

# Update on Suspension Design for Advanced LIGO

**Norna A Robertson**  
**LIGO-Caltech & University of Glasgow**

**for the Advanced LIGO Suspensions  
Group**

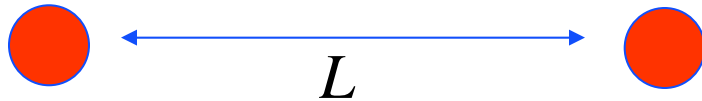


**APS April Meeting  
Denver  
2<sup>nd</sup> May 2009**



- Introduction to gravitational wave detection
- Suspension design for gravitational wave detectors
- Advanced LIGO suspension design
- Conclusion

- Gravitational waves are waves in the curvature of space time.
- We expect a significant flux from astronomical events such as inspiral and merger of neutron stars or black holes, supernova explosions, pulsars.
- We can look for these signals by measuring the time-dependent tidal strain,  $h$ , in space
- Simplest detector – two free masses a distance  $L$  apart whose separation is monitored



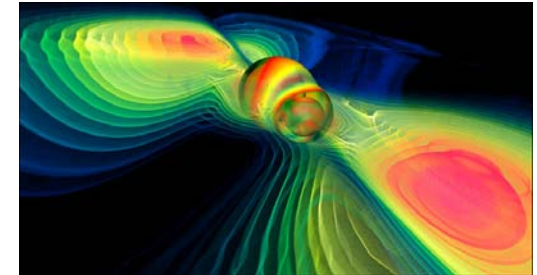
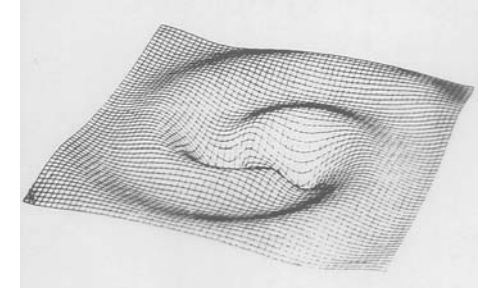
$$\frac{\Delta L}{L} \approx h$$

- Magnitude of  $h$  for reasonable event rate:

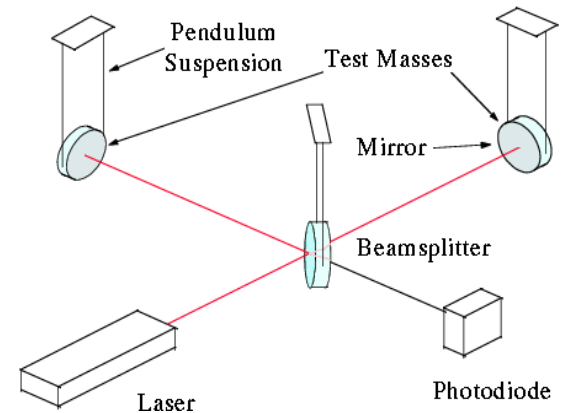
$$h \sim 10^{-22} - 10^{-23}$$

- Practical detector: Michelson Interferometer

- » long baseline interferometry between freely suspended test masses
- » LIGO: Laser Interferometer Gravitational Wave Observatory



Merger of two black holes (Image: MPI for Gravitational Physics/W.Benger-ZIB)



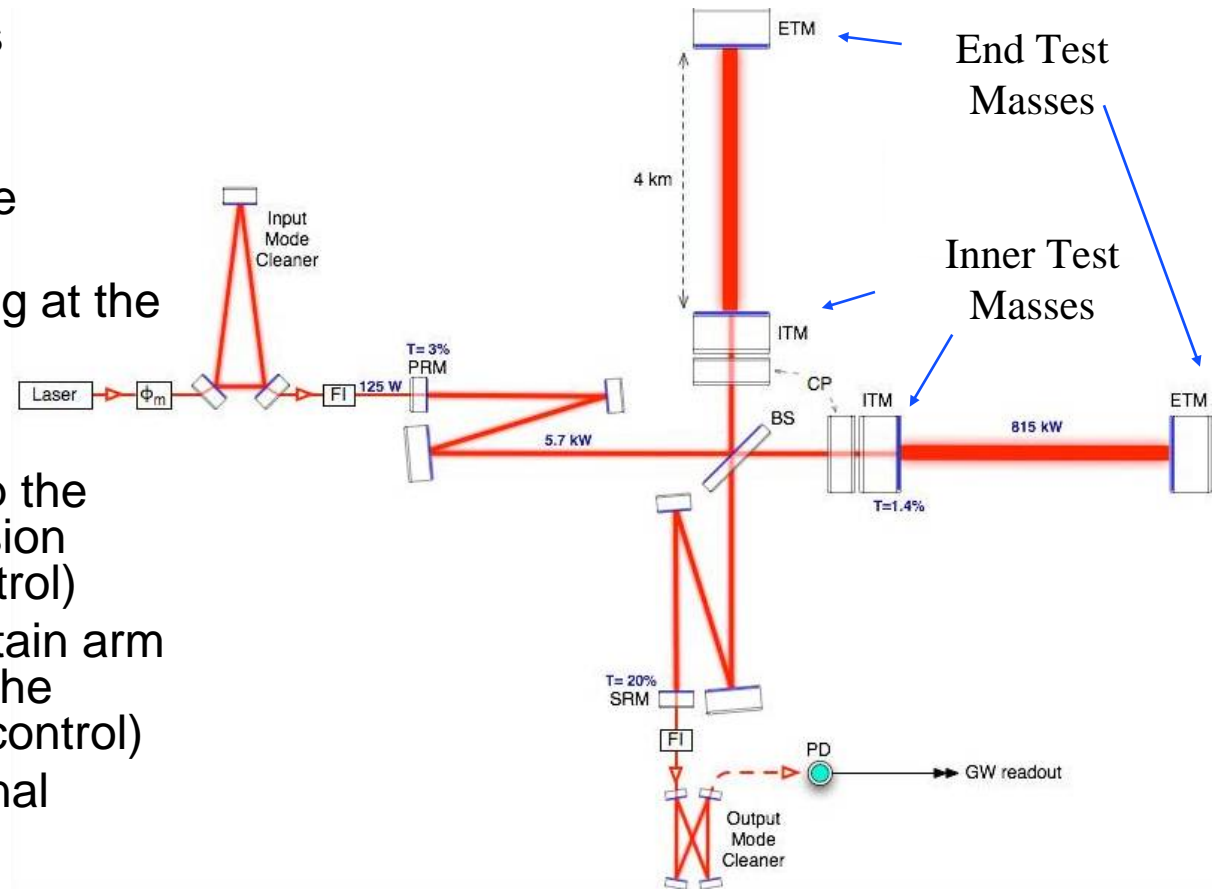
- In principal: long baseline laser interferometry between **freely suspended** test masses

