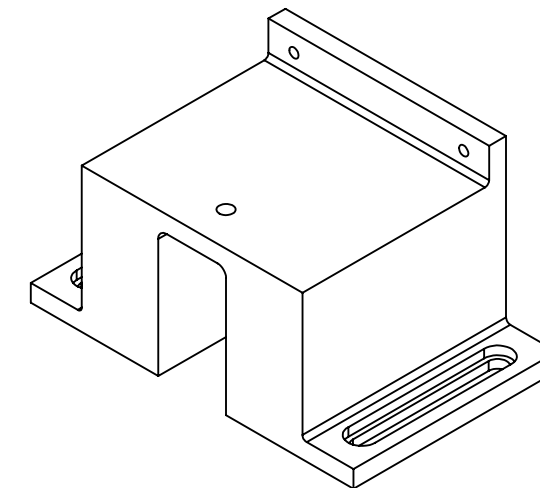
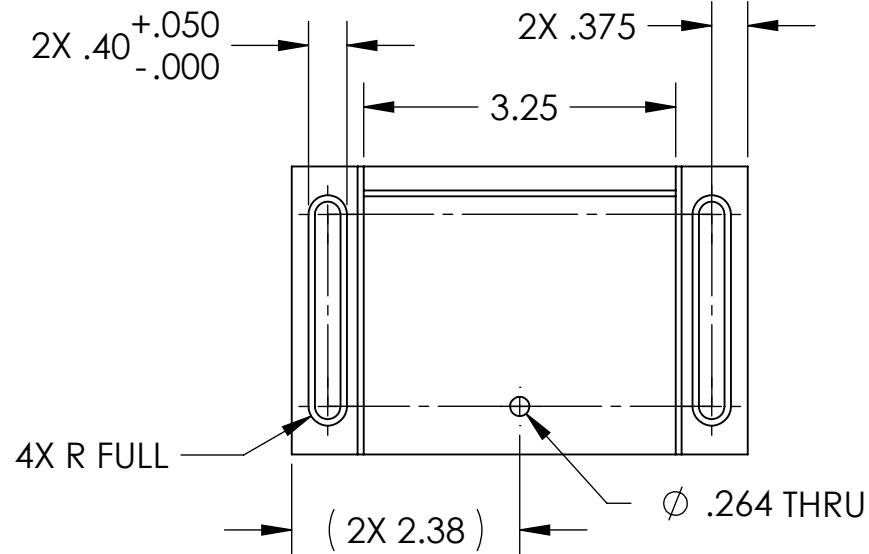


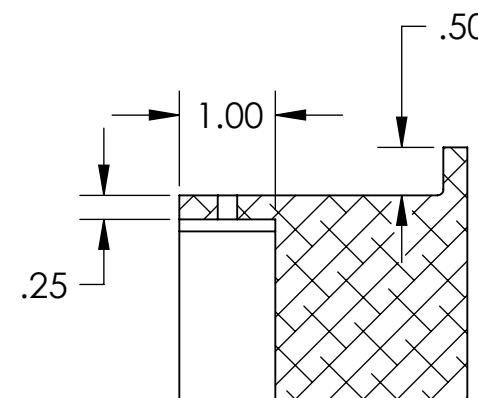
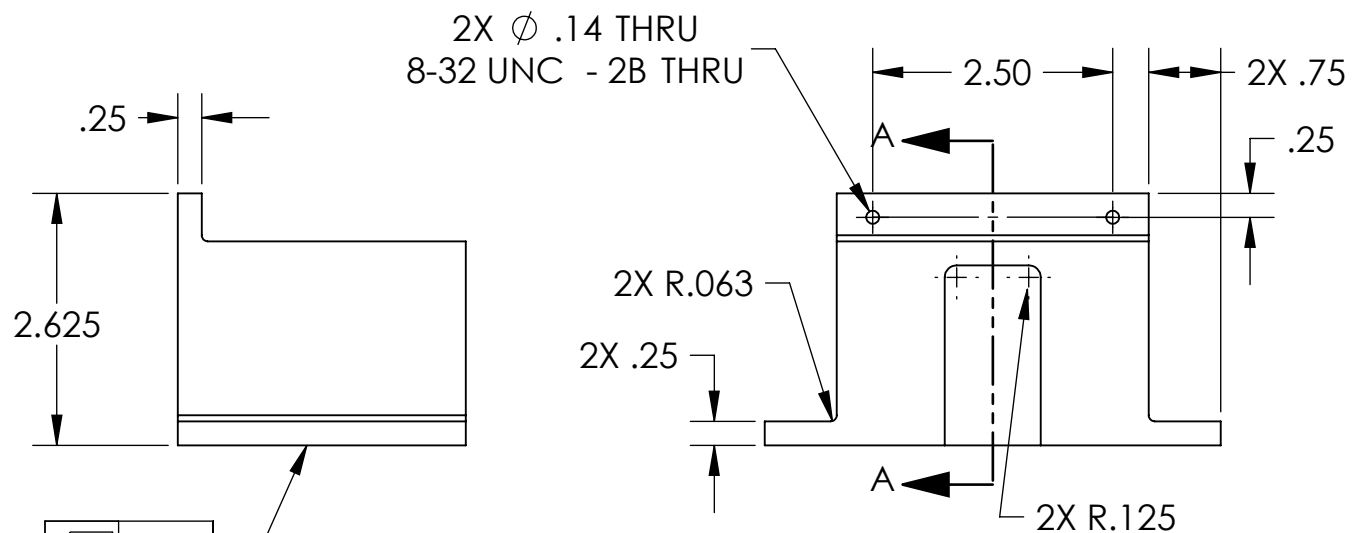
NOTES CONTINUED:
 5. SCRIBE, ENGRAVE, OR MECHANICALLY STAMP (NO INKS OR DYES) DRAWING PART NUMBER, REVISION (AND VARIANT OR "TYPE" IF APPLICABLE) ON NOTED SURFACE OF PART FOLLOWED ON THE NEXT LINE WITH A THREE DIGIT SERIAL NUMBER. SERIAL NUMBERS START AT 001 FOR THE FIRST ARTICLE AND PROCEED CONSECUTIVELY. USE MINIMUM 0.12" HIGH CHARACTERS, UNLESS THE SIZE OF THE PART DICTATES SMALLER CHARACTERS. A VIBRATORY TOOL MAY BE USED.
 EXAMPLE: DXXXXXX-VY, TYPE-XX, S/N XXX

