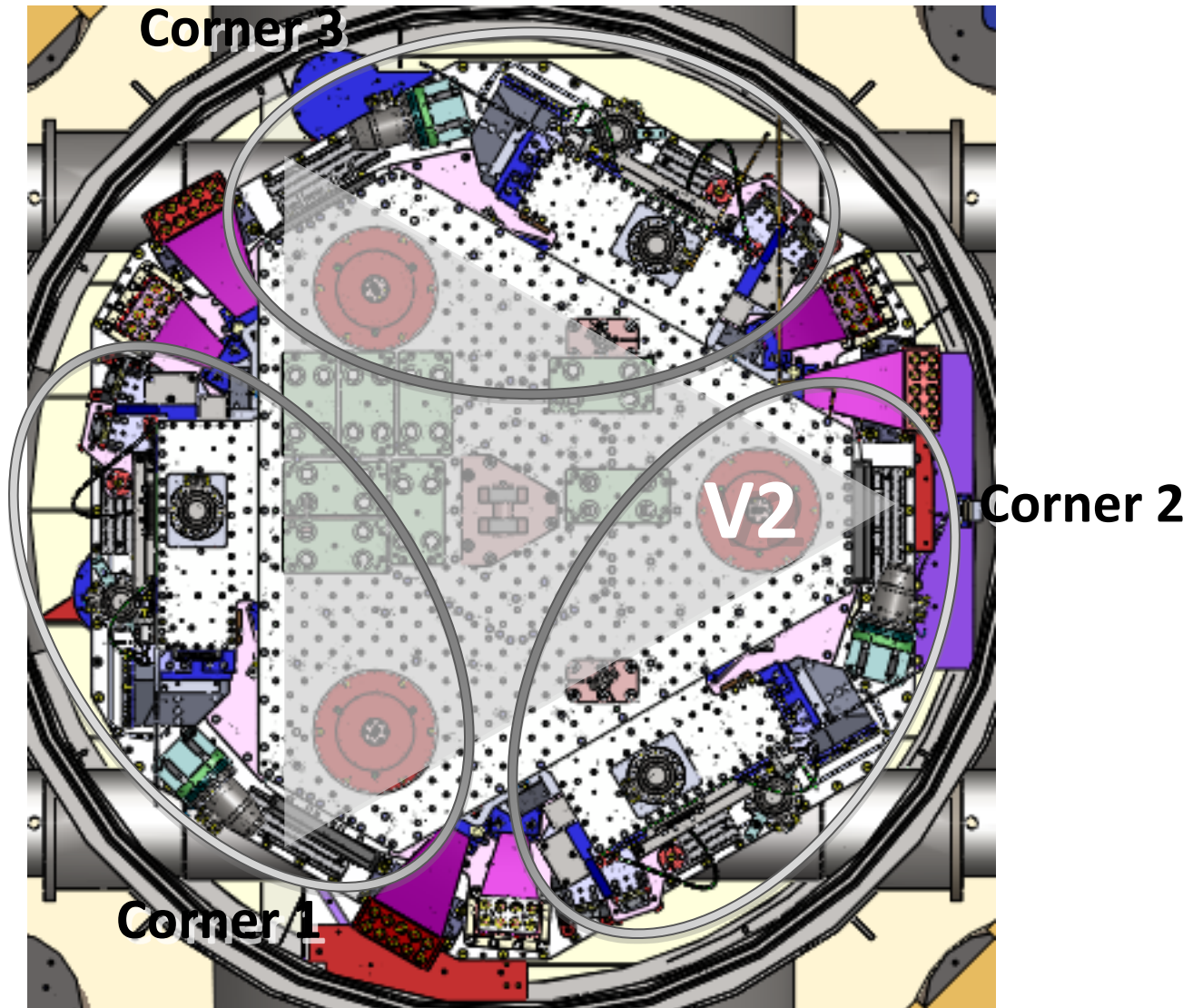


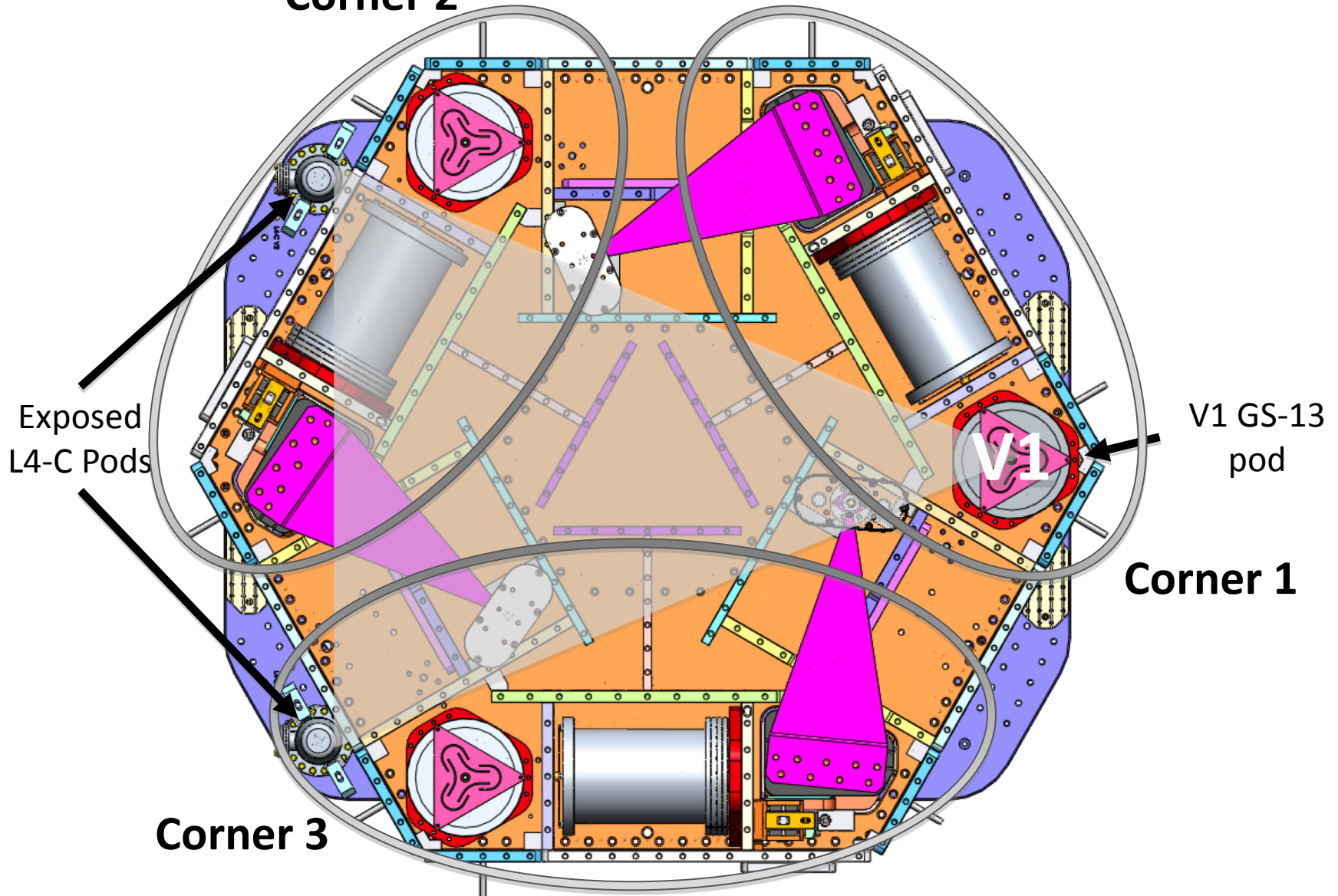
We define the orientation of the BSC ISI using the grey isosceles triangle below.



The base of the triangle spans the support tubes; the rest of the triangle follows the shape of the keel plate

We define the orientation of the HAM ISI using the grey isosceles triangle below.