- Fundamental requirements

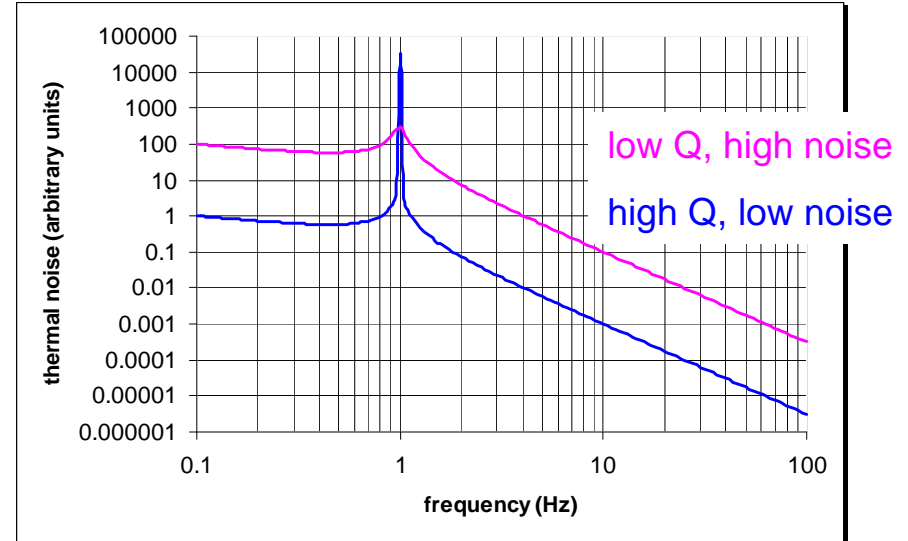
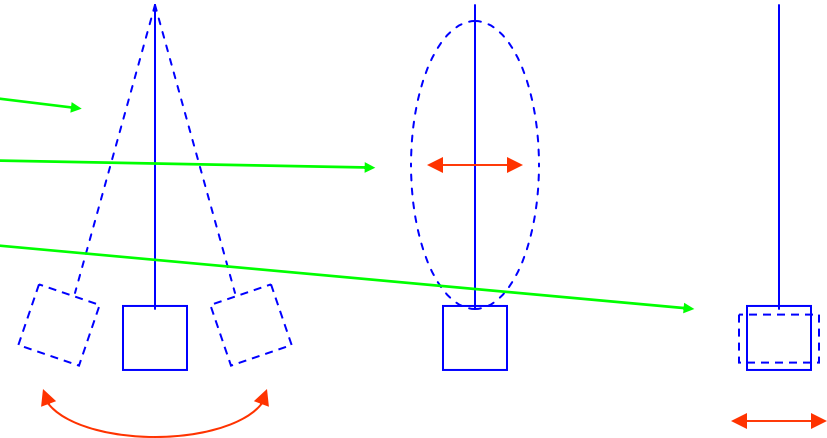
- » support the mirrors to minimise the effects of
  - **thermal noise** in the suspensions
  - **seismic noise** acting at the support point

- Technical requirements

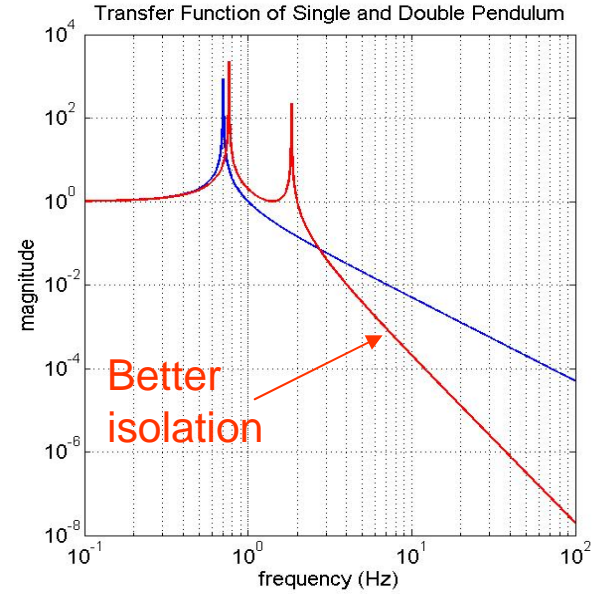
- » allow a means to damp the low frequency suspension resonances (local control)
- » allow a means to maintain arm lengths as required in the interferometer (global control) *without* adding additional noise



- Thermally excited vibrations of
  - » suspension pendulum modes
  - » suspension violin modes
  - » mirror substrates + coatings
- Use fluctuation-dissipation theorem to estimate magnitude of motion
- To minimise:
  - » use low loss (high quality factor, Q) materials for mirror and suspension – gives low thermal noise off resonance -*silica* is a good choice
    - *silica fibre loss angle*  $\sim 2e-7$ ,  
*c.f. steel wire*  $\sim 2e-4$
    - *breaking stress can be larger than steel*
  - » use thin, long fibres to reduce effect of losses from bending

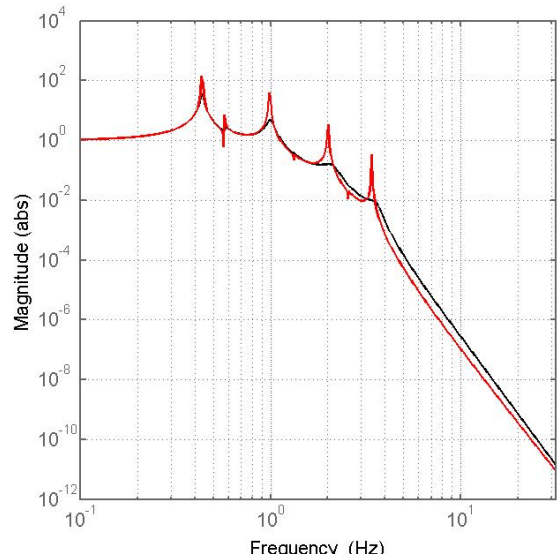


- Seismic noise limits sensitivity at low frequencies - “seismic wall”
- Typical seismic noise at quiet site at 10 Hz is  $\sim \text{few} \times 10^{-10} \text{ m}/\sqrt{\text{Hz}}$ 
  - » many orders of magnitude above target noise level
- Solution - use multiple stages of isolation
- Isolation required in vertical direction as well as horizontal due to cross-coupling



