



Adv LIGO BSC-ISI Stage 0

Design Review

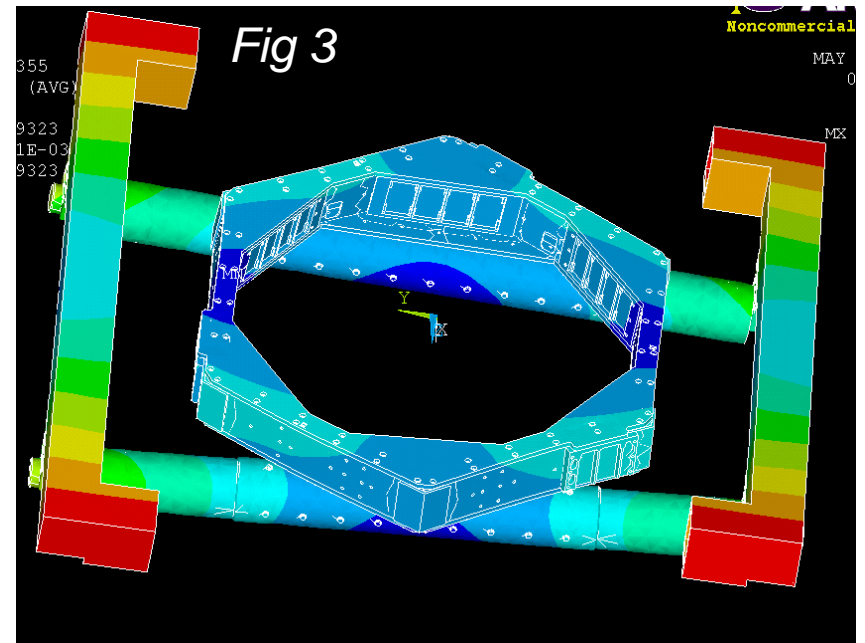
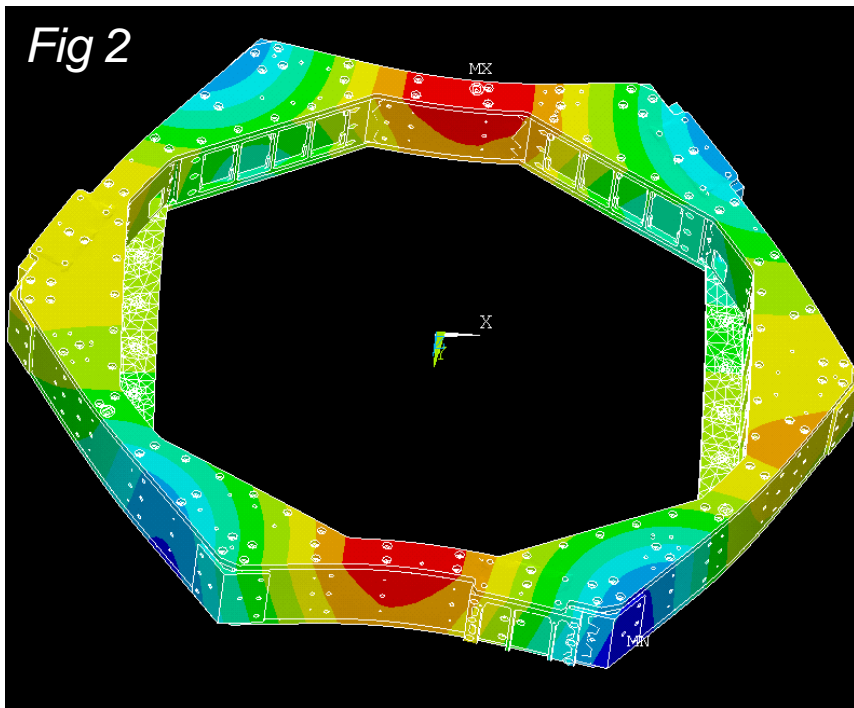
Celine Ramet
May, 22nd 2009

Overview

- LASTI prototype
- New design approach
- New design analysis
- Yet to be added...

LASTI Prototype

- 11 parts
- 1077 lbs (967+110)
- 1st natural frequency: 77 Hz
- 1st natural frequency Stage0+ support structure: 27 Hz



LASTI Prototype (2)

- FEA Static

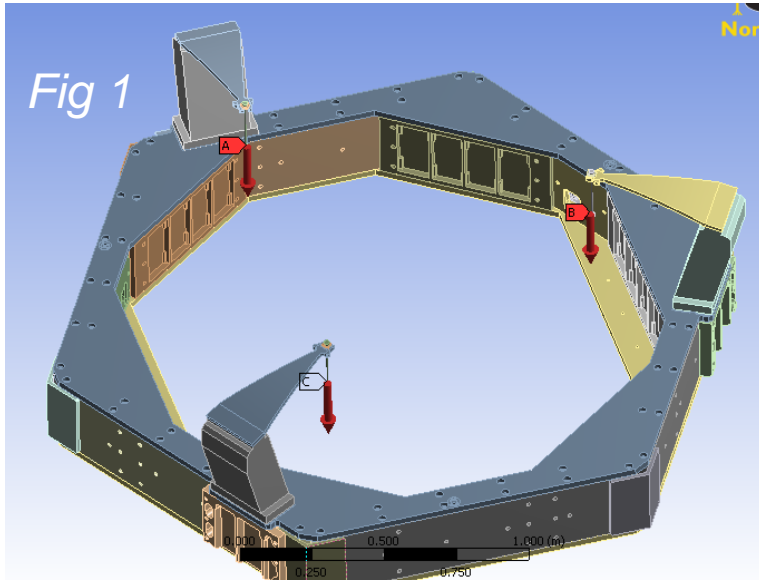


Fig1: Load

Post #	z Displacement bottom flexure rod		% between Z displacement
	mm	mil	
1	0.770	30.3	7.85
2	0.757	29.8	
3	0.710	27.9	