Corner 2



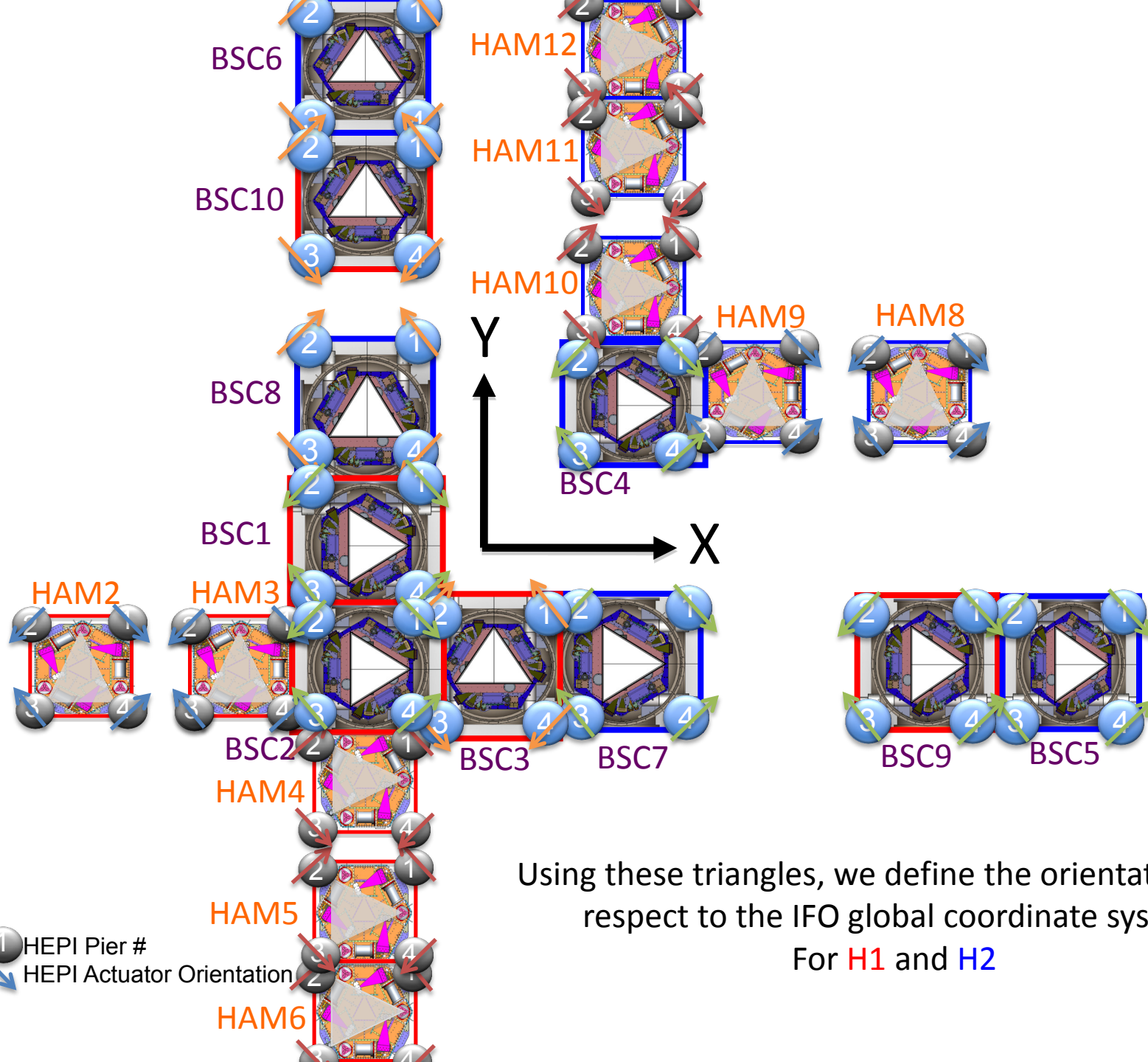
Exposed
L4-C Pods

V1 GS-13
pod

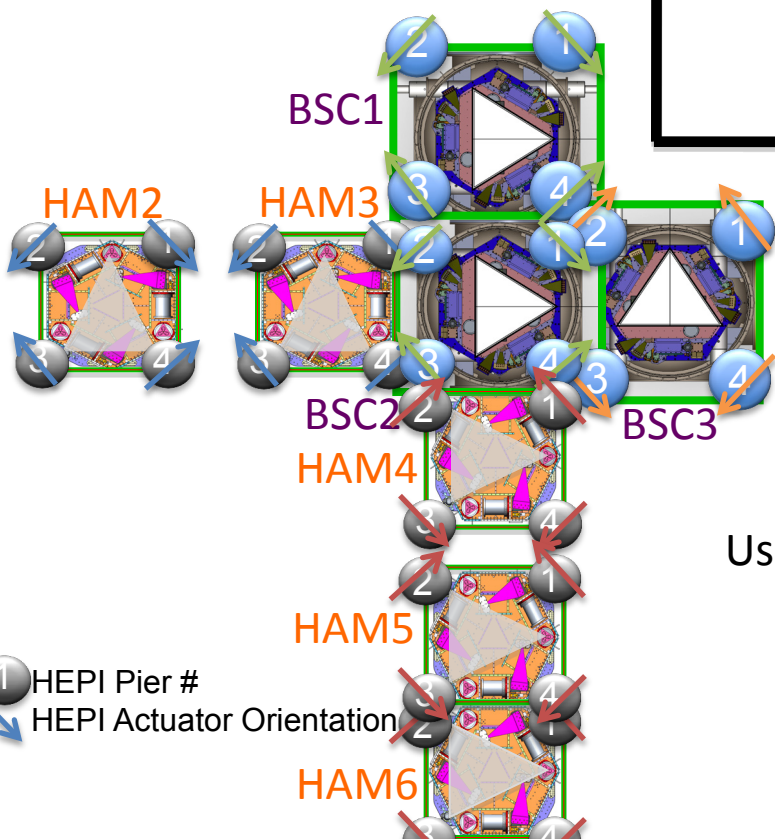
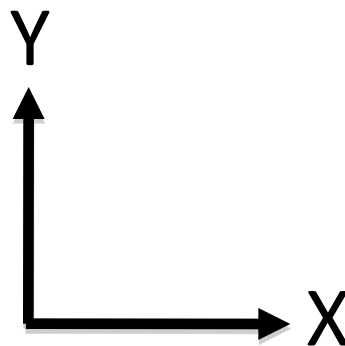
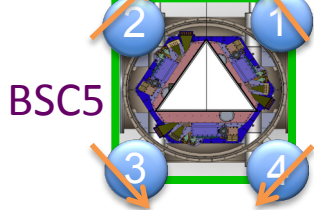
Corner 1

Corner 3

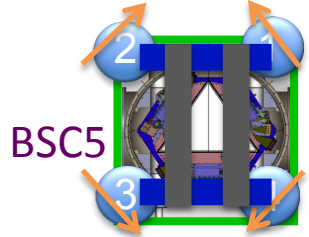
From a top-down view, the base of the triangle is formed by the two exposed L4-C pods, and the tip of the triangle is formed by the V1 GS-13 pod.



