



Whelan for LSC:
SB search w/ALLEGRO & LIGO
LIGO-G060371-00-Z



Stochastic Background Search with ALLEGRO and LIGO Science Data

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on behalf of the LIGO Scientific Collaboration

XIth Marcel Grossman Meeting

2006 July 28

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Outline

I Background/Motivation for LLO-ALLEGRO Search

- LLO-ALLEGRO Pair (proximity, overlap modulation)
- Technical Considerations (sampling, heterodyning)

II S4 Data Analysis

- Data Volume by Orientation; Projected Sensitivity
- Statistical Interpretation
- Software & Hardware Injections
- Cross-Corr Analysis Complete; Under Internal Review



Sensitivity to Stochastic GW Backgrounds

- Optimally filtered CC statistic

$$Y = \int df \underbrace{\tilde{s}_1^*(f) \tilde{Q}(f) \tilde{s}_2(f)}_{Y(f)}$$

- Optimal filter $\tilde{Q}(f) \propto \frac{S_{gw}(f)\gamma_{12}(f)}{P_1(f)P_2(f)}$
(Initial analyses assume $S_{gw}(f)$ or $\Omega_{gw}(f) \propto f^3 S_{gw}(f)$ constant across band)
- Optimally filtered cross-correlation method has Ω_{gw} sensitivity

$$\sigma_\Omega \propto \left(T \int \frac{df}{f^6} \frac{\gamma_{12}^2(f)}{P_1(f)P_2(f)} \right)^{-1/2}$$

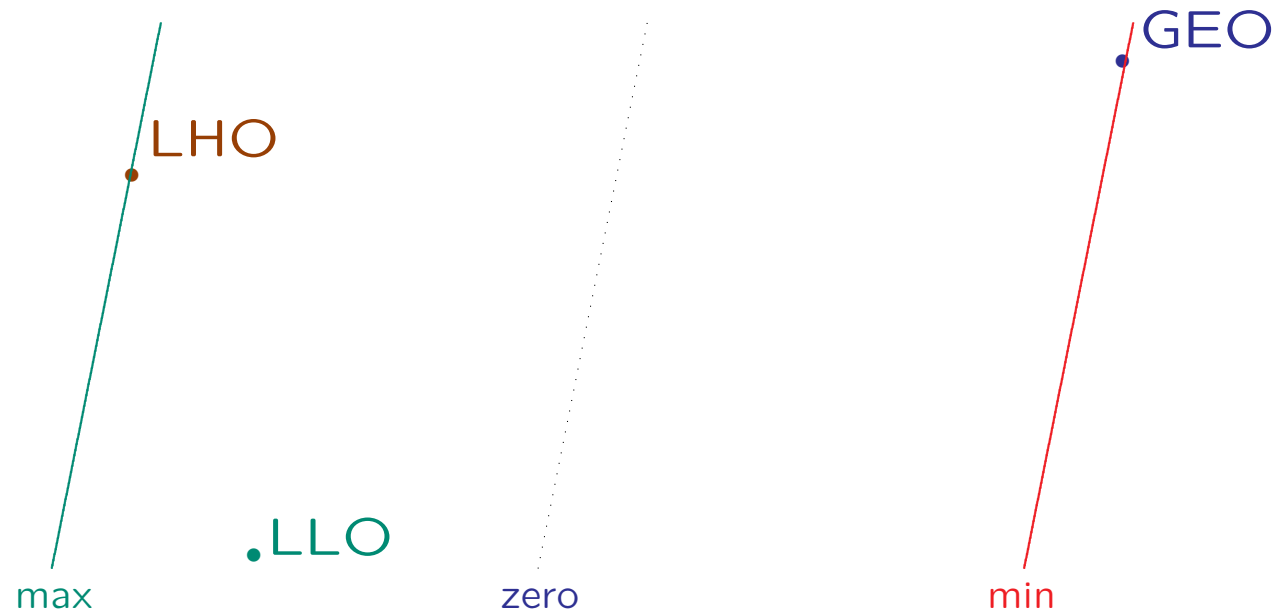
- Significant contributions when
 - detector noise power spectra $P_1(f)$, $P_2(f)$ small
 - overlap reduction function $\gamma_{12}(f)$ (geom correction) near ± 1



Overlap Reduction Function

$$\gamma_{12}(f) = d_{1ab} d_{2cd} \frac{5}{4\pi} \iint_{S^2} d^2\Omega_{\hat{n}} P^{TT}_{cd}{}^{ab}(\hat{n}) e^{i2\pi f \hat{n} \cdot \Delta \vec{r}/c}$$

Depends on alignment of detectors (polarization sensitivity)
Frequency dependence from cancellations when $\lambda \lesssim$ distance
→ Widely separated detectors less sensitive at high frequencies



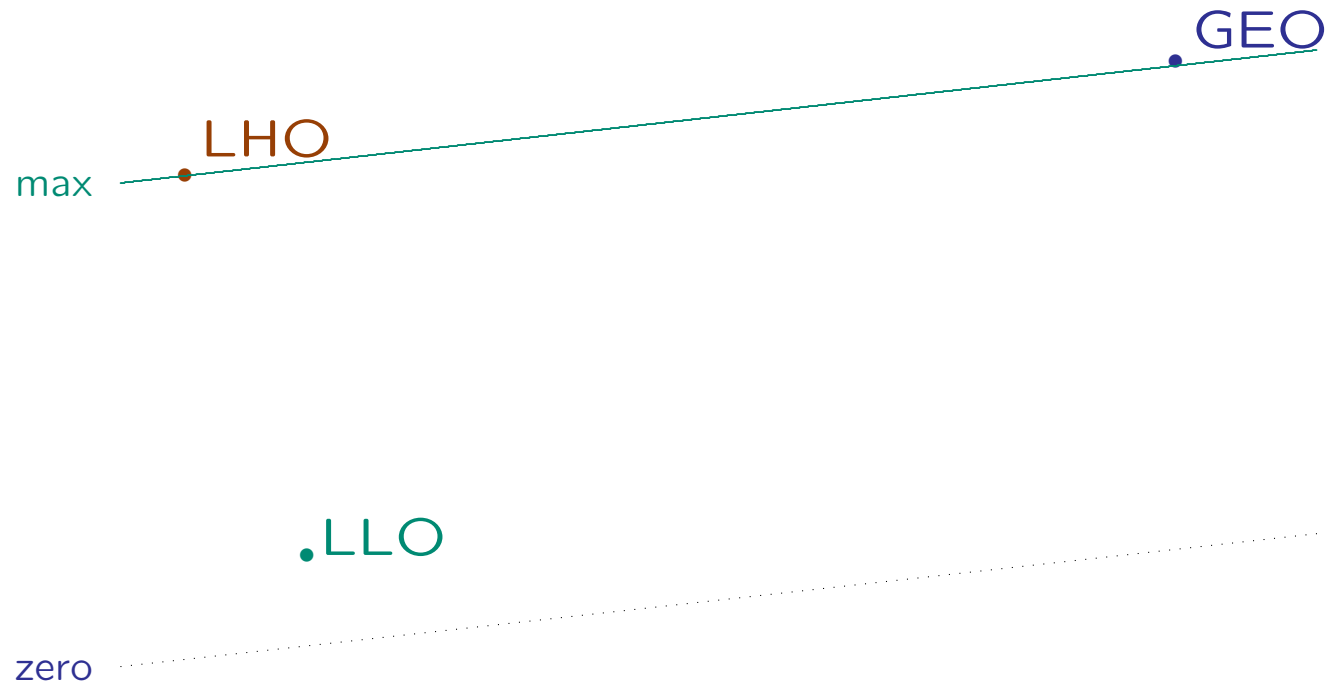
This wave drives LHO & GEO out of phase



Overlap Reduction Function

$$\gamma_{12}(f) = d_{1ab} d_2^{cd} \frac{5}{4\pi} \iint_{S^2} d^2\Omega_{\hat{n}} P^{TT}_{cd}{}^{ab}(\hat{n}) e^{i2\pi f \hat{n} \cdot \Delta \vec{r} / c}$$