Stage 0 is asymmetrically deformed under load

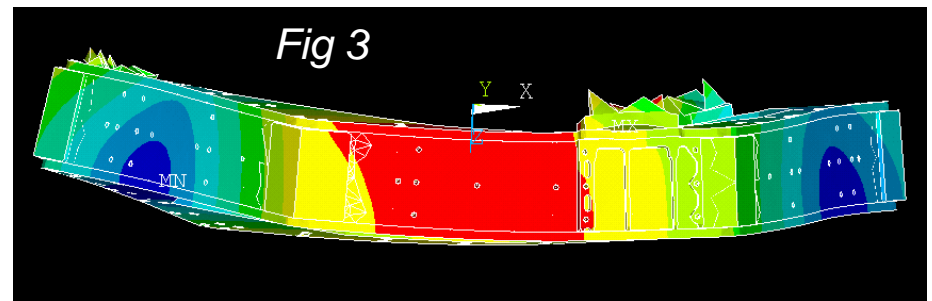
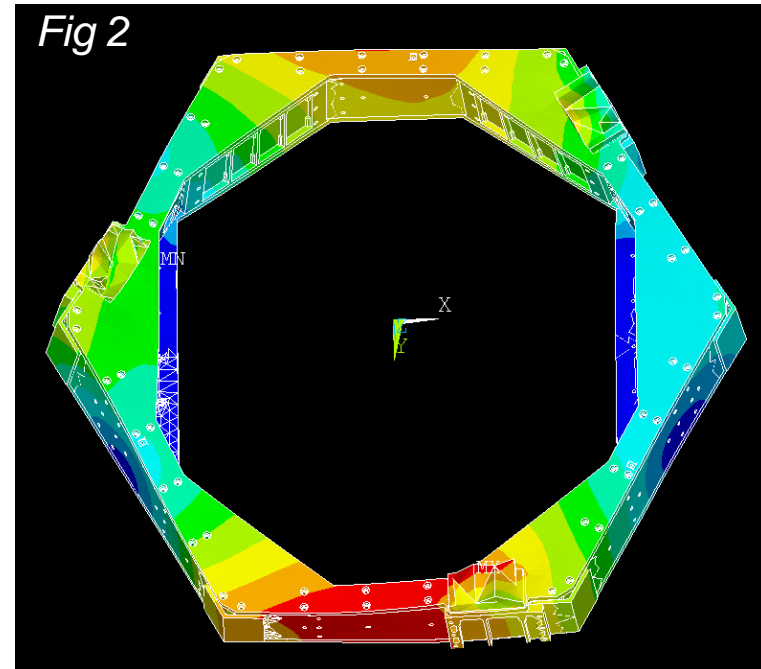
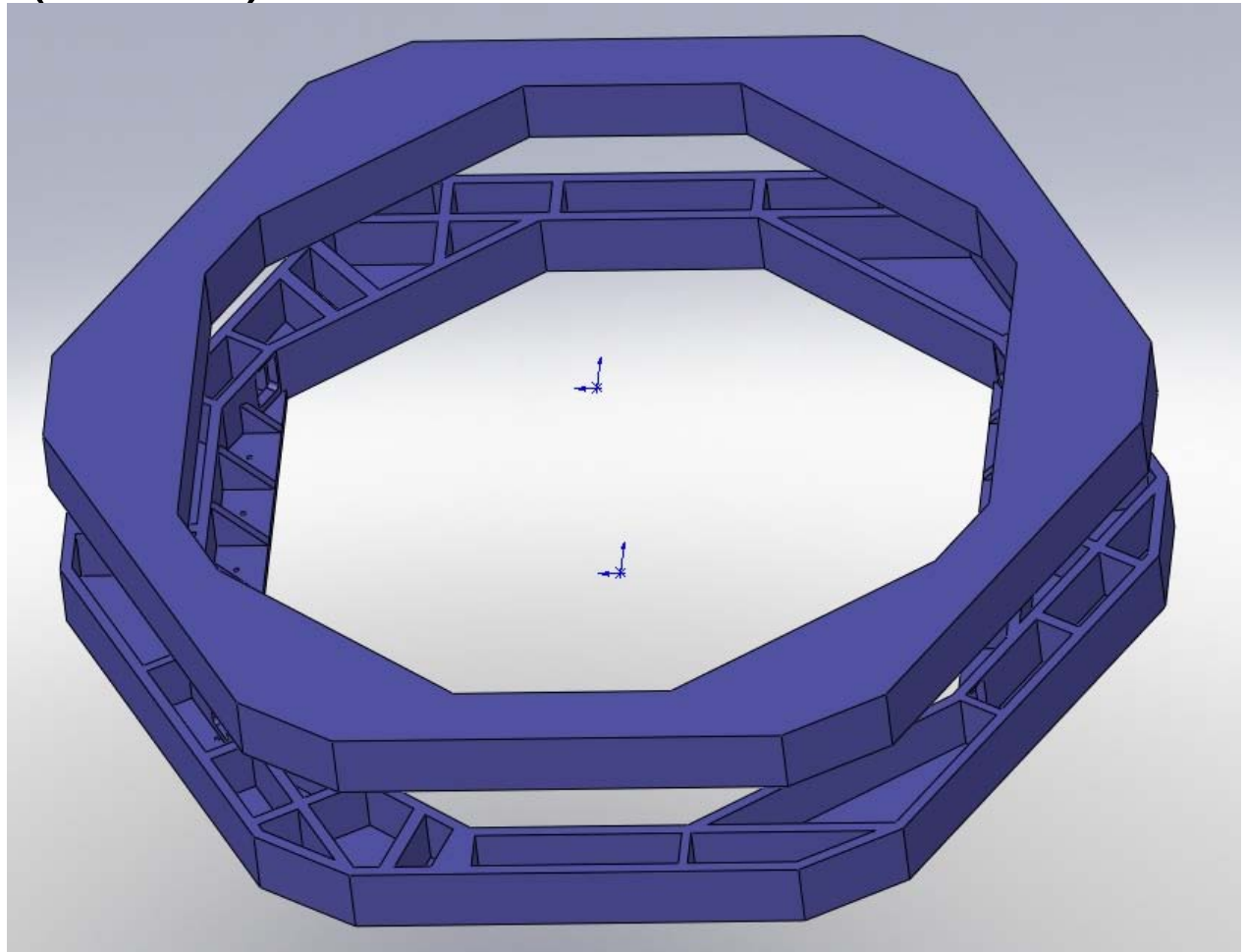


