

LIGO Laboratory / LIGO Scientific Collaboration

LIGO-T0900324-v2

LIGO

6/22/10

Design Equations for Initially Flat Blade Springs at Arbitrary Mounting Angles

Michael Smith, Jesse Amato-Grill

Distribution of this document: LIGO Scientific Collaboration

This is an internal working note of the LIGO Laboratory.

California Institute of Technology LIGO Project – MS 18-34 1200 E. California Blvd. Pasadena, CA 91125 Phone (626) 395-2129 Fax (626) 304-9834 E-mail: info@ligo.caltech.edu

LIGO Hanford Observatory P.O. Box 1970 Mail Stop S9-02 Richland WA 99352 Phone 509-372-8106 Fax 509-372-8137 Massachusetts Institute of Technology LIGO Project – NW22-295 185 Albany St Cambridge, MA 02139 Phone (617) 253-4824 Fax (617) 253-7014 E-mail: info@ligo.mit.edu

LIGO Livingston Observatory P.O. Box 940 Livingston, LA 70754 Phone 225-686-3100 Fax 225-686-7189

http://www.ligo.caltech.edu/

LIG0

1 Introduction

The purpose of this document is to describe the design equations for a cantilevered flat blade spring, mounted at an arbitrary tilt angle, which takes a precise circular curvature under load with the tip of the spring having a horizontal slope. The test results of two specimen blade spring designs are shown.

2 Design Equations

The bending and deflection of a flat blade cantilever spring are calculated from fundamental principles. 1

The geometry of the cantilever blade spring is shown in Figure 1.

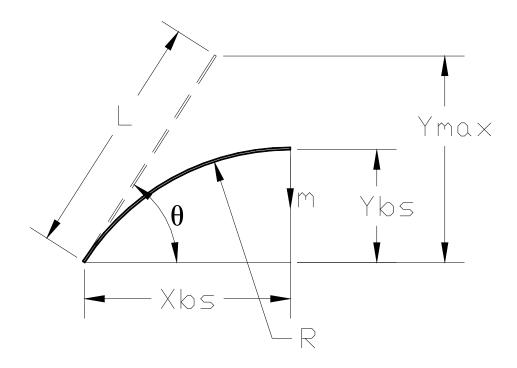


Figure 1: Geometry of the Cantilever Blade Spring

¹ Design of Machine Elements, M.R. Spotts, 2nd ed. 1953, Prentice-Hall, N.J

2.1 Theory

2.1.1 Beam Bending

The maximum normal stress at any cross section of the blade occurs at the outer surface of the blade and is proportional to applied moment, to the distance from the neutral axis of the cross section to the outer surface, and inversely proportional to the area moment of inertia of the cross section.

Bending moment	М
Thickness of blade	t
Width of blade	b
Moment of inertia of cross section	Ι
For a rectangular cross section	
	$\mathbf{L} = \frac{\mathbf{b} \cdot \mathbf{t}^3}{12}$
Maximium normal stress	

The maximum strain at the outer surface of the blade is inversely proportional to the bending radius of the blade at the particular cross section.

 $\varepsilon := \frac{\frac{t}{2}}{R}$

 $S_{\text{M}} := \frac{M \cdot \frac{t}{2}}{T}$

maximum strain

Introducing the modulus of elasticity through the stress/strain relationship for a material that obeys Hook's law, $S_{\alpha} := E \cdot \epsilon$

$$S_{\text{M}} := E \cdot \frac{t}{2 \cdot R}$$

In general, the width of the blade is >> than the thickness, and the effective modulus of elasticity must be increased to account for the additional stiffness caused by the Poisson's ratio, μ .

$$E_{eff} := \frac{E}{\left(1 - \mu^2\right)}$$

The deflected shape of the blade spring will be circular with a constant radius, R, if the stress is equal at every cross section. The design will use a safe working stress for the material, which does not exceed the elastic limit.

