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# Waveform Consistency Test in Burst Detection

Laura Cadonati  
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# Test goal

The LIGO Burst Search pipeline uses *Event Trigger Generators (ETGs)* to flag times when “something anomalous” occurs in the strain time series

⇒ **burst candidate events** ( $\Delta t$ ,  $\Delta f$ , SNR)

Events from the three LIGO interferometers are brought together in coincidence (time, frequency, power).

In order to use the full power of a coincident analysis:

- » Are the waveforms consistent? To what confidence?
- » Can we suppress the false rate in order to lower thresholds and dig deeper into the noise?

Cross correlation of coincident events

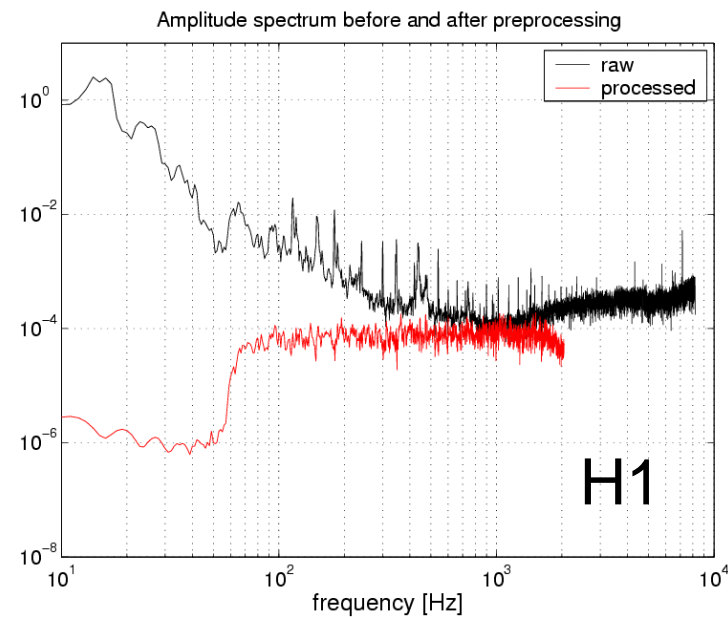
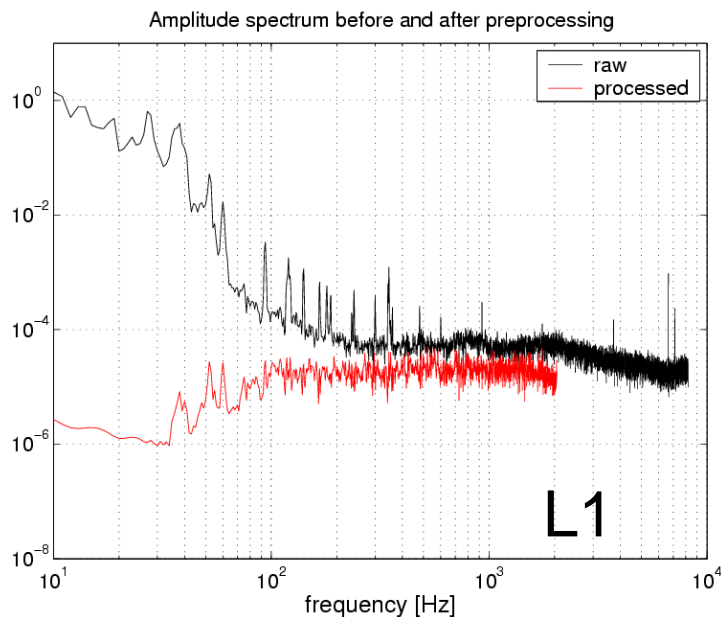


# Data Conditioning

Decimate and high-pass few seconds of data around event  $\Rightarrow$  100-2048 Hz

Remove predictable content (effective whitening/line removal): train a linear predictor error filter over 1 s of data (1 s before event start), apply as second order sections model using zero-phase filtering - described in S. Chatterji's talk on data conditioning (LIGO-G030439)

$\Rightarrow$  emphasis on transients, avoid non-stationary, correlated lines.



# r-statistic

$$r = \frac{\sum_i (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_i (x_i - \bar{x})^2} \sqrt{\sum_i (y_i - \bar{y})^2}}$$

Linear correlation coefficient or normalized cross correlation for the two series  $\{x_i\}$  and  $\{y_i\}$

NULL HYPOTHESIS: the two (finite) series  $\{x_i\}$  and  $\{y_i\}$  are uncorrelated

⇒ Their linear correlation coefficient (**Pearson's r**) is normally distributed around zero, with  $\sigma = 1/\sqrt{N}$  where N is the number of points in the series ( $N \gg 1$ )

$$S = \text{erfc}(|r| \sqrt{N/2})$$

double-sided significance of the null hypothesis

i.e.: probability that  $|r|$  is larger than what measured, if  $\{x_i\}$  and  $\{y_i\}$  are uncorrelated

$$C = -\log_{10}(S)$$

confidence that the null hypothesis is FALSE ⇒ that the two series are correlated

# Delay and Integration Time

## What delay?

Shift  $\{y_i\}$  vs  $\{x_i\}$  and calculate:  $r_k$ ;  $S_k$ ;  $C_k$   
 ...then look for the maximum confidence  $C_M$   
 Time shift for  $C_M$  = delay between IFOs  
 Shift limits:  $\pm 10$  ms (LLO-LHO light travel time)

$$r_k = \frac{\sum_i (x_i - \bar{x})(y_{i+k} - \bar{y})}{\sqrt{\sum_i (x_i - \bar{x})^2} \sqrt{\sum_i (y_{i+k} - \bar{y})^2}}$$

