

# Advanced LIGO

*the Laser Interferometer  
Gravitational-wave Observatory*

## Development and Status

Brian Lantz, Stanford University  
for the LIGO Scientific Collaboration  
(40+ institutions and hundreds of people...)

SESAPS Nov. 9, 2006

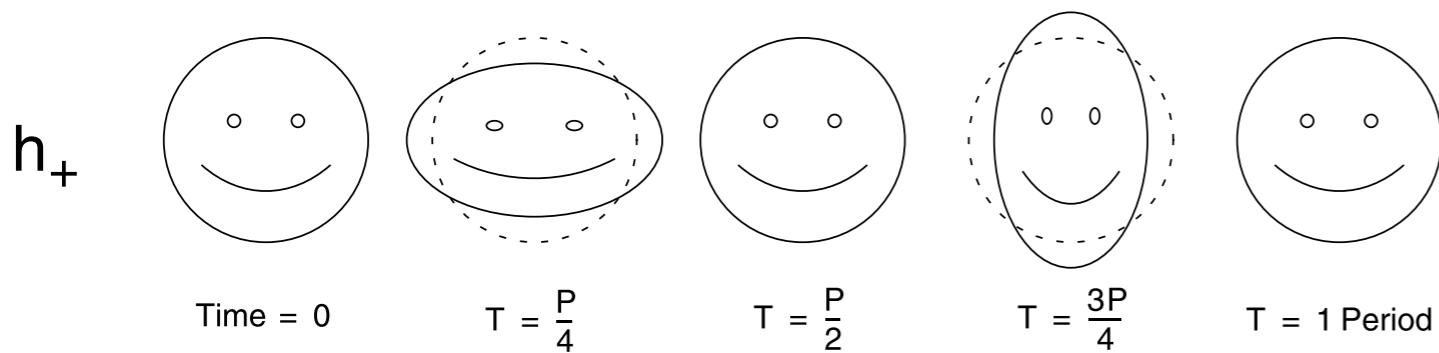
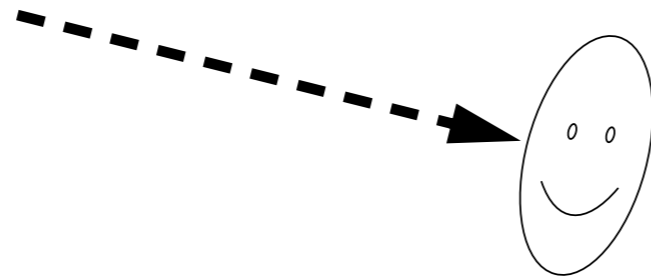
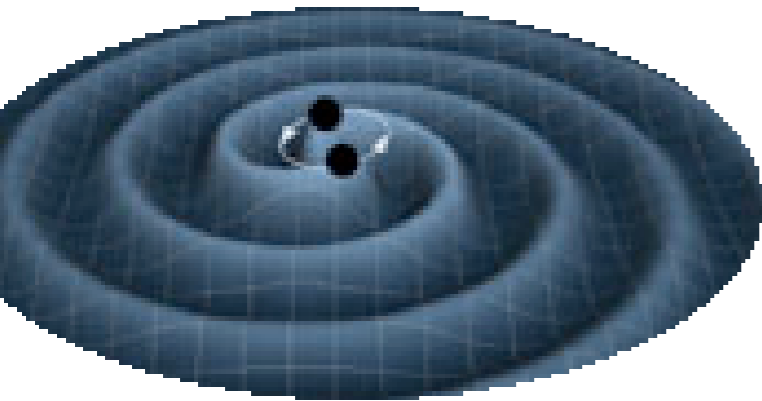
# The Advanced LIGO *proposal*

- Improve the sensitivity of existing observatories to dramatically enhance the astrophysics.
- Same facilities as Initial LIGO, but with new detectors.
- Development is very far along.
- Requested construction funding from NSF in FY2008.
- Project cost \$186 M (US, 2006\$)
  - NSF \$172 M
  - AEI to supply the lasers.  
Already funded by Max Planck Gesellschaft for development and for \$7.1M in 2006\$ for fabrication.
  - UK/GEO for suspensions and core optics  
Already funded by PPARC for development and for \$6.87M in 2006\$ for fabrication.
  - ANU funding request submitted for ~\$1.7M for output modecleaner.

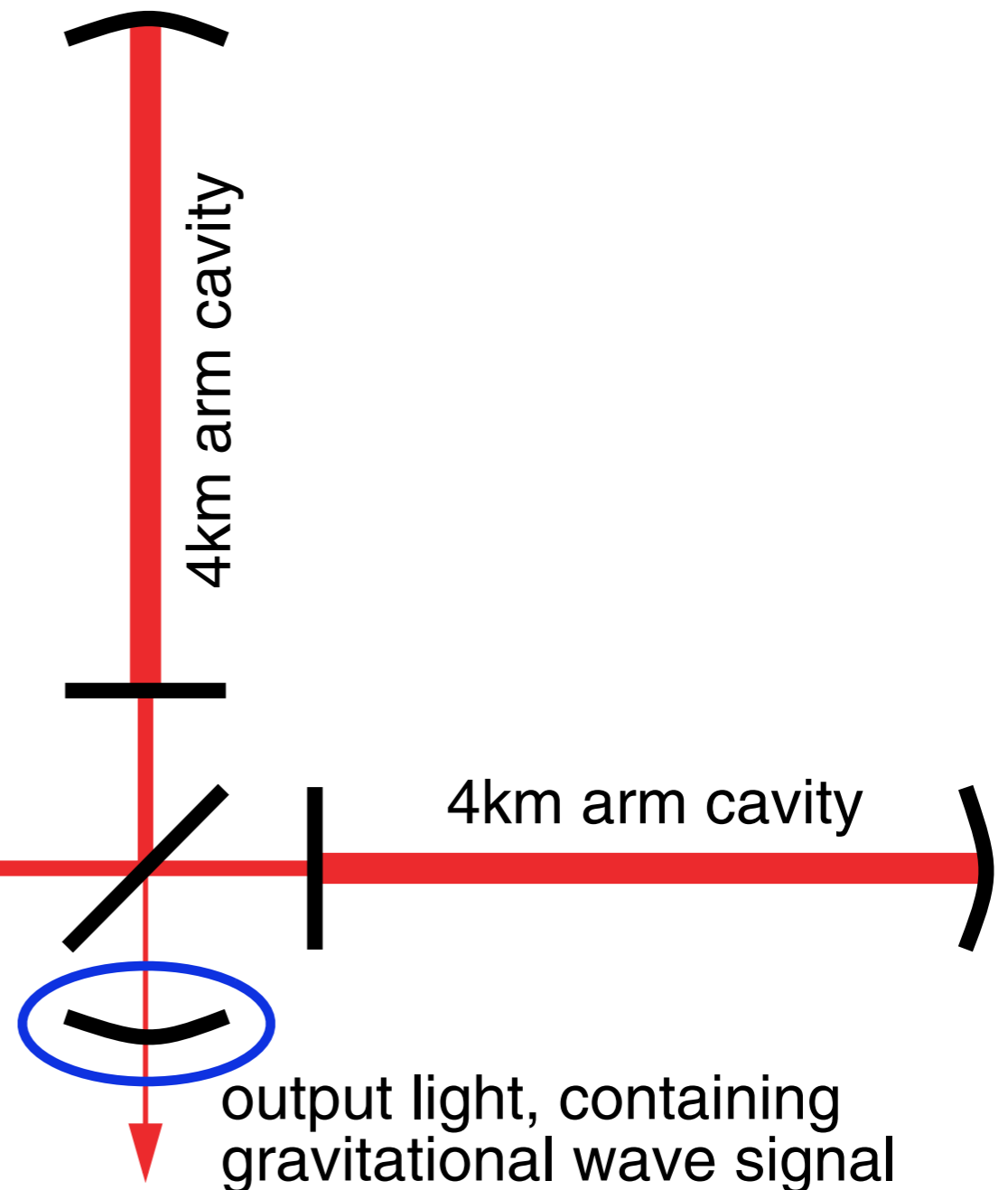
# The Advanced LIGO *proposal*

- Milestones:
  - Advanced LIGO funding at start of FY2008; fabrication, assembly, and stand-alone testing of detector components
  - Advanced LIGO starts decommissioning initial LIGO instruments in early 2011, installing new detector components from stockpile.
  - First Advanced LIGO interferometer accepted in early 2013, second and third in mid-2014.  
Project completes!
  - Commissioning of instruments, engineering runs starting in 2014.

# Detecting Gravitational Waves



input light



4km baseline power-recycled Michelson interferometer with Fabry-Perot arm cavities.

Advanced LIGO will also use signal-recycling

# Initial LIGO

Observatories in Livingston LA  
and Hanford WA.

Science run 5 now underway at  
design sensitivity.

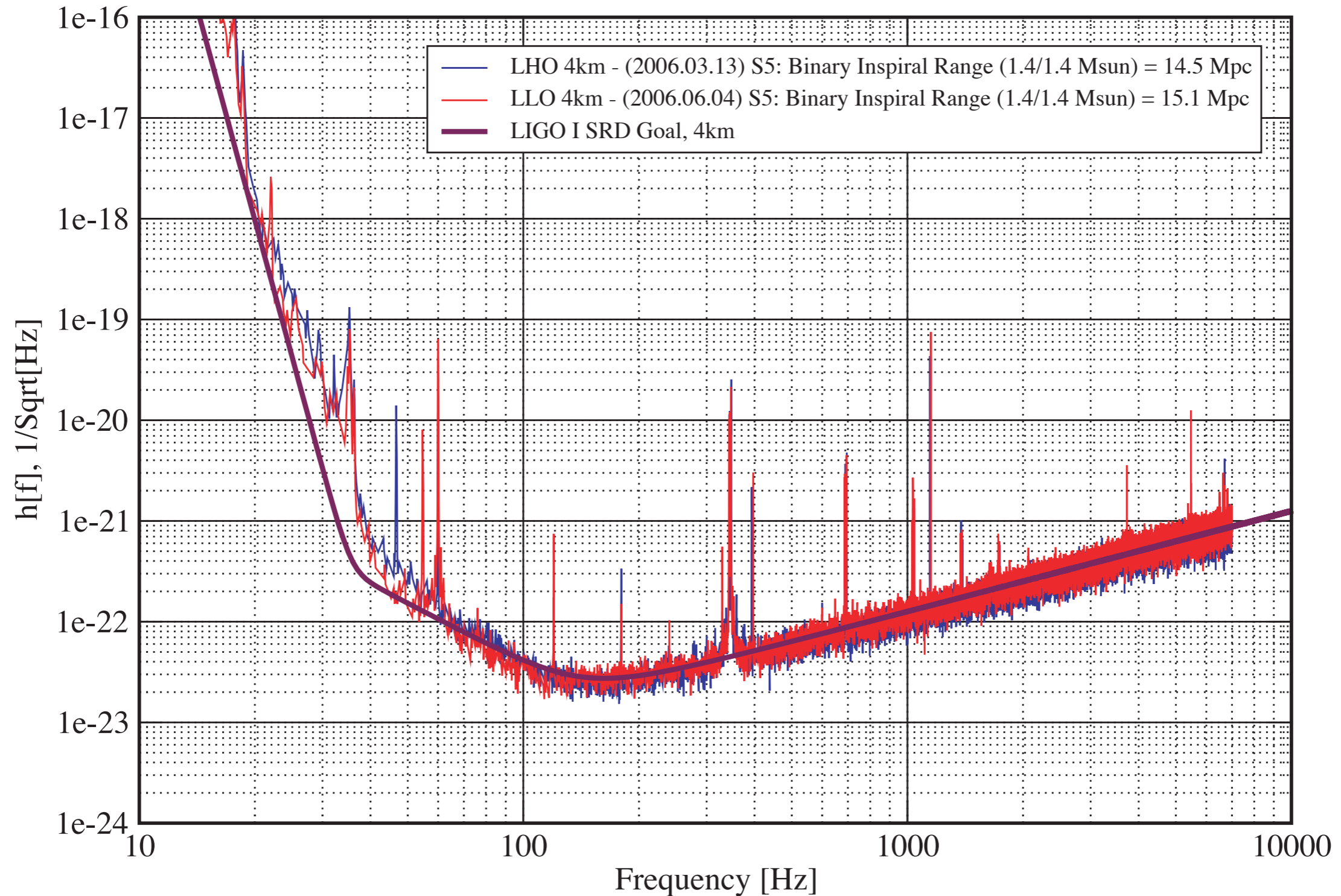


# Initial LIGO Sensitivity

## Strain Sensitivity for the LIGO 4km Interferometers

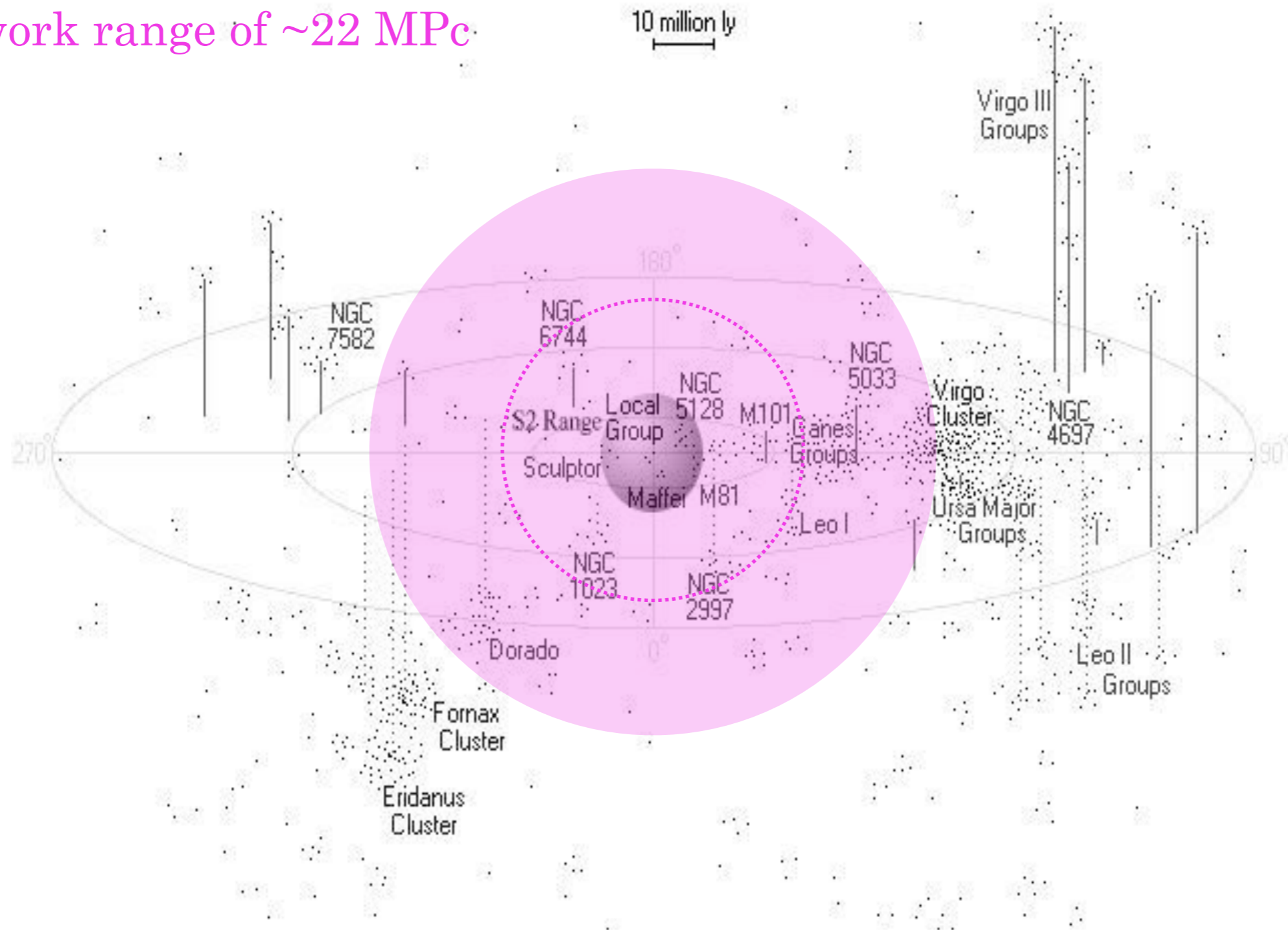
S5 Performance - June 2006

LIGO-G060293-00-Z



# The Seeing

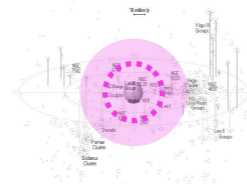
Initial LIGO NS/NS range  $\sim 15$  MPc,  
network range of  $\sim 22$  MPc