$$S_{W} := S_{W}$$

2.1.2 Vertical Bounce Frequency

The vertical bounce frequency of a mass on a spring with a spring constant k is

$$f_{0} := \frac{1}{2 \cdot \pi} \cdot \sqrt{\frac{k}{m}}$$

The spring constant is defined as the ratio of vertical force to vertical displacement.

$$k := \frac{m \cdot g}{y}$$

Substituting the spring constant into the frequency equation, we obtain

$$f_{QA} := \frac{1}{2 \cdot \pi} \cdot \sqrt{\frac{g}{y}}$$

which is the equation for the frequency of a pendulum of length y. This result relies on the spring being linear with a single spring const.

Strangely enough, even though the blade spring is non-linear and the spring constant varies with deflection, the measured vertical bounce frequency of the blade spring can be predicted precisely by using the pendulum formula and by choosing y = ymax, the total deflection of the blade spring under the load.

LIGO

2.2 Design Equations

Blade spring Test 45 deg 7/2/09

acceleration of gravity, m/s^2 g := 9.8

BLADE SPRING TEST @ 45 deg

Faraday upper blade spring design

yield strength of 1095 spring steel, psi	Syieldpoin:= 84000	
Poisson's ratio	щ:= 0.3(
modulus of elasticity, psi	$E_{\text{maxim}} = 30 \cdot 10^6$	
modulus of elasticity, Pa	$\mathbf{E} := \mathbf{E}_{\mathbf{psi}} \cdot 6895$	$E = 2.0685 \times 10^{11}$
working stress of 1095 spring steel, psi	$S_{\text{wpsiv}} = S_{\text{yieldpsi}} \cdot 0.28$	$S_{wpsi} = 2.352 \times 10^4$
working stress of 1095 spring steel, Pa	$S_{\text{wpsi}} = \frac{S_{\text{wpsi}}}{1.45 \cdot 10^{-4}}$	$S_{W} = 1.62207 \times 10^{8}$
radius of blade spring, m	$R_{\text{Mass}} = 14.0254$	$R_{bs} = 0.3556$
radius of blade spring, in	$R_{basinan} := \frac{R_{bs}}{.0254}$	$R_{bsin} = 14$
thickness of blade spring, m	$t := \frac{2 \cdot R_{bs} \cdot S_{w} \cdot (1 - \mu^2)}{E}$	$t = 5.07513 \times 10^{-4}$
thickness of blade spring, in	$t_{\text{inax}} = \frac{t}{.0254}$	$t_{in} = 0.01998$
arc of blade spring, rad	$ \bigoplus_{n=1}^{\infty} \frac{\pi}{4} $	
blade arc angle, deg	$\mathfrak{H}_{\mathbf{madeg}}(\theta_{\mathbf{m}}) \coloneqq \theta_{\mathbf{m}} \cdot \frac{180}{\pi}$	$\theta_{mdeg}(\theta_m) = 45$

LIG0

length of blade spring, in	$l_{bsin} := R_{bsin} \cdot \theta_m$	l _{bsin} = 10.99557
length of blade spring, m	$l_{bs} := l_{bsin} \cdot .0254$	$l_{bs} = 0.27929$
horizontal distance of suspension point from blade spring mount, in	$\mathbf{x}_{bsin} \coloneqq \mathbf{R}_{bsin} \cdot \sin(\theta_m)$	x _{bsin} = 9.89949
vertical height of suspension from blade spring mount, m	$y_{bsin} := R_{bsin} \cdot (1 - \cos(\theta_m))$	y _{bsin} = 4.10051
unloaded height of blade spring, m	$y_{max} := l_{bs} \cdot sin(\theta_m)$	
vertical distance blade moves, m	$y_r := y_{max} - y_{bsin} \cdot 0.025^2$	
	$y_{r} = 0.09333$	
approximate vertical resonant frequency based on blade depression, Hz	$f_0 := \frac{\sqrt{\frac{g}{y_r}}}{2 \cdot \pi}$	f ₀ = 1.63085
distance along spring, m	l.:= 0	
distance along spring, in	$l_{in} := \frac{1}{.0254}$	
mass supported by each blade spring, kg	m _{bs} := 0.2	
load on blade spring, N	$P := m_{bs} \cdot 9.8$	P = 1.96

