
Commissioning of the LIGO Detector life out in the wild wild (north)west

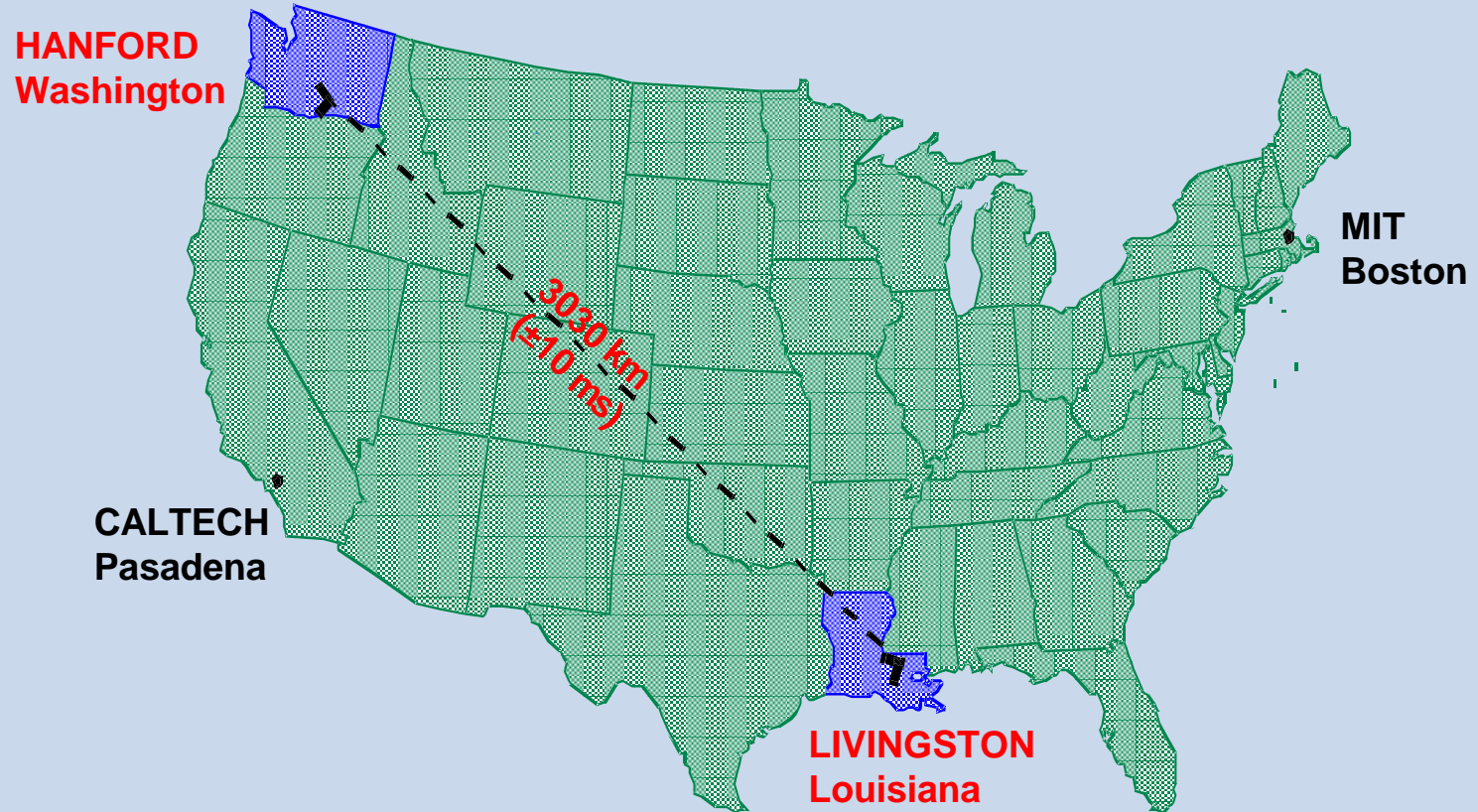
Rick Savage

LIGO Hanford Observatory

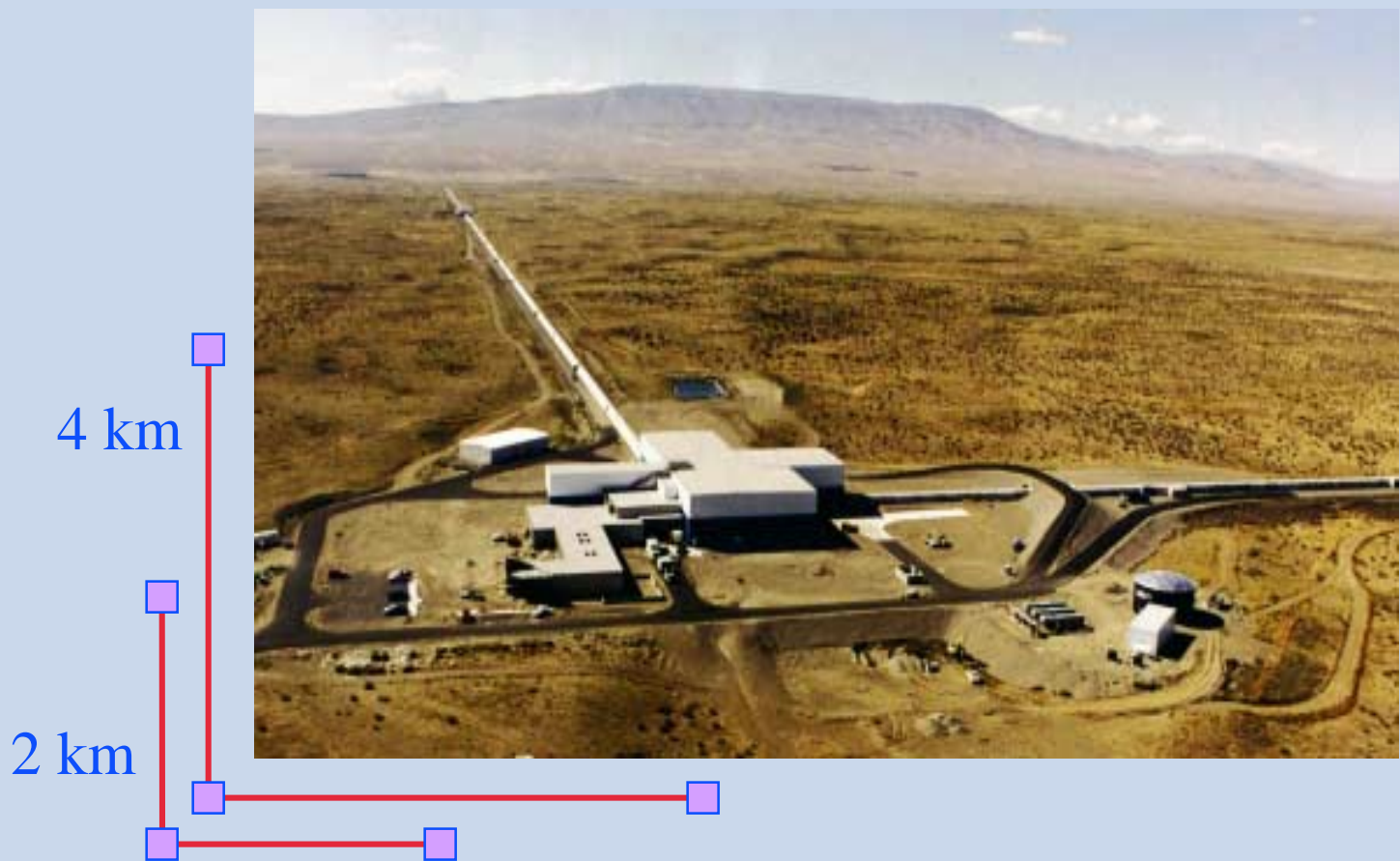
Tenmondai, Mitaka

July 3, 2002

LIGO Observatories



Hanford Observatory



Livingston Observatory



LIGO Hanford Observatory Commissioning Players

- Resident at LHO

- » Dick Gustafson – UM
- » Michael Landry – postdoc
- » Fred Raab – Head LHO
- » Rick Savage
- » Paul Schwinberg
- » Daniel Sigg

- Visiting

- » Stan Whitcomb – CIT
- » Robert Schofield – UO
- » Nergis Mavalvala – MIT
- » Peter Fritschel – MIT
- » Rana Adhikari – MIT (student)
- » Bill Kells – CIT
- » Luca Matone - CIT

- Grad Students

- » Bill Butler – Rochester
- » Masahiro Ito – UO
- » Rana Rakhola – UO

- Operators

- » Betsy Bland
- » Corey Gray
- » Mark Guenther
- » Nathan Hindman
- » Mark Lubinski
- » Gerardo Moreno
- » Hugh Radkins
- » Cheryl Vorvick

LHO Support Staff

- Support Staff

- » Dave Barker – CDS
- » Greg Mendell – LDAS (theory)
- » Richard McCarthy – Electronics
- » Josh Myers – Electronics
- » Doug Cook – Optics
- » Kyle Ryan – Vacuum
- » John Worden – Vacuum
- » Bartie Rivera – Vacuum prep.
- » Christine Patton – Sys. Admin.
- » Otto Matherny – Business
- » Jill Berry - Administrative