LIGO  
advancedligo

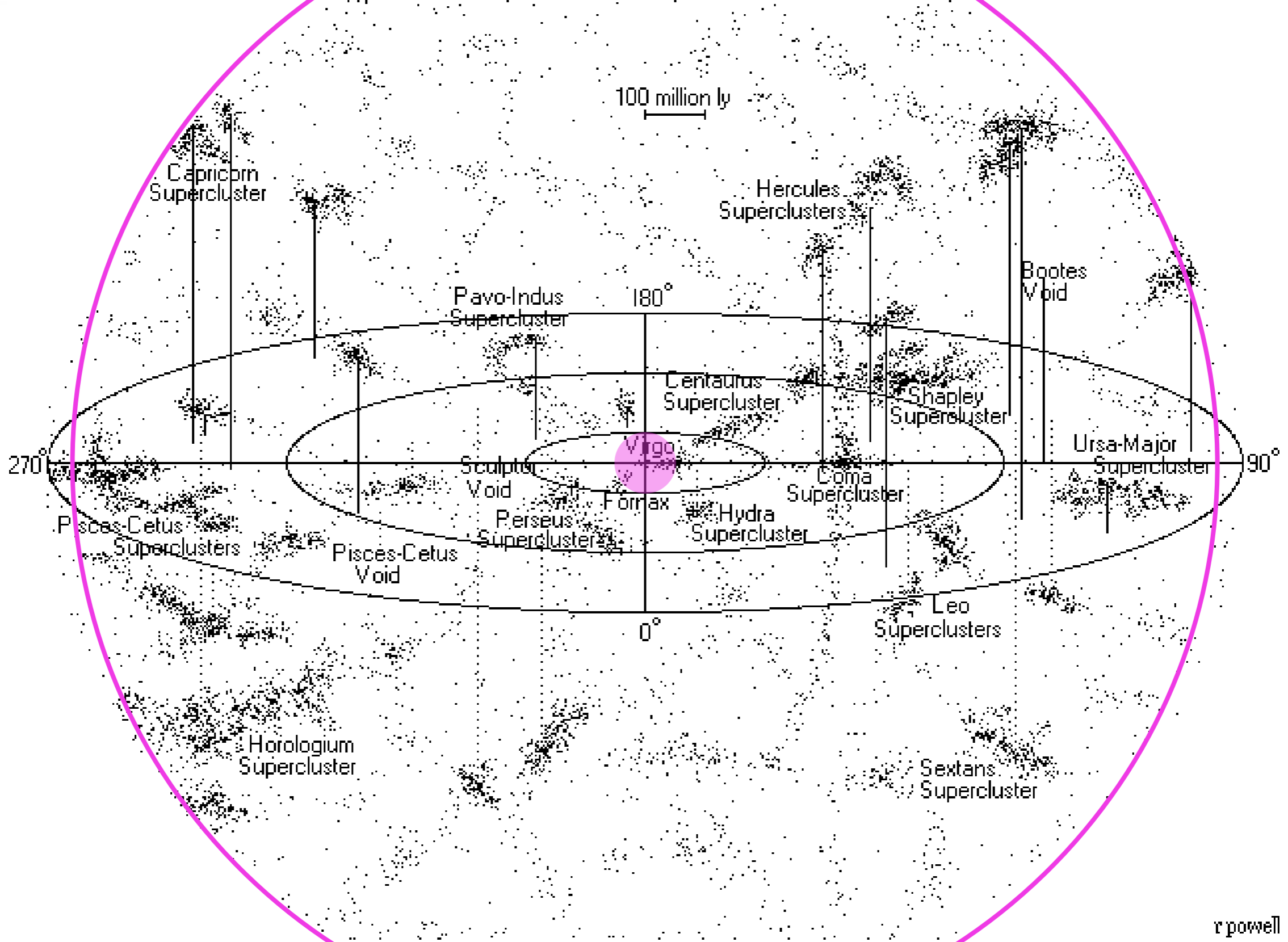
# The Seeing

Initial LIGO NS/NS range  $\sim 15$  MPc,  
network range of  $\sim 22$  MPc





### 3 detector network range for NS/NS of 300 MPc



r powell

image by R. Powell

# Advanced LIGO - Sources

Neutron star and  
Black hole binaries

inspiral  
merger  
GRBs?

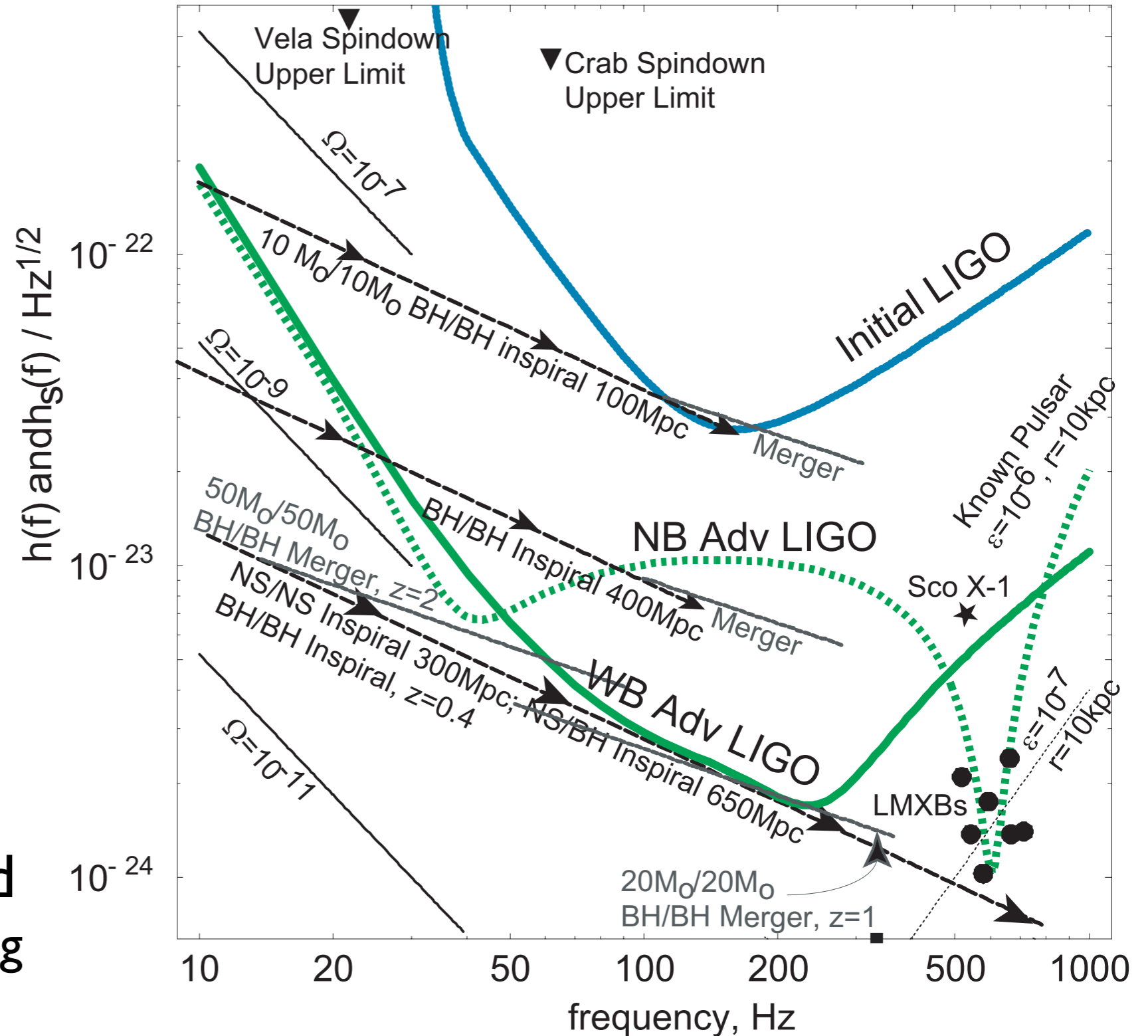
Spinning NS's

LMXB  
known pulsars  
unknown?

Birth of NS  
(supernovas)

tumbling  
convection

Stochastic Background  
remnants of the big bang



# Advanced LIGO - Technology

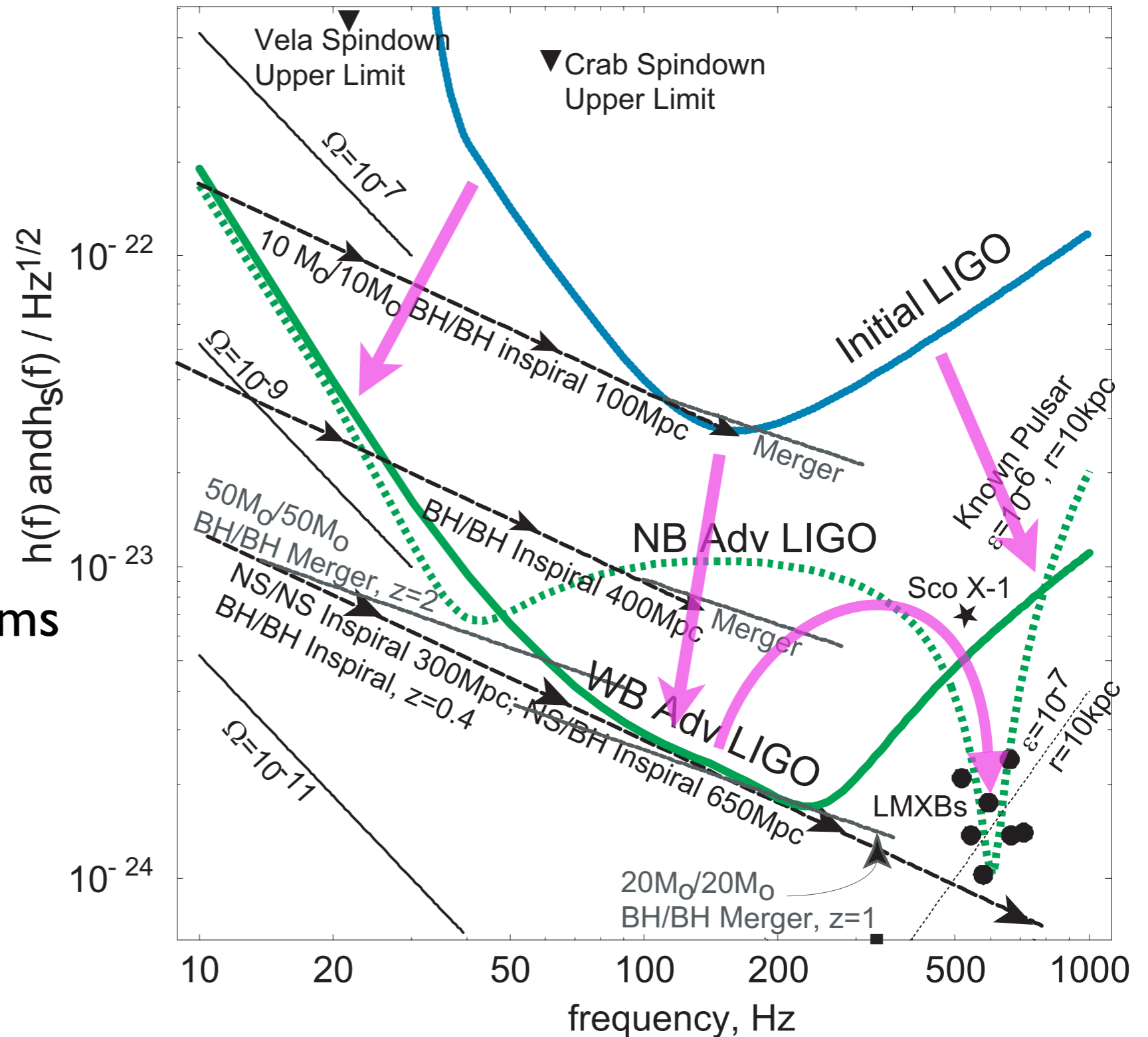
## Technical Improvements

Environmental Isolation:  
platforms & pendulums

Thermal Noise control:  
suspensions & coatings

More Power  
new 180 W laser  
830 kW circulating in arms

Signal recycling  
gives tunable response



# Seismic Isolation & Alignment

Isolation of the test mass

10 Hz motion

test mass  $1 \times 10^{-19} \text{ m}/\sqrt{\text{Hz}}$   
 ground  $\sim 4 \times 10^{-10} \text{ m}/\sqrt{\text{Hz}}$

