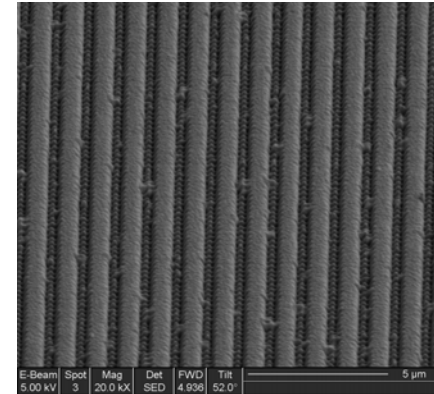
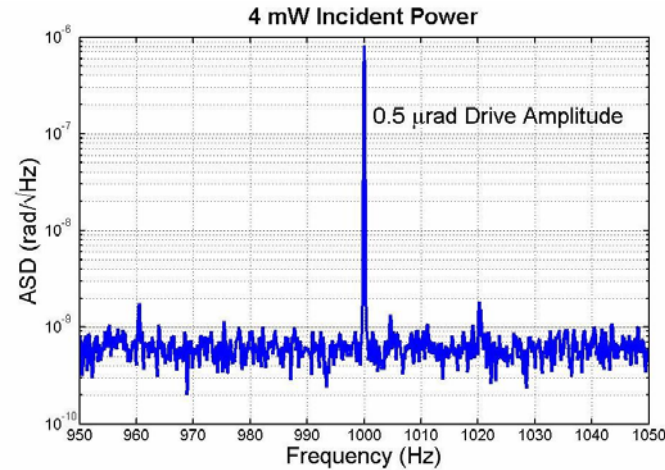


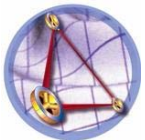


A Symmetric, Robust Grating Angular Sensor for LIGO Sensing and Control



Ke-Xun Sun, Patrick Lu, and Robert Byer
Stanford University

LIGO Science Collaboration (LSC) Meeting
Louisiana State University
August 16, 2006



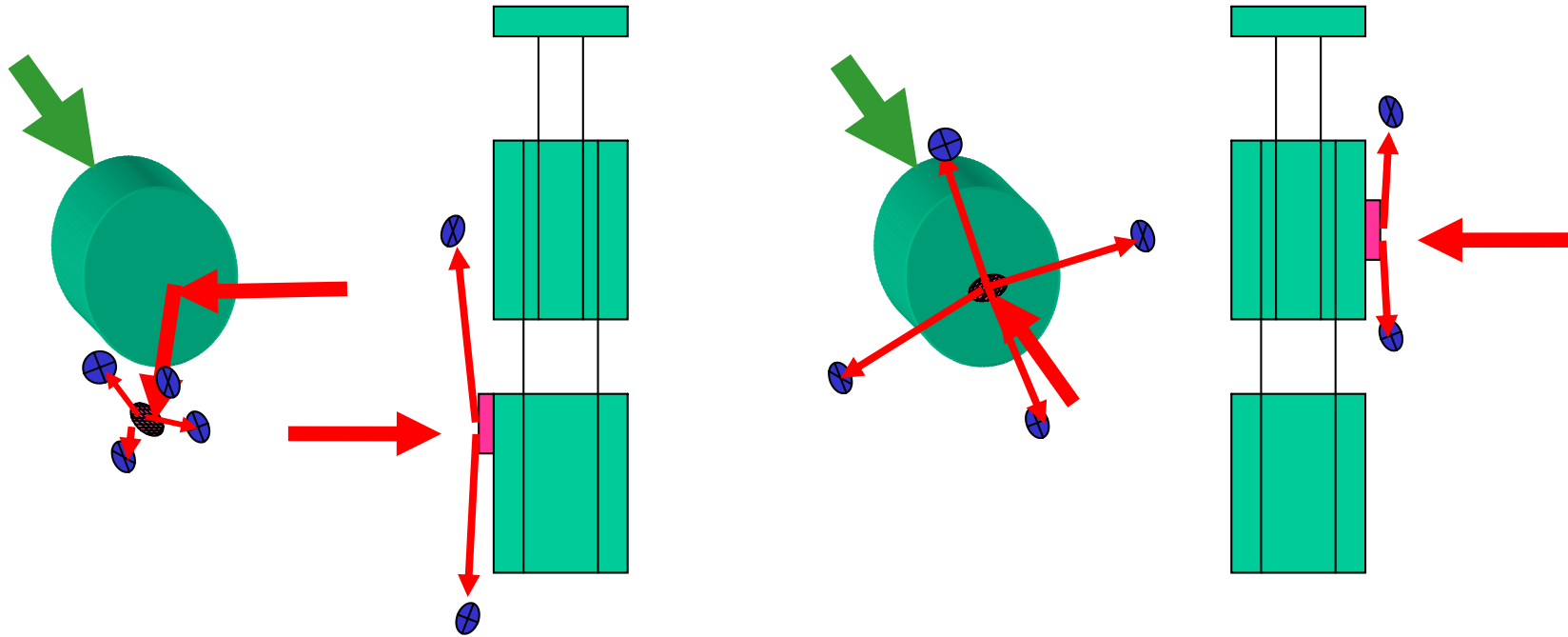
LSC Meeting August , 2006
Louisiana State University

