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Calculation of fields in a Dual Recycled Michelson Cavity using linear approximation

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■ Revision history

■ Version 1.0 : April 7, 2004 : Initial release

Fabry-Perot is used to illustrate the basic idea. That part is copied from a separate note, and mathematics part for FP summation should be merged with the mathematics part at the end. Also, PRM calculation is appended without any consistency review.

■ Introduction

The time domain simulation of a compound optics system forming resonators uses a time step which is determined by cavity lengths of the system. Usually, the CPU time to simulate a given duration of physics process is proportional to the number of iterations, which, in turn, is inversely proportional to the simulation time step.

For a large scale interferometer, like LIGO and Virgo, the naive approach combining constituent optics becomes very slow because short cavities in the Michelson cavity determine the simulation time step. The time scale of interest is usually the trip time of laser through the long FP arm. The Michelson cavity is usually 100 to 1000 times shorter than the long arm, and the simulation becomes slower by this amount compared to the case that the simulation runs using the one trip time through the long arm as the simulation time step.

In order to overcome this problem, it was proposed to use an analytic calculation of the field evolution in the Michelson cavity over the longer time using an adiabatic approximation. This showed a good success to speed up the simulation of a system where different cavity sizes exist.

The original method used an adiabatic approximation, i.e., mirror positions and input fields do not change during the one time step. This revealed a limitation when the simulation was used to study a case when the frequency noise was important. Because the time dependence of the phase of a field is the frequency, this approach of using a constant input field during one time step can be used only for limited situations where derivatives of physics quantities can be neglected.

A solution to address this issue is to use a linear approximation of physics quantities, like input fields and mirror positions, during one time step. Then the lowest order effect due to the frequency change can be included in the calculation.

In this note, formulas are derived to calculate the field evolution in a Fabry Perot cavity and in a dual recycling Michelson cavity using a linear approximation. This result can be used to calculate the field evolution using a time step much longer than the time step determined by the cavity lengths in the Michelson cavity.

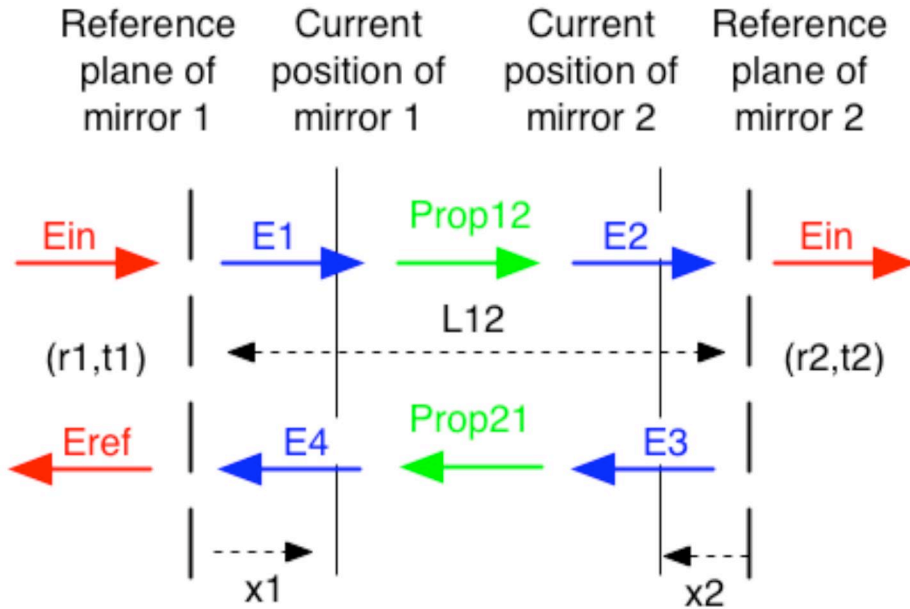
The full interferometer with long arms can be calculated by attaching propagators and end mirrors to this compound cavity. The bandwidth of length control systems of large interferometers is typically of the same order as the half spectral range of the long arm, and the calculation using the combination of compound Michelson cavity and end mirrors is an appropriate choice for most of the case.

■ Preparation (many similar names are used)

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Off[General::"spell"];  
Off[General::"spell1"];
```

■ Field evolution in Fabry-Perot cavity

■ Fig. 1 : Fabry-Perot cavity schematic view



■ basic formulation

In Fig.1, vertical dashed lines are the reference positions of two mirrors. All fields are calculated at these reference positions which do not move. Vertical solid lines are the actual positions of mirrors. Their positions are specified by the distances from their respective reference position.

$E_2(t)$ is the field at the mirror 2 reference plane at time t , and $E_3(t)$ is the reflected field at the same place at the same time. The reflection occurs on the actual mirror position, where the incident field is $E_2(t) \cdot \text{Exp}[i k x_2(t)]$ and the reflected field is $-r_2 \cdot E_2(t) \cdot \text{Exp}[i k \cdot x_2(t)]$. $E_3(t)$ is defined on the reference plane, so $E_3(t) = -r_2 E_2(t) \cdot \text{Exp}[i 2 k \cdot x_2(t)]$. The approximation here is that $E_2(t)$ and $x_2(t)$ does not change in the time scale of $v x / c \approx 10^{-6} 10^{-6} / 10^8 = 10^{-20}$.

$$\begin{aligned}
 E_1(t) &= t_1 E_{in}(t) - r_1 \cdot E_4(t) \cdot \text{Exp}[i 2 k \cdot x_1(t)] \\
 E_2(t) &= E_1(t - \tau) \cdot \text{Exp}[-i k \cdot L_0] \\
 E_3(t) &= -r_2 \cdot E_2(t) \cdot \text{Exp}[i 2 k \cdot x_2(t)] \\
 E_4(t) &= E_3(t - \tau) \cdot \text{Exp}[-i k \cdot L_0]
 \end{aligned}$$

$$\tau = \frac{L_0}{c}$$

$$\begin{aligned}
E_1(t) &= t_1 E_{\text{in}}(t) - r_1 \cdot E_4(t) \cdot \text{Exp}[i 2 k \cdot x_1(t)] \\
&= t_1 E_{\text{in}}(t) - r_1 \cdot E_3(t - \tau) \cdot \text{Exp}[-i k \cdot L_0] \cdot \text{Exp}[i 2 k \cdot x_1(t)] \\
&= t_1 E_{\text{in}}(t) + r_1 r_2 \cdot E_2(t - \tau) \cdot \text{Exp}[i 2 k \cdot x_2(t - \tau)] \cdot \text{Exp}[-i k \cdot L_0] \cdot \text{Exp}[i 2 k \cdot x_1(t)] \\
&= t_1 E_{\text{in}}(t) + r_1 r_2 \cdot E_1(t - 2\tau) \cdot \text{Exp}[-i k \cdot L_0] \cdot \text{Exp}[i 2 k \cdot x_2(t - \tau)] \cdot \text{Exp}[-i k \cdot L_0] \cdot \text{Exp}[i 2 k \cdot x_1(t)]
\end{aligned}$$

$$\begin{aligned}
E_1(t) &= t_1 E_{\text{in}}(t) + r_1 r_2 \cdot E_1(t - 2\tau) \cdot \text{Exp}[-i 2 \cdot k \cdot (L_0 - x_2(t - \tau) - x_1(t))] \\
&= t_1 E_{\text{in}}(t) + R \cdot E_1(t - 2\tau) \cdot \text{Exp}[i \phi(t)]
\end{aligned}$$

$$\begin{aligned}
\phi(t) &= 2 \cdot k \cdot (x_1(t) + x_2(t - \tau)) \\
R &= r_1 \cdot r_2 \cdot \text{Exp}[-i 2 k L_0]
\end{aligned}$$

$$\begin{aligned}
E_1(t) &= t_1 E_{\text{in}}(t) + R \cdot \text{Exp}[i \phi(t)] \cdot E_1(t - 2\tau) \\
&= t_1 E_{\text{in}}(t) + R \cdot \text{Exp}[i \phi(t)] \cdot (t_1 E_{\text{in}}(t - 2\tau) + R \cdot \text{Exp}[i \phi(t - 2\tau)] \cdot E_1(t - 4\tau)) \\
&= t_1 E_{\text{in}}(t) + R \cdot \text{Exp}[i \phi(t)] \cdot t_1 E_{\text{in}}(t - 2\tau) + R^2 \text{Exp}[i(\phi(t) + \phi(t - 2\tau))] \cdot E_1(t - 4\tau) \\
&= t_1 E_{\text{in}}(t) + R \cdot \text{Exp}[i \phi(t)] \cdot t_1 E_{\text{in}}(t - 2\tau) + R^2 \text{Exp}[i(\phi(t) + \phi(t - 2\tau))] \cdot (t_1 E_{\text{in}}(t - 4\tau) + R \cdot \text{Exp}[i \phi(t - 4\tau)] \cdot E_1(t - 6\tau)) \\
&= t_1 E_{\text{in}}(t) + R \cdot \text{Exp}[i \phi(t)] \cdot t_1 E_{\text{in}}(t - 2\tau) + \\
&\quad R^2 \cdot \text{Exp}[i(\phi(t) + \phi(t - 2\tau))] \cdot t_1 E_{\text{in}}(t - 4\tau) + R^3 \text{Exp}[i(\phi(t) + \phi(t - 2\tau) + \phi(t - 4\tau))] \cdot E_1(t - 6\tau)
\end{aligned}$$

$$E_1(t) = t_1 E_{\text{in}}(t) + t_1 \cdot \sum_{n=1}^{N-1} R^n E_{\text{in}}(t - 2n\tau) \cdot \text{Exp}[i \sum_{m=0}^{n-1} \phi(t - 2m\tau)] + R^N \text{Exp}[i \sum_{m=0}^{N-1} \phi(t - 2m\tau)] \cdot E_1(t - 2N\tau)$$

$$\begin{aligned}
E_1(t + 2N\tau) &= t_1 E_{\text{in}}(t + 2N\tau) + \\
&\quad t_1 \cdot \sum_{n=1}^{N-1} R^n E_{\text{in}}(t + 2N\tau - 2n\tau) \cdot \text{Exp}[i \sum_{m=0}^{n-1} \phi(t + 2N\tau - 2m\tau)] + R^N \text{Exp}[i \sum_{m=0}^{N-1} \phi(t + 2N\tau - 2m\tau)] \cdot E_1(t)
\end{aligned}$$

■ Summary of formulation

$$\begin{aligned}
E_1(t + 2N\tau) &= t_1 E_{\text{in}}(t + 2N\tau) + \\
&\quad t_1 \cdot \sum_{n=1}^{N-1} \{R^n E_{\text{in}}(t + 2N\tau - 2n\tau) \cdot \text{Exp}[i \sum_{m=0}^{n-1} \phi(t + 2N\tau - 2m\tau)]\} + R^N \text{Exp}[i \sum_{m=0}^{N-1} \phi(t + 2N\tau - 2m\tau)] \cdot E_1(t)
\end{aligned}$$

$$\begin{aligned}
\phi(T) &= 2 \cdot k \cdot (x_1(T) + x_2(T - \tau) - x_1(t) - x_2(t)) \\
R &= r_1 \cdot r_2 \cdot \text{Exp}[-i 2 k (L_0 - x_1(t) - x_2(t))]
\end{aligned}$$

■ Linear approximation

$$\begin{aligned}
x_j(t + \Delta) &= x_j(t) + v_j \cdot \Delta \\
E_{\text{in}}(t + m\tau) &= E_{\text{in}}(t) \text{Exp}[\beta \cdot m \cdot \tau]
\end{aligned}$$

■ single summation

■ Calculation

$$\begin{aligned} \frac{1}{2k} \sum_{m=0}^{n-1} \phi(t + 2N\tau - 2m\tau) &= \sum_{m=0}^{n-1} \{x_1(t + 2N\tau - 2m\tau) + x_2(t + 2N\tau - 2m\tau - \tau)\} = \\ \sum_{m=0}^{n-1} \{x_1(t) + \tau \cdot 2(N - m) \cdot v_1 + x_2(t) + \tau \cdot (2N - 2m - 1) \cdot v_2\} &= \\ n \{x_1(t) + x_2(t) + \tau \cdot (2N \cdot v_1 + (2N - 1) \cdot v_2)\} - 2\tau(v_1 + v_2)n(n - 1)/2 &= \\ n \{x_1(t) + x_2(t) + \tau \cdot (2N \cdot v_1 + (2N - 1) \cdot v_2) - \tau(v_1 + v_2)(n - 1)\} & \end{aligned}$$

```
FSUM1[n_] := n (x1 + x2 + τ (2 N v1 + (2 N - 1) v2) - τ (v1 + v2) (n - 1))
Simplify[FSUM1[N]]
```

$$N((1 + N)\tau v_1 + N\tau v_2 + x_1 + x_2)$$

$$N(\tau v_1 + x_1(t) + N\tau v_1 + x_2(t) + N\tau v_2) = N(\tau v_1 + \frac{x_1(t) + x_1(t + 2N\tau) + x_2(t) + x_2(t + 2N\tau)}{2}) \approx N^2 \tau(v_1 + v_2)$$

```
FullSimplify[Series[FSUM1[n], {n, 0, 2}]]
```

$$((\tau + 2N\tau)v_1 + 2N\tau v_2 + x_1 + x_2)n - \tau(v_1 + v_2)n^2 + O[n]^3$$

$$\sum_{m=0}^{n-1} \phi(t + 2N\tau - 2m\tau) = 2k(FS1 \cdot n - FS2 \cdot n^2) = 2k \cdot FS2 \cdot n(2N - n)$$

$$FS1 = (\tau + 2N\tau)v_1 + 2N\tau v_2 \approx 2N(v_1 + v_2)\tau = 2N \cdot FS2$$

$$FS2 = \tau(v_1 + v_2)$$

■ Summary

$$\sum_{m=0}^{n-1} \phi(t + 2N\tau - 2m\tau) = 2k \cdot FS2 \cdot n(2N - n)$$

$$FS2 = \tau(v_1 + v_2)$$

■ double summation

■ calculation

$$\begin{aligned}
 DS[N] &= \sum_{n=1}^{N-1} \left\{ R^n E_{in}(t + 2N\tau - 2n\tau) \cdot \text{Exp}\left[i \sum_{m=0}^{n-1} \phi(t + 2N\tau - 2m\tau)\right] \right\} \\
 &= \sum_{n=1}^{N-1} \left\{ R^n E_{in}(t) \text{Exp}[2(N-n)\beta\tau] \cdot \text{Exp}[i 2k \cdot FS2 \cdot n(2N-n)] \right\} \\
 &= E_{in}[t + 2N\tau] \sum_{n=1}^{N-1} \left\{ R^n \text{Exp}[-n2\beta\tau] \cdot \text{Exp}[i 2k \cdot FS2 \cdot n(2N-n)] \right\} \\
 &= E_{in}[t + 2N\tau] \sum_{n=1}^{N-1} \left\{ (R \cdot \text{Exp}[-2\beta\tau + i 2k \cdot FS2 \cdot 2N])^n \cdot \text{Exp}[-i 2k \cdot FS2 \cdot n^2] \right\} \\
 &= E_{in}[t + 2N\tau] \sum_{n=1}^{N-1} \left\{ \tilde{R}^n \cdot \text{Exp}[-i 2k \cdot FS2 \cdot n^2] \right\}
 \end{aligned}$$

$$\tilde{R} = R \cdot \text{Exp}[-2\beta\tau + i 4kN \cdot FS2]$$

$$2k \cdot FS2 = 4 \times \pi / \lambda \times \tau (v_1 + v_2) = 12 / 10^{-6} \times 10^{-7} 10^{-6} = 10^{-6} \sim 10 \cdot \tau$$

$$SP[a_, N_, M_] := \text{FullSimplify}\left[\sum_{n=1}^{N-1} (a^n n^M)\right]$$

```
SP[a, N, 0]
SP[a, N, 2]
SP[a, N, 4]
```

$$\frac{-a + a^N}{-1 + a}$$

$$\frac{-a(1+a) + a^N(a(1+a) - 2(-1+a)aN + (-1+a)^2 N^2)}{(-1+a)^3}$$

$$\frac{1}{(-1+a)^5} (-a(1+a)(1+a(10+a)) + a^N(a(1+a)(1+a(10+a)) - 4(-1+a)a(1+a(4+a))N + 6(-1+a)^2 a(1+a)N^2 - 4(-1+a)^3 aN^3 + (-1+a)^4 N^4)$$

■ numerical values

```

SP[0.9, ∞, 0]
SP[0.9, ∞, 2]
SP[0.9, ∞, 4]
SP[0.9, ∞, 6]
SP[0.9, 100, 0]
SP[0.9, 100, 2]
SP[0.9, 100, 4]
SP[0.9, 100, 6]
SP[0.9, 50, 0]
SP[0.9, 50, 2]
SP[0.9, 50, 4]
SP[0.9, 50, 6]

```

9.

1710.

1.84851×10^6

4.9956×10^9

8.99973

1706.82

1.80909×10^6

4.48366×10^9

8.94846

1525.96

1.10257×10^6

1.34843×10^9

■ Summation expression of the field

■ calculation

$$FS2 = \tau (v_1 + v_2)$$

$$R = r_1 \cdot r_2 \cdot \text{Exp}[i 2 k (L_0 - x_1(t) - x_2(t))]$$

$$\tilde{R} = R \cdot \text{Exp}[-2 \beta \tau + i 4 \text{kN} \cdot FS2]$$

$$E_1(t + 2N\tau)$$

$$= t_1 E_{in}(t + 2N\tau) + t_1 \cdot \sum_{n=1}^{N-1} \left\{ R^n E_{in}(t + 2N\tau - 2n\tau) \cdot \text{Exp}\left[i \sum_{m=0}^{n-1} \phi(t + 2N\tau - 2m\tau)\right] \right\} +$$

$$\begin{aligned}
& R^N \text{Exp} \left[i \sum_{m=0}^{N-1} \phi (t + 2 N \tau - 2 m \tau) \right] \cdot E_1 (t) \\
&= t_1 E_{\text{in}} (t + 2 N \tau) + t_1 E_{\text{in}} [t + 2 N \tau] \sum_{n=1}^{N-1} \left\{ \tilde{R}^n \cdot \text{Exp} [-i 2 k \cdot \text{FS2} \cdot n^2] \right\} + \\
& R^N \text{Exp} [i 2 k \cdot \text{FS2} \cdot N^2] \cdot E_1 (t) \\
&\approx t_1 E_{\text{in}} (t + 2 N \tau) \left\{ 1 + \frac{-\tilde{R} + \tilde{R}^N}{-1 + \tilde{R}} + \text{SP2} \right\} + R^N \text{Exp} [i 2 k \cdot \text{FS2} \cdot N^2] \cdot E_1 (t) \\
&= t_1 E_{\text{in}} (t + 2 N \tau) \left\{ \frac{1 - \tilde{R}^N}{1 - \tilde{R}} - i 2 k \cdot \text{FS2} \cdot \text{SP2} \right\} + R^N \text{Exp} [i 2 k \cdot \text{FS2} \cdot N^2] \cdot E_1 (t) \\
\text{SP2} &= \frac{\tilde{R} (1 + \tilde{R}) - \tilde{R}^N (\tilde{R} (1 + \tilde{R}) + 2 (1 - \tilde{R}) \tilde{R} N + (1 - \tilde{R})^2 N^2)}{(1 - \tilde{R})^3}
\end{aligned}$$

■ Summary

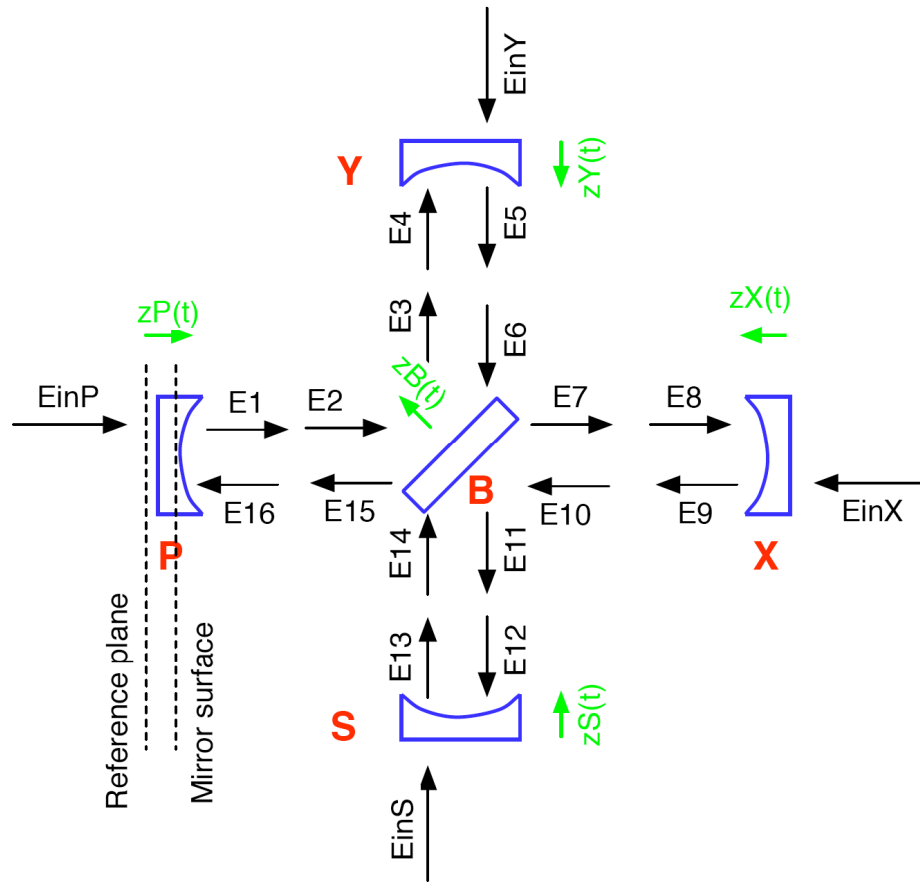
$$\begin{aligned}
E_1 (t + 2 N \tau) &= t_1 E_{\text{in}} (t + 2 N \tau) \left\{ \frac{1 - \tilde{R}^N}{1 - \tilde{R}} - i 2 k \cdot \text{FS2} \cdot \text{SP2} \right\} + R^N \text{Exp} [i 2 k \cdot \text{FS2} \cdot N^2] \cdot E_1 (t) \\
\text{FS2} &= \tau (v_1 + v_2) \\
R &= r_1 \cdot r_2 \cdot \text{Exp} [-i 2 k (L_0 - x_1 (t) - x_2 (t))] \\
\tilde{R} &= R \cdot \text{Exp} [-2 \beta \tau + i 4 k N \cdot \text{FS2}] \\
\text{SP2} &= \frac{\tilde{R} (1 + \tilde{R}) - \tilde{R}^N (\tilde{R} (1 + \tilde{R}) + 2 (1 - \tilde{R}) \tilde{R} N + (1 - \tilde{R})^2 N^2)}{(1 - \tilde{R})^3}
\end{aligned}$$

■ Reflected and transmitted field

$$\begin{aligned}
E_1 (t) &= t_1 E_{\text{in}} (t) - r_1 \cdot E_4 (t) \cdot \text{Exp} [i 2 k \cdot x_1 (t)] \\
E_2 (t) &= E_1 (t - \tau) \cdot \text{Exp} [-i k \cdot L_0] \\
E_3 (t) &= -r_2 \cdot E_2 (t) \cdot \text{Exp} [i 2 k \cdot x_2 (t)] \\
E_4 (t) &= E_3 (t - \tau) \cdot \text{Exp} [-i k \cdot L_0] \\
E_{\text{tra}} (t) &= t_2 \cdot E_2 (t) = t_2 \cdot E_1 (t - \tau) \cdot \text{Exp} [-i k \cdot L_0] \\
E_{\text{ref}} (t) &= r_1 \cdot \text{Exp} [-i 2 k \cdot x_1 (t)] \cdot E_{\text{in}} (t) + t_1 \cdot E_4 (t) \\
&= r_1 \cdot \text{Exp} [-i 2 k \cdot x_1 (t)] \cdot E_{\text{in}} (t) + t_1 \cdot (t_1 \cdot E_{\text{in}} (t) - E_1 (t)) / (r_1 \cdot \text{Exp} [i 2 k \cdot x_1 (t)]) \\
&= E_{\text{in}} (t) \cdot \frac{r_1^2 + t_1^2}{r_1 \cdot \text{Exp} [i 2 k \cdot x_1 (t)]} - E_1 (t) \cdot \frac{t_1}{r_1 \cdot \text{Exp} [i 2 k \cdot x_1 (t)]}
\end{aligned}$$

■ Dual recycling Michelson cavity : Formulation

■ Fig.2 Schematic view of dual recycling Michelson cavity



■ Definitions

All fields are assumed to have a common constant angular frequency, ω , e.g., the carrier frequency. When incoming fields have different frequencies, like carrier and sideband components, fields with different frequencies are calculated separately. The fluctuation of frequency of fields can be simulated as the time dependence of phase of fields.

Fields at various locations in the dual recycling Michelson cavity (DRM) have following relations. $E_n[t]$ is the amplitude of the field N at time t without the fast oscillating part, i.e., the full amplitude is $\text{Exp}[i \omega t] E_n[t]$.

$E_{11hs}[t]$ and $E_{13lhs}[t]$ are there to stop recursion. rfM and rbM are amplitude reflectance from the front and back side of mirror M, and tfM and tbM are transmittance from respective sides. $\Pi_{A \leftarrow B}$ is the propagation phase from B to A. For a scalar field case, it is $\text{Exp}[-i \omega L_{MN}]$ with L_{MN} being the distance between mirror M and N. When the phase of the field going through a cavity is changing, the time derivative of the phase is properly included in the form effectively changing the frequency. τ_M is the trip time between mirror M and the beam splitter, i.e., $\tau_M = L_{BS-M} / \text{speed of light}$.

■ Relations among fields at different locations