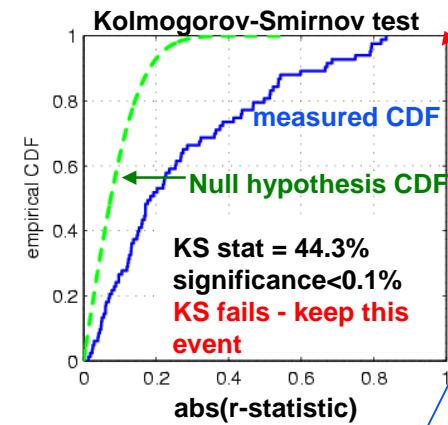
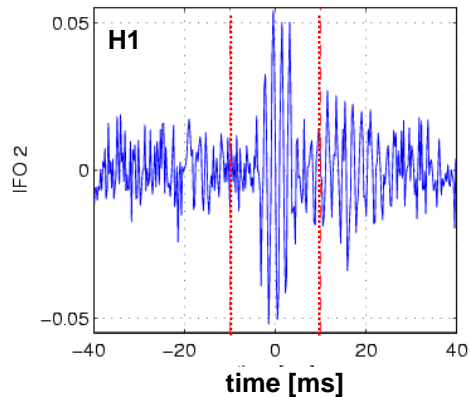
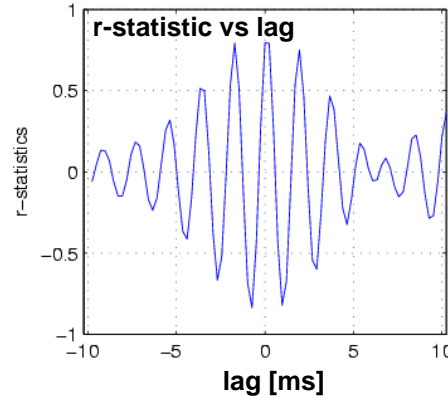
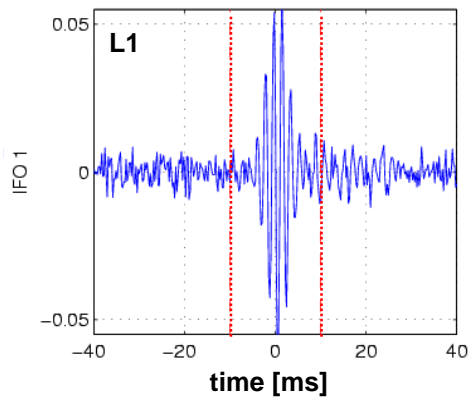
Integration time  $\tau$ :

## How long?

- » If too small, we lose waveform information and the test becomes less reliable
- » If too large, we wash out the waveform in the cross-correlation

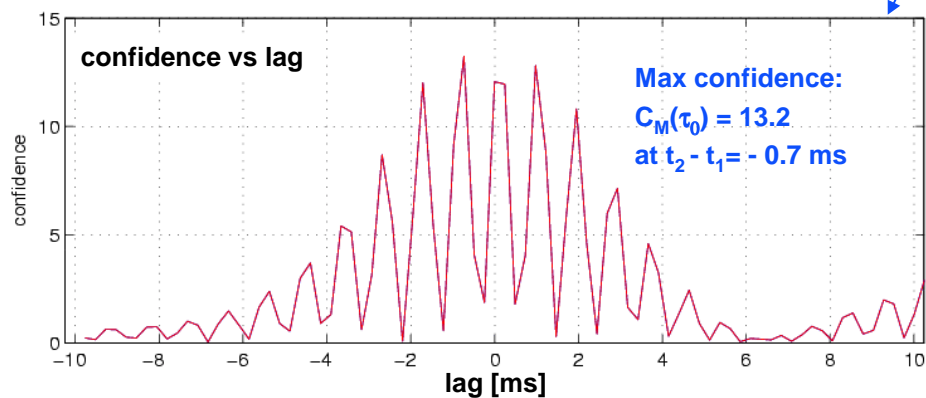
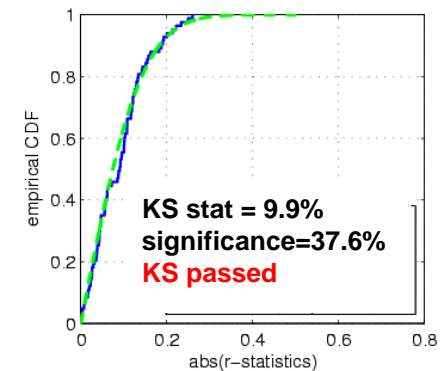
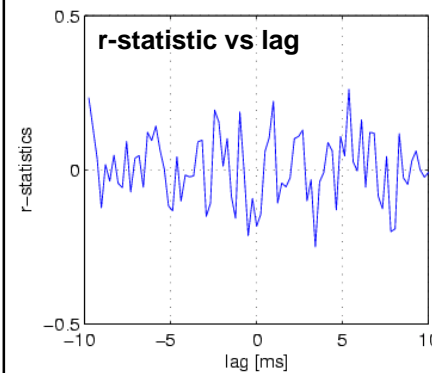
**Test different  $\tau$ 's and do an OR of the results** (20ms, 50ms, 100ms)

Simulated Sine-Gaussian  $Q=9$ ,  $f_0=554\text{Hz}$  (passed through IFO response function)  
 $h_{\text{peak}}=1\text{e-}18$  [strain];  $h_{\text{rss}}=5\text{e-}20$  [strain/rtHz]