LIGO_LSC_Sun_Grating_060816.ppt, K. Sun

1



Possible LIGO Installations Options

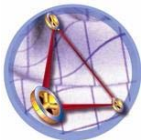


Tilted
Illumination

Main test mass

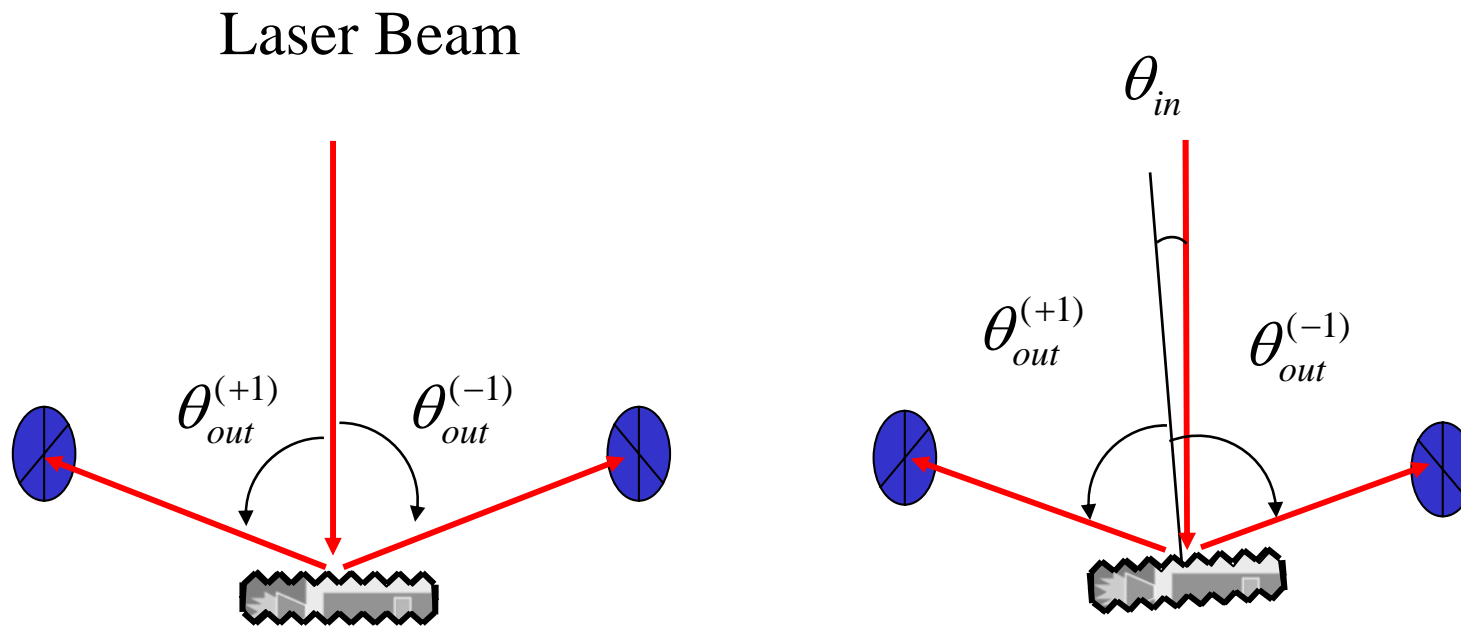
Back of the high
reflectors

Intermediate test mass
Or suspension point
interferometer

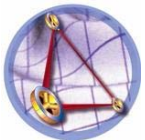


Grating Based Angular Sensor

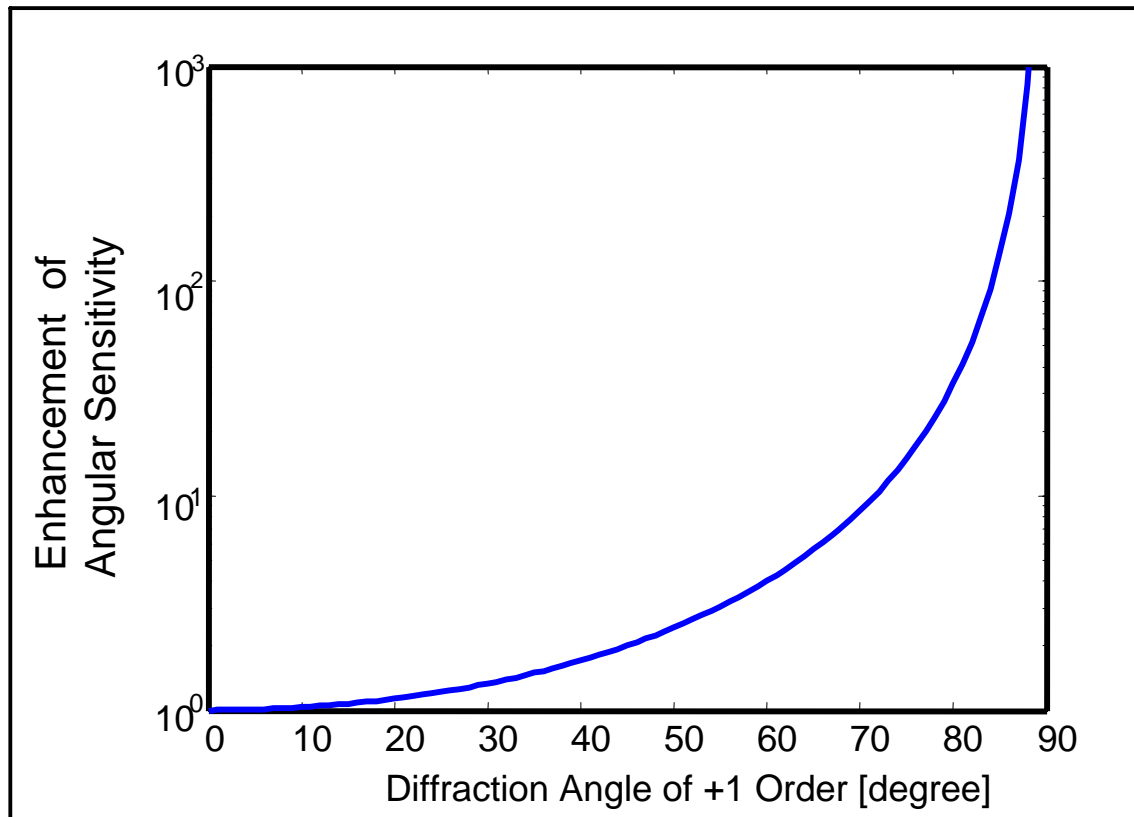
Sensitive to Differential Movement of the Diffracted Beams



$$d(\sin \theta_m - \sin \theta_{in}) = m\lambda$$



Overall Enhancement of Angular Sensitivity



- Grating angle amplification

- Beam cross section compression

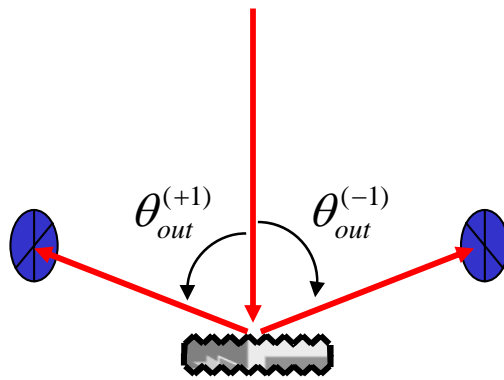
$$P_m = K \left(\frac{\cos(\theta_{in})}{\cos(\theta_m)} \right)^2 P_{in}$$

K. Sun, S. Buchman, and R. L. Byer, "Grating Angle Magnification Enhanced Angular and Integrated Sensors for LISA Applications," accepted for publication at J. Phys. C. Special issue of Almadi 6 Conference on Gravitational Waves

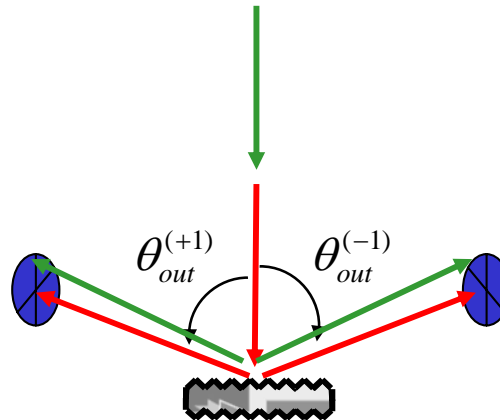


Robustness of the Symmetric Grating Angular Sensor

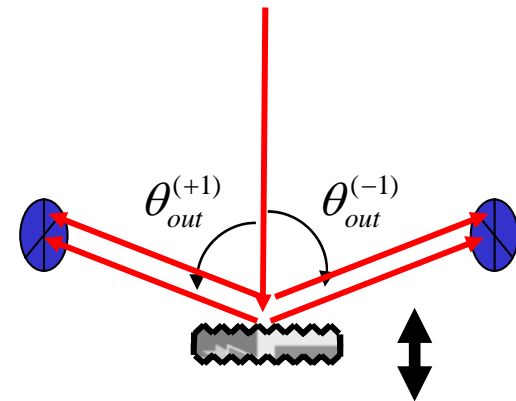
Laser Beam



Laser Frequency Variation $\Delta\nu$



Pure Rotational Measurement

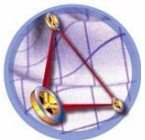


$$d(\sin \theta_m - \sin \theta_{in}) = m\lambda = mc/\nu$$

$$\Delta\theta_m = \left(\frac{Nm\lambda^2}{c} \right) \frac{\Delta\nu}{\cos \theta_m}$$