Fig 2 & 3: Nodal displacement contours on deformed structure (max 0.220 mm)

New Design Approach

- Monolithic (6"+6")
 - 2 parts
 - 1195 lbs

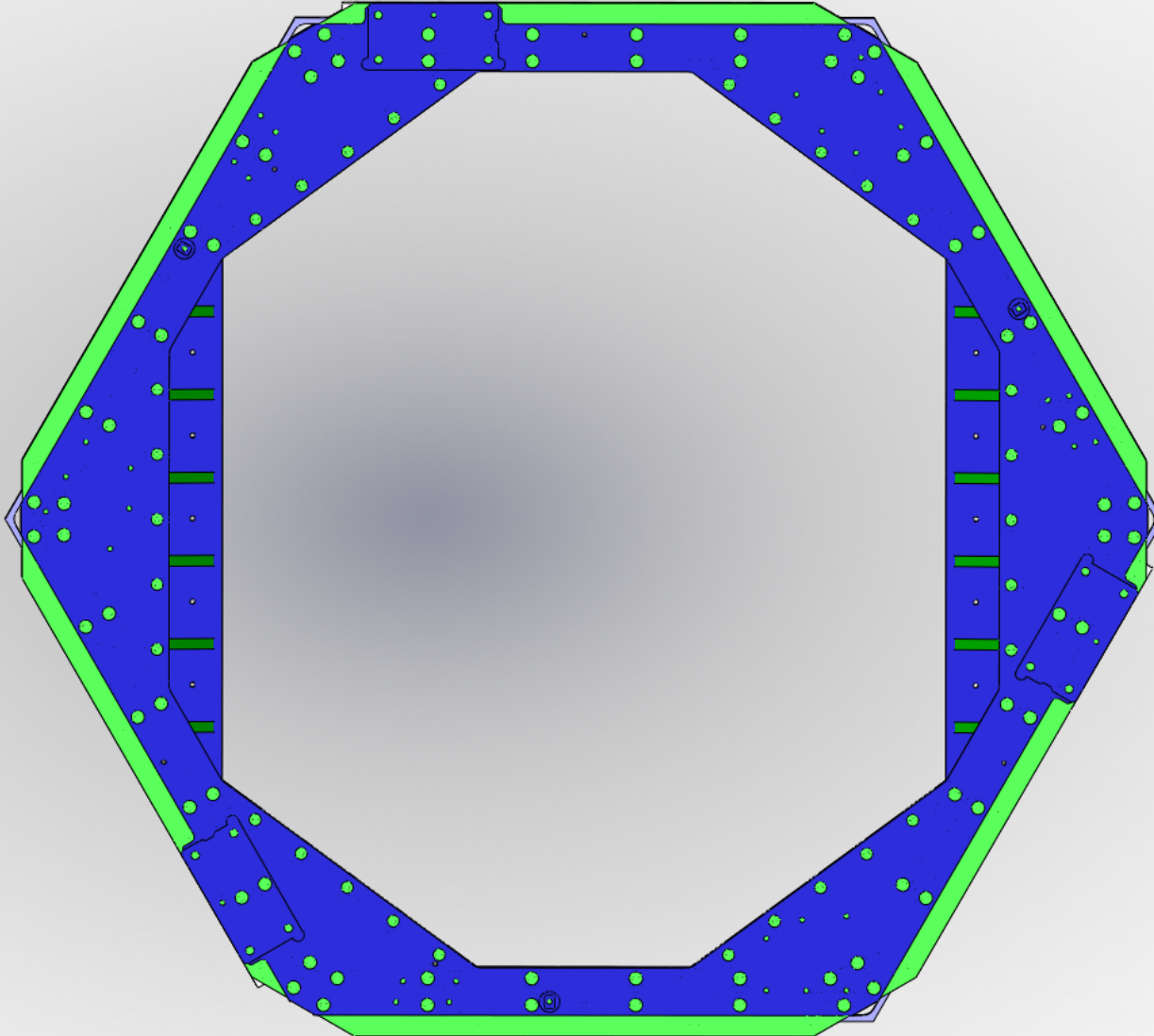
Assembly checked
in the vault
D0900896



Exploded view

New Design Approach (2)