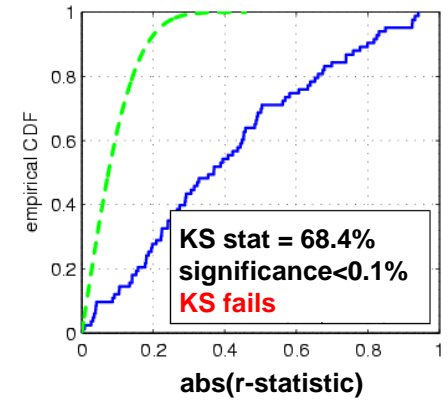
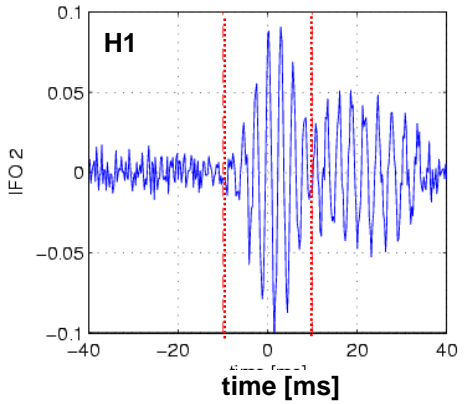
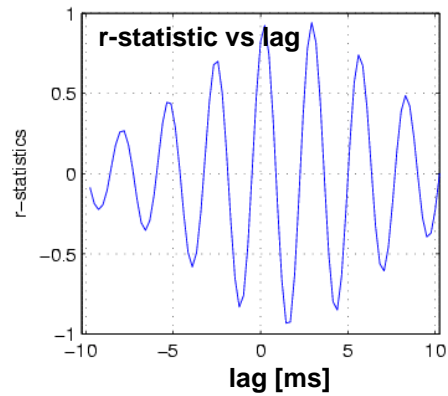
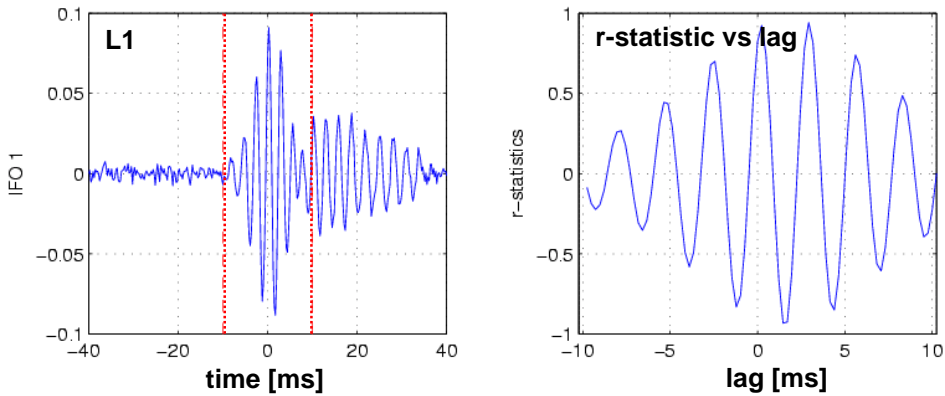


- L1-H1 pre-processed waveforms and r-statistic plot
  - integration time  $\tau = 20$  ms,
  - centered on the signal peak time.
- a Kolmogorov-Smirnov (KS) test states the  $\{r_k\}$  distribution is NOT consistent with the null hypothesis.
