

Adaptive Thermal Compensator Retrofit for Initial LIGO Interferometers

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3/31/03

rev -01, 4/1/03

Problem

- Currently achieve only 6% sideband coupling--> shot noise high by factor of ~ 3 in strain
- RM polished "too flat" by design; thermal lensing in ITM's relied on to stabilize recycling cavity for sidebands
- Designed for "exactly" 25 mW ($\pm?$) heat in each ITM
 - 15mW < bulk substrate absorption of 150W in RC (x2)
 - 10mW < surface absorption of 18 kW carrier in arm cavity
- Even at 'full power' we may fall short or overshoot
 - absorptions, circulating powers have substantial variation
 - MC transmission, laser output, contamination may vary over time
 - Even a lucky hit may not last
 - Unable to optimize shot noise given power we can get
- "Point Design" is *fragile*

What do we know now?

- H1: Probably too much lensing @ full power (?)
- H2: Can't really tell until bad ITM is replaced
- L1: Measurements not understood yet
- Bottom line: measurements need more work
 - Invasive methods (break lock) after S2
 - Use phase camera to look at SB field explicitly ?
 - Improved interpretation (explicit modeling?)

Possible Approach: New Tailored RM's

- Refine the point design:
 - Measure 'as-built' lensing vs. power in each IFO
 - Best technique & accuracy TBD
 - Model "full power" & back out best RM curvature
 - Grind, polish, coat, install, & retest
- Downsides:
 - Vulnerable to measurement and model errors
 - Minimum 6 months, \$much to get new RM's
 - H2 can't be measured reliably until after ITM replacement
 - Much downtime for install, degassing
 - Vulnerable to a new set of mfg. tolerances
 - Even if it works, you still have a *POINT DESIGN*

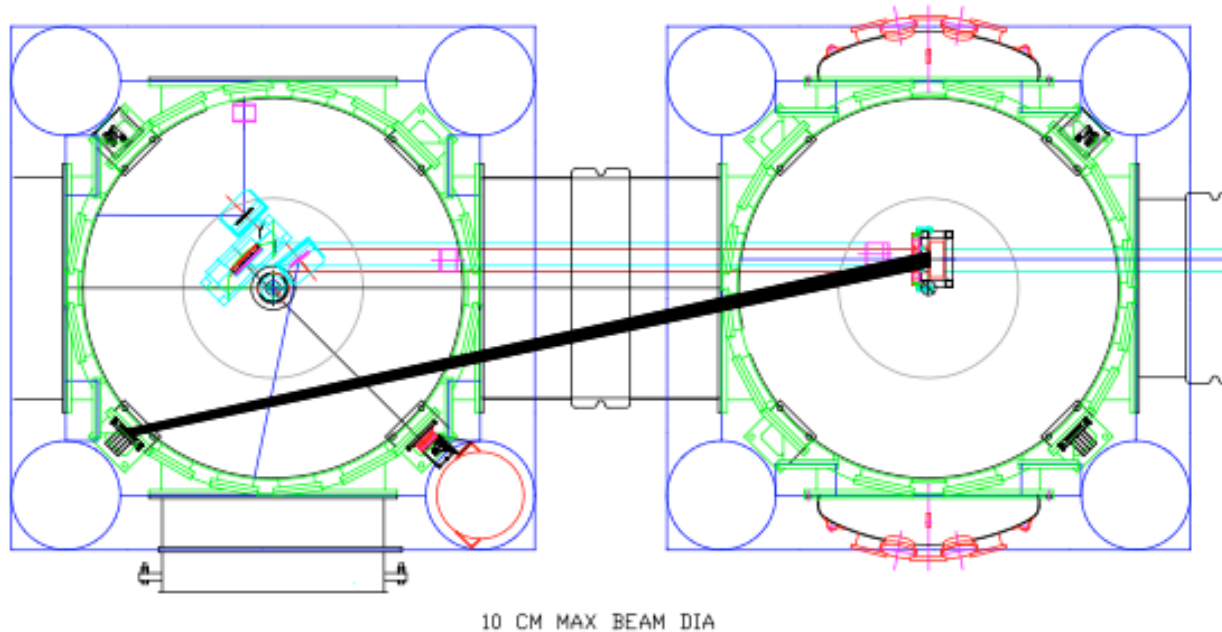
More Interesting: Adaptive Thermal Compensator