```

E1lhs[t_] := tbP[t] EinP[t] + rfP[t] E16[t];
E2[t_] :=  $\Pi_{B \leftarrow P}$  E1[t -  $\tau P$ ];
E3[t_] := rfB[t] E2[t] + tbB[t] E14[t];
E4[t_] :=  $\Pi_{Y \leftarrow B}$  E3[t -  $\tau Y$ ];
E5[t_] := rfY[t] E4[t] + tbY[t] EinY[t];
E6[t_] :=  $\Pi_{B \leftarrow Y}$  E5[t -  $\tau Y$ ];
E7[t_] := rbB[t] E14[t] + tfB[t] E2[t];
E8[t_] :=  $\Pi_{X \leftarrow B}$  E7[t -  $\tau X$ ];
E9[t_] := rfX[t] E8[t] + tbX[t] EinX[t];
E10[t_] :=  $\Pi_{B \leftarrow X}$  E9[t -  $\tau X$ ];
E11[t_] := rbB[t] E10[t] + tfB[t] E6[t];
E12[t_] :=  $\Pi_{S \leftarrow B}$  E11[t -  $\tau S$ ];
E13lhs[t_] := rfS[t] E12[t] + tbS[t] Eins[t];
E14[t_] :=  $\Pi_{B \leftarrow S}$  E13[t -  $\tau S$ ];
E15[t_] := rfB[t] E6[t] + tbB[t] E10[t];
E16[t_] :=  $\Pi_{P \leftarrow B}$  E15[t -  $\tau P$ ];

```

■ Independent fields

When above equations are solved, they come to the following two independent equations.

E1lhs[t]

```

EinP[t] tbP[t] +
rfP[t]  $\Pi_{P \leftarrow B}$  (rfB[t -  $\tau P$ ]  $\Pi_{B \leftarrow Y}$  (rfY[t -  $\tau P - \tau Y$ ]  $\Pi_{Y \leftarrow B}$  (E1[t - 2  $\tau P - 2 \tau Y$ ] rfB[t -  $\tau P - 2 \tau Y$ ]  $\Pi_{B \leftarrow P}$  +
E13[t -  $\tau P - \tau S - 2 \tau Y$ ]  $\Pi_{B \leftarrow S}$  tbB[t -  $\tau P - 2 \tau Y$ ]) + EinY[t -  $\tau P - \tau Y$ ] tbY[t -  $\tau P - \tau Y$ ]) +
 $\Pi_{B \leftarrow X}$  tbB[t -  $\tau P$ ] (EinX[t -  $\tau P - \tau X$ ] tbX[t -  $\tau P - \tau X$ ] + rfX[t -  $\tau P - \tau X$ ]  $\Pi_{X \leftarrow B}$  (E13[t -
 $\tau P - \tau S - 2 \tau X$ ] rbB[t -  $\tau P - 2 \tau X$ ]  $\Pi_{B \leftarrow S}$  + E1[t - 2  $\tau P - 2 \tau X$ ]  $\Pi_{B \leftarrow P}$  tfB[t -  $\tau P - 2 \tau X$ ]))))

```

E13lhs[t]

```
EinS[t] tbS[t] +
rfS[t] ΠS←B (ΠB←Y (rfY[t - τS - τY] ΠY←B (E1[t - τP - τS - 2 τY] rfB[t - τS - 2 τY] ΠB←P +
E13[t - 2 τS - 2 τY] ΠB←S tbB[t - τS - 2 τY]) + EinY[t - τS - τY] tbY[t - τS - τY])
tfB[t - τS] + rbB[t - τS] ΠB←X (EinX[t - τS - τX] tbX[t - τS - τX] +
rfX[t - τS - τX] ΠX←B (E13[t - 2 τS - 2 τX] rbB[t - τS - 2 τX] ΠB←S +
E1[t - τP - τS - 2 τX] ΠB←P tfB[t - τS - 2 τX] )))
```

■ Basic relations

■ Basic idea of linear approximation

When a field evolution over a time step of τ is given as

$$E(t_0) = M(t_0) E(t_0 - \tau),$$

a longer jump can be given as

$$E(t_0) = M(t_0) M(t_0 - \tau) M(t_0 - 2\tau) \dots M(t_0 - (N-1)\tau) E(t_0 - N\tau)$$

In the expression of $M(t - n\tau)$, use a linearized formula - time dependence is linear -, like

$$r(t) = r_0 \exp(i \omega \Delta t), \Delta t = t - t_0,$$

which is valid between t and $t - N\tau$. In this formula, r_0 and ω are evaluated using given values at time t and $t - N\tau$.

By using this linear approximation, the product of $M(t)$ s shown above can be simplified as is shown below.

Another approximation used is to keep only the first term proportional to time, e.g., $\exp[i \omega t] \approx 1 + i \omega t$. Typical value of this expansion parameter is estimated as follows.

$$\omega_{xxx} N \tau = N \times O(k v \tau) = N \times O\left(\frac{2\pi}{\lambda} v \frac{L}{c}\right) = N \times O\left(\frac{2\pi}{10^{-6} (m)} 10^{-6} (m/s) \frac{2 \times 10 (m)}{3 \times 10^8 (m/s)}\right) = N \times O(10^{-6})$$

This is a case of 10 m cavity, with a mirror moving at 10^{-6} m/s. For this case, the accuracy. or the second order correction which is neglected, is $O(10^{-6})$ with $N = 1000$.

■ Calculation of fields

Right hand sides of E1lhs and E13lhs are split into two parts, one depending on the past values of E1 and E13 and the part depending on the external fields.

```
E1Internal [t_] := E1lhs[t] /. {EinP[_] → 0, EinX[_] → 0, EinY[_] → 0, EinS[_] → 0}
E13Internal [t_] := E13lhs[t] /. {EinP[_] → 0, EinX[_] → 0, EinY[_] → 0, EinS[_] → 0}
E1External [t_] := Simplify[E1lhs[t] - E1Internal [t]]
E13External [t_] := Simplify[E13lhs[t] - E13Internal [t]]
```

E1Internal[t]

$$\begin{aligned} & \text{rfP}[t] \Pi_{P \leftarrow B} (\text{rfB}[t - \tau P] \text{rfY}[t - \tau P - \tau Y] \Pi_{B \leftarrow Y} \Pi_{Y \leftarrow B} \\ & \quad (\text{E1}[t - 2 \tau P - 2 \tau Y] \text{rfB}[t - \tau P - 2 \tau Y] \Pi_{B \leftarrow P} + \text{E13}[t - \tau P - \tau S - 2 \tau Y] \Pi_{B \leftarrow S} \text{tbB}[t - \tau P - 2 \tau Y]) + \\ & \quad \text{rfX}[t - \tau P - \tau X] \Pi_{B \leftarrow X} \Pi_{X \leftarrow B} \text{tbB}[t - \tau P] \\ & \quad (\text{E13}[t - \tau P - \tau S - 2 \tau X] \text{rbB}[t - \tau P - 2 \tau X] \Pi_{B \leftarrow S} + \text{E1}[t - 2 \tau P - 2 \tau X] \Pi_{B \leftarrow P} \text{tfB}[t - \tau P - 2 \tau X])) \end{aligned}$$

E1External[t]

$$\begin{aligned} & \text{EinP}[t] \text{tbP}[t] + \text{rfP}[t] \Pi_{P \leftarrow B} (\text{EinX}[t - \tau P - \tau X] \Pi_{B \leftarrow X} \text{tbB}[t - \tau P] \text{tbX}[t - \tau P - \tau X] + \\ & \quad \text{EinY}[t - \tau P - \tau Y] \text{rfB}[t - \tau P] \Pi_{B \leftarrow Y} \text{tbY}[t - \tau P - \tau Y]) \end{aligned}$$

E13Internal[t]

$$\begin{aligned} & \text{rfS}[t] \Pi_{S \leftarrow B} (\text{rfY}[t - \tau S - \tau Y] \Pi_{B \leftarrow Y} \Pi_{Y \leftarrow B} \\ & \quad (\text{E1}[t - \tau P - \tau S - 2 \tau Y] \text{rfB}[t - \tau S - 2 \tau Y] \Pi_{B \leftarrow P} + \text{E13}[t - 2 \tau S - 2 \tau Y] \Pi_{B \leftarrow S} \text{tbB}[t - \tau S - 2 \tau Y]) \\ & \quad \text{tfB}[t - \tau S] + \text{rbB}[t - \tau S] \text{rfX}[t - \tau S - \tau X] \Pi_{B \leftarrow X} \Pi_{X \leftarrow B} \\ & \quad (\text{E13}[t - 2 \tau S - 2 \tau X] \text{rbB}[t - \tau S - 2 \tau X] \Pi_{B \leftarrow S} + \text{E1}[t - \tau P - \tau S - 2 \tau X] \Pi_{B \leftarrow P} \text{tfB}[t - \tau S - 2 \tau X])) \end{aligned}$$

E13External[t]

$$\begin{aligned} & \text{EinS}[t] \text{tbS}[t] + \text{rfS}[t] \Pi_{S \leftarrow B} (\text{EinX}[t - \tau S - \tau X] \text{rbB}[t - \tau S] \Pi_{B \leftarrow X} \text{tbX}[t - \tau S - \tau X] + \\ & \quad \text{EinY}[t - \tau S - \tau Y] \Pi_{B \leftarrow Y} \text{tbY}[t - \tau S - \tau Y] \text{tfB}[t - \tau S]) \end{aligned}$$

■ Linear approximation

Mirrors are moving at constant velocities, and they are reflected as the change of reflectivity of each mirror. The change of the external input fields are explicitly assumed to be of the form

$$E_0 \times \text{Exp}[i \beta t]$$

where E_0 and β are constant during the time to calculate the field evolution.

v_B is $\frac{1}{\sqrt{2}}$ of the beam splitter mirror velocity due to the mirror tilt.

t should be interpreted as $t-t_0$, or the current time is set to 0.

```
LinearMotion := {rfP[t_] -> rfP0 Exp[i 2 k v_p t], rfB[t_] -> rfB0 Exp[i 2 k v_B t],
  rbB[t_] -> rbB0 Exp[-i 2 k v_B t], rfX[t_] -> rfX0 Exp[i 2 k v_x t],
  rfY[t_] -> rfY0 Exp[i 2 k v_y t], rfS[t_] -> rfS0 Exp[i 2 k v_s t], tbP[t_] -> tbP0,
  tbB[t_] -> tbB0, tfB[t_] -> tfB0, tbX[t_] -> tbX0, tbY[t_] -> tbY0, tbS[t_] -> tbS0};
LinearField := {EinP[t_] -> EinP0 Exp[i \beta_p t], EinX[t_] -> EinX0 Exp[i \beta_x t],
  EinY[t_] -> EinY0 Exp[i \beta_y t], EinS[t_] -> EinS0 Exp[i \beta_s t]};
```

Expand[E1Internal[t] /. LinearMotion]

$$\begin{aligned}
& e^{2 i k t v_P + 2 i k (t - \tau_P - \tau_X) v_X} \text{rfP0 rfx0 tbB0 tfB0 E1}[t - 2 \tau_P - 2 \tau_X] \Pi_{B \leftarrow P} \Pi_{B \leftarrow X} \Pi_{P \leftarrow B} \Pi_{X \leftarrow B} + \\
& e^{-2 i k (t - \tau_P - 2 \tau_X) v_B + 2 i k t v_P + 2 i k (t - \tau_P - \tau_X) v_X} \text{rbB0 rfp0 rfx0 tbB0 E13}[t - \tau_P - \tau_S - 2 \tau_X] \Pi_{B \leftarrow S} \Pi_{B \leftarrow X} \Pi_{P \leftarrow B} \Pi_{X \leftarrow B} + \\
& e^{2 i k (t - \tau_P) v_B + 2 i k (t - \tau_P - 2 \tau_Y) v_B + 2 i k t v_P + 2 i k (t - \tau_P - \tau_Y) v_Y} \text{rfB0}^2 \text{rfP0 rfy0 E1}[t - 2 \tau_P - 2 \tau_Y] \Pi_{B \leftarrow P} \Pi_{B \leftarrow Y} \Pi_{P \leftarrow B} \Pi_{Y \leftarrow B} + \\
& e^{2 i k (t - \tau_P) v_B + 2 i k t v_P + 2 i k (t - \tau_P - \tau_Y) v_Y} \text{rfB0 rfp0 rfy0 tbB0 E13}[t - \tau_P - \tau_S - 2 \tau_Y] \Pi_{B \leftarrow S} \Pi_{B \leftarrow Y} \Pi_{P \leftarrow B} \Pi_{Y \leftarrow B}
\end{aligned}$$

Expand[E13Internal[t] /. LinearMotion]

$$\begin{aligned}
& e^{-2 i k (t - \tau_S) v_B + 2 i k t v_S + 2 i k (t - \tau_S - \tau_X) v_X} \text{rbB0 rfs0 rfx0 tfB0 E1}[t - \tau_P - \tau_S - 2 \tau_X] \Pi_{B \leftarrow P} \Pi_{B \leftarrow X} \Pi_{S \leftarrow B} \Pi_{X \leftarrow B} + \\
& e^{-2 i k (t - \tau_S) v_B - 2 i k (t - \tau_S - 2 \tau_X) v_B + 2 i k t v_S + 2 i k (t - \tau_S - \tau_X) v_X} \\
& \quad \text{rbB0}^2 \text{rfs0 rfx0 E13}[t - 2 \tau_S - 2 \tau_X] \Pi_{B \leftarrow S} \Pi_{B \leftarrow X} \Pi_{S \leftarrow B} \Pi_{X \leftarrow B} + \\
& e^{2 i k (t - \tau_S - 2 \tau_Y) v_B + 2 i k t v_S + 2 i k (t - \tau_S - \tau_Y) v_Y} \text{rfB0 rfs0 rfy0 tfB0 E1}[t - \tau_P - \tau_S - 2 \tau_Y] \Pi_{B \leftarrow P} \Pi_{B \leftarrow Y} \Pi_{S \leftarrow B} \Pi_{Y \leftarrow B} + \\
& e^{2 i k t v_S + 2 i k (t - \tau_S - \tau_Y) v_Y} \text{rfs0 rfy0 tbB0 tfB0 E13}[t - 2 \tau_S - 2 \tau_Y] \Pi_{B \leftarrow S} \Pi_{B \leftarrow Y} \Pi_{S \leftarrow B} \Pi_{Y \leftarrow B}
\end{aligned}$$

Expand[E1External[t] /. LinearMotion /. LinearField]

$$\begin{aligned}
& e^{i t \beta_P} \text{EinP0 tbP0} + e^{2 i k t v_P + i (t - \tau_P - \tau_X) \beta_X} \text{EinX0 rfp0 tbB0 tbX0} \Pi_{B \leftarrow X} \Pi_{P \leftarrow B} + \\
& e^{2 i k (t - \tau_P) v_B + 2 i k t v_P + i (t - \tau_P - \tau_Y) \beta_Y} \text{EinY0 rfb0 rfp0 tbY0} \Pi_{B \leftarrow Y} \Pi_{P \leftarrow B}
\end{aligned}$$

Expand[E13External[t] /. LinearMotion /. LinearField]

$$\begin{aligned}
& e^{i t \beta_S} \text{EinS0 tbS0} + e^{-2 i k (t - \tau_S) v_B + 2 i k t v_S + i (t - \tau_S - \tau_X) \beta_X} \text{EinX0 rbB0 rfs0 tbX0} \Pi_{B \leftarrow X} \Pi_{S \leftarrow B} + \\
& e^{2 i k t v_S + i (t - \tau_S - \tau_Y) \beta_Y} \text{EinY0 rfs0 tbY0 tfB0} \Pi_{B \leftarrow Y} \Pi_{S \leftarrow B}
\end{aligned}$$

■ Propagation times, τ 's

- $\tau_N \equiv \frac{L(N \leftrightarrow B)}{c}$: distance between mirror N and the beam splitter
 $\tau = 2 \times (\max[\tau_P, \tau_S] + \max[\tau_X, \tau_Y])$
 $\Delta_{XY} = \tau_X - \tau_Y$
 $\Delta_{PS} = \tau_P - \tau_S$

$$\begin{aligned} & \tau_P + 2 \tau_X + \tau_S / . \{ \tau_P \rightarrow \tau - \tau_X - \tau_Y - \tau_S \} / . \{ \tau_Y \rightarrow \tau_X - \Delta_{XY} \} \\ & \tau_P + 2 \tau_Y + \tau_S / . \{ \tau_P \rightarrow \tau - \tau_X - \tau_Y - \tau_S \} / . \{ \tau_X \rightarrow \Delta_{XY} + \tau_Y \} \\ & 2 \tau_P + 2 \tau_X / . \{ 2 \tau_P + 2 \tau_X \rightarrow \tau + \tau_P + \tau_X - \tau_Y - \tau_S \} / . \{ \tau_P \rightarrow \Delta_{PS} + \tau_S, \tau_X \rightarrow \Delta_{XY} + \tau_Y \} \\ & 2 \tau_P + 2 \tau_Y / . \{ 2 \tau_P + 2 \tau_Y \rightarrow \tau + \tau_P - \tau_X + \tau_Y - \tau_S \} / . \{ \tau_P \rightarrow \Delta_{PS} + \tau_S, \tau_X \rightarrow \Delta_{XY} + \tau_Y \} \\ & 2 \tau_X + 2 \tau_S / . \{ 2 \tau_X + 2 \tau_S \rightarrow \tau - \tau_P + \tau_X - \tau_Y + \tau_S \} / . \{ \tau_P \rightarrow \Delta_{PS} + \tau_S, \tau_X \rightarrow \Delta_{XY} + \tau_Y \} \\ & 2 \tau_Y + 2 \tau_S / . \{ 2 \tau_Y + 2 \tau_S \rightarrow \tau - \tau_P - \tau_X + \tau_Y + \tau_S \} / . \{ \tau_P \rightarrow \Delta_{PS} + \tau_S, \tau_X \rightarrow \Delta_{XY} + \tau_Y \} \end{aligned}$$

$$\tau + \Delta_{XY}$$

$$\tau - \Delta_{XY}$$

$$\tau + \Delta_{PS} + \Delta_{XY}$$

$$\tau + \Delta_{PS} - \Delta_{XY}$$

$$\tau - \Delta_{PS} + \Delta_{XY}$$

$$\tau - \Delta_{PS} - \Delta_{XY}$$

■ Choice of τ

The choice of τ is arbitrary. For the case of FP cavity, one round trip time was a convenient choice and it worked. For the case of DRM, there are several cavity lengths, and the choice is not unique. Most natural choice is the average trip time,

$$\tau_P + \tau_S + \tau_X + \tau_Y$$

Unfortunately, it turns out that one needs to do "extrapolation" (explained below) if this value is used, and "extrapolation" makes simulation unstable. In order to avoid that,

$$\tau = 2 \times (\max[\tau_P, \tau_S] + \max[\tau_X, \tau_Y])$$

is used in the following calculation, with which all calculations can be done by "interpolation".

■ Linearlination of internal fields

■ The formula expressing $E_P (=E1)$ and $E_S (=E13)$ at time t by using past internal fields and external input fields

$$\begin{aligned} E_p[t] &= M_{pxp}[t] E_p[t - \tau - \delta_{pxp}] + M_{pyp}[t] E_p[t - \tau - \delta_{pyp}] \\ &+ M_{pxs}[t] E_p[t - \tau - \delta_{pxs}] + M_{pys}[t] E_p[t - \tau - \delta_{pys}] \\ &+ E_{pExt}[t] \end{aligned}$$

$$\begin{aligned} E_s[t] &= M_{sxp}[t] E_p[t - \tau - \delta_{sxp}] + M_{syyp}[t] E_p[t - \tau - \delta_{syyp}] \\ &+ M_{sxs}[t] E_s[t - \tau - \delta_{sxs}] + M_{sys}[t] E_p[t - \tau - \delta_{sys}] \\ &+ E_{sExt}[t] \end{aligned}$$

Fields at time $t-\tau-\delta$ can be expressed by fields at time t and $t-\tau$ as follows by linear interpolation.

$$E_p[t-\tau-\delta] = E_p[t-\tau] - \Delta E_p \delta = E_p[t-\tau] - (E_p[t] - E_p[t-\tau]) \frac{\delta}{\tau}$$

The choice of τ discussed above is that all δ 's become negative, i.e., evaluation can be done by "interpolating" fields between time t and $t-\tau$.

$$\begin{aligned} E_p[t] &= M_{pxp}[t] (E_p[t-\tau] - \Delta E_p \delta_{pxp}) + M_{pyp}[t] (E_p[t-\tau] - \Delta E_p \delta_{pyp}) + M_{pxs}[t] (E_s[t-\tau] - \Delta E_s \delta_{pxs}) + M_{pys}[t] (E_s[t-\tau] - \Delta E_s \delta_{pys}) + E_{pExt}[t] \\ &= (M_{pxp}[t] + M_{pyp}[t]) E_p[t-\tau] + (M_{pxs}[t] + M_{pys}[t]) E_s[t-\tau] \\ &\quad - M_{pxp} \frac{\delta_{pxp}}{\tau} (E_p[t] - E_p[t-\tau]) - M_{pyp} \frac{\delta_{pyp}}{\tau} (E_p[t] - E_p[t-\tau]) - M_{pxs} \frac{\delta_{pxs}}{\tau} (E_s[t] - E_s[t-\tau]) - M_{pys} \frac{\delta_{pys}}{\tau} (E_s[t] - E_s[t-\tau]) \\ &+ E_{pExt}[t] \\ &= - (M_{pxp} \frac{\delta_{pxp}}{\tau} + M_{pyp} \frac{\delta_{pyp}}{\tau}) E_p[t] - (M_{pxs} \frac{\delta_{pxs}}{\tau} + M_{pys} \frac{\delta_{pys}}{\tau}) E_s[t] \\ &\quad + (M_{pxp} + M_{pyp} + M_{pxp} \frac{\delta_{pxp}}{\tau} + M_{pyp} \frac{\delta_{pyp}}{\tau}) E_p[t-\tau] + (M_{pxs} + M_{pys} + M_{pxs} \frac{\delta_{pxs}}{\tau} + M_{pys} \frac{\delta_{pys}}{\tau}) E_s[t-\tau] + E_{pExt}[t] \\ &= -m_{pp} E_p[t] - m_{ps} E_s[t] + M_{pp} E_p[t-\tau] + M_{ps} E_s[t-\tau] + E_{pExt}[t] \end{aligned}$$

$$\begin{aligned} m_{pp} &= M_{pxp} \frac{\delta_{pxp}}{\tau} + M_{pyp} \frac{\delta_{pyp}}{\tau} \\ m_{ps} &= M_{pxs} \frac{\delta_{pxs}}{\tau} + M_{pys} \frac{\delta_{pys}}{\tau} \end{aligned}$$

$$\begin{aligned} M_{pp} &= M_{pxp} + M_{pyp} + m_{pp} \\ M_{ps} &= M_{pxs} + M_{pys} + m_{ps} \end{aligned}$$

$$\begin{pmatrix} 1 + m_{pp} & m_{ps} \\ m_{sp} & 1 + m_{ss} \end{pmatrix} [t] \begin{pmatrix} E_p \\ E_s \end{pmatrix} [t] = \begin{pmatrix} M_{pp} & M_{ps} \\ M_{sp} & M_{ss} \end{pmatrix} [t] \begin{pmatrix} E_p \\ E_s \end{pmatrix} [t - \tau] + \begin{pmatrix} E_{pExt} \\ E_{sExt} \end{pmatrix} [t]$$

M_{PXP} is the coupling of the previous $E_P(t-\tau)$ to the current $E_P(t)$, through the reflection by mirror X.

m_{pp} also couples the past and present E_P , but is directly caused by the difference of the length between $L_{X \leftrightarrow B}$ and $L_{Y \leftrightarrow B}$. m_{sp} is an important coupling to observe. If a field is resonant in the cavity (all propagators are 1) and if two ITMs have same refractive indexes ($rf_X = rf_Y$), then m_{sp} is proportional to $\tau_X - \tau_Y$. Due to this coupling, the field E_P can leak into the signal recycling cavity even when the dark port condition is fully satisfied.

$$\begin{aligned} E_P \text{ Internal} &= A_{PXP} \text{Exp}[i \omega_{PXP} t] (E_P[t-\tau] - (E_P[t] - E_P[t-\tau]) \frac{\delta_{XPX}}{\tau}) \\ &+ A_{PYP} \text{Exp}[i \omega_{PYP} t] E_P[t-\tau] + (A_{PXS} \text{Exp}[i \omega_{PXS} t] + A_{PYS} \text{Exp}[i \omega_{PYS} t]) E_S[t-\tau] \end{aligned}$$

$$M_{pp} = A_{PXP} \text{Exp}[i \omega_{PXP} t] + A_{PYP} \text{Exp}[i \omega_{PYP} t] + m_{pp} = AM_{pp} + m_{pp}$$

$$\begin{aligned} mpp &= A_{PXP} \text{Exp}[i \omega_{PXP} t] \frac{\delta_{PXP}}{\tau} + A_{PYP} \text{Exp}[i \omega_{PYP} t] \frac{\delta_{PYP}}{\tau} \\ &\simeq A_{PXP} \frac{\delta_{PXP}}{\tau} + A_{PYP} \frac{\delta_{PYP}}{\tau} + i t (A_{PXP} \omega_{PXP} \frac{\delta_{PXP}}{\tau} + A_{PYP} \omega_{PYP} \frac{\delta_{PYP}}{\tau}) \end{aligned}$$

■ Moving the left hand side matrix to right

$$\begin{pmatrix} E_p \\ E_s \end{pmatrix}[t] = \begin{pmatrix} 1 + mpp & mps \\ msp & 1 + mss \end{pmatrix}^{-1} [t] \begin{pmatrix} M_{pp} & M_{ps} \\ M_{sp} & M_{ss} \end{pmatrix} [t] \begin{pmatrix} E_p \\ E_s \end{pmatrix}[t - \tau] + \begin{pmatrix} 1 + mpp & mps \\ msp & 1 + mss \end{pmatrix}^{-1} [t] \begin{pmatrix} E_{pExt} \\ E_{sExt} \end{pmatrix} [t]$$

