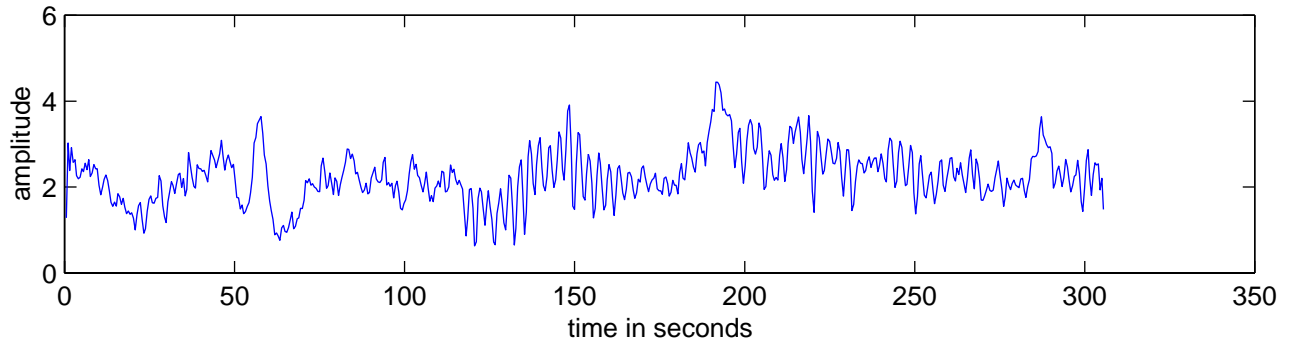
- QAM demodulate line to  $\sim 0$  Hz
- Resample to low bandwidth
  - $\sim 5$  Hz
- Apply filter
  - Estimate line contribution to in-phase, quadrature components
- Resample *estimator* to full bandwidth
- QAM Estimator
- Form residual

# Line Estimator



- Amplitude
  - Modulus  $x+iy$
- Phase
  - Less  $2\pi f_0 t$
- Instantaneous Frequency
  - Less  $f_0$

40m data, Kalman Estimator : 19Nov94.4, Locked001.nc,samples(2000001:5010560),f<sub>s</sub>=9868.421 Hz



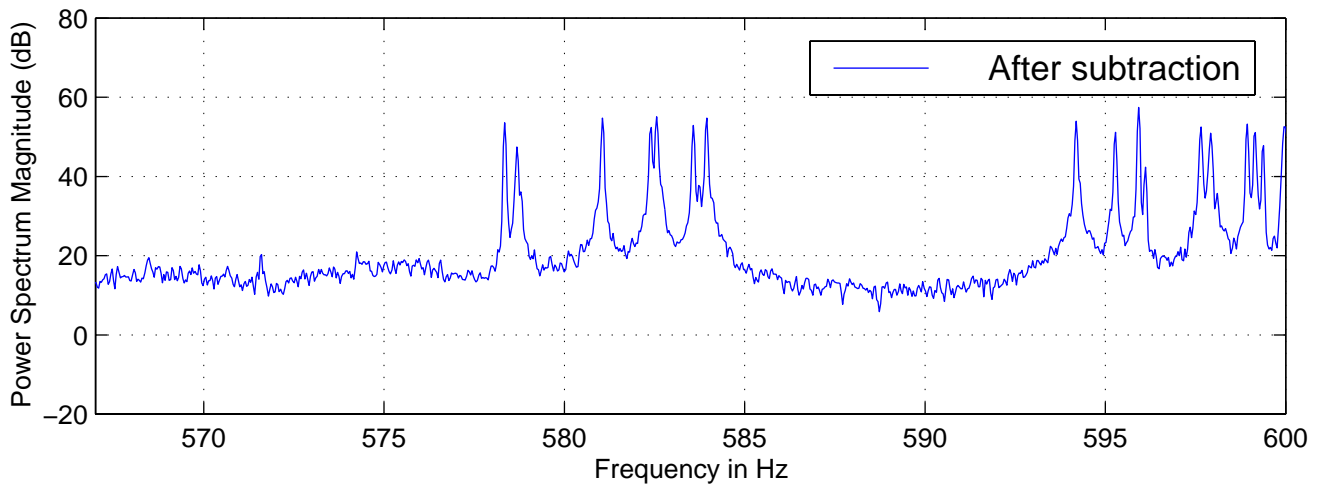
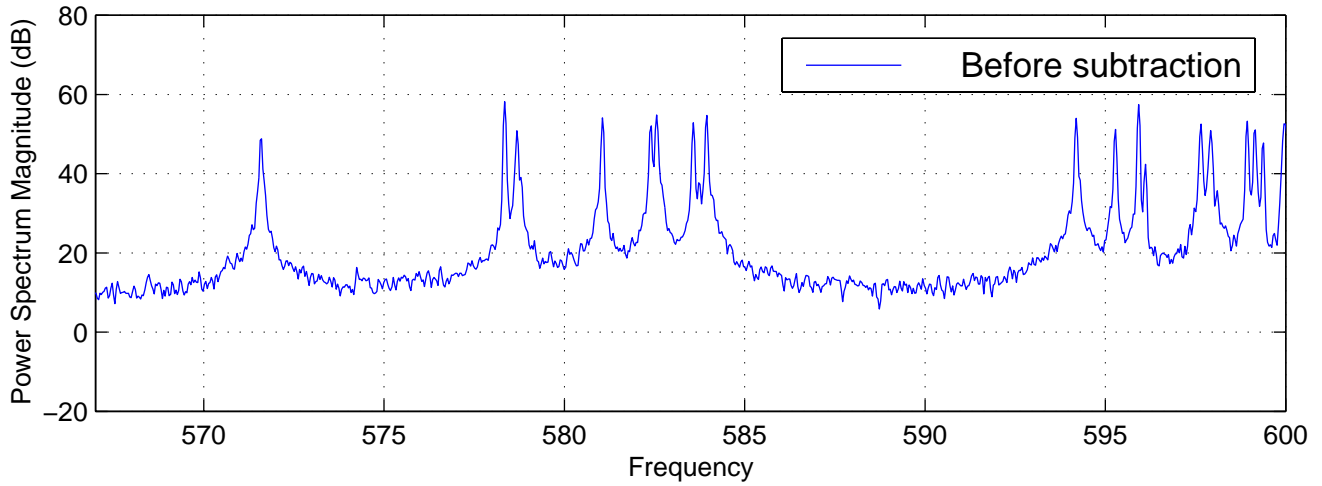
# Residual