Shape Comparison

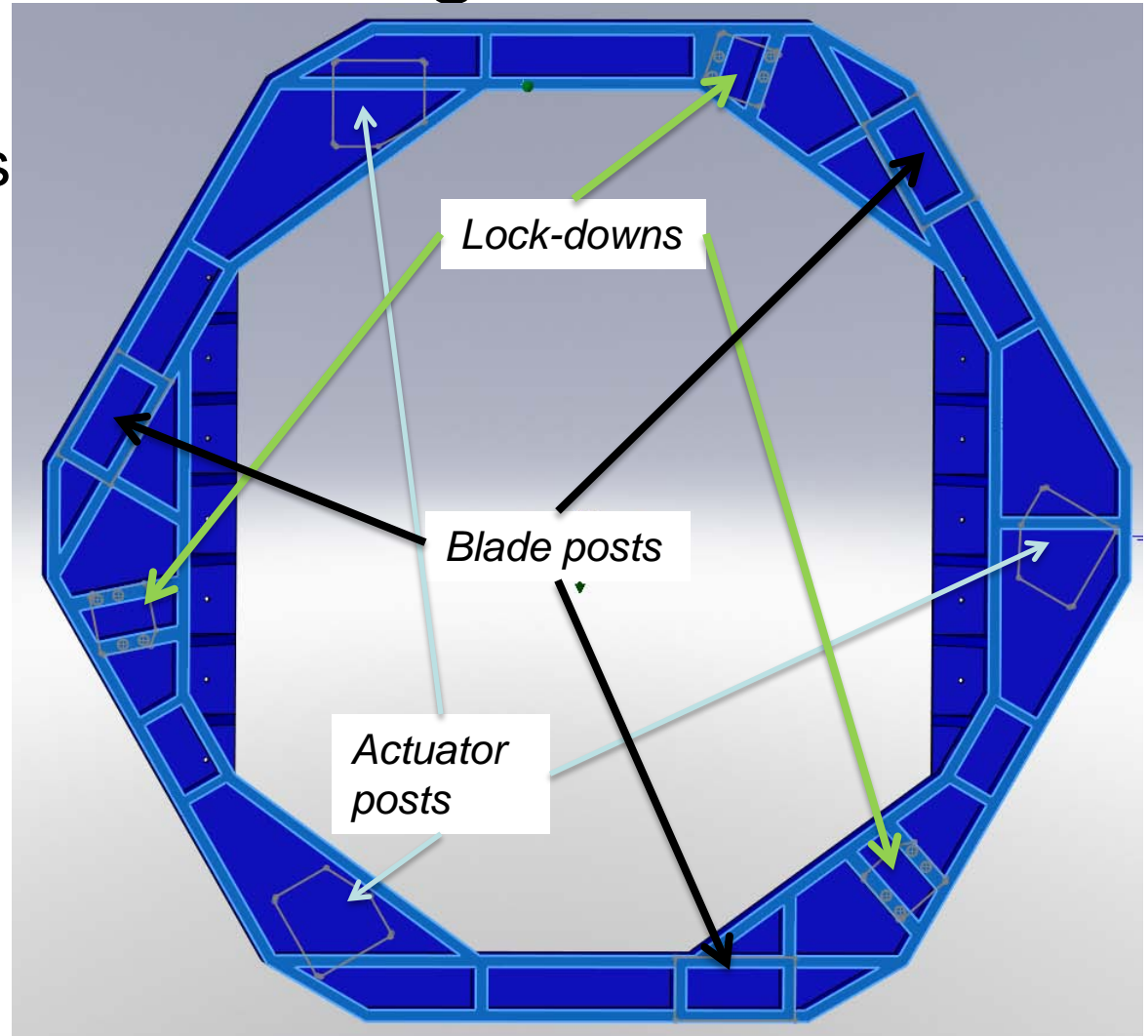


- Blue: old design
- Green : new design
- Same height
- Same interior shape
- 1.75" larger on all sides

New Design Approach (3)

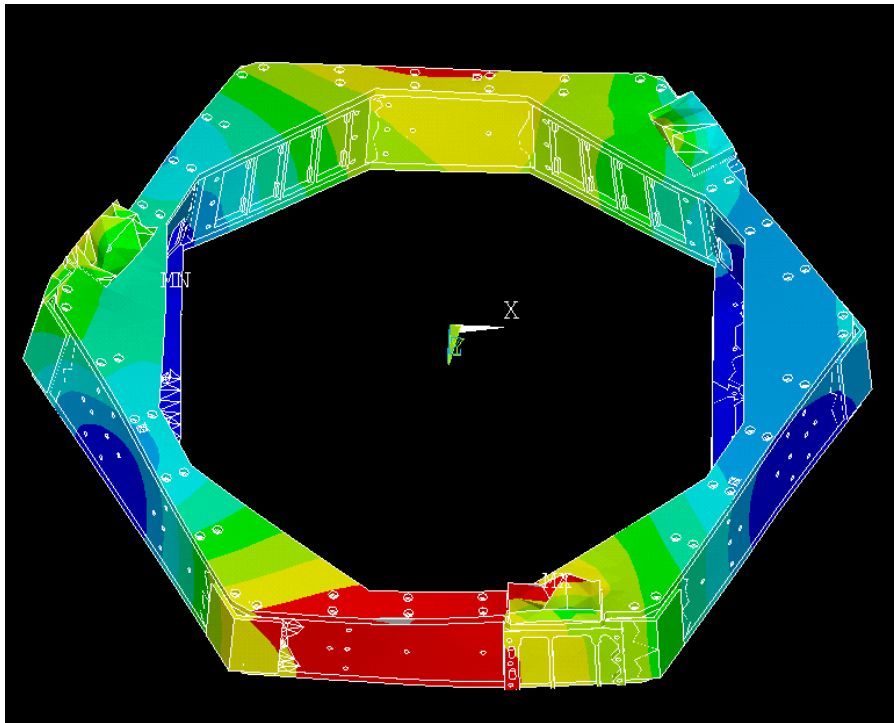
Webbing

- Allow sufficient bolting of the 2 parts
- Allow bolting & support of blade posts and lock-downs
- Maximize 'horizontal' webbing to oppose static deformation