- Adds capabilities beyond "this problem"
 - Cold start @ full steady-state sensing matrix
 - Also "ride through" dropouts, perhaps better lock acquisition
 - No sign flips to dance through on REFL
 - Low-power diagnostics w/"lensed" sensing matrix
 - Soft failure on laser, COC, MC degradation
 - Future flexibility
- Proposed requirements:
 - Added noise $< \text{SRD}/10$
 - Noninvasive/minimally invasive installation
 - "Bipolar" lensing range
 - Optimize SB coupling down to ZERO main beam heating
 - Opposite (- lens) sign for excess beam heating (range TBD)

Compensator Approaches

- Initially favored "ring heater" concept
 - Simple & cheap (one already in GEO!), *but*:
 - "+" lensing variant needed; possible with shielding, but needs work (both "+" and "-" in same setup?)
 - Requires bolting something onto LOS
 - Human ingress, misalignment & damage potential, water degassing time...
 - No offline test facility: iterations require more ingress etc.
- Can we do it all from outside the VE?
 - Beam heater might involve only adding a viewport
 - Can do "+" and "-" lensing (at least in principle)
 - Can develop & iterate non-invasively

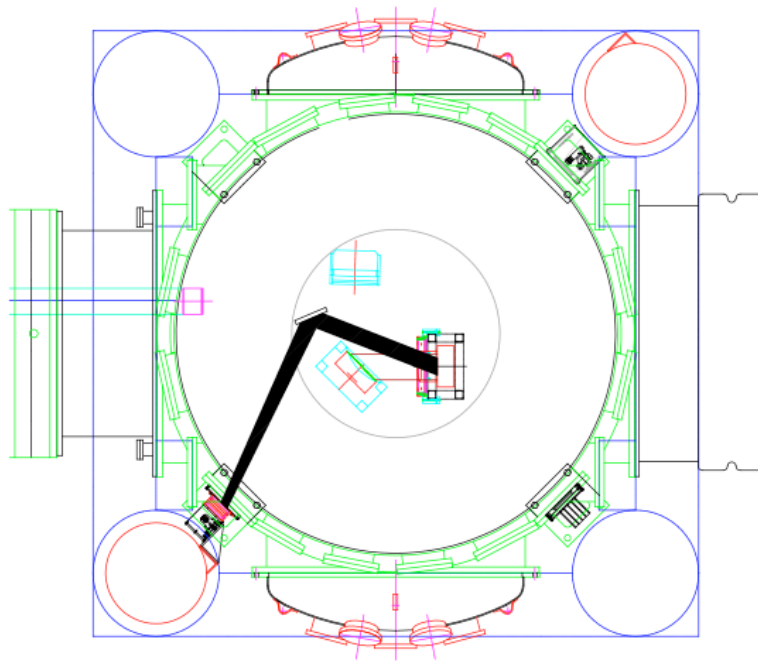
4k Beam Path



Aperture limited by elliptical baffle behind ITM

2" ZnSe viewport added (no entry planned)

2k Beam Path (internal relay)