LHO Daily Schedule

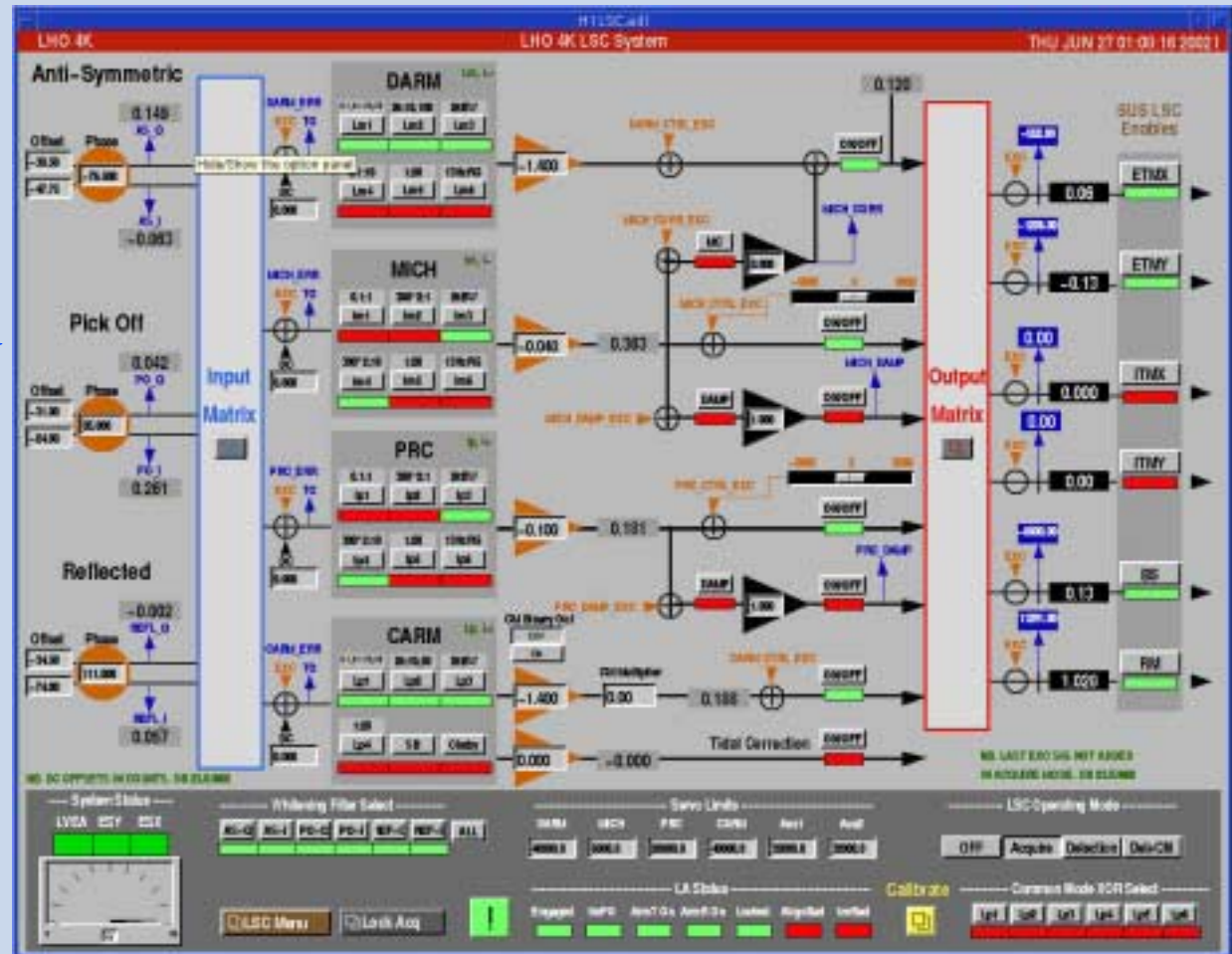
- Operators on site seven days per week.
 - » Two shifts per day
 - 7:00 AM to 5:00 PM
 - 4:00 PM to 2:00 AM
 - » Two operators per shift
- Increased seismic noise due to construction of new building
 - » Typically 6:30 AM to 3:30 PM
- Electronics troubleshooting, cabling, system maintenance, etc. typically in the mornings.
- Begin operation of interferometers at about 2:00 PM daily.
- High winds (> 25 mph) typically make full lock difficult, if not impossible.

LIGO Control and Data System (D. Barker at LHO)

- 12,770 “slow” EPICS channels per interferometer (LHO 4k ifo. with digital suspension controllers)
- 425 “fast” channels per ifo. (256 Hz, 2 kHz, 16 kHz)
- 60 16-kHz channels per ifo.
- 16 CDS computers (IOCs) per ifo.
- 3 MB/sec per ifo. written to frames
- 15 TB of full-frame storage capacity at LHO
- --> Previous 390 hrs. or 16.25 days of data available on disk
- Past 25 days of second-trend data available on disk
- All past minute-trend data available on disk

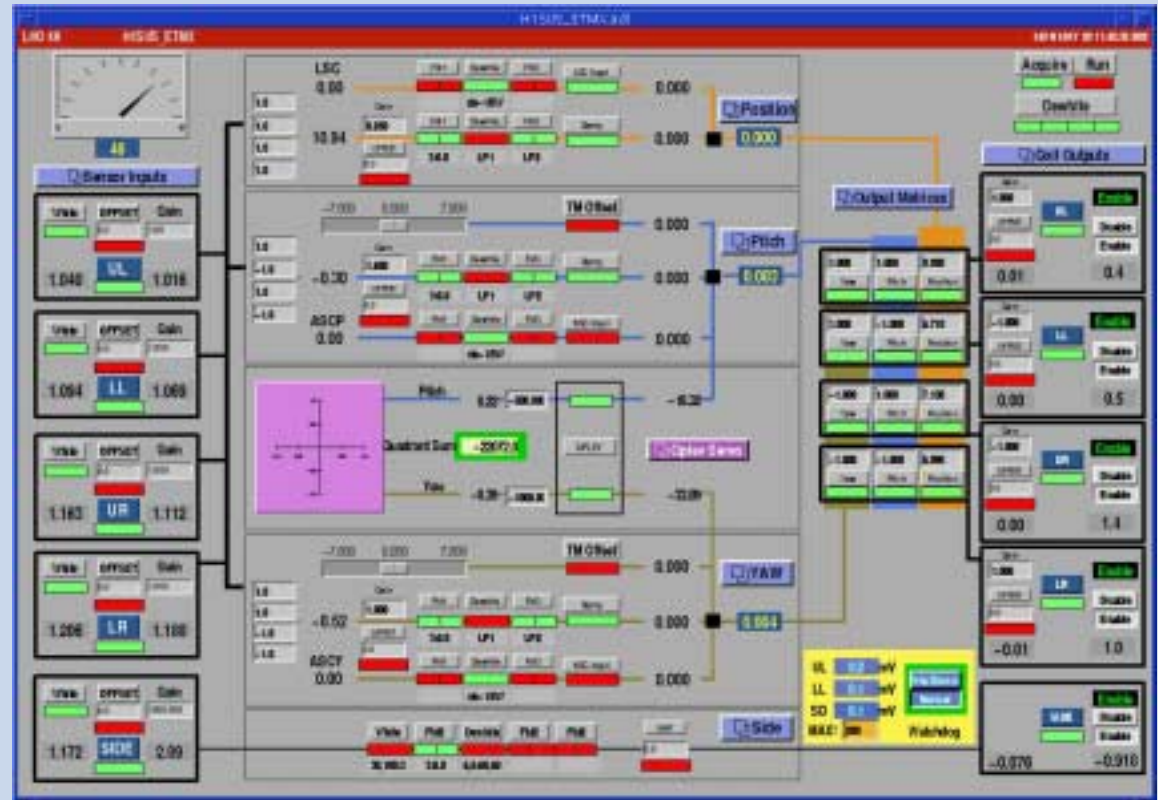
Epics Control System

- All control via computer
- Digital length and alignment control
- Dynamic control of input matrix in acquisition mode (ala M. Evans)



4k Digital Suspension Control Screen

- Lots of digital filter stages
 - » Whitening and dewhitening
 - » Resonant gain stages
 - » Notches
 - » Combs
 - » Etc.
- Improved optical lever performance



Automation of Interferometer Configuration Changes

Common mode transition script

(D. Sigg)

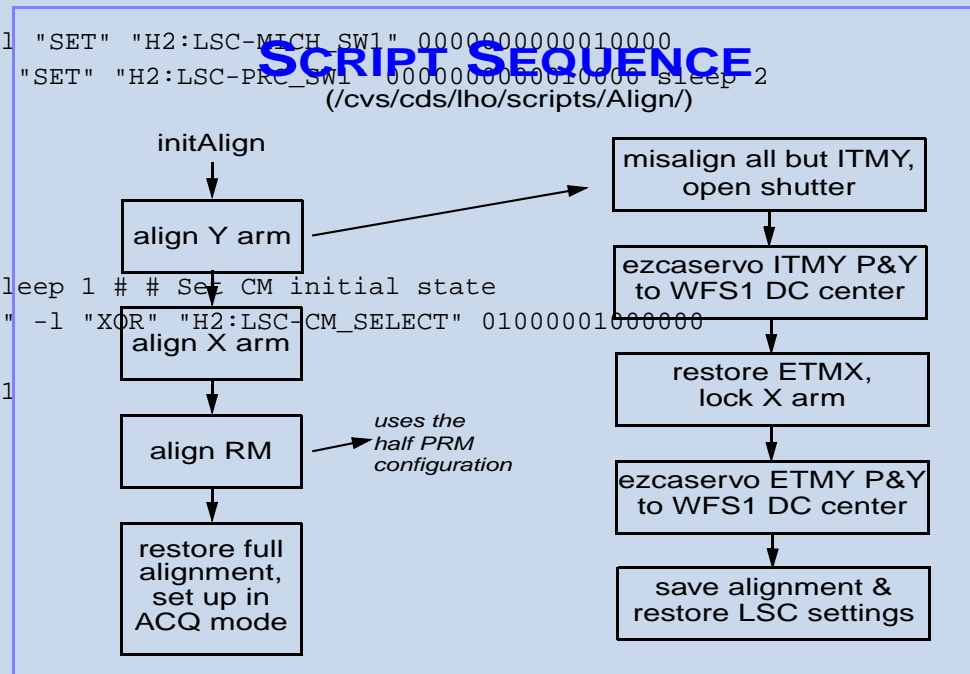
```

# Turn MICH and PRC boost on
excawrite -b -r "H2:LSC-MICH_SW1R" -1 "SET" "H2:LSC-MICH_SW1" 0000000000010000
ezcawrite -b -r "H2:LSC-PRC_SW1R" -1 "SET" "H2:LSC-PRC_SW1" 0000000000010000 sleep 2
#
# Turn servo gains to final values
ezcawrite "H2:LSC-DARM_ERR_K" -1.2
ezcawrite "H2:LSC-CARM_ERR_K" -1.0
ezcawrite "H2:LSC-MICH_ERR_K" -0.085
ezcawrite "H2:LSC-PRC_ERR_K" -0.15 sleep 1 # # Set CM initial state
ezcawrite -b -r "H2:LSC-CM_SELECT_RD" -1 "XOR" "H2:LSC-CM_SELECT" 01000001000000
ezcawrite H2:LSC-CM_OVERRIDE 0
ezcawrite H2:LSC-ComMode_CommGainIn 1
ezcawrite H2:LSC-ComMode_AOGainIn 11
ezcawrite H2:LSC-ComMode_ALGainIn 3
ezcawrite H2:I00-MC_ERR_EXC_ENABLE 0
ezcawrite H2:I00-MC3_LSC_IN 1
ezcawrite H2:LSC-ComMode_OpenLoop 1
#

