LIGO ADVANCED SYSTEM TEST INTERFEROMETER

Program Status Report

Dave Ottaway, Gregg Harry, Ken Mason, Mike Zucker

LIGO Science Collaboration Meeting
LIGO Hanford Observatory
14 August, 2001



LASTI Mission

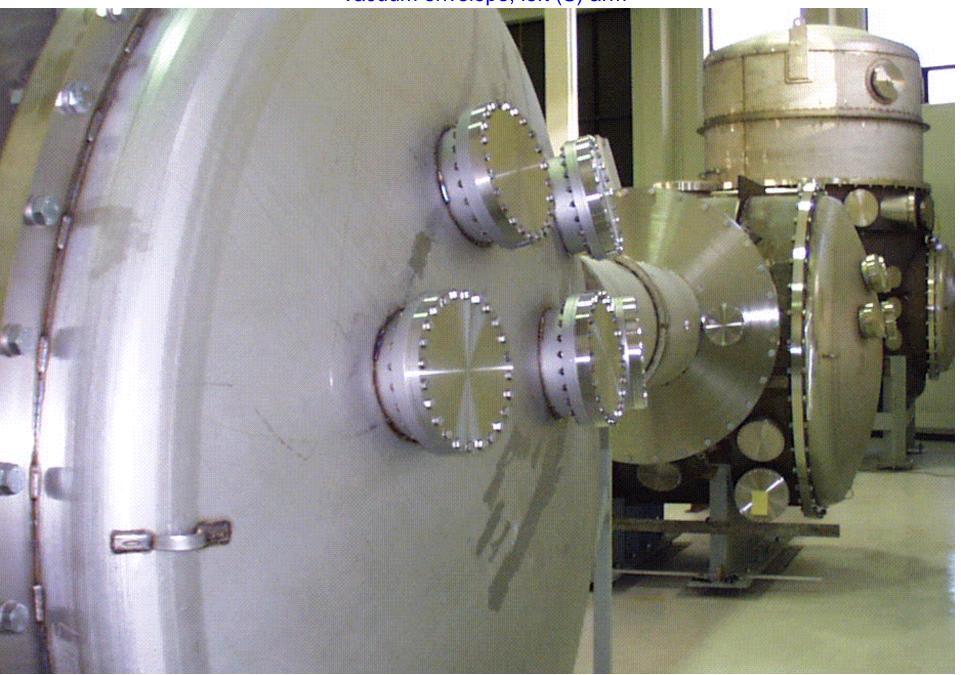
- Test LIGO components & systems at full mechanical scale
- Practice installation & commissioning
- Minimize delays & downtime for LIGO observatory upgrades

Specific Advanced LIGO Program Tasks ('01 - '06+):

- Qualify advanced seismic isolation & suspension systems and associated controls at full scale
- Develop detailed SEI/SUS installation & commissioning handbook
- Look for unforeseen interactions & excess displacement noise
- Test LASER and Input Mode Cleaner together at full power



Vacuum envelope, left (S) arm





People

Local Staff

Grads - Jamie Rollins, Josh Phinney
Engineering - Ken Mason, Dan Mason
Tech support - Myron MacInnis, Fred Miller, Bob LaLiberte
Scientists - Rich Mittleman, Gregg Harry, Dave Ottaway
Lunch - David Shoemaker, Mike Zucker

Visitors (since previous LSC meeting)

Initial SEI - Corey Gray, Hugh Radkins

Advanced SEI - Joe Giaime, Giles Hammond, Brian Lantz, Wensheng Hua, Tuck Stebbins Advanced SUS - Norna Robertson, Calum Torrie, Janeen Romie, Phil Willems CDS/DAQ/PSL/Initial SUS - Jay Heefner, Rick Karwoski, Paul Russel

