



SenseMonitor: Plans for S4+

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SenseMonitor

- SNR-based figure-of-merit monitor for the LIGO IFOs
- Real-time range estimates:

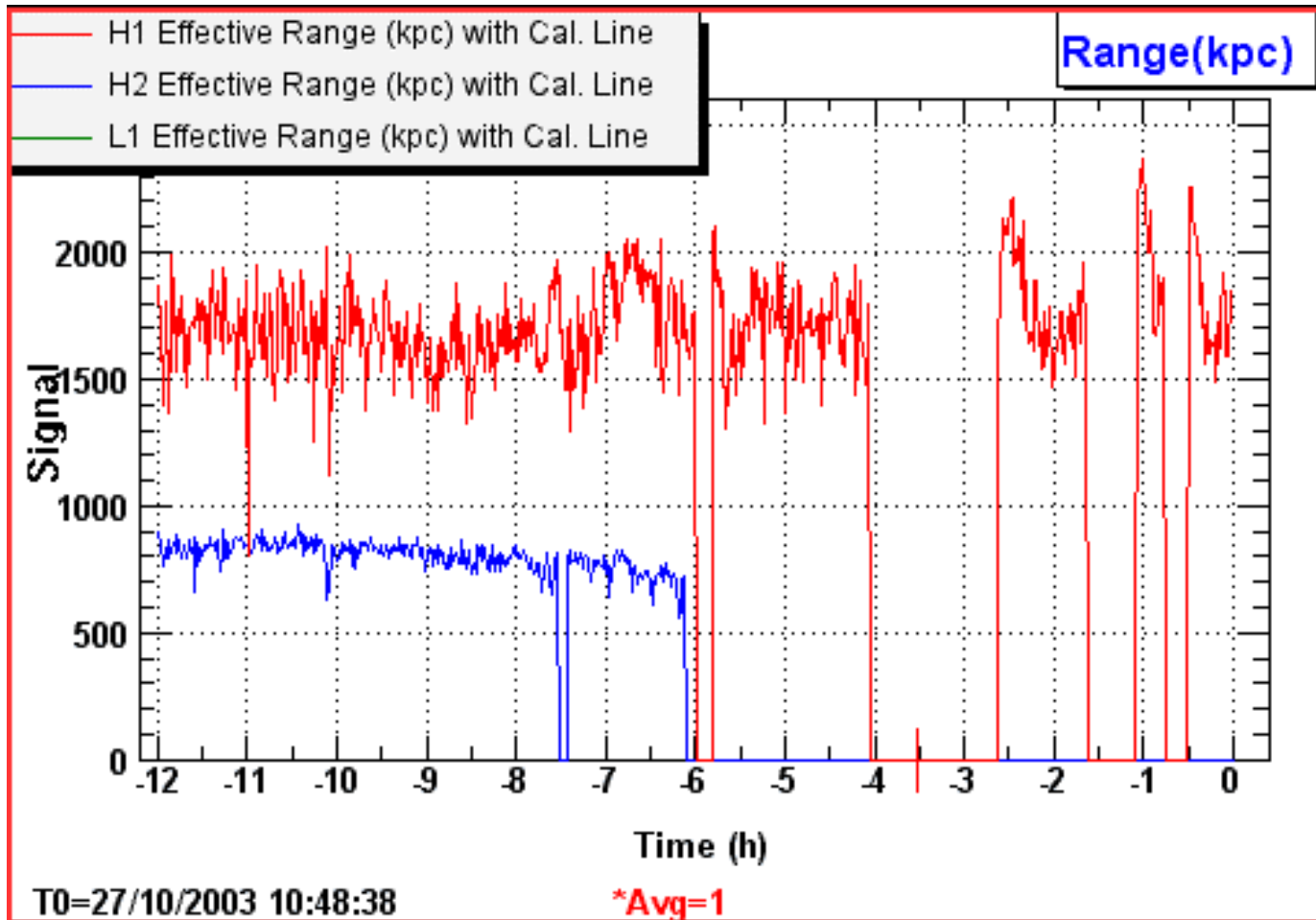
$$r = \left(\frac{5\mathcal{M}^{5/3}\theta^2}{96\pi^{4/3}\rho_0^2} \int_{30\text{Hz}}^{1400\text{Hz}} df \frac{f^{-7/3}}{S_h(f)} \right)^{1/2}$$

