

Adv. LIGO Arm Length Stabilisation



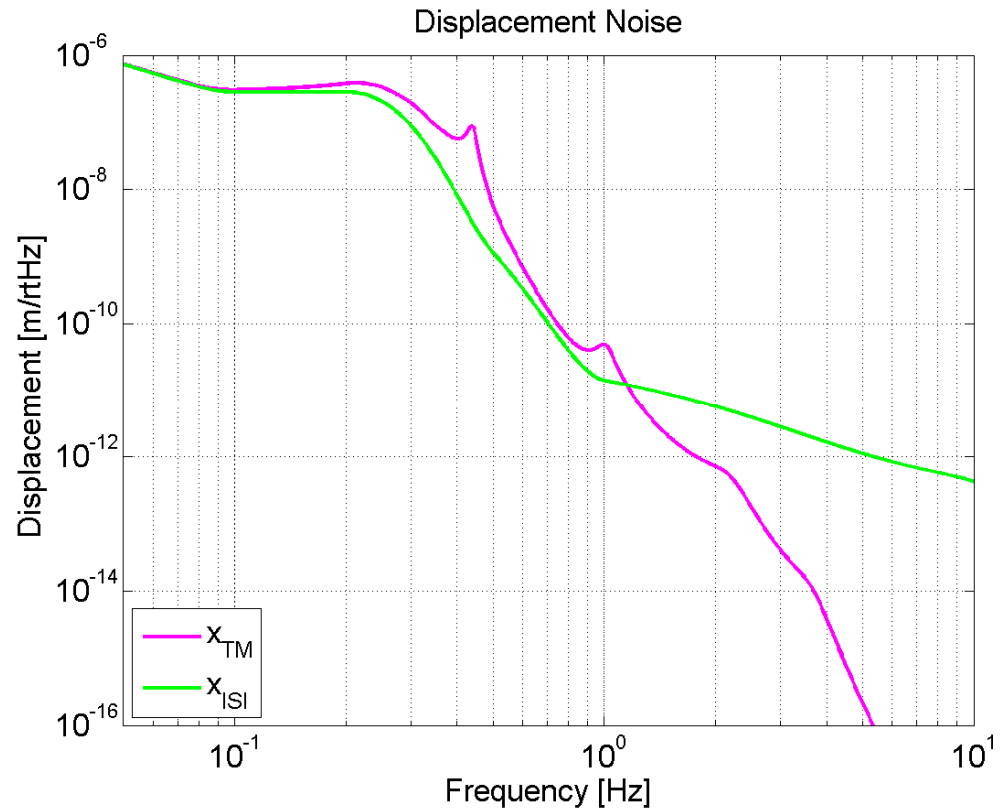
Bram Slagmolen, Adam Mullavey, David Rabeling,
Daniel Shaddock, David McClelland
The Australian National University

Matt Evans, Peter Fritschel
LIGO-MIT

Rana Adhikari, Yoichi Aso
LIGO-Caltech

Adv LIGO Arm Cavity Lock Acquisition Challenges

- IFO acquisition procedure
 - Stabilise the arm cavity length, with offset wrt. PSL(preventing swinging through resonance).
 - Bring recycling cavities into resonance (central IFO).
 - Reduce arm cavity offset, to bring arm cavities on resonant with PSL.
- Stabilise the arm cavity length fluctuations to within arm cavity linewidth (equivalent ~ 1 nm).
 - The test mass motion below 0.5 Hz is $\sim 0.1 \mu\text{m}/\text{rtHz}$.