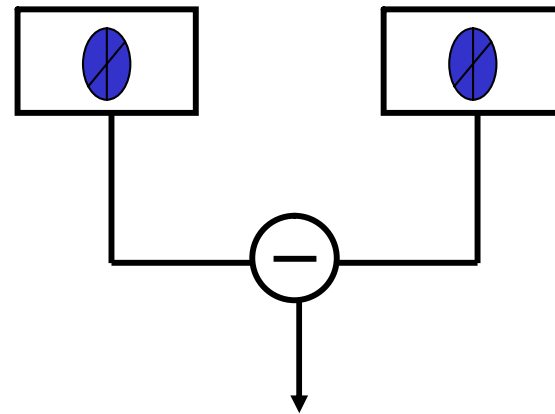
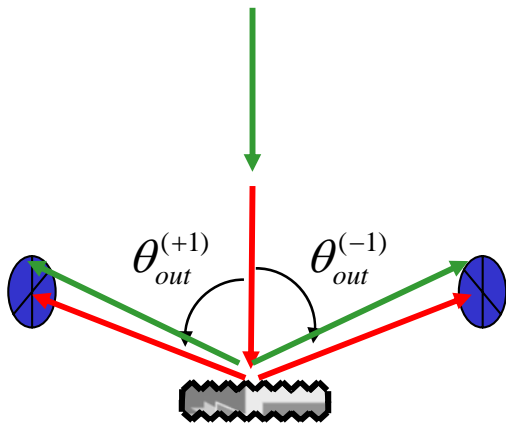
Grating Displacement

$\Delta\nu$ induced angular movement also magnified by grating



Common Mode Rejection to Reduce the Laser Frequency Noise Effect (Angular Signal Doubled)

Laser Frequency Variation $\Delta\nu$



$$(\Delta\theta_{+1} - \Delta\theta_{-1}) = \text{CMRR} \times (\Delta\theta_{\pm 1})$$

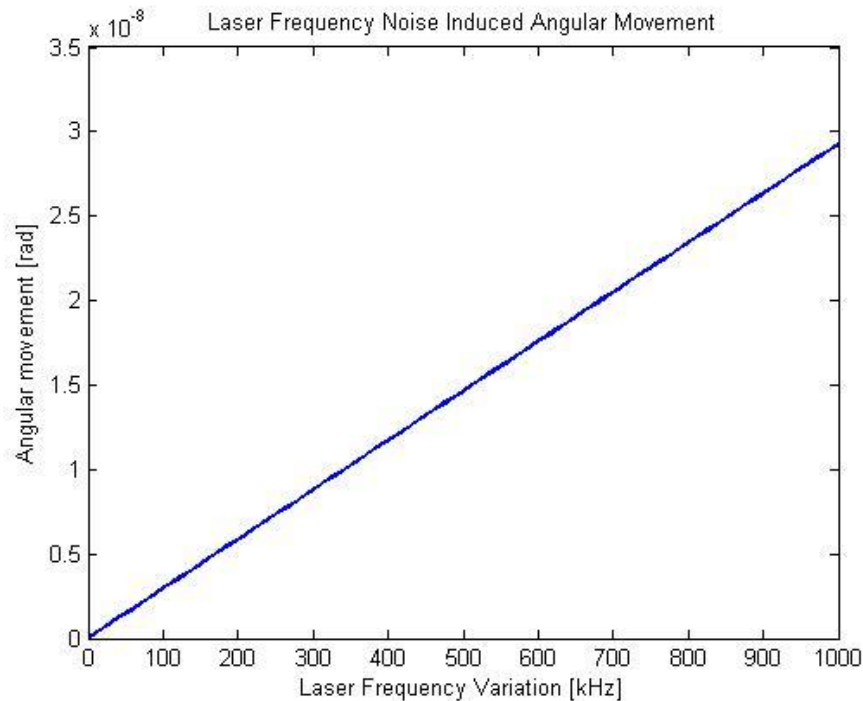
$$I(\Delta\theta_{+1} - \Delta\theta_{-1}) = \text{CMRR} \times I(\Delta\theta_{\pm 1})$$

Common mode rejection also works for



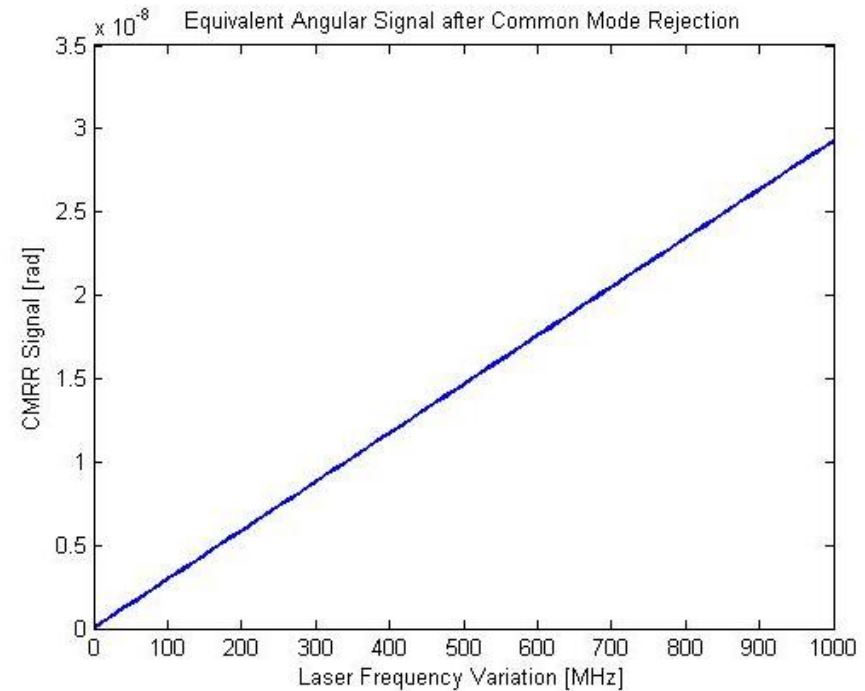
CMRR Loosens Laser Frequency Stability Requirements

Example given: CMRR $\sim 10^3$



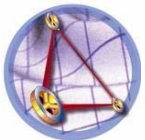
[kHz]