Blade Shape

blade width at I from end, m

 $b(l_{in}) := \frac{6 \cdot P \cdot R_{bs} \cdot sin\left(\frac{l_{in}}{R_{bsin}}\right)}{S_{w} \cdot t^{2}}$ b(l) = 0

$$C = \frac{6 \cdot P \cdot R_{bs}}{.0254 \, S_{W} \cdot t^{2}} \qquad C = 3.94069$$

blade width at I from end, in

 $\mathbf{b}_{in}(\mathbf{l}_{in}) \coloneqq \frac{\mathbf{b}(\mathbf{l}_{in})}{.0254}$ $b_{in}(l) = 0$

$$b_{in}\left(\frac{l_{bsin}}{4}\right) = 0.76879 \qquad \qquad \frac{l_{bsin}}{4} = 2.74889$$
$$b_{in}\left(\frac{l_{bsin}}{2}\right) = 1.50804 \qquad \qquad \frac{l_{bsin}}{2} = 5.49779$$

 $b_{in}(l_{bsin} \cdot 0.75) = 2.18933$ $l_{bsin} \cdot 0.75 = 8.24668$

 $b_{in}(l_{bsin}) = 2.78649$ $l_{bsin} = 10.99557$

$$b_{inmax} := \frac{3 \cdot P \cdot E^2 \cdot sin\left(\frac{l_{bs}}{R_{bs}}\right)}{2 \cdot R_{bs} \cdot S_w^3 \cdot (1 - \mu^2)^2 \cdot 0.0254} \qquad b_{inmax} = 2.78649$$

 $b_{max} := b_{inmax} 0.025^2$ $b_{max} = 0.07078$

$$\frac{C}{2} = 1.97034$$
 $R_{bsin} = 14$ $t_{in} = 0.01998$
 $x := 0$

$$y_{down} := -1.97034 \sin\left(\frac{x}{14}\right)$$

Solid Works equation

alternative formula

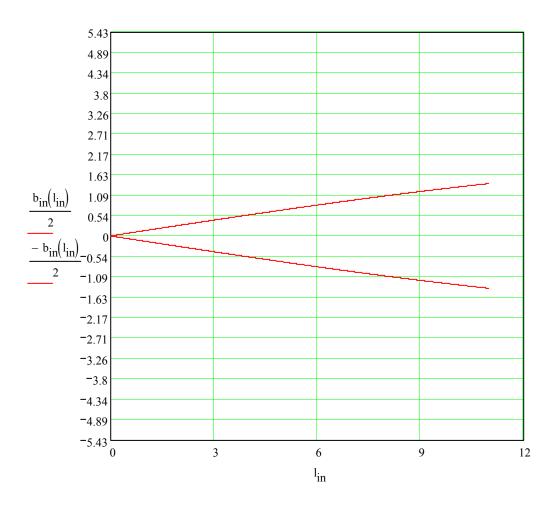
$$y_{up} := 1.97034 \sin\left(\frac{x}{14}\right)$$
stress at l_{in} Pa
$$S_{w} = 1.62207 \times 10^{8}$$

$$S_{w} = 1.62207 \times 10^{8}$$

$$S_{w} = 1.62207 \times 10^{8}$$

$$S_{psi}(l_{bsin}) := S(l_{bsin}) \cdot (1.4 \text{sp}_{psi}(\overset{1}{l_{bsin}}) = 2.352 \times 10^{4}$$

lina,:= 0,0.01.. lbsin



3 Test Results

A drawing of the loaded blade spring was placed behind and adjacent to the spring under test to measure the deviation from the designed radius of curvature. A vertical scale was read to measure the height of the tip of the blade spring above the mounting point. The spring was loaded with mass until the height of the loaded spring matched the design height. With this amount of load, the spring was given a vertical impulse, and the oscillation period was measured with a stop watch.

