

Advanced LIGO Subsystems

NSF Review of the
Advanced LIGO Project
31 May 2006



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Part 1: Dennis Coyne

- **Advanced LIGO Technical Overview**
- **Subsystem Breakdown**
- **Subsystem Overviews:**
 - » **Control & Data System (CDS) Infrastructure**
 - Data Acquisition (DAQ, WBS 4.09)
 - Data Computing System (DCS, WBS 4.12)
 - » **Isolation:**
 - Seismic Isolation (SEI, WBS 4.02)
 - Suspensions (SUS, WBS 4.03)
 - » **Integration**
 - Systems Engineering (SYS, WBS 4.14.5)
 - Facility Modifications & Preparation (FMP, WBS 4.01)
 - Installation & System Test (INS, WBS 4.13)

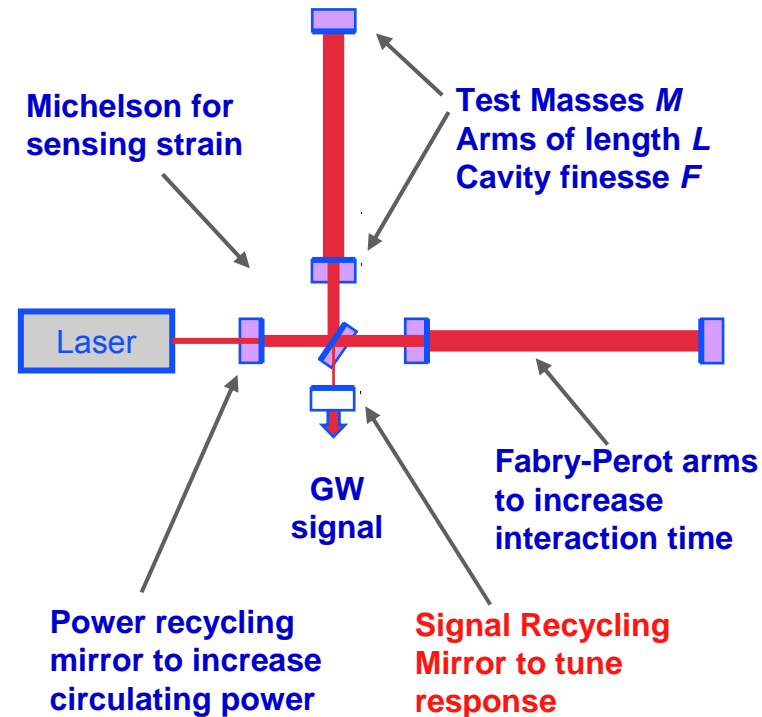
Part 2: Peter Fritschel

- » **Lasers & Optics**
 - Pre-Stabilized Laser (PSL, WBS 4.04)
 - Input Optics (IO, WBS 4.05)
 - Core Optic Components (COC, WBS 4.06)
 - Auxiliary Optics System (AOS, WBS 4.07)
- » **Global Interferometer Controls**
 - Interferometer Sensing & Controls (ISC, WBS 4.08)
- **Open Trade Studies/Options**
- **Performance**
- **System Test Beds**

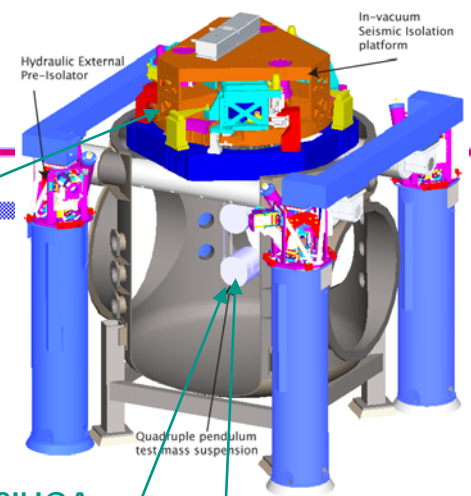
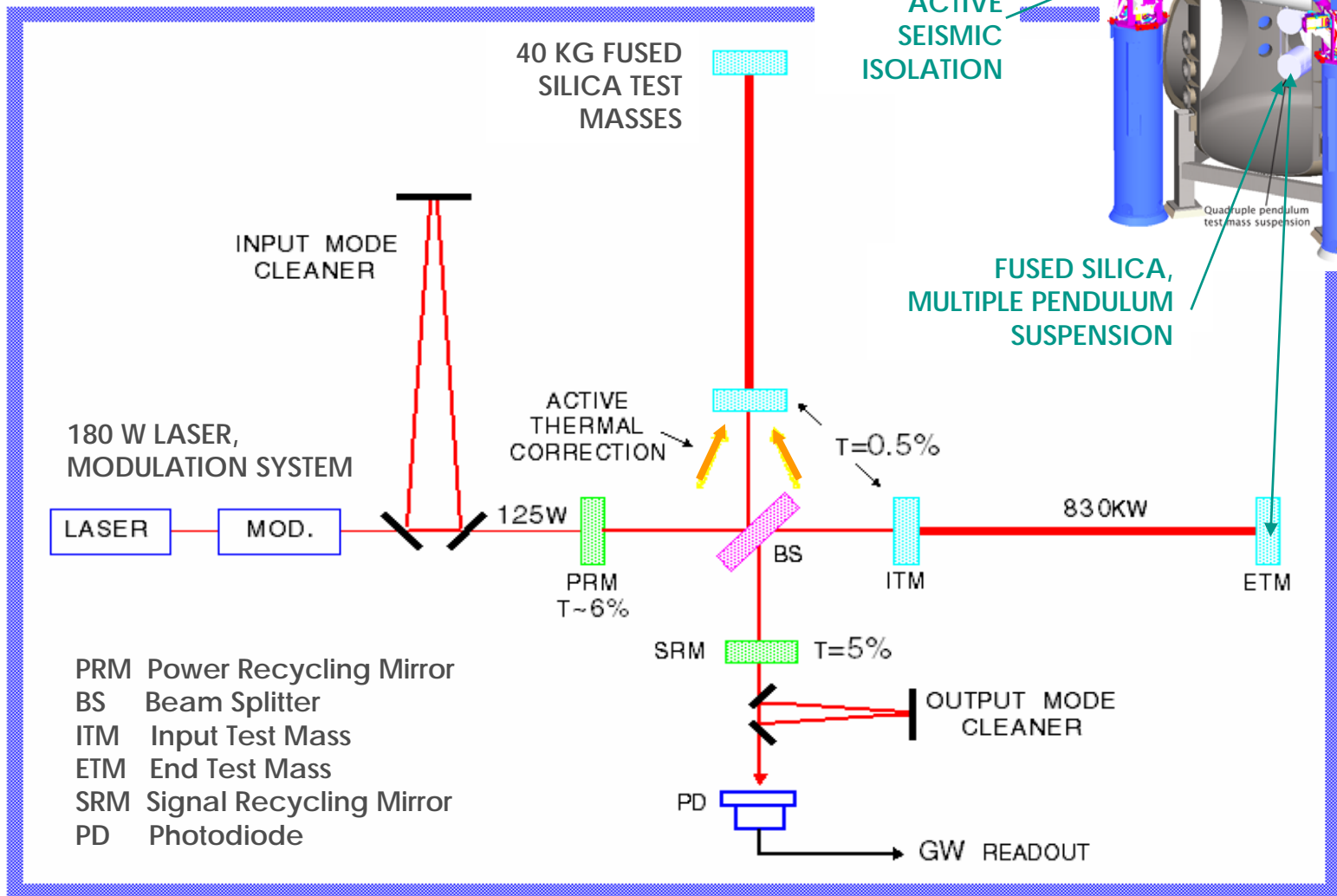
Retain infrastructure, vacuum chambers, and Initial LIGO layout of power recycled interferometer

- **Recombined Fabry-Perot Michelson**
 - » Signal recycling (increase sensitivity & add tunability)
- ~20x higher input power (lower shot noise)
- 40 kg masses (lower photon pressure noise)
- Fused Silica Suspension (lower thermal noise)
- Active seismic isolation, quadruple pendulum suspensions (lower frequency response)
- Leads to:
 - » Increased Thermal Compensation
 - » Improved Scattered Light Control
 - » Addition of Output Optical Filtering (Mode Cleaner)
 - » Seismically isolated, in-vacuum detection
 - » Increased Control Complexity
 - » Modifications to the Vacuum Envelope