```

Automated initial alignment

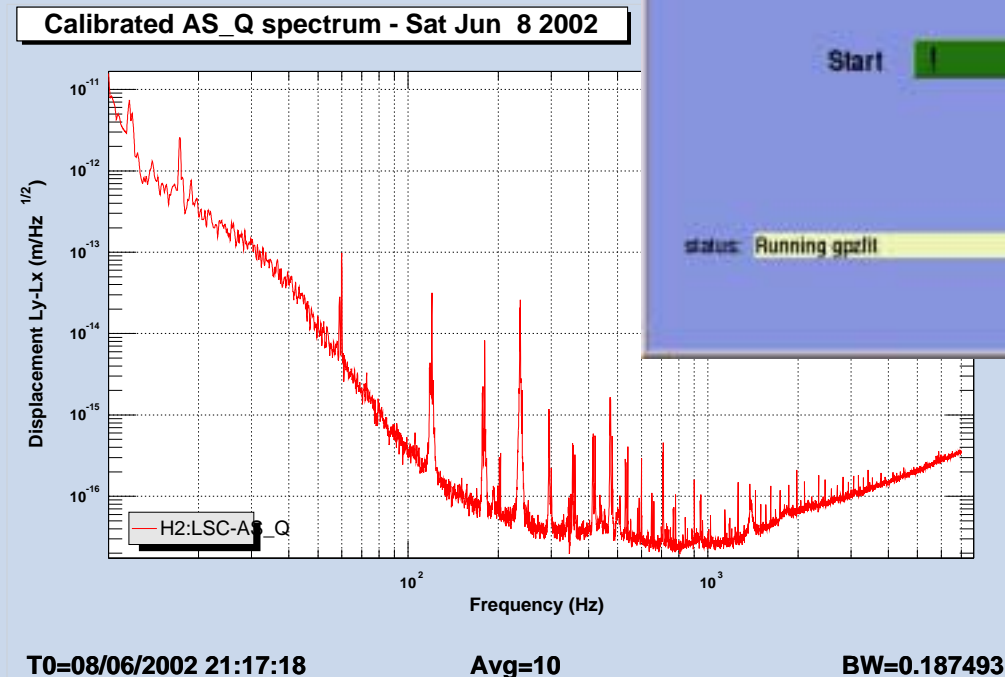
(M. Evans)



“One-click” Generation of Calibrated Spectra (M. Landry)

- uses most recent actuation calibrations
- makes swept sine measurement of transfer function from TM drive to AS_Q
- pole-zero fit using Root
- measures AS_Q spectrum and applies calibration

DTT software package
by D. Sigg



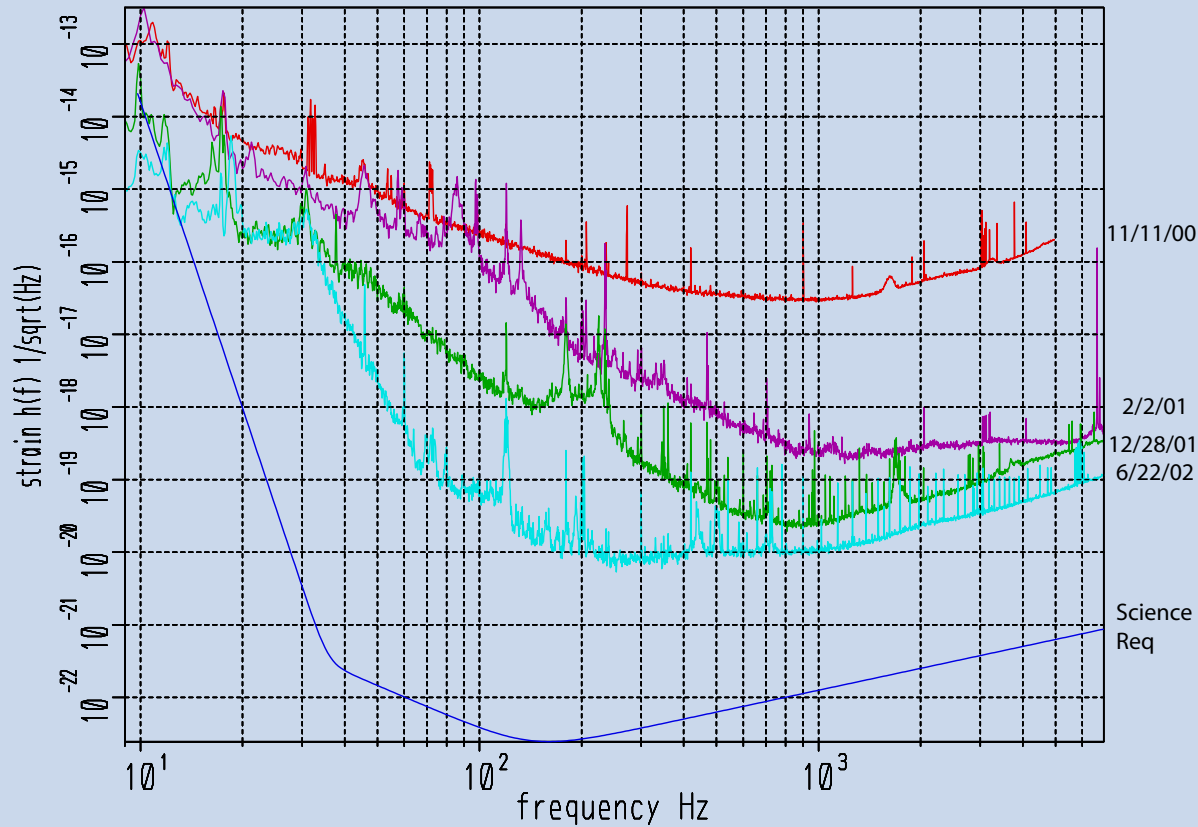
LHO 2k Interferometer Status

- 5 Watts laser power delivered to modecleaner.
- Analog suspension controllers.
- Only WFS 1 active
 - » Now used for differential control of ITM alignment.
 - » Improved optical lever damping for ETMs
- Common-mode servo configuration changed (now similar to TAMA)
- Tidal prediction applied to reference cavity temperature.
- Fine actuators (PZTs on ETM stacks) used for tidal compensation.
- First part of intensity stabilization loop is active.
- Automated calibration working.
- Several-hour locked stretches, often 6-10 hours.



Sensitivity Improvement Hanford 2k Ifo.