CONFIGURATION	DESCRIPTION
-01	SOLID BASE
-02	FINNED BASE (SHEET 2)

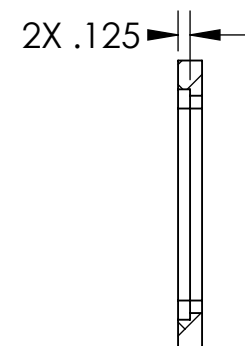
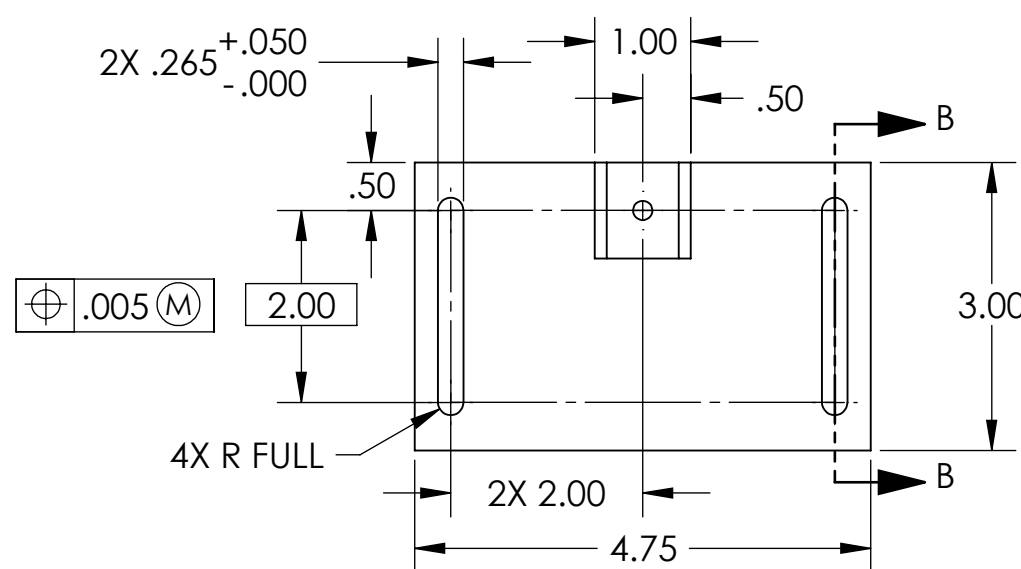
REV.	DATE	DCN #	DRAWING TREE #
-	-	-	-
-	-	-	-
-	-	-	-



CONFIGURATION -01
SOLID BASE



SECTION A-A
SCALE 1 : 2



SECTION B-B
SCALE 1 : 2

NOTES AND TOLERANCES: (UNLESS OTHERWISE SPECIFIED)