```
InvS = Series[Inverse[ ( ONEmpp0 + i t mpp1   mps0 + i t mps1
                        msp0 + i t msp1   ONEmss0 + i t mss1 ) ], {t, 0, 1}];
```

$$\text{ONEmpp0} = 1 + mpp0, \text{ONEmss0} = 1 + mss0$$

```
InvS /. {t -> 0}
```

$$\left\{ \left\{ \frac{\text{ONEmss0}}{-mps0 msp0 + \text{ONEmpp0 ONEmss0}}, -\frac{mps0}{-mps0 msp0 + \text{ONEmpp0 ONEmss0}} \right\}, \right. \\ \left. \left\{ -\frac{msp0}{-mps0 msp0 + \text{ONEmpp0 ONEmss0}}, \frac{\text{ONEmpp0}}{-mps0 msp0 + \text{ONEmpp0 ONEmss0}} \right\} \right\}$$

```
FullSimplify[SeriesCoefficient[InvS[[1, 1]], 1]]
FullSimplify[SeriesCoefficient[InvS[[1, 2]], 1]]
FullSimplify[SeriesCoefficient[InvS[[2, 1]], 1]]
FullSimplify[SeriesCoefficient[InvS[[2, 2]], 1]]
```

$$\begin{aligned} &-\frac{i (mps0 msp0 mss1 - (mps1 msp0 + mps0 msp1) \text{ONEmss0} + mpp1 \text{ONEmss0}^2)}{(mps0 msp0 - \text{ONEmpp0 ONEmss0})^2} \\ &\frac{i (-mps0^2 msp1 + mps0 mss1 \text{ONEmpp0} + mpp1 mps0 \text{ONEmss0} - mps1 \text{ONEmpp0 ONEmss0})}{(mps0 msp0 - \text{ONEmpp0 ONEmss0})^2} \\ &\frac{i (-mps1 msp0^2 + mps0 mss1 \text{ONEmpp0} + mpp1 msp0 \text{ONEmss0} - mps1 \text{ONEmpp0 ONEmss0})}{(mps0 msp0 - \text{ONEmpp0 ONEmss0})^2} \\ &-\frac{i (mpp1 mps0 msp0 + \text{ONEmpp0} (-mps1 msp0 - mps0 msp1 + mss1 \text{ONEmpp0}))}{(mps0 msp0 - \text{ONEmpp0 ONEmss0})^2} \end{aligned}$$

```
Expand[(A0 + i t A1) * (B0 + i t B1)]
```

$$A0 B0 + i A1 B0 t + i A0 B1 t - A1 B1 t^2$$


```

Mpp := Apxp Exp[ i wpxp t ] + Aypyp Exp[ i wpyyp t ] + mpp;
Mps := Apxs Exp[ i wpxs t ] + Apys Exp[ i wpys t ] + mps;
Msp := Asxp Exp[ i wsxp t ] + Asyp Exp[ i wsyp t ] + msp;
Mss := Asxs Exp[ i wsxs t ] + Asys Exp[ i wsys t ] + mss;
mpp := Apxp Exp[ i wpxp t ] δpxp + Aypyp Exp[ i wpyyp t ] δpyyp;
mps := Apxs Exp[ i wpxs t ] δpxs + Apys Exp[ i wpys t ] δpys;
msp := Asxp Exp[ i wsxp t ] δsxp + Asyp Exp[ i wsyp t ] δsyp;
mss := Asxs Exp[ i wsxs t ] δsxs + Asys Exp[ i wsys t ] δsys;
MEp := App Exp[ i wpp t ] + ApX Exp[ i wpx t ] + Apy Exp[ i wpy t ];
MEs := Ass Exp[ i wss t ] + Asx Exp[ i wsx t ] + Asy Exp[ i wsy t ];

```

■ valication

```

Apxp := rP rX tB2 ΠP←B ΠB←X ΠX←B ΠB←P;
Aypyp := rP rY rB2 ΠP←B ΠB←Y ΠY←B ΠB←P;
Apxs := rB rP rX tB ΠP←B ΠB←X ΠX←B ΠB←S;
Apys := -rB rP rY tB ΠP←B ΠB←Y ΠY←B ΠB←S;
Asxp := rB rS rX tB ΠS←B ΠB←X ΠX←B ΠB←P;
Asyp := -rB rS rY tB ΠS←B ΠB←Y ΠY←B ΠB←P;
Asxs := rB2 rS rX ΠS←B ΠB←X ΠX←B ΠB←S;
Asys := rS rY tB2 ΠS←B ΠB←Y ΠY←B ΠB←S;
ΠP←B := Exp[ -i k Lp ];
ΠB←P := Exp[ -i k Lp ];
ΠB←X := Exp[ -i k Lx ];
ΠX←B := Exp[ -i k Lx ];
ΠB←Y := Exp[ -i k Ly ];
ΠY←B := Exp[ -i k Ly ];
ΠS←B := Exp[ -i k Ls ];
ΠB←S := Exp[ -i k Ls ];
ttaauu = 2 (Ls + Lx);
Δps := (Lp - Ls) / ttaauu;
Δxy := (Lx - Ly) / ttaauu;
δcorr := Δxy - Δps;
δpxp := Δps + Δxy - δcorr;
δpyyp := Δps - Δxy - δcorr;
δpxs := Δxy - δcorr;
δpys := -Δxy - δcorr;
δsxp := Δxy - δcorr;
δsyp := -Δxy - δcorr;
δsxs := Δxy - Δps - δcorr;
δsys := -Δxy - Δps - δcorr;

```

```

LPRM = 37.5 10^-6;
TPRM = 0.0086;

LSRM = 37.5 10^-6;
TSRM = 0.005;

RBS = 0.49985;
TBS = 0.49985;

LITMX = 37.5 10^-6;
TITMX = 0.005;

LITMY = 37.5 10^-6;
TITMY = 0.005;

(* cavity quantities *)
LengPRM = 0.2;
LengITMX = 2;
LengITMY = 1.7;
LengSRM = 0.4058;

SBFreq = 69.625263 10^6;
Cspeed = 2.99792458 10^8;

delZ = 6.22125057 10^-12;

```

```

numeric := {
  rB -> Sqrt[ RBS ],
  tB -> Sqrt[ TBS ],
  rX -> Sqrt[ 1 - LITMX - TITMX ],
  rY -> Sqrt[ 1 - LITMY - TITMY ],
  rS -> Sqrt[ 1 - LSRM - TSRM ] Exp[ i 2 π  $\frac{2 \text{delZ}}{1.064 10^{-6}}$  ],
  rP -> Sqrt[ 1 - LPRM - TPRM ],
  tP -> Sqrt[ TPRM ],
  k -> 2 Pi SBFreq / Cspeed 0, (* for now CR *)
  cc -> Cspeed,
  Lp -> LengPRM, Lx -> LengITMX, Ly -> LengITMY, Ls -> LengSRM }

```

```

MM00 = ( Apxp + Apyp  Apxs + Apys ) /. numeric
        ( Asxp + Asyp  Asxs + Asys )

```

```

{{0.992863, 0.}, {5.55112×10-17 + 0. i, 0.994664 + 0.000073084 i}}

```

```

mm11 = ( Apxp δpxp + Apyp δpyp  Apxs δpxs + Apys δpys ) /. numeric
        ( Asxp δsxp + Asyp δsyyp  Asxs δsxs + Asys δsys )

```

```

{{-0.146837, 0.0619043}, {0.0620166 + 4.55674×10-6 i, -0.0620166 - 4.55674×10-6 i}}

```

```
( Apxp Apyp Apxs Apys Asxp Asyp Asxs Asys ) /. numeric
```

```
{{0.496431, 0.496431, 0.496431, -0.496431, 0.497332 + 0.000036542 i,
  -0.497332 - 0.000036542 i, {{0.497332 + 0.000036542 i, 0.497332 + 0.000036542 i}}}}
```

```
( δpxp δpyy δpxs δpys δsxp δsyp δsxs δsys ) /. numeric
```

```
{{-0.0855433, -0.210242, -0.0427716, -0.16747, -0.0427716, -0.16747, 0, -0.124699}}
```

```
MM11Amp = Inverse[ (  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$  + mm11 ]. ( MM00 + mm11 )
```

```
{{0.991594 - 3.17408 × 10-9 i, 0.000414761 - 5.67857 × 10-6 i},
 {0.000555764 + 4.37451 × 10-8 i, 0.994284 + 0.0000782618 i}}
```

```
{EigVal0, EigVec0} = Eigensystem[MM00]
```

```
{EigVal1, EigVec1} = Eigensystem[MM11]
```

```
{{0.860184 - 0.498603 i, 0.859352 + 0.49812 i},
 {0.482234 - 0.000753907 i, 0.876042 + 0. i}, {0.875672 + 0. i, -0.482905 + 0.000754955 i}}
```

```
{{0.887288 - 0.470133 i, 0.825569 + 0.52815 i},
 {0.47953 + 0.0000812605 i, 0.877525 + 0. i}, {0.874212 + 0. i, -0.485544 - 0.000370173 i}}
```

```
Abs[ EigVal0[[1]] ]
```

```
Abs[ EigVal0[[2]] ]
```

```
Abs[ EigVal1[[1]] ]
```

```
Abs[ EigVal1[[2]] ]
```

```
0.994244
```

```
0.993282
```

```
1.00414
```

```
0.980054
```

■ EInternal

$$e^{2ik t v_p + 2ik(t - \tau_P - \tau_X) v_x} r_{fP0} r_{fX0} t_{bB0} t_{fB0} E1[t - 2\tau_P - 2\tau_X] \Pi_{B \leftarrow P} \Pi_{B \leftarrow X} \Pi_{P \leftarrow B} \Pi_{X \leftarrow B} +$$

$$e^{-2ik(t - \tau_P - 2\tau_X) v_B + 2ik t v_p + 2ik(t - \tau_P - \tau_X) v_x} r_{bB0} r_{fP0} r_{fX0} t_{bB0} E13[t - \tau_P - \tau_S - 2\tau_X]$$

$$\Pi_{B \leftarrow S} \Pi_{B \leftarrow X} \Pi_{P \leftarrow B} \Pi_{X \leftarrow B} + e^{2ik(t - \tau_P) v_B + 2ik(t - \tau_P - 2\tau_Y) v_B + 2ik t v_p + 2ik(t - \tau_P - \tau_Y) v_Y}$$

$$r_{fB0}^2 r_{fP0} r_{fY0} E1[t - 2\tau_P - 2\tau_Y] \Pi_{B \leftarrow P} \Pi_{B \leftarrow Y} \Pi_{P \leftarrow B} \Pi_{Y \leftarrow B} +$$

$$e^{2ik(t - \tau_P) v_B + 2ik t v_p + 2ik(t - \tau_P - \tau_Y) v_Y} r_{fB0} r_{fP0} r_{fY0} t_{bB0} E13[t - \tau_P - \tau_S - 2\tau_Y] \Pi_{B \leftarrow S} \Pi_{B \leftarrow Y} \Pi_{P \leftarrow B} \Pi_{Y \leftarrow B}$$

■ phase

```
Simplify[ Series[ Factor[ 2 i k t v_p + 2 i k (t - tauP - tauX) v_x ] / (2 i k), {t, 0, 1}]]
Simplify[ Series[
  Factor[ 2 i k (t - tauP) v_B + 2 i k (t - tauP - 2 tauY) v_B + 2 i k t v_p + 2 i k (t - tauP - tauY) v_Y ] / (2 i k),
  {t, 0, 1}]]
Simplify[ Series[ Factor[ -2 i k (t - tauP - 2 tauX) v_B + 2 i k t v_p + 2 i k (t - tauP - tauX) v_x ] / (2 i k),
  {t, 0, 1}]]
Simplify[ Series[ Factor[ 2 i k (t - tauP) v_B + 2 i k t v_p + 2 i k (t - tauP - tauY) v_Y ] / (2 i k),
  {t, 0, 1}]]
```

$$-(\tau P + \tau X) v_x + (v_p + v_x) t + O[t]^2$$

$$-(\tau P + \tau Y) (2 v_B + v_Y) + (2 v_B + v_p + v_Y) t + O[t]^2$$

$$((\tau P + 2 \tau X) v_B - (\tau P + \tau X) v_x) + (-v_B + v_p + v_x) t + O[t]^2$$

$$(-\tau P v_B - (\tau P + \tau Y) v_Y) + (v_B + v_p + v_Y) t + O[t]^2$$

$$E1[t-2 \tau P-2 \tau X] = E1[t-\tau - \Delta_{PS} - \Delta_{XY}] : \delta p_x p = \Delta p_s + \Delta x_y$$

$$E1[t-2 \tau P-2 \tau Y] = E1[t-\tau - \Delta_{PS} + \Delta_{XY}] : \delta p_y p = \Delta p_s - \Delta x_y$$

$$E13[t-\tau P-\tau S-2 \tau X] = E13[t-\tau - \Delta_{XY}] : \delta p_x s = \Delta x_y$$

$$E13[t-\tau P-\tau S-2 \tau Y] = E13[t-\tau + \Delta_{XY}] : \delta p_y s = -\Delta x_y$$

■ summary

$$E_p = E1, E_s = E13$$

$$E_p \text{ Internal} = (A_{pXP} \text{Exp}[i \omega_{pXP} t] + A_{pYP} \text{Exp}[i \omega_{pYP} t]) E_p[t - \tau] + (A_{pXS} \text{Exp}[i \omega_{pXS} t] + A_{pYS} \text{Exp}[i \omega_{pYS} t]) E_s[t - \tau]$$

$$A_{pXP} = r f P 0 r f X 0 t B 0^2 \Phi B P \Phi B X \Phi P B \Phi X B \text{Exp}[-i 2 k (\tau P + \tau X) v_x]$$

$$\omega_{pXP} = 2 k (v_p + v_x)$$

$$\delta p_x p = \Delta p_s + \Delta x_y$$

$$A_{pYP} = r f B 0^2 r f P 0 r f Y 0 \Phi B P \Phi B Y \Phi P B \Phi Y B \text{Exp}[-i 2 k (\tau P + \tau Y) (2 v_B + v_Y)]$$

$$\omega_{pYP} = 2 k (2 v_B + v_p + v_Y)$$

$$\delta p_y p = \Delta p_s - \Delta x_y$$

$$A_{pXS} = r f B 0 r f P 0 r f X 0 t B 0 \Phi B P \Phi B X \Phi S B \Phi X B E13 \text{Exp}[-i 2 k (-(\tau P + 2 \tau X) v_B + (\tau P + \tau X) v_x)]$$

$$\omega_{pXS} = 2 k (-v_B + v_p + v_x)$$

$$\delta p_x s = \Delta x_y$$

$$A_{pYS} = r f B 0 r f P 0 r f Y 0 t B 0 \Phi B P \Phi B Y \Phi S B \Phi Y B \text{Exp}[-i 2 k (\tau P v_B + (\tau P + \tau Y) v_Y)]$$

$$\omega_{pYS} = 2 k (v_B + v_p + v_Y)$$

$$\delta p_y s = -\Delta x_y$$

```
Apxp := rP0 rX0 tB0^2 propP^2 propX^2;
Apyy := rP0 rY0 rB0^2 propP^2 propY^2;
Apxs := -rB0 rP0 rX0 tB0 propP propX^2 props;
ApyS := rB0 rP0 rY0 tB0 propP propY^2 props;
```

■ E13internal

$$\begin{aligned}
& e^{-2ik(t-\tau S)v_B + 2ikt v_S + 2ik(t-\tau S-\tau X)v_x} \text{rbB0 rfs0 rfx0 tfB0 E1}[t - \tau P - \tau S - 2\tau X] \Pi_{B \leftarrow P} \Pi_{B \leftarrow X} \Pi_{S \leftarrow B} \Pi_{X \leftarrow B} + \\
& e^{-2ik(t-\tau S)v_B - 2ik(t-\tau S-2\tau X)v_B + 2ikt v_S + 2ik(t-\tau S-\tau X)v_x} \text{rbB0}^2 \text{rfs0 rfx0} \\
& \text{E13}[t - 2\tau S - 2\tau X] \Pi_{B \leftarrow S} \Pi_{B \leftarrow X} \Pi_{S \leftarrow B} \Pi_{X \leftarrow B} + e^{2ik(t-\tau S-2\tau Y)v_B + 2ikt v_S + 2ik(t-\tau S-\tau Y)v_Y} \\
& \text{rfB0 rfs0 rfy0 tfB0 E1}[t - \tau P - \tau S - 2\tau Y] \Pi_{B \leftarrow P} \Pi_{B \leftarrow Y} \Pi_{S \leftarrow B} \Pi_{Y \leftarrow B} + \\
& e^{2ikt v_S + 2ik(t-\tau S-\tau Y)v_Y} \text{rfs0 rfy0 tbB0 tfB0 E13}[t - 2\tau S - 2\tau Y] \Pi_{B \leftarrow S} \Pi_{B \leftarrow Y} \Pi_{S \leftarrow B} \Pi_{Y \leftarrow B}
\end{aligned}$$

■ phase

```

Simplify[
  Series[Factor[-2 ik (t - τS) v_B + 2 i k t v_S + 2 i k (t - τS - τX) v_x] / (2 i k), {t, 0, 1}]]
Simplify[Series[Factor[2 i k (t - τS - 2 τY) v_B + 2 i k t v_S + 2 i k (t - τS - τY) v_Y] / (2 i k),
  {t, 0, 1}]]
Simplify[Series[Factor[-2 i k (t - τS) v_B - 2 i k (t - τS - 2 τX) v_B +
  2 i k t v_S + 2 i k (t - τS - τX) v_x] / (2 i k), {t, 0, 1}]]
Simplify[Series[Factor[2 i k t v_S + 2 i k (t - τS - τY) v_Y] / (2 i k), {t, 0, 1}]]

```

$$(\tau S v_B - (\tau S + \tau X) v_x) + (-v_B + v_S + v_x) t + O[t]^2$$

$$(-(\tau S + 2\tau Y) v_B - (\tau S + \tau Y) v_Y) + (v_B + v_S + v_Y) t + O[t]^2$$

$$(\tau S + \tau X) (2v_B - v_x) + (-2v_B + v_S + v_x) t + O[t]^2$$

$$-(\tau S + \tau Y) v_Y + (v_S + v_Y) t + O[t]^2$$

$$E1[t-\tau P-\tau S-2\tau X] = E1[t-\tau - \Delta_{XY}] : \delta_{sxp} = \Delta_{xy}$$

$$E1[t-\tau P-\tau S-2\tau Y] = E1[t-\tau + \Delta_{XY}] : \delta_{syp} = -\Delta_{xy}$$

$$E13[t-2\tau S-2\tau X] = E13[t-\tau + \Delta_{PS} - \Delta_{XY}] : \delta_{sxs} = \Delta_{xy} - \Delta_{ps}$$

$$E13[t-2\tau S-2\tau Y] = E13[t-\tau + \Delta_{PS} + \Delta_{XY}] : \delta_{sys} = -\Delta_{xy} - \Delta_{ps}$$

■ summary

$$E_p = E1, E_s = E13$$

$$E_S \text{ Internal} = (A_{SXP} \text{Exp}[i \omega_{SXP} t] + A_{SYP} \text{Exp}[i \omega_{SYP} t]) E_P[t - \tau] + (A_{SXS} \text{Exp}[i \omega_{SXS} t] + A_{SYS} \text{Exp}[i \omega_{SYS} t]) E_S[t - \tau]$$

$$A_{SXP} = \text{rbB0 rfs0 rfx0 tB0} \otimes \text{BS} \otimes \text{BX} \otimes \text{PB} \otimes \text{XB} \text{Exp}[-i 2k (-\tau S v_B + (\tau S + \tau X) v_x)]$$

$$\omega_{SXP} = 2k (-v_B + v_S + v_x)$$

$$\delta_{sxp} = \Delta_{xy}$$

$$A_{SYP} = \text{rfB0 rfs0 rfy0 tB0} \otimes \text{BS} \otimes \text{BY} \otimes \text{PB} \otimes \text{YB} \text{Exp}[-i 2k ((\tau S + 2\tau Y) v_B + (\tau S + \tau Y) v_Y)]$$

$$\omega_{SYP} = 2k (v_B + v_S + v_Y)$$

$$\delta_{syp} = -\Delta_{xy}$$

$$A_{SXS} = \text{rbB0}^2 \text{rfs0 rfx0} \otimes \text{BS} \otimes \text{BX} \otimes \text{SB} \otimes \text{XB} \text{Exp}[-i 2k (\tau S + \tau X) (-2v_B + v_x)]$$

$$\omega_{SXS} = 2k (-2v_B + v_S + v_x)$$

$$\delta_{sxs} = \Delta_{xy} - \Delta_{ps}$$

$$A_{SYS} = \text{rfs0 rfy0 tB0}^2 \otimes \text{BS} \otimes \text{BY} \otimes \text{SB} \otimes \text{YB} \text{Exp}[-i 2k (\tau S + \tau Y) v_Y]$$

$$\omega_{SYS} = 2k (v_S + v_Y)$$

$$\delta_{sys} = -\Delta_{xy} - \Delta_{ps}$$

■ E1external

$$e^{i t \beta_P} \text{EinP0 } tP0 - e^{2 i k t v_P + i (t - \tau_P - \tau_X) \beta_X} \text{EinX0 } rP0 tB0 tX0 \Phi_{BP} \Phi_{XB} +$$

$$e^{2 i k (t - \tau_P) v_B + 2 i k t v_P + i (t - \tau_P - \tau_Y) \beta_Y} \text{EinY0 } rB0 rP0 tY0 \Phi_{BP} \Phi_{YB}$$

■ phase