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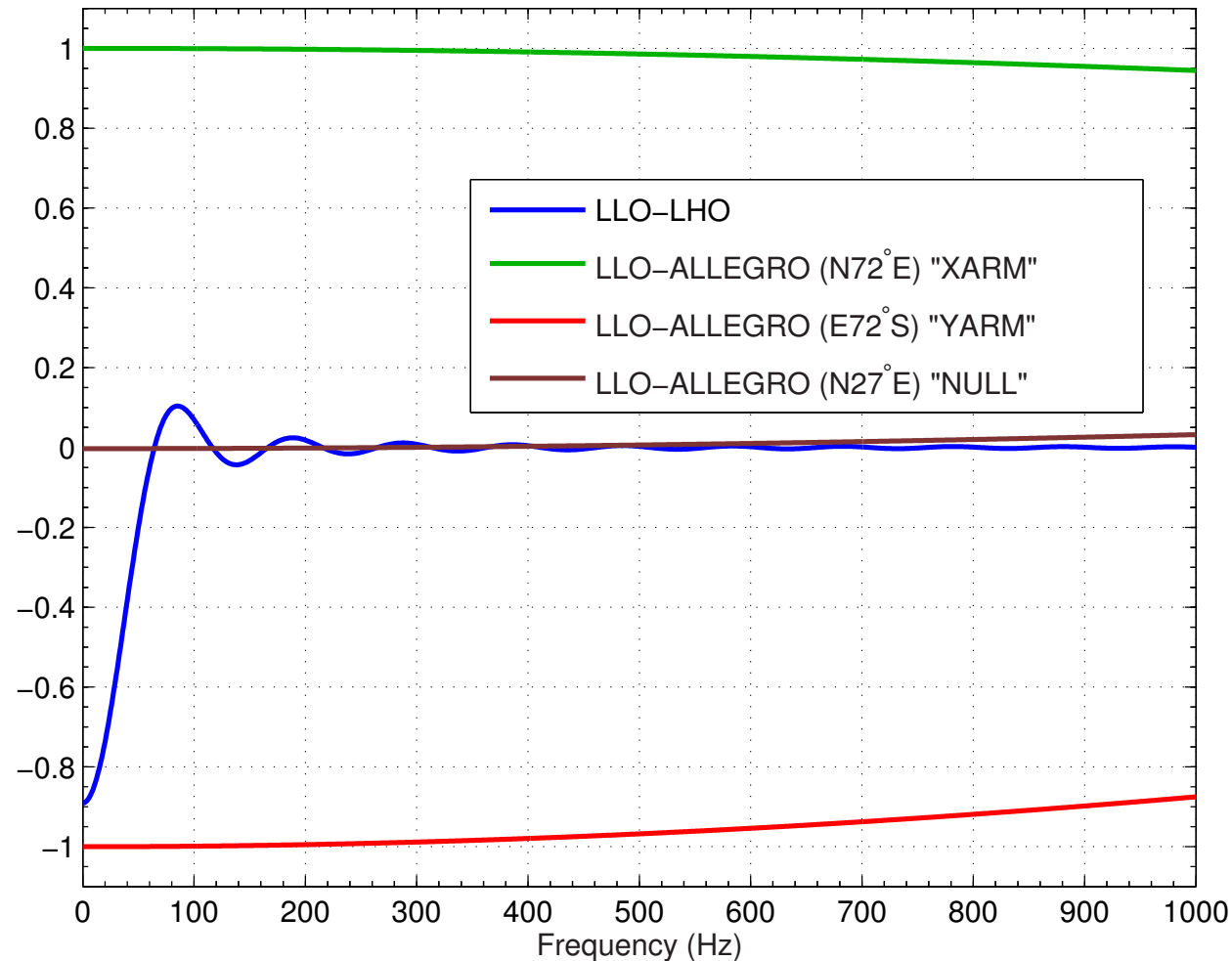
This wave (same λ) drives LHO & GEO in phase



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Overlap Reduction Function



LLO-ALLEGRO only ~ 40 km apart \rightarrow still sensitive @ 900 Hz

Response different for XARM, YARM, NULL orientations

ALLEGRO ran in all 3 orientations during LIGO S4 Run (2005 Feb 22-Mar 23)



LLO-ALLEGRO: Technical Considerations

- LIGO data digitally downsampled 16384 Hz \rightarrow 4096 Hz
ALLEGRO data heterodyned at 904 Hz & sampled at 250 Hz
- Heterodyning means CC stat complex:

$$Y = \int_{f_{\min}}^{f_{\max}} df \tilde{s}_1^*(f) \tilde{Q}(f) \tilde{s}_2(f)$$

real part Gaussian-distributed about SGWB strength;

imag part Gaussian-distributed about 0.