Laser Frequency Requirement:
3 ~ 300 kHz

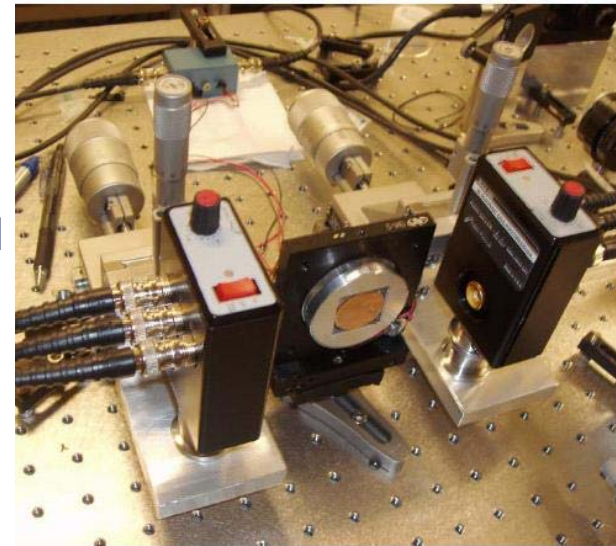
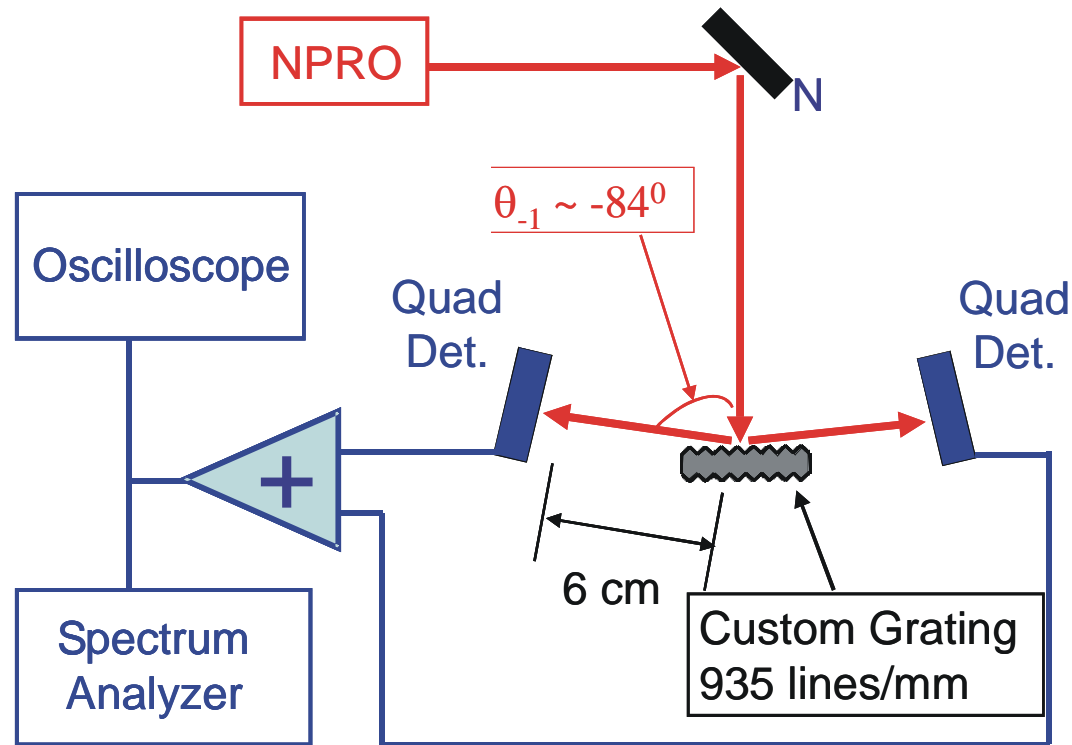


[MHz]

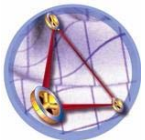
Laser Frequency Requirement:
3 ~ 300 MHz



Symmetric Grating Angular Sensor Experiment

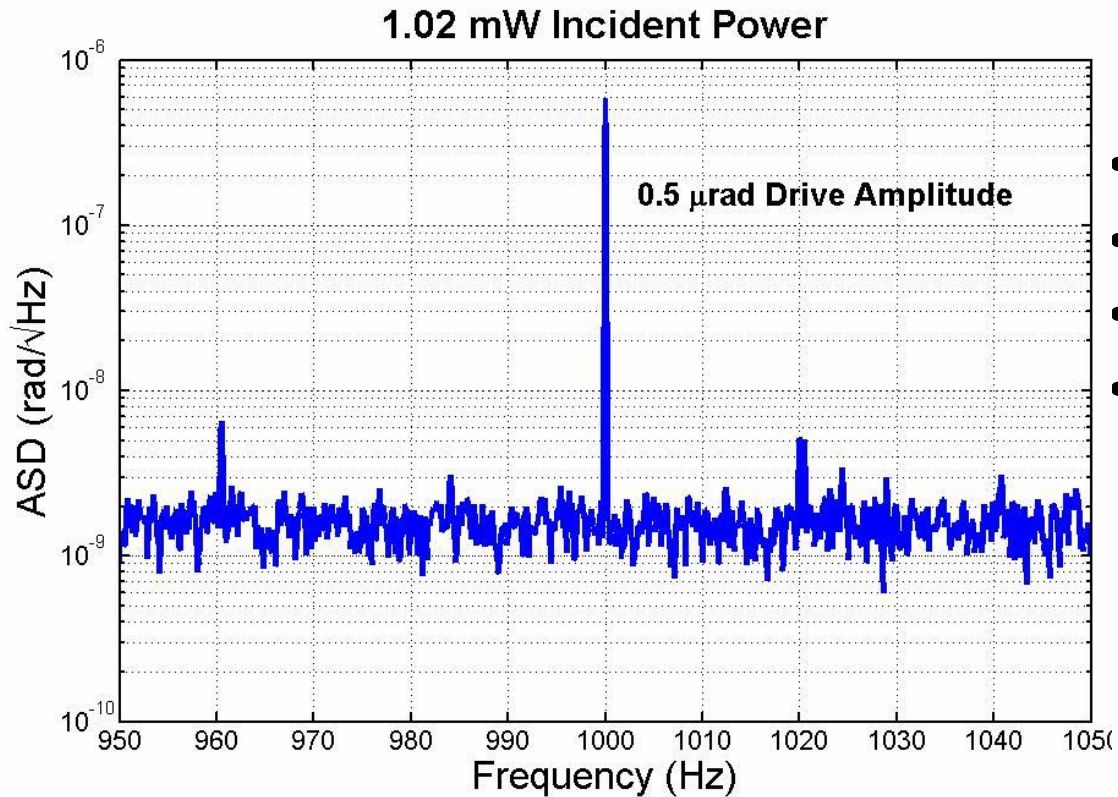


Ke-Xun Sun, Patrick Lu, and Robert L. Byer, "A robust, symmetric grating angular sensor", LISA 6th Symposium, 19-23 June 2006, Goddard Space Flight Center, Greenbelt, MD