rms length variation

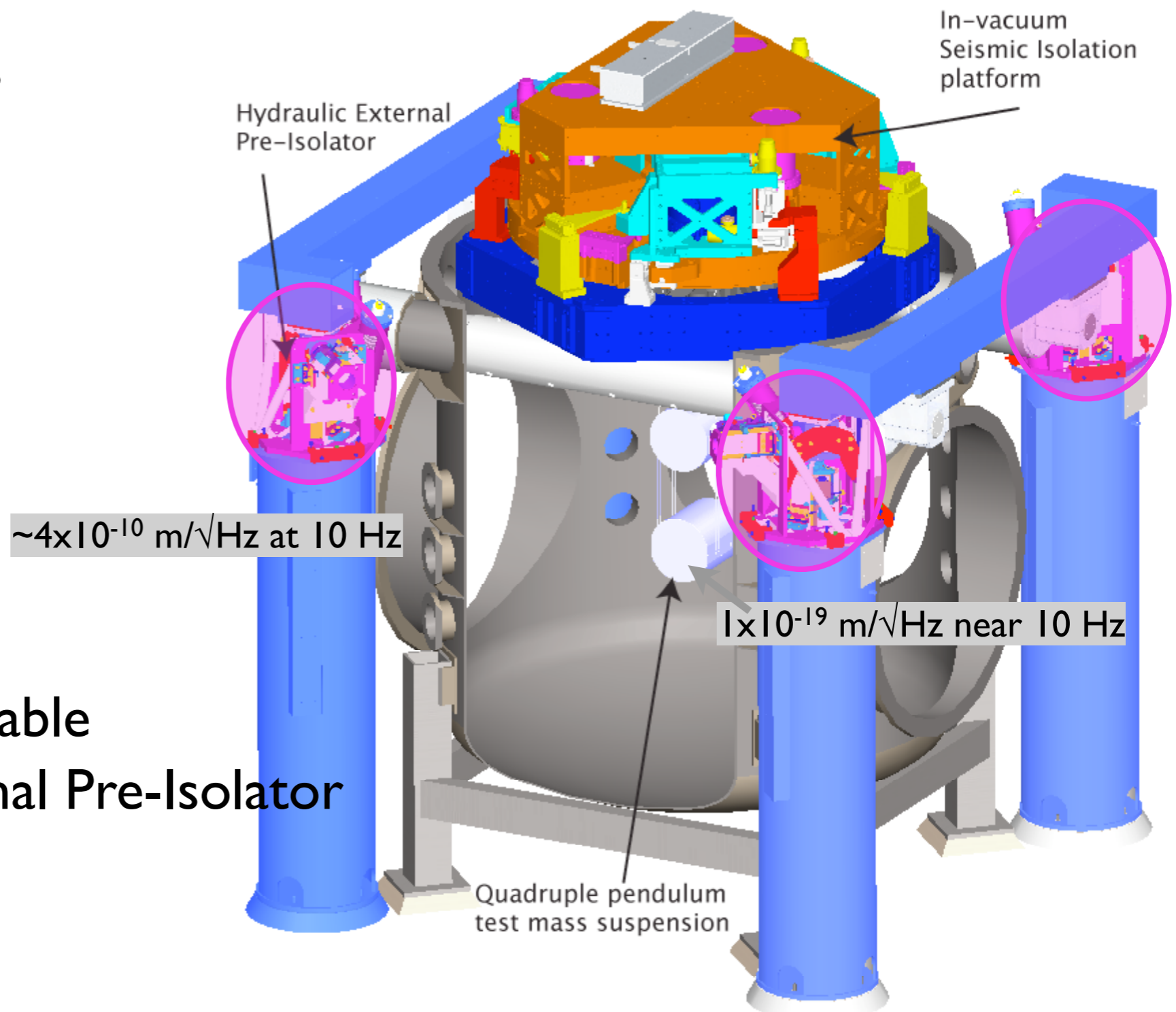
$< 1 \times 10^{-14} \text{ m}$

7 layers of isolation

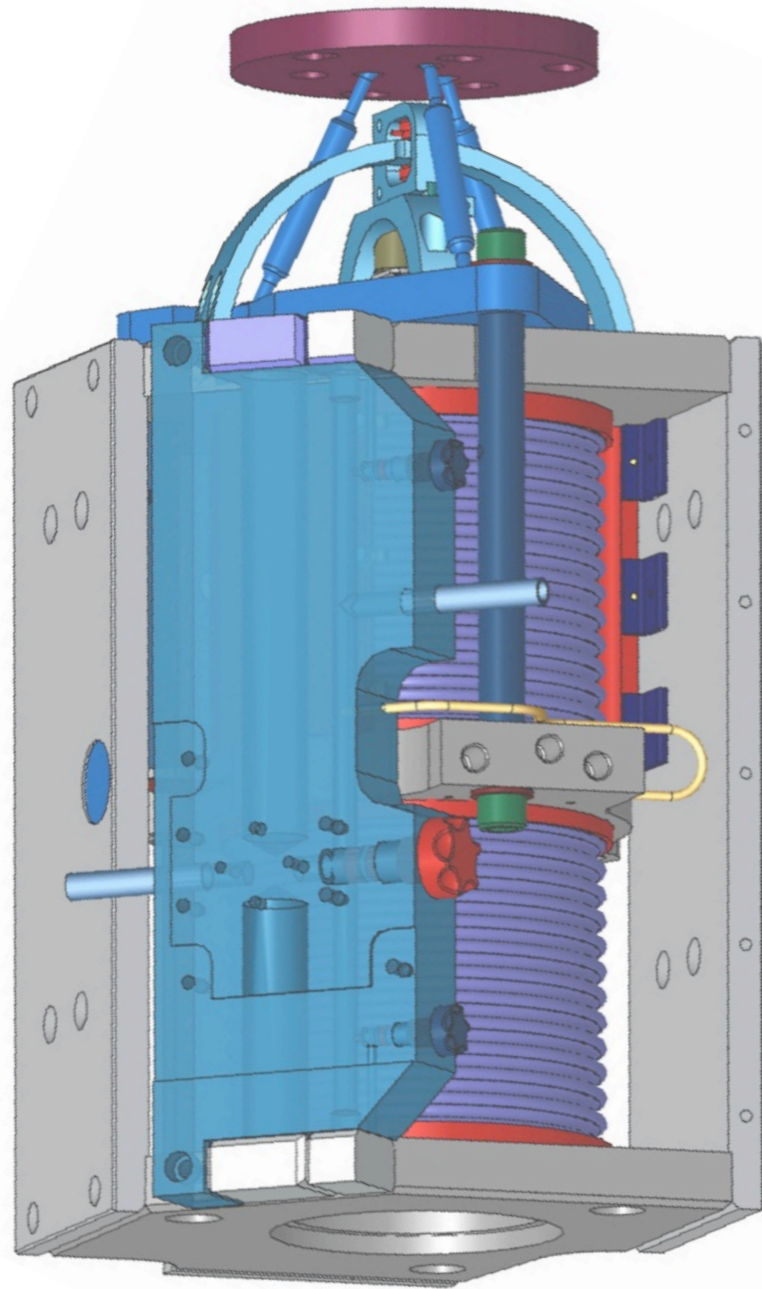
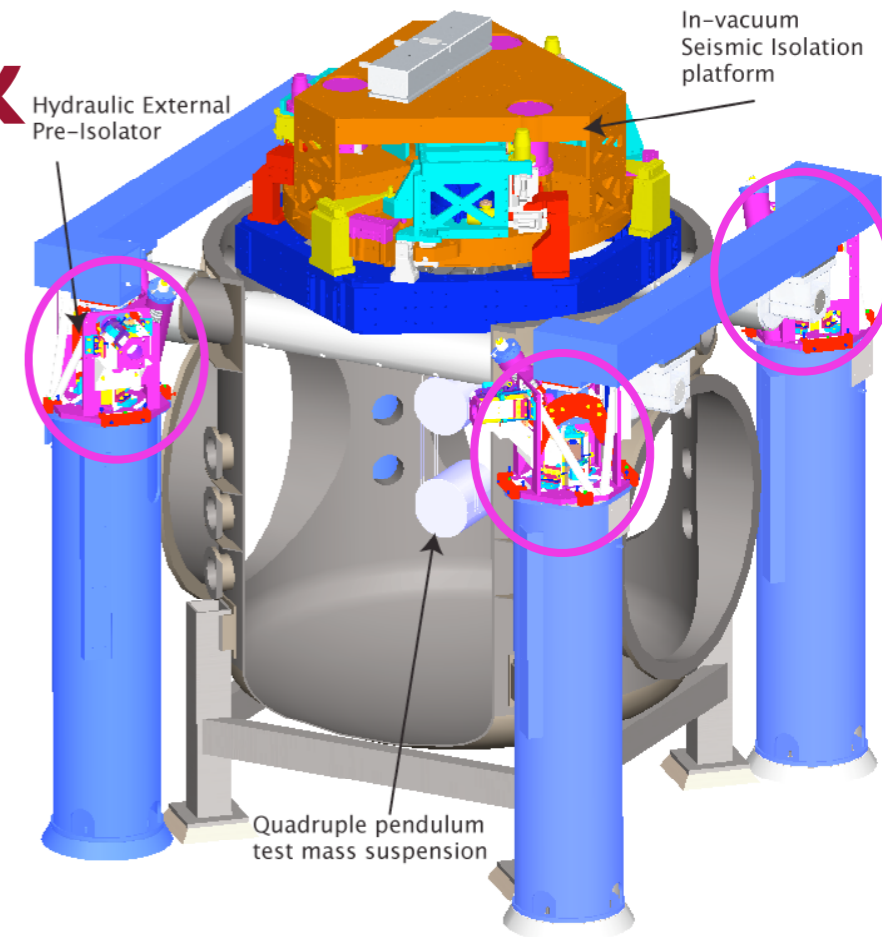
4 stage pendulum

2 stage active isolation table

1 stage Hydraulic External Pre-Isolator

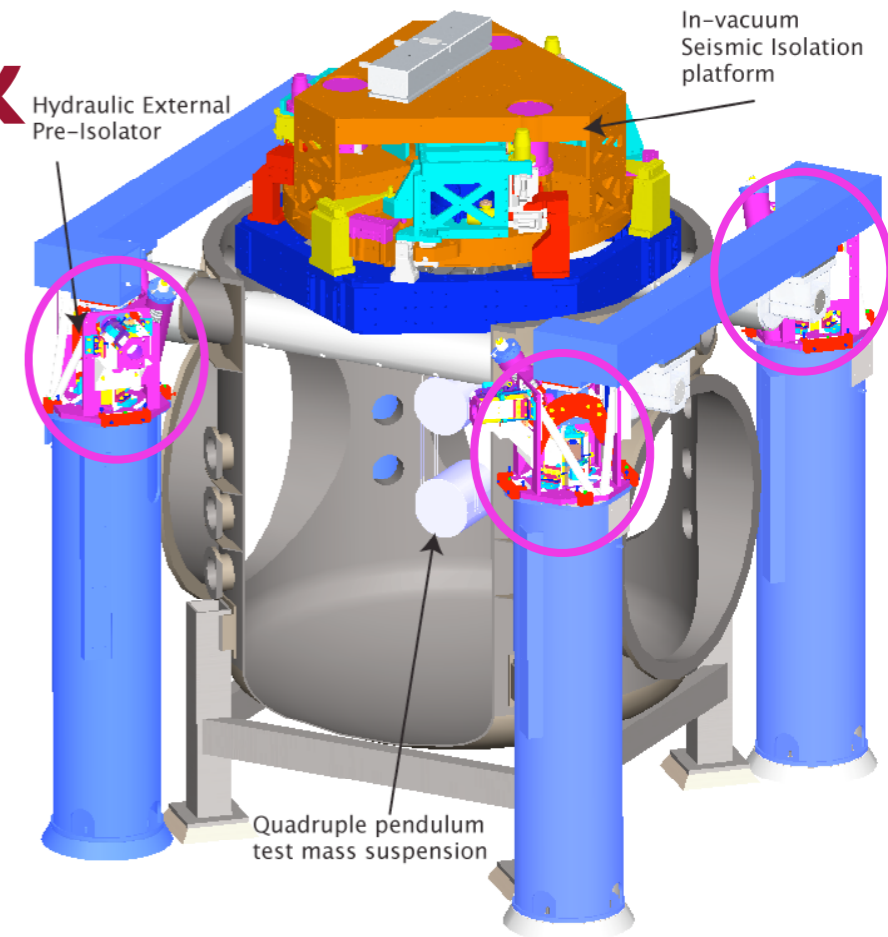


# Seismic Isolation & Alignment - HEPI



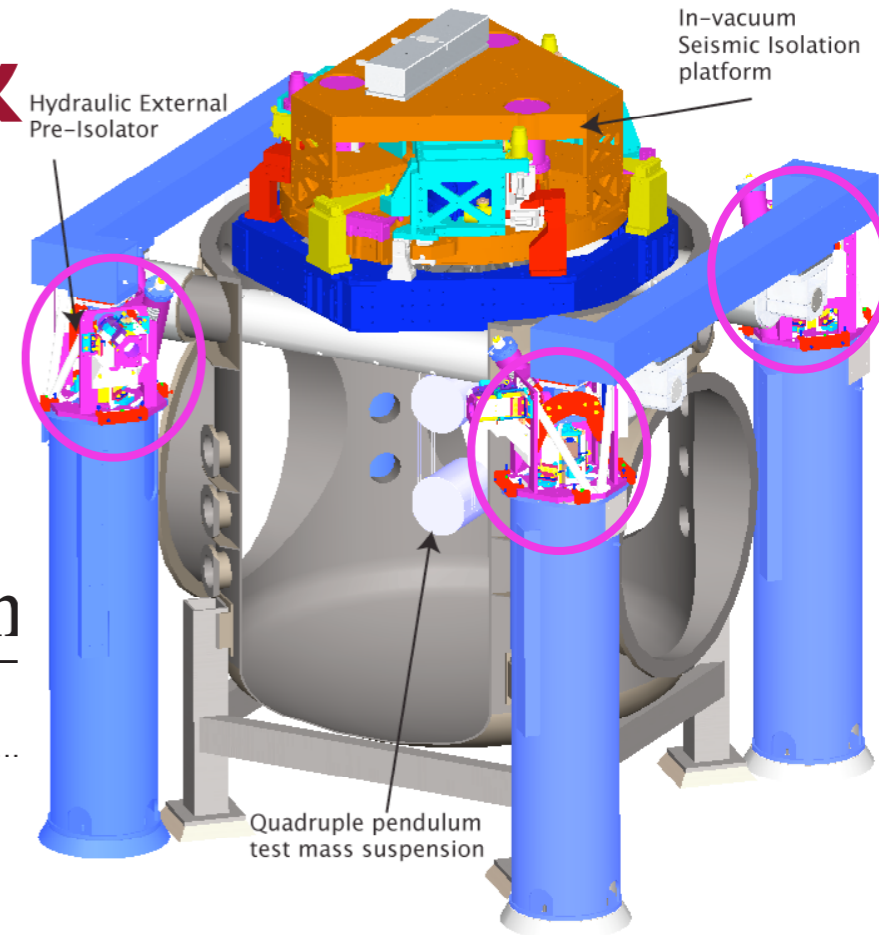
- > Range of +/- 1 mm
- > Easily holds  $1e3$  N (400 lbs) static offset
- > Quiet ( $< 1$  nm/ $\sqrt{\text{Hz}}$  at 1 Hz)

# Seismic Isolation & Alignment - HEPI

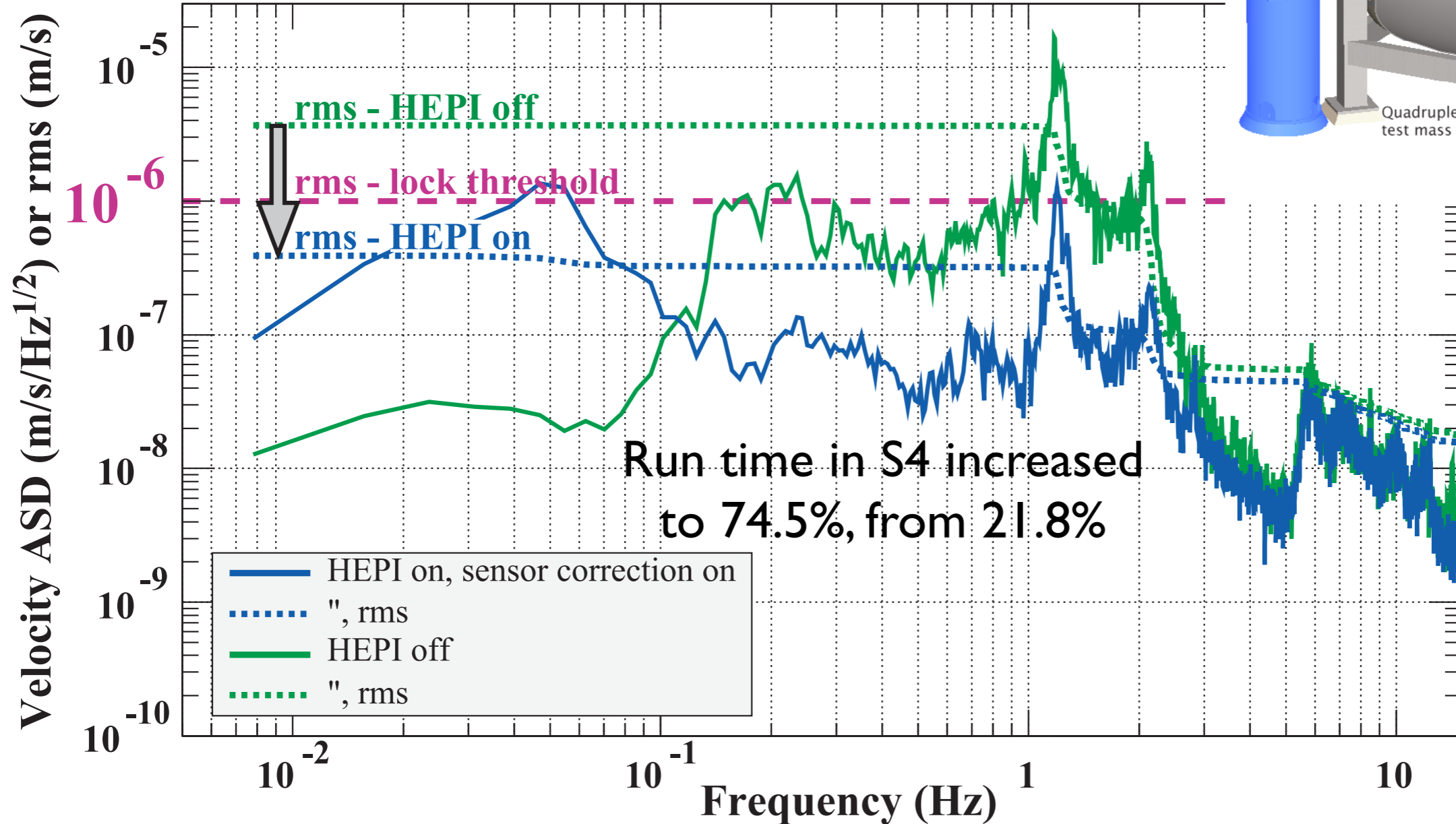


- > Range of +/- 1 mm
- > Easily holds  $1e3$  N (400 lbs) static offset
- > Quiet ( $<1$  nm/ $\sqrt{\text{Hz}}$  at 1 Hz)
- > 1 Vert, 1 Horz per pier for full 6DOF control
- > springs carry static load
- > Feed-forward ground sensors and feed-back local sensors for alignment and isolation.
- > Installed and running at LLO.