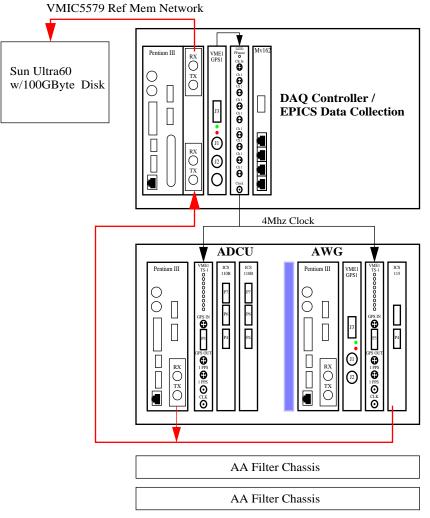
•TODAY'S TOPICS

- ♦ Optical configuration & PSL progress (Dave Ottaway)
- ♦ Displacement noise model projections (Gregg Harry)
- ♦ Hydraulic SEI pre-isolator design (Ken Mason; companion talk later by Brian Lantz)
- ♦ Milestones, schedule, etc. (MZ)
- ♦ Note: advanced quad suspension work @ MIT will be reported next session



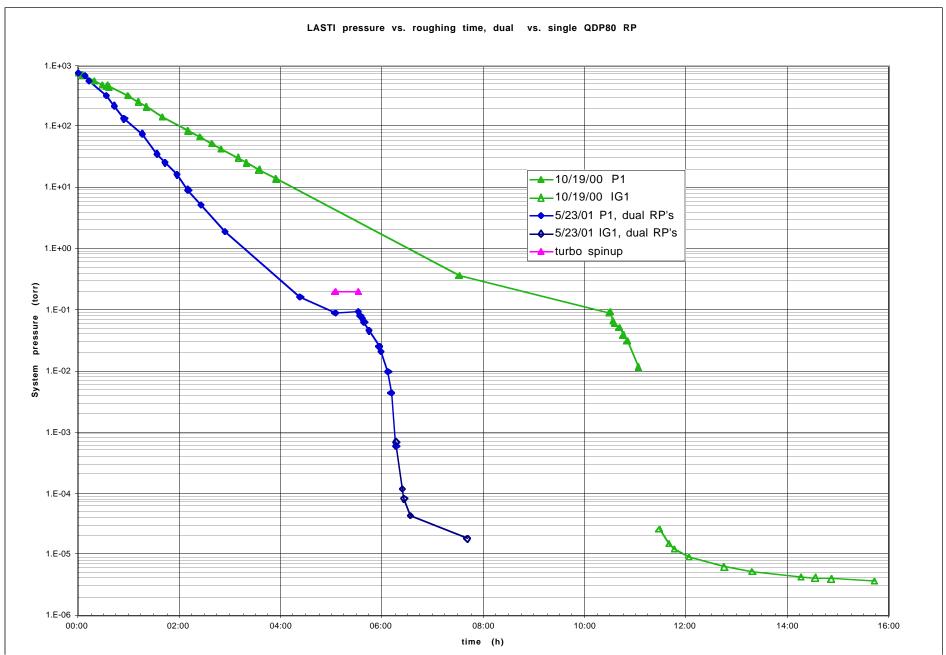
New Infrastructure: DAQ, EPICS, GDS*







NEW! IMPROVED!! Faster Pumpdowns!





Special BSC Cleanroom





Quad Pendulum







LASTI PSL





Status & Plan

Accomplishments this period

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♦ SEI base installation & leakcheck completed*
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- ♦ BSC cleanroom completed, HAM cleanrooms refurbished
- ♦ pumping system augmentation completed
- ♦ CDS backbone, DAQ, EPICS systems installed & tested
- ♦ Initial SOS and PSL controls complete (except live-ammo testing)

Coming up

- ♦ Initial 2-mirror test cavity suspension & installation: 9/01
- ♦ PSL complete & operating, "first light": 9/01
- ♦ Test cavity program starts (cavity locking): 10/01
- ♦ Cable tray installation: 11/01
- ♦ SEI/SUS assembly "Mezzanine": 1/02