LIGO Hanford 2km sensitivity vs time



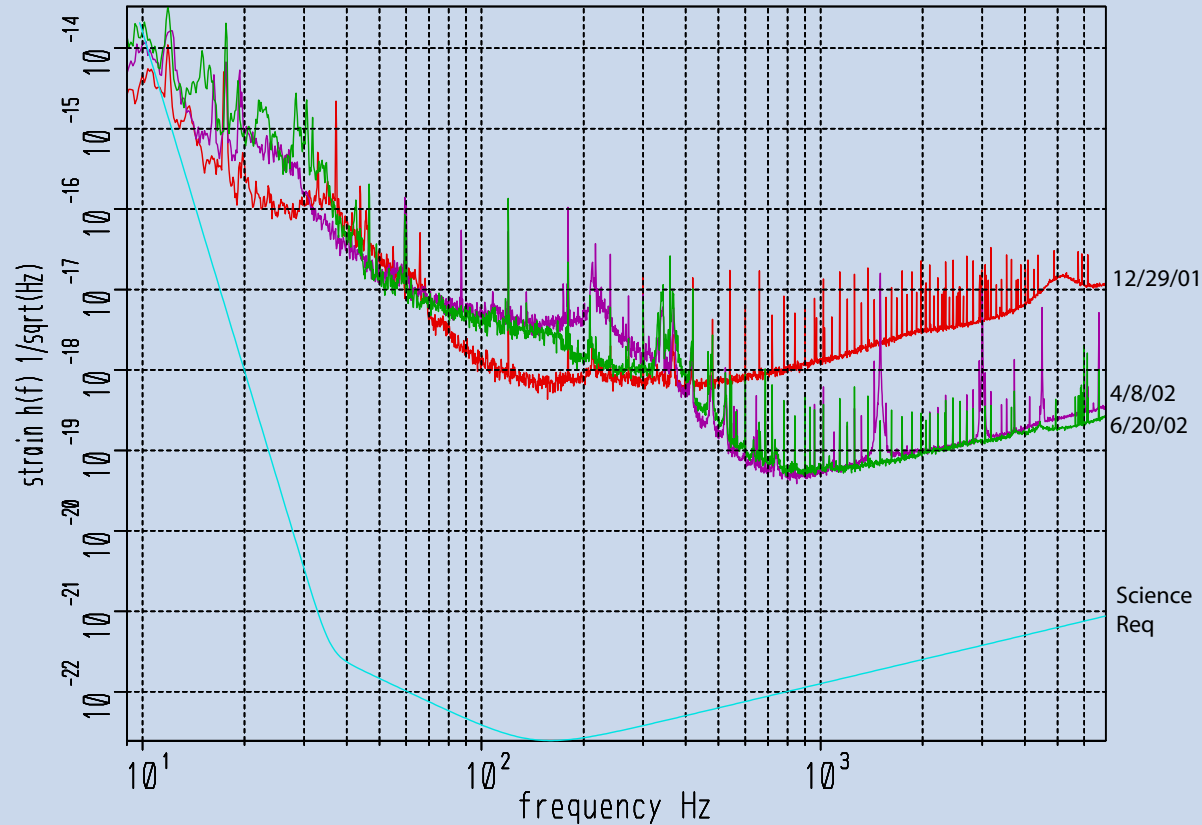
LHO 4k Interferometer Status

- 1 Watt laser power delivered to modecleaner
- Digital suspension controllers
 - » Lots of digital filter stages
 - » Dynamic diagonalization of drive of optics
- Only WF1 active
- Old common-mode servo configuration
- Tidal prediction to reference cavity temperature
- Fine actuators on ETM stacks for balance of tidal correction.
- Inner loop of intensity stabilization active.
- Lots of code changes.
- Shakedown of digital suspension code now (almost) complete.
- Now locking for up to 8 hours.
- Radiation pressure induced alignment variations?



Sensitivity Improvement Hanford 4K Ifo.

LIGO Hanford 4km sensitivity vs time

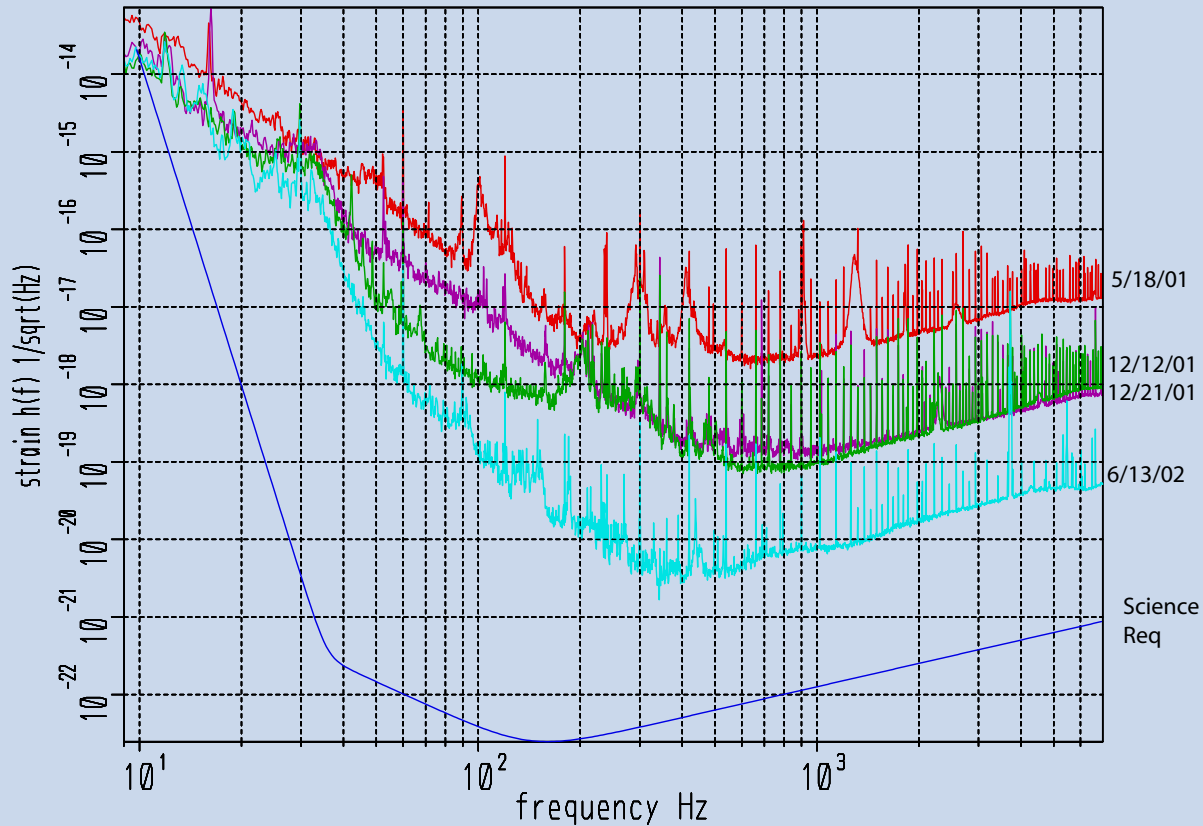


LLO 4k Interferometer Status

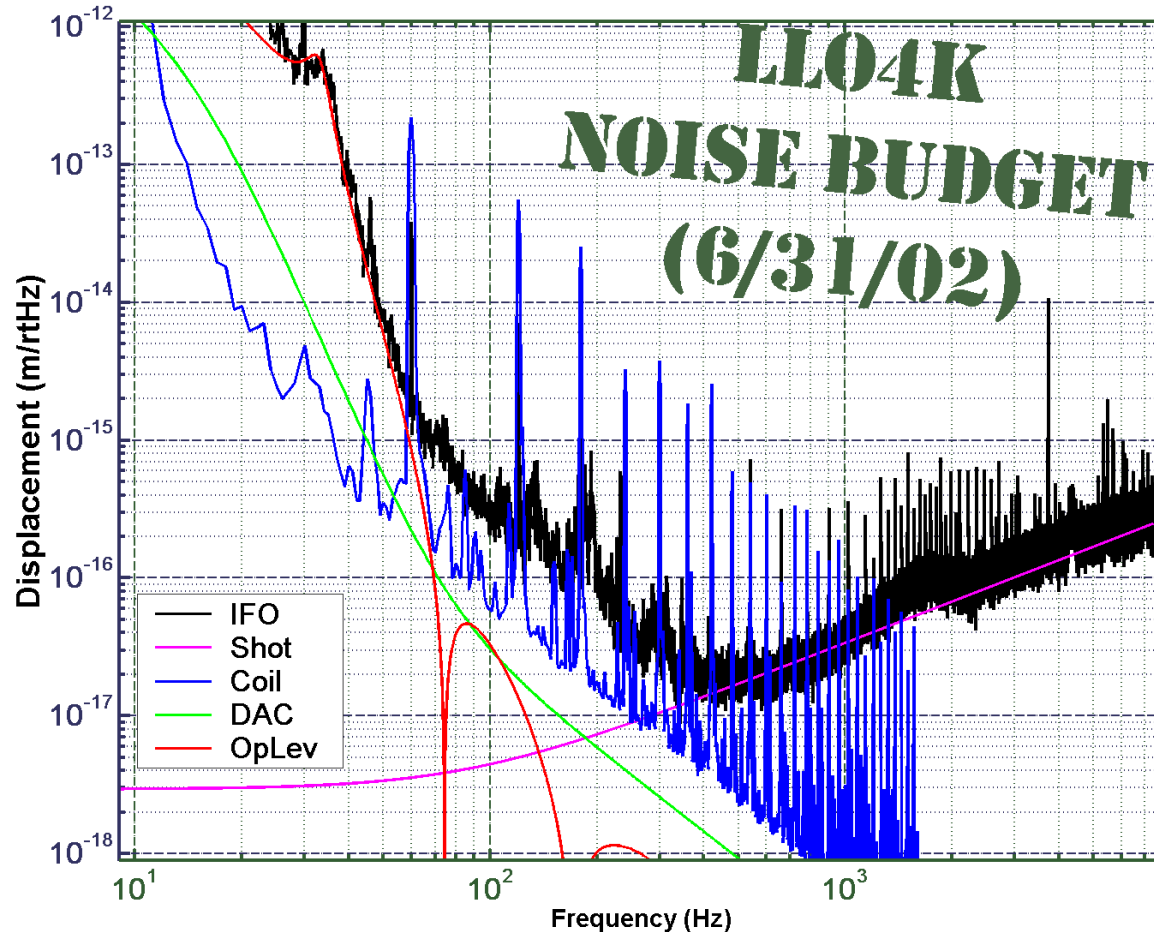
- 2 Watt laser power delivered to modecleaner.
- Analog suspension controllers.
- Old common-mode servo configuration.
- Closed-loop control of reference cavity temperature to compensate for CM tides.
- Fine actuators for residual tidal correction.
- FSS beam sampled after PMC.
- Inner loop of intensity servo active.
- Unable to lock during logging – most weekdays.
- Adversely affected by traffic on highway.
- Lock broken by trains twice nightly.
- Large microseism.
- Locking for multi-hour stretches when ambient noise allows.

Sensitivity Improvement Livingston 4k Ifo.