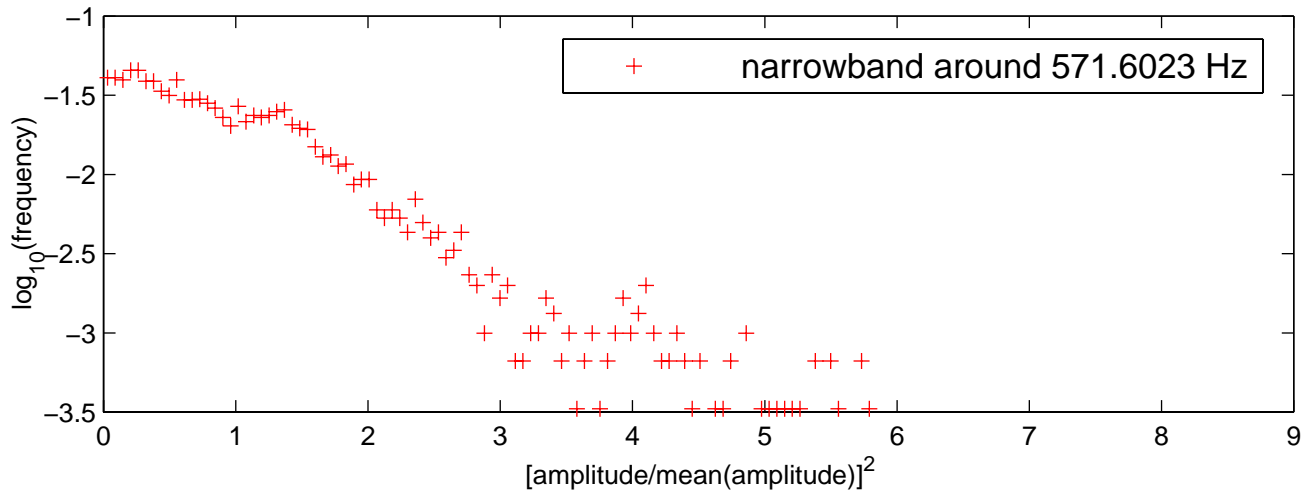
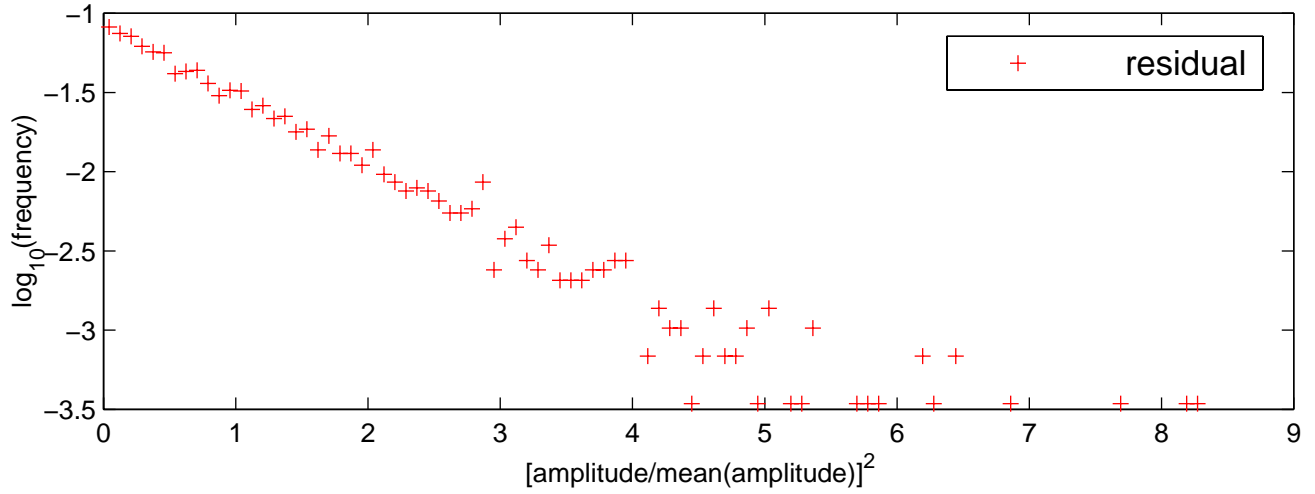
- Spectrum
- Distribution