Milestones/longer term

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♦4Q99 / 4Q99 act: LASTI vacuum envelope commissioned √
♦1Q00sch / 3Q01 act: LASTI external structures installed (site tooling & help) √
♦ 2Q00sch / 4Q00 act: LASTI infrastructure design review
♦3Q01: LASTI infrastructure completion (DAQ, CDS, PSL, test cavity, ...)
       test cavity program, hydraulics, intensity stabilization, other expt's?
♦ 1Q02: HAM pathfinder installed for standalone testing probable slip
♦ 2Q02: MC controls SUS installed testing starts possible slip
♦3Q02: BSC pathfinder installed for standalone testing probable slip
♦4Q02: TM controls SUS installed for standalone testing
♦ 3Q03: LASTI controls test review
♦ 2Q04: LASTI noise prototype installed not allowed to slip!
♦ $\omega 2005: LASTI SUS/SEI test review
♦ 3Q05: Adv LIGO PSL/MC tests start
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Pressing Issues

Integration test of hydraulic pre-isolators

♦ Based on LIGO I pressure, looks best to do HAM13 as soon as working prototypes are ready; can we do this & get useful data in time to influence pathfinder HAM and BSC advanced SEI deliveries? can there/will there be a LLO LIGO I retrofit?

Short cavity test

♦ g-parameter nearly unstable (coincidentally, close to adLIGO baseline)

♦ tests to help relieve anxiety about cavity instability, Guoy phase separation, WFS operation with "the big spots"?

♦ can we fit in some backlogged PSL-enabled tests (req'd for adLIGO but unassigned)?

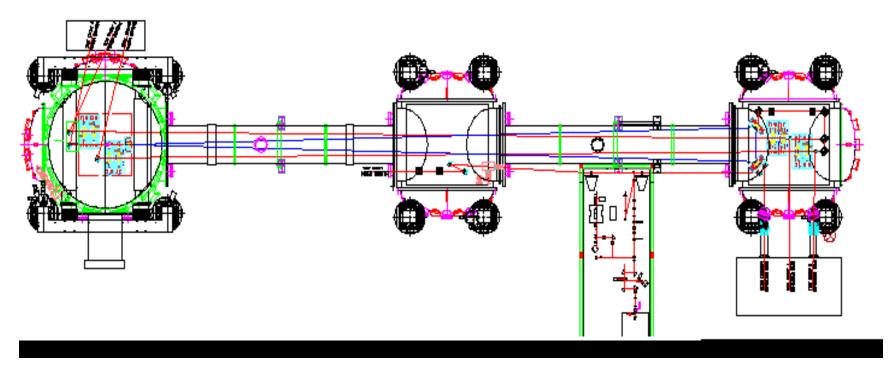
- -super-duper intensity stabilization (like 3e-9/rHz)
- —high power photodetectors
- -spatial wavefront sensing
- -other ideas?