ADVANCED LIGO LAYOUT



Advanced LIGO Design Features

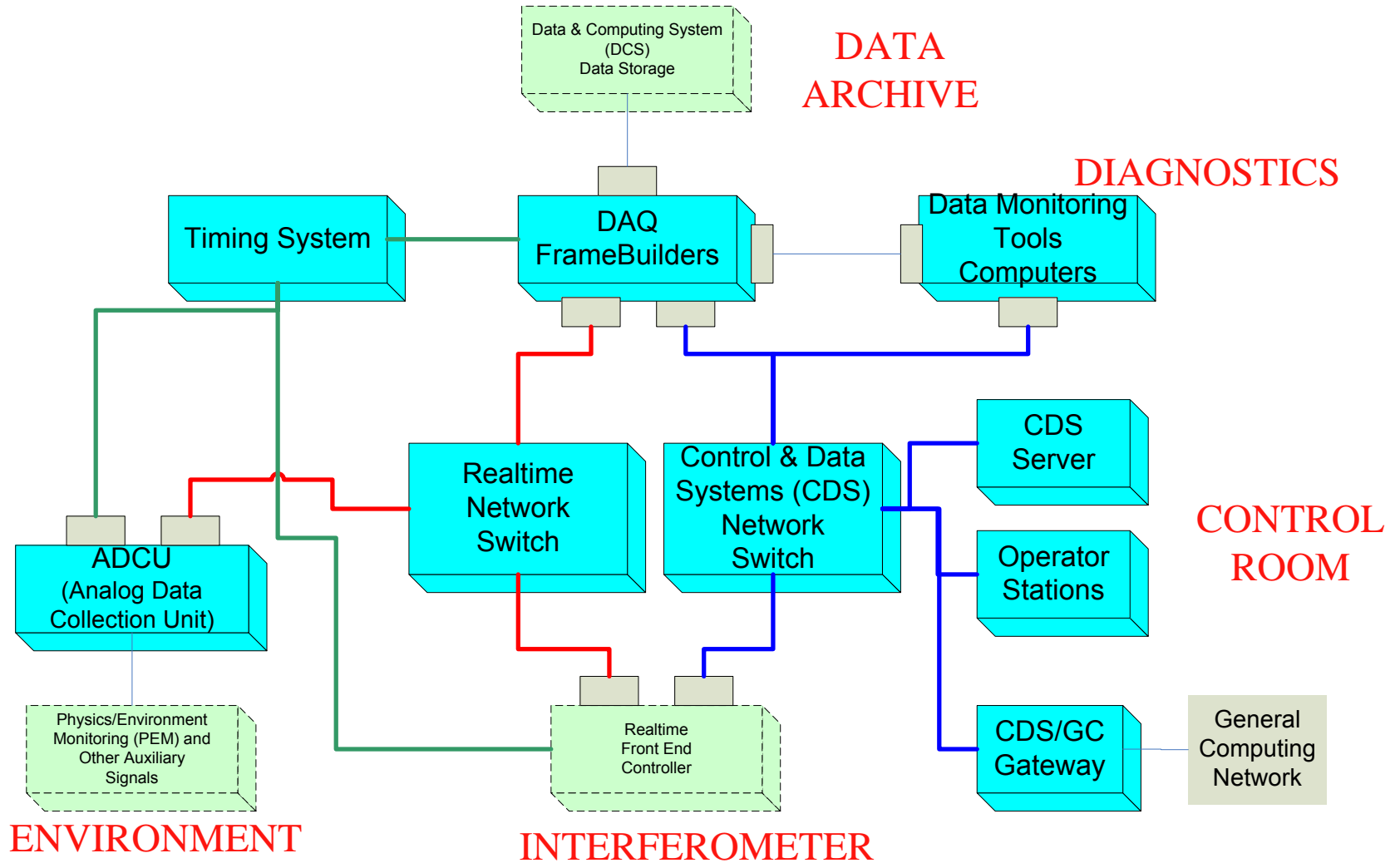


- PRM Power Recycling Mirror
- BS Beam Splitter
- ITM Input Test Mass
- ETM End Test Mass
- SRM Signal Recycling Mirror
- PD Photodiode

- **Data Acquisition System Infrastructure**
 - » receive, digitize, format and store data
 - » “FrameBuilder”
- **Networking infrastructure**
- **Interferometer Supervisory Controls**
- **Control Room Equipment**
- **Timing System**
- **Mass Storage Systems**
- **Diagnostics Monitoring and Test Tools (computers & software)**
- **Control & Data System Test Stand for each Observatory**



DAQ Block Diagram

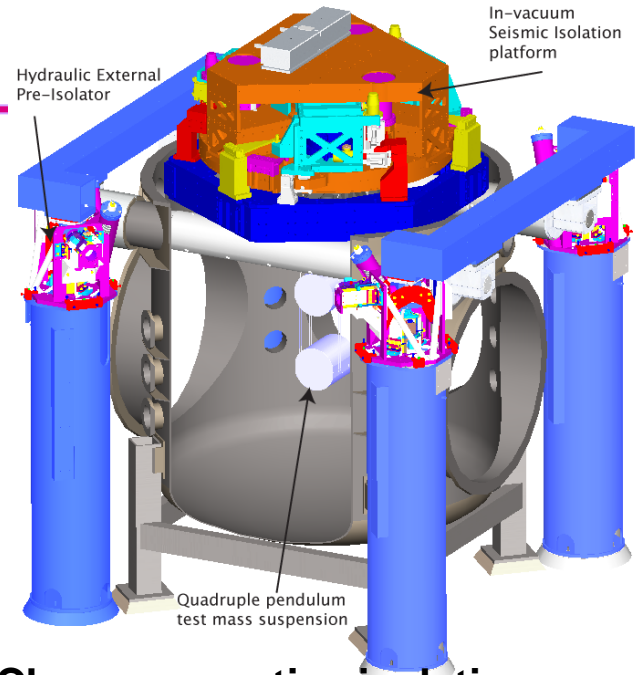
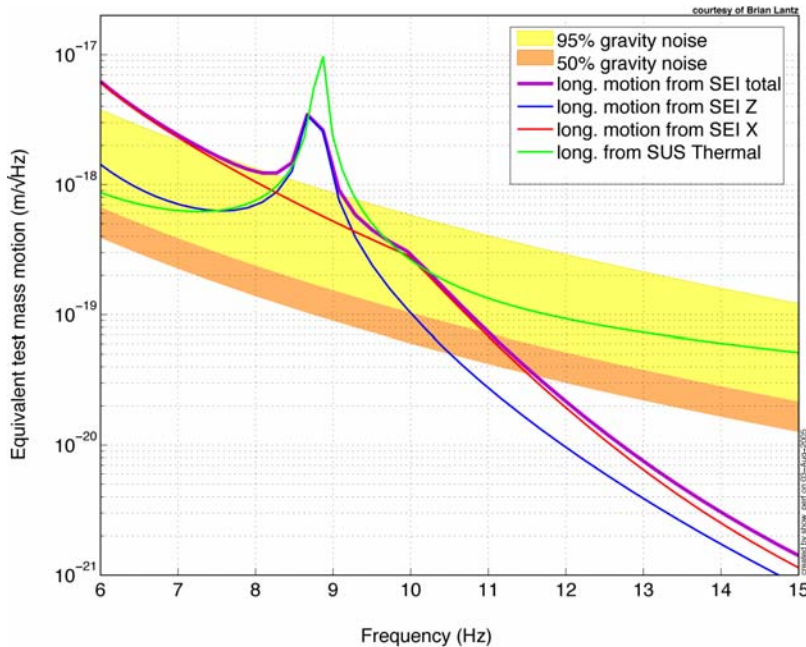


- **Data Archival**
 - » 30 Mb/s raw data rate for 3 interferometers
 - 1.8 PB/year storage (3 copies)
 - » Data striped across disks in cluster (RAID)
 - 10 TB per node – 14.5 PB aggregate
 - » Utilize existing tape robots (with upgrades) for “salt mine” archive
- **Data Distribution**
 - » Existing LIGO WAN expected to handle AdL bandwidth
 - » Infrastructure built on grid technology
- **Computing**
 - » Require ~5 TFLOPS, or ~10 x Initial LIGO FLOPS
 - Longer templates for compact object binary inspiral detection using Weiner filtering techniques
 - » Planned Configuration is ~10 x existing
 - Planned: 23K+ CPUs, >51 THz, 1456 nodes, >10 Gbps switch, SMP data servers
 - Current: 2.3K CPUs, 5.6 THz



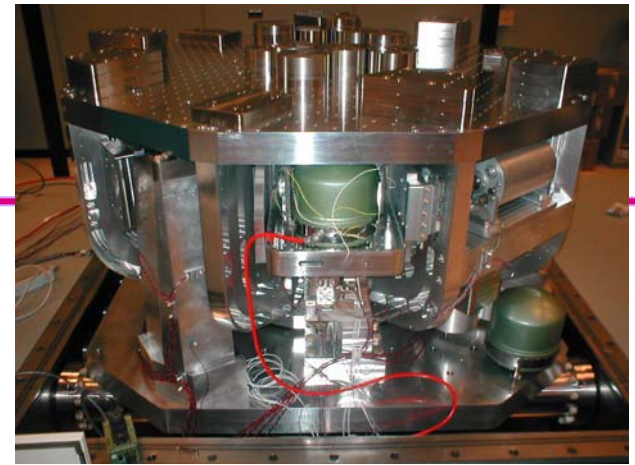
Seismic Isolation: Multi-Stage Solution

- **Render seismic noise a negligible limitation to GW searches**
 - » Both suspension and isolation systems contribute to attenuation
 - » Newtonian background will dominate for frequencies less than ~15 Hz
- **Reduce actuation forces on test masses**

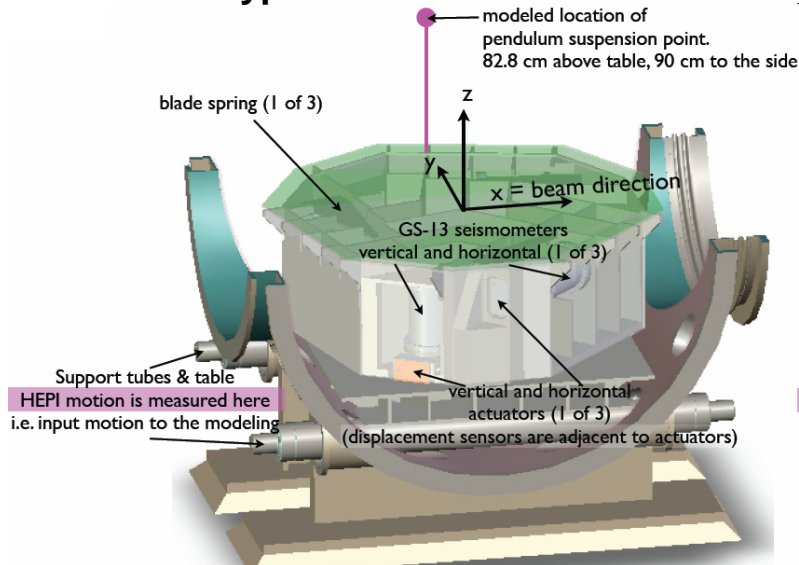


- **Choose an active isolation approach:**
 - » 3 stages of 6 degree-of-freedom each
 - » Hydraulic External Pre-Isolation (HEPI)
 - » Two Active Stages of Internal Seismic Isolation
- **Increase number of passive isolation stages in suspensions**
 - » From single suspensions in initial LIGO to quadruple suspensions₉ for Adv. LIGO

- **BSC Chamber Design**
 - » Full Scale Prototype is being assembled at LASTI
 - » Installation & Test this year with Quadruple Pendulum Suspension Prototype
 - » Modeling based on ~2/3 Scale “Technology Demonstrator” at Stanford’s Engineering Test Facility (ETF) indicates Performance Meets Requirements
- **HAM Chamber design**
 - » Modeling indicates a Single Stage Internal Seismic Isolation (ISI) System meets Requirements
 - » Full Scale Design to be completed for LASTI Prototype



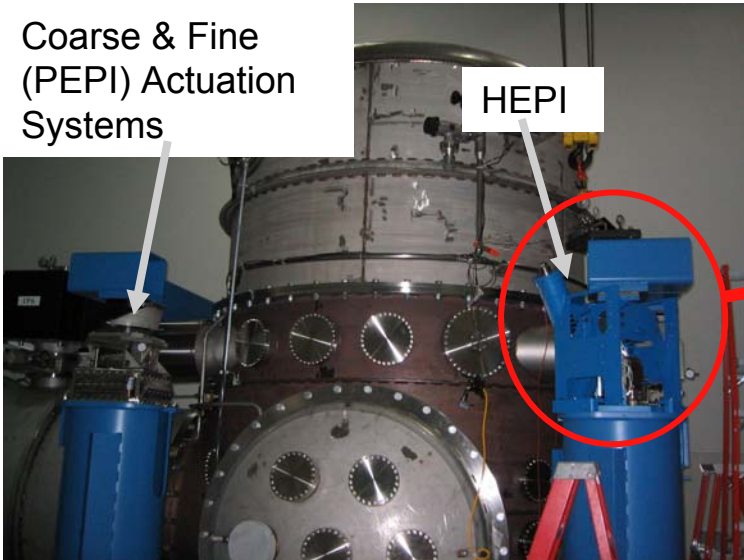
SEI Technology Demonstrator at the Stanford Engineering Test Facility (ETF)