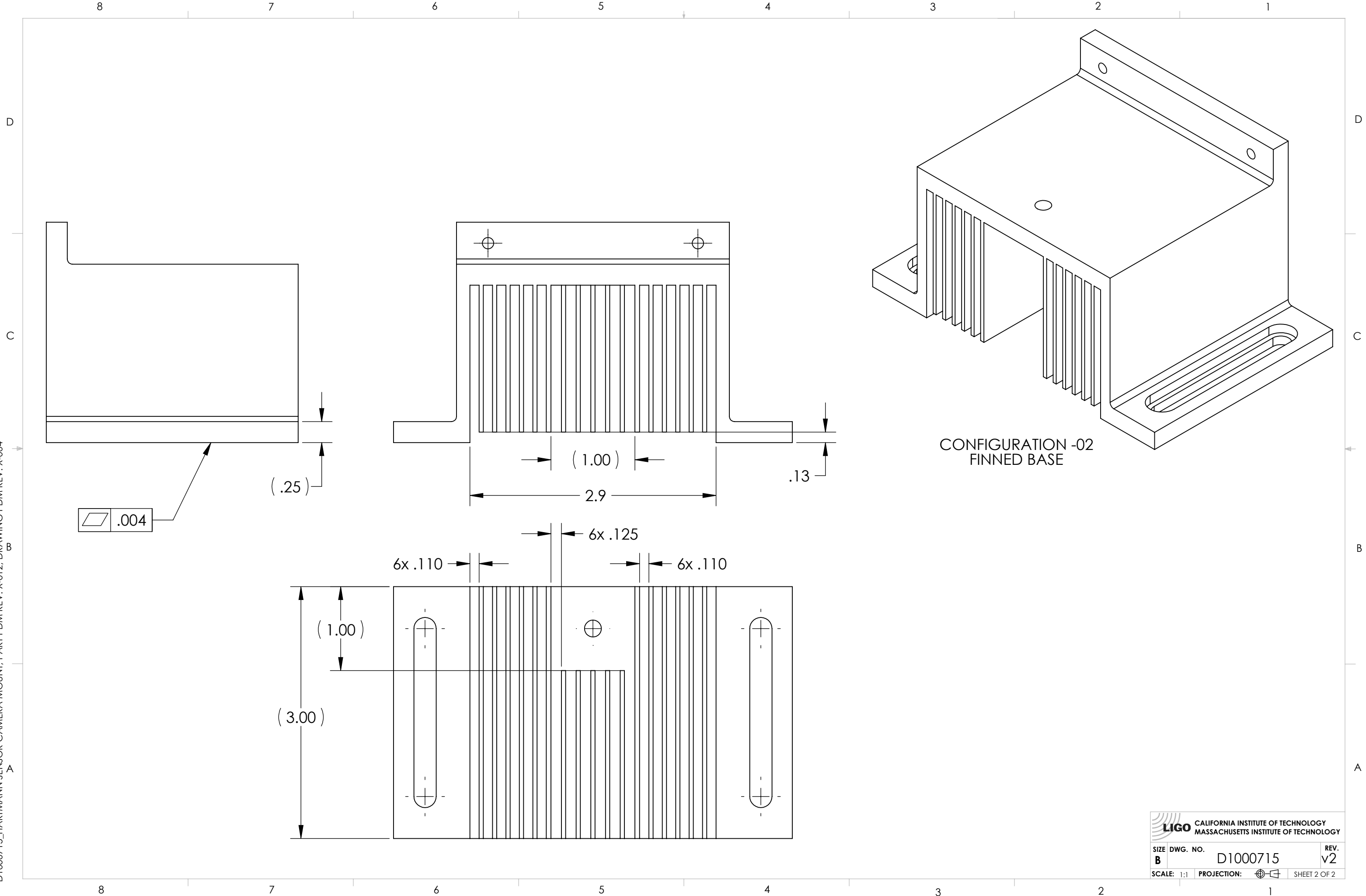
DIMENSIONS ARE IN INCHES [MM]
 TOLERANCES:
 .XX ± .01
 .XXX ± .005
 ANGULAR ± 0.5°
 1. INTERPRET DRAWING PER ASME Y14.5-1994.
 2. REMOVE ALL SHARP EDGES, R.02 MIN.
 3. DO NOT SCALE FROM DRAWING.
 4. ALL MACHINING FLUIDS MUST BE FULLY SYNTHETIC, FULLY WATER SOLUBLE AND FREE OF SULFUR, SILICONE, AND CHLORINE.

LIGO CALIFORNIA INSTITUTE OF TECHNOLOGY
 MASSACHUSETTS INSTITUTE OF TECHNOLOGY
 SYSTEM: ADVANCED LIGO
 SUB-SYSTEM: AOS
 NEXT ASSY: D1000657



PART NAME: HARTMANN SENSOR CAMERA MOUNT
 DESIGNER: M. JACOBSON 26-MAR-2010
 DRAFTER: M. JACOBSON 22 APR 2010
 CHECKER: M. JACOBSON 25 MAY 2010
 APPROVAL: A. BROOKS 22 APR 2010
 SIZE: B
 DWG. NO.: D1000715
 REV.: v2
 SCALE: 1:1
 PROJECTION: SHEET 1 OF 2

D1000715_HARTMANN SENSOR CAMERA MOUNT, PART PDM REV: X-012, DRAWING PDM REV: X-004

D1000715_HARTMANN SENSOR CAMERA MOUNT, PART PDM REV: X-012, DRAWING PDM REV: X-004



CONFIGURATION -02
FINNED BASE

 CALIFORNIA INSTITUTE OF TECHNOLOGY MASSACHUSETTS INSTITUTE OF TECHNOLOGY		
SIZE B	DWG. NO. D1000715	REV. v2
SCALE: 1:1	PROJECTION: 	SHEET 2 OF 2