Optical Configuration and Initial Experiments

LASTI Review
LSC 9
LIGO Hanford Observatory
August 8th, 2001

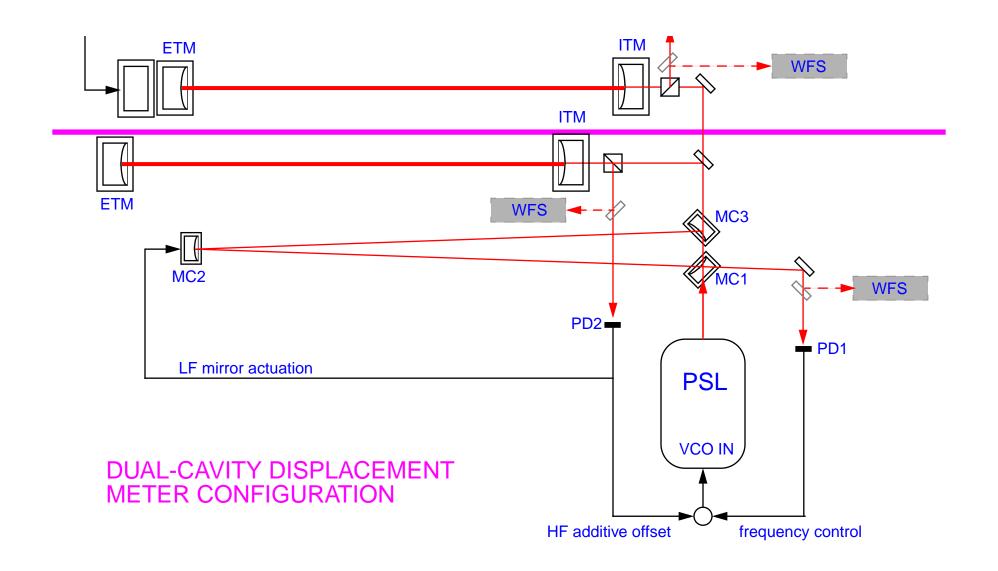
LASTI Configuration



- Initial test cavity included in center HAM
- Full LASTI in end HAM and BSC chamber

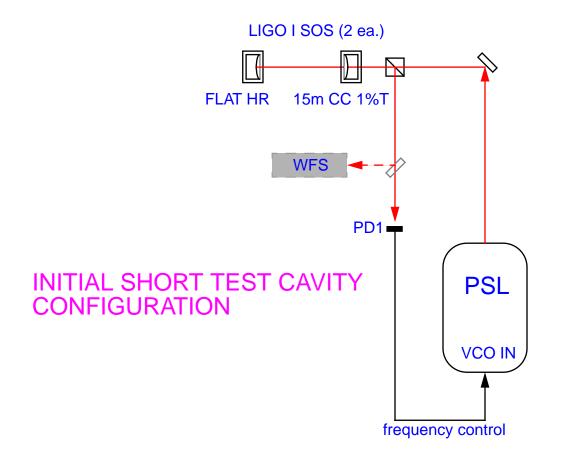
LASTI Features

- LIGO I style PSL
- Advance LIGO mode cleaner inc. suspensions
- Two test cavities
 - -Limits frequency noise
 - Increases spot size to limit thermoelastic noise for sapphire
- Test cavity properties
 - -waist size ~3.5 mm, length 16m
 - **-**g factor ~ 0.9, finesse ~ 2000
 - Triple suspensions (HAM), Quad suspensions (BSC)
- Test cavity parameters realized by selecting the properties of the input mirrors



Initial In-Vacuum Suspended CavityTest

- Aim: To commission the LASTI 10W PSL and to gain experience operating suspended marginally stable cavities inc. wavefront sensing (small Guoy phase separation)
- Initial Cavity Parameters:
 - Length ~1 m
 - Mirrors: Flat HR Mirror, 10m ROC 0.63 % T
 - Derived Cavity Parameters: g ~ 0.9, Finesse ~1000
 - -I and finesse similar to full LASTI test cavities
- Suspensions are LIGO I SOS suspension



Summary of Current Status

PSL

- Table layout design completed
- Optical assembly commenced
- Electrical installation completed
- —Full commissioning to commence early Sept. 2001.
- Enclosure designed and expected delivery late Sept. 2001

Initial Test Cavity

- -Assembly of suspended mirrors to start early Sept. 2001.
- In vacuum installation to be completed by end Sept. 2001'.

Seismic Isolation

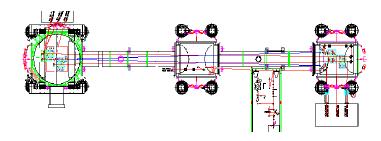
—Initial LIGO I HAM installation completed

Displacement noise modeling and trade studies

LASTI Progress Report
LSC 9
LIGO Hanford Observatory
August 8, 2001



Baseline Configuration



- 15 meter cavity length
- 2 cavities side-by-side
- Fused silica input couplers in HAM21 suspended from recycling mirror (3 stage) suspensions
- Sapphire ETMs in BSC00 suspended from core optics (4 stage) suspensions
- Pendulum suspensions with fused silica fibers/ribbons