Requirement	HAM Chamber Value	BSC Chamber Value
Payload mass	510 kg	800 kg
Range	$\pm 1 \text{ mm}, \pm 0.5 \text{ mrad}$	$\pm 1 \text{ mm}, \pm 0.5 \text{ mrad}$
Optics table noise	$4 \times 10^{-11} \text{ m}/\sqrt{\text{Hz}}$ (@10 Hz)	$3 \times 10^{-13} \text{ m}/\sqrt{\text{Hz}}$ (@10 Hz)
Angular noise	100 nrad RMS	10 nrad RMS

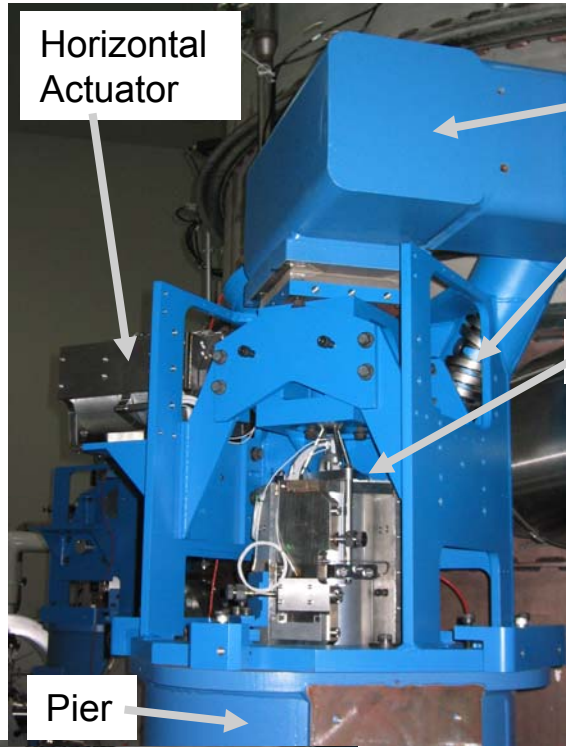
Seismic Isolation, HEPI Subsystem Installation at LIGO Livingston Observatory

Coarse & Fine
(PEPI) Actuation
Systems



HEPI

Horizontal
Actuator

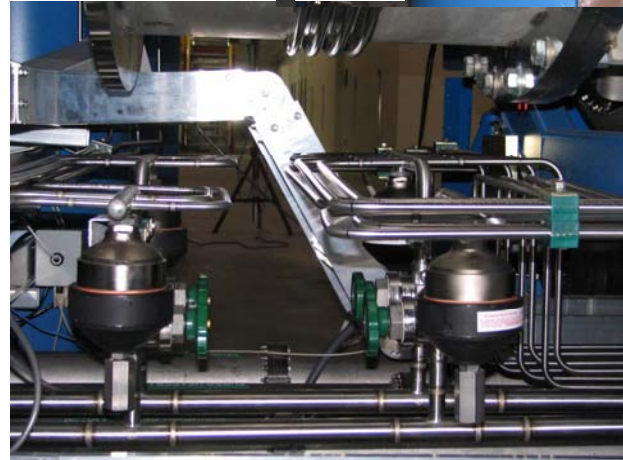


Crossbeam

Helical Spring
(1 of 2)

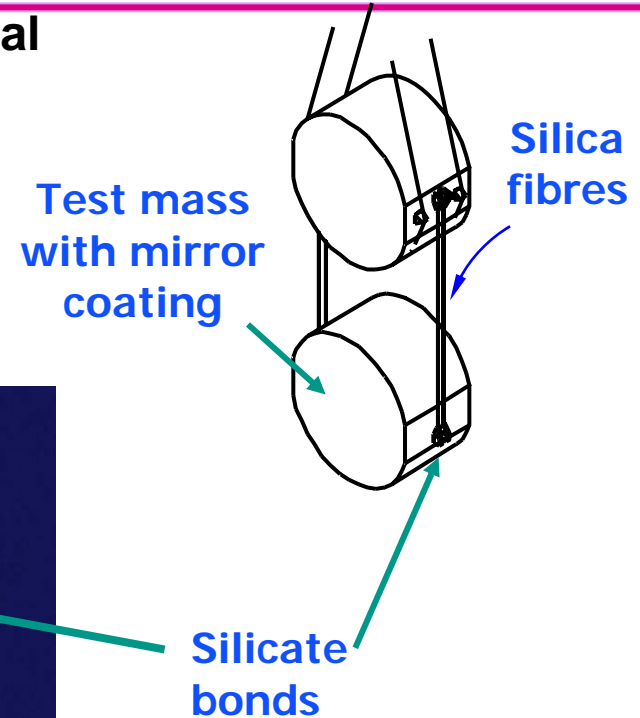
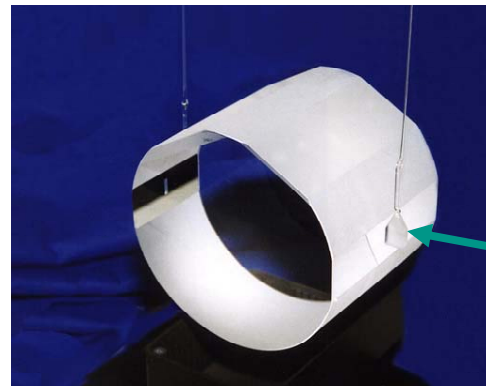
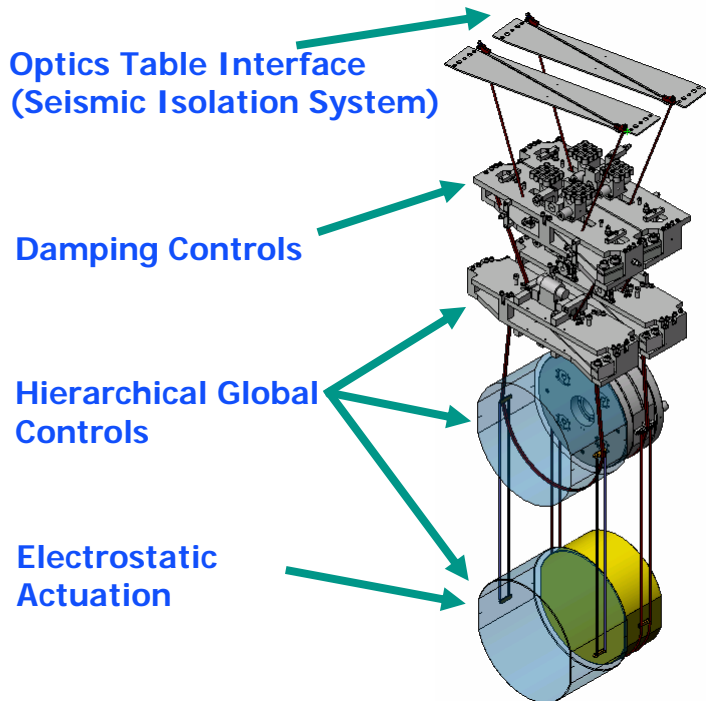
Vertical Actuator

Pier



Thermal Noise Suppression Suspension Subsystem (SUS) Design

- Minimize noise from damping controls and global control actuation
- Minimise thermal noise from pendulum modes
 - » Thermally induced motion of the test masses sets the sensitivity limit in the range $\sim 10 - 100$ Hz
 - » Required noise level at each of the main optics is 10^{-19} m/ $\sqrt{\text{Hz}}$ at 10 Hz, falling off at higher frequencies



- Choose **quadruple** pendulum suspensions for the main optics and **triple** pendulum suspensions for less critical cavity optics
- Create quasi-monolithic pendulums using fused silica ribbons to suspend 40 kg test mass

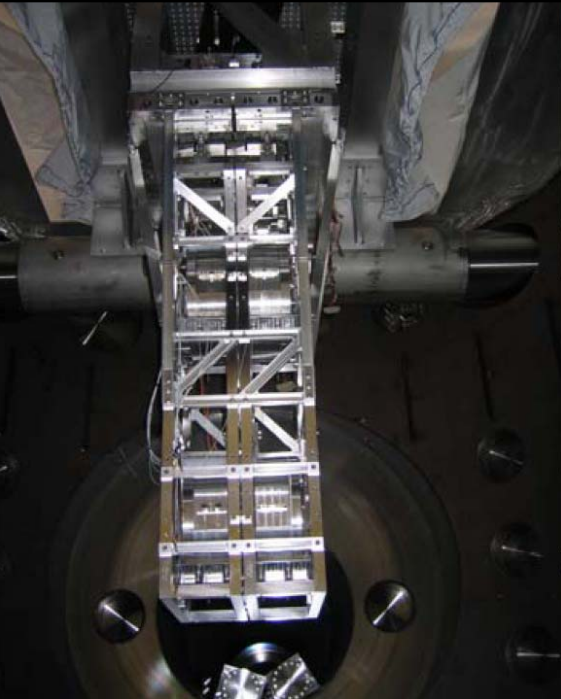
Suspensions Update

(Combined US and UK Effort)

- **Test Mass (Quad) Suspension**

- » ‘Controls’ Prototype installed at LASTI & under Test
- » Preliminary Results in June for Concurrent “Noise” Prototype Development
- » The UK Group delivers the “Noise” Prototype (essentially final design) in early 2007

Quad Suspension in LASTI BSC Chamber



Triple Suspension in LASTI HAM Chamber



- **Mode Cleaner (Triple) Suspension**

- » LASTI Testing of controls prototype completed
- » Performance as expected
- » Model-measurement comparison caught some model shortcomings & an as-built difference
- » Final “Noise” Prototype is next

- **Other suspensions (extensions of existing designs):**

- **Recycling mirror (triple) –full design**
- **Beamsplitter (triple) –conceptual design**
- **Folding Mirror (triple) –conceptual design**
- **Output mode cleaner (double) –conceptual design underway**
- **Mode matching telescopes, steering mirrors etc (single) –**
modified LIGO 1 suspensions