Advantage of **double** over **single** pendulum, same overall length

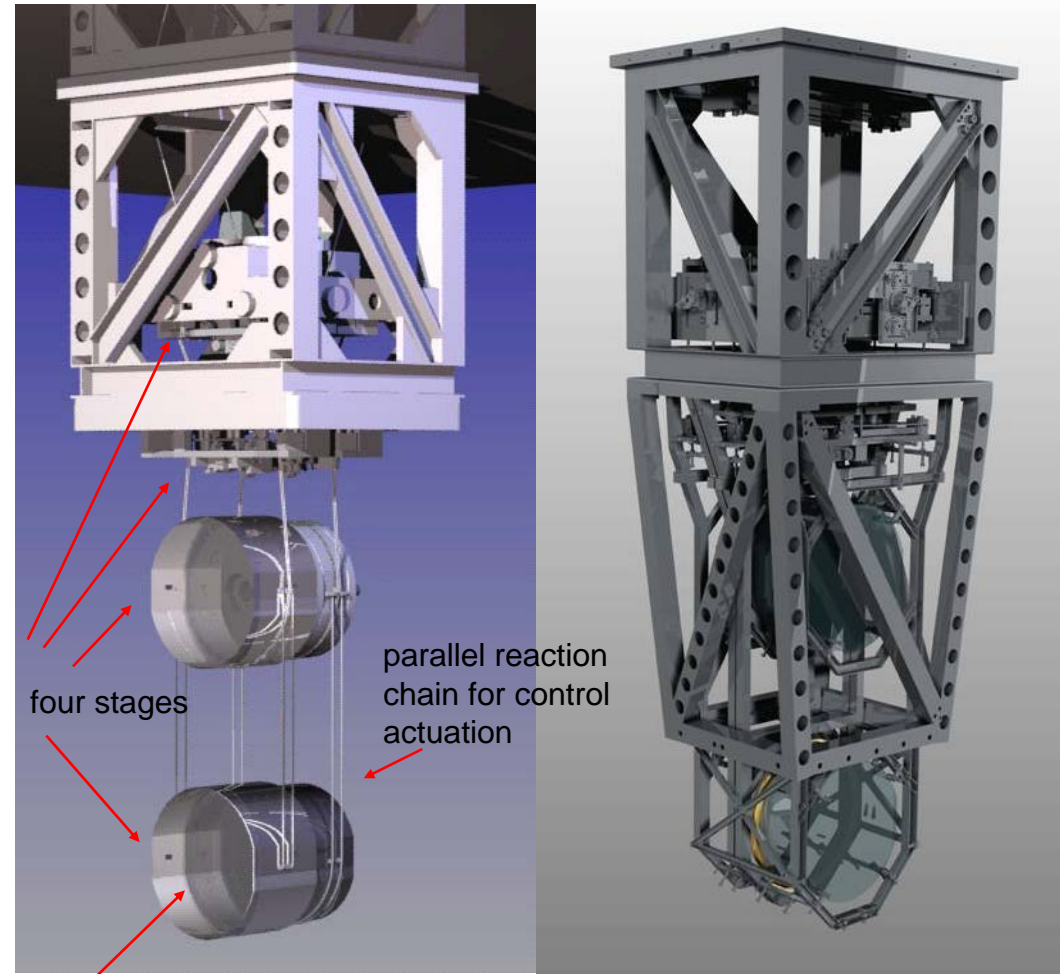
Initial LIGO uses a single stage wire suspension



Quadruple pendulum transfer function: predicted longitudinal isolation  $\sim 3 \times 10^{-7}$  at 10 Hz



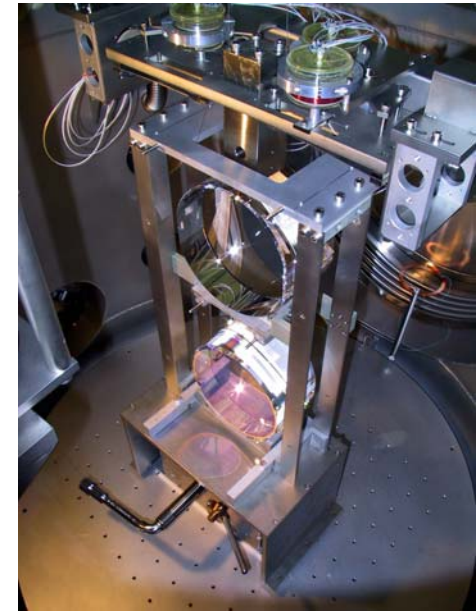
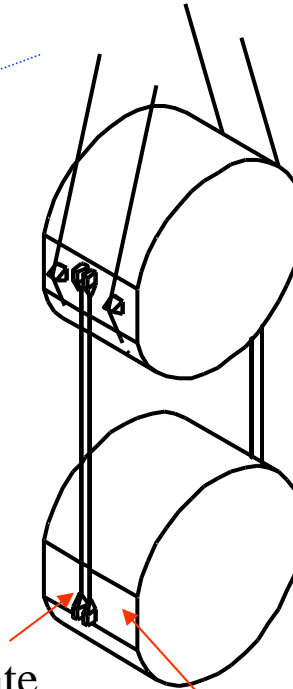
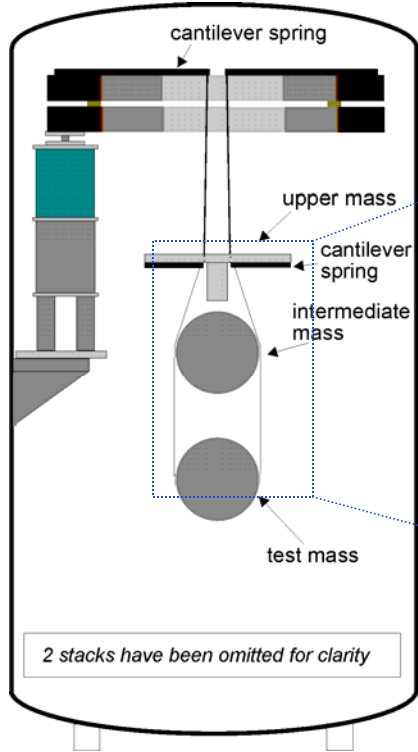
- Target noise level (both for thermal and seismic noise):  $10^{-19}$  m/  $\sqrt{\text{Hz}}$  at 10 Hz
- Thermal noise reduction: use monolithic fused silica suspension as final stage
- Seismic isolation: use quadruple pendulum + 3 stages of maraging steel blades for vertical isolation
  - » *isolation @ 10Hz: quad ~ 3e-7, c.f. single stage ~ 5e-3*
- Control noise minimisation: apply damping at top mass (for 6 degrees of freedom) + use quiet reaction pendulum for global control actuation
  - » coil/magnet actuation at top 3 stages
  - » electrostatic drive at test mass



40 kg silica test mass

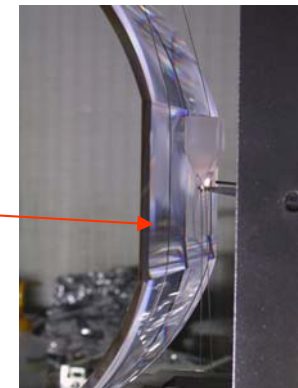
# Monolithic Silica Suspensions developed for GEO 600

**Monolithic fused silica suspensions** are used in the German/UK GEO600 detector: makes use of silicate bonding technique developed for Gravity Probe B