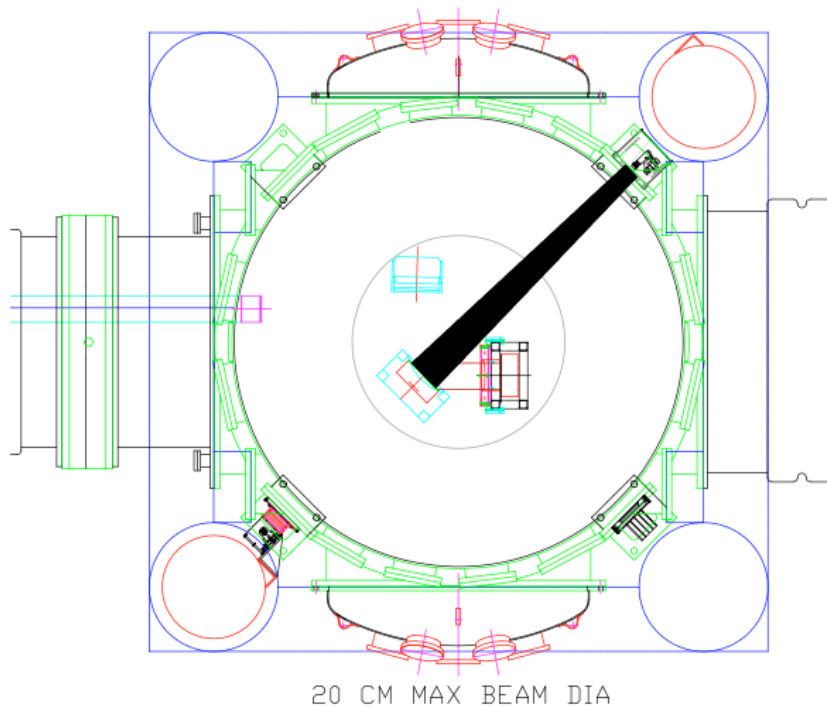


10 CM MAX BEAM DIA

Requires ingress & adding
(small) mass moment to
stack

Relay mirror is well
above IFO plane

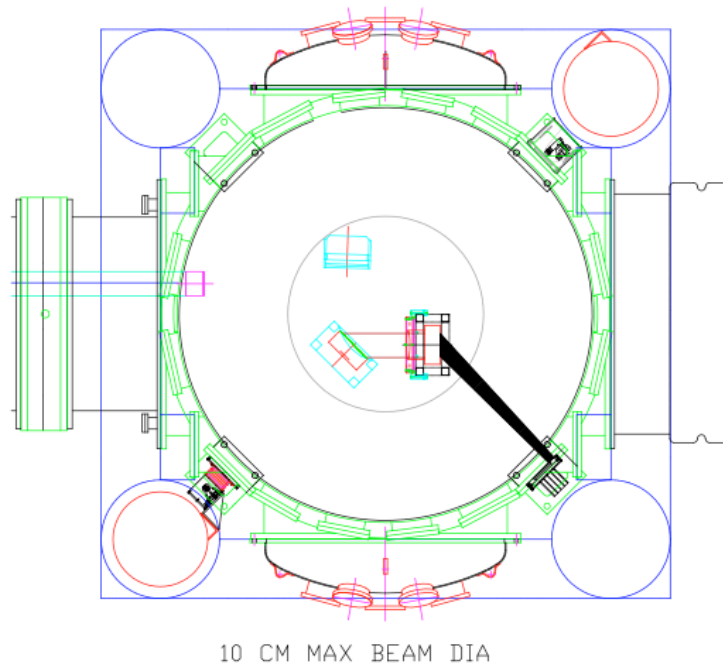
2k Beam Path (FM face)



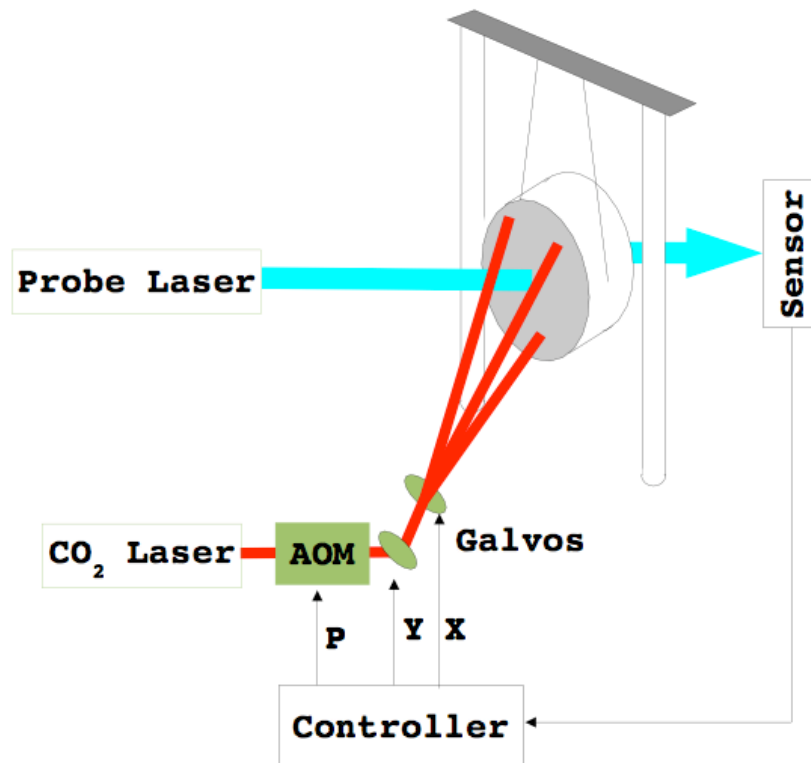
Requires $\sim 20x$ power for comparable effect