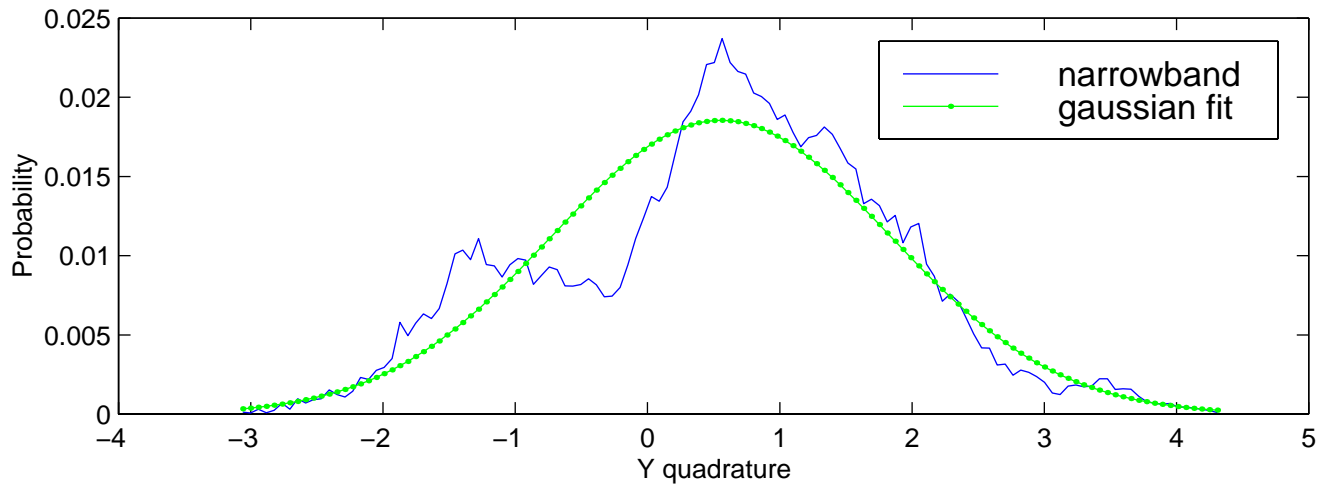
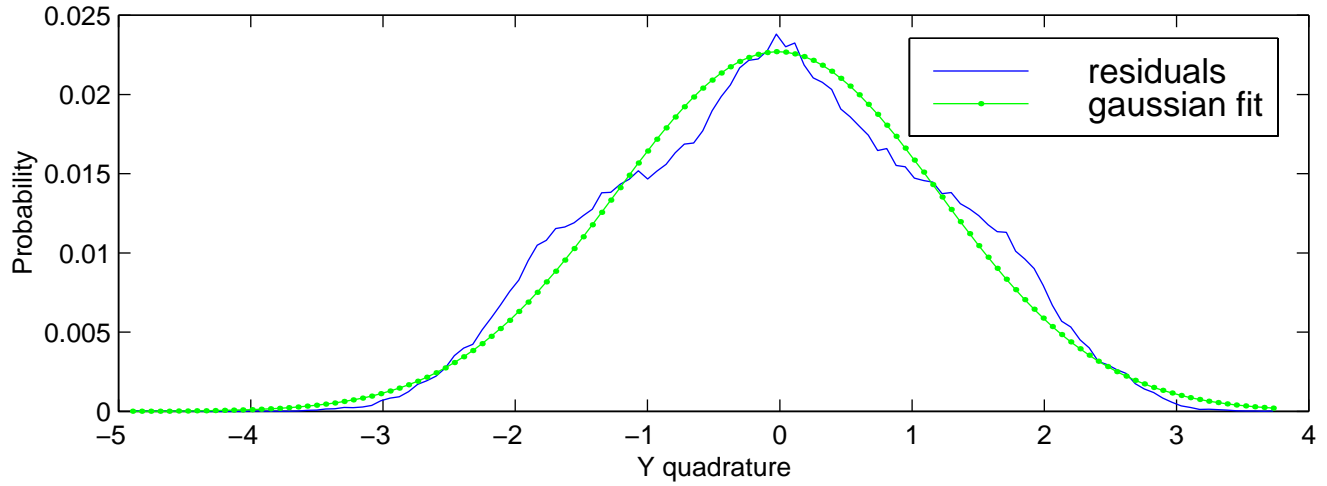
40m data : 19Nov94.4, Locked001.nc,samples(200001:5010560), $f_s=9868.421$  Hz