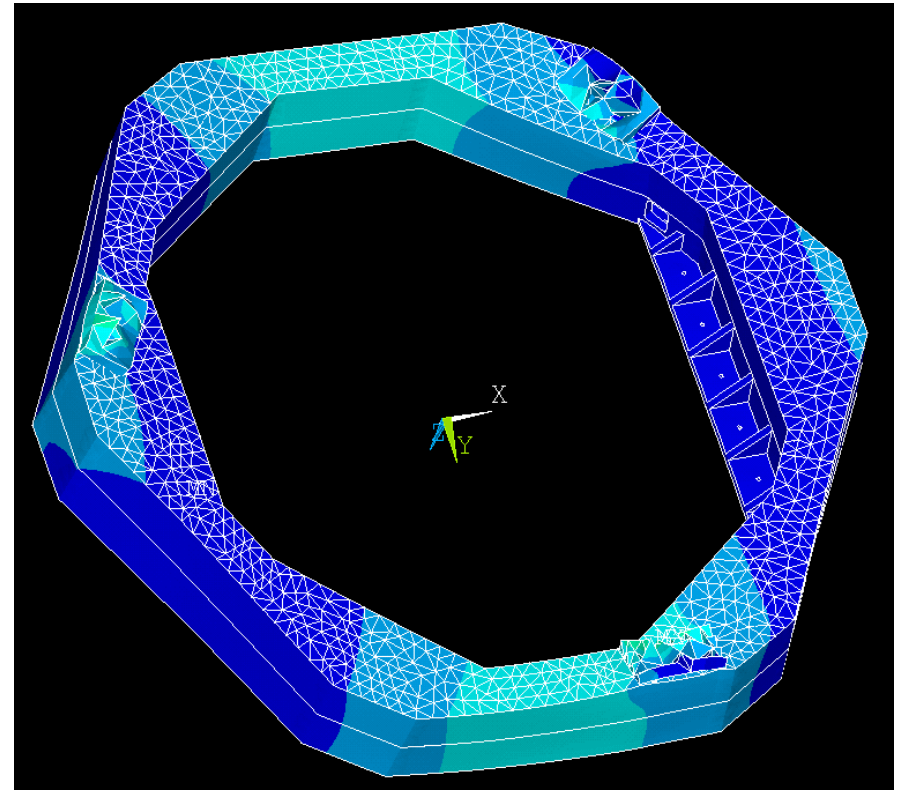


FEA: Nodal Displacement Comparison

LASTI Prototype



Monolithic

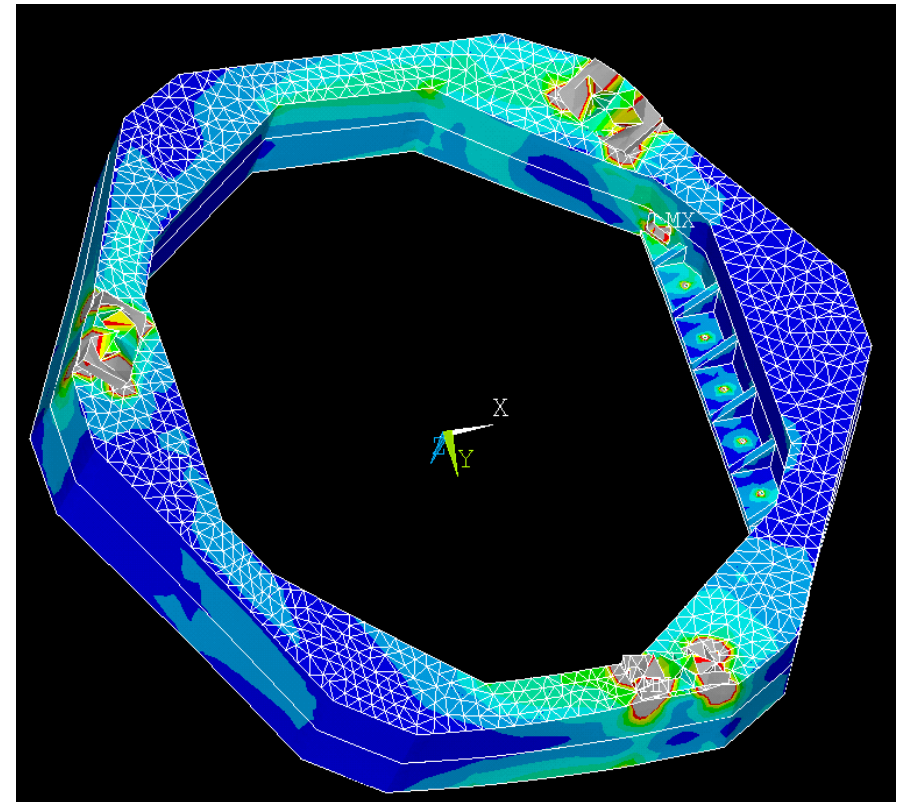
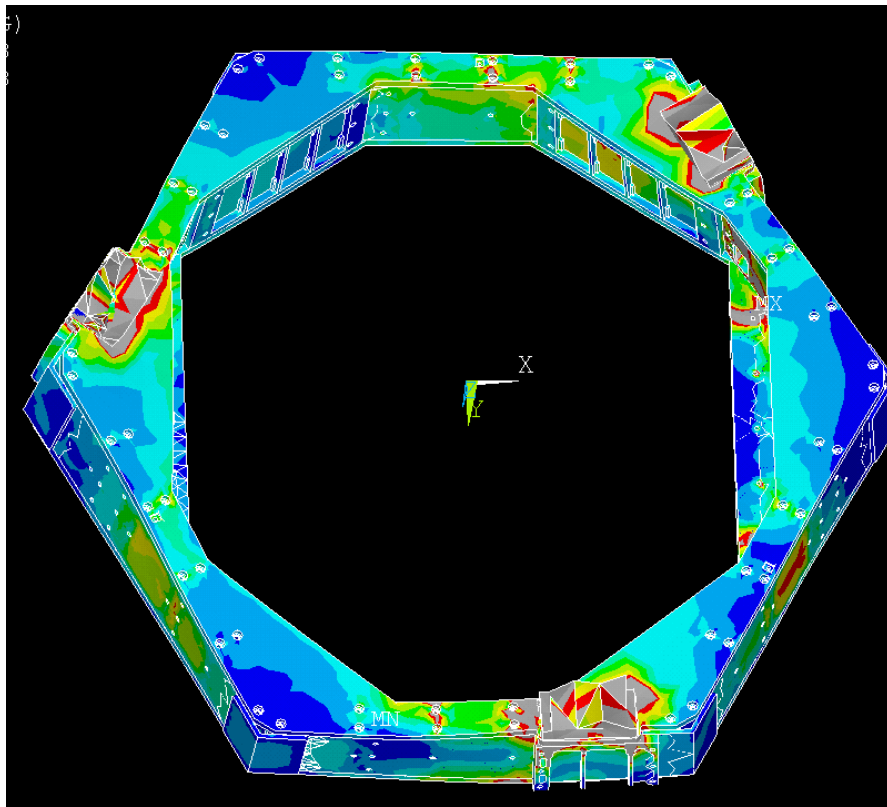