'Bowling' effect makes net concave hard to achieve

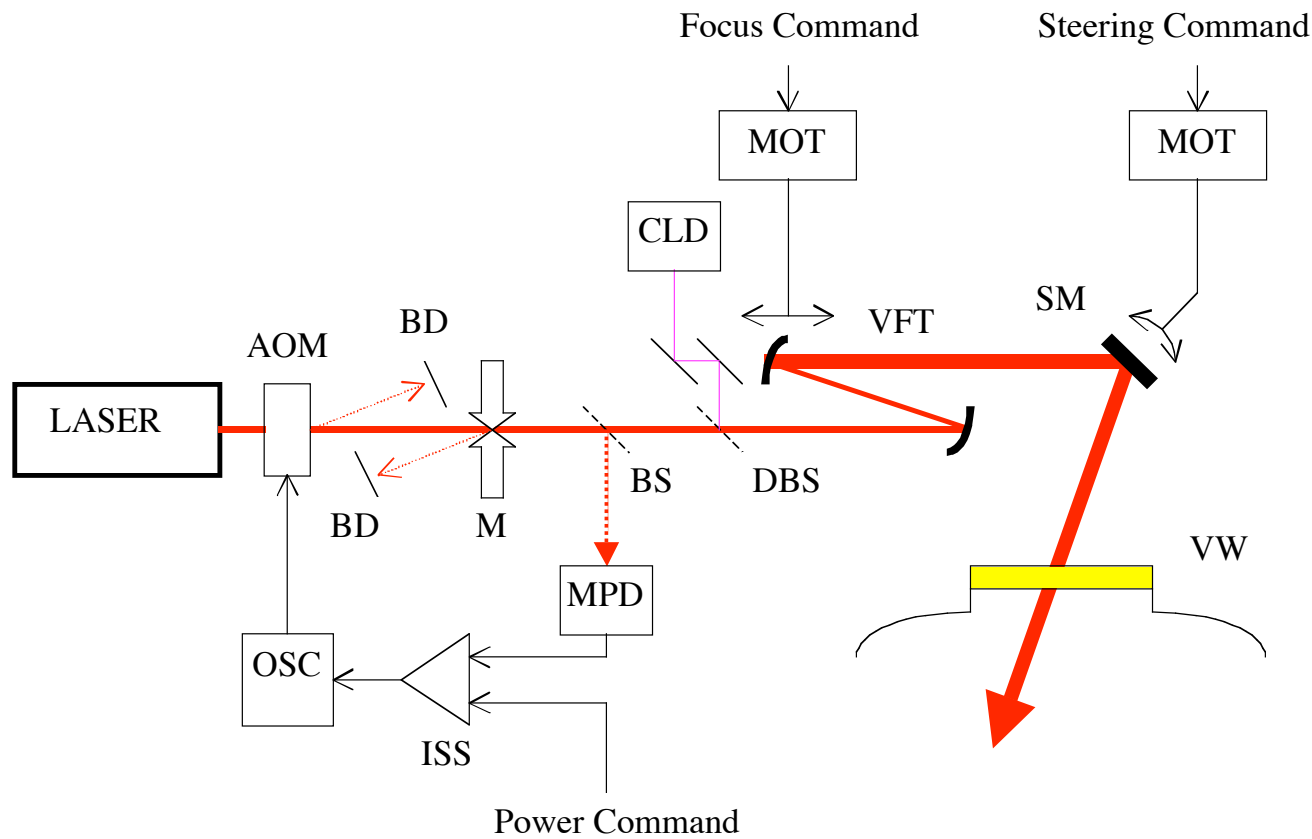
ITM face path



"Scanning" beam actuator



"Staring" beam heater concept



Main Features

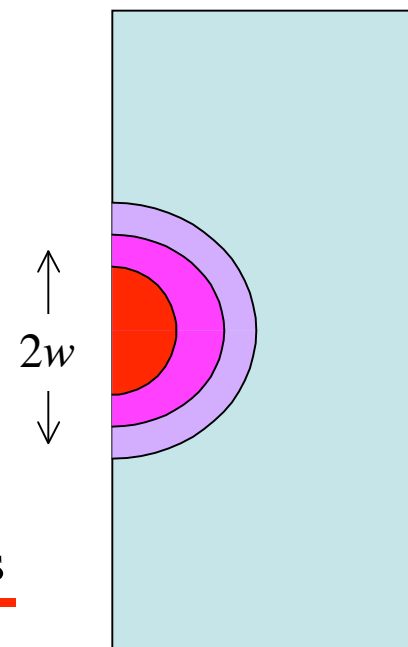
- Laser: 10-30W CW TEM₀₀ CO₂ (10.6 μm)
- Ge AOM: intensity stab., power selection
- Reflective mask: intensity profile & astigmatism compensation (power to burn)
- Relay optics (adj. focus/pattern size, pos'n)
- Pilot laser: visible LD w/pattern generator

Issues/Challenges

- Feasible limit of "negative" compensation?
 - 10 cm clear aperture limits "edge" heating
- Can you really do anything with the FM?
- Intensity stabilization of CO₂ laser
 - Direct actuation on ITM couples heat to Δx
 - Radiation pressure
 - Thermal expansion (if cavity surface is heated)
 - Index variation

Laser AM for SRD/10 (crude estimate)

- External radiative time constant $\sim 2\text{h}$, so behavior \sim infinite silica half space; local transport dominated by conduction
- Thermal volume of radius w equilibrates to center-edge temp. rise ΔT_w , with time constant τ_w
- Laser power variation \Rightarrow OPD fluctuation over this volume, filtered by τ_w (also surface deformation; 5x worse effect if actuating HR face, negligible for AR face)