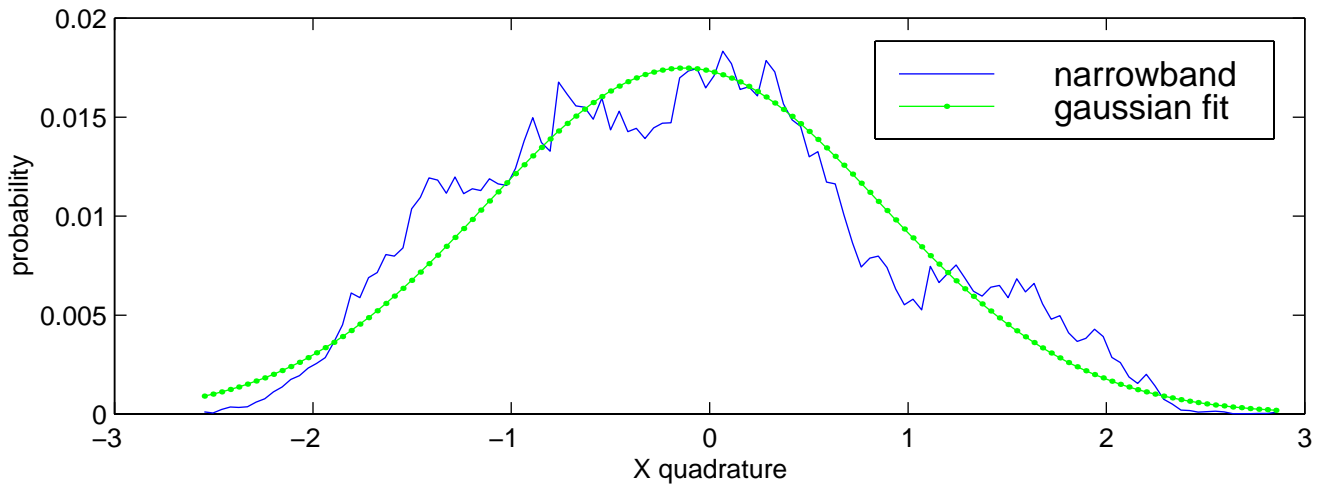
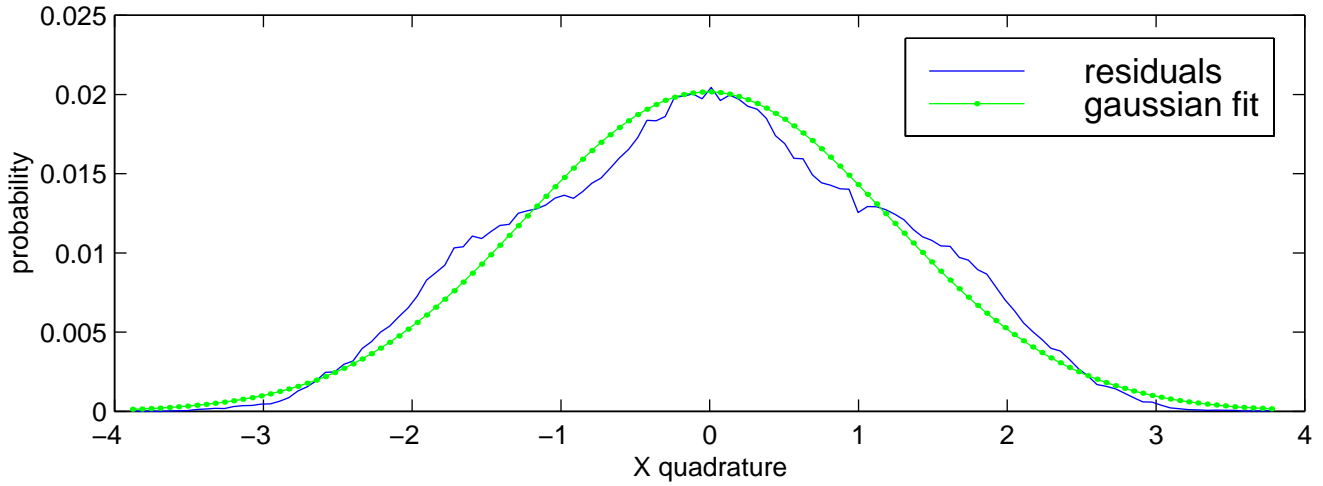
40m data : 19Nov94.4, Locked001.nc,samples(2000001:3000001), $f_s=9868.421$  Hz