```
Simplify[ Series[ Factor[ 2 i k (t - \tau_P) v_B + 2 i k t v_P ] / (2 i k), {t, 0, 1}]]
```

$$-\tau_P v_B + (v_B + v_P) t + O[t]^2$$

■ summary

$$E_p = E1, E_s = E13$$

$$E_P \text{ External} = A_{PP} \text{Exp}[i \omega_{PP} t] \text{EinP0} + A_{PX} \text{Exp}[i \omega_{PX} t] \text{EinX0} + A_{PY} \text{Exp}[i \omega_{PY} t] \text{EinY0}$$

$$A_{PP} = tP0$$

$$\omega_{PP} = \beta_P$$

$$A_{PX} = -rP0 tB0 tX0 \Phi_{BP} \Phi_{XB} \text{Exp}[-i (\tau_P + \tau_X) \beta_X]$$

$$\omega_{PX} = \beta_X + 2 k v_P$$

$$A_{PY} = rB0 rP0 tY0 \Phi_{BP} \Phi_{YB} \text{Exp}[-i ((\tau_P + \tau_Y) \beta_Y + 2 k \tau_P v_B)]$$

$$\omega_{PY} = \beta_Y + 2 k (v_B + v_P)$$

■ E13external

$$e^{i t \beta_S} \text{EinS0 } tS0 - e^{-2 i k (t - \tau_S) v_B + 2 i k t v_S + i (t - \tau_S - \tau_X) \beta_X} \text{EinX0 } rBConj0 rS0 tX0 \Phi_{BS} \Phi_{XB} -$$

$$e^{2 i k t v_S + i (t - \tau_S - \tau_Y) \beta_Y} \text{EinY0 } rS0 tB0 tY0 \Phi_{BS} \Phi_{YB}$$

■ phase

```
Simplify[ Series[ Factor[ -2 i k (t - \tau_S) v_B + 2 i k t v_S ] / (2 i k), {t, 0, 1}]]
```

$$\tau_S v_B + (-v_B + v_S) t + O[t]^2$$

■ summary

$$E_p = E1, E_s = E13$$

$$\begin{aligned}
E_S \text{ External} &= A_{SS} \text{ Exp}[i \omega_{SS} t] \text{ EinS0} + A_{SX} \text{ Exp}[i \omega_{SX} t] \text{ EinX0} + A_{SY} \text{ Exp}[i \omega_{SY} t] \text{ EinY0} \\
A_{SS} &= tS0 \\
\omega_{SS} &= \beta_S \\
A_{SX} &= -rB \text{ Conj0} rS0 tX0 \Phi BS \Phi XB \text{ Exp}[-i((\tau S + \tau X) \beta_X - 2 k \tau S v_B)] \\
\omega_{SX} &= \beta_X + 2 k (v_S - v_B) \\
A_{SY} &= -rS0 tB0 tY0 \Phi BS \Phi YB \text{ Exp}[-i(\tau S + \tau Y) \beta_Y] \\
\omega_{SY} &= \beta_Y + 2 k v_S
\end{aligned}$$

■ Summart of fields

$$\begin{aligned}
E_P \text{ Internal} &= (A_{PXP} \text{ Exp}[i \omega_{PXP} t] + A_{PYP} \text{ Exp}[i \omega_{PYP} t]) E_P[t - \tau] + (A_{PXS} \text{ Exp}[i \omega_{PXS} t] + A_{PYS} \text{ Exp}[i \omega_{PYS} t]) E_S[t - \tau] \\
E_S \text{ Internal} &= (A_{PXP} \text{ Exp}[i \omega_{PXP} t] + A_{PYP} \text{ Exp}[i \omega_{PYP} t]) E_P[t - \tau] + (A_{PXS} \text{ Exp}[i \omega_{PXS} t] + A_{PYS} \text{ Exp}[i \omega_{PYS} t]) E_S[t - \tau] \\
E_P \text{ External} &= A_{PP} \text{ Exp}[i \omega_{PP} t] \text{ EinP0} + A_{PX} \text{ Exp}[i \omega_{PX} t] \text{ EinX0} + A_{PY} \text{ Exp}[i \omega_{PY} t] \text{ EinY0} \\
E_S \text{ External} &= A_{SS} \text{ Exp}[i \omega_{SS} t] \text{ EinS0} + A_{SX} \text{ Exp}[i \omega_{SX} t] \text{ EinX0} + A_{SY} \text{ Exp}[i \omega_{SY} t] \text{ EinY0}
\end{aligned}$$

■ Details list

"t" in the exponent = t - t(now).

$$\begin{aligned}
\text{EPint}[t_] &:= (CA_{PXP} \text{ Exp}[i C \omega_{PXP} t] + CA_{PYP} \text{ Exp}[i C \omega_{PYP} t]) \text{ Ep}[t0 - \tau] + \\
&\quad (CA_{PXS} \text{ Exp}[i C \omega_{PXS} t] + CA_{PYS} \text{ Exp}[i C \omega_{PYS} t]) \text{ Es}[t0 - \tau]; \\
A_{PXP} &:= r0_P r0_X t0_B^2 \Pi_{P \leftarrow B} \Pi_{B \leftarrow X} \Pi_{X \leftarrow B} \Pi_{B \leftarrow P} \text{ Exp}[-i 2 k (\tau_P + \tau_X) v_X] \text{ Exp}[-i V_{EP} (\Delta_{PS} + \Delta_{XY})]; \\
\omega_{PXP} &:= 2 k (v_P + v_X); \\
A_{PYP} &:= r0_P r0_Y r0_B^2 \Pi_{P \leftarrow B} \Pi_{B \leftarrow Y} \Pi_{Y \leftarrow B} \Pi_{B \leftarrow P} \text{ Exp}[-i 2 k (\tau_P + \tau_Y) (2 v_B + v_Y)] \text{ Exp}[-i V_{EP} (\Delta_{PS} - \Delta_{XY})]; \\
\omega_{PYP} &:= 2 k (2 v_B + v_P + v_Y); \\
A_{PXS} &:= \\
&\quad rB0_B r0_P r0_X t0_B \Pi_{P \leftarrow B} \Pi_{B \leftarrow X} \Pi_{X \leftarrow B} \Pi_{B \leftarrow S} \text{ Exp}[-i 2 k ((\tau_P + \tau_X) v_X - (\tau_P + 2 \tau_X) v_B)] \text{ Exp}[-i V_{ES} \Delta_{XY}]; \\
\omega_{PXS} &:= 2 k (v_P + v_X - v_B); \\
A_{PYS} &:= r0_B r0_P r0_Y t0_B \Pi_{P \leftarrow B} \Pi_{B \leftarrow Y} \Pi_{Y \leftarrow B} \Pi_{B \leftarrow S} \text{ Exp}[-i 2 k (\tau_P v_B + (\tau_P + \tau_Y) v_Y)] \text{ Exp}[i V_{ES} \Delta_{XY}]; \\
\omega_{PYS} &:= 2 k (v_P + v_Y + v_B);
\end{aligned}$$

$$\begin{aligned}
\text{ESint}[t_] &:= (CA_{SXP} \text{ Exp}[i C \omega_{SXP} t] + CA_{SYP} \text{ Exp}[i C \omega_{SYP} t]) \text{ Ep}[t0 - \tau] + \\
&\quad (CA_{SXS} \text{ Exp}[i C \omega_{SXS} t] + CA_{SYS} \text{ Exp}[i C \omega_{SYS} t]) \text{ Es}[t0 - \tau]; \\
A_{SXP} &:= rB0_B r0_S r0_X t0_B \Pi_{S \leftarrow B} \Pi_{B \leftarrow X} \Pi_{X \leftarrow B} \Pi_{B \leftarrow P} \text{ Exp}[-i 2 k ((\tau_S + \tau_X) v_X - \tau_S v_B)] \text{ Exp}[-i V_{EP} \Delta_{XY}]; \\
\omega_{SXP} &:= 2 k (v_S + v_X - v_B); \\
A_{SYP} &:= \\
&\quad r0_B r0_S r0_Y t0_B \Pi_{S \leftarrow B} \Pi_{B \leftarrow Y} \Pi_{Y \leftarrow B} \Pi_{B \leftarrow P} \text{ Exp}[-i 2 k ((\tau_S + 2 \tau_Y) v_B + (\tau_S + \tau_Y) v_Y)] \text{ Exp}[i V_{EP} \Delta_{XY}]; \\
\omega_{SYP} &:= 2 k (v_B + v_S + v_Y); \\
A_{SXS} &:= rB0_B^2 r0_S r0_X \Pi_{S \leftarrow B} \Pi_{B \leftarrow X} \Pi_{X \leftarrow B} \Pi_{B \leftarrow S} \text{ Exp}[-i 2 k (\tau_S + \tau_X) (v_X - 2 v_B)] \text{ Exp}[i V_{ES} (\Delta_{PS} - \Delta_{XY})]; \\
\omega_{SXS} &:= 2 k (v_S + v_X - 2 v_B); \\
A_{SYS} &:= r0_S r0_Y t0_B^2 \Pi_{S \leftarrow B} \Pi_{B \leftarrow Y} \Pi_{Y \leftarrow B} \Pi_{B \leftarrow S} \text{ Exp}[-i 2 k (\tau_S + \tau_Y) v_Y] \text{ Exp}[i V_{ES} (\Delta_{PS} + \Delta_{XY})]; \\
\omega_{SYS} &:= 2 k (v_S + v_Y);
\end{aligned}$$

```

EPext[t_] := CA_PP Exp[i Cω_PP t] Ein0_P + CA_PX Exp[i Cω_PX t] Ein0_X + CA_PY Exp[i Cω_PY t] Ein0_Y;
A_PP := t0_P;
ω_PP := β_P;
A_PX := -r0_P t0_B t0_X Π_P←B Π_B←X Exp[-i (τ_P + τ_X) β_X];
ω_PX := β_X + 2 k v_P;
A_PY := r0_B r0_P t0_Y Π_P←B Π_B←Y Exp[-i ((τ_P + τ_Y) β_Y + 2 k τ_P v_B)];
ω_PY := β_Y + 2 k (v_B + v_P);

```

```

ESext[t_] := CA_SS Exp[i Cω_SS t] Ein0_P + CA_SX Exp[i Cω_SX t] Ein0_X + CA_SY Exp[i Cω_SY t] Ein0_Y;
A_SS := t0_S;
ω_PP := β_S;
A_SX := -rb0_B r0_S t0_X Π_S←B Π_B←X Exp[-i ((τ_S + τ_X) β_X - 2 k τ_S v_B)];
ω_SX := β_X + 2 k (v_S - v_B);
A_SY := -t0_B r0_S t0_Y Π_S←B Π_B←Y Exp[-i (τ_S + τ_Y) β_Y];
ω_SY := β_Y + 2 k v_S;

```

■ Some calculation

```
vMT00 := {v_P → 0, v_S → 0, v_X → 0, v_Y → 0, v_B → 0}
```

```
VET00 := {V_ES → 0, V_EP → 0}
```

```
FullSimplify[(A_PXP + A_PYP) - (A_SXS + A_SYs) /. vMT00 /. VET00]
```

$$r0_P \Pi_{B \leftarrow P} \Pi_{P \leftarrow B} (r0_X t0_B^2 \Pi_{B \leftarrow X} \Pi_{X \leftarrow B} + r0_B^2 r0_Y \Pi_{B \leftarrow Y} \Pi_{Y \leftarrow B}) - r0_S \Pi_{B \leftarrow S} \Pi_{S \leftarrow B} (r0_X rb0_B^2 \Pi_{B \leftarrow X} \Pi_{X \leftarrow B} + r0_Y t0_B^2 \Pi_{B \leftarrow Y} \Pi_{Y \leftarrow B})$$

```
FullSimplify[((A_PXP + A_PYP) - (A_SXS + A_SYs))^2 + 4 (A_PXS + A_PYS) (A_SXP + A_SYP) /. vMT00 /. VET00]
```

$$4 r0_P r0_S t0_B^2 \Pi_{B \leftarrow P} \Pi_{B \leftarrow S} \Pi_{P \leftarrow B} \Pi_{S \leftarrow B} (r0_X rb0_B \Pi_{B \leftarrow X} \Pi_{X \leftarrow B} - r0_B r0_Y \Pi_{B \leftarrow Y} \Pi_{Y \leftarrow B})^2 +$$

$$(r0_P \Pi_{B \leftarrow P} \Pi_{P \leftarrow B} (r0_X t0_B^2 \Pi_{B \leftarrow X} \Pi_{X \leftarrow B} + r0_B^2 r0_Y \Pi_{B \leftarrow Y} \Pi_{Y \leftarrow B}) -$$

$$r0_S \Pi_{B \leftarrow S} \Pi_{S \leftarrow B} (r0_X rb0_B^2 \Pi_{B \leftarrow X} \Pi_{X \leftarrow B} + r0_Y t0_B^2 \Pi_{B \leftarrow Y} \Pi_{Y \leftarrow B}))^2$$

■ Expression for iteration

$$\vec{E}(t) = \overleftarrow{\text{Min}}(t) \cdot \vec{E}(t - \tau) + \overleftarrow{\text{Mext}}(t) \cdot \vec{E}_{\text{ext}}$$

$$\vec{E} = \begin{pmatrix} E_P \\ E_S \end{pmatrix}, \quad \vec{E}_{\text{ext}} = \begin{pmatrix} \text{EinP0} \\ \text{EinS0} \\ \text{EinX0} \\ \text{EinY0} \end{pmatrix}$$

$$E_{\text{ext}}(t) = \text{Eext0} \times \text{Exp}[i \beta t]$$

$$\mathbf{r}(t) = \mathbf{r}(0) \text{Exp}[i 2 k v t]$$

v_B is $\frac{1}{\sqrt{2}}$ of the beam splitter mirror velocity due to the mirror tilt.
 t is measured "now" as the origine.

■ Recursive formulation and summation

■ Recursive formula

$$\vec{E}(t) = \prod_{k=0}^{N-1} \overleftarrow{\text{Min}}(t - k\tau) \cdot \vec{E}(t - N\tau) + \sum_{j=1}^{N-1} \prod_{k=0}^{j-1} \overleftarrow{\text{Min}}(t - k\tau) \cdot \overleftarrow{\text{Mext}}(t - j\tau) \cdot \vec{E}_{\text{ext}}(t - j\tau) + \overleftarrow{\text{Mext}}(t) \cdot \vec{E}_{\text{ext}}(t)$$

$$\begin{aligned} \vec{E}(t) &= \overleftarrow{\text{Min}}(t) \cdot \vec{E}(t - \tau) + \overleftarrow{\text{Mext}}(t) \cdot \vec{E}_{\text{ext}}(t) \\ &= \overleftarrow{\text{Min}}(t) \cdot (\overleftarrow{\text{Min}}(t - \tau) \cdot \vec{E}(t - 2\tau) + \overleftarrow{\text{Mext}}(t - \tau) \cdot \vec{E}_{\text{ext}}(t - \tau)) + \overleftarrow{\text{Mext}}(t) \cdot \vec{E}_{\text{ext}}(t) \\ &= \overleftarrow{\text{Min}}(t) \cdot \overleftarrow{\text{Min}}(t - \tau) \cdot \vec{E}(t - 2\tau) + \overleftarrow{\text{Min}}(t) \cdot \overleftarrow{\text{Mext}}(t - \tau) \cdot \vec{E}_{\text{ext}}(t - \tau) + \overleftarrow{\text{Mext}}(t) \cdot \vec{E}_{\text{ext}}(t) \\ &= \overleftarrow{\text{Min}}(t) \cdot \overleftarrow{\text{Min}}(t - \tau) \cdot (\overleftarrow{\text{Min}}(t - 2\tau) \cdot \vec{E}(t - 3\tau) + \overleftarrow{\text{Mext}}(t - 2\tau) \cdot \vec{E}_{\text{ext}}(t - 2\tau)) + \\ &\quad \overleftarrow{\text{Min}}(t) \cdot \overleftarrow{\text{Mext}}(t - \tau) \cdot \vec{E}_{\text{ext}}(t - \tau) + \overleftarrow{\text{Mext}}(t) \cdot \vec{E}_{\text{ext}}(t) \\ &= \overleftarrow{\text{Min}}(t) \cdot \overleftarrow{\text{Min}}(t - \tau) \cdot \overleftarrow{\text{Min}}(t - 2\tau) \cdot \vec{E}(t - 3\tau) + \overleftarrow{\text{Min}}(t) \cdot \overleftarrow{\text{Min}}(t - \tau) \cdot \overleftarrow{\text{Mext}}(t - 2\tau) \cdot \vec{E}_{\text{ext}}(t - 2\tau) + \\ &\quad \overleftarrow{\text{Min}}(t) \cdot \overleftarrow{\text{Mext}}(t - \tau) \cdot \vec{E}_{\text{ext}}(t - \tau) + \overleftarrow{\text{Mext}}(t) \cdot \vec{E}_{\text{ext}}(t) \\ &= \prod_{i=0}^{N-1} \overleftarrow{\text{Min}}(t - i\tau) \cdot \vec{E}(t - N\tau) + \sum_{j=1}^{N-1} \prod_{i=0}^{j-1} \overleftarrow{\text{Min}}(t - i\tau) \cdot \overleftarrow{\text{Mext}}(t - j\tau) \cdot \vec{E}_{\text{ext}}(t - j\tau) + \overleftarrow{\text{Mext}}(t) \cdot \vec{E}_{\text{ext}}(t) \end{aligned}$$

$$\vec{E}(t) = \prod_{k=0}^{N-1} \overleftarrow{\text{Min}}(t - k\tau) \cdot \vec{E}(t - N\tau) + \sum_{j=1}^{N-1} \prod_{k=0}^{j-1} \overleftarrow{\text{Min}}(t - k\tau) \cdot \overleftarrow{\text{Mext}}(t - j\tau) \cdot \vec{E}_{\text{ext}}(t - j\tau) + \overleftarrow{\text{Mext}}(t) \cdot \vec{E}_{\text{ext}}(t)$$

$$\begin{aligned}
\mathbf{M}_{\text{in}} [t_-] &:= \begin{pmatrix} \mathbf{A}_{\text{PXYP}} \text{Exp}[\dot{\mathbf{i}} \omega_{\text{PXYP}} t] & \mathbf{A}_{\text{PXYS}} \text{Exp}[\dot{\mathbf{i}} \omega_{\text{PXYS}} t] \\ \mathbf{A}_{\text{SXYP}} \text{Exp}[\dot{\mathbf{i}} \omega_{\text{SXYP}} t] & \mathbf{A}_{\text{SXYS}} \text{Exp}[\dot{\mathbf{i}} \omega_{\text{SXYS}} t] \end{pmatrix}; \\
\text{Min0} &:= \begin{pmatrix} \mathbf{A}_{\text{PXYP}} & \mathbf{A}_{\text{PXYS}} \\ \mathbf{A}_{\text{SXYP}} & \mathbf{A}_{\text{SXYS}} \end{pmatrix}; \\
\text{Min1} &:= \dot{\mathbf{i}} \begin{pmatrix} \mathbf{A}_{\text{PXYP}} \omega_{\text{PXYP}} & \mathbf{A}_{\text{PXYS}} \omega_{\text{PXYS}} \\ \mathbf{A}_{\text{SXYP}} \omega_{\text{SXYP}} & \mathbf{A}_{\text{SXYS}} \omega_{\text{SXYS}} \end{pmatrix} t; \\
\mathbf{A}_{\text{PXYP}} &:= \mathbf{A}_{\text{PXP}} + \mathbf{A}_{\text{PYP}}; \\
\omega_{\text{PXYP}} &:= \frac{\mathbf{A}_{\text{PXP}} \omega_{\text{PXP}} + \mathbf{A}_{\text{PYP}} \omega_{\text{PYP}}}{\mathbf{A}_{\text{PXP}} + \mathbf{A}_{\text{PYP}}}; \\
\mathbf{A}_{\text{PXYS}} &:= \mathbf{A}_{\text{PXS}} + \mathbf{A}_{\text{PYS}}; \\
\omega_{\text{PXYS}} &:= \frac{\mathbf{A}_{\text{PXS}} \omega_{\text{PXS}} + \mathbf{A}_{\text{PYS}} \omega_{\text{PYS}}}{\mathbf{A}_{\text{PXS}} + \mathbf{A}_{\text{PYS}}}; \\
\mathbf{A}_{\text{SXYP}} &:= \mathbf{A}_{\text{SXP}} + \mathbf{A}_{\text{SYP}}; \\
\omega_{\text{SXYP}} &:= \frac{\mathbf{A}_{\text{SXP}} \omega_{\text{SXP}} + \mathbf{A}_{\text{SYP}} \omega_{\text{SYP}}}{\mathbf{A}_{\text{SXP}} + \mathbf{A}_{\text{SYP}}}; \\
\mathbf{A}_{\text{SXYS}} &:= \mathbf{A}_{\text{SXS}} + \mathbf{A}_{\text{SYS}}; \\
\omega_{\text{SXYS}} &:= \frac{\mathbf{A}_{\text{SXS}} \omega_{\text{SXS}} + \mathbf{A}_{\text{SYS}} \omega_{\text{SYS}}}{\mathbf{A}_{\text{SXS}} + \mathbf{A}_{\text{SYS}}}; \\
\mathbf{E}_{\text{ext}} [t_-] &:= \begin{pmatrix} \mathbf{A}\mathbf{E}_P \text{Exp}[\dot{\mathbf{i}} \omega_{\mathbf{E}_P} t] \\ \mathbf{A}\mathbf{E}_S \text{Exp}[\dot{\mathbf{i}} \omega_{\mathbf{E}_S} t] \end{pmatrix}; \\
\mathbf{A}\mathbf{E}_P &:= \text{Ein}_P \mathbf{0} \mathbf{A}_{\text{PP}} + \text{Ein}_X \mathbf{0} \mathbf{A}_{\text{PX}} + \text{Ein}_Y \mathbf{0} \mathbf{A}_{\text{PY}}; \\
\omega_{\mathbf{E}_P} &:= \frac{\text{Ein}_P \mathbf{0} \mathbf{A}_{\text{PP}} \omega_{\text{PP}} + \text{Ein}_X \mathbf{0} \mathbf{A}_{\text{PX}} \omega_{\text{PX}} + \text{Ein}_Y \mathbf{0} \mathbf{A}_{\text{PY}} \omega_{\text{PY}}}{\text{CAE}_P}; \quad (* /. \text{CAE}_P \rightarrow \mathbf{A}\mathbf{E}_P *) \\
\mathbf{A}\mathbf{E}_S &:= \text{Ein}_S \mathbf{0} \mathbf{A}_{\text{SS}} + \text{Ein}_X \mathbf{0} \mathbf{A}_{\text{SX}} + \text{Ein}_Y \mathbf{0} \mathbf{A}_{\text{SY}}; \\
\omega_{\mathbf{E}_S} &:= \frac{\text{Ein}_S \mathbf{0} \mathbf{A}_{\text{SS}} \omega_{\text{SS}} + \text{Ein}_X \mathbf{0} \mathbf{A}_{\text{SX}} \omega_{\text{SX}} + \text{Ein}_Y \mathbf{0} \mathbf{A}_{\text{SY}} \omega_{\text{SY}}}{\text{CAE}_S};
\end{aligned}$$

■ Summation

$$\vec{E}(t) = \begin{pmatrix} E_P(t) \\ E_S(t) \end{pmatrix}$$

$$\vec{E}(t) = \prod_{k=0}^{N-1} \overleftarrow{\text{Min}}(t - k\tau) \cdot \vec{E}(t - N\tau) + \sum_{j=1}^{N-1} \prod_{k=0}^{j-1} \overleftarrow{\text{Min}}(t - k\tau) \cdot \overleftarrow{\text{Mext}}(t - j\tau) \cdot \vec{E}_{\text{ext}}(t - j\tau) + \overleftarrow{\text{Mext}}(t) \cdot \vec{E}_{\text{ext}}(t)$$

■ Basic strategy

$$\text{Min}(t - n\tau) \approx \text{Min0} - n\tau \text{Min1}$$

$$\text{Min0} \sim \begin{pmatrix} P \leftarrow P & P \leftarrow S \\ S \leftarrow P & S \leftarrow S \end{pmatrix}$$

$$\text{Min0} = \mathbf{U} \mathbf{M0} \mathbf{U}^{-1} = \mathbf{U} \begin{pmatrix} \mathbf{G1} & 0 \\ 0 & \mathbf{G2} \end{pmatrix} \mathbf{U}^{-1}$$

Internal

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \mathbf{i} \begin{pmatrix} A_{PXYP} \omega_{PXYP} & A_{PXYS} \omega_{PXYS} \\ A_{SXYP} \omega_{SXYP} & A_{SXYs} \omega_{SXYs} \end{pmatrix} \tau$$

$$\prod_{k=0}^{N-1} \text{Min}(t - k \tau) = \text{UmatIn} . (M0^N - M0M1N[N - 1]) . \text{InvUMatIn}$$

External

$$\sum_{j=1}^{N-1} \prod_{k=0}^{j-1} \overrightarrow{\text{Min}}(t - k \tau) \cdot \overrightarrow{\text{Mext}}(t - j\tau) = \sum_{j=1}^{N-1} \text{UmatIn} . (M0^j - M0M1N[j - 1]) . \text{InvUmatIn} . \overrightarrow{\text{Mext}}(t - j\tau)$$

$$\prod_{k=0}^{j-1} \text{Min}(t - k \tau) = \text{UmatIn} . (M0^j - M0M1N[j - 1]) . \text{InvUMatIn}$$

$$\text{Mexp}(t - j \tau) = \begin{pmatrix} \text{AE}_P \text{Exp}[-i \omega_{E_P} \tau j] \\ \text{AE}_S \text{Exp}[-i \omega_{E_S} \tau j] \end{pmatrix} = \begin{pmatrix} \text{AE}_P \text{EPT}^j \\ \text{AE}_S \text{EST}^j \end{pmatrix},$$

$$\text{EPT} = \text{Exp}[-i \omega_{E_P} \tau]$$

$$\text{EST} = \text{Exp}[-i \omega_{E_S} \tau]$$

Mathematics

Diagonalization

$$\mathbf{Mx}[n_] := \begin{pmatrix} A & B \\ C & D \end{pmatrix} + n \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