Same scale

FEA (2): Elastic Strain Comparison

LASTI Prototype

Monolithic



Same scale

LIGO

FEA (3): Bottom Flexure Rod Displacement

	Post #	X Displacement		y Displacement		x-y displacement		z Displacement		% between Z displacement
		mm	mil	mm	mil	mm	mil	mm	mil	
LASTI Prototype	1	-0.059	-2.339	-0.117	-4.624	0.132	5.182	0.770	30.316	7.85
	2	-0.229	-9.019	0.035	1.370	0.232	9.123	0.757	29.813	
	3	0.277	10.913	0.073	2.868	0.287	11.283	0.710	27.937	
Monolithic	1	-0.037	-1.444	-0.111	-4.370	0.117	4.602	0.735	28.918	6.36
	2	-0.179	-7.028	0.037	1.458	0.182	7.178	0.729	28.710	
	3	0.194	7.624	0.063	2.464	0.204	8.012	0.688	27.079	

Yet to be added...

- $\frac{3}{4}$ inch fillets inside
- Screws locations
 - Larger webbing around screws
 - Thinner webbing in between
- Deep counterbores & partial threads
- No blind tapped holes
- Vented pockets for vacuum AND cleaning
- *Thicker “top plate” below critical parts (such as blade posts) ?*

Yet to be added... (2)

Hardware

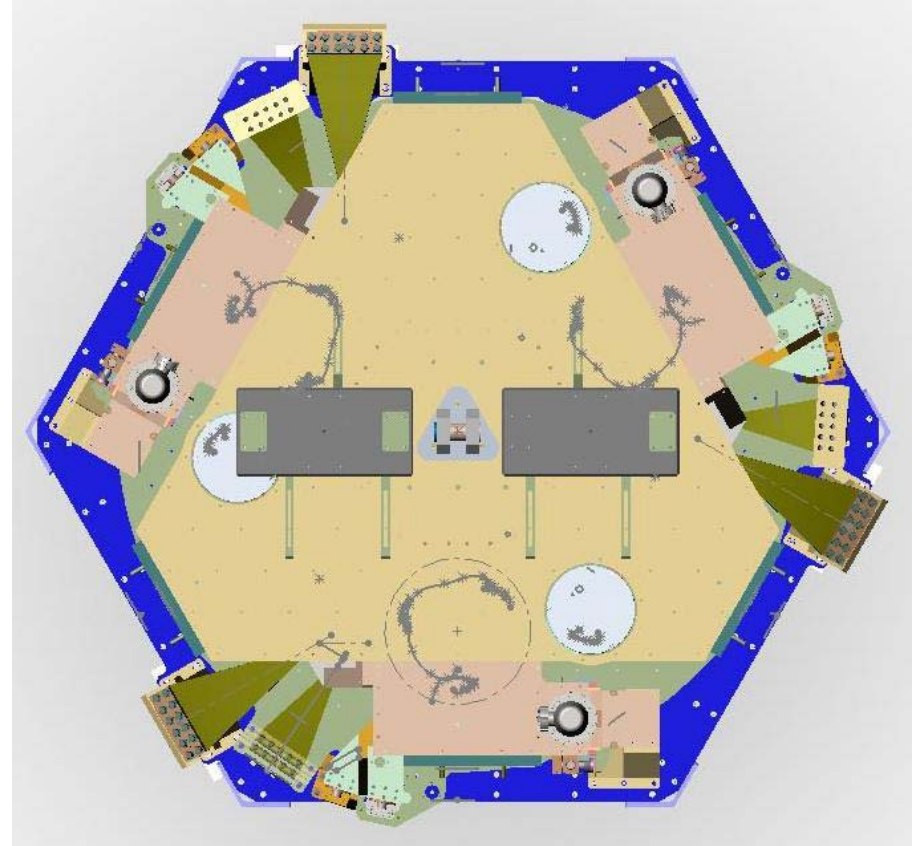
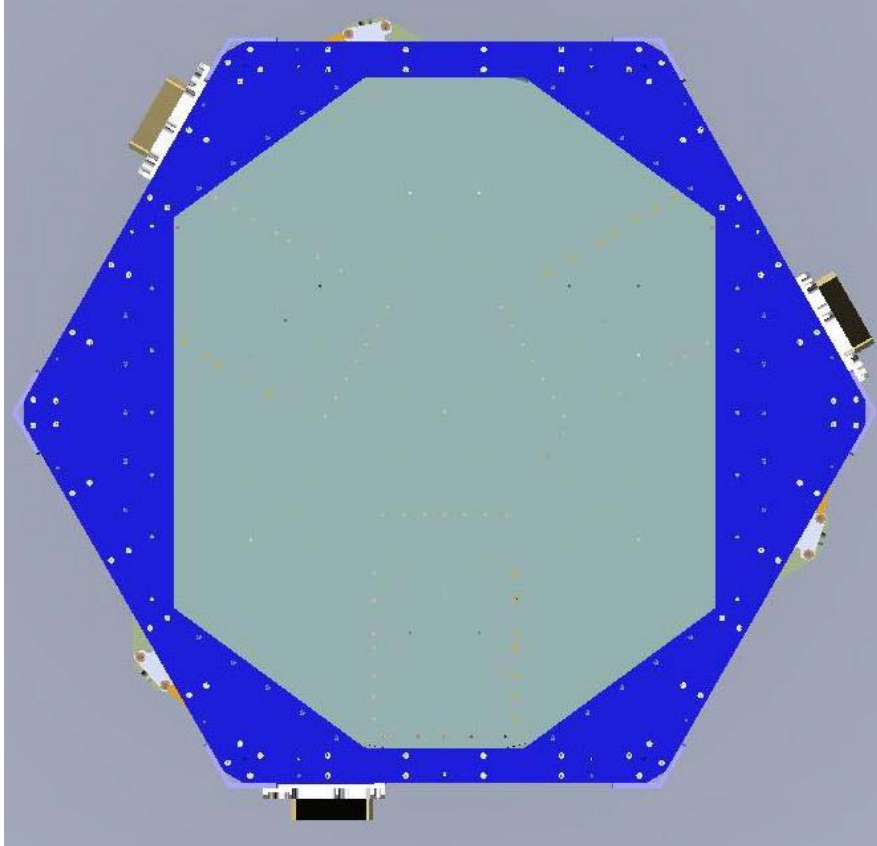
- Alignment pins
 - Taper or ‘multi-stage’
 - Offset from center (to avoid 180 deg rotation)
- Eyebolts to move assembly
- *Nitronic heli-coil?*