Two Variants

- Different radii of curvature on mirrors
 - Changes in stability of cavity (g factor)
 - Changes in beam radius (thermal noise)
- "Conservative" approach
 - Stable cavity g = 0.33
 - Smaller beam $w_0 = 2.25 \text{ mm}$
- "Aggressive" approach
 - Close to marginal stability g = 0.85
 - Larger beam $w_0 = 3.6 \text{ mm}$



Parameters

Cavity length: 15 m

• Residual gas pressure: Water at 10⁻⁶ torr

Mode cleaner length: 15 m

• HAM seismic noise: 2×10^{-13} m/Hz^{1/2} @ 10 Hz

• Finesse: 2000

Laser power: 6 W

Frequency noise stabilization gain: 10⁹ / f²

Ta₂O₅/SiO₂ optical coatings, 3% and 1 ppm

40 kg Silica input couplers (RM) / Sapphire ETMs



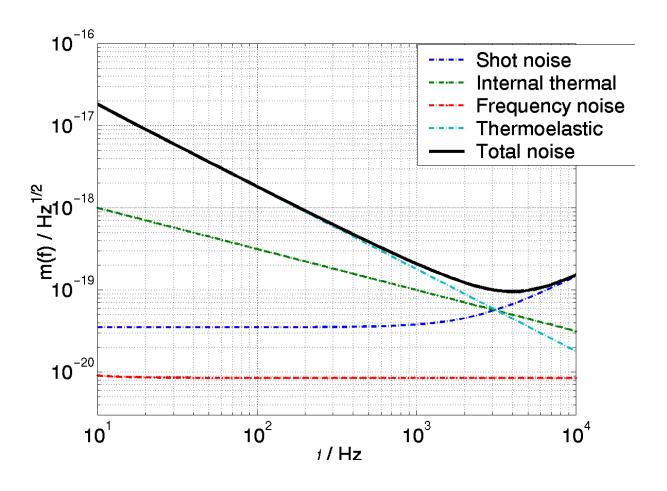
Noise sources I

Noise sources that contribute to total noise

- Seismic
 - Advanced LIGO seismic isolation stacks/suspensions
- Thermoelastic thermal noise
 - Only important in sapphire mirrors
- Structural thermal noise (coating thermal noise)
 - Ta₂O₅/SiO₂ coatings-see talks by Rowan & Gretarsson
- Technical frequency noise
 - 5 kg mode cleaner mirrors
 - Reduced by servo from second cavity
- Shot noise