  - » there is less than 0.1% probability that this distribution is due to uncorrelated series.
- On to the calculation of the confidence series and of its maximum  $C_M(j)$

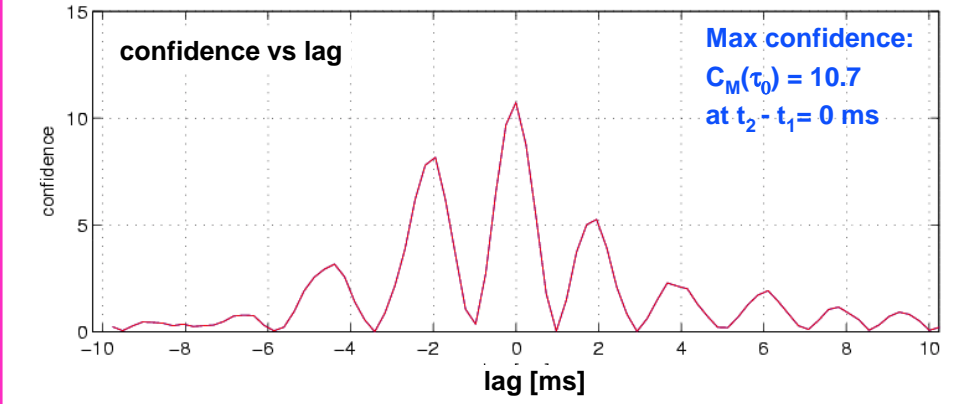
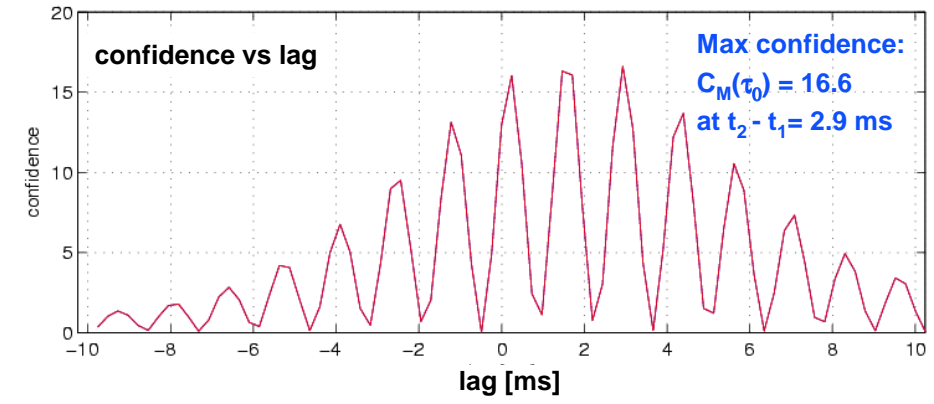
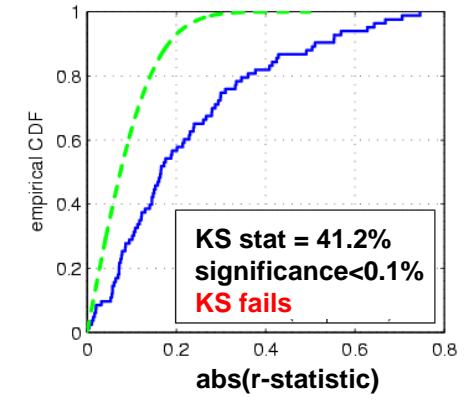
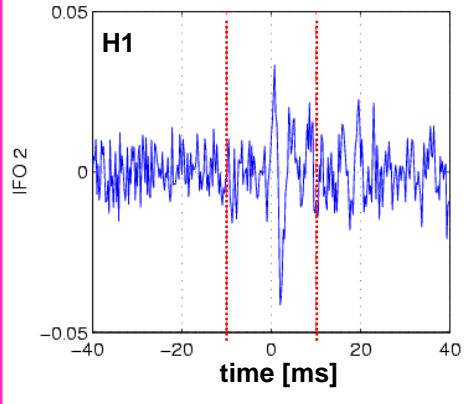
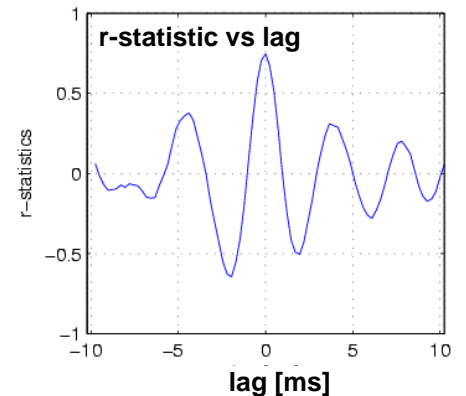
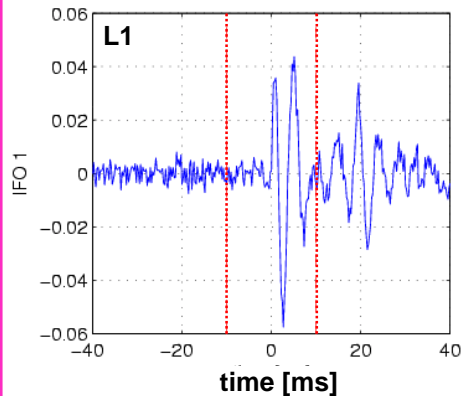
### Noise only (no added signal)