Signal Spectrum for 1 mW Incident Power

Noise floor lower than $2 \text{ nrad/Hz}^{1/2}$



- PZT displacement 10 nm
- Grating rotation 0.5 μrad
- SNR ~ 50 dB
- Noise floor level $\sim 2 \text{ nrad}/\sqrt{\text{Hz}^{1/2}}$

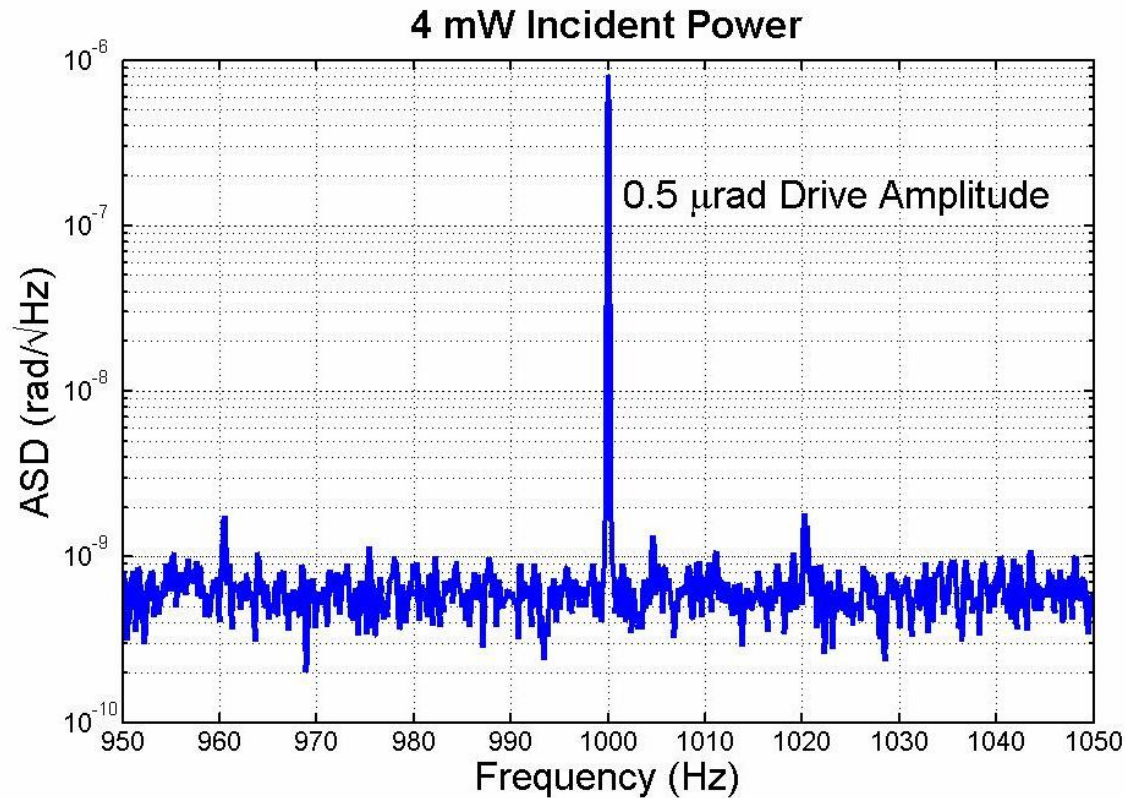




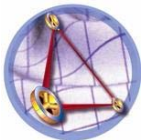
Signal Spectrum for 4 mW Incident Power Signal



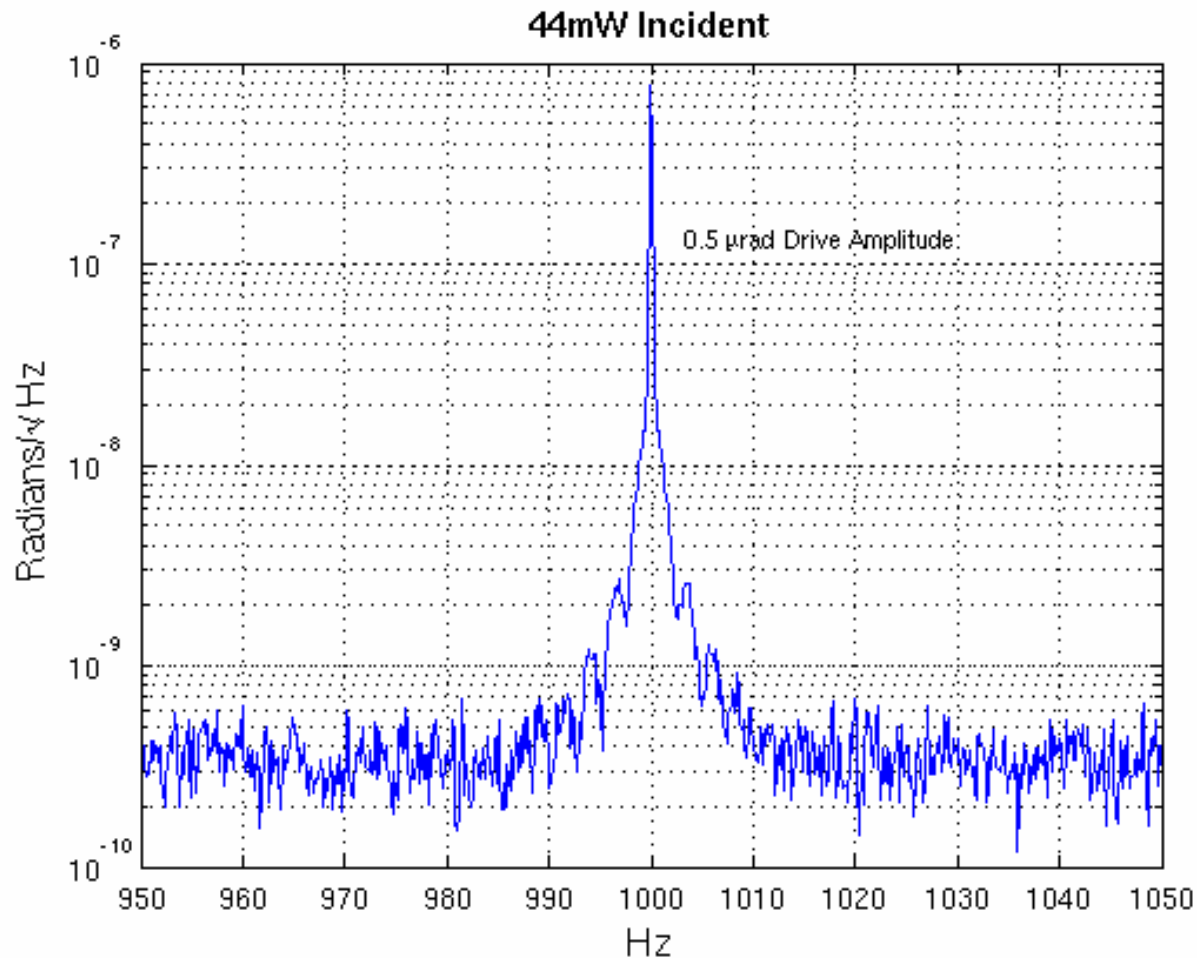
Noise floor lower than $1 \text{ nrad/Hz}^{1/2}$