40m data : 19Nov94.4, Locked001.nc,samples(2000001:5010560), $f_s=9868.421$  Hz



40m data : 19Nov94.4, Locked001.nc,samples(2000001:5010560), $f_s=9868.421$  Hz



# Time-frequency characterization

## ■ Rayleigh Statistics

$$P(x) = e^{-x}, \quad \bar{x} = 1, \quad \sigma = 1$$

## ■ Evaluate $r(f) = \overline{\sigma(f)} / \overline{x(f)}$

- If larger than unity, distribution is too broad

  - | E.g., excess noise

- If smaller than unity, distribution is too peaked

  - | E.g., sinusoid

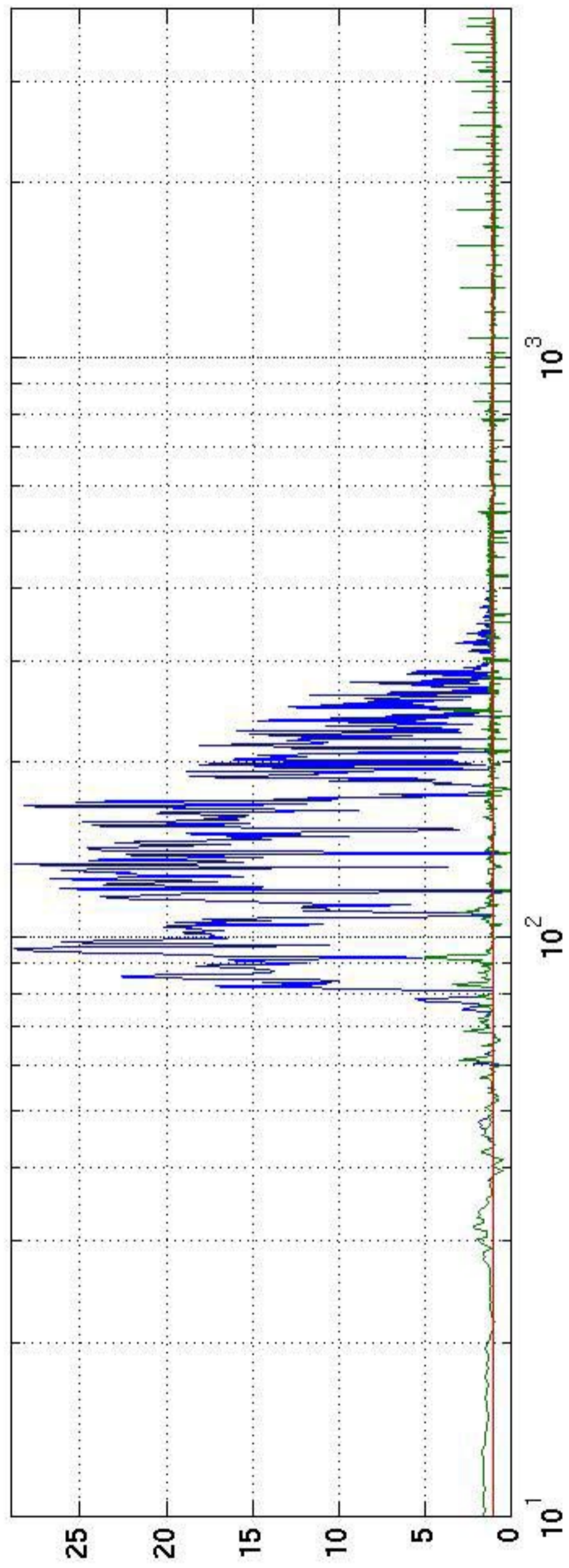
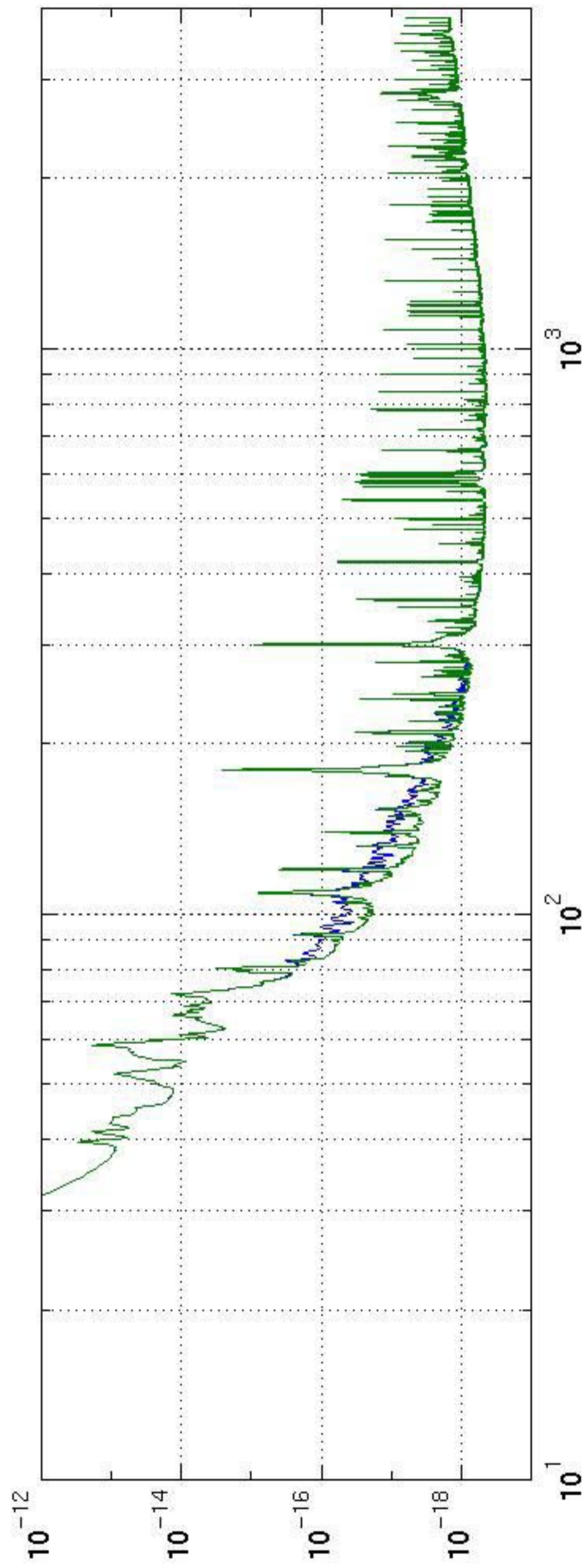
## ■ Focus on $r(f/t)$