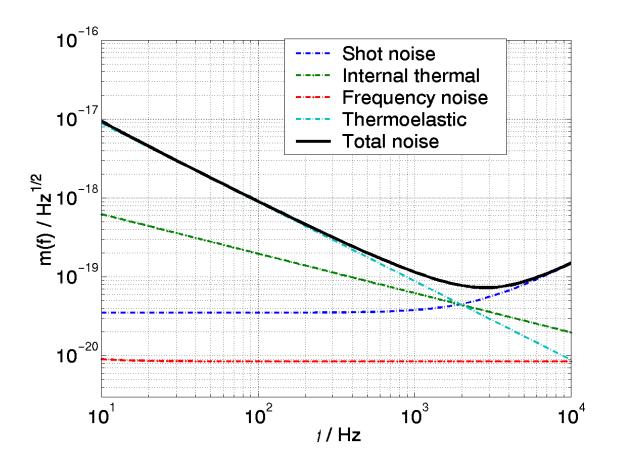


Conservative configuration





Aggressive configuration





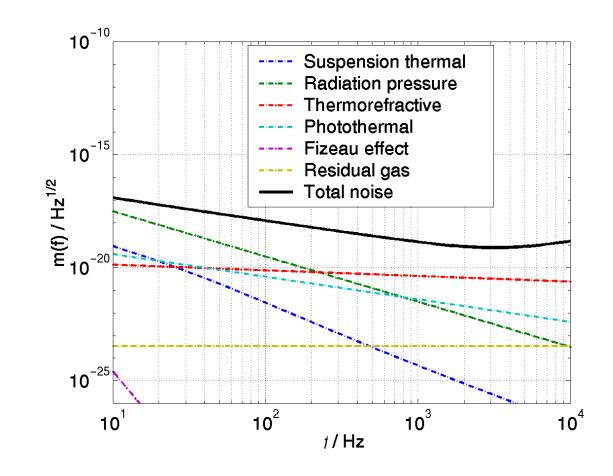
Sources of noise II

Noise sources that do not contribute

- Fizeau noise (Noise from transmission through moving optic)
 - -5 cm Faraday isolator, n = 1.5
- Photothermal noise (Elastic response to photon heating)
 - –Coating absorption 0.5×10^{-6}
- Thermorefractive noise (Change in n from thermal fluctuations)
 - -Ta₂O₅/SiO₂ coatings
- Suspension thermal noise
- Residual gas noise
- Radiation pressure



Smaller noise sources



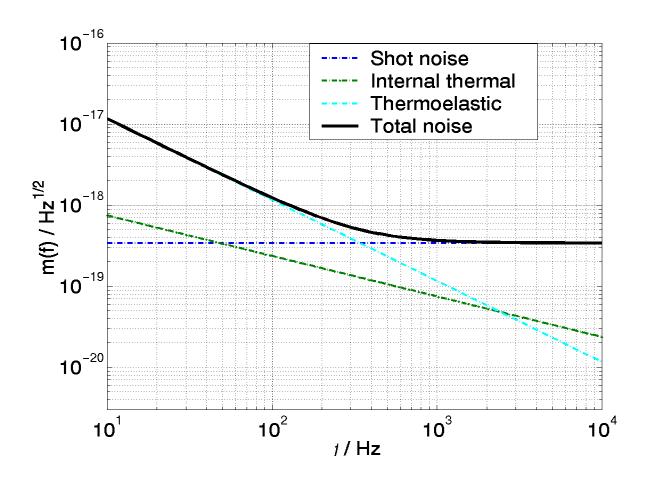


Other configurations Under possible consideration

- Short (20 cm), nearly flat-flat cavity
 - Larger spot size reduces thermal noise
 - Measure thermoelastic dependance on w₀
 - Cavity very near unstable, hard to get finesse of 200
- Silica end mirrors (if problems develop with sapphire)
 - Reduced thermoelastic noise
 - Coating thermal noise detectable
- Flat-top beams
 - Reduces thermoelastic noise