The equation is annotated with pink text and arrows:

- chirp mass** points to \mathcal{M}
- angle factor** points to θ^2
- SNR threshold** points to the denominator $96\pi^{4/3}\rho_0^2$
- strain noise** points to $S_h(f)$
- inspiral signal** points to the numerator $f^{-7/3}$

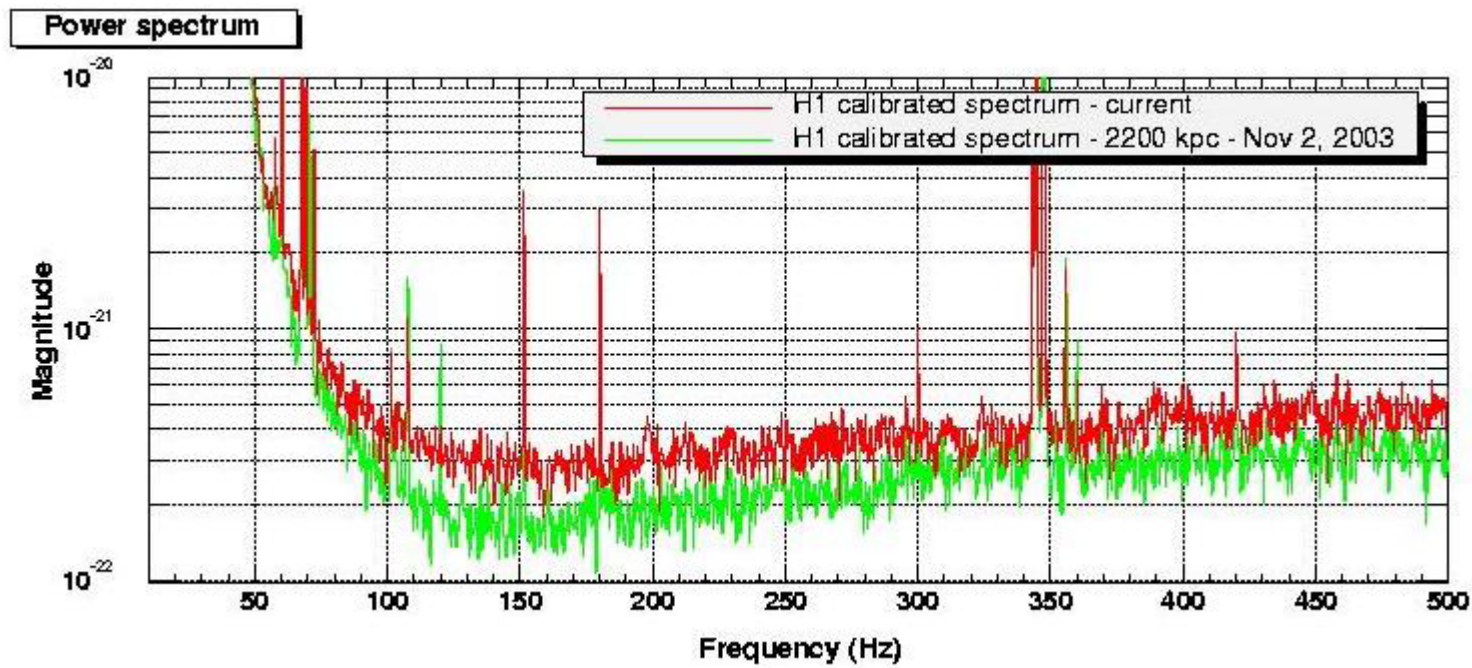
- SenseMonitor uses $M_1 = M_2 = 1.4 M_\odot$, $\rho_0=8$.