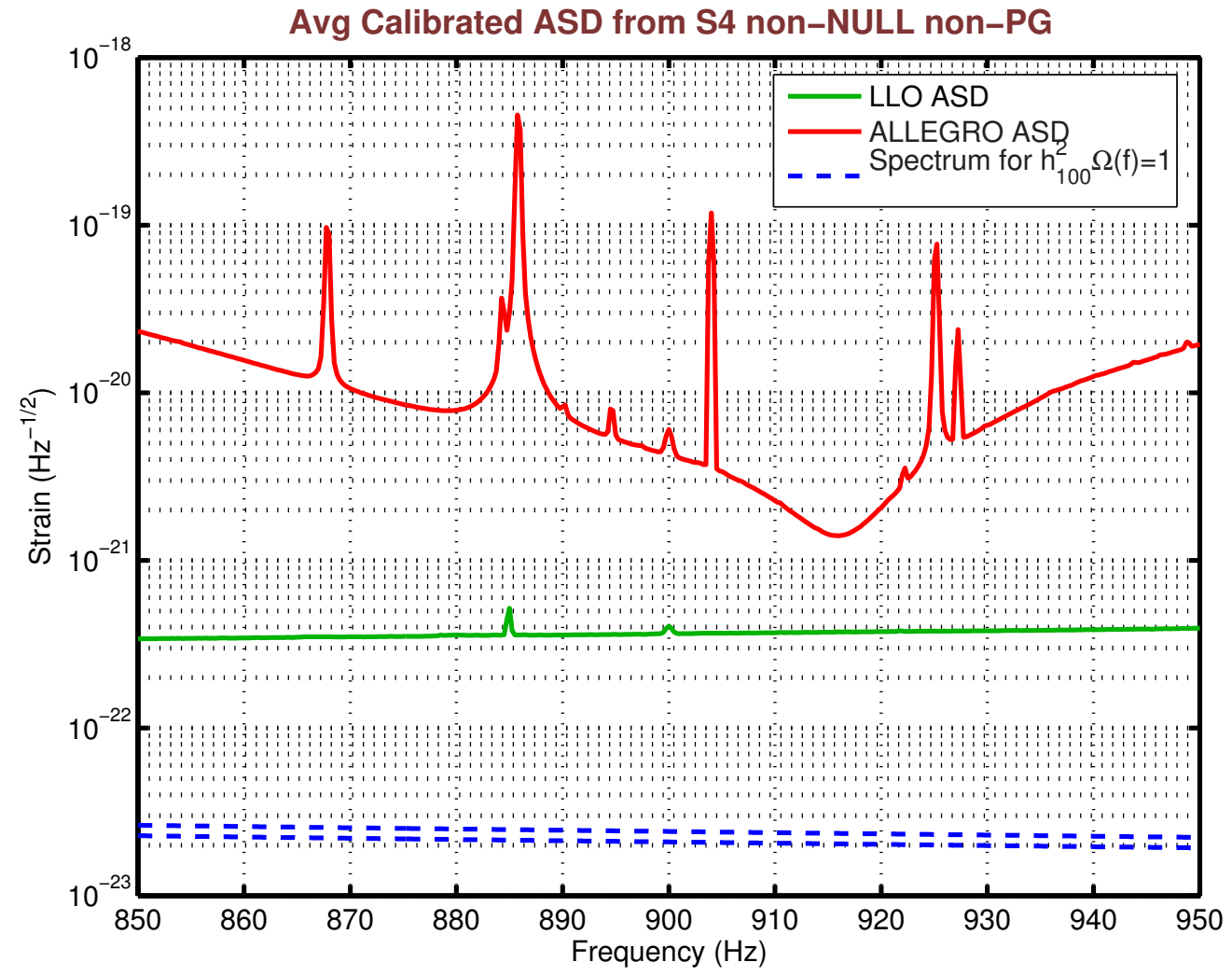


LLO-ALLEGRO data from LIGO S4 Run

- $\sim 10\%$ of data set aside as “playground” ;
Non-PG data divided into 60s segments; 3 orientations:
 - “NULL” ($0.023 < \gamma(f) < 0.029$): ≈ 5200 min after cuts
“off-source” data useful for data quality & cross-checks
 - “YARM” ($-0.89 > \gamma(f) > -0.91$): ≈ 6600 min after cuts
 - “XARM” ($0.95 < \gamma(f) < 0.96$):] ≈ 10400 min after cuts
- Projected $h_{100}^2 \Omega$ sensitivity using non-playground data: $\sim 0.3-1$;
Corresponds to $\sqrt{S_{\text{gw}}(f = 915 \text{ Hz})}$ of $\sim 1-2 \times 10^{-23} \text{ Hz}^{-1/2}$



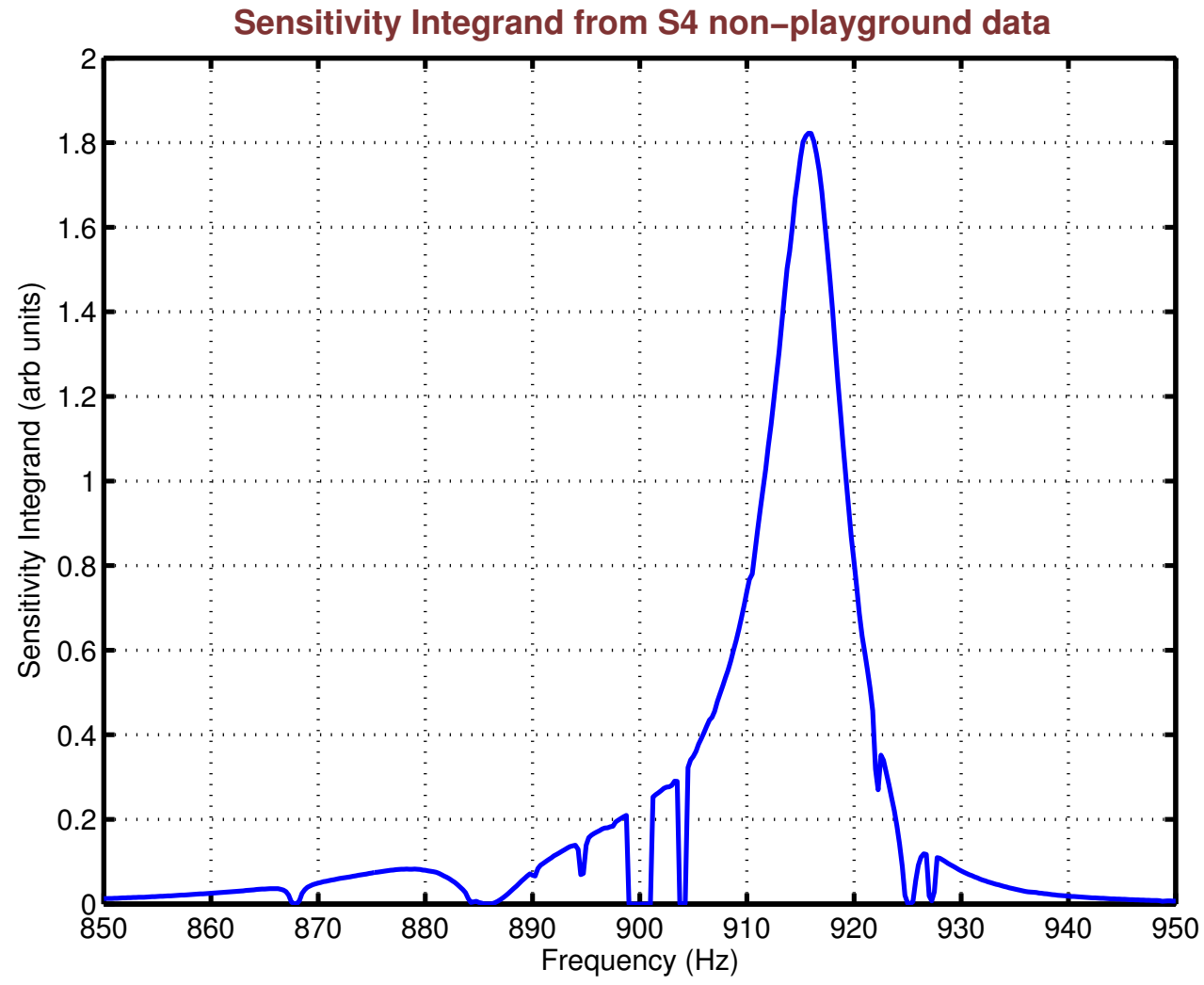
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Frequency band determined by ALLEGRO noise curve



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Most of sensitivity from 905–925 Hz



Constructing Posterior PDF

- Overall estimate $h_{100}^2 \widehat{\Omega} = x + iy$ has likelihood function (for given actual $\Omega_R = h_{100}^2 \Omega_{\text{gw}}(915 \text{ Hz})$)

$$P(x, y | \Omega_R, \sigma_\Omega) \propto \exp\left(-\frac{|x + iy - \Omega_R|^2}{2\sigma_\Omega^2}\right)$$

- Bayes's theorem gives posterior PDF

$$\begin{aligned} P(\Omega_R | x, y, \sigma_\Omega) &= \frac{P(x, y | \Omega_R, \sigma_\Omega) P(\Omega_R)}{P(x, y | \sigma_\Omega)} \\ &\propto e^{-(x - \Omega_R)^2 / 2\sigma_\Omega^2} P(\Omega_R) \end{aligned}$$