```
{EigVal, EigVec} = Eigensystem[Mx[0]];
DiagonalMatrix[EigVal] // MatrixForm
Umat = Transpose[EigVec] // MatrixForm
```

$$\begin{pmatrix} \frac{1}{2} (A + D - \sqrt{A^2 + 4BC - 2AD + D^2}) & 0 \\ 0 & \frac{1}{2} (A + D + \sqrt{A^2 + 4BC - 2AD + D^2}) \end{pmatrix}$$

$$\begin{pmatrix} -\frac{-A+D+\sqrt{A^2+4BC-2AD+D^2}}{2C} & -\frac{-A+D-\sqrt{A^2+4BC-2AD+D^2}}{2C} \\ 1 & 1 \end{pmatrix}$$

Change eigenvalues so that (1,1) ((2,2)) component becomes A (D) when $\sqrt{(A - D)^2 + 4BC} \approx (A - D)$

$$Z_{ABCD} := (A - D)^2 + 4BC$$

$$\text{Umat} = \begin{pmatrix} 1 & \frac{A-D-\sqrt{CZ_{ABCD}}}{2C} \\ -\frac{A-D-\sqrt{CZ_{ABCD}}}{2B} & 1 \end{pmatrix};$$

`FullSimplify[Inverse[Umat] /. CZABCD -> ZABCD] // MatrixForm`

$$\begin{pmatrix} \frac{1}{2 - \frac{2(A-D)}{A + \sqrt{4BC + (A-D)^2} - D}} & \frac{B}{\sqrt{4BC + (A-D)^2}} \\ -\frac{C}{\sqrt{4BC + (A-D)^2}} & \frac{1}{2 - \frac{2(A-D)}{A + \sqrt{4BC + (A-D)^2} - D}} \end{pmatrix}$$

$$2 - \frac{2(A-D)}{A + \sqrt{4BC + (A-D)^2} - D} = \frac{A-D + \sqrt{(A-D)^2 + 4BC}}{2\sqrt{(A-D)^2 + 4BC}} = \frac{1}{2} + \frac{A-D}{2\sqrt{Z_{ABCD}}}$$

■ Inv Umat

$$\text{InvUmat} = \begin{pmatrix} \frac{1}{2} \left(1 + \frac{A-D}{\sqrt{CZ_{ABCD}}} \right) & \frac{B}{\sqrt{CZ_{ABCD}}} \\ -\frac{C}{\sqrt{CZ_{ABCD}}} & \frac{1}{2} \left(1 + \frac{A-D}{\sqrt{CZ_{ABCD}}} \right) \end{pmatrix};$$

`FullSimplify[Umat.InvUmat /. CZABCD -> ZABCD]`

`FullSimplify[InvUmat.Umat /. CZABCD -> ZABCD]`

`{{1, 0}, {0, 1}}`

`{{1, 0}, {0, 1}}`

■ Make sure : $\begin{pmatrix} A & B \\ C & D \end{pmatrix} = \text{Umat} \cdot \begin{pmatrix} G1 & 0 \\ 0 & G2 \end{pmatrix} \cdot \text{InvUmat}$

`FullSimplify[InvUmat. $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$.Umat /. CZABCD -> ZABCD]`

`{{ $\frac{1}{2} (A + \sqrt{4BC + (A-D)^2} + D)$, 0}, {0, $\frac{1}{2} (A - \sqrt{4BC + (A-D)^2} + D)$ }}`

■ Rotations

`M0 = FullSimplify[InvUmat. $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$.Umat /. CZABCD -> ZABCD]`

`{{ $\frac{1}{2} (A + \sqrt{4BC + (A-D)^2} + D)$, 0}, {0, $\frac{1}{2} (A - \sqrt{4BC + (A-D)^2} + D)$ }}`

$$G1 = M0[[1, 1]]$$

$$G2 = M0[[2, 2]]$$

$$\frac{1}{2} \left(A + \sqrt{4BC + (A-D)^2} + D \right)$$

$$\frac{1}{2} \left(A - \sqrt{4BC + (A-D)^2} + D \right)$$

$$G1 = \frac{1}{2} \left(A + D + \sqrt{4BC + (A-D)^2} \right);$$

$$G2 = \frac{1}{2} \left(A + D - \sqrt{4BC + (A-D)^2} \right);$$

$$M1 = \text{FullSimplify} \left[\text{InvUmat} \cdot \begin{pmatrix} a & b \\ c & d \end{pmatrix} \cdot \text{Umat} /. \text{CZ}_{ABCD} \rightarrow \text{Z}_{ABCD} \right]$$

$$\left\{ \left\{ \frac{2Bc + 2bC + a \left(A + \sqrt{4BC + (A-D)^2} - D \right) + d \left(-A + \sqrt{4BC + (A-D)^2} + D \right)}{2\sqrt{4BC + (A-D)^2}}, \right. \right.$$

$$\left. \frac{ABc + AbC - 2aBC + 2BCd - Bc\sqrt{4BC + (A-D)^2} + bC\sqrt{4BC + (A-D)^2} - BcD - bCD}{2C\sqrt{4BC + (A-D)^2}} \right\},$$

$$\left\{ \frac{ABc + AbC - 2aBC + 2BCd + Bc\sqrt{4BC + (A-D)^2} - bC\sqrt{4BC + (A-D)^2} - BcD - bCD}{2B\sqrt{4BC + (A-D)^2}}, \right.$$

$$\left. \frac{-2Bc - 2bC + d \left(A + \sqrt{4BC + (A-D)^2} - D \right) + a \left(-A + \sqrt{4BC + (A-D)^2} + D \right)}{2\sqrt{4BC + (A-D)^2}} \right\} \right\}$$

$$M1 = \left\{ \left\{ \frac{2Bc + 2bC + a \left(A + \sqrt{4BC + (A-D)^2} - D \right) + d \left(-A + \sqrt{4BC + (A-D)^2} + D \right)}{2\sqrt{4BC + (A-D)^2}}, \right. \right.$$

$$\left. \frac{ABc + AbC - 2aBC + 2BCd - Bc\sqrt{4BC + (A-D)^2} + bC\sqrt{4BC + (A-D)^2} - BcD - bCD}{2C\sqrt{4BC + (A-D)^2}} \right\},$$

$$\left\{ \frac{ABc + AbC - 2aBC + 2BCd + Bc\sqrt{4BC + (A-D)^2} - bC\sqrt{4BC + (A-D)^2} - BcD - bCD}{2B\sqrt{4BC + (A-D)^2}}, \right.$$

$$\left. \frac{-2Bc - 2bC + d \left(A + \sqrt{4BC + (A-D)^2} - D \right) + a \left(-A + \sqrt{4BC + (A-D)^2} + D \right)}{2\sqrt{4BC + (A-D)^2}} \right\} \right\};$$

■ Products

■ calculation

$$\text{Uinv Mx}[n] \text{U} = M0 - n M1, \quad M0 = \begin{pmatrix} G1 & 0 \\ 0 & G2 \end{pmatrix}, \quad M1 = \begin{pmatrix} m11 & m12 \\ m21 & m22 \end{pmatrix}$$

$$\begin{aligned} \text{Mx}[0] \text{Mx}[1] \text{Mz}[2] \dots \text{Mx}[N] &= \text{U} \text{Uinv Mx}[0] \text{U} \text{Uinv Mx}[1] \text{U} \dots \text{Uinv Mx}[N] \text{U} \text{Uinv} \\ &= \text{U} (M0) (M0 - M1) (M0 - 2M1) \dots (M0 - N M1) \text{Uinv} \\ &= \text{U} (M0^{N+1} - M0 M1 M0^{N-1} - 2 M0^2 M1 M0^{N-2} - \dots - N M0^N M1) \text{Uinv} \end{aligned}$$

$$\text{Sum}\left[\mathbf{k} \begin{pmatrix} \text{CG1}^{\mathbf{k}} & 0 \\ 0 & \text{CG2}^{\mathbf{k}} \end{pmatrix} \cdot \begin{pmatrix} \text{m11} & \text{m12} \\ \text{m21} & \text{m22} \end{pmatrix} \cdot \begin{pmatrix} \text{CG1}^{N-\mathbf{k}} & 0 \\ 0 & \text{CG2}^{N-\mathbf{k}} \end{pmatrix}, \{\mathbf{k}, 1, N\}\right]$$

$$\sum_{\mathbf{k}=1}^N \{\{\text{CG1}^N \mathbf{k} \text{ m11}, \text{CG1}^{\mathbf{k}} \text{CG2}^{-\mathbf{k}+N} \mathbf{k} \text{ m12}\}, \{\text{CG1}^{-\mathbf{k}+N} \text{CG2}^{\mathbf{k}} \mathbf{k} \text{ m21}, \text{CG2}^N \mathbf{k} \text{ m22}\}\}$$

FullSimplify[Sum[CG1^N k m11, {k, 1, N}]]
FullSimplify[Sum[CG1^k CG2^{-k+N} k m12, {k, 1, N}]]
FullSimplify[Sum[CG1^{-k+N} CG2^k k m21, {k, 1, N}]]
FullSimplify[Sum[CG2^N k m22, {k, 1, N}]]

$$\frac{1}{2} \text{CG1}^N \text{m11} N (1 + N)$$

$$\frac{\text{CG1} \text{CG2}^N \text{m12} \left(\text{CG2} - \left(\frac{\text{CG1}}{\text{CG2}}\right)^N (\text{CG2} - \text{CG1} N + \text{CG2} N)\right)}{(\text{CG1} - \text{CG2})^2}$$

$$\frac{\text{CG1}^N \text{CG2} \text{m21} \left(\text{CG1} - \left(\frac{\text{CG2}}{\text{CG1}}\right)^N (\text{CG1} + \text{CG1} N - \text{CG2} N)\right)}{(\text{CG1} - \text{CG2})^2}$$

$$\frac{1}{2} \text{CG2}^N \text{m22} N (1 + N)$$

■ Summary

$$\text{Uinv Mx}[n] \text{U} = \mathbf{M0} - n \mathbf{M1}, \quad \mathbf{M0} = \begin{pmatrix} \text{G1} & 0 \\ 0 & \text{G2} \end{pmatrix}, \quad \mathbf{M1} = \begin{pmatrix} \text{m11} & \text{m12} \\ \text{m21} & \text{m22} \end{pmatrix}$$

$$\begin{aligned} \text{Mx}[0] \text{Mx}[1] \text{Mz}[2] \dots \text{Mx}[N] &= \text{U Uinv Mx}[0] \text{U Uinv Mx}[1] \text{U} \dots \text{Uinv Mx}[N] \text{U Uinv} \\ &= \text{U} (\mathbf{M0}) (\mathbf{M0} - \mathbf{M1}) (\mathbf{M0} - 2\mathbf{M1}) \dots (\mathbf{M0} - N \mathbf{M1}) \text{Uinv} \\ &= \text{U} (\mathbf{M0}^{N+1} - \mathbf{M0} \mathbf{M1} \mathbf{M0}^{N-1} - 2 \mathbf{M0}^2 \mathbf{M1} \mathbf{M0}^{N-2} - \dots - N \mathbf{M0}^N \mathbf{M1}) \text{Uinv} \\ &= \text{U} [\mathbf{M0}^{N+1} - \mathbf{M0} \mathbf{M1} N + \dots] \text{Uinv} \end{aligned}$$

$$\mathbf{MOM1N}[n_] := \left(\begin{array}{cc} \frac{1}{2} \text{CG1}^n n (n + 1) \text{m11} & \frac{\text{CG1} (\text{CG2} (\text{CG2}^n - \text{CG1}^n) - \text{CG1}^n (\text{CG2} - \text{CG1}) n)}{(\text{CG1} - \text{CG2})^2} \text{m12} \\ \frac{\text{CG2} (\text{CG1} (\text{CG1}^n - \text{CG2}^n) - \text{CG2}^n (\text{CG1} - \text{CG2}) n)}{(\text{CG1} - \text{CG2})^2} \text{m21} & \frac{1}{2} \text{CG2}^n n (n + 1) \text{m22} \end{array} \right);$$

■ Numerical verification

$$\mathbf{TM0} := \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix};$$

$$\mathbf{TM2} := \begin{pmatrix} 3 & 7 \\ 2 & 9 \end{pmatrix};$$

$$\mathbf{TMN}[n_] := \mathbf{TM0} - n \mathbf{TM2};$$

$$\mathbf{Prod}[n_] := \{\mathbf{EE} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}; \text{Do}[\mathbf{EE} = \mathbf{TMN}[k] \cdot \mathbf{EE}, \{\mathbf{k}, n, 0, -1\}]; \mathbf{EE}\}$$

$$\mathbf{Prod}[1]$$

$$\{\{\{1 - 3\epsilon, -7\epsilon\}, \{-4\epsilon, 2(2 - 9\epsilon)\}\}\}$$

```

Series[ Prod[10], {ε, 0, 1}]
Series[ Prod[5], {ε, 0, 1}]

{{{1 - 165 ε + 0[ε]2, -14252 ε + 0[ε]2}, {-36868 ε + 0[ε]2, 2048 - 506880 ε + 0[ε]2}}

{{{1 - 45 ε + 0[ε]2, -399 ε + 0[ε]2}, {-516 ε + 0[ε]2, 64 - 4320 ε + 0[ε]2}}

MOM1N[10] /. {CG1 → 1, CG2 → 2, m11 → 3, m12 → 7, m21 → 2, m22 → 9}
MOM1N[5] /. {CG1 → 1, CG2 → 2, m11 → 3, m12 → 7, m21 → 2, m22 → 9}

{{165, 14252}, {36868, 506880}}

{{45, 399}, {516, 4320}}

```

■ Misc calculations

$$\frac{A - D - \sqrt{Z_{ABCD}}}{2C} = \frac{A - D - (A - D) \sqrt{1 + \frac{4BC}{(A-D)^2}}}{2C} =$$

$$\frac{A - D}{2C} \left(1 - \sqrt{1 + \frac{4BC}{(A-D)^2}} \right) = \frac{A - D}{2C} \frac{-\frac{4BC}{(A-D)^2}}{1 + \sqrt{1 + \frac{4BC}{(A-D)^2}}} = -\frac{2B}{A - D} \frac{1}{1 + \sqrt{1 + \frac{4BC}{(A-D)^2}}}$$

$$2(Bc + bC) + (a - d)(A - D) + (a + d)(A - D) \zeta_{ABCD} = 2(Bc + bC) + (A - D)(a - d + (a + d) \zeta_{ABCD})$$

$$(A - D)(Bc + bC) - 2BC(a - d) - (Bc - bC)(A - D) \zeta_{ABCD} =$$

$$(A - D)(Bc + bC - (Bc - bC) \zeta_{ABCD}) - 2BC(a - d)$$

$$(A - D)(Bc + bC) - 2BC(a - d) + (Bc - bC)(A - D) \zeta_{ABCD} =$$

$$(A - D)(Bc + bC + (Bc - bC) \zeta_{ABCD}) - 2BC(a - d)$$

$$-2(Bc + bC) - (a - d)(A - D) + (a + d)(A - D) \zeta_{ABCD} =$$

$$-2(Bc + bC) - (A - D)((a - d) - (a + d) \zeta_{ABCD})$$

$$\frac{Bc(1 - \zeta_{ABCD})}{2C \zeta_{ABCD}} + \frac{b(1 + \zeta_{ABCD})}{2 \zeta_{ABCD}} - \frac{B(a - d)}{(A - D) \zeta_{ABCD}}$$

$$= \frac{-Bc \frac{2B}{(A-D)^2}}{\zeta_{ABCD} (1 + \zeta_{ABCD})} + \frac{b(1 + \zeta_{ABCD})}{2 \zeta_{ABCD}} - \frac{B(a - d)}{(A - D) \zeta_{ABCD}}$$

$$= \frac{1}{\zeta_{ABCD}} \left(\frac{1 + \zeta_{ABCD}}{2} b - \frac{2B^2 c}{(A - D)^2 (1 + \zeta_{ABCD})} - \frac{B(a - d)}{(A - D)} \right)$$

$$\frac{1}{\zeta_{ABCD}} \left(\frac{(A - D)(Bc(1 + \zeta_{ABCD}) + bC(1 - \zeta_{ABCD}))}{2B(A - D)} - \frac{C(a - d)}{(A - D)} \right)$$

$$= \frac{1}{\zeta_{ABCD}} \left(\frac{(1 + \zeta_{ABCD})}{2} c + \frac{bC \frac{(-2C)}{(A-D)^2}}{(1 + \zeta_{ABCD})} - \frac{C(a - d)}{(A - D)} \right)$$

$$= \frac{1}{\zeta_{ABCD}} \left(\frac{(1 + \zeta_{ABCD})}{2} c - \frac{2bC^2}{(A - D)^2 (1 + \zeta_{ABCD})} - \frac{C(a - d)}{(A - D)} \right)$$

- **Mathematics Summary**

- **Summary formula**

(* generic matrix with small perturbation *)

$$\mathbf{Mx}[n_] := \begin{pmatrix} A & B \\ C & D \end{pmatrix} - n \begin{pmatrix} a & b \\ c & d \end{pmatrix};$$

(* definition *)

$$\mathbf{CZ}_{ABCD} := (A - D)^2 + 4 B C;$$

$$\mathbf{CSZ}_{ABCD} := \sqrt{1 + \frac{4 B C}{(A - D)^2}};$$

(* Diagonalizing the main matrix, $\text{InvUMat} * \begin{pmatrix} A & B \\ C & D \end{pmatrix} * \text{Umat} = \begin{pmatrix} G1 & 0 \\ 0 & G2 \end{pmatrix}$

$$\sqrt{\mathbf{Z}_{ABCD}} = (A - D) \sqrt{1 + \frac{4 B C}{(A - D)^2}} = (A - D) \mathbf{SZ}_{ABCD} \text{ when } A \neq D. \text{ This makes } G1 \rightarrow A,$$

$$G2 \rightarrow D \text{ when } \text{Umat} \rightarrow \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

*)

$$\mathbf{Umat} = \begin{pmatrix} 1 & \frac{-2 B}{(A - D) (1 + \mathbf{SZ}_{ABCD})} \\ \frac{2 C}{(A - D) (1 + \mathbf{SZ}_{ABCD})} & 1 \end{pmatrix};$$

$$\mathbf{InvUmat} = \begin{pmatrix} \frac{1}{2} \left(1 + \frac{1}{\mathbf{SZ}_{ABCD}}\right) & \frac{B}{(A - D) \mathbf{SZ}_{ABCD}} \\ -\frac{C}{(A - D) \mathbf{SZ}_{ABCD}} & \frac{1}{2} \left(1 + \frac{1}{\mathbf{SZ}_{ABCD}}\right) \end{pmatrix};$$

$$G1 = \frac{1}{2} (A + D + (A - D) \mathbf{SZ}_{ABCD});$$

$$G2 = \frac{1}{2} (A + D - (A - D) \mathbf{SZ}_{ABCD});$$

(* small matrix after rotation, $\mathbf{M1} = \text{InvUMat} * \begin{pmatrix} a & b \\ c & d \end{pmatrix} * \text{Umat}$ *)

$$\mathbf{M1} = \left\{ \left\{ \frac{2 (B c + b C) + (A - D) (a - d + (a + d) \mathbf{SZ}_{ABCD})}{2 (A - D) \mathbf{SZ}_{ABCD}}, \right. \right. \\ \left. \frac{1}{\mathbf{SZ}_{ABCD}} \left(\frac{1 + \mathbf{SZ}_{ABCD}}{2} b - \frac{2 B^2 c}{(A - D)^2 (1 + \mathbf{SZ}_{ABCD})} - \frac{B (a - d)}{(A - D)} \right) \right\}, \\ \left\{ \frac{1}{\mathbf{SZ}_{ABCD}} \left(\frac{1 + \mathbf{SZ}_{ABCD}}{2} c - \frac{2 b C^2}{(A - D)^2 (1 + \mathbf{SZ}_{ABCD})} - \frac{C (a - d)}{(A - D)} \right), \right. \\ \left. \frac{-2 (B c + b C) - (A - D) ((a - d) - (a + d) \mathbf{SZ}_{ABCD})}{2 (A - D) \mathbf{SZ}_{ABCD}} \right\} \};$$

(* $\mathbf{Mx}[0] \mathbf{Mx}[1] \dots \mathbf{Mx}[N]$

$$= \text{Umat} (\mathbf{M0}) (\mathbf{M0} - \mathbf{M1}) \dots (\mathbf{M0} - N \mathbf{M1}) \text{InvUmat}$$

$$= \text{Umat} (\mathbf{M0}^{N+1} - \mathbf{M0M1N}[N] + \dots) \text{InvUmat}$$

$$\mathbf{M0} = \begin{pmatrix} \mathbf{CG1} & 0 \\ 0 & \mathbf{CG2} \end{pmatrix}, \mathbf{M1} = \begin{pmatrix} m11 & m12 \\ m21 & m22 \end{pmatrix}$$

*)

$$\mathbf{M0M1N}[n_] := \begin{pmatrix} \frac{1}{2} \mathbf{CG1}^n n (n + 1) m11 & \frac{\mathbf{CG1} (\mathbf{CG2} (\mathbf{CG2}^n - \mathbf{CG1}^n) - \mathbf{CG1}^n (\mathbf{CG2} - \mathbf{CG1}) n)}{(\mathbf{CG1} - \mathbf{CG2})^2} m12 \\ \frac{\mathbf{CG2} (\mathbf{CG1} (\mathbf{CG1}^n - \mathbf{CG2}^n) - \mathbf{CG2}^n (\mathbf{CG1} - \mathbf{CG2}) n)}{(\mathbf{CG1} - \mathbf{CG2})^2} m21 & \frac{1}{2} \mathbf{CG2}^n n (n + 1) m22 \end{pmatrix};$$

■ Explicit Validation