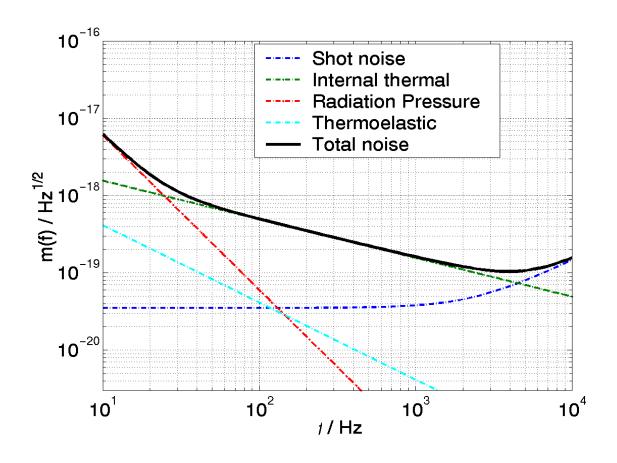


Short cavity





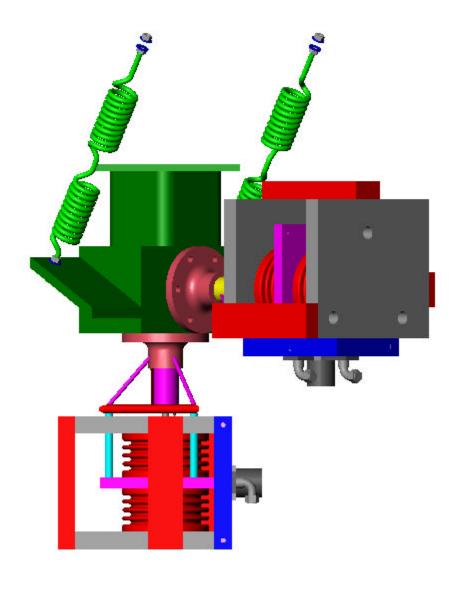
Silica test mass substrates





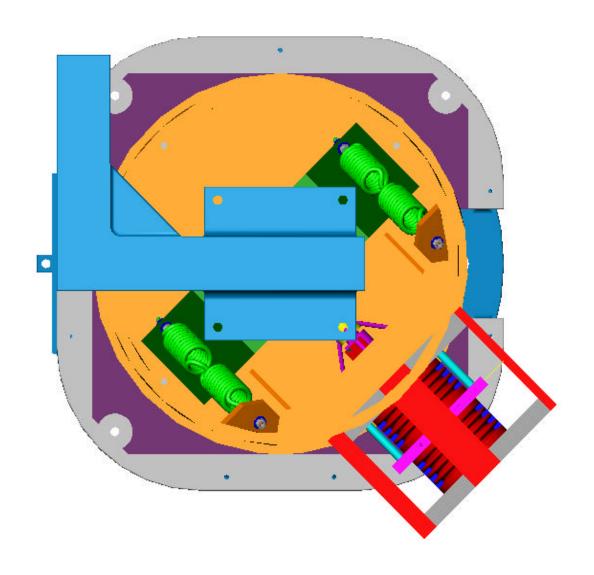
Hydraulic SEI Pre-isolator Design

- Hydraulic actuator, pumping, and control system has been developed at Stanford.
- Implementation and testing of a 6 DOF system under a LIGO stack at MIT
- Joshua Phinney (MIT) at Stanford for 3 weeks
- Part of LIGO 2 seismic plan T000024
- Purpose of Quiet Hydraulic actuation system is to:
 - provide factor of 10 sensor correction of low frequency ground noise (.1 to 10 HZ)
 - provide sufficient dynamic range (+/- 1mm) for earth tide and seasonal drift correction



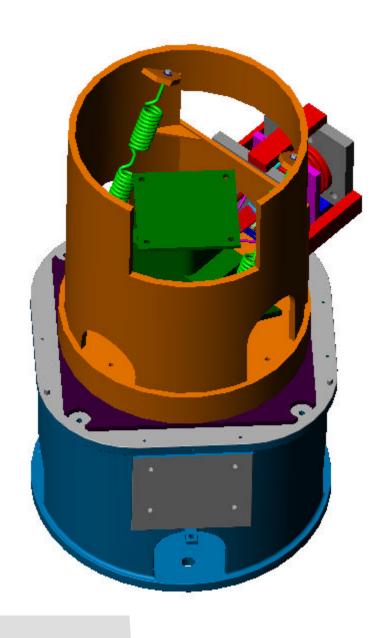
- Counterwound springs 2 pc
- Hydraulic Actuators
- Flange mount to center element
- Position sensors concentric to actuator axis