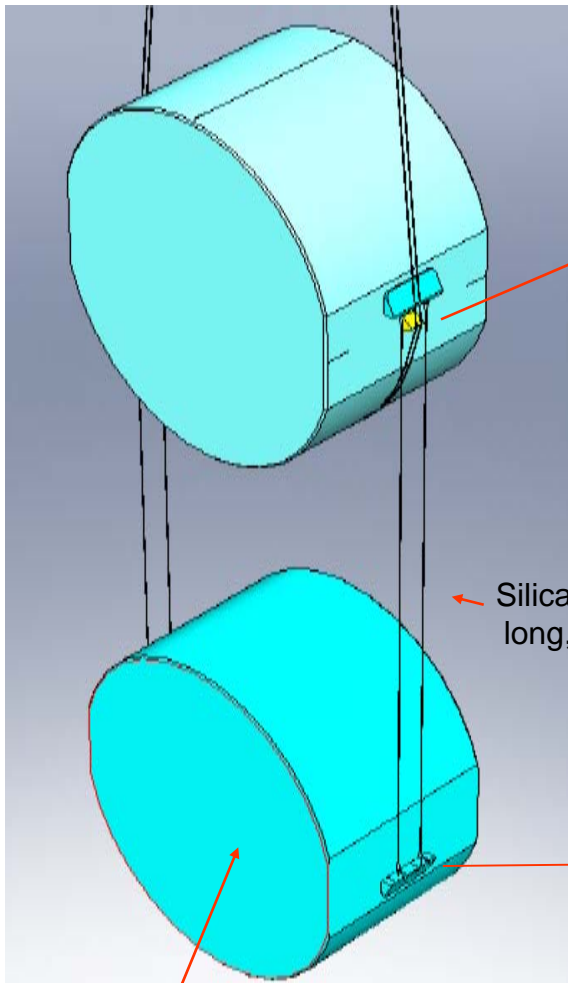


Ears silicate bonded to masses

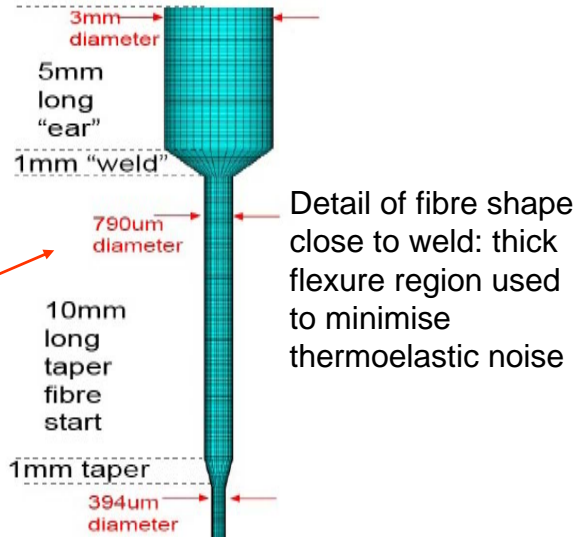
Silica fibres welded to ears





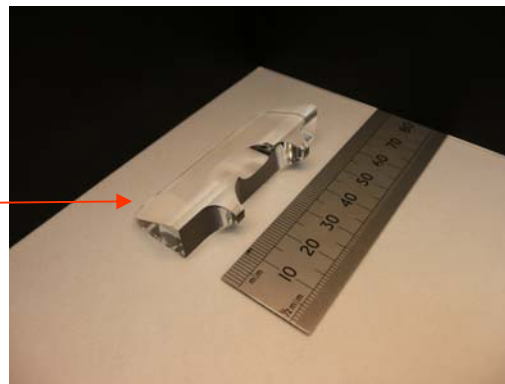


Mirror: 40 kg silica mass



Detail of fibre shape close to weld: thick flexure region used to minimise thermoelastic noise

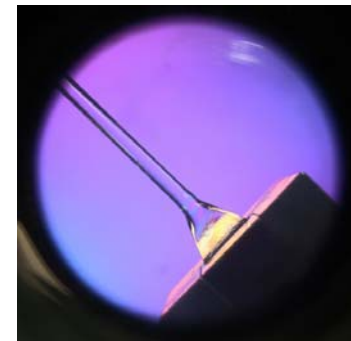
Silica fibres 600 mm long, 0.4 mm diam.



Example of ear to be bonded to silica mass



Fibre pulling machine at MIT

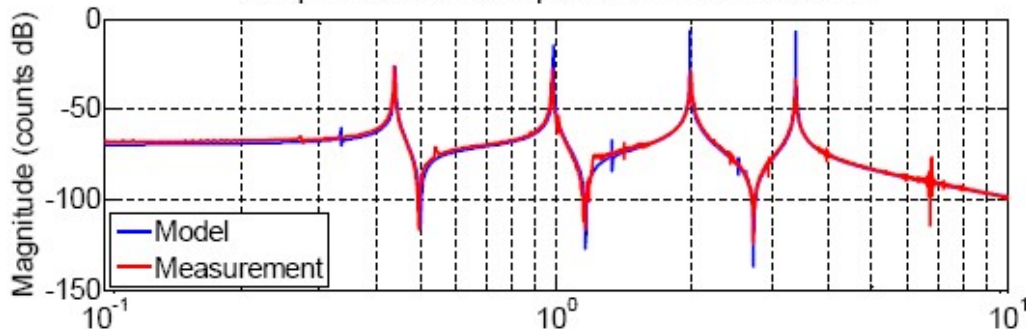


Visual inspection of test weld using crossed polarisers at Glasgow

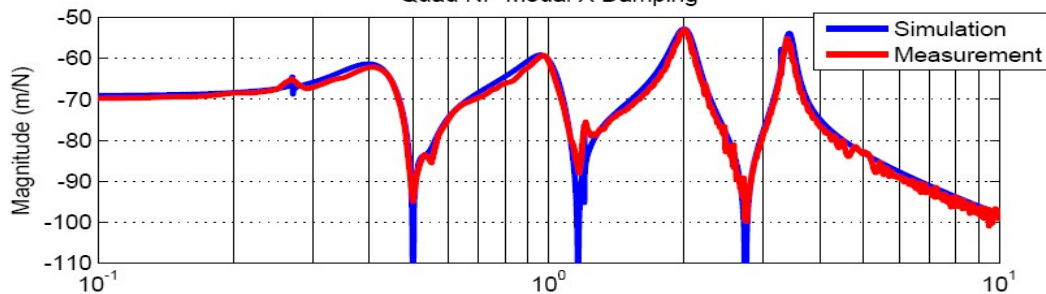


Welding test at Glasgow

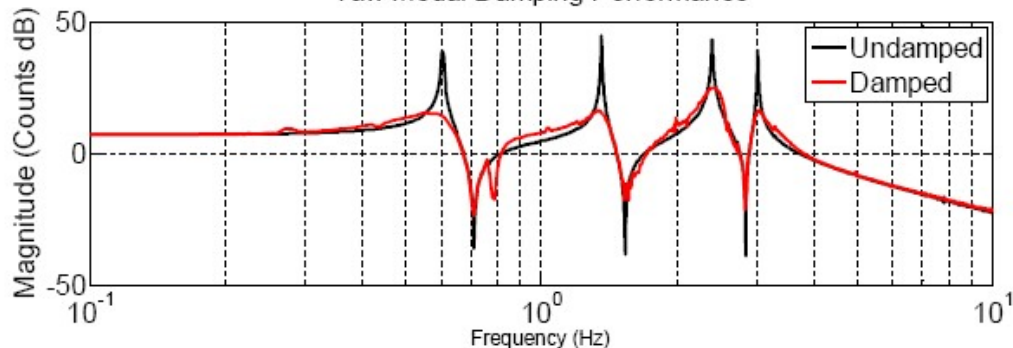
X Top Mass Model Comparison with Measurements