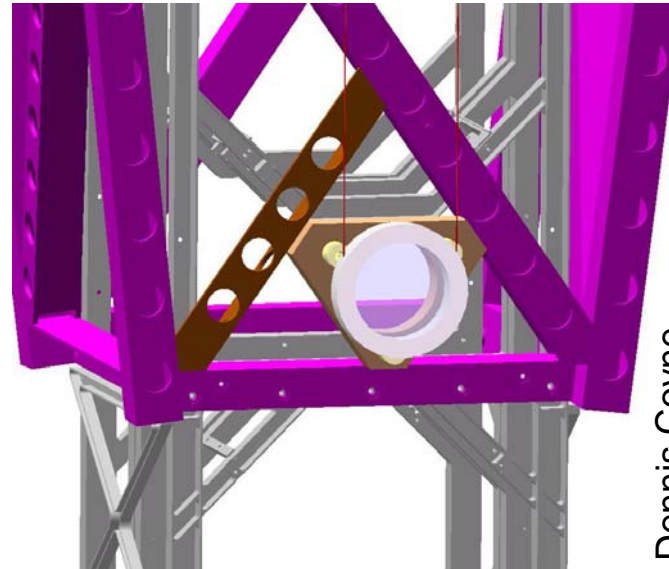
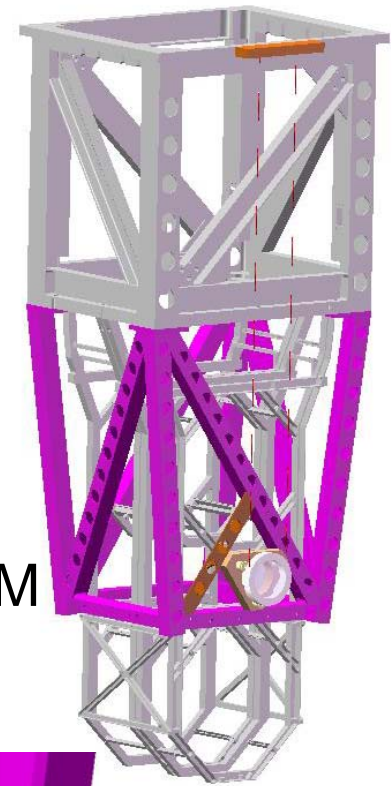


Possible Implementations

- Suspension Point Interferometer
 - Sensing motion of the Quad suspension point (ISI Platform).
 - Feedback to the Quad suspension point.
- Standard PDH reflection locking
 - Auxiliary cavity between the the masses.
 - Using 532nm laser.
 - Injection from the end-station or the corner-station.
- Digital Interferometry
 - Auxiliary sensing between the test masses using, digital interferometry.
 - Injection from the corner-station or the end-station.

Suspension Point Interferometer

- Make a second suspended cavity between the BSC ISI platform (is the Quad suspension point).
- The SPI Mirrors are lowered to be between the PM and the TM.
- The SPI Mirrors have independent actuators.
- Main feedback is to the ISI Platform.
- SPI has been discussed, and I will focus on the baseline and fallback options.