# Seismic Isolation & Alignment - HEPI

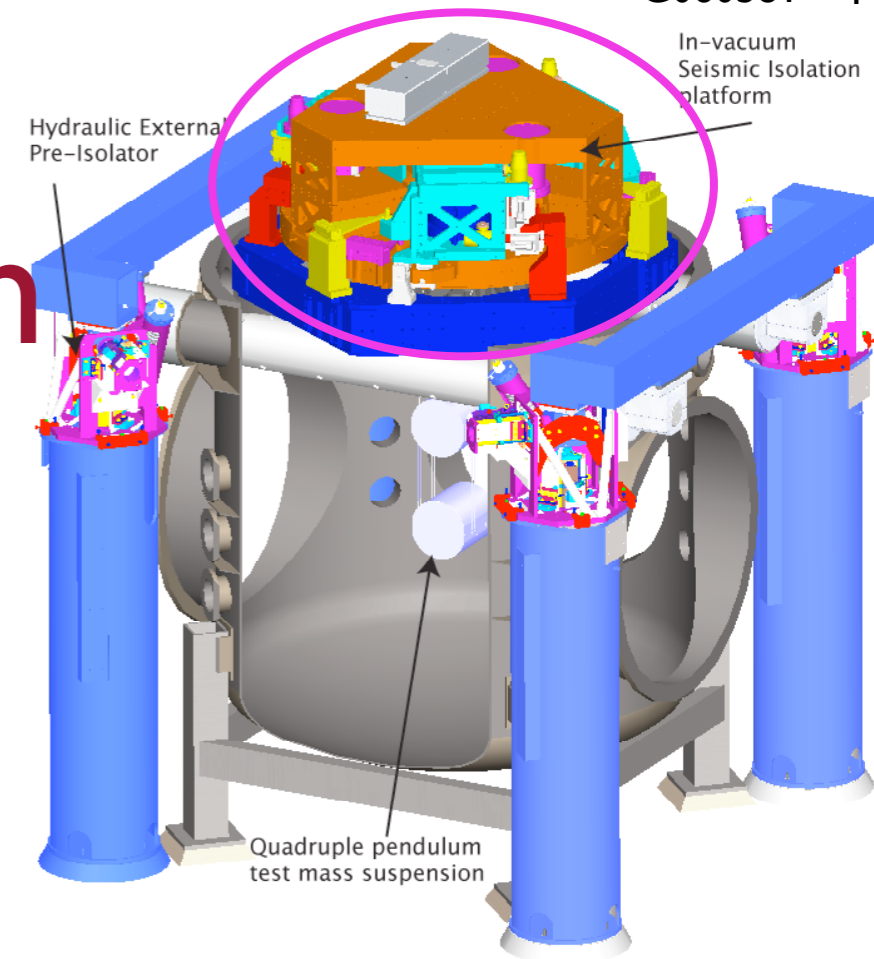


X-arm length disturbance, noisy aftern



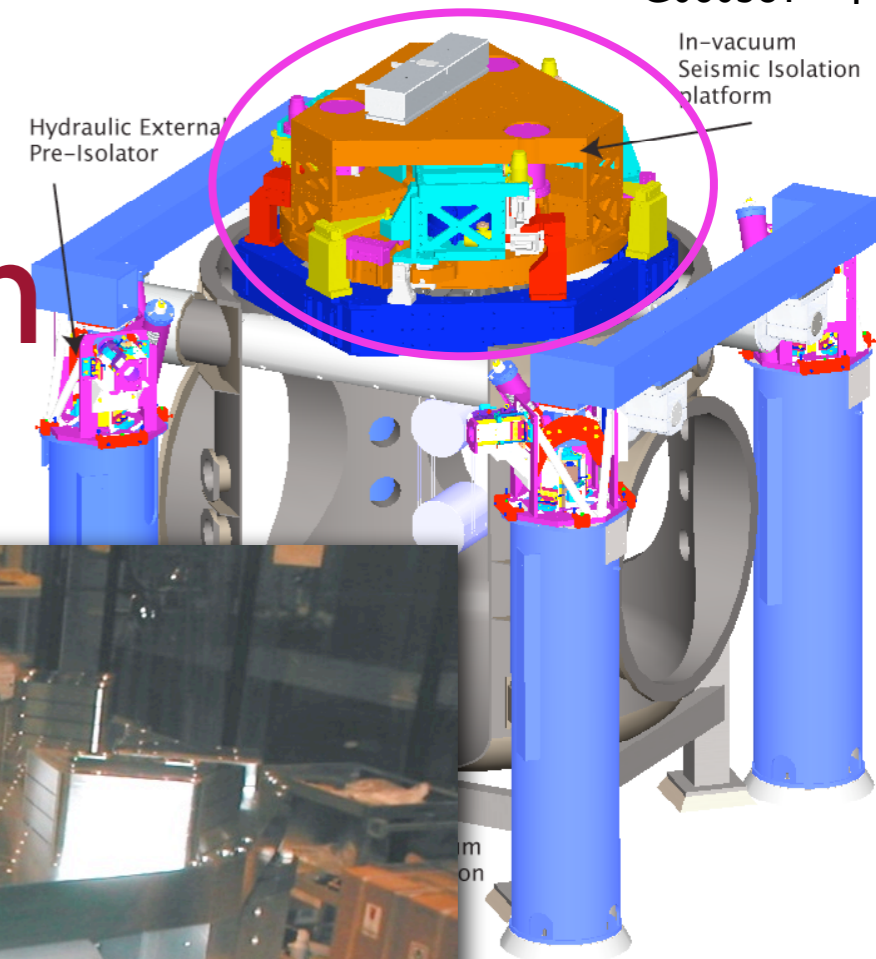
# Seismic Isolation & Alignment - platform

- Technology demonstrator designed and installed in Stanford vacuum system (ETF).
  - ▶ mechanical system designed for approximately LIGO size platform, with approx half-size payload capacity.
  - ▶ most sensors and actuators as final design.
- True prototype being installed at MIT for full scale, UHV, tests with suspension systems.
  - ▶ modal frequencies designed to be  $> 150$  Hz to accommodate  $\approx 50$  Hz servo unity-gain point.
  - ▶ modeling of  $6 \times 6$  DOF stiffness at low frequencies. We design horizontal-tilt cross coupling  $< 1/500$  rad/m.
  - ▶ new design for rigid and strong stops, to exactly position stages and restrict motion during earthquakes.
  - ▶ can accommodate  $\approx 800$  kg payload. Servo and mechanical design need to tolerate mechanically reactive massive payload

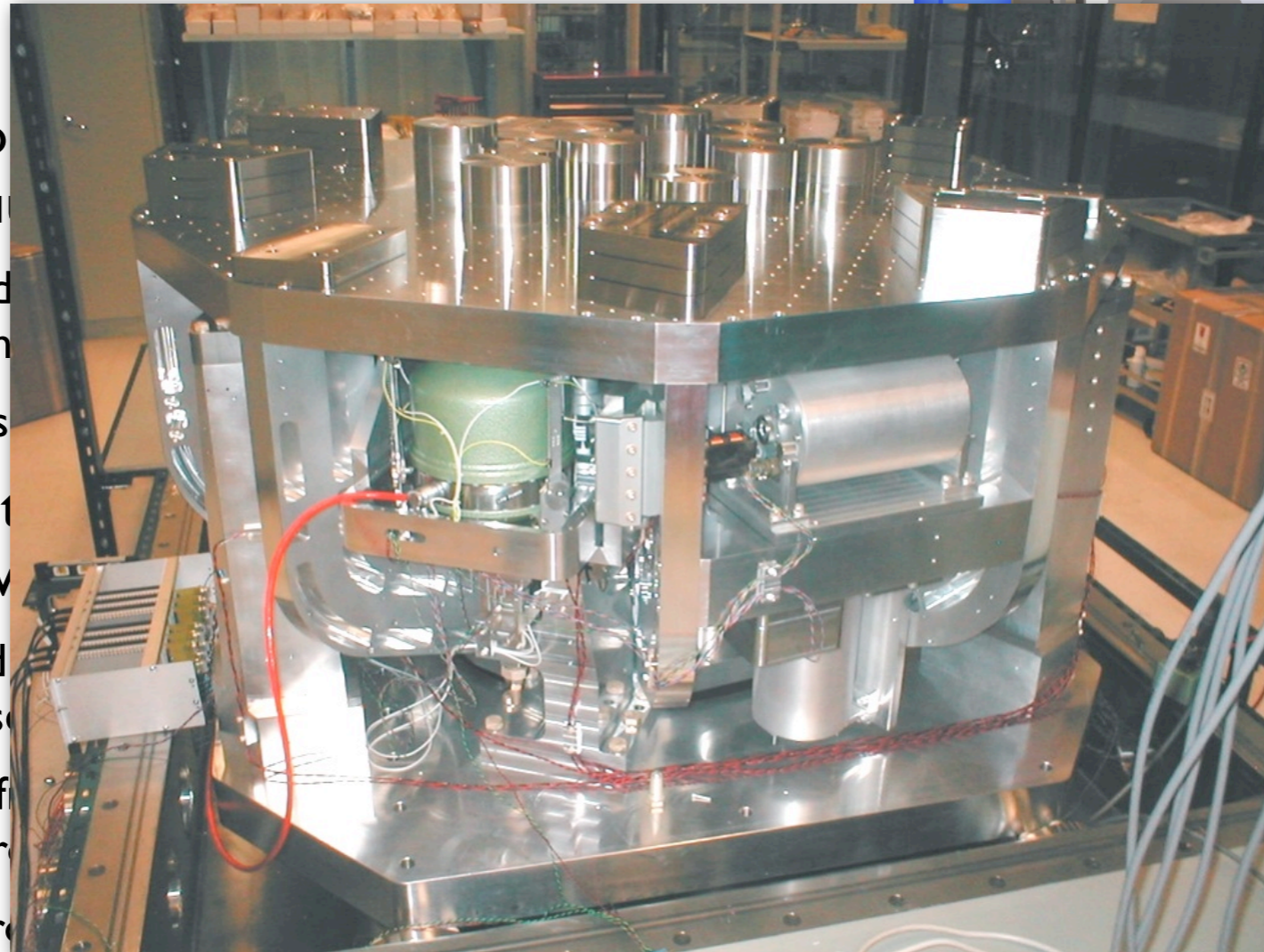




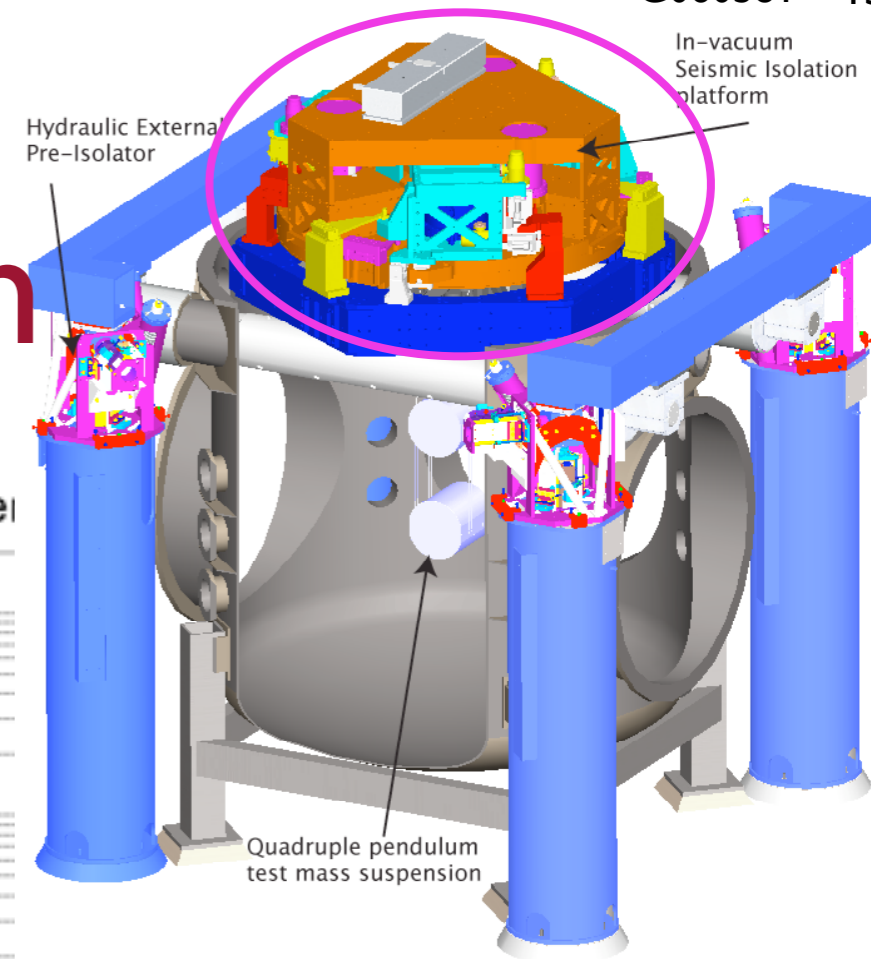
# Seismic Isolation & Alignment - platform



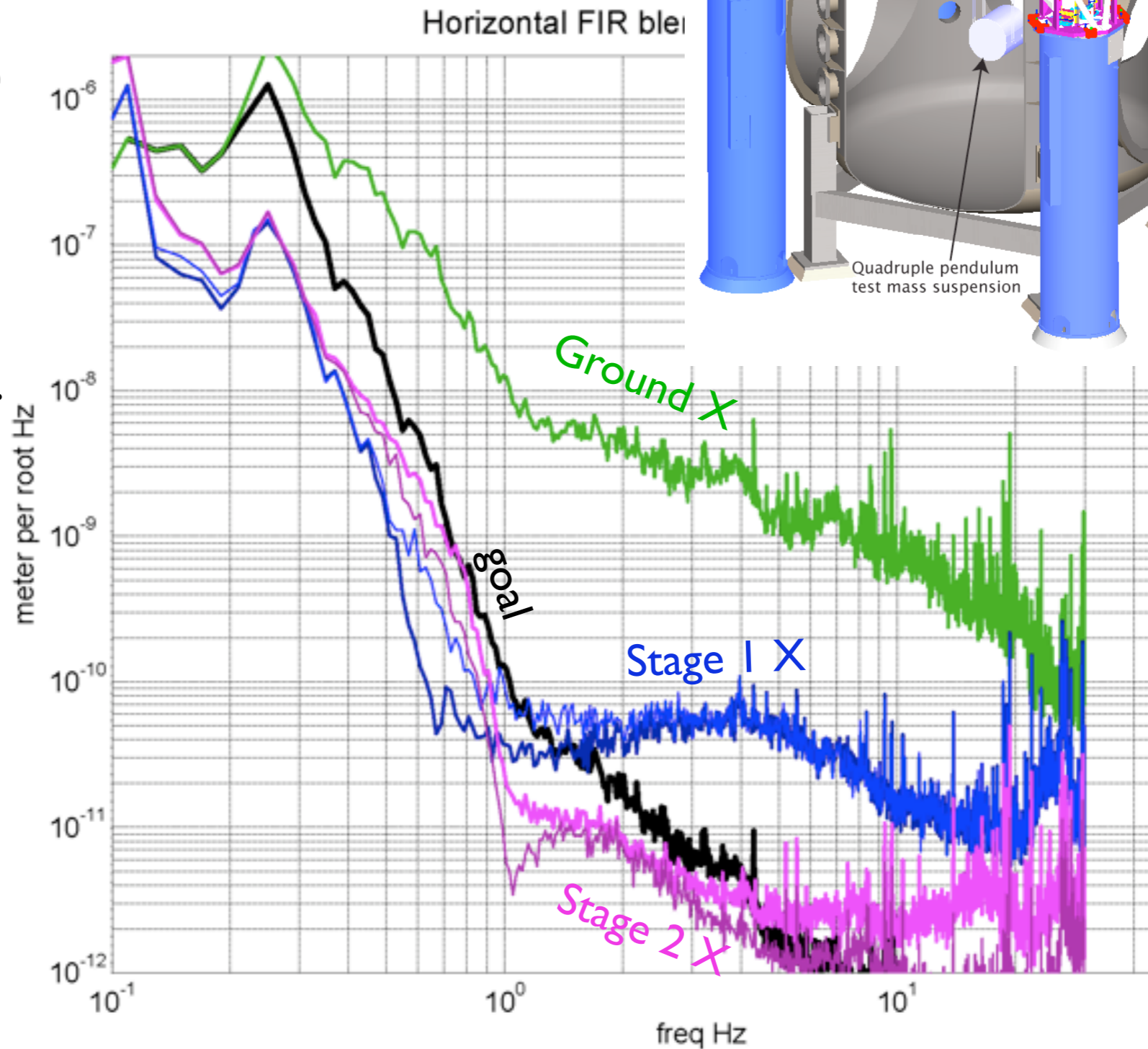
- Technology demonstrator installed in Stanford vacuum chamber
  - ▶ mechanical system designed to support large size platform, with approx height of 1.5m
  - ▶ most sensors and actuators are located on the platform
- True prototype being installed in LIGO for full scale, UHV, tests with payload
  - ▶ modal frequencies designed to accommodate  $\approx 50$  Hz seismic noise
  - ▶ modeling of 6 x 6 DOF stiffness matrix. We design horizontal-tilt cross-coupling
  - ▶ new design for rigid and strong structure to resist motion during earthquakes.
  - ▶ can accommodate  $\approx 800$  kg payload. Servo and mechanical design need to tolerate mechanically reactive massive payload