LIGO Livingston 4km sensitivity vs time



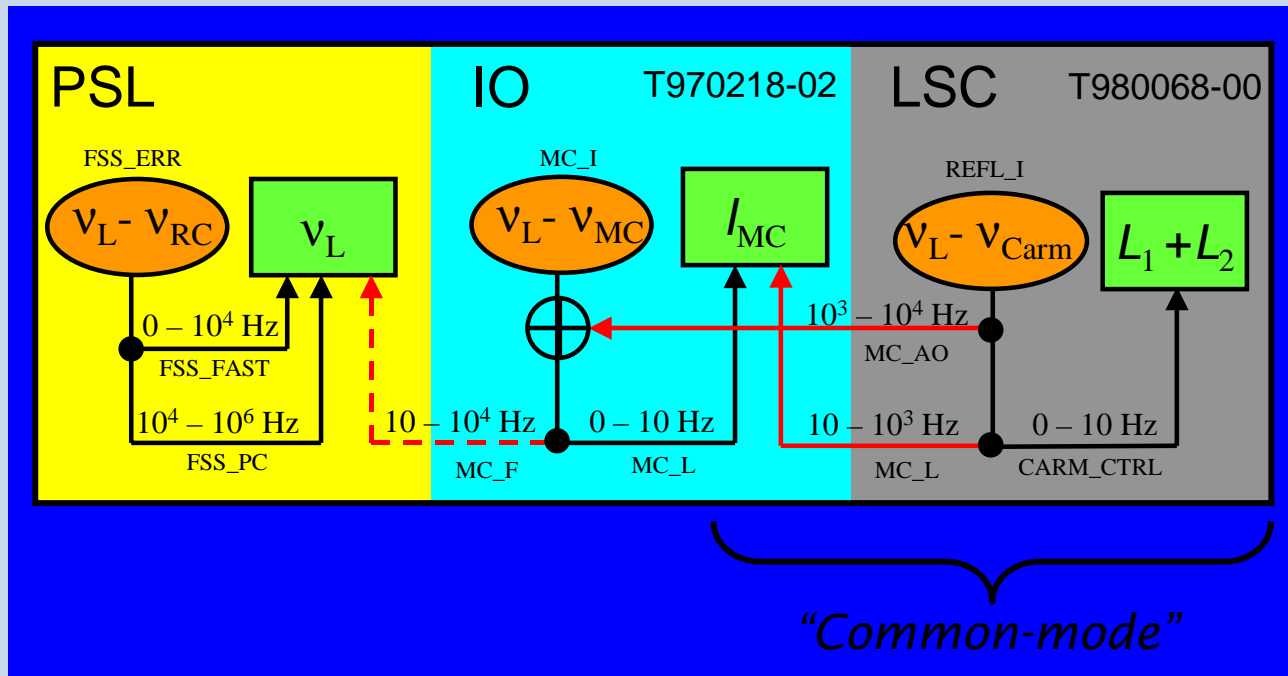
Interferometer noise modeling (R. Adhikari)



- EO shutter at AS port attenuates light by factor of 50
- New optical lever whitening filters should reduce ADC noise by factor of 400
- Below 15 Hz, freq. noise resulting from MC radiation pressure fluctuations dominates

2k Sensitivity Improvement: Reconfiguration of CM servo

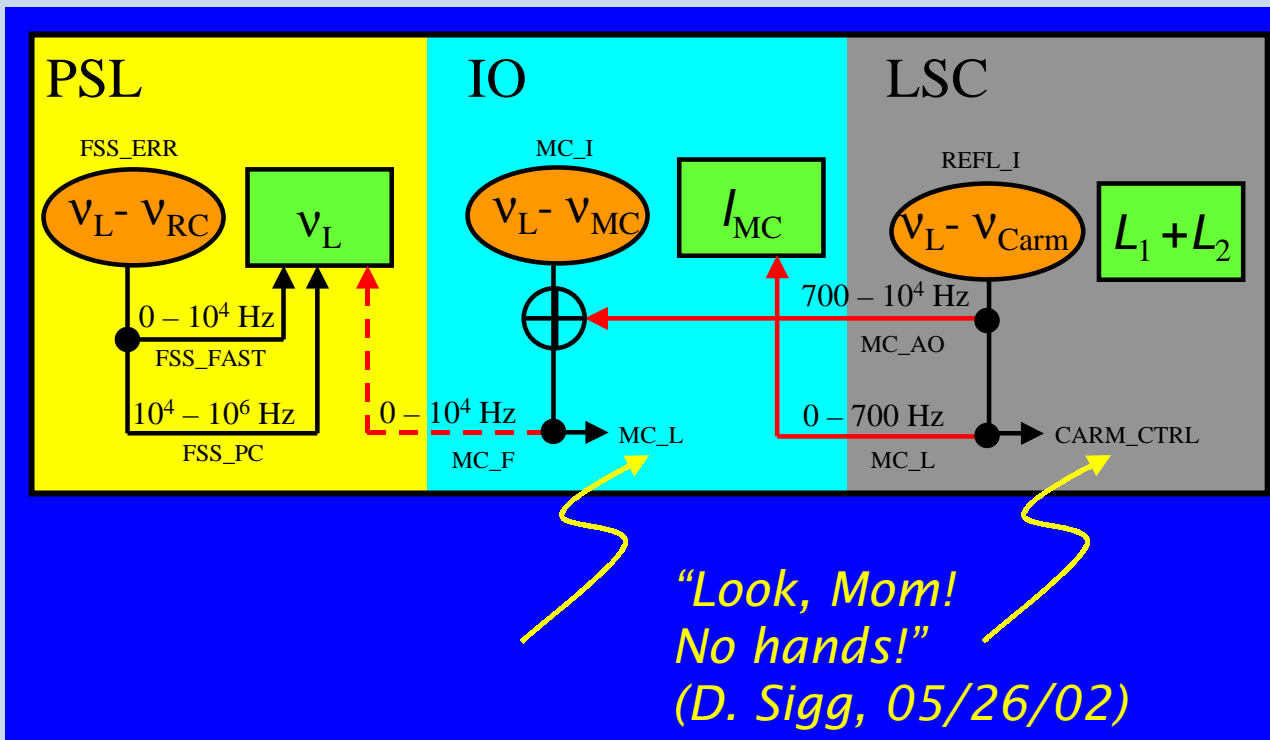
- Original configuration of frequency stabilization topology



From Nergis M.

Reconfiguration of Common-mode Servo (D. Sigg)

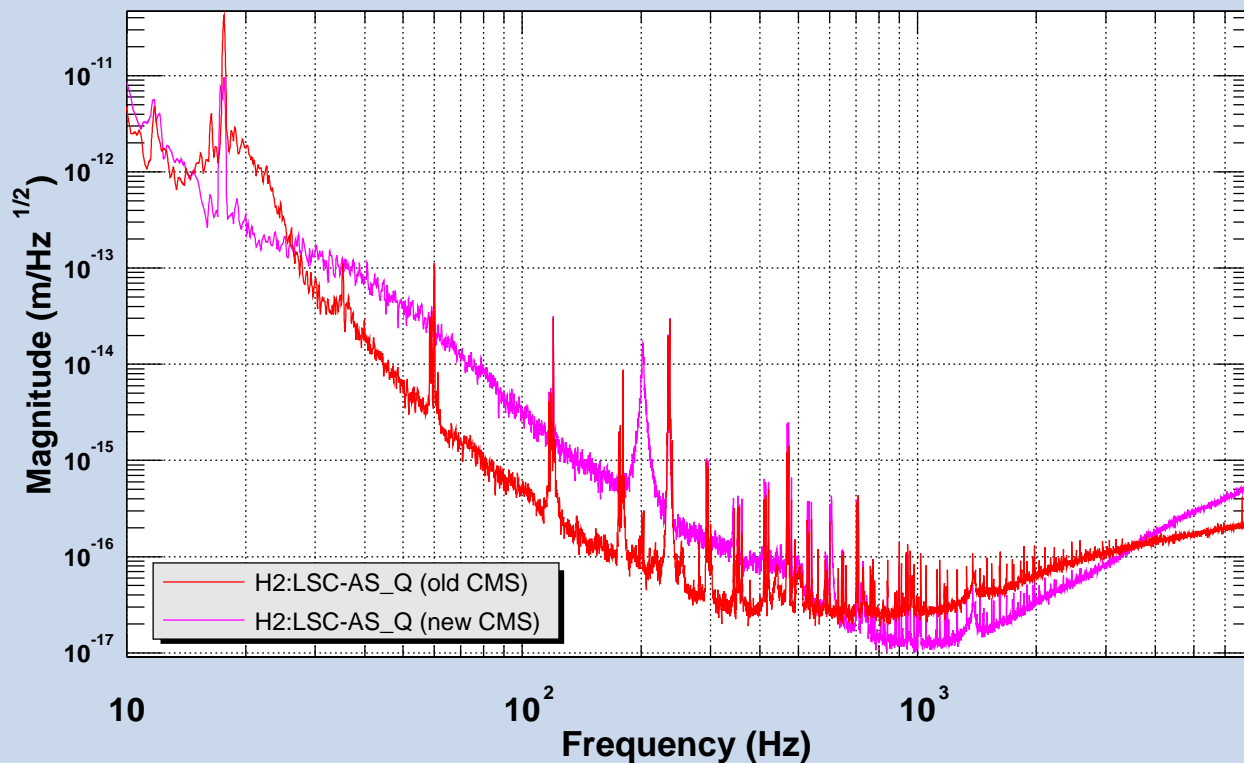
- Eliminate CARM drive to ETMs
- MC servo feedback to laser frequency actuator only



From Nergis M.