```
FullSimplify[InvUmat.  $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ .Umat -  $\begin{pmatrix} G1 & 0 \\ 0 & G2 \end{pmatrix}$ ] /. SZABCD → CSZABCD]
```

```
{{0, 0}, {0, 0}}
```

```
FullSimplify[Umat.M1.InvUmat -  $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ ] /. SZABCD → CSZABCD]
```

```
{{0, 0}, {0, 0}}
```

■ MOM1N as a polynomial

$$\text{MON1N1N}[n_] := \text{CG1}^n \begin{pmatrix} \frac{1}{2} n (n+1) m11 & -\frac{\text{CG1} (\text{CG2} - (\text{CG1} - \text{CG2}) n)}{(\text{CG1} - \text{CG2})^2} m12 \\ \frac{\text{CG1} \text{CG2}}{(\text{CG1} - \text{CG2})^2} m21 & 0 \end{pmatrix};$$

$$\text{MON1N1N0}[n_] := \text{CG1}^n \begin{pmatrix} 0 & -\frac{\text{CG1} \text{CG2}}{(\text{CG1} - \text{CG2})^2} m12 \\ \frac{\text{CG1} \text{CG2}}{(\text{CG1} - \text{CG2})^2} m21 & 0 \end{pmatrix};$$

$$\text{MON1N1N1}[n_] := n \text{CG1}^n \begin{pmatrix} \frac{1}{2} m11 & \frac{\text{CG1}}{\text{CG1} - \text{CG2}} m12 \\ 0 & 0 \end{pmatrix};$$

$$\text{MON1N1N2}[n_] := n^2 \text{CG1}^n \begin{pmatrix} \frac{1}{2} m11 & 0 \\ 0 & 0 \end{pmatrix};$$

$$\text{MON1N2N}[n_] := \text{CG2}^n \begin{pmatrix} 0 & \frac{\text{CG1} \text{CG2}}{(\text{CG1} - \text{CG2})^2} m12 \\ -\frac{\text{CG2} (\text{CG1} + (\text{CG1} - \text{CG2}) n)}{(\text{CG1} - \text{CG2})^2} m21 & \frac{1}{2} n (n+1) m22 \end{pmatrix};$$

$$\text{MON1N2N0}[n_] := \text{CG2}^n \begin{pmatrix} 0 & \frac{\text{CG1} \text{CG2}}{(\text{CG1} - \text{CG2})^2} m12 \\ -\frac{\text{CG2} \text{CG1}}{(\text{CG1} - \text{CG2})^2} m21 & 0 \end{pmatrix};$$

$$\text{MON1N2N1}[n_] := n \text{CG2}^n \begin{pmatrix} 0 & 0 \\ -\frac{\text{CG2}}{\text{CG1} - \text{CG2}} m21 & \frac{1}{2} m22 \end{pmatrix};$$

$$\text{MON1N2N2}[n_] := n^2 \text{CG2}^n \begin{pmatrix} 0 & 0 \\ 0 & \frac{1}{2} m22 \end{pmatrix};$$

```

MON1NX[n_] := CG1^n ( CA10 + n CA11 + n^2 CA12) + CG2^n (CA20 + n CA21 + n^2 CA22);

CA10 :=  $\begin{pmatrix} 0 & -\frac{CG1 \cdot CG2}{(CG1 - CG2)^2} m12 \\ \frac{CG1 \cdot CG2}{(CG1 - CG2)^2} m21 & 0 \end{pmatrix};$ 

CA11 :=  $\begin{pmatrix} \frac{1}{2} m11 & \frac{CG1}{CG1 - CG2} m12 \\ 0 & 0 \end{pmatrix};$ 

CA12 :=  $\begin{pmatrix} \frac{1}{2} m11 & 0 \\ 0 & 0 \end{pmatrix};$ 

CA20 :=  $\begin{pmatrix} 0 & \frac{CG1 \cdot CG2}{(CG1 - CG2)^2} m12 \\ -\frac{CG2 \cdot CG1}{(CG1 - CG2)^2} m21 & 0 \end{pmatrix};$ 

CA21 :=  $\begin{pmatrix} 0 & 0 \\ -\frac{CG2}{CG1 - CG2} m21 & \frac{1}{2} m22 \end{pmatrix};$ 

CA22 :=  $\begin{pmatrix} 0 & 0 \\ 0 & \frac{1}{2} m22 \end{pmatrix};$ 

```

■ Misc rotation by Umat and InvUmat

Umat * M0^N * InvUmat

$$\begin{pmatrix} U11 & U12 \\ U21 & U22 \end{pmatrix} \cdot \begin{pmatrix} CG1^N & 0 \\ 0 & CG2^N \end{pmatrix} \cdot \begin{pmatrix} IU11 & IU12 \\ IU21 & IU22 \end{pmatrix}$$

{ {CG1^N IU11 U11 + CG2^N IU21 U12, CG1^N IU12 U11 + CG2^N IU22 U12},
 {CG1^N IU11 U21 + CG2^N IU21 U22, CG1^N IU12 U21 + CG2^N IU22 U22} }

Umat * CAxxx * InvUmat

$$\begin{pmatrix} U11 & U12 \\ U21 & U22 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} IU11 & IU12 \\ IU21 & IU22 \end{pmatrix}$$

{ {IU11 U11, IU12 U11}, {IU11 U21, IU12 U21} }

$$\begin{pmatrix} U11 & U12 \\ U21 & U22 \end{pmatrix} \cdot \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} IU11 & IU12 \\ IU21 & IU22 \end{pmatrix}$$

{ {IU21 U12, IU22 U12}, {IU21 U22, IU22 U22} }

$$\begin{pmatrix} U11 & U12 \\ U21 & U22 \end{pmatrix} \cdot \begin{pmatrix} 0 & X12 \\ X21 & 0 \end{pmatrix} \cdot \begin{pmatrix} IU11 & IU12 \\ IU21 & IU22 \end{pmatrix}$$

{ {IU21 U11 X12 + IU11 U12 X21, IU22 U11 X12 + IU12 U12 X21},
 {IU21 U21 X12 + IU11 U22 X21, IU22 U21 X12 + IU12 U22 X21} }

$$\begin{pmatrix} \mathbf{U11} & \mathbf{U12} \\ \mathbf{U21} & \mathbf{U22} \end{pmatrix} \cdot \begin{pmatrix} \mathbf{x11} & \mathbf{x12} \\ 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} \mathbf{IU11} & \mathbf{IU12} \\ \mathbf{IU21} & \mathbf{IU22} \end{pmatrix}$$

$$\{ \{ \mathbf{IU11} \mathbf{U11} \mathbf{x11} + \mathbf{IU21} \mathbf{U11} \mathbf{x12}, \mathbf{IU12} \mathbf{U11} \mathbf{x11} + \mathbf{IU22} \mathbf{U11} \mathbf{x12} \}, \\ \{ \mathbf{IU11} \mathbf{U21} \mathbf{x11} + \mathbf{IU21} \mathbf{U21} \mathbf{x12}, \mathbf{IU12} \mathbf{U21} \mathbf{x11} + \mathbf{IU22} \mathbf{U21} \mathbf{x12} \} \}$$

$$\begin{pmatrix} \mathbf{U11} & \mathbf{U12} \\ \mathbf{U21} & \mathbf{U22} \end{pmatrix} \cdot \begin{pmatrix} 0 & 0 \\ \mathbf{x21} & \mathbf{x22} \end{pmatrix} \cdot \begin{pmatrix} \mathbf{IU11} & \mathbf{IU12} \\ \mathbf{IU21} & \mathbf{IU22} \end{pmatrix}$$

$$\{ \{ \mathbf{IU11} \mathbf{U12} \mathbf{x21} + \mathbf{IU21} \mathbf{U12} \mathbf{x22}, \mathbf{IU12} \mathbf{U12} \mathbf{x21} + \mathbf{IU22} \mathbf{U12} \mathbf{x22} \}, \\ \{ \mathbf{IU11} \mathbf{U22} \mathbf{x21} + \mathbf{IU21} \mathbf{U22} \mathbf{x22}, \mathbf{IU12} \mathbf{U22} \mathbf{x21} + \mathbf{IU22} \mathbf{U22} \mathbf{x22} \} \}$$

External sources

$$\text{MOM1NX}[n] = \text{CG1}^n (\text{CA10} + n \text{CA11} + n^2 \text{CA12}) + \text{CG2}^n (\text{CA20} + n \text{CA21} + n^2 \text{CA22})$$

$$\sum_{j=1}^{N-1} \prod_{k=0}^{j-1} \overrightarrow{\text{Min}}(t - k\tau) \cdot \overrightarrow{\text{Mext}}(t - j\tau) = \sum_{j=1}^{N-1} \text{UmatIn} \cdot (\text{M0}^j - \text{MOM1N}[j-1]) \cdot \text{InvUmatIn} \cdot \overrightarrow{\text{Mext}}(t - j\tau)$$

$$\prod_{k=0}^{j-1} \text{Min}(t - k\tau) = \text{UmatIn} \cdot (\text{M0}^j - \text{MOM1N}[j-1]) \cdot \text{InvUmatIn}$$

$$\text{Mexp}(t - j\tau) = \begin{pmatrix} \text{AE}_P \text{Exp}[-i \omega_{E_P} \tau j] \\ \text{AE}_S \text{Exp}[-i \omega_{E_S} \tau j] \end{pmatrix} = \begin{pmatrix} \text{AE}_P \text{Exp}[-i \omega_{E_P} \tau j] \\ \text{AE}_S \text{Exp}[-i \omega_{E_S} \tau j] \end{pmatrix} = \begin{pmatrix} \text{AE}_P \text{EPT}^j \\ \text{AE}_S \text{EST}^j \end{pmatrix},$$

$$\text{EPT} = \text{Exp}[-i \omega_{E_P} \tau]$$

$$\text{EST} = \text{Exp}[-i \omega_{E_S} \tau]$$

$$\sum_{j=1}^{N-1} \text{UmatIn} (\text{M0}^j - \text{MOM1N}[j-1]) \text{InvUmatIn} \cdot \text{Mext}(t - j\tau)$$

$$= \sum_{j=0}^{N-2} \text{UmatIn} \left(\begin{pmatrix} \text{CG1}^{j+1} & 0 \\ 0 & \text{GC2}^{j+1} \end{pmatrix} - \text{MOM1N}[j] \right) \text{InvUmatIn} \cdot \begin{pmatrix} \text{AE}_P \text{EPT}^{j+1} \\ \text{AE}_S \text{EST}^{j+1} \end{pmatrix}$$

=

$$\sum_{j=0}^{N-2} \text{UmatIn} \left(\text{CG1}^j \left(\begin{pmatrix} \text{CG1} & 0 \\ 0 & 0 \end{pmatrix} - \text{CA10} \right) - j \text{CA11} - j^2 \text{CA12} \right) + \text{CG2}^j \left(\begin{pmatrix} 0 & 0 \\ 0 & \text{CG2} \end{pmatrix} - \text{CA20} \right) - j \text{CA21} - j^2 \text{CA22} \right)$$

$$\text{InvUmatIn} \cdot \begin{pmatrix} \text{AE}_P \text{EPT}^{j+1} \\ \text{AE}_S \text{EST}^{j+1} \end{pmatrix}$$

$$= \sum_{j=0}^{N-2} \left(\text{CG1}^j (\text{DA10} - j \text{DA11} - j^2 \text{DA12}) + \text{CG2}^j (\text{DA20} - j \text{DA21} - j^2 \text{DA22}) \right) \cdot \begin{pmatrix} \text{AE}_P \text{EPT}^{j+1} \\ \text{AE}_S \text{EST}^{j+1} \end{pmatrix}$$

$$DA10 = \text{UmatIn} \cdot \left(\text{CG1} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} - \text{CA10} \right) \text{InvUmatIn},$$

$$DA11 = \text{UmatIn} \cdot \text{CA11} \cdot \text{InvUmatIn}, \quad DA12 = \text{UmatIn} \cdot \text{CA12} \cdot \text{InvUmatIn}$$

$$DA20 = \text{UmatIn} \cdot \left(\text{CG2} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} - \text{CA20} \right) \text{InvUmatIn},$$

$$DA21 = \text{UmatIn} \cdot \text{CA21} \cdot \text{InvUmatIn}, \quad DA22 = \text{UmatIn} \cdot \text{CA22} \cdot \text{InvUmatIn}$$

$$\begin{pmatrix} \text{AE}_P \text{EPT}^{j+1} \\ \text{AE}_S \text{EST}^{j+1} \end{pmatrix} = \begin{pmatrix} \text{EPT}^{j+1} & 0 \\ 0 & \text{EST}^{j+1} \end{pmatrix} \begin{pmatrix} \text{AE}_P \\ \text{AE}_S \end{pmatrix}$$

$$\begin{aligned} & \sum_{j=0}^{N-2} (\text{CG1}^j (\text{DA10} - j \text{DA11} - j^2 \text{DA12}) + \text{CG2}^j (\text{DA20} - j \text{DA21} - j^2 \text{DA22})) \cdot \begin{pmatrix} \text{AE}_P \text{EPT}^{j+1} \\ \text{AE}_S \text{EST}^{j+1} \end{pmatrix} = \\ & \sum_{j=0}^{N-2} (\text{CG1}^j (\text{DA10} - j \text{DA11} - j^2 \text{DA12}) + \text{CG2}^j (\text{DA20} - j \text{DA21} - j^2 \text{DA22})) \cdot \begin{pmatrix} \text{EPT}^j & 0 \\ 0 & \text{EST}^j \end{pmatrix} \begin{pmatrix} \text{AE}_P \text{EPT} \\ \text{AE}_S \text{EST} \end{pmatrix} \\ & = \sum_{j=0}^{N-2} \left(\text{DA10} \begin{pmatrix} (\text{CG1} * \text{EPT})^j & 0 \\ 0 & (\text{CG1} * \text{EST})^j \end{pmatrix} - \text{DA11} \begin{pmatrix} j(\text{CG1} * \text{EPT})^j & 0 \\ 0 & j(\text{CG1} * \text{EST})^j \end{pmatrix} - \right. \\ & \quad \text{DA12} \begin{pmatrix} j^2(\text{CG1} * \text{EPT})^j & 0 \\ 0 & j^2(\text{CG1} * \text{EST})^j \end{pmatrix} + \text{DA20} \begin{pmatrix} (\text{CG2} * \text{EPT})^j & 0 \\ 0 & (\text{CG2} * \text{EST})^j \end{pmatrix} - \\ & \quad \left. \text{DA21} \begin{pmatrix} j(\text{CG2} * \text{EPT})^j & 0 \\ 0 & j(\text{CG2} * \text{EST})^j \end{pmatrix} - \text{DA22} \begin{pmatrix} j^2(\text{CG2} * \text{EPT})^j & 0 \\ 0 & j^2(\text{CG2} * \text{EST})^j \end{pmatrix} \right) \begin{pmatrix} \text{AE}_P \text{EPT} \\ \text{AE}_S \text{EST} \end{pmatrix} \end{aligned}$$

■ Summation for double summation

$$\sum_{j=0}^N a^j$$

$$\frac{-1 + a^{1+N}}{-1 + a}$$

$$\text{Simplify} \left[\text{Series} \left[\frac{-1 + a^{1+N}}{-1 + a} /. \{a \rightarrow 1 - \epsilon\}, \{\epsilon, 0, 3\} \right] / (1 + N) \right]$$

$$1 - \frac{N\epsilon}{2} + \frac{1}{6} (-1 + N) N \epsilon^2 - \frac{1}{24} ((-2 + N) (-1 + N) N) \epsilon^3 + O[\epsilon]^4$$

$$\text{Simplify} \left[\text{Series} \left[\left(\frac{-1 + a^{1+N}}{-1 + a} /. \{a \rightarrow 1 - \epsilon\} \right) / (1 + N) - \text{Exp} \left[-\frac{\epsilon N}{2} \right], \{\epsilon, 0, 3\} \right] \right]$$

$$\frac{1}{24} (-4 + N) N \epsilon^2 - \frac{1}{48} (N (4 - 6N + N^2)) \epsilon^3 + O[\epsilon]^4$$

$$\sum_{j=0}^N j a^j$$

$$\frac{a (1 - a^N - a^N N + a^{1+N} N)}{(-1 + a)^2}$$

$$\text{Simplify}[\text{Series}[\frac{a (1 - a^N - a^N N + a^{1+N} N)}{(-1 + a)^2} / \left(\frac{1}{2} N (N + 1) \right) - \text{Exp}[-(1 + 2 N) / 3 \epsilon] /. \{a \rightarrow 1 - \epsilon\}, \{\epsilon, 0, 3\}]]$$

$$\frac{1}{36} (-8 - 11 N + N^2) \epsilon^2 + \frac{(-152 + 87 N + 363 N^2 - 28 N^3) \epsilon^3}{1620} + O[\epsilon]^4$$

$$\text{Simplify}[\text{Series}[\frac{a (1 - a^N (1 + N - a N))}{(1 - a)^2} / \left(\frac{1}{2} N (N + 1) \right) - \text{Exp}[-(1 + 2 N) / 3 \epsilon] /. \{a \rightarrow 1 - \epsilon\}, \{\epsilon, 0, 3\}]]$$

$$\frac{1}{36} (-8 - 11 N + N^2) \epsilon^2 + \frac{(-152 + 87 N + 363 N^2 - 28 N^3) \epsilon^3}{1620} + O[\epsilon]^4$$

$$-28 / 1620$$

$$-\frac{7}{405}$$

$$\sum_{j=0}^N j^2 a^j$$

$$\frac{a (-1 - a + a^N + a^{1+N} + 2 a^N N - 2 a^{1+N} N + a^N N^2 - 2 a^{1+N} N^2 + a^{2+N} N^2)}{(-1 + a)^3}$$

$$\text{Simplify}[\text{Series}[\frac{a (-1 - a + a^N + a^{1+N} + 2 a^N N - 2 a^{1+N} N + a^N N^2 - 2 a^{1+N} N^2 + a^{2+N} N^2)}{(-1 + a)^3} / \left(\frac{1}{6} N (1 + 3 N + 2 N^2) \right) - \text{Exp}\left[-\frac{3 (N (1 + N)) \epsilon}{2 + 4 N}\right] /. \{a \rightarrow 1 - \epsilon\}, \{\epsilon, 0, 3\}]]$$

$$-\frac{(4 + 34 N + 91 N^2 + 54 N^3 - 3 N^4) \epsilon^2}{40 (1 + 2 N)^2} + \frac{(-24 - 172 N - 324 N^2 + 199 N^3 + 925 N^4 + 501 N^5 - 25 N^6) \epsilon^3}{240 (1 + 2 N)^3} + O[\epsilon]^4$$

```
Simplify[
Series[ $\frac{a(1+a-a^N(a+(1+N(1-a))^2))}{(1-a)^3} / \left(\frac{1}{6}N(1+3N+2N^2)\right) - \text{Exp}\left[-\frac{3(N(1+N))\epsilon}{2+4N}\right] /.$ 
{a -> 1 - \epsilon}, {\epsilon, 0, 3}]]
```

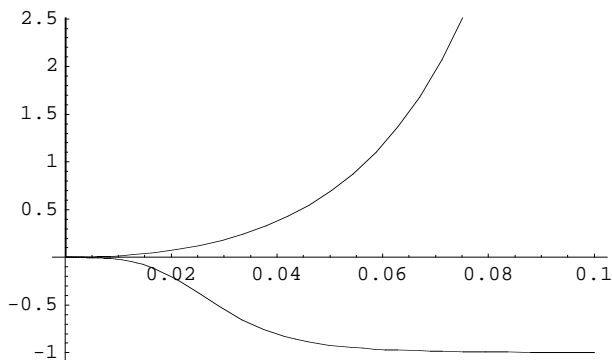
$$-\frac{(4+34N+91N^2+54N^3-3N^4)\epsilon^2}{40(1+2N)^2} + \frac{(-24-172N-324N^2+199N^3+925N^4+501N^5-25N^6)\epsilon^3}{240(1+2N)^3} + O[\epsilon]^4$$

$$\frac{25}{2408}$$

$$\frac{5}{384}$$

```
dAJ[N_, \epsilon_] :=  $\frac{1 - (1 - \epsilon)^{1+N}}{\epsilon} / \left( (1+N) \text{Exp}\left[-\frac{\epsilon N}{2}\right] \right) - 1;$ 
dJAJ[N_, \epsilon_] :=  $\frac{(1 - \epsilon)(1 - (1 - \epsilon)^N(1 + \epsilon N))}{\epsilon^2} / \left( \frac{1}{2}N(N+1) \text{Exp}\left[-\frac{(1+2N)\epsilon}{3}\right] \right) - 1;$ 
dJJAJ[N_, \epsilon_] :=
 $\frac{(1 - \epsilon)(2 - \epsilon - (1 - \epsilon)^N(1 - \epsilon + (1 + N\epsilon)^2))}{\epsilon^3} / \left( \frac{1}{6}N(1+3N+2N^2) \text{Exp}\left[-\frac{3(N(1+N))\epsilon}{2(1+2N)}\right] \right) - 1;$ 
dJJAJ2[N_, \epsilon_] :=  $\frac{(1 - \epsilon)(2 - \epsilon - (1 - \epsilon)^N(1 - \epsilon + (1 + N\epsilon)^2))}{\epsilon^3} /$ 
 $\left( \frac{1}{6}N(1+3N+2N^2) \left( \text{Exp}\left[-\frac{3(N(1+N))\epsilon}{2(1+2N)}\right] + \frac{3}{160}(N\epsilon)^2 \right) \right) - 1;$ 
```

```
Plot[{dJJAJ[100, \epsilon], dJJAJ2[100, \epsilon]}, {\epsilon, 0, 0.1}]
```



- Graphics -