- Short-time Fourier Transforms

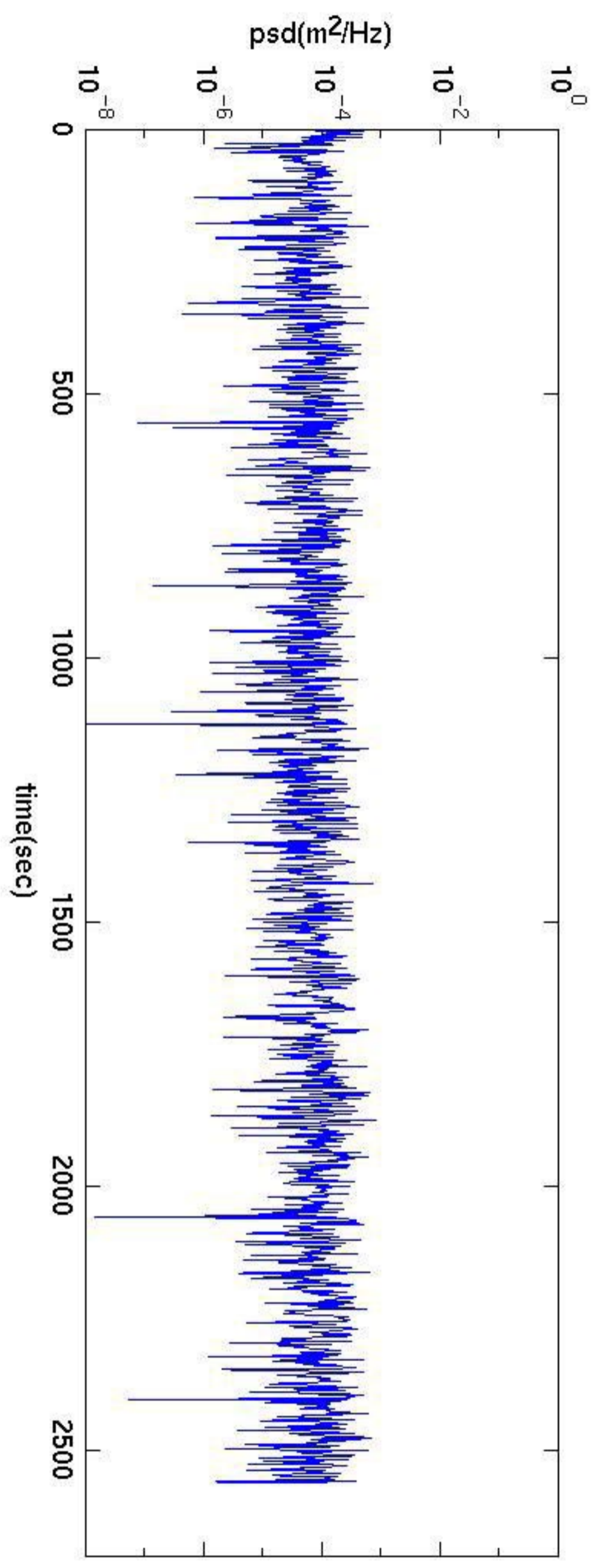
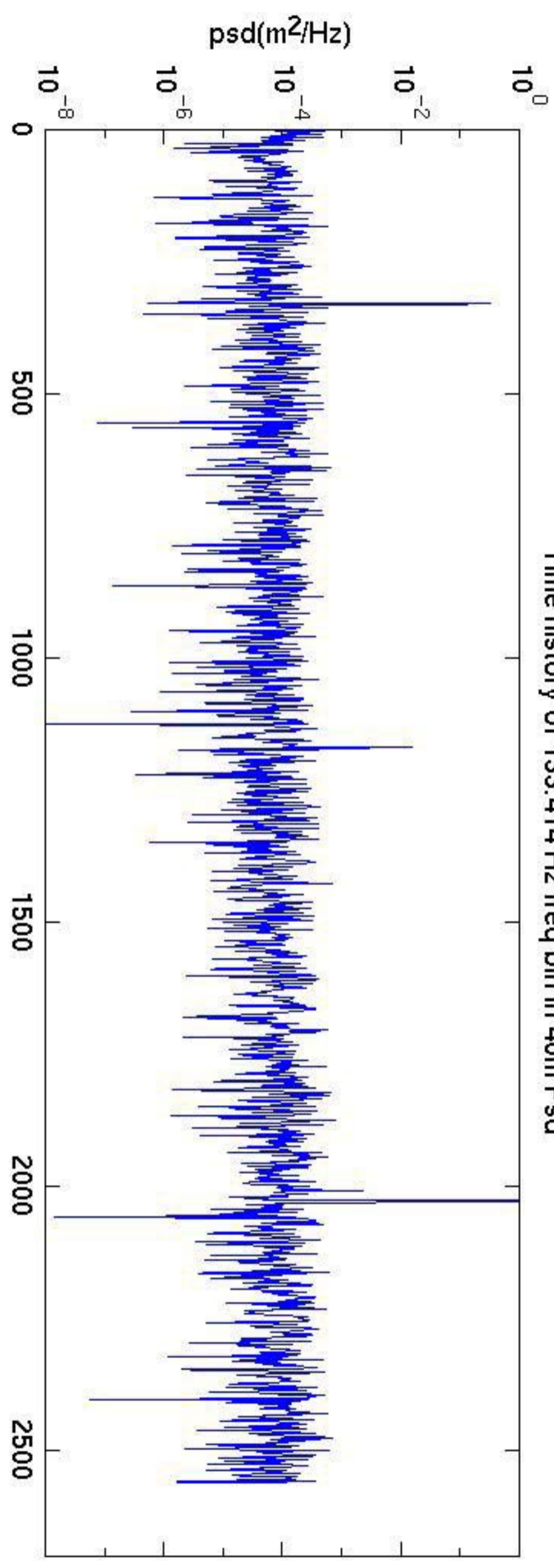
# Time-frequency characterization