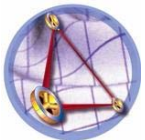
- PZT displacement 10 nm
- Grating rotation 0.5 μrad
- 4 mW input power
- Noise floor level $\sim 1 \text{ nrad}/\sqrt{\text{Hz}}$
- Potential applications:
 - Telescope orientation
 - Fiber collimator orientation
 - Coarse Frequency stabilization



Signal Spectrum for 44 mW Incident Power

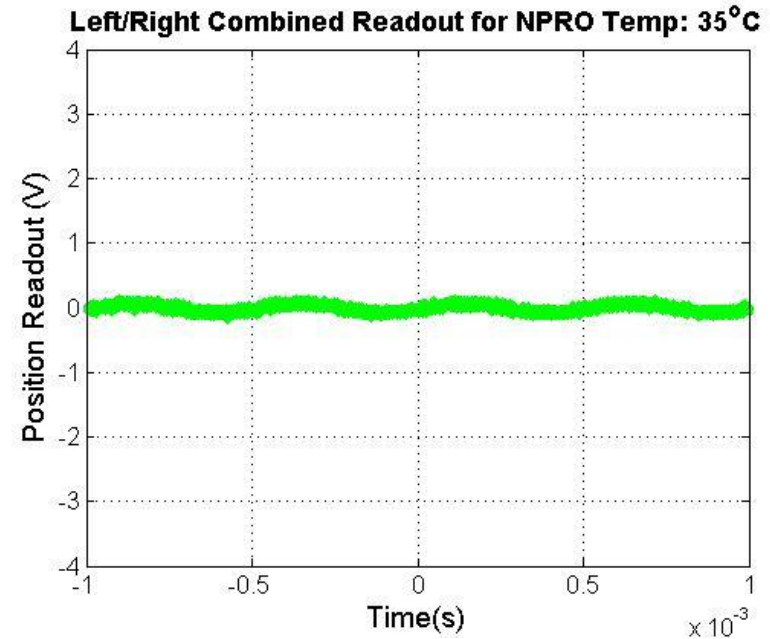
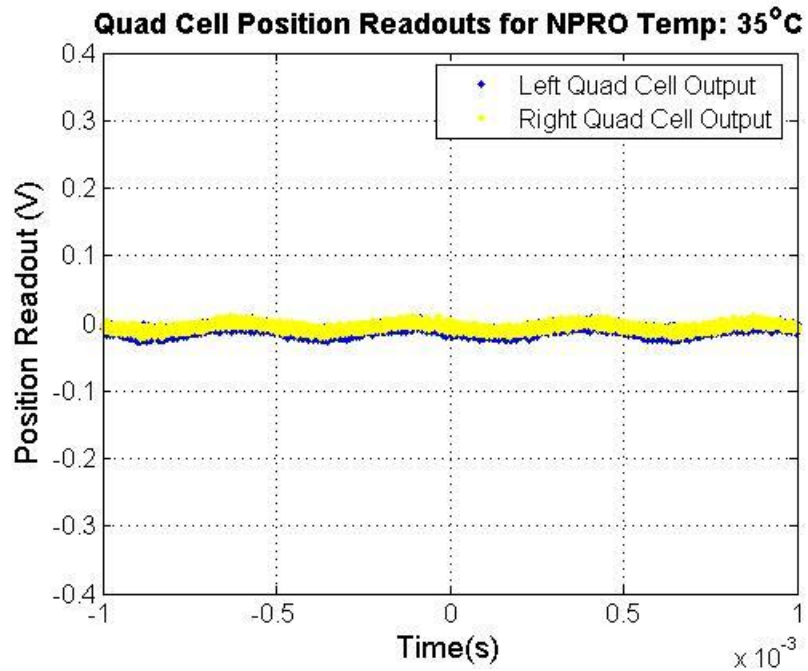


- PZT displacement 10 nm
- Grating rotation 0.5 μrad
- 4 mW input power
- Noise floor level ~ 0.3 nrad/ $\sqrt{\text{Hz}^{1/2}}$