Dennis Coyne

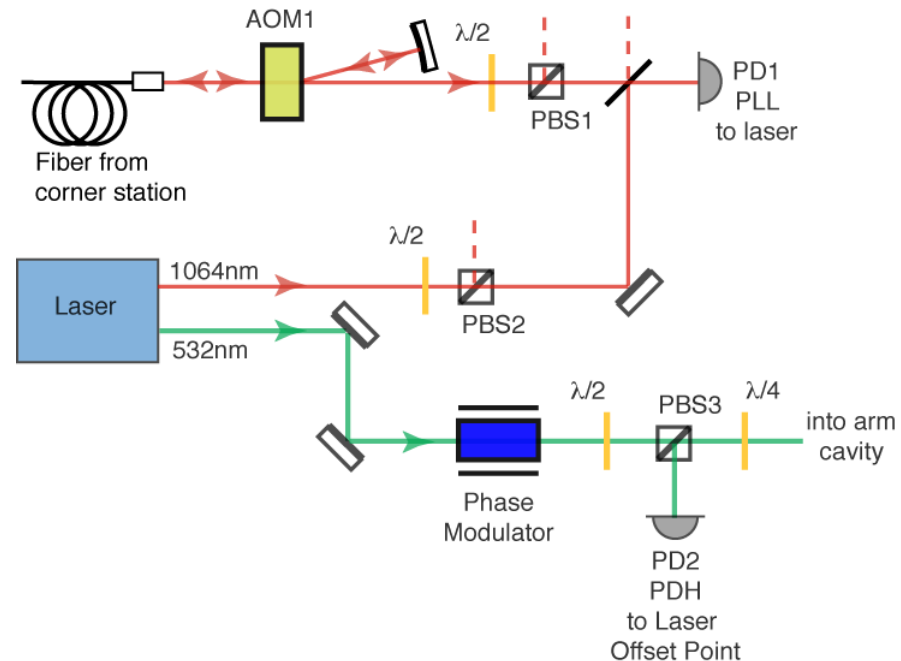


PDH from the End-Station

- Set up a cavity between the test masses, inject from the End-Station.
 - Use 532 nm laser, this to prevent the arm cavity resonance to interact with the recycling cavities during lock acquisition.
- Use the widely used PDH technique to obtain a feedback error signal.
- To acquire lock, feedback to a frequency actuator (effectively the 532 nm laser).
 - Once locked, hand-over to the Quad-suspension actuation (PM/TM).
 - Reduce the relative test mass motion to ~ 1 nm rms.

PDH Injection

- Use a 1064/532 nm laser.
 - 1064 nm output phase lock to the PSL.
 - 532 nm for the PDH injection.
- Readout of a low finesse cavity in the arms.