3.1 45 Degree, 11 inch Blade Spring

3.1.1 Design Values

Material	1095 steel
Modulus of elasticity, psi	30 E6
Length of flat blade, in	11.00
Width at base, in	2.786
Thickness, in	0.020
Vertical height of loaded spring, in	4.10
Mass load, kg	0.200
Radius of curvature, in	14.00
Vertical bounce frequency, Hz	1.63

3.1.2 Experimental Results

The spring loaded with mass at the design height is shown in Figure 2. With this amount of load, the spring was given a vertical impulse, and the oscillation frequency was determined.

The following experimental results were obtained.

Mass load for design height	0.186 kg	error = 0.07
Radius of curvature	14.00 +/- 0.02	
Frequency	1.65	error = 0.01

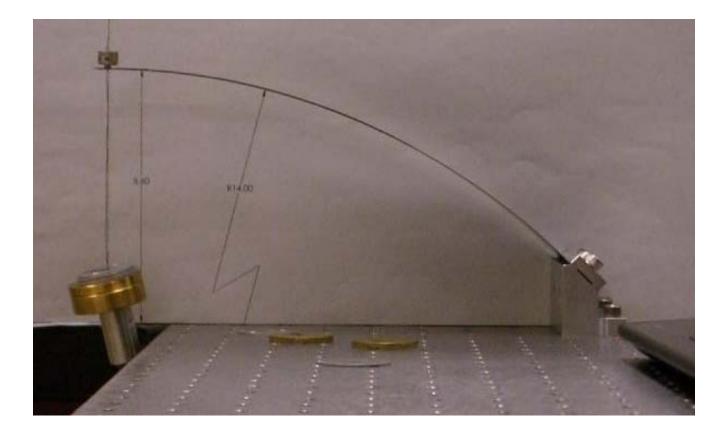


Figure 2: Measured Curvature of 11 in Blade Spring under Balanced Load

3.2 Faraday Isolator Prototype Blade Spring

3.2.1 Design Values

Material C-250 maraging steel
Modulus of elasticity, psi 27 E6
Length of flat blade, in 11
Width at base, in2.83
Thickness, in0.0625
Vertical height of loaded spring, in 4.1
Mass load, kg 5.6
Radius of curvature, in 14.03
Vertical bounce frequency, Hz 1.63

3.2.2 Experimental Results

The two springs supporting the Faraday Isolator optics table with dummy masses are shown in Figure 3. A full scale drawing of the loaded spring is shown behind the actual springs in the picture. The curvature and the height of the loaded springs match reasonably well to the design values. The vertical resonance frequency is approximately 1.4 Hz, as shown in the transmissibility curve in Figure 4.

The following experimental results were obtained.