Note **imag** part y of pt est **factors out**



Marginalization Over Calibration Uncertainty

- Calibration of LLO & ALLEGRO uncertain in amp & phase
Marginalize over unknown correction factor $e^{\Lambda+i\phi}$:

$$P(x, y | \Omega_R, \sigma_\Omega, \Lambda, \phi) \propto \exp\left(-\frac{|x + iy - \Omega_R e^{\Lambda+i\phi}|^2}{2\sigma_\Omega^2}\right)$$

so the posterior after marginalizing the likelihood function is

$$P(\Omega_R | x, y, \sigma_\Omega) \propto \int_{-\infty}^{\infty} d\Lambda \int_{-\pi}^{\pi} d\phi \exp\left(-\frac{|x + iy - \Omega_R e^{\Lambda+i\phi}|^2}{2\sigma_\Omega^2}\right) P(\Lambda, \phi) P(\Omega_R)$$

which does depend on imag part y



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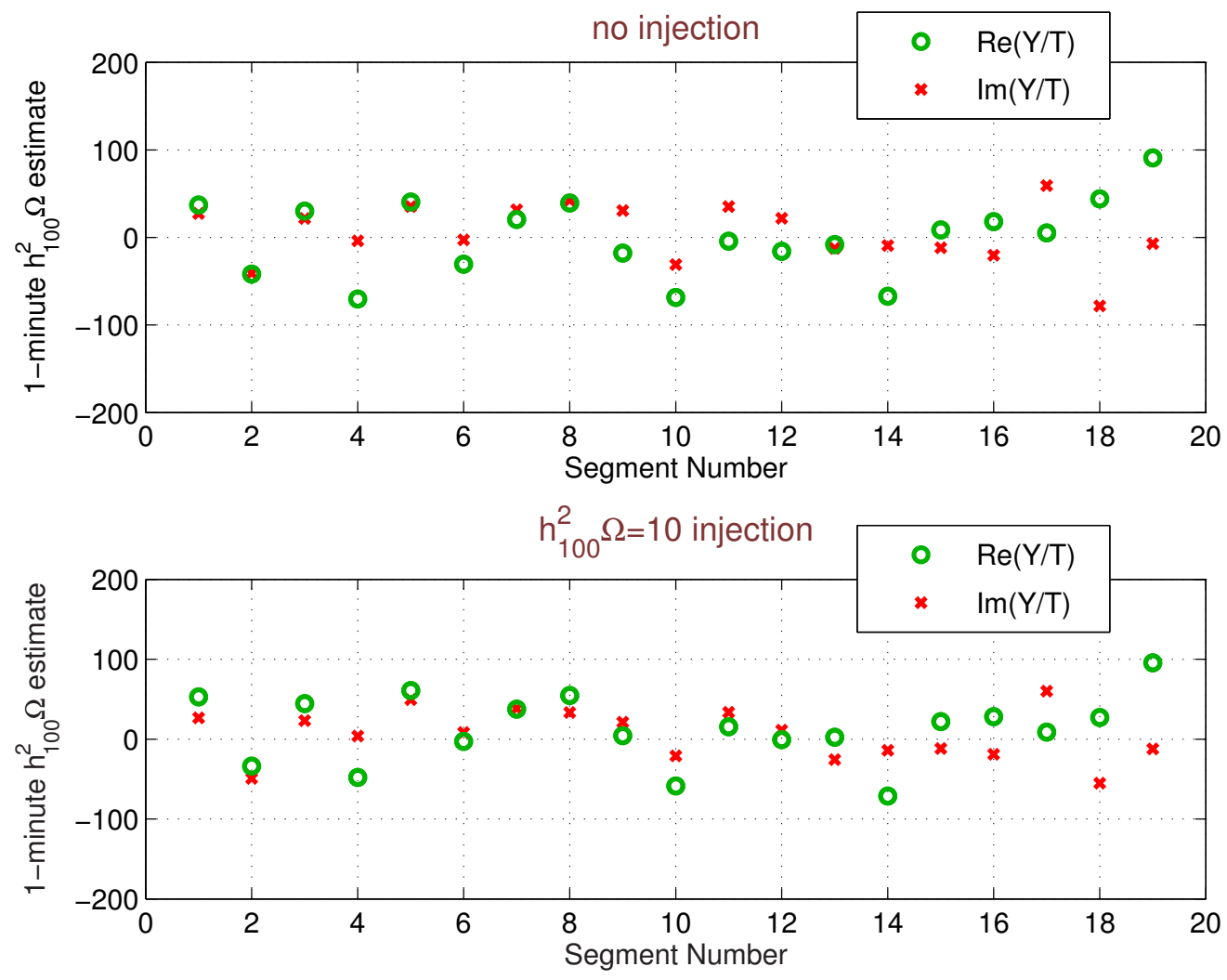


Software Injections into S4 Playground

- Combined 90% error bar for all PG data: 0.8
(XARM-only: 0.9; YARM-only: 1.4; NULL-only 46)
- Inject $h_{100}^2 \Omega(f) = 1, 2, 5, 10$.
- Note: individual jobs have error bars around 60.
SW injections only detectable over time.



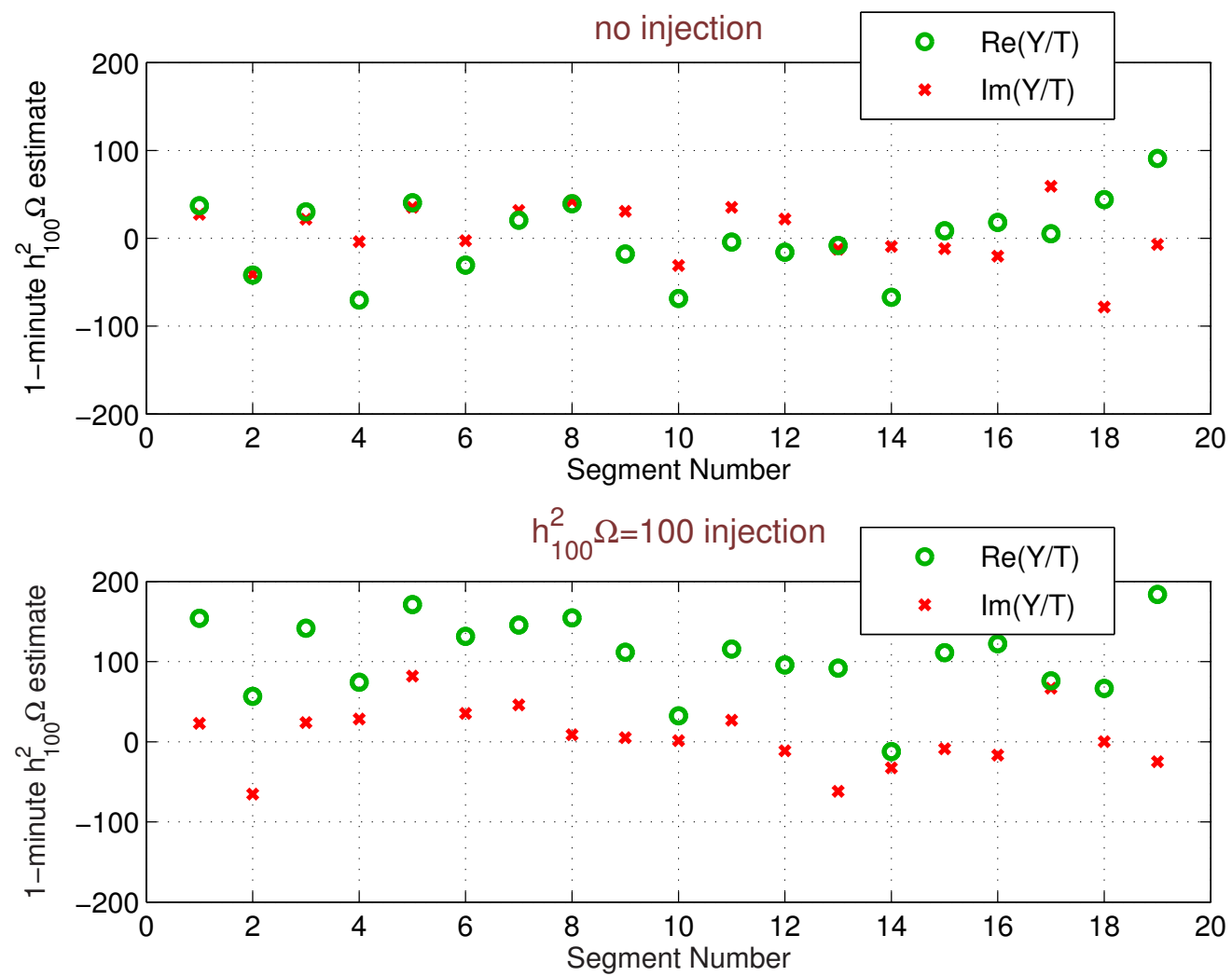
Stats w/ & w/o SW Inj (19 60-sec segs)