Robustness Against Laser Frequency Variations

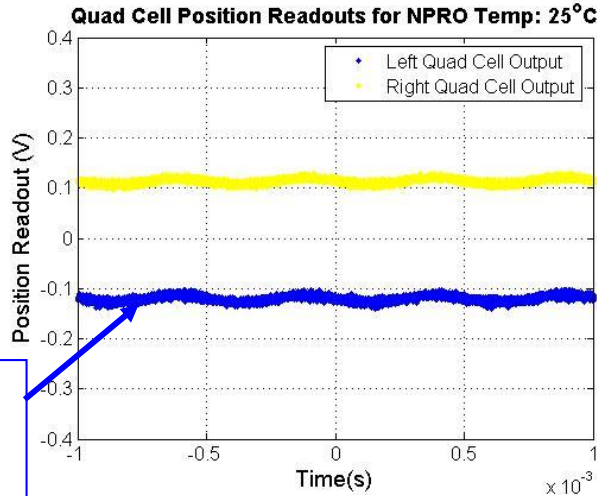


NPRO laser head temperature: 35°C

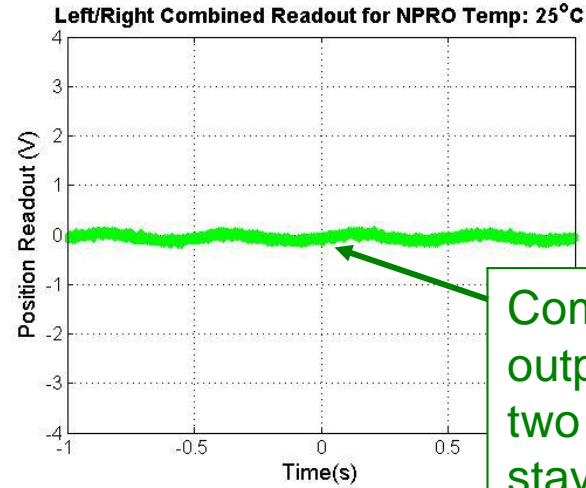


Symmetry Enabled Robustness Against Laser Frequency Variations

Laser Freq.
@ $T_{\text{head}}=25^{\circ}\text{C}$

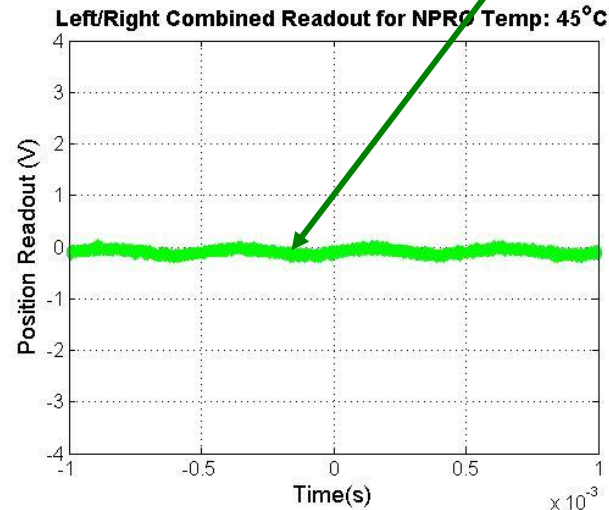
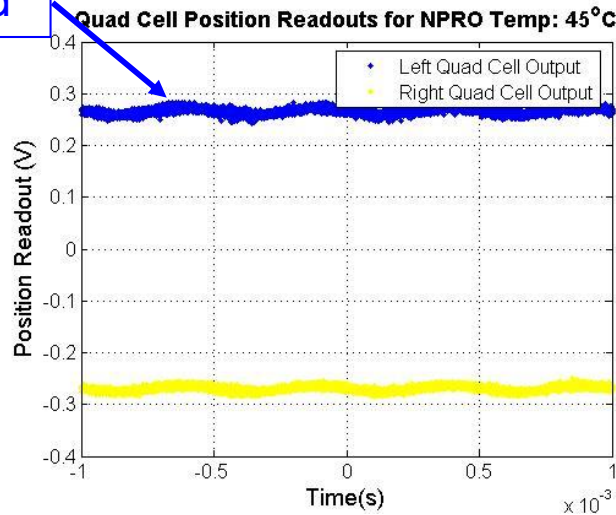


Single quad
detector
output moved



Combined
output from
two detectors
stay constant

Laser Freq.
@ $T_{\text{head}}=45^{\circ}\text{C}$



NPRO laser head temperature: 25°C & 45°C

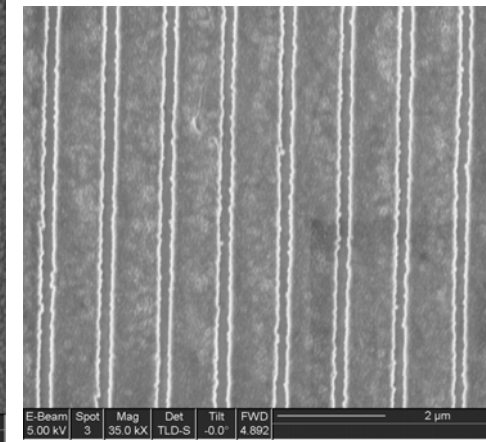
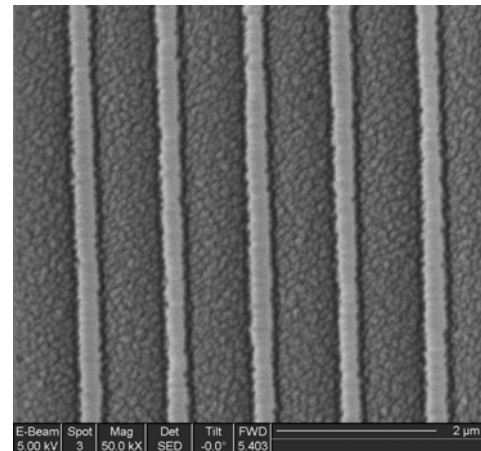
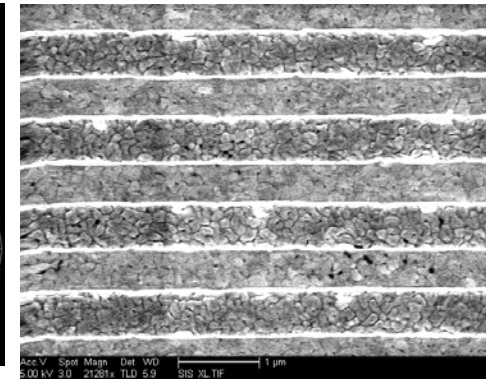
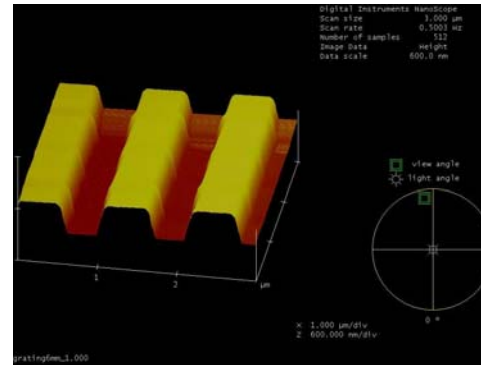
LSC Meeting August, 2006
Louisiana State University

LIGO_LSC_Sun_Grating_060816.ppt, K. Sun

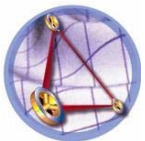


Improvements of Grating Quality

- Transfer-imprinting of gold gratings
 - This is performed by pressing a dielectric grating into a gold surface with force sufficient to exceed the yield stress of gold
 - Centimeter-sized dielectric gratings were fabricated with e-beam lithography on quartz wafers.
 - Gold gratings had 933 lines/mm and 300nm of depth.
 - Various duty cycles have been demonstrated.
 - 275nm depth 50% duty cycle gold gratings have been measured to have 26% diffraction efficiency in the +/-1 orders and 36% efficiency in the 0th order.



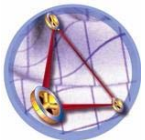
Patrick Lu, Ke-Xun Sun, and Robert L. Byer, “Methods of Fabricating Grating Patterns on Dielectric and Metal Surfaces”, LISA 6th Symposium, 19-23 June 2006, Goddard Space Flight Center, Greenbelt, MD