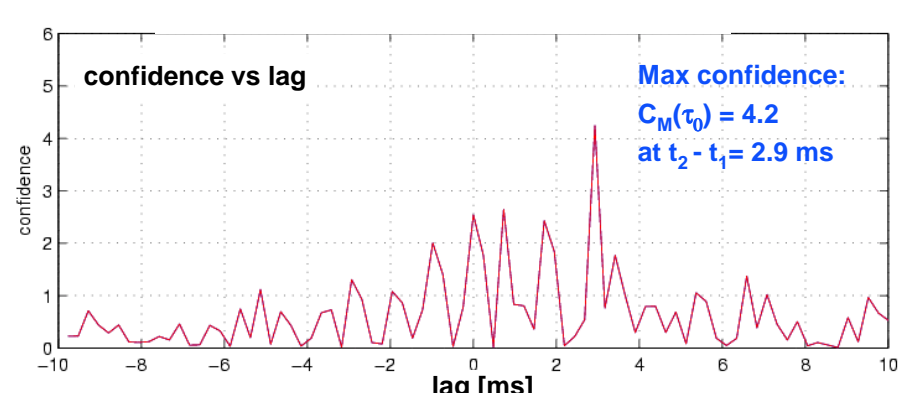
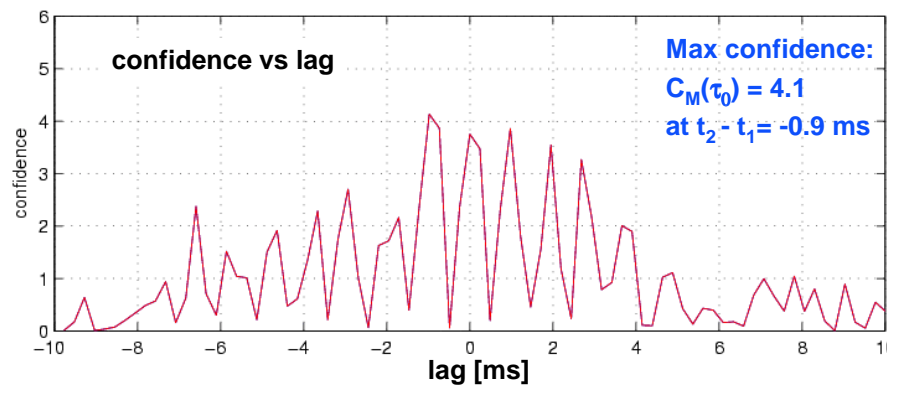
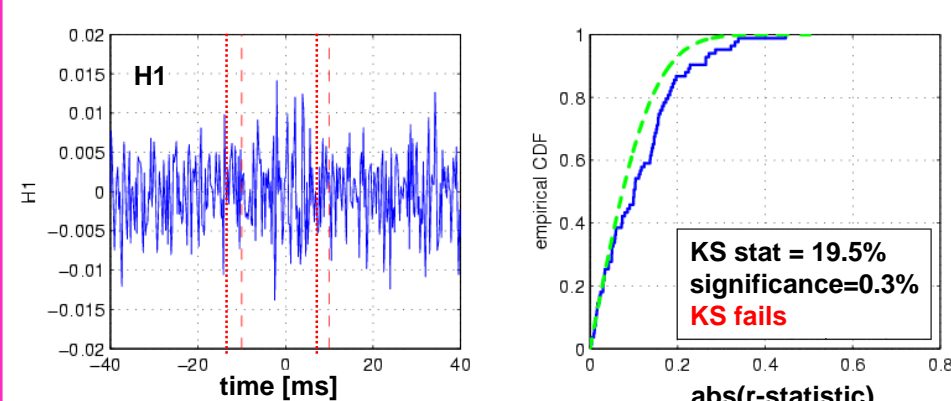
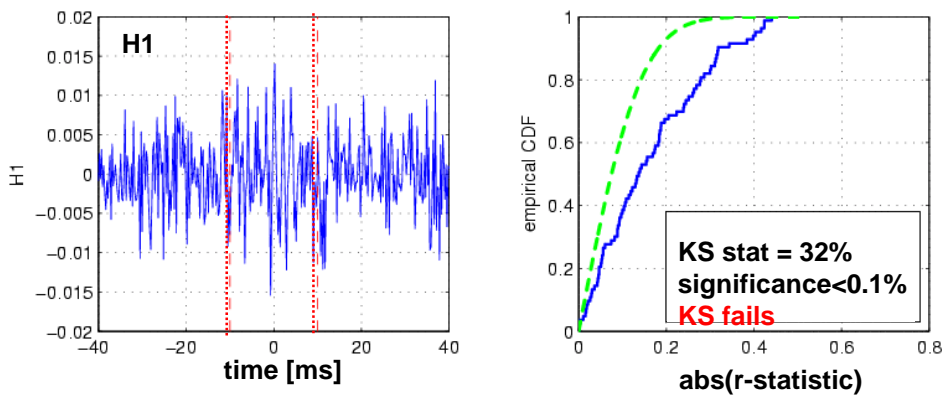
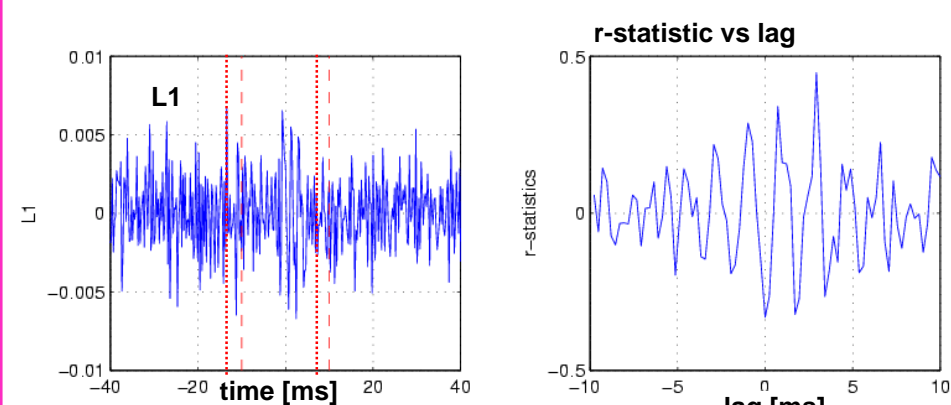
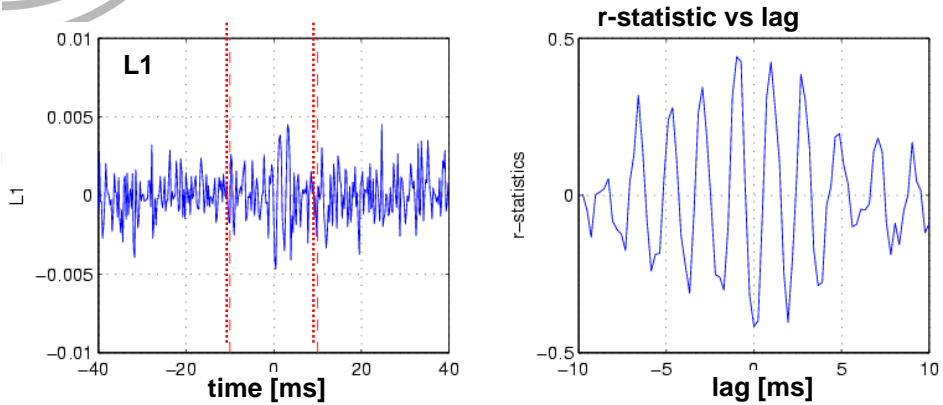
**Simulated Sine-Gaussian  $Q=9$ ,  $f_0=361\text{Hz}$   
(passed through IFO response function)  $h_{\text{peak}}=1\text{e-}18$**