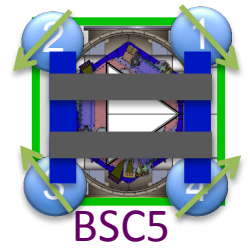
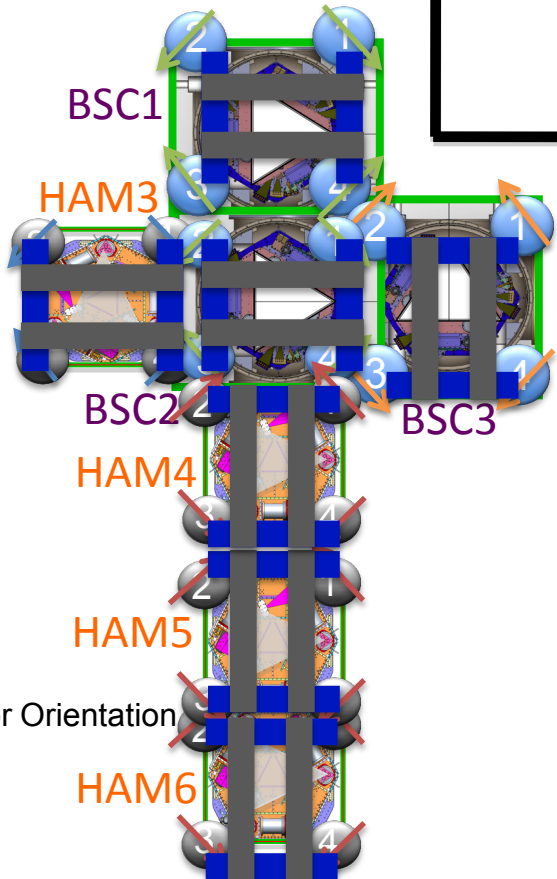
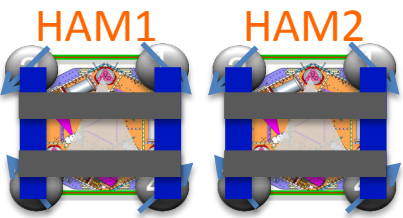
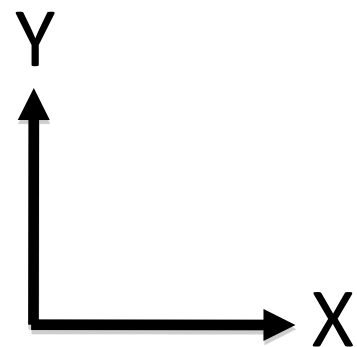
Using these triangles, we define the orientation with respect to the IFO global coordinate system
 For H1 and H2



Using these triangles, we define the orientation with respect to the IFO global coordinate system
 For L1