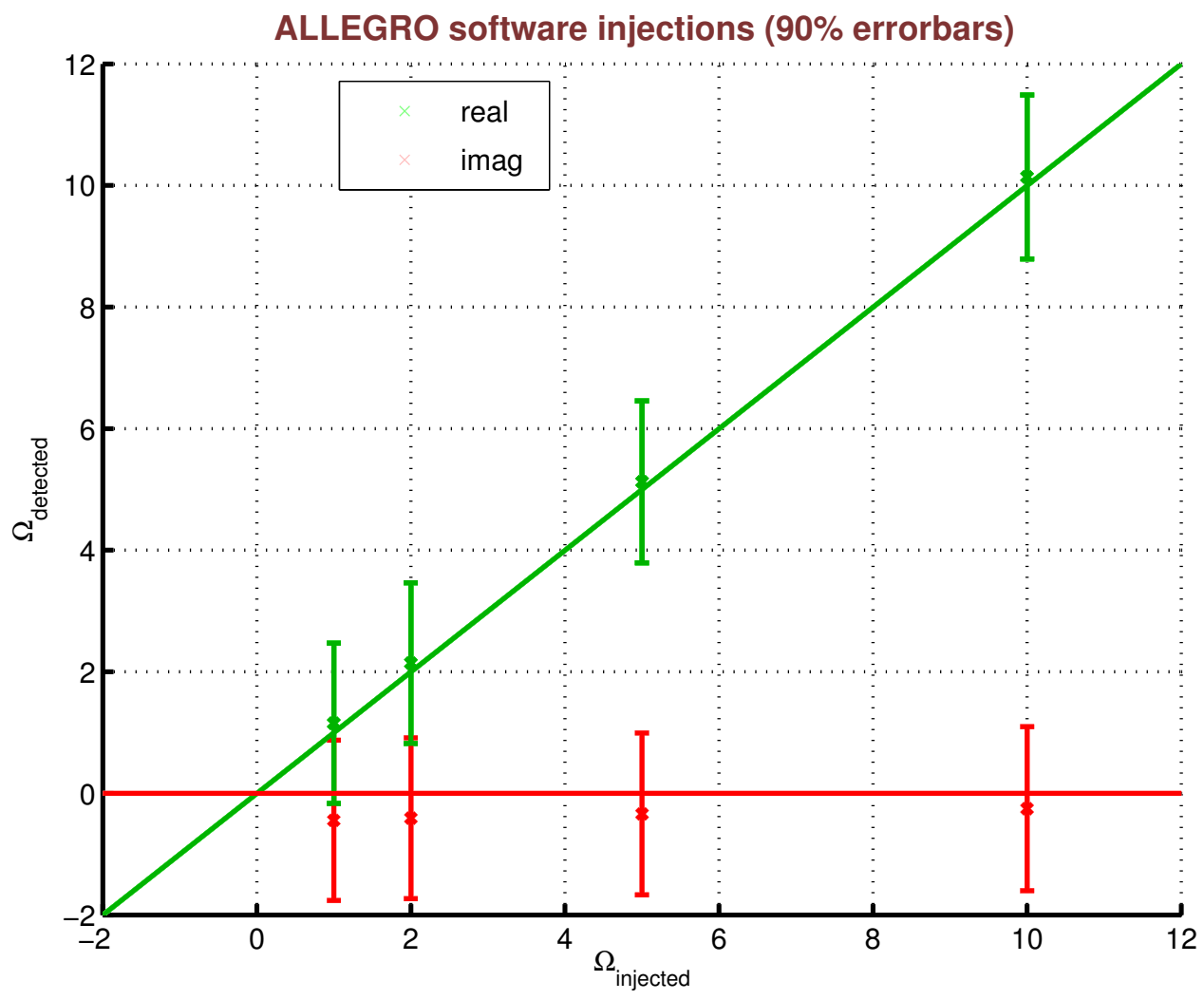
Injecting $h^2_{100} \Omega(f) = 10$ has negligible impact on minute-by-minute correlations



Stats w/ & w/o SW Inj (19 60-sec segs)



Compare $h^2_{100} \Omega(f) = 100$ injection, which is visible minute-by-minute



$h_{100}^2 \Omega(f) = 2, 5, 10$ injections recovered from full PG

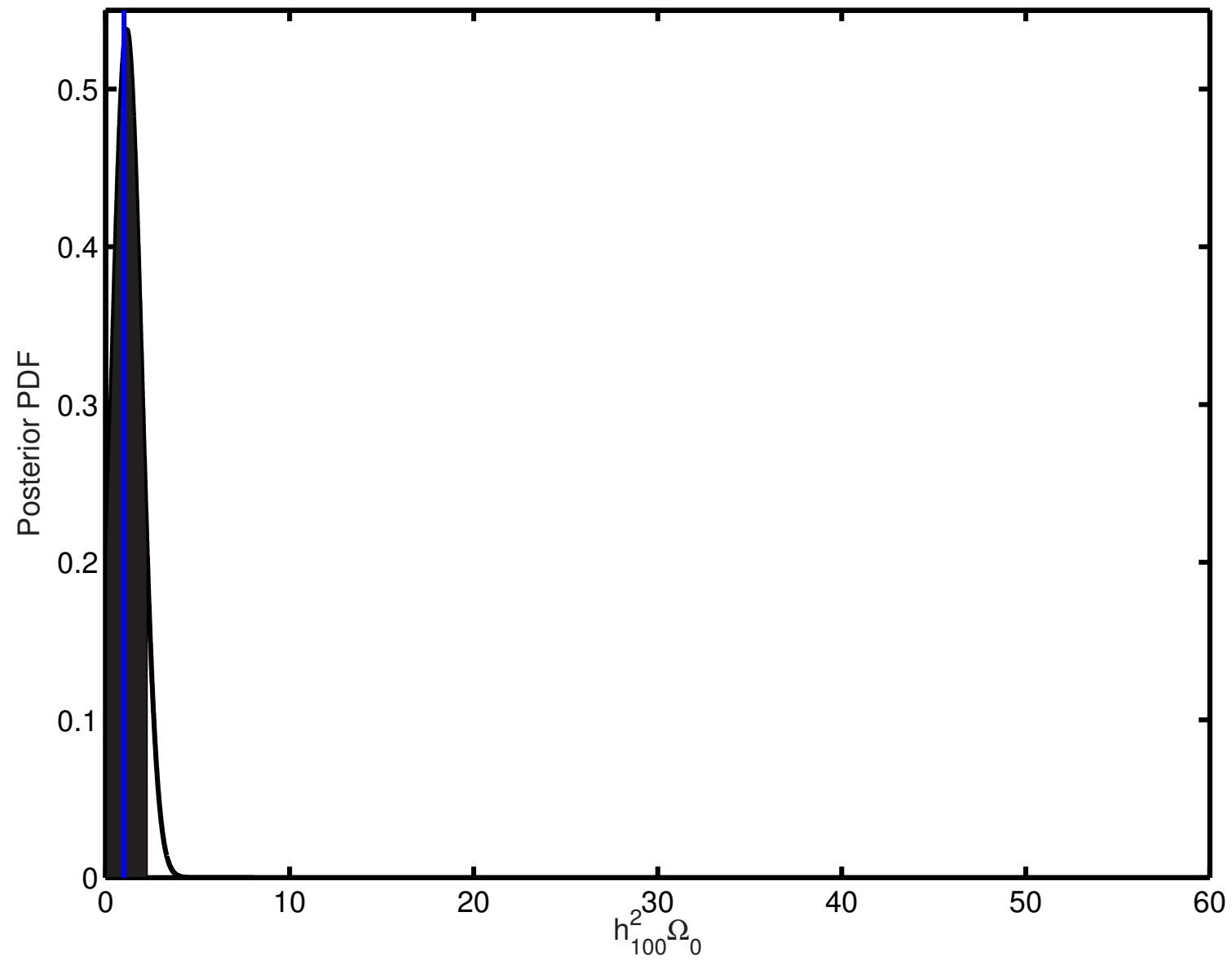
Note: injected same random signals w/different amplitudes into same noise