```

dAJ[10, 0.1]
dAJ[100, 0.01]
dAJ[1000, 0.001]
dJAJ[10, 0.1]
dJAJ[100, 0.01]
dJAJ[1000, 0.001]
dJJAJ[10, 0.1]
dJJAJ[100, 0.01]
dJJAJ[1000, 0.001]

```

0.0284864

0.0408622

0.0420582

-0.0027208

0.0264814

0.02906

-0.0179656

0.01654

0.0196469

■ Summary

$$a = 1 - \epsilon$$

$$\sum_{j=0}^N a^j = \frac{1-a^{1+N}}{1-a} \simeq (1+N) \left(\text{Exp}\left[-\frac{\epsilon N}{2}\right] + \frac{1}{24} (N\epsilon)^2 - \frac{1}{48} (N\epsilon)^3 \right)$$

$$\sum_{j=0}^N j a^j = \frac{a(1-a^N(1+N-aN))}{(1-a)^2} \simeq \frac{1}{2} N(N+1) \left(\text{Exp}\left[-\frac{(1+2N)\epsilon}{3}\right] + \frac{1}{36} (N\epsilon)^2 - \frac{7}{405} (N\epsilon)^3 \right)$$

$$\sum_{j=0}^N j^2 a^j =$$

$$\frac{a(1+a-a^N(a+(1+N(1-a))^2))}{(1-a)^3} \simeq \frac{1}{6} N(1+N)(1+2N) \left(\text{Exp}\left[-\frac{3N(1+N)\epsilon}{2(1+2N)}\right] + \frac{3}{160} (N\epsilon)^2 - \frac{5}{384} (N\epsilon)^3 \right)$$

■ Verification

```

FullSimplify[M1 /. {A → 1, B → 2, C → 3, D → 4, a → -10, b → 21, c → -40, d → 50}]
FullSimplify[
  InvUmat.  $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ .Umat /. {A → 1, B → 2, C → 3, D → 4, a → -10, b → 21, c → -40, d → 50}]
FullSimplify[InvUmat.  $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ .Umat /.
  {A → 1, B → 2, C → 3, D → 4, a → -10, b → 21, c → -40, d → 50}]
G1 /. {A → 1, B → 2, C → 3, D → 4, a → -10, b → 21, c → -40, d → 50}
G2 /. {A → 1, B → 2, C → 3, D → 4, a → -10, b → 21, c → -40, d → 50}
{{20 -  $\frac{73}{\sqrt{33}}$ ,  $\frac{143}{6} - \frac{257}{2\sqrt{33}}$ }, { $\frac{1}{44}(-1573 - 257\sqrt{33})$ ,  $20 + \frac{73}{\sqrt{33}}$ }}
{{ $\frac{1}{2}(5 - \sqrt{33})$ , 0}, {0,  $\frac{1}{2}(5 + \sqrt{33})$ }}
{{20 -  $\frac{73}{\sqrt{33}}$ ,  $\frac{143}{6} - \frac{257}{2\sqrt{33}}$ }, { $\frac{1}{44}(-1573 - 257\sqrt{33})$ ,  $20 + \frac{73}{\sqrt{33}}$ }}
 $\frac{1}{2}(5 - \sqrt{33})$ 
 $\frac{1}{2}(5 + \sqrt{33})$ 
M1 /. {A → 1, B → 0, C → 0, D → 4, a → -10, b → 21, c → -40, d → 50}
InvUmat.  $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ .Umat /. {A → 1, B → 0, C → 0, D → 4, a → -10, b → 21, c → -40, d → 50}
InvUmat.  $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ .Umat /. {A → 1, B → 0, C → 0, D → 4, a → -10, b → 21, c → -40, d → 50}
G1 /. {A → 1, B → 0, C → 0, D → 4, a → -10, b → 21, c → -40, d → 50}
G2 /. {A → 1, B → 0, C → 0, D → 4, a → -10, b → 21, c → -40, d → 50}
{{-10, 21}, {-40, 50}}
{{1, 0}, {0, 4}}
{{-10, 21}, {-40, 50}}
1
4
TM0 :=  $\begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$ ;
TM2 :=  $\begin{pmatrix} 3 & 7 \\ 2 & 9 \end{pmatrix}$ ;
TMN[n_] := TM0 + n ∈ TM2;
Prod[n_] := {EE =  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ ; Do[EE = TMN[k].EE, {k, n, 0, -1}]; EE}

```

```

Series[ Prod[10], {e, 0, 1}]
Series[ Prod[5], {e, 0, 1}]

{{{1 + 165 e + O[e]^2, 14252 e + O[e]^2}, {36868 e + O[e]^2, 2048 + 506880 e + O[e]^2}}}

{{{1 + 45 e + O[e]^2, 399 e + O[e]^2}, {516 e + O[e]^2, 64 + 4320 e + O[e]^2}}}

MOM1N[10] /. {CG1 -> 1, CG2 -> 2, m11 -> 3, m12 -> 7, m21 -> 2, m22 -> 9}
MOM1N[5] /. {CG1 -> 1, CG2 -> 2, m11 -> 3, m12 -> 7, m21 -> 2, m22 -> 9}

{{165, 14252}, {36868, 506880}}

{{45, 399}, {516, 4320}}

```

```

(MON1N1N[10] + MON1N2N[10]) /. {CG1 -> 1, CG2 -> 2, m11 -> 3, m12 -> 7, m21 -> 2, m22 -> 9}
(MON1N1N[5] + MON1N2N[5]) /. {CG1 -> 1, CG2 -> 2, m11 -> 3, m12 -> 7, m21 -> 2, m22 -> 9}

```

```

{{165, 14252}, {36868, 506880}}

{{45, 399}, {516, 4320}}

```

```

(MON1N1N0[10] + MON1N1N1[10] + MON1N1N2[10] + MON1N2N0[10] + MON1N2N1[10] +
MON1N2N2[10]) /. {CG1 -> 1, CG2 -> 2, m11 -> 3, m12 -> 7, m21 -> 2, m22 -> 9}

```

```

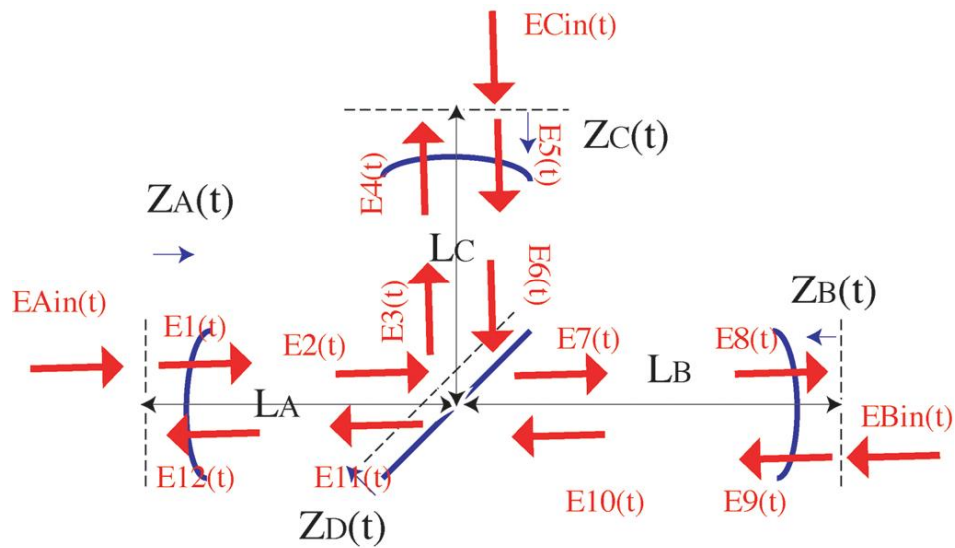
{{165, 14252}, {36868, 506880}}

```

Fields in Power recycled Michelson cavity

I append this old note for completeness.
 Consistency is not guaranteed.

■ Field definition



■ Formulation - basic relationship

■ Basic formulation

■ A input calculations

```

E1lhs[t_] := tA[t] EAin[t] + rA[t] E12[t];
E2[t_] :=  $\Phi$ [A → D] E1[t -  $\tau_A$ ];
E3[t_] := rD[t] E2[t];
E4[t_] :=  $\Phi$ [D → C] E3[t -  $\tau_C$ ];
E5[t_] := rC[t] E4[t] + tC[t] ECin[t];
E6[t_] :=  $\Phi$ [C → D] E5[t -  $\tau_C$ ];
E7[t_] := tD[t] E2[t];
E8[t_] :=  $\Phi$ [D → B] E7[t -  $\tau_B$ ];
E9[t_] := rB[t] E8[t] + tB[t] EBin[t];
E10[t_] :=  $\Phi$ [B → D] E9[t -  $\tau_B$ ];
E11[t_] := rD[t] E6[t] + tD[t] E10[t];
E12[t_] :=  $\Phi$ [D → A] E11[t -  $\tau_A$ ];

```

```
E1lhs[t]
```

```

EAin[t] tA[t] + rA[t]  $\Phi$ [D → A]
(tD[t -  $\tau_A$ ]  $\Phi$ [B → D] (EBin[t -  $\tau_A$  -  $\tau_B$ ] tB[t -  $\tau_A$  -  $\tau_B$ ] + E1[t - 2  $\tau_A$  - 2  $\tau_B$ ] rB[t -  $\tau_A$  -  $\tau_B$ ]
tD[t -  $\tau_A$  - 2  $\tau_B$ ]  $\Phi$ [A → D]  $\Phi$ [D → B]) + rD[t -  $\tau_A$ ]  $\Phi$ [C → D] (ECin[t -  $\tau_A$  -  $\tau_C$ ] tC[t -  $\tau_A$  -  $\tau_C$ ] +
E1[t - 2  $\tau_A$  - 2  $\tau_C$ ] rC[t -  $\tau_A$  -  $\tau_C$ ] rD[t -  $\tau_A$  - 2  $\tau_C$ ]  $\Phi$ [A → D]  $\Phi$ [D → C]))

```

```
E1Internal[t_] := E1lhs[t] /. {EAin[_] → 0, ECin[_] → 0, EBin[_] → 0}
```

```
E1External[t_] := Simplify[E1lhs[t] - E1Internal[t]]
```

```

E1Internal[t]
E1External[t]

```

```

rA[t]  $\Phi$ [D → A]
(E1[t - 2  $\tau_A$  - 2  $\tau_B$ ] rB[t -  $\tau_A$  -  $\tau_B$ ] tD[t -  $\tau_A$ ] tD[t -  $\tau_A$  - 2  $\tau_B$ ]  $\Phi$ [A → D]  $\Phi$ [B → D]  $\Phi$ [D → B] +
E1[t - 2  $\tau_A$  - 2  $\tau_C$ ] rC[t -  $\tau_A$  -  $\tau_C$ ] rD[t -  $\tau_A$ ] rD[t -  $\tau_A$  - 2  $\tau_C$ ]  $\Phi$ [A → D]  $\Phi$ [C → D]  $\Phi$ [D → C])

EAin[t] tA[t] + rA[t] (EBin[t -  $\tau_A$  -  $\tau_B$ ] tB[t -  $\tau_A$  -  $\tau_B$ ] tD[t -  $\tau_A$ ]  $\Phi$ [B → D] +
ECin[t -  $\tau_A$  -  $\tau_C$ ] rD[t -  $\tau_A$ ] tC[t -  $\tau_A$  -  $\tau_C$ ]  $\Phi$ [C → D])  $\Phi$ [D → A]

```

```

LinearMotion :=
  {rA[t_] -> rA0 Exp[i 2 k v_A t], rB[t_] -> rB0 Exp[i 2 k v_B t], rC[t_] -> rC0 Exp[i 2 k v_C t],
   rD[t_] -> rD0 Exp[i 2 k v_D t], tA[t_] -> tA0, tB[t_] -> tB0, tC[t_] -> tC0, tD[t_] -> tD0};
LinearField := {EAin[t_] -> EAin0 Exp[β_A t],
  EBin[t_] -> EBin0 Exp[β_B t], ECin[t_] -> ECin0 Exp[β_C t]};

```

```
EIInternal[t] /. LinearMotion
```

$$e^{2 i k t v_A} rA0 \Phi[D \rightarrow A] (e^{2 i k v_B (t - \tau_A - \tau_B)} rB0 tD0^2 EI[t - 2 \tau_A - 2 \tau_B] \Phi[A \rightarrow D] \Phi[B \rightarrow D] \Phi[D \rightarrow B] + e^{2 i k v_D (t - \tau_A) + 2 i k v_D (t - \tau_A - 2 \tau_C) + 2 i k v_C (t - \tau_A - \tau_C)} rC0 rD0^2 EI[t - 2 \tau_A - 2 \tau_C] \Phi[A \rightarrow D] \Phi[C \rightarrow D] \Phi[D \rightarrow C])$$

```
Simplify[e^{2 i k t v_A} e^{2 i k v_B (t - \tau_A - \tau_B)}]
```

$$e^{2 i k (t v_A + v_B (t - \tau_A - \tau_B))}$$

```
Simplify[e^{2 i k t v_A} e^{2 i k v_D (t - \tau_A) + 2 i k v_D (t - \tau_A - 2 \tau_C) + 2 i k v_C (t - \tau_A - \tau_C)}]
```

$$e^{2 i k (t v_A + (v_D + 2 v_C) (t - \tau_A - \tau_C))}$$

```
2 \tau_A + 2 \tau_B /. {\tau_A -> (\tau - \tau_B - \tau_C) / 2} /. {\tau_B -> \tau_C + 2 \Delta}
```

$$2 \Delta + \tau$$