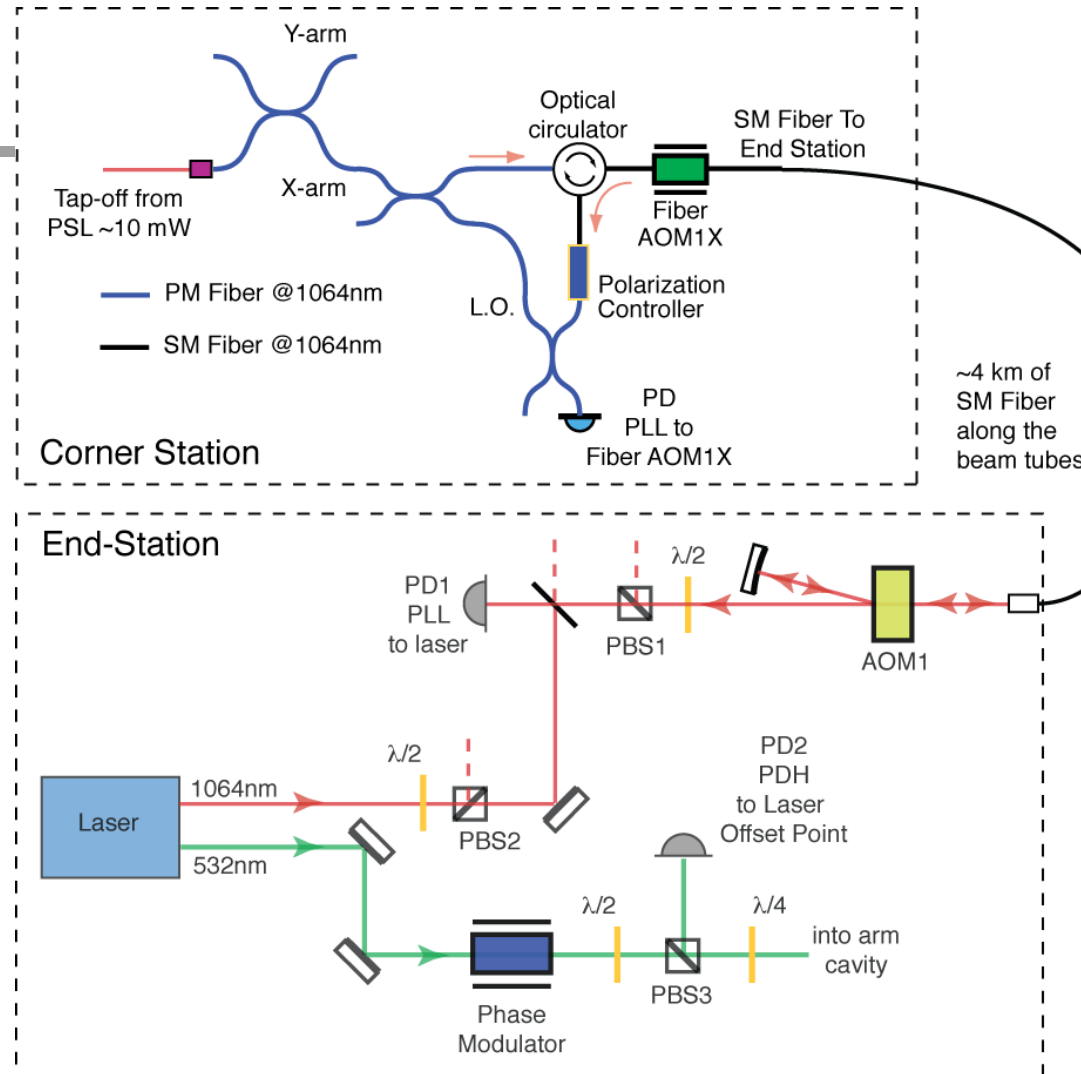
ETM Coating Modification

- The HR coating on the test masses are slightly modified.
 - In addition to being low loss and HR for 1064 nm, the layer thicknesses are adjusted to create a controlled reflectivity at 532 nm.
 - The 532nm reflectivity is set to create a cavity finesse of ~30.
- Possible coating transmission (modeled by LMA-Lyon).
 - @1064nm: 4.6 ppm
 - @532nm: 5 %
- Negligible change in coating thermal noise.

QuickTime™ and a
TIFF (LZW) decompressor
are needed to see this picture.

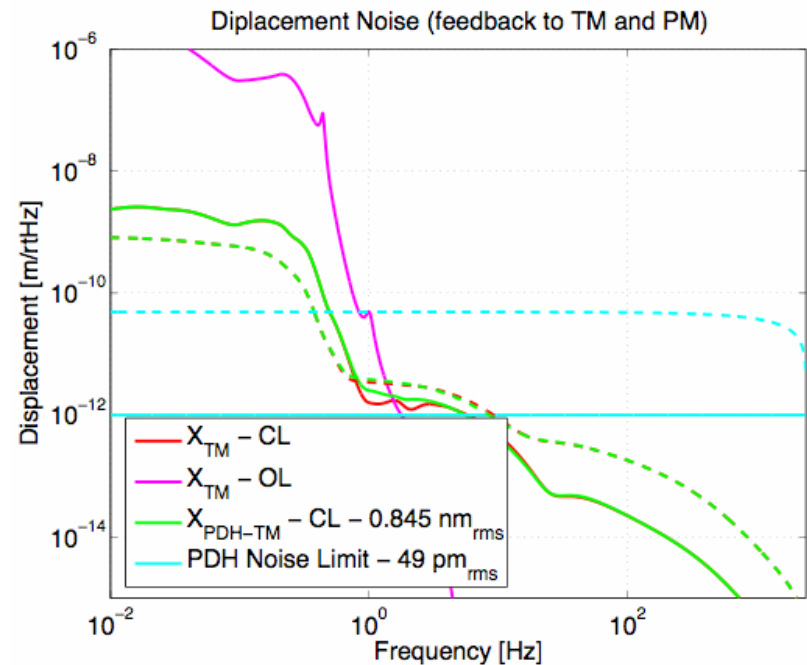
Phase Reference in the End-Station

- Use a tap-off from the PSL to inject into a fiber going to the end-stations.
- Frequency stability requirements
 - $<70 \text{ Hz/rtHz @ 1Hz}$
 - $<0.1 \text{ Hz/rtHz @ 10 Hz}$, not to saturate the Quad actuators.
- Implement a fiber noise cancellation scheme, to suppress the fiber induced phase noise when required.



PDH Performance

- To acquire lock, the laser is locked to the 4km long arm cavity.
- Once locked, the feedback is distributed to the Quad suspension.
 - PDH noise limit ~ 1 pm/rtHz.
 - Set by the fiber stabilisation (< 0.1 Hz/rtHz).
 - May add a reference cavity in the end-station.