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Posterior PDF from $h_{100}^2 \Omega_0 = 1$ injection (no cal marg)

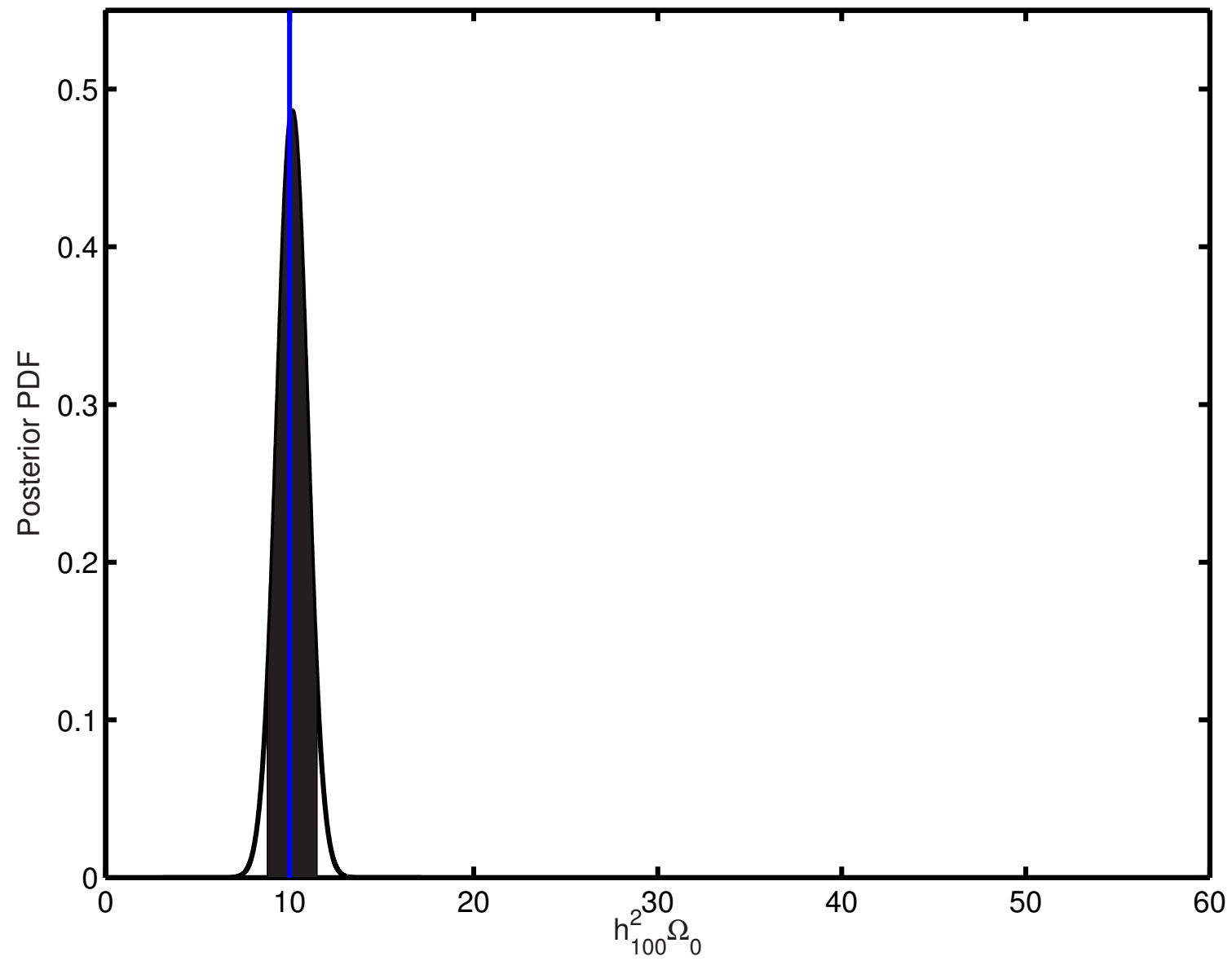




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Posterior PDF from $h_{100}^2 \Omega_0 = 10$ injection (no cal marg)





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S4 Hardware Injections

- 1024-second simulated signals injected into LLO & ALLEGRO hardware a total of nine times. Simulated all three orientations.
- “second” & “third” rounds injected const $h_{100}^2 \Omega_{\text{gw}}(f) = 4195$
Sensitivity of cross-correlation to injections simulating XARM (“plus”) and YARM (“minus”) is comparable
“null” injection less correlated b/c of simulated misalignment



Time-Shift Analyses

- Learned about timing issues via HW injections:
Time-shift analysis helped resolve issues w/ALLEGRO timing
Also revealed sample-and-hold & other digital effects
in injection system which introduce relative time shift of