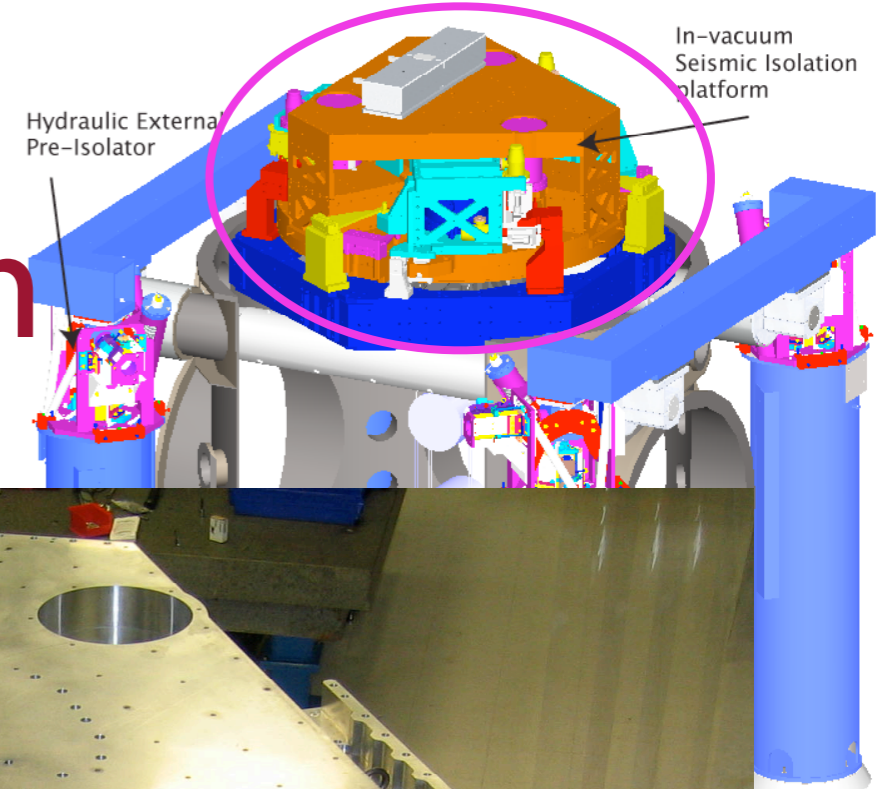
# Seismic Isolation & Alignment - platform



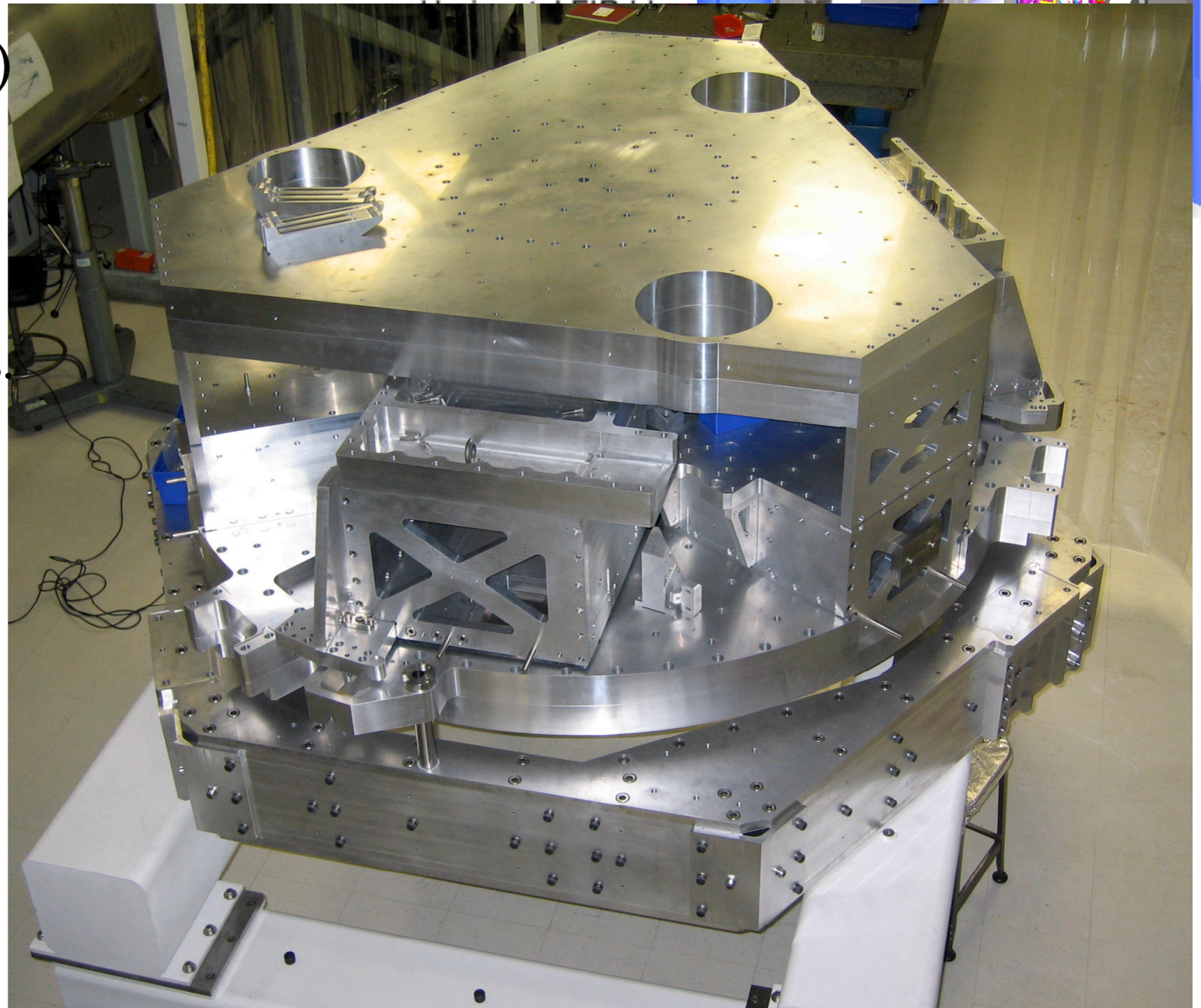
- Isolation requirement:  
100 at 1 Hz (met!)  
3000 at 10 Hz (design mod)
- We modified the LASTI prototype to increase vertical passive isolation at 10 Hz, based on these tests.



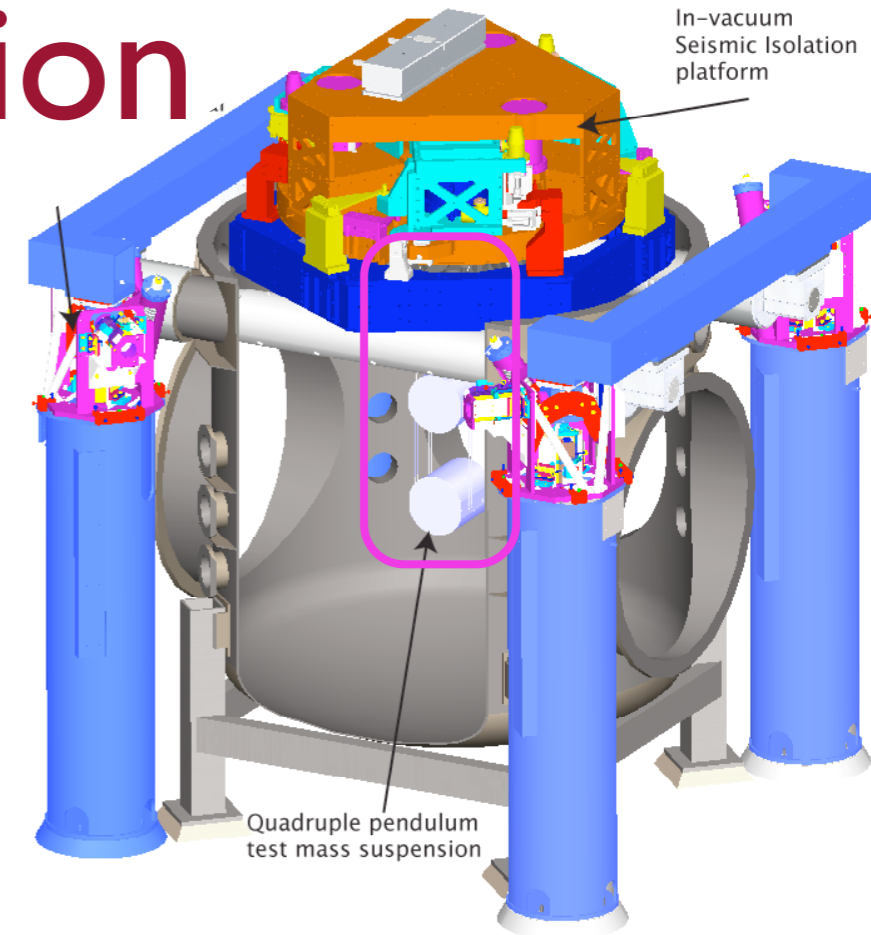
# Seismic Isolation & Alignment - platform



- Isolation requirement:  
100 at 1 Hz (met!)  
3000 at 10 Hz (design mod)
- We modified the LASTI prototype to increase vertical passive isolation at 10 Hz, based on these tests.
- LASTI prototype now being assembled at MIT. Testing to commence forthwith.



In-vacuum  
Seismic Isolation  
platform

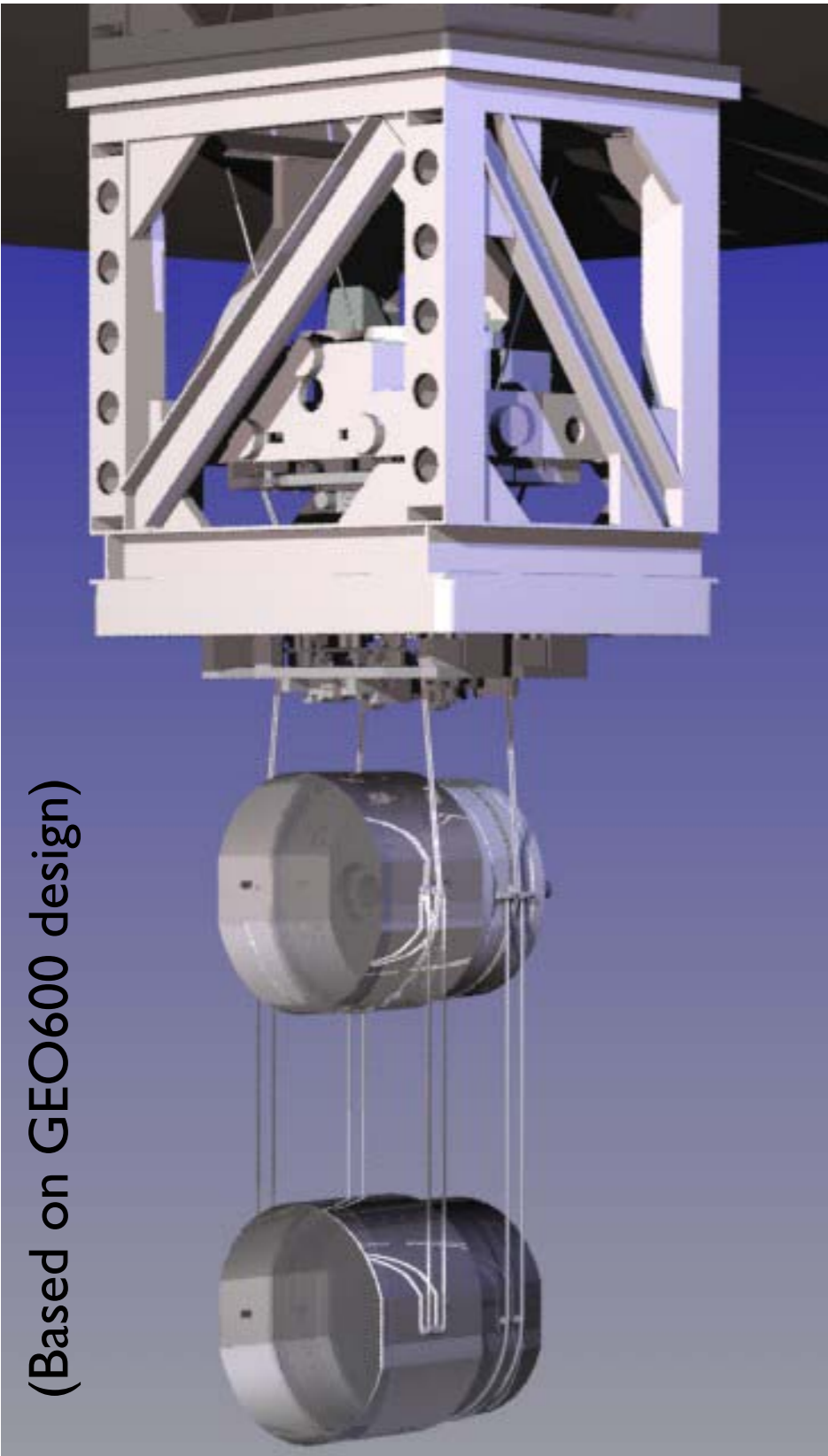


Multiple-pendulums  
for control flexibility &  
seismic attenuation

Test masses:  
Synthetic fused silica,  
40 kg, 34 cm dia.  
»  $Q \geq 1e7$   
» low optical absorption

Final suspensions are fused silica,  
joined to form monolithic final stages.

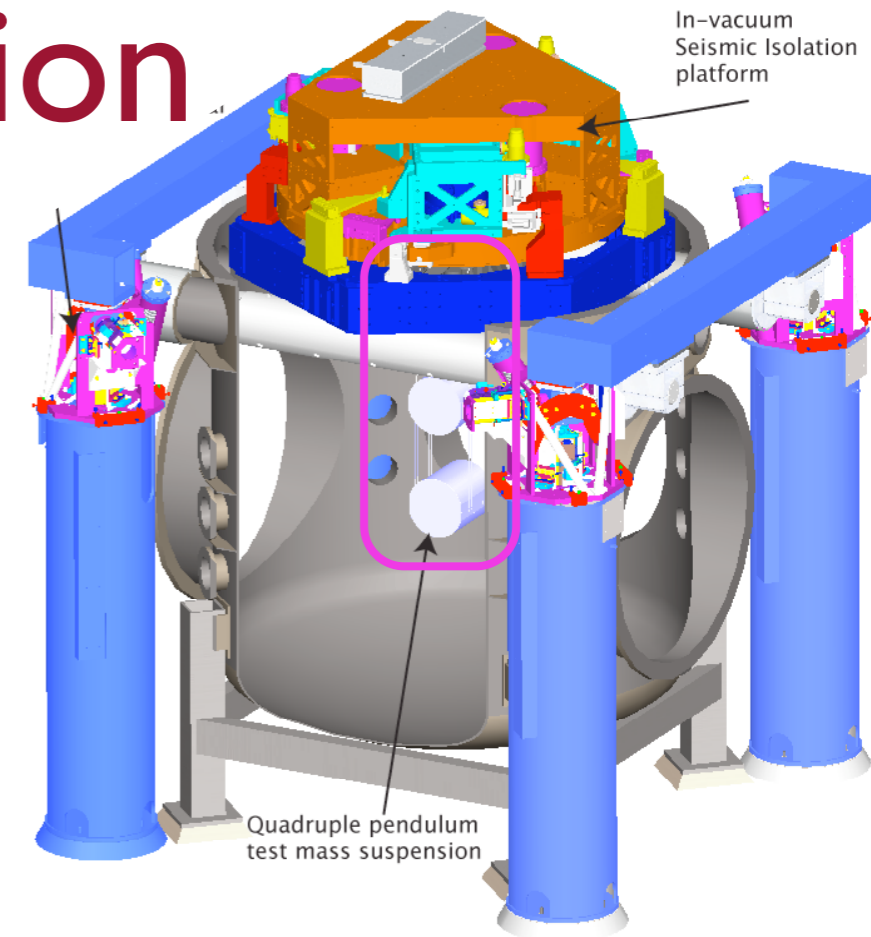
Thermal vibrations at the optical surface  
set the performance limit of the  
suspension.