- **Silica Fiber/Ribbon Pulling**

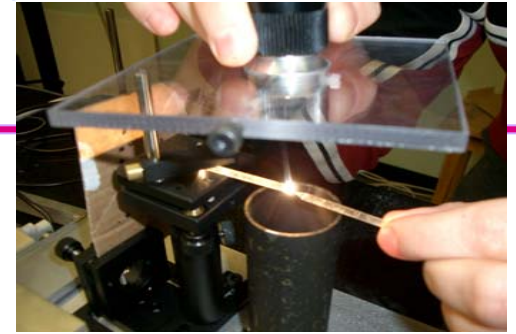
- » R&D on computer controlled CO₂ laser system proceeding well
- » Fibers up to 570 mm long, 184 ± 5 microns diameter (15 microns dia. repeatability)
- » 3 GPa breaking stress (factor of safety ≈ 4)

- **Fiber/Ribbon Welding**

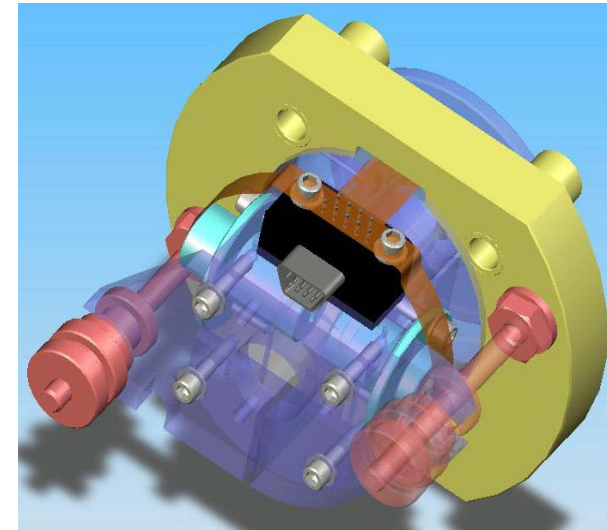
- » Fiber & ribbon welding demonstrated
- » Working to improve welded strength

- **Electronics**

- » Improved Optical Sensing & Electro-Magnetic actuator (OSEM) assembly
- » New Control & Data Systems (CDS), Bus & Network Topology at LASTI implemented to support Seismic & Suspension Prototype Testing



Welding 3mm silica rod with 9W CO₂ laser

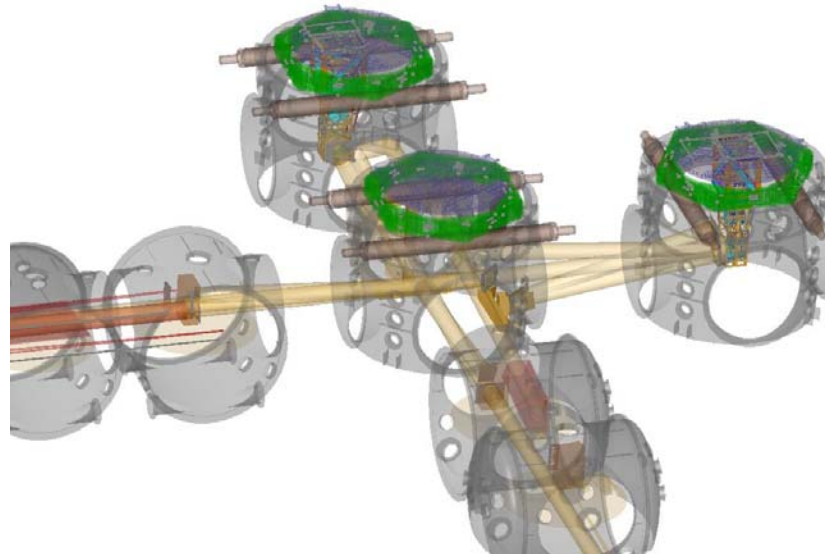


Modified Hybrid
OSEM Design

- **Systems Engineering is Level-Of-Effort in the Construction Phase**
- **Maintain Interface Control Documentation (ICD)**
- **Continue Modeling/Simulation**
- **Maintain technical configuration management**
- **Define integrated test plans & procedures**
- **Review/Approve Subsystem acceptance test plans, test reports, EMI/EMC & grounding implementation, ...**

•3D, Integrated Opto-mechanical layout captured in SolidWorks CAD

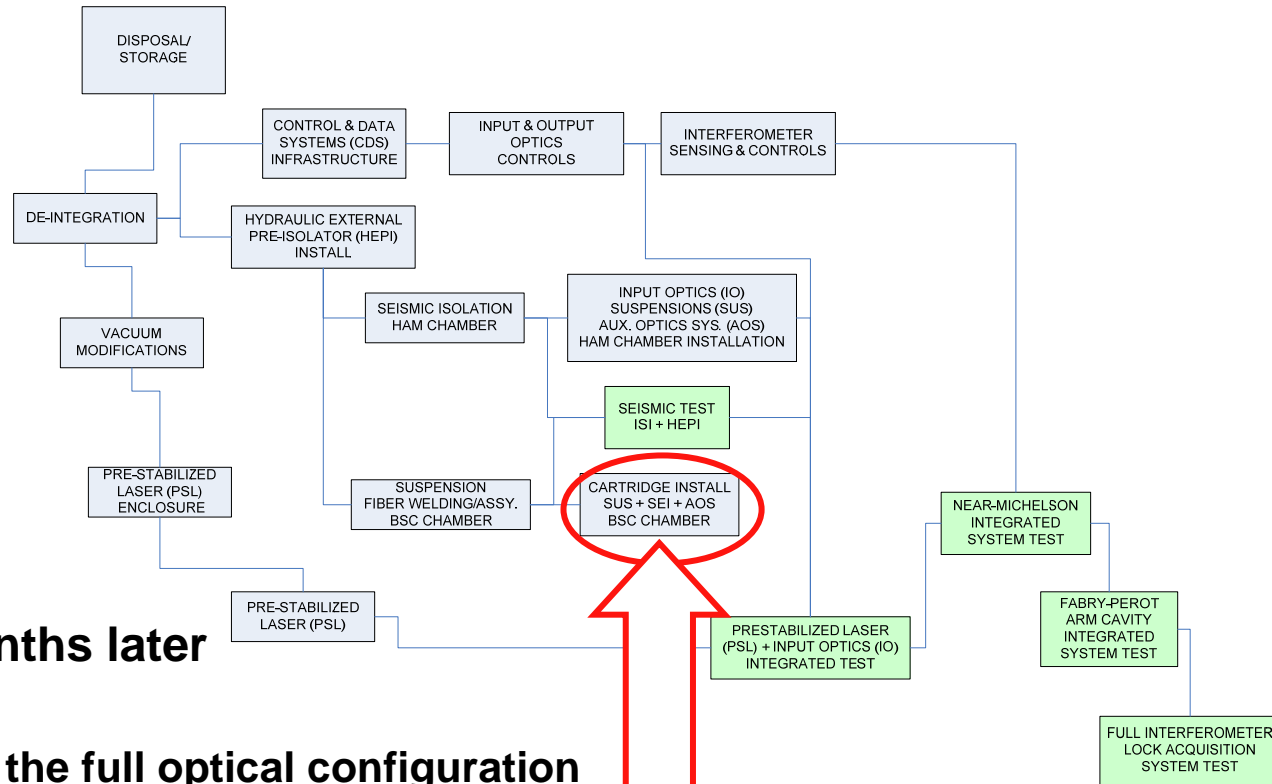
•Optical layout defined with Zemax



- **Plan for Installation, Logistics and Staging**
- **Procure new Vacuum System components**
 - » 2K to 4K conversion
 - » large diameter mode cleaner tubes
 - » Relocation of 2 HAM chambers for each interferometer
- **Procure more class 100 clean room space for assembly and installation**
- **Provide assembly workspace and storage**
- **Procure installation fixtures and tooling**
- **Refurbish existing optics lab space, purchase bake oven, cleaning supplies**

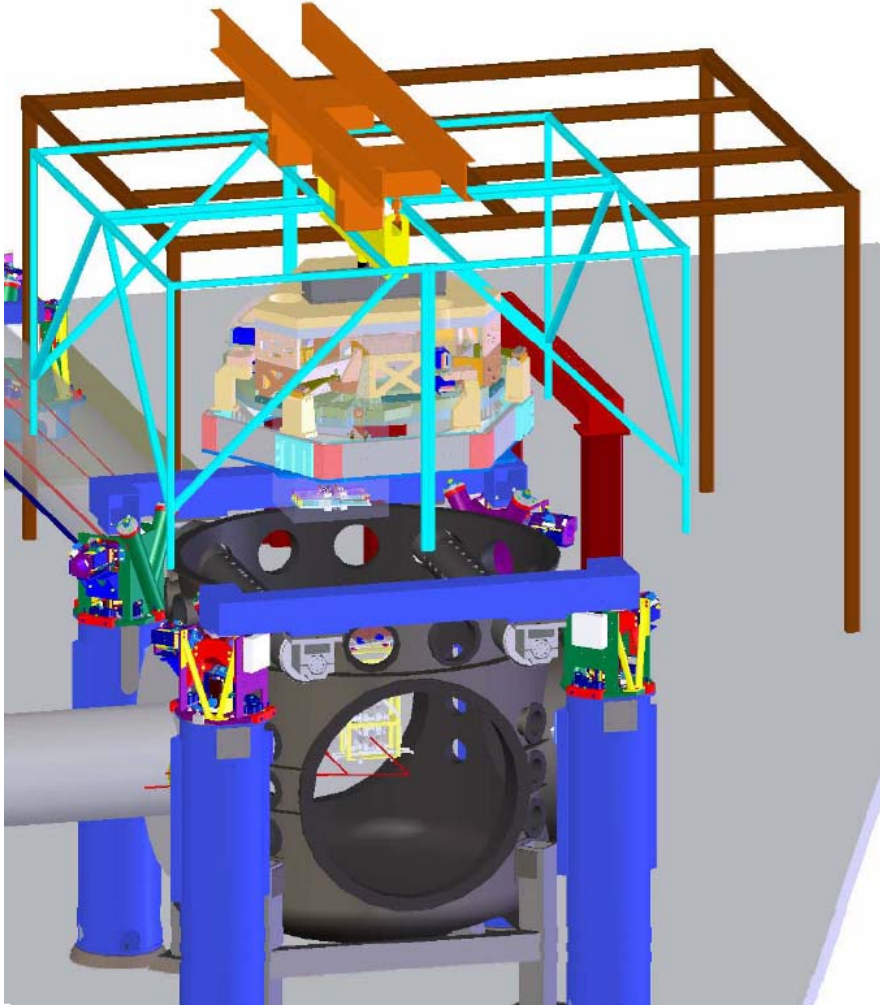
- **Basic Task Sequence per Interferometer:**