HEPI Cross Beams
Orientation
L1&H1

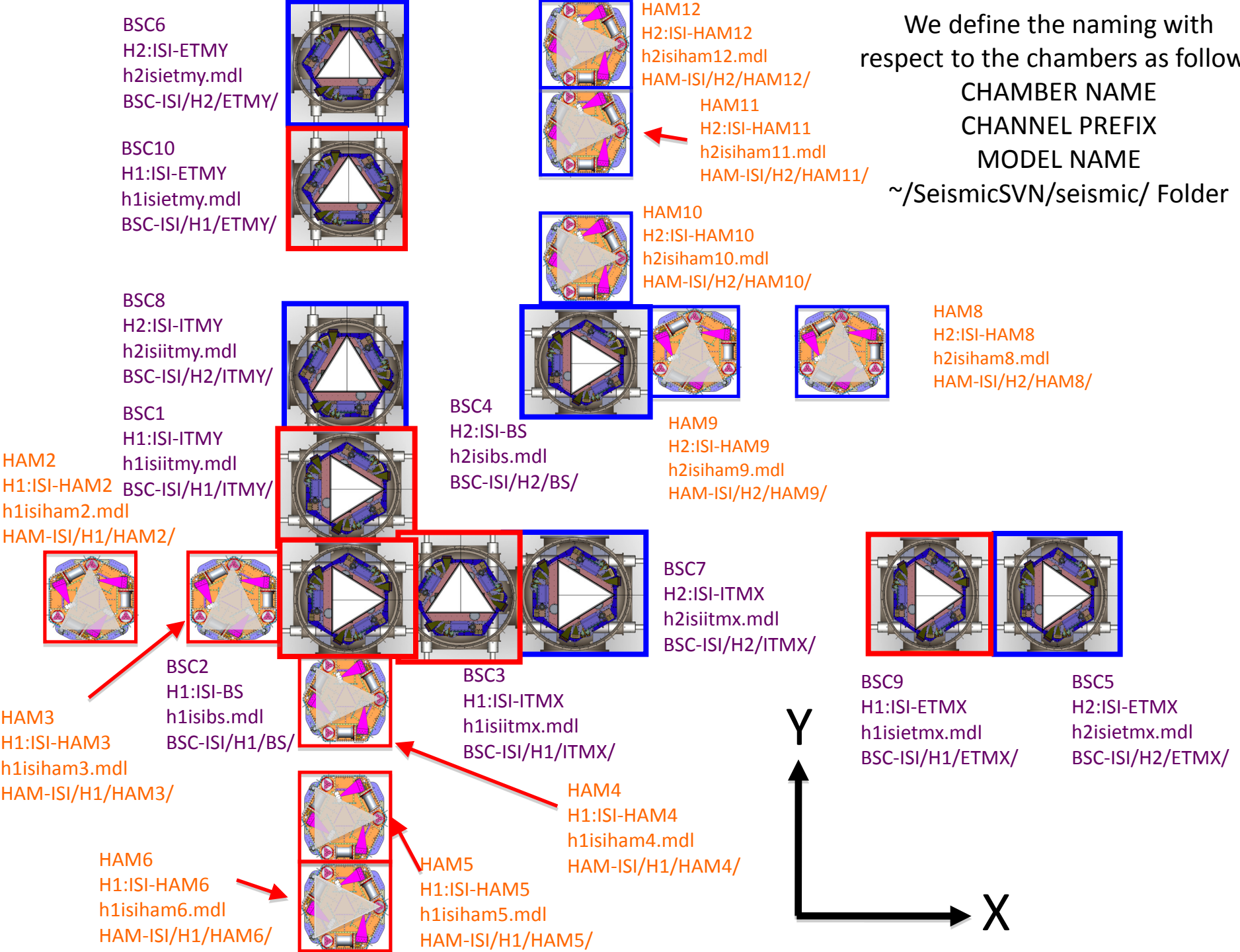


1 HEPI Pier #
↓ HEPI Actuator Orientation

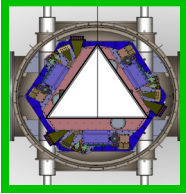
We define the naming with respect to the chambers as follows:

CHAMBER NAME
CHANNEL PREFIX
MODEL NAME

~/SeismicSVN/seismic/ Folder

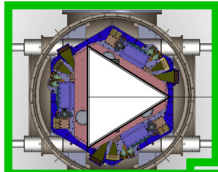


BSC5
L1:ISI-ETMY
l1isietmy.mdl
BSC-ISI/L1/ETMY/

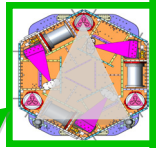
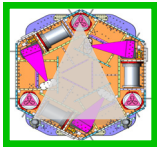


We define the naming with respect to the chambers as follows:
CHAMBER NAME
CHANNEL PREFIX
MODEL NAME
~/SeismicSVN/seismic/ Folder

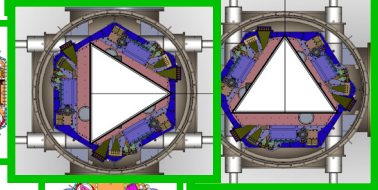
BSC1
L1:ISI-ITMY
l1isiitmy.mdl
BSC-ISI/L1/ITMY/



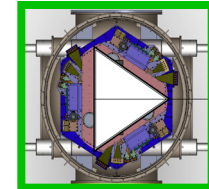
HAM2
L1:ISI-HAM2
l1isiham2.mdl
HAM-ISI/L1/HAM2/



BSC2
L1:ISI-BS
l1isibs.mdl
BSC-ISI/L1/BS/

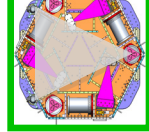


BSC3
L1:ISI-ITMX
l1isiitmx.mdl
BSC-ISI/L1/ITMX/



BSC4
L1:ISI-ETMX
l1isietmx.mdl
BSC-ISI/L1/ETMX/

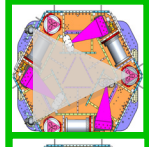
HAM3
L1:ISI-HAM3
l1isiham3.mdl
HAM-ISI/L1/HAM3/



HAM4
L1:ISI-HAM4
l1isiham4.mdl
HAM-ISI/L1/HAM4/



HAM6
L1:ISI-HAM6
l1isiham6.mdl
HAM-ISI/L1/HAM6/



HAM5
L1:ISI-HAM5
l1isiham5.mdl
HAM-ISI/L1/HAM5/