(Based on GEO600 design)

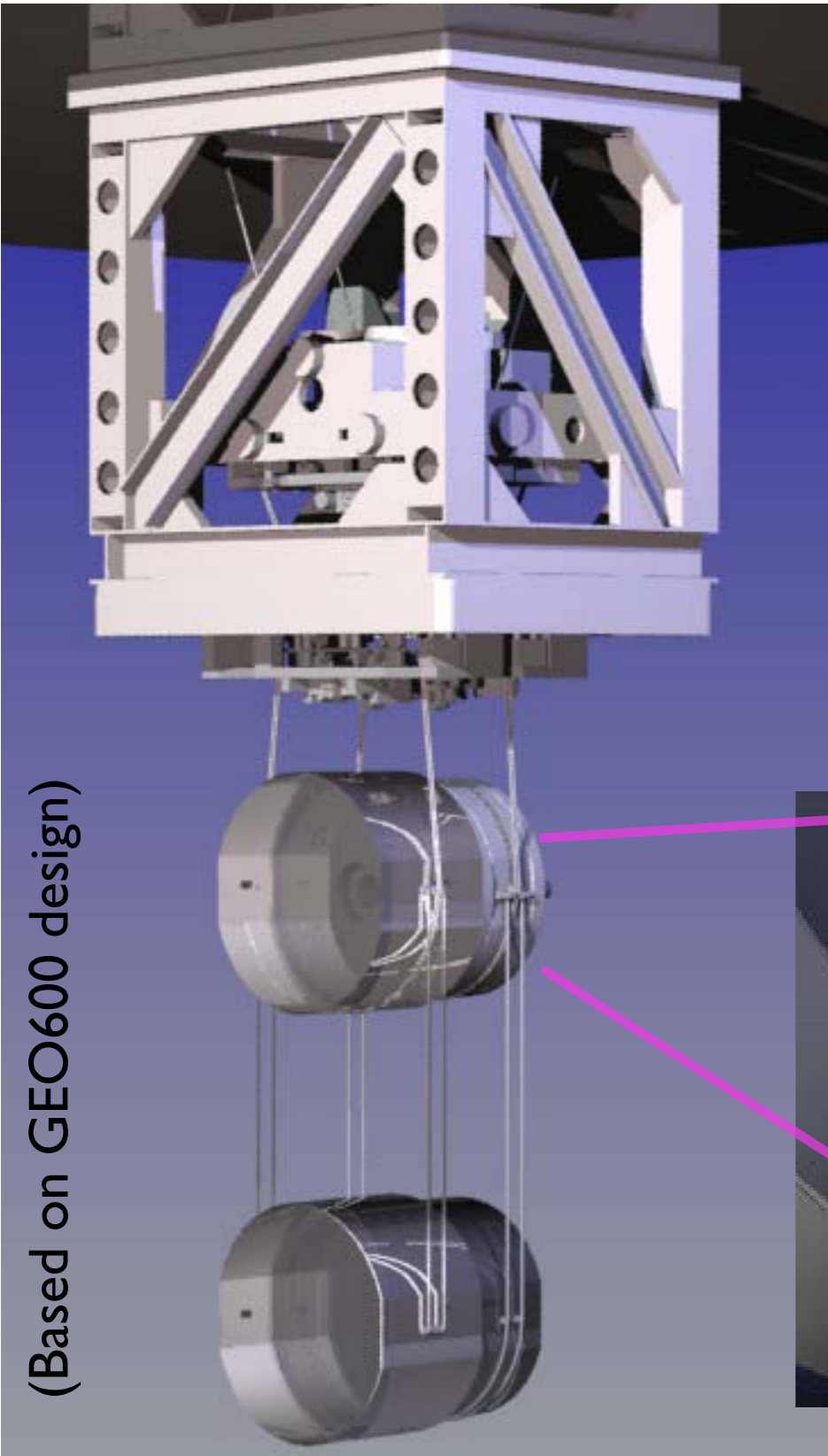
# Pendulum Suspension

In-vacuum  
Seismic Isolation  
platform

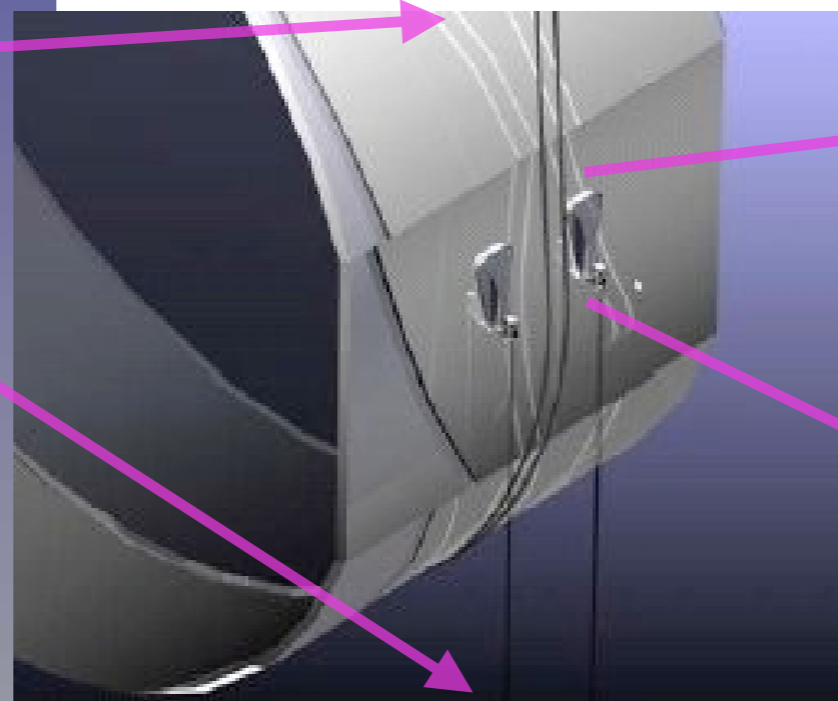


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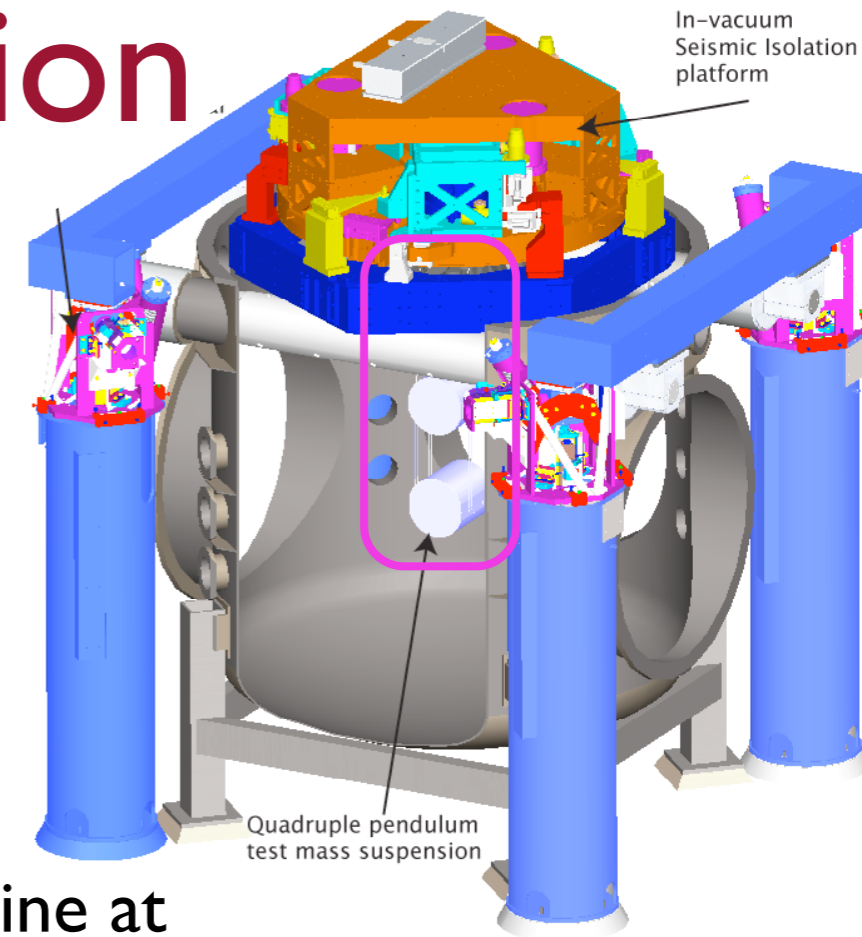
(Based on GEO600 design)



silicate bonding creates a monolithic final stage

# Pendulum Suspension

In-vacuum  
Seismic Isolation  
platform



Installing 'controls prototype' at MIT  
(metal masses, metal wires)

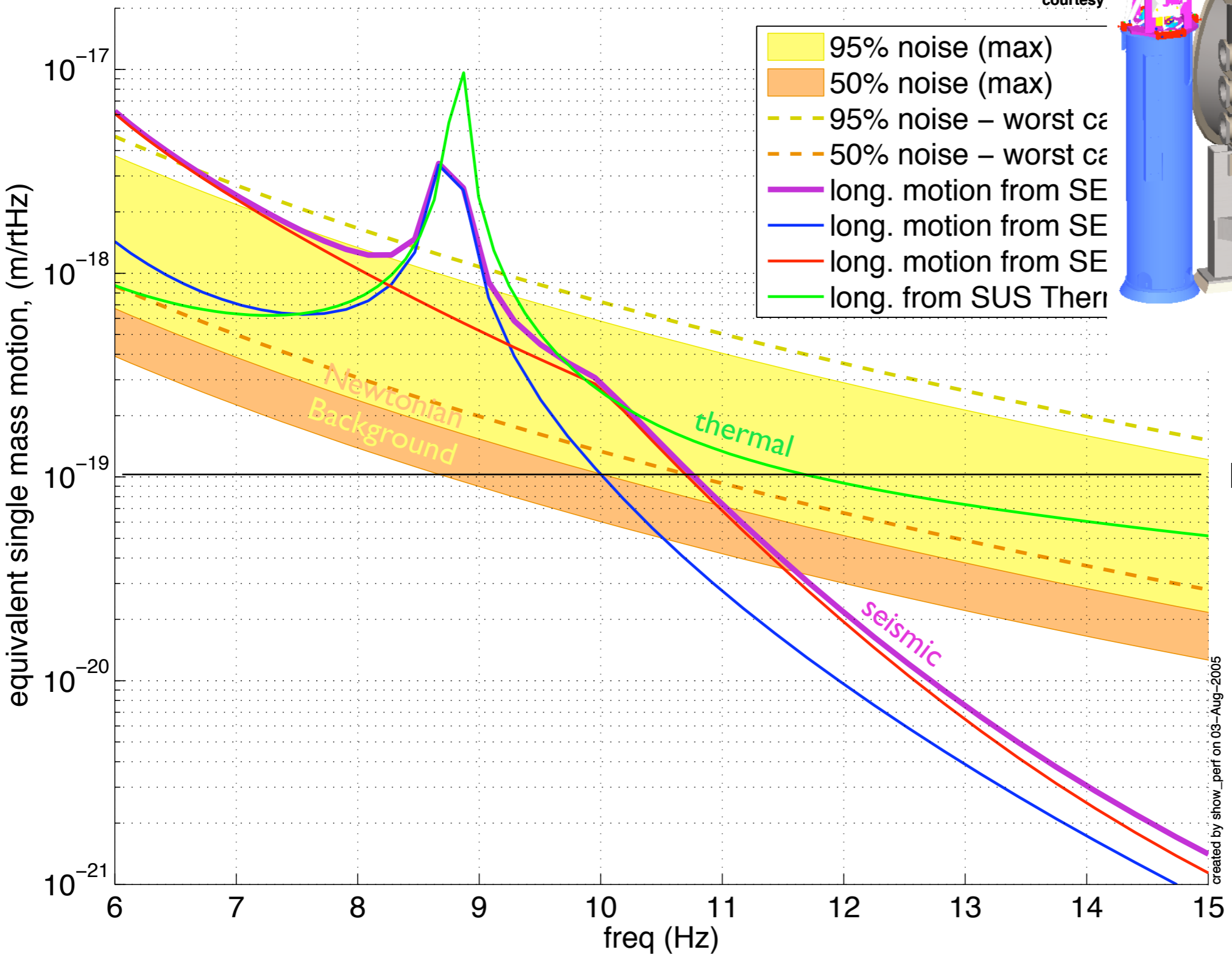
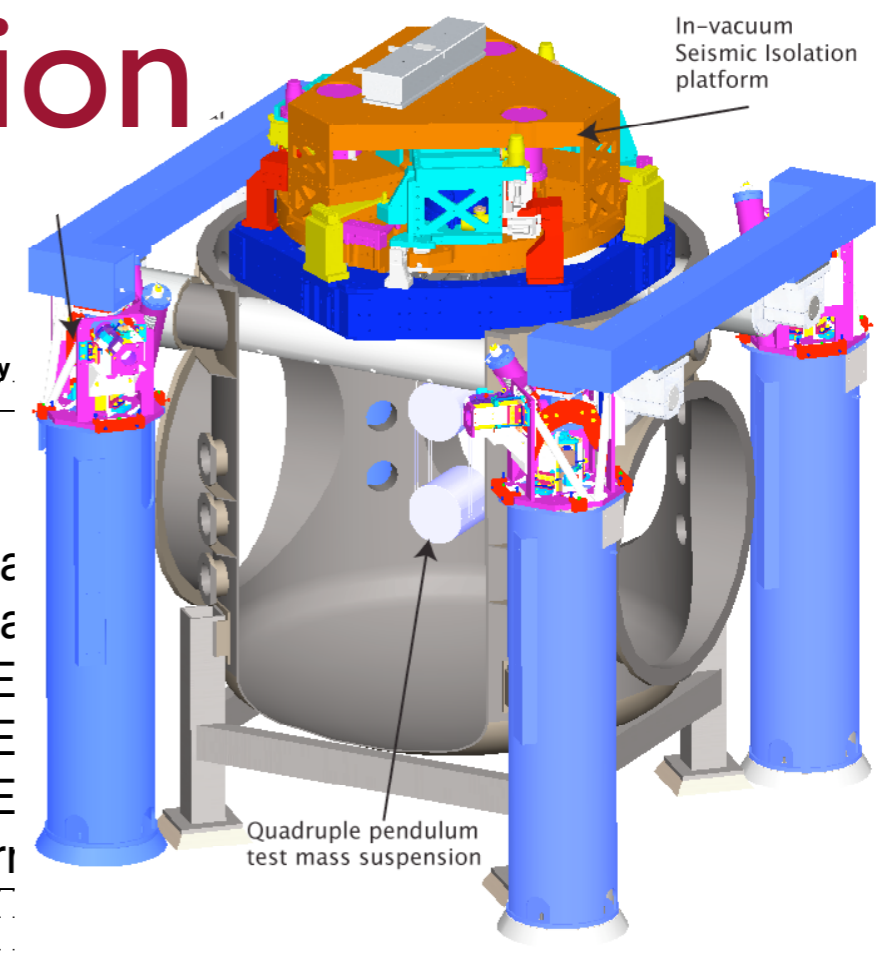
'Noise prototype' due in early 2007  
(glass optics, silica ribbon suspensions)