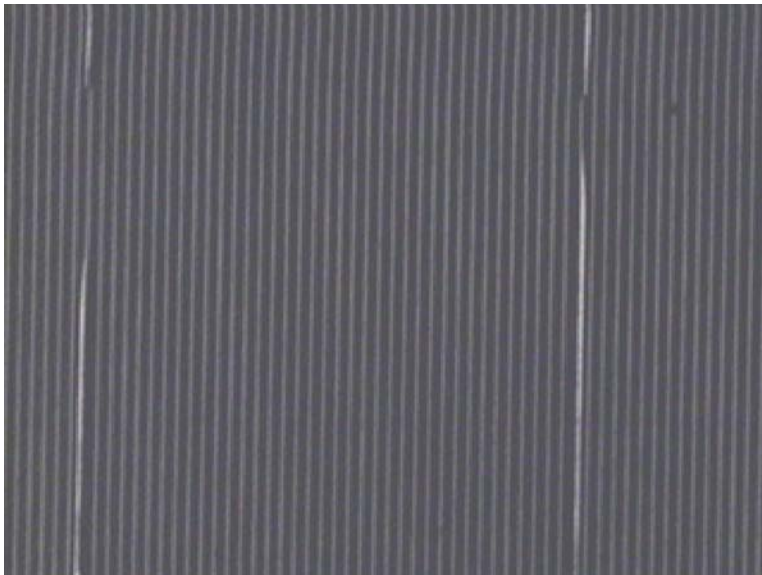


Grating Fabrication Improvements

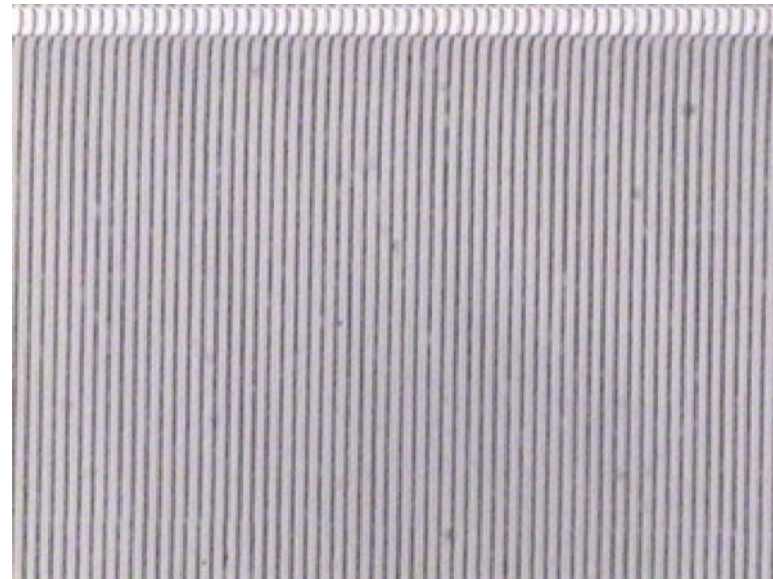
1. Electron-beam lithographic techniques for dielectric gratings
 - More masking in all steps
2. Trans-Imprinting for metallic gratings
 - pressure optimization
3. Focused Ion Beam
 - Beam current optimization
 - Focusing optimization
4. Ion etcher (Collaboration with LLNL)



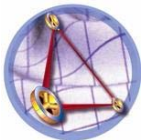
Grating Duty Cycle Variation



Chrome etch mask
25% duty cycle.

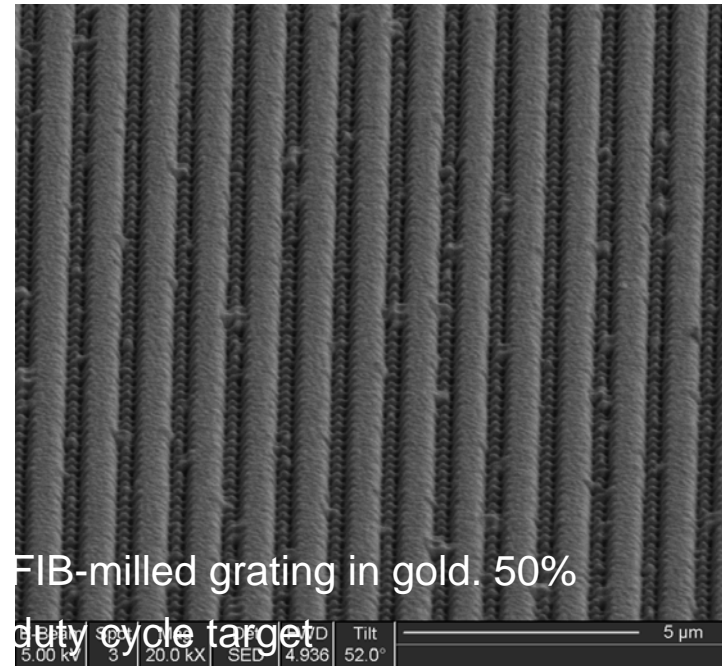


Chrome etch mask
75% duty cycle.

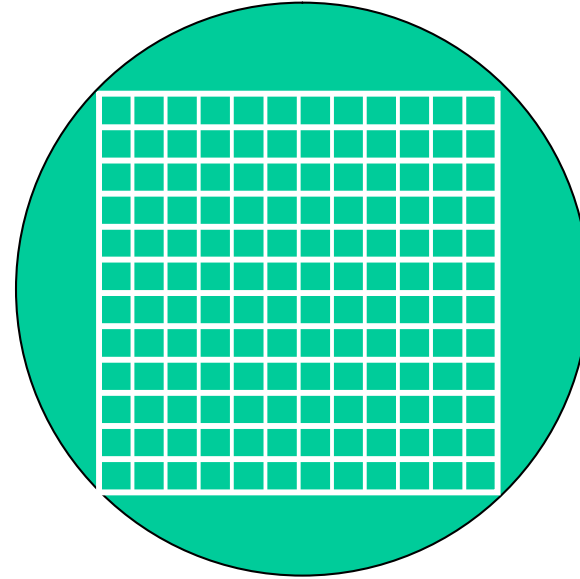
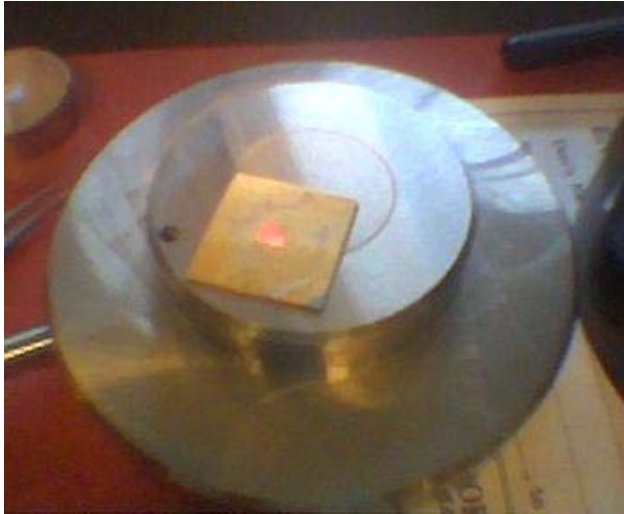


Grating Fabrication for Grating Angular Sensor

- Direct ion milling of gold gratings
 - 1 mm gratings with 50% duty cycle and 300nm depth have been fabricated.
 - Performed using an FEI Focused Ion Beam machine
 - Efficiency of +/-1 order: >20%
 - Studying the “side lobes”



Gratings Can Be Cost Effective



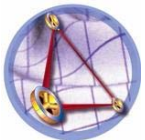
- 2 mm or 3 mm square grating is big enough for

- Smaller gratings can cut from a large wafer
- 100s gratings made at once time
- 10s dollars per grating



Conclusion

- Symmetric grating angular sensor sensitivity beats $1 \text{ nrad/Hz}^{1/2}$
- Symmetric grating angular sensor with proper electronics chain is more robust against laser frequency noises
- In-house grating fabrication techniques allow grating elements to be produced cost effectively
- Future tasks
 - Electronics for higher sensitivity
 - Environmental control for lower frequencies





Acknowledgements

- Support for this project comes from
 - NSF LIGO for gravitational wave detection
 - LLNL for supporting high power dielectric grating development for Stanford LIGO program
 - JPL DRDF for precision angular sensing for LISA proof mass sensing