Questions?
Comments?
Suggestions?

Vertical Asymmetry measured at LASTI

- Blade vertical stiffness: 2700pds/in
- Loading asymmetry: 80pds
- Virtual Tip Blades height asymmetry:
80/2700~30mils
- (stop allows only +/-12 mils deviation)

Bottom/Top views



AL alloys properties

AL	Density (lb/in ³)	Tensile Strength (ksi)	Young Modulus (ksi)
6061-T6	0.0975	45	10.0e3
7075-T6	0.1015	83	10.4e3
2024-T4	0.1012	68	10.6e3

Source: Mechanical Engineer's Handbook-Materials and Mechanical Design (3rd Ed.), Myer Kutz, Ed John Wiley & Sons

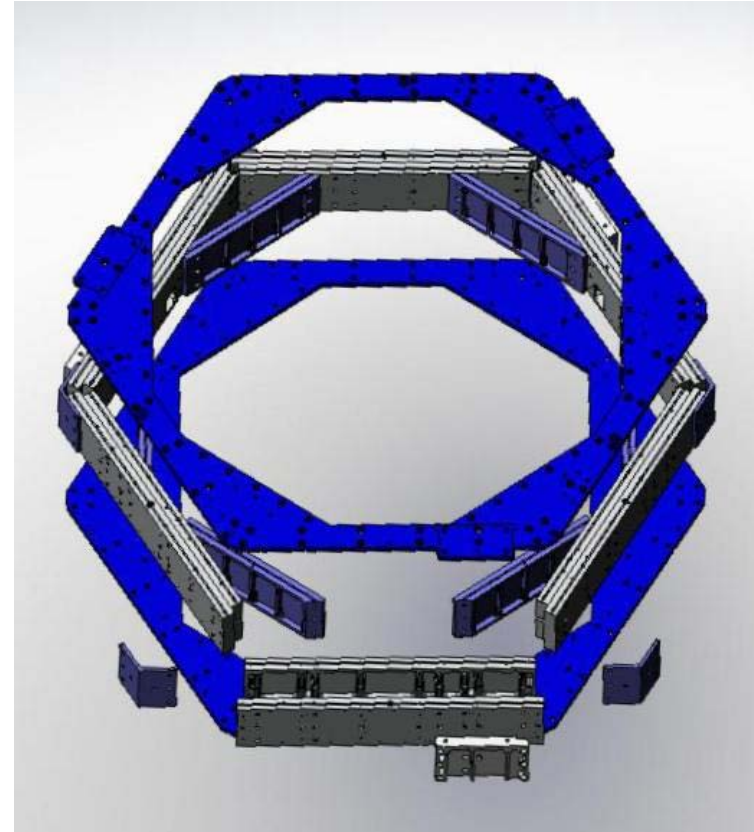
Vacuum capable

LIGO

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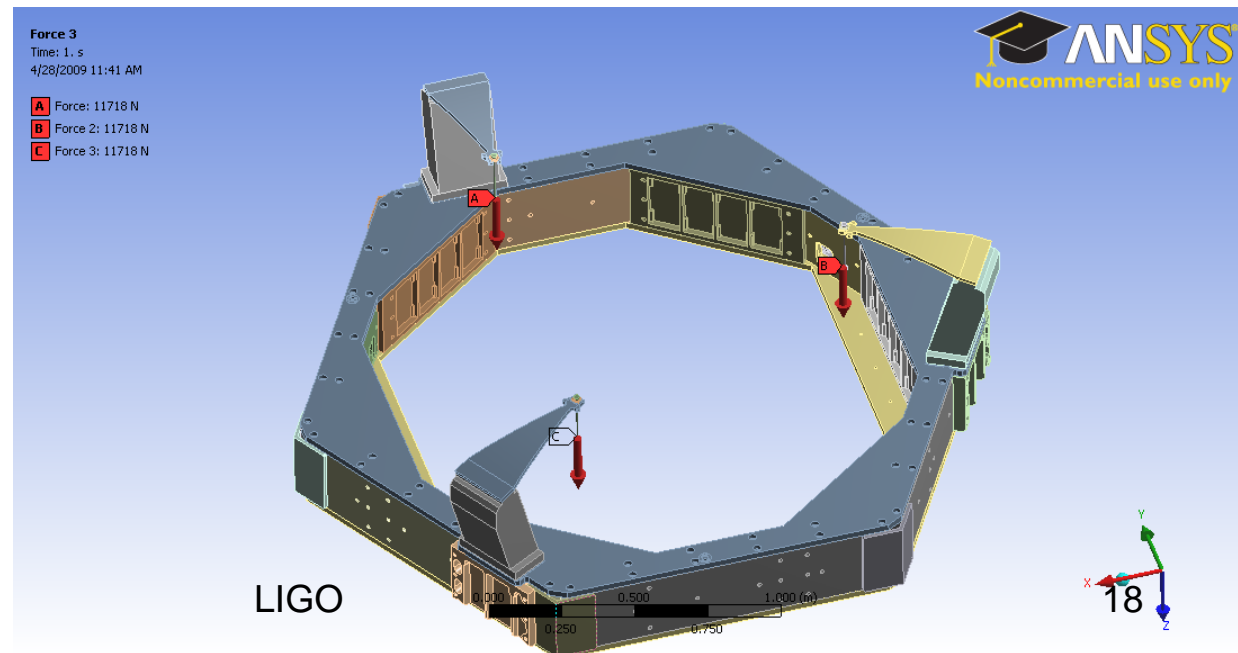
Goals