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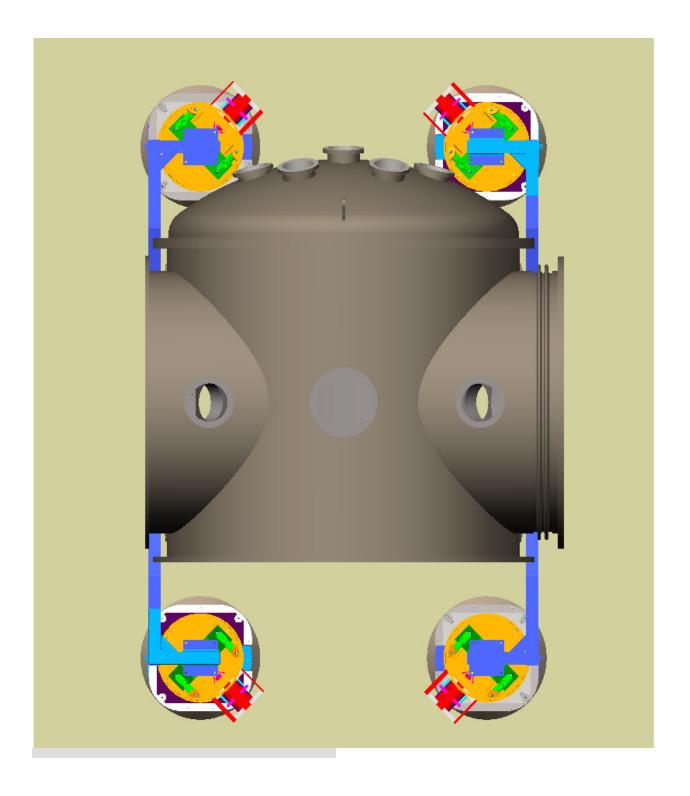
- Springs attach to support structure
- Takes stack weight and provides tension on actuator
- Uses existing piers and adapter plates

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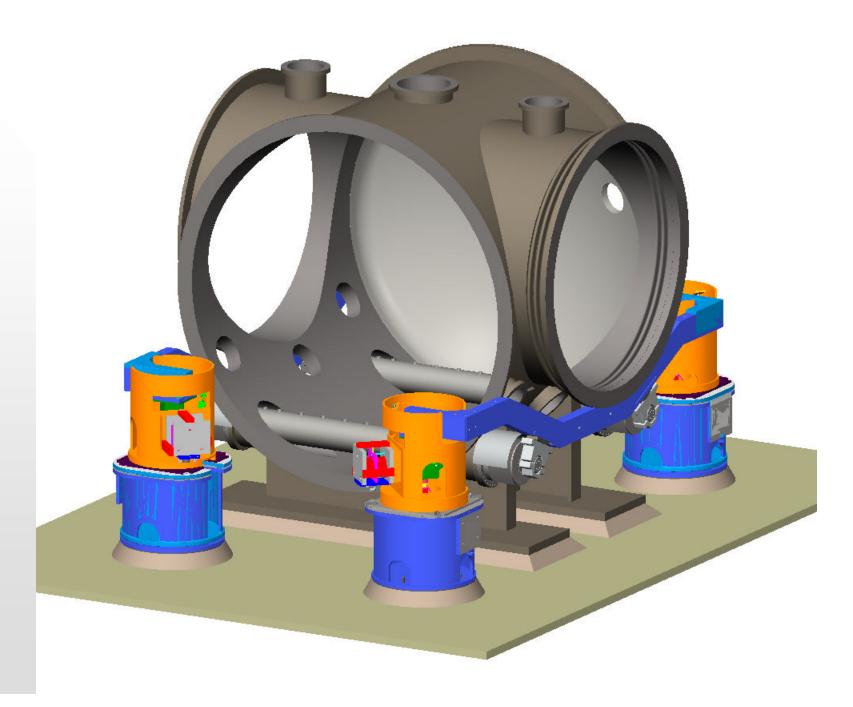


- Hard stops and top plate not shown
- Fits in place of existing course actuators
- Course
 actuators
 to consist
 of x and y
 axis
 dovetails
 kinematic z
 axis

8/14/2001



- 6 DOF actuation
- Tangent to table center
- Analysis remaining



SCHEDULING MILESTONES

Joshua returns from Stanford	9/1/01
Design and analysis complete	11/24/01
 Long lead and fabricated parts in house 	2/15/02
 Mechanical and electronics assembly complete 	4/1/02
 Programming and troubleshooting complete 	5/15/02
 6 DOF testing complete 	7/30/02

Note:

Schedule could be accelerated to resolve problems with impulsive noise disturbing lock at LLO