Ribbon pulling machine at  
the University of Glasgow



# Pendulum Suspension

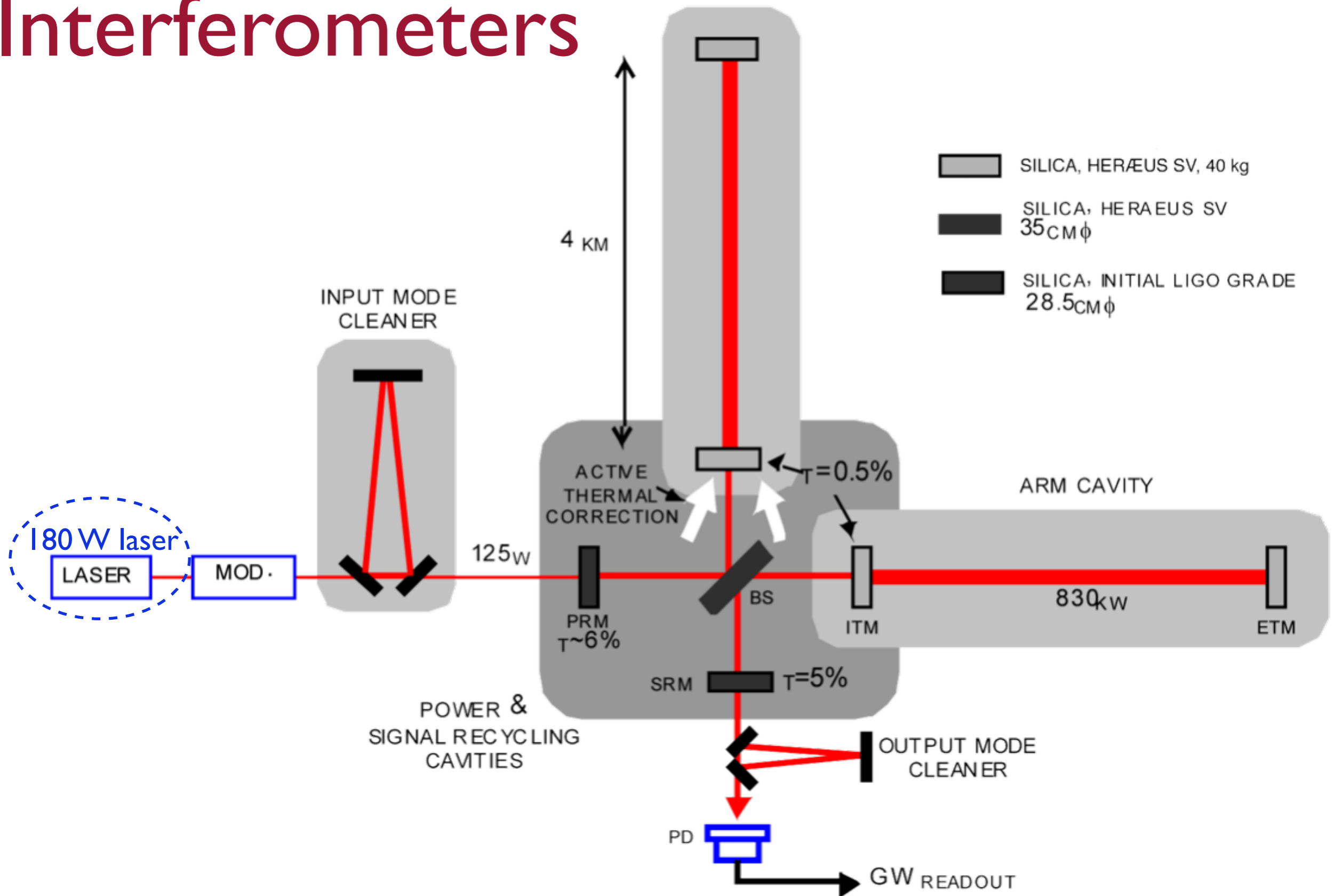
Predicted motion of the Advanced LIGO Test Mass



courtesy

created by show\_perf on 03-Aug-2005

# Power, Optics, and Interferometers

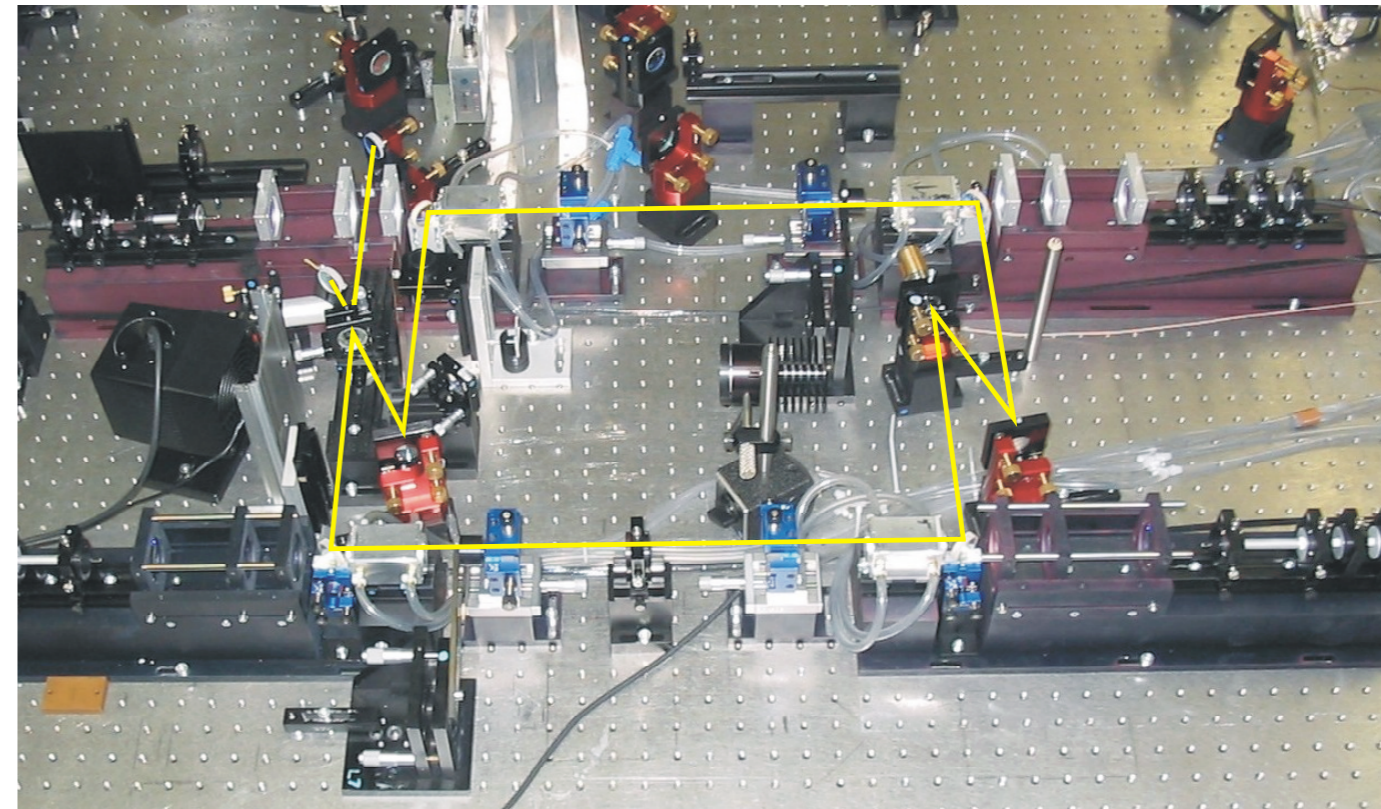
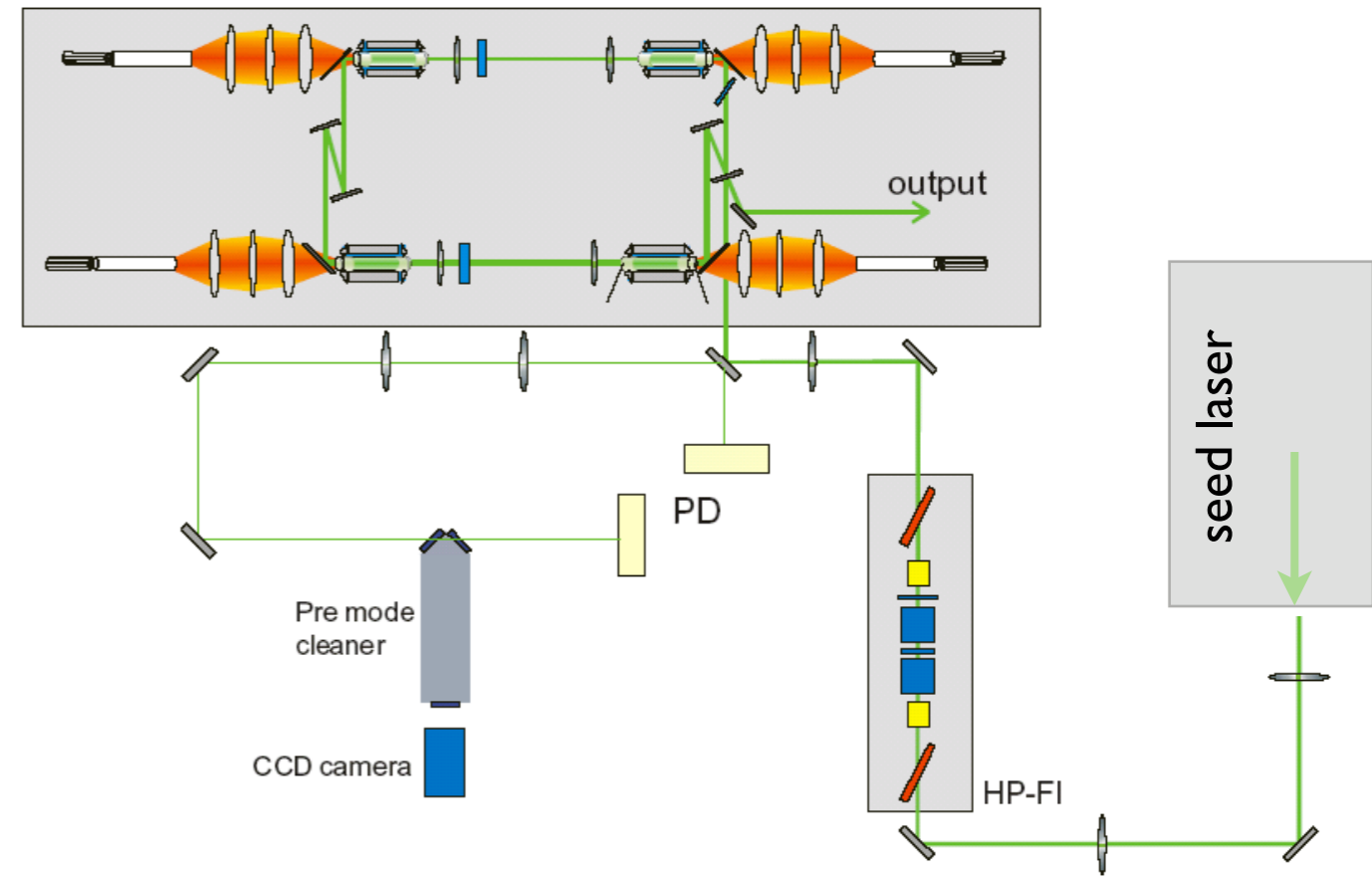




# advancedligo High Power Laser

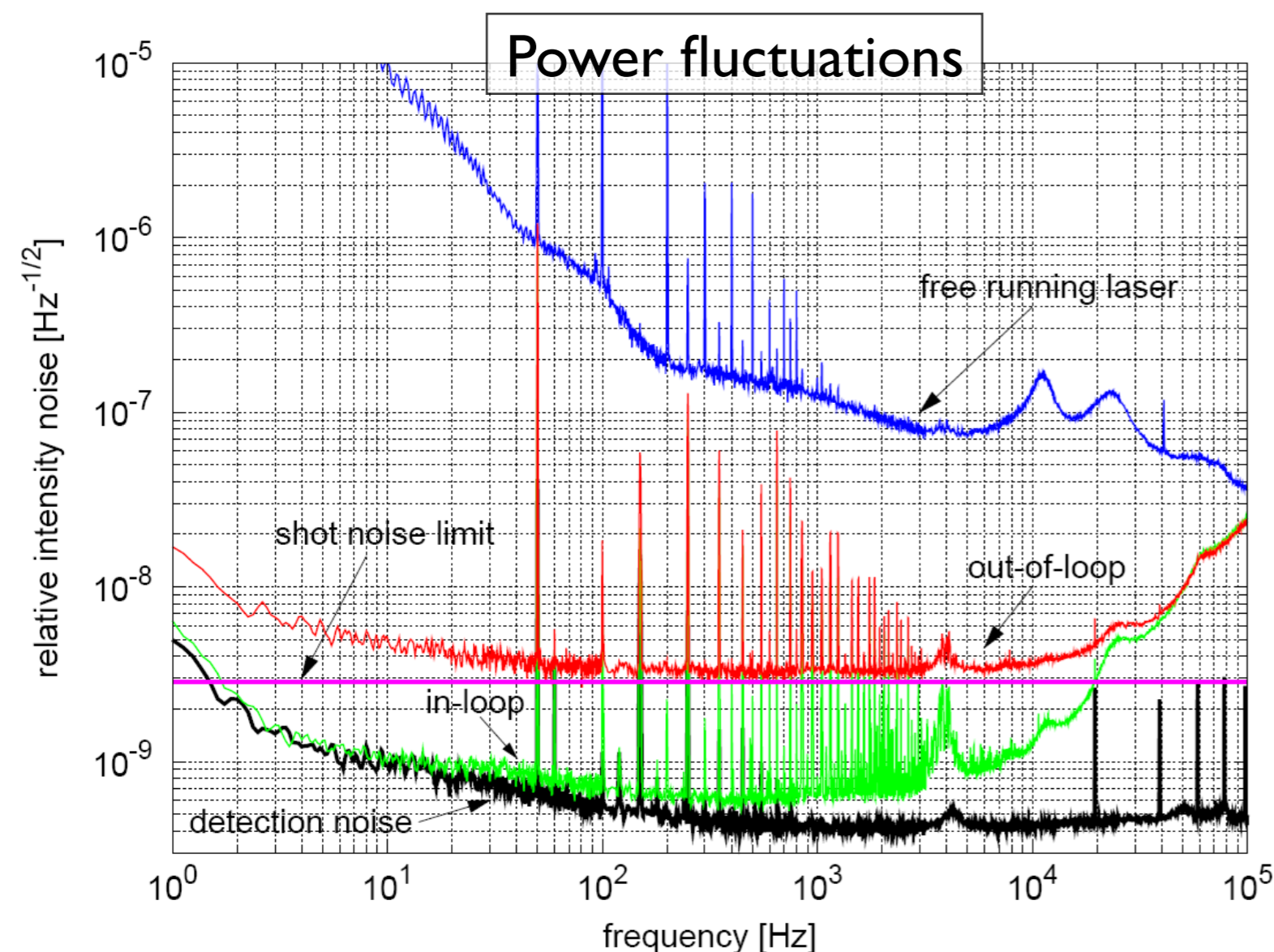
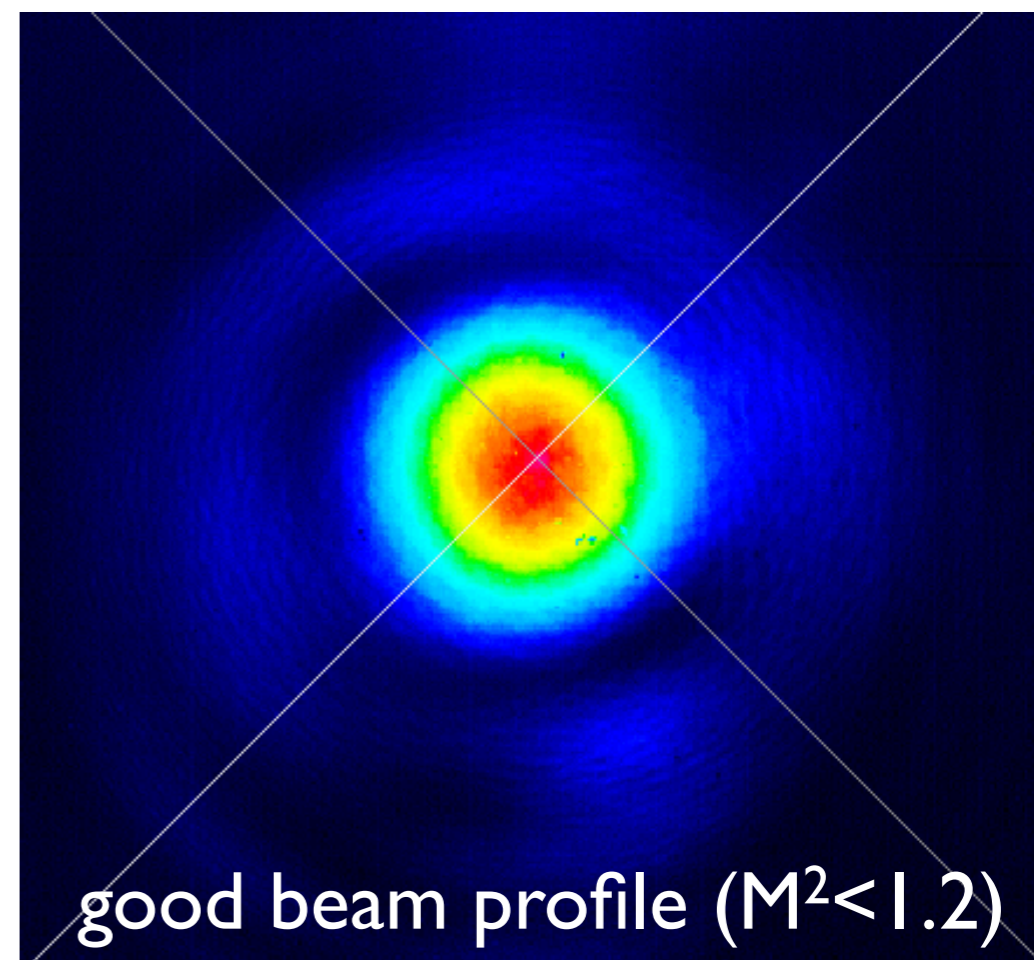
- 180 W with good beam shape
- 1064 nm (YAG)
- very low intensity and frequency noise
- Developed by Max-Planck Institute, Hanover & Laser Zentrum Hanover
- stable front end determines laser frequency and frequency fluctuations.
- high power stage, Injection seeded ring oscillator determines power, power fluctuations, and beam shape.

high-power injection-locked oscillator



## Achieved:

- 180 W output power
- good spatial profile
- power fluctuations close to requirement.