- » Removal
- » Vacuum Equipment & Infrastructure Modifications
- » Installation
- » Testing



- **Start at Livingston**
- **Hanford starts ~9 months later**
- **Duration is ~3 years**
 - » **Multi-hour “lock” in the full optical configuration for all 3 interferometers**
 - » **Transition to operations as Subsystems and Interferometers are Accepted**

**@LASTI
next page**



Advanced LIGO Subsystem Descriptions

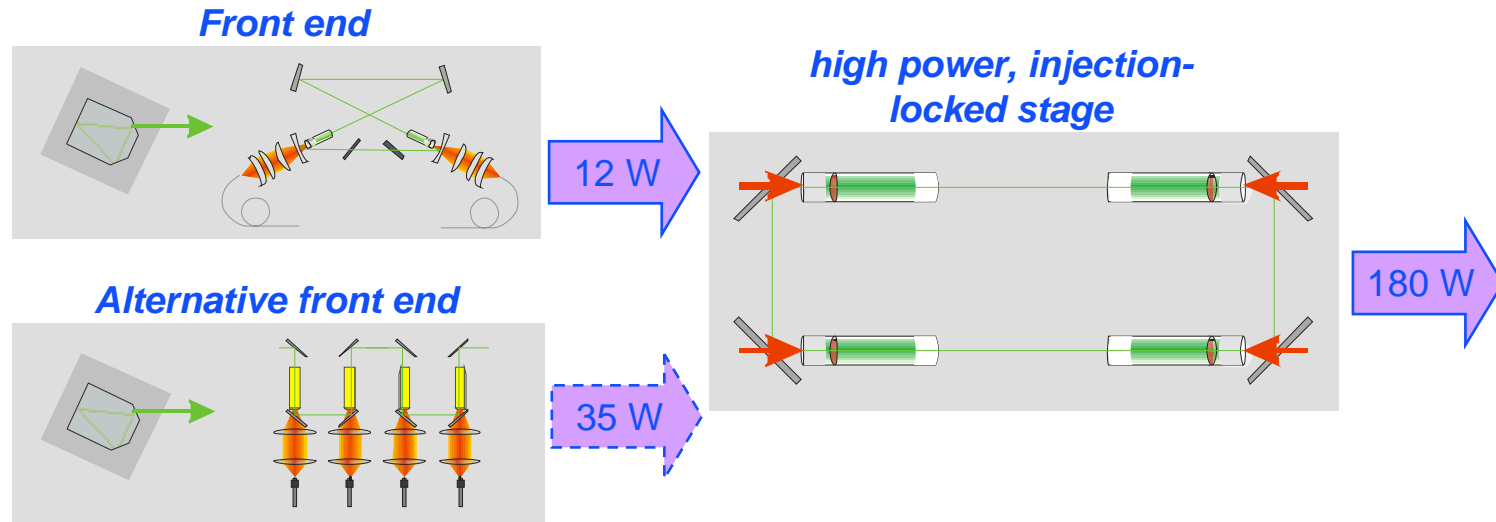
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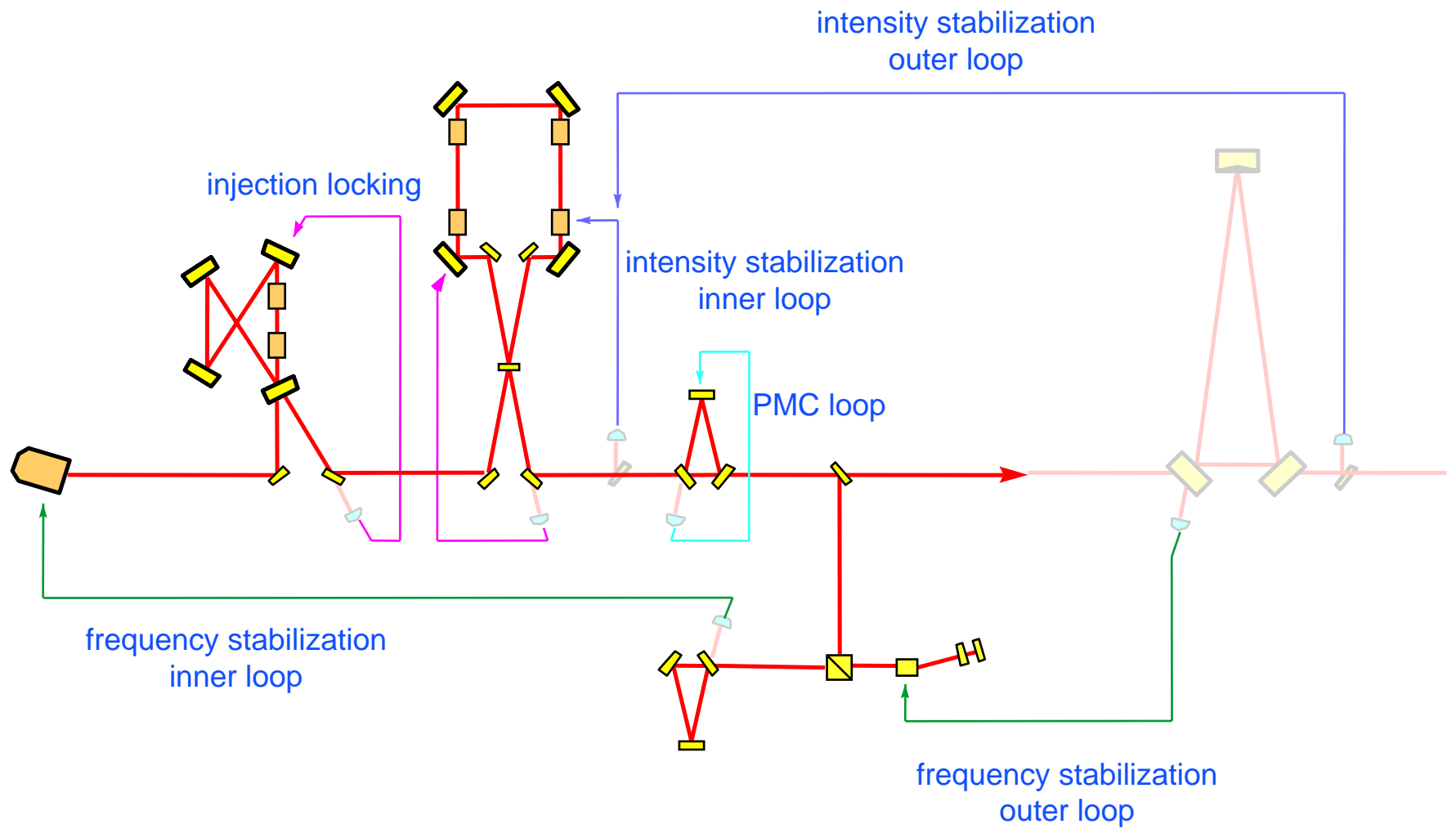
Pre-stabilized laser (PSL)

- High power laser: 180 Watts

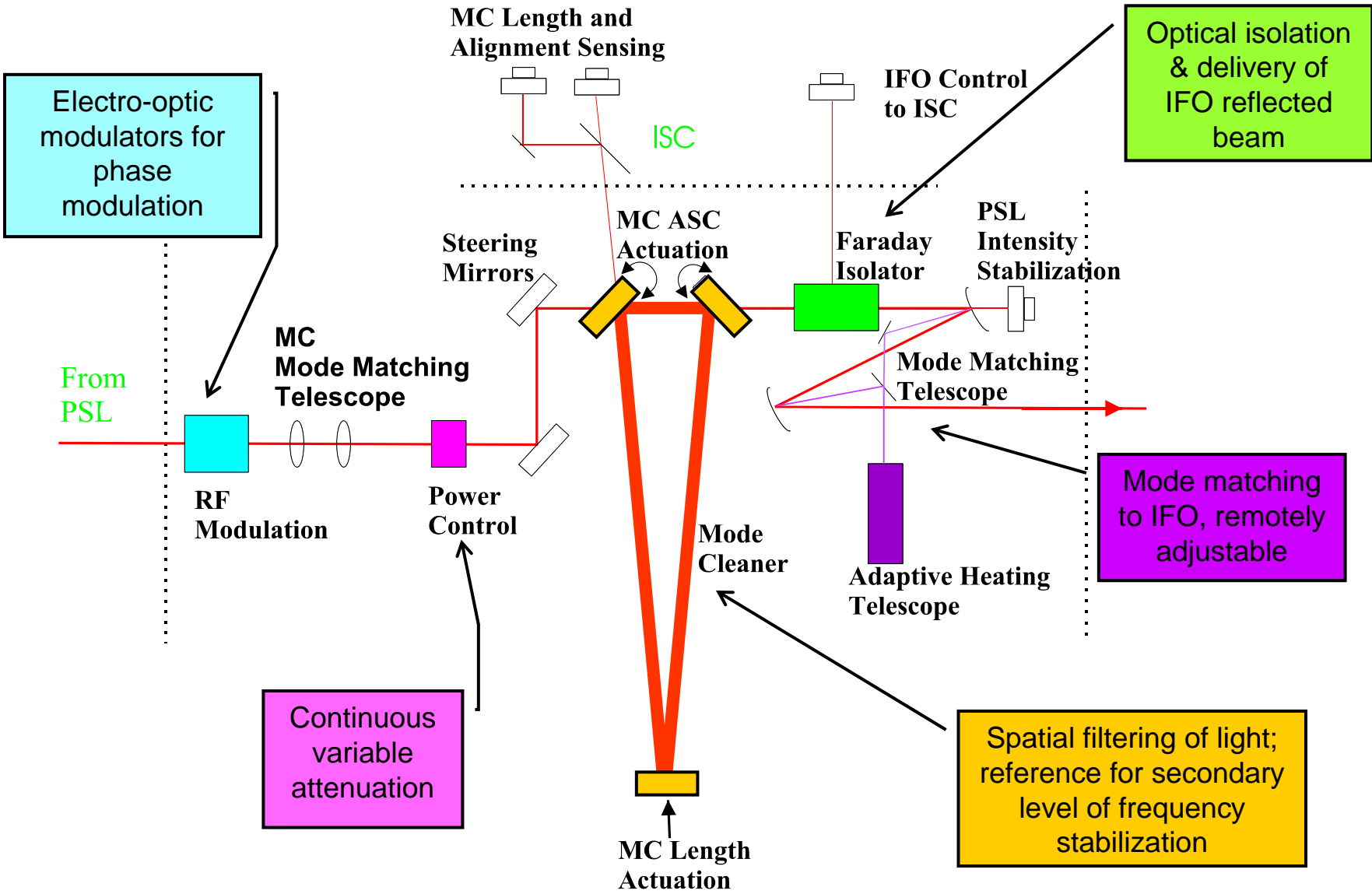


- Laser power stabilization
- Laser frequency pre-stabilization
 - » Wideband frequency actuation for further stabilization
- Pre-mode cleaner for spatial clean-up and high-frequency filtering
- Diagnostic tools
- Laser safety measures