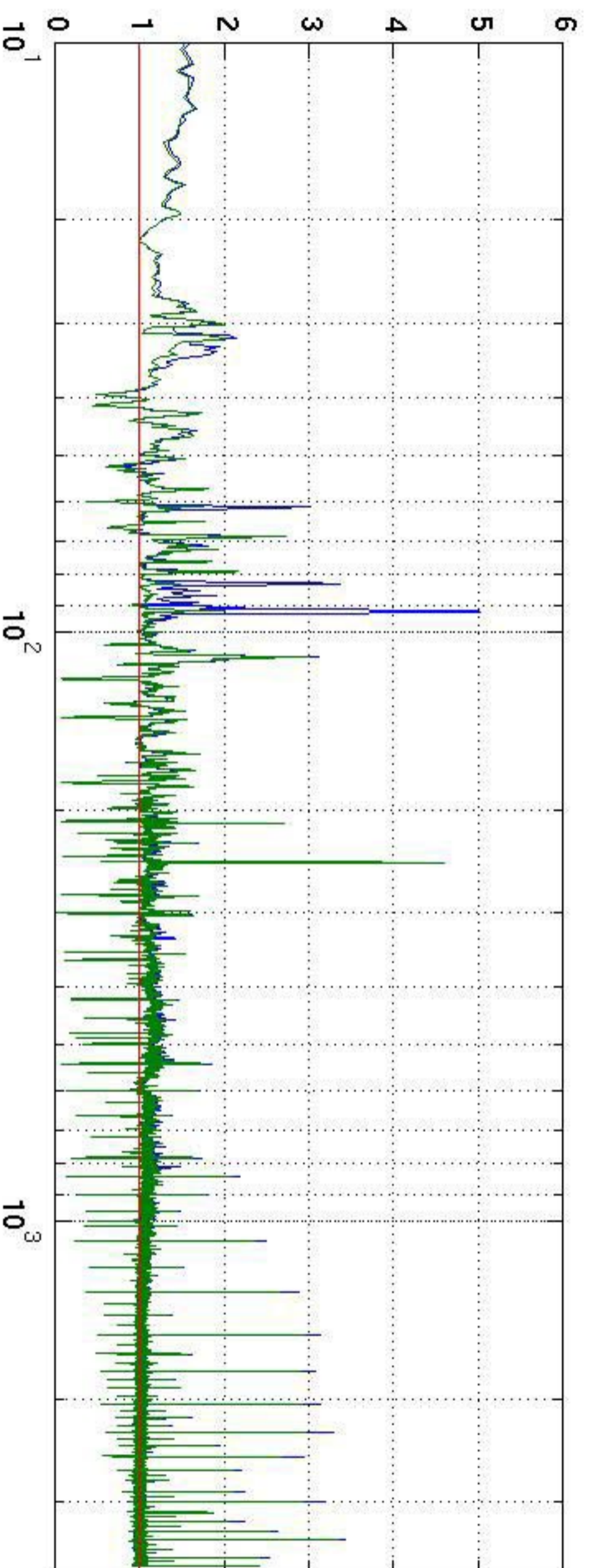
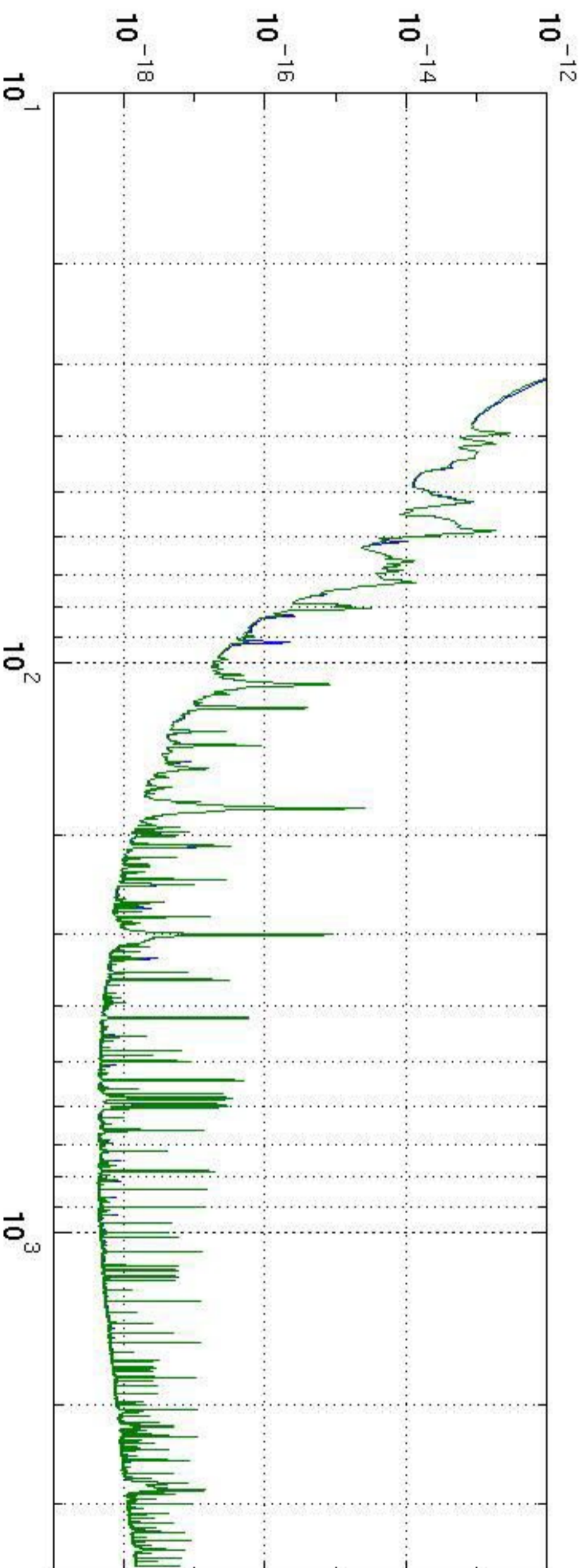
- Pick frequency with greatest excess noise
  - Time history shows non-stationarity
  - Identify statistically significant excursions and mark as “bad”
  - Re-compute statistics without “bad” data segments