Improved Displacement Spectrum

Calibrated AS_Q spectrum - Sun May 26 2002



*T0=27/05/2002 05:10:01

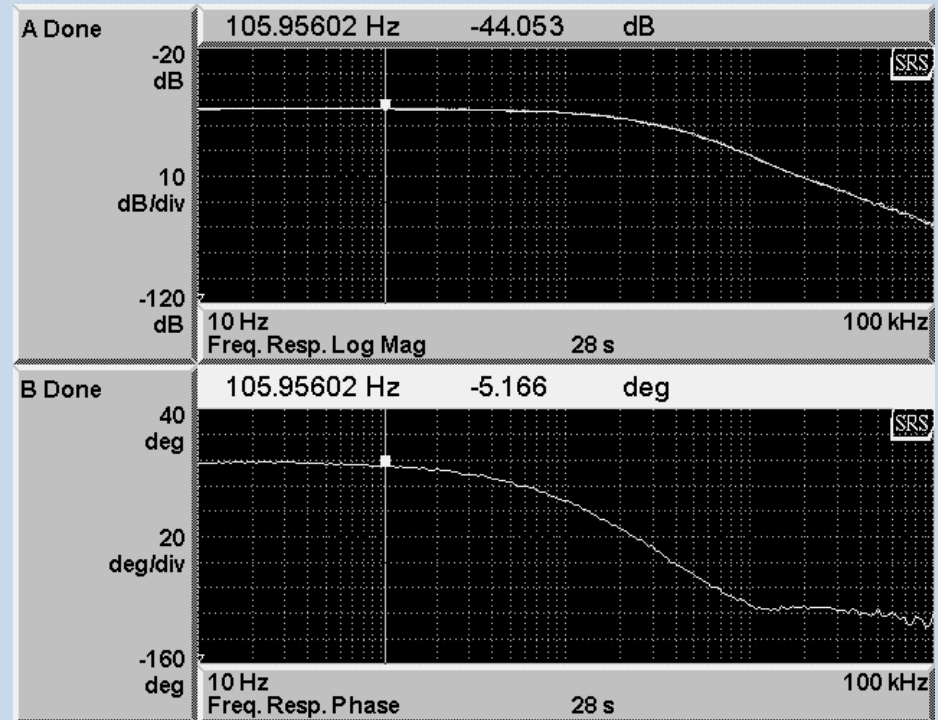
Avg=10

BW=0.187493

Relative Intensity Noise Stabilization

- Previous servo had insufficient drive range, resulting in intermittent power glitches (with Y. Aso, 5/02)
- Free-running slow power variations ~1-2%
- Current shunt actuator design range > +,- 2.5%

4k laser current shunt xfer. fctn.



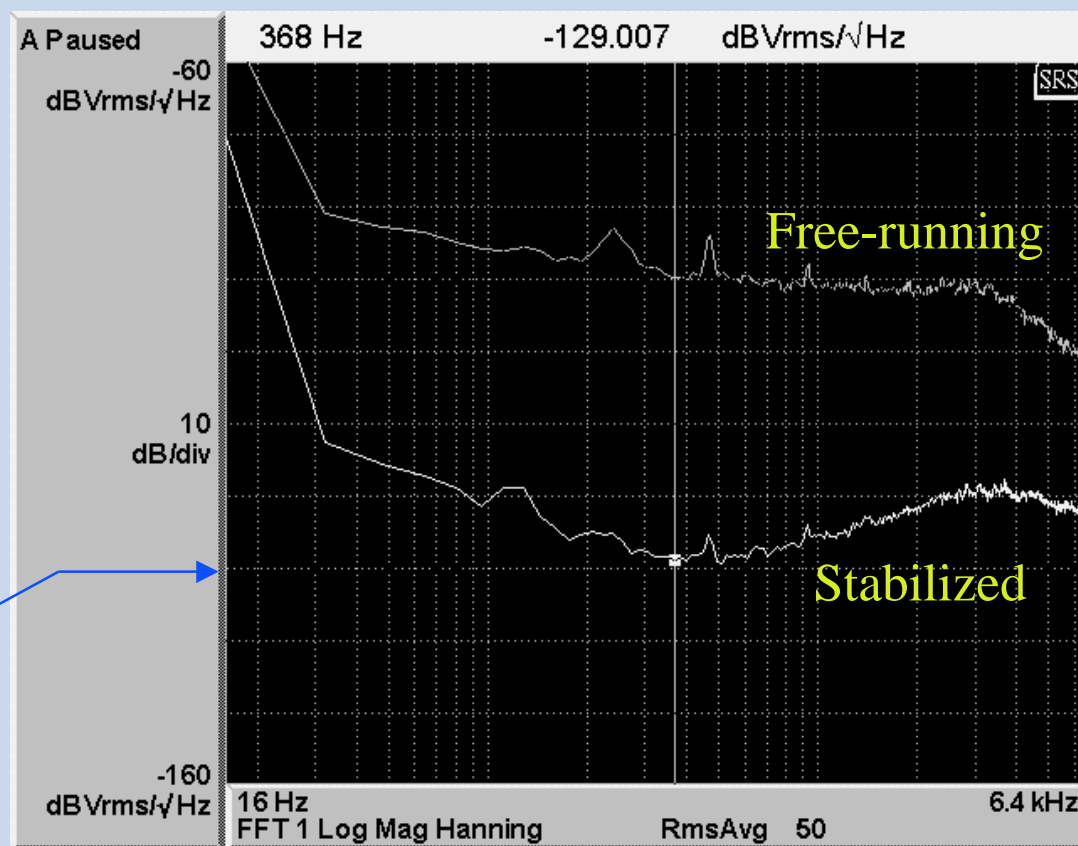
D.C level = 1.7 V \rightarrow 3.7%/V

New Intensity Stabilization Servo

LHO 4k Outside-the-loop RIN Spectra

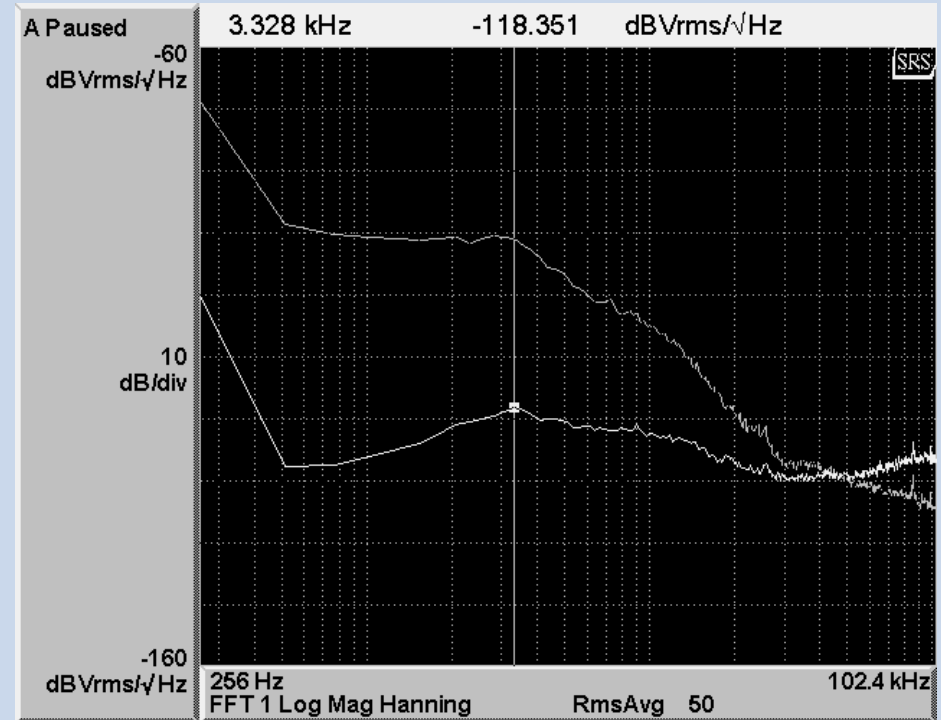
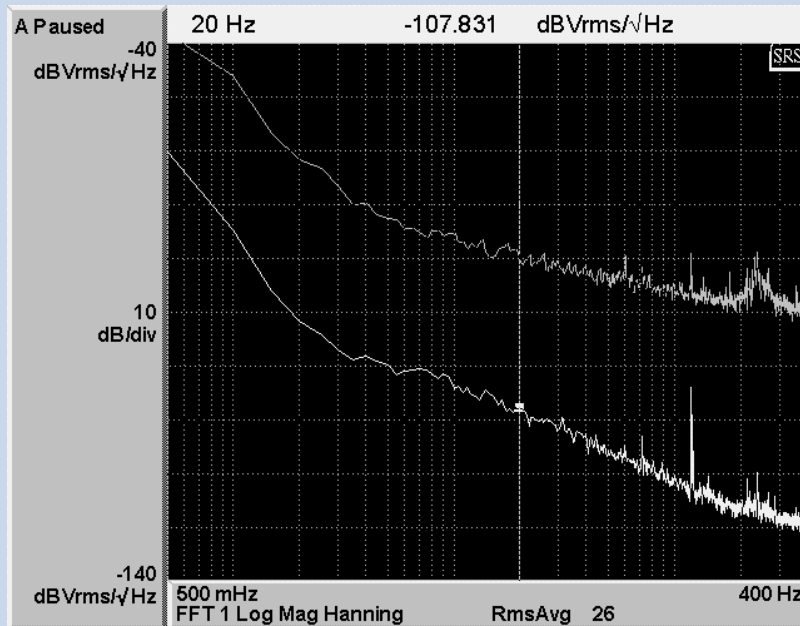
- New two-loop servo and new low-noise photodetectors
- Inner loop with PD just after pre-modecleaner
- Outer loop with PD just after modecleaner (outside vacuum)
- RIN goal: $1e-8/\text{rtHz}$
- Only inner loop installed, June, 2002
- +/- 10 V drive range

$$\Delta P/P = 5e-8 \text{ Hz}^{-1/2}$$



LHO 4k RIN Spectra

Gain ~ 30 dB at 1 Hz

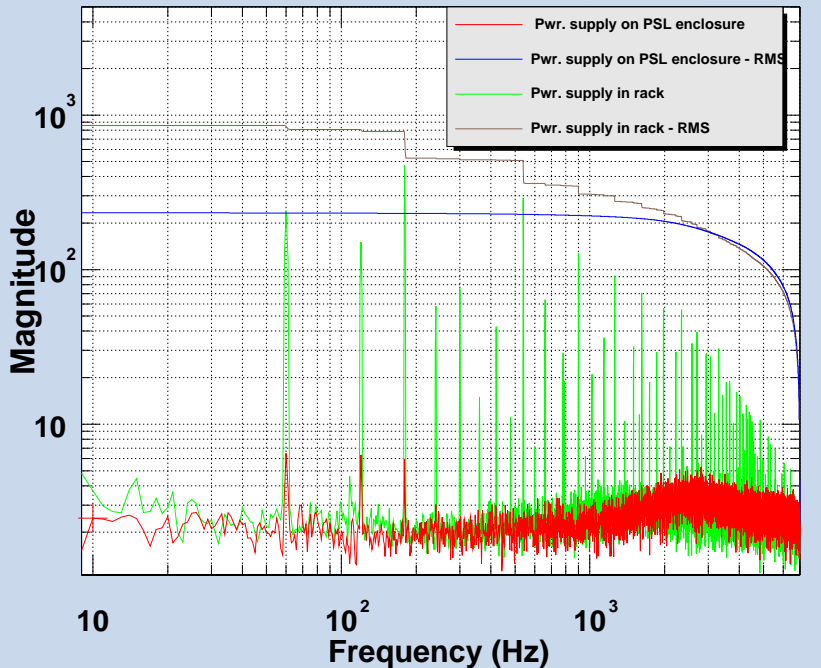


RIN not yet measured downstream of MC with this servo.