PSL: stabilization systems

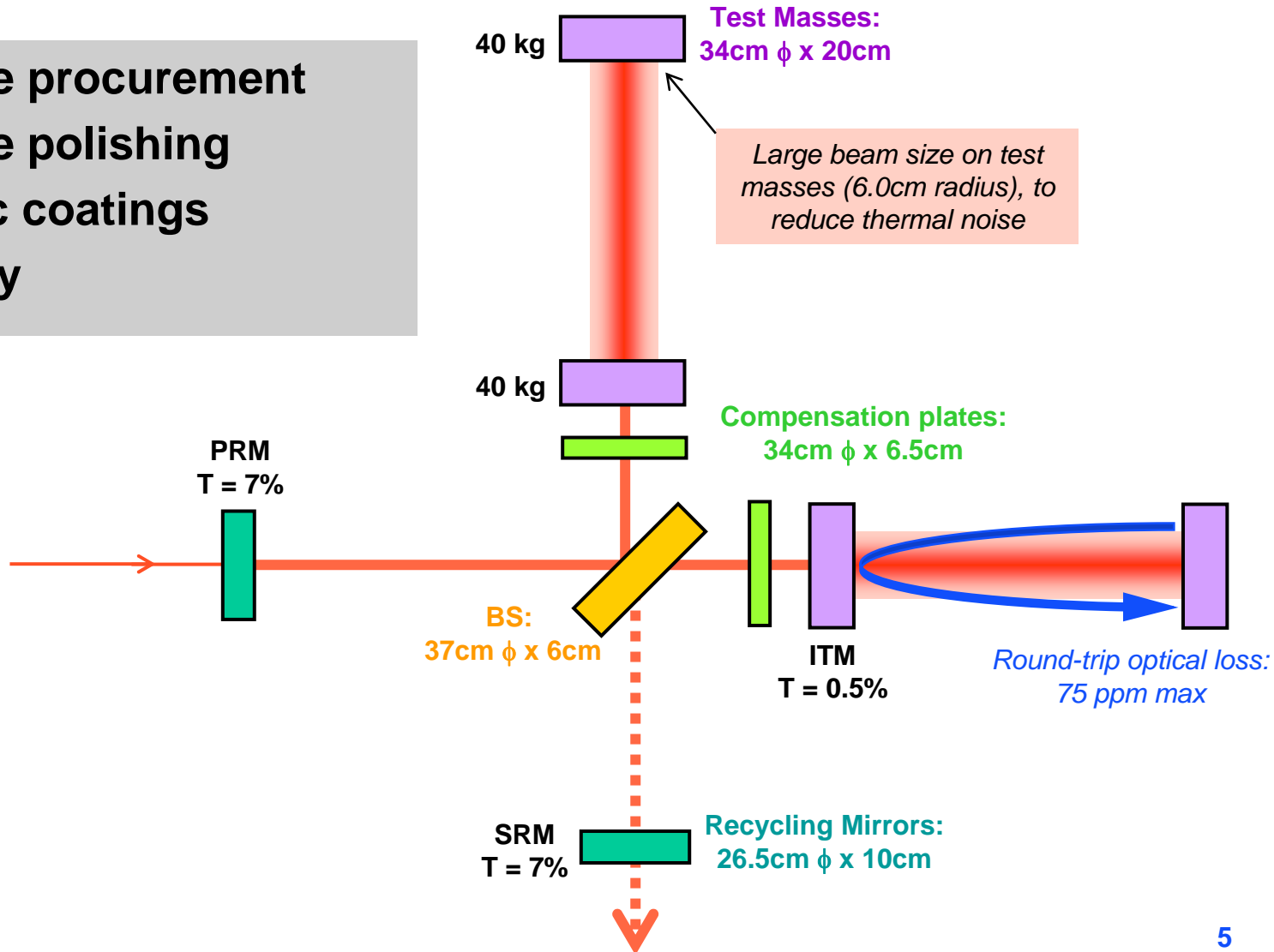


Input Optics



Core Optics Components

- Substrate procurement
- Substrate polishing
- Dielectric coatings
- Metrology



Core Optics Components

- **Substrates**
 - » Fused silica: Heraeus (for low absorption) or Corning
 - » Specific grade and absorption depends on optics
 - » ITMs and BS most critical (need low absorption and good homogeneity)
- **Polishing**
 - » Low micro-roughness (< 1 angstrom-rms)
 - » Low residual figure distortion (< 1 nm-rms over central 120mm diameter)
 - » Accurate matching of radii-of-curvature
 - » Surfaces for attachment of suspension fibers
- **Dielectric coatings**
 - » Low absorption (0.5 ppm or smaller)
 - » Low scatter
 - » Low mechanical loss ($< 2e-4$)
- **In-house Metrology**
 - » ROC, figure distortion, scattering, absorption

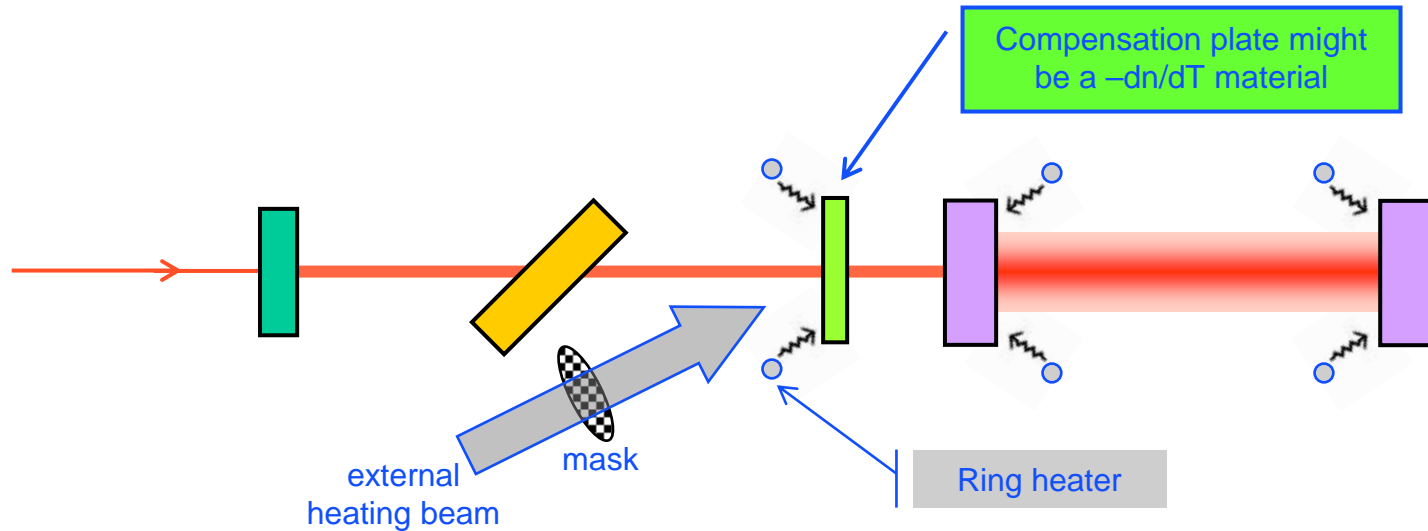
Auxiliary Optics Subsystem (AOS)

- **Initial Alignment System**
 - » Surveying support for proper installation of components
- **Photon calibrators**
 - » Calibration tool using photon pressure of a modulated laser beam
- **Viewports**
 - » For beams entering and exiting vacuum
- **Optical levers**
 - » Orientation monitors of each suspended optic, relative to the floor
- **In-vacuum stray light control**
 - » Baffles and beam dumps for diffuse scattering and ghost beams
- **Beam reducing telescopes**
 - » For pick-off beams and the output beam
- **Thermal compensation system**
 - » Senses thermal distortions of core optics and corrects by adding compensating heat

Thermal compensation system

Absorption and thermal lensing at high power operation

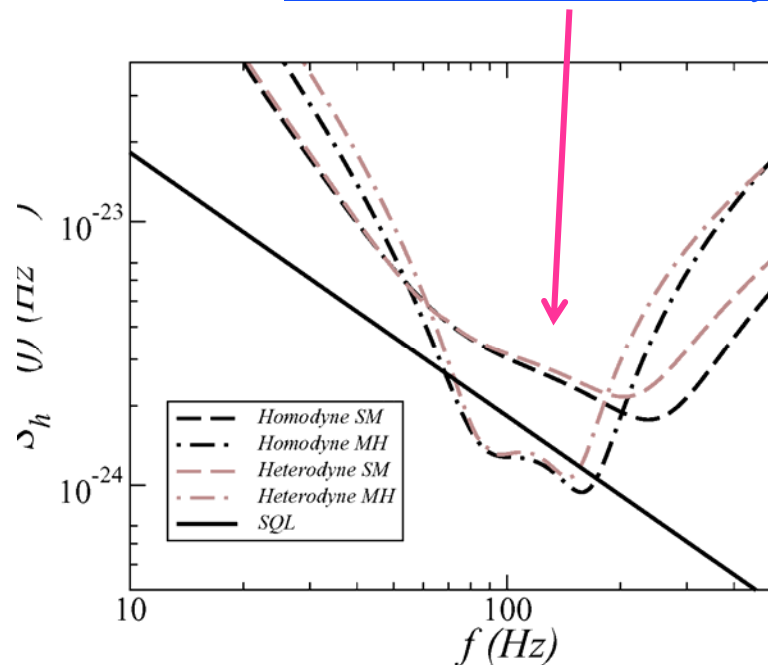
Optic	Substrate			Surface		
	Power	absorbed power	Induced lens	Power	absorbed power	Induced lens
ITM	1 kW	120 mW	$(6.8 \text{ km})^{-1}$	800 kW	400 mW	$(100 \text{ km})^{-1}$
ETM				800 kW	400 mW	$(100 \text{ km})^{-1}$