$$\frac{\Delta T_w}{\langle P_A \rangle} = \frac{1}{2\pi w} \approx 3.2 \frac{\text{K}}{\text{W}} \quad \tau_w = \frac{\pi w^2 C}{3\pi} = \frac{\pi w^3 C}{6\pi} \frac{\Delta T_w}{\langle P_A \rangle} \approx \underline{500 \text{ s}}$$

$$\tilde{x}_w^{AR}(f) \approx \sqrt{N} \cdot \text{RIN} \cdot \frac{\Delta T_w}{2\pi f w} \cdot w \cdot \frac{1}{2F}$$

$$\approx 1.0 \cdot 10^{20} \frac{\text{m}}{\sqrt{\text{Hz}}} \cdot \frac{150 \text{ Hz}}{f} \cdot \frac{\langle P_A \rangle}{25 \text{ mW}} \cdot \frac{\text{RIN}}{\underline{2 \cdot 10^5 \text{ Hz}^{-1/2}}}$$

ROM Cost Estimate

- Approx. \$60k/IFO (\$30k/ITM)
 - (Includes 15% hardware contingency)
- Add'l \$20k/site for IR diagnostics equip.
- Est. 0.25 PY sci, 0.1 PY eng, 0.1 PY tech for development & fab.
- Main cost risk: unforeseen technical obstacles in pursuit of low RIN (e.g., single-mode laser could add \$30k/IFO)

Tentative Plan (if approved)

- Set up intensity stabilizer exp't & establish RIN, imaging feasibility this summer
- Build & field test first article end of summer; install 6 ZnSe viewports at vent opportunities summer & fall
- Finalize design and build 5 more for phased installation & test in fall & winter