**Simulated 1 ms Gaussian  
(passed through IFO response function)  $h_{\text{peak}}=1\text{e-}18$**



Hardware injection Sine-Gaussian  $Q=9, f_0=554\text{Hz}$  - April 9 2003  
 $h_{\text{peak}} \sim 1e-18$   $h_{\text{peak}} \sim 6e-21$  [strain/rtHz]

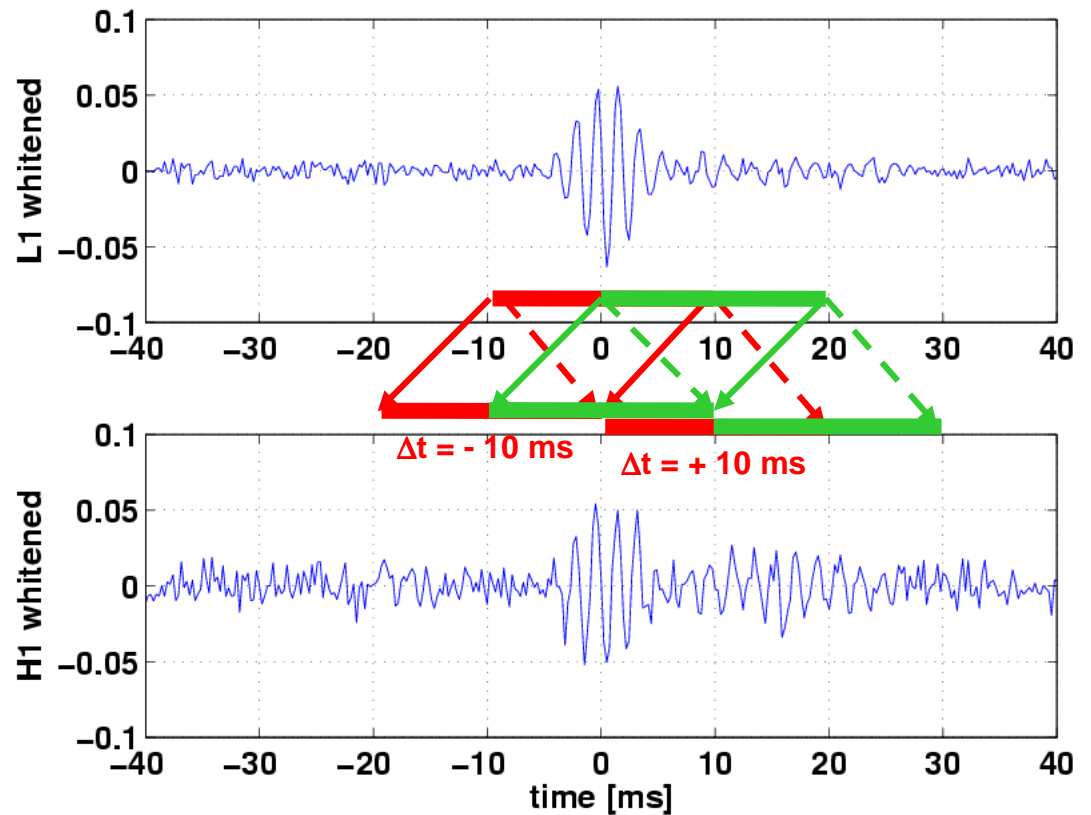


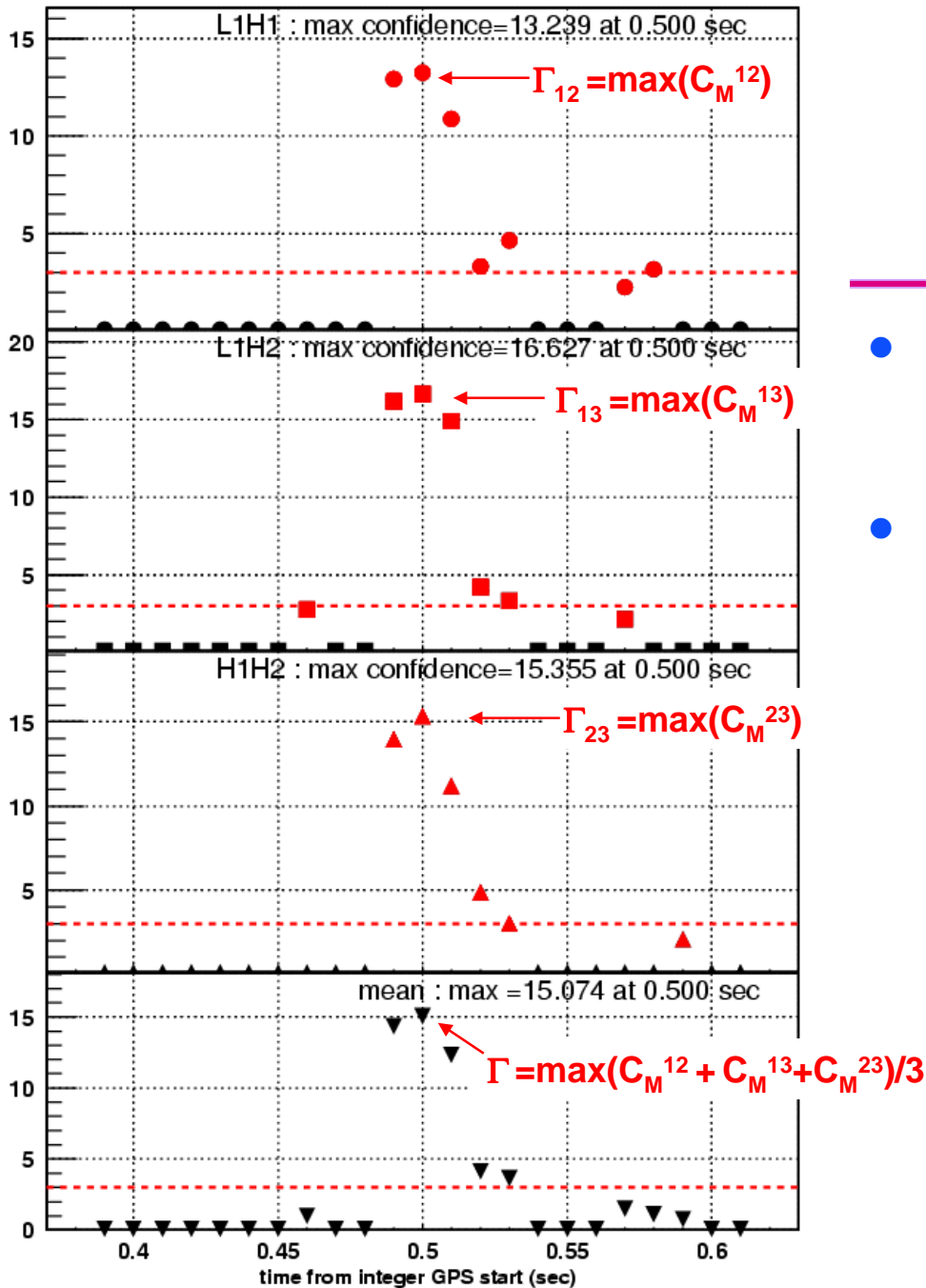
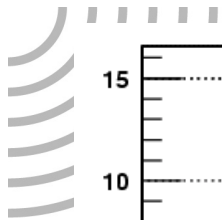