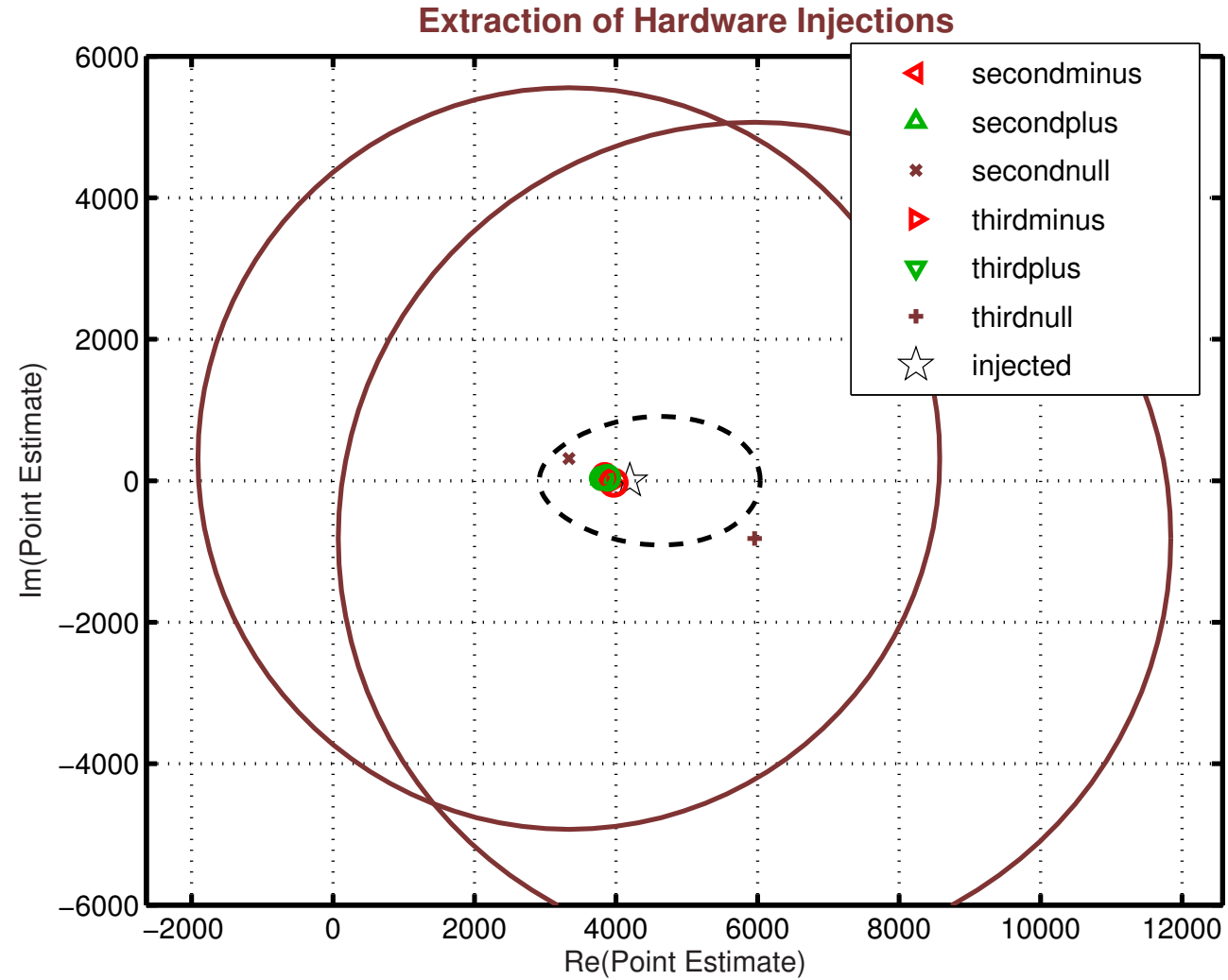
$$\frac{1}{2 \times 4096 \text{ Hz}} - 18 \mu\text{s} = 104 \mu\text{s}$$

- Post-processing correction:
Simulate small timeshift w/freq-dependent phase shift

$$Y(f) \longrightarrow Y(f) e^{i2\pi f\tau}$$

inv FT of CC integrand gives CC values as fcn of time-shift:

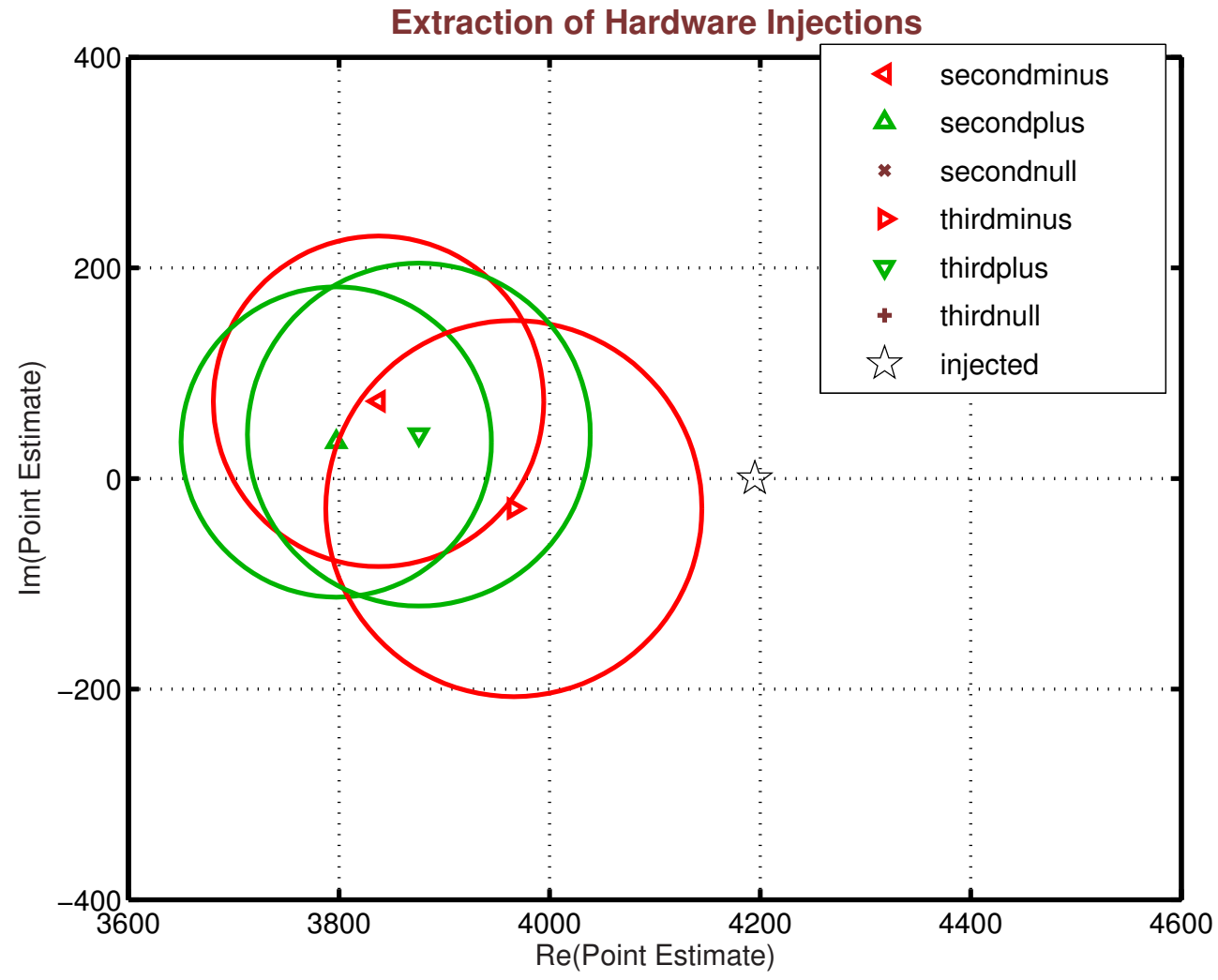
$$Y(\tau) = \int_{f_{\min}}^{f_{\max}} df Y(f) e^{i2\pi f\tau}$$



Circles: 90% statistical uncertainty (null measurements less sensitive)