## Still to Verify:

- RIN at modulation freq.
- higher order mode content
- pointing fluctuations

# advancedligo Test Mass Requirements

Mass	40 kg, fused silica
Dimensions	340 mm x 200 mm
Surface figure	< 1 nm rms
Micro-roughness	< 0.1 nm rms
Double-pass optical homogeneity	< 20 nm rms,
Bulk absorption	< 3 ppm/cm <b>good enough for Thermal Comp. System</b>
Bulk mechanical loss	< $3 \times 10^{-9}$
Optical coating: Titania doped Tantalum/ silica	
Optical coating absorption	< 0.5 ppm(required) < 0.2 ppm(goal) <b>small samples OK</b>
Optical coating mechanical loss	< $2 \times 10^{-4}$ (required) < $3 \times 10^{-5}$ (goal) <b>measured <math>8.5 \times 10^{-5}</math></b>
Optical coating scatter	< 2 ppm(required) < 1 ppm(goal) <b>not yet...</b>
Arm cavity optical loss / round trip	< 75 ppm

# advancedligo Test Mass Requirements

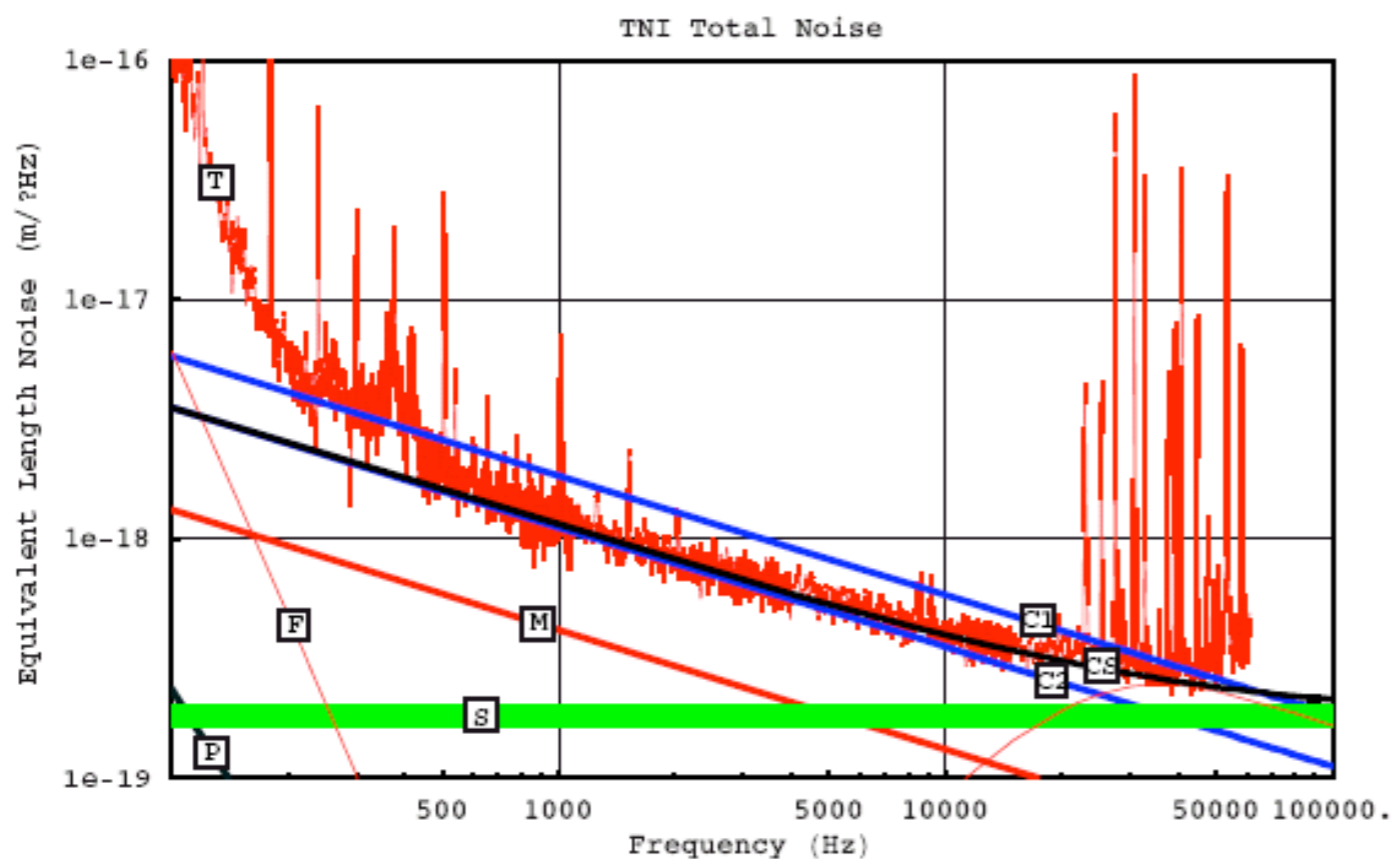
Mass	40 kg, fused silica
Dimensions	340 mm x 200 mm
Surface figure	< 1 nm rms
Micro-roughness	< 0.1 nm rms
Double-pass optical homogeneity	< 20 nm rms,

good enough for Thermal Comp. System

quired) < 0.2 ppm(goal) small samples OK

quired) <  $3 \times 10^{-5}$  (goal) measured  $8.5 \times 10^{-5}$

quired) < 1 ppm(goal) not yet...

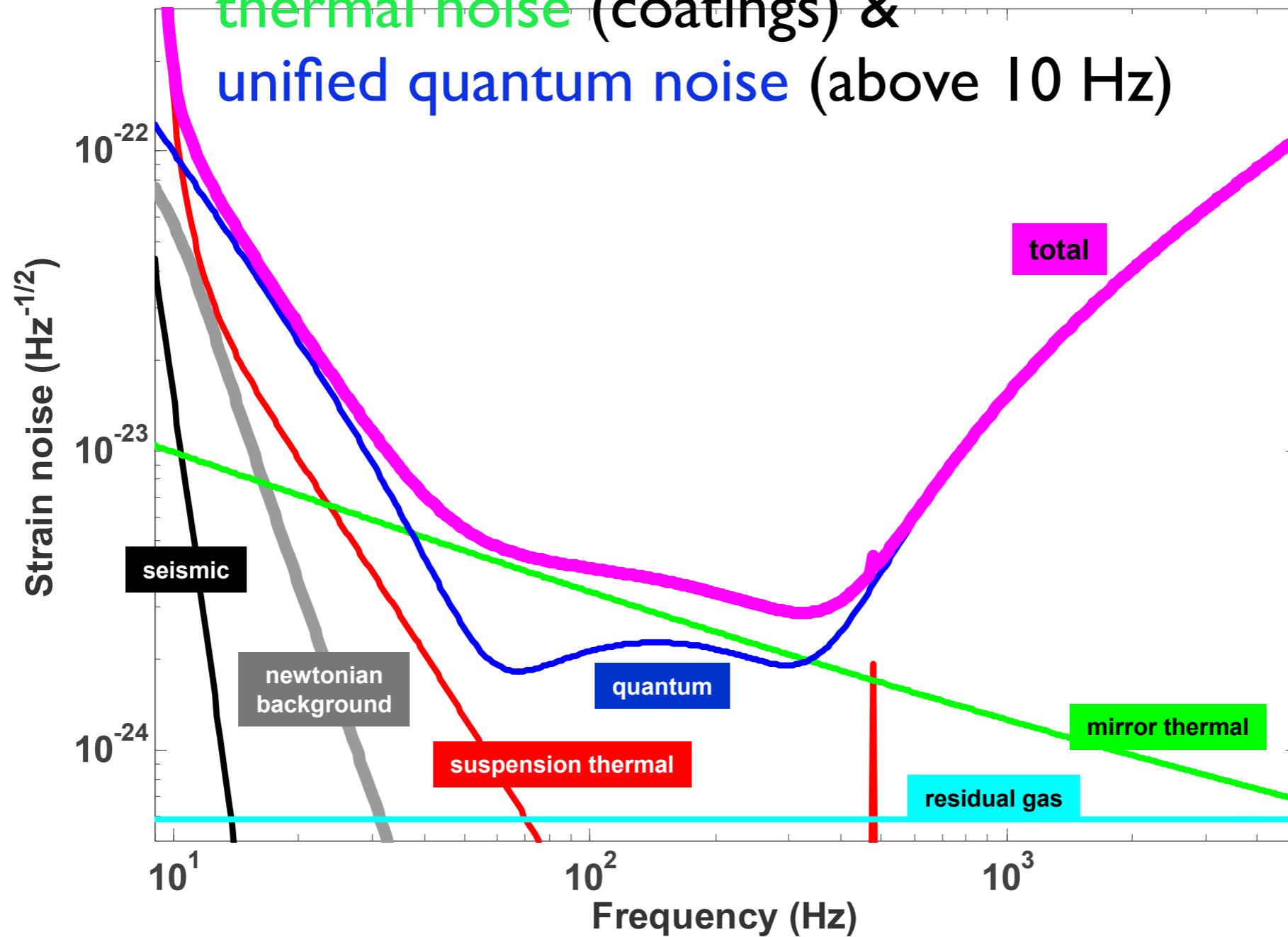


# and more...

- End-to-end model
- Sensing and control for all length and angle DOFs
- Big computing pipeline for both instrument control and for data analysis.
- output mode cleaner (CIT 40 meter lab)
- high power input optics (Univ. Florida)
- 40 m lab & Thermal noise interferometer at Caltech, LASTI at MIT, high-power test facility at Gingin, 10 meter lab at Univ. Glasgow, ETF at Stanford, the LIGO and GEO observatories...

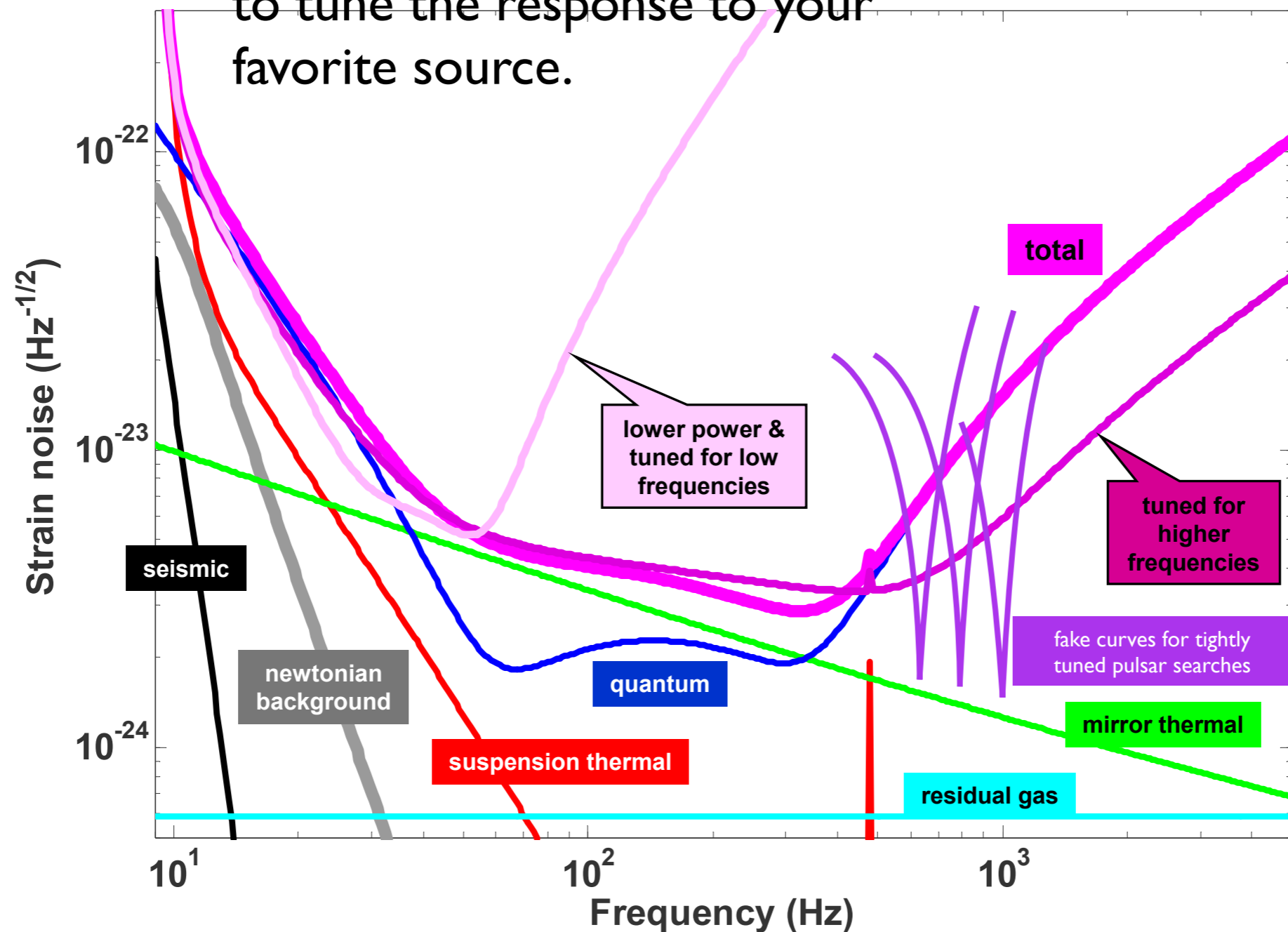
# Tuning

Instrument noise floor set by  
 thermal noise (coatings) &  
 unified quantum noise (above 10 Hz)



# Tuning

Signal recycling mirror makes it possible to tune the response to your favorite source.



When we start measuring gravitational waves, this flexible instrument can be directed towards many different astrophysical goals.

# in Conclusion...

- LIGO science collaboration is large and active,
- We've developed a tremendous amount of new technology,
- We now have the technology in hand to make a fantastic new instrument, and
- We'll be ready to start construction next fall.

**The astrophysics will be great!**