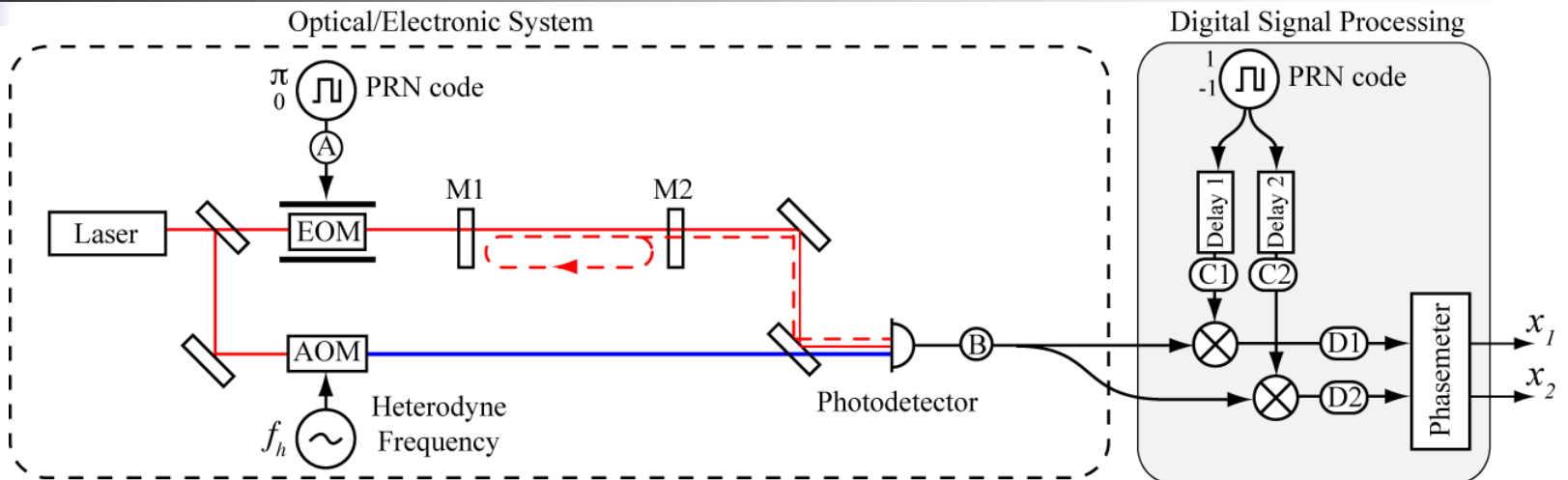




Digital Interferometry¹ - I

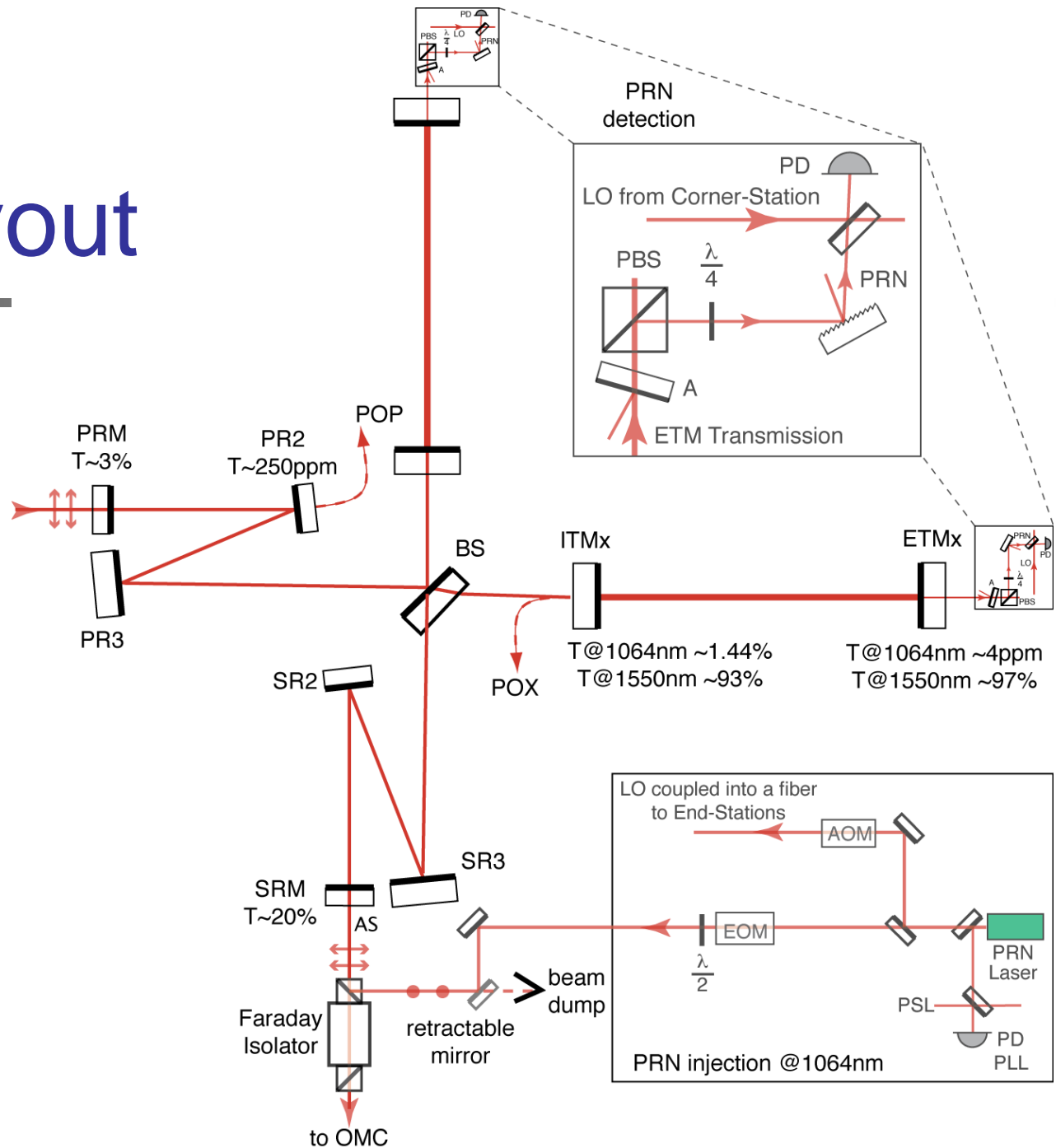
- Using standard heterodyne measurement, isolating individual signals with an ultra-fast waveguide phase modulator.
- The phase modulator provides a pseudo-random noise (PRN) code with a modulation depth of 100% (power spread across ‘all’ frequencies).
- The pseudo-random noise code enables to isolate the reflections depending on time-of-flight.
- The detected signal is demodulated with the PRN code, using the appropriate delay (depending on the time-of-flight), isolating other reflections.
- After demodulation by the PRN code, a standard heterodyne phase measurement is performed.
- The DI readout has picometer sensitivity, with larger dynamic range $\gg 1\mu\text{m}$.