Grounding and EMI

60 Hz and harmonics

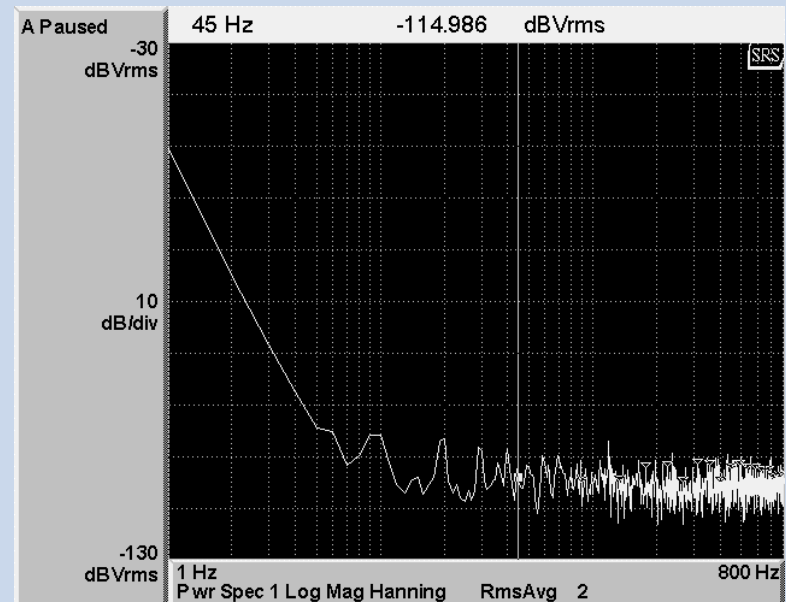
4k PSL frequency servo error point (FSS_MIXERM_F)



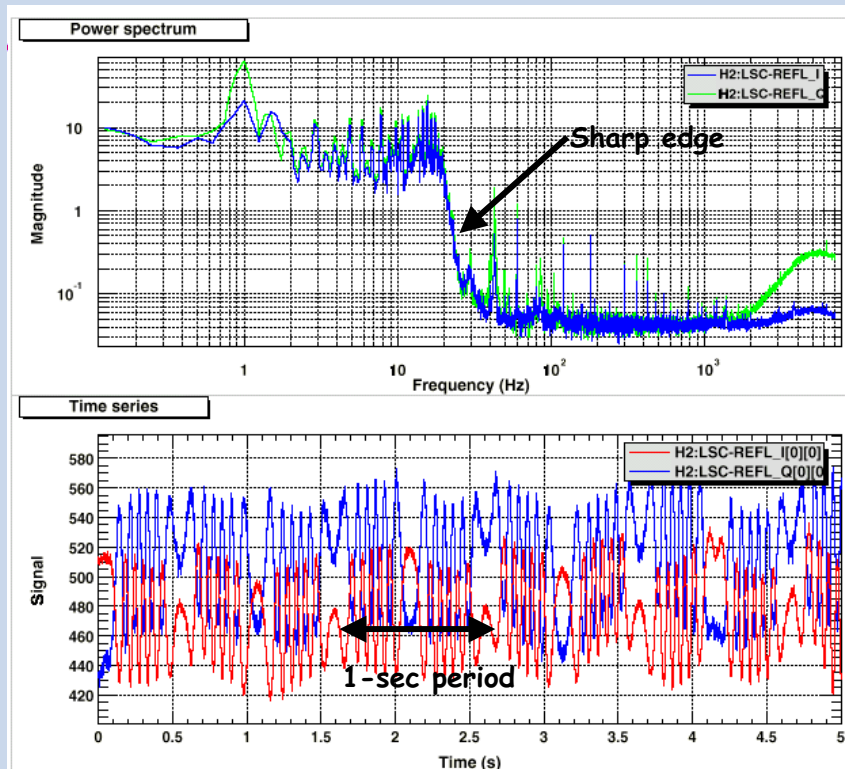
*T0=13/05/2002 19:27:12.0235980

BW=1.49999

- Frequency stabilization servo error point
 - » **Green** – laser power supply in rack
 - » **Red** – laser power supply moved to top of PSL enclosure



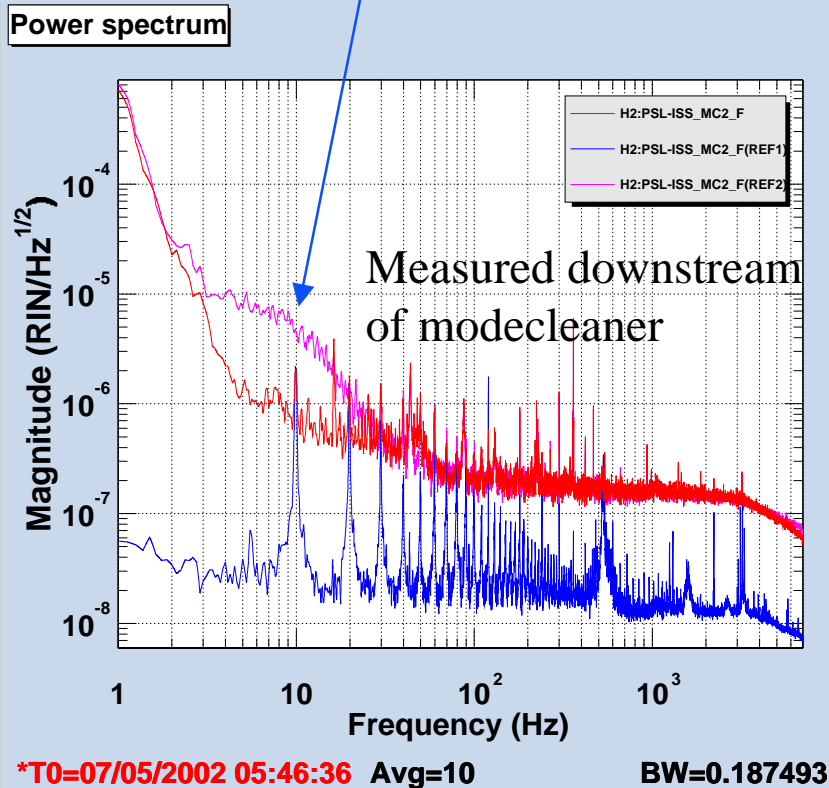
Parasitic Interferometer LHO 2k



- Measurement made with RM aligned and other optics misaligned
- 1 Hz period indicates small optic motion
- 6 fringes \gg 3 microns_{peak}
- Tried to identify which optic moving by changing damping gains – no change observed
- Investigation abandoned because edge is below seismic wall

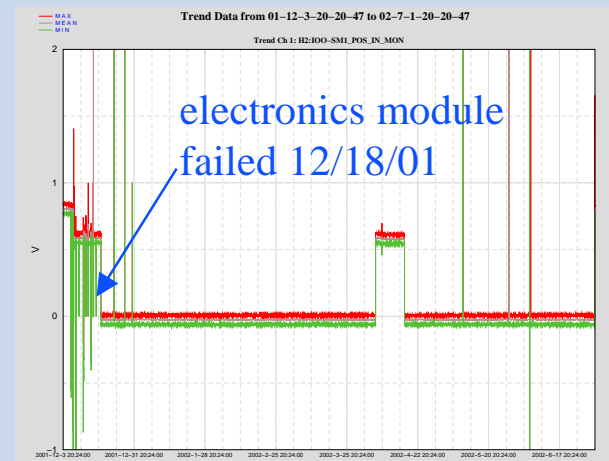
Source of Parasitic Interferometer Identified?

Non-stationary noise from parasitic ifo.