- Address known problems
 - Wrong materials, etc...
- Simplify assembly
 - Reduce parts number
 - Reduce parts with small differences
 - Simplify alignment
 - Reduce tolerances on cutouts
- Increase stiffness



LASTI Prototype BSC-Stage 0 (2)

- FEA Static
 - Curved blades w/ infinite Young Modulus
 - Stage 0 fixed at the



Static Analysis

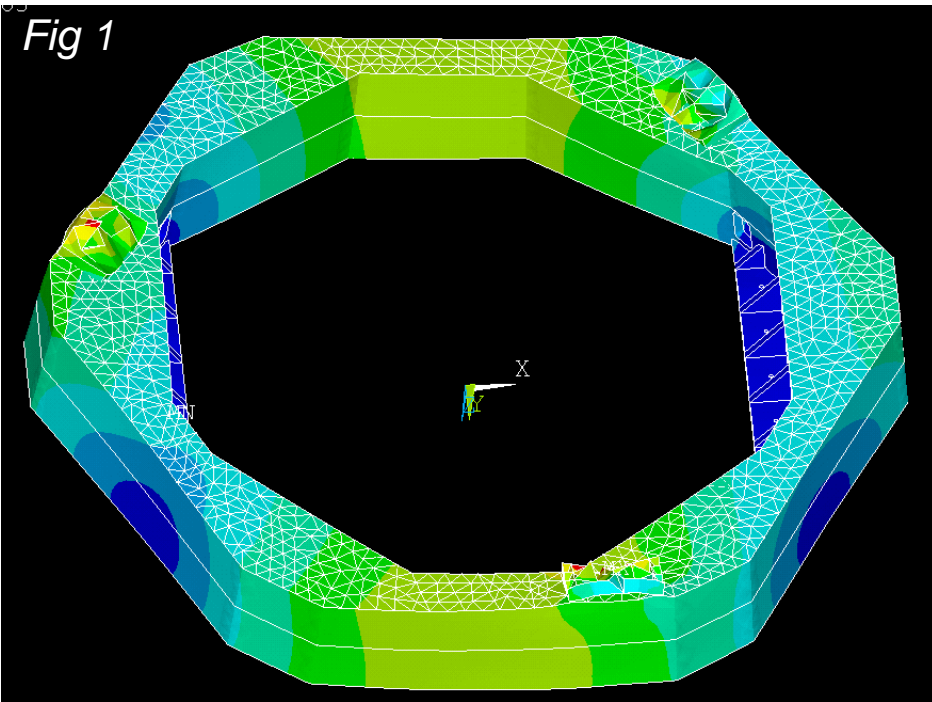


Fig 1: Nodal displacement contours on deformed structure (max 0.120 mm)

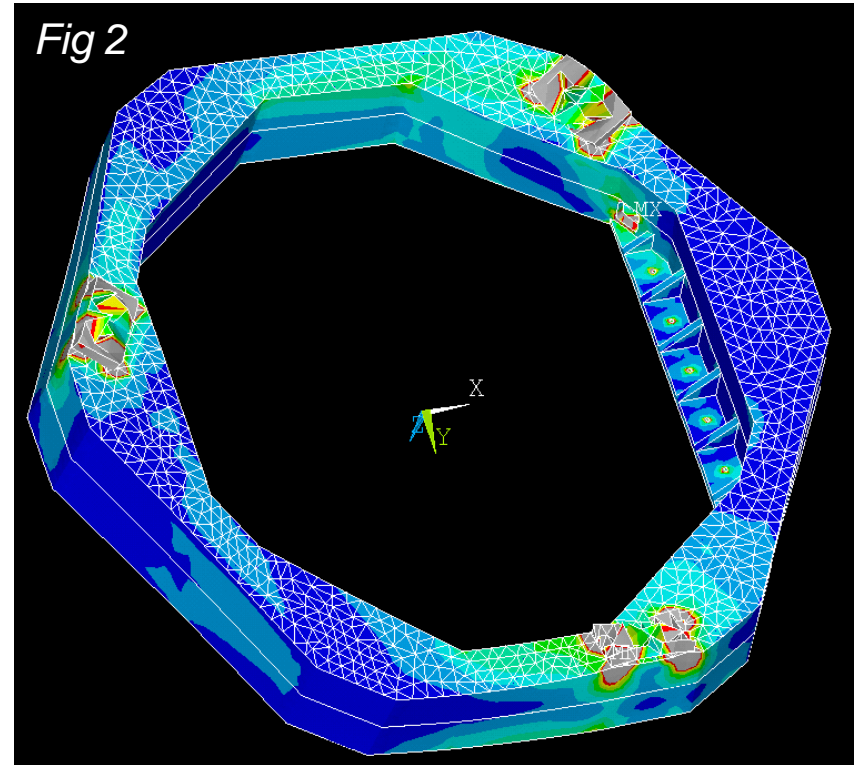


Fig 2: Elastic strain contours on deformed structure (max 0.856 mm)

Post #	z Displacement bottom flexure rod		% between Z displacement
	mm	mil	
1	0.735	28.90	6.36
2	0.729	28.71	
3	0.688	271.1	