Digital Interferometry - II



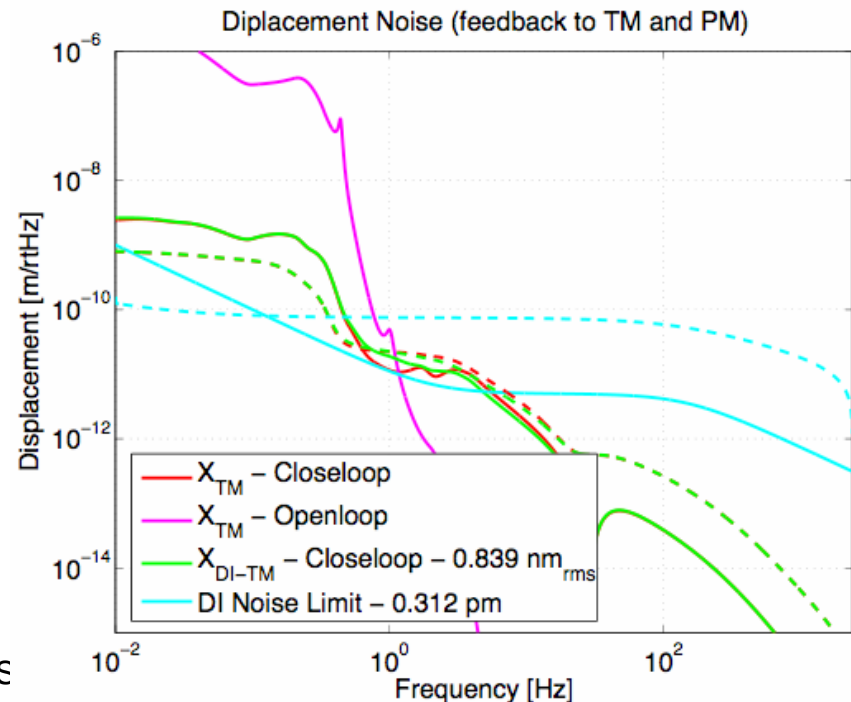
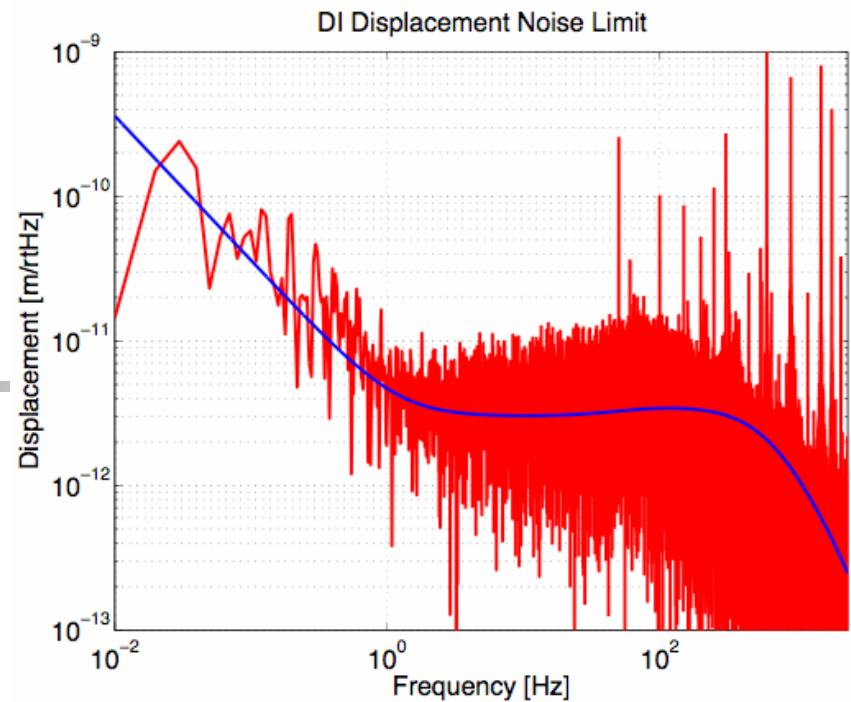
	Decoding delay optimized for M1	Detected first pass signal
Conventional heterodyne		
PRN encoding	(A)	(A)
Detected signal from M1	(B)	(B)
PRN decoding	(C1)	(C2)
Decoded output	(D1)	(D2)

DI Layout



DI Performance

- The DI readout is shot noise limited, while it is performance limited by the phasemeter.
- Displacement noise level is ~ 3 pm/rtHz.
 - Rollup at lower frequencies - > polarisation drift
 - Corner at 100 Hz due to the PDH locking servo.





Conclusion

- The PDH reflection technique is chosen as the baseline.
 - Simple, familiar sensing scheme.
 - Larger signal-to-noise, assuming fiber noise can be suppressed far enough (<0.1 Hz/rtHz @10Hz).
 - 1064 nm/532 nm source preferred, this avoids the need for dual-wavelength reference cavity.
 - Possibility to implement wave-front sensing.
- Further details about injection from the end-station or the corner-station is ongoing.
- In addition, the DI is a fallback technique.
- More details can be found at: http://ilog.ligo-wa.caltech.edu:7285/advligo/Seismic_Platform_Interferometer