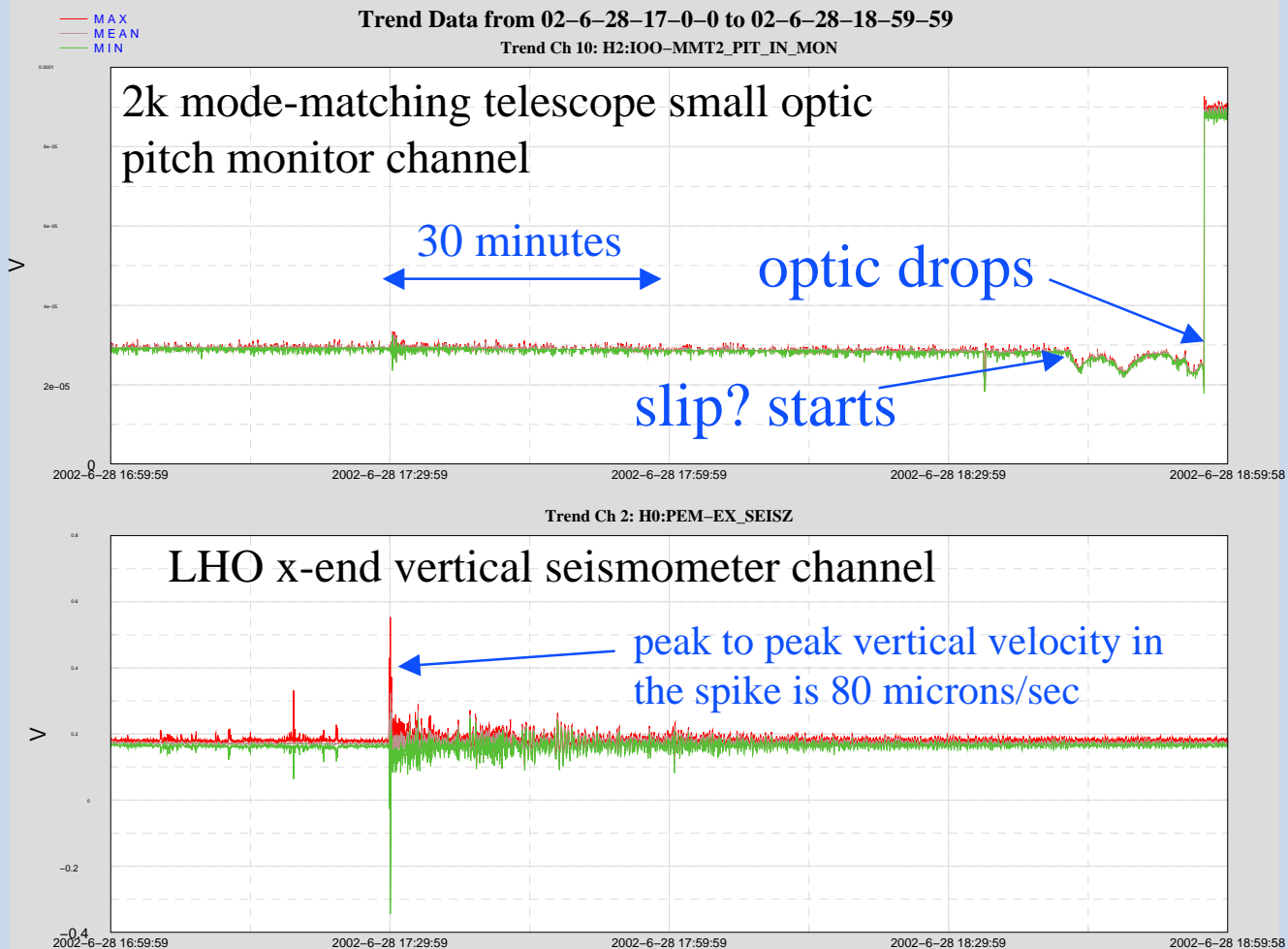


- Post MMT2 slippage investigation

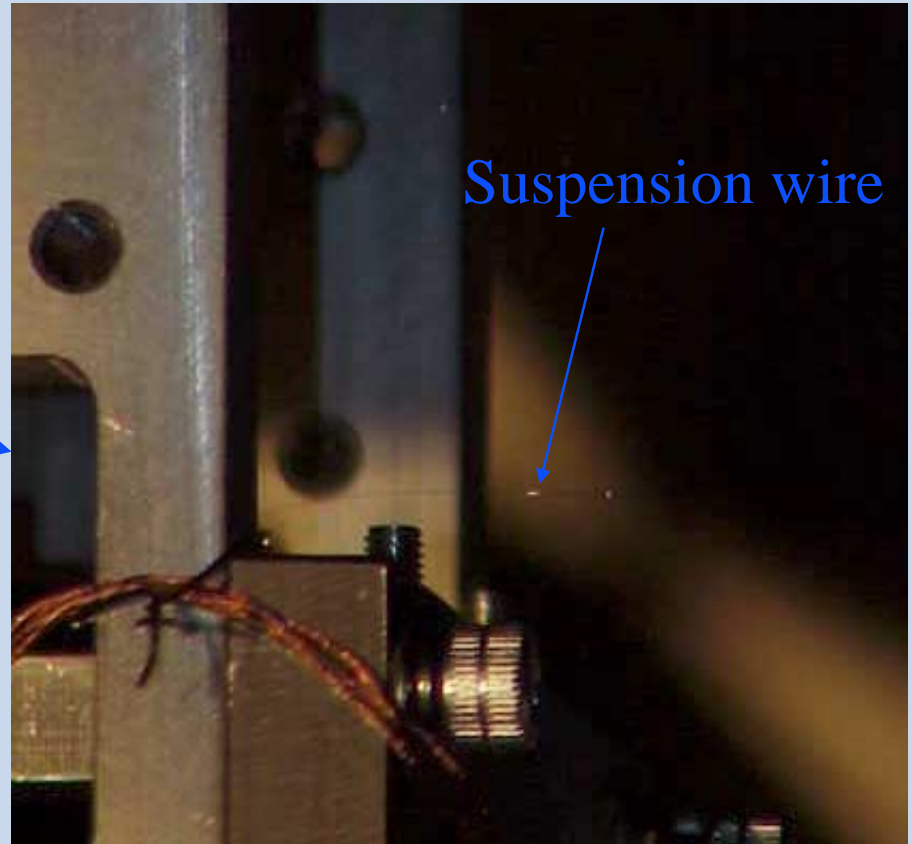
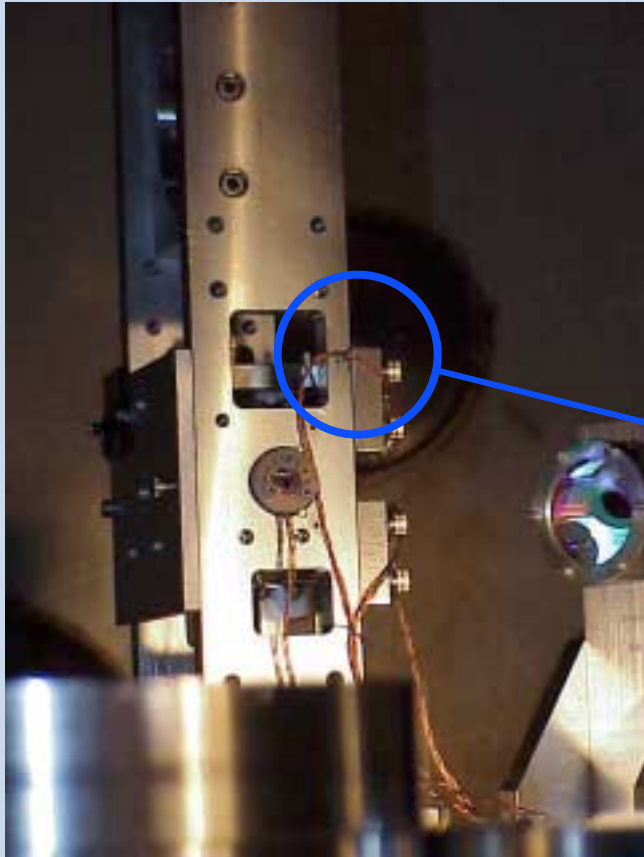
» “uncovered an unsettling scenario. From the plots, **SM1** has been without it's photodiode sensor readbacks (and damping) since ~12/18/01.” J. Myers July1, 2002 elog entry



Delay of S1 Run Friday, June 28, 2002



Slack MMT2 Suspension Wire



Repair of MMT2 Suspension

- Vacuum system opened this morning
- “A preliminary inspection of mirror MMT2 shows two broken magnet assemblies. The wire break is along the free section of wire, not in the clamp. The optic is on its way to the optics lab for a post-mortem and repairs. Chamber door is going back on and we hope to be pumping soon.”
- “There is a very TENTATIVE plan to reschedule the S1 science run to start Thursday August 1, ending on or before the LSC meeting that begins August 19. This is an optimistic schedule that assumes the Hanford 2K repair can be done quickly.”

Fred Raab 7/2/02

Keith Riles 7/1/02

After the S1 Run

- Still lots to be done!
- Many pending hardware and software installation tasks

Installation Task	L1	H1	H2
new LSC code (generic filter modules)		✓	
new ASC code (generic filter modules)		✓	
Code updates: add test points, channel name changes	✓	✓	✓
DSC system	✓		✓
PEPI on ITMs	✓		
Microseismic FF		✓	✓
AS port table re-layout & auto-alignment sequencing	✓	✓	✓
Optlev WH filter	✓	✓	✓
Pentek Diff. DRV/RCV	✓	✓	✓
ISS outer loop	✓	✓	✓
RFI cleanup/electronics infrastructure rework	✓	✓	✓
Core optics fix			✓
Add AS port LSC PDs	✓	✓	✓
Photon calibrators	✓	✓	✓

New Design Tasks
LSC Dewhitening filter: stage-by-stage, smooth turn-on ?
Mode cleaner servo: incorporate revs, fix flaws, digital MC_L path
Common mode servo: incorporate revisions
PSL FSS board: incorporate BW increasing revs
DSC-compatible coil driver for LLO
RFI cleanup & grounding solutions
WFS auto-centering system (ISC table beam stabilization)
Stabilize input beam pointing

P. Fritschel 6/02

LIGO Run Plan

- Science 1 run – Upper Limits
 - » June 29 to July 15 (Delayed)
 - » 2.5 weeks comparable to E7
 - » Target sensitivity: 200x design
- Science 2 run – Upper Limits
 - » Nov. 22 to Jan. 6, 2003
 - » 8 weeks
 - » Target sensitivity: 20x design
- Science 3 run – Search Run
 - » July 1, 2003 to Jan. 1, 2004
 - » 26 weeks
 - » Target sensitivity: 5x design
- “During 2003 and 2004, we will plan to run in this search mode for at least 50% of the calendar time, followed by the planned one year integrated LIGO science run at design sensitivity. This science run will be completed prior to proposed major interferometer replacements.”

LIGO Lab Planning Memo.