90% calib uncertainty “teardrop” around $h_{100}^2 \Omega_{gw}(f) = 4195$

HW injections recovered consistent w/cal uncertainty



Circles: 90% statistical uncertainty

90% calib uncertainty “teardrop” around $h_{100}^2 \Omega_{gw}(f) = 4195$

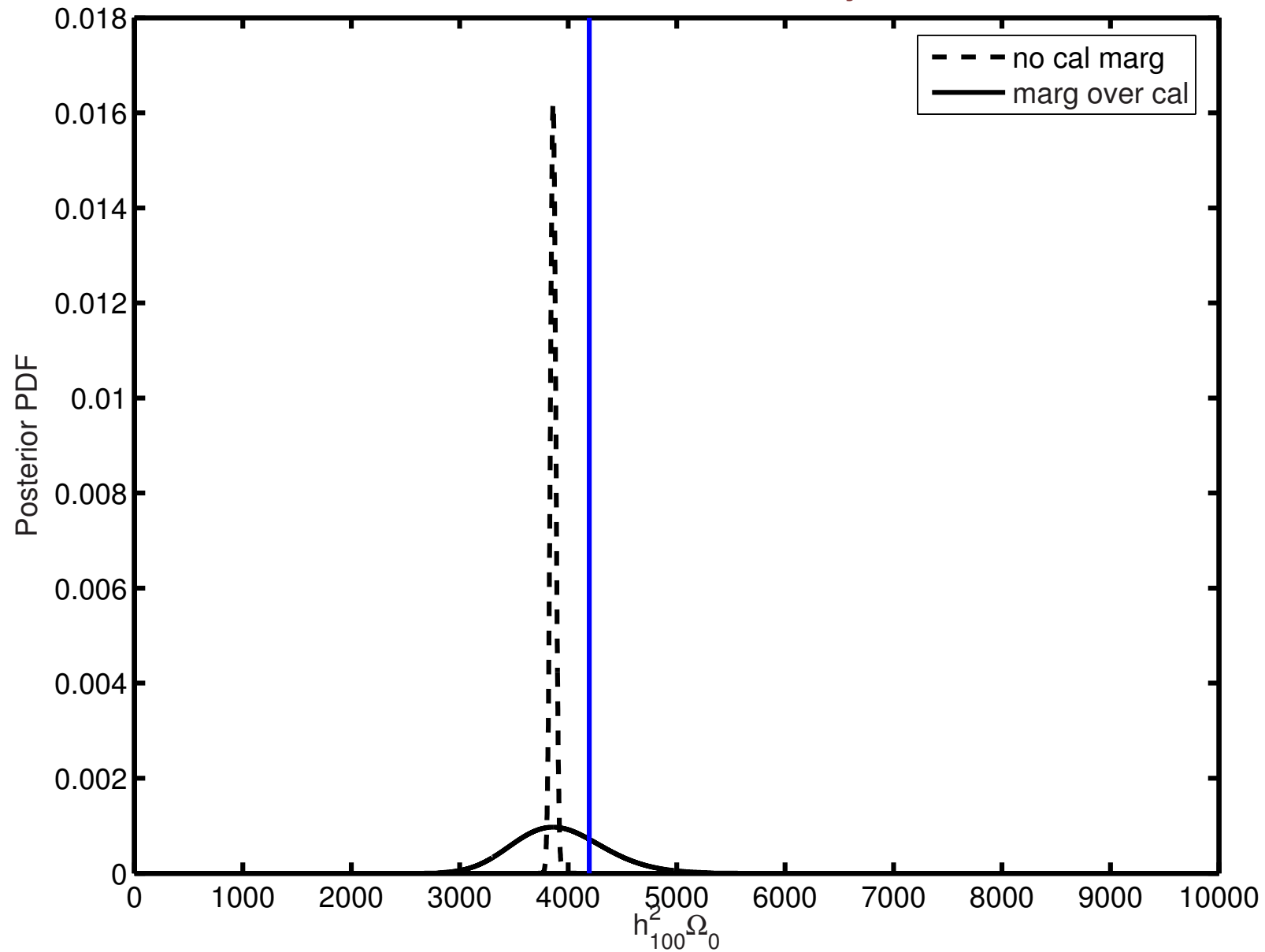
Systematic offset < cal uncertainty



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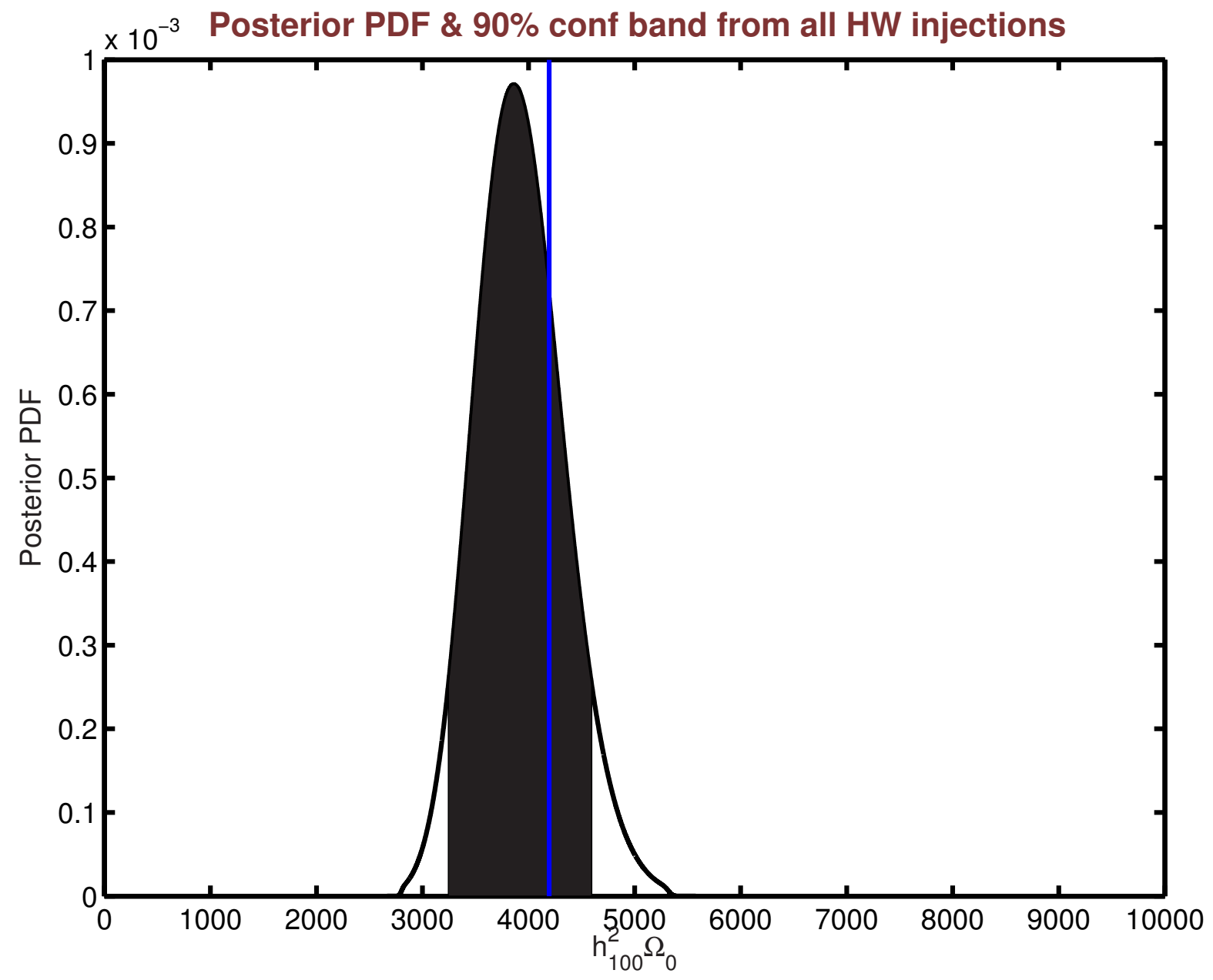


Posterior PDF from all HW injections





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LLO-ALLEGRO: Summary

- First stochastic measurement correlating **bar** w/**ifo** data;
Probes **higher frequency band** than **LLO-LHO**: $\sim 850 - 950$ Hz
- **Rotation** of **ALLEGRO** modulates stochastic response
(data taken in **3 orientations** during **S4**)
- **Projected S4** sensitivity from ~ 370 hrs of data:
 $h_{100}^2 \Omega_{\text{gw}}(f) \sim 0.3-1$ or $\sqrt{S_{\text{gw}}(f)} \sim 1-2 \times 10^{-23} \text{ Hz}^{-1/2}$
- Analysis extracts long-time, low-amplitude **simulated signals**
(software injections)
- **Hardware inj** extracted consistent w/**calibration uncertainty**
- **Analysis complete**; Under **internal review**. Stay tuned ...