- **Specifies input beam modulation scheme to:**
 - » Sense the global interferometer lengths
 - » Sense the global interferometer mirror angles
- **Detection tables for all sensed beams**
 - » Opto-mechanical hardware, photodetectors
 - » All beams involved in critical control loops will be detected in-vacuum, on vibrationally isolated tables
- **Digital controls hardware and software for all length and alignment controls**
 - » Including data conversion
- **Lock acquisition of the interferometer**
- **Readout of the gravitational wave channel**

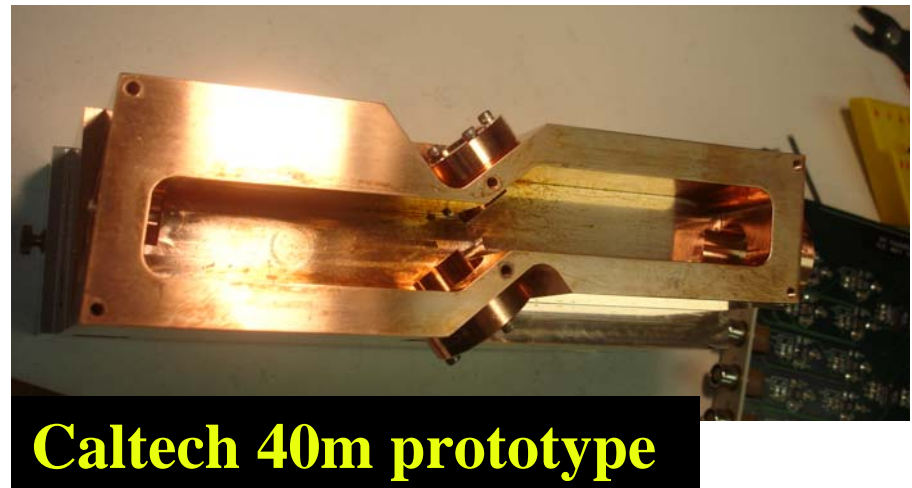
ISC: DC detection & output mode cleaner

- **DC (homodyne) detection: decided in favor of in 2003**
 - » Interferometer is offset from the dark fringe (1-10 pm), and the resulting DC carrier field is used as the local oscillator for detecting the GW signal
 - » Less sensitive to input beam noise than RF (heterodyne) detection
 - » Quantum noise sensitivity as good as or better than RF detection



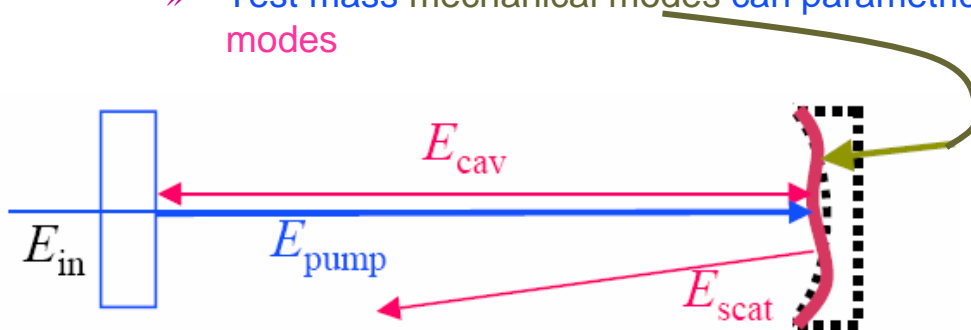
- **Output mode cleaner**

- » Needed to reject higher-order mode light at the output
- » Rejects RF sideband power for DC detection



Caltech 40m prototype

- **Unstable optical spring when the SRC is detuned**
 - » ISC length control system will provide wideband feedback (~200 Hz) to stabilize (unstable mode at 50-60 Hz for nominal tuning)
- **Angular instability due to radiation torque**
 - » Led to choice of negative g-parameters for cavities: $1 - L/R = -0.93$
 - » Feedback stabilization provided by ISC alignment controls: challenge is to provide enough feedback to stabilize, without introducing noise
- **Parametric instabilities**
 - » Test mass mechanical modes can parametrically pump energy into higher-order cavity modes



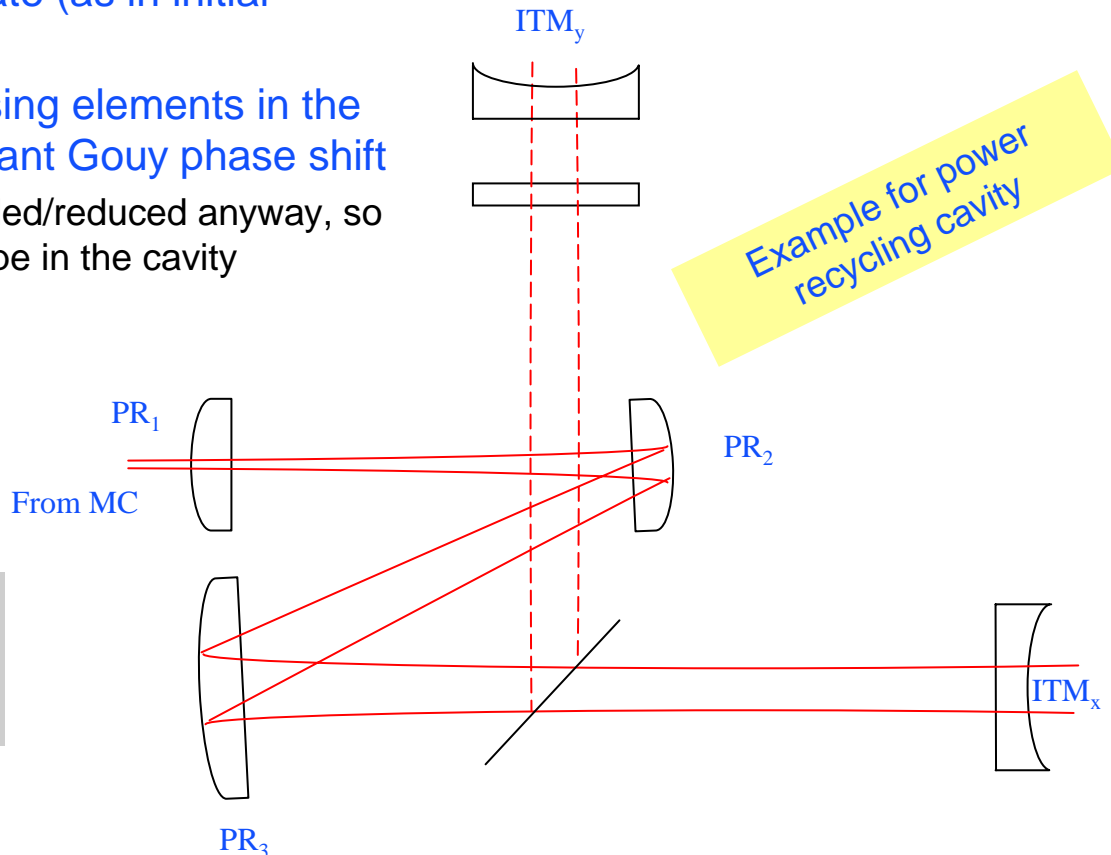
Mitigation options:

- reduce Q of mechanical modes by selective application of lossy material
- increase cavity mode loss by tuning coating aperture, and/or ITM transmission
- fine tune the cavity mode spectrum using the TCS actuation of ROCs, to avoid critical modes

- » Modeling of the phenomenon is being further refined (Braginsky, UWA, CIT)
- » Currently ~10 modes predicted to be unstable at full power

- **Configuration of recycling cavities**

- » Current design: Gouy phase shift in the RCs is very small; RCs are at the edge of stability, and thus rather degenerate (as in initial LIGO)
- » Alternative: include focusing elements in the RCs to achieve a significant Gouy phase shift
 - beam has to be expanded/reduced anyway, so just include the telescope in the cavity



Stable configuration appears to have many advantages, and is being carefully studied

- **Concept:**

- » form a 'simple', relatively low-sensitivity interferometer between the ITM & ETM platforms
- » Use it to stabilize the 4km arm lengths at low frequencies (below a few Hertz)