Quad NP Modal X Damping



Yaw Modal Damping Performance

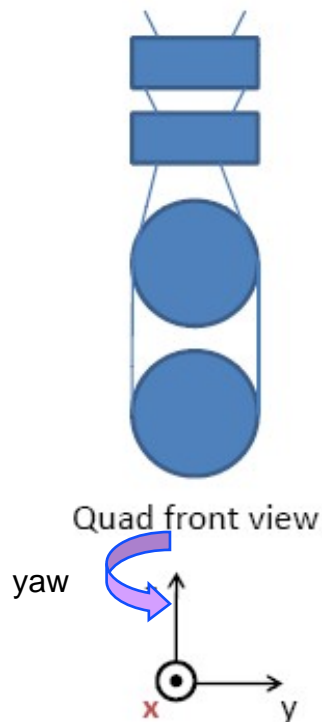


Example of transfer functions (TF) taken at top mass (drive to response)

Top: measured and modelled TF in X direction with no damping applied

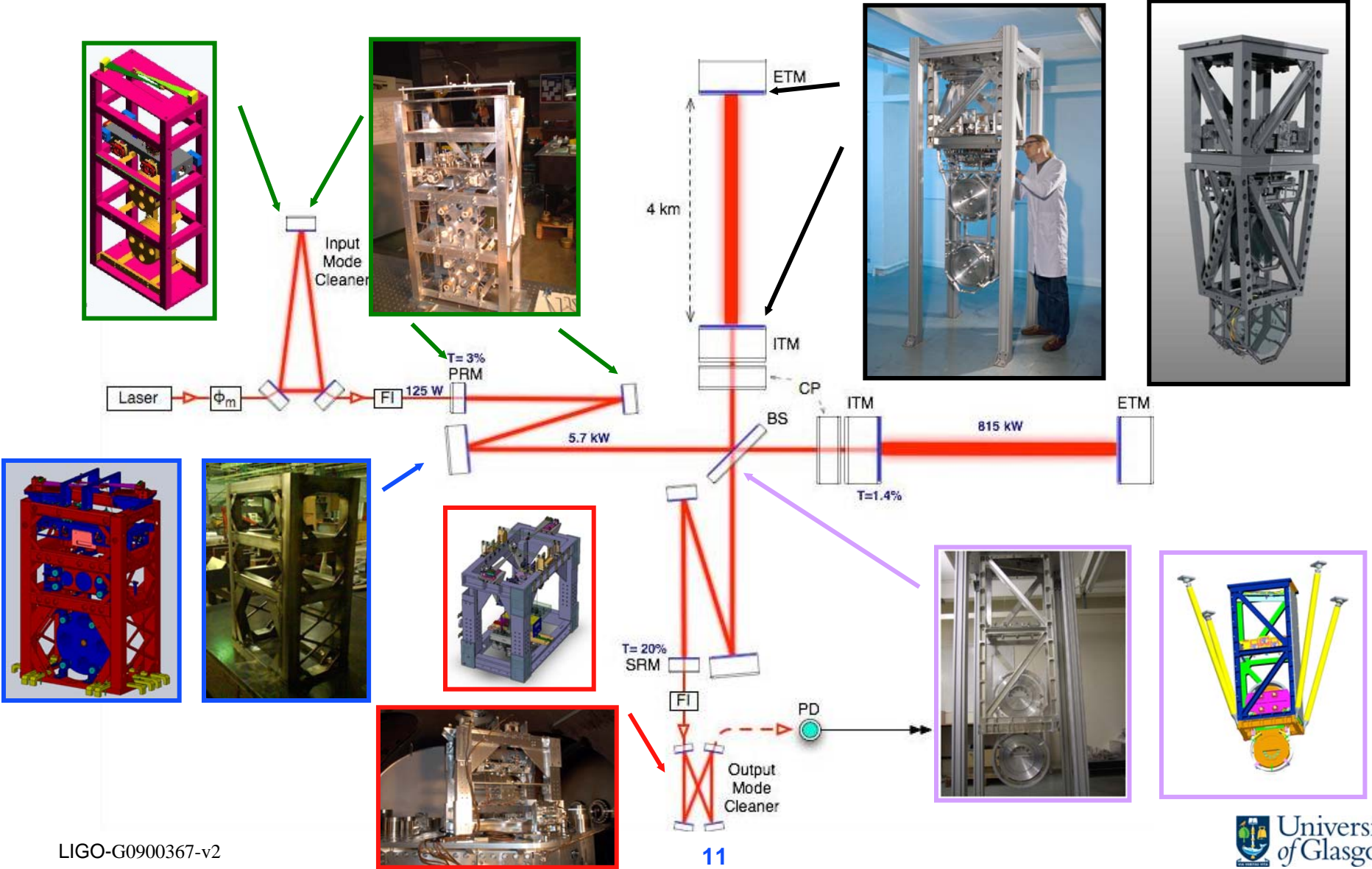
Middle: simulated and measured modal damping of TF in X direction

Bottom: measurements of yaw TF undamped and damped



# Design Concept: other suspensions

Similar concept to test mass suspensions but with reduced number of stages, use of wire suspensions, and no reaction chain





- Advanced LIGO suspensions work is progressing:
  - » Ongoing development work, in particular on the monolithic suspensions
  - » Program of tests on full-scale prototypes
  - » Production of some parts already underway and assembly imminent
    - 2009 - 2011: 47 major suspensions will be constructed
  - » Experience to date gives us confidence that we can meet our requirements
  - » Large international team effort



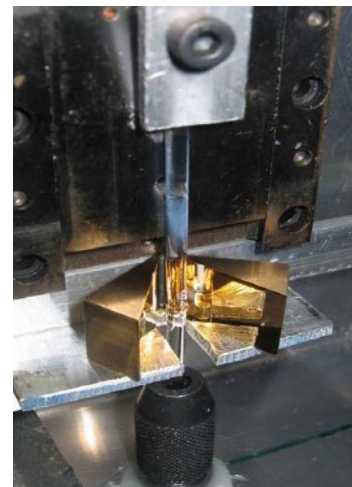
Sensor/actuator units for control in production at Birmingham