```
2 \tau_A + 2 \tau_C /. {\tau_A -> (\tau - \tau_B - \tau_C) / 2} /. {\tau_B -> \tau_C + 2 \Delta}
```

$$-2 \Delta + \tau$$

$$EIInt = ACAamp \cdot \text{Exp}[i \phi_{ACA}] + ABAamp \cdot \text{Exp}[i \phi_{ABA}]$$

$$ABAamp = rA0 rB0 tD0^2 EI[t - 2 \tau_A - 2 \tau_B] \Phi[A \rightarrow D] \Phi[B \rightarrow D] \Phi[D \rightarrow B] \Phi[D \rightarrow A]$$

$$\phi_{ABA} = 2 k t (v_A + v_B) - 2 k v_B (\tau_A + \tau_B)$$

$$ACAamp = rA0 rC0 rD0^2 EI[t - 2 \tau_A - 2 \tau_C] \Phi[A \rightarrow D] \Phi[C \rightarrow D] \Phi[D \rightarrow C] \Phi[D \rightarrow A]$$

$$\phi_{ACA} = 2 t k (v_A + v_C + 2 v_D) - 2 k (\tau_A + \tau_C) (v_C + 2 v_D)$$

$$\tau = 2 \tau_A + \tau_B + \tau_C$$

$$2 \Delta = \tau_B - \tau_C$$

$$EI[t - 2 \tau_A - 2 \tau_B] = EI[t - \tau - 2 \Delta]$$

$$EI[t - 2 \tau_A - 2 \tau_C] = EI[t - \tau + 2 \Delta]$$

E1External[t] /. LinearMotion /. LinearField

$$e^{t \beta_A} E_{\text{Ain0}} t_{\text{A0}} + e^{2 i k t v_A} r_{\text{A0}} \\ (e^{\beta_B (t - \tau_A - \tau_B)} E_{\text{Bin0}} t_{\text{B0}} t_{\text{D0}} \Phi[\text{B} \rightarrow \text{D}] + e^{2 i k v_D (t - \tau_A) + \beta_C (t - \tau_A - \tau_C)} E_{\text{Cin0}} r_{\text{D0}} t_{\text{C0}} \Phi[\text{C} \rightarrow \text{D}]) \Phi[\text{D} \rightarrow \text{A}]$$

$$2 i k t v_A + \beta_B (t - \tau_A - \tau_B)$$

$$2 i k t v_A + \beta_B (t - \tau_A - \tau_B)$$

$$2 i k t v_A + 2 i k v_D (t - \tau_A) + \beta_C (t - \tau_A - \tau_C)$$

$$2 i k t v_A + 2 i k v_D (t - \tau_A) + \beta_C (t - \tau_A - \tau_C)$$

$$E1\text{Ext} = \text{AAamp} \cdot \text{Exp}[\phi_{\text{AA}}] + \text{ACamp} \cdot \text{Exp}[\phi_{\text{AC}}] + \text{ABamp} \cdot \text{Exp}[\phi_{\text{AB}}]$$

$$\text{AAamp} = E_{\text{Ain0}} \cdot t_{\text{A0}}$$

$$\phi_{\text{AA}} = \beta_A t$$

$$\text{ACamp} = E_{\text{Cin0}} r_{\text{A0}} r_{\text{D0}} t_{\text{C0}} \Phi[\text{C} \rightarrow \text{D}] \Phi[\text{D} \rightarrow \text{A}]$$

$$\phi_{\text{AC}} = t (i 2 k (v_A + v_D) + \beta_C) - (i 2 k v_D \tau_A + \beta_C (\tau_A + \tau_C))$$

$$\text{ABamp} = E_{\text{Bin0}} r_{\text{A0}} t_{\text{B0}} t_{\text{D0}} \Phi[\text{B} \rightarrow \text{D}] \Phi[\text{D} \rightarrow \text{A}]$$

$$\phi_{\text{AB}} = t (i 2 k v_A + \beta_B) - \beta_B (\tau_A + \tau_B)$$

■ Summary of recursion relation

$$\tau = 2 \tau_A + \tau_B + \tau_C$$

$$2\Delta = \tau_B - \tau_C$$

$$V_{E1} = dE_1 / dt / E1$$

$$E1[t] = E1Int[t] + E1Ext[t]$$

$$E1Int = (C_{ACA} \cdot \text{Exp}[i \xi_{ACA} t] + C_{ABA} \cdot \text{Exp}[i \xi_{ABA} t]) E1[t-\tau]$$

$$C_{ACA} = \Phi[A \rightarrow D] \Phi[C \rightarrow D] \Phi[D \rightarrow C] \Phi[D \rightarrow A] \times rA0 rC0 rD0^2 \text{Exp}[-i 2k (v_C + 2 v_D) (\tau_A + \tau_C)] (1 + 2\Delta V_{E1})$$

$$\xi_{ACA} = 2k(v_A + v_C + 2 v_D)$$

$$C_{ABA} = \Phi[A \rightarrow D] \Phi[B \rightarrow D] \Phi[D \rightarrow B] \Phi[D \rightarrow A] \times rA0 rB0 tD0^2 \text{Exp}[-i 2k v_B (\tau_A + \tau_B)] (1 - 2\Delta V_{E1})$$

$$\xi_{ABA} = 2k(v_A + v_B)$$

$$E1Ext = C_A \cdot \text{Exp}[\zeta_A t] + C_C \cdot \text{Exp}[\zeta_C t] + C_B \cdot \text{Exp}[\zeta_B t]$$

$$C_A = EAin0 \cdot tA0$$

$$\zeta_A = \beta_A$$

$$C_C = \Phi[C \rightarrow D] \Phi[D \rightarrow A] \times ECin0 rA0 rD0 tC0 \text{Exp}[-i 2k v_D \tau_A - \beta_C (\tau_A + \tau_C)]$$

$$\zeta_C = i 2k (v_A + v_D) + \beta_C$$

$$C_B = \Phi[B \rightarrow D] \Phi[D \rightarrow A] \times EBin0 rA0 tB0 tD0 \text{Exp}[-\beta_B (\tau_A + \tau_B)]$$

$$\zeta_B = i 2k v_A + \beta_B$$

■ Manual calculation

■ A inputs

$$E1(t) = t_A(t) \cdot EAin(t) + r_A(t) \cdot E12(t)$$

$$E2(t) = \Phi[A \rightarrow D] E1(t - \tau_A)$$

$$E3(t) = r_D(t) \cdot E2(t)$$

$$E4(t) = \Phi[D \rightarrow C] E3(t - \tau_C)$$

$$E5(t) = r_C(t) \cdot E4(t)$$

$$E6(t) = \Phi[C \rightarrow D] \cdot E5(t - \tau_C)$$

$$E7(t) = t_D(t) \cdot E2(t)$$

$$E8(t) = \Phi[D \rightarrow B] \cdot E7(t - \tau_B)$$

$$E9(t) = r_B(t) \cdot E8(t)$$

$$E10(t) = \Phi[B \rightarrow D] \cdot E9(t - \tau_B)$$

$$E11(t) = r_D(t) \cdot E6(t) + t_D(t) \cdot E10(t)$$

$$E12(t) = \Phi[D \rightarrow A] \cdot E11(t - \tau_A)$$

$$E1(t)$$

$$= t_A(t) \cdot EAin(t) + r_A(t) \cdot E12(t)$$

$$= t_A(t) \cdot EAin(t) + r_A(t) \cdot \Phi[D \rightarrow A] \cdot E11(t - \tau_A)$$

$$= t_A(t) \cdot EAin(t) + r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot E6(t - \tau_A) + t_D(t - \tau_A) \cdot E10(t - \tau_A))$$

$$= t_A(t) \cdot EAin(t) + r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot E5(t - \tau_A - \tau_C) + t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot E9(t - \tau_A - \tau_B))$$

$$= t_A(t) \cdot EAin(t) + r_A(t) \cdot \Phi[D \rightarrow A] \cdot$$

$$(r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot r_C(t - \tau_A - \tau_C) \cdot E4(t - \tau_A - \tau_C) + t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot E8(t - \tau_A - \tau_B))$$

$$= t_A(t) \cdot EAin(t) + r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] E3(t - \tau_A - \tau_C - \tau_C) +$$

$$t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot E7(t - \tau_A - \tau_B - \tau_B))$$

$$= t_A(t) \cdot EAin(t) +$$

$$r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] r_D(t - \tau_A - \tau_C - \tau_C) \cdot E2(t - \tau_A - \tau_C - \tau_C) +$$

$$t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot t_D(t - \tau_A - \tau_B - \tau_B) \cdot E2(t - \tau_A - \tau_B - \tau_B))$$

$$= t_A(t) \cdot EAin(t) + r_A(t) \cdot \Phi[D \rightarrow A] \cdot$$

$$(r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] r_D(t - \tau_A - \tau_C - \tau_C) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_C - \tau_C - \tau_A) +$$

$$t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot t_D(t - \tau_A - \tau_B - \tau_B) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_B - \tau_B - \tau_A))$$

$$E5(t) = t_C(t) \cdot ECin(t) + r_C(t) \cdot E4(t)$$

$$E6(t) = \Phi[C \rightarrow D] \cdot E5(t - \tau_C)$$

$$E1(t) = r_A(t) \cdot E12(t)$$

$$E2(t) = \Phi[A \rightarrow D] E1(t - \tau_A)$$

$$E3(t) = r_D(t) \cdot E2(t)$$

$$E4(t) = \Phi[D \rightarrow C] E3(t - \tau_C)$$

$$E7(t) = t_D(t) \cdot E2(t)$$

$$E8(t) = \Phi[D \rightarrow B] \cdot E7(t - \tau_B)$$

$$E9(t) = r_B(t) \cdot E8(t)$$

$$E10(t) = \Phi[B \rightarrow D] \cdot E9(t - \tau_B)$$

$$E11(t) = r_D(t) \cdot E6(t) + t_D(t) \cdot E10(t)$$

$$E12(t) = \Phi[D \rightarrow A] \cdot E11(t - \tau_A)$$

■ EA1 summary

E1(t)

$$= t_A(t) \cdot \text{EAin}(t) + r_A(t) \cdot \Phi[D \rightarrow A] \cdot \\ (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] r_D(t - \tau_A - \tau_C - \tau_C) \cdot \Phi[A \rightarrow D] \text{E1}(t - \tau_A - \tau_C - \tau_C - \tau_A) + \\ t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot t_D(t - \tau_A - \tau_B - \tau_B) \cdot \Phi[A \rightarrow D] \text{E1}(t - \tau_A - \tau_B - \tau_B - \tau_A))$$

■ Linear calculation

$$R_X[t] = R_X[0] \cdot \exp[i 2 k X[t]] = R_X[0] \cdot \exp[i 2 k (X_0 + v_X t)]$$

Extrnal input field

$$\text{Fin}[t] = \text{Fin}[0] \cdot \exp[\beta_F t]$$

E1(t)

$$= t_A(t) \cdot \text{EAin}(t) + r_A(t) \cdot \Phi[D \rightarrow A] \cdot \\ (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] r_D(t - \tau_A - \tau_C - \tau_C) \cdot \Phi[A \rightarrow D] \text{E1}(t - \tau_A - \tau_C - \tau_C - \tau_A) + \\ t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot t_D(t - \tau_A - \tau_B - \tau_B) \cdot \Phi[A \rightarrow D] \text{E1}(t - \tau_A - \tau_B - \tau_B - \tau_A)) \\ = t_A(t) \cdot \text{EAin}(t) + R(t) \cdot \text{E1}(t - \tau)$$

$$\tau_J = L_J / c$$

$$\tau_{JK} = \tau_J + \tau_K$$

$$\tau = 2 \tau_A + \tau_B + \tau_C$$

$$\Delta = (L_B - L_C) / 2$$

$$\tau_\Delta = \Delta / c = (\tau_{ABBA} - \tau) / 2 = (\tau - \tau_{ACCA}) / 2$$

$$\begin{aligned} \text{E1}(t - \tau_A - \tau_C - \tau_C - \tau_A) &= \text{E1}(t - \tau_{ACCA}) = \text{E1}(t - \tau + 2 \tau_\Delta) = \text{E1}(t - \tau) (1 + V_{\text{E1}}(t - \tau) 2 \tau_\Delta) \approx \\ \text{E1}(t - \tau) (1 + V_{\text{E1}}(t) 2 \tau_\Delta) \\ \text{E1}(t - \tau_A - \tau_B - \tau_B - \tau_A) &= \text{E1}(t - \tau_{ABBA}) = \text{E1}(t - \tau - 2 \tau_\Delta) = \text{E1}(t - \tau) (1 - V_{\text{E1}}(t - \tau) 2 \tau_\Delta) \approx \\ \text{E1}(t - \tau) (1 - V_{\text{E1}}(t) 2 \tau_\Delta) \end{aligned}$$

R(t)

$$= r_A(t) \cdot \Phi[D \rightarrow A] \cdot \\ (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] r_D(t - \tau_A - \tau_C - \tau_C) \cdot \Phi[A \rightarrow D] \cdot (1 + V_{\text{E1}}(t) 2 \tau_\Delta) + \\ t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot t_D(t - \tau_A - \tau_B - \tau_B) \cdot \Phi[A \rightarrow D] \cdot (1 - V_{\text{E1}}(t) 2 \tau_\Delta))$$

AC(t)

$$= r_A(t) \cdot \Phi[D \rightarrow A] \cdot r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] r_D(t - \tau_A - \tau_C - \tau_C) \cdot \Phi[A \rightarrow D] \cdot (1 + V_{\text{E1}}(t) 2 \tau_\Delta) \\ = \text{AC0} \cdot \exp(i \phi_{\text{AC}}) \\ \text{AC0} = r_A(t) \cdot \Phi[D \rightarrow A] \cdot r_D(t) \cdot \Phi[C \rightarrow D] \cdot r_C(t) \cdot \Phi[D \rightarrow C] r_D(t) \cdot \Phi[A \rightarrow D] \cdot (1 + V_{\text{E1}}(t) 2 \tau_\Delta) \\ \phi_{\text{AC}} / 2k = v_D \cdot (t - \tau_A) + v_C \cdot (t - \tau_A - \tau_C) + v_D \cdot (t - \tau_A - 2 \tau_C) = t \cdot (2 v_D + v_C) - (2 v_D + v_C) \cdot (\tau_A + \tau_C)$$

AB(t)

$$= r_A(t) \cdot \Phi[D \rightarrow A] \cdot t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot t_D(t - \tau_A - \tau_B - \tau_B) \cdot \Phi[A \rightarrow D] \cdot (1 - V_{\text{E1}}(t) 2 \tau_\Delta) \\ = \text{AB0} \cdot \exp(i \phi_{\text{AB}}(t)) \\ \text{AB0} = r_A(t) \cdot \Phi[D \rightarrow A] \cdot t_D(t) \cdot \Phi[B \rightarrow D] \cdot r_B(t) \cdot \Phi[D \rightarrow B] \cdot t_D(t) \cdot \Phi[A \rightarrow D] \cdot (1 - V_{\text{E1}}(t) 2 \tau_\Delta) \\ \phi_{\text{AB}} / 2k = v_B \cdot (t - \tau_A - \tau_B)$$

■ C inputs

$$\begin{aligned}
E1(t) &= r_A(t) \cdot E12(t) \\
E2(t) &= \Phi[A \rightarrow D] E1(t - \tau_A) \\
E3(t) &= r_D(t) \cdot E2(t) \\
E4(t) &= \Phi[D \rightarrow C] E3(t - \tau_C) \\
E5(t) &= t_C(t) \cdot \text{ECin}(t) + r_C(t) \cdot E4(t) \\
E6(t) &= \Phi[C \rightarrow D] \cdot E5(t - \tau_C) \\
E7(t) &= t_D(t) \cdot E2(t) \\
E8(t) &= \Phi[D \rightarrow B] \cdot E7(t - \tau_B) \\
E9(t) &= r_B(t) \cdot E8(t) \\
E10(t) &= \Phi[B \rightarrow D] \cdot E9(t - \tau_B) \\
E11(t) &= r_D(t) \cdot E6(t) + t_D(t) \cdot E10(t) \\
E12(t) &= \Phi[D \rightarrow A] \cdot E11(t - \tau_A)
\end{aligned}$$

$$\begin{aligned}
E1(t) &= r_A(t) \cdot E12(t) \\
&= r_A(t) \cdot \Phi[D \rightarrow A] \cdot E11(t - \tau_A) \\
&= r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot E6(t - \tau_A) + t_D(t - \tau_A) \cdot E10(t - \tau_A)) \\
&= r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot E5(t - \tau_A - \tau_C) + t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot E9(t - \tau_A - \tau_B)) \\
&= r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot (t_C(t - \tau_A - \tau_C) \cdot \text{ECin}(t - \tau_A - \tau_C) + r_C(t - \tau_A - \tau_C) \cdot E4(t - \tau_A - \tau_C)) + \\
&\quad t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot E9(t - \tau_A - \tau_B)) \\
&= r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot t_C(t - \tau_A - \tau_C) \cdot \text{ECin}(t - \tau_A - \tau_C) + \\
&\quad r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot (r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] E3(t - \tau_A - \tau_C - \tau_C)) + \\
&\quad t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot E8(t - \tau_A - \tau_B)) \\
&= r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot \Phi[C \rightarrow D] \cdot t_C(t - \tau_A - \tau_C) \cdot \text{ECin}(t - \tau_A - \tau_C) + \\
&\quad r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot (r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] r_D(t - \tau_A - \tau_C - \tau_C) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_C - \tau_C - \tau_A)) + \\
&\quad t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot t_D(t - \tau_A - \tau_B - \tau_B) \cdot E2(t - \tau_A - \tau_B - \tau_B)) \\
&= r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot t_C(t - \tau_A - \tau_C) \cdot \text{ECin}(t - \tau_A - \tau_C) + \\
&\quad r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot (r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] r_D(t - \tau_A - \tau_C - \tau_C) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_C - \tau_C - \tau_A)) + \\
&\quad t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot t_D(t - \tau_A - \tau_B - \tau_B) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_B - \tau_B - \tau_A))
\end{aligned}$$

■ EC1 summary

$$\begin{aligned}
E1(t) &= r_A(t) \cdot \Phi[D \rightarrow A] \cdot r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot t_C(t - \tau_A - \tau_C) \cdot \text{ECin}(t - \tau_A - \tau_C) + \\
& r_A(t) \cdot \Phi[D \rightarrow A] \cdot (r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot (r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] r_D(t - \tau_A - \tau_C - \tau_C) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_C - \tau_C - \tau_A)) + \\
&\quad t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot t_D(t - \tau_A - \tau_B - \tau_B) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_B - \tau_B - \tau_A))
\end{aligned}$$

■ EC1 Linear calculation

$$R_X[t] = R_X[0] \cdot \exp[i 2k X[t]] = R_X[0] \cdot \exp[i 2k (X_0 + v_X t)]$$

Extrnal input field

$$Fin[t] = Fin[0] \cdot \exp[\beta_F t]$$

$$\begin{aligned} E1(t) &= r_A(t) \cdot \Phi[D \rightarrow A] \cdot r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot t_C(t - \tau_A - \tau_C) \cdot ECin(t - \tau_A - \tau_C) + \\ &r_A(t) \cdot \Phi[D \rightarrow A] \cdot \\ &(r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] r_D(t - \tau_A - \tau_C - \tau_C) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_C - \tau_C - \tau_A)) + \\ &t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot t_D(t - \tau_A - \tau_B - \tau_B) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_B - \tau_B - \tau_A)) \end{aligned}$$

$$\begin{aligned} E1External(t) &= r_A(t) \cdot \Phi[D \rightarrow A] \cdot r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot t_C(t - \tau_A - \tau_C) \cdot ECin(t - \tau_A - \tau_C) \\ &= r_A(t) \cdot \Phi[D \rightarrow A] \cdot r_D(t) \cdot \exp(-i 2k v_D \tau_A) \cdot \Phi[C \rightarrow D] \cdot t_C \cdot ECin(t) \cdot \exp(-\beta(\tau_A + \tau_C)) \\ &= r_A(t) \cdot \Phi[D \rightarrow A] \cdot r_D(t) \cdot \Phi[C \rightarrow D] \cdot t_C \cdot \exp(-\beta(\tau_A + \tau_C) - i 2k v_D \tau_A) \cdot ECin(t) \end{aligned}$$

E1Internal

$$\begin{aligned} &= r_A(t) \cdot \Phi[D \rightarrow A] \cdot \\ &(r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] r_D(t - \tau_A - \tau_C - \tau_C) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_C - \tau_C - \tau_A)) + \\ &t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot t_D(t - \tau_A - \tau_B - \tau_B) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_B - \tau_B - \tau_A)) \end{aligned}$$

■ Summart after linearlization

$$\begin{aligned} E1(t) &= E1extern(t) + r_A(t) \cdot \Phi[D \rightarrow A] \cdot \\ &(r_D(t - \tau_A) \cdot \Phi[C \rightarrow D] \cdot r_C(t - \tau_A - \tau_C) \cdot \Phi[D \rightarrow C] r_D(t - \tau_A - \tau_C - \tau_C) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_C - \tau_C - \tau_A) + \\ &t_D(t - \tau_A) \cdot \Phi[B \rightarrow D] \cdot r_B(t - \tau_A - \tau_B) \cdot \Phi[D \rightarrow B] \cdot t_D(t - \tau_A - \tau_B - \tau_B) \cdot \Phi[A \rightarrow D] E1(t - \tau_A - \tau_B - \tau_B - \tau_A)) \\ &= E1extern(t) + (C_{AC} \cdot \exp(i 2k v_{AC} \cdot t) + C_{AB} \cdot \exp(i 2k v_{AB} \cdot t)) \cdot E1(t - \tau) \end{aligned}$$

$$E1extern(t) = E1Aextern(t) + E1Cextern(t) + E1Bextern(t)$$

$$E1Aextern(t) = t_A(t) \cdot EAin(t)$$

$$E1Cextern(t) = r_A(t) \cdot \Phi[D \rightarrow A] \cdot r_D(t) \cdot \Phi[C \rightarrow D] \cdot t_C \cdot \exp(-\beta_C(\tau_A + \tau_C) - i 2k v_D \tau_A) \cdot ECin(t)$$

$$E1Bextern(t) = r_A(t) \cdot \Phi[D \rightarrow A] \cdot t_D(t) \cdot \Phi[B \rightarrow D] \cdot t_B \cdot \exp(-\beta_B(\tau_A + \tau_B)) \cdot EBin(t)$$

$$C_{AC} = r_A(t) \cdot \Phi[D \rightarrow A] \cdot$$

$$r_D(t) \cdot \Phi[C \rightarrow D] \cdot r_C(t) \cdot \Phi[D \rightarrow C] r_D(t) \cdot \Phi[A \rightarrow D] \cdot (1 + V_{E1}(t) 2 \tau_A) \cdot \exp(-i 2k v_{AC} \cdot (\tau_A + \tau_C))$$

$$v_{AC} = 2 v_D + v_C$$

$$C_{AB} = r_A(t) \cdot \Phi[D \rightarrow A] \cdot$$

$$t_D(t) \cdot \Phi[B \rightarrow D] \cdot r_B(t) \cdot \Phi[D \rightarrow B] \cdot t_D(t) \cdot \Phi[A \rightarrow D] \cdot (1 - V_{E1}(t) 2 \tau_A) \cdot \exp(-i 2k v_{AB} \cdot (\tau_A + \tau_B))$$

$$v_{AB} = v_B$$

■ Recursive formulation

■ Basic calculation

$$E(t) = E_{\text{ext}}(t) + R(t) \cdot E(t - \tau)$$

$$E(t) = E_{\text{ext}}(t) + \sum_{n=1}^{N-1} E_{\text{ext}}(t - n\tau) \prod_{m=0}^{n-1} R(t - m\tau) + \prod_{m=0}^{N-1} R(t - m\tau) \cdot E(t - N\tau)$$

$$E(t + N\tau) = E_{\text{ext}}(t + N\tau) + \sum_{n=1}^{N-1} E_{\text{ext}}(t + N\tau - n\tau) \prod_{m=0}^{n-1} R(t + N\tau - m\tau) + \prod_{m=0}^{N-1} R(t + N\tau - m\tau) \cdot E(t)$$

$$R(t) = C_{\text{ACA}} \cdot \text{Exp}[i \xi_{\text{ACA}} t] + C_{\text{ABA}} \cdot \text{Exp}[i \xi_{\text{ABA}} t]$$

$$\begin{aligned} \text{PR}(n) &= \prod_{m=0}^{n-1} R(t + N\tau - m\tau) = \prod_{m=0}^{n-1} (C_{\text{ACA}} \cdot \exp(i \xi_{\text{ACA}} \cdot (t + N\tau - m\tau)) + C_{\text{ABA}} \cdot \exp(i \xi_{\text{ABA}} \cdot (t + N\tau - m\tau))) \\ &= \prod_{m=0}^{n-1} (C_{\text{ACA}}(t + N\tau) \cdot \exp(-i \xi_{\text{ACA}} \tau m) + C_{\text{ABA}}(t + N\tau) \cdot \exp(-i \xi_{\text{ABA}} \tau m)) \\ &\approx \prod_{m=0}^{n-1} C_{\text{ACB}}(t + N\tau) \cdot \exp(-i \xi_{\text{ACB}}(t + N\tau) m) \\ &= C_{\text{ACB}}(t + N\tau)^n \exp(-i \xi_{\text{ACB}}(t + N\tau) \cdot n(n-1)/2) \end{aligned}$$

$$\begin{aligned} C_{\text{ACA}}(t) &= C_{\text{ACA}} \cdot \exp(i \xi_{\text{ACA}} \cdot t) \\ C_{\text{ABA}}(t) &= C_{\text{ABA}} \cdot \exp(i \xi_{\text{ABA}} \cdot t) \end{aligned}$$

$$C_{\text{ABC}}(t) = C_{\text{ACA}}(t) + C_{\text{ABA}}(t)$$

$$\xi_{\text{ACB}}(t) = \frac{\xi_{\text{ACA}} C_{\text{ACA}}(t) + \xi_{\text{ABA}} C_{\text{ABA}}(t)}{C_{\text{ACA}}(t) + C_{\text{ABA}}(t)} \tau$$

$$E_{\text{ext}}(t) = E_0 \exp(\beta t)$$

$$\begin{aligned} &\sum_{n=1}^{N-1} E_{\text{ext}}(t + N\tau - n\tau) \prod_{m=0}^{n-1} R(t + N\tau - m\tau) = \\ &\sum_{n=1}^{N-1} E_0 \cdot \exp(\zeta \cdot (t + N\tau)) \cdot \exp(-\zeta \tau n) \cdot C_{\text{ACB}}(t + N\tau)^n \exp(-i \xi_{\text{ACB}}(t + N\tau) \cdot n(n-1)/2) \\ &= E_0 \cdot \exp(\zeta \cdot (t + N\tau)) \cdot \sum_{n=1}^{N-1} \exp(-\zeta \tau n) \cdot C_{\text{ACB}}(t + N\tau)^n \exp(-i \xi_{\text{ACB}}(t + N\tau) \cdot n(n-1)/2) \\ &= E_0 \cdot \exp(\zeta \cdot (t + N\tau)) \cdot \sum_{n=1}^{N-1} \tilde{C}_{\text{ACB}}^n \exp(-i \xi_{\text{ACB}}(t + N\tau) \cdot n^2/2) \\ &= E_0 \cdot \exp(\zeta \cdot (t + N\tau)) \cdot \sum_{n=1}^{N-1} \tilde{C}_{\text{ACB}}^n (1 - i \xi_{\text{ACB}}(t + N\tau) \cdot n^2/2) \\ &= E_0 \cdot \exp(\zeta \cdot (t + N\tau)) \cdot \left\{ \frac{1 - \tilde{C}_{\text{ACB}}^N}{1 - \tilde{C}_{\text{ACB}}} - 1 - i \xi_{\text{ACB}}(t + N\tau) / 2 \times \text{SP2}(\tilde{C}_{\text{ACB}}) \right\} \end{aligned}$$

$$\tilde{C}_{\text{ACB}} = C_{\text{ABC}}(t + N\tau) \exp(-\zeta \tau + i \xi_{\text{ABC}}(t + N\tau) / 2)$$

$$\text{SP2}(x) = \sum_{n=1}^{N-1} x^n \cdot n^2$$

$$\sum_{n=1}^{N-1} x^n n^2$$

$$\frac{-x - x^2 + N^2 x^N + x^{1+N} + 2N x^{1+N} - 2N^2 x^{1+N} + x^{2+N} - 2N x^{2+N} + N^2 x^{2+N}}{(-1 + x)^3}$$

$$\frac{\text{FullSimplify}[-x - x^2 + N^2 x^N + x^{1+N} + 2 N x^{1+N} - 2 N^2 x^{1+N} + x^{2+N} - 2 N x^{2+N} + N^2 x^{2+N}]}{(-1 + x)^3}$$

$$\frac{-x (1 + x) + x^N (x + (N + x - N x)^2)}{(-1 + x)^3}$$

$$\text{SP2}(x) = \frac{x (1+x) - x^N (x + (N+x-Nx)^2)}{(1-x)^3}$$

■ Summary of recursive summation

$$E(t) = E_{\text{ext}}(t) + R(t) \cdot E(t - \tau)$$

$$E(t + N\tau) = E_{\text{ext}}(t + N\tau) + \sum_{n=1}^{N-1} E_{\text{ext}}(t + N\tau - n\tau) \prod_{m=0}^{n-1} R(t + N\tau - m\tau) + \prod_{m=0}^{N-1} R(t + N\tau - m\tau) \cdot E(t)$$

$$R(t) = C_{ACA} \cdot \text{Exp}[i \xi_{ACA} t] + C_{ABA} \cdot \text{Exp}[i \xi_{ABA} t]$$

$$E_{\text{ext}}(t) = E_0 \exp(\zeta t)$$

$$E(t+N\tau) = \left\{ \frac{1-C_{ACB}^N}{1-C_{ACB}} - i \xi_{ACB} (t+N\tau) / 2 \times \text{SP2}(C_{ACB}^{\sim}) \right\} E_{\text{ext}}(t+N\tau) + C_{ACB} (t+N\tau)^N \exp(-i \xi_{ACB} (t+N\tau) N^2 / 2) E(t)$$

$$C_{ACA}(t) = C_{ACA} \cdot \exp(i \xi_{ACA} \cdot t)$$

$$C_{ABA}(t) = C_{ABA} \cdot \exp(i \xi_{ABA} \cdot t)$$

$$C_{ACB}(t) = C_{ACA}(t) + C_{ABA}(t)$$

$$\xi_{ACB}(t) = \frac{\xi_{ACA} C_{ACA}(t) + \xi_{ABA} C_{ABA}(t)}{C_{ACA}(t) + C_{ABA}(t)} \tau$$

$$C_{ACB}^{\sim} = C_{ACB}(t + N\tau) \exp(i \xi_{ACB}(t + N\tau) / 2) \cdot \exp(-\zeta \tau)$$

$$\text{SP2}(x) = \frac{x (1+x) - x^N (x + (N+x-Nx)^2)}{(1-x)^3}$$

■ Programming

■ Basics

■ Initialization before run

$$\tau = 2 \tau_A + \tau_B + \tau_C$$

$$\tau_{AC} = \tau_A + \tau_C$$

$$\tau_{AB} = \tau_A + \tau_B$$

$$2\Delta = \tau_B - \tau_C$$

for each sideband

$$\Phi[A \rightarrow D \rightarrow C \rightarrow D \rightarrow A] = \Phi[A \rightarrow D] \Phi[C \rightarrow D] \Phi[D \rightarrow C] \Phi[D \rightarrow A]$$

$$\Phi[A \rightarrow D \rightarrow B \rightarrow D \rightarrow A] = \Phi[A \rightarrow D] \Phi[B \rightarrow D] \Phi[D \rightarrow B] \Phi[D \rightarrow A]$$

$$\Phi[C \rightarrow D \rightarrow A] = \Phi[C \rightarrow D] \Phi[D \rightarrow A]$$

$$\Phi[B \rightarrow D \rightarrow A] = \Phi[B \rightarrow D] \Phi[D \rightarrow A]$$

■ Initialization when mirror is moved

Using reference k

$rA0, rB0, rC0, rD0, v_A, v_B, v_C, v_D$

■ Calculation of fields

For each sideband

$$C_{ACA0} = \Phi[A \rightarrow D \rightarrow C \rightarrow D \rightarrow A] \times rA0 rC0 rD0^2 \text{Exp}[-i 2k (v_C + 2 v_D) \tau_{AC}]$$

$$C_{ABA0} = \Phi[A \rightarrow D \rightarrow B \rightarrow D \rightarrow A] \times rA0 rB0 rD0^2 \text{Exp}[-i 2k v_B \tau_{AB}]$$

$$C_{C0} = \Phi[C \rightarrow D \rightarrow A] \times rA0 rD0 tC0 \text{Exp}[-i 2k v_D \tau_A]$$

$$C_{B0} = \Phi[B \rightarrow D \rightarrow A] \times rA0 tB0 tD0$$

$$\xi_{ACA} = 2k(v_A + v_C + 2v_D)$$

$$\xi_{ABA} = 2k(v_A + v_B)$$

For each External source

$$V_{E1} = dE_1 / dt / E1$$

β for each

$$C_{ACA} = C_{ACA0} (1 + 2\Delta V_{E1})$$

$$C_{ABA} = C_{ABA0} (1 - 2\Delta V_{E1})$$

$$C_A = tA0 EAin0$$

$$\zeta_A = \beta_A$$

$$C_C = C_{C0} ECin0 \text{Exp}[-\beta_C (\tau_A + \tau_C)]$$

$$\zeta_C = i 2k (v_A + v_D) + \beta_C$$

$$C_B = C_{B0} EBin0 \text{Exp}[-\beta_B (\tau_A + \tau_B)]$$

$$\zeta_B = i 2k v_A + \beta_B$$

$$C_{ACA}(N\tau) = C_{ACA} \cdot \exp(i \xi_{ACA} \cdot N\tau)$$

$$C_{ABA}(N\tau) = C_{ABA} \cdot \exp(i \xi_{ABA} \cdot N\tau)$$

$$C_{ACB}(N\tau) = C_{ACA}(N\tau) + C_{ABA}(N\tau)$$

$$\xi_{ACB}(N\tau) = \frac{\xi_{ACA} C_{ACA}(N\tau) + \xi_{ABA} C_{ABA}(N\tau)}{C_{ACB}(N\tau)} \tau$$

$$C_{ACB}^{\sim}(N\tau) = C_{ACB}(N\tau) \exp(i \xi_{ACB}(N\tau) / 2) \cdot \exp(-\zeta \tau)$$

$$E(t+N\tau) = \left\{ \frac{1 - C_{ACB}^{\sim N}}{1 - C_{ACB}^{\sim}} - i \xi_{ACB}(N\tau) / 2 \times SP2(C_{ACB}^{\sim}) \right\} Eext(N\tau) + C_{ACB}(N\tau)^N \exp(-i \xi_{ACB}(N\tau) N^2 / 2) E(t)$$

$$SP2(x) = \frac{x(1+x) - x^N (x + (N+x-Nx)^2)}{(1-x)^3}$$