## **Design Specifications for the OMC Suspension**

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Further updated for FDR Feb 2009 by NAR (updates in italics) T070189-v1

Further updated by NAR Feb 7<sup>th</sup> 2014, updates in red. T070189-v3

Note I am calling this v3 as there is confusion in numbering on the DCC between v1 and v2.

Property	Value or Description	Comment	Comments added for 2 <sup>nd</sup> prototype readiness review Aug/ Sept 2007 Further comments Feb 2009
Baseplate Dimensions	450 mm x 150 mm x 40 mm	Baseplate only	Actual silica bench (aka baseplate) 450 mm x 150 mm x 39 mm aLIGO size 450mm x 150mm x 41.275 mm (D1200105)
Payload Mass	6.0 kg  Current design has mass ~ 6.9 kg  ALIGO Target 7.0 kg (ref L0900064, pg 3	Baseplate plus components	Design allows for +/-10% (i.e. maximum of 6.6 kg)  Blades redesigned for higher mass  Actual ~ 7.2 kg (in ICS entries)
Baseplate Material	Light-weighted aluminum, or fused silica	Baseplate provided by ISC	Al bench suspended and tested, silica bench still to be suspended  Silica benches now suspended
Baseplate internal modes	First mode > 1000 Hz	Get it above IFO noise minimum and violin mode fundamental	FEA shows ~ 1100 Hz (see supporting documentation)

Isolation	Double pendulum, with two stages of blades for vertical isolation	analysis of baseplate	Isolation at 10 Hz Long: ~ 5 x 10^-4 Vert: ~ 4 x 10^-3 (exact values depend on level of damping and details of bench design)	
Solid-body mode eigenfrequencie	0.8-2 Hz es	This is a guideline only. Modes involving stretching of the bottom stage wires will of course be higher.	Actual frequencies are in range 0.5 Hz (lower yaw mode) to ~ 7 Hz (higher roll mode).  Details on OMC Suspension wiki site under "Testing" link  Final values in SUS Ops manual under OMCS https://awiki.ligo-wa.caltech.edu/aLIGO/Suspensions/OpsManual	
Suspension fiber Steel - music type wire				
Beam height	101.6 mm +/- 2 mm[4.0 inches] above HAM optics table; 25.4 mm +/- 2 mm [1.0 inch] above baseplate Current design	same as iLIGO ISC	Beam is now below bench, not above	
	has beam 20 mm below the baseplate			
Suspension structure footprint	TBD	Keep as small as practical, to leave as much room as possible on HAM table for other components		
Structure resonances	First mode > 150 Hz		Lowest freq. is ~ 140 Hz (see supporting documentation)	
Suspension structure height	725 mm ?	This is not really a spec that needs to defined here	Structure height has been looked at in HAM 6 layout to check it doesn't hit ceiling. (see supporting documentation)	
Suspension point locations	4 points	Along (150mm) width, as close to	Susp. points moved in from edge in width direction to reduce higher pitch mode from 9	

on baseplate edges as possible; Hz to ~ 4 Hz. Susp points are at 20% of length along length, position from ends in the long axis direction. points to reduce plate Updated – see FDD T0900060-v2 or above motion (e.g., 22% of length from ends minimizes static deflection) Slots in plate, or pegs Countersunk through holes chosen for ease of Suspension manufacture of silica bench inserted in side of **TBD** point design plate Updated – see FDD T0900060-v2 or above Local damping Active, 6 DOF Same as IMC B'ham OSEMS used **Probably** OSEM type **TBD** 'Birmingham OSEMs' Pointing range using B'ham OSEMs of order 2 Few hundred Baseplate Guesstimate -- what's milliradians in roll, pitch and yaw positioning & microns, few the IMC control pointing range hundred microrange? (DC) rads Not expected to be Actuator force TBD spectrum critical Actuator noise Not expected to be **TBD** limits difficult Optical line of sight/clearance regs Electrical wiring TBD No., gauge, type, to baseplate connector type Accuracy of mechanical pitch and yaw positioning Accuracy of

provide Still to be specified

Beam dumps on mounting holes SUS hardware on uprights, at beam height

mechanical vertical positioning Mechanical stops for baseplate In place – see detailed mechanical drawings