LIGO- Installation of quad prototype with full optics at MIT



Testing rig for UHV compatibility at RAL



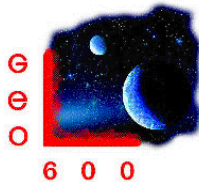
Welding test at Glasgow



Welding set-up at MIT

## Advanced LIGO Suspensions Team

- **LIGO Caltech:** M. Aronsson, D. Coyne, T Edzel, J. Heefner, A. Heptonstall, A. Ivanov, G. McIntyre, N. Robertson (also Glasgow) – team leader, C Torrie (also Glasgow)
- **LIGO Hanford Observatory:** M Barton, B. Bland, D. Cook, G. Moreno
- **LIGO Livingston Observatory:** D. Bridges, M. Meyer, B. Moore, J. Romie, D. Sellers, G. Traylor
- **LIGO MIT:** P. Fritschel, R. Mittleman, B. Shapiro
- **University of Glasgow:** C. Craig, L. Cunningham, A. Cumming, G. Hammond, K. Haughian, J. Hough, R. Jones, R. Kumar, I. Martin, S. Rowan, K. Strain, M. Van Veggel, A. Wanner
- **Rutherford Appleton Laboratory (RAL):** A. Brummitt, J. Greenhalgh, J. O'Dell
- **University of Birmingham:** S. Aston, R. Cutler, D. Lodhia, A. Vecchio
- **Strathclyde University:** N. Lockerbie, K. Tokmakov