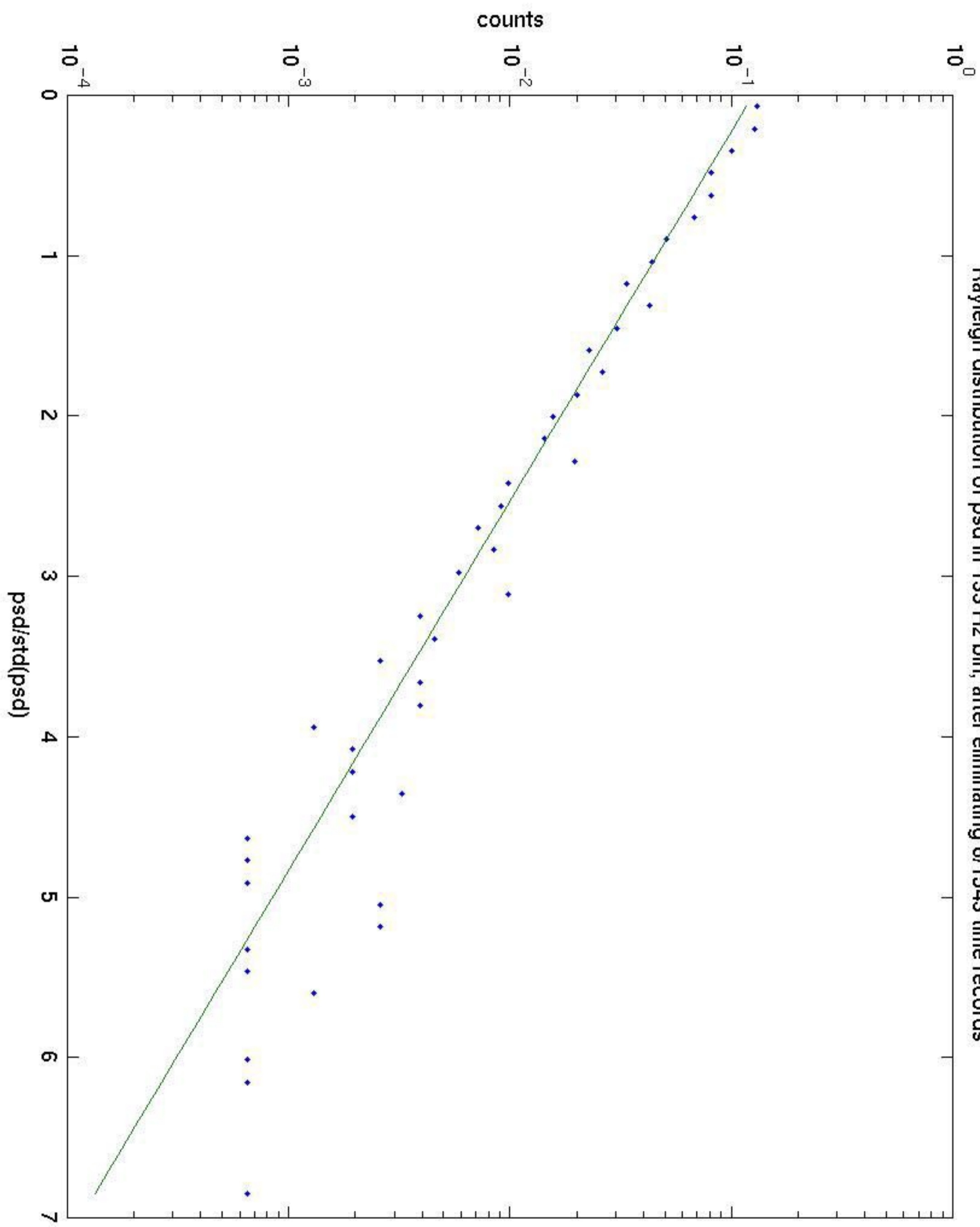
Time history of 133.414 Hz freq bin in 40m Psd







Rayleigh distribution of psd in 133 Hz bin, after eliminating 6/1543 time records



# Lessons Learned



- Instrumental artifacts can be identified
  - Resolve data into known artifacts and residuals
  - Artifacts tend to be poorly-behaved, residuals well-behaved
- Bad instrument” behavior is confined to short stretches
  - Which can be identified through character in narrow band
- Search for gravitational-waves in residual

# On-going work



- Automated tools
  - Kalman filter
  - Data quality “bit”
- Resolve data stream
  - Artifacts & residual
- System modeling
  - Better characterizations of Gaussianity, Stationarity
- Addendum
  - Locked segments of Nov’94  
locked segments available as netCDF files

*Note 1, LIGO, 03/18/99 08:45:23 AM*  
LIGO-G990022-28-M