SenseMonitor in S3

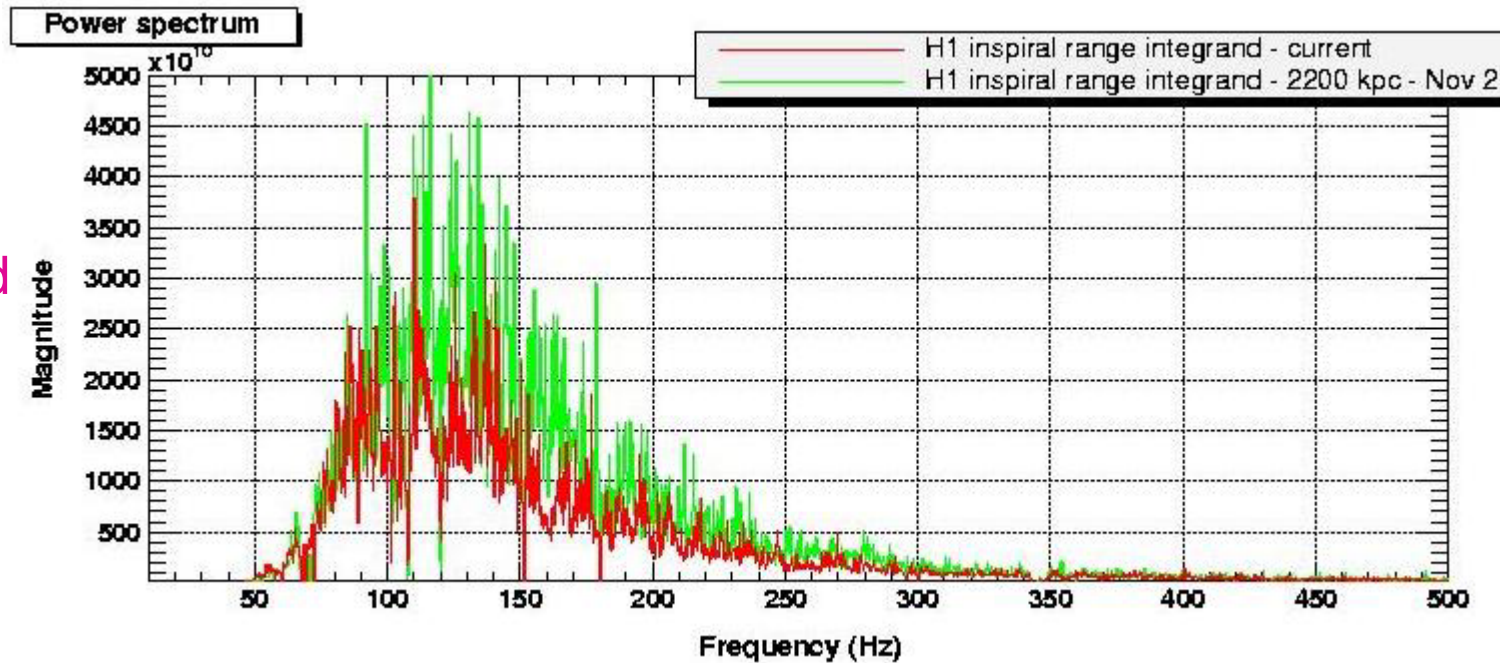


range estimates, calibrations

strain noise
spectrum $S(f)$



range integrand
 $f^{-7/3} / S(f)$



What's new for S4

By popular demand...

- Implement new calibration classes.
 - » makes use of monitor much easier to run
- Additional FOM: range to $10M_{\odot}$ - $10M_{\odot}$ binary black-hole inspiral
 - » samples very-low-frequency portion of noise spectrum ($f < \sim 200\text{Hz}$)



Summary

- See previous slide.