University  
of Glasgow



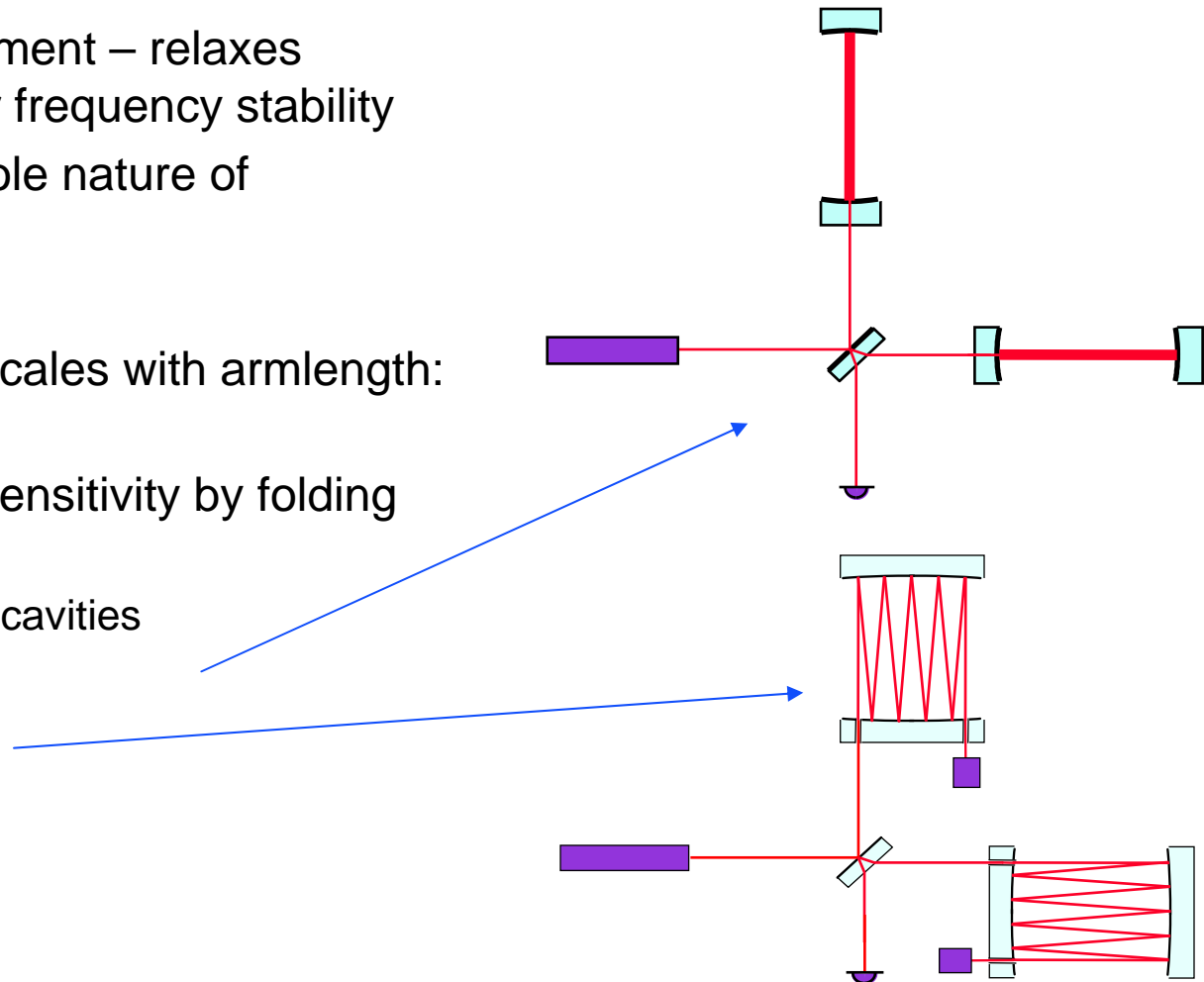
THE UNIVERSITY  
OF BIRMINGHAM



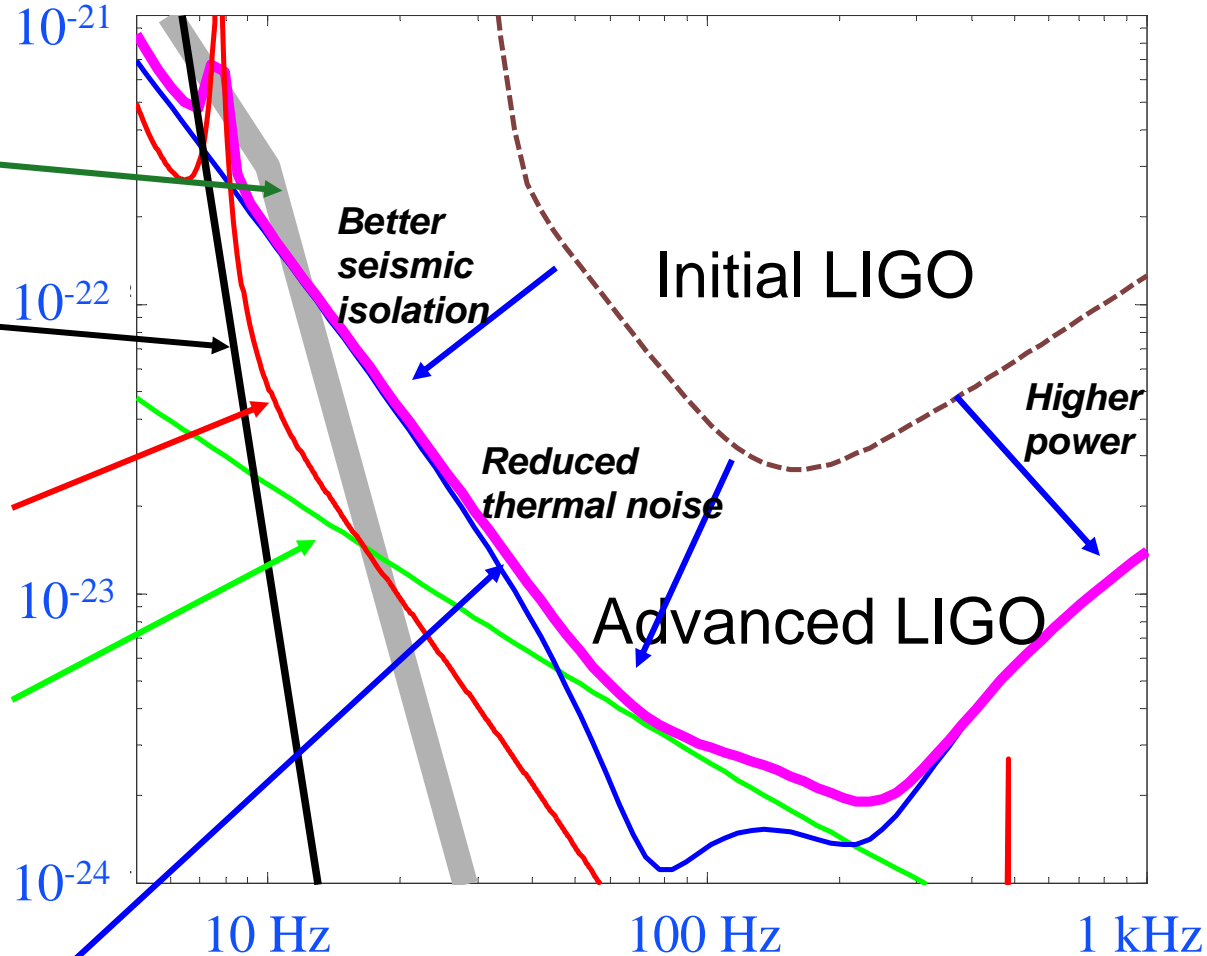




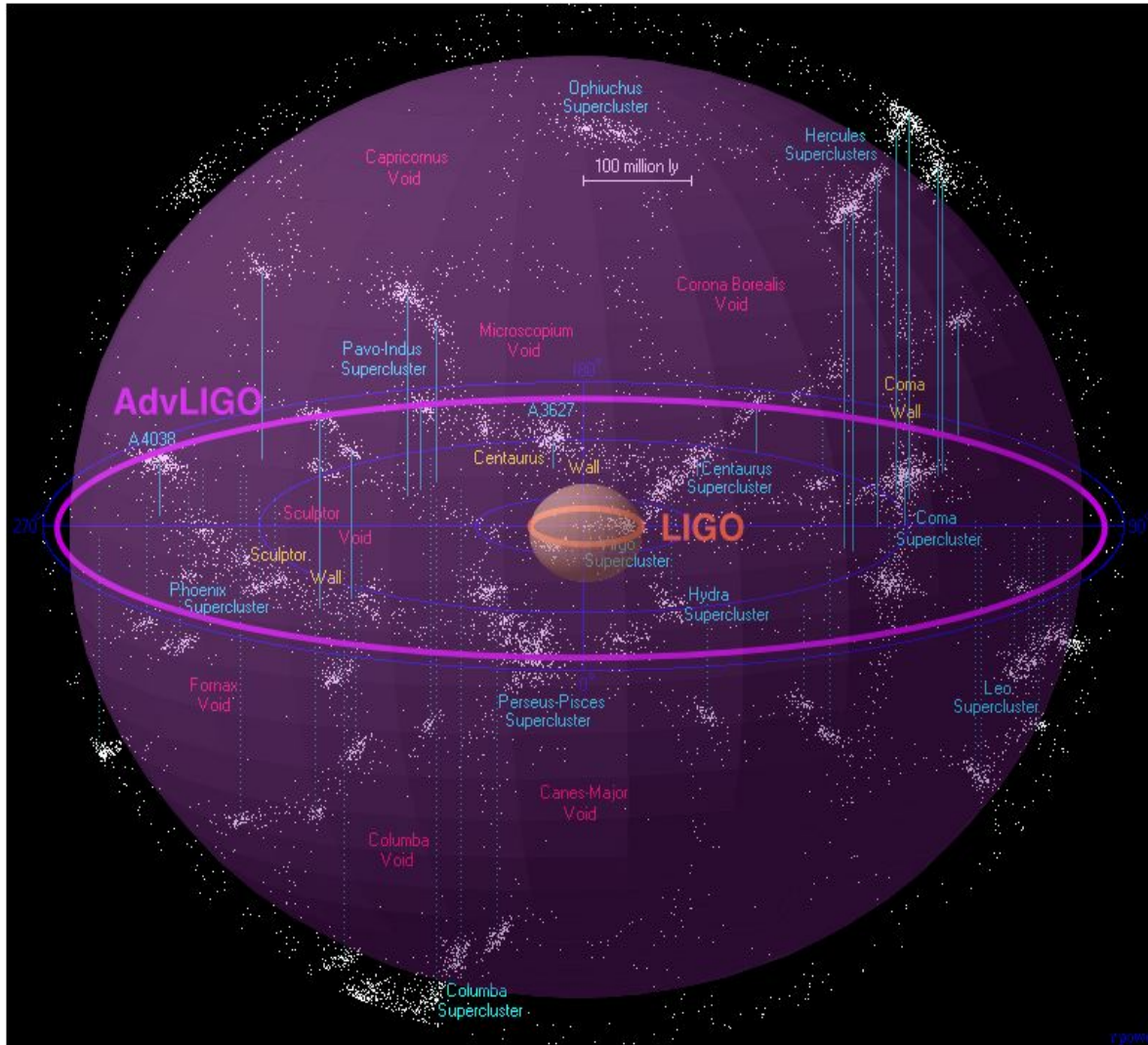
- Differential measurement – relaxes requirement on laser frequency stability
- Matches to quadrupole nature of gravitational wave
- Wideband operation
- Sensitivity to strain scales with armlength: use long baseline,  $L$
- Further increase in sensitivity by folding light in the arms:
  - » Fabry Perot cavities
  - » delay lines



- Newtonian background, estimate for LIGO sites
- Seismic cutoff at 10 Hz
- Suspension thermal noise
- Test mass mirror coatings thermal noise
- Unified quantum noise: dominates at most frequencies for full power, broadband tuning



(y scale:  $h/\sqrt{rt}$  Hz)



Factor of 10 in sensitivity gives factor of 1000 in volume and hence in event rate