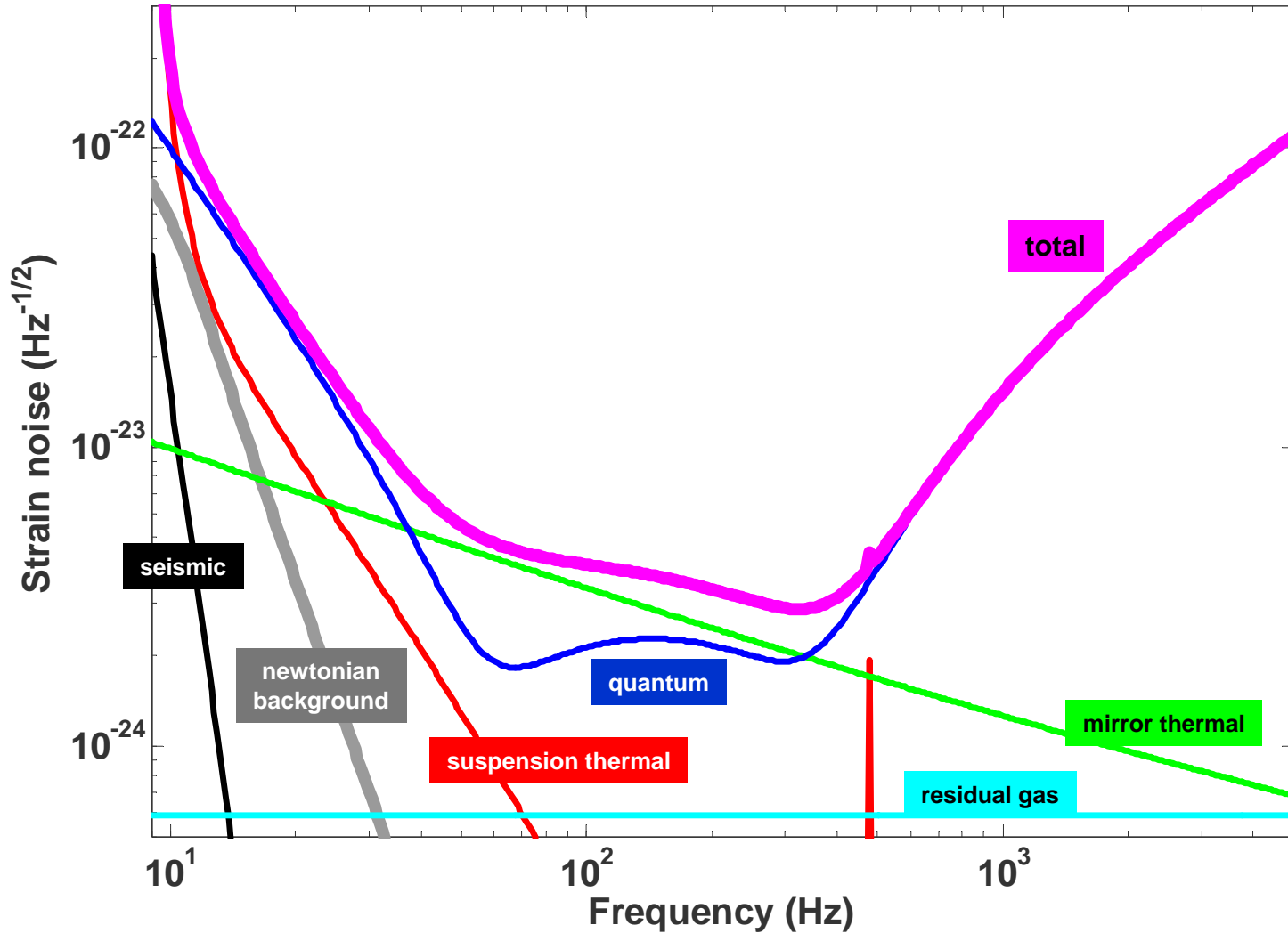
- **Motivation:**

- » Arm length fluctuations are dominated by low frequency motions, $f < 0.5$ Hz; motion in this band (~100 nm-rms) not expected to be much lower than in initial LIGO (@LLO, w/ HEPI)
- » Reducing this rms by another factor of 10-100x could:
 - Make lock acquisition much simpler
 - Enable lock acquisition during times of high micro-seism
 - Possibly beneficial during interferometer operation as well

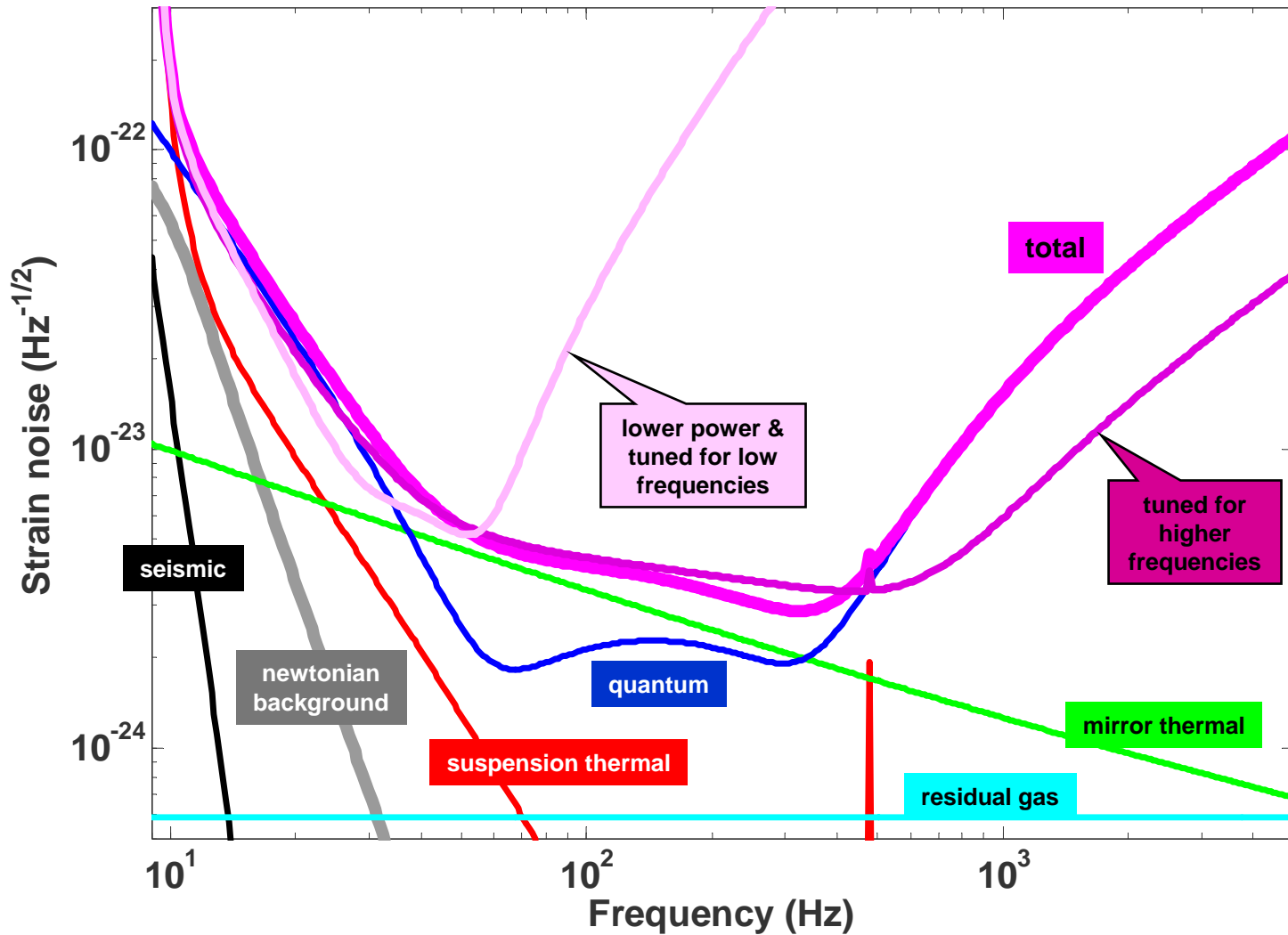
- **Status:**

- » Schemes for implementing an SPI are being considered
- » Falls in the domain of the ISC subsystem, if implemented

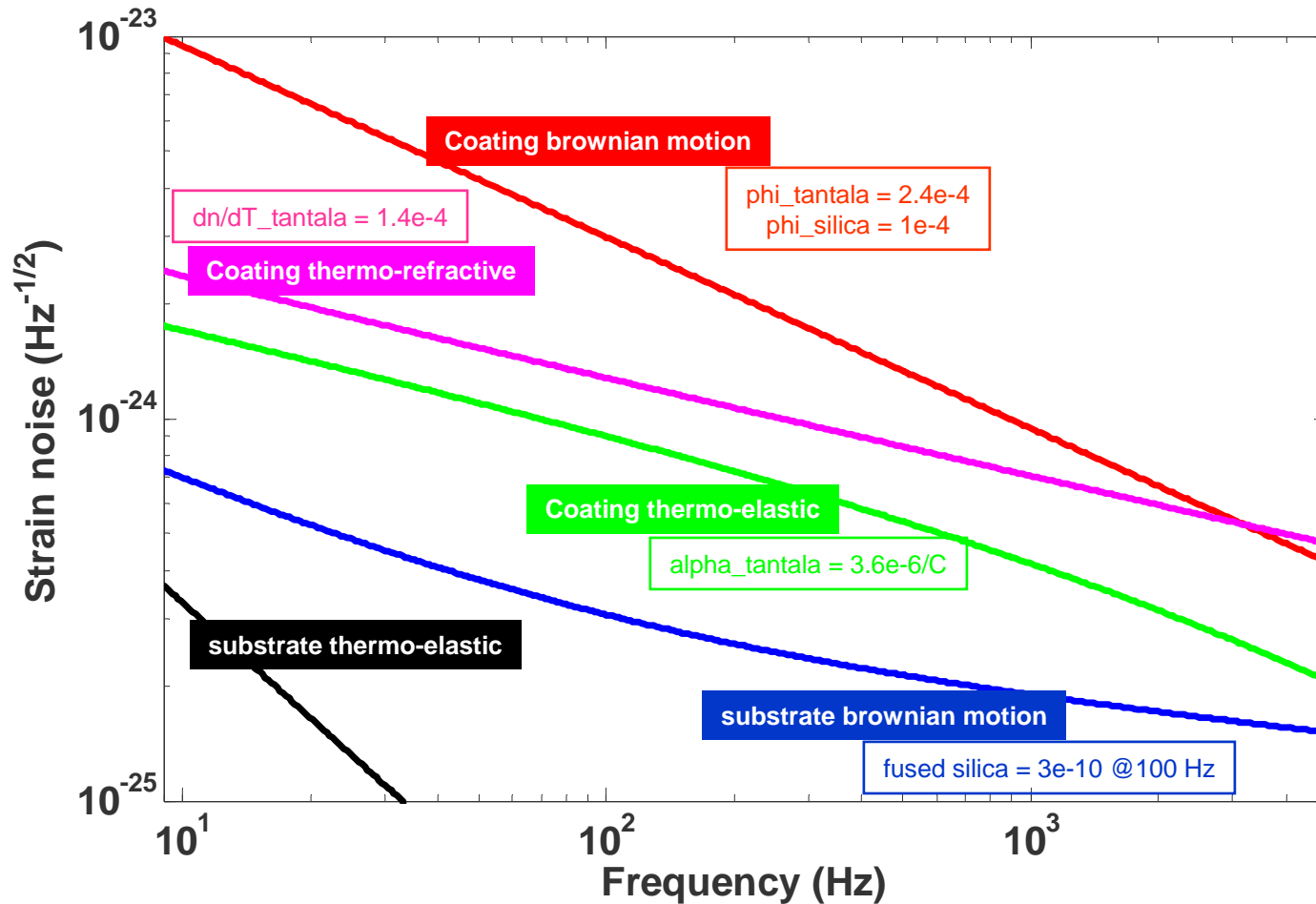
Interferometer performance estimate



Interferometer performance estimate



Mirror thermal noise contributors



- **Two major LIGO prototype test facilities:**

- » **LIGO Advanced System Test Interferometer (LASTI) @MIT** – full scale tests of :
 - seismic isolation
 - suspensions, laser
 - mode cleaner
- » **40m Interferometer @Caltech**
 - Sensing/controls tests of readout
 - Lock acquisition
 - Engineering model for data acquisition, software

- **Support from LSC testbeds**

- » **Gingin Facility @Gingin, Australia** – high power cavity, for:
 - Thermal compensation: sensors and actuators
 - Parametric instabilities
- » **10m Interferometer @U of Glasgow** – readout
- » **Engineering Test Facility (ETF) @Stanford** – seismic isolation
- » **GEO600 @Hanover, Germany** – much more than a prototype! (test of the quasi-monolithic fused silica suspension)

- **Initial & enhanced LIGO**

- » Hydraulic External Pre-Isolator (HEPI)
- » Thermal Compensation System
- » High power modulators & isolators
- » Output mode cleaner & DC readout

LASTI (Triple Suspension in a HAM Chamber)



Gingin Facility



40 M Lab