Mass load for design height, kg	11
Frequency, Hz	1.4
Radius of curvature, in	14

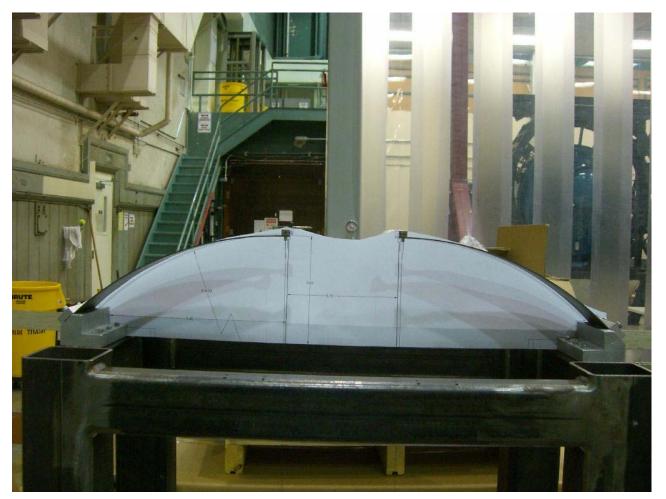


Figure 3: Prototype C-250 Faraday Isolator Blades under Design Load

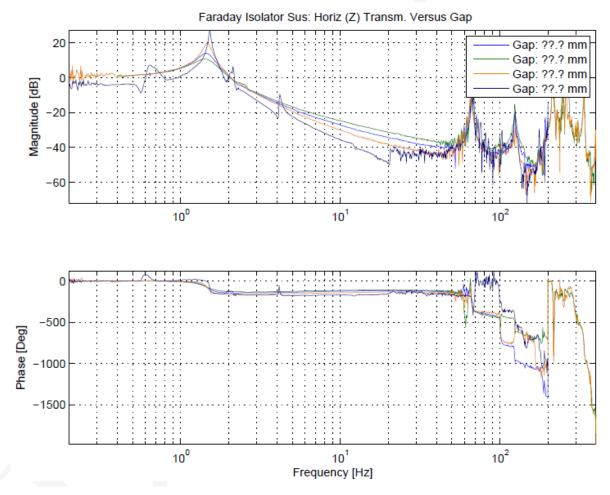


Figure 4: Output Faraday Isolator SUS Transmissibility in Vertical Direction.

3.3 45 Degree, 6.7 inch Blade Spring

3.3.1 Design Values

Material	1095 steel
Modulus of elasticity, psi	30 E6
Length of flat blade, in	6.68
Width at base, in	2.350
Thickness, in	0.015
Vertical height of loaded spring, in	2.49
Mass load, kg	0.200
Radius of curvature, in	8.50
Vertical bounce frequency, Hz	2.09

3.3.2 Experimental Results

The spring loaded with mass at the design height is shown in Figure 5. With this amount of load, the spring was given a vertical impulse, and the oscillation frequency was determined.

The following experimental results were obtained.

Mass load for design height	0.184 kg	error = 0.08
Frequency	2.09	error = 0.00
Radius of curvature	6.68 +/- 0.04	

The radius of curvature matched the printed design profile within twice the thickness of the blade, as shown in the photograph in Figure 5.

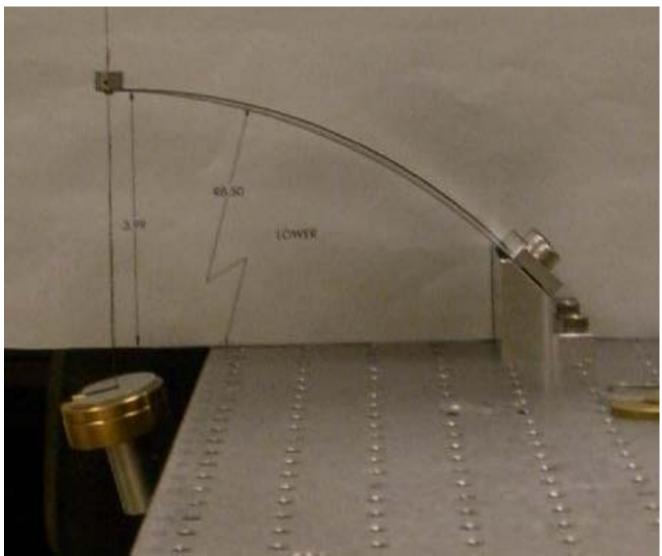


Figure 5: Measured Curvature of 6.7 in Blade Spring under Balanced Load

LIG0

3.4 22.5 Degree, 28 inch Blade Spring

3.4.1 Design Values

Design Values:

Length of flat blade	11.00 in
Vertical height of loaded spring	4.10 in
Mass load	0.200 kg
Radius of curvature	14.00 in

3.4.2 Experimental Results

TBD

LIG0