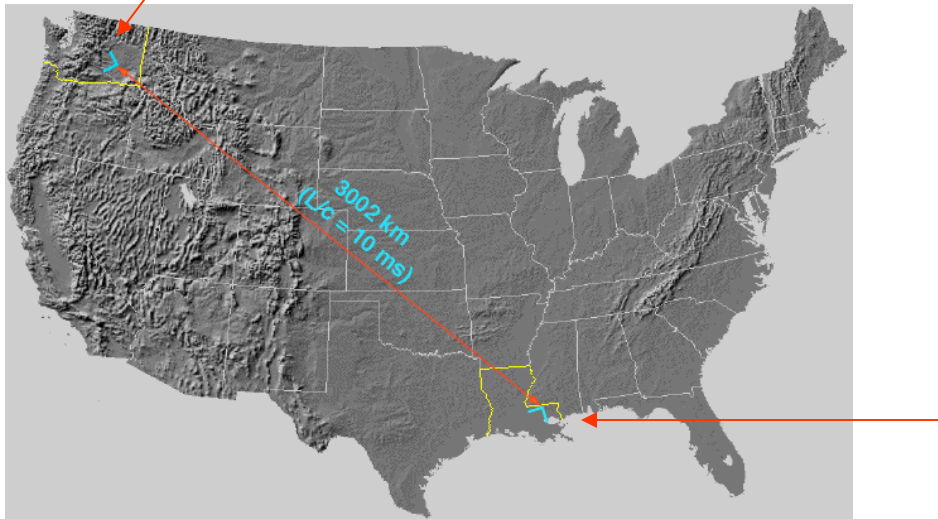


### LIGO Hanford Observatory, WA

2 detectors: currently 4 km arm length and 2 km arm length

### LIGO Livingston Observatory, LA

1 detector: 4 km arm length



NSF funded. Designed and built by Caltech and MIT.

LIGO-G0900367-v2



## LIGO

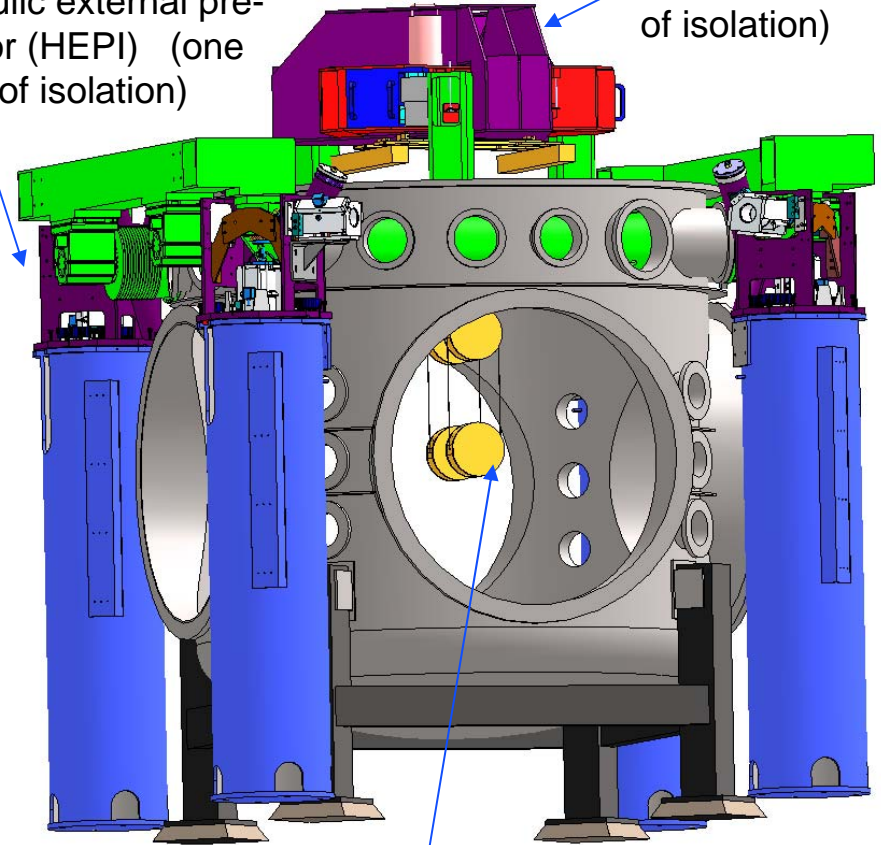
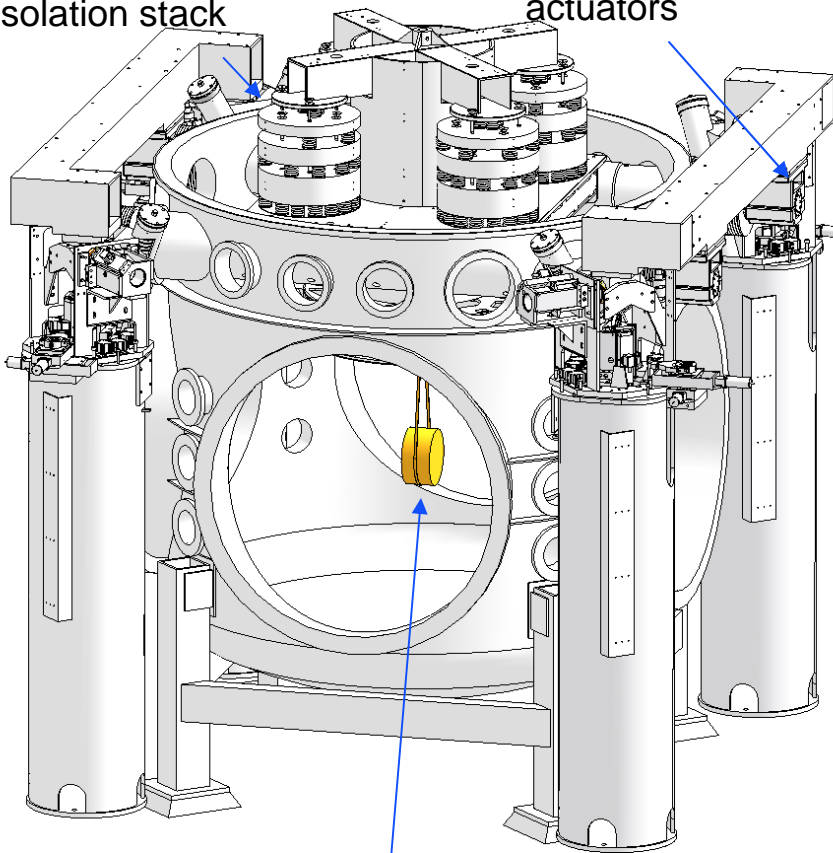
## Advanced LIGO

4 layer passive  
isolation stack

coarse & fine  
actuators

hydraulic external pre-  
isolator (HEPI) (one  
stage of isolation)

active isolation  
platform (2 stages  
of isolation)



single pendulum on  
steel wire

quadruple pendulum (four  
stages of isolation) with  
monolithic silica final stage