# Scanning the Trigger Duration $\Delta T$

- » Partition trigger in  $N_{\text{sub}} = (2\Delta T/\tau) + 1$  subsets and calculate  $C_M(j)$  ( $j=1.. N_{\text{sub}}$ )
- » Use  $\Gamma_{ab} = \max_j(C_M(j))$  as the correlation confidence for a pair of detectors over the whole event duration





# $C_M(j)$ plots

- Each point: max confidence  $C_M(j)$  for an interval  $\tau$  wide (here:  $\tau = 20\text{ms}$ )
- Define a cut (pattern recognition?):  
 2 IFOs:  
 $\Gamma = \max_j(C_M(j)) > \beta_2$   
 3 IFOs:  
 $\Gamma = \max_j(C_M^{12} + C_M^{13} + C_M^{31})/3 > \beta_3$

In general, we can have  $\beta_2 \neq \beta_3$   
 $\beta=3$ : 99.9% correlation probability



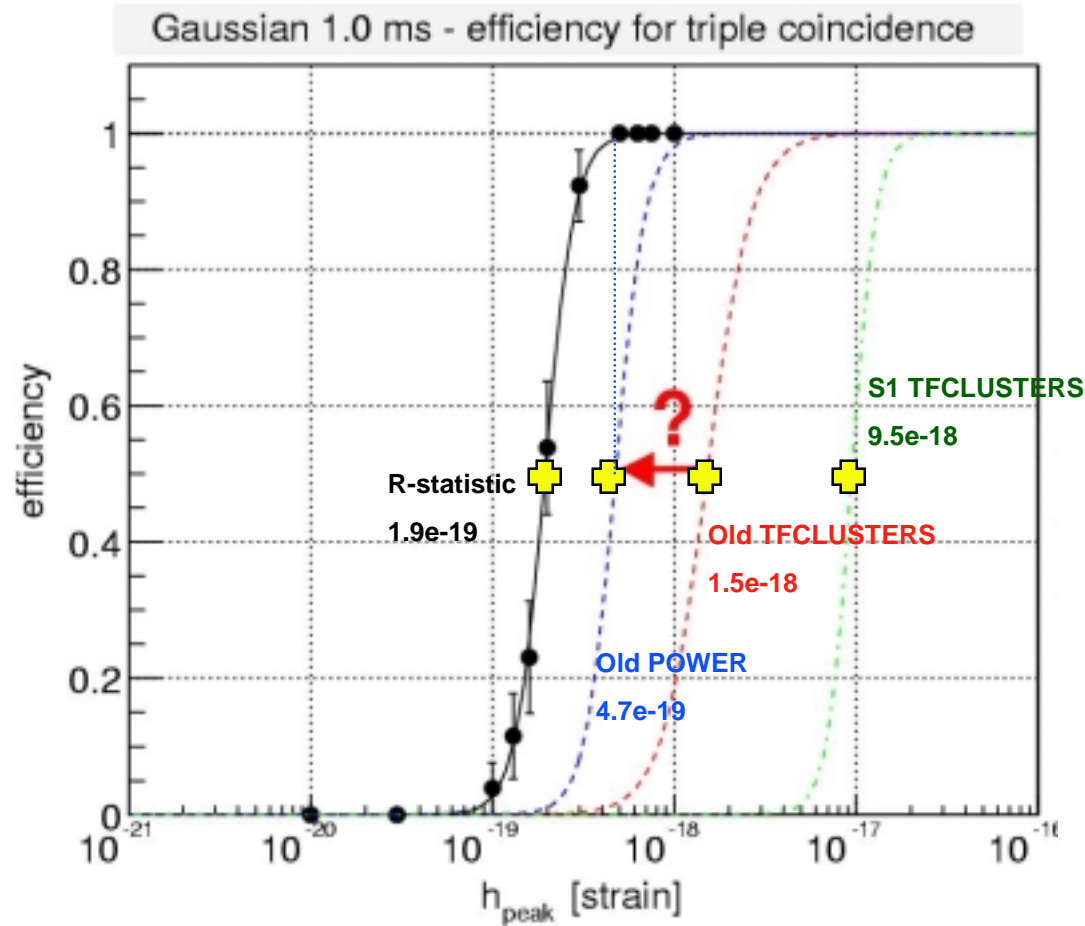
# Open Issues

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- Calibration
  - » Needed to account for waveform distortions due to frequency-dep calibration
- Time resolution
  - » Depends on waveform
  - » Affected by detector response function
    - Implement phase calibration to match IFOs?
  - » Affected by pre-processing filters
    - Do a second test pass with less aggressive filters?
  - » At the moment, no use is made of the delay time in assessing the confidence
    - Implement a T-statistic test?



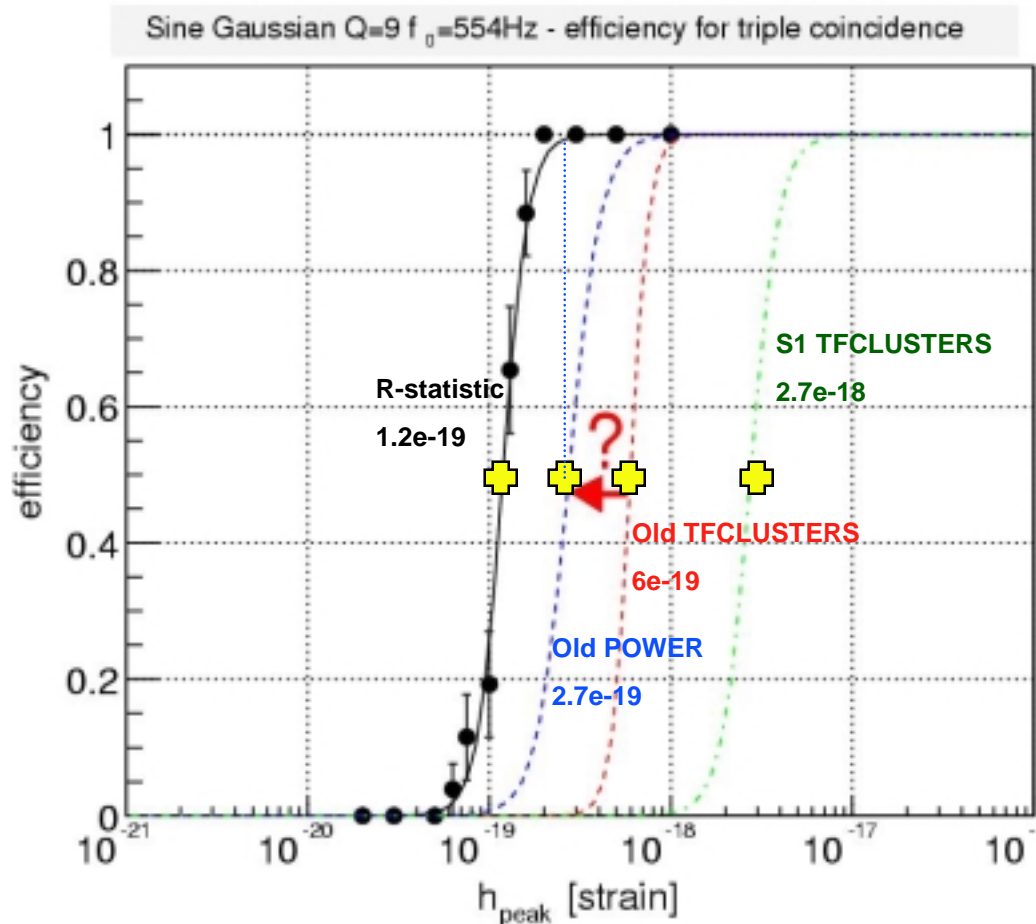
# Triple-coincidence efficiency for 1 ms gaussians



- Same amplitude event injected in L1, H1, H2
- 0.2 sec around the injection time passed through the r-test.
- Sigmoid fit to efficiency curve:  
50% at  $h_{\text{peak}} = 2 \times 10^{-19}$



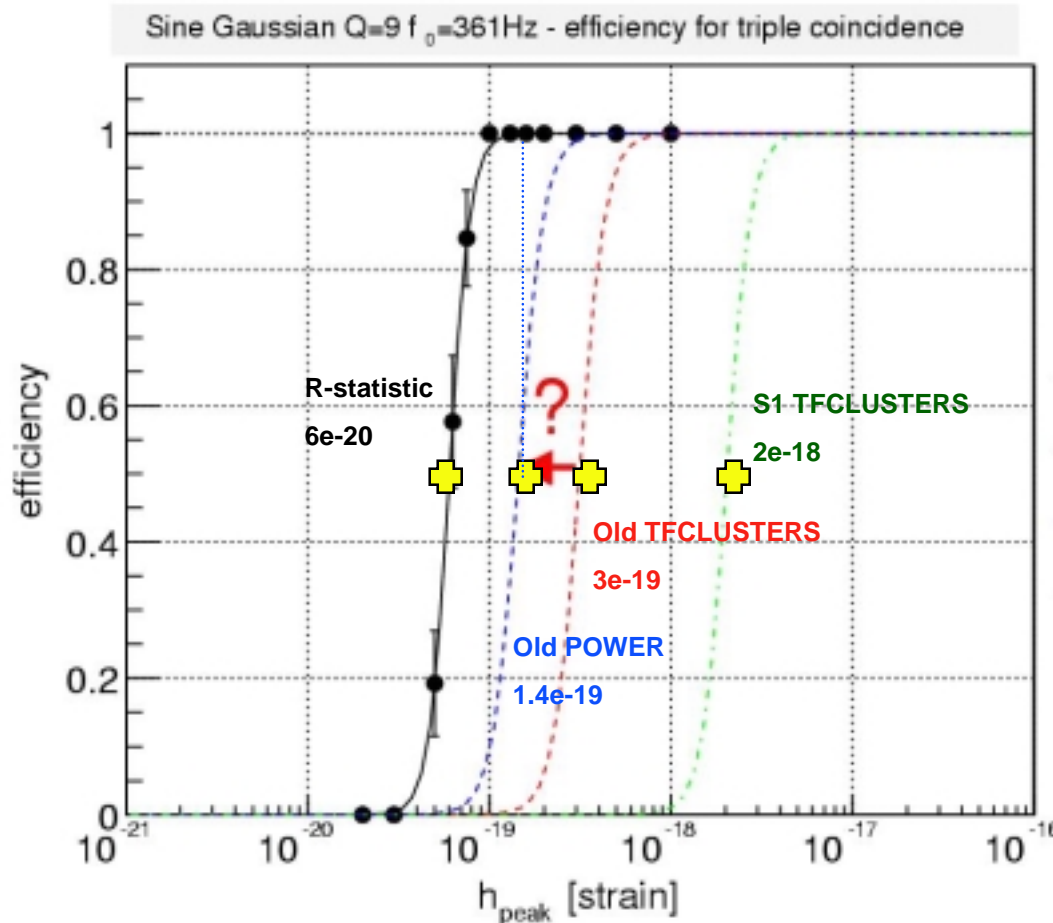
# Triple-coincidence efficiency for 554 Hz Q=9 sine gaussians



- Same amplitude event injected in L1, H1, H2
- 0.2 sec around the injection time passed through the r-test.
- Sigmoid fit to efficiency curve:  
50% at  $h_{\text{peak}}=1.2e-19$   
 $h_{\text{rss}}=6e-21$  strain/rtHz



# Triple-coincidence efficiency for 361 Hz Q=9 sine gaussians



- Same amplitude event injected in L1, H1, H2
- 0.2 sec around the injection time passed through the r-test.
- Sigmoid fit to efficiency curve:  
50% at  $h_{\text{peak}}=6e-20$   
 $h_{\text{rss}}=3.6e-21$  strain/rtHz